A coarse-graining, ultrametric approach to resolve the phylogeny of prokaryotic strains

with frequent homologous recombination

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ABSTRACT

A frequent event in the evolution of prokaryotic genomes is homologous recombination,

where a foreign DNA stretch replaces a genomic region similar in sequence. Recombination

can affect the relative position of two genomes in a phylogenetic reconstruction in two

different ways: (i) one genome can recombine with a DNA stretch that is similar to the other

genome, thereby reducing their pairwise sequence divergence; (ii) one genome can

recombine with a DNA stretch from an outgroup genome, increasing the pairwise divergence.

While several recombination-aware phylogenetic algorithms exist, many of these cannot

account for both types of recombination; some algorithms can, but do so inefficiently.

Moreover, many existing algorithms require that a substantial portion of each genome has not

been affected by recombination, a sometimes unrealistic assumption. Here, we propose a

novel coarse-graining approach for phylogenetic reconstruction (CGP), which is

recombination-aware, applicable even if all genomic regions have experienced substantial

amounts of recombination, and can be used on both nucleotide and amino acid sequences.

CGP considers the local density of substitutions along pairwise genome alignments, fitting a

model to the empirical distribution of substitution density to infer the pairwise coalescent

time. Given all pairwise coalescent times, CGP reconstructs an ultrametric tree representing

vertical inheritance. Based on simulations, we show that the proposed approach can

reconstruct ultrametric trees with accurate topology, branch lengths, and root positioning.

Applied to a set of *E. coli* strains, the reconstructed trees are most consistent with gene

distributions when inferred from amino acid sequences, a data type that cannot be utilized by

many alternative approaches.

AUTHOR SUMMARY

In homologous recombination, segments of foreign DNA overwrite similar segments of a prokaryotic genome. A single recombination event can simultaneously introduce many DNA substitutions. This disturbs phylogenetic signals, making it difficult to reconstruct prokaryotic family trees. While a handful of recombination-aware phylogenetic algorithms have been proposed, most do not take all effects of recombination into account; others rely on the frequently unrealistic assumption that a substantial part of a genome has not been affected by recombination at all. Here, we introduce a novel approach to phylogenetic reconstruction, which estimates the age of the most recent common ancestor of two strains from the density distribution of DNA or amino acid substitutions between their genomes. The proposed phylogenetic tree is the tree most compatible with these age estimates. Based on nucleotide or amino acid sequences, our approach accurately predicts the topology, branch lengths, and root positioning of prokaryotic family trees.

INTRODUCTION

The transfer of DNA stretches from one prokaryotic genome to another—termed horizontal gene transfer (HGT) or lateral gene transfer (LGT)—is a major driver of prokaryotic evolution [1]. It is caused by a variety of mechanisms, including transformation, transduction, conjugation, and gene transfer agents [2,3]. Many prokaryotic genomes encode defense systems against foreign DNA, such as the restriction modification system [4]. A foreign DNA stretch that enters the prokaryotic cell and survives these host defenses may be incorporated into the host genome. If the incoming DNA stretch is highly similar to a stretch on the host genome, homologous recombination may occur, where the incoming DNA stretch homologously recombines with the host stretch and overwrites it [5,6]. Alternatively, the

incoming stretch may be inserted directly into the host genome through non-homologous

recombination.

HGT allows the fast spread of genes through prokaryotic pangenomes, and facilitates

rapid adaptation to environmental changes. A point in case is the spread of antibiotic

resistance genes in pathogenic bacteria via HGT [7]. But recombination is also crucial for the

long-term maintenance of prokaryotic populations, as it helps to repair DNA damaged by

deleterious mutations, thereby avoiding the mutational meltdown of Muller's ratchet [8]; in

that sense, prokaryotic recombination may fulfill the same function as does sex in eukaryotes.

Computational modelling also suggests that recombination may help prokaryotes to purge

selfish mobile genetic elements [9].

Recombination can severely affect phylogeny reconstructions. Its effects on genome

divergence are complex. Depending on the circumstances, recombination can speed up the

divergence of a genome pair or slow it down [6]; its effects may severely affect the accuracy

of estimated branch lengths of phylogenetic tree. For example, (i) when a stretch of genome

X is replaced by DNA from genome Y, some of the single nucleotide polymorphisms that

previously differentiated X and Y will be erased, shortening the apparent evolutionary

distance between the two genomes. Conversely, (ii) when X recombines with a DNA stretch

of an outgroup genome (a genome that diverged before the split of the X and Y lineages),

then this introduces further nucleotide polymorphisms into X, thereby increasing the apparent

X-Y distance.

Multilocus sequence typing (MLST) aims to extract sequences of housekeeping genes

from prokaryotic genomes, which can then be utilized to resolve evolutionary relationships

[10]. However, MLST genes may also experience frequent recombination, and phylogenetic

reconstruction without accounting for recombination can compromise the resulting trees [11].

In fact, the frequency with which recombination affects a gene can be of the same order of

magnitude as the corresponding mutation rate [5]. If two lineages recombine with each other, application of conventional phylogenetic algorithms without accounting for recombination will generally lead to an underestimation of the age of the common ancestors [12]. When there are more than two strains, recombination affects the reliability of inference of relative divergence times between strains and may hence compromise both tree topology and branch length estimates. There are several popular recombination-aware algorithms, including ClonalFrameML (and its predecessor ClonalFrame) [13,14], the Bacter package in BEAST2 (which implements the ClonalOrigin model) [15,16], and Gubbins [17]; there are also non-phylogenetic algorithms that detect recombination, such as BratNextGen and fastGEAR [18,19]. While these algorithms can identify genomic stretches with high numbers of substitutions due to recombination with distant strains and thus account for type (ii) recombination effects, many do not take type (i) recombination effects into account; Bacter can account for type (i) effects, but is not computationally efficient for long genome sequences. Some of these algorithms rely on the assumption of low recombination rates, such that a substantial part of a genome remains clonal and has not been affected by recombination. This is unrealistic at least for some bacteria: *e.g.*, *E. coli* strains whose DNA sequences have diverged by more than 1.3% share very few segments larger than a few kilo-basepairs that have not been affected by recombination in at least one of the two lineages [5].

In this paper, we present a novel model that does not assume low recombination rates. This model follows a coarse-graining approach, which considers the local density of substitutions on a sequence alignment instead of site-specific substitutions, and which is applicable to both nucleotide and amino acid sequences. The source code implementing this model is available at https://github.com/TinPang/coarse-graining-phylogenetics.

MATERIALS AND METHODS

The CGP model describing the evolution of single site polymorphism distributions of

genome pairs in a Fisher-Wright population

Our coarse-graining phylogenetic (CGP) model is based on a Fisher-Wright haploid

population with nonoverlapping generations, constant population size, and homologous

recombination [20,21]. In this framework, a node in one generation inherits the genome of a

random node in the previous generation, followed by mutation and homologous

recombination. The CGP model considers segments instead of nucleotide / amino-acid sites

as the basic unit of a genome, because the local density of single site polymorphism (SSP)

can be defined conveniently on segments; an SSP can be a single nucleotide polymorphism

(SNP) on a nucleotide sequence, or a single amino acid polymorphism (SAP) on an amino

acid sequence. A genome sequence is divided into L_{seg} consecutive and non-overlapping

segments, where every segment has length l_s (*i.e.*, consists of l_s sites). The rate of mutation is

μ per site per generation. The rate for a site to be covered by a foreign DNA stretch

attempting to recombine with the host genome is ρ per generation; the rate for a segment to

be covered by a recombination-attempting DNA stretch is also approximatly ρ, assuming that

the segment is much shorter than the DNA stretch. Here, $\rho=\rho_{ini}L$, where ρ_{ini} is the probability

for a recombination-attempting foreign DNA stretch to start at any given site, and L is the

average length of the foreign DNA stretch. When a recombination attempt happens on a

segment, it either succeeds, and the foreign DNA replaces the host DNA at the segment, or it

fails. The success rate of an attempt is approximately $\exp(-\delta/\delta_{TE})$, where δ is the divergence

between the incoming DNA and the host DNA, and δ_{TE} is the transfer efficiency, a constant

that governs the success rate [5]. The average site divergence in the population is denoted as

θ, with $\theta=2\mu N_e$ and population size N_e.

CGP's model [5,6] considers the evolution of a SSP distribution between a pair of

genomes, X and Y. As the alignment of genome X and Y is divided into L_{seg} consecutive and

non-overlapping segments with l_s sites, let $f(x|t)$ be the distribution of segment divergence,

where $x=0, 1, …, l_s$ represents the number of SSPs on a segment of the XY alignment, $t≥0$ is

the (continuous) XY coalescent time, and $f(x|t)$ is normalized to unity by summing over x. To

save computational resources, we assume an upper bound $l_s^{cutoff}≤l_s$ to x. At $t=0$, the most

recent common ancestor (MRCA) of XY splits into two lineages; initially, the two have

identical genomes, and thus $f(x|0)=\delta_{x,0}$ (where $\delta_{x,0}$ is the Kronecker delta, *i.e.*, $f(x|0)$ is non-

zero only at $x=0$). At $t>0$, mutations and recombinations occur, and the evolution of $f(x|t)$ is

described by the following equation:

$$\frac{df(x|t)}{dt} = 2l_s\mu \sum_{y=0}^{l_s^{cutoff}} (M(x|y) - I(x|y))f(y|t) + 2\rho \sum_{y=0}^{l_s^{cutoff}} (P(x|y,\theta,\delta_{TE},l_s) - I(x|y))f(y|t) \tag{1}$$

The first term of Eq (1) accounts for mutations on a segment—M($x|y$) models a

mutation event, where a segment in the pair XY with y SSPs increases to $x=y+1$ SSPs during

a mutation (*i.e.,* M($x|y$)=0 for $x≠y+1$); I($x|y$) is the identity matrix. For simplicity, we ignore

back mutations.

The second term accounts for recombination—P($x|y,\theta,\delta_{TE},l_s$) models a recombination

event (see Eq. (S4) of *Dixit et al.* [5] or Eq. (3) of *Dixit et al.* [6] for a detailed derivation).

Since a segment can recombine with its counterpart on another genome, it assumes that each

segment of a genome, along with its counterparts in different genomes of the population,

have their own phylogeny, which is detached from the genomes' phylogeny, and the segment

population structure is approximated by the coalescent model. For an attempted

recombination between Y and an external donor D, we can use the coalescent model to

calculate the probability distribution for the segment divergence δ between D and X, and then

obtain x from $x=l_s\delta$. As mutation and recombination can equally occur on either X or Y,

there is a factor 2 attached to both terms. See Supplementary Text for the exact form of

$P(x|y,\theta,\delta_{TE},l_s)$. We solved Eq. (1) with boundary condition $f(x|0)=\delta_{x,0}$ to obtain the theoretical

SSP distribution $f(x|t)$ at different coalescent times t.

We fit the the theoretical distribution obtained with the CGP model to an empirical

SSP distribution to infer the coalescent time of the pair of genomes. Let us consider an

alignment for a genome pair XY that is divided into L_{seg} segments, with empirical SSP

distribution $g_{XY}(x)$ following the normalization condition:

$$\sum_{x=0}^{l_s{}^{cutoff}} g_{XY}(x) = L_{seg}$$

8   Let us denote the theoretical distribution as $f_{\mu,\rho,\theta,\delta TE}(x|t)$, which is normalized to unity.

9   The probability to observe the empirical distribution $g_{XY}(x)$ given the theoretical distribution

10    $f_{\mu,\rho,\theta,\delta TE}(x|t)$ is

(2)

$$\prod_x [f_{\mu,\rho,\theta,\delta_{TE}}(x|t)]^{g_{XY}(x)}$$

If we take the logarithm of this expression, it becomes the (negative) cross entropy between

$g(x)$ and $f_{\mu,\rho,\theta,\delta TE}(x|t)$ [22,23]. The higher their similarity, the higher is this negative cross

entropy; it attains its maximum when $f_{\mu,\rho,\theta,\delta TE}(x|t)$ is equal to $g(x)$.

Suppose that we have n genomes (X_i, $i=1,...,n$), where their phylogeny is described by

an ultrametric tree T; the $n(n-1)/2$ pairwise SSP distributions have evolved according to the

model with parameters $\mu,\ \rho,\ \theta,\ \delta_{TE}$. Let $t_T(X_a,X_b)$ be the coalescent time of X_a and X_b in the

tree T. We use a score function, $S(X_1,X_2,\ldots,X_n|\mu,\ \rho,\ \theta,\ \delta_{TE},T)$, which is defined as the

logarithm of the probability to observe the $n(n-1)/2$ empirical SSP distributions given the

model and the tree, to quantify the model fit to the empirical SSP distributions. This score is

the summation of the $n(n-1)/2$ negative mutual entropy terms:

$$S(X_1, \ldots X_n | \mu, \rho, \theta, \delta_{TE}, T) = \sum_{all \; (X_a, X_b) \; pairs} log\{\prod_x [f_{\mu, \rho, \theta, \delta_{TE}}(x | t_T(X_a, X_b))]^{g_{X_a X_b}(x)}\} \tag{3}$$

Since the $n(n$-1$)/2$ SSP distributions are not completely independent of each other, Eq. (3) is

not exactly a probability and so we call it a score. We developed an algorithm that samples

the tree+model space and searches for the configuration with the maximum score using

Monte Carlo simulation with annealing and Metropolis acceptance (See Supplementary Text

for details).

RESULTS

A coarse-graining approach to phylogenetic reconstruction

The coarse-graining phylogenetics (CGP) model is based on a mathematical model [5,6] that

quantitatively describes the evolution of genomic sequence divergence; this model is

applicable to both nucleotide and amino acid sequences, and does not assume low

recombination rate. Recombination can introduce DNA stretches characterised by a high

density of substitutions, and the CGP model considers substitution densities defined on the

genomic segments. A nucleotide genome sequence alignment (or a corresponding

concatenation of amino acid sequence alignments) is divided into a chain of consecutive,

non-overlapping segments, each with l_s sites; for a pair of genomes, the single site

polymorphisms (SSPs) on each segment are counted, resulting in an SSP distribution. CGP

takes the SSP distribution of every pair of considered genomes as input. The coalescent time

of two genomes can be inferred by fitting the CGP model to the empirical SSP distribution.

The ultrametric tree describing the vertical component of inheritance among n genomes can

be inferred from the coalescent times resulting from the fits to the $n(n$-1$)/2$ empirical SSP

distributions, implemented by the score function of Eq. (3). We developed the CGP

algorithm, which employs Monte Carlo simulation to sample the model+tree space,

identifying the tree and parameters that result in the highest score.

Testing the CGP algorithm on simulated genomes

We performed Fisher-Wright simulations with recombination to generate genome sequences,

allowing us to test different phylogenetic reconstruction algorithms. In the simulation, each

recombination-attempting DNA stretch starts at a random site of a genome, with equal chance

to be either a micro (geometric distribution, mean 100bp) or a macro stretch (geometric

distribution, mean 1kb). We used three sets of parameters that correspond to prokaryotic

populations with r/m=2, 40, 80 (r/m is the ratio between substitutions contributed by

mutations and by recombinations; these three settings are denoted as low, intermediate, and

high recombination level, respectively), and prepared the test groups, each with 4-10 genome

sequences. For comparison, r/m values observed in nature range from 0.02 to 63.6 [11].

The MRCA of a group of random genomes in a simulated population has an average

age close to the age of the population root node t_{root}. We would like to mimic the condition

where a single lineage diverges from the rest of the population and forms its own

subpopulation, so that the genomes in its subpopulation continue exchanging DNA among

themselves and with the rest outside. Hence, when picking genomes in the population to form

test groups, we constrained the age of the MRCA of the genomes in a test group, $t_{test-group-root}$,

to be $t_{test-group-root} \ll t_{root}$ (see Supplementary Text for the details and Supplementary File S3 for

the genome sequences in each test-group).

We applied CGP, as well as the previously published methods RaxML [24],

ClonalFrameML [13], and Gubbins [17] to the sequences of each test group. The RAxML

and Gubbins trees are midpoint-rooted. ClonalFrameML requires an initial tree as input and

we used the RAxML tree. CGP uses segment size $l_s=150$ and $l_s^{cutoff}=100$. We compared each

reconstructed tree with the true tree, measuring their unrooted symmetric distance (SD) [25], as well as their rooted and unrooted branch score distance (BSD) [26] to quantify the accuracy of the reconstructed phylogeny (see Supplementary File S1 for the these values); the lower the unrooted SD / unrooted BSD / rooted BSD, the more accurate is the topology / branch lengths / root positioning, respectively. We normalized the branch lengths of each tree by its total branch length when calculating BSD.

CGP can predict the topology of a phylogeny of vertical inheritance as accurately as the other algorithms. Figure 1 shows the histograms of unrooted SD; ClonalFrameML is excluded as it uses the topology of RAxML trees. The distributions of SD of CGP are not significantly different from the distributions of RAxML and Gubbins. Two-sided Wilcoxon signed-rank tests (WSRT) at low, intermediate, and high recombination levels resulted in p=0.25, 0.69, 0.54 between CGP and RAxML, and p=0.25, 0.38, 0.92 between CGP and Gubbins.

Branch length predictions are more accurate with CGP than with alternative programs at higher levels of recombination. Figure 2 plots the distributions of the unrooted BSD of different algorithms and their z-scores; the unrooted BSD of trees reconstructed by different algorithms on the same test group sequences are pooled together to calculate their z-scores to help data visualization. The distribution of the unrooted BSD of CGP is significantly lower than RAxML and Gubbins ($p<10^{-10}$ at low, intermediate, and high recombination level compared to both RAxML and Gubbins). The unrooted BSD of CGP is significantly lower than ClonalFrameML except at low recombination levels (p=0.76, 2.2×10^{-7}, 10^{-7} at low, intermediate, and high recombination levels).

CGP can perform accurate root positioning. Figure 3 plots the distribution of the rooted BSD and their z-scores; the rooted BSD of trees reconstructed by different algorithms on the same test group sequences are pooled together to calculate their z-scores. The

1   distribution of the rooted BSD of CGP is significantly lower than the other algorithms

2   ($p<2\times10^{-17}$ at all recombination levels for CGP compared with the other three algorithms).

3   Testing the CGP algorithm on real *E. coli* genomes

We tested CGP, RAxML, ClonalFrameML, and Gubbins using *E. coli* and *Shigella* genome

sequences (see Supplementary Table S1 for their names); we refer to them as *E. coli*, as these

two species have intertwined phylogenies. We prepared test groups, each with 10 random

strains, where each strain is represented by a nucleotide and an amino acid sequence made

from its concatenated core genes (see Supplementary File S2 for the strains in each test

group, and also the 1,636 orthologous gene families of core genes; see Supplementary File S3

for their sequences). We applied CGP, RAxML, ClonalFrameML (with the topology from

RAxML trees), and Gubbins on the nucleotide sequences, and CGP and RAxML on amino

acid sequences; the RAxML and Gubbins trees are midpoint-rooted. CGP uses segment

length $l_s=150$ and $l_s^{cutoff}=100$ for nucleotide sequences, and $l_s=50$, $l_s^{cutoff}=50$ for amino acid

sequences.

To assess the accuracy of the phylogenetic trees reconstructed by the different

algorithms, we compared the reconstructed trees with the phylogenetic signal inferred from

the distribution of orthologous gene families in different genomes. We applied the GLOOME

algorithm [27], which considers the interior nodes of the tree as ancestral strains and

reconstructs their gene distribution; it takes a tree and the presence-and-absence of genes

across the extant strains as input, and performs a reconstruction of presence-and-absence of

genes in the ancestral strains based on the GLOOME posterior likelihood (GPL). We used

GPL as a score to quantify the accuracy of the tree fed into GLOOME; the more consistent

the phylogenetic signal from the gene distributions with a given tree, the higher the GPL (see

Supplementary File S2 for the GPL values of the reconstructed trees).

Figure 4 plots the distribution of the GPLs and the corresponding z-scores; the GPLs

of trees of the same test groups reconstructed by different methods are pooled together to

calculate the z-scores. Trees reconstructed from amino acid sequences have a higher GPL

than trees calculated from nucleotide sequences; moreover, CGP trees based on amino acids

are more accurate than tress calculated using RAxML ($p<4\times10^{-14}$ when comparing CGP on

amino acid sequences with any other algorithm). Considering only trees reconstructed from

nucleotide sequences, the CGP trees generally have higher GPL than RAxML,

ClonalFrameML, and Gubbins trees ($p=5.2\times10^{-4}$, 0.049, 1.4×10^{-15}, respectively).

DISCUSSION

We introduced a coarse-graining phylogenetic (CGP) model, which infers a phylogenetic tree

from the estimated pairwise coalescent times of genomes. We conducted extensive analyses

to compare the accuracy of the CGP algorithm with other state-of-the-art algorithms to

demonstrate its ability to reliably predict the topology, branch lengths, and root positioning of

phylogenetic trees. The CGP model does not rely on the assumption of low recombination

rates, which allows it to predict branch lengths accurately even if the vast majority of the

considered genome segments have experienced recombination on the timescale covered by

the phylogeny.

Analyses performed on the real *E. coli* genome sequences showed that trees

reconstructed from core genome amino acid sequences are more accurate, *i.e.*, more

consistent with the signal inferred from the distribution of genes in the extant genomes, than

trees calculated from nucleotide sequences. Amino acid sequences of core genes tend to

evolve more slowly than the corresponding DNA sequences, as these genes show dN/dS

values <1 [28], and accordingly, the divergence of a pair of amino acid sequences is lower

than that of their nucleotide counterparts (see Supplementary File S3 for nucleotide and

amino acid sequence divergence between *E. coli* genome pairs). Thus, amino acid sequences

may be more "clonal" than nucleotide sequences and thus may provide more accurate

phylogenetic signals.

The computational demand of the CGP algorithm is independent of sequence length,

as CGP considers only SSP distributions that are represented by a vector of $1+l_s^{cutoff}$ elements

in the computer code. Calculation of the CGP score (Eq. (3)) involves multiplication of

$(1+l_s^{cutoff}) \times (1+l_s^{cutoff})$ matrices; thus, the computational time scales as $O((l_s^{cutoff})^k)$, where $k \leq 3$

depends on the algorithm that carries out the matrix operations. When reconstructing a tree of

n genomes, the score calculation involves the summation over $n(n-1)/2$ pairs, making it scale

as $O(n^2)$. The segment size l_s affects the efficiency and accuracy of the algorithm. While a

smaller l_s leads to lower accuracy, increasing l_s leads to higher computational demand; a large

l_s combined with a small l_s^{cutoff} can also reduce the accuracy. Hence, one needs to set l_s and

l_s^{cutoff} carefully to balance the need for speed and accuracy.

The current algorithm that implements the CGP model is very simple; it should be

considered a proof of concept. While it makes use of Monte Carlo simulation to sample the

tree+parameter space, a hill-climbing method may be more efficient. Other possible

improvements involve better local search moves in the ultrametric tree space; one might even

drop the stringent ultrametricity constraint, and replace it with a more flexible matrix-tree

mapping method that allows a more efficient search in the tree space. The mutation matrix in

the current model can be improved to include back mutations and a more complex mutation

model. We leave these possible improvements to future studies.

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SUPPORTING INFORMATION

1. Source code of the CGP algorithm: https://github.com/TinPang/coarse-graining-
phylogenetics

2. Supplementary Text, Figures and Tables.

3. Supplementary File S1: Analyses of the simulated genomes: the symmetric distance
(SD) and branch score distance (BSD) between the reconstructed trees and the true
trees.

4. Supplementary File S2: Analyses of the real genomes: b-number of the *E. coli* core
genes used to make the 'super-gene' sequences, strains in each test-group, and also
the GLOOME posterior likelihood (GPL) of the reconstructed trees.

5. Supplementary File S3: Sequences and their phylogenetic trees: sequences of the
simulated genomes in different test-groups, their true trees and also the phylogenetic
trees reconstructed by different algorithms; sequences of the *E. coli* genomes and their
trees reconstructed by different algorithms; genes to orthologous gene families map
provided by ProteinORTHO.

FIGURES

2 **Figure 1.** Histograms showing the distributions of the unrooted symmetric distance (SD)

3 between true trees and trees reconstructed by CGP, RaxML, and Gubbins, from genome

4 sequences derived from Fisher-Wright simulations with low, intermediate, and high

5 recombination levels.

2 **Figure 2.** Boxplots showing the distributions of the unrooted branch score distance (BSD)

3 and the distributions of the z-score of unrooted BSD between the true trees and trees

4 reconstructed by CGP, RaxML, and Gubbins, from genome sequences from Fisher-Wright

5 simulations with low, intermediate, and high recombination levels.

2 **Figure 3.** Boxplots showing the distributions of the rooted branch score distance (BSD) and

3 the distributions of the z-score of rooted BSD between the true trees and trees reconstructed

4 by CGP, RaxML, and Gubbins, from genome sequences from Fisher-Wright simulations with

5 low, intermediate, and high recombination levels.

2 **Figure 4.** Boxplots showing the distributions of the GLOOME posterior likelihood (GPL)

3 and the distributions of the z-scores of GPL. The trees were reconstructed from observed *E.*

4 *coli* genome sequences, applying CGP, RAxML, ClonalFrameML, and Gubbins to nucleotide

5 sequences, and CGP and RAxML to amino acid sequences.