

Activations of Deep Convolutional Neural Network are Aligned with Gamma Band Activity of Human Visual Cortex

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Previous work demonstrated a direct correspondence between the hierarchy of the human visual areas and layers of deep convolutional neural networks (DCNN) trained on visual object recognition. We used DCNNs to investigate which frequency bands carry feature transformations of increasing complexity along the ventral visual pathway. By capitalizing on intracranial depth recordings from 100 patients and 11293 electrodes we assessed the alignment between the DCNN and signals at different frequency bands in different time windows. We found that activity in low and high gamma bands was aligned with the increasing complexity of visual feature representations in the DCNN. These findings show that activity in the gamma band is not only a correlate of object recognition, but carries increasingly complex features along the ventral visual pathway. These results demonstrate the potential that modern artificial intelligence algorithms have in advancing our understanding of the brain.

1 Significance Statement

2 Recent advances in the field of artificial intelligence have revealed
3 principles about neural processing, in particular about vision.
4 Previous works have demonstrated a direct correspondence
5 between the hierarchy of human visual areas and layers of deep
6 convolutional neural networks (DCNNs), suggesting that DCNN
7 is a good model of visual object recognition in primate brain.
8 Studying intracranial depth recordings allowed us to extend pre-
9 vious works by assessing when and at which frequency bands the
10 activity of the visual system corresponds to the DCNN. Our key
11 finding is that signals in gamma frequencies along the ventral
12 visual pathway are aligned with the layers of DCNN. Gamma
13 frequencies play a major role in transforming visual input to
14 coherent object representations.

Introduction

1 Biological visual object recognition is mediated by a hierarchy
2 of increasingly complex feature representations along the ventral
3 visual stream (DiCarlo et al., 2012). Intriguingly, these transfor-
4 mations are matched by the hierarchy of transformations learned
5 by deep convolutional neural networks (DCNN) trained on natu-
6 ral images (Güçlü and van Gerven, 2015). It has been shown that
7 DCNN provides the best model out of a wide range of neurosci-
8 entific and computer vision models for the neural representation
9 of visual images in high-level visual cortex of monkeys (Yamins et
10 al., 2014) and humans (Khaligh-Razavi and Kriegeskorte, 2014).
11 Other studies have demonstrated with fMRI a direct correspon-
12 dence between the hierarchy of the human visual areas and layers
13 of the DCNN (Güçlü and van Gerven, 2015; Eickenberg et al.,
14 2016; Seibert et al., 2016; Cichy et al., 2016b). In sum, the
15 increasing feature complexity of the DCNN corresponds to the
16

1 increasing feature complexity occurring in visual object recog-
2 nition in the primate brain (Kriegeskorte, 2015; Yamins and
3 DiCarlo, 2016).

4 However, fMRI based studies only allow one to localize object
5 recognition in space, but biological visual object recognition is
6 also specific in time and frequency. With time-resolved magne-
7 toencephalography (MEG) recordings it has been demonstrated
8 that the correspondence between the DCNN and neural signals
9 peaks in the first 200 ms (Cichy et al., 2016b; Seeliger et al.,
10 2017). Here we test the remaining dimension: that biological
11 visual object recognition is also specific to certain frequencies.
12 In particular, there is a long-standing hypothesis that especially
13 gamma band (30 – 150 Hz) signals are crucial for object recog-
14 nition (Singer and Gray, 1995; Singer, 1999; Fisch et al., 2009;
15 Tallon-Baudry et al., 1997; Tallon-Baudry and Bertrand, 1999;
16 Lachaux et al., 1999; Wyart and Tallon-Baudry, 2008; Lachaux
17 et al., 2005; Vidal et al., 2006; Herrmann et al., 2004; Hipp et
18 al., 2011; Gaillard et al., 2009; Srinivasan et al., 1999; Levy et
19 al., 2015). Hence, if DCNN capture biological object recognition
20 there should be a correspondence between the DCNN layers and
21 gamma signals along the ventral visual pathway.

22 To empirically evaluate the specific role of gamma frequency
23 in visual object recognition we assessed the alignment between
24 the responses of layers of the DCNN and the neural signals in five
25 distinct frequency bands and three time windows along the areas
26 constituting the ventral visual pathway. Based on the previous
27 findings we expected that: 1) mainly gamma frequencies should
28 be aligned to the DCNN; 2) the correspondence between the
29 DCNN and gamma should be confined to early time windows; 3)
30 the correspondence between gamma and the DCNN layers should
31 be restricted to visual areas. In order to test these predictions
32 we capitalized on direct intracranial depth recordings from 100
33 patients with epilepsy and a total of 11293 electrodes implanted
34 throughout the cerebral cortex.

35 Studying the alignment between the DCNN and gamma fre-
36 quencies would also help to elucidate the role of gamma band
37 signals in object recognition. The classic view is that gamma
38 band activity signals the emergence of coherent object represen-
39 tations (Singer and Gray, 1995; Singer, 1999; Fisch et al., 2009).
40 However, it is possible that gamma frequencies carry feature
41 transformations of increasing complexity instead of reflecting
42 solely the final product of object recognition. Suggestive evidence
43 for this view is provided by studies demonstrating that feedfor-
44 ward activity from lower to higher visual areas is carried by the
45 gamma frequencies along the ventral visual pathway (Van Kerkorle
46 et al., 2014; Bastos et al., 2015; Michalareas et al., 2016). The
47 existence of quantifiable increase of feature complexity along the
48 layers of DCNN allows one to use the DCNN as a computational
49 model to assess whether signals in the gamma frequency indeed
50 reflect such gradual transformations.

51 We observed that activity in the gamma range along the ven-
52 tral pathway is statistically significantly aligned with the activity
53 along the layers of DCNN: gamma (31 – 150 Hz) activity in the
54 early visual areas correlates with the activity of early layers of
55 DCNN, while the gamma activity of higher visual areas is bet-
56 ter captured by the higher layers of the DCNN. We also found
57 that neural activity in the theta range (5 – 8 Hz) throughout the
58 visual hierarchy correlated with higher layers of DCNN.

Materials and Methods

Our methodology involves four major steps described in the fol-
lowing subsections. In “Patients and Recordings” we describe
the visual recognition task and data collection. In “Processing
of Neural Data” we describe the artifact rejection, extraction of
spectral features and the electrode selection processes. “Process-
ing of DCNN Data” shows how we extract activations of artificial
neurons of DCNN that occur in responses to the same images as
were shown to human subjects. In the final step we map neural
activity to the layers of DCNN using representational similarity
analysis. See Figure 1 for the illustration of the analysis workflow.

Patients and Recordings

100 patients of either gender with drug-resistant partial epilepsy
and candidates for surgery were considered in this study and
recruited from Neurological Hospitals in Grenoble and Lyon
(France). All patients were stereotactically implanted with multi-
lead EEG depth electrodes (DIXI Medical, Besançon, France).
All participants provided written informed consent, and the
experimental procedures were approved by local ethical commit-
tee of Grenoble hospital (CPP Sud-Est V 09-CHU-12). Recording
sites were selected solely according to clinical indications, with
no reference to the current experiment. All patients had normal
or corrected to normal vision.

Electrode Implantation

Eleven to 15 semi-rigid electrodes were implanted per patient.
Each electrode had a diameter of 0.8 mm and was comprised
of 10 or 15 contacts of 2 mm length, depending on the target
region, 1.5 mm apart. The coordinates of each electrode con-
tact with their stereotactic scheme were used to anatomically
localize the contacts using the proportional atlas of Talairach
and Tournoux (Talairach and Tournoux, 1993), after a linear
scale adjustment to correct size differences between the patients
brain and the Talairach model. These locations were further
confirmed by overlaying a post-implantation CT scan (show-
ing contact sites) with a pre-implantation structural MRI with
VOXIM[®] (IVS Solutions, Chemnitz, Germany), allowing direct
visualization of contact sites relative to brain anatomy.

All patients voluntarily participated in a series of short exper-
iments to identify local functional responses at the recorded sites
(Vidal et al., 2010). The results presented here were obtained
from a test exploring visual recognition. All data were recorded
using approximately 120 implanted depth electrode contacts per
patient with a sampling rates of 512 Hz, 1024 Hz or 2048 Hz. For
the current analysis all recordings were downsampled to 512 Hz.
Data were obtained in a total of 11293 recording sites.

Stimuli and Task

The visual recognition task lasted for about 15 minutes. Patients
were instructed to press a button each time a picture of a fruit
appeared on screen (visual oddball paradigm). Non-target stim-
uli consisted of pictures of objects of eight possible categories:
houses, faces, animals, scenes, tools, pseudo words, consonant
strings, and scrambled images. The target stimuli and last three
categories were not included in this analysis. All the included

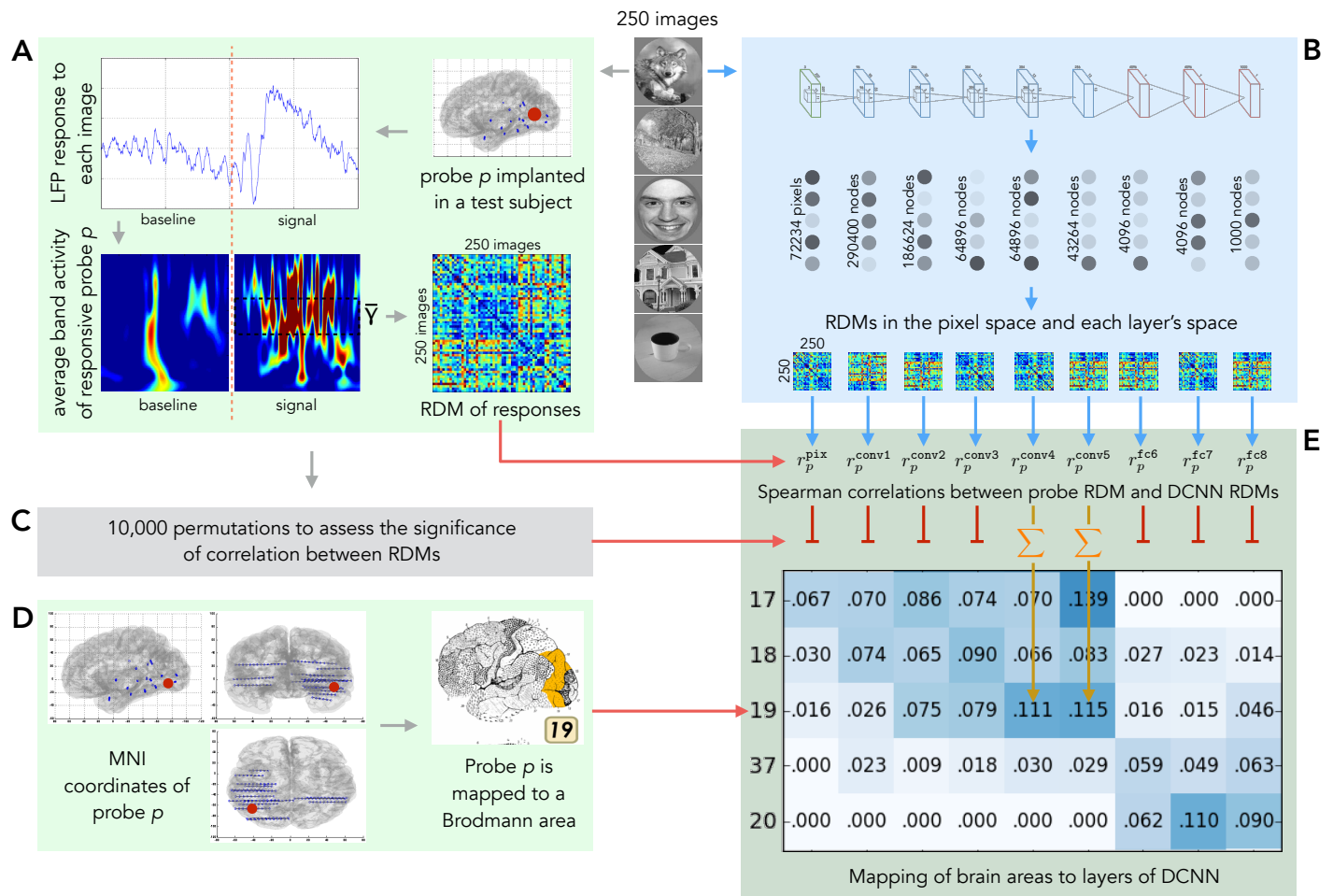


Figure 1 Overview of the analysis pipeline. 250 natural images are presented to human subjects (panel A) and to an artificial vision system (panel B). The activities elicited in these two systems are compared in order to map regions of human visual cortex to layers of deep convolutional neural networks (DCNNs). **A:** LFP response of each of 11293 electrodes to each of the images is converted into the frequency domain. Activity evoked by each image is compared to the activity evoked by every other image and results of this comparison are presented as a representational dissimilarity matrix (RDM). **B:** Each of the images is shown to a pre-trained DCNN and activations of each of the layers are extracted. Each layer's activations form a representation space, in which stimuli (images) can be compared to each other. Results of this comparison are summarized as a RDM for each DCNN layer. **C:** Subject's intracranial responses to stimuli are randomly reshuffled and the analysis depicted in panel A is repeated 10000 times to obtain 10000 random RDMs for each electrode. **D:** Each electrode's MNI coordinates are used to map the electrode to a Brodmann area. The figure also gives an example of electrode implantation locations in one of the subjects (blue circles are the electrodes). **E:** Spearman's rank correlation is computed between the true (non-permuted) RDM of neural responses and RDMs of each layer of DCNN. Also 10000 scores are computed with the random RDM for each electrode-layer pair to assess the significance of the true correlation score. If the score obtained with the true RDM is significant (the value of $p < 0.001$ is estimated by selecting a threshold such that none of the probes would pass it on the permuted data), then the score is added to the mapping matrix. The procedure is repeated for each electrode and the correlation scores are summed and normalized by the number of electrodes per Brodmann area. The resulting mapping matrix shows the alignment between the consecutive areas of the ventral stream and layers of DCNN.

1 stimuli had the same average luminance. All categories were presented within an oval aperture (illustrated on Figure 1). Stimuli
 2 were presented for a duration of 200 ms every 1000 – 1200 ms in
 3 series of 5 pictures interleaved by 3-s pause periods during which
 4 patients could freely blink. Patients reported the detection of a
 5 target through a right-hand button press and were given feed-
 6 back of their performance after each report. A 2-s delay was
 7 placed after each button press before presenting the follow-up
 8 stimulus in order to avoid mixing signals related to motor action
 9

with signals from stimulus presentation. Altogether, we measured
 responses to 250 natural images. Each image was presented only
 once.

Processing of Neural Data

The final dataset consists of 2823250 local field potential (LFP)
 recordings – 11293 electrode responses to 250 stimuli.

To remove the artifacts the signals were linearly detrended and the recordings that contained values $\geq 10\sigma_{images}$, where σ_{images} is the standard deviation of responses (in the time window from -500 ms to 1000 ms) of that particular probe over all stimuli, were excluded from data. All electrodes were re-referenced to a bipolar reference. The signal was segmented in the range from -500 ms to 1000 ms, where 0 marks the moment when the stimulus was shown. The -500 to -100 ms time window served as the baseline. There were three time windows in which the responses were measured: $50 - 250$ ms, $150 - 350$ ms and $250 - 450$ ms.

We analyzed five distinct frequency bands: θ ($5 - 8$ Hz), α ($9 - 14$ Hz), β ($15 - 30$ Hz), γ ($31 - 70$ Hz) and Γ ($71 - 150$ Hz). To quantify signal power modulations across time and frequency we used standard time-frequency (TF) wavelet decomposition (Daubechies, 1990). The signal $s(t)$ is convoluted with a complex Morlet wavelet $w(t, f_0)$, which has Gaussian shape in time (σ_t) and frequency (σ_f) around a central frequency f_0 and defined by $\sigma_f = 1/2\pi\sigma_t$ and a normalization factor. In order to achieve good time and frequency resolution over all frequencies we slowly increased the number of wavelet cycles with frequency ($\frac{f_0}{\sigma_f}$ was set to 6 for high and low gamma, 5 for beta, 4 for alpha and 3 for theta). This method allows obtaining better frequency resolution than by applying a constant cycle length (Delorme and Makeig, 2004). The square norm of the convolution results in a time-varying representation of spectral power, given by: $P(t, f_0) = |w(t, f_0)s(t)|^2$.

Further analysis was done on the electrodes that were responsive to the visual task. We assessed neural responsiveness of an electrode separately for each region of interest – for each frequency band and time window we compared the average post-stimulus band power to the average baseline power with a Wilcoxon signed-rank test for matched-pairs. All p-values from this test were corrected for multiple comparisons across all electrodes with a false discovery rate (FDR) procedure (Genovese et al., 2002). In the current study we deliberately kept only positively responsive electrodes, leaving the electrodes where the post-stimulus band power was significantly weaker than the average baseline power for future work. Table 1 contains the numbers of electrodes that were used in the final analysis in each of 15 regions of interest across the time and frequency domains.

	θ	α	β	γ	Γ
50 – 250 ms	1299	709	269	348	504
150 – 350 ms	1689	783	260	515	745
250 – 450 ms	1687	802	304	555	775

Table 1 Number of positively responsive electrodes in each of the 15 regions of interest in a time-resolved spectrogram.

Each electrode’s MNI coordinates were mapped to a corresponding Brodmann brain area (Brodmann, 1909) using Brodmann area atlas contained in MRICron (Rorden, 2007) software.

To summarize, once the neural signal processing pipeline is complete, each electrode’s response to each of the stimuli is represented by one number – the average band power in a given time window normalized by the baseline. The process is repeated independently for each time-frequency region of interest.

Processing of DCNN Data

We feed the same images that were shown to the test subjects to a deep convolutional neural network (DCNN) and obtain activations of artificial neurons (nodes) of that network. We use Caffe (Jia et al., 2014) implementation of AlexNet (Krizhevsky et al., 2012) architecture (see Figure 7) trained on ImageNet (Russakovsky et al., 2015) dataset to categorize images into 1000 classes. Although the image categories used in our experiment are not exactly the same as the ones in the ImageNet dataset, they are a close match and DCNN is successful in labelling them.

The architecture of the AlexNet artificial network can be seen on Figure 7. It consists of 9 layers. The first is the input layer, where one neuron corresponds to one pixel of an image and activation of that neuron on a scale from 0 to 1 reflects the color of that pixel: if a pixel is black, the corresponding node in the network is not activated at all (value is 0), while a white pixel causes the node to be maximally activated (value 1). After the input layer the network has 5 convolutional layers referred to as conv1-5. A convolutional layer is a collection of filters that are applied to an image. Each filter is a small image that represents a particular visual pattern. A filter is applied to every possible position on an input image and if the underlying patch of an image coincides with the pattern that the filter represents, the filter becomes activated and translates this activation to the artificial neuron in the next layer. That way, nodes of conv1 tell us where on the input image each particular visual pattern occurred. Hierarchical structure of convolutional layers gives rise to the phenomenon we are investigating in this work – increase of complexity of visual representations in each subsequent layer of the visual hierarchy: in both the biological and artificial systems. Convolutional layers are followed by 3 fully-connected layers (fc6-8). Each node in a fully-connected layer is, as the name suggests, connected to every node of the previous layer allowing the network to decide which of those connections are to be preserved and which are to be ignored.

For each of the images we store the activations of all nodes of DCNN. As the network has 9 layers we obtain 9 representations of each image: the image itself (referred to as layer 0) in the pixel space and the activation values of each of the layers of DCNN. See pane B of figure 1 for the cardinalities of those feature spaces.

Mapping Neural Activity to Layers of DCNN

Once we extracted the features from both neural and DCNN responses our next goal was to compare the two and use a similarity score to map the brain area where a probe was located to a layer of DCNN. By doing that for every probe in the dataset we obtained cross-subject alignment between visual areas of human brain and layers of DCNN. There are multiple deep neural network architectures trained to classify natural images. Our choice of AlexNet does not imply that this particular architecture corresponds best to the hierarchy of visual layers of human brain. It does, however, provide a comparison for hierarchical structure of human visual system and was selected among other architectures due to its relatively small size and thus easier interpretability.

Recent studies comparing the responses of visual cortex with the activity of DCNN have used two types of mapping methods. The first type is based on linear regression models that predict

1 neural responses from DCNN activations (Güçlü and van Gerven,
2 2015). The second is based on representational similarity analy-
3 sis (RSA) (Kriegeskorte et al., 2008). We used RSA to compare
4 distances between stimuli in the neural response space and in the
5 DCNN activation space (Cichy et al., 2016a).

6 Representational Dissimilarity Matrices

7 We built a representation dissimilarity matrix (RDM) of size
8 *number of stimuli* × *number of stimuli* (in our case 250 × 250)
9 for each of the probes and each of the layers of DCNN. Given
10 a matrix $RDM^{\text{feature space}}$ a value $RDM_{ij}^{\text{feature space}}$ in the *i*th
11 row and *j*th column of the matrix shows the Euclidean distance
12 between the vectors \mathbf{v}_i and \mathbf{v}_j that represent images *i* and *j*
13 respectively in that particular feature space. Note that the pre-
14 processed neural response to an image in a given frequency band
15 and time window is a scalar, and hence correlation distance is not
16 applicable. Also, given that DCNNs are not invariant to the scal-
17 ing of the activations or weights in any of its layers, we preferred
18 to use closeness in Euclidean distance as a more strict measure
19 of similarity. In our case there are 10 different feature spaces
20 in which an image can be represented: the original pixel space,
21 8 feature spaces for each of the layers of the DCNN and one
22 space where an image is represented by the preprocessed neural
23 response of probe *p*. For example, to analyze region of interest
24 of high gamma in 50 – 250 ms time window we computed 504
25 RDM matrices on the neural responses – one for each positively
26 responsive electrode in that region of interest (see Table 1), and
27 9 RDM matrices on the activations of the layers of DCNN. A
28 pair frequency band and a time window, such as “high gamma
29 in 50-250 ms window” is referred to as *region of interest* in this
30 work.

31 Representational Similarity Analysis

32 The second step was to compare the $RDM^{\text{probe } p}$ of each probe
33 *p* to RDMs of layers of DCNN. We used Spearman’s rank
34 correlation as measure of similarity between the matrices:

$$\rho_{\text{layer } l}^{\text{probe } p} = \text{Spearman}(RDM^{\text{probe } p}, RDM^{\text{layer } l}). \quad (1)$$

35 As a result of comparing $RDM^{\text{probe } p}$ with every $RDM^{\text{layer } l}$
36 we obtain a vector with 9 scores: $(\rho_{\text{pixels}}, \rho_{\text{conv1}}, \dots, \rho_{\text{fc8}})$ that
37 serves as a distributed mapping of probe *p* to the layers of
38 DCNN (see pane E of Figure 1). The procedure is repeated
39 independently for each probe in each region of interest.

40 Statistical significance and controls

41 To assess the statistical significance of the correlations between
42 the RDM matrices we run a permutation test. In particular, we
43 reshuffled the vector of brain responses to images 10000 times,
44 each time obtaining a dataset where the causal relation between
45 the stimulus and the response is destroyed. On each of those
46 datasets we ran the analysis and obtained Spearman’s rank cor-
47 relation scores. To determine score’s significance we compared
48 the score obtained on the original (unshuffled) data with the dis-
49 tribution of scores obtained with the surrogate data. If the score
50 obtained on the original data was bigger than value obtained on
51 the surrogate sets with $p < 0.001$ significance we considered the

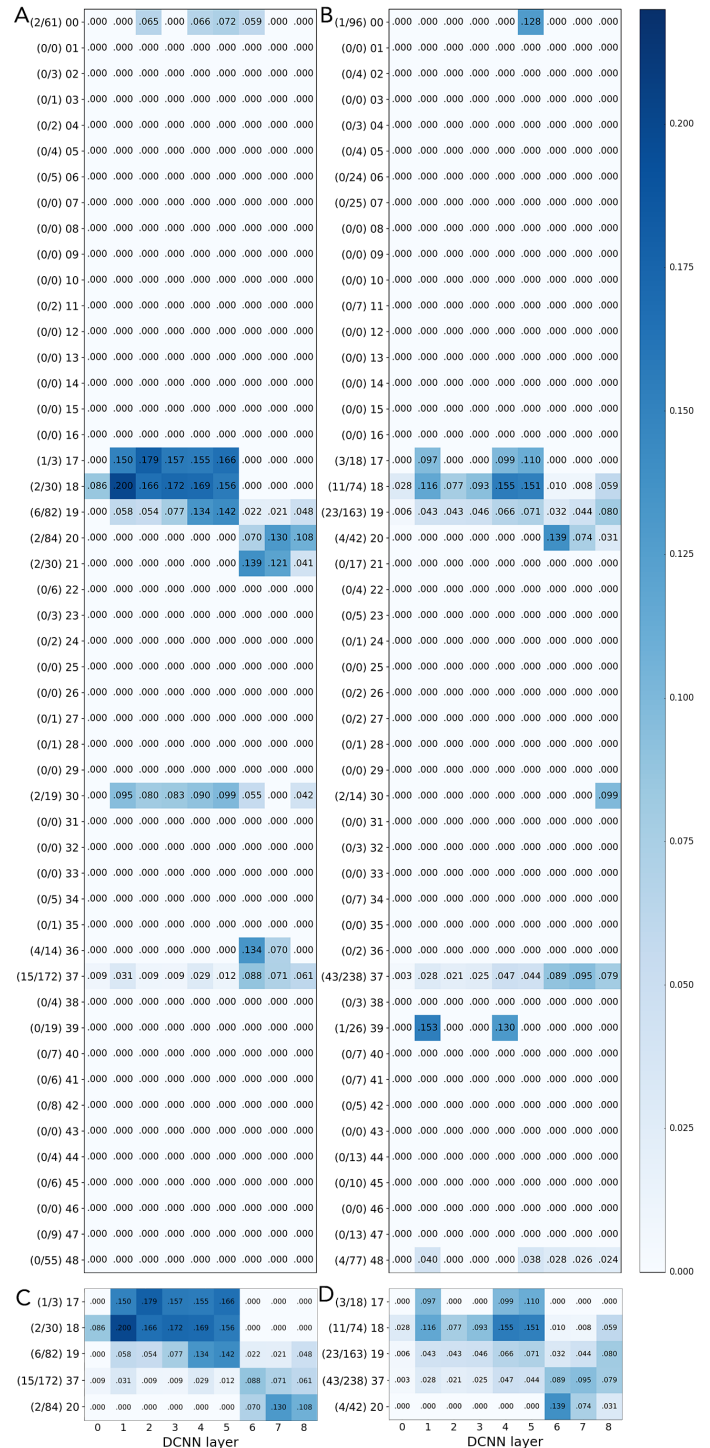


Figure 2 Mapping of the activity in Brodmann areas to DCNN layers. Underlying data comes from the activity in low gamma (31-70 Hz, subfigures A and C) and high gamma (71-150 Hz, subfigures B and D) bands in 150-350 ms time window. C and D are subselection of the areas that constitute ventral stream: 17, 18, 19, 37, 20. There are two important observations to be made out of this plot: a) statistically significant neural responses are specific to visual areas b) the alignment between the ventral stream and layer of DCNN is clearly visible. Area 0 contains the regions of the brain not mapped by the atlas. The numbers on the left of each panel show the number of significantly correlating probes in each area out of the total number of responsive probes in that area.

score to be significantly different. The threshold of $p = 0.001$ is estimated by selecting such a threshold that on the surrogate data none of the probes would pass it.

To size the effect caused by training artificial neural network on natural images we performed a control where the whole analysis pipeline depicted on figure 1 is repeated using activations of a network that was not trained – its weights are randomly sampled from a Gaussian distribution $\mathcal{N}(0, 0.01)$.

9 Quantifying properties of the mapping

To evaluate the results quantitatively we devised a set of measures specific to our analysis. *Volume* is the total sum of significant correlations (see Equation 1) between the probes in a subset of brain areas A and DCNN layers L :

$$V_{\text{layers } L}^{\text{areas } A} = \sum_{a \in A} \sum_{l \in L} \sum_{p \in S_l^a} \rho_{\text{layer } l}^{\text{probe } p}, \quad (2)$$

where A is a subset of brain areas, L is a subset of layers, and S_l^a is the set of all probes in area a that significantly correlate with layer l .

We express *volume of visual activity* as

$$V_{\text{all layers}}^{\{17,18,19,37,20\}}, \quad (3)$$

which shows the total sum of correlation scores between all layers of the network and the Brodmann areas that are located in the ventral stream: 17, 18, 19, 37, and 20.

Visual specificity of activity is the ratio of volume in visual areas and volume in all areas together, for example visual specificity of all of the activity in the ventral stream that significantly correlates with any of layers of DCNN is

$$S_{\text{all layers}}^{\{17,18,19,37,20\}} = \frac{V_{\text{all layers}}^{\{17,18,19,37,20\}}}{V_{\text{all areas}}^{\text{all areas}}} \quad (4)$$

The measures so far did not take into account hierarchy of the ventral stream nor the hierarchy of DCNN. The following two measures are the most important quantifiers we rely on in presenting our results and they do take hierarchical structure into account.

The *ratio of complex visual features to all visual features* is defined as the total volume mapped to layers `conv5`, `fc6`, `fc7` divided by the total volume mapped to layers `conv1`, `conv2`, `conv3`, `conv5`, `fc6`, `fc7`:

$$C^{\text{areas } A} = \frac{V_{\text{conv5,fc6,fc7}}^{\text{areas } A}}{V_{\text{conv1,conv2,conv3,conv5,fc6,fc7}}^{\text{areas } A}}. \quad (5)$$

Note that for this measure layers `conv4` and `fc8` are omitted: layer `conv4` is considered to be the transition between the layers with low and high complexity features, while layer `fc8` directly represents class probabilities and does not carry visual representations of the stimuli (if only on very abstract level).

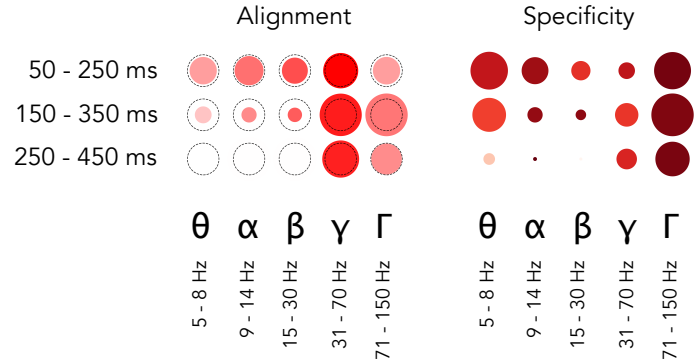


Figure 3 Overall relative statistics of brain responses across frequency bands and time windows. The left panel shows the alignment between visual brain areas and DCNN layers (see Equation 6). The color indicates the correlation value (ρ) while the size of the marker shows the logarithm (so that not significant results are still visible on the plot) of inverse of the statistical significance of the correlation, dotted circle indicates $p = 0.0003(3)$ – the Bonferroni-corrected significance threshold level of 0.005. The right panel shows whether activity in a region of interest is specific to visual areas (see Equation 4): intensive red means that most of the activity in that band and time window happened in visual areas, size of the marker indicates total volume (Equation 2) of activity in all areas. The maximal size of a marker is defined by the biggest marker on the figure.

Finally, the *alignment* between the activity in the visual areas and activity in DCNN is estimated as Spearman’s rank correlation between the vector of electrode assignments to visual areas and the vector of electrode assignments to DCNN layers:

$$\rho = \text{Spearman} \left(\begin{array}{l} \text{Brodmann areas with sig-} \\ \text{nificantly correlating probes} \\ \text{ordered by the hierarchy of,} \\ \text{the ventral stream: BA17,} \\ \text{BA18, BA19, BA37, BA20} \end{array} \begin{array}{l} \text{DCNN layers where} \\ \text{significantly correlating} \\ \text{probes are mapped,} \\ \text{ordered by the hierarchy} \\ \text{of DCNN architecture} \end{array} \right). \quad (6)$$

We note that although the hierarchy of the ventral stream is usually not defined through the progression of Brodmann areas, such ordering nevertheless provides a reasonable approximation of the real hierarchy (Lerner et al., 2001; Grill-Spector and Malach, 2004). As both the ventral stream and the hierarchy of layers in DCNN have an increasing complexity of visual representations, the relative ranking within the biological system should coincide with the ranking within the artificial system. Based on the recent suggestion that significance levels should be shifted to 0.005 (Dienes et al., 2017) and after Bonferroni-correcting for 15 time-frequency windows we accepted alignment as significant when it passed $p < 0.0003(3)$.

Results

Increasing complexity of visual representations is captured by activity in gamma band

We tested the hypothesis that gamma activity carries increasingly complex features along the ventral stream. To that end we assessed the alignment of neural activity in different frequency bands and time windows to the activity of layers of a DCNN.

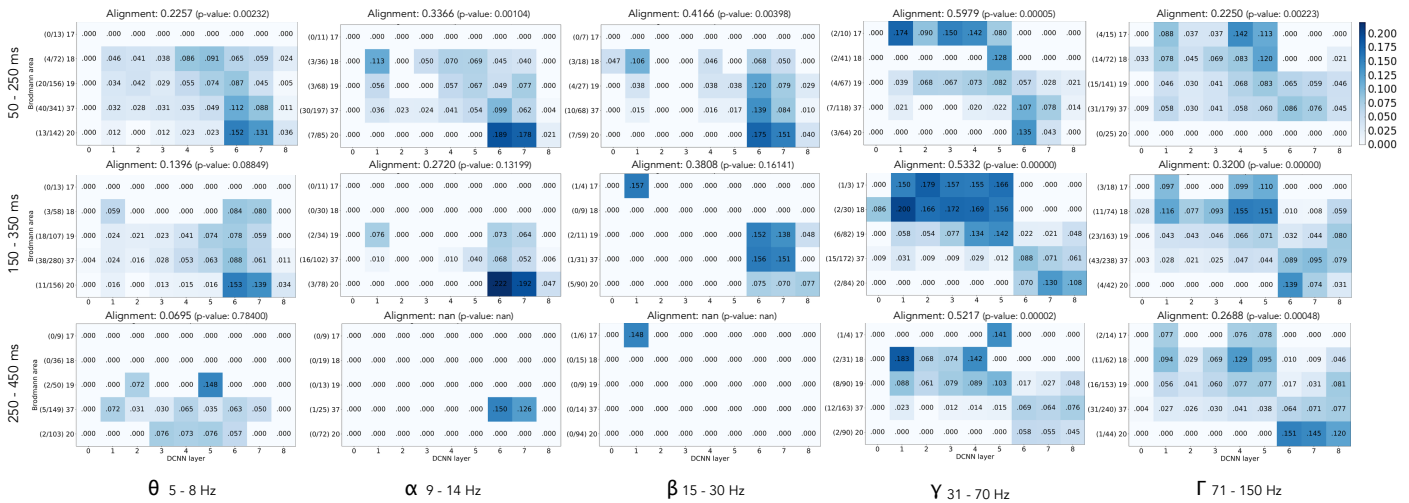


Figure 4 Mapping of activity in visual areas to activations of layers of DCNN across five frequency bands and three time windows. The alignment score is computed as Spearman's rank correlation between electrode assignment to Brodmann areas and electrode assignment to DCNN layers (Equation 6). The numbers on the left of each subplot show the number of significantly correlating probes in each area out of the total number of responsive probes in that area.

In particular, we used RSA to compare the representational geometry of different DCNN layers and the activity patterns of different frequency bands of single electrodes (see Figure 1). We consistently found that signals in low gamma (31 – 70 Hz) frequencies across all time windows and high gamma (71 – 150 Hz) frequencies in 150 – 350 ms window are aligned with the DCNN in a specific way: increase of the complexity of features along the layers of the DCNN was matched by the transformation in the representational geometry of responses to the stimuli along the ventral stream. In other words, the lower and higher layers of the DCNN explained gamma band signals from earlier and later visual areas, respectively.

Figure 2 illustrates assignment of neural activity in low gamma band (panel A) and high gamma band (panel B) to Brodmann areas and layers of DCNN. As one can see most of the activity was assigned to visual areas (areas 17, 18, 19, 37, 20). Focusing on visual areas (panels C, D) revealed a diagonal trend that illustrated the alignment between ventral stream and layers of DCNN. Our findings across all subjects, time windows and frequency bands are presented in table 2 and summarized on the left panel of figure 3. The results in table 2 show the comparison of alignment between DCNN and brain areas with both random and pre-trained networks. We can see that training a network to classify natural images drastically increases the alignment score ρ and its significance. We note that the alignment in the gamma bands is also present at the single-subject level as can be seen in Figure 6.

Apart from the alignment we looked at the total amount of correlation and its specificity to visual areas. On the right panel of Figure 3 we can see that the volume of significantly correlating activity was highest in the high gamma range. Remarkably, 97% of that activity was located in visual areas, which is confirmed by figure 2 where we see that in the gamma range only a few electrodes were assigned to Brodmann areas that are not part of the ventral stream.

Band	Window	Alignment with layers of randomly initialized AlexNet		Alignment with layers of AlexNet trained on ImageNet		*
		ρ	p-value	ρ	p-value	
θ	50-250 ms	0.0632	0.71	0.2257	0.00231575	*
θ	150-350 ms	-0.1013	0.59	0.1396	0.08848501	
θ	250-450 ms	0.1396	0.59	0.0695	0.78400416	
α	50-250 ms	-0.2411	0.32	0.3366	0.00103551	*
α	150-350 ms	0.0000	1.00	0.2720	0.13199463	
α	250-450 ms	–	–	–	–	
β	50-250 ms	–	–	0.4166	0.00397929	
β	150-350 ms	–	–	0.3808	0.16141286	
β	250-450 ms	–	–	–	–	
γ	50-250 ms	0.1594	0.62	0.5979	0.00004623	***
γ	150-350 ms	-0.1688	0.34	0.5332	0.00000059	***
γ	250-450 ms	-0.1132	0.56	0.5217	0.00001624	***
Γ	50-250 ms	0.0869	0.42	0.2259	0.00222940	*
Γ	150-350 ms	-0.0053	0.96	0.3200	0.00000051	***
Γ	250-450 ms	-0.1361	0.33	0.2688	0.00047999	*

Table 2 Alignment ρ score and significance for all 15 regions of interest. * indicates the alignments that pass p-value threshold of 0.05 Bonferroni-corrected to 0.003(3) and *** the ones that pass 0.005 (Dienes et al., 2017) Bonferroni-corrected to 0.0003(3). Note how the values differ between random (control) network and a network trained on natural images. Visual representation of alignment and significance is given on the left pane of Figure 3.

Activity in other frequency bands

To test the specificity of gamma frequency in visual object recognition, we assessed the alignment between the DCNN and other frequencies. The detailed mapping results for all frequency bands

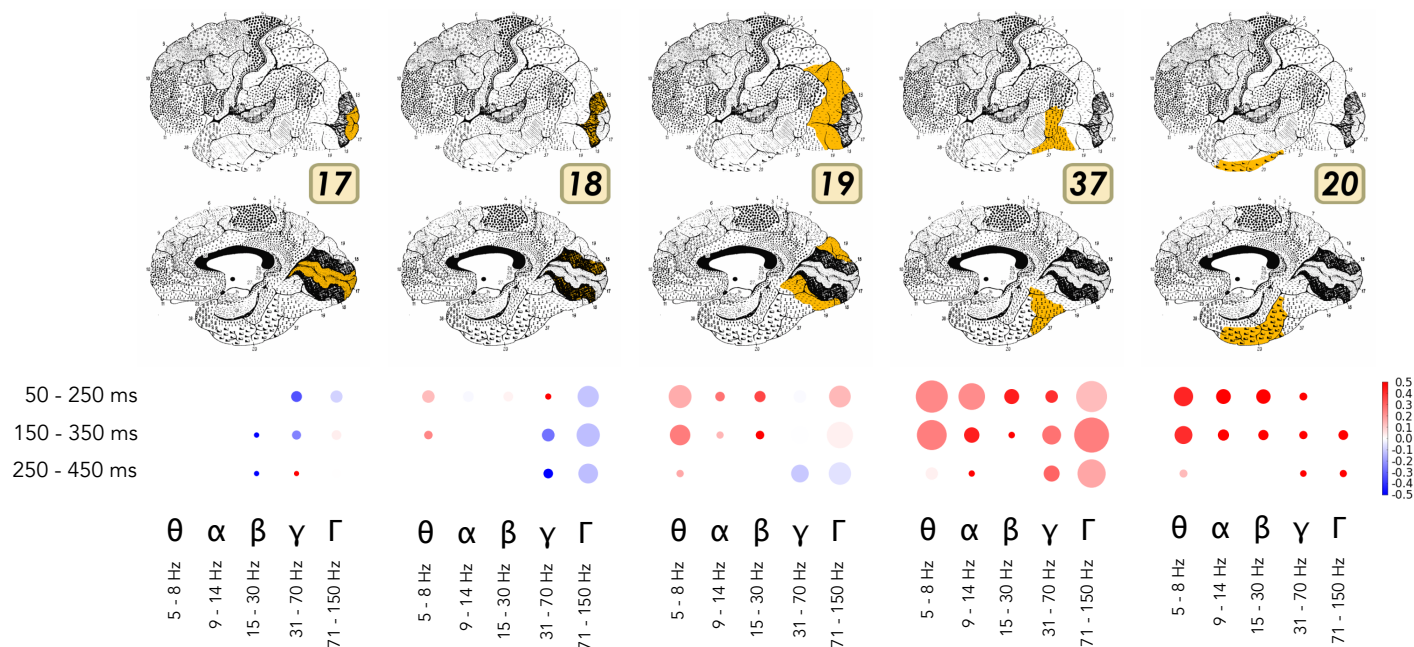


Figure 5 Area-specific analysis of volume of neural activity and complexity of visual features represented by that activity. Size of the marker shows the sum of correlation coefficients between the area and DCNN for each particular band and time window. Color codes the ratio of complex visual features to simple visual features, i.e. the comparison between the activity that correlates with the higher layers (*conv5*, *fc6*, *fc7*) of DCNN to the lower layers (*conv1*, *conv2*, *conv3*). Intensive red means that the activity was correlating more with the activity of higher layers of DCNN, while the intensive blue indicates the dominance of correlation with the lower areas. If the color is close to white then the activations of both lower and higher layers of DCNN were correlating with the brain responses in approximately equal proportion.

1 and time windows are presented in figures 3 and 4. We can see that weaker alignment (that does not survive the Bonferroni correction) is present in early time window in theta and alpha frequency range. No alignment is observed in the beta band.

2 To investigate the involvement of each frequency band more closely we analyzed each visual area separately. Figure 5 shows the volume of activity in each area (size of the marker on the figure) and whether that activity was more correlated with the complex visual features (red color) or simple features (blue color). In our findings the role of the earliest area (17) was minimal, however that might be explained by a very low number of electrodes in that area in our dataset (less than 1%). One can see from figure 5 that activity in theta frequency in time windows 50 – 250 ms and 150 – 350 ms had large volume and is correlated with the higher layers of DCNN in higher visual areas (19, 37, 20) of the ventral stream. This hints at the role of theta activity in visual object recognition. In general, in areas 37 and 20 all frequency bands carried information about high level features in the early time windows. This implies that already at early stages of processing the information about complex features was present in those areas.

22 **Gamma activity is more specific to convolutional**
 23 **layers, while the activity in lower frequency bands is**
 24 **more specific to fully connected layers**

25 We analysed volume and specificity of brain activity that corre-
 26 lates with each layer of DCNN separately to see if any bands or

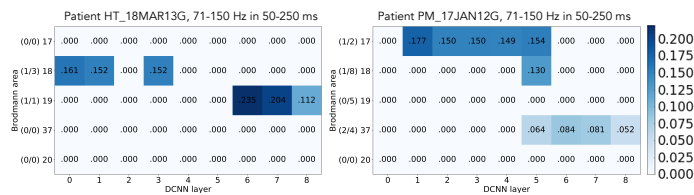


Figure 6 Single subject results from two different subjects. The numbers show the sum of correlations normalized by the number of probes in an area. On the left plot we see how a probe in Brodmann area 18 is mapped to the layers 0, 1, and 3 DCNN, while the activity in Brodmann area 19, which is located further along the ventral stream, is mapped to the higher layers of DCNN: 6, 7, 8. Similar trend is seen on the right plot. The numbers on the left of each subplot show the number of significantly correlating probes in each area out of the total number of responsive probes in that area.

time windows are specific to particular level of hierarchy of visual processing in DCNN. Figure 7 presents a visual summary of this analysis. In the “Methods” section we have defined total volume of visual activity in layers L . We used this measure to quantify the activity in low and high gamma bands. We noticed that while the fraction of gamma activity that is mapped to convolutional layers is high ($\frac{\bar{V}_{\{\text{conv1} \dots \text{conv5}\}}^{\gamma, \Gamma}}{\bar{V}_{\text{all bands}}^{\gamma, \Gamma}} = 0.71$), this fraction diminished in fully connected layers *fc6* and *fc7* ($\frac{\bar{V}_{\{\text{fc6}, \text{fc7}\}}^{\gamma, \Gamma}}{\bar{V}_{\{\text{conv1} \dots \text{conv5}\}}^{\gamma, \Gamma}} = 0.39$). Note that *fc8* was excluded as it represents class label probabilities and

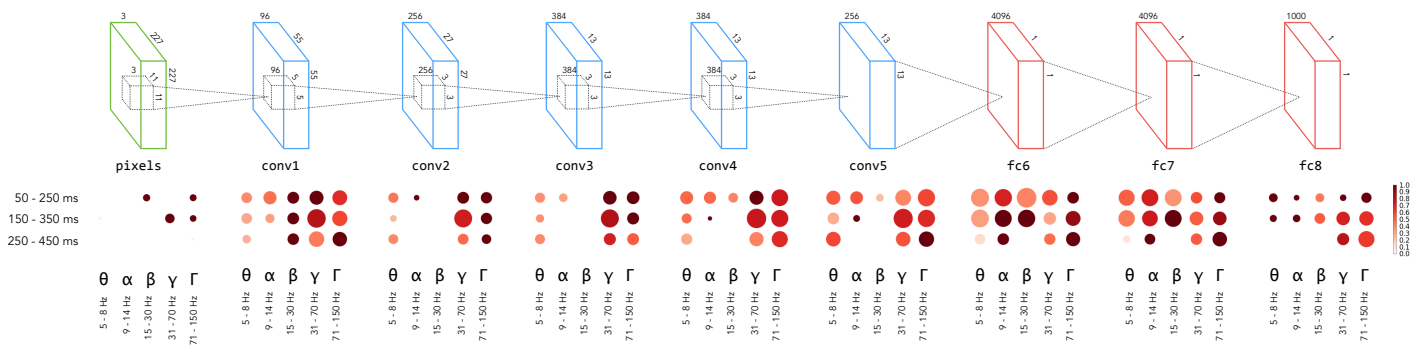


Figure 7 Specificity of neural responses across frequency bands and time windows for each layer of DCNN. Size of a marker is the total activity mapped to this layer and the intensity of the color is the specificity of the activity to visual areas.

1 does not carry information about visual features of the objects.
 2 On the other hand the activity in lower frequency bands (theta,
 3 alpha, beta) showed the opposite trend – fraction of volume in
 4 convolutional layers was 0.29, while in fully connected it grew
 5 to 0.61. This observation highlighted the fact that visual features
 6 extracted by convolutional filters of DCNN carry the signal that
 7 is more similar to the signal carried by gamma frequency bands,
 8 while the fully connected layers that do not directly correspond
 9 to intuitive visual features, carry information that has more in
 10 common with the activity in the lower frequency bands.

11 Discussion

12 The recent advances in artificial intelligence research have been
 13 breathtaking. Not only do the deep neural networks match
 14 human performance in visual object recognition, they also pro-
 15 vide the best model for how biological object recognition happens
 16 (Kriegeskorte, 2015; Yamins and DiCarlo, 2016). Previous work
 17 has established a correspondence between hierarchy of the DCNN
 18 and the fMRI responses measured across the human visual areas
 19 (Güçlü and van Gerven, 2015; Eickenberg et al., 2016; Seibert et
 20 al., 2016; Cichy et al., 2016b). Further research has shown that
 21 the activity of the DCNN matches the biological neural hierar-
 22 chy in time as well (Cichy et al., 2016b; Seeliger et al., 2017).
 23 Studying intracranial recordings allowed us to extend previous
 24 findings by assessing the alignment between the DCNN and corti-
 25 cal signals at different frequency bands. As there is a quantifiable
 26 increase of the complexity of features along the layers of the
 27 DCNN, any signal that is aligned to the DCNN has to carry simi-
 28 larly increasingly complex features built-up during visual object
 29 recognition. We observed that the lower layers of the DCNN
 30 explained gamma band signals from earlier visual areas, while
 31 higher layers of the DCNN, responsive for more complex features,
 32 matched with the gamma band signals from higher visual areas.
 33 Correspondence between layers of DCNN and visual hierarchy of
 34 human brain was present not only at the extremes, but also at the
 35 intermediate layers of the hierarchy. Hence, one can conclude that
 36 gamma band carries increasingly complex features required for
 37 object recognition along the ventral visual pathway. This finding
 38 confirms previous work that has given a central role for gamma
 39 band activity in visual object recognition (Singer and Gray, 1995;
 40 Singer, 1999; Fisch et al., 2009) and feedforward communication

(Van Kerkoerle et al., 2014; Bastos et al., 2015; Michalareas et
 al., 2016). However, importantly, our results show that gamma
 activity reflects not only object recognition per se but also the
 feature transformations that are computed on the way towards
 explicit object representations. Our work demonstrates that the
 correlation between the DCNN and the biological counterpart is
 specific not only in space and time, but also in frequency.

8 Feedforward and feedback computations in object 9 recognition

10 Visual object recognition in the brain involves both feedforward
 11 and feedback computations (DiCarlo et al., 2012; Kriegeskorte,
 12 2015). What do our results reveal about the nature of feedfor-
 13 ward and feedback components in visual object recognition? We
 14 observed that the DCNN corresponds to the biological processing
 15 hierarchy even in the latest analysed time-window (Figure 3). In
 16 a directly relevant previous work Cichy and colleagues compared
 17 DCNN representations to millisecond resolved MEG data from
 18 humans (Cichy et al., 2016b). There was a positive correlation
 19 between the layer number of the DCNN and the peak latency of
 20 the correlation time course between the respective DCNN layer
 21 and MEG signals. In other words, deeper layers of the DCNN
 22 predicted later brain signals. As evidenced on Figure 3 in (Cichy
 23 et al., 2016b), the correlation between DCNN and MEG activity
 24 peaked between ca 100 and 160 ms for all layers, but significant
 25 correlation persisted well beyond that time-window. However, in
 26 the work of (Cichy et al., 2016b) the correlation decreased over
 27 time, while in our data we evidenced no such clear drop in the
 28 later time windows: even between 250-450 ms the alignment in
 29 low gamma was strong and significant.

30 How could this late alignment be interpreted? In particular,
 31 feedforward object recognition is thought to be finished in ca
 32 200-250 milliseconds after stimulus onset (DiCarlo et al., 2012).
 33 Hence, one could think that the correspondence between the
 34 DCNN, which is a feedforward network and biological visual
 35 object recognition should be confined to early time windows.
 36 However, although the DCNN is a purely feedforward network
 37 it is important to notice that the alignment between electro-
 38 physiological signals and the DCNN does not imply that the
 39 respective signals have to reflect feedforward computations. Such

alignment only means that the progressive changes in representational geometry along the processing hierarchy are similar to the DCNN. In other words, it is possible that the activity patterns observed are a result of recurrent computations, but their outcome representational geometry resembles that of the DCNN. Therefore, the present results together with previous findings (Cichy et al., 2016b) demonstrate that the DCNN is a good model not only for feedforward object recognition, but also for the later phases, which most likely include feedback computations. This fits with the predictive coding framework where the feedback activity is not an unspecific modulatory signal but rather has to signal specific contents from higher to lower levels of the processing hierarchy (Bastos et al., 2012). Hence, within this theoretical framework, a specific representational geometry is expected even from a feedback channel.

Low vs high gamma in object recognition

We observed significant alignment to the DCNN in both low and high gamma bands. However, for high gamma this alignment was more restricted in time, surviving correction only in the middle time window. Previous studies have shown that low and high gamma frequencies are functionally different: while low gamma is more related to classic narrow-band gamma oscillations, high frequencies seem to reflect local spiking activity rather than oscillations (Manning et al., 2009; Ray and Maunsell, 2011), the distinction between low and high gamma activity has also implications from cognitive processing perspective (Vidal et al., 2006; Wyart and Tallon-Baudry, 2008). In the current work we approached the data analysis from the machine learning point of view and remained agnostic with respect to the oscillatory nature of underlying signals. Importantly, we found that numerically the alignment to the DCNN was stronger and persisted for longer in low gamma frequencies. However, high gamma was more prominent when considering volume and specificity to visual areas. The most striking difference between the low and high gamma with regard to specificity was in the earliest time window 50-250 ms where the correlation between the DCNN and high gamma was almost exclusive to visual areas.

Limitations

The present work relies on data pooled over the recordings from 100 subjects. Hence, the correspondence we found between responses at different frequency bands and layers of DCNN is distributed over many subjects. While it is expected that single subjects show similar mappings (see also Figure 6), the variability in number and location of recording electrodes in individual subjects makes it difficult a full single-subject analysis with this type of data. We also note that the mapping between electrode locations and Brodmann areas is approximate and the exact mapping would require individual anatomical reconstructions and more refined atlases.

Future work

Intracranial recordings are both precisely localized in space and time, thus allowing us to explore phenomena not observable with

fMRI. In this work we investigated the correlation of DCNN activity with five broad frequency bands and three time windows. Our next steps will include the analysis of the activity on a more granular temporal and spectral scale. Replacing representation similarity analysis with a predictive model (such as regularized linear regression) will allow us to explore which visual features elicited the highest responses in the visual cortex.

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