Article (Methods)

Inferring the Demographic History of Inbred Species From Genome-Wide SNP Frequency Data

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Abstract

Demographic inference using the site frequency spectrum (SFS) is a common way to understand 2 historical events affecting genetic variation. However, most methods for estimating demography 3 from the SFS assume random mating within populations, precluding these types of analyses in in-4 bred populations. To address this issue, we developed a model for the expected SFS that includes 5 inbreeding by parameterizing individual genotypes using beta-binomial distributions. We then 6 take the convolution of these genotype probabilities to calculate the expected frequency of bial-7 lelic variants in the population. Using simulations, we evaluated the model's ability to co-estimate 8 demography and inbreeding using one- and two-population models across a range of inbreeding 9 levels. We also applied our method to two empirical examples, American pumas (Puma concolor) 10 and domesticated cabbage (Brassica oleracea var. capitata), inferring models both with and with-11 out inbreeding to compare parameter estimates and model fit. Our simulations showed that we 12 are able to accurately co-estimate demographic parameters and inbreeding even for highly inbred 13 populations (F = 0.9). In contrast, failing to include inbreeding generally resulted in inaccurate 14 parameter estimates in simulated data and led to poor model fit in our empirical analyses. These 15 results show that inbreeding can have a strong effect on demographic inference, a pattern that was 16 especially noticeable for parameters involving changes in population size. Given the importance 17 of these estimates for informing practices in conservation, agriculture, and elsewhere, our method 18 provides an important advancement for accurately estimating the demographic histories of these 19 species. 20

²¹ Key words: Conservation, Demography, Domestication, Inbreeding, Site Frequency Spectrum.

22 Introduction

Estimating the demographic history of closely related populations or species is an important first 23 step in understanding the interplay of the evolutionary forces shaping genetic variation. Diver-24 gence, migration, changes in population size, and other historical events all contribute to pop-25 ulation allele frequency dynamics over time, a process that can be modeled using a variety of 26 approaches. Connecting the expectations from these models with observed genomic data is of-27 ten achieved using the site frequency spectrum (SFS), a genome-wide summary of genetic poly-28 morphism within and between populations (Sawyer and Hartl 1992; Adams and Hudson 2004; 29 Caicedo et al. 2007; Gutenkunst et al. 2009; Nielsen et al. 2009). The ease and affordability of col-30 lecting genomic SNP data make inferences of demography using the SFS especially appealing, 31 highlighting their importance in gaining insights into the historical factors affecting neutral varia-32 tion in populations. Several recent analyses have also applied SFS-based methods to infer the fit-33 ness effects of mutations (Kim et al. 2017; Tataru et al. 2017; Fortier et al. 2019), allowing researchers 34 to model patterns of selection while simultaneously controlling for demography (Williamson et al. 35 2005). 36 Generating the SFS from a demographic model is a well-studied problem with several possi-37 ble approaches, all based on different underlying methodologies, currently implemented [e.g., dif-38

fusion: Gutenkunst et al. (2009); spectral methods: Lukić and Hey (2012); the coalescent: Excoffier 39 et al. (2013); and moment closure: Jouganous et al. (2017)]. However, these methods generally as-40 sume panmixia or random mating within populations, which may not be a realistic assumption 41 for many groups of organisms that are inbred. The reason for this assumption is that the approxi-42 mations used by these approaches are all built on top of the Wright-Fisher model and rely on the 43 simplicity of its binomial sampling scheme for deriving expectations. The excess of homozygos-44 ity caused by inbreeding deviates from binomial expectations, leading to changes in the observed 45 SFS that cannot be captured by models assuming random mating that may affect estimates of 46 demography. Generalizations of the standard Wright-Fisher model have been made to include 47 inbreeding through partial self-fertilization (Wright 1951). Nevertheless, these modifications have 48 yet to be implemented in SFS-based methods for demographic inference. 49

Despite this lack of available SFS-based methods, previous approaches to infer demography 50 from inbred samples have successfully used alternative representations of genomic data to capture 51 the extent to which samples share blocks of their genome through non-random mating. This 52 typically entails identifying parts of the genome that are identical by descent (IBD), or that contain 53 runs of homozygosity (ROH), and using the length and distribution of these blocks to infer levels 54 of inbreeding and past population size dynamics (Kirin et al. 2010; Kardos et al. 2017; Browning 55 et al. 2018). Large IBD blocks are usually an indication of recent inbreeding, while the frequency 56 and distribution of smaller IBD blocks, which are shared due to common ancestry rather than 57 inbreeding, contain information about more long-term trends in population size (Kirin et al. 2010; 58 Ceballos et al. 2018). However, these methods are generally only used to model size changes in 59 single populations, which doesn't allow them to estimate other important demographic events 60 such as population divergence or rates of gene flow. Furthermore, the reliance of these methods 61 on fully sequenced genomes prevents them from being used in systems that lack such resources. 62

The ability to estimate demography in organisms that do not have a reference genome is a strength of SFS-based methods. This flexibility allows researchers using reduced representation methods (e.g., restriction enzyme-based approaches) to collect genomic data for demographic in-

ference. A large motivating factor for the work that we have conducted here is to understand 66 demography in domesticated crop species, which are often highly inbred due to how they are 67 bred and propagated (Gaut et al. 2018). Inbreeding is also of great concern in threatened and en-68 dangered species (Shafer et al. 2015; Xue et al. 2015; Robinson et al. 2016, 2019). For many of the 69 most economically or ecologically important species in these categories, full genome sequences 70 are typically available and can be used to guide estimates of genetic variation and past popula-71 tion dynamics that will help to inform breeding practices or management strategies, respectively. 72 However, for less well-studied agricultural or threatened species, it is crucial to have tools avail-73 able that can also provide this essential information without necessarily needing to obtain a fully 74 sequenced genome. 75

In this paper we introduce a new method for including inbreeding in estimates of demogra-76 phy by modifying the sampling distribution used to generate the expected SFS for a given demo-77 graphic model. We have implemented the approach in the Python package $\partial a \partial i$ (Gutenkunst *et al.* 78 2009), building on top of its existing machinery for estimating demography using the diffusion 79 approximation. To assess our ability to co-estimate inbreeding and demography, we generated 80 frequency spectra in both $\partial a \partial i$ and SLiM (Haller and Messer 2019) and used the new model to 81 make inferences from these simulated data. We also used simulated frequency spectra from $\partial a \partial i$ 82 to see how inbreeding affects estimates of demography when it is ignored. Finally, we used ge-83 nomic data from two empirical examples, American pumas (Puma concolor) and domesticated 84 cabbage (Brassica oleracea var. capitata), and evaluated estimates of their demographic histories 85 both with and without inbreeding. In general, our model is shown to be accurate even for highly 86 inbred populations (F = 0.9). We also found that failing to account for inbreeding leads to inac-87 curate estimates of parameters and poor model fit. Taken together, the model we have developed 88 provides a powerful tool to jointly estimate inbreeding and demography, and will help to facilitate 89 evolutionary inferences in a wide-range of species. 90

New Approaches

⁹² We start with a brief overview of the SFS and describe its derivation from the population distri-⁹³ bution of allele frequencies (DAF), which can be obtained using the diffusion approximation as ⁹⁴ described previously (Gutenkunst *et al.* 2009). We then propose a probability model for calcu-⁹⁵ lating the number of derived mutations in an inbred population and provide an expression for ⁹⁶ the expected SFS incorporating this distribution. Using this expression for the expected SFS with ⁹⁷ inbreeding we can perform parameter inference with a composite likelihood assuming a Poisson ⁹⁸ Random Field model (Sawyer and Hartl 1992).

99 The Site Frequency Spectrum

The site frequency spectrum (SFS) is a multidimensional summary of genetic variation within 100 and across populations that records how often derived biallelic variants of different frequencies 101 are observed in a sample of individuals. For example, given a sample of 20 chromosomes (10 102 diploid individuals) from three populations, the SFS entry at index [3,8,17] records how often we 103 observe a variant in three, eight, and 17 out of the 20 chromosomes in populations one, two, and 104 three, respectively. In general, for P populations with sample sizes n_1, n_2, \ldots, n_P , we index the 105 SFS using $[d_1, d_2, \ldots, d_P]$ to record how often we observe a variant with frequency d_1, d_2, \ldots, d_P in 106 populations one through P. 107

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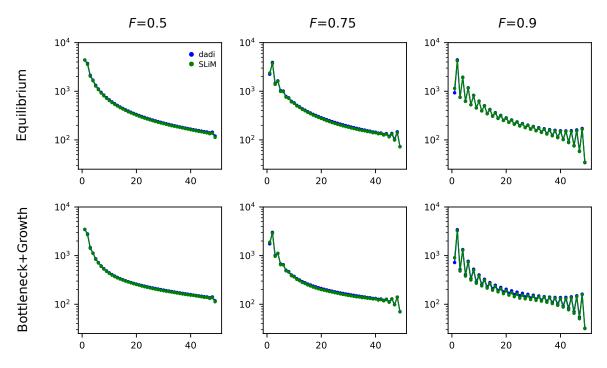


Figure 1: Comparison of expected spectra for F = 0.5, 0.75, and 0.9 between $\partial a \partial i$ (blue) and SLiM (green) for the equilibrium and bottleneck+growth models.

The observed SFS can be obtained from empirical data by tabulating derived SNP frequencies across sampled populations to generate the *P*-dimensional array described above. When a derived allele cannot be determined, we can instead record the frequency of the minor allele, effectively "folding" the spectrum in half by only considering the variants with frequency less than 0.5. Demographic inference can then be conducted by comparing the observed SFS with the SFS obtained from a demographic model (Sawyer and Hartl 1992).

Given the P-dimensional distribution of allele frequencies obtained from a given demographic 114 model, ϕ , the expected SFS can be obtained by calculating the probability of drawing d_1, \ldots, d_P 115 derived alleles while integrating across the distribution of allele frequencies in the populations. 116 Within each population, the number of derived alleles has a binomial distribution under pan-117 mixia. We then integrate across all possible allele frequencies, weighting the binomial probability 118 of drawing d_i derived alleles by the density determined by ϕ within population *i*. Taking this *P*-119 dimensional integral across the weighted product of binomial probabilities gives us the expression 120 for the joint expected SFS: 121

$$\mathbb{E}[d_1, \dots, d_P] = \int_0^1 \cdots \int_0^1 \prod_{i=1,\dots,P} \binom{n_i}{d_i} x_i^{d_i} (1-x_i)^{n_i-d_i} \phi(x_1, \dots, x_P) dx_i.$$
(1)

122 The Expected SFS with Inbreeding

¹²³ Through its use of binomial sampling, the preceding derivation for the expected SFS makes the ¹²⁴ assumption that matings within populations are random. When inbreeding has occurred, individ-

ual genotypes are more likely to be homozygous due to being IBD. One way to capture this excess 125 in homozygosity is to incorporate the inbreeding coefficient F into a generalized form for the ex-126 pected genotype frequencies under Hardy Weinberg equilibrium (Wright 1951). Here we use an 127 alternative model that captures the fact that genotypes within populations will be correlated due 128 to inbreeding, pushing the distribution of genotypes towards homozygotes. To capture this cor-129 relation among genotypes, Balding and Nichols (1995, 1997) proposed a probability model to in-130 corporate inbreeding using a beta-binomial distribution. Under this model, individual genotypes 131 are a random variable, $G_i \in \{0, 1, 2\}$, for the number of copies of the derived allele in individual 132 i (i = 1, ..., n) such that $Pr(G_i = g)$ at an individual locus with allele frequency $p \in (0, 1)$ and 133 population inbreeding coefficient $F \in (0, 1)$ is beta-binomial with the following form: 134

$$Pr(G_{i} = g|p, F) = \mathcal{B}\mathcal{B}\left(g, \alpha = p\left[\frac{1-F}{F}\right], \beta = (1-p)\left[\frac{1-F}{F}\right]\right)$$
$$= {\binom{2}{g}}\frac{B(g+\alpha, 2-g+\beta)}{B(\alpha, \beta)}.$$
(2)

Here \mathcal{BB} denotes the probability mass function for the beta-binomial distribution and B(x, y) is the beta function with dummy parameters x and y. The parameterization of $\alpha = p \left[\frac{1-F}{F}\right]$ and $\beta = (1-p) \left[\frac{1-F}{F}\right]$ introduces the overdispersion of probability towards homozygous genotypes that is expected as inbreeding increases (Balding and Nichols 1995, 1997).

To get the expected SFS, we need to be able to model the total number of derived alleles 139 sampled in the population, which is the sum across the genotypes of all individuals. Given a 140 sample of *n* diploid individuals (2*n* chromosomes), we use the random variable $D \in \{0, ..., 2n\}$ to 141 denote this quantity. The probability mass function for D is an n-fold convolution of beta-binomial 142 distributions, which does not have a simple distributional form. However, we can obtain the 143 probability mass function by considering all possible combinations of the probability of drawing 144 D = d alleles across n beta-binomial distributions, giving us a closed form expression for the 145 convolution of *n* beta-binomial random variables: 146

$$P(D = d|p, F) = \mathcal{B}\mathcal{B}_{n}^{*}\left(d, \alpha = p\left[\frac{1-F}{F}\right], \beta = (1-p)\left[\frac{1-F}{F}\right]\right)$$
$$= \sum_{R \in p_{n}(d)} \frac{n!}{n_{0}! n_{1}! n_{2}!} \left[\prod_{r \in R} \mathcal{B}\mathcal{B}(r, \alpha, \beta)\right].$$
(3)

Breaking this down, we can think of it as enumerating all possible ways to generate genotypes 147 in n individuals such that they sum to d, times the beta-binomial probability of sampling each 148 genotype. More specifically, let $p_n(d)$ be an array of integer partitions with n entries that sum 149 to d such that all entries in the partition are 0, 1, or 2 (corresponding to the possible genotype 150 values). For example, the partitions defined by $p_5(4)$ are [2, 2, 0, 0, 0], [2, 1, 1, 0, 0], and [1, 1, 1, 1, 0]. 151 Then for each of these partitions, we use the multinomial coefficient $\frac{n!}{n_0! n_1! n_2!}$, with n_0 , n_1 , and n_2 152 corresponding to the number of partition entries equal to 0, 1, and 2, respectively, to account for all 153 possible rearrangements of the partition entries. Next, we multiply the beta-binomial probability 154

for each genotype in a partition using Eq. 2. Taking the product across all possible partitions gives us the full expression for the *n*-fold convolution, which we denote \mathcal{BB}_n^* (* is the mathematical operator for convolutions). Inserting this distribution into Eq. 1 gives us the final form for the expected SFS with inbreeding:

$$\mathbb{E}_{F}[d_{1},\ldots,d_{P}] = \int_{0}^{1} \cdots \int_{0}^{1} \prod_{i=1,\ldots,P} \mathcal{B}\mathcal{B}_{n_{i}}^{*}\left(d_{i}, x_{i}\left[\frac{1-F_{i}}{F_{i}}\right], (1-x_{i})\left[\frac{1-F_{i}}{F_{i}}\right]\right) \phi(x_{1},\ldots,x_{P})dx_{i}.$$
 (4)

We have written a small R Shiny application illustrating the probability distribution for the beta-binomial convolution (available on GitHub). Figure 1 also shows a sample of example frequency spectra for different levels of inbreeding.

162 **Results**

163 Comparison with SLiM

We used SLiM (Haller and Messer 2019) to validate the expectations of the SFS with inbreeding 164 by simulating frequency spectra under three models (described in more detail in the **Simulations** 165 section below): a simple equilibrium model (standard neutral model), a one-population bottleneck 166 and growth model, and a two-population divergence and one-way migration model. Inbreeding 167 was assumed to occur through selfing and expected frequency spectra were obtained by taking the 168 mean of 5000 simulations for each model. Figure 1 plots the comparison between the SFS obtained 169 from $\partial a \partial i$ (blue) and SLiM (green) for the equilibrium and bottleneck models with F=0.5, 0.75, 170 and 0.9, respectively. The frequency spectra for these models for F=0.1 and F=0.25 are presented 171 in Figure S1 and the comparisons for the two-population divergence model are in Figure S2. The 172 percent differences between the frequency spectra from $\partial a \partial i$ and SLiM were between 0.1% to 0.2% 173 for the one-population models and were between 0.02% to 0.03% for the two-population model, 174 demonstrating that our results from modeling the expected SFS with beta-binomial distributions 175 corresponds well with the spectra simulated from SLiM. 176

¹⁷⁷ We also used simulated frequency spectra from SLiM to estimate parameters for these three ¹⁷⁸ models in $\partial a \partial i$. Figure 2 shows the distribution of estimated inbreeding coefficients for the bottle-¹⁷⁹ neck and growth model (RMSD = 0.094) and divergence and one-way migration models (RMSD ¹⁸⁰ = 0.163). Similar plots for all other estimated parameters across all three models are presented in ¹⁸¹ Figures S3–S5.

182 Simulations

183 Simulation 1: Co-Estimating Inbreeding and Demography

To assess our ability to estimate demographic parameters under increasing levels of inbreeding (F= 0.1, 0.25, 0.5, 0.75, and 0.9), as well as the inbreeding coefficient within a population itself, we performed demographic inference using simulated frequency spectra under three models: (1) a standard neutral model, (2) a one-population bottleneck and growth model, and (3) a two-population divergence model with unidirectional gene flow (models two and three are illustrated in Figure 2). For the standard neutral model, the inbreeding coefficient is the only parameter that ¹⁹⁰ needs to be estimated. The one-population bottleneck and growth model has three parameters: ¹⁹¹ the inbreeding coefficient, the relative size of the bottlenecked population ($\nu_0 = 0.1, 0.25, \text{ and } 0.5$), ¹⁹² and the recovery time back to the original size (T = 0.1, 0.2, and 0.3). The two-population model ¹⁹³ has four parameters: the inbreeding coefficient, the relative size of the diverging population ($\nu_2 =$ ¹⁹⁴ 0.1, 0.25, 0.5), the time of divergence from the main population (T = 0.1, 0.2, and 0.3), and the rate ¹⁹⁵ of gene flow from the main population into the diverged population ($M_{21} = 0.5, 1.0, \text{ and } 1.5$). All ¹⁹⁶ parameters are specified relative to the ancestral population size, which in $\partial a \partial i$ defaults to 1.0.

Figures S6–S8 shows the distribution of estimated inbreeding coefficients across 20 replicate 197 experiments for every combination of simulation parameters for the equilibrium, bottleneck, and 198 divergence models. For all three models, we are able to recover accurate estimates of F (Model 199 1 RMSD: 0.0139; Model 2 RMSD: 0.0176; Model 3 RMSD: 0.0406) even when inbreeding is quite 200 high (F = 0.9). Figure S7 also shows plots for estimates of bottleneck size and recovery time 201 across inbreeding levels for model two. The RMSD for these estimates across all simulated values 202 were 0.0236 and 0.0184 for v_0 and T, respectively. Figure S8 shows similar plots for estimates of 203 population size, divergence time, and one-way migration rate across inbreeding levels for model 204 three. The RMSD for these estimates across all simulated values were 0.0131 for ν_2 , 0.0103 for T, 205 and 0.158 for M₂₁. 206

207 Simulation 2: Parameter Estimation When Inbreeding is Ignored

To understand the impact of ignoring inbreeding on demographic inference, we simulated data sets with inbreeding under the same bottleneck and divergence models as above (models two and three) but performed inference under the assumption that inbreeding was absent. Because of initial issues with convergence in these analyses, particularly with the bottleneck model, and the fact that higher levels of inbreeding cause increasingly conspicuous changes to the SFS (e.g., see Figure 1), we used a smaller range for *F* in these simulations: 0.1, 0,2, 0.3, 0.4, and 0.5.

Parameter estimates for the bottleneck model had higher rates of error compared to when 214 inbreeding was directly modeled. The RMSDs for v_0 and T were 0.191 and 0.117, respectively. 215 Estimates of these parameters also got worse as inbreeding increased (Figure S9), clearly demon-216 strating the issues that can arise when inbreeding is ignored. In contrast, results for the divergence 217 model were surprising in that they didn't show the high levels of estimation error seen with the 218 bottleneck model (Figure S10). The RMSD values for the parameters of the divergence model were 219 0.0261 for v_2 , 0.0130 for T, and 0.142 for M_{21} . Interestingly, the RMSD for M_{21} was actually lower 220 in this simulation experiment than when inbreeding was modeled (0.158). However, the increase 221 in RMSD for the simulations where inbreeding is modeled is due to using higher levels of in-222 breeding (F > 0.5). If we restrict the calculation of RMSD in the estimates including inbreeding to 223 only those with $F \leq 0.5$, the RMSD is lower than when inbreeding is ignored, as expected (0.109). 224 RMSD values for v_2 and T where higher for model two than in *Simulation 1*, indicating that these 225 parameters may be more sensitive to the effects of unmodeled inbreeding. 226

227 Simulation 3: Masking Rare Variants

Several techniques to 'side-step' the impact of inbreeding have been taken in empirical analyses. This includes sampling only a single chromosome per site, per individual (e.g., Beissinger *et al.* 2016; Koenig *et al.* 2019) or masking rare variants (e.g., Cornejo *et al.* 2018), which are disproportionately affected at lower levels of inbreeding (Figure 1). Since sampling only a single chromosome cuts the sample size in half, and investigations on the effect of sample size on de-

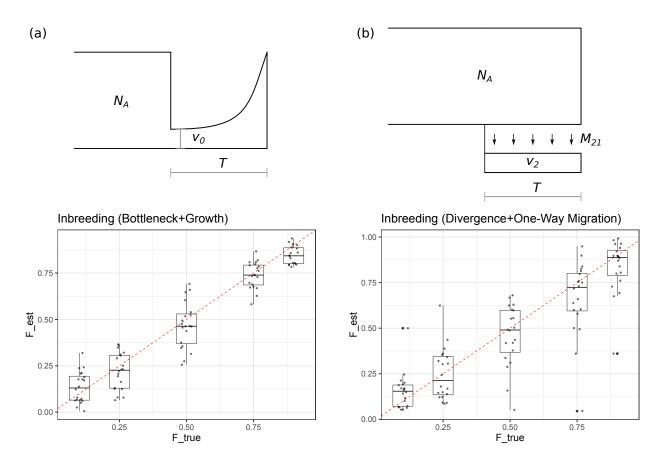


Figure 2: (a) Estimates of *F* from data generated with SLiM for the bottleneck and growth model (lower) plus an illustration of the model (upper). In this model, N_A is the ancestral population size, v_0 is the size of the bottleneck (proportion of N_A remaining after population reduction), and *T* is the amount of time for the population to recover back to a size of N_A . (b) Estimates of *F* from data generated with SLiM for the divergence with one-way migration model (lower) plus an illustration of the model (upper). N_A in this model is the same as the bottleneck model, v_2 is the size of the diverging population (again a proportion of N_A), *T* is the divergence time between populations, and M_{21} is the one-way migration rate of individuals from population one into population two.

mographic inference have already been explored (Robinson *et al.* 2014), we instead focused on the effect of masking rare variants under increasing levels of inbreeding. For the bottleneck model we masked the singleton and doubleton entries of the 1D-SFS, and for the divergence model we masked the bottom corner of the 2D-SFS (ie singletons, doubletons, and their combinations across both populations). We then used the same range of parameters as in the previous simulations to see how much masking affected our inferences.

For the bottleneck and growth model, data masking had a small but noticeable effect on parameter estimation. The bottleneck size was estimated with less accuracy compared to when inbreeding was included (RMSD = 0.0296) and estimates of recovery time also had higher error (RMSD = 0.0218), typically in the direction of underestimation (Figure S11). The effect of masking was more pronounced in the divergence model (Figure S12), particularly for the migration parameter, where the amount of gene flow was almost always underestimated across all parameter combinations (RMSD = 0.193). Estimates of population size and divergence time were also
 slightly underestimated when compared to models including inbreeding (RMSD = 0.0122 and
 0.0103, respectively) but the effect was less pronounced.

248 Simulation 4: Misspecified Inbreeding

As a final test of the model for inbreeding, we simulated frequency spectra under the bottleneck 249 and divergence models without inbreeding but included it as a parameter to be estimated. The 250 expectation in this case is that inbreeding should be estimated close to 0 and that its inclusion in 251 the model does not lead to poor estimates of other model parameters. However, for both models, 252 the inbreeding parameter was always estimated to be greater than 0. The mean estimates of F for 253 the bottleneck and divergence models were 0.0934 and 0.212, respectively. Nevertheless, despite 254 not estimating an absence of inbreeding, the other model parameters were estimated with only 255 slightly higher levels of error (Figures S13 and S14). For the bottleneck model, bottleneck size and 256 duration had RMSD values of 0.0280 and 0.0268, respectively, which are both higher levels of error 257 than the simulations where inbreeding was truly present. Parameters in the divergence model had 258 RMSDs of 0.0183 for ν_2 , 0.0110 for T, and 0.132 for M_{21} , showing that the two-population model 259 was not strongly affected by the level of inbreeding estimated in population two. 260

261 Empirical Examples

262 American Puma

The American puma (*Puma concolor*) is an iconic carnivore distributed primarily in western North 263 America and South America, occupying a large diversity of habitats across its range. However, in 264 the eastern United States, the only remnant population is the highly endangered Florida panther 265 (Hansen 1992; Culver et al. 2000). Florida panthers have been the subject of large-scale conserva-266 tion efforts aimed at ameliorating the adverse effects of small population size, including moving 267 individuals from their closest sister population, the Texas puma, to introduce novel genetic varia-268 tion (Seal and Lacy 1994; Johnson et al. 2010). Using genomic data from five individuals of Texas 269 pumas and two individuals of 'canonical' Florida panthers from Ochoa et al. (2019), we estimated 270 the demographic history of these two populations to investigate their divergence time, changes 271 in population size, and levels of inbreeding (see cartoon in Figure 3). More specifically, we fit a 272 model that included an initial change in population size to mimic the colonization of North Amer-273 ica by the Texas population (N_{TX}) , the duration of time spent at the new population size (T_1) , the 274 divergence time between Texas pumas and Florida panthers (T_2) , and the inbreeding coefficients 275 for both the Texas and Florida populations (F_{TX} and F_{FL}). 276

After processing (see Methods), 6,262,417 variant sites were retained for constructing the 2D-277 SFS. Because we lacked a suitable outgroup for determining ancestral versus derived allelic states, 278 we used the folded SFS for all model fits. Table 1 lists parameter estimates and their 95% confi-279 dence intervals for models fit with and without inbreeding ($\epsilon = 10^{-2}$) and uncertainty estimates 280 across different step sizes for numerical differentiation using the Godambe Information Matrix 281 (Coffman et al. 2015) are presented in Tables S3 and S4. In both models, the Texas and Florida 282 populations are estimated to have diverged 7,000–8,000 years ago, with both also having similar 283 estimates of the ancestral population size (120,000-130,000 individuals). As expected, the Florida 284 population experienced a severe reduction in population size down to 1,200–1,600 individuals, 285 as well as having a high estimate of F in the model including inbreeding ($F_{FL} = 0.607$). Texas 286

Table 1: Parameter estimates for *Puma concolor* from demographic models estimated both with and without inbreeding. 95% confidence intervals are given in parentheses and were estimated using a step size of $\epsilon = 10^{-2}$ for numerical differentiation. Population sizes are given in number of individuals and divergence time is given in years.

Parameter	Estimate With Inbreeding	Estimate Without Inbreeding
N _A	130,000 (129,000–132,000)	120,000 (92,400–157,000)
N_{TX}	70,800 (63,300–79,200)	23,700 (3,490–161,000)
N_{FL}	1,600 (128–19,100)	1,210 (118–12,500)
T1	247,000 (169,000–359,000)	26,800 (504–1,420,000)
T2	7,820 (650–94,200)	8,230 (784–86,500)
F_{TX}	0.440 (0.408–0.474)	-
F_{FL}	0.607 (0.588–0.626)	_

²⁸⁷ pumas were also inferred to be inbred, though less so than Florida panthers ($F_{TX} = 0.440$). Es-²⁸⁸ timates of population size for the Texas population were different between the models with and ²⁸⁹ without inbreeding (70,800 individuals versus 23,700 individuals) and the duration of the initial ²⁹⁰ population size change (T_1) were especially different as well (247,000 years versus 26,800 years). ²⁹¹ The log-likelihoods for the model with and without inbreeding are -318058.079 and -453003.048, ²⁹² respectively, and the Godambe-adjusted likelihood ratio statistic is 425.489 (p-value = ~0.0; Coff-²⁹³ man *et al.* 2015), demonstrating that the model with inbreeding has a significantly better fit to the

data. In addition, when comparing the predicted SFS from the models with the observed SFS
 (Figure 3), the residuals for the model with inbreeding were lower overall, providing even more

²⁹⁵ (Figure 3), the residuals for the model with inbreeding were lower overall, providing even more ²⁹⁶ support for preferring the model with inbreeding. Uncertainty estimates were also typically more

²⁹⁷ stable across step sizes for the model with inbreeding.

298 Domesticated Cabbage

Brassica oleracea is an agronomically important plant species cultivated primarily in Europe, Asia, 299 and North America (Maggioni 2015). It is especially well-known for its morphological diver-300 sity, having been domesticated into several different crops including broccoli, Brussels sprouts, 301 cauliflower, cabbage, kale, and kohlrabi, among others. The timing and origin of domestication 302 for these different *B. oleracea* crops is still uncertain, but several hypotheses have been proposed to 303 explain their evolutionary history (Maggioni 2015). Cabbage, B. oleracea var. capitata, is thought to 304 have been domesticated roughly 500 years ago in the Mediterranean region (Cheng et al. 2016a,b), 305 providing an interesting hypothesis that we can test using demographic models. 306

To infer the demographic history of domesticated cabbage, we used SNP data from publicly available resequencing data for 45 individuals from Cheng *et al.* (2016a,b). We then fit a demographic model for cabbage domestication that included two changes in population size (N_1 and N_2), the amount of time spent at these population sizes (T_1 and T_2), and the level of inbreeding (F) [see cartoon in Figure 4]. We used 2,941,018 intergenic SNPs to build the folded SFS for *B. oleracea* var. *capitata* and fit models with and without inbreeding. Parameter estimates were obtained us-

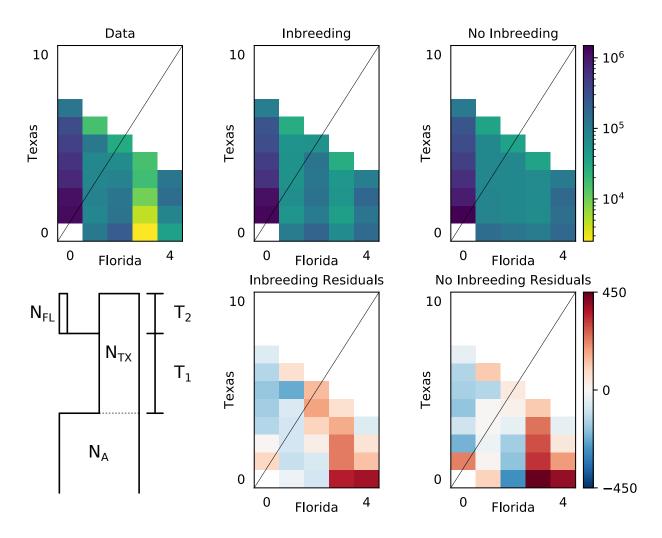


Figure 3: The observed joint site frequency spectrum for *Puma concolor* in Texas and Florida, along with the model fit and residuals, for models with inbreeding (middle) and without inbreeding (right). Residuals for each model are plotted below their expected spectra and a cartoon representation of the proposed demographic model is given in the bottom left.

ing newly implemented optimization routines in the $\partial a \partial i$ library built on top of the nlopt Python package (Johnson 2014). Parameter estimates and their 95% confidence intervals are listed in Table $2 (\epsilon = 10^{-2})$. Uncertainty estimates across different step sizes for numerical differentiation using the Godambe Information Matrix (Coffman *et al.* 2015) are presented in Tables S3 and S4.

Much like the models inferred with and without inbreeding for American pumas, the estimates of demography for cabbage are markedly different between the two analyses. When inbreeding was not modeled, we infer an ancestral population size for cabbage of 19,100 individuals, which expanded to a size of 123,000 individuals ~6,000 years ago. This expanded population then experienced a very recent and severe bottleneck 38 years ago down to a size of 592 individuals. The time estimate for the bottleneck consistently hit the lower bound of the parameter search space, however, suggesting that this estimate is likely not very reliable. Parameter estimates for

Table 2: Parameter estimates for *B. oleracea* var. *capitata* from demographic models estimated both with and without inbreeding. 95% confidence intervals are given in parentheses and were estimated using a step size of $\epsilon = 10^{-2}$ for numerical differentiation. Population sizes are given in number of individuals and times are given in years. Parameters estimated at the upper/lower bound of the given search space are marked with an asterisk (*).

Parameter	Estimate With Inbreeding	Estimate Without Inbreeding
N _A	17,500 (16,900–18,100)	19,100 (18,500–19,800)
N_1	31,600 (28,900–34,700)	123,000 (80,400–190,000)
N_2	215,000 (4,910–9,370,000)	592 (547–641)
T_1	16,600 (12,900–21,200)	5,870 (5,200–6,620)
T_2	322 (94.2–1,097)	38.3 (32.5–45.1)*
F	0.578 (0.557–0.599)	_

the inbreeding model inferred an ancestral population size of 17,500 individuals, which expanded 324 to a size of 31,600 individuals \sim 17,000 years ago. This population then experienced an even larger 325 expansion to a size of 215,000 individuals 322 years ago. The model with inbreeding inferred F 326 to be 0.578, showing that inbreeding in these cabbage samples is fairly high. The log-likelihoods 327 for the model with and without inbreeding were -4281.145 and -24330.403, respectively, and the 328 Godambe-adjusted likelihood ratio statistic was 127.562 (p-value = ~ 0.0 ; Coffman *et al.* 2015). Fig-329 ure 4 also shows the observed and predicted SFS for each model plus their residuals. The residual 330 plots clearly show that the model with inbreeding is able to capture more of the 'zig-zagging' pat-331 tern of the lower frequency variants than the model without inbreeding, demonstrating its overall 332 better fit. Uncertainty estimates were again typically more stable across step sizes for the model 333

³³⁴ with inbreeding.

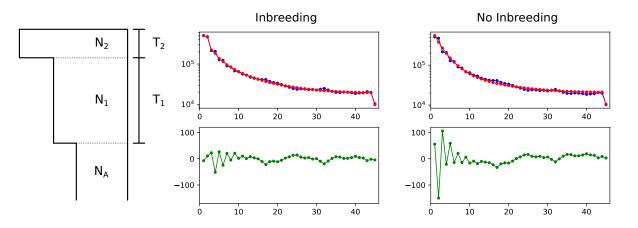


Figure 4: The observed site frequency spectrum for *Brassica oleracea* var. *capitata*, along with the model fit (red) and residuals (bottom panels), for models with inbreeding (middle) and without inbreeding (right). On the left is a cartoon of the proposed demographic model with parameters labeled.

335 Discussion

The prevalence of inbreeding in nature, especially among plant lineages and small and endan-336 gered populations, make it an important process to include in demographic models. Unlike 337 previous approaches that rely on full genome sequences to characterize patterns of identity by 338 descent or the distribution of runs of homozygosity, our model uses the frequency spectrum of 339 biallelic SNPs to infer demography, allowing it to be employed not only in model systems but in 340 organisms that lack a suitable reference genome as well. The impact of inbreeding on the SFS has 341 important consequences for demographic inference, however, a result that is well-demonstrated 342 by our simulations and example analyses. The relationship between inbreeding and population 343 size is especially relevant for understanding inferences of past population dynamics. Below we 344 describe this connection in the context of our simulations and the results of our empirical analyses, 345 drawing on previous theoretical work to help qualify our results. We then discuss the importance 346 of considering how our current model behaves for recent versus sustained inbreeding. 347

³⁴⁸ The Effects of Inbreeding on Estimates of Demography

349 Comparison with SLiM

In our analysis of frequency spectra from SLiM, we found a high level of agreement between the 350 expected SFS from the diffusion approximation and beta-binomial model in $\partial a \partial i$ and the mean 351 SFS from the three models we tested in SLiM. In addition, we were generally able to get accurate 352 estimates for the parameters of the three models, though there was a large amount of variation. 353 Part of this is likely driven by only simulating a 1 Mbp region, which limits the number of SNPs 354 being used to build the SFS. A more important contributor to the variation in parameter estimates 355 is the impact of inbreeding itself on the scaling of population level parameters such as θ . Previous 356 work in both the diffusion (Pollack 1987) and coalescent (Nordborg and Donnelly 1997; Nordborg 357 2000) frameworks have derived the appropriate scaling of population-level parameters for inbred 358 populations. In both cases, the equilibrium θ of a randomly mating population simply needs to be 359 rescaled by 1 + F to obtain the corresponding process with inbreeding (here inbreeding is achieved 360 through selfing). The same rescaling applies to parameters estimated by $\partial a \partial i$ when inbreeding is 36 included, so the appropriate scaling can be achieved by rescaling the affected parameters by 1 + F362 using the estimated value of the inbreeding coefficient. 363

364 Simulations with $\partial a \partial i$

From our more detailed simulation experiments, we were able to characterize several scenarios where inbreeding adversely affects inferences of demography. For the single-population bottleneck model in particular, not accounting for inbreeding had a dramatic impact on the accuracy of estimated population size. The primary reason for this is that inbreeding, much like population growth or contraction, affects the low frequency entries of the SFS in such a way that these factors are likely confounded (Figure 1).

The result of ignoring inbreeding for the two-population divergence with one-way migration model was much less drastic (Figures S10), such that parameter estimates were often nearly as accurate as when we included inbreeding in the model. It should be noted that in this case the highest level of inbreeding was F = 0.5, compared to the highest level in the co-estimating inbreeding simulations (F = 0.9). However, the fact that the results did not show the same pattern of extremely poor parameter inference as the one-population model despite also having a bottleneck was noteworthy. One possible explanation for this is that jointly modeling the demography of the inbred, bottlenecked population with the main, non-inbred population provided more information in the 2D-SFS to estimate parameters. Nevertheless, despite having more overall accuracy than the one-population model, parameter estimates in the two-population model were increasingly underestimated with higher levels of inbreeding, demonstrating its adverse effects even when including a second panmictic species in the model.

The other two simulation experiments, masking rare variants and misspecifying inbreed-383 ing, provide further examples of the extent to which the variants with lowest frequency are con-384 founded with inbreeding in ways that affect demographic inference. Masking the singleton and 385 doubleton entries of the 1D- and 2D-SFS for the bottleneck and divergence models, respectively, 386 had only a small effect on estimates of population size and the timing of demographic events, 387 showing that the signal for these inferences is also contained in the remaining entries of the SFS. 388 However, estimates of gene flow were consistently underestimated in the divergence model, likely 389 due to the fact that the influx of migrant alleles at low frequency were being masked. Simulations 390 that modeled inbreeding when it was absent provide a different view on the inference of inbreed-391 ing and demography. In this case, the inbreeding coefficient was inferred to be ~ 0.1 and ~ 0.2 in 392 the one- and two-population models, respectively, even though there was no inbreeding (Figure 393 S13 and S14). The accuracy of the remaining parameters was fairly high; however, there were 394 instances of certain parameter combinations leading to over- and underestimation of the true pa-395 rameter value. Therefore, to prevent poor estimation of other parameter values, it is advised that 39F inbreeding be included in a model only when there is an observable excess in homozygosity. 397

³⁹⁸ *Results from Empirical Analyses*

The impact of inbreeding on the results of our empirical analyses demonstrate the importance 399 of directly estimating this parameter when inferring demography. Analyses with and without 400 inbreeding provided different estimates of population size and duration for Texas pumas and in-401 fer strikingly different population size changes during the history of domesticated cabbage. In 402 the case of the American puma, our estimates of population divergence time between Texas and 403 Florida, the timing of movement from South America into North America, reductions in popula-404 tion size (especially for the Florida population), and a high level of inbreeding in Florida panthers 405 are all consistent with previous work (Culver et al. 2000; Ochoa et al. 2017, 2019). 406

The demographic history inferred for cabbage provides yet another example of how inbreed-407 ing and population contraction can be confounded since estimates of current population size with-408 out inbreeding were \sim 600 individuals, an unrealistic estimate given the prevalence of cabbage 409 cultivation, as well as the clear discrepancy between model fit and the observed SFS for low fre-410 quency variants (Figure 4). Including inbreeding, however, provides a potentially revealing look 411 into the domestication history of cabbage, especially regarding the signal for the textbook "domes-412 tication bottleneck" (Gaut et al. 2018). The expansion of the ancestral cabbage population \sim 17,000 413 years ago coincides with the end of glaciation in Europe and, in particular, the Mediterranean re-414 gion (Hughes et al. 2006; Clark et al. 2009; Hughes and Woodward 2017). Previous work has also 415 placed the timing of domestication for the cabbage morphotype of *B. oleracea* at approximately 500 416 years ago (Cheng et al. 2016b), which roughly agrees with the date that we estimated for the sec-417 ondary population expansion. This series of population expansions differs quite conspicuously 418 when compared to what is often expected for domesticated species (e.g., severe bottlenecks; Doe-419

⁴²⁰ bley *et al.* 2006; Meyer and Purugganan 2013; Gerbault *et al.* 2014; Gaut *et al.* 2018). Given the ⁴²¹ relatively high inbreeding coefficient estimated for cabbage (F = 0.58), and the fact that ignoring ⁴²² inbreeding led to inferences of a very recent and severe bottleneck, it is possible that past infer-⁴²³ ences of domestication bottlenecks have been partially misled by the occurrence of inbreeding ⁴²⁴ when inferring population dynamics.

425 Short- Versus Long-Term Inbreeding

In a review on the effects of inbreeding, Deborah Charlesworth (2003) discussed the temporal as-426 pects of its impact on genetic diversity, distinguishing between the short-term consequences on 427 patterns of diversity (i.e., excess homozygosity compared to panmixia) versus the long-term ef-428 fects of inbreeding that lead to an overall reduction in the effective size of the population. The 429 method we have introduced here is capable of modeling inbreeding in both categories by not 430 only fitting the physical manifestation of inbreeding in the SFS (i.e., spikiness), but also by being 431 able to appropriately scale the diffusion process to account for the reduction in diversity caused 432 by inbreeding ($\theta_F = \frac{\theta}{1+F}$). The reduction in effective population size, as well as the recombina-433 tion rate, that inbreeding causes has important consequences for the impact of selection and the 434 rate of adaptation in inbred populations (Charlesworth 1992; Hartfield and Glémin 2016; Hart-435 field and Bataillon 2019). Therefore, studies aiming to identify the targets of selection in inbred, 436 non-equilibrium populations must exercise special caution. This is especially relevant for domes-437 ticated species and organisms of conservation concern, whose evolutionary histories can often 438 involve drastic changes in population size. Moving forward, the joint inference of demography, 439 inbreeding, and selection will be an important advance for better understanding their collective 440 contributions to genetic variation, as well as having potentially large consequences on informing 441 decision making in agriculture and the designation of protection status for threatened or endan-442 gered species. 443

444 Materials and Methods

445 Comparison with SLiM

Simulations to validate the expected SFS with inbreeding were conducted using SLiM v3.3 (Haller 446 and Messer 2019). To include inbreeding, we set the selfing rate in SLiM to s = 2F/(1+F), F = 0.1, 447 0.25, 0.5, 0.75, and 0.9, and conducted 50 independent simulations, randomly sampling 25 indi-448 viduals with replacement 100 times for each replicate, for a total of 5000 simulated spectra for each 449 of three models: (1) equilibrium/standard neutral model, (2) bottleneck and growth model, and 450 (3) divergence with one-way migration model (models two and three are depicted in Figure 2). 451 Each simulation used $\theta = 4N_A L \mu = 10,000$, with $N_A = 1000$, $L = 1 \times 10^6$ bp, and $\mu = 2.5 \times 10^{-5}$. 452 We also set the recombination rate, r, equal to the mutation rate. For all models, we simulated 453 10,000 generations of burn-in to allow the ancestral population to reach equilibrium and included 454 selfing from the start of the simulation for models one and two. Individuals were sampled di-455 rectly after this phase for the standard neutral model. For model two, after burn-in, we reduced 456 the population size to 250 individuals and then allowed the population size to recover exponen-457 tially back to 1000 individuals over 400 generations: $N(t) = 250 \times \frac{1000}{250}^{\frac{t}{400}}$. Model three started 458 with an outcrossing equilibrium population, from which we split off a selfing population with a 459 size of 250 individuals. These two populations were then simulated forward for an additional 400 460

generations with the selfing population receiving migrants from the original population at a rate 461 of $m_{21} = 5 \times 10^{-4}$. At the end of each simulation, individual genotype information was exported 462 in variant call format and summarized using a Python script to obtained the SFS (available on 463 GitHub). The expected SFS was then calculated by taking the mean value of each entry of the sim-464 ulated spectra across replicates for each model and each value of the inbreeding coefficient. This 465 simulation routine was also replicated to generate 20 independent data sets for each model across 466 the five levels of inbreeding to infer parameters using $\partial a \partial i$ v2.0.3 (Gutenkunst *et al.* 2009). Models 467 were specified in Python v3.7 using the parameterizations described above and depicted in Fig-468 ure 2. Parameters were estimated for each simulated frequency spectrum using 100 optimization 460 runs initiated from different random starting points. Parameter estimates with the highest log-470 likelihood were then recorded for comparison with the true simulated values using the root mean 471 squared deviation (RMSD). 472

Because inbreeding rescales the effective population size by a factor of 1 + F (Pollack 1987; 473 Nordborg and Donnelly 1997), and $\partial a \partial i$ estimates parameters relative to the ancestral population 474 size, we rescaled parameters in $\partial a \partial i$ in the following ways for the simulations above. For the 475 standard neutral model, we included selfing from the start of the simulation, so for our compari-476 son between SLiM and $\partial a \partial i$ we divided the original θ of 10,000 by 1 + F. For the bottleneck and 477 growth models, the ancestral population was also inbred, so we rescaled θ by again dividing by 478 1 + F. The recovery time for this model was always set to 400 generations in SLiM, which in $\partial a \partial i'$ s 470 units would be equal to $0.2 \times 2N_A$. Because the effective ancestral population size gets smaller 480 as inbreeding increases, we had to account for this by multiplying by a factor of 1 + F. However, 481 when inferring parameters under this model, we have to rescale in the opposite direction by di-482 viding by 1 + F to get the correct estimate for the number of generations relative to the ancestral 483 population size. Finally, for the divergence with one-way migration model, the ancestral pop-484 ulation is not inbred, so the only rescaling that needs to be done is for the size of the diverged 485 selfing population (0.25 N_A in $\partial a \partial i$ units). When comparing the expected SFS between $\partial a \partial i$ and 486 SLiM, we divide 0.25 by 1 + F to get the correct size for the inbred population. When inferring 487 parameters, we instead multiply by 1 + F to recover the original $0.25N_A$. In practice, it should be 488 possible to estimate models assuming an outcrossing ancestral population and including a change 480 in population size to account for the effects of inbreeding. 490

491 Simulations

Simulations to explore a greater breadth of parameters were conducted in Python 3.7 using func-492 tions available in the $\partial a \partial i$ library (v2.0.3). For each simulation experiment, we used the same 493 basic setup for simulating frequency spectra under the two main models that were tested. The 494 two models were (1) a single-population model experiencing a bottleneck of varying size $[0.1N_A,$ 495 $0.25N_A$, $0.5N_A$] followed by exponential growth over different time scales $[0.2N_A, 0.4N_A, 0.6N_A]$ 496 back to the original size and (2) a two-population model where a small subpopulation diverges 407 from the main population at different times in the past $[0.2N_A, 0.4N_A, 0.6N_A]$, going through a 498 bottleneck of different sizes $[0.1N_A, 0.25N_A, 0.5N_A]$ and receiving migrants from the main pop-499 ulation at different rates $[0.25/N_A, 0.5/N_A, 0.75/N_A]$. For the **Co-Estimating Inbreeding and** 500 **Demography** simulations, we generated SFS under a standard neutral model with inbreeding as 501 well. We also used a larger range of inbreeding coefficients for this experiment (F_{IS} =0.1, 0.25, 0.5, 502 0.75, and 0.9). The remaining three simulations that were not focused on estimating inbreeding 503 used a smaller range (F_{IS} =0.1, 0.2, 0.3, 0.4, and 0.5) since optimizations at higher inbreeding levels 504

⁵⁰⁵ generally failed to converge. Each simulation experiment was replicated 20 times, with each repli-

cate having 25 individuals sampled per population and running 50 independent optimizations.

⁵⁰⁷ Site frequency spectra were generated for each replicate by first getting the expected SFS for the

model with the true parameters, followed by scaling the SFS using $\theta = 10,000$ and sampling chro-

mosomes assuming a Poisson distribution (sample() method in the Spectrum class within $\partial a \partial i$). Parameter estimates with the highest log-likelihood were selected from the 50 optimization runs

⁵¹¹ for each replicate.

⁵¹² We evaluated parameter estimates for each experiment (including estimates with SLiM above) ⁵¹³ by comparing the estimated values with the true parameters by calculating the RMSD in R v3.6.1 ⁵¹⁴ using the tidyverse package v1.2.1 (R Core Team 2019; Wickham *et al.* 2019). Plots from R were ⁵¹⁵ generated using ggplot2 v3.2.1 (Wickham 2009). Plots from Python were made using matplotlib ⁵¹⁶ v3.1.1 (Hunter 2007) or plotting functions within the $\partial a \partial i$ library.

517 Empirical Examples

518 American Puma

Genome-wide variant data from Ochoa et al. (2019) were obtained from the authors for five Texas 519 pumas and two Florida panthers in variant call format (VCF). SNPs within annotated genes were 520 removed using bedtools v2.28.0 (Quinlan and Hall 2010), followed by processing with VCFtools 521 v0.1.16 (Danecek et al. 2011) to retain only biallelic SNPs with no missing data. The final data 522 set contained 6,262,417 sites, which we converted from VCF format into $\partial a \partial i$'s 'SNP data format' 523 using a Python script (available on GitHub) for demographic analysis. We then estimated de-524 mographic parameters in $\partial a \partial i$ using 100 independent optimization runs from different random 525 starting points (Gutenkunst et al. 2009). Parameters were converted from estimated ratios of the 526 ancestral population size (N_A) to real units using a mutation rate of $\mu = 2.2 \times 10^{-9}$, a generation 527 time of 3 years, and a sequence length of 2,564,692,624 bp Ochoa et al. (2019). Confidence intervals 528 were estimated using the Godambe Information Matrix with 100 bootstrapped frequency spectra 529 that were constructed by randomly sampling genome scaffolds with replacement until we reached 530 the same number of scaffolds as the original full genome (Coffman *et al.* 2015). The Godambe In-531 formation Matrix uses numerical differentiation to estimate uncertainty and requires a step size 532 (ϵ) to be chosen. The choice of step size should be roughly proportional to the size of the uncer-533 tainty that is being estimated. To evaluate which step size was most appropriate for American 534 pumas, we used the bootstrapped spectra to estimate uncertainties across a range of step sizes: 535 $[10^{-2} - 10^{-7}]$ by factors of 10]. These bootstrapped frequency spectra were also used to conduct 536 a likelihood ratio test between the models with and without inbreeding using the LRT_adjust() 537 method in $\partial a \partial i$ and comparing the test statistic to a weighted sum of χ^2 distributions with zero, 538 one, and two degrees of freedom (Ota *et al.* 2000): $\frac{1}{4}\chi_0^2 + \frac{1}{2}\chi_1^2 + \frac{1}{4}\chi_2^2$. This weighted sum is used 539 because we are testing whether the inbreeding coefficients for the Texas and Florida populations 540 are equal to 0, which is the lower boundary of their parameter space since we are assuming in-541 breeding coefficients cannot be negative. Because of this, the typical normality assumptions used 542 in the construction of the likelihood ratio test do not apply and we must adjust the distribution 543 being used for assessing the significance of the likelihood ratio test statistic (Ota et al. 2000). 544

545 Domesticated Cabbage

⁵⁴⁶ We obtained a VCF file containing SNP calls for 45 cabbage individuals from resequencing data in

Cheng et al. (2016a,b). We then filtered out genic SNPs with bedtools v2.28.0 using gene anno-547 tations from http://www.genoscope.cns.fr/externe/plants/chromosomes.html (Belser et al. 548 2018). Biallelic SNPs containing no missing data were extracted with VCFtools v0.1.16 for a fi-549 nal data set with 2,941,018 variable sites. Demographic parameters were estimated in $\partial a \partial i$ with 550 the BOBYQA algorithm implemented in the nlopt Python package using 100 independent opti-551 mization runs from random starting points (Gutenkunst et al. 2009; Powell 2009; Johnson 2014). 552 Parameters were converted from estimated ratios of the ancestral population size to real units 553 using a mutation rate of $\mu = 1.5 \times 10^{-8}$, a generation time of 1 year, and a sequence length of 554 411,560,319 bp (chromosomes minus genic regions). Confidence intervals were then estimated 555 using the Godambe Information Matrix with 100 bootstrapped frequency spectra that were con-556 structed by randomly sampling 1 Mbp blocks with replacement until the total sequence length 557 was as close as possible to the size of the full genome (528,860,695 bp; Coffman *et al.* 2015). We 558 also repeated the same procedure described above for choosing a step size for numerical differen-559 tiation ($\epsilon \in [10^{-2}, \dots, 10^{-7}]$ by factors of 10]). These bootstrapped frequency spectra were again 560 used to conduct a likelihood ratio test between the models with and without inbreeding using 561 the LRT_adjust() method in $\partial a \partial i$ and comparing the test statistic to a weighted sum of χ^2 dis-562 tributions with zero and one degrees of freedom (see section above for rationale; Ota et al. 2000): 563 $\frac{1}{2}\chi_0^2 + \frac{1}{2}\chi_1^2$. 564

565 Confidence Intervals for Composite Parameters

We used the constants listed above for sequence length (L), mutation rate (μ), and generation time 566 (g) for pumas and domesticated cabbage to convert from the units used by $\partial a \partial i$ to real units of 567 years and individuals. However, in order to estimate confidence intervals for these converted 568 parameters, we need to correctly account for the fact that times and population sizes are products 569 of two estimated parameters (either $\theta \times T_{\partial a\partial i}$ or $\theta \times N_{\partial a\partial i}$): $T_{real} = \frac{2g}{4L\mu}\theta T_{\partial a\partial i}$ and $N_{real} = \frac{1}{4L\mu}\theta N_{\partial a\partial i}$. 570 We do this by propagating the uncertainty in our estimates of each individual parameter into a 571 combined estimate of the standard deviation for the composite parameter. In addition, because 572 our original uncertainty estimates for each parameter were large and led to negative values in our 573 confidence intervals, we instead estimated our uncertainty on a log scale. Taking the log of T_{real} 574 and N_{real} gives us the following expressions for each parameter: 575

$$\log T_{real} = \log \left(\frac{2g}{4L\mu}\right) + \log \theta + \log T_{\partial a \partial i} ,$$
$$\log N_{real} = \log \left(\frac{1}{4L\mu}\right) + \log \theta + \log N_{\partial a \partial i} .$$

⁵⁷⁶ The corresponding expressions for the standard deviations of $\log T_{real}$ and $\log N_{real}$ are then

$$\sigma_{\log T_{real}} = \sqrt{\sigma_{\log \theta}^2 + \sigma_{\log T_{\partial a \partial i}}^2 + 2\sigma_{\log \theta, \log T_{\partial a \partial i}}},$$

$$\sigma_{\log N_{real}} = \sqrt{\sigma_{\log \theta}^2 + \sigma_{\log N_{\partial a \partial i}}^2 + 2\sigma_{\log \theta, \log N_{\partial a \partial i}}},$$

where σ_x^2 , σ_y^2 , and $\sigma_{x,y}$ are the variances and covariance for arbitrary variables x and y. With these new estimates of the standard deviation, we can obtain the log-scaled confidence intervals for T_{real} and N_{real} : log $T_{real} \pm C\sigma_{\log T_{real}}$ and log $N_{real} \pm C\sigma_{\log N_{real}}$. Here C is a constant chosen based on the desired confidence level (e.g., C = 1.96 for 95% confidence intervals). Exponentiating these expressions then gives us our confidence limits on the original scale.

582 Data Availability

The inbreeding model is implemented in the Python package $\partial a \partial i$, which is available on Bitbucket (https://bitbucket.org/gutenkunstlab/dadi). Code for generating and analyzing simulated and empirical data sets from this paper are available on GitHub (https://github.com/ pblischak/inbreeding-sfs). The bbc-shiny/ folder in the GitHub repository also contains a small R Shiny application for plotting the probability mass function of the *n*-fold convolution of beta-binomials with different sample sizes, allele frequencies, and inbreeding coefficients.

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765 Supplemental Tables

ϵ	$\sigma_{\log \nu_{TX}}$	$\sigma_{\log v_{FL}}$	$\sigma_{\log \tau_1}$	$\sigma_{\log \tau_2}$	$\sigma_{\log F_{TX}}$	$\sigma_{\log F_{FL}}$	$\sigma_{\log \theta}$
10^{-2}	0.0604	1.281	0.1961	1.274	0.0385	0.0162	0.0061
10^{-3}	0.0175	0.1738	0.0749	0.1993	0.0171	0.0427	0.0114
	0.0104					0.0425	
10^{-5}	0.0307	0.3501	0.0258	0.3741	0.0248	0.0425	0.0177
10^{-6}	0.0595	0.3819	0.1853	0.4111	0.0330	0.0446	0.0671
10^{-7}	0.0039	0.0086	0.0114	0.0052	0.0184	0.0222	0.0097

Table S1: Log-scale standard deviations for parameters in the model with inbreeding for American pumas across a series of step sizes.

Table S2: Log-scale standard deviations for parameters in the model without inbreeding for American pumas across a series of step sizes.

ϵ	$\sigma_{\log \nu_{TX}}$	$\sigma_{\log v_{FL}}$	$\sigma_{\log \tau_1}$	$\sigma_{\log \tau_2}$	$\sigma_{\log \theta}$
10^{-2}	0.8452	1.057	1.894	1.067	0.1353
10^{-3}	0.0642	0.0312	0.1588	0.0370	0.0160
10^{-4}	0.1603	0.1758	0.3030	0.1818	0.0170
10^{-5}	0.0205	0.0109	0.0410	0.0114	0.0105
10^{-6}	0.0025	0.0079	0.0126	0.0029	0.0103
10^{-7}	5.50e-5	6.69e-5	5.87e-5	1.03e-4	9.76e-3

e			$\sigma_{\log \tau_1}$			
10^{-2}	0.0432	1.913	0.1347	0.6388	0.0184	0.0171
10^{-3}	0.0426	1.953	0.4052	0.8423	0.0187	0.0655
10^{-4}	0.0434	1.411	0.2900	0.5930	0.0189	0.0470
10^{-5}	0.0426	0.7802	0.2784	0.4184	0.0189	0.0453
10^{-6}	0.0582	1.828	0.5530	0.1422	0.0183	0.0920
10 ⁻⁷	0.1664	0.0979	0.1425	0.4607	0.0147	0.0953

Table S3: Log-scale standard deviations for parameters in the model with inbreeding for domesticated cabbage across a series of step sizes.

Table S4: Log-scale uncertainties for parameters in the model without inbreeding for domesticated cabbage across a series of step sizes.

ϵ	$\sigma_{\log \nu_1}$	$\sigma_{\log \nu_2}$	$\sigma_{\log \tau_1}$	$\sigma_{\log \tau_2}$	$\sigma_{\log \theta}$
10^{-2}	0.2236	0.0344	0.0597	0.0856	0.0161
10^{-3}	2.068	4.006	0.5373	3.679	0.0512
10^{-4}	2.596	1.325	0.5685	1.560	0.0438
10^{-5}	3.435	10.57	0.7405	11.32	0.0496
10^{-6}	0.9482	0.1776	0.2459	0.0701	0.0238
10^{-7}	0.0071	0.0077	0.0191	0.0211	0.0179

766 Supplemental Figures

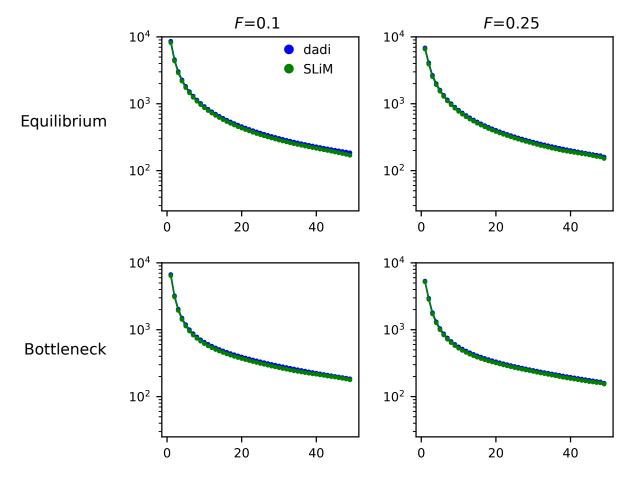
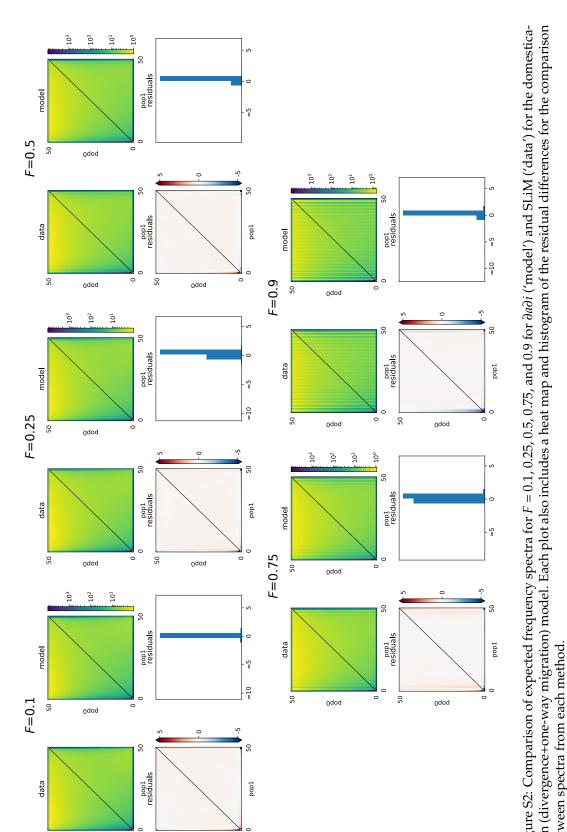


Figure S1: Comparison of expected frequency spectra for F=0.1 and 0.25 for $\partial a \partial i$ (blue) and SLiM (green) for the equilibrium and bottleneck+growth models.





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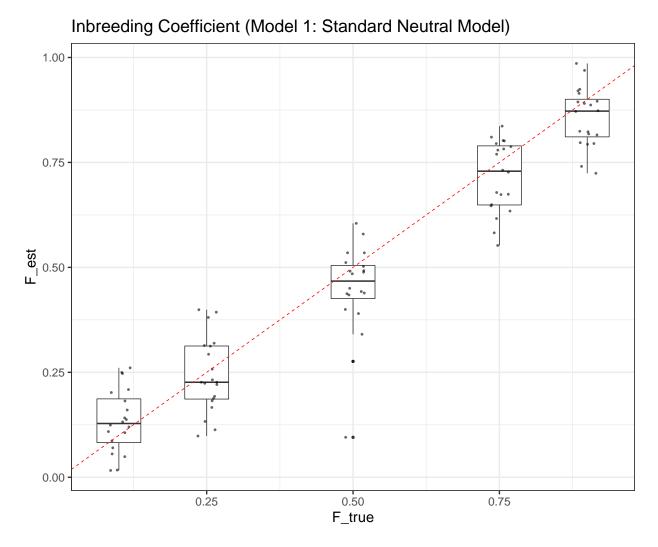


Figure S3: Estimates of the inbreeding coefficient for the equilibrium model generated by SLiM.

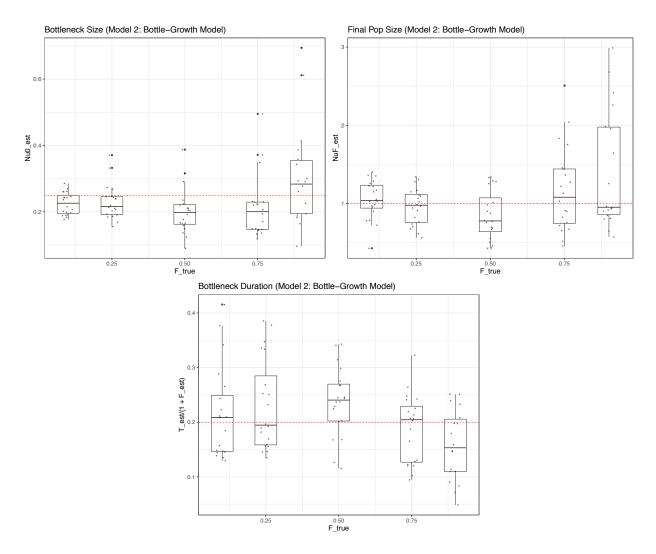


Figure S4: Parameter estimates from $\partial a \partial i$ for data simulated by SLiM for the bottleneck+growth model [bottleneck size (ν_0): top left; final size (ν_F): top right; scaled bottleneck duration ($\frac{\tau}{1+F}$): bottom].

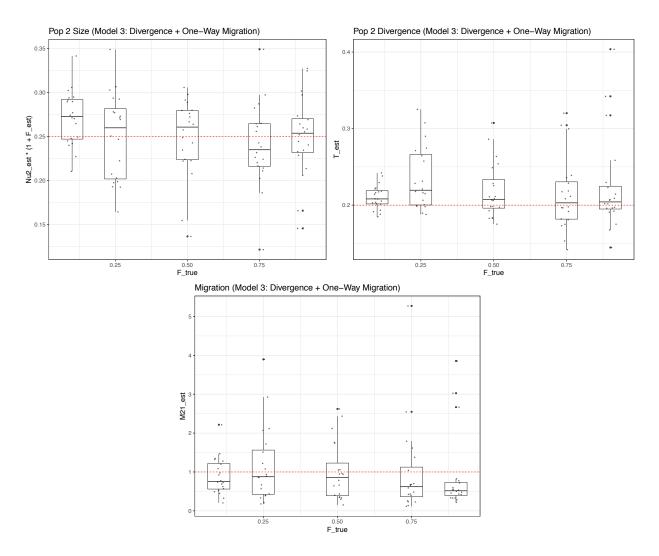
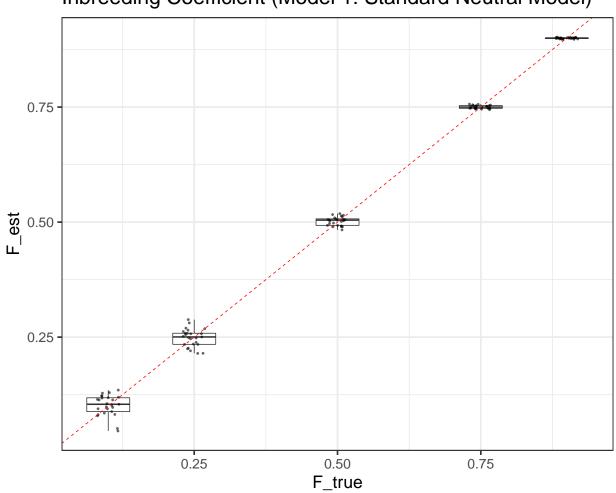
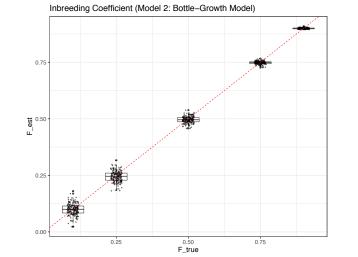


Figure S5: Parameter estimates from $\partial a \partial i$ for data simulated by SLiM for the domestication (divergence+one-way migration) model [scaled size of population two ($\nu_2 \times (1 + F)$): top left; divergence time (τ): top right; migration (M_{21}): bottom].



Inbreeding Coefficient (Model 1: Standard Neutral Model)

Figure S6: Estimates of the inbreeding coefficient for the standard neutral model for data generated by Poisson sampling within $\partial a \partial i$.



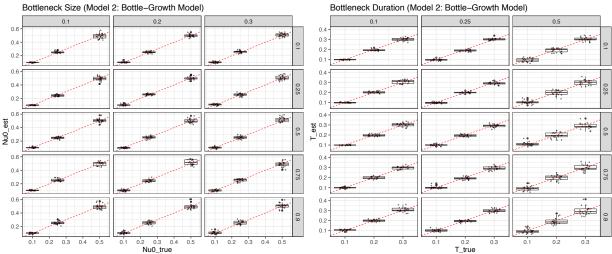


Figure S7: Parameter estimates from $\partial a \partial i$ for data generated by Poisson sampling for the bottleneck+growth model [inbreeding coefficient (*F*=0.1, 0.25, 0.5, 0.75, 0.9): top; bottleneck size (ν_0 =0.1, 0.25, 0.5): bottom left; bottleneck duration (τ =0.1, 0.2, 0.3): bottom right]. Plots for ν_0 and τ are split into rows (true inbreeding coefficient) and column (true simulated parameter value).

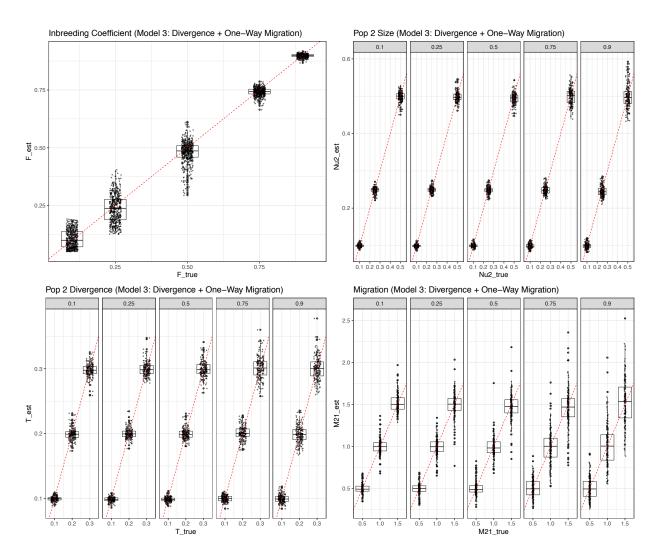


Figure S8: Parameter estimates from $\partial a \partial i$ for data generated by Poisson sampling for the divergence+oneway migration model [inbreeding coefficient (*F*=0.1, 0.25, 0.5, 0.75, 0.9): top left; size of population two (ν_2 =0.1, 0.25, 0.5): top right; divergence time (τ =0.1, 0.2, 0.3): bottom left; migration (M_{21} = 0.5, 1.0, 1.5): bottom right]. Plots for ν_2 , τ , and M_{21} are split into columns for each value of the inbreeding coefficient.

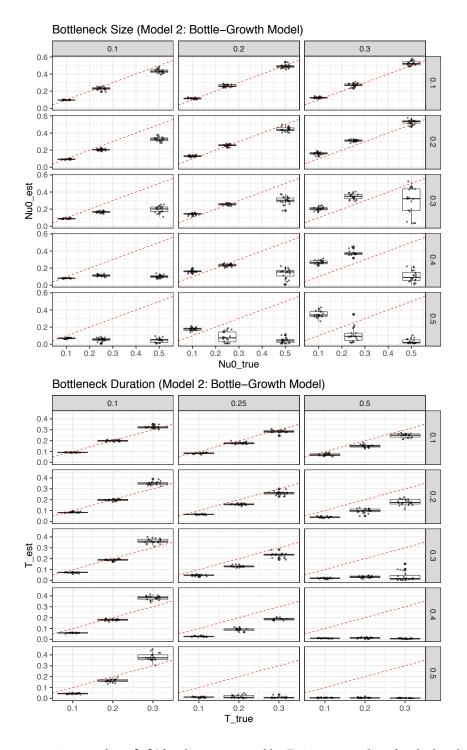


Figure S9: Parameter estimates from $\partial a \partial i$ for data generated by Poisson sampling for the bottleneck+growth model *when inbreeding is ignored* [inbreeding coefficient (*F*=0.1, 0.2, 0.3, 0.4, 0.5): *not estimated*; bottleneck size (ν_0 =0.1, 0.25, 0.5): top; bottleneck duration (τ =0.1, 0.2, 0.3): bottom]. Plots for ν_0 and τ are split into rows (true inbreeding coefficient) and column (true simulated parameter value).

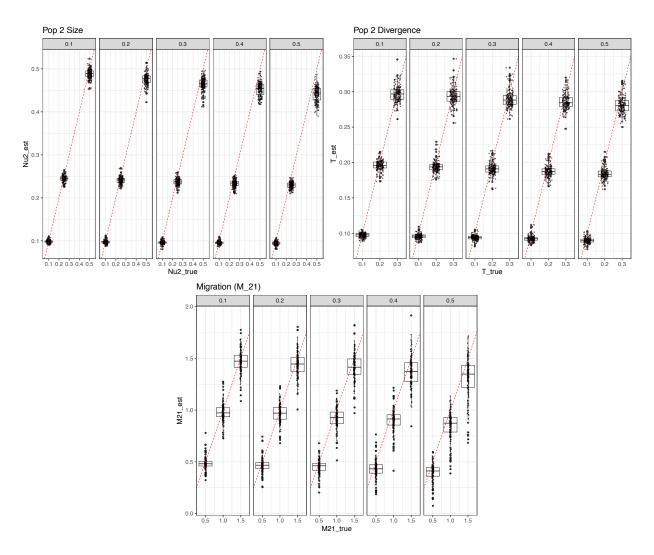


Figure S10: Parameter estimates from $\partial a \partial i$ for data generated by Poisson sampling for the divergence+oneway migration model *when inbreeding is ignored* [inbreeding coefficient (*F*=0.1, 0.2, 0.3, 0.4, 0.5): *not estimated*; size of population two (ν_2 =0.1, 0.25, 0.5): top left; divergence time (τ =0.1, 0.2, 0.3): top right; migration (M_{21} = 0.5, 1.0, 1.5): bottom]. Plots for ν_2 , τ , and M_{21} are split into columns for each value of the inbreeding coefficient.

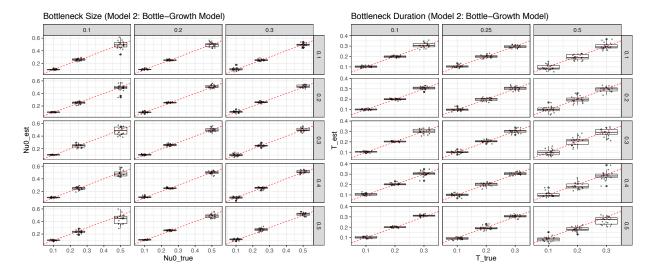


Figure S11: Parameter estimates from $\partial a \partial i$ for data generated by Poisson sampling for the bottleneck+growth model *when rare variants are masked* [inbreeding coefficient (*F*=0.1, 0.2, 0.3, 0.4, 0.5): *not estimated*; bottleneck size (ν_0 =0.1, 0.25, 0.5): left; bottleneck duration (τ =0.1, 0.2, 0.3): right]. Plots for ν_0 and τ are split into rows (true inbreeding coefficient) and column (true simulated parameter value).

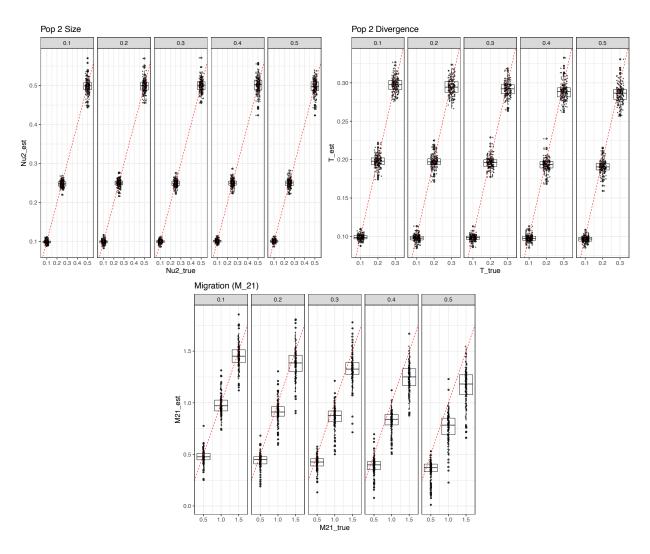


Figure S12: Parameter estimates from $\partial a \partial i$ for data generated by Poisson sampling for the divergence+oneway migration model *when rare variants are masked* [inbreeding coefficient (*F*=0.1, 0.2, 0.3, 0.4, 0.5): *not estimated*; size of population two (ν_2 =0.1, 0.25, 0.5): top left; divergence time (τ =0.1, 0.2, 0.3): top right; migration (M_{21} = 0.5, 1.0, 1.5): bottom]. Plots for ν_2 , τ , and M_{21} are split into columns for each value of the inbreeding coefficient.

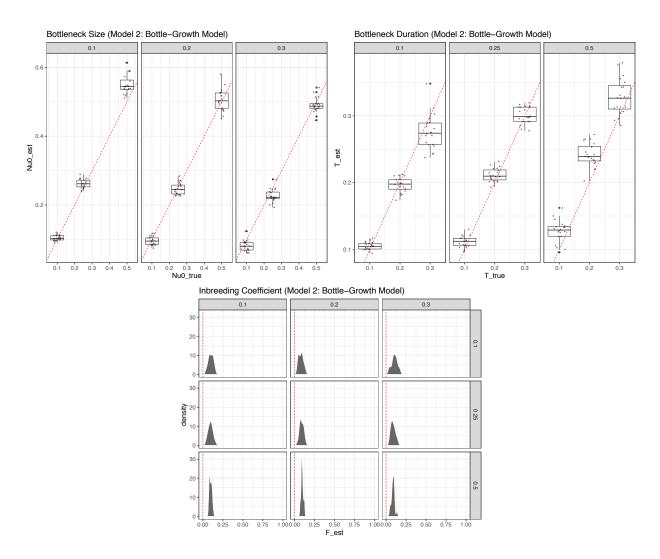


Figure S13: Parameter estimates from $\partial a \partial i$ for data generated by Poisson sampling for the bottleneck+growth model *when inbreeding is absent but is still inferred* [bottleneck size (ν_0 =0.1, 0.25, 0.5): top left; bottleneck duration (τ =0.1, 0.2, 0.3): top right; inbreeding coefficient (*F*=0): bottom]. Plots for ν_0 and τ are split into columns for each value of the other simulated parameter value.

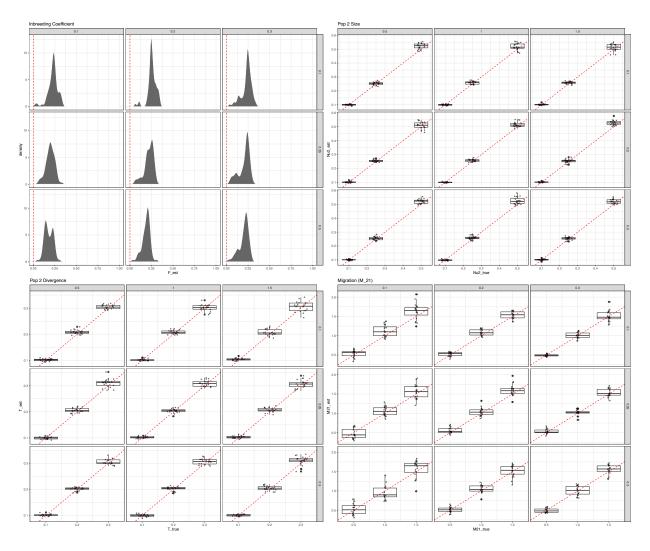


Figure S14: Parameter estimates from $\partial a \partial i$ for data generated by Poisson sampling for the divergence+oneway migration model *when inbreeding is absent but is still inferred* [inbreeding coefficient (*F*=0): top left; size of population two (ν_2 =0.1, 0.25, 0.5): top right; divergence time (τ =0.1, 0.2, 0.3): bottom left; migration (M_{21} = 0.5, 1.0, 1.5): bottom]. Plots for ν_2 , τ , and M_{21} are split into rows and columns for each value of the other two simulated parameters.