Swimming ghosts of the halophilic archaeon, *Haloferax volcanii*

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Y.K. and R.B designed the research. Y.K. performed all experiments and obtained all data; N.M. helped genetics, biochemistry, and preparation of figures; Z.L, F.B., T.EF.Q., C.v.d.D and S.-V. A. helped genetics; R.I helped the ghost experiments; N.M. and R.B helped microscope measurements; Y.K., and R.B. wrote the paper.

Abstract

Archaea swim driven by a membrane-embedded rotary machine, the archaellum. Current understanding

of the archaellar motor complex is limited by the lack of a versatile model system for its experimental

study. Here we establish a membrane permeabilized ghost-cell model which enables control

and quantification of ATP-coupled archaellar rotation. We find a high nucleotide

selectivity for rotation and no cooperativity which is a different characteristic of *in vitro*

studies.

Microorganisms exhibit various types of motilities, such as gliding, swimming, and

twitching, driven by supramolecular motility machinery composed of multiple different

proteins [1]. In archaea, cells swim driven by rotation of an archaellum (archaeal

flagellum) which consists of a torque-generating motor and a helical filament which acts

as a propeller (Fig. 1a) [2]. The archaellum is no homologous to any bacterial flagellum

protein but is evolutionarily and structurally related to bacterial type IV pili for a surface

motility. In Euryarchaeota, the filament encodes in two genes, *flgA (flaA in*

Methanococcus) or *flgB (flaB in Methanococcus)*, and the motor nine *fla*C-K (see Ref. 2

for details in Crenarchaeota). Furthermore, some Euryarchaeota possess chemotactic

proteins, such as CheY for a response regulator and CheF as an archaeal specific adaptor

protein, which might have been acquired by horizontal gene transfer from bacteria [3].

Figure 1a shows the current association of functions with the motor genes, based on

analysis of mutants and biochemical data: FlaC/D/E as switching proteins for the

directional switch of the archaellum rotation coupled with the signals from the chemotaxis

system [4]; FlaG and FlaF as a stator interacting with the surface layer (S-layer) with FlaF

regulating FlaG filament assembly [5, 6]; FlaH regulates the switch between assembly of

the archaella and rotation [2]; FlaI as the ATP-driven motor for both archaella assembly

and rotation [7]; FlaJ is the membrane protein; and FlaK/PibD as the pre-archaellin

peptidase [8]. An inhibitor of proton translocating ATP synthases reduced both

intracellular [ATP] and swimming speed in *Halobacterium salinarum*, suggesting that

archaellar rotation is driven by ATP [9]. However, direct evidence is still lacking, and

reconstituted systems to directly manipulate and investigate the motor complex are also

missing.

Here we present an *in vitro* system for the archaellum, similar to the Triton model for

the eukaryotic flagellum [10] and the permeabilized ghost model for gliding *Mycoplasma*

mobile [11, 12]. We use the halophilic archaeon *Haloferax volcanii* [13]. *Hfx. volcanii*

possesses multiple polar archaella and swims at 2-5 μm s^{-1} at room temperature, with CW

rotation more efficient for propulsion than CCW (Supplementary Result 1 and

Supplementary Movie 1) [14]. We increased the fraction of swimming *Hfx. volcanii* cells

from 20-30 % [13] to 80 % by adding 20 mM $CaCl_2$ (Fig. S1a).

To prepare our experimental model system, we suspended motile cells in buffers

containing 0.15 % sodium cholate and 2.5 mM ATP (Fig. 1c). Fluorescent imaging

revealed that ghosts still possessed archaellar filaments, the cell membrane, and S-layer

(Fig. 1b bottom and Fig. S3). The detergent reduced the refractive index of cells,

indicating permeabilization of the cell membrane and corresponding loss of cytoplasm.

Remarkably, the permeabilized cells still swam (Supplementary Movie 2 and Fig. 1c

lower right). We named them "ghosts," as in similar experiments on *Mycoplasma mobile*

[12]. Fig. 1d shows a typical example of a live swimming cell changing to a ghost, marked

by a sudden change of image density at 8.75 sec. In a solution containing 2.5 mM ATP,

the swimming speed did not change dramatically (Fig. 1e, see Fig. S4a for another

example). Fig. 1f shows histograms of swimming speed before and after adding detergent.

The average and SD were 1.79 $\pm$ 0.38 μm s^{-1} before and 1.55 $\pm$ 0.42 μm s^{-1} after

permeabilization (P = 0.421834>0.05 by *t*-test, ratio 0.93 $\pm$ 0.24, n = 24, Fig. S4b),

indicating that ghosts swim at the same speed as live cells in this, saturating, ATP

concentration. The single speed peak, unlike Fig. S1b, might indicate a lack of CW

rotation in these swimming cells in presence of detergent (Fig. 1f). However, we found it

difficult to track swimming ghosts due to their low contrast, and were not able to

determine the direction of archaellar rotation.

To overcome these difficulties, we established a ghost-bead assay for measuring ATP-

coupled motor rotation (Fig. 2a). We attached cells with biotinylated archaellar filaments

nonspecifically to the cover glass surface, and then introduced streptavidin beads (500

nm or 1000 nm diameter) which attached to the filaments (Supplementary Method and

Results 2). Addition of 0.1 mg ml^{-1} streptavidin (which would crosslink adjacent filaments

in a rotating bundle) did not stop bead rotation, indicating that beads are rotated by a

single motor [15] (Supplementary movie 3). For the preparation of ghosts, live cells

labelled with rotating beads were treated with 0.3 % sodium cholate for less than 30 sec

to permeabilize their cell membrane in a flow chamber, and subsequently the detergent

was replaced with buffer containing ATP (Supplementary movie 4 and Fig. 2b). Motor

rotation was stopped by permeabilization and reactivated by the addition of ATP. Beads

on ghost cells rotated in both directions (see Supplementary Results 3). However, we did

not see any differences in rotation rates under various ATP concentrations and therefore

analyzed speeds collectively. Beads on live cells with CheY deleted showed a reduced

probability of CW rotation: 6% showed some CW rotation during 30s observation,

compared to 37% in the wild-type. Switching was very rare: 15% of wild-type and no

ΔcheY cells switched during 30s recordings (Supplementary table 3). Wild type ghost still

exhibits switching, but the bias and fraction of CW/CCW/switching were slightly

changed, suggesting the chemotaxis system still active, although not entirely. Note that

our finding that archaeal CheY controls CW bias in a motor rotation is inconsistent with

a previous report (see details in Supplementary Result 4) [16].

We then investigated the effect of nucleotides on rotation using 500-nm beads. First, we

checked the nucleotide selectivity of rotation. Previous bulk experiments showed that

purified FlaI could hydrolyze different nucleotide triphosphates (NTPs) at similar rates

[17]. However, the rotational rates of 500 nm beads on ghosts in 10 mM GTP, CTP, and

UTP in ghost experiments were 5-10 times slower than in ATP (Fig. 2c). This suggests

that the motor complex might increase the selectivity of FlaI for nucleotides and/or

prevent extra energy consumption *in vivo* like the endopeptidase Clp (see Fig. 1B in [18]).

Second, we examined the ATP-dependence of rotation of the range of 8 μM to 10 mM

[ATP] (Figure 2d and Supplementary movie 5). Rotation speeds followed simple

Michaelis-Menten kinetics, with V_{max} 7.14 Hz and K_m, 284 μM (n = 452; Fig. 2d red). A

fit with the Langmuir-Hill equation showed no cooperativity in ATP turnover (Hill

coefficient 0.85) consistent with previous measurements of purified FlaI [19]. Finally, we

found that ATP-γ-S, ADP, and ADP+Pi inhibited motor rotation as competitive inhibitors,

showing that the rotation is driven by the hydrolysis of ATP into ADP+ Pi (Supplementary

Results 6). We furthermore examined the effects of detergent, pH, and ion concentration

on rotation (Supplementary Results 7-8).

We then examined ATP-dependent rotation using 1000-nm beads (Supplementary movie

6). Rotation speeds again obeyed simple Michaelis-Menten kinetics, with V_{max}, K_m, and

Hill coefficient estimated to be 2.79 Hz, 161 μM, and 0.79 (n = 189; Fig. 2d blue). We

estimated motor torques of 180.83 ± 43.06 pN nm for live cells (Fig. 2e *top*, n = 72) and

151.10 ± 27.23 pN nm for ghosts at 10 mM [ATP] (Fig. 2e *bottom*, n = 46), using $T =$

$2\pi f\xi$, where f is rotation speed and ξ the viscous drag coefficient of the bead (See

Supplementary Methods). These values are in good agreement with previous

measurements of *Hbt. salinarum* live cells [20]. By contrast we estimated motor torques

approximately 100 pN nm when driving 500-nm beads, suggesting a speed-dependence

of torque in *Hfx. volcanii* motor which is similar to the bacterial flagellar motor [21] but

different from the *Hbt. salinarum* archaellar motor [20] (Supplementary Result 9). We

also observed one instance of a sudden change in the speed of a motor during long-term

observation (Fig. S13), similar to speed changes attributed to load-dependent structural

dynamics of the bacterial flagellar motor [22, 23].

As previously for *Hbt. salinarum* [20], our measured torque requires by conservation of

energy the hydrolysis of ~12 ATP molecules to drive a single rotation of a motor labelled

with a 1000 nm bead. That paper proposed a model of motor rotation driven by multiple

ATP molecules per mechanochemical cycle of the 6-fold FlaI ATPase, to reconcile this

contradiction; however, our ghost data indicate no cooperativity in ATP hydrolysis for

rotation (Fig. 2d). To address this paradox, we need to measure and analyse the stepping

patterns of archaellar rotation. If dwell times between steps show a single or double

exponential distribution, this would be consistent with stochastic reaction kinetics and no

cooperativity, as seen in F_1-ATPase [24]. On the other hand, a coordinated chemical cycle

between dwell and burst phases as seen in bacteriophage φ29 [25] is another possibility.

Our ghost-cell model system will allow us to address the above paradox and understand

the torque generation mechanism at the single-molecule level.

The ghost technique also has the potential for application to other biological systems.

Archaea display chemotactic [3] and cell division machineries [26] acquired by horizontal

gene transfer from bacteria. Although the archaellum and bacterial flagellum are

completely different motility systems, they share common chemotactic proteins. In

principle, the effect of chemotactic proteins from different hosts on motor switching could

be monitored by combing ghost cells and purified proteins. Similarly, our ghost cells offer

the potential to manipulate and study the archaeal cell division machinery as with *in vitro*

ghost models of *Schizosaccharomyces pombe* [27]. Ghost archaea offer the advantages of

both *in vivo* and *vitro* experimental methods, and will allow the exploration of the

universality, diversity, and evolution of biomolecules in microorganisms.

Figure 1 Swimming ghosts

(a) The current model of archaeal motor in Euryarchaeota. Details were described in the main text. (b) Merge image of live cells (*top*) and ghosts (*bottom*) labeled with a streptavidin dylight488 which binds to biotinylated cells. (c) Procedures to observe swimming ghosts. Live cells were permeabilized in a tube, then induced into a flow chamber to observe swimming motility. *Lower middle*: Phase-contrast image. Black arrows indicate ghosts. Scale bar, 10 μm. Lower right: The sequential images with 0.5-s intervals were integrated for 30 sec with the intermittent color code "red → yellow → green → cyan → blue." White arrows indicate trajectories of ghosts. (d) Sequential images of change from a live cell to ghost. Scale bar, 5 μm. (e) Time course of a swimming speed (*v*, triangles) and cell density (circles) of (d). Arrow indicates the time of permeabilization. (f) Histogram of a swimming speed, where the average and SD were 1.79 ± 0.38 μm s^{-1} before permeabilization (live cells) and 1.55 ± 0.42 μm s^{-1} after permeabilization (ghosts), respectively (n = 24).

Figure 2 Visualization of a motor rotation of ghost through a bead rotation attached to an archaellar filament.

(a) The schematics of an experimental setup (*top*) and a phase-contrast image of live cell (*lower left*) and ghost (*lower right*). Scale bar, 5 μm. (b) *Top*: Time course of *y*-trace during ghost preparations, each color section corresponds to *y*-time traces (*lower left*) and Fourier transform analysis (*lower right*). At the blue section, a live cell exhibited a bead rotation, and then motor rotation after treatment with 0.3 % sodium cholate became gradually slow or almost stopped at an orange section. After the addition of ATP, the motor was reactivated and exhibited rotation again. Data from Supplementary movie 4. (c) Rotation rate at 10 mM [NTP]. The average and SD were 6.14 ± 1.48 Hz for ATP (n = 47), 0.69 ± 0.24 Hz for GTP (n = 30), 1.18 ± 0.36 Hz for CTP (n = 32), and 0.99 ± 0.32 Hz for UTP (n = 29), respectively, (d) *Left*: The rotation rate of 500 nm bead (red) and 1000 nm bead (blue) attached to an archaellar filament at different [ATP]s in

solution. The solid lines show a fit with Hill-Langmuir equation $\frac{V_{max} \times [ATP]^n}{K_m{}^n + [ATP]^n}$; where

V_{max}, K_m and n are 7.14 Hz, 284 µM, and 0.85 for 500 nm bead (n = 452), and

2.79 Hz, 161 µM, and 0.79 for 1000 nm bead (n = 189) respectively. Right: The

rotation rate of live cells, where the average and SD were 10.17 ± 2.39 Hz for

500 nm bead (n = 32) and 3.16 ± 1.29 Hz for 1000 nm bead (n = 62). (e)

Histograms of torque using a 1000 nm bead, where the average and SD were

180.83 ± 40.36 pN nm for live cells (*top*, n = 72) 151.10 ± 27.23 pN nm (*bottom*,

n = 46) for ghosts, (*P* = 0.0001<0.05 by *t*-test).

Acknowledgements

We thank Dr. Abhishek Mazumder and Prof. Achillefs Kapanidis for sharing

chemicals, and Dr. Mitsuhiro Sugawa for technical advice in the microscope

measurement. This study was supported in part by a grant from the Funding

Program for the Biotechnology and Biological Sciences Research Council (to

R.M.B), Collaborative Research Center Grant from the Deutsche

Forschungsgemeinschaft (to S-V.A.). Y.K was recipient of the Japan Society for

the Promotion of Science Postdoctoral Fellowship for Research Abroad and the

Uehara Memorial Foundation postdoctoral fellow, and N.M was recipient of the

Yoshida Scholarship Foundation.

Conflict of interest

The authors declare no competing financial interests.

Supplementary methods

Supplementary Results 1-9

Supplementary Figures 1-14

Supplementary Table 1-3

Captions for Supplementary Movies

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