

1 **Similarities in the behaviour of dance followers among**
2 **honey bee species suggest a conserved mechanism of dance**
3 **communication**

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17 **Abstract**

18 Group living organisms rely on intra-group communication to adjust individual and
19 collective behavioural decisions. Complex communication systems are predominantly
20 multimodal and combine modulatory and information bearing signals. The honey bee
21 waggle dance, one of the most elaborate form of communication in invertebrates,
22 stimulates nestmates to search for food and communicates symbolic information
23 about the location of the food source. Previous studies on the dance behaviour in
24 diverse honey bee species demonstrated distinct differences in the combination of
25 visual, auditory, olfactory, and tactile signals produced by the dancer. We now studied
26 the behaviour of the receivers of the dance signals, the dance followers, to explore the
27 significance of the different signals in the communication process. In particular, we
28 ask whether there are differences in the behaviour of dance followers between the 3
29 major Asian honey bee species, *A. florea*, *A. dorsata* and *A. cerana*, and whether these
30 might correlate with the differences in the signals produced by the dancing foragers.
31 Our comparison demonstrates that the behaviour of the dance followers is highly
32 conserved across all 3 species despite the differences in the dance signals. The highest
33 number of followers was present lateral to the dancer throughout the waggle run, and
34 the mean body orientation of the dance followers with respect to the waggle dancer
35 was close to 90° throughout the run for all 3 species. These findings suggest that dance
36 communication might be more conserved than implied by the differences in the
37 signals produced by the dancer. Along with studies in *A. mellifera*, our results indicate
38 that all honey bee species rely on tactile contacts between the dancer and follower to
39 communicate spatial information. The cues and signals that differ between the species
40 may be involved in attracting the followers towards the dancer in the different nest
41 environments.

42

43 **Keywords**

44 *Apis florea*, *Apis cerana*, *Apis dorsata*, waggle dance evolution, spatial information
45 transfer, tactile hypothesis

46 **Introduction**

47 Organisms have evolved various ways to communicate amongst themselves [1].

48 Communication involves indirect cues and direct signals and varies in its complexity
49 [2,3]. Complexity in communication systems correlates with social group complexity
50 [4, but see 5]. Social communication mechanisms consist of multiple signal channels
51 which can be of the same modality, e.g. ant pheromone trails, or different modalities,
52 as in the case of ritualised courtship signals in birds [6,7]. In these communication
53 systems, the different signals are either equally informative, or one of the signals
54 contains the information and the others act as modulators, enhancing the effect or
55 spread of the signal [8]. Finally, environmental factors and plasticity in the signal can
56 lead to divergence in signals across closely related species [9–11].

57 One of the most elaborate types of social communication in invertebrates is the honey
58 bee waggle dance used by foragers returning from profitable food sources to recruit
59 nestmates [12]. The waggle dance motivates foragers to fly out and in addition encodes
60 spatial information about the food source [13,14]. Each waggle dance consists of
61 multiple circuits and one circuit contains two phases; a straight walking phase in
62 which the dancer waggles its abdomen back and forth (the waggle run or the waggle
63 phase) and a circular walking phase which brings the dancer back towards the point of
64 origin of the first phase (the return phase). The duration of the waggle run
65 corresponds to the distance to the food source [12,14]. In *Apis mellifera*, in which
66 foragers dance in the dark on vertical combs, the body orientation of the dancer with
67 respect to the vertical (gravity) axis during the waggle run corresponds to the
68 direction of the food source from the hive with respect to the sun's azimuth [12].
69 Further, the duration of the return phase corresponds to the reward value of the food
70 source as perceived by the forager [15]. For food sources very close to the hive, the
71 dance circuit becomes nearly circular with a very short waggle run [16].

72 Cues and signals from the environment and nestmates can modulate the probability
73 and intensity of dance behaviour [15,17–19]. Interactions with nestmates in the hive
74 inform nectar foragers about the colony food stores and the nectar influx into the
75 colony [18,20–22]. In addition, interactions with other foragers provide information

76 about predation and overcrowding at the food source [23–26]. An individual forager’s
77 dance activity is modulated by the perceived reward value of the food source along
78 with information from these interactions [19]. This in turn drives recruitment to each
79 food source proportional to its relative reward value, which leads to an efficient
80 distribution of the colony’s foraging force [27]. Thus, the waggle dance acts as the
81 primary regulatory mechanism of the colony’s recruitment activity in addition to its
82 role in the efficient spatial distribution of the colony’s foragers.

83 Although extensive research has been done on the honey bee waggle dance behaviour,
84 the mechanism underlying the transfer of spatial information has remained elusive
85 [28,29]. The experimental difficulty lies in determining which of the multiple dances
86 followed is used to obtain information [27] and in tracking whether the follower
87 visited the indicated food source. Moreover, recent studies showed that followers can
88 choose to rely on either the information from the dancer or their own memory [30,31].
89 Currently, there are two major hypotheses on which signals dance followers use to
90 obtain spatial information from the dancer. The “tactile hypothesis” proposes that
91 dance followers use tactile signals, associated with physical contact between the
92 dancer and follower [32,33] or even mechanosensory signals, associated with the air
93 flow caused by a dancer’s vibrating wings [34,35]. The “follow hypothesis” suggests
94 that followers obtain information from dancers by following the path of the dancer
95 from behind [36]. In this case, followers receive the dance information from their own
96 body positions and walking paths to calculate the direction and distance of the food
97 source being advertised. Studies on the mechanism of spatial information transfer in
98 *A. mellifera* offered preliminary evidence for both hypotheses [32,36]. Instead,
99 comparative studies on dance communication including the behaviour of the dance
100 followers in different honey bee species might help to decide the controversy [37].

101 Interestingly, there are characteristic differences between the species in the
102 combination of signals generated by the dancer [37–42]. Dances of the dwarf honey
103 bees (e.g. *A. florea*), which take place on a horizontal surface exposed to the sun,
104 include a conspicuous visual signal (raised abdomens) but no auditory signals [43].
105 The giant honey bees (e.g. *A. laboriosa* and *A. dorsata*) usually dance on the vertical
106 surface of the bee curtain exposed to the sun [41]. Dances of the diurnal *A. laboriosa*

107 are silent [44], whereas those of the crepuscular *A. dorsata* contain auditory signals
108 [45]. All cavity nesting species investigated (e.g. *A. mellifera*, *A. cerana* and *A.*
109 *nigrocincta*), which perform dances in the hive, produce auditory signals [41].
110 However, it is unclear whether these differences in dance signals imply the evolution
111 of different mechanisms for information transfer across the genus or whether the
112 mechanism is the same with the different signals and cues serving to attract followers
113 [46,47].

114 We performed a comparative study to explore the dance follower behaviour of Asian
115 honey bees and to test if possible differences in dance follower behaviour might
116 correlate with differences in the signals and cues produced by the dancer. Parallel
117 changes in the behaviour of the dancer and dance follower would be a strong
118 argument for the evolution of different mechanisms of information transfer across the
119 genus *Apis*. On the other hand, a high degree of similarity in the behaviour of the
120 dance follower would suggest that the major mechanism of information transfer is
121 conserved. Further, we monitored the spatial positions of the followers to obtain
122 evidence for either of the two proposed hypotheses regarding the mechanism of
123 information transfer. If followers arrange themselves towards the side of the dancer,
124 then it is likely that they use tactile cues (“tactile hypothesis”) to obtain information
125 about the food source [32]. In contrast, if followers orient themselves behind the
126 dancer, they are more likely using their own body orientation (“follow hypothesis”) to
127 determine the spatial position of the food source [36].

128 **Methods**

129 **Colonies**

130 Experiments were done with two *A. florea* and *A. cerana* colonies each and one *A.*
131 *dorsata* colony. For *A. florea*, we obtained colonies which were nesting on the
132 National Centre for Biological Sciences (NCBS) campus, Bangalore. The *A. cerana*
133 colonies was obtained from Karnataka Apiaries, Bangalore. For *A. dorsata*, we
134 observed a colony which had made a nest in the Naik Bhavan building adjacent to our
135 experimental location in the University of Agricultural Sciences (UAS), Gandhi Krishi
136 Vignana Kendra (GKVK), Bangalore. The first set of colonies from all 3 species was

137 observed in January - March 2017, and the second *A. cerana* and *A. florea* colony was
138 observed in February - April 2018. The experiments were part of a larger study on
139 dance dialects in Asian honey bees and are described in detail in section 2.2 of Kohl *et*
140 *al.*, 2020 (in preparation). A brief description of the same experimental protocol is
141 provided below.

142 **Experimental Location**

143 Our experiments were performed in the Botanical Garden at GKVK (latitude: 13.07,
144 longitude: 77.57). The garden covers an area of 26 hectares and is home to around
145 2000 plant species including trees and shrubs. This provided dense vegetation cover
146 and hence good optic flow for the foragers (fig S1 a). We obtained a straight line
147 transect of at least 500m from the colony location to train foragers along.

148 **Colony Preparation**

149 We cut the branch holding the *A. florea* colonies and shifted them into a wooden box
150 which had one opening at the top (fig S1 b). This opening was used to record the
151 activity on the crown area of the colony, where most of the recruitment activity
152 happens [43]. In the case of *A. dorsata*, we did not shift the colony from the building
153 where it had made its hive. We used a feeder box (fig S1 c) to train foragers from the
154 colony to the ground first, and then along the transect. Four frame *A. cerana* colonies
155 were housed in a specially constructed box, with glass walls on one side (fig S1 d).
156 This allowed us to observe the waggle dances and the dance follower behaviour in a
157 non-invasive manner and without having to move the colony into a traditional 2
158 frame vertical observation hive.

159 **Distance training**

160 *Apis florea* and *Apis cerana*

161 We used a similar protocol for distance training in *A. florea* and *A. cerana*. We trained
162 foragers to an artificial feeder near the colony filled with sucrose solution scented with
163 star anise (*Illicium verum*) extract. The sucrose concentration at the feeder was
164 adjusted between 1 and 2.5 M depending on the number of foragers visiting our food
165 source. Once 5-10 foragers were trained to the artificial feeder, we shifted it away from
166 the hive, along the transect. At 25 m we individually paint marked foragers at the

167 feeder using Uni POSCA Paint markers (Uni Mitsubishi Pencil, UK). Once all foragers
168 coming to the feeder were marked, the feeder was shifted further along the transect.
169 We recorded the dance activity of the marked foragers for one hour each at 100m,
170 200m, 300m, 400m and 500m using a Sony HDR CX260V Handycam (Sony
171 Corporation, Tokyo). The videos were recorded at 1080p and 50 frames per second and
172 covered the dance floor area (crown area in *A. florea* and the frame facing the glass
173 wall of the box in *A. cerana*).

174 *Apis dorsata*

175 Since the *A. dorsata* colony was on the side of a building, we used a different protocol
176 for training the foragers. First, we got foragers to come to a long rod with a piece of
177 comb filled with sucrose solution which was kept next to the bee curtain. We then
178 transferred these foragers carefully into a feeder box (fig S1 c), closed the box and
179 transported it to an artificial feeder at the ground level. We released the foragers at the
180 feeder and repeated the process till foragers came to the feeder on their own. After
181 this, the same protocol of paint marking, feeder shifts, and video recordings were done
182 as described earlier. We recorded the dance activity of *A. dorsata* foragers at distances
183 of 100m, 200m, 300m and 400m. Since we recorded dances for the *A. dorsata* colony
184 during a time of plentiful flowering, we could not get foragers to come to a feeder
185 further than 400m from the hive. The transect used for *A. dorsata* feeder training was
186 in the opposite direction of the ones used for *A. florea* and *A. cerana* as the colony had
187 nested on a building at the opposite end of the botanical garden.

188 **Video Analysis**

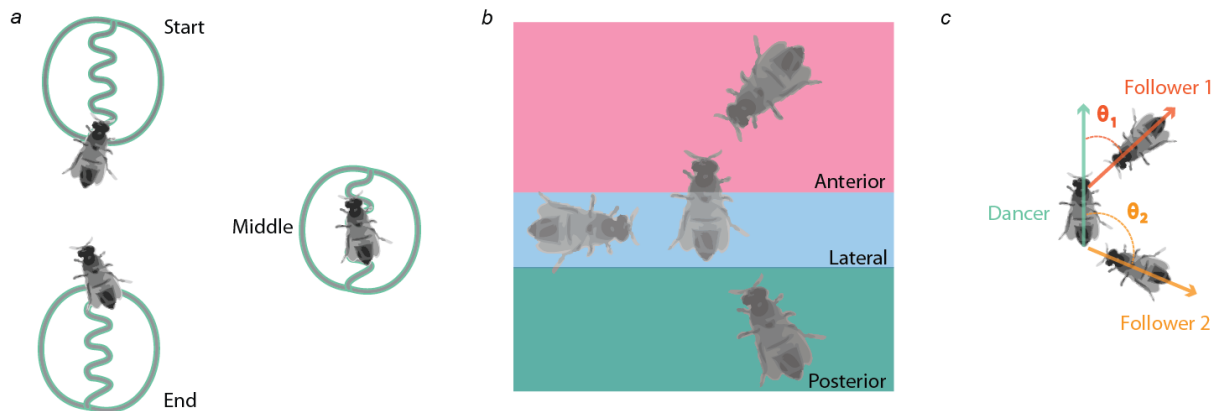
189 For the video analysis, individual foragers were first shortlisted based on whether they
190 were active at the feeder at multiple distances. We then analysed each dance circuit in
191 the dances by these individuals to determine the duration of the waggle run. The
192 videos were observed frame-by-frame in Virtual Dub 1.10.4
193 (<http://www.virtualdub.org>). The first frame in which a focal bee clearly moved its
194 abdomen laterally or dorsoventrally was defined as the start of the waggle run in that
195 circuit. The frame in which the bee stopped wagging its abdomen and started turning

196 to the left or right was defined as the end of the waggle run. The time between the
197 start and the end frames was calculated as the duration of the waggle run.

198 Follower Behaviour

199 We analysed dance follower behaviour for each waggle run in each waggle dance and
200 did not observe the behaviour of dance attendants. Dance followers were defined as
201 those bees which positioned themselves within one bee length of the dancer while we
202 excluded dance attendants, who were beyond this distance threshold and not
203 following the dancer [33]. In each run, we focussed on 3 phases (time-points); the
204 start, middle and end, based on the waggle run duration we had calculated (fig 1 a).
205 This was done to look at whether there was a change in the number of followers as the
206 run progressed [32]. At each time-point, the number of followers present in the
207 following three zones (fig 1 b) around the dancer was counted; the anterior zone
208 around the head region of the dancer, the lateral zone near the thorax and abdomen,
209 and the posterior zone behind the abdomen [32].

210 **Figure 1**



211

212

213 Schematic of the analysis done on the dance followers. (a) Each waggle run was
214 divided into 3 phases, the start, middle and end and the number of followers around
215 the dancer was quantified. (b) Followers around the dancer were grouped into 3 zones
216 (Anterior, Lateral and Posterior) based on the position they occupied around the
217 dancer (area of the zones in the figure are representative). (c) The orientations of the
218 followers were then quantified by obtaining the angle made by a vector representing
219 the follower with respect to the vector representing the dancer in the clockwise
220 direction.

221 The body angles of the follower with respect to the angle of the dancer were also
222 quantified. We used OnScreenProtractor v0.3 (<http://osprotractor.sourceforge.net>), to
223 do this manually. We first used the program to make a vector representing the dancer,
224 pointing in the direction of the dancer's head, away from its abdomen. We then made
225 a similar vector for the follower, but from its head to abdomen. Finally, the body angle
226 of the follower was quantified as the angle subtended by the follower vector with
227 respect to the dancer vector in the clockwise direction (fig 1 c). In total, we calculated
228 5036 follower positions and body angles (from 330 waggle runs of 41 waggle dances) in
229 *A. florea*, 1363 (from 119 waggle runs of 7 waggle dances) in *A. dorsata* and 4989 (from
230 411 waggle runs of 35 waggle dances) in *A. cerana* (table S1). Since followers were not
231 individually identifiable, it is possible that some of the followers we counted were the
232 same across multiple runs and dances.

233 **Statistical Analysis**

234 *Number of Followers*

235 We used a model comparison approach to analyse the variables which affected the
236 number of dance followers. The dataset of the number of followers in each zone
237 during each of the waggle run phase was zero inflated, with 21.17 % (1639 out of 7740)
238 of the observations being zero. To take this into account, we fit zero-inflated Poisson
239 models [48] with bee ID as a random effect. In total, 27 models were built (table S2)
240 with a combination of our 4 predictors for the conditional part of the model: i) zone of
241 dance follower (a categorical variable of 3 levels; Anterior, Lateral and Posterior), ii)
242 phase of waggle run (a categorical variable of 3 levels; Start, Middle and End), iii)
243 species (a categorical variable of 3 levels; *A. florea*, *A. cerana* and *A. dorsata*) and iv)
244 distance (a continuous variable which was scaled with a mean of zero and a standard
245 deviation of 1). For the zero-inflated part of the model, we only included the 3
246 categorical variables. Although we tried to include the same predictors for the zero-
247 inflated part of the model in all 27 models, we had to fit a reduced number of
248 predictors in 5 of them, to prevent errors with model convergence (see table S2). We
249 then compared the models based on their AIC values and shortlisted the models
250 within a cut-off of 0.95 cumulative Akaike weights [49]. The list of predictors, effect
251 sizes and confidence intervals from the shortlisted model(s) was then obtained.

252 Further, we performed multiple comparisons (with Tukey corrections for multiple
253 comparisons) of the estimated mean number of followers. We focussed on: i)
254 comparison between the 3 species, ii) comparisons between the different zones within
255 each waggle run phase and iii) comparisons between the same zones across the waggle
256 run phases. We did these specific comparisons as in our shortlisted model, the
257 important predictors were the species and an interaction term between the waggle run
258 phase and the zone of the follower (table S2 and S3).

259 *Orientation of followers*

260 We used circular statistics to analyse the orientation of the dance followers. We first
261 constrained the body angles of all the dance followers to lie between 0° and 180° , by
262 converting all the angles greater than 180° to their mirror images in the $0^\circ - 180^\circ$ range
263 (e.g., 210° was converted to 150° , 270° to 90° and 300° to 60°). We based this on the
264 assumption that occupying either the left or the right side of the dancer provided
265 similar access to information for the follower. In addition, this prevented us from
266 obtaining biased estimates of the circular mean and length due to potential bimodality
267 in the circular distributions to the left and the right of the dancer. We focussed the
268 statistical analysis on the median orientation of the dance follower in each of the three
269 waggle run phases within each species. First, we checked whether the circular
270 distribution of the dance follower orientation angles during each phase for each
271 species showed uniformity using the Rayleigh test for unimodal departures from
272 uniformity [50]. Then we checked whether the distributions showed reflective
273 symmetry [51]. Finally, we used Fishers Circular Nonparametric test to compare the
274 median angles of the circular distributions [52,53]. We compared the circular
275 distributions for each of the 3 pairs of the waggle run phase to determine which were
276 different from each other (Start – Middle, Start – End and Middle – End).

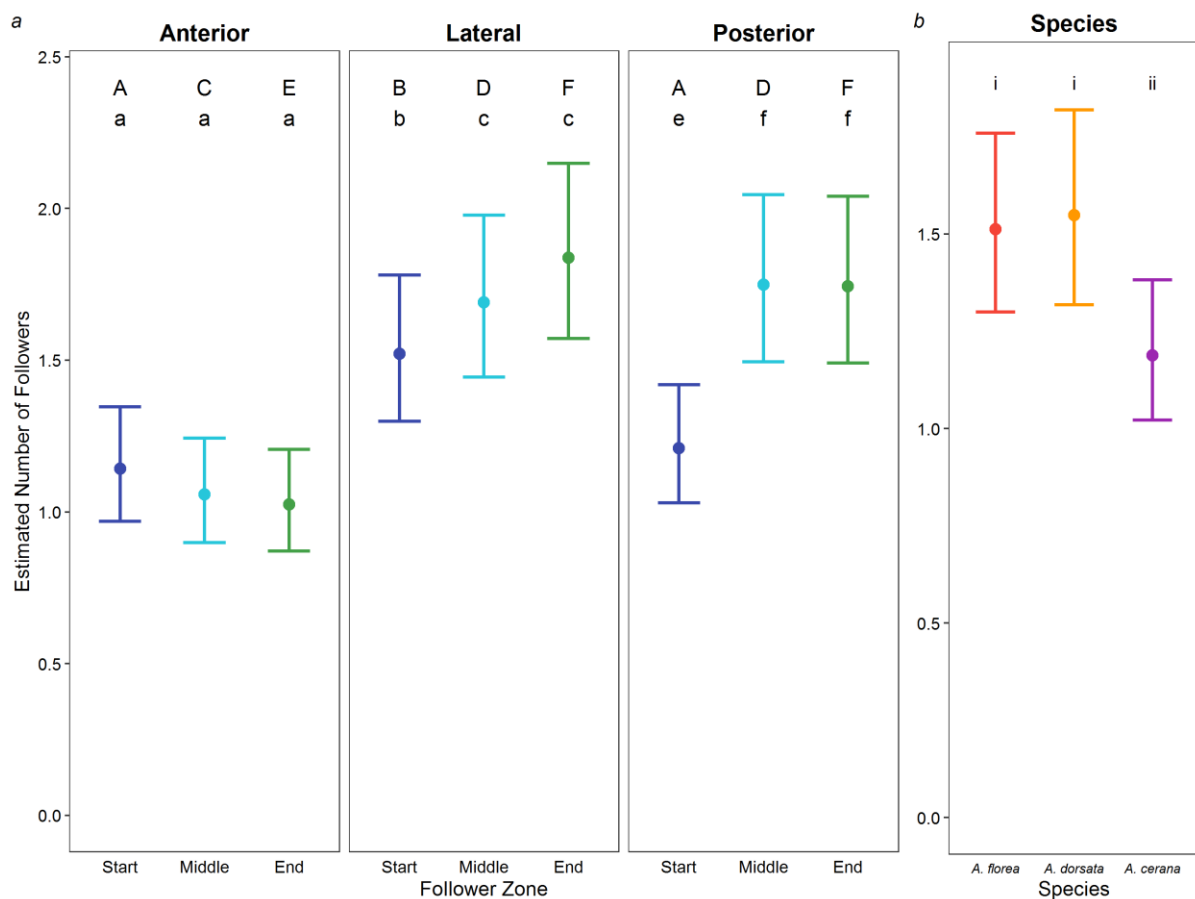
277 All the models and the plots were made in R [54] using the RStudio IDE [55]. The
278 GLMMs were fit using the glmmTMB package [56], model selection and averaging
279 were done using the MuMIn package [57] and the model assumptions were checked
280 using the DHARMA package [58]. Multiple comparisons were done using the emmeans
281 package [59]. Circular statistics were done using the circular package [60] and code
282 found in Pewsey et al. 2013.

283 Results

284 Number of Followers

285 We found only one model at the 0.95 cut-off level for cumulative sum of Akaike
286 weights based on our model comparisons (table S3). In this model, the important
287 predictors were the species and an interaction between the waggle run phase and the
288 zone of the follower, but not the distance (table S4). In the zero-inflated part of this
289 model, none of the predictors significantly correlated with the number of absences
290 (i.e., in the number of observations where there were no followers), and these results
291 are provided in the supplementary information (table S4).

292 Figure 2



293

294 Estimated number of followers and the 95% confidence intervals (circles and error
295 bars) for the different predictors present in the conditional part of the final shortlisted
296 model (model 18, see Tables 2 and 3). (a) Waggle run phase and the zone of the
297 follower had an interactive effect on the number of followers. The number of followers
298 in the anterior zone were similar throughout the waggle run. The number of followers
299 in the lateral zone showed an increasing trend, with significantly higher numbers than
300 the other two zones in the start of the run. The number of followers in the posterior

301 zone was similar to the number of followers in the anterior at the beginning of the run
302 but increased to numbers similar to the lateral zone in the middle and the end of the
303 run. The circles and error bars are coloured according to the waggle run phase with
304 blue representing the start, cyan representing the middle and green representing the
305 end of the waggle run. The alphabets above each circle represents results from the
306 multiple comparisons done (estimates with different alphabets were significantly
307 different from each other at the $p < 0.05$ level). Upper case alphabets represent
308 differences in the number of followers present in the same waggle run phase across
309 zones. Lower case alphabets represent differences in the number of followers present
310 in the same zone across different waggle run phases. (b) The species had an effect on
311 the number of followers present in the waggle run. The number of followers per run
312 for *A. florea* and *A. dorsata* were much higher than the number of followers for *A.*
313 *cerana* (different roman numerals above the estimates represent significant differences
314 at the $p < 0.05$ level). The circles and error bars are coloured according to the species,
315 with red for *A. florea*, orange for *A. dorsata* and purple for *A. cerana*.

316

317 *Effect of species*

318 The species had an effect on the number of followers in the conditional model, but
319 this effect was the same across the different zones, species and distance, i.e., there was
320 no interaction between species and any of the other predictors (table S4 and fig 2 and
321 S2). There were fewer followers per run in *A. cerana* as compared to both *A. florea* and
322 *A. dorsata* (*A. cerana* vs *A. florea*: estimated mean number of followers = 1.188 vs 1.512, t
323 ratio = 10.705, $p < 0.001$; *A. cerana* vs *A. dorsata*: estimated mean = 1.188 vs 1.549, t
324 ratio = 7.082, $p < 0.001$). The number of followers in *A. florea* and *A. dorsata* were not
325 significantly different (*A. florea* vs *A. dorsata*: estimated mean = 1.512 vs 1.549, t ratio = -
326 0.621, $p = 0.809$).

327 *Effect of waggle run phase and zone of the followers*

328 The waggle run phase and the zone around the dancer had an interactive effect on the
329 number of followers in the conditional model and hence their main effects are not
330 considered (table S4 and fig 2 and S2). Within each waggle run phase, there were
331 differences in the number of followers in the different zones. At the Start of the waggle
332 run, there were more followers in the lateral zone as compared to both the anterior
333 and the posterior zone (Anterior vs Lateral: estimated mean number of followers =
334 1.142 vs 1.521, t ratio = -6.360, $p < 0.001$; Lateral vs Posterior: estimated mean = 1.521 vs
335 1.209, t ratio = 5.578, $p < 0.001$). The number of followers in the anterior and posterior

336 zone were similar (Anterior vs Posterior: estimated mean = 1.142 vs 1.209, t ratio = -
337 1.213, $p = 0.446$).

338 In the middle of the waggle run phase, there were fewer followers in the anterior zone
339 as compared to both the lateral and the posterior zone (Anterior vs Lateral: estimated
340 mean = 1.057 vs 1.690, t ratio = -11.226, $p < 0.001$; Anterior vs Posterior: estimated mean
341 = 1.057 vs 1.748, t ratio = -12.110, $p < 0.001$). The number of followers in the lateral and
342 posterior zone were similar (Lateral vs Posterior: estimated mean = 1.690 vs 1.748, t
343 ratio = -0.927, $p = 0.623$).

344 In the end of the waggle run phase, there were fewer followers in the anterior zone as
345 compared to both the lateral and the posterior zone (Anterior vs Lateral: estimated
346 mean = 1.025 vs 1.838, t ratio = -14.046, $p < 0.001$; Anterior vs Posterior: estimated mean
347 = 1.025 vs 1.743, t ratio = -12.656, $p < 0.001$). The number of followers in the lateral and
348 the posterior zone were similar (Lateral vs Posterior: estimated mean = 1.838 vs 1.743, t
349 ratio = 1.478, $p = 0.301$).

350 There were differences between each zone in the number of followers across the
351 waggle run phase. In the Anterior zone, there were similar number of followers in all 3
352 phases of the waggle run (Start vs Middle: estimated mean = 1.142 vs 1.057, t ratio =
353 1.597, $p = 0.247$; Start vs End: estimated mean = 1.142 vs 1.025, t ratio = 2.212, $p = 0.069$;
354 Middle vs End: estimated mean = 1.057 vs 1.025, t ratio = 0.654, $p = 0.790$).

355 In the Lateral zone, the number of followers increased as the waggle run progressed.
356 There were fewer followers in the Start of the run as compared to both the Middle and
357 the End (Start vs Middle: estimated mean = 1.521 vs 1.690, t ratio = -2.802, $p = 0.014$;
358 Start vs End: estimated mean = 1.521 vs 1.838, t ratio = -5.125, $p < 0.001$). Although there
359 was an increase in the number of followers from the Middle to the End of the waggle
360 run, this difference was non-significant (Middle vs End: estimated mean = 1.690 vs
361 1.838, t ratio = -2.333, $p = 0.051$).

362 In the Posterior zone, the number of followers changed with the waggle run phase
363 There were fewer followers in the Start of the run as compared to both the Middle and
364 the End (Start vs Middle: estimated mean = 1.209 vs 1.748, t ratio = -9.24, $p < 0.001$;
365 Start vs End: estimated mean = 1.209 vs 1.743, t ratio = -9.169, $p < 0.001$). There were no

366 significant differences in the number of followers between the Middle and the End of
 367 the waggle run (Middle vs End: estimated mean = 1.748 vs 1.743, t ratio = 0.072, $p =$
 368 0.997).

369 *Effect of distance*

370 Distance had no effect on the number of followers (fig S3). Distance was not a
 371 predictor that was present in the short-listed models (table S4). Thus, the main effects
 372 of the waggle run phase and the interactive effects of zone and species were similar
 373 across all distances.

374 **Orientation of followers**

375 The species differed in the change of the median circular orientation of the dance
 376 followers from the start to the end of the waggle run, even though all the median
 377 orientations were close to 90° (table 1, fig 3 and S4).

378 *Apis florea*

379 The mean of the circular distribution for the dance follower angles during each of the
 380 3 phases in *A. florea* were all close to 90° (mean (95 % confidence interval) - Start:
 381 88.293 (85.2671 - 91.3188); Middle: 105.152 (102.449 - 107.8549); End: 98.2651 (95.5425 -
 382 100.9876); see table 1, fig 3 and S4). None of the 3 circular distributions were uniform
 383 (Rayleigh test statistic - Start: 0.668, $p < 0.001$; Middle: 0.669, $p < 0.001$; End: 0.656, $p <$
 384 0.001) or reflectively symmetric (test statistic - Start: 2.879, $p = 0.004$; Middle: 8.557, $p <$
 385 0.001; End: 4.529, $p < 0.001$). The medians of the 3 circular distributions were
 386 significantly different from each other (median - Start: 86.69; Middle: 108.43; End:
 387 100.33; Fisher test statistic - Start vs Middle: 58.898, $p < 0.001$; Start vs End: 25.878, $p <$
 388 0.001; Middle vs End: 10.109, $p = 0.001$).

389 **Table 1**

Species	Waggle Run Phase	μ (CI)	ρ (CI)	β_2 (CI)	$\bar{\alpha}_2$ (CI)	Median
<i>Apis florea</i>	Start	88.293 (85.2671 - 91.3188)	0.6676 (0.6834 - 0.6518)	87.466 (85.7509 - 89.1812)	85.6183 (83.4845 - 87.752)	86.69
	Middle	105.152 (102.449 - 107.8549)	0.6688 (0.6836 - 0.654)	96.8049 (95.282 - 98.3277)	84.6392 (82.6064 - 86.6719)	108.43

	<i>End</i>	<i>98.2651</i> (95.5425 - 100.9876)	<i>0.6561</i> (0.6703 - 0.6419)	<i>93.662</i> (92.0888 - 95.2352)	<i>86.8135</i> (84.9144 - 88.7126)	<i>100.33</i>
<i>Apis dorsata</i>	Start	85.6489 (80.1198 - 91.178)	0.6755 (0.7044 - 0.6466)	0	84.8189 (80.9594 - 88.6785)	86.36
	Middle	89.3173 (84.1632 - 94.4714)	0.6701 (0.6973 - 0.6428)	0	85.1766 (81.5321 - 88.821)	91.925
	End	92.2348 (86.8583 - 97.6112)	0.6576 (0.6858 - 0.6293)	0	86.5634 (82.8405 - 90.2862)	90.665
<i>Apis cerana</i>	Start	<i>83.3729</i> (80.3027 - 86.4432)	<i>0.6471</i> (0.6626 - 0.6316)	<i>85.7728</i> (83.9274 - 87.6182)	<i>88.2383</i> (86.1242 - 90.3524)	<i>79.555</i>
	Middle	<i>94.5799</i> (91.966 - 97.1939)	<i>0.6858</i> (0.6999 - 0.6718)	<i>91.4155</i> (90.0163 - 92.8147)	<i>83.1709</i> (81.2688 - 85.0729)	<i>94.075</i>
	End	<i>100.9708</i> (98.2417 - 103.6999)	<i>0.6695</i> (0.6842 - 0.6548)	<i>94.9577</i> (93.4502 - 96.4652)	<i>84.8524</i> (82.8413 - 86.8636)	<i>104.4</i>

390

391 List of circular summary statistics for the dance follower angles in each of the 3 waggle
 392 run phase for each of the 3 species. The mean direction (μ), mean resultant length (ρ),
 393 second central sine movement (β_2), second central cosine movement (α_2) along with
 394 the estimated 95% confidence intervals is provided. In addition, the median of the
 395 circular distribution is also provided. The circular distributions for each of the 3
 396 phases for *A. dorsata* showed reflective symmetry and hence the central sine
 397 movements are set to 0. The waggle run phases within each species which significantly
 398 differed in their medians at the $p < 0.05$ level are highlighted in italics.

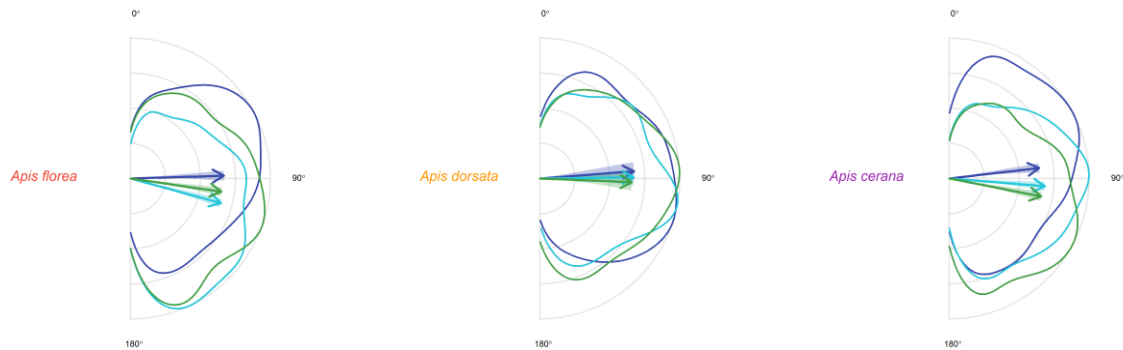
399

400 *Apis dorsata*

401 The mean of the circular distribution for the dance follower angles during each of the
 402 3 phases in *A. dorsata* were all close to 90° (mean and 95 % confidence interval - Start:
 403 85.6489 (80.1198 - 91.178); Middle: 89.3173 (84.1632 - 94.4714); End: 92.2348 (86.8583 -
 404 97.6112); see table 1, fig 3 and S4). None of the 3 circular distributions were uniform
 405 (Rayleigh test statistic - Start: 0.676, $p < 0.001$; Middle: 0.671, $p < 0.001$; End: 0.658, $p <$
 406 0.001) but all of them were reflectively symmetric (test statistic - Start: 0.107, $p = 0.915$;
 407 Middle: 0.193, $p = 0.847$; End: 0.105, $p = 0.916$). The medians of the 3 circular
 408 distributions did not significantly differ from each other (median - Start: 86.36;

409 Middle: 91.92; End: 90.66; Fisher test statistic – Start vs Middle: 0.404, $p = 0.525$; Start
410 vs End: 0.194, $p = 0.659$; Middle vs End: 0.017, $p = 0.896$).

411 **Figure 3**



412

413 Relative circular density plots of the constrained dance follower angle for each of the
414 different wagggle run phase for (a) *A. florea*, (b) *A. dorsata* and (c) *A. cerana*. The
415 relative circular density is obtained by normalising the density in each bin to the
416 highest density value, such that the relative circular density for each bin lies within 0
417 and 1. The arrows in the plot represent the mean of the constrained circular
418 distribution with the shaded region around the arrow representing the 95%
419 confidence interval. The length of the arrow corresponds to the mean resultant length
420 of the distribution (ρ). The lines representing the density plot as well as the arrows are
421 coloured based on the wagggle run phase, with blue representing the start, cyan
422 representing the middle and green representing the end of the wagggle run.

423

424 *Apis cerana*

425 The mean of the circular distribution for the dance follower angles during each of the
426 3 phases in *A. cerana* were all close to 90° (mean and 95 % confidence interval - Start:
427 83.3729 (80.3027 - 86.4432); Middle: 94.5799 (91.966 - 97.1939); End: 100.9708 (98.2417
428 - 103.6999); see table 1, fig 3 and S4). None of the 3 circular distributions were uniform
429 (Rayleigh test statistic – Start: 0.647, $p < 0.001$; Middle: 0.686, $p < 0.001$; End: 0.669, $p <$
430 0.001) or reflectively symmetric (test statistic – Start: 4.449, $p < 0.001$; Middle: 1.978, p
431 = 0.048; End: 6.358, $p < 0.001$). The medians of the 3 circular distributions were
432 significantly different from each other (median – Start: 79.55; Middle: 94.07; End:
433 104.4; Fisher test statistic – Start vs Middle: 24.725, $p < 0.001$; Start vs End: 61.418, $p <$
434 0.001; Middle vs End: 17.150, $p = 0.001$).

435 Discussion

436 The results of our study demonstrate that dance followers in three Asian honey bee
437 species, *A. florea*, *A. dorsata* and *A. cerana* behave similarly throughout the waggle
438 run. At the start of the run, most followers positioned themselves laterally to the
439 dancer. Then, in the middle and the end of the run, the number of followers in the
440 lateral and posterior positions around the dancer was similar. Further, in all three
441 species, the mean orientation of the dance follower was close to 90° throughout the
442 waggle run. The species differed in the number of followers per run. Dances by *A.*
443 *florea* and *A. dorsata* foragers attracted larger number of followers than those by *A.*
444 *cerana* foragers. The distance of the food source, and hence the duration of the waggle
445 phase had no effect on the average number of followers present per waggle run in all 3
446 species.

447 The waggle run is hypothesized to represent a ritualization of the initiation of flight
448 towards the food source [37–39,42]. In the open nesting and phylogenetically ancestral
449 honey bee *A. florea*, dances are indeed oriented in direction of the food source and
450 there is no transposition of the direction information to a vertical plane, unlike in the
451 giant and cavity nesting honey bees [43]. With respect to these two traits, one would
452 predict that there should be strong differences in the dance follower behaviour
453 between *A. florea* and the other species. Specifically, dance followers should align
454 themselves behind the dancers as this would allow them to most easily obtain the
455 direction of the food source. However, in contrast to these two predictions *A. florea*
456 dance followers neither aligned themselves behind the dancer nor showed any other
457 major differences in their behavior in comparison with followers in the other species'.
458 This finding supports the idea of an evolutionarily conserved mechanism of spatial
459 information transfer in the dance behavior in all honey bees species [for *A. mellifera*,
460 see 34].

461 Regarding the question of which sensory signals the dance followers use to obtain the
462 spatial information of the dance, our results provide two arguments for the “tactile
463 hypothesis”. The first is the higher number of followers in the lateral positions around
464 the dancer throughout the run, which is similar to the pattern observed in *A. mellifera*
465 [28,32,61]. The second line of evidence comes from the median body angle of the

466 dance followers, which was close to 90° throughout the waggle run for all 3 species.
467 Thus, followers preferred arranging themselves perpendicular to the dancer, likely
468 using the same signals associated with this position, to obtain the spatial information
469 in all 3 species.

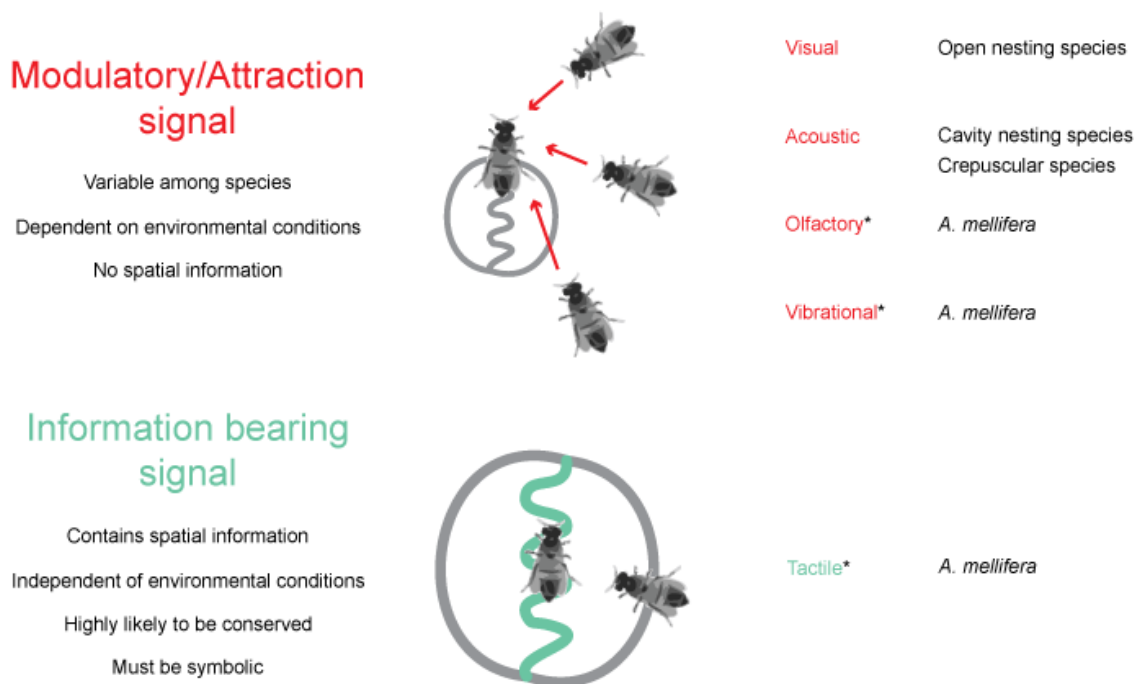
470 Regarding the “follow hypothesis”, the pattern of the number of followers in the
471 posterior position seen in our study provides an argument against it. The number of
472 followers in the posterior position at the start of the run was not significantly different
473 from the number of followers in the anterior position and was lower than the number
474 of followers in the lateral position. Since the entire run encodes spatial information,
475 the number of followers in the posterior position should have been high throughout
476 the dance if following from this position was important for the information transfer.
477 Similar to previous studies, the number of followers in the posterior position increased
478 as the run progressed [32,62], certainly a direct consequence of the dancers forward
479 movement during the run [32,61]. As the dancer moves forward, followers are shifted
480 from the lateral to the posterior position. However, there was no decrease in the
481 number of followers in the lateral position in the middle and the end of the waggle run
482 in our observations. This suggests that either some of the followers are able to actively
483 maintain their lateral positions or that vacated positions to the lateral side of the
484 dancer are immediately occupied. Both possibilities would support the idea that the
485 lateral position is more important than the posterior.

486 If the “tactile hypothesis” is correct, tactile cues associated with the lateral position
487 around the dancer are the mechanism by which spatial information is transferred
488 during the waggle dance. Dance followers who are laterally positioned experience a
489 regular pattern of antennal deflections which correlate strongly with the number of
490 abdomen waggles [32,62,63]. Since the frequency of waggling of the abdomen is
491 physically constrained to be similar amongst bees of the same species [64], followers
492 can use this to estimate the duration of the waggle phase. At the same time, the dance
493 followers can obtain the orientation of the waggle run by using their own body
494 position with respect to gravity as a reference. The Johnston’s organ may play a major
495 role in sensing information about the direction of the waggle phase and hence the
496 direction of the food source [65–67]. The similarity in dance follower behaviour across

497 four species of the genus *Apis* [this study, 34] suggests that the mechanism of spatial
498 information transfer in the waggle dance is likely through these tactile cues.

499 To further substantiate the “tactile hypothesis”, detailed high-speed video recordings
500 of the antennal contacts between the dancers and the followers in all 3 species during
501 the waggle run would be needed. In addition, the follower’s flight patterns after
502 exiting the hive should also be observed to identify whether the information is
503 transmitted. Even though our study provides strong support for the tactile hypothesis,
504 we can not completely rule out the possibility that followers can also obtain relevant
505 information from orienting themselves behind the dancer [68]. Recent studies which
506 have focused on the information transfer during the dance show that the transfer does
507 not depend on the follower position around the dancer [36,68,69]. However, these
508 studies only quantified the number of followers in the various zones around the
509 dancer and did not compare the mean body orientation of the followers while
510 following the dance. Combining detailed observations of the follower behaviour using
511 a high-speed camera with tracking of their foraging trips [31] is essential to gain a
512 better understanding of the mechanism underlying spatial information transfer in the
513 waggle dance and confirm the tactile hypothesis.

514 **Figure 4**



516 Signals produced by the dancer in different honey bee species. Signals can either
517 attract followers to the dancer or contain information. While the former is expected to
518 be different amongst species depending on nesting and foraging conditions, the latter
519 should be highly conserved amongst the species. Signals with an asterisk (*) next to
520 them have only been studied in *A. mellifera* so far. Visual and acoustic signals are only
521 present in some species, olfactory signals can not contain any spatial information and
522 vibrational signals are not expected to play a role in the open nesting species as the
523 dances often happen over other bees [37]. Tactile signals are the most likely to contain
524 spatial information about the food source in all the closely related species of the genus
525 *Apis*.

526

527 Differences in other signals associated with the waggle dance in the various *Apis*
528 species is linked to the modality best suited to attract followers to the dancer
529 according to the nest environment of the species (fig 4). In our study, the two open
530 nesting species, *A. florea* and *A. dorsata*, had higher numbers of dance followers
531 throughout the waggle run as compared to the cavity nesting *A. cerana*. Additionally,
532 the median body orientation did not change significantly throughout the run in the
533 case of *A. dorsata*, while it increased from the start to the end of the run in both *A.*
534 *florea* and *A. cerana*. Dancers in *A. dorsata* produce both a visual and an acoustic
535 signal, while dancers in *A. florea* and *A. cerana* are known to use only one additional
536 signal modality, visual and acoustic respectively [39,43,70]. Further work will be
537 needed to tease out the exact modulatory effect of the additional signals in the waggle
538 dance in these species.

539 In conclusion, the behavioural responses of the followers to the differing dance signals
540 in Asian honey bees provides new insights into the evolution of this complex
541 communication system. The difficulty in incorporating a mechanism for the transfer of
542 spatial information into any communication system is evident from the fact that such
543 a mechanism has evolved only rarely in animals [12]. The symbolic communication of
544 navigational information in *Apis* likely evolved on the basis of a less complicated and
545 non-error prone modulatory communication as seen in the closely related stingless
546 bees and bumblebees [37–39,71]. Given the difficulty in evolving such a symbolic
547 communication system, it can be expected that there will be very little variation in the
548 mechanism for information transfer within a small group of closely related species. In
549 line with this, we found that the behaviour of the dance followers, who receive the

550 spatial information, is highly conserved across the genus. Additional signals in the
551 waggle dance of the different species may be involved in attracting followers to the
552 dancer (fig 4). Thus, our study highlights the usefulness of comparative studies to
553 understand complex communication systems like the honey bee waggle dance and
554 provides a foundation for future studies exploring the dancer and follower behaviour
555 in the genus *Apis*.

556 **Data Accessibility**

557 All the raw data obtained from these experiments is available online at Figshare
558 (<https://doi.org/10.6084/m9.figshare.11790342.v1>).

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563 **Author Contributions**

564 E.A.G. participated in the conception and design of the study, participated in the
565 experiments, performed the data analysis and drafted the manuscript. S. P.
566 participated in the video and data analysis and critically revised the manuscript. N. T.
567 participated in the experiments and the video analysis and critically revised the
568 manuscript. A. B. participated in the conception and design of the study, coordinated
569 the study and helped draft the manuscript.

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