**Title:** Automatic encoding of a view-centered background image in the macaque temporal lobe

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**Abstract**

Perceptual processing along the ventral visual pathway to the hippocampus is hypothesized to be

substantiated by signal transformation from retinotopic space to relational space, which

represents interrelations among constituent visual elements. However, our visual perception

necessarily reflects the first person's perspective based on the retinotopic space. To investigate

this two-facedness of visual perception, we compared neural activities in the temporal lobe

(anterior inferotemporal cortex, perirhinal and parahippocampal cortices, and hippocampus)

between when monkeys gazed on an object and when they fixated on the screen center with an

object in their peripheral vision. We found that in addition to the spatially invariant object signal,

the temporal lobe areas automatically represent a large-scale background image, which specify

the subject's viewing location. These results suggest that a combination of two distinct visual

signals on relational space and retinotopic space may provide the first person's perspective

serving for perception and presumably subsequent episodic memory.

**Introduction**

Visual information of our external world could be once decomposed into "what" and "where" before we attained its mental representation as the first person's perspective (Eichenbaum, Yonelinas, & Ranganath, 2007; Palombo et al., 2015; Tulving, 2002). For several decades, it has been considered that the perception of these two visual features proceeds exclusively through the ventral and dorsal pathways (Goodale & Milner, 1992; Haxby et al., 1991; Mishkin & Ungerleider, 1982). Instead of this widespread dichotomy, contemporary visual neuroscience research suggests a presence of spatial information in the ventral pathway for perception (Chen & Naya, 2019; Connor & Knierim, 2017; Russell A. Epstein & Julian, 2013; Freud, Plaut, & Behrmann, 2016; Hong, Yamins, Majaj, & DiCarlo, 2016; Kornblith, Cheng, Ohayon, & Tsao, 2013; Mormann et al., 2017; Schenk, 2010). For instance, neurons in the inferotemporal (IT) cortex (TEO and TEd) of non-human primates exhibited preferential responses to scene-like stimuli rather than object-like stimuli (Kornblith et al., 2013; Vaziri, Carlson, Wang, & Connor, 2014). The response pattern of scene-selective IT neurons may be comparable to an activation pattern in the parahippocampal place area detected in human functional imaging studies (R. Epstein & Kanwisher, 1998; Julian & Epstein, 2013). The parahippocampal place area is located within the parahippocampal cortex (PHC) of the medial temporal lobe (MTL), which receives inputs from the early stages of the ventral pathway including the TEO and posterior TEd in addition to inputs from the dorsal pathway, and provides spatial information to the hippocampus (HPC) – a candidate of the final brain region for scene perception (Burgess, 2008) - via the medial/posterior entorhinal cortex (ERC) (Rolls, 2018). On the other hand, neurons in the IT cortex also represent location information of an object within a scene either at population-coding level (Hong et al., 2016) or at single-neuron level (Chen &

Naya, 2019). It is worth noting that while most neurophysiological studies had shown a spatial

invariance of object at single-neuron level during monkeys' fixating on the center of a display

under either the passive-viewing task (Hong et al., 2016; Kobatake & Tanaka, 1994) or delayed

matching-to-sample (object) task (Miyashita & Chang, 1988; Nakamura, Matsumoto, Mikami, &

Kubota, 1994), our recent study demonstrated equivalent or even more neurons exhibiting

location signal compared with object signal in the ventral part of the anterior inferotemporal

cortex (TEv) and its downstream MTL area (e.g., perirhinal cortex, PRC) during an item-location

retention (ILR) task requiring monkeys to encode both identity and location of a sample object

using a foveal vision (Fig. 1). Importantly, the location-selective activity during the ILR task

could not be explained by the animals' eye-positions themselves (Chen & Naya, 2019).

Considering that different gaze positions cause a substantial difference in the large-scale

visual input in the ILR task using the foveal-view (F-V) condition (Fig. 1D), the most

straightforward explanation for the robust location signal might be that a substantial number of

neurons in the IT cortex and MTL areas are driven by the retinotopic signal including parafoveal

vision, which would not only serve for recognizing a scene (Connor & Knierim, 2017; Dilks,

Julian, Kubilius, Spelke, & Kanwisher, 2011; Kornblith et al., 2013; Vaziri et al., 2014) but also

signal a particular location in the scene (Chen & Naya, 2019; Hong et al., 2016). An alternative

explanation would be the location information of an object is coded into internal spatial

relationships within a large complex stimulus including an object and its background regardless

of their absolute retinotopic positions. In other words, the IT cortex and MTL areas would

represent object location by transforming representations of the object and its background on the

retinotopic space (Zhaoping, 2019) into those on the "relational space" (Connor & Knierim,

2017). In this case, the location signal in the ILR task would be sensitive to the task demand

requiring the animals to retain the object location for a following action rather than a retinotopic

image depending on the animals' gaze position.

To address this question and investigate characteristics of spatial information in the

ventral pathway and its downstream (i.e., MTL areas), we examined single-unit activities and

local-field potentials (LFPs) from the TEv and MTL subregions during an object stimulus

presented randomly at one of the quadrants on the display in a peripheral-view (P-V) as well as

in an F-V condition (Fig. 1). In the P-V condition, animals were required to fixate on a central

dot and obtain the location and item-identity information of the sample object using their

peripheral vision (Fig. 1A). We compared the location effects between the two-view conditions

by testing two rhesus macaques, and found that regardless of the task demands for encoding of

an object and its location, there were much more abundant location signal in the F-V condition

compared with the P-V condition on all the recording regions of the two monkeys.

**Results**

We collected data in both F-V and P-V conditions from two rhesus macaques (Fig. 1B). During the recording, Monkey A was required to encode an identity of a sample stimulus and its location actively for a subsequent response (i.e., ILR task). We reported the single-unit data in the F-V condition of the ILR task in the previous study (Chen & Naya, 2019); here, we refer to the ILR task as an "active-encoding task." On the other hand, monkey F was only required to fixate on a small white dot, viewing a sample stimulus passively ("passive-encoding task") in both view conditions (Figs. 1A&B). We did not record from the single monkeys in both encoding tasks because it would be difficult to exclude both explicit and implicit influences of learning the active-encoding task on the cognitive process in the passive-encoding task. We used the same six visual objects (yellow Chinese characters, radius = 3°) as sample stimuli for both monkeys through all the recording sessions (Fig. 1C). It should be noted that the retinotopic images differed entirely between F-V and P-V conditions although a position of a sample stimulus was identical relative to the external world including a large square background (48° each side) on the display between the two view conditions (Figs. 1C&D). This two-by-two experimental design ("F-V vs. P-V" × "active-encoding vs. passive-encoding") allowed us to compare the neural signals in the F-V condition with those in the P-V condition in the animals with different task demands. Monkey A performed the active-encoding task at high performances in both F-V (96.2 ± 3.7 %, 454 sessions) and P-V (92.2 ± 7.1 %, 477 sessions) conditions.

*Gaze-related location signal*

We first investigated single-unit activities signaling location information. Figure 2A shows an example of TEv neurons that were recorded in the active-encoding task. The neuron

showed the largest responses when the animal fixated on the *position I* (*top right* on the large

square background). Although the responses once decayed, the neuron responded strongly when

an item stimulus was presented as a sample stimulus at the same *position I* in the F-V condition.

We examined the neuronal responses during 80-1000 ms after the onset of sample presentation

(sample period) using a two-way ANOVA with item identities (six items) and locations (four

locations) as main effects. The neuron showed a significant location effect [$P < 0.0001$, $F(3,156)$

$= 18.98$] but not for item identities of sample stimuli [$P = 0.309$, $F(5,156) = 1.21$]. In contrast to

the strong location-selectivity in the F-V condition, the same TEv neuron did not show location-

selective activities in the P-V condition during the sample period [$P = 0.183$, $F(3,157) = 1.63$].

Figure 2B shows an example of PRC neurons that also exhibited location-selective activities

only in the F-V conditions. This neuron signaled location information only after sample

presentation in the F-V condition, suggesting that the presence of location signal in the F-V

condition cannot be necessarily explained by preceding location-selective activity before sample

presentation. We examined the prevalence of location signal in the two view conditions among

the recording regions by calculating proportions of neurons with significant ($P < 0.01$, two-way

ANOVA) location-selective activities during the sample period in each area. All recording

regions contained significantly ($P < 0.0016$ in each region, $\chi^2$ test) larger proportions of location-

selective cells in the F-V condition (24%, TE; 27%, PRC; 21%, HPC; 20%, PHC) than the P-V

condition (7%, TE; 10%, PRC; 7%, HPC; 4%, PHC) (Fig. 3A). These results indicated that the

location information in the ventral pathway and MTL areas were sensitive to the view

conditions, although the same task-relevant information was required for a following action in

the active-encoding task. The robust location signal only in the F-V condition implicates that the

temporal lobe areas represent a visual image, which subjects view rather than the goal-directed

spatial information related with an action plan.

The different sensitivity to the two view conditions was also observed for the location

signal in the passive-encoding task (Figs. 2C&D). Similar to the active-encoding task, we found

a substantial number of neurons exhibiting location effect (29%, TE; 15%, PRC; 21%, HPC;

34%, PHC) under the F-V condition (Fig. 3B). This result indicates that the location-selective

response in the active-encoding task did not result from the task requirement, in which the

animal was required to maintain actively a location of a sample stimulus. Compared with the F-V

condition, the number of location-selective cells decreased dramatically under the P-V condition

in all areas (8%, TE; 4%, PRC; 0%, HPC; 10%, PHC) (Fig. 3B). These results are also consistent

with the single-unit results in the active-encoding task, and suggest that the gaze-sensitive

location signal is automatically encoded by neurons in the TEv and MTL. The marked reduction

of location signal in the P-V condition during either active or passive-encoding task argued

against the possibility that the location-selective cells distinguish the structural organization of

large objects with internal structures (e.g., a large grey square with a small letter at its top-left vs.

at its bottom-right) which would be represented by the relational rather than the retinotopic space

(Connor & Knierim, 2017).

The most straight-forward interpretation of fewer active location-selective cells under the

P-V condition may be that fixating on the center of the display reduces attention to a sample

stimulus and attenuates the response of location-selective cells, which showed robust location

signals in the F-V condition. If this situation applies, we would then expect that neurons with

stronger location selectivity in the F-V condition would show relatively stronger location

selectivity in the P-V condition (i.e., a positive correlation). To test this possibility, we estimated

strengths of location signals for neurons with location-selective activity in either F-V or P-V

condition using $F$ values indicating a location effect in the two-way ANOVA. Notably, we

observed a negative correlation in amplitudes of the $F$ values between the conditions in all areas

during either active-encoding (Spearman rank correlation = -0.24 among 229 neurons across

areas, $P = 0.0003$, two-tailed) (Fig. 4A) or passive-encoding task (Spearman rank correlation = -

0.20 among 71 neurons, $P = 0.090$, two-tailed) (Fig. 4B). These results suggest that the weak

location signal in the P-V condition was not due to the attenuated attention to a sample item. A

reasonable interpretation of the negatively correlated location signal might be that separate visual

inputs on the retinae drive different ensembles of neurons between the two view conditions (Fig.

1D). This interpretation is consistent with the significant reduction in the proportion of location-

selective cells from the F-V to the P-V condition (Fig. 3) because a retinotopic shift of a large

background square (48°, each side, Fig. 1C) in the F-V condition (Fig. 1D, left) would drive

more neurons than that of a small sample stimulus (3°, radius) in the P-V condition (Fig. 1D,

right). Collectively, the TEv and MTL areas may automatically signal large-scale background

information represented on the retinotopic space, which necessarily reflects a perspective that a

subject is viewing.

*Task-dependent item signal*

In contrast to the dramatic difference in the location-selective activity between the F-V

and P-V conditions, neurons in the temporal lobe showed consistent item-selective responses

between the two view conditions during the active-encoding task (Fig. S1). In all recording

regions except for the PHC, we found a substantial number of item-selective cells under the P-V

condition (TE 23%, PRC 22%, HPC 27%, and PHC 2%) as well as F-V condition (TE 14%,

PRC 22%, HPC 32%, and PHC 3%) (Fig. 3A, bottom). These results are consistent with

previous studies indicating the spatial invariance of object representation (Kobatake & Tanaka,

1994; Miyashita & Chang, 1988; Nakamura et al., 1994), which would be obtained by

transforming it from the retinotopic space into the relational space along the ventral pathway

(Connor & Knierim, 2017). In contrast to the location signal, the signal strengths of item

information positively correlated between the F-V and P-V conditions (Figs. 4&D). These results

indicate distinct processing between the item and its background (i.e., location signal) regarding

their sensitivity to the view conditions. Interestingly, the number of item-selective cells was

negligible in all areas under both view conditions in the passive-encoding task (F-V condition:

TE 6%, PRC 0%, HPC 2%, PHC 3%; P-V condition: TE 2%, PRC 2%, HPC 3% PHC 1%; Fig.

3B, bottom), which contrasts to the substantial number of item-selective cells in the active-

encoding task. The inconsistency in the item signal between the two tasks suggests that the

object representation depends on the task demand, which required the subject to maintain an item

identity of a sample stimulus for the following action.

*Population-coding analysis*

The analyses based on the spike-firing data of individual neurons indicated substantially

stronger location signal in the F-V condition compared with the P-V condition regardless of the

task demands. One remaining question might be whether the location signal could be represented

equivalently between the two view conditions by population coding. To test this possibility, we

conducted the "representational similarity analyses" (RSA) (Kriegeskorte, Mur, & Bandettini,

2008); we first constructed a population vector consisting of firing rates of all recorded neurons

in each area as its elements. In each combination of view condition and encoding-type, there

were twenty-four (six items × four locations) of $n$-dimensional population vectors. "$n$" indicates

a number of the recorded neurons in each area. We then calculated correlation coefficients

between the population vectors, indicating the similarity level of neural representations between

trial-types with different item-location combinations. Figures 5A and 5B displayed the similarity

level of neural representations in the HPC during the sample presentation period in the active-

encoding and passive-encoding tasks, respectively. In both tasks, the representational similarities

between trial-types with same locations (e.g., location 1 item 1 & location 1 item 2) were

substantially larger than the similarities between trial-types with different locations (e.g., location

1 item 1 & location 2 item 2) in the F-V condition ($P <0.001$ in both tasks, one-side, simulation

test), suggesting that the HPC represents the item location that the animals were viewing,

regardless of the task demands. In contrast to the F-V condition, the HPC's discriminability in

the location of a sample stimulus was considerably diminished in the P-V condition (Figs.

5A&B). In the RSA, other recorded regions also showed the marked reduction of the location

signal in the P-V condition compared with the F-V condition in both tasks (Figs. 5C&D).

Together, consistent with the analyses based on the single neurons, the analyses examining the

population coding suggest that the temporal lobe areas represent the location information more

robustly in the F-V condition than the P-V condition. As to the item signal, the RSA also

provided the results which were consistent with the results of the single-neuron-based analyses

(Fig. S2).

*LFP activity depending on both view-condition and task-demand*

In addition to spiking data, we investigated the LFP activity during the sample period.

Figure 6A shows the differential spectrums between the viewing conditions (F-V condition

minus P-V condition) in each recording region under the active-encoding task (*left column*) and

passive-encoding task (*right column*). During the early sample presentation period (0-300 msec

after sample onset), there is an enhanced beta-band activity (1- 25 Hz) expressed non-selectively

across the brain regions and tasks (Fig. 6B). This higher beta-band activity in the F-V condition

is consistent with preceding literature indicating that larger beta-band activity is observed when

the current cognitive or perceptual status should be actively maintained (i.e. the sample stimulus

appears at the same position as with the fixation period in the F-V condition) than when the

current state is disrupted by an unexpected event (i.e. the sample stimulus appears randomly at

one out of the four positions in the P-V condition) (Engel & Fries, 2010). A view-condition

dependent LFP activity was also observed in a gamma-band (30-80 Hz) during the late sample

presentation period (350-800 msec after sample onset) (Fig. 6A). In contrast to the widely

distributed beta-band, the gamma-band activity was selectively expressed only in the PRC and

HPC when a sample item and its location were encoded actively by the foveal vision (Fig. 6B),

in which situation both the item and location signals appeared robustly in these brain regions

(Figs. 3&5&S2). These results may implicate that the increased gamma-band activity is related

with the interaction between the item and location signals, which reportedly occurs in the PRC

and HPC but not in TEv nor PHC (Chen & Naya, 2019).

**Discussion**

The present study provides single-unit data showing robust spatial information in the TEv

and MTL areas, which signaled a particular location where the animals were viewing (F-V

condition) rather than an object position presented in the peripheral view (P-V condition). These

results were shown for each of the recording regions by the independent analyses for each of the

two monkeys, indicating the very robust animal consistency. In addition, this animal consistency

was confirmed even though the two animals were tested in different task demands (i.e., active-

encoding and passive-encoding of an object and its location), which manifests the robustness of

the present findings showing an existence of the location signal characterized by the clear

difference in its sensitivity to the two view conditions. These new findings suggest that the

location signal in the primate temporal lobe areas may represent a view-centered background

image, which could specify the current gaze position within a scene (Fig. 7). This view-centered

background may be automatically represented in the temporal lobe areas because it was observed

in the passive-encoding task as well as the active-encoding task. The TEv and MTL areas except

for the PHC also signaled object information. However, in contrast to the background

information, the object information was represented regardless of the view conditions when it

was actively encoded. These results from the single-neuron-based analyses were confirmed by

population-coding analyses. Taken together, the present study suggests that the ventral pathway

and its downstream in the MTL signal not only spatially-invariant object information but also

view-centered background information, which may automatically locate the object in a scene

when it is viewed by the foveal vision.

One naïve question on the gaze-related location signal might be whether the location

signal could be explained by non-visual sensory/motor information, which reflects the animals'

eye positions relative to their heads. Our previous study indicated that neurons in the TEv and

MTL areas responded differently to the same gaze positions depending on the position of the

large background square within the display (leftward or rightward) (Chen & Naya, 2019),

suggesting that the gaze-related location signal reflects visual inputs rather than

somatosensory/motor-related information of the gaze itself. In the present study, we

characterized the location signal, which were widely distributed over the temporal lobe areas, by

revealing the underlying visual inputs not to be represented on the relational space, but instead

on the retinotopic space (i.e., view-centered background). An important question about the view-

centered background information on the retinotopic space might be whether it only reflects the

parafoveal vision or not. In the present study, the location-selective activity depends on the

parafoveal vision of the background, which shows an edge of the large grey square or the display

frame. However, some neurons exhibited location-selective activities only after sample

presentation in the F-V condition (Figs. 2B-D) (10.8% and 8.5% across areas in the active and

passive-encoding tasks), which suggest an existence of neuronal population that represent the

view-centered background including foveal vision as well as parafoveal vision. The view-

centered background signal in the present study may explain response patterns of "spatial view

cells" in the HPC (and posterior PRC) reported by Rolls (Rolls, Robertson, & Georges-François,

1997). The spatial view cells show selective responses to a particular location where an animal

views regardless of its standing position. This allocentric coding property of the spatial view

cells could be due to similar visual inputs when an animal views the same location from different

positions.

In spite of the location signal which may reflect the background information on the

retinotopic space, the object signal was detected regardless of its retinotopic position in the

active encoding task (Fig. 7), which confirmed the preceding literature showing the spatial

invariant of object representation in the IT cortex (Miyashita & Chang, 1988; Nakamura et al.,

1994). The representation of an object may be explained by a spatial relationship among the

internal elements of it, which necessarily accompany its transformation from the retinotopic

space into the relational space (Connor & Knierim, 2017). The present study suggests that

neurons in the temporal lobe signal the location information of an object as its background image

represented on the retinotopic space (Fig. 7) rather than an interrelation between the object and

any other spatial structure such as a large gray square behind it. Based on the present

experimental set up, the background image encoded by neurons in the TEv and MTL areas

301 should cover larger than 30 degrees in the visual angle (diameter) to include the edge of the large

302 gray square background, which may cause different responses according to the gaze positions.

303 As well as the object signal, the large-scale background image is reportedly processed along the

304 ventral pathway (Kornblith et al., 2013; Vaziri et al., 2014). One remaining question is whether

305 the processing of the background image in the ventral pathway imparts more generalized spatial

306 features (e.g., field, valley, forest), which may be represented on the relational space and serve

307 for recognizing an entire scene (e.g., suburb rather than modern city) regardless of the gaze

308 positions (e.g., an eagle over the valley).

309   In addition to the view conditions testing the representation spaces (i.e., relational vs.

310 retinotopic), the object and the background signals showed differential sensitivity patterns to the

311 task demands in the present study. The background signal was encoded irrespective of the task

312 demand while the object signal was encoded only in the active-encoding task. The automatic

313 encoding of the background signal suggests that when we direct our gaze toward an object to

314 obtain its high-resolution image, we would spontaneously receive the spatial information, which

315 would be assigned to the object (Chen & Naya, 2019). One remaining problem about the object

316 signal might be whether the lack of item-selective activity in the passive-encoding task is due to

317 the present stimulus set (i.e., Chinese character) because the IT neurons reportedly respond to

318 object stimuli such as face stimuli in a passive-viewing task (Kiani, Esteky, Mirpour, & Tanaka,

319 2007; Tsao, Freiwald, Knutsen, Mandeville, & Tootell, 2003). Compared with a natural object

320 such as a face stimulus, a fabricated two-dimensional stimuli used in the present study may not

321 bring about a bottom-up attention to be perceived as an object. In the active-encoding task, the

322 monkey learned the Chinese characters to discriminate one from another. The repetitive training

323 in the active-encoding task might form a long-term learning effect on the stimulus to induce the

bottom-up attention, which may lead a transformation of representations of Chinese-characters

from the retinotopic space into the relational space. Although we cannot address if the attention

was derived from the bottom-up or the top-down, the attention-dependent object signal and the

attention-independent background signal may derive from a figure-background segmentation,

which reportedly occurred at the V4, a start point of the ventral pathway (Roe et al., 2012).

Previous studies have focused on the object information which is filtered, and implicated that the

object representation is transformed from the retinotopic space into the relational space with the

increase of neurons' receptive fields along the ventral pathway (Connor & Knierim, 2017). We

hypothesize that the background information, which is filtered-out at the figure-ground

segmentation, spreads into the ventral pathway with its representation remaining on the

retinotopic space rather than the relational space. Our previous report has demonstrated that the

two distinct signals, which are segmented from the same retinal image, are integrated step-by-

step from the TEv, PRC to HPC (Chen & Naya, 2019). From the ventral stream to the MTL

areas, the strongest integration effect was found in the PRC at the single neurons level. This

integration process may be related with the largest gamma-band LFP activity in the PRC, which

was observed when the monkey gazed at an object to encode its identity and location information

actively (Fig. 6).

In the present study, the PHC represents the view-centered background signal whose

property is similar to that in the TEv and other MTL areas including the PRC. Considering the

heavier projections from the posterior parietal cortex to the PHC compared with the AIT cortex

including the PRC (Kravitz, Saleem, Baker, & Mishkin, 2011), the PHC may also process the

spatial information related with the eye/self-movement. Contributions of the PHC to scene

construction process may become apparent when a subject perceives the environment by moving

their gazes (Zhang & Naya, 2019) in which multiple views should be coordinated according to

the eye/self-movements, beyond encoding a single snapshot focusing on one object which was

investigated in the present study. We propose a future study to investigate how the past multiple

views influence on the present view to build the current first person's perspective (Eichenbaum

et al., 2007; Palombo et al., 2015; Tulving, 2002), which may be related with an encoding of

episodic memory.

**Materials and Methods**

*Subjects*

Two male monkeys (*Macaca mulatta*) (9.3 kg, monkey A; 10.1 kg, monkey F) were

used for the experiments. All procedures and treatments were performed in accordance with the

NIH Guide for the Care and Use of Laboratory Animals and were approved by the Institutional

Animal Care and Use Committee (IACUC) of Peking University.

*Behavioral task*

We trained monkey A on a foveal-view/F-V condition of an active-encoding task with six

visual items (Fig. 1). During both training and recording sessions, monkeys performed the task

under dim light in an electromagnetic shielded room (length * width * height = 160 cm *120 cm

* 222 cm). The task began with an encoding phase, which was initiated by the animal pulling a

lever and fixating on a white square (0.6 ° of visual angle) presented within one of the four

quadrants (12.5 ° from the center) of a touch screen (3MTM MicroTouchTM Display M1700SS,

17 inch, horizontal viewing angle: ~59 °, vertical viewing angle: ~49 °) with a custom-made

metal frame (diagonal size: 22 inch, horizontal viewing angle: ~72 °, vertical viewing angle: ~71

°) situated ~28 cm from the subjects. Eye position was monitored using an infrared digital

camera with a 120 Hz sampling frequency (ETL-200, ISCAN) placed next to the left edge of the

touch screen. The eye position calibration was conducted before starting each recording session

(Monkey logic). After a 0.6 s fixation, one of the six items (3.0 °, radius) was presented in the

same quadrant as a sample stimulus for 0.3 s, followed by another 0.7 s fixation on the white

square. An additional 0.017 s, reflecting the design of software and hardware controlling the

behavioral task was added to each trial event. If the fixation was successfully maintained

(typically, < 2.5 °), the encoding phase ended with the presentation of a single drop of water.

The encoding phase was followed by a blank interphase delay interval of 0.7-1.4 s during

which no fixation was required. Then, the response phase was initiated with a fixation dot

presented at the center of the screen. One of the six items was then presented at the center for 0.3

s as a cue stimulus. After another 0.5 s delay period, five discs were presented as choices,

including a blue disc in each quadrant and a green disc at the center. When the cue stimulus was

the same as the sample stimulus, the subject was required to choose by touching the blue disc in

the same quadrant as the sample (i.e., match condition). Otherwise, the subject was required to

choose the green disc (i.e., nonmatch condition). If the animal made the correct choice, four to

eight drops of water were given as a reward; otherwise, an additional 4 s was added to the

standard intertrial interval (1.5-3 s). During the trial, a large gray square (48 ° on each side, RGB

value: 50, 50, 50, luminance: 3.36 cd/m$^2$) was presented at the center of the display (backlight

luminance: 0.22 cd/m$^2$) as a background. After the end of a trial, all stimuli disappeared and the

entire screen displayed light-red color during the inter-trial interval. The start of a new trial was

indicated by the re-appearance of the large gray square on the display, upon which the monkey

could start to pull the lever triggering an appearance of a white fixation dot. In the match

condition, sample stimuli were pseudorandomly chosen from six well-learned visual items, and

each item was presented pseudorandomly within the four quadrants, resulting in 24 (6 × 4)

different configuration patterns. In the nonmatch condition, the position of the sample stimulus

was randomly chosen from the four quadrants, and the cue stimulus was randomly chosen from

the five items that differed from the sample stimulus. The match and nonmatch conditions were

randomly presented at a ratio of 4:1, resulting in 30 (24+6) different configuration patterns. The

same six stimuli were used during all recording sessions.

In addition to the F-V condition, we tested the neuronal responses of monkey A in the

peripheral-view/P-V condition of the active-encoding task. In this view condition, fixation on the

center of the display was required during the encoding phase (Fig. 1). Other parameters were the

same as those in the F-V condition of the active-encoding task. Correct performance under F-V

condition: $97.5 \pm 2.6\%$ in the match trials and $90.8 \pm 8.1\%$ in the nonmatch trials (n = 454

sessions); P-V condition: $94.3 \pm 6.2\%$ in the match trials and $84.1 \pm 10.8\%$ in the nonmatch trials

(n = 478 sessions).

We tested the neuronal responses of monkey F in both F-V and P-V condition of a

passive-encoding task, in which the task sequence and requirement were same as the encoding

phase of the active-encoding task but without a lever-pulling requirement (no interphase delay

interval and response phase). The configuration of visual stimuli (such as visual angles,

configuration patterns, and others) was same as that for monkey A. We tested the neuronal

response of both monkey A and monkey F in the F-V and P-V conditions in a block manner.

*Electrophysiological recording*

Following initial behavioral training, animals were implanted with a head post and

recording chamber under aseptic conditions using isoflurane anesthesia. To record single-unit

activity, we used a 16-channel vector array micrILRobe (V1 X 16-Edge, NeuroNexus), 16-

channel U-Probe (Plexon), tungsten tetrode probe (Thomas RECORDING), or a single-wire

tungsten microelectrode (Alpha Omega), which was advanced into the brain using a hydraulic

Microdrive (MO-97A, Narishige) (Naya & Suzuki, 2011). The microelectrode was inserted

through a stainless steel guide tube positioned in a customized grid system on the recording

chamber. Neural signals for single units were collected (low-pass, 6 kHz; high-pass, 200 Hz) and

digitized (40 kHz) (OmniPlex Neural Data Acquisition System, Plexon). These signals were then

sorted using an offline sorter provided by the OmniPlex system. We did not attempt to prescreen

isolated neurons. Instead, once we isolated any neuron, we started to record its activity. The

location of microelectrodes in target areas was guided by individual brain atlases from MRI

scans (3T, Siemens). We also constructed individual brain atlases based on the

electrophysiological properties around the tip of the electrode (e.g., gray matter, white matter,

sulcus, lateral ventricle, and bottom of the brain). The recording sites were estimated by

combining the individual MRI atlases and physiological atlases (Naya, Chen, Yang, & Suzuki,

2017). To record LFPs, we used neural signals from the same electrodes as we used for the

recording of spikes. However, the signals were collected using different filters (low-pass, 200

Hz; high-pass, 0.05 Hz), and digitized at 1 kHz.

The recording sites in monkey A covered an area between 5 and 24 mm anterior to the

interaural line (right hemisphere). The recording sites in monkey F covered an area between 6.6

and 23.4 mm anterior to the interaural line (right hemisphere). The recording sites in HPC

appeared to cover all its subdivisions (i.e., dentate gyrus, CA3, CA1, and subicular complex).

The recording sites in PHC focused on approximately the lateral 2/3. The recording sites in PRC

appeared to cover areas 35 and 36 from the fundus of the rhinal sulcus to the medial lip of the

anterior middle temporal sulcus (amts). The border of PRC's caudal limit (PHC's rostral limit)

was determined according to the rostral limit of the occipital temporal sulcus and the caudal limit

of the rhinal sulcus (Suzuki & Amaral, 2003). In monkey A, the caudal limit of the recording

sites in PRC is 2 mm posterior to the caudal limit of its rhinal sulcus and 1 mm anterior to the

rostral limit of the occipital temporal sulcus. In monkey F, the caudal limit of the recording sites

in PRC is 0 mm posterior to the caudal limit of its rhinal sulcus and 0 mm anterior to the rostral

limit of the occipital temporal sulcus. The recording sites in TE were limited to its ventral area,

including both banks of the amts.

*Data analysis*

All neuronal data were analyzed using MATLAB (MathWorks) with custom written

programs, including the statistics toolbox. For responses before sample presentation, we tested

each neuron's firing rate during the 700 ms period before the sample stimulus onset, including

the 100 ms before the fixation start, as the monkeys typically started fixation 160-170 ms after

fixation dot presentation. For responses during/after sample presentation, the firing rate during

the period extending from 80 to 1000 ms after sample onset was tested. For responses before

sample presentation, we evaluated the effects of "location" for each neuron using one-way

ANOVA ($P < 0.01$). For sample responses, we evaluated the effects of "location" and "item" for

each neuron using two-way ANOVA with interactions ($P < 0.01$ for each). We analyzed neurons

that we tested in at least 60 trials (10 trials for each stimulus, 15 trials for each location).

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**Figures**

**Fig. 1. Encoding of location and item in two view conditions**

(A) Schematic diagram of location and item encoding in the F-V and P-V conditions of the

active-encoding and passive-encoding tasks. In the active-encoding task, the cue stimulus was

the same as the sample stimulus during the encoding phase in the match trial (Top), while the

two stimuli differed in the nonmatch trial (Bottom). Red circles indicate correct answers.

Passive-encoding task consisted of only the encoding phase of the active-encoding task. (B)

Example of coronal sections from monkey A and monkey F. The sections from Monkey A are 16

mm and 10.5 mm anterior to the interaural line and include the hippocampus (HPC),

parahippocampal cortex (PHC), perirhinal cortex (PRC), and area TE (TE). amts, anterior middle

temporal sulcus; ots, occipital temporal sulcus; rs, rhinal sulcus. Coronal sections from monkey F

are 19.2 mm and 8.4 mm anterior to the interaural line. (C) Six object stimuli were used in the

task, and an example of spatial composition during the sample period is shown. A yellow disk

indicates an object position. (D) Schematic diagram of visual inputs to the retinae during the

sample period; white dashed lines indicate the horizontal and vertical meridians of the visual

field.

**Fig. 2. Responses of the location-selective cells in the active-encoding and passive-encoding task**

(A) Example of the location-selective cells from TE in the F-V and P-V condition of the active-encoding task. (Left) Spike-density functions (SDFs) (sigma = 20 ms) indicating the firing rates under two conditions (best location and the average of other three locations). (Right) Bar graph indicating the mean firing rate during sample period (80-1000 ms after sample on) under each location and each item. (B) Example of the location-selective cells from PRC in the F-V and P-V condition of the active-encoding task. (C-D) Examples of the location-selective cells in TE (C) and PHC (D) in the F-V and P-V conditions of the passive-encoding task.

**Fig. 3. Proportions of location-selective and item-selective cells**

(A) Proportions of location-selective cells (Top) and item-selective cells (Bottom) during the

sample period (80-1000 ms after sample on) in the F-V (filled bars) and P-V conditions (open

bars) in the active-encoding task. Numbers of recorded neurons (tested in both view conditions)

are indicated in parentheses. **$P < 0.0016$, $\chi^2 = 10.0$ for PHC, d.f. = 1. ***$P < 0.0001$. $\chi^2 =$

19.5, 20.0, and 28.3 for TE, PRC, and HPC, respectively. (B) Proportions of location-selective

cells (Top) and item-selective cells (Bottom) during the sample period in the F-V (filled bars)

and P-V conditions (open bars) in the passive-encoding task. *$P < 0.026$, $\chi^2 = 4.9$ for PRC, d.f. =

1. **$P < 0.005$. $\chi^2 = 11.1$ and 8.7 for TE and PHC, respectively. ***$P < 0.0001$. $\chi^2 = 20.3$ for

HPC.

**Fig. 4. Location and item signal intensity between the two view conditions**

(A) Location effect of the location-selective cells in the F-V and P-V conditions of the active-

encoding task. F values in the P-V condition are plotted against those in the F-V condition for

location-selective cells in either of the two view conditions. Neurons showing significant effects

in either of the two conditions were used for the calculation of the F values. Numbers of the

location-selective cells used for final calculation in each region are indicated in parentheses. (B)

Location effect in the F-V and P-V conditions of the passive-encoding task. (C) Item effect of

the item-selective cells in the two view conditions of the active-encoding task. The axis ranges in

A-C were adjusted for display purpose, which included majorities of the data sets (A: 97.8%, B:

98.6%, C: 99.6%). (D) Correlation of the signal intensity between the two view conditions. Data

from MTL and TEv were merged in the active-encoding and passive-encoding tasks,

643     respectively. The total numbers of location-selective and item-selective cells used for final

644     calculation are indicated in parentheses (left and right, respectively). na, not accountable. P =

645     0.0003, 0.0000(3.4E-07) and 0.09; $\rho$ = -0.24, 0.32, and -0.20; d.f. = 227, 241 and 69 for the

646     active-encoding (location), active-encoding (item), and passive-encoding (location), respectively.

647     Spearman's rank correlation, two-tailed.

**Fig. 5. Location effects at population level**

(A-B) Correlation coefficients of each pair out of the full 24 (four locations × six items)* 24

(four locations × six items) population vectors in the HPC under the F-V and P-V conditions of

the (A) active-encoding and (B) passive-encoding tasks. Correlation coefficients of dummy data

sets with location labels randomly shuffled (n=1000) were subtracted from the raw correlation

coefficients. All recorded neurons from HPC were used in this analysis. Pearson's linear

correlation coefficient. (C-D) Difference value between the mean correlation coefficient under

the same and different location pairs in the F-V and P-V conditions of the (C) active-encoding

and (D) passive-encoding tasks in each brain region. The correlation coefficients between the

659     population vectors for the trial-types with the same items (i.e., a diagonal line of each small

660     matrix sorted by the locations, blue pixels in Figs. 5A&B) were excluded from this analysis.

**A**

### Differential spectrums
### (F-V minus P-V)

**B**

### Average differential intensity of
### beta and gamma bands

Ae: Active encoding
Pe: Passive encoding

TE    HPC    ***, *P* < 0.01
PRC   PHC

**Fig. 6. The difference spectrums of the local field potential activities between the F-V and**

**P-V conditions in the active-encoding and passive-encoding tasks**

(A) The average difference local field potential (LFP) spectrums between the F-V and P-V

conditions of active-encoding and passive-encoding tasks during the sample period ( 0:1000

msec after sample on). Raw spectrums from different recording sites (indicated in parentheses)

were used for this analysis. Average intensity of each frequency during the baseline period

(600:0 msec before sample on) was subtracted at the corresponding frequency. (B) The average

difference value of beta-band (1-25 Hz) and gamma-band (30-80 Hz) intensity during early

sample (0:300 msec after sample on) and late sample (350:800 msec after sample on) periods

(see Fig. 6A) in each task and recording region.

**Fig. 7. Parallel scene processing on the retinotopic and relational spaces.**

*Top,* Assume that a subject was in wheat field and viewing the valley. An eagle was in

parafoveal vision of the subject in view A, while it was in the subject's foveal vison in View B.

*Middle*, When the subject attended the eagle either voluntarily or involuntarily, the eagle would

be selected as an object from the retinotopic image and processed on the relational space (*right*)

regardless of its original retinotopic. Conversely, background images would be automatically

captured and processed on the retinotopic space, which specify a location of the view point in the

scene accordingly (*left*). *Bottom*, The location of the object in the scene would be assigned by an

associated information between the view-centered background and the object. This model

hypothesizes that first person's perspective of a scene containing objects depends on the parallel

visual processing on the retinotopic and relational spaces, and their association. The original

painting is titled Wheat Field with Cypresses by Vincent Willem van Gogh.

**Supplementary Figures**

**Fig. S1. Responses of the item-selective cells in the active-encoding task**

(A) Example of the item-selective cells from TE in the F-V and P-V conditions of the active-

encoding task. (Left) Spike-density functions (SDFs) (sigma = 20 ms) indicating the firing rates

under two conditions (best item and the average of other five items). (Right) Bar graph indicating

the mean firing rate during sample period (80-1000 ms after sample on) under each location and

each item. (B) Example of the item-selective cells from PRC in the F-V and P-V conditions of

the active-encoding task.

**Fig. S2. Item effects at population level**

(A-B) Correlation coefficients of each pair out of the full 24 (six items × four locations) * 24 (six

items × four locations) population vectors in the HPC under the F-V and P-V conditions of the

(A) active-encoding and (B) passive-encoding tasks. Correlation coefficients of dummy data sets

with item labels randomly shuffled (n=1000) were subtracted from the raw correlation

coefficients. All recorded neurons from HPC were used in this analysis. Pearson's linear

correlation coefficient. (C-D) Difference value between the mean correlation coefficient under

the same and different item pairs in the F-V and P-V conditions of the (C) active-encoding and

(D) passive-encoding tasks in each brain region. The correlation coefficients between the

population vectors for the trial-types with the same items (i.e., a diagonal line of each small

matrix sorted by the items, blue pixels in Figs. S2A&B) were excluded from this analysis.