# An estimator of the Opportunity for Selection that is independent of mean fitness

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July 2020

**Abstract**

Variation among individuals in number of offspring (fitness, $k$) sets an upper limit to the
evolutionary response to selection.  This constraint is quantified by Crow's Opportunity for
Selection ($I$), which is the variance in relative fitness ($I=\sigma_k^2/(u_k)^2$).  Crow's $I$ has been widely
used but remains controversial because it depends on mean offspring number in a sample ($\bar{k}$).
Here I used a generalized Wright-Fisher model that allows for unequal probabilities of producing
offspring to evaluate behavior of Crow's $I$ and related indices under a wide range of sampling
scenarios.  Analytical and numerical results are congruent and show that rescaling the sample
variance ($s_k^2$) to its expected value at a fixed $\bar{k}_2$ removes dependence of $I$ on mean offspring
number, but the result still depends on choice of $\bar{k}_2$.  A new index is introduced, $\Delta_I = \hat{I}-\text{E}(\hat{I}_{\text{drift}}) =$
$\hat{I}-1/\bar{k}$, which makes $\hat{I}$ independent of sample $\bar{k}$ without the need for variance rescaling.  $\Delta_I$ has a
straightforward interpretation as the component of variance in relative fitness that exceeds that
expected under a null model of random reproductive success. $\Delta_I$ can be used to directly compare
estimates of the Opportunity for Selection for samples from different studies, different sexes, and
different life stages.

Over a half century ago, James Crow introduced two indices that quantify variation in
reproductive success among individuals, based on the mean ($\mu_k$) and variance ($\sigma_k^2$) in the number
of offspring per individual ($k$).  Crow and Morton (1955) defined the ratio $\sigma_k^2/\mu_k$ as the Index of
Variability, denoted here by φ.  With random reproductive success of $N$ parents, the expected
variance in offspring number due to drift [$E(\sigma_{k(drift)}^2)$] takes the form of a binomial variance
$\mu_k(N\text{-}1)/N$, which is often approximated by the Poisson variance $\sigma_k^2=\mu_k$, leading to $E(\varphi_{\text{drift}}) \approx 1$.
Therefore, the Index of Variability is a useful indicator of the degree to which variance in
offspring number is overdispersed, relative to the Poisson expectation, which in turn has a strong
influence on the effective population size ($N_e$) and the key ratio $N_e/N$.  Shortly thereafter, Crow
(1958) defined the parameter $I = \sigma_k^2/\mu_k^2 = \varphi/\mu_k$, which he called the Index of Total Selection, but
subsequent authors generally refer to this as the Opportunity for Selection (Arnold and Wade
1984a,b; Clutton-Brock 1988; Brodie et al. 1995).  Crow's $I$ measures "the total amount of
selection possible, given the demographics of a population.  It answers the question, By what
fraction would the mean population fitness increase in one generation of selection if its
heritability were perfect (i.e., $h^2 = 1$)?" (Crow 1989, p 776).  The Opportunity for Selection thus
sets an upper limit to the evolutionary response to selection; mathematically, $I$ also represents the
variance in relative fitness (Walsh and Lynch 2018).

Crow and Morton (1955) showed that the Index of Variability is very sensitive to mean
offspring number (= mean fitness) in a sample ($\bar{k}$), and it is well known that Crow's $I$ also
depends on $\bar{k}$.  In a stable population of diploids, each parent contributes on average half the
genes to two adult offspring; therefore, assuming exhaustive sampling of offspring, $\mu_k = 2$.
However, $\mu_k>2$ is possible for increasing populations, and $\bar{k}>2$ can easily occur when sampling
juvenile offspring of a highly fecund species (e.g., a marine fish).  Conversely, $\bar{k}<2$ is possible
for declining populations or when only a portion of the offspring are sampled.  Therefore,
sampling from real populations in nature can produce a wide range of sample $\bar{k}$ values, even
when the population is stable.  Dependence of the estimators $\hat{\varphi}$ and $\hat{I}$ on $\bar{k}$ means that, based on
experimental design and sampling effort, the same underlying biological process could lead to
very different conclusions about the distribution of reproductive success and the Opportunity for
Selection.  For this reason, a number of authors have questioned the practical utility of Crow's $I$
for drawing inferences about natural selection (Trail 1985; Downhower et al. 1987; Fairbairn and
Wilby 2001).

This topic merits a new look, for two reasons.  First, Crow and Morton (1955) proposed a
simple solution to the problem caused by dependence of the Index of Variability on $\bar{k}$:  one can
rescale $\hat{\varphi}$ to its expected value at a different mean offspring number using the following
equation:

$$E(\hat{\varphi}_2) = 1 + \frac{\bar{k}_2}{\bar{k}_1}(\hat{\varphi}_1 - 1) \quad , \tag{1}$$

where $\bar{k}_1$ is mean offspring number in the initial sample, $\bar{k}_2$ is the target mean offspring number,
$\hat{\varphi}_1$ is the initial estimate of the Index of Variability, and $\hat{\varphi}_2$ is the rescaled index.  Equation 1

solves for the expected value of $\hat{\varphi}$, assuming random mortality of offspring until the target $\bar{k}$ is
reached. Allowing for random mortality of individuals in a sample is statistically equivalent to
randomly sampling fewer offspring in the first place. Setting $\bar{k}_2 = 2$ yields the expected value of
$\hat{\varphi}$ for a constant population. Waples (2002) showed that Equation 1 also can be used for the
common situation where $\bar{k}_1 < 2$; in this case, the result is the value of $\hat{\varphi}$ one would expect to find
if the same offspring distribution were sampled more intensively, until $\bar{k}_2 = 2$. There is nothing
magical about scaling to $\bar{k}_2 = 2$, but it is a useful reference point because most populations that
persist for any period of time must have a long-term mean offspring number close to 2.

Because of the simple relationship between $I$ and $\varphi$, Crow and Morton's method for
rescaling $\varphi$ can also be applied to $I$ to remove the dependence on the sample mean. However,
few published papers cite both Crow (1958) and Crow and Morton (1955). Crow himself did not
mention the 1955 variance-rescaling method in either his original 1958 paper introducing the
Index of Total Selection or his 1989 retrospective. Others (e.g., Wade and Arnold 1980 and
Cabana and Kramer 1991) noted Crow and Morton's method but did not use it to rescale $I$
values. Therefore, it is important to evaluate the degree to which rescaling raw $I$ values can
resolve ongoing controversies regarding the Opportunity for Selection.

The second interesting issue is that, under random reproductive success, the Opportunity
for Selection has a simple expectation: $E(\hat{I}_{drift}) = E(\hat{\varphi})/\bar{k} \approx 1/\bar{k}$. Downhower et al. (1987)
suggested, but did not recommend, that the difference between empirical $\hat{I}$ and $1/\bar{k}$ might be used
to compare $\hat{I}$ values from different studies. Their logic was that the result would still be a ratio,
and ratios have some undesirable statistical properties. As demonstrated below, Downhower et
al.'s idea has some real merit: Although both empirical $\hat{I}$ and $E(\hat{I}_{drift})$ depend on sample $\bar{k}$, their
difference does not and hence is independent of mean fitness in the sample.

Here, analytical and numerical methods are used to explore the relationship between
Crow's Index of Variability and the Opportunity for Selection. Objectives are to: (1) Illustrate
the effects of rescaling estimators $\hat{\varphi}$ and $\hat{I}$ to a constant $\bar{k} = 2$, under three different reproductive
systems: random reproductive success, and moderate and strong reproductive skew. (2)
Introduce a new index $\Delta_I = \hat{I} - E(\hat{I}_{drift})$ and show that this removes the dependence of $\hat{I}$ on mean
offspring number, without any need for rescaling to constant population size. $\Delta_I$ represents the
component of variance in relative fitness that exceeds that due to random demographic
stochasticity. (3) Examine an index of relative resource monopolization ($Q$) proposed by
Ruzzante et al. (1996) for evaluating the Opportunity for Selection, but recast the index in terms
of $I$ rather than the variance in offspring number. (4) Use raw and scaled reproductive success
data to calculate inbreeding and variance effective sizes and evaluate their sensitivity to the
scaling issues that affect $\varphi$.

## Methods

Both of the "1"s in Crow and Morton's Equation 1 are a consequence of using the
Poisson approximation that $E(\varphi_{drift}) \approx 1$, rather than the exact $E(\varphi_{drift}) = (N\text{-}1)/N$. The difference

is generally negligible, but it can become important when both $N$ and mean offspring number are
small. The analytical treatment below follows Crow and Morton in using the Poisson
approximation. In rescaling empirical data, the following adjustment to Equation 1 can be used
to incorporate the exact variance:

$$E(\hat{\varphi}_2) = (N - 1)/N + \frac{\bar{k}_2}{\bar{k}_1}(\hat{\varphi}_1 - (N - 1)/N) \qquad . \qquad (1A)$$

**Analytical model**

The model used here is a generalization of the standard Wright-Fisher model of
reproduction, whereby $N$ monoecious adults each contribute equally to a large (~ infinite) pool of
gametes, which unite at random to form the next generation. The current model differs in two
respects. First, separate sexes are allowed. For simplicity, the treatment below assumes the sex
ratio is equal; if not, the only major difference is that mean offspring number to produce a stable
population will be <2 for the more numerous sex and >2 for the less numerous sex. Second, and
more importantly, the model allows for unequal contributions to the initial gamete pool,
specified by the vector of individual weights $W = w_1, w_2, \ldots w_N$ (Figure 1). A version of this
weighted Wright-Fisher model was first introduced by Robertson (1961) for the special case of
full-sibling families, but the more general treatment here follows Felsenstein (2019). The
number of gametes contributed by the $i^{th}$ parent ($k_i$) is proportional to its weight: $k_{i\alpha} = Dw_i$,
where $i = 1 \ldots N$, $D$ is a (very) large constant, and the subscript $\alpha$ indicates that the $k_i$ values
apply to the initial gamete pool. It follows that the mean number of gametes per parent in the
gamete pool is given by

$$\mu_{k\alpha} = D\bar{w} , \qquad (2)$$

and the variance of initial $k_i$ is

$$\sigma_{k\alpha}^2 = Var(Dw_i) = D^2\sigma_w^2. \qquad (3)$$

After the gametes randomly combine to form zygotes, random survival reduces the
number of surviving offspring ($N_j$) at successive life stages. The number of life stages to
consider is arbitrary; the schematic diagram in Figure 1 shows three stages following the gamete
pool ($j = \alpha, \beta, \gamma, \omega$), with $j=\omega$ denoting the final (adult) stage. Mean offspring number per parent
at the various life stages is determined by the stage-specific population sizes according to $\mu_{kj} =$
$2N_j/N$. If sex ratio is equal and the number of surviving offspring at the final life stage is $N_\omega =$
$N$, population size is constant and $\mu_{k\omega} = 2$, as in the original Wright-Fisher model. Each stage-
specific variance in offspring number per parent ($\sigma_{kj}^{2*}$) is not uniquely determined by the initial
weights and $N_j$; instead, it merely represents one of many possible random realizations of a
stochastic process. In the notation, the asterisk (*) is used to denote the fact that ($\sigma_{kj}^{2*}$) can be
considered to be both a population parameter (because it applies to all individuals in the
population at a given point in time) and a random variable (because it represents only one of
many possible outcomes, given the fixed composition of the initial gamete pool and the survival
rate through stage $j$). Waples and Faulkner (2009) also used the asterisk in a similar way in their

evaluations of variation in realized reproductive parameters under the standard Wright-Fisher
model.

The Crow-Morton model envisions enumerating a population at two time periods
separated by random mortality, and it can be related directly to this generalized Wright-Fisher
model as follows. Let time period 1 be the initial gamete pool (so time 1 = life stage α). From
Equations 2-3 we have $\mu_{k\alpha} = \mu_{k1} = D\overline{w}$ and $\sigma_{k\alpha}^2 = \sigma_{k1}^2 = D^2\sigma_w^2$, so the variance-to-mean ratio in
the gamete pool is

$$\phi_\alpha = \phi_1 = D^2\sigma_w^2/D\overline{w} = D\sigma_w^2/\overline{w}. \tag{4}$$

We are now interested in predicting what the realized values of $\sigma_{k2*}^2$, $\phi_{2*}$, and $I_{2*}$ will be at a
second (later) life stage, after random mortality has reduced the offspring population size to $N_2$
and the mean offspring number to $\mu_{k2} = 2N_2/N$. A simple rearrangement of Equation 1 (Waples
2002), using the notation above, leads to

$$E(\sigma_{k2*}^2|\mu_{k2}) = \mu_{k2}\left[1 + \frac{\mu_{k2}}{\mu_{k1}}(\varphi_1 - 1)\right] \quad , \tag{5}$$

with the "|" notation indicating that this is a conditional expectation that depends on the value of
$\mu_{k2}$. Substituting for $\phi_1$ from Equation 4 produces

$$E(\sigma_{k2*}^2|\mu_{k2}) = \mu_{k2}\left[1 + \frac{\mu_{k2}}{D\overline{w}}\left(\frac{D\sigma_w^2}{\overline{w}} - 1\right)\right] = \mu_{k2}\left[1 + \frac{\mu_{k2}\sigma_w^2}{\overline{w}^2} - \frac{\mu_{k2}}{D\overline{w}}\right]. \tag{6}$$

Because $D$ is a very large constant, the last term can be ignored, leading to

$$E(\sigma_{k2*}^2|\mu_{k2}) \approx \mu_{k2}\left[1 + \frac{\mu_{k2}\sigma_w^2}{\overline{w}^2}\right] = \mu_{k2}[1 + \mu_{k2}CV^2(w)], \tag{7}$$

where $CV^2(w)$ is the squared coefficient of variation of the individual weights. Finding the
conditional expectation of $\phi_{2*}$ is straightforward:

$$E(\varphi_{2*}|\mu_{k2}) = E(\sigma_{k2*}^2)/\mu_{k2} = 1 + \mu_{k2}CV^2(w) . \tag{8}$$

When the initial weights are equal, $CV^2(w) = 0$ and we recover the standard Wright-Fisher model
with $E(\varphi_{drift}) = 1$. Note that this result is independent of the life stage or the stage-specific $\mu_k$,
a property first demonstrated by Fisher (1939).

The analogous conditional expectation for the Opportunity for Selection is

$$E(I_{2*}|\mu_{k2}) \approx E(\varphi_{2*}|\mu_{k2})/\mu_{k2} = CV^2(w) + 1/\mu_{k2} . \tag{9}$$

Under a pure drift model, $CV^2(w) = 0$ and Equation 8 reduces to

$$E(I_{drift2}|\mu_{k2}) = 1/\mu_{k2}, \tag{10}$$

which is the inverse of the mean offspring number per parent (Downhower et al. 1987). Unlike
$E(\varphi_{drift})$, therefore, $E(I_{drift})$ is a conditional expectation that depends on the life stage at which
mean offspring number is calculated.

It is useful to define new metrics $\Delta_\varphi$ and $\Delta_I$, obtained by subtracting the random
expectation from the raw value of the index. Letting subscript 1 represent raw data and subscript
2 rescaled data, we have:

$\Delta_{\varphi 1}= \varphi_{1*} - E(\varphi_{drift}) = \varphi_{1*} - 1;$

$E(\varphi_{2*}) = 1 + \dfrac{\mu_{k2}}{\mu_{k1}}(\varphi_{1*} - 1);$

$\Delta_{\varphi 2}= \varphi_{2*} - E(\varphi_{drift}) = \dfrac{\mu_{k2}}{\mu_{k1}}(\varphi_{1*} - 1)$    .

Thus, $\Delta_{\varphi 1}$ and $\Delta_{\varphi 2}$ differ by the factor $\mu_{k2}/\mu_{k1}$. $\Delta_\varphi$ quantifies the degree of overdispersion in $\sigma^2_{k*}$,
but since the adjustment only involves subtracting a constant, $\Delta_\varphi$ still depends on mean offspring
number, regardless whether raw or scaled values are used.

Results are different for the Opportunity for Selection:

$I_{1*} = \dfrac{\varphi_{1*}}{\mu_{k1}};$

$\Delta_{I1}= \dfrac{\varphi_{1*}}{\mu_{k1}} - \dfrac{1}{\mu_{k1}} = \dfrac{1}{\mu_{k1}}(\varphi_{1*} - 1);$

$I_{2*} = \dfrac{\varphi_{2*}}{\mu_{k2}} = \dfrac{1}{\mu_{k2}} + \dfrac{1}{\mu_{k1}}(\varphi_{1*} - 1);$

$\Delta_{I2}= \dfrac{\varphi_{2*}}{\mu_{k2}} - \dfrac{1}{\mu_{k2}} = \dfrac{1}{\mu_{k1}}(\varphi_{1*} - 1).$

Therefore,

$\Delta_{I1}= \Delta_{I2}= \Delta_I = \dfrac{1}{k_1}(\varphi_{1*} - 1).$         (11)

After scaling $\varphi_{1*}$ to $\mu_{k2} = 2$, one obtains the following:

$\Delta_I = \dfrac{\varphi_2 - 1}{2}.$         (11A)

Notably, the Opportunity for Selection, adjusted to account for the contribution from random
reproductive success, is the same whether it is calculated for raw or rescaled values of $I$ (hence
independent of mean offspring number or the life stage at which reproductive success is
quantified).

Thus far we have only dealt with population parameters, including some that can be
considered random variables with respect to the initial gamete pool.  Samples for empirical data
analysis might be taken at any life stage; in the example in Figure 1, it is stage $\beta$.  Mean
offspring number in a sample is uniquely determined by the number of offspring sampled ($n$)
according to $\bar{k} = 2n/N$, but the sample variance ($s_{k1}^2$) is a random realization of a stochastic
process that also depends on $\bar{k}$.  From a statistical standpoint, taking a random sample of $n$
offspring from any life stage subsequent to the initial gamete pool is mathematically equivalent
to finding a life stage at which random mortality has reduced the population to $N_j = n$ individuals
and sampling all of them.  Therefore, for sampling in any life stage $j$, the expected sample
variance in offspring number, conditional on mean offspring number in the sample, is given by
(modified from Equation 7):

$$E\left(s_{kj}^2 | \bar{k}_j\right) = \bar{k}_j\left[1 + \bar{k}_j CV^2(w)\right]. \tag{12}$$

Similarly, the conditional expected values of $\hat{\varphi}$ and $\hat{I}$ for random samples are given by simple
modifications of Equations 8 and 9:

$$E\left(\hat{\varphi}_j | \bar{k}_j\right) = E\left(s_{kj}^2 | \bar{k}_j\right)/\bar{k}_j = 1 + \bar{k}_j CV^2(w) \ . \tag{13}$$

$$E(\hat{I}_j | \bar{k}_j) \approx E\left(\hat{\varphi}_j | \bar{k}_j\right)/\bar{k}_j = CV^2(w) + 1/\bar{k}_j \ . \tag{14}$$

The hat "^" is used for $\hat{\varphi}$ and $\hat{I}$ to indicate that they are estimates based on samples (and are
conditional on the sample mean offspring number) and do not reflect population parameters.

Another way to scale indices of reproductive success is to identify upper limits to
possible values for $\sigma_k^2$, $\varphi$, and $I$.  Ruzzante et al. (1996) provided the following expression for the
maximum possible variance in offspring number among $N$ parents:

$$\sigma_{k(MAX)}^2 = N\bar{k}^2,$$

from which it is straightforward to derive the other maxima, assuming a sample of $n$ offspring:

$$\varphi_{(MAX)} = N\bar{k}^2/\bar{k} = N\bar{k} = n; \tag{15}$$

$$I_{(MAX)} = N\bar{k}/\bar{k} = N. \tag{16}$$

Ruzzante et al. (1996) used $\sigma_{k(MAX)}^2$ to define an index of relative resource monopolization as

$$Q = \frac{\sigma_k^2 - \bar{k}}{\sigma_{k(MAX)}^2 - \bar{k}} \ .$$

$Q$ is the ratio of the empirical variance in offspring number to the maximum possible variance,
after both have been adjusted by subtracting the expected value under Poisson variance in
reproductive success ($\bar{k}$).  In the current notation, $Q = \Delta\sigma_k^2/\Delta\sigma_{k(MAX)}^2$. As a result of this
standardization, $Q$ is independent of mean reproductive success.  However, as noted by

Fairbairn and Wilby (2001), because $Q$ is calculated using the variance in reproductive success
rather than $I$, it is not readily interpretable in terms of the Opportunity for Selection.  A more
useful index for this purpose is

$$\hat{Q}_I = \frac{\hat{\Delta}_I}{I_{MAX} - E(\hat{I}_{drift})} \approx \frac{\hat{\Delta}_I}{N - 1/\bar{k}} \ ,\tag{17}$$

which uses $I$ directly.

Crow's Index of Variability can also be used to calculate both inbreeding and variance
effective population size (Crow and Denniston 1988):

Inbreeding $N_e = \dfrac{\mu_k N - 1}{\mu_k - 1 + \varphi}\ ;$ $\qquad\qquad\qquad\qquad\qquad\qquad$ (18)

Variance $N_e = \dfrac{\mu_k (2N - 1)}{2(1 + \varphi)}\ .$ $\qquad\qquad\qquad\qquad\qquad\qquad$ (19)

These equations give effective size for a single sex, and Eq. 19 ignores the (generally minor)
adjustment for departure from Hardy-Weinberg genotypic proportions.  If effective size is
calculated separately for males and females ($N_{em}$, $N_{ef}$), overall $N_e$ can be obtained using Wright's
(1938) sex ratio adjustment: $N_e = 4N_{em}N_{ef}/(N_{em} + N_{ef})$.

Felsenstein (2019) showed that in the weighted Wright-Fisher model, variance $N_e$ in a
stable population ($u_k = 2$) can be expressed as a simple function of the initial weights:

$N_e = N/(1 + CV_w^2)\ .$

It can be shown that this result holds more generally for inbreeding effective size assessed at any
given life stage $j$.  Ignoring the "-1" term in the numerator, Equation 18 becomes

Inbreeding $N_e = \dfrac{\mu_{kj} N}{\mu_{kj} - 1 + \varphi_j}\ .$

From Equation 8 we have $E(\varphi_j | \mu_{kj}) = 1 + \mu_{kj} CV_w^2$, and making that substitution produces

Inbreeding $N_e = \dfrac{\mu_{kj} N}{\mu_{kj} + \mu_{kj} CV_w^2} = \dfrac{N}{1 + CV_w^2}\ .$ $\qquad\qquad$ (20)

**Simulations**

The analytical results above demonstrate the conditional dependence of $\varphi$ and $I$ on mean
offspring number.  To illustrate these relationships for a wide range of sample $\bar{k}$ values, and to
evaluate performance of the newly-proposed indices $\hat{Q}_I$ and $\hat{\Delta}_I$, a simulation model was
developed that mimics the weighted Wright-Fisher model.  For each of $N_{Off}$ offspring a
(nominally female) parent was randomly chosen from the pool of $N$ potential parents.  A total of

$N_{Off} = 100N$ offspring were produced initially, and random subsamples of different numbers of
offspring ($n$) were taken to produce a series of sample $\bar{k}_1$ values; because only one parent was
chosen for each offspring, $\bar{k}_1 = n/N$. Three reproductive scenarios were considered, defined by
different vectors of parental weights. (1) Each female was equally likely to be the parent of
every offspring (this is the Wright-Fisher model with equal parental weights; $W_1 = 1, 1, \ldots 1$).
(2) Moderate reproductive skew created by unequal weighting of parents ($W_2 = 1, 2, 3 \ldots N$). (3)
Stronger reproductive skew created by more unequal parental weights ($W_3 = W_2^2 = 1, 4, 9 \ldots N^2$).
Both for the raw data and after scaling to constant population size, the statistics $\bar{k}, s_k^2, \hat{\varphi}$, and $\hat{I}$
were calculated for each sample size for each of 1,000 replicates, with 10-fold additional
replication for $\bar{k} < 1$. Because the ratios $\hat{\varphi}$ and $\hat{I}$ are upwardly skewed, geometric means across
replicates were used as measures of central tendency. For each sample size and resulting $\bar{k}$, both
effective sizes were estimated using geometric means of $s_k^2$ and raw and scaled $\hat{\varphi}$ from the
simulated reproductive success data.

# Results

The analytical results in **Methods** showed how expected values of the Index of
Variability, the Opportunity for Selection, and effective population size can be expressed as a
simple function of weighted parental contributions to an initial gamete pool. The simulation
model employed a comparable scheme for assigning relative probabilities that different parents
would produce offspring. Simulation results for a representative scenario with $N = 100$ parents
and $N_{Off} = 10^4$ total offspring are illustrated in Figures 2-4. Taking a series of random
subsamples of offspring ($n = 10 \ldots 5000$) produced results for raw $\bar{k}_1$ spanning three orders of
magnitude (0.1 – 100).

**Crow's indices**

Sensitivity of both raw $\hat{\varphi}_1$ and raw $\hat{I}_1$ to sampling intensity is apparent; the one exception
is for $\varphi$ under random reproductive success, in which case $\hat{\varphi}_1 \approx 1$ regardless what $\bar{k}_1$ is (Figure
2A). But with overdispersed variance in reproductive success, $\hat{\varphi}_1$ increases strongly with $\bar{\hat{k}}_1$
(raw $\hat{\varphi}_1 > 80$ for $\bar{k}_1 = 100$ under strong reproductive skew). Underdispersed variance in
reproductive success produces the mirror-image pattern: raw $\hat{\varphi}_1$ is very low (<<1) when $\bar{k}_1 >> 2$
and converges on 1 as $\bar{k}_1$ approaches 0 (Appendix A and Figure S1). It is apparent from Figure
S1 that sparse sampling of offspring will generally have a poor chance of detecting
underdispersed variance in reproductive success, even when underdispersion is pronounced.

For the scenarios depicted in Figure 2, stronger reproductive skew produces larger values
of $\hat{I}_1$. However, whereas $\hat{\varphi}_1$ increases with $\bar{k}_1$ when reproductive success is overdispersed, $\hat{I}_1$
shows the opposite pattern: the Opportunity for Selection is negatively correlated with mean
offspring number (Downhower et al. 1987; Cabana and Kramer 1991).

Scaling raw $\hat{\varphi}_1$ and $\hat{I}_1$ values to a fixed $\bar{k}_2 = 2$ removes the dependence on mean
offspring number for both indices (Figure 2B). In rescaling the empirical data for the simulation
results, I used the exact expectation for random variation in offspring number (Equation 1A).
Use of the Poisson approximation in Crow and Morton's formula (Equation 1) produces a slight
bias when $\bar{k}_1 < \bar{k}_2$ (Figure S2). The scaled values in Figure 2B, obtained from the raw values in
Figure 1A using Equation 1, are the same values identified in Figure 2A by the intersection of
the vertical line for $\bar{k}_2 = 2$ and the curves for the empirical data. That is, subsampling from the
original data to reach $\bar{k}_2 = 2$ produces essentially the same result as scaling the raw data using
the Crow and Morton method. Note, however, that for both $\hat{\varphi}_2$ and $\hat{I}_2$, the magnitude of the
rescaled values depends on choice of $\bar{k}_2$.

Independence of $\hat{\Delta}_I$ from both raw and scaled $\bar{k}$ is also illustrated in Figure 2. Although
it is not visually apparent with the log scaling of the $Y$ axis, for strong reproductive skew the two
$\hat{\Delta}_{I1}$ values for different $\bar{k}_1$ in Figure 2A are the same ($\hat{\Delta}_{I1} = 0.8$), and both are equal to rescaled
$\hat{\Delta}_{I2}$ from Figure 2B ($\hat{\Delta}_{I2} = \frac{\hat{\varphi}_2 - 1}{2} = \frac{2.6 - 1}{2} = 0.8$ using Equation 11A).

**Index of resource monopolization**

In the simulations, the estimator $\hat{Q}_I = \hat{\Delta}_I / (\hat{I}_{MAX} - 1/\bar{k}_1)$ (modified from Ruzzante et al. 1996
according to Eq. 17) was independent of sample $\bar{k}_1$ under both random and overdispersed
variance in reproductive success (Figure 3). Equations 15 and 16 show that maximum possible $\hat{\varphi}$
is just the number of offspring sampled ($n$), whereas the maximum possible $\hat{I}$ is the number of
parents. These results show that $\hat{Q}_I$ could be useful in quantifying the effects of resource
monopolization in the context of the Opportunity for Selection (Ruzzante et al. 1996; Fairbairn
and Wilby 2001).

**Effective population size**

With random reproductive success, $E(\varphi) \approx 1$ and inbreeding $N_e \approx \mu_k N / \mu_k = N$, regardless
what $\mu_k$ is because inbreeding $N_e$ depends on the number of parents (Crow 1954; Equation 18).
In contrast, for variance $N_e$, the $\mu_k$ term in the numerator is not balanced by a separate $\mu_k$ term in
the denominator (Equation 19), and as a consequence variance $N_e$ depends heavily on mean
offspring number in a sample (Figure 4A). Harmonic mean inbreeding $\hat{N}_e$ is invariant with $\bar{k}_1$
for all reproductive scenarios, and the sample estimates agree almost exactly with the true $N_e$
predicted by Equation 20 based on weighted contributions to the initial gamete pool. In contrast,
variance $\hat{N}_e$ is directly proportional to $\bar{k}_1$ for random reproductive success and has a more
complex but positive correlation with $\bar{k}_1$ when variance in reproductive success is overdispersed.
The two effective sizes are the same only when $\bar{k}_1 = 2$ (vertical line in Figure 4A), indicative of a
stable population (Crow 1954). Rescaling $\hat{\varphi}_1$ to its expectation for a population of constant size
removes the dependence of variance $\hat{N}_e$ on mean offspring number (Figure 4B).

### Effects of age structure

All of the above analyses have implicitly assumed that generations are discrete. Because most species are age structured (Hughes 2017), this is an important limitation. In age-structured species having birth-pulse reproduction (Caswell 2001), there are two major ways to calculate the mean and variance in reproductive success: 1) seasonal reproductive success among all mature individuals during a single year or season; 2) lifetime reproductive success among all individuals from the same cohort. Below I consider some of the consequences of age structure for Crow's indices of reproductive success and related analyses.

*Index of Variability*

Analysis of seasonal reproductive success conforms to the discrete-generation model, with one exception: reproductive success for all adults in a single season can be partitioned by parental age. Seasonal reproduction within an age-structured population can be described by vectors of age-specific mean reproductive success and age-specific variance in reproductive success: $\bar{k}_x$ and $s_{kx}^2$, where $x$ indicates age. $\bar{k}_x$ is an estimate of the familiar $b_x$ (or $m_x$) from a standard life table, published data for which are available for many species. $s_{kx}^2$ is the analogous age-specific sample variance, but empirical estimates of this key parameter are seldom published. The ratio of the age-specific variance and mean is $\hat{\varphi}_x$ (Waples et al. 2011; Waples 2016), which also is rarely reported in the literature.

As is the case with discrete generations, $s_{kx}^2$ and $\hat{\varphi}_x$ are sensitive to $\bar{k}_x$. These indices can be rescaled to a different mean offspring number using Equation 1, but there is a complication: it is not generally the case that scaling to $\bar{k}_x = 2$ will produce results expected for a stable population. Instead, $s_{kx}^2$ and $\hat{\varphi}_x$ can be rescaled to the vector of $b_x$ values that produce a stable population. This requires that measures of relative, age-specific reproductive success be converted to measures of absolute reproductive success by ensuring that $\Sigma l_x b_x = 2$, where $l_x$ is cumulative survival through age $x$. This in turn requires knowing or being able to estimate age-specific survival rates. Table 2 in Waples et al. (2018) shows how age-specific $s_{kx}^2$ and $\hat{\varphi}_x$ values can be rescaled to constant size in a species with overlapping generations.

*Effective size*

Because of its insensitivity to mean offspring number, inbreeding effective size is much more generally useful than is variance effective size when analyzing age-structured data. For these species, Equation 18 can be used to estimate the effective number of breeders per year or season ($N_b$) (Waples 1990; 2016), which generally differs from $N_e$ per generation. For this purpose, the age-specific vectors of $\bar{k}_x$ and $s_{kx}^2$ values are converted into scalars ($\bar{k}$, $s_k^2$) that reflect seasonal reproductive success for adults of all ages. Estimating $N_e$ per generation requires integration of reproductive success data across multiple years or seasons to obtain the lifetime estimators $\bar{k}\bullet$ and $s_k^2\bullet$; see Waples et al. (2011, 2014) for details.

 *Opportunity for Selection*

Although the concept of age-specific Opportunity for Selection isn't particularly
meaningful, Crow's *I* can be (and often is) calculated in two fundamentally different ways: (1)
among all individuals reproducing in a single year or season, and (2) using lifetime reproductive
output among all individuals in a single cohort. For seasonal data, $\hat{I} = s_k^2/(\bar{k})^2$ and $\hat{\Delta}_I = \hat{I} - 1/\bar{k}$.
As is the case with discrete-generation data, $\hat{\Delta}_I$ for seasonal reproduction is independent of mean
offspring number in the sample, whether raw or scaled data are used.

When applied to lifetime reproductive success data for members of a cohort, $\hat{I}_\bullet =$
$s_k^2\bullet/(\bar{k}\bullet)^2$ is appropriate when estimating the Opportunity for Selection. Calculation of $E(\hat{I}_{\bullet\text{drift}})$
is complicated by the necessity of considering random stochasticity in both survival and
reproduction over individual lifetimes. In general, even under a null model that assumes all
individuals in a cohort experience the same age-specific probabilities of survival and
reproduction, lifetime $s_k^2\bullet$ will exceed $\bar{k}\bullet$ because some individuals, by chance, survive longer
and have more opportunities to reproduce. It does not appear that an analytical approximation is
currently available for lifetime $E(\hat{I}_{\bullet\text{drift}})$. However, under the null model, a stochastic, absorbing
Markov chain model with rewards developed by Caswell and colleagues (Caswell 2011; van
Daalen and Caswell 2017) could be used to calculate lifetime $E(\hat{I}_{\bullet\text{drift}})$ and hence lifetime $\hat{\Delta}_{I\bullet}$,
given information on age-specific vital rates from a standard life table. A limitation of the
Caswell model is that it implicitly assumes that $\varphi_x \approx 1$ for each age and sex. The *AGENE* model
(Waples et al. 2011) is more general in this respect, as it allows for age-specific and sex-specific
values of $\varphi_x$, but has the limitation that it is deterministic. Age-structured simulations have
shown, however, that *AGENE* accurately predicts lifetime $s_k^2\bullet$ under conditions of random
demographic stochasticity, as envisioned by Caswell and colleagues (Waples et al. 2014).
Therefore, lifetime $s_k^2\bullet$, calculated in *AGENE* after setting $\varphi_x = 1$ and assuming lifetime $\bar{k}\bullet = 2$,
could be used to estimate $E(\hat{I}_{\bullet\text{drift}})$ as $= s_k^2\bullet/(\bar{k}\bullet)^2 = s_k^2\bullet/4$. From this one could estimate lifetime
$\Delta_I$ as $\hat{\Delta}_{I\bullet} = \hat{I}_\bullet - s_k^2\bullet/4$.

## Discussion

The weighted Wright-Fisher model used here is a convenient way to link the analytical
and simulation models, which produced congruent results. This model provides a way to express
the Index of Variability, the Opportunity for Selection, and effective population size as simple
functions of proportional contributions by individual parents to an initial gamete pool. Major
points to emerge include the following:

(1) Rescaling $\hat{I}$ to a fixed $\bar{k}_2$ (as Crow and Morton proposed for the Index of Variability many
decades ago) removes the dependence of the Opportunity for Selection on mean offspring
number, but the result still depends on choice of $\bar{k}_2$. Although an argument can be made that
$\bar{k}_2 = 2$ is a logical reference point for standardizing offspring number, that is not the only

plausible target for variance rescaling. Furthermore, this transformation raises the question
whether rescaled $\hat{I}$ can still be interpreted as the variance in relative fitness.

(2) The new index $\hat{\Delta}_I$ introduced here solves this problem by simultaneously (1) removing the
dependence of $\hat{I}$ on mean fitness in the sample, without the need for rescaling variance in
reproductive success; and (2) quantifying the degree to which empirical $\hat{I}$ exceeds the value
expected under a null model of random variation in reproductive success. This means that $\Delta_I$
can be used to compare empirical estimates of the Opportunity for Selection from:
• different studies;
• different samples within the same study;
• samples taken from different life stages;
• samples of males and females when the sex ratio is uneven.
The $\hat{\Delta}_I$ index also directly addresses the need for an appropriate null model for the
Opportunity for Selection, which has been pointed out by numerous authors (e.g., McClain
1986; Downhower et al. 1987; Ruzzante et al. 1996). Although the analytical and numerical
methods used here modeled diploids with separate sexes, the approach could easily be
extended to monoecious or haploid populations.

(3) The modified index $Q_I$ is cast in terms of the Opportunity for Selection; it is independent of
mean offspring number and might have some practical utility. However, conditions that lead
to $I_{MAX}$, where one or a few parents produce all the offspring and the rest of the parents none,
are quite extreme for any stable population. This is the type of scenario proposed by
Hedgecock (1994) in his Sweepstakes Reproductive Success hypothesis, which might apply
to some marine fishes with high fecundity and Type III survivorship (Hauser and Carvalho
2008; Hedgecock and Pudovkin 2011). For most species, however, scaling $Q$ using $I_{MAX}$ will
generally produce very low $\hat{Q}_I$ values even when overdispersion is relatively strong (Figure
3).

(4) Simulation results confirm that Equation 20 provides a simple way to predict inbreeding
effective size based on individual weights that reflect relative probabilities that different
individuals will be the parent of a random offspring. With modern genomics technology and
access to methods that can non-invasively sample DNA from individuals in the wild,
parentage analyses are now routinely conducted for natural populations of many plants and
animals. Such data are typically collected annually and later integrated across years. Each
set of annual reproductive success data can be used to estimate the annual effective number
of breeders, $N_b$, and the ratio $N_b/N$. These demographic estimates can also be compared with
single-sample genetic estimates of inbreeding $N_b$, which are now widely applied to natural
populations (Palstra and Fraser 2012; Whitely et al. 2015; Wang 2016). Because of its
sensitivity to sample $\bar{k}$, variance effective size is not well-suited for these applications.

A case can be made that Crow's $I$ can be meaningfully applied to either seasonal or lifetime
reproductive success data, and examples of both are common in the literature. Quantifying
variance in lifetime reproductive success is clearly important, as this parameter strongly
influences $N_e$ per generation and long-term evolutionary behavior of the population. Calculation

of $\hat{\Delta}_I$, based on lifetime reproductive success is complicated by having to account for
stochastisity in both survival and reproduction propagated across the lifespan (Brommer et al.
2002), but the stochastic "Markov chain with rewards" model of Caswell and colleagues should
be useful here.  On the other hand, reproduction only occurs among individuals that co-occur in
space and time.  Furthermore, sexual selection in terms of competition for mates only occurs
among individuals reproducing in the same season.  Seasonal/annual data on variance in
reproductive success and the estimators $\hat{\varphi}$ and $\hat{I}$ therefore can provide valuable insights into
mating systems and behavioral dynamics associated with reproduction.

Although $\Delta_I$ provides a simple way to standardize empirical estimates of Crow's $I$,
interpretation of the Opportunity for Selection remains complicated.   Even if $\hat{\Delta}_I$ is positive, it
does not prove that natural selection is operating–it only shows that the distribution of
reproductive success is more skewed than expected under random mating dynamics.  As an
alternative to random survival, Crow and Morton (1955) considered an extreme case of family
correlated mortality, in which entire families either survive or do not as a unit.  This type of
result could occur in two general ways.  First, survival might reflect individual survival
phenotypes of the offspring or nurturing phenotypes of the parents.  In this scenario, high
mortality within a clutch of offspring could be due to failure of the offspring to grow quickly and
avoid predators, or failure of the parent to provide food or ward off predators.  To the extent that
these phenotypes have a genetic basis, this would reflect the operation of natural selection.  This
can be called the "bad genes" explanation for family correlated mortality.

Under an alternative scenario, most or all offspring from a family might fail to survive
merely because, for a short period of time, they share a common environment.  This could occur,
for example, if the tree supporting a bird nest blows over in a storm, or if all the eggs a female
salmon lays in the gravel get washed away during a flood.  In these scenarios, survival or
mortality might have nothing to do with offspring phenotypes or genotypes; instead, it could
simply be a case of being in the wrong place at the wrong time, together with your siblings. This
can be called the "bad luck" explanation.  Parsing family-correlated survival into "bad genes" vs
"bad luck" hypotheses can be complicated and is likely to be species and population specific
(e.g., see Snyder and Ellner 2018).  One needs to consider questions such as, "When choosing
nest sites, would some birds (those with better genes) have avoided trees likely to suffer storm
damage?" and "Would a bigger, stronger female salmon have dug a nest deep enough to
withstand high flows, or located the nest in an area less prone to scouring?"   This and related
issues are why most authors refer to Crow's $I$ as the Opportunity for Selection; his original term
Index of Total Selection seems to imply a more direct link to actual natural selection.

One potential caveat applies to use of $\Delta_I$.  This index is most useful when, as will often be
the case, mean offspring number in a sample depends on logistical constraints or aspects of
experimental design such as sampling intensity or life stage sampled.  In these situations, sample
$\bar{k}$ largely represents noise in the analysis and its effects are best removed.  However, mean
fitness in the population as a whole ($u_k$) is a key parameter that can reflect differential response
to selection under different environmental conditions (e.g, Cao et al. 2019).   In cases where it is

possible to essentially inventory the entire population (such that $\bar{k} \to u_k$), applying the $\Delta_I$
adjustment could be counterproductive by removing part of the signal.

**Sampling considerations**

The above analyses have assumed random subsampling of all offspring.  Family-
correlated sampling, in which siblings are collected together more often than would occur by
chance, can affect the estimate of mean fitness and can have complex, cascading effects on $\hat{\varphi}$
and $\hat{I}$.  These sampling effects can be difficult to avoid for highly fecund species when offspring
are sampled at an early life stage.

For adults, a key consideration is whether sampling probability is independent of (a) an
individual's reproductive success, and (b) whether its offspring also have been sampled.  If both
criteria are met, then randomly sampling just a portion of the adults should not lead to bias,
although it would increase uncertainty in extrapolating from the sample to the population as a
whole.  Also, performance of some genetic parentage programs can degrade if the fraction of
unsampled parents becomes too large (Jones et al. 2010), so incomplete sampling of potential
parents could indirectly affect performance of indices that estimate variance of reproductive
success.

Probably the most pervasive source of potential bias in sampling adults involves those
that produce no offspring.  Under random reproductive success, it is expected that some fraction
of mature adults will produce no offspring in a given year/season, or even across their entire
lifetime; with overdispersed variance in reproductive success, the fraction of null parents will be
higher.  In practical applications, it is essential to know whether these null parents and those that
actually produce offspring are equally likely to be sampled.  This equiprobable-sampling
criterion would be violated, for example, if potential parents are only sampled on the breeding
grounds, but each year some fraction of adults skip breeding.  Failing to account for these null
parents would overestimate mean fitness and underestimate variance in reproductive success and
related quantities (Hadfield 2007; Klug et al. 2010; Waples and Antao 2014; van Daalen and
Caswell 2019).  Interestingly, failing to sample non-reproducers has no effect on inbreeding $\widehat{N}_e$;
this type of sampling would affect all the parameters in Equation 12, but they change in such a
way that $\widehat{N}_e$ and $\widehat{N}_b$ remain constant (Waples and Waples 2011).  However, this scenario would
affect the estimated $N_e/N$ or $N_b/N$ ratios, if some fraction of mature adults are not accounted for
in the denominator.

**Acknowledgments:** I am grateful to Joe Felsenstein, Marty Kardos, and Tom Reed for useful
discussions and comments.  Daniel Ruzzante, Jarle Tufto, and an anonymous reviewer provided
useful comments on an earlier draft.  The author declares no conflict of interest.

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Table 1. Notation used in this document. In some instances, not all of the subscripts are used. Asterisks (*) indicate terms that are both population parameters and random variables whose expectations depend on a stochastic process of random sampling from the initial gamete pool.

| | |
|---|---|
| $j$ | An index for life stage ($j = \alpha, \dots \omega$), with $\alpha$ = initial gamete pool and $\omega$ = adult. In discussing the Crow and Morton (1955) model, subscripts 1 and 2 are used rather than $j$ to refer to two time periods for assessing the population. |
| $N_j$ | Number of individuals in the population at life stage $j$. Without a subscript, $N$ refers to the number of parents. |
| $n_j$ | Number of individuals sampled at life stage $j$ |
| $W$ | A vector of individual weights ($w_i$, $i = 1,N$) that determine proportional contributions of the $N$ parents to the initial gamete pool |
| $k_i$ | Number of offspring produced by the $i^{th}$ parent |
| $\mu_{kj}$ | Mean number of offspring per parent in the population at life stage $j$; because each offspring has two parents, $\mu_{kj} = 2N_j/N$ |
| $\bar{k}_j$ | Mean number of offspring per parent in a sample taken from life stage $j$; $\bar{k}_j = 2n_j/N$ |
| $\sigma^2_{kj*}$ | Variance in number of offspring per parent in the population at life stage $j$ |
| $s^2_{kj}$ | Variance in number of offspring per parent in a sample taken from life stage $j$ |
| $\varphi_{j*}$ | Index of Variability = ratio $\sigma^2_{kj*}/\mu_{kj}$ in the population at life stage $j$ |
| $\hat{\varphi}_j$ | The ratio $s^2_{kj}/\bar{k}_j$ in a sample taken at life stage $j$ |
| $I_{j*}$ | Opportunity for Selection = ratio $\sigma^2_{kj*}/(\mu_{kj})^2 = \varphi_{j*}/\mu_{kj}$ in the population at life stage $j$ |
| $\hat{I}_j$ | The ratio $s^2_{kj}/(\bar{k}_j)^2 = \hat{\varphi}_j/\bar{k}_j$ in a sample taken at life stage $j$ |
| $\Delta_{Ij*}$ | $I_{j*} - \mathrm{E}(I_{\mathrm{drift},j}) = I_{j*} - 1/\mu_{kj}$ = Crow's $I$ for the population, adjusted for drift at life stage $j$ |
| $\hat{\Delta}_{Ij}$ | $\hat{I}_j - \mathrm{E}(\hat{I}_{\mathrm{driftj}}) = \hat{I}_j - 1/\bar{k}_j$ = Crow's $I$ for a sample, adjusted for drift at life stage $j$ |
| $\hat{Q}_I$ | A sample estimate of Ruzzante's Index of Resource Monopolization, modified to use $I$ rather than variance in offspring number |
| $N_e$ | Effective population size per generation |
| $N_b$ | Effective number of breeders per year or season |

Figure 1. Schematic representation of a generalized Wright-Fisher model of reproduction that allows for unequal probabilities of reproductive success. $N$ adults contribute gametes in the proportions $w_1$, $w_2$, … $w_N$ to a very large (~infinite) gamete pool (life stage α), where gametes unite at random to produce zygotes. Subsequently, random mortality (squiggly arrows) reduces the number of surviving offspring ($N_j$) at successive life stages ($j = \beta, \gamma, \omega$) and leads to smaller values of $\mu_{kj}$ = mean offspring number per parent. If the number of surviving offspring at the final life stage is $N_\omega = N$, population size is constant population and $\mu_{k\omega j} = 2$, as in the original Wright-Fisher model. Each stage-specific variance in offspring number per parent ($\sigma^2_{kj*}$) is a random variable, conditional on $\mu_{kj}$. Samples for empirical data analysis might be taken at any life stage (stage $\beta$ in this example). Mean offspring number in the sample ($\bar{k}$) is determined by the number of offspring sampled ($n$) according to $\bar{k} = 2n/N$; the sample variance ($s^2_k$) is a random variable conditional on the sample $\bar{k}$ according to Equation 12.

Figure 2. Dependence of Crow's Index of Variability ($\varphi$) and Opportunity for Selection ($I$) on mean number of offspring per parent in the sample ($\bar{k}$). With $N$ parents and $n$ offspring in the sample, $\bar{k} = 2n/N$. Sample $\bar{k} > 2$ can occur in an increasing population or when sampling early life stages; $\bar{k} < 2$ implies a declining population or incomplete sampling of offspring. Shown are geometric mean values of $\hat{\varphi}$, $\hat{I}$, and $\hat{\Delta}_I$ for 10,000 simulated reproductive events, using either a Wright-Fisher random reproductive success model, or moderate or strong overdispersion (unequal parental weights). A: raw data, plotted as a function of mean offspring number in the original sample ($\bar{k}_1$). B: raw data scaled to expected values at $\bar{k}_2 = 2$, using Eq. 1. Rescaled values in panel B are essentially the same values obtained by random subsampling the original data to reach $\bar{k}_1 = 2$ (indicated by vertical line in panel A). $\hat{\Delta}_I$ is the difference between the sample $\hat{I}$ and the expected value of $\hat{I}$ under random reproductive success. The three $\hat{\Delta}_I$ values for strong reproductive skew in the two panels (plotted at arbitrary values of $\bar{k}_1$) are all of the same magnitude ($\hat{\Delta}_I = 0.8$).

Figure 3. The *Q* index of relative resource monopolization, modified from Ruzzante et al. (1996) as shown in Equation 17. $\hat{Q}_I$ is the ratio of the empirical $\hat{I}$ to the maximum possible $\hat{I}$, after both have been adjusted by subtracting the expected value under random reproductive success. Results are based on the simulated data analyzed in Figure 2.

Figure 4. Dependence of variance $\widehat{N}_e$ (but not inbreeding $\widehat{N}_e$) on mean offspring number in an initial sample ($\bar{k}_1$), for the three reproduction scenarios considered in Figure 2 with $N = 100$ parents. A: raw data; harmonic mean variance $\widehat{N}_e$ is positively correlated with $\bar{k}_1$ for all reproductive scenarios, whereas harmonic mean inbreeding $\widehat{N}_e$ is independent of $\bar{k}_1$. Empirical data are depicted by symbols; horizontal gray lines show true $N_e$ (from Equation 20) for the three reproductive scenarios ($N_e = 100$ for random reproductive success, $N_e = 75.2$ for moderate reproductive skew, and $N_e = 55.6$ for strong reproductive skew). B: after scaling raw $\hat{\varphi}_1$ to constant population size ($\bar{k}_2 = 2$) using Equation 1, variance $\widehat{N}_e$ produces essentially the same result as raw (unscaled) inbreeding $\widehat{N}_e$. Rescaling to $\bar{k} = 2$ actually produces identical values for variance and inbreeding $\widehat{N}_e$; in Figure 4B, the rescaled variance $\widehat{N}_e$ is plotted against the raw inbreeding $\widehat{N}_e$ to illustrate why it is not necessary to rescale sample $\hat{\varphi}_1$ when estimating inbreeding $N_e$.

**Appendix**

**A. Underdispersed variance in reproductive success.**

This paper has focused on overdispered variance in reproductive success ($s_{k1}^2 > \bar{k}_1$, using the Poisson approximation), which reduces effective size and provides opportunities for natural selection to operate. Underdispersion ($s_{k1}^2 < \bar{k}_1$) is less common but nevertheless occurs in many taxa, at least with respect to seasonal reproduction. For example, the number of eggs or early-juvenile offspring can be constrained to a relatively small range of values, and this limits how large $s_{k1}^2$ can be. At the extreme, females of many large animal species, and some birds, can only produce 0 or 1 offspring per season, in which case it is impossible for the variance in offspring number to be as large as the mean. This can be shown as follows. Of the $N$ females, assume that $XN$ produce exactly 1 offspring that appears in a sample, and the rest produce none. Mean offspring number in the sample is $\bar{k}_1 X$ and $s_{k1}^2 =$ mean of the squares minus the square of the mean $= SS/N - (\bar{k}_1)^2 = XN/N - X^2 = X - X^2$, which leads to $\hat{\varphi}_1 = 1 - X$.

The original Wright-Fisher model of reproduction incorporated an extreme version of this underdispersion scenario: each of $N$ potential parents were imagined to contribute equally to an infinitely large pool of gametes, which then united at random to form the next generation of $N$ individuals. Under this scenario, using the current notation, $s_{k1}^2$ and $\hat{\varphi}_1$ were both 0 while $\bar{k}_1$ was infinitely large, and substituting these values into Eq. 1A produces

$$E(\hat{\varphi}_2) = \frac{N-1}{N} + \frac{\bar{k}_2}{\infty}\left(0 - \frac{N-1}{N}\right) = \frac{N-1}{N} \ , \tag{A1}$$

which is simply $E(\hat{\varphi}_{drift})$ (i.e., RS is neither overdispersed nor underdispersed). Note that because the initial gamete pool (and hence $\bar{k}_1$) is assumed to be infinitely large, this result holds regardless what $\bar{k}_2$ is.

All real populations of are of course finite in size. Also, we can generalize the idea of an initial gamete pool to production of diploid offspring ranging from zygotes to adults. If we still assume equal contributions to the initial pool of offspring ($s_{k1}^2 = 0$), but in finite amounts by each parent, we have

$$E(\hat{\varphi}_2) = \frac{N-1}{N} + \frac{\bar{k}_2}{X}\left(0 - \frac{N-1}{N}\right) = \frac{N-1}{N}\left(1 - \frac{\bar{k}_2}{X}\right) , \tag{A2}$$

where $X = \bar{k}_1$ could be relatively large but is finite. Equation A2 shows that $E(\hat{\varphi}_2)$ is always less than the random expectation, so variance in RS is underdispersed, and the degree of underdispersion depends on the ratio $\bar{k}_2/X$.

This model is still not very realistic, as it assumes 0 variance among parents in contributions to the initial gamete pool. Overdispersion can be generated by having unequal parental contributions to the initial gamete pool. Waples et al. (2018) used a variation of this approach to provide a minimum estimate of $\hat{\varphi}_2$ in southern bluefin tuna (*Thunnus maccoyii*), based on empirical data for variation in female size at specific ages (and hence assumed variance in age-specific egg production). For the current project, in modeling underdispersion I relaxed that

restrictive assumption that $s_{k1}^2 0$ by having two separate processes for producing offspring: 1) a directed process, whereby each parent contributes equally to the fraction $Y$ of all offspring; and 2) a random process, whereby parents for the remaining fraction (1-$Y$) of all offspring are chosen randomly from the $N$ candidates. As in the main text, in the simulations 100 parents produced a total of 10,000 initial offspring (so $\bar{k}_1$ = 100), and random subsampling produced $\bar{k}_2$ values as small as 0.1. I considered two values of $Y$: 0.5 (moderate underdispersion) and 0.9 (strong underdispersion).

Results (Figure S1) show that initial Index of Variability for the two scenarios is simply the fraction of offspring that were randomly assigned to parents (i.e., $\hat{\varphi}_1 = 1$-$Y$). As the sample size of offspring declines, $\hat{\varphi}_1$ for both scenarios rapidly approach 1, in agreement with predictions from Equation 1A. It is apparent that sparse sampling of offspring will generally have a poor chance of detecting underdispersed variance in reproductive success, even when underdispersion is pronounced.

Figure S1. Relationship between the estimated Index of Variability ($\hat{\varphi}_1$) and sample $\bar{k}_1$ when variance in reproductive success is underdispersed. Observed values (symbols) are from simulations that initially generated 10,000 offspring from 100 parents and then randomly subsampled offspring to produce smaller sample $\bar{k}_1$ values. Expected values (lines) were obtained from Equation 1A using the empirical value of raw $\hat{\varphi}_1$ for maximum $\bar{k}_1$ = 100. Moderate and strong underdispersion scenarios are described in the Appendix text.

**B. Poisson approximation to the binomial variance.**

Figure S2. Comparison of results for rescaling empirical data for $\hat{\varphi}_1$ from Figure 2A to $\bar{k}_2 = 2$, using Equation 1 (black) and Equation 1A (gray). The two equations differ in that 1 uses the Poisson approximation that $E(\hat{\varphi}_{drift}) \approx 1$, whereas 1A uses the exact value $E(\hat{\varphi}_{drift}) = (N\text{-}1)/N$, with $N$ being the number of parents. The difference between $(N\text{-}1)/N$ and 1 is small (0.99 vs 1 for the $N = 100$ parents used in simulating the data), but that difference becomes magnified when $\bar{k}_1$ is small, in which case the term $\bar{k}_2/\bar{k}_1 = 2/\bar{k}_1$ becomes large.