

1 **How citizen science could improve Species Distribution Models and their independent assessment**

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18

19 **Abstract**

- 20 1. Species distribution models (SDM) have been increasingly developed in recent years but their  
21 validity is questioned. Their assessment can be improved by the use of independent data but  
22 this can be difficult to obtain and prohibitive to collect. Protoled data from citizen science  
23 may be used to establish external evaluation datasets and to improve SDM validation and  
24 applicability.
- 25 2. We used opportunistic presence-only data along with presence-absence data from a  
26 standardized citizen science program to establish and assess habitat suitability maps for 9  
27 species of amphibian in western France. We assessed Generalized Additive and Random Forest  
28 Models' performance by (1) cross-validation using 30% of the opportunistic dataset used to  
29 calibrate the model or (2) external validation using different independent data sets derived  
30 from citizen science monitoring. We tested the effects of applying different combinations of  
31 filters to the citizen data and of complementing it with additional protoled fieldwork.
- 32 3. Cross-validation with an internal evaluation dataset resulted in higher AUC (Area Under the  
33 receiver operating Curve) than external evaluation causing overestimation of model accuracy  
34 and did not select the same models; models integrating sampling effort performed better with  
35 external validation. AUC, specificity and sensitivity of models calculated with different filtered  
36 external datasets differed for some species. However, for most species, complementary  
37 fieldwork was not necessary to obtain coherent results, as long as the citizen science data was  
38 strongly filtered.
- 39 4. Since external validation methods using independent data are considered more robust,  
40 filtering data from citizen sciences may make a valuable contribution to the assessment of  
41 SDM. Limited complementary fieldwork with volunteer's participation to complete ecological  
42 gradients may also possibly enhance citizen involvement and lead to better use of SDM in  
43 decision processes for nature conservation.
- 44

45 **Keywords**

46 Amphibians, biodiversity conservation, data filtering, data culling, external evaluation, habitat  
47 suitability modelling, sampling effort.

48

49 **Introduction**

50 In the current context of biodiversity loss, a stronger relationship between conservation  
51 science and citizen participation could help to make conservation actions more effective (Ahmadi et  
52 al., 2017; Lewandowski & Oberhauser, 2017). Availability of data from citizen sciences has considerably  
53 increased over the past few decades (Dickinson, Zuckerberg & Bonter, 2010; McKinley et al., 2017).  
54 This data has great potential because (i) large quantities of data can be collected over large areas,  
55 which would be difficult and expensive for researchers to collect; (ii) data may be collected over long  
56 time periods, which is especially useful for studying the effects of climate and landscape changes on  
57 population dynamics at large scales; (iii) citizens are involved in the research process, thereby gaining  
58 knowledge, and their involvement might lead to improved implementation of biodiversity  
59 conservation action (Dickinson, Zuckerberg & Bonter, 2010; McKinley et al., 2017). However, quality  
60 of data from participatory sciences is heterogeneous and different methods have been developed to  
61 boost data accuracy and account for bias, including interactive project development, volunteer  
62 training, expert data validation and statistical modelling improvement (Kosmala et al., 2016). Although  
63 researchers have been skeptical about the value of datasets from citizen science, recent publications  
64 show that some could be as valid as data collected by professional scientists (Kosmala et al., 2016).  
65 This is conditional on such data being judged in context (i.e. according to the sampling methods used,  
66 program objectives and applications) on the use of rigorous data sorting and analyses (Isaac et al.,  
67 2014; Steen, Elphick & Tingley, 2019; Robinson et al., 2020).

68           Opportunistic presence-only data collected by citizens at large scales have contributed to the  
69 expansion of species distribution models (SDM) over the past twenty years, particularly for biological  
70 conservation applications (Guisan & Thuiller, 2005). The validity of presence-only SDM is however  
71 increasingly questioned as well as their applicability (Barve et al., 2011). Presence-only data come from  
72 different source databases reduced to simple species presence records and mostly collected in an  
73 unstandardized way by volunteers. In contrast to presence-absence data, they are abundant but have  
74 poor quality, few metadata and come from different sources (Robinson et al., 2020). This introduces  
75 numerous sources of bias that need to be assessed and accounted for in modelling processes (Phillips  
76 et al., 2009, Guillera-Aroita et al., 2015). Common problems are heterogeneous sampling effort,  
77 conditions and methods, imprecise spatial and temporal resolutions and different levels of expertise  
78 among observers (Schulman, Toivonen & Ruokolainen, 2007; Phillips et al., 2009, Dickinson,  
79 Zuckerberg & Bonter, 2010; McKinley et al., 2017). Different methods have been developed to correct  
80 these biases, including sorting or weighting presence-data to reduce identification errors and pseudo-  
81 replication linked to sampling effort (Guisan & Theurillat, 2000; Phillips et al., 2009) and/or using  
82 sampling effort assumptions to establish pseudo-absence sampling strategies (Barbet-Massin et al.,  
83 2012). Understanding the structure and intensity of sampling effort in space is essential to determine  
84 whether an undetected species is truly absent. For example, it may be conditioned by site accessibility  
85 (Kadmon, Farber & Danin, 2004; Phillips et al., 2009), site attractiveness or observer distribution  
86 (Phillips et al., 2009; Robinson, Ruiz-Gutierrez & Fink, 2018). Not accounting for heterogeneous  
87 sampling effort or using erroneous assumptions to define it can lead to over-assessment of model  
88 accuracy and/or false interpretation (Schulman, Toivonen & Ruokolainen, 2007; Phillips et al., 2009;  
89 Guillera-Aroita et al., 2015).

90           SDM validation is challenging (Vaughan & Ormerod, 2005) but is a crucial step for applying  
91 results to conservation objectives. There is still debate about SDM validity, especially when presence-  
92 only data is used to calibrate models (Barve et al., 2011). Using data with the same spatial bias to  
93 calibrate and assess a model tends to over-estimate prediction accuracy, by modelling observation

94 processes more than ecological processes therefore producing erroneous results. Currently, testing  
95 model accuracy with a fully independent dataset is considered the most robust method for assessing  
96 SDM (Araujo et al., 2005; Guisan, Thuiller & Zimmermann, 2017). However, obtaining an external data  
97 set for large-scale studies is often cost prohibitive and exploiting data from protocolled citizen science  
98 programmes may in some cases provide the solution. For example, Robinson et al. 2020 have shown  
99 that using filtered large-scale citizen science data for SDM calibration can improve model accuracy.  
100 Alternatively, detection-nondetection data from more standardized citizen sciences programs which  
101 are rarer than opportunistic data but have higher quality could provide presence-absence sets for  
102 external validation of presence-only SDM. In addition, using presence-only and presence-absence data  
103 at different stages of the modelling process could be a method for combining different data sets with  
104 heterogeneous quality which is a current challenge to improve SDM validity (Zipkin & Saunders, 2018;  
105 Robinson et al., 2020).

106 Amphibians are among the most threatened taxa in the world with rapid and widespread  
107 population declines (Stuart et al., 2004). They are particularly sensitive to fragmentation and habitat  
108 loss (Cushman, 2006) because they need different resources during their life cycle involving  
109 movements (seasonal migration and dispersion) between aquatic sites (usually ponds) and terrestrial  
110 areas (Sinsch, 1990; Cushman, 2006). Many citizen science programmes have been initiated for  
111 monitoring amphibian species (e.g. De Solla et al., 2005; Schmeller *et al.*, 2008) and data collected have  
112 been used in some conservation studies to describe population trends (Petrovan & Schmidt, 2016),  
113 road effects (Cosentino et al., 2014), climate change (Préau et al., 2019) and large-scale species  
114 distributions (Brown et al., 2016). Despite abundant literature on amphibian ecology and the  
115 availability of several citizen science databases, few studies have attempted predictive amphibian  
116 distribution models at large scales (Graham & Hijmans, 2006; Brown et al., 2016; Préau et al., 2019).  
117 Therefore, amphibian data could be suitable for testing the capacity of different types of citizen data  
118 (presence-absence or opportunist) for calibrating and assessing SDM.

119 Here we compare the predictive performance of presence-only SDM for nine amphibian  
120 species using different types of data (*internal* presence-only or *external* presence-absence) from citizen  
121 science programs for their assessment. We also test the opportunity to use filtered standardized  
122 citizen science data to constitute the independent data set for external evaluation. We hypothesized  
123 that (1) the type of data used for validation (internal or external) would influence the assessment of  
124 model accuracy; (2) standardized citizen science datasets might be used as independent data for  
125 external evaluation of SDM using data filters and/or complementary fieldwork.

126

## 127 **Materials and Methods**

### 128 **1.1. Study area**

129 Our study was performed in Pays de la Loire (western France), a region covering 32 082 km<sup>2</sup> with low  
130 relief and bordering on the Atlantic Ocean to the west. The region has an extensive hydrographic  
131 network organized around the River Loire and its tributaries, influencing local climate and landscape  
132 configuration. Agricultural landscapes dominate the region and traditional hedgerow network  
133 landscapes associated with extensive livestock farming are recognized for their conservation value.  
134 Such mosaics of small pastures delimited by hedgerows and small woods and generally associated with  
135 dense pond systems (Baudry, Bunce & Burel, 2000) are favourable for many organisms including  
136 endangered species such as some amphibians species (Boissinot, Besnard & Lourdais, 2019). With 21  
137 known species (for 43 species recorded in France), the region has a high responsibility for the  
138 preservation of amphibians and their habitats, including traditional hedgerow landscape and wetlands.

139

### 140 **1.2. Biological data**

141 We studied habitat suitability of 9 amphibian species: *Bufo spinosus*, *Hyla arborea*, *Rana dalmatina*,  
142 *Rana temporaria*, *Triturus cristatus*, *Triturus marmoratus*, *Lissotriton helveticus*, *Salamandra*  
143 *Salamandra*, and *Pelodytes punctatus*. Two types of amphibian data were used: (1) opportunistic data  
144 from a citizen database with presence-only records for model calibration and internal evaluation (2)  
145 standardized detection-nondetection data from a citizen science programme and complementary field  
146 work for external evaluations. A more detailed description of the data sets and complementation  
147 strategies is available in Appendix 1.

#### 148 1.2.1. Opportunistic presence data (calibration and cross-validation dataset)

149 We accessed presence-only occurrences from a regional database for the period 2013-2019. 86% of  
150 the dataset was collected by citizens and recorded online (website or associated mobile application)  
151 and 14% by various professional organisations involved in nature protection. All data were compiled  
152 for the regional Atlas of amphibians by a French non-governmental organisation (French BirdLife  
153 partner - LPO). See Appendix 1 Table 1 for data sources. We retained only species with enough data  
154 according to number of predictors used (i.e. at least 477 presence cells; see Appendix 1 Table 2). We  
155 selected only precise GPS records (precision of the observation under 50 meters) and we checked all  
156 data for anomalies in geographical location or species identification.

157 For each species, we sorted data to reduce spatial autocorrelation by projecting presence data on a  
158 500m resolution grid and retaining only cells containing at least one occurrence as presence cells for  
159 the analyses (Guisan & Theurillat, 2000). We chose a 500m resolution as it is the mean size of species'  
160 home ranges (Semlitsch & Bodie, 2003). Finally, we excluded all opportunist data intersecting cells  
161 used for external validation described below to increase independency between calibration and  
162 validation sets.

#### 163 1.2.2. Standardised detection-nondetection data (external validation datasets)

164 For external validation, we firstly extracted *detection-nondetection* amphibian data for the period  
165 2013-2019 collected as part of a citizen science program called “Un Dragon dans mon Jardin”  
166 (Appendix 1 section 1.2.). We retained 576 sites which were monitored at least 3 times between  
167 February and June during at least one year and following a standard method commonly used for  
168 amphibian community surveys (Boissinot, Besnard & Lourdais, 2019). We called this dataset *CS.O* (see  
169 Figure 1). Some large areas of the region were not sampled due to lack of observers so that data were  
170 clustered near cities, with spatial autocorrelation. Therefore, with help from volunteers, we completed  
171 this dataset with some additional fieldwork and applied filters.

172 To complete and filter *CS.O*, different strategies were used. Firstly, we organised complementary  
173 fieldwork in 2018 and 2019 to complete two landscape gradients (woody element density and pond  
174 density) which are two variables known to strongly affect amphibian distribution and which are  
175 relevant in our regional context. All sites were selected randomly but so as to maximise and decorrelate  
176 the two landscape gradients in different areas (see Appendix 1 section 1.3.). In total, 263 sites were  
177 monitored: 132 sites by experts in 2018-2019 (called *PRO*, see Figure 1) and 131 by 75 volunteers in  
178 2019 (called *VOL*, see Figure 1). All data (*CS.O*, *PRO* and *VOL*) were projected on the same 500m  
179 resolution grid. One further problem, common in citizen science programmes (Geldmann et al., 2016),  
180 is that only aquatic sites are surveyed while areas known to be very unsuitable for amphibians such as  
181 urban areas and intensive agriculture are generally excluded. To reduce this source of bias, we  
182 randomly selected 5% more 500m grid cells in totally urbanized areas without aquatic sites and 5%  
183 more grid cells in homogeneous croplands without trees or ponds and we attributed “absence” values  
184 to each after field checks (called *ABS*, see Figure 1). These landscapes represent 9% of the total area of  
185 the region.

186 Secondly, we applied different filter combinations to establish sub-sets from *CS.O*, *PRO* and *VOL* (see  
187 Figure 1):

188 (1) a minimum distance of 1km between two grids containing data;



189 (2) threshold values to validate non-detection as absence data and exclude under-sampled sites,  
190 defined as a minimum sampling effort required to detect a species based on the species'  
191 detectability group and observer level of expertise. Four species detectability groups were defined  
192 from occupancy studies in France (Boissinot, 2009; Petitot et al., 2014) and the UK (Sewell, Beebee  
193 & Griffiths, 2010). Observers were classed as either *expert*, *intermediate* or *novice* using 3 criteria:  
194 number of years of participation, number of species observed and permit-holder for amphibian  
195 capture. A “*novice*” observer was considered more likely to miss or misidentify a species which was  
196 actually present than an “*expert*” observer for the same considered survey effort. In addition,  
197 novice observers did not use sampling nets, influencing detectability, in particular of Urodeles.  
198 Based on our observer classes and sampling methods used (e.g. acoustic, visual and/or fishing), we  
199 set threshold values for the minimal sampling effort needed to validate absence data, depending  
200 on species detectability (see Appendix 1 section 1.4. for details) and according to the results from  
201 Boissinot 2009 for minimum sampling effort needed to detect a focal species (with 95% probability)  
202 in a similar biological and landscape context.

203 (3) target species to valid nondetection as absence, as recommended by Phillips and co-workers in  
204 2009. So, if *species A* with the same detectability as *species B* is detected at a site, then *species B* is  
205 likely to be truly absent (see Appendix 1 section 1.5. for target species list).

206 (4) stratified sampling on final prediction maps (see STRAT\_CS and STRAT\_ALL in Figure 1). We  
207 established independent datasets, stratified by model predictions for each species (Newbold et al.,  
208 2010; Guisan, Thuiller & Zimmermann, 2017) with equal random sampling of validation cells with  
209 presence or absence data in 4 habitat suitability classes predicted (i.e. [0;0.3[, [0.3;0.5[, [0.5;0.7[  
210 and [0.7;1]). We obtained an equal number of validation cells by predicted suitability class (see  
211 1.4.3. for predictive map used).

212

### 213 **1.3. Environmental dataset and variables**

214 We assembled environmental data relevant to amphibian ecology and of importance in the study  
215 region (Guisan, Thuiller & Zimmermann, 2017). A more detailed description of variables with associate  
216 references is available in Appendix 2 Table 1.

217 Bioclimatic variables were accessed from a compilation of climate data for the period 1950-2000 at a  
218 spatial resolution of 5km<sup>2</sup> (Hijmans et al., 2005). An altitude variable was derived from the U.S.  
219 Geological Survey's Hydro-K data set, at the same spatial resolution. We performed a principal-  
220 components analysis (PCA) on 11 bioclimatic variables relevant for amphibians and the altitudinal layer  
221 to produce 2 uncorrelated axes (see Appendix 2 Table 4 and Figure 2). Land cover data were  
222 downloaded from the highly detailed vector database OCS GE 1.1 (IGN 2019), the Theia OSO Land  
223 Cover Map 2017 (available at [www.theia-land.fr](http://www.theia-land.fr)) and from BDTopo (IGN 2019). This was coupled with  
224 a more detailed regional inventory of hedgerows (from 2005 to 2008) and ponds (2012) and a national  
225 farming database from the EU LPIS (Land Parcel Identification System 2016) used to classify agricultural  
226 areas (see Table 1).

227 We calculated land-cover variables in windows composed of a 500m grid cell with a buffer of 300m  
228 (see Table 1). This took into account landscape context based on species' dispersal capacities as well  
229 as the resolution of the species data set (Guisan & Thuiller, 2005). Distance and home range differ  
230 among amphibian species but a 1km circle may be accepted as an average maximum range (Collins &  
231 Fahrig, 2017). Collins and Fahrig (2017) and Boissinot et al. (2019) show that landscape variables affect  
232 Anuran occupancy and diversity at this scale in agriculture-dominated regions. We use the same  
233 environmental variables for all species (see Table 1) except *B. spinosus* for which "pond density" (water  
234 point <5000m<sup>2</sup>) was substituted by "water point density" because of this species' ability to reproduce  
235 in larger water bodies with fish (Boissinot, Besnard & Lourdais, 2019).

236 All predictive variables were centred and scaled. The spatial correlation between environmental  
237 predictors was investigated using the variance inflation factor (VIF) as a measure of multicollinearity

238 and Pearson correlation tests with  $VIF < 6$  and  $r < 0.6$  as advised by O'Brien, 2007 (see Appendix 2 Table  
239 2 and 3).

240

## 241 **1.4. Habitat suitability modelling**

### 242 1.4.1. Statistical models

243 Different modelling algorithms can lead to varying results according to heterogeneous sensitivities and  
244 calculation processes (Thuiller et al., 2009). Therefore, consensus models based on multi-modelling  
245 approaches (ensemble-modelling) can improve final results by reducing 'noise' associated with  
246 individual model errors (Araujo et al., 2005; Thuiller et al., 2009; Meller et al., 2014). For each species,  
247 we used one regression-based approach (Generalized Additive Models, GAM) and one machine  
248 learning algorithm (Random Forest, RF) to predict and assess habitat suitability within the studied  
249 region with 50 bootstrap replicates. Presence points were randomly split 50 times into a training set  
250 (70% of the whole dataset) and the remaining 30% were used as testing set for internal evaluation (see  
251 1.4.). To construct these models, we used biomod2 package (Thuiller et al., 2009) in R environment v.  
252 3.5.3 (R Development Core Team, 2019).

### 253 1.4.2. Background data and pseudo-absence selection

254 Modelling habitat suitability for a species with GAM or Random Forest requires both presence and  
255 absence data. In order to overcome the problem of missing absence data needed for most SDM,  
256 pseudo-absence selection strategies have been developed to select absence data where real absence  
257 is most likely (Barbet-Massin et al., 2012, Phillips et al., 2009). We tested three strategies for generating  
258 artificial absence points: (s1) simple random selection of background points within the studied region  
259 (Guisan, Thuiller & Zimmermann, 2017); (s2) random pseudo-absence selection excluding known  
260 presence points (Engler, Guisan & Rechsteiner, 2004); (s3) random pseudo-absence selection  
261 constrained to take sampling effort into account (see Appendix 3 for method). The latter strategy

262 aimed to select pseudo-absences where true absences were more likely. For this strategy we  
263 considered three main sources of bias in pseudo-absence selection: accessibility, linked to distance  
264 from roads or urban areas (Kadmon, Farber & Danin, 2004; Barbet-Massin et al., 2012), attractiveness,  
265 relating to oversampling in protected sites or tourist areas (Phillips et al., 2009; Robinson, Ruiz-  
266 Gutierrez & Fink, 2018) and observer effort, because certain administrative areas are covered by  
267 particularly active nature protection organisations (see Appendix 3). For each strategy, the number of  
268 artificial absences was fixed equal to the number of presence data (Barbet-Massin et al., 2012; Liu,  
269 Newell & White, 2019) and we performed 10 replicates of the artificial absence generation processes.

#### 270 1.4.3. Ensemble modelling

271 Finally, we conducted ensemble modelling by calculating the median value of (1) all individual  
272 maps generated by GAM and Random forest (i.e. 500 maps/algorithm) (Thuiller et al., 2009) to  
273 compare internal *versus* external evaluation for each species. Secondly, we also calculated median  
274 values from ensemble maps calibrated with 100% of presence-only data to compare different external  
275 evaluations sets (i.e. 10 maps/algorithm).

276

#### 277 1.5. Internal and external model validation

278 We firstly use a cross-validation method using a 30% random split of the whole set to asses each model  
279 (for pseudo-absence selection strategies s1, s2 and s3) with 50 bootstraps repeated 10 times. We  
280 calculated the area under the curve (AUC) of a receiver operating characteristic (ROC) plot of the  
281 predicted model habitat suitability scores with (1) the 30% test dataset for internal validation and (2)  
282 with the larger filtered external independent dataset (e.g. *CS.2+ABS+SUP*, see Figure 1) using Biomod2  
283 package (Thuiller et al., 2009). AUC is the most common metric used in SDM studies, as it has the  
284 advantage of being threshold and prevalence independent and has been accepted as the standard

285 measure for assessing SDM accuracy (Guisan, Thuiller & Zimmermann, 2017). AUC > 0.50 signifies that  
286 the model has better prediction than a random model.

287 Secondly, we calculated AUC values, specificity (true negative rate) and sensitivity (true positive rate)  
288 of ensemble models calibrated with 100% of the presence-only data using different evaluation sets  
289 derived from the global external dataset used in the previous stage (see Figure 1). These calculations  
290 (with 100 bootstraps) were performed using PresenceAbsence package (Freeman 2012) with a  
291 standard threshold value for presence-absence discrimination fixed at 0.5.

292

## 293 **Results**

### 294 Model performance and selection

295 For each species, the median AUC was higher with internal validation than external validation for all  
296 three pseudo-absence selection strategies (s1, s2 and s3), both for GAM and Random Forest (see Figure  
297 2 and Appendix 4) with a delta-AUC ranging from 0.05 (*T. marmoratus*) to 0.21 (*B. spinosus*). With  
298 internal evaluation (cross-validation), all models had excellent (AUC>0.90) very good (0.80-0.90) or  
299 good accuracy (0.70-0.80) except for the model of *B. spinosus* and *H. arborea* including sampling effort  
300 parameters (s3). However, with external evaluation, only four species had a high level of accuracy  
301 (AUC>0.70): *S. salamandra*, *T. marmoratus*, *P. punctatus* and *R. temporaria*. For *R. dalmatina*, *T.*  
302 *cristatus* and *L. helveticus*, model accuracies were poor (0.60<AUC<0.70) and for *B. spinosus* and *H.*  
303 *arborea* even poorer (AUC<0.60). The strategy s1 (background data) was not selected neither with  
304 internal nor external evaluation.

305 The method used for pseudo-absence selection influenced the predictive performance of models but  
306 differences between AUC values were minimal (Figure 2). However, s2 (uncorrected sampling bias)  
307 was the best strategy for six species when internal validation was used, while s3 was best for seven

308 species when external validation was used. Results for RF can be found in the supplementary material  
309 but do not differ greatly (Appendix 4 Figure 1).

#### 310 Impact of model selection on final habitat suitability map

311 Internal or external validation resulted in different models being selected, based on AUC comparison.  
312 Therefore, the final habitat suitability maps selected by each of these two assessment methods would  
313 lead to different interpretation and conservation decisions. Maps for *H. arborea* and *B. spinosus* are  
314 not shown because of poor accuracy (see supplementary results Appendix 4). All response curves and  
315 associated variable contributions can be found in the supplementary material (Appendix 4 Figures 2  
316 and 3).

#### 317 Comparison of external evaluation sets

318 Values of AUC, sensitivity and specificity to four species are shown in Table 2 (two Anurans and two  
319 Urodeles; one forest species and one generalist specie each). Results for other species and CS.1 (similar  
320 to CS.2) are presented in Appendix 4 Table 3. Considering AUC values, evaluation with the external  
321 dataset from participative science without filter data (CS.0) show more similar model selection results  
322 than internal cross-validation except for *R. temporaria*. Sorting presence data led to decreased  
323 sensitivity and increased specificity for all species except for *S. Salamandra*. The models selected (s2  
324 or s3) were similar for most species whether using stratified data from volunteers' only (STRAT\_CS) or  
325 stratified data with added professional observations (STRAT\_ALL), or professional data only (PRO). See  
326 Table 2 and Appendix 4. We excluded the s1 model from the comparison because this model is never  
327 selected, either with internal or external evaluation.

328

#### 329 Discussion

330 External evaluation with independent data generated lower AUC values than cross-validation, which  
331 calls into question the validity of models validated by commonly used selection threshold values such  
332 as  $AUC > 0.70$ . According to Araujo et al. 2005, internal evaluation with non-independent data always  
333 leads to over-optimistic assessment of model performance. Even if cross-validation is better than  
334 substitution procedures (Araujo et al., 2005; Vaughan & Ormerod, 2005; Edwards et al., 2006), split  
335 data for internal validation are non-independent and do not avoid the main limits of correlative models  
336 in SDMs because of spatial or temporal autocorrelation, especially when sampling effort is highly  
337 heterogeneous (Edwards et al., 2006, Roberts et al. 2017). Our result supports criticisms of certain  
338 types of SDM and further highlights the need to be careful in their general interpretation and  
339 assessment (Lobo, Jiménez-valverde & Real, 2008).

340 The difference between internal-AUC and external-AUC is particularly pronounced for the most  
341 common and generalist species in spite of the large number of available data, especially for *B. spinosus*  
342 and *H. arborea* whose models failed to attain an acceptable level of accuracy with external evaluation.  
343 Brotons et al. 2004 highlighted the difficulty of predicting distributions of the most generalist species.  
344 However, for such species, the use of filters increases specificity values considerably and the results  
345 are coherent with these species' wide ranging and ubiquitous distributions. Using external presence-  
346 absence data also makes it possible to exploit the whole presence-only data set for calibration and to  
347 use stricter filters to reduce sampling bias or data culling to retain higher quality data (Steen et al.  
348 2019, Isaak et al. 2014). Our study shows that it is possible to apply strong filters (e.g. STRAT\_CS) but  
349 finally retain reasonable sample sizes for most species.

350 It should be noted that, for four species, *R. temporaria*, *T. marmoratus*, *S. salamandra* and *P.*  
351 *punctatus*, our results were ambiguous. For the first three, all forest-dwelling species or very closely  
352 related to woodlands (Boissinot, Besnard & Lourdais, 2019), both internal and external validation  
353 methods selected models with sampling effort integrated (s3). Two main reasons could explain these  
354 results: firstly, presence data may have been insufficient for *R. temporaria*, and secondly these species'

355 affinity for forest habitats. *R. temporaria* is a rare species and is more dependent on wet forest, flood  
356 meadows and small streams as breeding sites than other species (Boissinot et al., 2015). This species  
357 has a patchy distribution (i.e. locally abundant but regionally rare) and is difficult to detect. Hence,  
358 presence data are few in the studied area both in the opportunist dataset (N=477 presence-cells) and  
359 in the independent dataset (N=13 presence-cells). As highlighted by Vaughan & Ormerod (2005) such  
360 factors can lead to model over fit, even with a relatively small number of variables, resulting in high  
361 AUC values. In addition, according to Brotons et al. (2004), low-density habitat (i.e. forest habitat in  
362 our region) may be over-weighted and it can be difficult to assess between good or bad suitability  
363 without adapted presence-absence data. Monitored forest sites are rare in our validation dataset and  
364 the assumptions we used to define sampling effort may not be well adapted for forest specialists.  
365 Finally, *P. punctatus* is a rare species but abundant on the Atlantic coast. Unlike the other species, it is  
366 a pioneer, adapted to open areas, especially primary unvegetated habitats such as sand dunes and  
367 mudflats with frequent physical disturbance (Joly et al., 2005). These habitats are mainly located near  
368 the coast and along the main regional floodplains (Loire Valley), with a high local density of presence  
369 data. So this species is also patchily distributed and models may be affected by the same bias as *R.*  
370 *temporaria*. Alternatively, the similarity between AUC values may also relate to sampling effort bias  
371 along the Atlantic coast (e.g. Fithian et al., 2015). These results highlight the need to adapt methods  
372 and filters used for each species.

### 373 **Using heterogeneous data from citizen science in SDM**

374 The reduction of all available data to presence-only leads to loss useful information from the original  
375 data and the combined use of different data type and quality could improve SDM (Isaac et al., 2019;  
376 Robinson et al., 2020). Our results show that it is possible to obtain useful external and independent  
377 datasets for model validation from filtered protocolled citizen science data. Indeed, the use of filters  
378 have successfully reduce bias and noise in citizen science data sets for SDM in others studies (Robinson,  
379 Ruiz-Gutierrez & Fink, 2018; Isaac et al., 2019; Steen, Elphick & Tingley, 2019). In addition, filtered



380 evaluation dataset showed coherent results according to Phillips et al. 2009. Indeed, choosing pseudo-  
381 absence data with the same bias as occurrence data improved model performance.

382 Since external independent data is necessary for more robust assessment of SDM (Araujo et al., 2005),  
383 but prohibitive to collect, filtering low quality but large datasets from monitoring to obtain more  
384 standard and independent data may be worthwhile. In addition, AUC appears to be more informative  
385 when presence-absence data is used to assess and compare models than when presence-background  
386 data alone is used (Jiménez-Valverde, 2012). However, using detection-nondetection citizen data  
387 without filters may also lead to erroneous results because of overlapping sources of bias in both  
388 datasets (e.g. *CS.O* selects the same model as cross-validation). The large amount of available data  
389 allows us to strongly select data according to our research objective. Our results using *PRO* datasets  
390 are inconclusive for rare species perhaps because their detection was insufficiently frequent (e.g. only  
391 two observations of *R. temporaria* for 132 sampled sites). Finally, we found that general rules to guide  
392 data sorting were difficult to define. Our results were sensitive to the type of data used, and the species  
393 studied, reinforcing the need to define filters according to available data and species' ecology (Steen,  
394 Elphick & Tingley, 2019).

395 Independence between training and testing sets is an essential criterion, but data should also be  
396 unbiased or corrected. Selection methods have been developed to try to divide the opportunistic  
397 dataset strategically to increase the independence of the testing set for cross-validation (see Block-  
398 cross-validation in Robert et al. 2017). However, this method does not make it possible to escape from  
399 the general biases linked to sampling effort and/or can create extrapolation problems (see Robert et  
400 al. 2017). Using a more standardized dataset from a participatory science program (e.g. *CSO*) for the  
401 evaluation makes it easier to understand the sources of bias (presence of metadata and non-detection  
402 data), to better control them and to obtain more robust information on the absence data. However,  
403 these data may also share biases with the opportunistic dataset used for calibration. In our case, the  
404 sampling of the monitored sites (*CSO*) was partly biased towards volunteers' place of residence and

405 areas with a higher density of observers. These biases were reduced through additional sampling  
406 involving volunteers. Our results show that certain filters, as well as targeted complementary  
407 fieldwork, make it possible to reduce the biases identified and produce conclusive results. In addition,  
408 the use of a stratified sampling of the testing set along the suitability gradient from the SDM results  
409 (e.g. our STRAT\_CS and STRAT\_ALL datasets) appears to be a particularly interesting method showing  
410 stable and consistent results according to Phillips et al 2009.

411 However, our method may be not applicable in all cases. In our study, external data came from a  
412 program with general population monitoring objectives, using standard methods designed to be  
413 accessible to a wide audience (eg. novice and professionals). This program concerns all amphibians  
414 and their habitats, whereas many citizen science programs are limited to a particular taxonomic group  
415 or habitat type (cities, gardens or farms...) and would therefore be difficult to extrapolate to wider  
416 contexts.

#### 417 **Involved stakeholders and citizens in the research process**

418 Our study was part of a wider project for amphibian conservation in the Pays-de-la-Loire region of  
419 western France. Involving citizens in the SDM evaluation process may make conservation action easier  
420 to implement, through both better shared knowledge and stronger personal involvement. Forrester et  
421 al. (2017) and Lewandowski and Oberhauser (2017) highlighted an increase in conservation advocacy  
422 among participants of citizen science projects that might improve access to evidence for  
423 conservationists and decision makers (Sutherland & Wordley, 2017). Maps are a specially a good tool  
424 for improving communication between researchers and volunteers in the context of citizen science  
425 (Zapponi et al., 2017). Indeed, many nature protection organisations are already involved in  
426 distribution atlas projects and naturalists are aware of data collection methods and local species  
427 distributions. They seek out ways to prioritise field observations; making a useful contribution to  
428 developing SDMs to guide conservation action can be a source of motivation, making scientist-  
429 volunteer interactions easier.

430 **Acknowledgements**

431 This work would not have been possible without the support of the Pays de la Loire Herpetological  
432 Group, the CPIE Regional Union and the French BirdLife International partner (LPO). We are especially  
433 grateful to Benoit Marchadour (LPO) who coordinates the regional distribution atlas. We also  
434 acknowledge the many naturalists involved, for access to data and for additional fieldwork, especially  
435 Dorian Angot, Anne-Lise Charpentier, Baptiste Gaboriau, Ludovic Aubry, Jeanne Abbou, Flore Gamet,  
436 François Varenne, Adrien Maitrepierre, Leslie Michal, and Martin Bonhomme. We thank Xavier  
437 Lozupone for his help for mapping of environmental variables at regional level and Véronique  
438 Beaujouan, Adeline Bulot, Hervé Daniel, Gilles Martel and Aurélien Besnard for providing helpful  
439 discussion. Our work was supported by funding from Angers Loire Metropole, The French Society for  
440 Ecology and Evolution and “Humanity and Biodiversity”.

441 **Author contributions**

442 F.M., M.S., G.P., J.B. and J.P. contributed to the original idea. F.M. collected biodiversity data, M.S. and  
443 F.M. coordinated the voluntary work. F.M. analysed the data and led the writing of the manuscript. All  
444 authors contributed critically to the drafts and gave final approval for publication.

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