1	Title: Evolution of the genetic architecture of local adaptations under genetic rescue is
2	determined by mutational load and polygenicity
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4	Running title: Local adaptations under genetic rescue
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18	Abstract:
19	Inbred populations often suffer from heightened mutational load and decreased fitness
20	due to lower efficiency of purifying selection at small effective population size. Genetic
21	rescue (GR) is a tool that is studied and deployed with the aim of increasing fitness of such
22	inbred populations. The success of GR is known to depend on certain factors that may vary
23	between different populations, such as their demographic history and distribution of
24	dominance effects of mutations. While we understand the effects of these factors on the
25	evolution of overall ancestry in the inbred population after GR, it is less clear what the effect
26	is on local adaptations and their genetic architecture. To this end, we conduct a population
27	genetic simulation study evaluating the effect of several different factors on the efficacy of
28	GR including trait complexity (Mendelian vs. polygenic), dominance effects, and

29 demographic history. We find that the effect on local adaptations depends highly on the mutational load at the time of GR, which is shaped dynamically by interactions between 30 demographic history and dominance effects of deleterious variation. While local adaptations 31 are generally restored post-GR in the long run, in the short term they are often compromised 32 33 in the process of purging deleterious variation. We also show that while local adaptations are almost always fully restored, the degree to which ancestral genetic variation comprising the 34 trait is replaced by donor variation can vary drastically, and is especially high for complex 35 traits. Our results provide considerations for practical GR and its effects on trait evolution. 36

37

38 **Keywords:** Genetic rescue; conservation genetics; local adaptations; mutational load;

- 39 dominance; demographic history; polygenic traits
- 40

41 **1. Introduction**

Genetic rescue (GR) is a strategy used in conservation biology to increase fitness of an endangered inbred (recipient) population by introducing genetic variation from another (donor) population. GR is accomplished by assisted migration of individuals from closely related, healthy populations to the inbred imperiled population. This process naturally causes the replacement of local genetic variation in the recipient population with that of the donor population. Typically, only a small number of individuals are introduced in order to conserve local genetic variation (Whiteley, Fitzpatrick, Funk & Tallmon, 2015).

The strategy has now been practiced on many highly inbred populations from different 49 taxa, including the Florida panther (Johnson et al., 2010), robins (Heber et al., 2012), guppies 50 (Fitzpatrick et al., 2016), wood rats (Smyser et al., 2013), and adders (Madsen et al., 1999). In 51 several cases, GR efficiently increased the absolute fitness of the inbred population and 52 reduced inbreeding depression (Frankham, 2015). A famous example is the introduction of 53 54 mountain lions from Texas of the sub-species P. c. stanleyana to the Florida P. c. coryi population, for which the number of P. c. corvi increased three-fold after only five years, with 55 increased survival rates and a doubling of the heterozygosity (Johnson et al., 2010). A meta-56

analysis provided evidence that the beneficial effect of GR can persist through the F3
generation (Frankham, 2016). These empirical tests suggest that GR is a powerful
conservation tool for increasing fitness in endangered inbred populations.

However, despite its promise, there is skepticism and caution towards the application of 60 GR due to concerns about outbreeding depression and genetic homogenization (Bell, et al. 61 2019). In the case of the Florida panther, an estimated genetic replacement of 41% has been 62 reported. In another case of the Isle Royale wolf, the immigration of one single male to Isle 63 Royale caused a genetic replacement of 56% to the local inbred population within two 64 generations (Adams et al. 2011). Hwang et al (2012) also reported a negative fitness effect 65 after practicing GR with two species that are genetically highly divergent due to outbreeding 66 depression. 67

Several different theoretical studies have been conducted to examine the expected 68 efficacy of GR (Hedrick, Hellsten & Grattapaglia, 2016; Harris, Zhang & Nielsen, 2019; 69 Tallmon et al., 2004; Frankham, et al., 2011). The dynamics of GR is complex, depending on, 70 among other factors, the amount of gene-flow, the demographic model (e.g. effective 71 population size), and the dominance coefficients of mutations. Harris et al (2019) showed that 72 with a higher amount of introgression, the relative fitness of the recipient population recovers 73 more quickly; however, this occurs at the cost of replacing an increasing proportion of the 74 75 recipient's ancestral genomes with those of the donor population. Demographic history of the recipient and donor populations also determines the dynamics of GR. For example, small 76 effective population size (N_e) limits the efficacy of natural selection; thus, in most cases 77 admixture from a population with large N_e helps restore fitness (Harris et al., 2019). However, 78 several studies have shown that demography and dominance of deleterious mutations have 79 key interaction effects on the GR process (Harris et al., 2019; Kyriazis, Wayne & Lohmueller, 80 81 2019). For example, Kyriazis et al (2019) showed that fitness in populations with historically 82 low N_e can be more robust to severe bottlenecks than those with historically large N_e , as these populations are less efficient at purging recessive deleterious mutations. 83

84 Previous studies suggest that the genetic replacement caused by GR can be controlled if

85 the amount of admixture is limited (Harris et al., 2019; Whiteley et al., 2015; Bell et al., 2019). However, whether local adaptation plays a role in GR remains an open question. 86 Recently, Osmond & Coop (2019) investigated the population genetic signatures of selective 87 sweeps under evolutionary rescue, i.e. the adaptive response and recovery from reduced 88 absolute fitness due to environmental change. Also, Tomasini & Peischl (2019) investigated 89 the effect of local adaptations on evolutionary rescue. But whether GR would lead to the loss 90 of unique local adaptations, or whether local adaptations could affect the process of fitness 91 restoration by GR, remain largely unexplored. 92

Here, we explore how the addition of linked locally-adaptive variation affects the GR process. Specifically, we explore the dynamics under GR of (1) a Mendelian trait, and (2) a polygenic trait under stabilizing selection with a shift in the optimum. Our results illustrate how the genetic architecture of adaptive traits evolve under GR, and how the dynamics of GR depends on the joint effects of demographic models and genetic factors such as dominance.

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99 2. Materials and Methods

We simulate under two demographic models from Harris, et al. (2019), as illustrated in 100 101 Figure 1. The simulations are conducted using SLiM (Haller & Messer, 2019). Model 1 (Fig. 1A) represents a population that undergoes a long-term bottleneck of 0.1 times the ancestral 102 103 population size ($N_e=10^4$), which last for 16,000 generations. This demographic history represents a population that is inbred for a long period of time and is similarly to that 104 estimated for Neanderthals by Prufer et al. (2014). Neanderthals represent a good example of 105 a long-term inbred population where genomic analyses have discovered a substantial 106 accumulation of deleterious alleles (Prufer et al., 2014). Model 2 (Fig. 1B) represents instead 107 a population with an extreme, short-lived bottleneck with $N_e=10$ that lasts for 20 generations, 108 which might be more representative of many currently endangered species. Prior to the time 109 110 of divergence, we conduct a burn-in phase of 44,000 generations. We simulate two modes of adaptation: a Mendelian trait, with only one adaptive site contributing to the trait, and a 111 polygenic trait controlled by a large mutational target. 112

113 We simulate the Mendelian trait under two selection models: (1) a hard sweep, in which a 114 rare additive beneficial mutation occurs after the split of the population, and (2) a soft sweep 115 from a standing variant, in which an allele segregating neutrally leading up to the split is 116 picked at random, and its selection coefficient is then changed so that the allele is then 117 beneficial. Selection acts on the trait only after the split of two populations. For both models, 118 we have examined different selection coefficients, $s = 10^{-4}$, 10^{-3} , and 10^{-2} for the adaptive 119 mutation.

We simulate the polygenic trait under a model of stabilizing selection with Gaussian 120 fitness. To model the effects of local adaptation in the recipient population we allow the 121 phenotypic optimum in this deme to increase by some amount, immediately following the 122 divergence from the ancestral population. With V_S as the variance of the fitness function (not 123 to be confused with the variance in fitness among individuals), we simulated scenarios where 124 the inbred population's phenotypic optimum shifts by $\delta = 1, 2, 5$ immediately after the split, 125 while the phenotypic optimum remains 0 for the outbred population. We considered different 126 selection strengths by setting the variance of the fitness function to be $V_S = 3,000$ and 10,000. 127 We assume genetic effects among loci are purely additive. Under this model, at equilibrium 128 129 (phenotypic mean equal to the optimum), alleles are under under-dominant selection with $s = a^2/V_s$, where a is the effect of the allele, on the same scale on which the fitness 130 function is defined (Simons, et al. 2018). In the transient phase after a large shift in the 131 optimum, selection is approximately additive with $s = a\delta/V_s$ (Hayward & Sella, 2019). In 132 order to ensure selection coefficients of causal SNPs are roughly $s \sim 10^{-4} - 10^{-3}$, in line 133 with current estimates that SNPs ascertained for complex traits in humans have been under 134 weak selection (Simons, et al. 2018), we draw the effects of causal alleles (a) from a standard 135 normal distribution (i.e. mean 0 and variance 1). See Table S1 for more details. 136

In addition to the adaptive mutations described above, we also allow for accumulation of deleterious mutations assumed to be (1) additive (h=0.5), (2) partially recessive (h=0.1) and (3) recessive (h=0), where h is the dominance coefficient. To specify a set of simulation parameters realistic for mammals, we chose parameters estimated in humans for

recombination rates and distribution of fitness effects. We use the UCSC exon map from the
HG19 genome and the Distribution of Fitness Effect (DFE) on non-synonymous mutations
estimated by (Eyre-Walker, Woolfit, & Phelps, 2006), assuming a non-synonymous mutation
rate of 7×10⁻⁹ per bp/generation and log additive interactions among selected loci. A summary
of the simulations is provided in Supplementary Table S1.
For all simulations, we have recorded fitness in the inbred population relative to that of

147 the outbred population, the ancestry proportion in the inbred recovering population, the 148 varying allele frequency of the adaptive mutation in the Mendelian model, and the fluctuation 149 of mean phenotype in the stabilizing selection model.

150

151 **3. Results**

152 *3.1 Selection on Mendelian traits*

We simulated a Mendelian trait that is fixed for the derived (locally adaptive) allele in the recipient population, and fixed for the ancestral allele in the donor population. We varied the selection coefficient on the trait, the dominance coefficient of the linked deleterious variation, the admixture proportion during GR, and the demographic model (Model 1 vs. Model 2, see Fig. 1).

We investigated the effect of GR on fitness in the recipient population (i.e. hybrid fitness, 158 Fig. 2 A-C) as well as on ancestral genome proportion (Fig. 2 D-F). Fitness is measured by 159 taking the average of the fitness of offspring in the recipient population, and normalizing by 160 the same quantity for the donor population. The fitness calculated in generation T is the 161 fitness of parents (rather than offspring produced) in generation T. We found that, depending 162 on the demographic model and dominance of deleterious variation, GR has drastically 163 different success in terms of achieving rapid increase in hybrid fitness. For example, when 164 deleterious mutations are partially recessive, GR is successful but somewhat slow for Model 2 165 (Fig. 2E). In Model 1, under the same scenario, fitness is not fully recovered even after 1000 166 generations post admixture with 10% admixture from the donor population (Fig 2B). By 167 contrast, under a fully recessive load, fitness is restored extremely quickly under Model 2, 168

provided sufficient admixture (1%), whereas with the same level of admixture in Model 1,
fitness is not restored even in the long run (>1000 generations post admixture) (Fig 2C).
Generally, we find that the lower the recipient fitness before admixture, the higher the amount
of genomic replacement by the donor population in the long run (Fig. 2D-F). Furthermore, the
more successful the GR is at restoring fitness, the higher the amount of genomic replacement
in the long run (Fig. 2C,F). These conclusions are similar to those previously observed by
Harris *et al.* (2019).

We also considered how ancestry and fitness evolve jointly in the recipient population 176 (Fig. 3). Here, we show dynamics for a population under Model 2 with recessive deleterious 177 variation. We found that in the first generation after GR, native ancestry is either 0 or 100% in 178 the parents, where native ancestry is associated with much lower fitness (Fig. 3A). After one 179 generation of admixture, a large proportion of offspring were inbred-outbred crosses, despite 180 low admixture proportion (1%). Due to the large fitness advantage associated with outbred 181 ancestry, these crossed individuals enjoyed much higher fitness than not only the inbred 182 individuals, but also the non-crossed outbred individuals, because it is extremely rare for 183 these crosses to be homozygous for recessive deleterious variation (it would require a 184 185 recessive deleterious variant to segregate in both inbred and outbred populations since divergence up to the admixture). In the following generations, as ancestry proportions range 186 between ~30-90%, there is a clear trend of lower native ancestry incurring increased hybrid 187 fitness (Fig. 3C,D) 188

A short term bottleneck (Model 2) does not increase or decrease the average number of 189 mutations an individual carries. However, it will allow recessive deleterious mutations of 190 strong effect, which were already segregating in the population, to increase in frequency and 191 potentially go to fixation (while others are lost). Models of recessive mutations allow for 192 193 much more standing variation of deleterious mutations, that potentially can increase in 194 frequency during the bottleneck, than models of additive mutations (e.g. Fig. 2A vs 2C). GR is particularly effective in this case because the recipient population may have fixed strongly 195 deleterious recessive mutations that can be purged immediately after GR (Fig. 2C). In the case 196

of a constant low population size (Model 1), deleterious mutations (both in the recessive and
additive model) will accumulate and can slowly go to fixation if they have weak effects, but
one is unlikely to observe the same kind of strong effect of strongly deleterious recessive
mutations going to fixation as you would in models with recessive mutations and a bottleneck
(Fig. 2B-C).

Next, we looked at the dynamics of local adaptations under a Mendelian trait model (i.e., 202 a single adaptive allele). We found that, in the short term (0-100 generations post-GR) the 203 adaptive allele decreases in frequency following the loss of ancestral DNA fractions (Fig. 4; 204 Fig. S1), which is the consequence of a selection-induced reduction in native ancestry after 205 the admixture (Fig. 2D-F). However, while the ancestral genome proportion continued to 206 decline slowly after 10 generations after GR (Fig. 2D-F), the adaptive allele generally 207 increased in frequency after 10-100 generations when enough recombination occurred to 208 break up linkage between the adaptive allele and the deleterious alleles. However, even for 209 very strong selection (s = 0.01), it took hundreds of generations for the adaptive allele to reach 210 high frequency in the population. In some extreme cases, with sufficiently high levels of 211 admixture (10%), GR under Model 2 actually caused the adaptive allele to be lost with high 212 213 probability after a total genetic replacement when the selection coefficient is sufficiently small (≤ 0.001) (Fig. 4F). 214

We also examined the joint effects of dominance coefficients of linked deleterious 215 variation and demographic history on the efficacy of GR. Under both model I and II, we saw a 216 217 greater degree of genetic replacement (Figure 2D-F), leading to a greater reduction in the frequency of the adaptive allele, as deleterious mutations become more recessive (Fig. 3 & 218 S1). For example, there was a smaller short-term reduction in allele frequency of the adaptive 219 allele under Model 2 (Fig. 4D-F, Fig. S1 D-F, relative to Model 1 [Fig. 4A-C, Fig. S1 A-C]) 220 but a larger reduction for partially recessive/recessive deleterious variants (Fig. 4B,C,E,F, Fig. 221 S1 B,C,E,F), following the same pattern of the ancestral DNA proportion decline in those 222 scenarios (Fig 4. G-H). However, the locally adaptive locus itself had only a minor effect on 223 the recovery of relative fitness and reduction of ancestral DNA proportion of the recipient 224

population (Fig. 4, 5, S1, S2, S3). We considered that sweeps from standing variation may
have different patterns of linked deleterious variation around the adaptive allele; however,
when simulating under alternative selection models we found no difference between the hard
vs soft sweep models (see Fig. 4, S2, S3 vs Fig. S4, S5, S6).

229

230 *3.2 Polygenic adaptation*

We also simulated a polygenic trait under a model of stabilizing selection with a shift in the optimum (Fig. 5-7). Here we varied the strength of stabilizing selection on the trait (controlled by $\sqrt{V_s}$, the 'width' of the fitness function), the size of the shift in the local optimum after population 2 diverges from population 1, $\delta = 0,1,2,5$, measured in units of $\sqrt{V_s}$), dominance coefficient of deleterious mutations, admixture fraction during GR as well as demographic model.

We examined two features of polygenic trait evolution: first, we evaluated the effect of GR on the perturbation of the adaptive phenotype from its optimum (Fig. 5, Fig. S7); we measure this by looking at the average distance of the population mean phenotype from the optimum. We also considered the extent of replacement of ancestral variation causal for the trait (Fig. 6); we measure this replacement by examining the relative proportion of genetic variance of the trait due to ancestral variation *vs* donor variation introduced by GR.

We found that under Model 1, polygenic adaptations are not significantly affected by GR, 243 as the trait's evolution appears to follow the same trajectory regardless of admixture 244 proportions or dominance coefficients of the deleterious load (Fig. 5A-C). However, under 245 Model 2, we found that following rapid phenotypic drift from the optimum due to a severe 246 bottleneck (Fig. S7), polygenic adaptations subsequently follow dramatically different 247 trajectories depending on several factors (Fig. 5D-F): for example, GR allows the polygenic 248 adaptation to recover to its optimal value much more quickly than without GR (Fig. 5F); and 249 this effect is most pronounced under scenarios where there is fully recessive load (Fig. 5F), 250 251 although it is still significant under a partially recessive load (Fig. 5E). We also explored how the genetic basis of the polygenic adaptation in the recipient 252

253 population is replaced by donor variation (Fig. 6). We quantify this using the proportion of the genetic variance attributable to standing variation in the recipient population just before 254 admixture; genetic variance post-admixture is the sum of this quantity, plus genetic variance 255 attributable to standing variation in the donor population just before admixture, plus that of *de* 256 novo mutations occurring in the recipient population post-admixture (although this has 257 negligible contributions over short timescales). Generally, we find that the genetic basis is 258 quickly replaced due to GR, with >90% of the genetic variance being replaced with donor 259 variation when GR is most successful; for example, under Model 2, especially when the 260 deleterious load is recessive and the admixture fraction is high (Fig. 6A). Broadly, patterns of 261 genetic variance replacement are consistent with patterns of ancestry replacement (Fig. 6 vs. 262 Fig. 2D-F), with stronger replacement in situations where GR is more successful at recovering 263 fitness. However, details of the local adaptation do affect the dynamics of how the genetic 264 variance evolves; for example, when the optimal phenotype is more highly diverged in the 265 recipient vs donor population, the fraction of the genetic variance replaced by the donor 266 population is lower (Fig. 6B), because in this case donor individuals are more poorly adapted 267 to the environment of the recipient population, and thus GR is countervailed by this force. 268 269 Lastly, we directly compared hybrid fitness trajectories under the Mendelian vs. polygenic trait models (Fig. 7). We found that, under the simulations models we considered, 270 271 varying parameters controlling the local adaptation does not have any appreciable effect on hybrid fitness as an outcome of GR. In Fig. 7 we compare simulations of a Mendelian trait 272 under strong selection vs. a polygenic trait under strong stabilizing selection (see Methods). 273 The results are comparable both under Model 1 and Model 2 (Fig. 7A, B vs 7C, D) and under 274 various levels of dominance (Fig. 7). 275

276

277 **4. Discussion**

We have presented a population genetic simulation study that elucidates the dynamics of local adaptation and genetic rescue (GR). We considered various models of the selection strength and architecture of the adaptive trait, dominance of the mutational load, demography,

and admixture. The results of our simulations show that when a locally adaptive trait consists
of a single locus (e.g. a Mendelian trait), GR decreases the allele frequency in the short term.
Dominance of the linked deleterious variants and demographic history of the population
jointly determine the degree of its short-term loss while the strength of positive selection
determines the rate of trait recovery.

There are substantial differences in the evolutionary dynamics of the Mendelian trait and 286 the polygenic trait under GR. In simulations of a polygenic trait, the consequences of GR on 287 the trait is decided by both the loss of genetic materials as a whole and the distance between 288 the phenotype and its optimum before admixture. Generally speaking, it takes about 100 289 generations for a polygenic trait to return to its optimum in most cases, which is shorter than 290 that for a Mendelian trait under the same situation. Because polygenic traits have large 291 mutational targets, causal genetic variation that was previously exclusive to the donor 292 population is introduced to the inbred population via GR; this variation quickly replaces 293 native causal genetic variation, which is linked to many deleterious alleles. Thus, the 294 apparently higher efficiency with which the polygenic adaptation is restored comes at the cost 295 of long-term replacement by genetic variation from the donor population. We also showed 296 297 that the distance of the phenotypic optimum between the donor and the recipient population has appreciable influence on how much genomic replacement is incurred by GR. 298

299 Our results demonstrate a marked difference between a long-term small effective population size (Model 1) and a short-term severe bottlenecks (Model 2), with the latter 300 interacting strongly with the dominance of the deleterious mutation load. Our simulations 301 assume that, following GR/admixture, the effective population size of the recipient population 302 immediately recovers to the full size of the ancestral population. Future directions could 303 consider more gradual recoveries in the effective population size, possibly by using 304 305 evolutionary rescue models such as those discussed by Osmond & Coop (2019). Thus, our 306 models show GR operating at the upper limit of its efficiency, since the aforementioned alternative models would have strictly lower effective population sizes in the short term 307 following admixture. 308

309	One caveat of our results is that our simulations do not assume epistasis and, therefore,
310	does not allow for the evolution of Dobzhansky-Muller incompatibilities (DMIs). However, in
311	the presence of DMIs, outbreeding depression may lead to limited genetic replacement or
312	even reduce the absolute fitness after GR.
313	Although our results suggest that locally adaptive traits, especially those that are
314	Mendelian or moderately polygenic, will be strongly affected by GR in the short term, but the
315	causal variant is generally retained and returns to fixation in the long run. While locally
316	adaptive polygenic traits are less susceptible to shifts due to GR, their underlying genetic
317	architecture is highly susceptible to long-term replacement by donor ancestry.
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- 384
- 385 Data accessibility
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- 387 Scripts are available on GitHub at https://github.com/YulinZhang9806/GR_adaptation_scripts.
- 388

389 Authors contribution

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AJS and RN conceptualized the study; YZ and AJS designed the methods; YZ wrote the
software; YZ and AJS conducted the analysis; YZ and AJS wrote the manuscript; YZ, AJS, and
RN edited the manuscript; AJS and RN supervised the research.

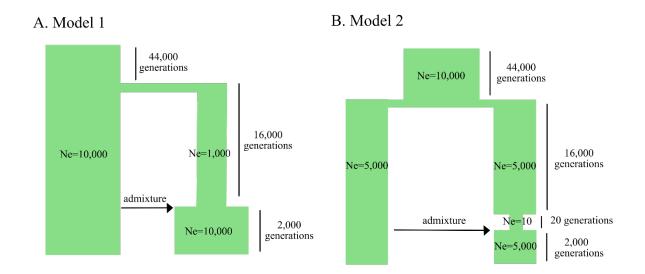


Figure 1. Two demographic models used for simulations. Time runs from top to bottom. Admixture happens at the generation right after the population size increases and lasts for only one generation. Population size changes are assumed to be discrete as depicted in the figure. Samples are taken from the inbred population on the right (p2) after the admixture up to 2,000 generations.

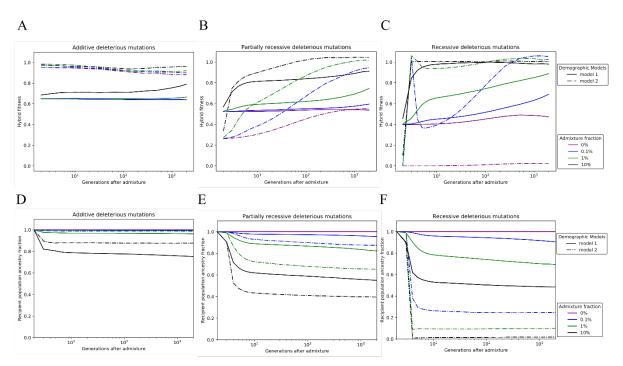


Figure 2. (A-C) Hybrid fitness change of the inbred population after admixture and (D-F) Recipient population ancestral genome fraction changes after GR with a Mendelian adaptive trait, under hard sweep selection model and demographic Model 1 (solid lines) and demographic Model 2 (dashed lines). The adaptive mutation is additive (dominance coefficient h=0.5) while selection coefficient is set differently (shown with different line styles in A-F). Deleterious mutations are assumed additive (h=0.5) in A, D, partially recessive (h=0.1) in B,E and recessive (h=0) in C,F.

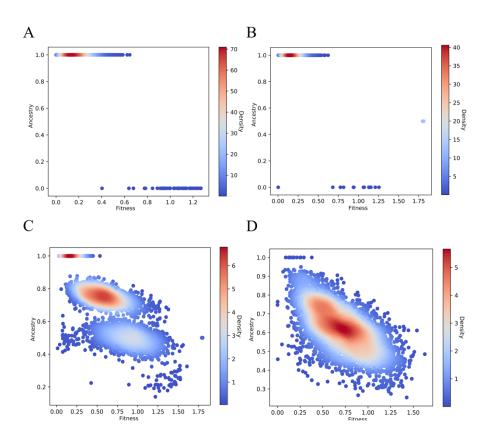


Figure 3. Relation between individual fitness and its ancestral genome proportion under demographic Model 2, with recessive deleterious mutations and admixture fraction of 1%. Each dot represents an individual, depicting relation between ancestry proportion and relative fitness (to the mean fitness of the outbred population) of each individual in the inbred recipient population. Figure A shows the population before mating with outbred individuals. Figure B indicates the first generation after admixture (e.g. F1), while figure C represents the second generation (e.g. F2) and figure D shows the third generation (e.g. F3).

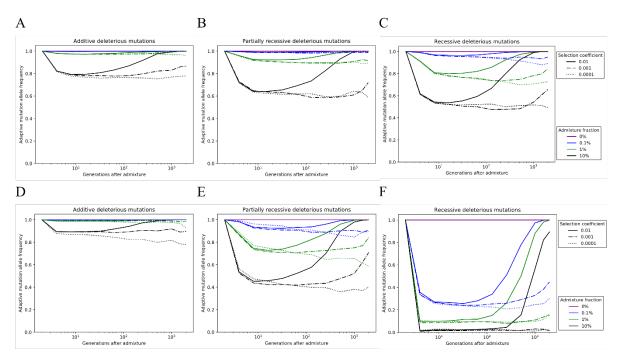


Figure 4. Allele frequency changes after admixture for a Mendelian trait under hard sweep selection model and (A-C) demographic Model 1 (D-F) demographic Model 2. The adaptive mutation is additive (dominance coefficient h=0.5) while selection coefficient is set differently (shown with different line styles). Deleterious mutations are assumed additive (h=0.5) in A, D, partially recessive (h=0.1) in figure B,E and recessive (h=0) in C,F.

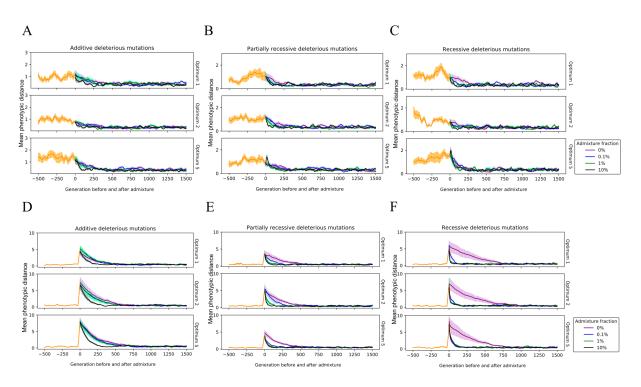


Figure 5. Mean phenotype distance from optimum over time. (A-C) Simulations under Model 1, (D-F) simulations under Model 2. Shaded bars signify 95% confidence intervals for the mean phenotypic distance.

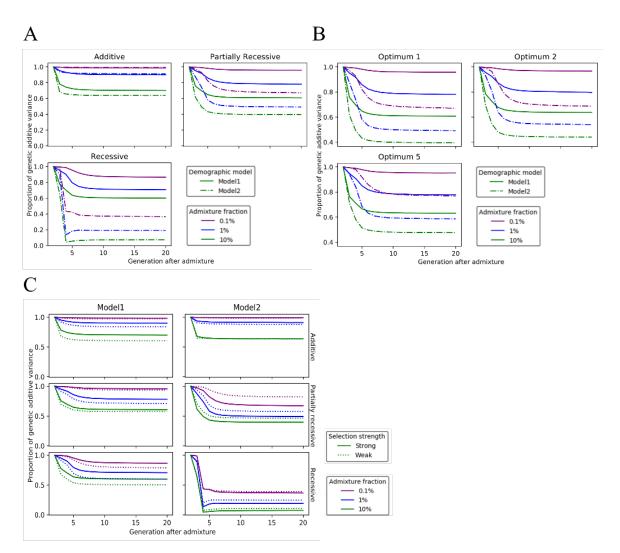


Figure 6. Proportion of genetic additive variance of a polygenic adaptation, recording mutations that originate from the recipient population for 20 generations after GR. (A) Scenarios under strong selection, with optimum of 1 for the recipient population and different dominance coefficients for deleterious mutations. (B) Scenarios under strong selection, with partially recessive deleterious mutations and different optimum for the recipient population. (C) Scenarios with optimum equals 1 and different selection strength for the adaptive trait. Each line represents the proportion of genetic additive variance contributed by variants, which compose the trait, from the ancestral genome of inbred population. Here, genetic additive variance is calculated as $G = \sum_{l \in SNPs} 2a_l^2 p_l (1 - p_l)$, where a_l represents the effect of SNP l, and p_l its frequency.

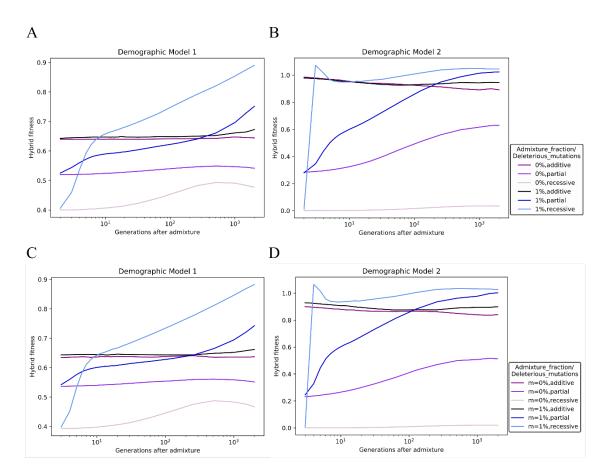


Figure 7. Hybrid fitness changes of the inbred population after admixture with (A-B) a Mendelian adaptive trait, under hard sweep selection model and (C-D) a polygenic trait under stabilizing selection with strong selection. Figure A and C are results of demographic Model 1 while B and D are that of demographic Model 2. Lines of different colors are indicating scenarios with different admixture fraction and dominance (of deleterious mutations).