Scaling dictates the decoder structure

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ABSTRACT

Despite variability in embryo size, the tissue, organ and body plan develop *in*
proportion with embryo size, known as the scaling phenomenon[1-7]. Scale-invariant
patterning of gene expression is a common feature in development and regeneration,
and can be generated by mechanisms such as scaling morphogen gradients[8,9] and
dynamic oscillation[10,11]. However, whether and how static non-scaling morphogens
(input) can induce a scaling gene expression (output) across the entire embryo is not
clear[2,12,13]. Here we show that scaling requirement sets severe constraints on the
geometric structure of the input-output relation (the decoder), from which information
about the regulation and mutants' behavior can be deduced without going into any
molecular details. We applied and tested our theory on *Drosophila* gap gene system[14-
17] using the three maternal gradients (Bcd, Nos and Tor) as input. Remarkably, the
parameter-free decoder correctly and quantitatively accounted for the gap gene
expression patterns in nearly all morphogen mutants. It also revealed the regulation
logic and the coding/decoding strategy of the gap gene system. Our work provides a
general theoretical framework on a large class of problems where scaling output is
induced by non-scaling input, as well as a unified understanding of scaling, mutants'
behavior and regulation in the *Drosophila* gap gene and related systems.

In development and regeneration, a cell has to know its position in space in order

to determine its fate. Often this positional information is encoded in a space-dependent

signal like morphogen gradient[2,14,18]. The decoder in the cell (usually gene networks)

reads the local value of the signal to infer its spatial position by expressing the

appropriate genes, as exemplified in the French-flag model[2,19,20]. A common feature in

these processes is that the gene expression pattern generated by the decoder is often

scale-invariant with respect to fluctuations in the overall length of the system, which

ensures the organism develops in the correct proportion[6,7,21-24]. A scale invariant output

can be achieved with a scale invariant input. Indeed, this strategy is adopted by systems

such as *Xenopus* embryo[8,25], *Drosophila* wing[9,26,27] and probably *Drosophila*

dorsoventral axis[28], where the morphogen itself scales with the system size. However,

achieving scale-invariant patterning from non-scaling morphogens is still largely an

open question. A prototypical example is the scaling of *Drosophila* segmentation gene

patterning[12,23,29-35], in which the gradients of the maternal morphogens seem to have

fixed length constants that do not scale with the embryo size[29,33,35-38]. In this paper, we

first establish a general theoretical framework. We show that the necessary and

sufficient condition for a decoder to generate a scale-invariant expression pattern from

non-scaling morphogens contains rich information on the geometric structure of the

decoder. We then apply and test our theory on the *Drosophila* gap gene system,

providing a comprehensive understanding on this classic scaling problem.

Geometric structure of the decoder and the fate map

We first illustrate our basic idea using a bi-gradient model[2,12,13]. In this simplified

model, there are two morphogens, M_1 and M_2, having anterior and posterior exponential

gradients with a fixed length constant λ (Fig. 1a, length of a standard-sized embryo is

defined as $L=1$). For larger (smaller) embryos, the effective length constant should

shrink (expand) if measured in the relative coordinate ($y \equiv x/L$, $M_1 = e^{-yL/\lambda}$, $M_2 =$

$e^{-(1-y)L/\lambda}$, Fig. 1b). Consider for example the position $y=0.35$ as the boundary

separating two different cell fates in the embryo. In a smaller (larger) embryo, as the

absolute distance to both termini are shorter (longer) at this position, local levels of both

morphogens are higher (lower). When L varies, the $y=0.35$ point traces out a line on the

M_1-M_2 plane (Fig. 1c). Therefore, in order to achieve perfect scaling, this y-constant

line must be followed by the decision boundary of the decoder, which maps a (M_1, M_2)

pair to a gene expression state ("fate"). In other words, the requirement imposed by

scaling is enough to determine the effective input-output relation (coloring scheme) of

the decoder on the M_1-M_2 plane, no matter how the decoder is implemented

biochemically. The cell fate can also be represented by its equivalent position in wild-
type (WT), denoted as $\tilde{y}$. In this case:

$$\tilde{y}(M_1, M_2) = \frac{\ln M_1}{\ln M_1 M_2} . \tag{1}$$

Once determined by its scale-invariant performance in WT embryos, the same
decoder can be applied to mutant embryos where the maternal morphogen profiles are
perturbed but the decoding machines are intact. In the case considered here, all y points
belonging to a WT embryo of size L correspond to the hyperbolic curve $M_1 \cdot M_2 =$
$e^{-L/\lambda}$ (Fig. 1c). On the other hand, consider a mutant embryo of which $L=1$ but the M_1
copy number is doubled:

$$M_1' = 2e^{-y_{mut}/\lambda}, \ M_2' = e^{-(1-y_{mut})/\lambda}. \tag{2}$$

This mutant is also represented by a hyperbolic curve $M_1' \cdot M_2' = 2e^{-1/\lambda}$ (Fig. 1d).
This curve is exactly the one corresponding to a WT embryo of size $L = 1 - \lambda \ln 2$,
though points of the same cell fate locate at different y's in WT and the mutant. For
example, the blue-green boundary at $y=0.35$ in WT is shifted to 0.46 in the mutant. In
general, for any y_{mut} in this mutant embryo, there always exists a corresponding
position y_{WT} in WT embryo with the same morphogen values, hence the same cell
fate $\tilde{y}$:

$$y_{WT}(y_{mut}) \equiv \tilde{y}(y_{mut}) = \frac{y_{mut} - \lambda \ln 2}{1 - \lambda \ln 2} . \tag{3}$$

83 We call this mapping $\tilde{y}(y_{mut})$ the "fate-map" of this mutant, which can also be
84 obtained by directly substituting Eq. 2 into Eq. 1. This fate map can be tested
85 experimentally by plotting the positions y_{WT} against y_{mut} for the expression domain
86 boundaries (Fig. 1e).

Fig. 1. Generating scaling output by reading the local values of two non-scaling gradients. (**a**) A schematic sketch with two embryos of different sizes. The two morphogen gradients are shown in the upper panel and the desired scaling output patterns are shown below. (**b**) The same relative position $y \equiv x/L = 0.35$ has higher level of both morphogens in a smaller embryo (marked by "o") than a larger one ("x"). (**c**) In the M_1-M_2 space, an embryo of size L is represented by the curve $M_1 M_2 = e^{-L/\lambda}$. As L varies, the $y = 0.35$ point traces out a line. (**d**) Maternal morphogen profiles in a mutant are also represented by a curve in the M_1-M_2 space. The red curve stands for an $L = 1$ embryo where the M_1 dosage is doubled. The corresponding cell fates along this red curve, hence along the A-P axis of this mutant, can be directly read out. (**e**) The predicted "fate map" of the mutant in (c). All gene expression boundaries, if their positions in WT were plotted against their shifted positions in the mutant, should lie on the fate map. □

Drosophila gap gene system

Following the arguments presented in the last section, we next construct a decoder for the *Drosophila* gap gene system, using the three major morphogen gradients Bcd, Nos/mHb and Tor. Based on experimental data[33,35,38-43], the profiles of the morphogens are given by Eq. 4 below (see SI-1 and SI-4 for details) (Fig. 2a, Extended Data Fig. 1).

$$\begin{cases} Bcd(y) = L^{\beta} e^{-yL/\lambda_B} \\ mHb(y) = mHb_0 \left(1 + e^{\alpha L(y-1+(1-\lambda_H)/L)}\right)^{-1} \\ Tor(y) = e^{-yL/\lambda_T} + e^{-(1-y)L/\lambda_B} \end{cases} \tag{4}$$

The gap genes (*hb*, *Kr*, *kni* and *gt*) are the first set of zygotic segmentation genes downstream of the maternal morphogens, and the first to display a scaling pattern[29,34,35]. The *Drosophila* embryo has around 100 rows of cells along the Anterior-Posterior (A-P) axis before gastrulation. Nearly any two of them can be distinguished by their gap gene expression[44,45], so there are effectively around 100 different cell fates along the A-P axis and the fate map $\tilde{y}$ should be discussed at the resolution of 0.01. To visualize these cell fates by colors, we group them into 8 classes according to the dominantly expressing gap gene (Fig. 2b). A standard-sized WT embryo is then represented by a 1-d curve in the space of (Bcd, mHb, Tor). When L varies, this curve sweeps out a 2-d WT manifold. Following our arguments in Fig. 1, the ideal output of a scaling decoder on this WT manifold can be immediately determined – lines of constant y values should have the same cell fate (Fig. 2c).

In reality, *Drosophila melanogaster*[23] embryo length varies approximately between
450 and 570 μm (~±10%) across different fly stocks. To have a more realistic picture,
we hereafter sample L from a normal distribution $L\sim N(1, 0.1)$ to simulate the effects of
length fluctuation across *Drosophila* stocks. Another important aspect is noise in
morphogen profiles. When morphogen level approaches zero it should have huge
relative noise thus cannot carry useful information. We introduced explicitly a Poisson
noise term to the morphogen values to reflect this effect (Methods). As a result, the
"colored lines" in Fig. 2c now transform into the WT-point-cloud in Fig. 2d.

Interestingly, for the *Drosophila* case the boundaries between regions of different
colors are effectively linear – any decoder that achieves scaling should effectively
behave like a set of *linear* classifiers. Therefore, we fit the phenomenological decision
boundaries with planes (Methods). Points of different colors seem to be separated
satisfactorily in this way (Fig. 2d, e, Extended Data Fig. 2d).

The three maternal gradients can not only determine boundaries of gap gene
expression domains, but also ~100 distinct A-P cell fates as mentioned above. Thus, we
can construct a (approximately) continuous version of the decoding function using
more linear classifiers of this kind. Along the A-P axis, we fit 100 such classification
planes at 100 equally spaced y positions (Methods). The linear classifiers work
sufficiently well with the decoding task. Fig. 2f shows the decoding result of the WT
ensemble of Fig. 2d using the linear classifiers. Despite the presence of Poisson noise,
positions ($\tilde{y}$) decoded by reading the maternal morphogen values are always close to
the ground truth positions (y).

Fig. 2. The structure of a phenomenological decoder of *Drosophila*. (**a**) The three non-
scaling maternal gradients in the coordinate normalized by embryo length $y \equiv x/L$ (Eq.
4). The morphogen profiles for a standard size WT embryo ($L=1$, darker lines) and a
smaller one ($L=0.8$, lighter lines) are shown. (**b**) About 100 different cell fates along
the A-P axis are grouped into 8 domains according to the gap gene expression. The
normalized gap gene profiles are adopted from Ref.[49] and a Gaussian smoothing is
applied. (**c**) In the (Bcd, mHb, Tor) space, the standard-sized WT embryo is represented
by the black curve along which y varies from 0 to 1. When L changes, each point on
this curve traces out a line representing the morphogen values at this y position in WT
embryos of different sizes. Only the region corresponding to $L=0.8 \sim 1.2$ are plotted here.
The y lines shown there have spacing 0.01 along the A-P axis. (**d**) A Poisson noise is
added to the morphogen levels and the embryo length is sampled from a normal
distribution, turning the 2-d WT manifold in (c) to a point cloud. The decision
boundaries can be well approximated by a set of linear planes. (**e**) A magnification of
(d). The iv-v, v-vi and vi-vii boundary planes are shown. (**f**) Positions decoded from
the morphogen values ($\tilde{y}$) *vs.* the ground truth (y) for the WT point cloud in (d). Since
gap gene expression is affected by the dorsoventral system when being very close to
embryo termini, we only discuss y between 0.05 and 0.95 hereafter. The root-mean-
square-error is hardly larger than 1%. □

The decoder quantitatively predicts phenotypes of morphogen mutants

We next demonstrate that such a decoder based on scaling has a remarkable power
to predict nearly all phenotypes of morphogen mutants in *Drosophila*. Note that the
values of (Bcd, mHb, Tor) in mutants may lie outside of the WT region (color point
cloud in Fig. 2d). In this case, we linearly extrapolate the classification planes (SI-2).

Fig. 3a-c show the intersections of the linearly extrapolated classification planes
with the bottom/left/back faces of the cube in Fig. 2d (marked by α/β/γ, on which
Tor=0/Bcd=0/mHb=mHb$_0$), with the same color scheme as in Fig. 2. Maternal
morphogen null mutants lie on these faces. For example, in the *nos*⁻ mutant mHb is
equal to mHb$_0$ throughout the entire embryo, corresponding to projecting the WT curve
in the (Bcd, mHb, Tor) space onto the γ plane. It is clear in Fig. 3c that along this
projected *nos*⁻ curve, domain iv is followed immediately by domain vii, indicating the
loss of abdominal *kni* (v) and *gt* (vi) domains. This is exactly the case observed in
experiments[45-47]. As another example, consider the *bcd*⁻*tor*⁻. mHb is now the only
morphogen gradient, decreasing from its maximum value to zero from the anterior to
posterior pole. It is obvious in Fig. 3a-b that points on the mHb axis fall into the iv, v
and vi domains successively, corresponding to three gap gene domains *Kr*, *kni* and *gt*

appearing successively in this mutant embryo. As the Bcd=Tor=mHb=0 point is
classified into domain vi, the *gt* domain should extend all the way to the posterior pole.
This is also the pattern observed experimentally[45,48].

More than the predictions on presence or absence of certain gap gene domains, a
continuous valued fate map $\tilde{y}(y_{mut})$ can be constructed by incorporating all the 100
classification planes. In Fig. 3d, the predicted fate map for WT and 11 maternal
morphogen mutants are shown as black curves. To test our predictions against
experiments, we identify the peak and boundary positions for all gap gene domains
(Table S1) from the published quantitative measurements of gap gene profiles in WT
and various mutants[40,45,49-51]. For each of them, its position in mutant is plotted against
its WT positions (yellow squares in Fig. 3d). Remarkably, predictions and experiments
are consistent in all cases.

Fig. 3. Quantitative prediction on mutant fate map by the decoder. (**a-c**) The decoding
results on the bottom/left/back faces (marked by α/β/γ) of the cube in Fig. 2d. Solid

black curves are projections of the L=1 WT curve onto these planes, which also
represents the standard-sized mutant embryos *tor⁻/bcd⁻/nos⁻*, respectively. Arrowheads
on them are pointing from head to tail. The predicted gap gene expression in these
mutants can be read out along these lines. (**d**) Fate map $\tilde{y}(y)$ predicted for WT and
another 11 different mutants (black lines) and the comparison with experimental
measurements (yellow squares, cited from published works, see main text for
references). See SI-6 for discussion on the panels of *mhb⁻* and *vas⁻exu⁻bcd6X*. (**e**) The
predicted domain boundaries in *bcd⁻* as L changes. As L shrinks from 1.0 to 0.9 to 0.8
(solid, dashed and dotted lines), the *Kr* (iv) and *kni* (v) domains disappear successively.
(**f**) Shift of cephalic furrow (CF) under Bcd dosage change. Solid line is our prediction
and red dots with error bars are from experimental data[40]. Dashed grey line shows the
position of the same Bcd concentration as CF in WT. □
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Our model can also account for some recent and more quantitative experiments, in
which multiple factors such as Bcd dosage, morphogen mutation and change of the
embryo length were at play. For example, the model predicts that missing Bcd destroys
scaling completely and the gap gene pattern changes greatly with *L*. With decreasing
embryo length, the *bcd⁻* embryo losses domains iv (*Kr*) and then v (*kni*) (Fig. 3e). A
recent experiment[35] provides an excellent support for this prediction (Extended Data
Fig. 5c). Another example is the shift of cephalic furrow (CF) ($\tilde{y} = 0.344$) under
mutation of the posterior or terminal morphogens plus Bcd dosage change[40]. Our model
quantitatively captured the shifts observed in experiment (Fig. 3f).

Decoder structure reveals underlying gene regulation

Predicted fate map can also be converted to a predicted gap gene pattern. For y_{mut}
in a mutant embryo, the gap gene expression levels here can be approximated by the
composite function $G\big(\tilde{y}(y_{mut})\big)$, where G stands for the WT gap gene pattern, and
$\tilde{y}(y_{mut})$ is the fate map. Figs. 4a and c show two examples (solid lines). Measured
profiles[45] are shown as dotted lines in lighter colors for comparison.

Further analysis reveals the connection between the decoder structure and the
underlying gene regulation. Consider the *tor⁻* mutant as an example. As dictated by
scaling, the decision boundaries *Kr-kni*, *kni-gt* and *gt-hb* should be inclined in 3-d, not
perpendicular to the Bcd-mHb plane (Fig. 2e). This means that Tor should participate
in positioning these boundaries to allow for scaling. Geometrically, when extrapolated
to the Tor=0 plane following these inclined classification planes, a cell fate in WT
should appear at a more posterior position than if being orthogonally projected

downward. Thereby in the *tor*⁻ mutant, besides that posterior *hb* domain disappears, the
rest of the abdominal domains should also shift posteriorly. This prediction is fully
consistent with experiments (Fig. 4a). This example may help us to understand the
ubiquitous "redundant" regulations in the gap gene network. According to the simplest
interpretation, mHb gradient defines the anterior boundary of abdominal *gt* (vi) domain
through inhibition; Gt inhibits *kni*, thereby setting the posterior boundary of *kni* (v)
domain[48]. There is no "need", in principle, for Tor to be involved. But the observed
shift of *kni* boundary in *tor*⁻ clearly shows that in reality Tor contributes (probably
through *tll*) to the repression on *kni*[47,52], setting its posterior boundary together with
mHb. We propose that such seemingly redundant regulations actually tune the slope of
kni-gt classification plane, so that it could align with the angle required by scaling (Fig.
4b).

Another example deals with the *bcd*⁻ mutant (Fig. 4c). Bcd is well known to
function in the anterior part. However, the region where Bcd plays a role seems to be
much wider than naively expected – *bcd*⁻ mutant affects even domain vi and vii near
the posterior pole. This aspect of Bcd should also contribute to tuning the decision
boundary orientations to allow for scaling, as it has clearly been captured by our
scaling-based phenomenological model. To be more precise, the decision plane
representing the *gt-hb* (vi-vii) boundary at $\tilde{y}$=0.75 is:

$$-0.85Bcd - 0.12mHb + 0.45Tor = Const.,$$

indicating that Tor should be effectively an activator for *hb* here while Bcd should play
a repressive role (Fig. 4d). This speculation is consistent with existing biological
knowledges. Tor is long known to activate the posterior *hb* domain through
tailless(*tll*)[52]. And the effective repression by Bcd is most probably meditated by *Kr*
and *kni*, upon whose mutation the posterior *hb* domain expands anteriorly[53]. Similar
line of arguments can be applied to other cases of regulations (SI-10).

The decoder can be implemented with gene regulation

Scaling requirement can implicate regulation. To see if the converse is true, i.e., if
gene regulation can produce scale-invariant decision boundary, consider a toy model
with a static anterior morphogen *B* (like Bcd) of fixed length constant and a single gap
gene *H* whose initial condition H_{init} serves as a posterior gradient (like mHb) (Fig. 4e).
The desired output is to have *H* being activated in the anterior half with the boundary
locating at *y*=0.5 regardless of the embryo length *L*. This requires that the morphogen
levels marked by the black dots and empty triangles (Fig. 4e) should both lie on the *H*
boundary. This can be achieved with the regulation network shown in Fig. 4f (inset).

From a dynamical perspective, this network is well known to have bi-stability and Fig.
4f shows a typical bifurcation diagram. Within the bistable range, the *H-high/H-low*
states are separated by a critical line (red squares), which means exactly the decision
boundary between cell fates. If the activation strengths are properly tuned, this critical
line can be adjusted to have identical slope as the desired decision boundary in Fig. 4g.

The gap gene network has more degrees of freedom and more scaling boundaries,
and does not necessarily have to reach a dynamical attracting point. But the general
idea is the same. Based on the known gap gene network shown in Fig. 4h[17], we construct
a differential equation model (see SI-11 for details). If fitted to the WT data[49] plus
scaling requirement, the model can produce very similar decision boundaries as the
phenomenological decoder (Fig. 4, i, j).

Fig. 4. Connecting the decoder with gene regulation. (**a**, **c**) The predicted gap gene
pattern (solid lines) in *tor*⁻ (a) and *bcd*⁻ (c) are compared to measurements[45] (dashed
lines). The peak positions of the posterior *kni*, *hb* and *gt* domains are marked by filled
arrowheads, and their WT positions by empty arrowheads. (**b**) Redundant regulation on
the posterior boundary of *kni* domain as required by scaling. (**d**) The vi-vii boundary
($\tilde{y}$=0.75) is set by the balance between the opposing gradients Bcd and Tor. (**e**) The
profiles of two morphogens in a toy model, shown for two embryos of standard size
(darker lines) and larger size (lighter lines). (**f**) The bifurcation diagram for the network

in the inset. A cell can reach one of the two bi-stable states depending on the values of
the two morphogens, separated by the unstable manifold (red squares). This unstable
manifold is the decision boundary separating the Hb-high and Hb-low fates. Its slope
can be tuned by the activation strengths. (**g**) Within the realistic L range (highlighted
region), The y=0.5 line is well approximated by the decision boundary in (f) (red
squares). (**h**) The known gap gene network[17]. (**i, j**) The same plots as Fig. 3a and b, but
using an ODE model of (h). □

Concluding remarks

We developed a theoretical framework on scale-invariant gene patterning from
non-scaling signals and illustrated its application and utility in the *Drosophila* gap gene
system, providing a unified understanding to scaling, regulation and the many observed
phenomena in the *Drosophila* system. Since our framework is rather general and does
not depend on specific molecular details, it can be readily extended to other systems
(see an example in SI-13 on the long-germband insect *Megaselia abdita*).

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Methods

Fitting the linear classification planes.

The WT point cloud (Fig. 2d) used for fitting the linear classification planes are
generated as follows. First, the A-P axis is discretized into 101 points y=0% to 100%.
For each of the y position, we sample 400 embryo length values from the normal
distribution $L{\sim}N(1, 0.1)$ and calculate the corresponding (Bcd, mHb, Tor) levels using
equation (4). The three morphogen values are noted by m=(m_1, m_2, m_3) for convenience.
Obviously, $0<m_{1,3}<1$ and $0<m_2<mHb_0$ (mHb_0=0.1 here).

Then, a Poisson noise is added to each m_i by assuming the actual number of molecules
is a Poisson variable n_i with $<n_i>=N*m_i$, and the final morphogen value with noise is
n_i/N. The maximum molecule number N controls the noise magnitude, and set to
N=1000 throughout the main text. Note that we do not claim that the *actual* morphogen
noise follows independently identically Poisson distribution. And N does *not*
correspond directly to the number of molecules per nucleus. Instead, N=1000 is chosen
to make the positional error of Bcd gradient close to that measured by Gregor, et. al.[39]
(about 1~2% embryo length in the anterior half of embryo). Our model is not sensitive
to the exact value of N, see Extended Data Fig. 4, g-h for the results for N=500 or 2000.

The entire point cloud in Fig. 2d thus consists of 101 subsets $m|_y$, each of them have
400 points. The 100 classification planes are located at y=0.5%, 1.5%, …, 99.5%,
denoted as classifiers #1, …, #100. Since gap gene expression is affected by the
dorsoventral system when being very close to embryo termini, only classifiers #6 to
#95 are considered in the main text. Each of the planes should perform the *local*
classification task of distinguishing adjacent m point sets. For example, the plane
locates at y=2.5% should go through the *noise-free* y=2.5% point for *standard-sized*
embryo $m|_{L=1,y=2.5\%}$ by itself. And its orientation is such that it can best distinguishing
the point sets $\bigcup_L \bigcup_{y=\{0\%,1\%,2\%\}} m|_y$ against $\bigcup_L \bigcup_{y=\{3\%,4\%,5\%\}} m|_y$. To find the best
plane orientation numerically, we simply enumerate the Euler angles θ and φ of its
normal vector at the resolution of 1° and find the one with the highest classification
accuracy.

The noise due to finite sampling and discretizing θ and φ can be eliminated by averaging
the classification plane orientations for 25 repeats of the above sampling and fitting
steps.

Predicting the fate-map function with the ensemble of linear classifiers.

In principle, 100 well-separated planes should divide the morphogen space (the cube
with $0<m_1<1$, $0<m_2<0.1$, $0<m_3<1$) into 101 slices, corresponding to $\tilde{y}$=0% to 100%. If
a query $\boldsymbol{m}$ point falls into the slice $\tilde{y}$=n%, it locates on the posterior side of
classification planes #1 through #n, and on the anterior side of planes #n+1 to #100.
Therefore, the corresponding cell fate $\tilde{y}$ can be read out from the classification results
of all the linear classification planes (SI-2).
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In some situations, however, the 100 linear classifiers could have contradictory outputs.
Say, a point may be classified to the posterior side by classifier #70 but to the anterior
side by #30. We introduce a "posterior dominance rule" to tackle this difficulty.
Anytime when this happens, output of the anterior classifier (#30 here) is always
ignored. The reason for us to introduce the posterior dominance rule is simple – some
anterior classification planes may intersect with the much more posterior region of the
point cloud, vary far from where they were fitted (Extended Data Fig. 3b). This
posterior dominance rule works well, and finally yields all the results in Figs. 2-3.
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