Scaling dictates the decoder structure

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Abstract

Despite variability in embryo size, the tissue, organ and body plan develop *in proportion* with embryo size, known as the scaling phenomenon. Scale-invariant patterning of gene expression is a common feature in development and regeneration, and can be generated by mechanisms such as scaling morphogen gradient and dynamic oscillation. However, whether and how static non-scaling morphogens (input) can induce a scaling gene expression (output) across the entire embryo is not clear. Here we show that scaling requirement sets severe constraints on the geometric structure of the input-output relation (the decoder), from which information about the regulation and mutants' behavior can be deduced without going into any molecular details. We demonstrate that the *Drosophila* gap gene system achieves scaling in the way that is entirely consistent with our theory. Remarkably, following the geometry dictated by scaling, a parameter-free decoder correctly and quantitatively accounts for the gap gene expression patterns in nearly all morphogen mutants. Furthermore, the regulation logic and the coding/decoding strategy of the gap gene system can also be revealed from the decoder geometry. Our work provides a general theoretical framework on a large class of problems where scaling output is induced by non-scaling input, as well as a unified understanding of scaling, mutants' behavior and regulation in the *Drosophila* gap gene and related systems.

Significance Statement

Within a given species, fluctuation in egg or embryo size is unavoidable. Despite this, the gene expression pattern and hence the embryonic structure often scale in proportion with the body length. This *scaling* phenomenon is very common in development and regeneration, and has long fascinated scientists. In this paper, the authors address the question of whether and how a scaling gene expression pattern can originate from non-scaling signals (morphogens). They found that scaling has profound implications in the developmental programming -- properties and behaviors of the underlying gene network can be deduced from the scaling requirement. They demonstrated that the scaling in fruit fly embryogenesis indeed works in this way. Thus, although biological regulatory systems are very complex in general, it can be forced to exhibit simple macroscopic behaviors due to selection pressure, as demonstrated in this study.

Main Text

Introduction

In development and regeneration, a cell has to know its position in space in order to determine its fate. Often this positional information is encoded in a space-dependent signal like morphogen gradient (1-3). The decoder in the cell (usually gene networks) reads the local value of the signal

to infer its spatial position by expressing the appropriate genes, as exemplified in the French-flag
model (1, 4, 5).

A common feature in these processes is that the gene expression pattern generated by the decoder
is often scale-invariant with respect to fluctuations in the overall length of the system, which
ensures the organism develops in the correct proportion (6-11). A scale invariant output can be
achieved with a scale invariant input. Indeed, this strategy is adopted by systems such as *Xenopus*
embryo (12, 13), *Drosophila* wing (14-16) and probably *Drosophila* dorsoventral axis (17), where
the morphogen itself manages to scale with the system size. Another mechanism known to generate
a scaling pattern is dynamic oscillation, as seen in vertebrate somite segmentation (18-20), in which
the oscillation period and the body axis elongation rate are tuned to adapt to altered embryo sizes.
However, achieving scale-invariant patterning from non-scaling morphogens is still largely an open
question. A prototypical example is the scaling of *Drosophila* segmentation gene patterning (8, 21-
28), in which the gradients of the maternal morphogens seem to have fixed length constants, set by
the diffusion constant and decay rate, that do not scale automatically with the embryo size (21, 26,
28-31). In this paper, we establish a general theoretical framework. We show that the necessary
and sufficient condition for a decoder to generate a scale-invariant expression pattern from non-
scaling morphogens contains rich information on the geometric structure of the decoder. We then
provide strong evidences that *Drosophila* gap gene system achieves scaling in our proposed way.
Our work provides a comprehensive understanding on this classic scaling problem.

Results

The Geometric Structure of the Decoder is Determined by the Scaling Requirement.

We first illustrate our basic idea using a bi-gradient kind toy model (1, 22, 32). In this simplified
model, there are two morphogens, M_1 and M_2, having anterior and posterior exponential gradients
with a fixed length constant λ (Fig. 1A, length of a standard-sized embryo is defined as $L=1$). For
larger (smaller) embryos, the effective length constant should shrink (expand) if measured in the
relative coordinate ($y \equiv x/L$, $M_1 = e^{-yL/\lambda}$, $M_2 = e^{-(1-y)L/\lambda}$, Fig. 1B). Consider for example the
position $y=0.35$ as the boundary separating two different cell fates in the embryo. In a smaller
(larger) embryo, as the absolute distance to both termini are shorter (longer) at this position, local
levels of both morphogens are higher (lower). When L varies, the $y=0.35$ point traces out a line on
the M_1-M_2 plane (Fig. 1C). Therefore, in order to achieve perfect scaling, this y-constant line must
be followed by the decision boundary of the decoder, which maps a (M_1, M_2) pair to a gap gene
expression state ("fate"). In other words, the requirement imposed by scaling is enough to
determine the effective input-output relation (coloring scheme) of the decoder on the M_1-M_2 plane,
no matter how the decoder is implemented biochemically. The cell fate can also be represented by
its equivalent position in wild-type (WT), denoted as $\tilde{y}$. In this case:

$$82 \qquad\qquad \tilde{y}(M_1, M_2) = \frac{\ln M_1}{\ln M_1 M_2} \, . \qquad\qquad (1)$$

83   Once determined by its scale-invariant performance in WT embryos, the same decoder can be
84   applied to mutant embryos where the maternal morphogen profiles are perturbed but the decoding
85   machines are intact. In the case considered here, all y points belonging to a WT embryo of size L
86   correspond to the hyperbolic curve $M_1 \cdot M_2 = e^{-L/\lambda}$. On the other hand, consider a mutant embryo
87   of which $L=1$ but the M_1 copy number is doubled:

$$88 \qquad\qquad M_1' = 2e^{-y_{mut}/\lambda}, \, M_2' = e^{-(1-y_{mut})/\lambda}. \qquad\qquad (2)$$

This mutant is also represented by a hyperbolic curve $M_1' \cdot M_2' = 2e^{-1/\lambda}$ (Fig. 1D). This curve is
exactly the one corresponding to a WT embryo of size $L = 1 - \lambda \ln 2$, though points of the same
cell fate locate at different y's in WT and the mutant. For example, the blue-green boundary at
$y=0.35$ in WT is shifted to 0.46 in the mutant. In general, for any y_{mut} in this mutant embryo, there
always exists a corresponding position y_{WT} in WT embryo with the same morphogen values, hence
the same cell fate $\tilde{y}$:

$$95 \qquad\qquad y_{WT}(y_{mut}) \equiv \tilde{y}(y_{mut}) = \frac{y_{mut} - \lambda \ln 2}{1 - \lambda \ln 2} \, . \qquad\qquad (3)$$

We call this mapping $\tilde{y}(y_{mut})$ the "fate-map" of this mutant, which can also be obtained by directly
substituting Eq. 2 into Eq. 1. This fate map can be tested experimentally by plotting the positions
y_{WT} against y_{mut} for the measured expression domain boundaries (Fig. 1E).

Construction of a Phenomenological Decoder for *Drosophila*.

Following the arguments represented in the last section, we next construct a decoder for the
Drosophila gap gene system, using all the three maternal morphogen gradients Bcd, Nos/mHb and
Tor. These three are also the only upstream-most gradients (33), since *bcd⁻nos⁻tor⁻* triple mutant
shows spatially uniform gap gene expression (34, 35). Based on experimental data (26, 28, 36-40)
and the minimal assumption that they all have fixed length constants, the profiles of the gradients
are given by Eq. 4 below (see SI-1 and SI-6 for details) (Fig. 2A and Fig. S1).

$$107 \qquad \begin{cases} Bcd(y) = L^{\beta} e^{-yL/\lambda_B} \\ mHb(y) = mHb_0 \left(1 + e^{\alpha L(y-1+(1-\lambda_H)/L)} \right)^{-1} \\ Tor(y) = e^{-yL/\lambda_T} + e^{-(1-y)L/\lambda_B} \end{cases} \qquad (4)$$

The gap genes (*hb*, *Kr*, *kni* and *gt*) are the first set of zygotic segmentation genes downstream of
the maternal morphogens, and the first to display a scaling pattern (21, 27). Therefore, by reading
the non-scaling maternal morphogens, a robust and near-perfect scaling blueprint of future body
plan is already established at the gap gene stage. This blueprint is believed to have enough
information to uniquely determine the fate of each cell hereafter (41, 42).

The *Drosophila* embryo has around 100 rows of cells along the Anterior-Posterior (A-P) axis before
gastrulation. Nearly any two of them can be distinguished by their gap gene expression (42), so
there are effectively around 100 different cell fates along the A-P axis and the fate map $\tilde{y}$ should
be discussed at the resolution of 0.01. To visualize these cell fates by colors, we group them into 8
classes according to the dominantly expressing gap gene (Fig. 2B). A standard-sized WT embryo
is represented by a 1-d curve in the space of (Bcd, mHb, Tor). When L varies, this curve sweeps
out a 2-d WT manifold. Following our arguments in Fig. 1, the ideal output of a scaling decoder on
this WT manifold can be immediately determined – lines of constant y values should have the same
cell fate (Fig. 2C).

In reality, *Drosophila melanogaster* embryo length varies approximately between 450 and 570 μm
(~±10%) across different fly stocks (8). To have a more realistic picture, we hereafter sample L
from a normal distribution $L \sim N(1, 0.1)$ to simulate the effects of length fluctuation across
Drosophila stocks. Another important aspect is noise in morphogen profiles. When morphogen
level approaches zero it should have huge relative noise thus cannot carry useful information. We
introduced explicitly a Poisson noise term to the morphogen values to reflect this effect (See
Methods and SI-2 for details). As a result, the "colored lines" in Fig. 2C now transform into the
WT-point-cloud in Fig. 2D.

The gap gene network (i.e., the decoder) should be able to classify all the points in Fig. 2D into
classes (real cell fate) that matches their colors. Besides just obtaining a classifier that performs the
classification task (like a Bayesian one discussed in SI-5), we are more interested in figuring out
the shape of those decision boundaries explicitly. Complexity and nonlinearity of the decision
boundaries are directly related to whether it can be satisfactorily approximated by a gene regulation
network as will be discussed later. Here comes an important observation, that for the *Drosophila*
case the boundaries between regions of different colors are effectively linear – any decoder that
achieves scaling by reading the local morphogen levels should effectively behave like a set of *linear*
classifiers, at least within the WT point cloud. Therefore, we fit the phenomenological decision
boundaries with planes (see Methods and SI-3 for details). Points of different colors seem to be
separated satisfactorily in this way (Fig. 2, D and E, and Fig. S2D).

The three maternal gradients can not only determine boundaries of gap gene expression domains,
but also ~100 distinct A-P cell fates as mentioned above. Thus, we can construct a (approximately)
continuous version of the decoding function using more linear classifiers of this kind. Along the A-

P axis, we fit 100 such classification planes at 100 equally spaced y positions (see Methods and SI-
3). The linear classifiers work sufficiently well with the decoding task, i.e., possible nonlinearities
in the ideal classification boundaries can indeed be safely ignored. Fig. 2F shows the decoding
result of the WT ensemble of Fig. 2D using the linear classifiers. Despite the presence of Poisson
noise, positions ($\tilde{y}$) decoded by reading the maternal morphogen values are always close to the
ground truth positions (y). The root-mean-square-error $RMSE = \sqrt{\langle(\tilde{y} - y)^2\rangle}$ is hardly larger than
1%, even smaller than the $RMSE$ of a Bayesian decoder which allows arbitrary decision boundary
geometry (SI-4 and Fig. S2).

The Decoder Quantitatively Predicts Phenotypes of Morphogen Mutants.

We next demonstrate that such a decoder, whose overall geometry is solely determined by scaling,
has a remarkable power to predict nearly all phenotypes of morphogen mutants in *Drosophila*. Note
that the values of (Bcd, mHb, Tor) in mutants may lie outside of the WT region (color point cloud
in Fig. 2D). In this case, we linearly extrapolate the classification planes (see SI-4 for justification
of the extrapolation).

Fig. 3A-C show the intersections of the linearly extrapolated classification planes with the bottom
/left /back faces of the cube in Fig. 2D (marked by α /β /γ, on which Tor=0 /Bcd=0 /mHb=mHb$_0$),
with the same color scheme as in Fig. 2. Maternal morphogen null mutants lie on these faces. For
example, in the *nos⁻* mutant mHb is equal to mHb$_0$ throughout the entire embryo, corresponding to
projecting the WT curve in the (Bcd, mHb, Tor) space onto the *γ* plane. It is clear in Fig. 3C that
along this projected *nos⁻* curve, domain iv is followed immediately by domain vii, indicating the
loss of abdominal *kni* (v) and *gt* (vi) domains. This is exactly the case observed in experiments (35,
43, 44). As another example, consider the *bcd⁻tor⁻*. mHb is now the only morphogen gradient,
decreasing from its maximum value to zero from the anterior to posterior pole. It is obvious in Fig.
3A-B that points on the mHb axis fall into the iv, v and vi domains successively, corresponding to
three gap gene domains *K*r, *kni* and *gt* appearing successively in this mutant embryo. As the
Bcd=Tor=mHb=0 point is classified into domain vi, the *gt* domain should extend all the way to the
posterior pole. This is also the pattern observed experimentally (34, 35).

More than the predictions on presence or absence of certain gap gene domains, a continuous valued
fate map $\tilde{y}(y_{mut})$ can be constructed by incorporating all the 100 classification planes. In Fig. 3D,
the predicted fate map for WT and 11 maternal morphogen mutants are shown as black curves. To
test our predictions against experiments, we identify the peak and boundary positions for all gap
gene domains (Table S1) from the published quantitative measurements of gap gene profiles in WT
and various mutants (35, 45-47). For each of them, its position in mutant is plotted against its WT

positions (yellow squares in Fig. 3D). Remarkably, predictions and experiments are consistent in
all cases.

Decoder Structure Reveals Features of Underlying Gene Regulation.

Predicted fate map can also be converted to a predicted gap gene pattern. For y_{mut} in a mutant
embryo, the gap gene expression levels here can be approximated by the composite function
$G(\tilde{y}(y_{mut}))$, where G stands for the WT gap gene pattern, and $\tilde{y}(y_{mut})$ is the fate map. Fig. 4A-
B show two examples (solid lines). Measured profiles (35) are shown as dotted lines in lighter
colors for comparison.

Further analysis reveals interesting connections between the decoder structure and the underlying
gene regulation. Consider the *tor*⁻ mutant as an example. As dictated by scaling, the decision
boundaries *Kr-kni*, *kni-gt* and *gt-hb* should be inclined in 3-d, not perpendicular to the Bcd-mHb
plane (Fig. 2E). This means that Tor should participate in positioning these boundaries to allow for
scaling. Geometrically, when extrapolated to the Tor=0 plane following these inclined
classification planes, a cell fate in WT should appear at a more posterior position than if being
orthogonally projected downward. Thereby in the *tor*⁻ mutant, besides that posterior *hb* domain
disappears (48), the rest of the abdominal domains should also shift posteriorly. This prediction is
fully consistent with experiments (Fig. 4A, where the filled and empty triangles mark the measured
peak positions in *tor*⁻ and WT, respectively).

This example may help us to understand the ubiquitous "redundant" regulations in the gap gene
network. According to the simplest interpretation, mHb gradient defines the anterior boundary of
abdominal *gt* (vi) domain through inhibition; Gt inhibits *kni*, thereby setting the posterior boundary
of *kni* (v) domain (34). There is no "need", in principle, for Tor to be involved. But the observed
shift of *kni* boundary in *tor*⁻ clearly shows that in reality Tor contributes (probably through *tll*) to
the repression on *kni* (44, 49, 50), setting its posterior boundary together with mHb as well as Bcd
(51). We propose that such seemingly redundant regulations actually tune the slope of *kni-gt*
classification plane, so that it could align with the angle required by scaling (Fig. 4C). Scaling
seems to be one important "goal" of such redundancy in the gap gene network.

Another example deals with the *bcd*⁻ mutant (Fig. 4B). Bcd is well known to function in the anterior
part. However, the region where Bcd plays a role seems to be much wider than naively expected –
bcd⁻ mutant affects even domain vi and vii near the posterior pole. This aspect of Bcd should also
contribute to tuning the decision boundary orientations to allow for scaling, as it has clearly been
captured by our scaling-based phenomenological model. To be more precise, the decision plane
representing the *gt-hb* (vi-vii) boundary at $\tilde{y}$=0.75 is:

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$$-0.85Bcd - 0.12mHb + 0.45Tor = Const.,$$

indicating that Tor should be effectively an activator for *hb* here while Bcd should play a repressive
role (Fig. 4D). This speculation is consistent with existing biological knowledges. Tor is long
known to activate the posterior *hb* domain through *tailless* (*tll*) (49). And the effective repression
by Bcd is most probably meditated by *Kr* and *kni*, upon whose mutation the posterior *hb* domain
expands anteriorly (52).

A third example of this kind regards the head gap gene *orthodenticle* (*otd*), which is expressed
between $\tilde{y}$=0.08 and 0.25 along the A-P axis. Position of the *otd* domain in mutants can be predicted
straightforwardly by finding $\tilde{y}$=0.08 and 0.25 points in the corresponding mutant fate maps (Fig.
4E). These predictions are again in nice agreements with experiments (53): decreasing Bcd dosage
shift both anterior and posterior *otd* boundaries anteriorly, while lacking Tor will make the *otd*
domain fail to retract from the anterior pole, and shift its posterior boundary slightly forward. These
observations in mutants are directly related to underlying regulations (as in (54)), that Bcd and Tor
both activate *otd* in defining its posterior boundary, while at the same time both represses *otd* (most
probably through *huckebein*) in setting the anterior boundary (Fig. 4F). The gap gene regulation
network seems to be organized in such a way to allow scaling.

Different Morphogens Play Different Roles in Scaling.

In our framework, scaling originates from the insensitivity of decoder output to the correlated
fluctuations in the local morphogen levels. The forms of such correlated fluctuations are determined
by the morphogen profiles. Therefore, if the morphogen profiles were perturbed, the alignment
between *y*-constant lines and the decoder's decision boundaries will be affected thus scaling would
be as least partially destroyed. To provide quantitative tests of our model from this perspective, fate
maps in mutant embryos with non-standard length ($L \neq 1.0$) are studied.

Missing Bcd destroys scaling completely and the gap gene pattern changes greatly with *L*. With
decreasing embryo length, the *bcd*⁻ embryo losses domains iv (*Kr*) and then v (*kni*) (Fig. 5A). A
recent experiment (28) provides an excellent support for this prediction. (See Fig. S5C for detailed
discussion). Increasing Bcd dosage also affects matching between the decoder and the *y*-constant
lines. The mid-embryo *hb* boundary is reported to be unscaled in shortened embryos when Bcd
dosage is doubled (28) (Fig. 5B, red dots), which is accurately capture by the decoder (Fig. 5B,
black line. See also SI-8 for an analytical calculation).

In contrast to Bcd, missing mHb or Tor should have limited influence on scaling and affects only
part of the embryo (Fig. 5C-D). The relative contributions to patterning and scaling from the three
morphogens across the embryo can be quantitatively defined (SI-9) and are shown in Fig. 5E. Note

that the morphogen mHb has long been considered dispensable or redundant, since losing mHb

does not lead to any direct loss of the segment (36, 37). However, our results indicate that it actually

plays a crucial role for scaling in the abdominal region.

As a final example, we study the shift of cephalic furrow (CF) under mutation of the posterior or

terminal morphogens plus Bcd dosage change. CF is the morphological boundary between head

and thorax locating at $y=0.344$ in WT. It is a morphological trait much down-stream of the gap

genes. But, as we believe that the scaling blueprint is established at the gap gene stage and passed

down, we can regard CF as a hypothetical gap gene boundary $\tilde{y} = 0.344$ and predict its position

$y \equiv X_{CF}$ in various mutants. These predictions are compared with the measurements reported in (40)

(Fig. 5, F-H).

When Bcd dosage is perturbed, the predicted X_{CF} matches well with experimental measurements

(Fig. 5F). Note that X_{CF} shows robustness against Bcd dosage change – its shift is always visibly

smaller than that of the iso-concentration point of Bcd (Fig. 5, gray dashed line).

Truly nontrivial are the cases when Bcd dosage is altered in the absence of mHb or Tor gradient.

For example, in *nos⁻* mutant where mHb gradient is eliminated (Fig. 5G), with *increasing* Bcd

dosage such robustness disappears, and X_{CF} follows the Bcd threshold exactly (marked by white

arrow); while for *decreasing* Bcd dosage, such robustness still exists (black arrow). Similar but

opposite phenomenon is seen in *tor⁻* mutant (Fig. 5H). These phenomena are successfully captured

by our model without any further tuning on parameters. Shift of CF in these cases can be easily

understood from information provided in Fig. 5E – Bcd and Tor are the main contributing bi-

gradient pair anterior to the CF, while the Bcd-mHb pair dominants the middle part behind CF.

Therefore, positional robustness of the CF upon Bcd dosage change has different origins when

shifted anteriorly or posteriorly.

The Scaling Decoder Can be Implemented with Gene Regulation.

The discussions so far are quite general, independent of the detailed biochemical implementations

of the decoder. In this section we provide evidence that the scaling decoder can be implemented by

gene regulation and more specifically by the known gap gene network.

First, consider a toy model with a static anterior morphogen *B* (like Bcd) of fixed length constant

and a single gap gene *H* whose initial condition H_{init} serves as the second posterior gradient (like

mHb) (Fig. 6A). The desired output is to have *H* being activated in the anterior half with the

boundary locating at $y=0.5$ regardless of the embryo length *L*. This requires that morphogen levels

marked by the black dots or empty triangles (Fig. 6A) should both lie on the *H* boundary. The

regulation network follows that of the inset in Fig. 6B. From a dynamical perspective, this network

is well known to have bi-stability and Fig. 6B shows a typical bifurcation diagram. Within the
bistable range, the *H-high/H-low* states are separated by a critical line (red squares), which means
exactly the decision boundary between cell fates. If the activation strengths are properly tuned, this
critical line can be adjusted to have identical slope as the desired decision boundary in Fig. 6C.
Such first-order approximation is already good enough for $\pm 20\%$ variations in embryo length.

The gap gene network has more degrees of freedom and more scaling boundaries, and does not
necessarily have to reach a dynamical attracting point. But the general idea is the same. Based on
the known gap gene network shown in Fig. 6D (33), we construct a differential equation model
(see SI-11 for details). If fitted to the WT data (46) plus scaling requirement, the model can produce
very similar decision boundaries as the phenomenological decoder (Fig. 6, E and F), hence correct
predictions on mutants.

Discussion

Scale-invariant gene patterning can originate from integrative decoding of non-scaling signals. In
this case, the effective input-output structure of the decoder is largely dictated by the requirement
of scaling. Consequently, the underlying gene regulation system evolves to have its macroscopic
behavior approximating the ideal decoder geometry. All the intricate biochemical details seem to
be hidden and largely irrelevant.

We provided strong evidences that scaling in the *Drosophila* gap gene expression patterns indeed
emerge in this way. There are quantitative agreements between model predictions and experiments
on nearly all maternal morphogen mutants. We then showed that the scaling requirement alone
contains rich information about the overall gene regulation logic and the way the morphogen
signals are being integrated. The decoder was further demonstrated to be implementable by
dynamical gene regulation models, and consistent with the existing knowledge of the gap gene
regulation network.

Overall, our results provide a unified understanding to scaling, mutants' behavior and gene
regulation in the *Drosophila* gap gene system. Since our framework is rather general, the arguments
presented in this paper can be readily extended to other systems where scaling is achieved through
integrating non-scaling morphogens. In SI-13, we discuss such an example: the long-germband
insect *Megaselia abdita*.

Methods

Fitting the linear classification planes.

The WT point cloud (Fig. 2d) used for fitting the linear classification planes are generated as
follows. First, the A-P axis is discretized into 101 points y=0% to 100%. For each of the y position,
we sample 400 embryo length values from the normal distribution $L{\sim}N(1, 0.1)$ and calculate the
corresponding (Bcd, mHb, Tor) levels using equation (4). The three morphogen values are noted
by $\boldsymbol{m}=(m_1, m_2, m_3)$ for convenience. Obviously, $0<m_{1,3}<1$ and $0<m_2<mHb_0$ (mHb_0=0.1 here).

Then, a Poisson noise is added to each m_i by assuming the actual number of molecules is a Poisson
variable n_i with $<n_i>=N*m_i$, and the final morphogen value with noise is n_i/N. The maximum
molecule number N controls the noise magnitude, and set to N=1000 throughout the main text. Note
that we do not claim that the *actual* morphogen noise follows independently identically Poisson
distribution. And N does *not* correspond directly to the number of molecules per nucleus. Instead,
N=1000 is chosen to make the positional error of Bcd gradient close to that measured by Gregor,
et. al.(55) (about 1~2% embryo length in the anterior half of embryo). Our model is not sensitive
to the exact value of N, see Extended Data Fig. 4, g-h for the results for N=500 or 2000.

The entire point cloud in Fig. 2d thus consists of 101 subsets $\boldsymbol{m}|_y$, each of them have 400 points.
The 100 classification planes are located at y=0.5%, 1.5%, …, 99.5%, denoted as classifiers #1, …,
#100. Since gap gene expression is affected by the dorsoventral system when being very close to
embryo termini, only classifiers #6 to #95 are considered in the main text. Each of the planes should
perform the *local* classification task of distinguishing adjacent $\boldsymbol{m}$ point sets. For example, the plane
locates at y=2.5% should go through the *noise-free* y=2.5% point for *standard-sized* embryo
$\boldsymbol{m}|_{L=1,y=2.5\%}$ by itself. And its orientation is such that it can best distinguishing the point sets
$\bigcup_L \bigcup_{y=\{0\%,1\%,2\%\}} \boldsymbol{m}|_y$ against $\bigcup_L \bigcup_{y=\{3\%,4\%,5\%\}} \boldsymbol{m}|_y$. To find the best plane orientation
numerically, we simply enumerate the Euler angles θ and φ of its normal vector at the resolution of
1° and find the one with the highest classification accuracy.

The noise due to finite sampling and discretizing θ and φ can be eliminated by averaging the
classification plane orientations for 25 repeats of the above sampling and fitting steps.

Predicting the fate-map function with the ensemble of linear classifiers.

In principle, 100 well-separated planes should divide the morphogen space (the cube with $0<m_1<1$,
$0<m_2<0.1$, $0<m_3<1$) into 101 slices, corresponding to $\tilde{y}$=0% to 100%. If a query $\boldsymbol{m}$ point falls into
the slice $\tilde{y}$=n%, it locates on the posterior side of classification planes #1 through #n, and on the
anterior side of planes #n+1 to #100. Therefore, the corresponding cell fate $\tilde{y}$ can be read out from
the classification results of all the linear classification planes (SI-2).

In some situations, however, the 100 linear classifiers could have contradictory outputs. Say, a
point may be classified to the posterior side by classifier #70 but to the anterior side by #30. We

introduce a "posterior dominance rule" to tackle this difficulty. Anytime when this happens, output
of the anterior classifier (#30 here) is always ignored. The reason for us to introduce the posterior
dominance rule is simple – some anterior classification planes may intersect with the much more
posterior region of the point cloud, vary far from where they were fitted (Fig. S3B). This posterior
dominance rule works well, and finally yields all the results in Figs. 2-5.
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354 **Acknowledgments**
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Figures

Figure 1. Generating scaling output by reading the local values of two non-scaling gradients.

(A) A schematic sketch with two embryos of different sizes. The two morphogen gradients are shown in the upper panel and the desired scaling output patterns are shown below.

(B) The same relative position $y \equiv x/L = 0.35$ has higher level of both morphogens in a smaller embryo (marked by "o") than a larger one ("x").

(C) In the M_1-M_2 space, the standard-sized WT embryo is represented by the black curve. As L varies, the $y=0.35$ point traces out a line.

(D) Maternal morphogen profiles in a mutant are also represented by a curve in the M_1-M_2 space. The red curve stands for an $L=1$ embryo where the M_1 dosage is doubled. The corresponding cell fates along this red curve, hence along the A-P axis of this mutant, can be directly read out.

(E) The predicted "fate map" of the mutant in (C). All gene expression boundaries, if their positions in WT were plotted against their shifted positions in the mutant, should lie on the fate map.

Figure 2. The structure of a phenomenological decoder of *Drosophila*.

(A) The three non-scaling maternal gradients in the coordinate normalized by embryo length $y \equiv x/L$

(Eq. 4). The morphogen profiles for a standard size WT embryo (L=1, darker lines) and a smaller

one (L=0.8, lighter lines) are shown.

(B) About 100 different cell fates along the A-P axis are grouped into 8 domains according to the

gap gene expression. The normalized gap gene profiles are adopted from (*36*) and a Gaussian

smoothing is applied.

(C) In the (Bcd, mHb, Tor) space, the standard-sized WT embryo is represented by the black curve

along which y varies from 0 to 1. When L changes, each point on this curve traces out a line

representing the morphogen values at this y position in WT embryos of different sizes. Only the

region corresponding to L=0.8~1.2 are plotted here. The y lines shown there have spacing 0.01

along the A-P axis.

(D) A Poisson noise is added to the morphogen levels and the embryo length is sampled from a

normal distribution, turning the 2-d WT manifold in (C) to a point cloud. The decision boundaries

can be well approximated by a set of linear planes.

(E) A magnification of (D). The iv-v, v-vi and vi-vii boundary planes are shown.

(F) Positions decoded from the morphogen values ($\tilde{y}$) *vs*. the ground truth (y) for the WT point

cloud in (D). Since gap gene expression is affected by the Dorsal-Ventral system when being very

close to embryo termini, we only discuss y between 0.05 and 0.95 hereafter. The root-mean-square-

error is hardly larger than 1%

Figure 3. Quantitative predictions on mutant fate maps by the phenomenological decoder.

(A-C) The decoding results on the bottom/left/back faces (marked by α/β/γ) of the cube in Fig. 2D.
Solid black curves are projections of the *L*=1 WT curve onto these planes, which also represents
the standard-sized mutant embryos *tor⁻*/*bcd⁻*/*nos⁻*, respectively. The predicted gap gene expression
in these mutants can be read out along these lines (arrowheads on them are pointing from head to
tail).

(D) Fate map *ỹ*(*y*) predicted for WT and another 11 different mutants (black lines) and the
comparison with experimental measurements (yellow squares, cited from published works, see
main text for references). See SI-7 for discussion on the panels of *mhb⁻* and *vas⁻exu⁻bcd6X*.

Figure 4. The decoder reveals information about regulation logic.

(A-B) The predicted gap gene patterns (solid lines) in *tor⁻* and *bcd⁻* are compared to that measured
in (35) (dashed lines). The peak positions of the posterior *kni*, *hb* and *gt* domains are marked by
filled arrowhead, their WT positions by the empty arrowheads.

(C) Redundant regulation on the posterior boundary of *kni* domain as required by scaling.

(D) According to the decoder, the vi-vii boundary ($\tilde{y}=0.75$) is set by the balance between the
opposing gradients Bcd and Tor. Biochemically, this is realized by an indirect activation of Tor
through *tll*, together with an indirect inhibition from Bcd, meditated by *Kr* and *kni*.

(E) The predicted expression patterns of the head gap gene *otd*, derived from the decoder. Structure
of the decoder requires both Bcd and Tor to effectively activate *otd* for positioning its posterior
boundary, while at the same time, both inhibit *otd* for defining its anterior boundary. This explains
the *otd* regulations proposed by experimentalists decades ago (F). The decoding results on the
bottom/left/back faces (marked by α/β/γ) of the cube in Fig. 2D. Solid black curves are projections
of the *L*=1 WT curve onto these planes, which also represents the standard-sized mutant embryos
tor⁻/bcd⁻/nos⁻, respectively. The predicted gap gene expression in these mutants can be read out
along these lines (arrowheads on them are pointing from head to tail).

Figure 5. Different morphogens collaborate to achieve scaling in different regions.

(A) Missing Bcd destroys scaling throughout the embryo. In *bcd⁻*, as *L* shrinks from 1.0 to 0.9 to 0.8 (solid, dashed and dotted lines), the *Kr* (iv) and *kni* (v) domains should disappear successively.

(B) The effect of Bcd dosage doubling on scaling is accurately captured by the decoder. The position of predicted (black line) vs. measured (red circles) (28) *hb* boundary (iii-iv boundary, $\tilde{y}$=0.47) are shown.

(C-D) In *mhb⁻* and *tor⁻*, scaling is affected mostly in the middle and the two termini, respectively.

(E) Relative contributions of the three morphogens to scaling across the embryo.

(F) Shift of cephalic furrow (CF) under Bcd dosage change. Solid line is our prediction and red dots with error bars are from experiment data (40). Dashed grey line shows the position of the same Bcd concentration as CF in WT.

(G-H) Shift of CF position in *nos⁻* and *nos⁻* backgrounds, respectively.

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Figure 6. The scaling decoder can be implemented by gene regulation network.

(A) The profiles of two morphogens in a toy model, shown for two embryos of standard size (darker
lines) and larger size (lighter lines).

(B) The bifurcation diagram for the network in the inset. A cell can reach one of the two bi-stable
states depending on the values of the two morphogens, separated by the unstable manifold (red
squares). This unstable manifold is the decision boundary separating the Hb-high and Hb-low fates.
Its slope can be tuned by the activation strengths.

(C) Within the realistic L range ($\pm20\%$, highlighted region), The y=0.5 line is well approximated
by the decision boundary in (B) (red squares).

(D) The known gap gene network from Ref.*(33)*.

(E-F) The same plots as Fig. 3A-B, but using an ODE model of (D) (see SI-11 for details).