

1 Ultrafast high-resolution multi-parametric brain MRI using 3D
2 Echo Planar Time-resolved Imaging

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1 **Abstract**

2 Multi-parametric quantitative MRI has shown great potential to improve the sensitivity and specificity of
3 clinical diagnosis, but suffers from impractical scan time especially at high spatial resolution, a major limiting
4 factor that prevents it from common use. To address this long-standing challenge, we introduce a novel approach,
5 termed 3D Echo Planar Time-resolved Imaging (3D-EPTI), which significantly increases the acceleration
6 capacity of MRI sampling, and provides unprecedented acquisition efficiency for multi-parametric MRI. The
7 high acceleration capability in 3D-EPTI is achieved by exploiting the spatiotemporal correlation of MRI data
8 at multiple timescales through new encoding strategies within and between its efficient continuous data readouts.
9 This has enabled robust and repeatable whole-brain multi-parametric mapping at high isotropic resolution
10 within minutes. 3D-EPTI may greatly facilitate the clinical adoption of quantitative MRI and push towards the
11 next-generation of brain examination with high efficacy and accuracy for improved diagnosis and longitudinal
12 monitoring. Moreover, 3D-EPTI also offers a powerful tool for fast and repeatable submillimeter multi-
13 parametric imaging that can be used to study detailed brain intra-cortical architectures for neuroscientific
14 research.

1 1. Introduction

2 Multiparametric MRI provides quantitative measurements that are sensitive to a variety of tissue properties
3 of the human brain. Its quantitative nature leads to less reliance on system conditions and human interpretation
4 compared to standard qualitative images, and therefore has a great potential to improve the accuracy and efficacy
5 of clinical diagnosis¹. This improvement has been demonstrated in a wide range of diseases, such as epilepsy^{2,3},
6 brain tumor^{4,5}, multiple-sclerosis⁶⁻⁸ and Alzheimer^{9,10}. In addition, the quantitative measurements make it
7 possible to measure the difference of tissue properties among different populations and along time, which is
8 critical for understanding neurological diseases, brain development, and aging¹¹⁻¹³.

9 A major limitation of quantitative MRI is its long acquisition time. The common approach to measure
10 quantitative parameters is to perform a model fitting using a series of qualitative images with different contrast
11 weightings. Traditionally, long imaging time is needed for the acquisition of a single weighted image to fulfill
12 the Shannon-Nyquist sampling theorem in the frequency (k -space) domain. This is dramatically exacerbated in
13 quantitative MRI due to the need to acquire multiple contrast weightings, and even further in multi-parametric
14 imaging due to the need to repeat such process for each parameter, leading to extremely long scan times. To
15 accelerate the acquisition, undersampling in the frequency domain has been made possible by taking advantage
16 of the spatial information provided by multi-channel coil arrays¹⁴⁻¹⁶ or by enforcing prior knowledge of image
17 properties, such as through compressed-sensing theory¹⁷. However, despite continuous efforts, the ability to
18 accelerate sampling without compromising the image quality is still limited and obtaining multi-parametric MRI
19 in clinical acceptable time remains a major challenge.

20 In this work, we introduce a novel method, termed 3D-Echo Planar Time-Resolved Imaging (3D-EPTI),
21 that solves this long-lasting problem by enabling unprecedented acceleration and significantly improved
22 imaging efficiency for multi-parametric imaging. By pushing multi-parametric MRI into an unprecedented fast
23 regime (as short as 1 minute), 3D-EPTI should help facilitate a paradigm shift from qualitative to quantitative
24 imaging in clinical practice, and also open up the possibility of acquiring multi-parametric maps at
25 submillimeter isotropic resolution within a few minutes to reveal exquisite brain structures for neuroscientific
26 research. With richer and more reproducible information obtained within a single scan, 3D-EPTI has the
27 potential to increase patient throughput, patient compliance and cost effectiveness, paving the way for large-
28 scale studies to establish new quantitative biomarkers for neurological diseases.

29 3D-EPTI pushes the limit of acceleration by exploiting the signal correlation in the spatiotemporal domain.
30 The use of spatiotemporal correlation to achieve high acceleration for quantitative MRI has been an emerging
31 area of research. Recent studies, such as MR fingerprinting¹⁸⁻²⁰ and MR multitasking²¹, have utilized
32 spatiotemporal correlation between readouts after different contrast-modulated excitations to accelerate multi-
33 parametric imaging, which have shown promising results especially when used in conjunction with the low-
34 rank subspace model²¹⁻²³. In pursuit of a significant further increase in acceleration capability over state-of-the-
35 art approaches, 3D-EPTI has been designed from the ground up to exploit stronger spatiotemporal correlations
36 by developing: i) a new efficient continuous readout scheme, and ii) a data sampling strategy that takes

1 advantage of the correlation at multiple timescales, both within and between its continuous readouts.

2 The continuous readout scheme distinguishes 3D-EPTI from other quantitative MRI methods not only by
3 its higher readout efficiency with minimal dead time, but also through exploiting the correlation between data
4 sampled at a much shorter timescale (submillisecond) within the readout, to help with data reconstruction. At
5 this timescale, only minimal phase accumulation and signal decay will occur, which lead to stronger temporal
6 correlation. This stronger correlation can significantly increase the ability to recover highly undersampled data,
7 and therefore pushes the boundaries of the acceleration to an unprecedented level. Previously, despite the
8 exceptional efficiency, the continuous readout has mainly been used in the echo planar imaging (EPI)
9 acquisition²⁴, where all signals across the readout are combined to form a single image without exploiting the
10 spatiotemporal correlation within it. This limits its acceleration capacity, makes it difficult to acquire multiple
11 images at a short time interval to track signal evolution for quantitative MRI, and also leads to severe image
12 distortion and blurring by combining signals with different phase and magnitude. By exploiting the
13 spatiotemporal correlation within the readout, 3D-EPTI is able to resolve a series of multi-contrast 3D images
14 across the readout instead of just one single image at a high acceleration rate, providing continuous tracking of
15 the signal evolution to fit the quantitative parameters. On the other hand, it ensures that each resolved image is
16 formed by signals with the same phase and magnitude, eliminating the undesirable image distortion and blurring.

17 The second unique feature of 3D-EPTI is its new controlled- and incoherent-aliasing encoding schemes in
18 the 4D spatiotemporal domain, which seamlessly integrates the use of the temporal correlation and the use of
19 spatial information provided by multi-channel coil arrays. Here, data correlations at multiple timescales are
20 exploited. Within readouts, a spatiotemporal encoding is designed by extending the controlled-aliasing
21 approach^{25,26} into the spatiotemporal domain. Conventionally, controlled-aliasing theory improves the ability to
22 recover undersampled data by using a complementary spatial encoding strategy that better exploits the coil
23 sensitivity. In 3D-EPTI, the complementary sampling is employed in the time dimension in addition to the
24 spatial dimensions, increasing the ability to take advantage of both the spatial information provided by multi-
25 channel coil arrays and the temporal correlation across adjacent signals, offering remarkably higher acceleration
26 capacity (e.g., 80×) in the spatiotemporal space. Between readouts, a novel radial-block encoding is developed
27 to exploit their correlation in a long timescale based on the compressed sensing theory¹⁷. The radial-block
28 sampling creates incoherent aliasing along time that can be well excluded from the coherent signal evolutions,
29 therefore provides another 10× acceleration. The combination of spatiotemporal CAIPI and radial-block
30 undersampling offers a remarkable ~800× acceleration in the spatiotemporal domain.

31 The harmonious integration of the continuous readout and the novel intra- and inter-readout spatiotemporal
32 encoding in 3D-EPTI provides unique datasets that allow us to time-resolve thousands of multi-contrast 3D
33 images by enforcing the spatiotemporal correlation in the reconstruction process. This acquisition scheme can
34 be applied to any sequence with different contrast-modulated radiofrequency (RF) pulses, or be adapted to other
35 types of readouts to accurately track the signal evolution, and therefore is suitable for measuring a variety of
36 quantitative parameters. This proof-of-concept work employs specific sequences to simultaneously obtain MR
37 relaxation time constants T_1 , T_2 , T_2^* as well as RF field (B_1^+) and proton density (PD). We demonstrated the

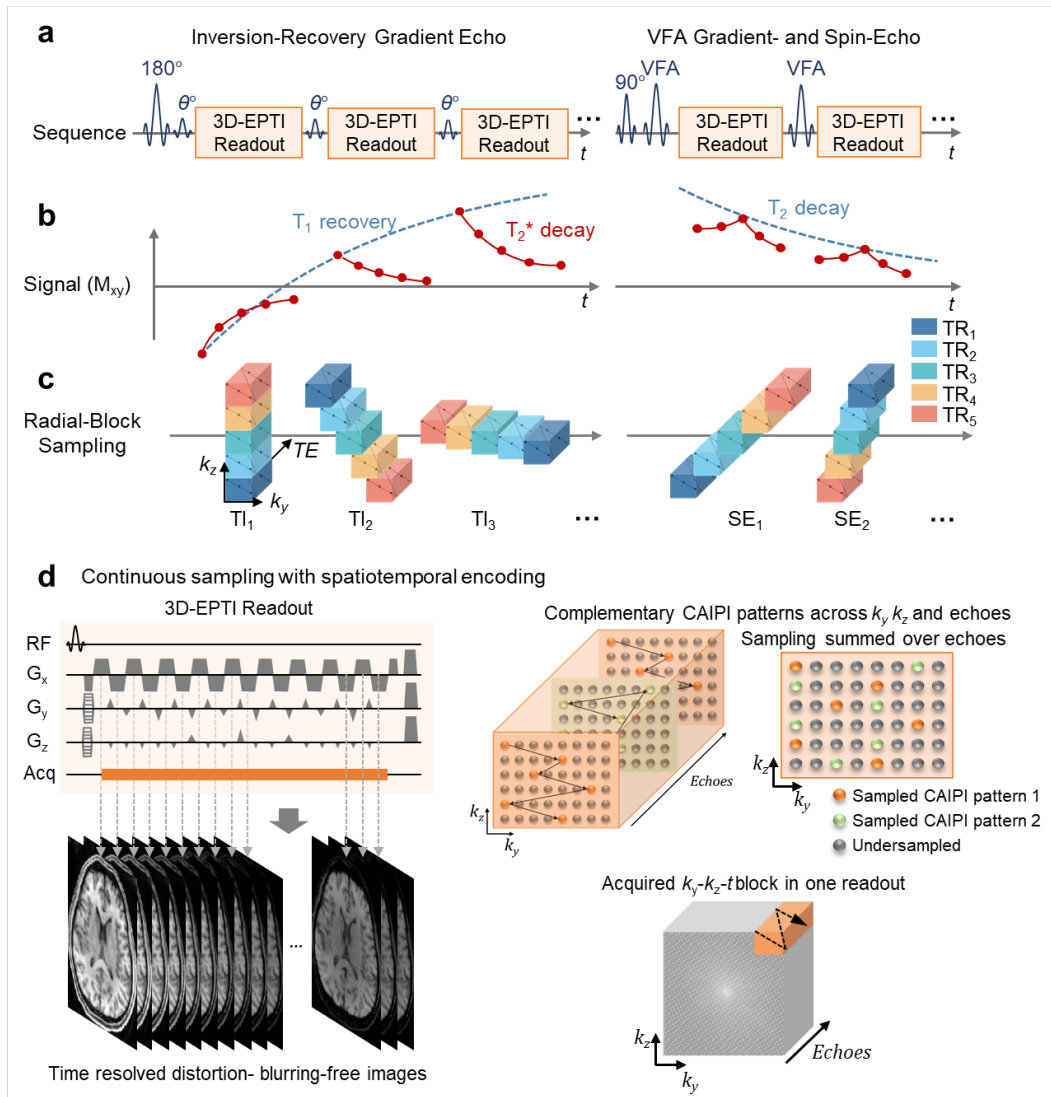
1 ability of 3D-EPTI to acquire high-quality whole-brain multi-parametric maps at isotropic 1.5-mm in 1 minute
2 or at isotropic 1-mm in 3 minutes, which could take hours to acquire using standard acquisitions or tens of
3 minutes using the state-of-the-art methods. This illustrates the potential of 3D-EPTI to enable the next-
4 generation of clinical brain exams with ultra-fast speed and high repeatability. An isotropic 0.7-mm 3D-EPTI
5 protocol was also developed to allow, for the first time, the examination of simultaneously acquired T_1 , T_2 , and
6 T_2^* in less than 10 minutes to investigate the intra-cortical architecture. Finally, we also present multiple
7 contrast-weighted images synthesized from the high-quality 3D-EPTI quantitative maps, offering optimal
8 visualization with arbitrary views and adjustable contrast weightings.

9 **2. Results**

10 **Efficient 3D-EPTI imaging framework.**

11 Figure 1 shows a detailed framework of the 3D-EPTI acquisition. An inversion-recovery gradient echo
12 (IR-GE) and a variable-flip-angle gradient-and-spin-echo²⁷ (VFA-GRASE) sequence (Fig. 1a) were chosen and
13 carefully optimized to provide signal evolutions that are sensitive to T_1 , T_2 , and T_2^* relaxations (Fig. 1b). After
14 each RF excitation, a 3D-EPTI readout is acquired, which continuously captures the temporal signal evolution
15 with efficient bipolar gradient. To resolve images within the readout with high acceleration, a spatiotemporal
16 CAIPI encoding is employed in a 4D spatiotemporal (k - t) domain (Fig. 1d, the readout dimension k_x is fully-
17 sampled and therefore omitted in the illustration). At each time point within the readout, a particular phase and
18 partition position (k_y - k_z) is acquired in the frequency domain that is interleaved to its neighboring time points in
19 a ‘controlled-aliasing’ pattern. Across a slightly longer timescale, two complementary CAIPI patterns are
20 interleaved across echoes (orange and green points in Fig. 1d) to provide more independent k -space sampling
21 locations. Each 3D-EPTI readout covers a relatively small block in k_y - k_z - t space to ensure that the neighboring
22 k_y - k_z samplings are close in time. The ‘controlled aliasing’ pattern, the complementary sampling across echoes,
23 and the proximity in time together result in high spatiotemporal correlation and allow effective use of the
24 available coil sensitivity information. Therefore, the highly-undersampled data (e.g., undersampling rate = $80\times$)
25 at each time point can be easily reconstructed, resolving a series images across the readout at a submillisecond
26 time interval (Fig. 1d, left).

27 In each repetition time (TR), multiple k - t blocks can be acquired across multiple readouts after different
28 excitations (Fig. 1c, blocks in the same color are acquired in the same TR). To quickly encode the 4D k - t space
29 using a small number of TRs, a golden-angle radial-block Cartesian sampling is employed across the readouts.
30 Specifically, the blocks acquired after the same excitation form a diagonal radial blade in the phase-partition
31 encoding (k_y - k_z) space, with different blade angulations across different readouts. This is developed to create a
32 favorable spatiotemporal incoherent aliasing across the readouts for constrained reconstruction, that permits a
33 further $\sim 10\times$ acceleration through acquiring only a few blades for each readout instead of the full k_y - k_z sampling.



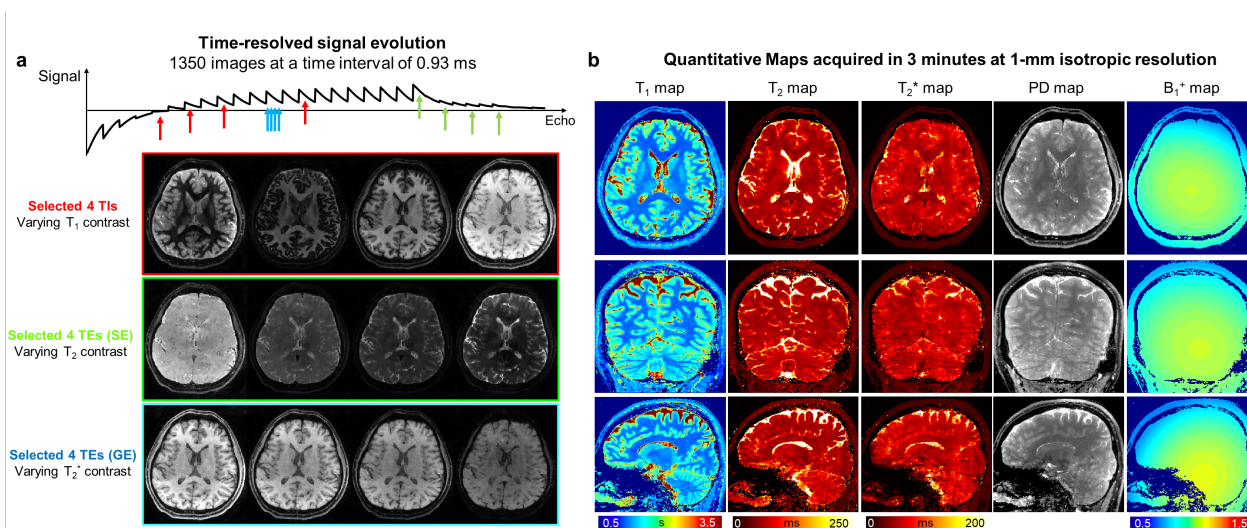
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 2 Figure 1. Illustration of the 3D-EPTI acquisition. **a**, The sequence diagrams of the inversion-recovery gradient-echo (IR-GE)
 3 and the variable-flip-angle gradient and spin-echo (VFA-GRASE) sequences with 3D-EPTI readouts at each inversion time
 4 (T_1) and spin-echo (SE). **b**, The designed sequence provides signal evolutions with high sensitivity to T_1 , T_2 and T_2^* relaxation,
 5 which can be continuously tracked by the 3D-EPTI sampling. **c**, Instead of acquiring data across the full frequency space
 6 (k_y-k_z) at every T_1 or SE, a radial-block sampling pattern is utilized, which creates spatiotemporal incoherent aliasing across
 7 the readouts for constrained reconstruction and permits $\sim 10\times$ acceleration. The blocks acquired in different TRs are color-
 8 coded. **d**, Details of the continuous bipolar readout with an optimized spatiotemporal CAIPI encoding used to efficiently
 9 covers a k_y-k_z-t block per 3D-EPTI readout. The neighboring data points are acquired close in time to create strong temporal
 10 correlation. Two CAIPI patterns (orange and green points) are utilized in a complementary fashion across the echoes to
 11 provide additional complementary sampling. The combination of spatiotemporal CAIPI and radial-block undersampling offers
 12 a remarkable $\sim 800\times$ acceleration in the spatiotemporal domain, that enables fast acquisition of more than a thousand multi-
 13 contrast images within a few TRs. Note that the readout (k_x) dimension is fully-sampled and therefore omitted in the
 14 illustration.

15 The acquired highly undersampled data, with carefully designed spatiotemporal encoding patterns that
 16 fully exploit the spatiotemporal correlation, were then reconstructed by a low-rank subspace reconstruction,
 17 tailored specifically to 3D-EPTI to time-resolve thousands of multi-contrast images (Supplementary Fig. 1).
 18 The low-rank subspace method²² was chosen for use based on its superior ability to improve the conditioning

1 in the reconstruction by utilizing the low-rank prior information of the signal evolution, therefore achieving
 2 high image SNR^{22,28-33}. Finally, the quantitative values were obtained by matching the signal evolution with a
 3 pre-calculated dictionary.

4 **Simultaneous T_1 , T_2 , and T_2^* mapping in 3-minutes at 1-mm isotropic resolution.**

5 T_1 , T_2 and T_2^* are different MR relaxation time constants that provide characteristic information of the
 6 underlying tissue properties. T_1 has been demonstrated to be sensitive to myelin concentration³⁴ and axon
 7 diameter³⁵, providing excellent white-gray matter contrast³⁶ and high sensitivity for evaluating pathologies such
 8 as demyelination³⁷. T_2^* can detect changes in iron concentrations that have been observed in many neurological
 9 disorders³⁸⁻⁴⁰. T_2 is affected by myelin⁴¹ and iron concentrations as well, and is also sensitive to abnormal fluids
 10 in the tissue which can be used to characterize inflammation and edema⁴². Therefore, the simultaneous
 11 acquisition of these three parameters will provide complementary information to improve the sensitivity and
 12 specificity in evaluating the heterogeneous properties of human brain. Further, recent studies have shown that
 13 analysis performed using a combination of quantitative parameters could help disentangle contributing signals
 14 from molecular and water compositions in the brain¹³.

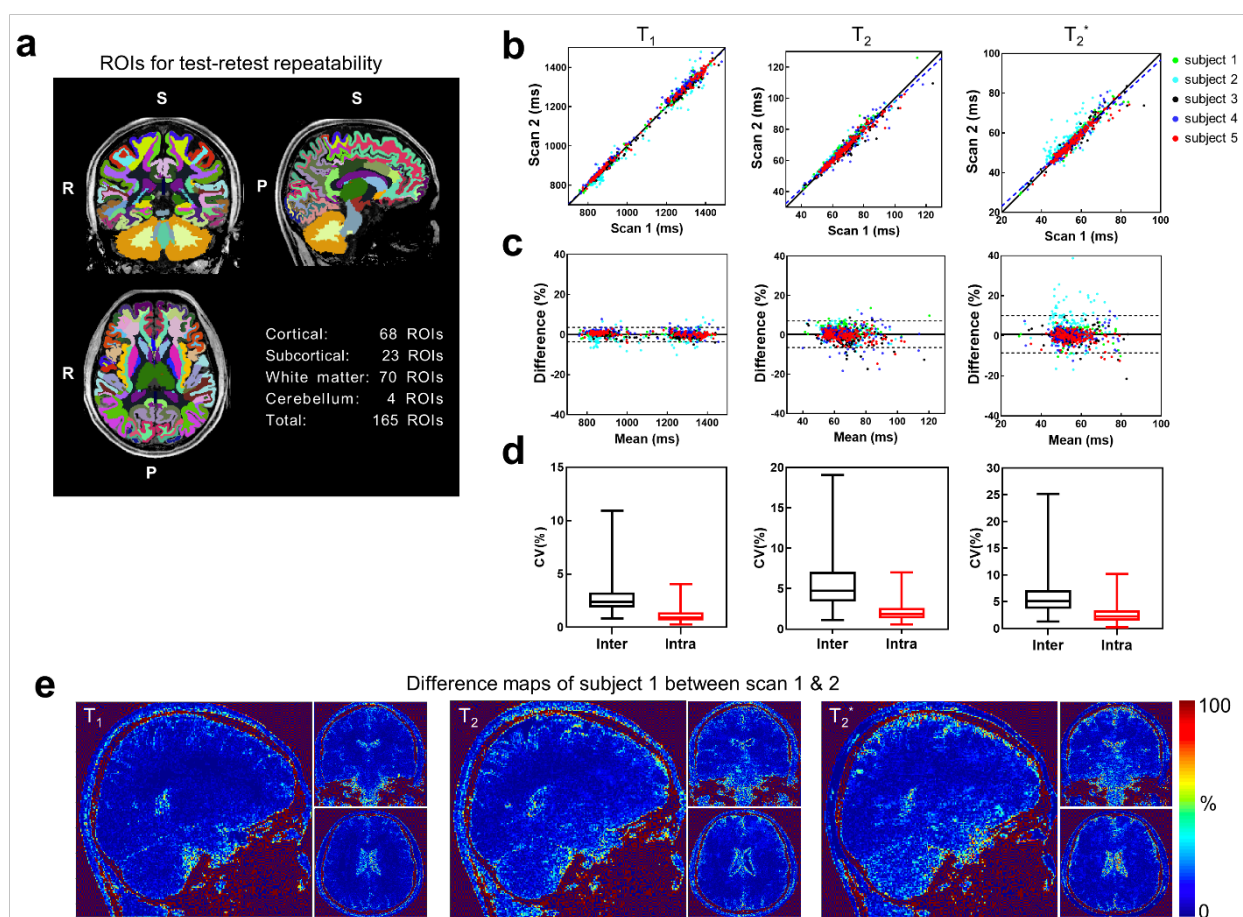


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 16 Figure 2. Simultaneous T_1 , T_2 and T_2^* mapping at 1-mm isotropic resolution whole-brain in 3 minutes acquired by 3D-EPTI.
 17 **a**, Representative reconstructed multi-contrast images with different T_1 , T_2 , and T_2^* weightings selected from the 1350
 18 resolved images. **b**, High-resolution quantitative maps estimated from the multi-contrast images, including T_1 , T_2 , T_2^* , PD
 19 and B_1^+ , shown in three orthogonal views.

20 Conventionally, each of the three relaxation parameters is mapped sequentially, which requires lengthy
 21 acquisition time. To address this, many fast quantification methods have been developed recently to obtain T_1
 22 and T_2 ^{2,18,19,43-47}, or T_1 and T_2 ⁴⁸⁻⁵⁰ simultaneously, but there are only a limited number of approaches that target
 23 all of these three parameters simultaneously⁵¹⁻⁵⁴. Additionally, even by using these cutting-edge methods, whole-
 24 brain multi-parametric mapping at high isotropic resolution (e.g., 1-mm) can still take more than half an hour
 25 of acquisition time. To overcome this issue, 3D-EPTI aims to achieve $\sim 10\times$ faster acquisition than the state-of-
 26 the-art methods for simultaneous acquisition of T_1 , T_2 , and T_2^* . In addition to these quantitative parameters, 3D-
 27 EPTI also estimates the RF field inhomogeneity (B_1^+), a major confounding factor that affects the accuracy of

1 the measurement for relaxation times, therefore achieving high accuracy without the need of an additional
 2 calibration scan for B_1^+ . Figure 2 demonstrates an example dataset acquired by 3D-EPTI at 1-mm isotropic
 3 resolution with whole brain coverage in just 3 minutes, resulting in a total of 1350 multi-contrast images
 4 resolved at a time interval as short as 0.93 ms (an echo-spacing). Representative reconstructed images with
 5 different T_1 , T_2 , T_2^* contrasts illustrate the high quality in the reconstruction that can be achieved from a highly
 6 undersampled dataset by fully exploiting the intra- and inter-readout spatiotemporal correlations (Fig. 2a). The
 7 resultant quantitative parameter maps, PD and B_1^+ field show high image SNR and resolution, free from any
 8 image distortions or aliasing artifacts (Fig. 2b). These multi-parametric maps acquired in a single scan are also
 9 perfectly aligned without the need for co-registration. Moreover, the high isotropic resolution of these images
 10 allows them to be reformatted in any orientation without loss of resolution, improving the ability to visualize
 11 detailed structures and small lesions. The accuracy of the quantitative estimates, including T_1 , T_2 , T_2^* , PD and
 12 B_1^+ , was also tested through a simulation study of the 3D-EPTI acquisition using gold standard reference
 13 parameter maps, where low errors were observed for all parameters as shown in Supplementary Fig. 2.

14 **Characterization of the repeatability and reliability for T_1 , T_2 , and T_2^* mapping.**



15
 16 Figure 3. Repeatability test of 3D-EPTI for simultaneous T_1 , T_2 and T_2^* mapping using the 3-minute 1-mm protocol. **a**, 3D
 17 volumes are segmented into 165 ROIs covering the whole-brain area. **b**, Scatter plots of the test-retest T_1 , T_2 , T_2^* values in
 18 the 165 ROIs measured from 5 subjects, shown along with the identity line (solid) and the regressed line (dashed). **c**, The
 19 Bland-Altman plot of the test-retest quantitative parameters. **d**, The box-plot of the coefficient of variation (COV) between

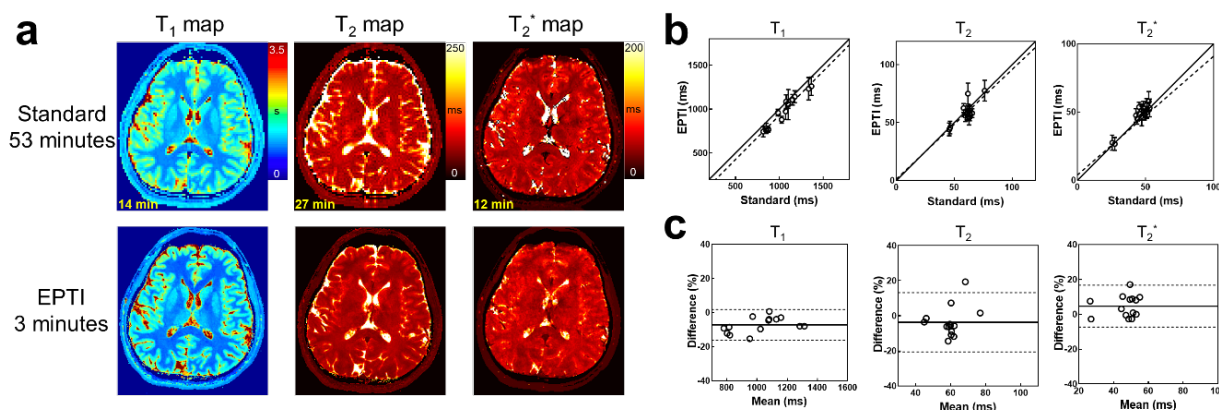
1 (inter) and within (intra) subjects. **e**, The percentage difference maps in subject 1 that shows the spatial distribution of the
2 test-retest variation for the 3 parameters.

3 Quantitative repeatability is crucial for monitoring and characterization of brain tissues over time and
4 among populations. To evaluate the repeatability of 3D-EPTI, a scan-rescan assessment was performed on 5
5 healthy volunteers using the 3-minute 1-mm protocol, where the subjects were taken out of the scanner and
6 repositioned between the two scans. Region Of Interest (ROI) analysis was performed using automatic
7 FreeSurfer^{36,55,56} segmentation, which includes a total of 165 ROIs in cortical, subcortical, white matter and
8 cerebellum regions after excluding cerebrospinal fluid (CSF) regions and ROIs smaller than 50 voxels (Fig. 3a).
9 High correlations and small differences were measured between the two scans for all three parameters as shown
10 in Fig. 2b and 2c. Specifically, the T_1 values from the first and the second scans are highly correlated with a
11 positive Pearson's correlation coefficient (PCC) of 0.996 ($P < 0.0001$). Bland Altman analysis revealed no
12 significant difference ($P = 0.821$, two-tailed t -test) between the two measurements. The T_2 values of the two
13 scans show a high positive correlation (PCC = 0.974, $P < 0.0001$) with a small difference of 0.28% ($P = 0.017$),
14 and the T_2^* values also show a high positive correlation (PCC = 0.938, $P < 0.0001$) and a small difference of
15 0.80% ($P < 0.0001$). The scan-rescan difference maps (Fig. 3e) show a low level of differences and a relative
16 homogeneous distribution in the gray and white matter areas of interest, while large differences are mainly
17 observed in the CSF regions, which could be attributed to the high physiological noise in these regions.

18 The intra-subject variability between test-retest scans and inter-subject variability among the five
19 volunteers were also evaluated and compared using coefficient of variation (COV). Figure 3d shows the
20 distribution of the intra-subject and inter-subject COVs across all ROIs in box plots with whiskers from
21 minimum to maximum data points. Small intra-subject variability was observed with a median COV at 0.93%,
22 1.88% and 2.27% for T_1 , T_2 and T_2^* respectively. The inter-subject COVs were also measured to be at a low
23 level, with median COVs of 2.39%, 4.75%, 5.09%, which are higher than the intra-subject measurements as
24 expected. The overall low level of COVs demonstrates the high level of repeatability of the 3D-EPTI
25 quantifications, while the expected differences between intra- and inter-subject suggest the potential ability of
26 3D-EPTI in capturing individual differences. The T_2^* values show the largest variability that could be reflective
27 of the variability in the head position between the scan and rescan acquisitions, where previous findings have
28 demonstrated variability in T_2^* values as a function of head orientation relative to the main field⁵⁷. The
29 repeatability of B_1^+ mapping was also evaluated, where consistent measurements were obtained across three
30 scans at different spatial resolutions for the same subject as shown in Supplementary Fig. 3.

31 To further validate 3D-EPTI's reliability, a comparison study between quantitative parameters provided by
32 3D-EPTI and those from lengthy standard acquisition methods was conducted *in vivo*. The well-established
33 standard methods provide high quality quantitative parameters at a cost of impractically long acquisition time
34 and therefore a higher level of susceptibility to motion induced artifacts. To mitigate this issue in our comparison,
35 we reduced the spatial resolution ($2 \times 2 \times 3 \text{ mm}^3$ for T_1 and T_2) as well as the slice coverage of the standard
36 acquisitions to keep them to an acceptable total acquisition time of 53 minutes. For 3D-EPTI, a single 3-minute
37 scan at 1-mm isotropic resolution with whole brain coverage was used to obtain all the quantitative estimates.

1 ROI analysis was performed with 14 manually selected ROIs that were contained within the slice coverage of
2 standard 2D acquisitions as shown in Fig. 4. T_1 measurements of 3D-EPTI and the standard method show high
3 positive correlation ($PCC = 0.972$, $P < 0.0001$), with a bias of -7.23% ($P < 0.0001$). Similarly, T_2 measurements
4 also show high positive correlation ($PCC = 0.790$, $P = 0.0008$) with no significant bias ($P = 0.1351$). Lastly, T_2^*
5 values are also highly correlated ($PCC = 0.948$, $p < 0.0001$) with a small bias of 4.68% ($P = 0.0137$). In addition
6 to the in-vivo validation, a phantom experiment was also performed where the quantitative measurements from
7 3D-EPTI are in good agreement with the standard methods (Supplementary Fig. 4).

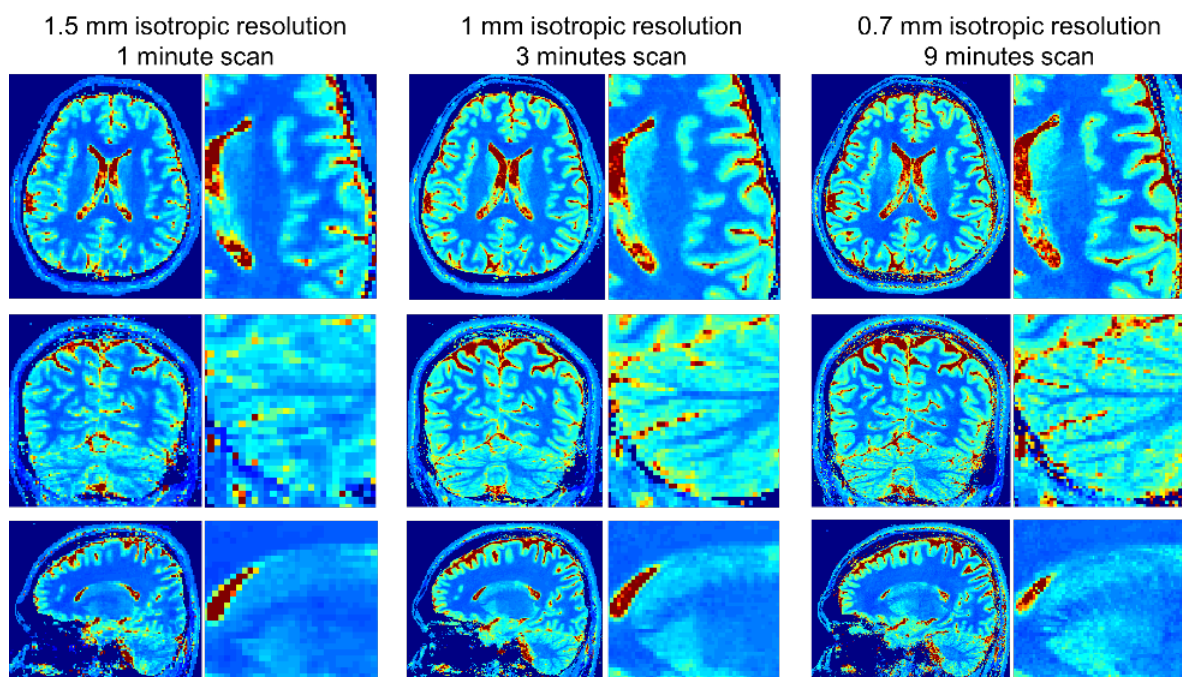


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9 Figure 4. Comparison of the quantitative measurements obtained using 3D-EPTI vs. well-established but lengthy standard
10 acquisitions *in vivo*. **a**, The quantitative maps acquired by the standard methods and 3D-EPTI. **b**, The scatter plots of the
11 quantitative values from 14 selected ROIs. **c**, The Bland-Alman plot of the same data.

12 **Ultra-fast 1-min scan and submillimeter mapping enabled by the high efficiency.**

13 In addition to the 3-minute 3D-EPTI protocol at 1-mm isotropic resolution, two additional whole-brain
14 protocols at different resolutions were developed with the purpose of showcasing the new possibilities that 3D-
15 EPTI can bring and the unmet needs that it can address for multi-parametric imaging.

16 First, an ultra-fast 1-minute protocol at 1.5-mm isotropic resolution was developed to obtain high quality
17 quantitative maps as shown in Fig. 5 and Supplementary Fig. 5. A one-minute ultra-fast scan has been an alluring
18 target for the MRI research community, that would enable rapid screening exam and dramatically improve
19 patient comfort and throughput. Recent studies have shown promising progress to acquire multi-contrast
20 weighted images in 1 minute⁵⁸, but no study so far has been able to obtain quantitative parameters in a scan as
21 short as 1 minute at a reasonable isotropic spatial resolution, let alone simultaneously mapping three quantitative
22 parameters at once. The 1-minute multi-parametric scan provided by 3D-EPTI could help fulfill this important
23 unmet need. The quick 3D-EPTI scan can also markedly reduce the chance of involuntary movements, a major
24 source of image artifacts in MRI, particularly in less compliant clinical patients (e.g., pediatric patients), and
25 reduce costly re-scan and patients called backs⁵⁹ as well as the need of harmful anesthesia⁶⁰.

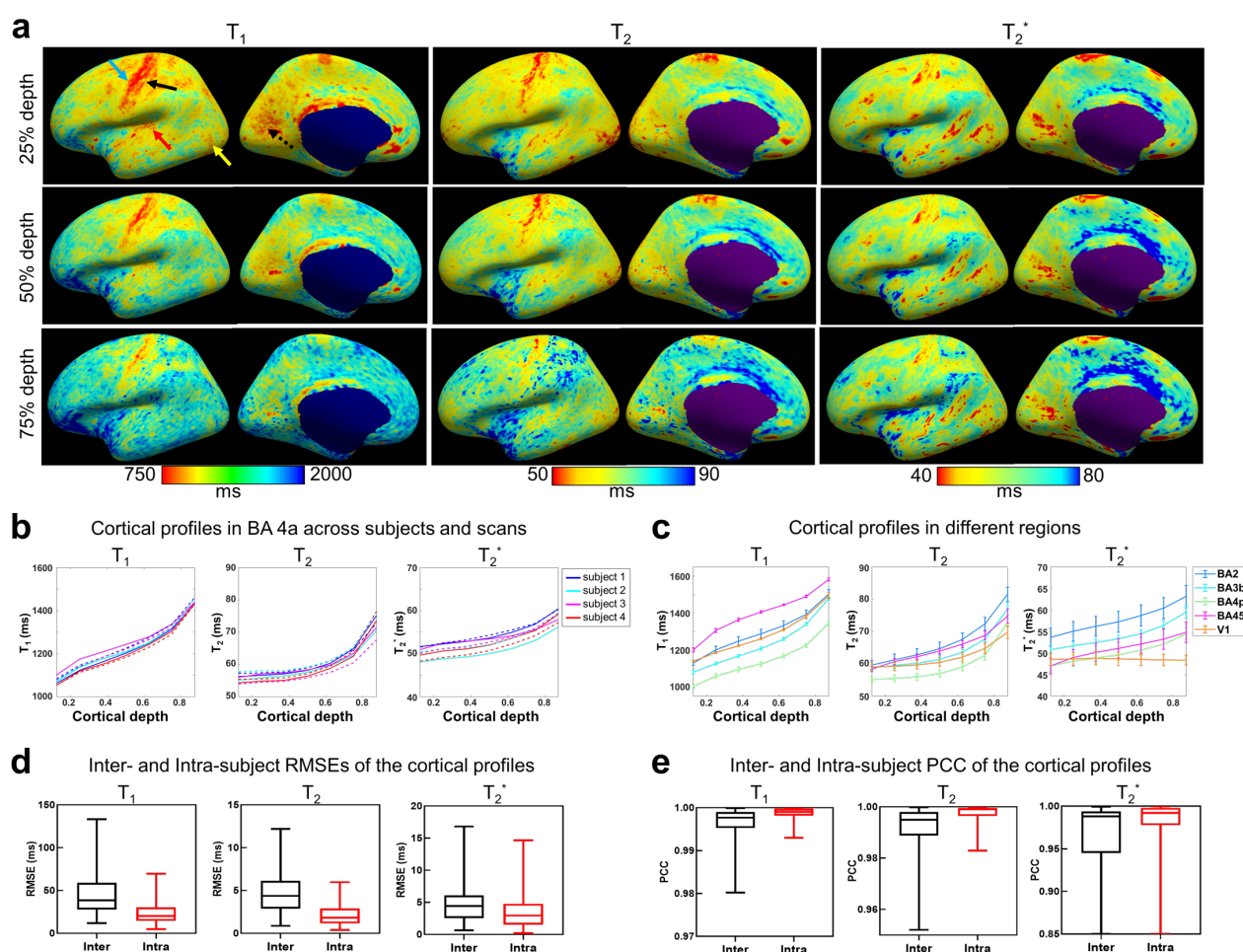


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2 Figure 5. Example T_1 maps with zoomed-in areas provided by 3D-EPTI protocols at different spatial resolutions: 1-minute
3 scan at 1.5-mm isotropic resolution, 3-minute scan at 1-mm isotropic resolution, and 9-minutes scan at 0.7-mm isotropic
4 resolution.

5 Another protocol has also been developed for the acquisition of 0.7-mm isotropic resolution quantitative
6 parameters in 9 minutes, to allow visualization and analysis of more detailed brain structures (Fig. 5, right
7 column). This should be particularly helpful in studying the intra-cortical architecture of the human brain, where
8 the thin cortex consists of multiple layers with different tissue properties, such as different levels of myelination
9 or iron concentration. The use of quantitative methods has emerged recently for better evaluation of these
10 different properties⁶¹⁻⁶⁷, but a lack of acquisition efficiency for high resolution imaging has been one of the key
11 obstacles. The high efficiency of 3D-EPTI enables for the first-time simultaneous acquisition of T_1 , T_2 , T_2^* at
12 submillimeter resolution within a few minutes, and provides a new powerful tool to study cortical layer-
13 dependent tissue properties. Importantly, this acquisition protocol has been designed for use on widely available
14 clinical MRI instrumentations (3 Tesla MRI with 32-channel receiver array), where 3D-EPTI enables the ability
15 to acquire high-quality sub-millimeters parameter maps with good SNR without need of specialized hardware
16 (e.g., ultra-high-field scanner).

17 Here, we explored the feasibility of using 3D-EPTI to assess intra-cortical structures of healthy volunteers,
18 evaluated its inter-scan and inter-subject repeatability, and explored its potential to identify specific spatial
19 features. Figure 6a shows the quantitative maps of all three parameters at different cortical depth from inner
20 (proximate to white matter) to outer (proximate to CSF) surface of a healthy volunteer. Consistent profiles
21 across layers can be observed with distinctly lower values in areas that are highly myelinated, such as motor,
22 sensory, auditory, MT and visual cortex, which are in accordance with previous literatures^{61,64-66,68}. For all three
23 relaxation parameters, there is a general increasing trend across cortical layers from inner to outer surface,
24 potentially reflecting the decrease of myelin and iron contents from the white matter surface to the CSF surface

1 that has been validated in histological studies⁶⁹. Figure 6b shows an example of such a profile within a
 2 representative ROI in the motor cortex (BA 4a), where consistent profiles from 4 healthy volunteers (color-
 3 coded) across two repeated scans (solid and dashed lines) were plotted, showing high inter-scan (intra-subject)
 4 and inter-subject repeatability. The high repeatability is also observed in all other representative ROIs as shown
 5 in Fig 6d and 6e, quantified by both the root mean square errors (RMSEs) and the PCC, which assess the
 6 differences and the similarities of the cortical profiles among subjects and between scans. The intra-subject
 7 profiles were measured with low differences (median RMSEs for T_1 , T_2 , T_2^* at 20.36 ms, 1.84 ms and 2.94 ms)
 8 and high correlations (median PCCs at 0.999, 0.999, 0.992). The inter-subject profiles showed higher variability
 9 than intra-subject as expected, but still with low median RMSEs at 38.47 ms, 4.37 ms and 4.42 ms as well as
 10 high median PCCs at 0.998, 0.995, 0.988 for T_1 , T_2 , T_2^* respectively.



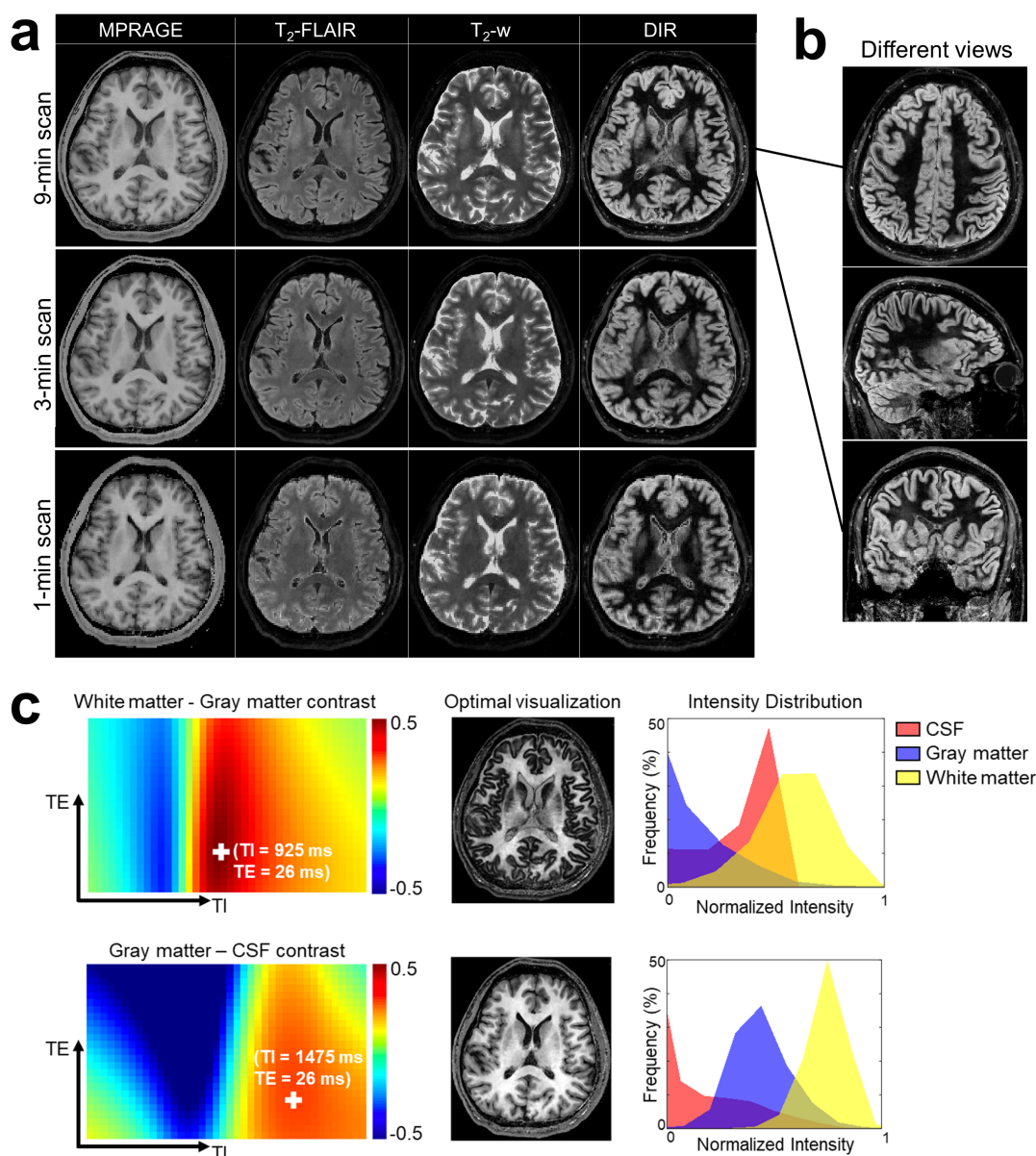
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 12 Figure 6. Surface-based cortical analysis of T_1 , T_2 and T_2^* of 0.7-mm isotropic resolution 3D-EPTI data. **a**, Quantitative
 13 parameters sampled at three different cortical depths (25%, 50%, 75%) shown on the reconstructed cortical surface. Lower
 14 quantitative values were observed in highly-myelinated regions such as motor (blue arrow), somatosensory (black arrow),
 15 auditory (red arrow), middle temporal visual area (yellow arrow) and visual cortex (dotted black arrow). **b**, Example of
 16 quantitative values as a function of cortical depth in the BA 4a area of 4 subjects across 2 repeated scans (solid line: scan
 17 1, dashed line: scan 2). **c**, Averaged quantitative values over the 2 scans across 4 subjects as function of cortical depth in
 18 5 representative ROIs. Error bars represent the standard deviations between the 4 subjects. **d**, Box plots of the root-mean-
 19 square-errors (RMSEs) of the cortical profiles of the quantitative parameters calculated between (inter) and within (intra)
 20 subjects. **e**, Box plots of Pearson correlation coefficients (PCCs) of the profiles calculated between (inter) and within (intra)

1 subjects.

2 Despite the remarkable consistency across scans and subjects, the cortical profiles differ across different
3 cortical regions. The average profiles in Fig. 6c revealed different slopes and global values in different ROIs.
4 The results provided by 3D-EPTI in a dramatically reduced scan time agree well with previous literatures
5 investigating T_1 or T_2^* cortical profiles^{62,65,66}. For example, highly myelinated areas such as the motor (BA 4p),
6 and the sensory (BA 3b) areas have globally lower T_1 profiles than other areas. A relative flat T_2^* profile was
7 observed in the visual cortex, which was also reported previously^{65,66} and might be attributed to the highly
8 myelinated middle layers and increasing susceptibility in the outer layers due to presence of blood vessels with
9 a high level of iron. Previous studies investigating T_2 profiles across cortical depths have been lacking due to
10 the need for prohibitively long acquisitions. Using 3D-EPTI, different T_2 profiles were also obtained in different
11 ROIs, which could reflect differences in both myelin water content and iron composition and complement to
12 the findings in T_1 and T_2^* .

13 **Generating arbitrary image contrasts with adjustable weightings**

14 Current clinical MRI relies on contrast-weighted images, which are acquired by sequentially applying
15 multiple sequences with predetermined acquisition parameters. This is time consuming, requires cross-contrast
16 registration, and results in suboptimal contrast if there are substantial individual differences, particularly in the
17 case of abnormalities. In a single scan within minutes, 3D-EPTI not only provides co-registered simultaneous
18 quantitative maps as mentioned above but is also able to generate arbitrary image contrasts with adjustable
19 contrast weightings, yielding optimized visualization for the tissue or lesion of interest. Figure 7 demonstrated
20 the contrast-synthesizing ability of 3D-EPTI in several examples. First, the standard routine clinical contrasts,
21 MPRAGE, T_2 -FLAIR and T_2 -weighted, were synthesized with high quality for all of the three protocols (Fig.
22 7a). Double inversion recovery (DIR) was also generated as an example to provide superior cortical
23 visualization. Previously, despite its higher sensitivity in the detection of cortical lesions for multiple
24 sclerosis^{70,71}, the adoption of DIR to clinical applications has been limited by the low SNR and lengthy
25 acquisition. With 3D-EPTI, DIR or any other useful contrasts can be synthesized simultaneously after a few
26 minutes of scan. The isotropic resolution of the 3D-EPTI protocols also facilitate the flexibility of viewing the
27 images in arbitrary orientations (Fig.7b). Moreover, the weighting of each of these contrasts is adjustable to
28 provide optimal visualization without the need to re-scan the subject. For instance, the contrast-determining
29 parameters of an IR-SE sequence (FLAIR), TI and TE, can be freely adjusted across a wide range, resulting in
30 a spectrum of possible contrasts between white and gray matter (Fig. 7c). From the spectrum, a particular set of
31 parameters can be identified and selected for final image synthesis, such as the ones that offer the maximum
32 white-grey contrast. We also showed the maximum image contrast between CSF and gray matter using a
33 different set of parameters identified from their spectrum. Here, the CSF, gray and whitter matter were used as
34 an illustration of the contrast optimization framework in healthy volunteer, but this can be easily applied to any
35 tissue or lesion types to improve the diagnostic power of MRI.



1
2 Figure 7. Synthesized multi-contrast images using 3D-EPTI. **a**, Synthetic MPRAGE, T₂-FLAIR, T₂-weighted, and double-
3 inversion recovery (DIR) contrasts from three protocols (9-min 0.7-mm protocol, 3-min 1-mm protocol, and 1-min 1.5-mm
4 protocol). **b**, Example of the flexibility in visualization in different views of the synthesized images at high isotropic resolution.
5 **c**, Example of contrast-optimized visualization between target-tissue pair by adjusting sequence parameters (TI and TE).
6 Two examples that maximized the contrast differences i) between white matter and gray matter, and ii) between gray matter
7 and CSF, are presented. The spectrum of contrast difference between the two tissues (c, left panel) is used to select the
8 parameters to synthesize the contrast for optimal visualization (c, middle panel). The intensity distribution of the optimized
9 contrast in three tissues are shown at the right panel.

10 3. Discussion

11 The goal of this study is to address the long-standing problem in quantitative MRI — the slow acquisition
12 speed. The key concept in 3D-EPTI of exploiting spatiotemporal correlation at multiple timescales through new
13 encoding strategies within and between its efficient continuous readouts was used to achieve rapid quantitative

1 MRI. This has allowed the acquisition of robust multi-parametric maps within minutes at high isotropic
2 resolution with whole brain coverage. As a proof-of-concept, a 3D-EPTI sequence for simultaneous T_1 , T_2 and
3 T_2^* mapping was developed and validated, as these are the fundamental relaxation time constants that determine
4 the contrast of most MR images.

5 High intra-subject repeatability of the quantitative parameters obtained using 3D-EPTI was demonstrated
6 across multiple healthy volunteers. This will be critical to the success of future deployment of 3D-PTI to various
7 applications such as in longitudinal monitoring of healthy and diseased tissues during complex biological
8 process of brain development or pathophysiological progression of neurological diseases. Nonetheless, despite
9 our efforts to minimize the bias in the repeatability assessment process itself, such as by using automatically
10 segmented ROIs instead of manual ROIs, the small variations (bias < 0.8% and COV < 2.27%) could still be
11 partially caused by errors in the registration process to align the two scans for comparison. Moreover, inherent
12 differences between scans are possible. For example, T_2^* shows slightly higher variability than T_1 and T_2 , which
13 may be explained by the differences due to its dependence on head orientations relative to the main magnetic
14 field.

15 The high inter-subject repeatability (COV < 5.09%) of the quantitative parameters obtained using 3D-EPTI
16 on healthy volunteers points to its potential for use in establishing population-average norms or atlases.
17 Currently, multi-parametric MRI atlases are still lacking, but the short scans enabled by 3D-EPTI can
18 significantly improve the cost effectiveness and facilitate large-scale studies for this purpose. On the other hand,
19 as expected, the inter-subject repeatability is lower than the intra-subject repeatability. This could reflect the
20 ability of 3D-EPTI to detect inherent individual differences, pointing to its potential in providing sensitive
21 quantitative biomarkers. However, some of the increased variability could also be attributed to the additional
22 segmentation variabilities across subjects, especially in challenging areas such as the optic chiasm. High intra-
23 and inter-subject repeatability was also observed in the intra-cortical profiles obtained by 3D-EPTI. This
24 illustrates the robust performance in using 3D-EPTI data to conduct reliable surface reconstruction and reveal
25 repeatable subtle features across cortical layers. In addition to its potential for use in longitudinal monitoring
26 and in establishing quantitative biomarkers, 3D-EPTI could be used to evaluate spatially varying profiles of
27 cortical myelination and iron concentration.

28 The reliability of the quantitative measures obtained using 3D-EPTI was further validated by comparing
29 them to ones obtained using lengthy standard acquisitions, where a generally high level of agreement was
30 observed in both in-vivo (Fig. 4) and phantom (Supplementary Fig. 4) experiments. The largest difference was
31 observed in the in-vivo T_1 -values, with a bias level of 7.23%. This could potentially be attributed to the magnetic
32 transfer (MT) effect, which causes a different level of exchange between water and macromolecular pools in
33 different sequences. This can create discrepancies between the actual and the modelled signal evolutions in both
34 3D-EPTI and in the standard acquisition, where the MT effect has not been accounted for. Such an effect is
35 more prominent in T_1 quantification, due to the use of an inversion recovery pulse. The characterization and
36 disentanglement of the MT effect in quantitative mapping is an active area of research⁷². Future work will
37 investigate the incorporation of a MT-sensitive sequence module into the 3D-EPTI acquisition, and model the

1 MT effect in both the reconstruction and parameter fitting.

2 With its unprecedented high efficiency for simultaneous multi-parametric mapping at high resolution with
3 high repeatability, 3D-EPTI has the potential to enable the next-generation of brain examination. In such an
4 examination, after ‘one click’, multiple quantitative parameters can be acquired in a single fast scan within a
5 few minutes at high resolution and whole brain coverage. Images with the optimal contrasts of choice can then
6 be generated post-acquisition and visualized in arbitrary views. Moreover, with robust quantitative measures,
7 abnormal changes can be automatically detected by comparing with established norms, and further monitored
8 over time. Beyond traditional diagnosis, the accuracy of computer-assisted diagnostic algorithms particularly
9 with machine learning can also benefit from the adoption of quantitative imaging data, where standardized data
10 with high repeatability will enable better network training. The successful implementation of these technologies
11 should facilitate a more efficient, accurate and cost-effective diagnostic work-flow, and provide a powerful tool
12 for neuroscientific research.

13 The concept of 3D-EPTI can be readily adopted to other pulse sequences for the quantification of other
14 tissue parameters. For example, 3D-EPTI should be exceptionally well suited for parameters estimation for
15 multiple pools models, because it can continuously track complex signal evolution at a very short time scale (<
16 1 ms) to offer more degrees of freedom in estimating these parameters. The concurrent distortion- and blurring-
17 free multi-contrast images obtained with 3D-EPTI can also be used in combination with the quantitative
18 parameters. A simple example is the adoption of this work into a typical functional MRI sequence, where the
19 obtained T_2^* value can be used to optimally combine time-resolved multi-echo images to enhance the contrast-
20 to-noise ratio. The unique features of 3D-EPTI also open up many possibilities for further technical
21 improvements. For example, the radial-block sampling of 3D-EPTI grants it the ability to monitor and correct
22 subject movements between repetitions for motion-immune scanning. Other advanced reconstruction
23 algorithms, including machine learning and multi-dimensional low-rank tensor approach, may further improve
24 the accuracy of time-resolving reconstruction.

25 **4. Methods**

26 **Pulse sequence and encoding design**

27 IR-GE and VFA-GRASE²⁷ sequences were implemented to provide high sensitivity to T_1 , T_2 , and T_2^* , with
28 the continuous 3D-EPTI readout inserted after each excitation (i.e., each TI or SE) (Fig. 1a). In the IR-GE
29 sequence, an adiabatic inversion pulse was applied, followed by 20 excitation pulses with small flip angles (30°).
30 In the VFA-GRASE sequence, 10 variable-flip-angle refocusing pulses were applied after the 90° pulse with
31 flip angles of 122° , 58° , 44° , 41° , 41° , 46° , 158° , 189° , 43° , 30° . The flip angles and the timing of the pulse
32 sequence were chosen based on the results of an optimization considering both the signal amplitude and the
33 differentiability between tissues. All the excitation and refocusing RF pulses in the IR-GE and GRASE
34 sequences were non-selective with short pulse durations (0.5 ms for excitation and 1 ms for refocusing),
35 therefore resulting in shorter achievable starting echo time and shorter sampling interval. Readout gradient was

1 applied along the Head-Foot (HF) direction to avoid signal wrap from the non-selective excitation. Spectrally-
2 selective fat saturation was applied before each excitation pulse in the IR-GE sequence and before the 90° pulse
3 in the GRASE sequence. Spoiling gradients were applied after each readout in the IR-GE sequence, and crusher
4 gradients were used for each refocusing pulse in the GRASE sequence.

5 The 3D-EPTI acquisition was performed to encode data in a 4D spatiotemporal space (k - t space) to capture
6 the signal temporal evolution across the readouts in the IR-GE and VFA-GRASE sequences. The frequency
7 space (k -space) itself consists of three encoding dimensions, k_x , k_y , and k_z , where k_x is the so-called frequency
8 encoding, and k_y and k_z are the two phase-encoding dimensions. To achieve efficient encoding and fast scan, a
9 number of tailored undersampling strategies were carefully designed and synergistically employed within and
10 across the 3D-EPTI readouts. In each 3D-EPTI readout, a block of k - t space (k_y - k_z - t) is acquired, which contains
11 multiple time segments of “echo sections” (Supplementary Fig. 6). In each echo section, the k_y - k_z sampling
12 locations at different time points are arranged to be complementary and are acquired in an interleaved fashion
13 using a spatiotemporal controlled aliasing sampling strategy⁷³. The distance between k_y - k_z samples within each
14 echo section was kept within the capability of parallel imaging and coil sensitivity to recover the missing points.
15 The distance along time was kept to 6-8 ms by using a small block size. Within each readout, two
16 complementary CAIPI patterns were used across echo sections to provide additional independent sampling that
17 has been shown to further improve the reconstruction performance at high acceleration rates²⁸. The encoding
18 patterns used in the 1.5-mm/1-mm protocol and 0.7 mm protocol are illustrated in Supplementary Fig. 6. For
19 each 3D-EPTI readout, the overall acceleration factor in k - t space is equal to the block size ($k_y \times k_z$), as only one
20 data point is sampled at each time point in the block. An acceleration factor of 80 ($k_y \times k_z = 8 \times 10$) was utilized
21 for 1.5-mm and 1-mm acquisitions, while a smaller acceleration factor of 48 ($k_y \times k_z = 8 \times 6$) was used for the
22 0.7-mm acquisition to compensate for the larger time interval (larger echo spacing).

23 In each TR of the IR-GE and VFA-GRASE sequences, one $k_y \times k_z$ block is acquired in each of the readout.
24 To quickly encode the 4D k - t space using a small number of TRs, a golden-angle radial block sampling is
25 employed across the readouts (Supplementary Fig. 6). Different blocks are acquired at different TRs to compose
26 a block-wise golden-angle radial pattern at every TI and SE, with the radial pattern rotating with a golden angle
27 across the different readouts. Such radial sampling creates spatiotemporal incoherent aliasing that is well suited
28 for constrained subspace reconstruction. It provides additional acceleration on top of the acceleration within the
29 block, where the acceleration factor depends on how many lines of radial blocks are acquired. The detailed
30 design of radial-block sampling is shown in Supplementary Fig. 7. For the 1-mm protocol, 2 radial lines were
31 acquired for the IR-GE sequence in 45 TRs (instead of $23 \times 23 = 529$ TRs without radial-block acceleration), and
32 3 radial lines in 65 TRs were acquired for the GRASE sequence. More lines were acquired in GRASE to
33 compensate for the fewer number of readouts to encode the k - t space (10 SEs in GRASE vs. 20 TIs in IR-GE).
34 For the 1.5-mm protocol, 3 radial lines with a reduction factor of 2 along the radial direction, equivalent to 1.5
35 lines, were acquired in 23 TRs (instead of $15 \times 15 = 225$ TRs), and 2 radial lines were acquired for GRASE in 29
36 TRs. The 0.7-mm protocol acquired 4 radial lines for both IR-GE and GRASE in a total of 161 TRs (instead of
37 $41 \times 41 = 1681$ TRs) to provide sufficient sampling for higher spatial resolution.

1 Image Reconstruction

2 The low-rank subspace method^{22,28} was utilized to jointly reconstruct the IR-GE and VFA-GRASE multi-
3 contrast images across different time points (Supplementary Fig. 1). At first, a large number of temporal signal
4 evolutions were simulated using the Extended Phase Graphs (EPG) approach, each contains N_t time points. A
5 wide range of quantitative parameters were used to exhaust all possibilities of interest: T_1 from 400 ms to 5000
6 ms, T_2 from 10 ms to 500 ms, T_2^* from 10 ms to 500 ms, B_1^+ factor from 0.75 to 1.25. Additional constraint of
7 T_2^* was also enforced to keep its value no higher than T_2 . Second, N_b subspace basis vectors $\phi \in \mathbb{C}^{N_t \times N_b}$ were
8 extracted from these simulated signals by using principal component analysis (PCA). In this study, we selected
9 12 bases that can approximate the simulated signals with an error smaller than 0.2%. Then, the full time series
10 of N_v spatial voxels can be represented by ϕc , where $c \in \mathbb{C}^{N_b \times N_v}$ contains the coefficient maps of the subspace
11 bases that can be estimated by solving:

$$12 \min_c \|UFSP\phi c - y\|_2^2 + \lambda R(c) \quad (1)$$

13 where $P \in \mathbb{C}^{N_v \times N_t}$ contains the phase evolutions across the time-series images including the background and B_0
14 inhomogeneity-induced phases, $S \in \mathbb{C}^{N_v \times N_c}$ denotes the coil sensitivity of a N_c -channel receiver coil, F is the
15 Fourier transform operator applied across the spatial dimensions, U is the undersampling mask, and y
16 represents the acquired k -space data. The phase map P and sensitivity map S can be obtained from a low-
17 resolution calibration pre-scan. A locally low-rank (LLR) regularization $R(c)$ was applied on coefficient maps
18 with a control parameter λ to further improve the conditioning. Since the number of unknowns in the
19 optimization problem is significantly reduced from thousands of images to a few coefficient maps, the subspace
20 method can achieve accurate image reconstruction for 3D-EPTI at high accelerations.

21 The subspace reconstruction was solved by the alternating direction method of multipliers (ADMM)
22 algorithm⁷⁴ implemented in the Berkeley Advanced Reconstruction Toolbox (BART)^{75,76}. A maximum number
23 of iterations = 100 was set to be the stop criterion. Other parameters of the reconstruction including rho of
24 ADMM and λ of LLR were set at 0.01 and 3×10^{-4} respectively. These reconstruction parameters were
25 selected empirically based on the results of a simulation test (example simulation results shown in
26 Supplementary Fig. 2). Each readout slice of the 3D volumetric dataset was reconstructed independently by
27 applying the inverse Fourier Transform along the fully-sampled frequency-encoding direction before the
28 reconstruction. After reconstruction, the quantitative parameters were estimated from a dictionary-based
29 matching. The dictionary was generated using the EPG approach with the same parameter range used in the
30 basis generation. After dictionary matching, the estimated B_1^+ maps were fitted by a 2nd-order polynomial
31 function in the 3D spatial domain, with an assumption that B_1^+ fields vary smoothly in the spatial domain, which
32 were then fed back into the dictionary matching to obtain more accurate quantitative parameters.

33 Acquisition parameters

34 All data were acquired on a Siemens Prisma 3T scanner with a 32-channel head coil (Siemens Healthineers,

1 Erlangen, Germany). The 3D-EPTI protocols were used in the scan-rescan experiment where the subject was
2 taken out of the scanner and repositioned between the two scans.

3 The 1-mm 3D EPTI data were all acquired with the following parameters: FOV = $220 \times 176 \times 210$ mm³
4 (AP-LR-HF), matrix size = $230 \times 184 \times 210$, spatial resolution = $0.96 \times 0.96 \times 1$ mm³, echo spacing = 0.93 ms,
5 TR of IR-GE = 2600 ms, TR of GRASE = 800 ms. There were 20 readouts in IR-GE, each containing 48 echoes,
6 and 10 readouts in GRASE, each containing 39 echoes. The total acquisition time was ~3 minutes, including
7 117 seconds for IR-GE, 54 seconds for GRASE, and a 12-second calibration scan. The k - t calibration scan was
8 acquired to estimate the B_0 and coil sensitivity maps using a GE sequence with bipolar readouts, where data
9 were acquired with the same FOV and echo spacing as the imaging scan. Other relevant acquisition parameters
10 were: matrix size = $42 \times 32 \times 210$, number of echoes = 9, TR = 24 ms. The k -space center (8×8) was fully-
11 sampled and the rest of k -space was undersampled along k_y and k_z by a factor of 2×2 . GRAPPA¹⁶ was used to
12 reconstruct the missing data points in the calibration data. The calibration scan for all of the following
13 acquisitions used the same matrix size along k_y and k_z with the same acceleration factor.

14 The acquisition parameters for the 1.5-mm protocol were: FOV = $218 \times 173 \times 230$ mm³ (AP-LR-HF),
15 matrix size = $150 \times 120 \times 154$, spatial resolution = $1.45 \times 1.44 \times 1.49$ mm³, TR of IR-GE = 1900 ms, TR of
16 GRASE = 600 ms, echo spacing = 0.72 ms, each readout contained 53 echoes in IR-GE, and 39 echoes in
17 GRASE. The total acquisition time was ~1 minute, including 44 s for IR-GE and 17 s for GRASE. The 1.5-
18 mm calibration scan took 10 seconds with a TR = 20 ms.

19 The acquisition parameters for the 0.7-mm protocol were: FOV = $224 \times 176.4 \times 224$ mm³ (AP-LR-HF),
20 matrix size = $328 \times 246 \times 322$, spatial resolution = $0.68 \times 0.72 \times 0.70$ mm³, TR of IR-GE = 2600 ms, TR of
21 GRASE = 800 ms, echo spacing = 1.2 ms, each readout contained 42 echoes in IR-GE, and 33 echoes in GRASE.
22 The total acquisition time was ~9 minutes, including 7 min for IR-GE and 2 min for GRASE. The calibration
23 scan took 12 seconds with 7 echoes and a TR of 24 ms.

24 To obtain reference quantitative maps for comparison, conventional gold-standard acquisition approaches
25 were used, including 2D IR-SE for T_1 mapping, 2D single-echo SE for T_2 mapping, and 3D multi-echo GRE
26 for T_2^* mapping. In the phantom experiment, the acquisition parameters of the IR-SE sequence for T_1 mapping
27 were: FOV = 256×256 mm², in-plane resolution = 1×1 mm², slice thickness = 3 mm, number of slices = 9,
28 acceleration factor along k_y = 2, TR = 8000 ms, TIs = 100, 200, 400, 800, 1600, 3200 ms. The T_2 mapping was
29 performed using the single-echo SE sequence with the same FOV, resolution, and acceleration as in IR-SE. The
30 TR was 3000 ms, and 6 echo times (25, 50, 75, 100, 150, 200 ms) were acquired to achieve robust fitting. The
31 3D multi-echo GRE sequence was used for the T_2^* mapping with FOV = $186 \times 176 \times 224$ mm³ at 1-mm isotropic
32 resolution. Seven echo times (5, 10, 15, 25, 35, 45, 60 ms) were acquired with an acceleration factor of 2×2
33 ($k_y \times k_z$). The total acquisition time for the phantom reference scans was about 1.5 hours, including 30 minutes
34 for IR-GE, 50 minutes for single-echo SE, and 12 minutes for 3D GRE. The same sequences were used for the
35 in-vivo test, however, a lower resolution of 2×2 mm² was used in the IR-SE and single-echo SE sequences to
36 reduce the scan time and mitigate potential motion-induced artifacts. Most of the other parameters were kept
37 the same as the phantom scan, except for, the number of slices = 19 for IR-SE and single-echo SE, TEs of single-

1 echo SE = 25, 50, 75, 100, 140, 180 ms, a higher acceleration factor along $k_y = 3$ for IR-GE and single-echo SE,
2 and FOV of 3D-GRE = $216 \times 176 \times 210 \text{ mm}^3$. Even with the lower resolution and higher acceleration, the total
3 scan time was still about 53 minutes, including 27 minutes for single-echo SE, 14 minutes for IR-SE, and 12
4 minutes for GRE.

5 **Image processing and analysis**

6 In the test-retest experiment, the quantitative maps from the two scans were first registered using FLIRT⁷⁷⁻
7 ⁷⁹. Then, the average R_1 maps of each subject were used for Freesurfer segmentation, which resulted in 165
8 ROIs in cortical, subcortical, white matter and cerebellum regions after removing CSF regions and ROIs smaller
9 than 50 voxels. For cortical analysis, surface-based cortical reconstruction was performed using Freesurfer^{36,55,56}
10 on the R_1 maps separately for each subject and for each scan. 9 equi-volume^{62,80} cortical layers were
11 reconstructed, and applied to all quantitative maps to investigate their distribution across different cortical
12 depths. These maps were sampled onto the average subject space with a 2-mm Gaussian surface smoothing for
13 final analysis.

14 Synthetic images are synthesized from the calculated quantitative maps based on signal equations of the
15 specific sequences. To illustrate the contrast optimization framework (Fig. 7c), a spectrum of the contrast
16 difference between two tissues was obtained using a range of acquisition parameters. The mean value of the
17 synthesized image intensity of the target tissues was used to calculate the contrast difference. The tissue can be
18 identified by the acquired quantitative maps, for example, a threshold-based segmentation on T_1 map was
19 performed in this instance to generate masks for gray matter, white matter and CSF.

20 **Materials**

21 All of the reconstructions were performed in MATLAB using a Linux workstation (CPU: Intel Xeon,
22 3.00GHz, 24 Cores; RAM: 512 GB; GPU: Quadro RTX 5000, 16 GB memory). The reconstruction time for
23 each imaging slice in the 1-mm dataset was about 1 minute, and the reconstruction of the whole-volume took
24 about 3 hours using one GPU.

25 **Human subjects**

26 Informed consent was collected from all healthy volunteers before imaging, with an institutionally
27 approved protocol.

28

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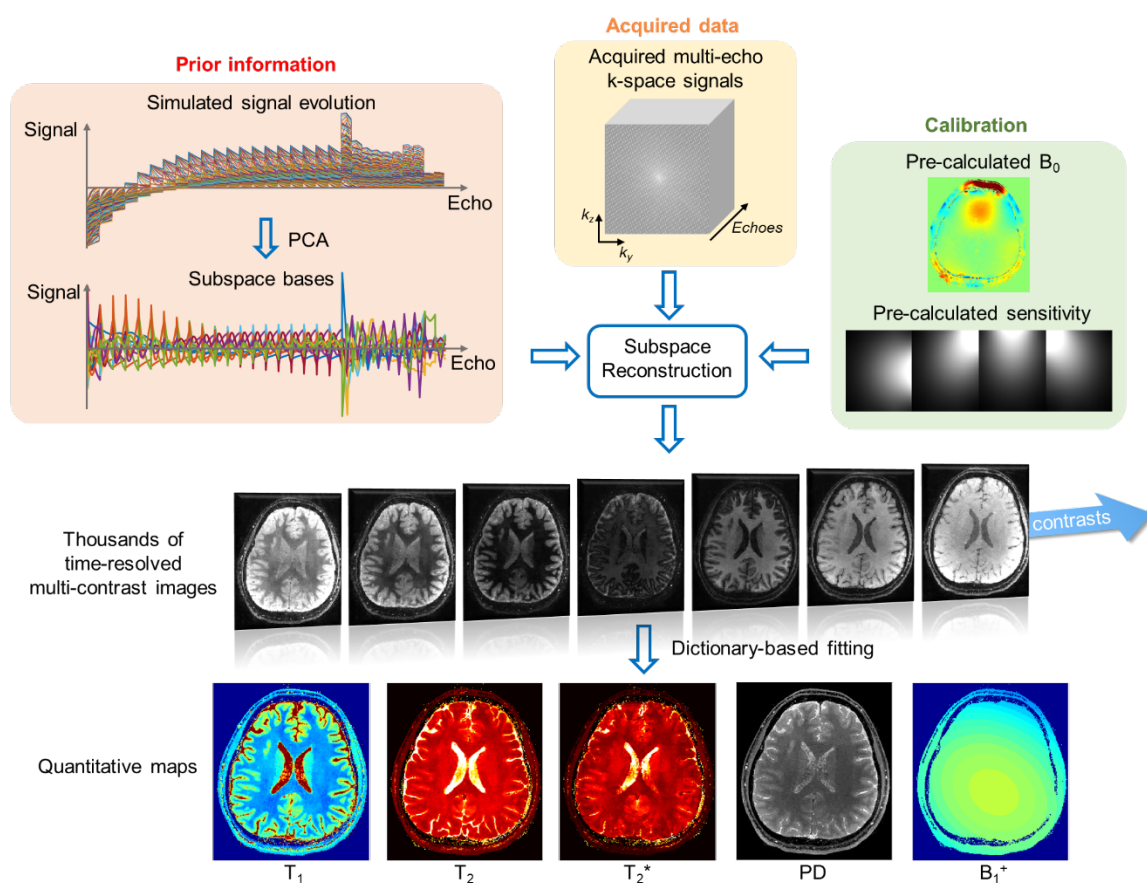
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- 52

1 Supplementary Information

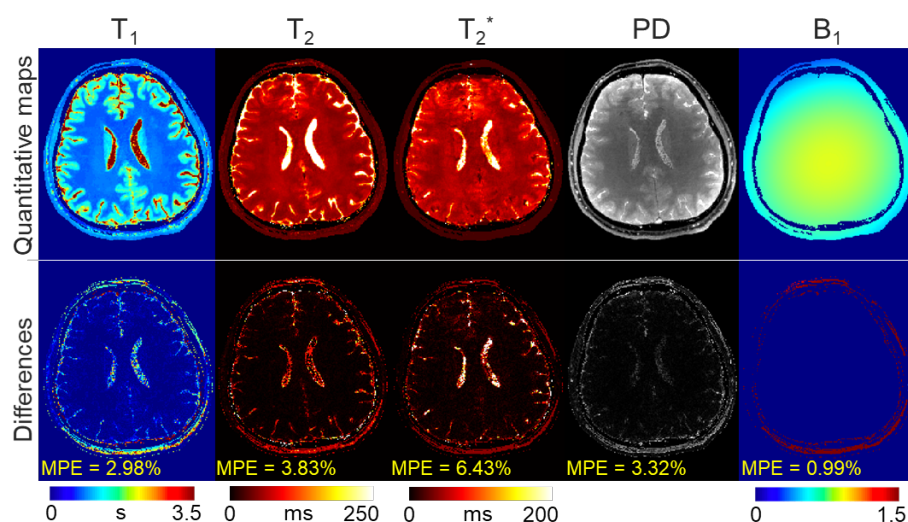


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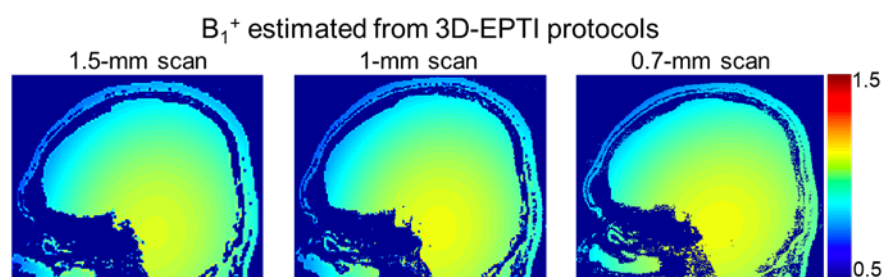
3 Supplementary Figure 1. Illustration of the reconstruction framework of 3D-EPTI using the low-rank subspace
 4 method. The signal evolutions can be represented by a linear combination of several subspace temporal bases
 5 instead of individual images, therefore reducing the number of unknowns. These subspace bases are extracted
 6 from the simulated signal space using principal component analysis (PCA). The subspace reconstruction is
 7 performed by integrating the information from a highly-undersampled spatiotemporal dataset, B_0 phase
 8 evolution and coil sensitivity maps obtained via a calibration dataset, and subspace bases. After the
 9 reconstruction, thousands of multi-contrast images are obtained without distortion and blurring, from which
 10 multiple quantitative parameters including T_1 , T_2 , T_2^* , PD, and B_1^+ can be estimated through dictionary matching.

11

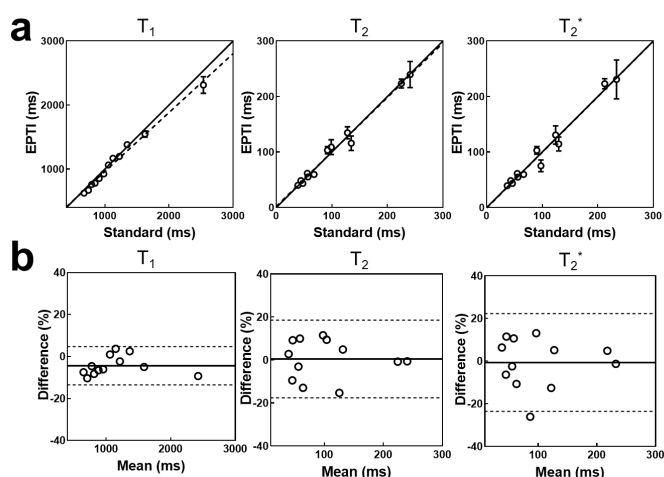
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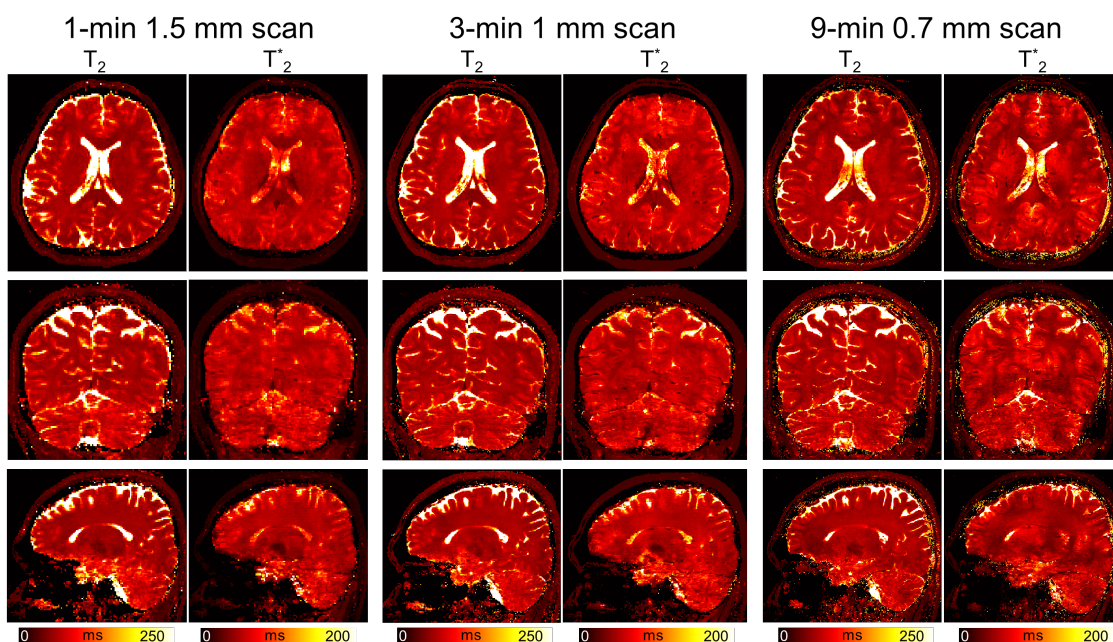
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2 Supplementary Figure 2. Example results of the simulation experiment. The undersampled EPTI data were
3 simulated from pre-acquired reference quantitative maps using acquisition parameters of the 1-mm 3-minute
4 protocol. The difference maps ($\times 2$: magnified by a factor of 2) were calculated by subtracting the reference
5 maps from the estimated quantitative maps. MPE: mean percentage error.



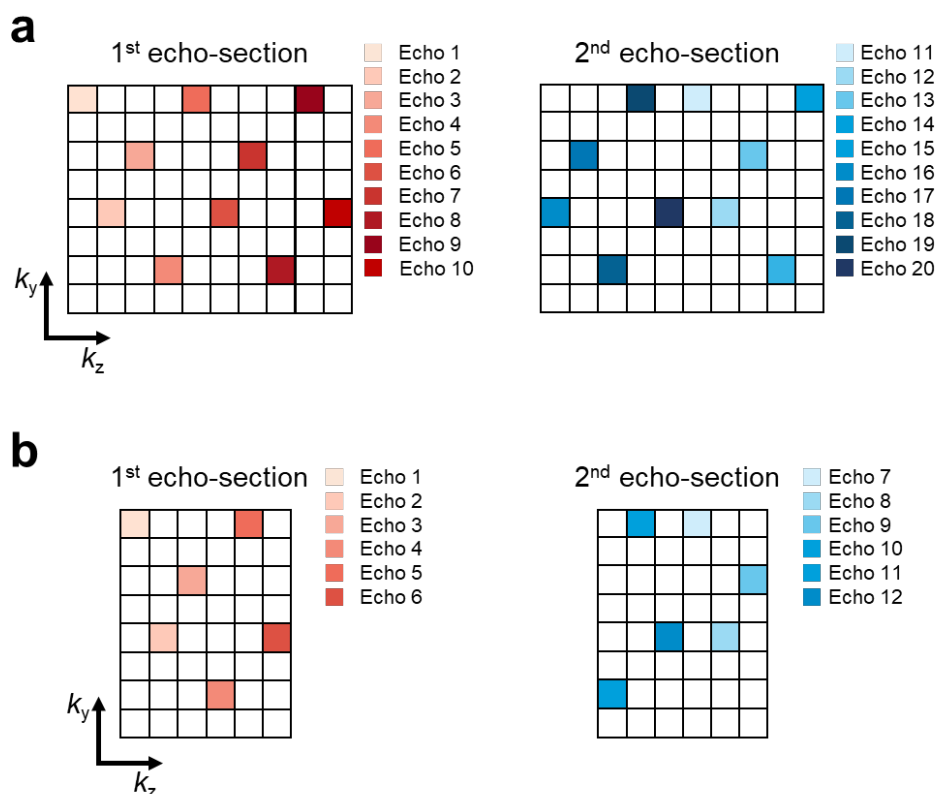
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7 Supplementary Figure 3. The estimation of B_1^+ field on the same subject from three 3D-EPTI scans at different
8 resolutions.



9
10 Supplementary Figure 4. Comparison of the quantitative measurements between 3D-EPTI and standard
11 acquisitions in the phantom experiment. **a**, Scatter plots of the quantitative values in 12 selected ROIs. **b**, Bland-
12 Altman plots of the same data.



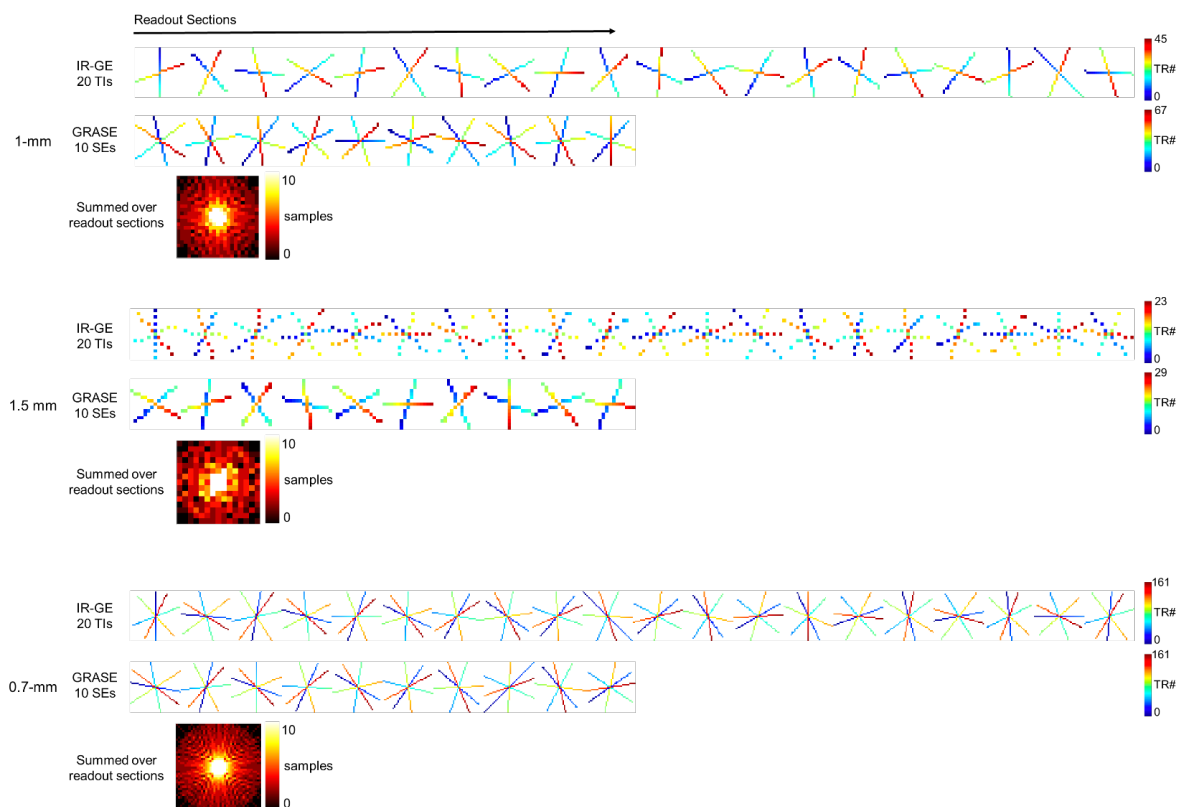
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 2 Supplementary Figure 5. The estimated T_2 and T_2^* maps from three different protocols on the same subject.
 3 Left panel: 1-minute protocol at 1.5-mm isotropic resolution; middle panel: 3-minute protocol at 1-mm isotropic
 4 resolution; right panel: 9-minute protocol at 0.7-mm isotropic resolution.



6
 7 Supplementary Figure 6. The encoding patterns in k_y - k_z space for (a) the 1.5-mm and 1-mm protocols, and (b)
 8 the 0.7 mm protocol. The different echo sections in each readout are encoded using two different patterns (red
 9 and blue) in an interleaved fashion to provide more complementary samplings (i.e., red for 1st echo section,

1 blue for 2nd, red for 3rd, blue for 4th, etc.).

2



3

4 Supplementary Figure 7. The golden-angle radial-blade sampling pattern used in the designed protocols (top:
5 1-mm protocol, middle: 1.5-mm protocol, bottom: 0.7-mm protocol). Each color-coded point represents one
6 sampling block acquired in a 3D-EPTI readout. After a few TRs, the sampling blocks acquired in the same
7 readout section will form a radial-block pattern. The color coding represents the acquisition order of the blocks.
8 For example, the index of TR (TR#) counts from 0 to the maximum, illustrated from blue to red. The combined
9 sampling patterns across all readout sections in IR-GE and VFA-GRASE result in a variable density pattern as
10 shown in the bottom.

11