Statistics of eigenvalue dispersion indices: quantifying the magnitude of

phenotypic integration

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1 Abstract

2 Quantification of the magnitude of covariation plays a major role in the studies of phenotypic 3 integration, for which statistics based on dispersion of eigenvalues of a covariance or 4 correlation matrix—eigenvalue dispersion indices—are commonly used. However, their use 5 has been hindered by a lack of clear understandings on their statistical meaning and sampling 6 properties such as the magnitude of sampling bias and error. This study remedies these issues 7 by investigating properties of these statistics with both analytic and simulation-based 8 approaches. The relative eigenvalue variance of a covariance matrix is known in the 9 statistical literature as a test statistic for sphericity, thus is an appropriate measure of 10 eccentricity of variation. The same of a correlation matrix is exactly equal to the average 11 squared correlation, thus is a clear measure of overall integration. Exact and approximate 12 expressions for the mean and variance of these statistics are analytically derived for the null 13 and arbitrary conditions under multivariate normality, clarifying the effects of sample size N, 14 number of variables p, and parameters on the sampling bias and error. Accuracy of the 15 approximate expressions are evaluated with simulations, confirming that most of them work 16 reasonably well with a moderate sample size ($N \ge 16-64$). Importantly, sampling properties 17 of these indices are not adversely affected by high p:N ratio, promising their utility in high-18 dimensional phenotypic analyses. These statistics can potentially be applied to shape 19 variables and phylogenetically structured data, for which necessary assumptions and 20 modifications are presented. 21 **Keywords:** covariance matrix; evolutionary constraint; morphometrics; phenotypic

22 integration; quantitative genetics; Wishart distribution.

23

24 Introduction

25 Analysis of trait covariation plays a central role in investigations into evolution of 26 quantitative traits. The well-known quantitative genetic theory of correlated traits predicts 27 that evolutionary response in a population under selection is dictated by the additive genetic 28 covariance matrix G as well as the selection gradient (Lande, 1979; Lande & Arnold, 1983). 29 Short-term evolutionary changes of a population are expected to be concentrated in major axes of the G matrix (Schluter, 1996). Arguably, the structure of the G matrix can be 30 31 approximated by that of the phenotypic covariance matrix for certain types of traits 32 (Cheverud, 1988, 1996; Roff, 1995; Dochtermann, 2011; Sodini et al., 2018), so the latter 33 could potentially be analyzed when accurate estimation of the G matrix is not feasible. These 34 theories and conjectures spurred extensive theoretical and empirical explorations on character 35 covariation as an evolutionary constraint (e.g., Steppan et al., 2002; Chenoweth et al., 2010; 36 Hansen et al., 2019 and references therein). Partly fueled by these developments, the study of 37 phenotypic integration has developed as an active field of research, where various aspects of 38 character covariation are investigated with diverse motivations and scopes (e.g., Olson & 39 Miller, 1958; Cheverud, 1982; Goswami, 2006; Hallgrímsson et al., 2009; Armbruster et al., 40 2014; Felice et al., 2018). In the latter context, many different levels of organismal variation 41 can be subjects of research, such as static, ontogenetic, and evolutionary levels (Klingenberg, 42 2014). For example, relationships between within-population integration and evolutionary 43 rate and/or trajectories have attained much attention as potential links between micro- and 44 macroevolutionary phenomena (e.g., Klingenberg et al., 2012; Renaud & Auffray, 2013; 45 Goswami et al., 2015; Haber, 2015, 2016).

An obvious target of investigation in these contexts is quantitative analysis of
magnitude of constraint or integration entailed in covariance structures. In particular, this
paper concerns methodology for quantifying the overall magnitude of covariation within a set

49 of traits. Quantification of relative (in)dependence between multiple sets of traits-the 50 modularity-integration spectrum-is another major way of studying integration which has 51 separate methodological frameworks (e.g., Goswami & Polly, 2010; Adams, 2016; Goswami 52 & Finarelli, 2016; Adams & Collyer, 2019a). Demonstrating the presence of integration with 53 a statistically justified measure can be the scope of an empirical analysis, sometimes as a part 54 of testing combined hypotheses (e.g., Brommer, 2014; Watanabe, 2018). A univariate 55 summary statistic for magnitude of integration can conveniently be used in comparative 56 analyses across developmental stages, populations, or phylogeny (e.g., Marroig et al., 2009; 57 Porto et al., 2009; Haber, 2016). A plethora of statistics have been proposed for such 58 purposes from various standpoints (e.g., Van Valen, 1974, 2005; Cheverud et al., 1983, 1989; 59 Wagner, 1984; Cane, 1993; Hansen & Houle, 2008; Agrawal & Stinchcombe, 2009; 60 Kirkpatrick, 2009; Pavlicev et al., 2009; Armbruster et al., 2009, 2014; Haber, 2011; Pitchers 61 et al., 2014). One of the most popular class of such statistics is based on the dispersion of 62 eigenvalues of a covariance or correlation matrix. These statistics have the forms

70
$$V = \frac{1}{p} \sum_{i=1}^{p} (\lambda_i - \bar{\lambda})^2$$

71
$$V_{\rm rel} = \frac{\sum_{i=1}^{p} (\lambda_i - \bar{\lambda})^2}{p(p-1) \,\bar{\lambda}^2}$$

63 where *p* is the number of variables (traits), λ_i is the *i*th eigenvalue of the covariance or 64 correlation matrix under analysis, and $\overline{\lambda}$ is the average of the eigenvalues. Here, *V* is the most 65 naïve form of eigenvalue dispersion, and V_{rel} is a scaled version which ranges between 0 and 66 1. Formal definitions are given below with distinction between population and sample 67 quantities. Some authors use square root or a constant multiple of these forms, but such 68 variants essentially bear identical information when calculated from the same matrix. 69 Alternative terms for this class of statistics include the tightness (for V_{rel} ; Van Valen, 1974;

72	later used for $\sqrt{V_{rel}}$ by Van Valen, 2005), integration coefficient of variation (for
73	$\sqrt{(p-1)V_{rel}}$; Shirai & Marroig, 2010), and phenotypic integration index (for V; Torices &
74	Muñoz-Pajares, 2015). In this paper, V and V_{rel} are called the eigenvalue variance and
75	relative eigenvalue variance, respectively, to take a balance between brevity and
76	descriptiveness. These quantities are not to be confused with the sampling variance
77	associated with eigenvalues in a sample (see below).

78 Since eigenvalues of a covariance or correlation matrix correspond to the variance 79 along the corresponding eigenvectors (principal components), these statistics are supposed to 80 represent eccentricity of variation across directions in a trait space (Fig. 1; Wagner, 1984). 81 Cheverud et al. (1983) and Wagner (1984) were the first to propose using V of a correlation matrix for quantifying magnitude of integration. Pavlicev et al. (2009) devised V_{rel} of a 82 83 correlation matrix, and explored its relationships to correlation structures in certain 84 biologically relevant conditions. Haber (2011) pointed out similarity between these indices 85 and Van Valen's (1974) tightness index for a covariance matrix, and proposed that these indices can be applied to either covariance or correlation matrices with slightly different 86 87 interpretations. Eigenvalue dispersion indices are frequently used in empirical analyses of 88 phenotypic integration at various levels of organismal variation, from phenotypic covariance 89 at the population level to evolutionary covariance at the interspecific level (e.g., Ordano et 90 al., 2008; Torices & Mendez, 2014; Haber, 2016; Haber & Dworkin, 2017; Watanabe, 2018; 91 Arlegi et al., 2020). However, use of these indices has been criticized for a lack of clear 92 statistical justifications; it has not been known-or not widely appreciated by biologists-93 exactly what they are designed to measure, beyond the intuitive allusion to eccentricity 94 mentioned above (Hansen & Houle, 2008; Hansen et al., 2019).

Another fundamental issue over the eigenvalue dispersion indices is a virtual lack of
 systematic understanding of their sampling properties. In empirical analyses, eigenvalue

97 dispersion indices are calculated from sample covariance or correlation matrices, but interests 98 will be in making inferences for the underlying populations. For example, interest may be in 99 detecting the presence of bias in a population, i.e., testing the null hypothesis of sphericity 100 (no eccentricity). As detailed below, however, sample eigenvalues are always estimated with 101 error, so that V and V_{rel} calculated from them take a positive value, even if the corresponding 102 population values are 0. In other words, empirical eigenvalue dispersion indices are biased 103 estimators of the corresponding population values under the null hypothesis. For statistically 104 justified inferences, it is crucial to capture essential aspects of their sampling distributions, 105 e.g., expectation and variance.

106 The presence of estimation or sampling bias in eigenvalue dispersion indices has been 107 well known in the literature (Wagner, 1984; Cheverud et al., 1989; Grabowski & Porto, 2017; 108 see also Marroig et al., 2012). Simulation-based approaches have been taken to sketch 109 sampling distributions of eigenvalue dispersion indices and related statistics (Haber, 2011; 110 Grabowski & Porto, 2017; Machado et al., 2019; Jung et al. 2020). However, these 111 approaches hardly give any systematic insight beyond the specific conditions considered. 112 Analytic results should preferably be sought to comprehend the sampling bias and error. In 113 this regard, it is notable that Wagner (1984) derived the first two moments of eigenvalues of 114 sample covariance and correlation matrices under the null conditions, proposing to use the 115 variance of sample eigenvalues obtained from these moments as an estimate of sampling bias 116 in these conditions. Strictly speaking, however, the variance of a sample eigenvalue is 117 fundamentally different from the expectation of the eigenvalue variance V. These quantities 118 are identical for correlation matrices under the null hypothesis, but this is not the case for 119 covariance matrices where the covariances between sample eigenvalues cannot be ignored 120 (see below). Furthermore, Wagner's (1984) results have a few restrictive conditions: 121 variables to have the means of 0, or equivalently, to be centered at the population mean rather

122 than the sample mean as is done in most empirical analyses (although this was probably 123 appropriate in the strict context of his theoretical model); and the sample size N to be equal to 124 or larger than the number of variables p, so their applicability to p > N conditions has not 125 been demonstrated.

126 In addition to the naïve null condition of no integration, moments under arbitrary 127 conditions are also desired. Such would be useful in testing hypotheses about the magnitude 128 (rather than the mere presence/absence) of integration (Harder, 2009; Fornoni et al., 2009) 129 and comparing the magnitudes between different samples (Cheverud et al., 1989). Also, the 130 assumption of no covariation is intrinsically inappropriate as a null hypothesis for shape 131 variables where raw data are transformed in such a way that individual "variables" are 132 necessarily dependent on one another (e.g., Mitteroecker et al., 2012). For this type of data, a 133 covariance matrix with an appropriate structure needs to be specified as the null model 134 representing the intrinsic covariation.

135 This paper addresses the issues over the eigenvalue dispersion indices mentioned 136 above. It first gives a theoretical overview of these statistics to clarify their statistical 137 justifications, particularly in connection to the sphericity test in multivariate analysis. Then 138 exact and approximate expressions are analytically derived for the expectation and variance 139 of V and V_{rel} of sample covariance and correlation matrices under the null and arbitrary 140 conditions, assuming the multivariate normality of original variables. These expressions are 141 derived without any assumption on p or N, except for the variance of V and V_{rel} of a 142 correlation matrix under arbitrary conditions, which is based on a strict large-sample 143 asymptotic theory. Simulations were subsequently conducted to obtain systematic insights 144 into sampling properties and to evaluate the accuracy of the approximate expressions. Potential extensions into shape variables and phylogenetically structured data are briefly 145 146 discussed.

147

148 Theory

- 149 **Preliminaries**
- 150 For the purpose here, the distinction between population and sample quantities is essential.
- 151 Corresponding Greek and Latin letters are used as symbols for the former and latter,
- 152 respectively. Let Σ be the $p \times p$ population covariance matrix, whose (i, j)-th component σ_{ij}
- 153 is the population variance (i = j) or covariance $(i \neq j)$. It is a symmetric, nonnegative
- 154 definite matrix with the eigendecomposition
- 155 $\boldsymbol{\Sigma} = \boldsymbol{\Upsilon} \boldsymbol{\Lambda} \boldsymbol{\Upsilon}^T, \tag{1}$

156 where the superscript ^T denotes matrix transposition, $\boldsymbol{\Upsilon}$ is an orthogonal matrix of

157 eigenvectors ($\mathbf{Y}\mathbf{Y}^T = \mathbf{Y}^T\mathbf{Y} = \mathbf{I}_p$ where \mathbf{I}_p is the $p \times p$ identity matrix), and $\mathbf{\Lambda}$ is a diagonal

- 158 matrix whose diagonal elements are the eigenvalues $\lambda_1, \lambda_2, ..., \lambda_p$ of Σ (population
- 159 eigenvalues). For convenience, the eigenvalues are arranged in the non-increasing order:

160 $\lambda_1 \ge \lambda_2 \ge \cdots \ge \lambda_p \ge 0$. Let μ be the $p \times 1$ population mean vector.

- 161 Let **X** be an $N \times p$ observation matrix consisting of *p*-variate observations, which are 162 individually denoted as \mathbf{x}_i ($p \times 1$ vector; transposed in the rows of **X**). (No strict notational
- 163 distinction is made between a random variable and its realization.) At this point, N
- 164 observations are assumed to be identically and independently distributed (i.i.d.). The sample
- 165 covariance matrix **S** and cross-product matrix **A** are defined as

166
$$\mathbf{S} = \frac{1}{n_*} \mathbf{A} = \frac{1}{n_*} (\mathbf{X} - \mathbf{1}_N \bar{\mathbf{x}}^T)^T (\mathbf{X} - \mathbf{1}_N \bar{\mathbf{x}}^T),$$
(2)

167 where $\mathbf{1}_N$ is a $N \times 1$ column vector of 1's, $\bar{\mathbf{x}} = \sum_{i=1}^N \mathbf{x}_i / N$ is the sample mean vector, and n_* 168 denotes an appropriate devisor; e.g., $n_* = N - 1$ for the ordinary unbiased estimator, and 169 $n_* = N$ for the maximum likelihood estimator under the normal distribution. The (i, j)-th 170 component of **S**, denoted s_{ij} , is the sample variance or covariance. The eigendecomposition

171 of **S** is constructed in the same way as above:

$$\mathbf{S} = \mathbf{U}\mathbf{L}\mathbf{U}^T,\tag{3}$$

173 where **U** is an orthogonal matrix of sample eigenvectors and **L** is a diagonal matrix whose

174 elements are the sample eigenvalues $l_1, l_2, ..., l_p$.

175 In what follows, the following identity entailed by the orthogonality of **U** is frequently176 utilized:

177
$$\sum_{i=1}^{p} s_{ii}^{r} = \operatorname{tr}(\mathbf{S}^{r}) = \operatorname{tr}(\mathbf{U}\mathbf{L}\mathbf{U}^{T}\mathbf{U}\mathbf{L}\mathbf{U}^{T} \dots \mathbf{U}\mathbf{L}\mathbf{U}^{T}) = \operatorname{tr}(\mathbf{L}^{r}) = \sum_{i=1}^{p} l_{i}^{r}, r = 1, 2, ..., (4)$$

178 where tr(·) denotes the matrix trace operator, i.e., summation of the diagonal elements; the 179 parentheses are omitted for visual clarity when little ambiguity exists. The sum of variances 180 tr $\mathbf{S} = \text{tr } \mathbf{L}$ is called total variance. Note that equation 4 holds even when n < p, in which 181 case $l_i = 0$ for some *i*. In other words, when n < p, the sample total variance is in a way 182 concentrated in a subspace with fewer dimensions than the full space.

183 The population and sample correlation matrices **P** and **R**, whose (i, j)-th components 184 are the population and sample correlation coefficients ρ_{ij} and r_{ij} , respectively, are obtained 185 by standardizing Σ and **S**:

186
$$\mathbf{P} = \operatorname{diag}(\sigma_{ii}^{-1/2}) \mathbf{\Sigma} \operatorname{diag}(\sigma_{ii}^{-1/2}),$$

187
$$\mathbf{R} = \operatorname{diag}\left(s_{ii}^{-1/2}\right) \mathbf{S} \operatorname{diag}\left(s_{ii}^{-1/2}\right), \tag{5}$$

188 where diag(·) stands for the $p \times p$ diagonal matrix with the designated *i*th elements. Their 189 eigendecomposition is defined as for covariance matrices, and the eigenvalues are denoted 190 with the same symbols here. For any *i*, $\rho_{ii} = r_{ii} = 1$, and hence, for correlation matrices

191 $\operatorname{tr} \mathbf{P} = \operatorname{tr} \mathbf{\Lambda} = \operatorname{tr} \mathbf{L} = p. \tag{6}$

In what follows, the notations E(·), Var(·), and Cov(·,·) are used for the expectation (mean),
variance, and covariance of random variables, respectively.

195 Eigenvalue dispersion

196 The eigenvalue variance *V* is defined as:

197
$$V(\mathbf{\Sigma}) = \frac{1}{p} \sum_{i=1}^{p} (\lambda_i - \bar{\lambda})^2,$$

198
$$V(\mathbf{S}) = \frac{1}{p} \sum_{i=1}^{p} (l_i - \bar{l})^2,$$
(7)

where $\bar{\lambda}$ and \bar{l} are the averages of the population and sample eigenvalues, respectively ($\bar{\lambda}$ = 199 $\sum_{i=1}^{p} \lambda_i / p = \operatorname{tr} \mathbf{\Lambda} / p, \ \overline{l} = \sum_{i=1}^{p} l_i / p = \operatorname{tr} \mathbf{L} / p$. Note that $V(\mathbf{\Sigma})$ is a quantity pertaining to the 200 201 population, whereas V(S) is a sample statistic. The definition here follows the convention in the literature that p, rather than p - 1, is used as the divisor (e.g., Cheverud et al., 1983; 202 203 Pavlicev et al., 2009; Haber, 2011). The latter might be more suitable for V(S) because the sum of squares is taken around the average sample eigenvalue which is a random variable. 204 205 After all, however, the choice of p-1 is not so useful because V(S) cannot be an unbiased 206 estimator of $V(\Sigma)$ even with that choice (below).

Note that the average and sum of squares are taken across all p eigenvalues, even if some eigenvalues are zero due to the condition n < p. This is reasonable given that sums of moments across all p sample eigenvalues are comparable in magnitude to those of population

210 eigenvalues (see below). One could alternatively use eigenvalue standard deviation \sqrt{V}

211 (Pavlicev et al., 2009; Haber, 2011), but this study concentrates on V rather than \sqrt{V} , because

the former is much more tractable for the purposes of characterizing distributions.

213 It is obvious that $V(\Sigma)$ takes a single minimum of 0 at $(\lambda_1, \lambda_2, ..., \lambda_p) = (\overline{\lambda}, \overline{\lambda}, ..., \overline{\lambda})$.

214 On the other hand, for a fixed $\overline{\lambda}$, it takes a single maximum of $(p-1)\overline{\lambda}^2$ at $(p\overline{\lambda}, 0, ..., 0)$ (e.g.,

215 Van Valen, 1974; Machado et al., 2019). Hence, not only is $V(\Sigma)$ scale-variant, but also its

216 range depends on p-1. Therefore, it is often useful to standardize V by division with this

217 maximum to obtain the relative eigenvalue variance V_{rel} :

218
$$V_{\rm rel}(\mathbf{\Sigma}) = \frac{\sum_{i=1}^{p} (\lambda_i - \overline{\lambda})^2}{p(p-1) \overline{\lambda}^2},$$

219
$$V_{\rm rel}(\mathbf{S}) = \frac{\sum_{i=1}^{p} (l_i - \bar{l})^2}{p(p-1)\,\bar{l}^2}.$$
 (8)

Because of the standardization, V_{rel} ranges between 0 and 1. This is a heuristic introduction of V_{rel} from V, but it will be seen below that $V_{rel}(\mathbf{S})$ has a clearer theoretical justification.

222 These indices are similarly defined for correlation matrices. By noting $\overline{\lambda} = \overline{l} = 1$ (eq. 223 6), these are

224
$$V(\mathbf{P}) = \frac{1}{p} \sum_{i=1}^{p} (\lambda_i - 1)^2$$

225
$$V(\mathbf{R}) = \frac{1}{p} \sum_{i=1}^{p} (l_i - 1)^2$$

226
$$V_{\rm rel}(\mathbf{P}) = \frac{\sum_{i=1}^{p} (\lambda_i - 1)^2}{p(p-1)},$$

227
$$V_{\text{rel}}(\mathbf{R}) = \frac{\sum_{i=1}^{p} (l_i - 1)^2}{p(p-1)}.$$
 (9)

228 In most of the following discussions, we will concentrate on V_{rel} for correlation matrices,

because $V(\mathbf{R})$ and $V_{rel}(\mathbf{R})$ are proportional to each other by the factor p - 1, and hence their distributions are identical up to this scaling. This is in contrast to those of covariance matrices, where \bar{l} in the denominator in $V_{rel}(\mathbf{S})$ is a random variable and affects sampling properties.

Importantly, a single value of V_{rel} in general corresponds to multiple combinations of eigenvalues even if the average eigenvalue is fixed, except when p = 2 or under the extreme conditions $V_{rel} = 0$ and $V_{rel} = 1$ (Fig. 1). As such, it is not always straightforward to discern how intermediate values of V_{rel} are translated into actual covariance structures when p > 2. Nevertheless, it is possible to show that $V_{rel} > 0.5$ cannot happen when multiple leading eigenvalues are of the same magnitude (Appendix A); in other words, such a large value indicates dominance of the first principal component.

240 As would be obvious from the definition, V and V_{rel} of covariance matrices only 241 describe the (relative) magnitudes of eigenvalues-proportions of the axes of variation-and 242 do not reflect any information of eigenvectors-directions of the axes. A large eigenvalue of 243 a covariance matrix can represent, e.g., strong covariation between equally varying traits or 244 large variation of a single trait uncorrelated with others; either of these cases describes 245 eccentricity of variation in the multivariate space. By contrast, a large eigenvalue of a 246 correlation matrix can only happen in the presence of correlation. Therefore, a large 247 eigenvalue dispersion in a correlation matrix constrains conformation of eigenvectors to a 248 certain extent. The correlations can nevertheless be realized in various ways depending on eigenvectors, whose conformation does influence the sampling distribution of $V_{rel}(\mathbf{R})$ (see 249 250 below).

For covariance matrices, $V_{rel}(\mathbf{S})$ has a natural relation to the test of sphericity, i.e., test of the null hypothesis that $\mathbf{\Sigma} = \sigma^2 \mathbf{I}_p$ for an arbitrary positive constant σ^2 . Simple

transformations from equation 8 lead to

263
$$V_{\rm rel}(\mathbf{S}) = \frac{1}{p-1} \left(p \frac{\sum l_i^2}{(\sum l_i)^2} - 1 \right).$$

(10)

254

By noting $\sum l_i^2 / (\sum l_i)^2 = \text{tr}(\mathbf{S}^2) / (\text{tr } \mathbf{S})^2 = \text{tr}(\mathbf{A}^2) / (\text{tr } \mathbf{A})^2$ (see eqs. 2 and 4), $V_{\text{rel}}(\mathbf{S})$ in the 255 256 form of equation 10 is exactly John's (1972) T statistic for the test of sphericity (see also 257 Ledoit & Wolf, 2002). Beyond the intuition that it measures eccentricity of variation along 258 principal components, this statistic (and its linear functions) can be justified as the most 259 powerful test statistic in the proximity of the null hypothesis under multivariate normality, 260 among the class of such statistics that are invariant against translation by a constant vector, 261 uniform scaling, and orthogonal rotation (John, 1971, 1972; Sugiura, 1972; Nagao, 1973). On the other hand, V(S) does not seem to have as much theoretical justification, but rather has a 262

264 practical advantage in the tractability of its moments and ease of correcting sampling bias

265 (see below).

For a correlation matrix, V_{rel} is a measure of association between variables. Following similar transformations, it is straightforward to see

274
$$V_{\text{rel}}(\mathbf{R}) = \frac{\text{tr}(\mathbf{R}^2) - p}{p(p-1)}$$

275
$$= \frac{2}{p(p-1)} \sum_{i< j}^{p} r_{ij}^2,$$

268

because $r_{ii}^2 = 1$ for all *i*. This relationship has been known in the statistical literature (e.g.,

(11)

270 Gleason & Staelin, 1975; Durand & Le Roux, 2017), and empirically confirmed by Haber

271 (2011). This statistic is used as a measure of overall association between variables (e.g.,

272 Schott, 2005; Durand & Le Roux, 2017), with the corresponding null hypothesis being $\mathbf{P} =$ 273 \mathbf{I}_p .

276

277 Sampling properties of eigenvalues

278 The distribution of eigenvalues of **S**, or equivalently those of **A** (which are n_* times those of 279 S), has been extensively investigated in the literature of multivariate analysis (see, e.g., 280 Jolliffe, 2002; Anderson, 2003). Unfortunately, however, most of such results are of limited 281 value for the present purposes. On the one hand, forms of the exact joint distribution of the 282 eigenvalues of A are known under certain assumptions on the population eigenvalues (e.g., 283 Muirhead, 1982: pp. 107, 388), but they do not allow for much intuitive interpretation (let 284 alone direct evaluation of moments), apart from the following points: 1) sample eigenvalues 285 are not stochastically independent from one another; and 2) the distribution of sample 286 eigenvalues are only dependent on the population eigenvalues, but not on the population

287 eigenvectors. On the other hand, a substantial body of results is available for large-sample asymptotic distributions of sample eigenvalues (assuming $n \to \infty$, p being constant; e.g., 288 289 Anderson, 1963, 2003), but their accuracy under finite n conditions is questionable. For example, a well-known result under a certain simple condition states that $l_i \sim N(\lambda_i, 2\lambda_i^2/n)$ 290 291 and $Cov(l_i, l_i) \approx 0$ for $i \neq j$, assuming all population eigenvalues to be distinct and $n_* = n$ 292 (Girshick, 1939; Anderson, 1963; Srivastava & Khatri, 1979). However, these expressions 293 ignore terms of order $O(n^{-1})$ —that is, all terms with n or its higher power in the 294 denominator—whose magnitude can be substantial for a finite n. Indeed, with further 295 evaluation of higher-order terms, it becomes evident that sample eigenvalues are biased 296 estimators of the population equivalents, where large eigenvalues are prone to overestimation and small ones are prone to underestimation, and that $\text{Cov}(l_i, l_j) = 2\lambda_i \lambda_j / [(\lambda_i - \lambda_j)n]^2 +$ 297 298 $O(n^{-3})$ for $i \neq j$ (Lawley, 1956; Srivastava & Khatri, 1979). An important insight is that 299 covariance between sample eigenvalues is nonzero. When all population eigenvalues are equal, then $\text{Cov}(l_i, l_j) = -\sigma^4/n$ (Girshick, 1939). 300

Much less is known about eigenvalues of a sample correlation matrix **R** (Jolliffe, 2002). Their distribution seems intractable except under certain special conditions (Anderson, 1963). Asymptotic results indicate that the limiting distribution $(n \rightarrow \infty)$ of an eigenvalue of **R** is normal with the mean coinciding with the corresponding population eigenvalue, but that its variance depends on population eigenvectors (Anderson, 1963; Konishi, 1979), unlike that of a covariance matrix where the distribution does not depend on population eigenvectors (above).

It is often of practical interest to detect the presence of eccentricity or integration, i.e., to test the null hypothesis of sphericity $\mathbf{\Sigma} = \sigma^2 \mathbf{I}_p$ or no correlation $\mathbf{P} = \mathbf{I}_p$. These hypotheses are equivalent to $V(\mathbf{\Sigma}) = V_{rel}(\mathbf{\Sigma}) = 0$ and $V_{rel}(\mathbf{P}) = 0$, respectively. Even under these conditions, nonzero sampling variance in sample eigenvalues renders $V(\mathbf{S}) > 0$, $V_{rel}(\mathbf{S}) > 0$,

and $V_{rel}(\mathbf{R}) > 0$ with probability 1, because these statistics are calculated from sum of

- 313 squares. The primary aim here is to derive explicit expressions for this sampling bias
- 314 (expectation), as well as sampling variance.
- 315 It should be remembered that the expectation of the eigenvalue variance E[V(S)] is 316 fundamentally different from the variance of eigenvalues $Var(l_i)$. This point will be clarified 317 by the following transformation:

326
$$E[V(\mathbf{S})] = \frac{1}{p} E\left(\sum_{i=1}^{p} l_i^2\right) - \frac{1}{p^2} E\left[\left(\sum_{i=1}^{p} l_i\right)^2\right]$$

327
$$= \frac{p-1}{p^2} \sum_{i=1}^{p} E(l_i^2) - \frac{1}{p^2} \sum_{i\neq j}^{p} \left[E(l_i) E(l_j) + Cov(l_i, l_j) \right].$$

318

319 Under the null hypothesis, the moments are equal across all *i*, and the above simplifies into

(12)

320
$$\frac{p-1}{p} \left[\operatorname{Var}(l_i) - \operatorname{Cov}(l_i, l_j) \right], i \neq j.$$
(13)

321 If $Cov(l_i, l_j)$ were zero, the expectation would coincide with $(p - 1)Var(l_i)/p$, which can be

322 evaluated from, e.g., Wagner's (1984) results. As already mentioned, however, this

- 323 covariance is nonzero and hence cannot be ignored for covariance matrices. This is unlike the
- 324 case for correlation matrices, where $E[V(\mathbf{R})] = Var(l_i)$ holds under the null hypothesis,
- 325 because \overline{l} is a constant and equals $E(l_i) = 1$.

328 In the following discussions on moments of eigenvalue dispersion indices,

- 329 observations are assumed to be i.i.d. multivariate normal variables. If the $N \times p$ matrix **X**
- 330 consists of N i.i.d. p-variate normal variables $\mathbf{x}_i \sim N_p(\boldsymbol{\mu}, \boldsymbol{\Sigma})$, then the distribution of the
- 331 sample-mean-centered cross product matrix **A** (eq. 2) is said to be the (central) Wishart
- distribution $W_p(\Sigma, n)$, where n = N 1 is the degree of freedom. It is well known that this is
- identical to the distribution of $\mathbf{Z}^T \mathbf{Z}$, where the $n \times p$ matrix \mathbf{Z} consists of n i.i.d. p-variate

normal variables $\mathbf{z}_i \sim N_p(\mathbf{0}_p, \boldsymbol{\Sigma})$ with $\mathbf{0}_p$ being the $p \times 1$ column vector of 0's (e.g., Anderson,

335 2003). Therefore, for analyzing statistics associated with sample covariance or correlation

336 matrices, we can conveniently consider

$$\mathbf{S} = \frac{1}{n_*} \mathbf{Z}^T \mathbf{Z}.$$
 (14)

338 without loss of generality, by bearing in mind the distinction between the degree of freedom

339 n and sample size N. From elementary moments of the normal distribution, the following

340 general relationships can be easily confirmed

341
$$E(s_{ij}) = \frac{1}{n_*} \sum_{k=1}^n E(z_{ki} z_{kj}) = \frac{n}{n_*} \sigma_{ijk}$$

342
$$E(s_{ij}s_{km}) = \frac{n^2}{n_*^2} \Big[\sigma_{ij}\sigma_{km} + \frac{1}{n} \big(\sigma_{ik}\sigma_{jm} + \sigma_{im}\sigma_{jk} \big) \Big].$$
(15)

343 where z_{ij} , s_{ij} , σ_{ij} and the like are the (i, j)-th elements of **Z**, **S**, and **\Sigma**, respectively.

344

345 Moments under null hypotheses

346 *Covariance matrix*

347 Before proceeding to arbitrary covariance structures, let us consider the null hypothesis of

348 sphericity: $\mathbf{\Sigma} = \sigma^2 \mathbf{I}_p$, where σ^2 is the population variance of arbitrary magnitude. For the

349 expectation of $V(\mathbf{S})$, we need $Var(l_i)$ and $Cov(l_i, l_j)$, or equivalently $E(\sum_{i=1}^p l_i^2)$ and

350 $E\left[\left(\sum_{i=1}^{p} l_{i}\right)^{2}\right]$ (see eqs. 12 and 13); we will proceed with the latter here. By use of equations 4 351 and 15, we have

352
$$E\left(\sum_{i=1}^{p} l_i^2\right) = E\left(\sum_{i,j=1}^{p} s_{ij}^2\right)$$

353
$$= E\left(\sum_{i=1}^{p} s_{ii}^{2} + \sum_{i\neq j}^{p} s_{ij}^{2}\right)$$

354
$$= [pE(s_{ii}^2) + p(p-1)E(s_{ij}^2)]$$

(16)

(17)

(18)

(19)

$$= \frac{pn}{n_*^2} (p+n+1)\sigma^4,$$

355

and similarly

363
$$E\left[\left(\sum_{i=1}^{p} l_i\right)^2\right] = E\left[\left(\sum_{i=1}^{p} s_{ii}\right)^2\right]$$

$$364 \qquad \qquad = \mathbb{E}\left[\sum_{i=1}^{p} s_{ii}^{2} + \sum_{i\neq j}^{p} s_{ii}s_{jj}\right]$$

365
$$= [pE(s_{ii}^2) + p(p-1)E(s_{ii}s_{jj})]$$

$$=\frac{pn}{n_*^2}(pn+2)\sigma^4.$$

357

358 Then, inserting these results into equation 12,

367
$$E[V(\mathbf{S})] = \frac{n}{pn_*^2}(p-1)(p+2)\sigma^4.$$

359

360 Alternatively, it could be seen that $\operatorname{Var}(l_i) = n(p+1)\sigma^2/n_*^2$ and $\operatorname{Cov}(l_i, l_j) = -n\sigma^4/n_*^2$

361 for $i \neq j$, with which equation 13 yields the identical result.

368 The variance of $V(\mathbf{S})$ is, by equation 12,

373
$$\operatorname{Var}[V(\mathbf{S})] = \frac{1}{p^2} \operatorname{Var}\left[\sum_{i=1}^p l_i^2\right] + \frac{1}{p^4} \operatorname{Var}\left[\left(\sum_{i=1}^p l_i\right)^2\right] - 2\frac{1}{p^3} \operatorname{Cov}\left[\sum_{i=1}^p l_i^2, \left(\sum_{i=1}^p l_i\right)^2\right].$$

369

- 370 The relevant moments can most conveniently be found as a special case of general
- 371 expressions under arbitrary Σ (see below and Appendix B), although direct derivation using

372 normal moments is possible:

377
$$E\left[\left(\sum l_i^2\right)^2\right] = \frac{pn}{n_*^4}(p^3n + pn^3 + 2p^2n^2 + 2p^2n + 2pn^2 + 8p^2 + 8n^2 + 21pn^2)$$

378
$$+ 20p + 20n + 20)\sigma^8;$$

379
$$E\left[\left(\sum l_i\right)^4\right] = \frac{pn}{n_*^4}(pn+2)(pn+4)(pn+6)\sigma^8;$$

380
$$E\left[\left(\sum l_i^2\right) \cdot \left(\sum l_i\right)^2\right] = \frac{pn}{n_*^4}(pn+2)(pn+4)(p+n+1)\sigma^8;$$

381
$$\operatorname{Var}\left[\sum l_{i}^{2}\right] = \frac{4pn}{n_{*}^{4}}(2p^{2} + 2n^{2} + 5pn + 5p + 5n + 5)\sigma^{8};$$

382
$$\operatorname{Var}\left[\left(\sum l_{i}\right)^{2}\right] = \frac{8pn}{n_{*}^{4}}(pn+2)(pn+3)\sigma^{8};$$

383
$$\operatorname{Cov}\left[\sum l_i^2, \left(\sum l_i\right)^2\right] = \frac{8pn}{n_*^4}(p+n+1)(pn+3)\sigma^8.$$

(20)

375 Inserting these into equation 19 yields

376
$$\operatorname{Var}[V(\mathbf{S})] = \frac{4n}{p^3 n_*^4} (p-1)(p+2)(2p^2+pn+3p-6)\sigma^8.$$
(21)

384 Next, consider the first two moments of $V_{rel}(\mathbf{S})$ under the null hypothesis (which have 385 previously been derived by John [1972]). Recalling the form of equation 10,

386
$$E[V_{rel}(\mathbf{S})] = \frac{1}{p-1} \left(p E\left[\frac{\sum l_i^2}{(\sum l_i)^2} \right] - 1 \right),$$

387 and
$$\operatorname{Var}[V_{\operatorname{rel}}(\mathbf{S})] = \left(\frac{p}{p-1}\right)^2 \operatorname{Var}\left[\frac{\sum l_i^2}{(\sum l_i)^2}\right].$$
 (22)

In general, moments of the ratio $\sum l_i^2 / (\sum l_i)^2$ do not coincide with the ratio of the moments of the numerator and denominator. Specifically under the null hypothesis, however,

390
$$\operatorname{E}\left[\frac{\Sigma l_i^2}{(\Sigma l_i)^2}\right] = \frac{\operatorname{E}[\Sigma l_i^2]}{\operatorname{E}[(\Sigma l_i)^2]}$$

391 and
$$E\left[\frac{\left(\sum l_i^2\right)^2}{\left(\sum l_i\right)^4}\right] = \frac{E\left[\left(\sum l_i^2\right)^2\right]}{E\left[\left(\sum l_i\right)^4\right]}$$
(23)

hold because of the stochastic independence between $\sum l_i^2 / (\sum l_i)^2$ and $\sum l_i$ in this special

(24)

(25)

393 condition (this point requires inspection of the density; John, 1972). Therefore, by use of

394 equations 16, 17, and 20,

400
$$E[V_{rel}(\mathbf{S})] = \frac{1}{p-1} \left(p \frac{E[\sum l_i^2]}{E[(\sum l_i)^2]} - 1 \right)$$

$$401 \qquad \qquad = \frac{p+2}{pn+2},$$

395

396 and

402
$$\operatorname{Var}[V_{\mathrm{rel}}(\mathbf{S})] = \left(\frac{p}{p-1}\right)^2 \left(\frac{\operatorname{E}[(\sum l_i^2)^2]}{\operatorname{E}[(\sum l_i)^4]} - \left\{\frac{\operatorname{E}[\sum l_i^2]}{\operatorname{E}[(\sum l_i)^2]}\right\}^2\right)$$

403
$$= \frac{4(p-1)(p+2)(n-1)(n+2)}{(pn+2)^2(pn+4)(pn+6)}.$$

397

398 These results are non-asymptotic (valid across any p and n) and exact under multivariate 399 normality.

404

405 *Correlation matrix*

406 Consider the null hypothesis $\mathbf{P} = \mathbf{I}_p$ or $\rho_{ij} = 0$ for $i \neq j$. The moments can conveniently be

407 obtained from the form of average squared correlation (eq. 11). It is well known that, under

408 the assumptions of normality and $\rho_{ij} = 0$ for $i \neq j, r_{ij}^2$ is distributed as

409 Beta(1/2, (n-1)/2), where *n* is the degree of freedom (e.g., Anderson, 2003). Therefore,

410 under the null hypothesis,

411
$$E(r_{ij}^2) = \frac{1}{n}, \ i \neq j,$$

412
$$\operatorname{Var}(r_{ij}^2) = \frac{2(n-1)}{n^2(n+2)}, \ i \neq j.$$
 (26)

413 The expectation of $V_{rel}(\mathbf{R})$ is simply the average:

420
$$E[V_{rel}(\mathbf{R})] = \frac{1}{n}.$$
414 (27)

415 This expression is identical to $(p-1)^{-1}$ Var (l_i) obtainable from Wagner's (1984) results,

416 except for having the degree of freedom n rather than the sample size N in the denominator.

417 This is because Wagner (1984) considered N uncentered observations with mean 0 without

418 explicitly distinguishing *n* and *N*. Most practical analyses would concern data centered at the

419 sample mean, thus should use *n* rather than *N*.

421 Derivation of the variance is more complicated than it may seem, because, in422 principle,

429
$$\operatorname{Var}[V_{\operatorname{rel}}(\mathbf{R})] = \frac{4}{p^2(p-1)^2} \left[\sum_{i < j} \operatorname{Var}(r_{ij}^2) + \sum_{\substack{i < j, k < l, \\ (i,j) \neq (k,l)}} 2\operatorname{Cov}(r_{ij}^2, r_{kl}^2) \right].$$

(28)

(29)

423

424 However, it is possible to show $Cov(r_{ij}^2, r_{kl}^2) = 0$ under the null hypothesis (Appendix C). 425 Therefore, from equations 26 and 28,

426 $\operatorname{Var}[V_{\operatorname{rel}}(\mathbf{R})] = \frac{4(n-1)}{p(p-1)n^2(n+2)}.$

427 These expressions are non-asymptotic and exact for any *p* and *n*. Schott (2005) proposed a

428 test for independence between sets of normal variables based on these moments.

430

431 Moments under arbitrary conditions

432 *Covariance matrix*

- 433 This section considers moments of eigenvalue dispersion indices under arbitrary
- 434 covariance/correlation structures and multivariate normality. It is straightforward to obtain
- 435 the first two moments of V(S) under arbitrary Σ , provided that the expectations of relevant
- 436 terms in equation 12 are available. The results are

444
$$E[V(\mathbf{S})] = \frac{n}{p^2 n_*^2} [(p-n)(\operatorname{tr} \mathbf{A})^2 + (pn+p-2)\operatorname{tr}(\mathbf{A}^2)]$$

445
$$= \frac{n}{pn_*^2} [(pn+p-2)V(\mathbf{\Sigma}) + (p-1)(p+2)(\mathrm{tr}\,\mathbf{\Lambda})^2/p^2],$$

446
$$\operatorname{Var}[V(\mathbf{S})] = \frac{4n}{p^4 n_*^4} \{2(p-n)^2 \operatorname{tr}(\mathbf{\Lambda}^2) (\operatorname{tr} \mathbf{\Lambda})^2 + (p^2 n + p^2 - 4p + 2n) [\operatorname{tr}(\mathbf{\Lambda}^2)]^2$$

447
$$+ 4(p-n)(pn+p-2)\operatorname{tr}(\Lambda^3)\operatorname{tr}\Lambda$$

448 +
$$(2p^2n^2 + 5p^2n + 5p^2 - 12pn - 12p + 12) \operatorname{tr}(\Lambda^4)$$
.

437

The derivations are given in Appendix B. The second expression for the expectation comes from the fact $V(\Sigma) = [p \operatorname{tr}(\Lambda^2) - (\operatorname{tr} \Lambda)^2]/p^2$, and clarifies that the expectation is a linear function of $V(\Sigma)$. These results are exact, and it can be easily verified that they reduce to equations 18 and 19 under the null hypothesis. Profiles of E[V(S)] across a range of $V(\Sigma)$ are shown in Figure 2 (top row), under single large eigenvalue conditions with varying *p* and *N* and a fixed tr Σ (details are described under simulation settings below).

(30)

449 Moments of $V_{rel}(\mathbf{S})$ are more difficult to obtain, as moments of the ratio $\sum l_i^2 / (\sum l_i)^2$ 450 do not coincide with the ratio of moments under arbitrary $\mathbf{\Sigma}$. Here we utilize the following 451 approximations based on the delta method (e.g., Stuart & Ord, 1994: chapter 10):

452
$$E\left(\frac{X}{Y}\right) \approx \frac{E(X)}{E(Y)} - \frac{Cov(X,Y)}{E(Y)^2} + \frac{E(X) \operatorname{Var}(Y)}{E(Y)^3},$$

453 and
$$\operatorname{Var}\left(\frac{X}{Y}\right) \approx \frac{\mathrm{E}(X)^2}{\mathrm{E}(Y)^2} \left[\frac{\operatorname{Var}(X)}{\mathrm{E}(X)^2} + \frac{\operatorname{Var}(Y)}{\mathrm{E}(Y)^2} - 2\frac{\operatorname{Cov}(X,Y)}{\mathrm{E}(X)\operatorname{E}(Y)}\right].$$
 (32)

454 The approximate moments are (Appendix B):

455
$$E\left[\frac{\sum l_i^2}{(\sum l_i)^2}\right] \approx \frac{(\operatorname{tr} \Lambda)^2 + (n+1)\operatorname{tr}(\Lambda^2)}{n(\operatorname{tr} \Lambda)^2 + 2\operatorname{tr}(\Lambda^2)} - \frac{8(n-1)(n+2)}{n[n(\operatorname{tr} \Lambda)^2 + 2\operatorname{tr}(\Lambda^2)]^3}$$

456
$$\times \{n(\operatorname{tr} \Lambda)^3 \operatorname{tr} (\Lambda^3) - n(\operatorname{tr} \Lambda)^2 [\operatorname{tr} (\Lambda^2)]^2 - 2 [\operatorname{tr} (\Lambda^2)]^3 - 2 \operatorname{tr} \Lambda \operatorname{tr} (\Lambda^2) \operatorname{tr} (\Lambda^3)$$

457
$$+ 3(\operatorname{tr} \Lambda)^2 \operatorname{tr} (\Lambda^4) \};$$

466
$$\operatorname{Var}\left[\frac{\sum l_i^2}{(\sum l_i)^2}\right] \approx \frac{4(n-1)(n+2)}{n[n(\operatorname{tr} \Lambda)^2 + 2\operatorname{tr}(\Lambda^2)]^4}$$

467
$$\times \{n(\operatorname{tr} \Lambda)^{4}[\operatorname{tr} (\Lambda^{2})]^{2} + 2n(n+1)(\operatorname{tr} \Lambda)^{2}[\operatorname{tr} (\Lambda^{2})]^{3} + 2(n+1)[\operatorname{tr} (\Lambda^{2})]^{4}$$

468
$$-4(n-1)(n+2)(\operatorname{tr} \Lambda)^3 \operatorname{tr} (\Lambda^2) \operatorname{tr} (\Lambda^3) + (2n^2+3n-6)(\operatorname{tr} \Lambda)^4 \operatorname{tr} (\Lambda^4)$$

469
$$-4n(\operatorname{tr} \Lambda)^2 \operatorname{tr} (\Lambda^2) \operatorname{tr} (\Lambda^4) - 4(\operatorname{tr} \Lambda)^4 [\operatorname{tr} (\Lambda^2)]^2 \}$$

458

463

459 Inserting these into equation 22 yields the desired moments. The approximate expectation

(33)

460 reduces to equation 24 under the null hypothesis, as the higher-order terms cancel out,

461 whereas this is not the case for the approximate variance. Because these expressions are

462 specified only by the population eigenvalues regardless of eigenvectors, they are invariant

464 it is easily discerned that these expressions are invariant with respect to uniform scaling of

with respect to orthogonal rotations, as expected from theoretical considerations above. Also,

465 the variables. The accuracy of these approximations will be examined in simulations below.

470 Profiles of the approximation of $E[V_{rel}(\mathbf{S})]$ across a range of $V_{rel}(\mathbf{\Sigma})$ are shown in

471 Figure 2 (middle row) for the same conditions as explained above. The profiles are nonlinear;

472 $V_{\rm rel}(\mathbf{S})$ tends to overestimate $V_{\rm rel}(\mathbf{\Sigma})$ when the latter is small, but tends to slightly

473 underestimate when the latter is large. The initial decrease of $E[V_{rel}(S)]$ observed in some

474 profiles appears to be an artifact of the approximation.

475

476 *Correlation matrix*

The expectation of $V_{rel}(\mathbf{R})$ under arbitrary conditions can be obtained from the expression of equation 11 with r_{ij}^2 replaced by its expectations, which is known to be (e.g., Ghosh, 1966; Muirhead, 1982)

480
$$\mathrm{E}(r_{ij}^{2}) = 1 - \frac{(n-1)\left(1-\rho_{ij}^{2}\right)}{n} {}_{2}F_{1}\left(1,1;\frac{n+2}{2};\rho_{ij}^{2}\right), \ i \neq j, \tag{34}$$

481 where

482
$${}_{2}F_{1}(a,b;c;z) = \sum_{k=0}^{\infty} \frac{(a)_{k}(b)_{k}}{(c)_{k}} \frac{z^{k}}{k!}$$
(35)

is the hypergeometric function, with $(x)_k = x(x + 1) \dots (x + k - 1)$ denoting rising factorial (defined to be 1 when k = 0). Taking the average of equation 34 gives the desired expectation. This result is non-asymptotic and exact. It is easily seen that equation 34 reduces to equation 26 under the null hypothesis.

487 When
$$p = 2$$
, the exact variance of $V_{rel}(\mathbf{R})$ is equal to that of the single squared

488 correlation coefficient, thus can be obtained from known results (Ghosh, 1966) as follows:

489
$$\operatorname{Var}[V_{\operatorname{rel}}(\mathbf{R})] = \operatorname{Var}(r^2) = \frac{(n-1)(n+1)(1-\rho^2)}{2n} \left[F - nF' - \frac{2(n-1)(1-\rho^2)}{n(n+1)} F^2 \right], \quad (36)$$

where
$$F = {}_{2}F_{1}(1, 1; (n + 2)/2; \rho^{2})$$
 and $F' = (F - 1)/2\rho^{2} = {}_{2}F_{1}(1, 2; (n + 4)/2; \rho^{2})/$
(*n* + 2); this last form is preferred to avoid numerical instability when ρ^{2} is close to 0. This
expression reduces to equation 26 under the null hypothesis. When $p > 2$, we cannot ignore
the covariance between squared correlation coefficients (see eq. 28), which appears to be
nonzero. Unfortunately, no exact expression seems available for this in the literature, so we
resort to asymptotic results. The following asymptotic expression based on Konishi's (1979)
theory may potentially be used (see Appendix D for derivation):

504
$$\operatorname{Var}[V_{\mathrm{rel}}(\mathbf{R})] \approx \frac{8}{p^2(p-1)^2 n} \sum_{\alpha,\beta=1}^p \lambda_{\alpha}^2 \lambda_{\beta}^2 \left[\delta_{\alpha\beta} - \left(\lambda_{\alpha} + \lambda_{\beta}\right) \sum_{i=1}^p \upsilon_{i\alpha}^2 \upsilon_{i\beta}^2 + \sum_{i,j=1}^p \rho_{ij}^2 \upsilon_{i\alpha}^2 \upsilon_{j\beta}^2 \right],$$
497 (37)

where δ_{ij} is the Kronecker delta (equals 1 for i = j and 0 otherwise) and $\upsilon_{i\alpha}$ is the (i, α) -th element of the population eigenvector matrix **Y**. For p = 2, the accuracy of this expression can be compared with the exact expression (Fig. 3); visual inspection of the profiles suggest that the accuracy is satisfactory past N = 32-64, except around $V_{rel}(\mathbf{P}) = 0$ where the asymptotic expression diminishes to 0. For p > 2, the accuracy is to be evaluated with simulations below.

505 Importantly, the expectation of $V_{rel}(\mathbf{R})$ is functions of $\rho^{2'}$ s rather than Λ , and cannot

506 be specified by the latter alone in general. For instance, consider $\begin{pmatrix} 1 & 0.9 & 0 \\ 0.9 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$ and

507 $\begin{pmatrix} 1 & 0.9/\sqrt{2} & 0\\ 0.9/\sqrt{2} & 1 & 0.9/\sqrt{2}\\ 0 & 0.9/\sqrt{2} & 1 \end{pmatrix}$, both of which are valid correlation matrices. These matrices

have identical eigenvalues $\mathbf{\Lambda} = \text{diag}(1.9, 1.0, 0.1)$ and hence an identical value of $V_{\text{rel}}(\mathbf{P})$ (= 0.27), but $E[V_{\text{rel}}(\mathbf{R})]$ with n = 10 are 0.3326 and 0.3156, respectively. Although the

510 difference in the expectations decreases as n increases, this example highlights that the

511 distribution of $V_{rel}(\mathbf{R})$ is also dependent on population eigenvectors.

512 Profiles of $E[V_{rel}(\mathbf{R})]$ across a range of $V_{rel}(\mathbf{P})$ are shown in Figure 2 (bottom row),

513 under the same conditions as above. These conditions with single large eigenvalues are

514 special cases in which $E[V_{rel}(\mathbf{R})]$ can be specified by $V_{rel}(\mathbf{P})$ regardless of eigenvectors

515 (detailed in Appendix A). Indeed, the profiles of the expectations are invariant across p in

these special conditions. In some way similar to $V_{rel}(S)$, $V_{rel}(R)$ tends to overestimate and

517 underestimate small and large values of $V_{rel}(\mathbf{P})$, respectively.

518

519 Bias correction

520 Some authors (Cheverud et al., 1989; Torices & Muñoz-Pajares, 2015) have suggested

521 correcting the sampling bias in eigenvalue dispersion indices by means of subtracting

522 Wagner's (1984) null expectation from empirical values (but see also Armbruster et al.,

523 2009). This method could potentially be used for V and V_{rel} with the correct null expectations

be derived above, to obtain estimators that is unbiased under the null hypothesis. For $V_{rel}(S)$ and

525 $V_{\rm rel}(\mathbf{R})$, however, the subtraction truncates the upper end of the range, potentially

526 compromising interpretability. To avoid this, it might be desirable to scale these indices in a

527 way analogous to the adjusted coefficient of determination in regression analysis (e.g.,

528 Cramer, 1987):

529

$$\bar{V}_{\rm rel}(\mathbf{S}) = 1 - \frac{1 - V_{\rm rel}(\mathbf{S})}{1 - E_{\rm null}[V_{\rm rel}(\mathbf{S})]} = \frac{pn+2}{p(n-1)} V_{\rm rel}(\mathbf{S}) - \frac{p+2}{p(n-1)}$$

530
$$\bar{V}_{rel}(\mathbf{R}) = 1 - \frac{1 - V_{rel}(\mathbf{R})}{1 - E_{null}[V_{rel}(\mathbf{R})]} = \frac{n}{n-1} V_{rel}(\mathbf{R}) - \frac{1}{n-1},$$
 (38)

where $E_{null}(\cdot)$ denotes expectation under the appropriate null hypothesis (eqs. 24 and 27). 531 This adjustment inflates the variance by the factor of $1/[1 - E_{null}(V_{rel})]^2$. Furthermore, 532 533 these adjusted indices are unbiased only under the null hypothesis (and trivially the case of complete integration), and uniformly underestimate the corresponding population values 534 535 otherwise (Fig. S2). As the population value gets away from 0, the adjusted index is 536 outperformed by the unadjusted one in both precision and bias (Fig. S3). It should also be 537 borne in mind that the profiles of expectations are nonlinear and dependent on N (Fig. 2). As 538 the adjusted indices will be increasingly conservative for small N, it is questionable whether 539 they can be used for comparing samples with different N, as originally intended by Cheverud 540 et al. (1989). For these reasons, use of this adjustment would be restricted to estimation of the 541 population value near 0 (up to 0.1-0.2, depending on p and N).

542 On the other hand, a global unbiased estimator of $V(\Sigma)$ can be derived from above 543 results:

547
$$\tilde{V}(\mathbf{S}) = \frac{n_*^2}{n(pn+p-2)} \left(pV(\mathbf{S}) - \frac{(p-1)(p+2)}{p^2(n-1)(n+2)} [(n+1)(\operatorname{tr} \mathbf{S})^2 - 2\operatorname{tr}(\mathbf{S}^2)] \right)$$

548
$$= \frac{1}{p^2 n(n-1)(n+2)} [(pn+2)(\operatorname{tr} \mathbf{A})^2 - (p+n+1)\operatorname{tr}(\mathbf{A}^2)].$$

544

545 The unbiasedness $E[\tilde{V}(\mathbf{S})] = V(\mathbf{\Sigma})$ can be easily confirmed. Its variance can be similarly 546 obtained:

556
$$\operatorname{Var}[\tilde{V}(\mathbf{S})] = \frac{4}{p^4 n(n-1)(n+2)} \{2(n-1)(n+2)\operatorname{tr}(\mathbf{A}^2)(\operatorname{tr}\mathbf{A})^2$$

557 +
$$(p^2n + 4p + 2n + 2)[tr(\Lambda^2)]^2 - 4p(n-1)(n+2)tr(\Lambda^3)tr\Lambda$$

558 +
$$(2p^2n^2 + 3p^2n - 6p^2 - 4pn - 4) \operatorname{tr}(\Lambda^4)$$
},

549

which reduces to
$$4(p-1)(p+2)\sigma^8/p^3n(n-1)(n+2)$$
 under the null hypothesis.

551 Comparison with equations 21 and 30 suggests that this variance is smaller than that of $V(\mathbf{S})$,

(40)

especially under the null hypothesis. Therefore, $\tilde{V}(\mathbf{S})$ seems superior in both precision and

bias and can be used when estimation of $V(\Sigma)$ is desired. It can be used to compare multiple

samples, provided that its sensitivity to overall scaling is not of concern, e.g., comparison

555 between closely related taxa.

559

560 Simulation

561 Methods

Simulations were conducted under various conditions in order to understand sampling properties of the eigenvalue dispersion indices. All simulations were done assuming multivariate normality, with varying population covariance matrix Σ , number of variables *p* (= 2, 4, 8, 16, 32, 64, 128, 256, and 1024), and sample size *N* (= 4, 8, 16, 32, 64, 128, and

566 256).

567 For every p, the following population eigenvalue conformations were considered: 1)

the null condition, 2) q-large λ conditions, 3) a linearly decreasing λ condition, and 4) a

569 quadratically decreasing λ condition (see Fig. 4 for examples). The null condition is where all

570 population eigenvalues are equal in magnitude ($\lambda_1 = \lambda_2 = \dots = \lambda_p = \overline{\lambda}$; $V_{rel}(\Sigma) = 0$),

571 corresponding to the null hypothesis of sphericity (Fig. 4A). The q-large λ conditions are

572 where the first q (= 1, 2, and 4, provided p > q) population eigenvalues are equally large and

the remaining p - q ones are equally small ($\lambda_1 = \cdots = \lambda_q > \lambda_{q+1} = \cdots = \lambda_p$), with varying 573 $V_{\text{rel}}(\Sigma)$ (= 0.1, 0.2, 0.4, 0.6, and 0.8; Fig. 4B–G). The necessary condition $\lambda_p \ge 0$ constrains 574 possible combinations of q and $V_{rel}(\Sigma)$: the possible choices of $V_{rel}(\Sigma)$ are 0.1–0.8, 0.1–0.4, 575 and 0.1–0.2 for q = 1, 2, and 4, respectively (Appendix A). These conditions are intended to 576 577 represent hypothetical situations where only a few components of meaningful signals are 578 present in the covariance structure. Individual eigenvalues were calculated for each 579 combination of p, q, and $V_{rel}(\Sigma)$ as described in Appendix A. The linearly and quadratically 580 decreasing λ conditions are where the population eigenvalues are linearly and quadratically, 581 respectively, decreasing in magnitude (Fig. 4H; Appendix A), in which cases the value of 582 $V_{\rm rel}(\Sigma)$ is fixed for a given p. These conditions are intended to represent covariance 583 structures with gradually decreasing signals. One might claim that some of these situations, 584 especially *q*-large λ conditions, are too simplistic and biologically unrealistic, but these 585 simple settings enable us to clarify systematic relationships between parameters and sampling 586 properties. The primary aim here is to explore sampling properties across a wide range of 587 parameters, rather than confined to a biologically "realistic" region (which would depend on 588 specific organismal systems). It should also be recalled that sampling error alone can yield 589 gradually decreasing patterns of sample eigenvalues typically observed in empirical datasets 590 (see above and below).

For sake of simplicity, all population covariance matrices were scaled to ensure $V(\Sigma) = V_{rel}(\Sigma)$; that is, tr $\Sigma = p(p-1)^{-1/2}$. This scaling also makes the magnitude of $V(\Sigma)$ comparable across varying p. In addition, a population covariance matrix Σ was constructed from a predefined set of eigenvalues such that its diagonal elements are equal: $\sigma_{ii} = \overline{\lambda} =$ $(p-1)^{-1/2}$ for all i, thereby enforcing $\Sigma = (p-1)^{-1/2} \mathbf{P}$. This construction allows for examining both covariance and correlation matrices with the same population V_{rel} from a single simulated dataset, saving computational resources. Σ was constructed from Λ by the 598 iterative Givens rotation algorithm of Davies & Higham (2000), which is guaranteed to 599 converge within p-1 iterations. This algorithm was implemented as coded by Waller 600 (2020), but with the following modifications for reproducibility: no random orthogonal 601 rotation was involved in the initial stage, and rotation axes were chosen in a fixed order. It 602 should be noted that the rotations involved—choice of eigenvectors—would in general 603 influence distributions of $V_{rel}(\mathbf{R})$, except for certain special cases including the 1-large λ 604 condition (see Appendix A). It is impractical to exhaustively examine numerous possible 605 conformations of eigenvectors, so only the single conformation generated by this algorithm 606 was used for each combination of parameters.

The eigenvalues of a sample covariance matrix were obtained from singular value decomposition of the data matrix, as the singular values squared and then divided by n_* (see, e.g., Jolliffe, 2002). When p > N - 1, 0's were appended to this vector so that p sample eigenvalues were present. Data were centered at the sample mean before the decomposition, therefore n = N - 1. It was chosen that $n_* = n$. The eigenvalues for a sample correlation matrix were obtained similarly from the sample-mean-centered data matrix scaled with the sample standard deviation for each variable.

614 To summarize, each set of simulations consists of the following steps: 1) define a 615 desired set of eigenvalues Λ ; 2) construct the population covariance matrix Σ with the rotation algorithm explained above; 3) generate N i.i.d. normal observations from $N_p(\mathbf{0}, \boldsymbol{\Sigma})$; 616 617 4) eigenvalues of sample covariance and correlation matrices were obtained from singular value decomposition of the sample-mean-centered data; 5) V(S), $V_{rel}(S)$, and $V_{rel}(R)$ were 618 619 calculated from the eigenvalues; 6) the steps 3-5 were iterated for 5,000 times in total with 620 the same N and Σ . The simulations were conducted on the R environment version 3.5.3 (R 621 Core Team, 2019). The function "genhypergeo" of the package "hypergeo" was used to

622 evaluate the hypergeometric function in the moments of $V_{rel}(\mathbf{R})$. The codes are provided as 623 Supplementary Material.

624

625 Results

626 Examined individually, sample eigenvalues were biased estimators of population eigenvalues, as expected. Examples of eigenvalue distribution of sample covariance and 627 628 correlation matrices are shown in Figures 4 and S1, respectively. Typically, the first few 629 eigenvalues were overestimated, with the rest being underestimated. Note that gradually 630 decreasing scree-like profiles of sample eigenvalues typical of empirical datasets can arise 631 even when most population eigenvalues are identical in magnitude. The sampling biases 632 decreased as N increases. These overall trends were similarly observed for correlation 633 matrices, although the upper tail of the largest eigenvalue tended to be truncated for 634 correlation matrices because of the constraint tr $\mathbf{R} = p$, effectively cancelling the tendency of

635 overestimation in this eigenvalue (Fig. S1).

Sampling distributions of $V(\mathbf{S})$ are shown in Figures 5 and S4–S6, and their summary statistics are shown in Tables 1 and S1. Distributions were unimodal but highly skewed with long upper tails, especially when N or p is small. As expected, sampling dispersion decreases consistently with increasing N, with skewness decreasing at the same time. Interestingly, the shape of distribution does not visibly change with increasing p, at least with moderately large N (\geq 32, say). In all conditions, $V(\mathbf{S})$ tended to overestimate the population value $V(\mathbf{\Sigma})$.

642 Increasing $V(\Sigma)$ drastically increased sampling dispersion and skewness, whereas increasing

643 q with a fixed $V(\Sigma)$ decreased sampling dispersion without affecting the mean as much.

644 Sampling distributions of V(S) under linearly and quadratically decreasing λ conditions look

645 similar to those under q-large λ conditions with similar $V(\Sigma)$ values for the respective p. The

646 expressions of the expectation and variance of $V(\mathbf{S})$ almost always coincided with the

sampling mean and variance within a reasonable range of random fluctuations (as expected,since those results are exact).

649 Results for $V_{rel}(S)$ are summarized in Figures 6 and S6–S8 and Tables 2 and S2. 650 Distributions were unimodal within the range (0, 1), except when N = 4 and p = 2 where the 651 distribution was essentially uniform. As was the case for V(S), the sampling dispersion of 652 $V_{\rm rel}(\mathbf{S})$ decreased drastically with increasing N, and to some extent with increasing p, and the 653 shape of distribution does not seem to change drastically with increasing p past certain N. $V_{\rm rel}(\mathbf{S})$ tended to overestimate the population value $V_{\rm rel}(\mathbf{\Sigma})$, except when the latter is rather 654 large (= 0.8) where slight underestimation was observed. With increasing q for a fixed 655 $V_{\rm rel}(\Sigma)$, the distributions tended to shrink, but the sampling bias remained virtually 656 657 unchanged or slightly increased. In the null conditions, the exact expressions of the 658 expectation and variance performed perfectly (as expected). The approximate expectation for 659 arbitrary conditions derived above yielded substantially smaller values than the empirical 660 means when N is small; however, the approximation worked satisfactorily with moderate N661 $(\geq 16-32)$, with the deviations from empirical means mostly falling within 2 standard error 662 units. In addition, the approximate expectation worked rather well, even with small N, under either A) the *q*-large λ conditions with q = 2 and $V_{rel}(\Sigma) = 0.4$, B) same with q = 4, or C) 663 linearly and quadratically decreasing λ conditions with moderately large $p \geq 16$. Other 664 conditions held constant, the accuracy of the approximate expectation in absolute scale 665 666 tended to slightly improve with increasing p, effectively balancing with the decreasing 667 sampling dispersion, so that the relative bias in standard error unit remains almost invariant 668 across varying p. The approximate variance for arbitrary conditions derived above yielded 669 substantially larger values than the empirical variance, except under the q-large λ conditions with q = 1 and $V_{rel}(\Sigma) = 0.8$ where it yielded smaller values. Even with the moderately 670 671 large N of 64, the expression yielded values inaccurate by $\sim 5\%$ in the scale of standard

672	deviation (SD scale hereafter), except under the linearly and quadratically decreasing λ
673	conditions with moderately large $p \ge 16$, where it worked largely satisfactorily.
674	Results for $V_{rel}(\mathbf{R})$ are summarized in Figures 7, S6, S9, and S10 and Tables 3 and
675	S3. Distributions were unimodal within the range (0, 1), except when $p = 2$ and $N \le 8$
676	where an additional peak is usually present near 0. The overall response to varying p and N is
677	largely similar to that of $V_{rel}(\mathbf{S})$, although the shape of distribution was substantially different
678	for small N. As expected from the theoretical expectations noted above, $V_{rel}(\mathbf{R})$ tends to
679	overestimate the population value $V_{rel}(\mathbf{P})$ when the latter is small but tends to underestimate
680	it when $V_{rel}(\mathbf{P}) = 0.8$. The expressions of expectation for the null and arbitrary conditions
681	and variance for the null condition derived above showed almost perfect match with the
682	empirical means and variances (as expected). The asymptotic variance for arbitrary
683	conditions with $p > 2$ derived above behaved somewhat idiosyncratically. It yielded larger
684	values than the empirical variances under A) the q-large λ conditions with $q = 1$ and
685	$V_{\rm rel}(\mathbf{P}) = 0.1 - 0.6$, B) same with $q = 2$ and $V_{\rm rel}(\mathbf{P}) = 0.1 - 0.2$ except when $p = 4$, and C)
686	the quadratically decreasing λ conditions with $p = 4$; whereas it yielded smaller values under
687	a) the <i>q</i> -large λ conditions with $q = 1$ and $V_{rel}(\mathbf{P}) = 0.8$, b) same with $q = 2$ and $V_{rel}(\mathbf{P}) = 0.8$
688	0.4, c) same with $q = 4$, d) same with $q = 2$ and $p = 4$, e) the linearly decreasing λ
689	conditions, and f) the quadratically decreasing λ conditions except when $p = 4$. This latter
690	underestimation of sampling dispersion seems to happen when the smallest population
691	eigenvalue is smaller than ~ 0.125 , although this is not true for the case d. In all cases, the
692	accuracy of the asymptotic expression tends to improve with increasing N . Relative error
693	decreases to 3–10% in SD scale with large N (\geq 64) under the <i>q</i> -large λ conditions with <i>q</i> =
694	1 (all cases), $q = 2$ and $V_{rel}(\mathbf{P}) = 0.1 - 0.2$, or $q = 4$ and $V_{rel}(\mathbf{P}) = 0.1$. However, in other
695	conditions, the relative error can be extremely large (10–300% in SD scale with $N = 256$),
696	especially when the smallest population eigenvalue is small (<0.1).

697

698 **Discussion**

699 Eigenvalue dispersion indices can be calculated for covariance or correlation matrices in 700 similar ways, but implications are rather different. On the one hand, the relative eigenvalue 701 variance of a sample covariance matrix $V_{rel}(\mathbf{S})$ is a test statistic for the sphericity (John, 702 1972; Sugiura, 1972; Nagao, 1973), and is thus interpreted as a measure of eccentricity of 703 variation, be it due to large variation of a single trait or covariation between traits. 704 Interpretation of the unstandardized eigenvalue variance of a sample covariance matrix V(S)705 is less straightforward, but it can potentially be useful in comparing eccentricity between 706 samples when the sensitivity to overall scaling is not of concern, primarily for the presence of 707 an unbiased estimator of the corresponding population value with a known variance (eq. 39). On the other hand, the relative eigenvalue variance of a sample correlation matrix $V_{\rm rel}(\mathbf{R})$ is 708 709 identical to the average of the squared correlation coefficients across all pairs of traits 710 (Durand & Le Roux, 2017; see above). The average squared correlation is another commonly used index of phenotypic integration (e.g., Cheverud et al., 1983), but its equivalence to 711 712 $V_{\rm rel}(\mathbf{R})$ seems to have been overlooked, apart from an empirical confirmation by Haber's (2011) simulations. Obviously, the choice between covariance and correlation should be 713 714 made according to the scope of individual analyses (Klingenberg, 1996; Hansen & Houle, 715 2008; Pavlicev et al., 2009; Goswami & Polly, 2010; see also Machado et al., 2019 for an 716 interesting discussion). Usual caveats for the choice between covariance and correlation is also pertinent here (Jolliffe, 2002): covariance between traits have clear interpretability only 717 if all traits are in the same unit and dimension. These are despite that $V_{rel}(S)$ is dimensionless 718 719 and independent of the overall scaling of traits.

Perhaps the most remarkable finding of this study is that the distributions of $V_{rel}(\mathbf{S})$ and $V_{rel}(\mathbf{R})$ do not seem to vary much with the number of variables *p* itself. The above

722 expressions for the (approximate) mean and variance can be readily calculated for any p, and simulation results indicate that their accuracy are not compromised by large p (Figs. 5–7 and 723 724 S2–S8; Tables 1–3 and S1–S3). This finding highlights potential applicability of these 725 measures to high-dimensional phenotypic data. Nevertheless, it should be remembered that, 726 when p exceeds the degree of freedom n, p - n of the sample eigenvalues are 0 and hence 727 the corresponding population eigenvalues are not estimable. In addition, the first sample 728 eigenvector tends to be consistently diverged from the first population eigenvector in high-729 dimensional settings (Johnstone & Paul, 2018).

730

731 Applications and limitations

732 The present analytic results assume simple independent sampling from a multivariate normal 733 population and the Wishart-ness of the cross-product matrix. For some biological datasets, 734 certain modifications would be required. A simple example is data consisting of multiple 735 groups with potentially heterogeneous means, e.g., intraspecific variation calculated from 736 multiple geographic populations or sexes. If uniform Σ across groups can be assumed, cross-737 product matrices from the data centered at the respective group's sample mean can be 738 summed across groups to obtain a pooled cross-product matrix, which is, by the additivity of 739 Wishart variables, distributed as $W_p(\Sigma, N - g)$, where N is the total sample size and g is the 740 number of groups. That is, all above expressions can be applied by simply using the degree of freedom N - g. A similar correction is required when eigenvalue dispersion indices are 741 742 applied to partial correlation matrices (Torices & Méndez, 2014; Torices & Muñoz-Pajares, 743 2015). The distribution of sample partial correlation coefficients in p_1 variables 744 conditionalized on p_2 other variables based on N observations is the same as that of ordinary 745 correlation coefficients based on $N - p_2$ observations with the same corresponding 746 parameters (e.g., Anderson, 2003: p. 143), so the appropriate degree of freedom is $n - p_2$.

These procedures are essentially to examine the covariance/correlation matrix of residualsafter conditionalizing on covariates.

749 Present analytical results may not be applicable to those empirical covariance or 750 correlation matrices that are not based on a Wishart matrix. Primary examples are the 751 empirical G matrices estimated from variance components in MANOVA designs or as 752 (restricted) maximum likelihood estimators in mixed models (e.g., Lynch & Walsh, 1998). 753 Mean-standardization, a method recommended for analyzing G matrices (e.g., Houle, 1992; 754 Hereford et al., 2004; Hansen & Houle, 2008; Haber, 2016), can also violate the 755 distributional assumption if sample means are used in the standardization. If eigenvalue 756 dispersion indices are to be used with any of these methods, their sampling properties need to 757 be critically assessed.

758 The assumption of multivariate normality may be intrinsically inappropriate for some 759 types of data. Examples include meristic (count) data, compositional or proportional data, 760 angles, and directional data. Application of eigenvalue dispersion indices (or indeed 761 covariance/correlation itself) to such data types would require special treatments, which are 762 beyond the scope of this paper. Needless to say, the appropriateness of multivariate normality 763 should be critically assessed in every empirical dataset when the present analytic results are 764 to be applied, even if the data type is conformable with normality. Robustness of the above 765 results against non-normality may deserve some investigations.

766

767 Shape variables

The application to traditional morphometric datasets, in which all variables are typically measured in the same unit, is rather straightforward, as covariance/correlation in such variables has full interpretability in the Euclidean trait space. Quite often, component(s) of little interest, e.g., size, are removed by transforming raw data, inducing covariation in

772 resultant variables that needs to be taken into account in hypothesis tests. The most typical 773 transformation is the division by an isometric or allometric size variable (Jolicoeur, 1963; Mosimann, 1970; Mosimann & James, 1979; Darroch & Mosimann, 1985; Klingenberg, 774 775 1996, 2016), which can conveniently be done by orthogonal projection in the space of log-776 transformed variables. The projection of objects onto the hyperplane orthogonal to a 777 subspace, say, the column space of **H** ($p \times k$ full-column-rank matrix; for the isometric size 778 vector, $\mathbf{H} = p^{-1/2} \mathbf{1}_n$), can be done by right-multiplying the data by the projection matrix 779 (e.g., Burnaby, 1966): $(\mathbf{u}^T \mathbf{u})^{-1} \mathbf{H}^T$

$$\mathbf{I}_p - \mathbf{H}(\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H}^T$$

780 Therefore, the covariance matrix in the resultant space can be obtained from that in the 781 original space Σ as

794
$$[\mathbf{I}_p - \mathbf{H}(\mathbf{H}^T\mathbf{H})^{-1}\mathbf{H}^T]\mathbf{\Sigma}[\mathbf{I}_p - \mathbf{H}(\mathbf{H}^T\mathbf{H})^{-1}\mathbf{H}^T].$$

782 Under the null condition ($\mathbf{\Sigma} = \sigma^2 \mathbf{I}_p$) specifically, this becomes

795
$$\sigma^2 [\mathbf{I}_p - \mathbf{H} (\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H}^T],$$

783 because the projection matrix is symmetric and idempotent. This transformation renders k784 eigenvalues to be 0 by construction. When the focus is on covariance rather than correlation, 785 these null eigenvalues can optionally be dropped from calculation of eigenvalue mean and 786 dispersion, so that the resultant dispersion index quantifies eccentricity of variation in the 787 subspace of interest. Theories derived above can be applied with minimal modifications, 788 although the asymptotic variance of $V_{\rm rel}(\mathbf{R})$ may not work well due to the singularity. These 789 discussions assume that independence between the raw variables can at least hypothetically 790 be conceived, e.g., when measurements are taken from non-overlapping parts of an organism. 791 If measurements are taken from overlapping parts of an organism, then there will be 792 dependence between variables due to the geometric configuration, which needs to be taken

into consideration on case-by-case basis (Mitteroecker et al., 2012). It may even be
inappropriate to assume multivariate normality for this last type of data.

798 Application to landmark-based geometric morphometric data is more complicated, 799 primarily because the shape space of Procrustes-aligned landmark configurations is (typically 800 a restricted region of) the surface of a hyper(hemi)sphere. In practice, however, empirical 801 analyses are usually conducted on a Euclidean tangent space instead of the shape space itself, 802 assuming that the former gives a satisfactory metric approximation of the latter (e.g., Rohlf, 803 1999; Marcus et al., 2000; Klingenberg, 2020). It will in principle be possible to obtain an 804 approximate population covariance matrix of landmark coordinates in this tangent space from 805 that of raw landmark coordinates before alignment, by using the orthogonal projection 806 method mentioned above with such an **H** whose columns represent the non-shape 807 components. Such a set of vectors can be obtained either as a basis of the complement of the 808 tangent space (see Rohlf & Bookstein, 2003) or directly from the consensus configuration 809 (Klingenberg, 2020). The stereographic projection might potentially be preferred over the 810 orthogonal projection in projecting aligned empirical configurations in the shape space to the 811 tangent space—not to be confused with the projection from the raw space to the tangent 812 space—for purposes of analysing eccentricity of variation. This is because the stereographic 813 projection tends to approximately preserve multivariate normality of the raw coordinates into 814 the resultant tangent space, provided that the variation in the raw coordinates is sufficiently 815 small and that the mean configuration is taken as the point of tangency (Rohlf, 1999). It 816 should be noted that Procrustes superimposition changes perceived patterns of variation in 817 landmark coordinates, often rather drastically (Rohlf & Slice, 1990; Walker, 2000). Such 818 phenomena are probably to be seen as properties of shape variables, rather than necessarily 819 nuisance artefacts (Klingenberg, 2021). Whether these can be of concern or not would 820 depend on the scope of individual analyses (see also Machado et al., 2019).

821

822 Phylogenetic data

823 So far data were assumed to be i.i.d. multivariate normal variables. Important applications in 824 evolutionary biology involve non-i.i.d. observations, most notably phylogenetically 825 structured data in which N observations (typically species) have covariance due to shared 826 evolutionary histories. Trait covariation at the interspecific level may have interpretations 827 under certain microevolutionary models (Felsenstein, 1988; Hansen & Martins, 1996; Revell 828 & Harmon, 2008; Uyeda & Harmon, 2014; Caetano & Harmon, 2019). Under the assumption 829 that trait evolution along phylogeny can be described by (potentially a mixture of) linear 830 invariant Gaussian models, such as the Brownian motion (BM), accelerating-decelerating 831 (ACDC; or early burst), and Ornstein–Uhlenbeck (OU) processes, the joint distribution of the 832 observations is known to be multivariate normal (Hansen & Martins, 1996; Manceau et al., 833 2017; Mitov et al., 2020). A brief overview is given below for potential applications of the 834 present analytic results to phylogenetically structured data.

835 For BM and its modifications, including BM with a trend, Pagel's λ , and ACDC 836 models, the covariance matrix of the $N \times p$ dimensional data **X** can be factorized into the 837 intertrait and interspecific components in the form of Kronecker product: $\Sigma \otimes \Psi$, where Ψ is 838 the $N \times N$ interspecific covariance matrix specified by the underlying phylogeny and 839 parameter(s) specific to the evolutionary model (see Hansen & Martins, 1996; Freckleton et 840 al., 2002; Blomberg et al., 2003; Clavel et al., 2015; Mitov et al., 2020). In this case the data 841 can conveniently be considered as a matrix-variate normal variable (see Gupta & Nagar, 1999): $\mathbf{X} \sim N_{N,p}(\mathbf{M}, \mathbf{\Sigma} \otimes \mathbf{\Psi})$, where **M** is a $N \times p$ matrix of means. If $\mathbf{\Psi}$ is known a priori— 842 843 that is, we have an accurate phylogenetic hypothesis and parameters— the change of variables $\mathbf{Y} = \mathbf{\Psi}^{-1/2} \mathbf{X}$ leads to $\mathbf{Y} \sim N_{N,p}(\mathbf{\Psi}^{-1/2} \mathbf{M}, \mathbf{\Sigma} \otimes \mathbf{I}_N)$, thereby essentially avoiding the 844 845 complication of dependence between observations. This procedure is widely recognized as

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the (phylogenetic) generalized least squares (GLS; e.g., Grafen, 1989; Martins & Hansen,

- 847 1997; Rohlf, 2001; Symonds & Blomberg, 2014). If we know the population mean **M** in
- addition, then the cross product matrix centered at it,

869
$$(\mathbf{Y} - \boldsymbol{\Psi}^{-1/2}\mathbf{M})^T (\mathbf{Y} - \boldsymbol{\Psi}^{-1/2}\mathbf{M}) = (\mathbf{X} - \mathbf{M})^T \boldsymbol{\Psi}^{-1} (\mathbf{X} - \mathbf{M}),$$

is distributed as $W_p(\Sigma, N)$. If we don't exactly know **M** yet still assume $\mathbf{M} = \mathbf{1}_N \boldsymbol{\mu}^T$ with the

unknown but uniform $p \times 1$ mean vector μ , then the GLS estimate of the mean $\hat{\mu} =$

851 $(\mathbf{1}_N^T \Psi^{-1} \mathbf{1}_N)^{-1} \mathbf{1}_N^T \Psi^{-1} \mathbf{X}$ (e.g., Martins & Hansen, 1997) can be used to obtain a sample-

852 mean-centered cross-product matrix

870
$$\left(\mathbf{Y} - \mathbf{\Psi}^{-1/2} \mathbf{1}_N \widehat{\boldsymbol{\mu}}^T\right)^T \left(\mathbf{Y} - \mathbf{\Psi}^{-1/2} \mathbf{1}_N \widehat{\boldsymbol{\mu}}^T\right) = (\mathbf{X} - \mathbf{1}_N \widehat{\boldsymbol{\mu}}^T)^T \mathbf{\Psi}^{-1} (\mathbf{X} - \mathbf{1}_N \widehat{\boldsymbol{\mu}}^T),$$

853 which can be shown to be distributed as $W_p(\Sigma, N-1)$. If there are multiple blocks of species with different means (regimes), then cross-product matrices calculated separately for each of 854 855 these can be summed to obtained a Wishart matrix with a modified degree of freedom as 856 mentioned above, although it would naturally be asked first whether those regimes share the 857 same Σ (Revell & Collar, 2009; Caetano & Harmon, 2019). Above analytic results can 858 directly be applied to these Wishart matrices. Estimation of Σ based on this transformation 859 has previously been devised (Revell & Harmon, 2008; see also Huelsenbeck & Rannala, 860 2003, Revell & Harrison, 2008; Adams & Felice, 2014), and has been shown to have superior 861 accuracy in estimating eigenvalues and eigenvectors over estimation ignoring phylogenetic 862 structure under model conditions (Revell, 2009). Variants of this method have already been 863 applied to analyze eccentricity of interspecific covariation (Haber, 2016; Watanabe, 2018). In 864 practice, however, Ψ is virtually never known accurately because phylogeny and parameters 865 of evolutionary models are generally estimated with error, so empirical cross-product 866 matrices may not be strictly Wishart. This source of error is inherent to any phylogenetic 867 comparative analysis. Unlike the GLS estimate of the mean, which remains unbiased even 868 when Ψ is misspecified, the GLS estimate of trait (co)variance is in general biased in this

871	case (see Rohlf, 2006). Although there are certain ways to incorporate phylogenetic
872	uncertainty into statistical inferences (e.g., Huelsenbeck & Rannala, 2003; Garamszegi &
873	Mundry, 2014; Nakagawa & de Villemereuil, 2019), potential consequences of the
874	uncertainty over the distributions of derived statistics require further investigation (see also
875	Revell et al., 2018). Nevertheless, the GLS estimation with slightly inaccurate Ψ is supposed
876	to yield a better estimate of trait (co)variance than the estimation ignoring phylogenetic
877	covariation altogether (Rohlf, 2006). It should be noted that uniform scaling of Ψ translates
878	to the reciprocal scaling of the cross-product matrix; $V(S)$ is sensitive to this scaling, whereas
879	$V_{\rm rel}(\mathbf{S})$ and $V_{\rm rel}(\mathbf{R})$ are not. Therefore, specifically under the BM model, the only major
880	concern for the latter two indices would be the phylogenetic uncertainty.
881	Unfortunately, the GLS estimation of trait covariance does not seem feasible for
882	multivariate OU models, where the joint covariance matrix cannot in general be factorized
883	into intertrait and interspecific components (Bartoszek et al., 2012; Mitov et al., 2020). This
884	is notably except when the selection strength matrix is spherical and the tree is ultrametric, in
885	which case a factorization of the form $\Sigma\otimes\Psi$ is possible (the scalar OU model; Bastide et al.,
886	2018) and hence the GLS cross-product matrix can in principle be calculated, assuming that
887	the relevant parameters are known. Otherwise, the random drift/diffusion matrix of the OU
888	model estimated in one or other criteria can potentially be analyzed, although little is known
889	about its sampling properties under various implementations, other than that accurate
890	estimation is notoriously difficult (e.g., Ho & Ané, 2014; Clavel et al., 2015). Further studies
891	are required on technical aspects of quantifying trait covariation in phylogenetically
892	structured data under such complex models, as well as its biological implications (e.g.,
893	Adams & Collyer, 2018, 2019b; Mitov et al., 2019, 2020; Clavel et al., 2019; Clavel &

894 Morlon, 2020).

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896 Concluding remarks

897 Eigenvalue dispersion indices of covariance or correlation matrices are commonly used as 898 measures of trait covariation, but their statistical implications have not been well appreciated, against which criticism has reasonably been directed (e.g., Hansen & Houle, 2008; Hansen et 899 al., 2019). As discussed above, $V_{rel}(S)$ and $V_{rel}(R)$ have clear statistical justifications as test 900 901 statistics for sphericity and no correlation, respectively. However, sample eigenvalue 902 dispersion indices are biased estimators of the corresponding population values. This paper 903 derived (or restated) exact and approximate expressions for the expectation and variance of $V(\mathbf{S})$, $V_{\rm rel}(\mathbf{S})$, and $V_{\rm rel}(\mathbf{R})$ under the respective null and arbitrary conditions, with which 904 905 empirical values can be compared. All null moments derived are exact, as well as both moments of $V(\mathbf{S})$ and the expectation of $V_{rel}(\mathbf{R})$ under arbitrary conditions. Moments of 906 $V_{\rm rel}(\mathbf{S})$ under arbitrary conditions are approximations based on the delta method; the 907 908 approximate expectation was shown to work reasonably well with a moderate sample size 909 $(N \ge 16-32)$, whereas the approximate variance requires a larger sample size (e.g., $N \ge 64$, depending on other conditions). The variance of $V_{rel}(\mathbf{R})$ under arbitrary conditions is 910 asymptotic, and was seen to work well with a relatively large sample size ($N \ge 64$) in some 911 912 conditions, but not so well in others even with an extremely large sample size. Under such 913 conditions where these expressions work, they can be used for (approximate) statistical 914 inferences and tests for arbitrary covariance/correlation structures, as well as for 915 determination of appropriate sample size in empirical analyses, essentially replacing 916 qualitative thresholds proposed earlier (e.g., Haber, 2011; Jung et al., 2020). 917 There are several conceivable ways for statistical inferences and hypothesis testing for 918 eigenvalue dispersion indices. When sample size is so large that distributions of the indices 919 are virtually symmetric ($N \ge 16-128$, depending on other conditions), the moments derived

920 above may potentially be used to construct approximate confidence intervals. If multivariate

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921 normality (or any other explicit distribution) can be assumed, then it is straightforward to 922 obtain empirical distributions under appropriate null or alternative conditions with Monte 923 Carlo simulations. Critical points of the null distributions and empirical power at $\alpha = 0.05$ 924 and 0.01 based on the present simulations are presented in Table S1–S3 as a quick guide for 925 sampling design. Several limiting and approximate distributions have been proposed for 926 related statistics (e.g., John, 1972; Nagao, 1973; Ledoit & Wolf, 2002; Schott, 2005), which 927 could be used for simple null hypothesis testing with large N. Resampling-based tests are 928 another potential avenue of development. Applicability and performance of these alternative 929 methods would deserve further investigations.

930

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1293

1294 Appendix A

1295 In this part, relationships between eigenvalue dispersion indices and individual eigenvalues

- 1296 are derived under certain restrictive conditions, in order to facilitate interpretation and to
- 1297 clarify algorithms used in simulations. For simplicity, it is assumed $\overline{\lambda} = 1$ in the following
- 1298 discussions; general cases easily follow by scaling.
- 1299 Let us first consider the simple conditions where the first q (< p) population
- 1300 eigenvalues are equally large and the rest p q eigenvalues are equally small: $\lambda_1 = \cdots =$

1301 $\lambda_q \ge \lambda_{q+1} = \dots = \lambda_p$ ("q-large λ conditions" in simulations). By noting $\sum \lambda_i = q\lambda_1 + 1$

1302 $(p-q)\lambda_p = p$, it is seen that

1303
$$V_{\text{rel}}(\mathbf{\Sigma}) = \frac{\sum_{i=1}^{p} (\lambda_i - 1)^2}{p(p-1)} = \frac{(p-q)}{q(p-1)} \left(1 - \lambda_p\right)^2, \tag{A1}$$

and hence

1311
$$\lambda_1 = 1 + \sqrt{\frac{(p-1)(p-q)}{q}} V_{\rm rel},$$

1312
$$\lambda_p = 1 - \sqrt{\frac{q(p-1)}{p-q}} V_{\text{rel}}$$

1305

1306 By noting the constraint $0 \le \lambda_p \le 1$, an upper limit of V_{rel} can be seen from equation A1:

1307
$$V_{\rm rel}(\Sigma) \le \frac{(p-q)}{q(p-1)} = \frac{1}{q} - \frac{q-1}{q(p-1)}.$$
 (A3)

(A2)

(A4)

1308 It is then obvious that, under these constraints, a value of V_{rel} greater than 0.5 cannot happen 1309 when q > 1; that is, such a large value implies the dominance of a single component of 1310 variance. The same arguments equally apply to correlation matrices.

1313 When q = 1 for the correlation matrix, $V_{rel}(\mathbf{P})$ completely specifies the magnitude of

1314 correlation in every pair of variables. This point can be seen from the definition of

1315 eigendecomposition:

1319
$$\rho_{ij} = \sum_{k=1}^{p} \lambda_k \upsilon_{ik} \upsilon_{jk}$$

1320
$$= (\lambda_1 - \lambda_p)\upsilon_{i1}\upsilon_{j1} + \lambda_p \sum_{k=1}^p \upsilon_{ik}\upsilon_{jk},$$

1316

- 1317 where the (i, j)-th element of the eigenvector matrix denoted as v_{ij} . Remember that
- 1318 $\sum_{k=1}^{p} v_{ik} v_{jk} = \delta_{ij}$, the Kronecker delta. Then, by noting equation A2 with q = 1,

1321
$$1 = \rho_{ii} = (\lambda_1 - \lambda_p)\upsilon_{i1}^2 + \lambda_p = (p\upsilon_{i1}^2 - 1)\sqrt{V_{rel}} + 1,$$
(A5)

1322 therefore $v_{i1}^2 = p^{-1/2}$ for any *i* (that is, the coefficients of the first eigenvector are equal in 1323 magnitude). Finally, we have

1324
$$\rho_{ij}^{2} = (\lambda_{1} - \lambda_{p})^{2} \upsilon_{i1}^{2} \upsilon_{j1}^{2} = V_{\text{rel}}$$
(A6)

for any combination of *i* and *j* ($i \neq j$); the magnitude of correlation is identical across all pairs. Taken differently, $\lambda_2 = \cdots = \lambda_p = |\rho|$. These relationships have previously been noted by Anderson (1963) and Pavlicev et al. (2009).

1328 The population eigenvalues of the linearly and quadratically decreasing λ conditions

1329 used in simulations are defined as
$$\lambda_i = (p - i + 1)\lambda_p$$
 and $\lambda_i = (p - i + 1)^2\lambda_p$ $(i = 1)^2\lambda_p$

1330 $1, 2, \ldots, p$) for linearly and quadratically decreasing conditions, respectively. Under the

assumption of a constant average eigenvalue, it is a simple matter of algebra to obtain the

1332 actual values of λ_p and $V_{rel}(\Sigma)$, which are simple functions of p. The latter equals

1333 1/3(p+1) and (8p+11)/5(p+1)(2p+1) for the linearly and quadratically decreasing λ 1334 conditions, respectively.

1335

1336 Appendix B

1337 In this part, the first two moments of V(S) and $V_{rel}(S)$ under the arbitrary Σ are derived,

1338 assuming multivariate normality. Derivation of the moments of the latter requires evaluation

1339 of moments of the ratio $\sum l_i^2 / (\sum l_i)^2 = \text{tr}(\mathbf{A}^2) / (\text{tr } \mathbf{A})^2$, which are not guaranteed to coincide

1340 with the ratio of moments except under the null hypothesis. Here we utilize the

1341 approximation based on the Taylor series expansion given in equation 32. In turn, we need

1342
$$E[tr(\mathbf{A}^2)], E[(tr \mathbf{A})^2], Var[tr(\mathbf{A}^2)], Var[(tr \mathbf{A})^2], and Cov[tr(\mathbf{A}^2), (tr \mathbf{A})^2].$$

1343 We will follow Srivastava & Yanagihara's (2010) approach to obtain these moments.

1344 As in the text, let the $n \times p$ matrix **Z** be $(\mathbf{z}_1, \mathbf{z}_2, ..., \mathbf{z}_n)^T$, where $\mathbf{z}_i \sim N_p(\mathbf{0}_p, \mathbf{\Sigma})$ for i =

1345 1, 2, ..., *n*. Consider the cross-product matrix

$$A = \mathbf{Z}^T \mathbf{Z}, \tag{B1}$$

1347 such that $\mathbf{A} \sim W_p(\boldsymbol{\Sigma}, n)$. Let the spectral decomposition of $\boldsymbol{\Sigma}$:

1348 $\boldsymbol{\Sigma} = \boldsymbol{\Upsilon} \boldsymbol{\Lambda} \boldsymbol{\Upsilon}^T, \tag{B2}$

1349 with the orthogonal matrix of eigenvectors \mathbf{Y} and the diagonal matrix of eigenvalues $\mathbf{\Lambda}$. Let

1350 the
$$n \times p$$
 matrix **J** be $(\mathbf{j}_1, \mathbf{j}_2, \dots, \mathbf{j}_n)^T$, where \mathbf{j}_i are i.i.d. $N_p(\mathbf{0}, \mathbf{I}_p)$, such that $\mathbf{Z} = \mathbf{J} \boldsymbol{\Sigma}^{1/2}$ with

1351 $\Sigma^{1/2} = \Upsilon \Lambda^{1/2} \Upsilon^T$. Then, it is possible to write

1352
$$\mathbf{A} = \boldsymbol{\Sigma}^{1/2} \mathbf{J}^T \mathbf{J} \boldsymbol{\Sigma}^{1/2} = \boldsymbol{\Upsilon} \boldsymbol{\Lambda}^{1/2} \boldsymbol{\Upsilon}^T \mathbf{J}^T \mathbf{J} \boldsymbol{\Upsilon} \boldsymbol{\Lambda}^{1/2} \boldsymbol{\Upsilon}^T = \boldsymbol{\Upsilon} \boldsymbol{\Lambda}^{1/2} \mathbf{V}^T \mathbf{V} \boldsymbol{\Lambda}^{1/2} \boldsymbol{\Upsilon}^T,$$
(B3)

1353 where
$$\mathbf{V} = \mathbf{J}\mathbf{Y} = (\mathbf{v}_1, \mathbf{v}_2, ..., \mathbf{v}_p)$$
 with \mathbf{v}_i being i.i.d. $N_n(\mathbf{0}, \mathbf{I}_n)$. Furthermore, let $w_{ij} = \mathbf{v}_i^T \mathbf{v}_j$,

1354 such that w_{ii} are i.i.d. chi-square variables with *n* degrees of freedom χ_n^2 . Obviously $w_{ij} =$

1355 w_{ji} . Note that

1356
$$\operatorname{tr} \mathbf{A} = \operatorname{tr} \left(\mathbf{Y} \mathbf{\Lambda}^{1/2} \mathbf{V}^T \mathbf{V} \mathbf{\Lambda}^{1/2} \mathbf{Y}^T \right) = \operatorname{tr} \left(\mathbf{\Lambda} \mathbf{V}^T \mathbf{V} \right) = \sum_{i=1}^n \lambda_i w_{ii}. \tag{B4}$$

1357 From well-known results on normal and chi-square moments, we have the following:

1358
$$E(w_{ii}^r) = n(n+2) \dots (n+2r-2), r = 1, 2, \dots,$$

1359
$$\mathbf{E}(w_{ii}^{r}w_{ij}^{2}) = \mathbf{E}[\mathrm{tr}(w_{ii}^{r}\mathbf{v}_{i}\mathbf{v}_{j}^{T}\mathbf{v}_{j}\mathbf{v}_{j}^{T})]$$

1360
$$= \operatorname{tr}\left[\operatorname{E}(w_{ii}^{r}\mathbf{v}_{i}\mathbf{v}_{i}^{T})\operatorname{E}(\mathbf{v}_{j}\mathbf{v}_{j}^{T})\right]$$

1361
$$= \operatorname{tr}[\mathrm{E}(w_{ii}^{r}\mathbf{v}_{i}\mathbf{v}_{i}^{T})\mathbf{I}_{n}]$$

$$1362 \qquad \qquad = \mathbf{E}(w_{ii}^{r+1})$$

1363
$$= n(n+2)...(n+2r), \quad i \neq j, \quad r = 0, 1, ...,$$

1364
$$\mathbf{E}(w_{ii}w_{jj}w_{ij}^2) = \mathbf{E}[\mathrm{tr}(w_{ii}\mathbf{v}_i\mathbf{v}_i^Tw_{jj}\mathbf{v}_j\mathbf{v}_j^T)]$$

1365
$$= \sum_{\alpha,\beta,\gamma,\delta}^{n} E(v_{i\alpha}^2 v_{i\gamma} v_{i\delta}) E(v_{j\beta}^2 v_{j\delta} v_{j\gamma})$$

1366
$$= 9n + 6n(n-1) + n(n-1)^2$$

1367
$$= n(n+2)^2, \quad i \neq j,$$

1370
$$E(w_{ij}^2 w_{ik}^2) = \sum_{\alpha,\beta}^n E(v_{i\alpha}^2 v_{i\beta}^2) E(v_{j\alpha}^2) E(v_{k\beta}^2)$$

1371
$$= 3n + n(n-1)$$

$$1372 = n(n+2), i \neq j \neq k,$$

1373
$$E(w_{ij}^{4}) = \sum_{\alpha,\beta,\gamma,\delta}^{n} E(v_{i\alpha}v_{i\beta}v_{i\gamma}v_{i\delta}) E(v_{j\alpha}v_{j\beta}v_{j\delta}v_{j\gamma})$$

1374
$$= 9n + 3n(n-1)$$

$$1375 \qquad \qquad = 3n(n+2), \qquad i \neq j,$$

1368

1369 where some intervening equations result from direct enumeration of the nonzero moments.

(B5)

1376 From the above expectations, one can evaluate the desired moments as follows:

1377
$$E[tr(\mathbf{A}^2)] = E[tr(\mathbf{\Lambda}\mathbf{V}^T\mathbf{V}\mathbf{\Lambda}\mathbf{V}^T\mathbf{V})]$$

1378
$$= \mathbf{E}\left(\sum_{i,j}^{n} \lambda_i \lambda_j w_{ij}^2\right)$$

1379
$$= \sum_{i}^{n} \lambda_{i}^{2} \operatorname{E}(w_{ii}^{2}) + \sum_{i \neq j}^{n} \lambda_{i} \lambda_{j} \operatorname{E}(w_{ij}^{2})$$

1380
$$= n(n+2)\sum_{i}^{n}\lambda_{i}^{2} + n\sum_{i\neq j}^{n}\lambda_{i}\lambda_{j},$$

1381
$$E[(tr \mathbf{A})^2] = E[[tr(\mathbf{A}\mathbf{V}^T\mathbf{V})]^2]$$

1382
$$= E\left(\sum_{i,j}^{n} \lambda_i \lambda_j w_{ii} w_{jj}\right)$$

1383
$$= \sum_{i}^{n} \lambda_{i}^{2} \operatorname{E}(w_{ii}^{2}) + \sum_{i \neq j}^{n} \lambda_{i} \lambda_{j} \operatorname{E}(w_{ii}) \operatorname{E}(w_{jj})$$

1384
$$= n(n+2)\sum_{i}^{n}\lambda_{i}^{2} + n^{2}\sum_{i\neq j}^{n}\lambda_{i}\lambda_{j},$$

1385
$$E[[tr(\mathbf{A}^2)]^2] = E[[tr(\mathbf{\Lambda}\mathbf{V}^T\mathbf{V}\mathbf{\Lambda}\mathbf{V}^T\mathbf{V})]^2]$$

1386
$$= \mathbb{E}\left(\sum_{i,j,k,l}^{n} \lambda_i \lambda_j \lambda_k \lambda_l w_{ij}^2 w_{kl}^2\right)$$

1387
$$= \sum_{i}^{n} \lambda_{i}^{4} \operatorname{E}(w_{ii}^{4}) + 4 \sum_{i \neq j}^{n} \lambda_{i}^{3} \lambda_{j} \operatorname{E}(w_{ii}^{2} w_{ij}^{2})$$

1388
$$+ \sum_{i \neq j}^{n} \lambda_{i}^{2} \lambda_{j}^{2} \left[E(w_{ii}^{2}) E(w_{jj}^{2}) + 2 E(w_{ij}^{4}) \right]$$

1389
$$+ \sum_{i \neq j \neq k}^{n} \lambda_{i}^{2} \lambda_{j} \lambda_{k} \left[2 \operatorname{E}(w_{ii}^{2}) \operatorname{E}(w_{jk}^{2}) + 4 \operatorname{E}(w_{ij}^{2} w_{ik}^{2}) \right]$$

1390
$$+ \sum_{\substack{i \neq j \neq k \neq l}}^{n} \lambda_i \lambda_j \lambda_k \lambda_l \operatorname{E}(w_{ij}^2) \operatorname{E}(w_{kl}^2)$$

1391
$$= n(n+2)(n+4)(n+6)\sum_{i=1}^{n}\lambda_{i}^{4} + 4n(n+2)(n+4)\sum_{i\neq j=1}^{n}\lambda_{i}^{3}\lambda_{j}$$

1392
$$+ n(n+2)(n^2 + 2n + 6) \sum_{i \neq j}^n \lambda_i^2 \lambda_j^2 + 2n(n+2) \sum_{i \neq j \neq k}^n \lambda_i^2 \lambda_j \lambda_k$$

1393
$$+ n^2 \sum_{\substack{i \neq j \neq k \neq l}}^n \lambda_i \lambda_j \lambda_k \lambda_l$$

1394
$$E[(tr \mathbf{A})^4] = E[[tr(\mathbf{A}\mathbf{V}^T\mathbf{V})]^4]$$

1395
$$= E\left(\sum_{i,j,k,l}^{n} \lambda_i \lambda_j \lambda_k \lambda_l w_{ii} w_{jj} w_{kk} w_{ll}\right)$$

1396
$$= \sum_{i}^{n} \lambda_{i}^{4} \operatorname{E}(w_{ii}^{4}) + 4 \sum_{i \neq j}^{n} \lambda_{i}^{3} \lambda_{j} \operatorname{E}(w_{ii}^{3}) \operatorname{E}(w_{jj}) + 3 \sum_{i \neq j}^{n} \lambda_{i}^{2} \lambda_{j}^{2} \operatorname{E}(w_{ii}^{2}) \operatorname{E}(w_{jj}^{2})$$

1397
$$+ 6 \sum_{i \neq j \neq k}^{n} \lambda_i^2 \lambda_j \lambda_k \operatorname{E}(w_{ii}^2) \operatorname{E}(w_{jj}) \operatorname{E}(w_{kk})$$

1398
$$+ \sum_{i \neq j \neq k \neq l}^{n} \lambda_i \lambda_j \lambda_k \lambda_l \operatorname{E}(w_{ii}) \operatorname{E}(w_{jj}) \operatorname{E}(w_{kk}) \operatorname{E}(w_{ll})$$

1399
$$= n(n+2)(n+4)(n+6)\sum_{i=1}^{n}\lambda_{i}^{4} + 4n^{2}(n+2)(n+4)\sum_{i\neq j=1}^{n}\lambda_{i}^{3}\lambda_{j}$$

1400
$$+ 3n^{2}(n+2)^{2} \sum_{i \neq j}^{n} \lambda_{i}^{2} \lambda_{j}^{2} + 6n^{3}(n+2) \sum_{i \neq j \neq k}^{n} \lambda_{i}^{2} \lambda_{j} \lambda_{k}$$

1401
$$+ n^4 \sum_{\substack{i \neq j \neq k \neq l}}^n \lambda_i \lambda_j \lambda_k \lambda_l,$$

1402
$$E[tr(\mathbf{A}^2) \cdot (tr \mathbf{A})^2] = E[tr(\mathbf{\Lambda}\mathbf{V}^T\mathbf{V}\mathbf{\Lambda}\mathbf{V}^T\mathbf{V}) \cdot [tr(\mathbf{\Lambda}\mathbf{V}^T\mathbf{V})]^2]$$

1403
$$= \mathbb{E}\left(\sum_{i,j,k,l}^{n} \lambda_i \lambda_j \lambda_k \lambda_l w_{ij}^2 w_{kk} w_{ll}\right)$$

1404
$$= \sum_{i}^{n} \lambda_{i}^{4} \operatorname{E}(w_{ii}^{4}) + \sum_{i \neq j}^{n} \lambda_{i}^{3} \lambda_{j} \left[2 \operatorname{E}(w_{ii}^{3}) \operatorname{E}(w_{jj}) + 2 \operatorname{E}(w_{ii}^{2} w_{ij}^{2}) \right]$$

1405
$$+ \sum_{i \neq j}^{n} \lambda_{i}^{2} \lambda_{j}^{2} \left[E(w_{ii}^{2}) E(w_{jj}^{2}) + 2 E(w_{ii}w_{jj}w_{ij}^{2}) \right]$$

1406
$$+ \sum_{i \neq j \neq k}^{n} \lambda_i^2 \lambda_j \lambda_k \left[\mathsf{E}(w_{ii}^2) \, \mathsf{E}(w_{jj}) \, \mathsf{E}(w_{kk}) + 4 \, \mathsf{E}(w_{ii} w_{ij}^2) \, \mathsf{E}(w_{kk}) \right]$$

1407
$$+ \operatorname{E}(w_{ii}^{2})\operatorname{E}(w_{jk}^{2})] + \sum_{\substack{i \neq j \neq k \neq l}}^{n} \lambda_{i}\lambda_{j}\lambda_{k}\lambda_{l}\operatorname{E}(w_{ij}^{2})\operatorname{E}(w_{kk})\operatorname{E}(w_{ll})$$

1411
$$= n(n+2)(n+4)(n+6)\sum_{i=1}^{n}\lambda_{i}^{4} + 2n(n+1)(n+2)(n+4)\sum_{i\neq j=1}^{n}\lambda_{i}^{3}\lambda_{j}$$

1412
$$+ n(n+2)^3 \sum_{i\neq j}^n \lambda_i^2 \lambda_j^2 + n^2(n+2)(n+5) \sum_{i\neq j\neq k}^n \lambda_i^2 \lambda_j \lambda_k$$

1413
$$+ n^3 \sum_{\substack{i \neq j \neq k \neq l}}^n \lambda_i \lambda_j \lambda_k \lambda_l,$$

1408

(B6)

(B7)

1409 where notations of the form $i \neq j \neq k \neq l$ represent inequality of every pairwise combination 1410 of the subscripts concerned.

1414 Although equations B6 can be evaluated for any Σ , calculating the product of all 1415 possible combinations of eigenvalues is rather cumbersome especially when *p* is large. For 1416 this practical reason, it would be preferable to simplify these expressions by noting

1418
$$\sum_{i}^{n} \lambda_{i}^{r} = \operatorname{tr}(\boldsymbol{\Lambda}^{r}), \qquad r = 1, 2, ...,$$

1419
$$\sum_{i\neq j}^{n} \lambda_i \lambda_j = \left(\sum_{i=1}^{n} \lambda_i\right)^2 - \sum_{i=1}^{n} \lambda_i^2 = (\operatorname{tr} \mathbf{\Lambda})^2 - \operatorname{tr}(\mathbf{\Lambda}^2),$$

1420
$$\sum_{i\neq j}^{n} \lambda_i^3 \lambda_j = \operatorname{tr} \mathbf{\Lambda} \operatorname{tr}(\mathbf{\Lambda}^3) - \operatorname{tr}(\mathbf{\Lambda}^4),$$

1421
$$\sum_{i\neq j}^{n} \lambda_i^2 \lambda_j^2 = 3[\operatorname{tr}(\Lambda^2)]^2 - \operatorname{tr}(\Lambda^4),$$

1422
$$\sum_{i\neq j\neq k}^{n} \lambda_i^2 \lambda_j \lambda_k = (\operatorname{tr} \Lambda)^2 \operatorname{tr} (\Lambda^2) - 2 \operatorname{tr} \Lambda \operatorname{tr} (\Lambda^3) - [\operatorname{tr} (\Lambda^2)]^2 + 2 \operatorname{tr} (\Lambda^4),$$

1423
$$\sum_{\substack{i\neq j\neq k\neq l}}^{n} \lambda_i \lambda_j \lambda_k \lambda_l = (\operatorname{tr} \Lambda)^4 - 6(\operatorname{tr} \Lambda)^2 \operatorname{tr}(\Lambda^2) + 8 \operatorname{tr} \Lambda \operatorname{tr}(\Lambda^3) + 3[\operatorname{tr}(\Lambda^2)]^2 - 6 \operatorname{tr}(\Lambda^4).$$

1417

1424 Then, equations B6 can be written as follows:

1429
$$\operatorname{E}[\operatorname{tr}(\mathbf{A}^2)] = n(\operatorname{tr}\mathbf{\Lambda})^2 + n(n+1)\operatorname{tr}(\mathbf{\Lambda}^2),$$

1430
$$E[(tr A)^2] = n^2(tr \Lambda)^2 + 2n tr(\Lambda^2),$$

1431
$$E[[tr(\mathbf{A}^2)]^2] = n^2(tr\,\mathbf{\Lambda})^4 + 2n(n^2 + n + 4)(tr\,\mathbf{\Lambda})^2 tr(\mathbf{\Lambda}^2) + 16n(n+1) tr\,\mathbf{\Lambda} tr(\mathbf{\Lambda}^3)$$

1432
$$+ n(n^3 + 2n^2 + 5n + 4)[tr(\Lambda^2)]^2 + 4n(2n^2 + 5n + 5)tr(\Lambda^4),$$

1433
$$\mathbf{E}[(\operatorname{tr} \mathbf{A})^4] = n^4 (\operatorname{tr} \mathbf{\Lambda})^4 + 12n^3 (\operatorname{tr} \mathbf{\Lambda})^2 \operatorname{tr} (\mathbf{\Lambda}^2) + 12n^2 \operatorname{tr} \mathbf{\Lambda} \operatorname{tr} (\mathbf{\Lambda}^3)$$

1434 $+ 32n^{2}[tr(\Lambda^{2})]^{2} + 48n tr(\Lambda^{4}).$

1435
$$E[tr(\mathbf{A}^2) \cdot (tr \mathbf{A})^2] = n^3 (tr \mathbf{\Lambda})^4 + n^2 (n^2 + n + 10) (tr \mathbf{\Lambda})^2 tr(\mathbf{\Lambda}^2)$$

1436 +
$$8n(n^2 + n + 2) \operatorname{tr} \Lambda \operatorname{tr}(\Lambda^3) + 2n(n^2 + n + 4)[\operatorname{tr}(\Lambda^2)]^2$$

1437
$$+ 24n(n+1) \operatorname{tr}(\Lambda^4)$$
,

1425

1426 Finally,

1438
$$Var[tr(\mathbf{A}^{2})] = E[[tr(\mathbf{A}^{2})]^{2}] - E[tr(\mathbf{A}^{2})]^{2}$$
1439
$$= 8n(tr \Lambda)^{2} tr(\Lambda^{2}) + 16n(n+1) tr \Lambda tr(\Lambda^{3})$$
1440
$$+ 4n(n+1)[tr(\Lambda^{2})]^{2} + 4n(2n^{2}+5n+5) tr(\Lambda^{4}),$$
1441
$$Var[(tr \mathbf{A})^{2}] = E[(tr \mathbf{A})^{4}] - E[(tr \mathbf{A})^{2}]^{2}$$
1442
$$= 8n^{3}(tr \Lambda)^{2} tr(\Lambda^{2}) + 32n^{2} tr \Lambda tr(\Lambda^{3}) + 8n^{2}[tr(\Lambda^{2})]^{2}$$
1443
$$+ 48n tr(\Lambda^{4}),$$
1444
$$Cov[tr(\mathbf{A}^{2}), (tr \mathbf{A})^{2}] = E[tr(\mathbf{A}^{2}) \cdot (tr \mathbf{A})^{2}] - E[tr(\mathbf{A}^{2})] E[(tr \mathbf{A})^{2}]$$
1445
$$= 8n^{2}(tr \Lambda)^{2} tr(\Lambda^{2}) + 8n(n^{2}+n+2) tr \Lambda tr(\Lambda^{3}) + 8n[tr(\Lambda^{2})]^{2}$$
1446
$$+ 24n(n+1) tr(\Lambda^{4}).$$
1427 (B9)

(B8)

1428 Inserting equations B8 and B9 into equations 12, 19, and 32 yields the desired results.

1447 Identical results can be derived from del Waal & Nel's (1973) results on the

1448 expectations of elementary symmetric functions of eigenvalues and their products for a

1449 Wishart matrix. However, these results appear to have been proved only under the condition 1450 n > p - 1 (see also Constantine, 1963; Muirhead, 1982: chapter 7). The above derivation is 1451 valid for any combination of p and n.

1452

1453 Appendix C

1454 This part demonstrates that $Cov(r_{ij}^2, r_{kl}^2) = 0$ for $(i, j) \neq (k, l)$ under the condition $\mathbf{P} = \mathbf{I}_p$, as

1455 cursorily mentioned by Schott (2005). Under this condition, a sample covariance can be

- 1456 written as $s_{ij} = n_*^{-1} (\sigma_{ii} \sigma_{jj})^{1/2} \mathbf{v}_i^T \mathbf{v}_j$, with \mathbf{v}_i and \mathbf{v}_j being i.i.d. $N_n(\mathbf{0}, \mathbf{I}_n)$. Therefore, a sample
- 1457 correlation coefficient can be written as $r_{ij} = s_{ij} (s_{ii} s_{jj})^{-1/2} = \mathbf{u}_i^T \mathbf{u}_j$, where $\mathbf{u}_i =$
- 1458 $(\mathbf{v}_i^T \mathbf{v}_i)^{-1/2} \mathbf{v}_i$ are uniformly distributed on the surface of the unit hypersphere in the *n*-
- 1459 dimensional space. By noting $\mathbf{u}_i^T \mathbf{u}_i = 1$, it is possible to see $E(\mathbf{u}_i \mathbf{u}_i^T) = n^{-1} \mathbf{I}_n$ for any *i*,
- 1460 because the elements of \mathbf{u}_i are symmetric and uncorrelated with one another (a formal

1461 demonstration requires introduction of the density function; see Anderson, 2003: p. 49). With

1462 these preliminaries, it is easily seen, for $i \neq j \neq k$,

1468 $\mathbf{E}(r_{ij}^2 r_{ik}^2) = \mathbf{E}(\mathbf{u}_i^T \mathbf{u}_j \mathbf{u}_j^T \mathbf{u}_i \mathbf{u}_i^T \mathbf{u}_k \mathbf{u}_k^T \mathbf{u}_i)$

1469
$$= \mathbf{E} \left[\mathbf{u}_i^T \mathbf{E} \left(\mathbf{u}_j \mathbf{u}_i^T \right) \mathbf{u}_i \mathbf{u}_i^T \mathbf{E} \left(\mathbf{u}_k \mathbf{u}_k^T \right) \mathbf{u}_i \right]$$

1470
$$= n^{-2} \mathbf{E}[\mathbf{u}_i^T \mathbf{u}_i \mathbf{u}_i^T \mathbf{u}_i]$$

1471
$$= n^{-2} = E(r_{ij}^2)E(r_{ik}^2).$$

1463

1464 The second equation is valid because \mathbf{u}_i , \mathbf{u}_j , and \mathbf{u}_k are stochastically independent from one 1465 another. Therefore, $\operatorname{Cov}(r_{ij}^2, r_{ik}^2) = 0$ for partly overlapping subscripts. Similarly, 1466 $\operatorname{Cov}(r_{ij}^2, r_{kl}^2) = 0$ for non-overlapping subscripts, although this could also be seen as a direct 1467 consequence of the independence between r_{ij} and r_{kl} in this case. 1472

(C1)

Appendix D 1473

1474 In this part, an asymptotic expression for the variance of $V_{rel}(\mathbf{R})$ is derived, somewhat 1475 heuristically, for arbitrary non-null conditions with p > 2. Konishi (1979) gave an 1476 asymptotic theory for the distribution of an arbitrary function of eigenvalues of a sample correlation matrix $f(l_1, ..., l_p)$ under multivariate normality. In particular, when $n \to \infty$, 1477 $\sqrt{n}[f(l_1, ..., l_p) - f(\lambda_1, ..., \lambda_p)]$ was shown to be normally distributed with mean 0 and 1478 1479 variance п Г п п

1492
$$\tau^{2} = 2 \sum_{\alpha,\beta=1}^{p} \lambda_{\alpha} \lambda_{\beta} \left[\delta_{\alpha\beta} - (\lambda_{\alpha} + \lambda_{\beta}) \sum_{i=1}^{p} \upsilon_{i\alpha}^{2} \upsilon_{i\beta}^{2} + \sum_{i,j=1}^{p} \rho_{ij}^{2} \upsilon_{i\alpha}^{2} \upsilon_{j\beta}^{2} \right] f_{\alpha} f_{\beta} ,$$

(D1)

where the summations are over all combinations of subscripts, $\delta_{\alpha\beta}$ is the Kronecker delta, $\upsilon_{i\alpha}$ 1481 is the (i, α) -th element of the population eigenvector matrix \mathbf{Y} , and $f_{\alpha} =$ 1482

- 1483 $\partial f/\partial l_{\alpha}|_{(l_1,\dots,l_p)=(\lambda_1,\dots,\lambda_p)}$, the partial derivative of f with respect to l_{α} evaluated at
- $(l_1, ..., l_p) = (\lambda_1, ..., \lambda_p)$. Note that Konishi's (1979; corollary 2.2) original notation also 1484
- 1485 concerned potential multiplicity of population eigenvalues, which is ignored here for
- 1486 simplicity; the population eigenvectors corresponding to multiplicated eigenvalues can in
- 1487 practice be chosen arbitrarily as a suite of orthogonal vectors in the appropriate subspace, as
- 1488 is done in numerical determination of eigenvectors. The derivative of $V_{rel}(\mathbf{R})$ is simply

1493
$$f_{\alpha} = \frac{\partial}{\partial l_{\alpha}} V_{\text{rel}}(\mathbf{R}) \Big|_{(l_1,\dots,l_p) = (\lambda_1,\dots,\lambda_p)} = \frac{2}{p(p-1)} \lambda_{\alpha}.$$
1489 (D2)

1489

Inserting equation D2 into equation D1, we obtain τ^2/n as an asymptotic expression of the 1490 variance of $V_{rel}(\mathbf{R})$ (eq. 37). 1491

- 1494 An empirically equivalent result can be obtained from the alternative expression of
- 1495 $V_{\rm rel}(\mathbf{R})$ as average squared correlation coefficients (eq. 11), from a similar theory for
- 1496 functions of a sample correlation matrix by Konishi (1979: theorem 6.2). However, that
- 1497 alternative expression does not seem to bear much practical advantage, for it typically takes
- substantially more computational time to evaluate as *p* grows.
- 1499

1500	Table 1. Summary statistics of selected simulation results for eigenvalue variance of
1501	covariance matrix $V(\mathbf{S})$. Theoretical expectation (E[$V(\mathbf{S})$]) and standard deviation
1502	(SD[V(S)]), as well as empirical median, mean, standard deviation (ESD), and bias of mean

1503 in standard error unit ($T = \sqrt{5000}$ {Mean - E[$V_{rel}(\mathbf{S})$]}/ESD, which should roughly follow t

- 1504 distribution with 4999 degrees of freedom if the expectation is exact) from 5000 simulation
- 1505 runs are shown for selected conditions. See Table S1 for full results.

	$E[V(\mathbf{S})]$	$SD[V(\mathbf{S})]$	Median	Mean	ESD	Т
p=2, V(x)	$\mathbf{\Sigma}) = 0$					
N = 8	0.2857	0.3582	0.1731	0.2876	0.3464	0.3845
N = 16	0.1333	0.1501	0.0876	0.1330	0.1466	-0.1703
N = 32	0.0645	0.0686	0.0438	0.0646	0.0689	0.0489
N = 64	0.0317	0.0327	0.0221	0.0315	0.0315	-0.6336
p=4, V(2)	$\Sigma) = 0$					
N = 8	0.2143	0.1551	0.1734	0.2131	0.1534	-0.5437
N=16	0.1000	0.0602	0.0861	0.0996	0.0603	-0.4826
N = 32	0.0484	0.0261	0.0429	0.0481	0.0261	-0.8676
<i>N</i> = 64	0.0238	0.0120	0.0216	0.0239	0.0119	0.5321
<i>p</i> = 16, <i>V</i>	$(\mathbf{\Sigma}) = 0$					
N = 8	0.1518	0.0304	0.1482	0.1510	0.0307	-1.8948
N=16	0.0708	0.0102	0.0702	0.0708	0.0102	-0.0003
N = 32	0.0343	0.0038	0.0341	0.0342	0.0037	-0.4806
N = 64	0.0169	0.0015	0.0168	0.0169	0.0015	-0.6023
<i>p</i> = 64, <i>V</i>	$(\mathbf{\Sigma}) = 0$					
N = 8	0.1473	0.0203	0.1464	0.1477	0.0204	1.2947

Table 1 (continued)

	E[V(S)]	SD[<i>V</i> (S)]	Median	Mean	ESD	Т		
N=16	0.0688	0.0067	0.0688	0.0689	0.0066	1.7306		
N=32	0.0333	0.0024	0.0332	0.0333	0.0024	0.6721		
N = 64	0.0164	0.0009	0.0163	0.0164	0.0009	-0.4407		
$p=256, V(\mathbf{\Sigma})=0$								
N = 8	0.1440	0.0097	0.1436	0.1440	0.0099	0.1215		
N=16	0.0672	0.0031	0.0672	0.0672	0.0031	0.9739		
N = 32	0.0325	0.0011	0.0325	0.0325	0.0011	-0.8132		
N = 64	0.0160	0.0004	0.0160	0.0160	0.0004	0.0842		
<i>p</i> = 1024,	$V(\mathbf{\Sigma})=0$							
N = 8	0.1431	0.0048	0.1430	0.1431	0.0048	-0.6874		
N=16	0.0668	0.0015	0.0668	0.0668	0.0015	1.7324		
N = 32	0.0323	0.0005	0.0323	0.0323	0.0005	0.3227		
N = 64	0.0159	0.0002	0.0159	0.0159	0.0002	0.3522		
<i>p</i> = 2, <i>q</i> =	$1, V(\mathbf{\Sigma}) = 0.4$							
N = 8	0.6857	0.8717	0.3967	0.6901	0.8663	0.3572		
N=16	0.5333	0.4852	0.3972	0.5426	0.4981	1.3183		
N = 32	0.4645	0.3023	0.3936	0.4616	0.3011	-0.6854		
N = 64	0.4317	0.2002	0.4044	0.4337	0.2019	0.6886		
<i>p</i> = 4, <i>q</i> =	$1, V(\mathbf{\Sigma}) = 0.4$							
N = 8	0.6429	0.7343	0.3949	0.6372	0.7364	-0.5426		
N=16	0.5133	0.4137	0.3968	0.5132	0.4183	-0.0225		
N = 32	0.4548	0.2598	0.3937	0.4544	0.2661	-0.1087		
N = 64	0.4270	0.1728	0.4025	0.4292	0.1756	0.8791		

 $p = 16, q = 1, V(\Sigma) = 0.4$

Table 1 (continued)

	$E[V(\mathbf{S})]$	SD[<i>V</i> (S)]	Median	Mean	ESD	Т
N = 8	0.6107	0.6427	0.4130	0.6165	0.6509	0.6282
N=16	0.4983	0.3668	0.4060	0.5036	0.3748	0.9922
N = 32	0.4476	0.2322	0.4057	0.4492	0.2314	0.5001
N=64	0.4234	0.1552	0.4005	0.4227	0.1546	-0.3205
<i>p</i> = 64, <i>q</i>	$=1, V(\mathbf{\Sigma})=0.4$	4				
N = 8	0.6027	0.6206	0.4227	0.6052	0.5988	0.2997
N=16	0.4946	0.3554	0.4061	0.5021	0.3631	1.4613
N = 32	0.4458	0.2255	0.4003	0.4445	0.2244	-0.4124
N=64	0.4225	0.1509	0.3986	0.4237	0.1546	0.5322
<i>p</i> = 256, <i>q</i>	$q=1, V(\mathbf{\Sigma})=0$	0.4				
N = 8	0.6007	0.6151	0.4140	0.6076	0.6137	0.7995
N=16	0.4936	0.3526	0.4000	0.4873	0.3492	-1.2751
N = 32	0.4453	0.2239	0.4068	0.4465	0.2213	0.3813
N=64	0.4223	0.1499	0.4003	0.4234	0.1505	0.5054
<i>p</i> = 1024,	$q=1, V(\mathbf{\Sigma})=$	0.4				
N = 8	0.6002	0.6138	0.3961	0.5940	0.6361	-0.6814
N=16	0.4934	0.3519	0.4015	0.4977	0.3638	0.8432
N = 32	0.4452	0.2235	0.4037	0.4489	0.2304	1.1498
N=64	0.4222	0.1496	0.4020	0.4240	0.1526	0.8140
<i>p</i> = 2, <i>q</i> =	$= 1, V(\mathbf{\Sigma}) = 0.8$					
N = 8	1.0857	1.2651	0.6587	1.0792	1.3030	-0.3520
N = 16	0.9333	0.7343	0.7440	0.9364	0.7250	0.3003
N = 32	0.8645	0.4698	0.7732	0.8675	0.4675	0.4571
N=64	0.8317	0.3157	0.7840	0.8333	0.3172	0.3574

Table 1 (continued)

	$E[V(\mathbf{S})]$	SD[V(S)]	Median	Mean	ESD	Т		
$p = 4, q = 1, V(\Sigma) = 0.8$								
N = 8	1.0714	1.2182	0.6903	1.0730	1.2081	0.0917		
N=16	0.9267	0.7096	0.7454	0.9328	0.7139	0.6117		
N=32	0.8613	0.4549	0.7682	0.8585	0.4565	-0.4368		
N=64	0.8302	0.3061	0.7903	0.8350	0.3069	1.1137		
<i>p</i> = 16, <i>q</i>	$= 1, V(\Sigma) = 0.8$							
N = 8	1.0607	1.1840	0.6778	1.0687	1.1804	0.4765		
N=16	0.9217	0.6917	0.7517	0.9147	0.6842	-0.7221		
N=32	0.8589	0.4442	0.7847	0.8683	0.4387	1.5248		
N=64	0.8290	0.2992	0.7925	0.8358	0.3067	1.5855		
<i>p</i> = 64, <i>q</i>	$=1, V(\mathbf{\Sigma})=0.8$							
N = 8	1.0580	1.1756	0.6979	1.0755	1.2081	1.0231		
N=16	0.9204	0.6873	0.7463	0.9304	0.7024	1.0083		
N = 32	0.8583	0.4415	0.7643	0.8495	0.4352	-1.4315		
N = 64	0.8287	0.2975	0.7873	0.8292	0.2977	0.1296		
<i>p</i> = 256, <i>q</i>	$q=1, V(\mathbf{\Sigma})=0.$	8						
N = 8	1.0574	1.1735	0.6982	1.0818	1.1935	1.4492		
N=16	0.9201	0.6862	0.7373	0.9122	0.6746	-0.8321		
N = 32	0.8581	0.4409	0.7749	0.8663	0.4540	1.2689		
N=64	0.8286	0.2971	0.7824	0.8219	0.2873	-1.6582		
<i>p</i> = 1024,	$q=1, V(\mathbf{\Sigma})=0$	0.8						
N = 8	1.0572	1.1729	0.6881	1.0573	1.1723	0.0072		
N=16	0.9200	0.6859	0.7655	0.9344	0.6943	1.4624		
N=32	0.8581	0.4407	0.7709	0.8531	0.4414	-0.7945		

Table 1 (continued)

	E[V(S)]	SD[<i>V</i> (S)]	Median	Mean	ESD	Т
N = 64	0.8286	0.2969	0.7840	0.8292	0.2987	0.1364

1506

1507	Table 2. Summary statistics of selected simulation results for relative eigenvalue variance of
1508	covariance matrix $V_{rel}(\mathbf{S})$. (Approximate) theoretical expectation (E[$V_{rel}(\mathbf{S})$]) and standard
1509	deviation (SD[$V_{rel}(\mathbf{S})$]), as well as empirical median, mean, standard deviation (ESD), and
1510	bias of mean in standard error unit (T) from 5000 simulation runs are shown for selected
1511	conditions. See Table 1 for further information and Table S2 for full results.

	$\approx \mathrm{E}[V_{\mathrm{rel}}(\mathbf{S})]$	\approx SD[$V_{rel}(\mathbf{S})$]	Median	Mean	ESD	Т
$p = 2, V_{\rm r}$	$r_{\rm el}(\mathbf{\Sigma}) = 0$					
N = 8	0.2500	0.1936	0.2079	0.2514	0.1924	0.4961
N=16	0.1250	0.1102	0.0953	0.1259	0.1098	0.6000
N = 32	0.0625	0.0587	0.0448	0.0628	0.0597	0.3234
<i>N</i> = 64	0.0313	0.0303	0.0224	0.0309	0.0289	-0.8301
$p=4, V_{\rm r}$	$r_{\rm el}(\mathbf{\Sigma}) = 0$					
N = 8	0.2000	0.0840	0.1856	0.2002	0.0858	0.1644
N=16	0.0968	0.0433	0.0907	0.0968	0.0434	0.0620
N=32	0.0476	0.0219	0.0438	0.0474	0.0221	-0.6146
<i>N</i> = 64	0.0236	0.0110	0.0218	0.0237	0.0110	0.6544
<i>p</i> = 16, V	$V_{\rm rel}(\mathbf{\Sigma}) = 0$					
N = 8	0.1579	0.0193	0.1562	0.1580	0.0197	0.3764
N=16	0.0744	0.0091	0.0738	0.0746	0.0094	1.4158
N = 32	0.0361	0.0044	0.0357	0.0361	0.0044	-1.2604
<i>N</i> =64	0.0178	0.0022	0.0177	0.0178	0.0022	0.4338
<i>p</i> = 64, V	$V_{\rm rel}(\mathbf{\Sigma}) = 0$					
N = 8	0.1467	0.0047	0.1462	0.1466	0.0046	-0.6909
N=16	0.0686	0.0022	0.0685	0.0686	0.0022	0.5618

Table 2 (continued)

	$\approx \mathrm{E}[V_{\mathrm{rel}}(\mathbf{S})]$	\approx SD[$V_{\rm rel}(\mathbf{S})$]	Median	Mean	ESD	Т				
N = 32	0.0332	0.0010	0.0332	0.0332	0.0011	0.0446				
N = 64	0.0164	0.0005	0.0163	0.0164	0.0005	-0.5869				
<i>p</i> = 256,	$p = 256, V_{\rm rel}(\mathbf{\Sigma}) = 0$									
N = 8	0.1438	0.0012	0.1437	0.1438	0.0012	-0.0173				
N=16	0.0672	0.0005	0.0671	0.0672	0.0005	1.4545				
N = 32	0.0325	0.0003	0.0325	0.0325	0.0003	-0.7481				
N=64	0.0160	0.0001	0.0160	0.0160	0.0001	0.3608				
<i>p</i> = 1024	$4, V_{\rm rel}(\mathbf{\Sigma}) = 0$									
N = 8	0.1431	0.0003	0.1431	0.1431	0.0003	-0.5105				
N=16	0.0668	0.0001	0.0668	0.0668	0.0001	0.0231				
N = 32	0.0323	0.0001	0.0323	0.0323	0.0001	-1.3055				
N = 64	0.0159	0.0000	0.0159	0.0159	0.0000	-0.0022				
<i>p</i> = 2, <i>q</i>	$=1, V_{\rm rel}(\mathbf{\Sigma})=0.$.4								
N = 8	0.4377	0.2825	0.4939	0.4804	0.2334	12.9356				
N=16	0.4232	0.1982	0.4457	0.4384	0.1764	6.0670				
N = 32	0.4132	0.1378	0.4169	0.4152	0.1297	1.1224				
N=64	0.4070	0.0963	0.4108	0.4083	0.0945	0.9214				
<i>p</i> = 4, <i>q</i>	$=1, V_{\rm rel}(\mathbf{\Sigma})=0.$.4								
N = 8	0.4319	0.2065	0.4730	0.4675	0.1658	15.1734				
N=16	0.4200	0.1444	0.4316	0.4288	0.1272	4.8902				
N = 32	0.4113	0.1001	0.4147	0.4125	0.0944	0.9058				
N = 64	0.4060	0.0699	0.4073	0.4067	0.0682	0.7503				
<i>p</i> = 16, <i>q</i>	$q = 1, V_{\rm rel}(\mathbf{\Sigma}) = 0$	0.4								
N = 8	0.4275	0.1691	0.4657	0.4626	0.1346	18.4219				

Table 2 (continued)

	$\approx \mathrm{E}[V_{\mathrm{rel}}(\mathbf{S})]$	\approx SD[$V_{rel}(\mathbf{S})$]	Median	Mean	ESD	Т
N=16	0.4174	0.1175	0.4302	0.4270	0.1049	6.4710
N = 32	0.4098	0.0813	0.4161	0.4129	0.0762	2.8682
N = 64	0.4052	0.0566	0.4070	0.4058	0.0548	0.7118
p = 64, q	$y = 1, V_{\rm rel}(\mathbf{\Sigma}) = 0$	0.4				
N = 8	0.4264	0.1613	0.4670	0.4599	0.1273	18.6017
N = 16	0.4168	0.1119	0.4286	0.4266	0.0996	6.9651
N = 32	0.4095	0.0773	0.4125	0.4109	0.0726	1.3497
N=64	0.4050	0.0538	0.4063	0.4056	0.0532	0.7287
<i>p</i> = 256,	$q = 1, V_{\rm rel}(\mathbf{\Sigma}) =$	0.4				
N = 8	0.4261	0.1594	0.4637	0.4606	0.1249	19.5222
N=16	0.4166	0.1105	0.4262	0.4228	0.0977	4.4222
N = 32	0.4094	0.0763	0.4148	0.4120	0.0718	2.5791
N=64	0.4050	0.0531	0.4066	0.4058	0.0520	1.1405
<i>p</i> = 1024	$\mathbf{I}, q = 1, V_{\text{rel}}(\mathbf{\Sigma})$	= 0.4				
N = 8	0.4261	0.1590	0.4566	0.4548	0.1261	16.1041
N=16	0.4166	0.1102	0.4272	0.4246	0.0990	5.7314
N = 32	0.4094	0.0761	0.4140	0.4123	0.0718	2.8690
N=64	0.4050	0.0530	0.4068	0.4058	0.0521	1.1494
<i>p</i> = 2, <i>q</i>	$= 1, V_{\rm rel}(\mathbf{\Sigma}) = 0.$	8				
N = 8	0.7847	0.1153	0.8314	0.7947	0.1473	4.8016
N=16	0.7929	0.0866	0.8164	0.7963	0.1004	2.4327
N = 32	0.7969	0.0625	0.8090	0.7990	0.0672	2.2207
N=64	0.7986	0.0445	0.8030	0.7983	0.0470	-0.3966

 $p = 4, q = 1, V_{rel}(\Sigma) = 0.8$

Table 2 (continued)

	$\approx \mathrm{E}[V_{\mathrm{rel}}(\mathbf{S})]$	\approx SD[$V_{\rm rel}(\mathbf{S})$]	Median	Mean	ESD	Т		
N = 8	0.7841	0.0920	0.8207	0.7927	0.1170	5.1526		
N=16	0.7927	0.0692	0.8086	0.7945	0.0793	1.6175		
N=32	0.7968	0.0498	0.8039	0.7967	0.0537	-0.1966		
N=64	0.7985	0.0354	0.8026	0.7993	0.0368	1.5352		
<i>p</i> = 16, <i>q</i>	$p = 16, q = 1, V_{rel}(\mathbf{\Sigma}) = 0.8$							
N = 8	0.7838	0.0810	0.8153	0.7913	0.1049	5.0688		
N=16	0.7926	0.0609	0.8067	0.7943	0.0696	1.7415		
N = 32	0.7968	0.0437	0.8044	0.7989	0.0452	3.3474		
N = 64	0.7985	0.0310	0.8019	0.7990	0.0323	1.0675		
<i>p</i> = 64, <i>q</i>	$\gamma = 1, V_{\rm rel}(\mathbf{\Sigma}) = 1$	0.8						
N = 8	0.7837	0.0787	0.8157	0.7915	0.1022	5.4258		
N=16	0.7926	0.0592	0.8072	0.7956	0.0669	3.2349		
N=32	0.7967	0.0425	0.8021	0.7967	0.0447	-0.0106		
N = 64	0.7985	0.0301	0.8018	0.7989	0.0308	0.8231		
<i>p</i> = 256,	$q = 1, V_{\rm rel}(\mathbf{\Sigma}) =$	= 0.8						
N = 8	0.7836	0.0781	0.8150	0.7930	0.0994	6.6508		
N=16	0.7926	0.0588	0.8058	0.7944	0.0663	1.9392		
N=32	0.7967	0.0422	0.8033	0.7976	0.0455	1.3138		
N = 64	0.7985	0.0299	0.8010	0.7983	0.0303	-0.5863		
$p = 1024, q = 1, V_{rel}(\Sigma) = 0.8$								
N = 8	0.7836	0.0780	0.8140	0.7904	0.1011	4.7652		
N=16	0.7926	0.0587	0.8081	0.7959	0.0665	3.5530		
N = 32	0.7967	0.0421	0.8026	0.7967	0.0448	-0.0218		
N = 64	0.7985	0.0299	0.8012	0.7987	0.0307	0.4338		

1513	Table 3. Summary statistics of selected simulation results for relative eigenvalue variance of
1514	correlation matrix $V_{rel}(\mathbf{R})$. Theoretical expectation (E[$V_{rel}(\mathbf{R})$]) and (approximate) standard
1515	deviation (SD[$V_{rel}(\mathbf{R})$]), as well as empirical median, mean, standard deviation (ESD), and
1516	bias of mean in standard error unit (T) from 5000 simulation runs are shown for selected
1517	conditions. See Table 1 for further information and Table S3 for full results.

	$E[V_{rel}(\mathbf{R})]$	\approx SD[$V_{\rm rel}(\mathbf{R})$]	Median	Mean	ESD	Т		
$p = 2, V_{rel}(\mathbf{P}) = 0$								
N = 8	0.1429	0.1650	0.0792	0.1429	0.1635	0.0363		
N=16	0.0667	0.0856	0.0336	0.0679	0.0862	1.0235		
N=32	0.0323	0.0435	0.0163	0.0326	0.0427	0.6113		
N = 64	0.0159	0.0219	0.0075	0.0156	0.0205	-1.0380		
$p = 4, V_{\rm re}$	$el(\mathbf{P}) = 0$							
N = 8	0.1429	0.0673	0.1332	0.1432	0.0673	0.3148		
N=16	0.0667	0.0349	0.0608	0.0661	0.0344	-1.0696		
N = 32	0.0323	0.0178	0.0292	0.0321	0.0175	-0.6906		
N=64	0.0159	0.0090	0.0142	0.0157	0.0087	-1.0749		
<i>p</i> = 16, <i>V</i>	$V_{\rm rel}(\mathbf{P}) = 0$							
N = 8	0.1429	0.0151	0.1411	0.1428	0.0151	-0.0917		
N=16	0.0667	0.0078	0.0663	0.0669	0.0080	1.7743		
N=32	0.0323	0.0040	0.0319	0.0322	0.0039	-1.7517		
N=64	0.0159	0.0020	0.0158	0.0159	0.0020	0.7127		
p = 64, V	$p = 64, V_{rel}(\mathbf{P}) = 0$							
N = 8	0.1429	0.0037	0.1425	0.1428	0.0036	-0.4617		
N=16	0.0667	0.0019	0.0666	0.0667	0.0019	0.4407		

	$E[V_{rel}(\mathbf{R})]$	\approx SD[$V_{\rm rel}(\mathbf{R})$]	Median	Mean	ESD	Т	
N = 32	0.0323	0.0010	0.0322	0.0323	0.0010	-0.0725	
N = 64	0.0159	0.0005	0.0159	0.0159	0.0005	-0.6525	
$p = 256, V_{rel}(\mathbf{P}) = 0$							
N = 8	0.1429	0.0009	0.1428	0.1429	0.0009	0.0105	
N=16	0.0667	0.0005	0.0667	0.0667	0.0005	1.8676	
N = 32	0.0323	0.0002	0.0323	0.0323	0.0002	-0.9701	
N = 64	0.0159	0.0001	0.0159	0.0159	0.0001	0.3244	
$p = 1024, V_{rel}(\mathbf{P}) = 0$							
N = 8	0.1429	0.0002	0.1428	0.1429	0.0002	-0.9639	
N=16	0.0667	0.0001	0.0667	0.0667	0.0001	0.5220	
N = 32	0.0323	0.0001	0.0323	0.0323	0.0001	-1.8393	
N=64	0.0159	0.0000	0.0159	0.0159	0.0000	-0.0357	
<i>p</i> = 2, <i>q</i> =	$=1, V_{\rm rel}(\mathbf{P})=0$).4					
N = 8	0.4318	0.2495	0.4362	0.4294	0.2516	-0.6571	
N=16	0.4111	0.1844	0.4230	0.4147	0.1832	1.3640	
N = 32	0.4046	0.1326	0.4056	0.4041	0.1322	-0.2806	
N=64	0.4021	0.0944	0.4058	0.4025	0.0954	0.3294	
<i>p</i> = 4, <i>q</i> =	$=1, V_{\rm rel}(\mathbf{P})=0$).4					
N = 8	0.4318	0.2078	0.4314	0.4287	0.1750	-1.2271	
N=16	0.4111	0.1420	0.4141	0.4093	0.1317	-0.9769	
N = 32	0.4046	0.0988	0.4054	0.4034	0.0960	-0.8743	
N=64	0.4021	0.0693	0.4033	0.4022	0.0687	0.1270	
$p = 16, q = 1, V_{rel}(\mathbf{P}) = 0.4$							
N = 8	0.4318	0.1682	0.4321	0.4329	0.1391	0.5780	

	$E[V_{rel}(\mathbf{R})]$	\approx SD[$V_{\rm rel}(\mathbf{R})$]	Median	Mean	ESD	Т		
N=16	0.4111	0.1149	0.4149	0.4120	0.1073	0.5980		
N = 32	0.4046	0.0799	0.4084	0.4055	0.0773	0.7996		
N = 64	0.4021	0.0561	0.4030	0.4021	0.0552	-0.0283		
$p = 64, q = 1, V_{rel}(\mathbf{P}) = 0.4$								
N = 8	0.4318	0.1598	0.4366	0.4332	0.1304	0.7802		
N=16	0.4111	0.1092	0.4144	0.4129	0.1015	1.2079		
N = 32	0.4046	0.0760	0.4052	0.4039	0.0733	-0.6457		
N=64	0.4021	0.0533	0.4029	0.4021	0.0535	0.0493		
<i>p</i> = 256,	$q=1, V_{\rm rel}(\mathbf{P})=$	= 0.4						
N = 8	0.4318	0.1578	0.4348	0.4343	0.1278	1.3865		
N=16	0.4111	0.1078	0.4118	0.4091	0.0995	-1.4526		
N = 32	0.4046	0.0750	0.4078	0.4052	0.0726	0.5664		
N=64	0.4021	0.0526	0.4033	0.4024	0.0522	0.4500		
<i>p</i> = 1024	$, q = 1, V_{\rm rel}(\mathbf{P})$) = 0.4						
N = 8	0.4318	0.1573	0.4266	0.4286	0.1287	-1.7550		
N=16	0.4111	0.1075	0.4127	0.4111	0.1008	-0.0454		
N = 32	0.4046	0.0748	0.4072	0.4055	0.0726	0.8769		
N=64	0.4021	0.0524	0.4035	0.4024	0.0524	0.4578		
$p = 2, q = 1, V_{rel}(\mathbf{P}) = 0.8$								
N = 8	0.7831	0.1596	0.8250	0.7853	0.1571	0.9790		
N=16	0.7918	0.1015	0.8141	0.7928	0.1033	0.6253		
N=32	0.7961	0.0674	0.8076	0.7976	0.0680	1.5536		
N = 64	0.7981	0.0462	0.8024	0.7976	0.0473	-0.6617		
$n = 4$ $q = 1$ $V_{1}(\mathbf{P}) = 0.8$								

 $p = 4, q = 1, V_{rel}(\mathbf{P}) = 0.8$

	$E[V_{rel}(\mathbf{R})]$	\approx SD[$V_{\rm rel}(\mathbf{R})$]	Median	Mean	ESD	Т	
N = 8	0.7831	0.1073	0.8149	0.7840	0.1249	0.4605	
N=16	0.7918	0.0733	0.8059	0.7913	0.0815	-0.4682	
N = 32	0.7961	0.0510	0.8027	0.7953	0.0543	-1.0173	
N=64	0.7981	0.0358	0.8019	0.7987	0.0370	1.2077	
$p = 16, q = 1, V_{rel}(\mathbf{P}) = 0.8$							
N = 8	0.7831	0.0939	0.8102	0.7835	0.1116	0.2370	
N=16	0.7918	0.0642	0.8045	0.7913	0.0716	-0.5326	
N = 32	0.7961	0.0446	0.8035	0.7976	0.0457	2.4043	
N=64	0.7981	0.0313	0.8013	0.7984	0.0325	0.7108	
p = 64, q	$= 1, V_{rel}(\mathbf{P}) =$	0.8					
N = 8	0.7831	0.0912	0.8098	0.7841	0.1083	0.6205	
N=16	0.7918	0.0623	0.8046	0.7928	0.0687	0.9579	
N = 32	0.7961	0.0433	0.8009	0.7955	0.0452	-0.9741	
N = 64	0.7981	0.0304	0.8012	0.7983	0.0309	0.4419	
<i>p</i> = 256,	$q=1, V_{\rm rel}(\mathbf{P})$	= 0.8					
N = 8	0.7831	0.0905	0.8098	0.7857	0.1056	1.7052	
N=16	0.7918	0.0618	0.8031	0.7915	0.0681	-0.3408	
N=32	0.7961	0.0430	0.8022	0.7963	0.0460	0.3738	
N=64	0.7981	0.0302	0.8004	0.7977	0.0305	-0.9565	
$p = 1024, q = 1, V_{rel}(\mathbf{P}) = 0.8$							
N = 8	0.7831	0.0903	0.8088	0.7830	0.1074	-0.0831	
N=16	0.7918	0.0617	0.8057	0.7930	0.0683	1.2443	
N = 32	0.7961	0.0429	0.8014	0.7954	0.0454	-0.9758	
N=64	0.7981	0.0301	0.8006	0.7981	0.0308	0.0710	

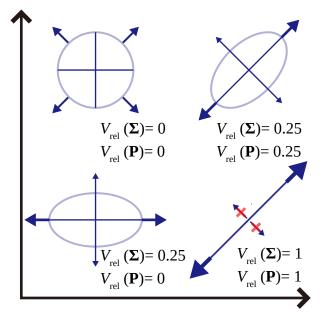


Figure 1. Schematic illustration of eigenvalue dispersion indices in bivariate cases. Ellipses representing equiprobability contours are shown on the Cartesian space of two hypothetical variables for four conditions, as well as the relative eigenvalue variance of the corresponding covariance and correlation matrices ($V_{rel}(\Sigma)$ and $V_{rel}(\mathbf{P})$, respectively). The scale is arbitrary but identical for the two axes. The axes of each ellipse are proportional to square roots of the two eigenvalues of the respective covariance matrix. $V_{rel}(\Sigma)$ represents eccentricity of variation and is sensitive to differing scale changes between axes but not to rotation (change of eigenvectors), whereas $V_{rel}(\mathbf{P})$ represents magnitude of correlation and is insensitive to scale changes. Arrows schematically represent variation along major axes (whose directions are arbitrary when $V_{rel}(\Sigma) = 0$).

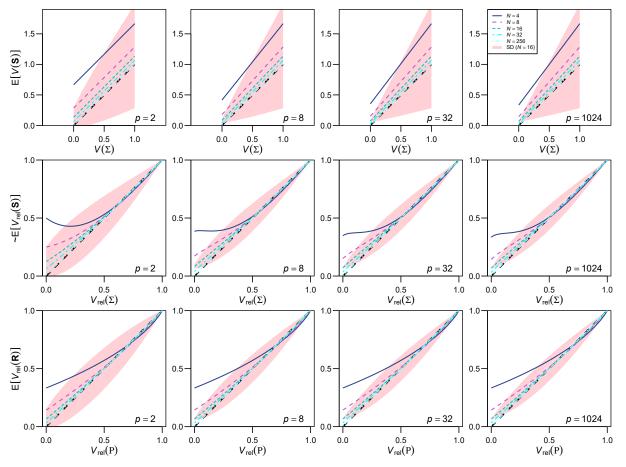


Figure 2. Profiles of the expectations of eigenvalue dispersion measures in selected conditions. The expectations of $V(\mathbf{S})$ (top row), $V_{\text{rel}}(\mathbf{S})$ (approximate; middle row), and $V_{\text{rel}}(\mathbf{R})$ (bottom row) are drawn with solid lines, for p = 2, 8, 32, and 1024 (from left to right) and for N = 4, 8, 16, 32, and 256 (from top to bottom on the left end of each box). In all cases, n = N - 1. The breadth of one standard deviation at N = 16 is also shown around the mean profiles with pink fills; these are approximations for $V_{\text{rel}}(\mathbf{S})$ and for $V_{\text{rel}}(\mathbf{R})$ with p > 2 (exact for $V_{\text{rel}}(\mathbf{R})$ with p = 2). Note that actual distributions might be skewed unlike these fills. There are generally many suites of eigenvalues corresponding to a single value of V_{rel} , and $E[V_{\text{rel}}(\mathbf{R})]$ can also depend on eigenvector configurations; the profiles shown here are from such eigenvalue configurations that there is one large eigenvalue, with the rest being equally small, in which case $E[V_{\text{rel}}(\mathbf{R})]$ does not depend on eigenvector configurations. The population covariance matrix Σ is scaled so that tr(Σ) = $p(p - 1)^{-1/2}$. The initial decrease of the $E[V_{\text{rel}}(\mathbf{S})]$ profiles in some cases seems to be an artifact of approximation. See text for further technical details.

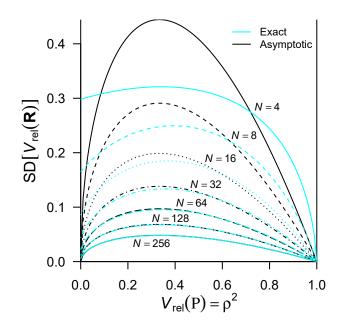


Figure 3. Comparison of exact and asymptotic standard deviations of $V_{rel}(\mathbf{R})$. Profiles of the exact (cyan lines) and asymptotic (black lines) standard deviations for p = 2 are shown across the entire range of the population value $V_{rel}(\mathbf{P})$, for N = 4, 8, 16, 32, 64, 128, and 256 (from top to bottom as labeled; shown with different line styles). Note that the asymptotic profiles converge to 0 when $V_{rel}(\mathbf{P}) = 0$.

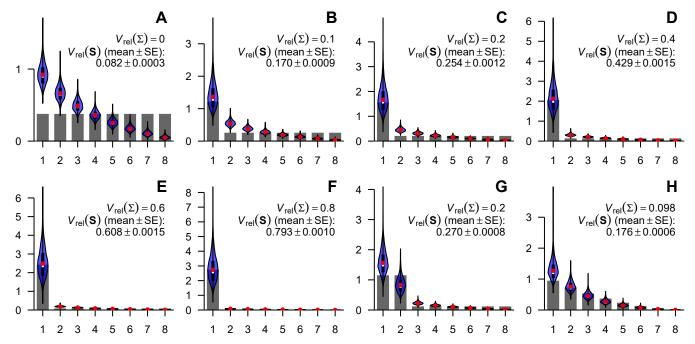


Figure 4. Selected population eigenvalue structures used in simulations and distributions of sample eigenvalues, examples for p = 8. The eigenvalues of population covariance matrix are shown as scree plots, and distributions of sample eigenvalues with N = 16 are shown as violin plots. A, null condition; **B–G**, *q*-large λ conditions, q = 1 (**B–F**) or 2 (**G**), with $V_{rel}(\Sigma) = 0.1, 0.2, 0.4, 0.6, 0.8,$ and 0.2, respectively; **H**, quadratically decreasing λ condition. Red dots denote empirical means of sample eigenvalues, whereas white bars (mostly overlapping with red dots) denote medians. Thick black bars within violins denote interquartile ranges. Note different scales of vertical axes.

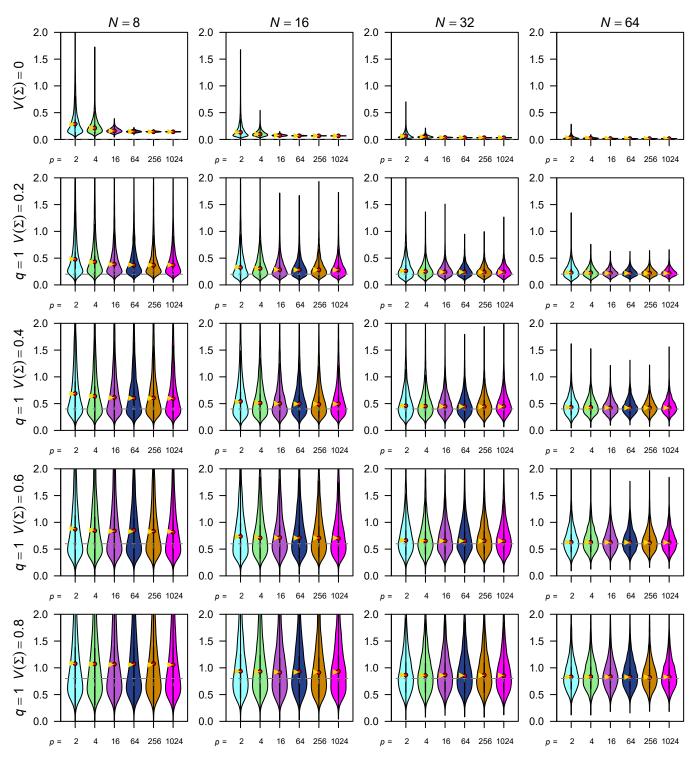


Figure 5. Selected results of simulation for the eigenvalue variance of covariance matrix V(S). Empirical distributions of simulated V(S) values are shown as violin plots, whose tails extend to the extreme values. Red dots denote empirical means, whereas yellow triangles denote expectations (which are exact). Thick black bars within violins denote interquartile ranges, with white bars near the center (in most cases overlapping with red dots) denote medians. Rows of panels correspond to varying population values of $V(\Sigma)$ (under 1-large λ conditions), whereas columns correspond to varying sample size *N*. Columns within each panel correspond to varying number of variables *p*. Note that extreme values in some panels are cropped for visual clarity. See Figure S2–S4 for full results.

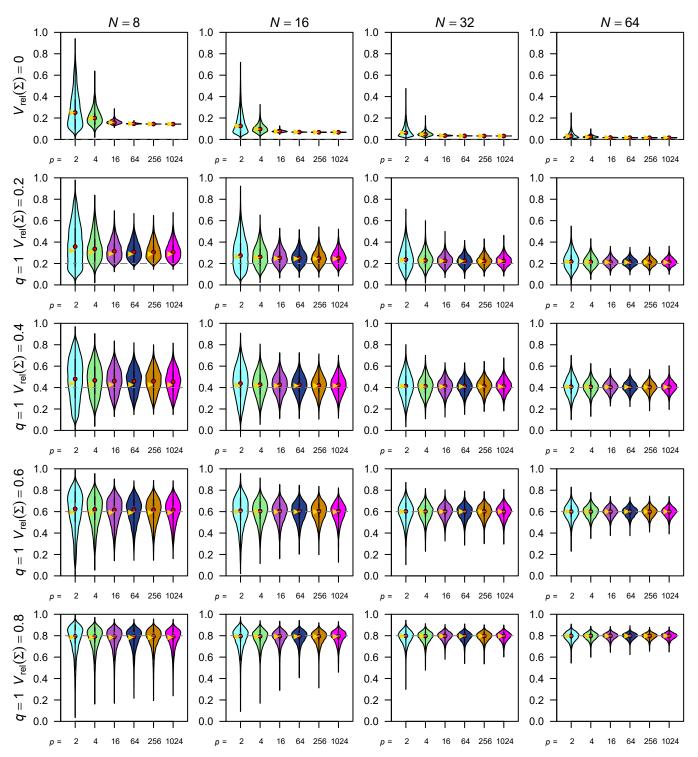


Figure 6. Selected results of simulation for the relative eigenvalue variance of covariance matrix $V_{rel}(S)$. Empirical distributions of simulated $V_{rel}(S)$ values are shown as violin plots. Yellow triangles denote expectations (which are approximate except under the null condition). Rows of panels correspond to varying population values of $V_{rel}(\Sigma)$ (under 1-large λ conditions). Other legends are as in Fig. 5. See Figure S4–S6 for full results.

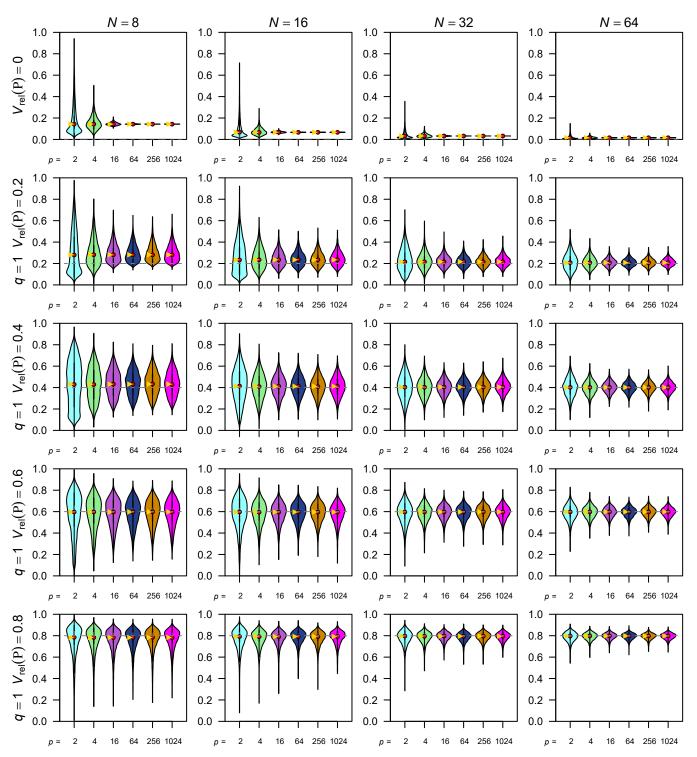


Figure 7. Selected results of simulation for the relative eigenvalue variance of correlation matrix $V_{rel}(\mathbf{R})$. Empirical distributions of simulated $V_{rel}(\mathbf{R})$ values are shown as violin plots. Yellow triangles denote expectations (which are exact). Rows of panels correspond to varying population values of $V_{rel}(\mathbf{P})$ (under 1-large λ conditions). Other legends are as in Fig. 5. See Figure S4, S7, and S8 for full results.