Residual errors in visuomotor adaptation persist despite extended motor preparation periods

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Running Head: Visuomotor errors persist despite extended motor preparation

Abstract

A consistent finding in sensorimotor adaptation is a persistent undershoot of full
compensation, such that performance asymptotes with residual errors greater than seen at
baseline. This behaviour has been attributed to limiting factors within the implicit
adaptation system, which reaches a sub-optimal equilibrium between trial-by-trial learning
and forgetting. However, recent research has suggested that allowing longer motor
planning periods prior to movement eliminates these residual errors. The additional
planning time allows required cognitive processes to be completed before movement onset,
thus increasing accuracy. Here we looked to extend these findings by investigating the
relationship between increased motor preparation time and the size of imposed visuomotor
rotation (30°, 45° or 60°), with regards to the final asymptotic level of adaptation. We found
that restricting preparation time to 0.35 seconds impaired adaptation for moderate and
larger rotations, resulting in larger residual errors compared to groups with additional
preparation time. However, we found that even extended preparation time failed to
eliminate persistent errors, regardless of magnitude of cursor rotation. Thus, the asymptote
of adaptation was significantly less than the degree of imposed rotation, for all
experimental groups. Additionally, there was a positive relationship between asymptotic
error and implicit retention. These data suggest that a prolonged motor preparation period
is insufficient to reliably achieve complete adaptation and therefore our results provide
support for the proposal that limitations within the implicit learning system contributes to
asymptotic adaptation levels.

Key Words: Sensorimotor Adaptation; Motor Preparation; Mental Rotation

New & Noteworthy: Residual errors in sensorimotor adaptation are commonly
attributed to an equilibrium between trial-by-trial learning and forgetting. Recent research
suggested that allowing sufficient time for mental rotation eliminates these errors. In a
number of experimental conditions, we show that while restricted motor preparation time
does limit adaptation - consistent with mental rotation - extending preparation time fails to
eliminate the residual errors in motor adaptation.

Introduction

Sensorimotor adaptation has been extensively studied using visuomotor rotations (Cunningham, 1989; Krakauer, Ghilardi, & Ghez, 1999; Krakauer, Pine, Ghilardi, & Ghez, 2000). In this task, individuals adapt reaching movements to counter visual feedback that is rotated, for example, 30° or 45° from the hand's position. However, adaptation is typically incomplete, and performance plateaus with errors a few degrees greater than at baseline, regardless of the rotation magnitude imposed (Fernandez-Ruiz, Wong, Armstrong, & Flanagan, 2011; Huberdeau, Haith, & Krakauer, 2015; van der Kooij, Brenner, van Beers, & Smeets, 2015; Vaswani et al., 2015; Weightman, Brittain, Punt, Miall, & Jenkinson, 2020; Langsdorf, Maresch, Hegele, McDougle, & Schween, 2021). State-space models of learning accurately capture this incomplete compensation (Smith, Ghazizadeh, & Shadmehr, 2006; Kording, Tenenbaum, & Shadmehr, 2007). In these models, error-driven learning and forgetting (or a reversion to baseline) work in opposition, and equilibrate below optimal performance, resulting in the commonly observed persistent error.

However, Vaswani and colleagues (2015) demonstrated that under certain conditions, individuals disengage from this limited error-dependent learning to attain greater task success. In one of their experimental conditions, Vaswani et al. (2015) 'clamped' visual feedback after an initial learning block, such that a small, fixed, visual error was presented, regardless of movement accuracy. They found that under these conditions, participants appeared to select an alternative, more exploratory learning policy, which enabled them to close the errors and even to overcompensate for the rotation (which differed from the partial reversion to baseline predicted by the state-space model). The authors suggested that the altered feedback distribution triggered alternative learning processes (and enabled

the elimination of residual errors), which are usually suppressed during naturalistic feedback

conditions.

More recently, Langsdorf et al. (2021) presented an alternative theory to explain why

under normal, non-clamped environments, the central nervous system fails to eliminate

residual errors during motor adaptation. They suggested an intrinsic speed-accuracy trade-

off: where time consuming planning processes are interrupted by the imperative onset of

movement, resulting in fast, but inaccurate movements. In their study, they showed that

when an obligatory 2.5 second wait period was introduced between target presentation and

movement initiation, participants were able to fully adapt to a 45° rotation, leaving no

persisting errors at the end of learning. However, if this wait period was not enforced or was

introduced at the end of the movement, when no planning was assumed to be taking place,

participants failed to fully counteract the rotation. The authors highlighted mental rotation

as a time-consuming cognitive process potentially involved in the planning of visuomotor

adaptation.

For some time now, visuomotor adaptation has been framed as a combination of distinct

learning processes (Mazzoni & Krakauer, 2006; Taylor, Krakauer, & Ivry, 2014; Bond &

Taylor, 2015; McDougle, Bond, & Taylor, 2015; Voets, Panouilleres, & Jenkinson, 2020).

These processes are customarily described as implicit and explicit. The implicit component

adapts slowly and is driven by sensory prediction errors (Smith et al., 2006; Tseng,

Diedrichsen, Krakauer, Shadmehr, & Bastian, 2007). The explicit component is a fast

adaptation process and involves, among other processes, strategic re-aiming to counter the

detected perturbation (Taylor & Ivry, 2011; Heuer & Hegele, 2008; McDougle et al., 2015).

Such strategies are thought to include a form of metal rotation (McDougle & Taylor, 2019).

Langsdorf et al. (2021) suggest that under naturalistic feedback conditions, parametric

mental rotations from the target to the intended movement goal are prematurely

terminated (despite no time constraints) and result in aimed movement trajectories falling

short of the imposed rotation.

Behavioural and neurophysiological research suggests a role of mental rotation in the

planning of movements aimed at angles away from visually defined targets (Georgopoulos

& Massey, 1987; Bhat & Sanes, 1998; Georgopoulos, Lurito, Petrides, Schwartz, & Massey,

1989; Lurito, Georgakopoulos, & Georgopoulos, 1991; Pellizzer & Georgopoulos, 1993).

Neuronal population vectors recorded in the monkey motor cortex gradually rotate from a

stimulus direction to a cued movement direction during the planning of a reach

(Georgopoulos et al., 1989; Lurito et al., 1991). Additionally, the completion of mental

rotation tasks require long reaction times with larger magnitudes of rotation (Shepard &

Metzler, 1971; Georgopoulos & Massey, 1987); a signature of cognitive strategies

(Fernandez-Ruiz et al., 2011; Haith, Huberdeau, & Krakauer, 2015; McDougle & Taylor,

2019).

Given this knowledge, we aimed to replicate and extend the findings of Langsdorf et al.

(2021), in order to further understand the roles of extended planning periods and mental

rotation in attaining full adaptation. We designed an online visuomotor adaptation task,

where participants had either long (2.5 seconds), medium (1 second) or short (0.35 seconds)

enforced preparation periods between target presentation and movement onset, and were

required to adapt to either a small (30°), moderate (45°) or large (60°) visuomotor rotation.

Previous studies (Langsdorf et al., 2021) suggest that the 45° rotation would be fully

corrected with the longest preparation period; errors for the middle interval would be

greater; and a substantial residual error should be found for the shortest preparation

interval. This negative relationship between preparation interval and residual error should

be most obvious for the 60° rotation; the smallest rotation (30°) might allow full

compensation even at the shortest preparation interval. In other words, the response time

could be considered the sum of a mental rotation period linearly related to the rotation

magnitude, and a fixed movement initiation period; if the sum exceeds the prescribed

preparation interval, then residual errors should be seen.

Materials and Methods

Participants

A total of 200 participants were recruited via posters, study averts and through personal

contact (aged 18-37 years, mean ± SD = 22.4 ± 3.5 years, 89 males); all gave informed

consent before participating and either received no remuneration or received course credit

which counted towards their university degree mark. The study was approved by the

University of Birmingham ethics board (Science, Technology, Engineering and Mathematics

Ethical Review Committee). Participants were self-reported as right-handed (181) or left-

handed (19) and used their preferred hand to complete the task (all but 5 of the left-handed

participants completed the task using their right hand). All participants had normal, or

corrected to normal, vision and reported no history of neurological disease. Initially, 180

participants were pseudorandomised into one of nine experimental groups (each n = 20),

which differed in the amount of preparation time provided (0.35, 1 or 2.5 seconds) and the

magnitude of cursor rotation (30°, 45° or 60°). These participants formed the online arm of

the study (Table 1). To avoid any possible confounds relating to online data collection and

only after COVID-19 restrictions relating to in-person human testing were lifted, we also

collected data from an additional experimental group who completed the task in a

laboratory setting. Participants in this group experienced a 45° cursor rotation, with 2.5

seconds of preparation time (Table 1) - a closer replication of Langsdorf et al. (2021).

	0.35 seconds			1 second			2.5 seconds			
	30°	45°	60°	30°	45°	60°	30°	45°	45° (lab)	60°
N (n male)	20 (9)	20 (6)	20 (8)	20 (11)	20 (12)	20 (4)	20 (10)	20 (13)	20 (7)	20 (9)
Mean age (years, ± SD)	23.5 (± 2.0)	25.4 (± 3.4)	25.9 (± 3.4)	21.0 (± 1.1)	21.5 (± 3.7)	22.6 (± 5.0)	20.8 (± 1.3)	21.0 (± 1.6)	20.2 (± 1.8)	22.7 (± 3.7)

Table 1: *Summary of experimental groups.*

Task

Online

We developed a visuomotor adaptation task using the behavioural science experiment

platform: PsychoPy (Peirce et al., 2019), which was implemented online via Pavlovia

(https://pavlovia.org). Participants were required to have access to a desktop or laptop

computer with internet connection and a mouse or trackpad to navigate through and

complete the task (117/180 participants used a trackpad; 63/180 participants used a

mouse). Participants were sent a link to access the task and entered a unique code which

determined which combination of preparation time and rotation angle they would

encounter. Participants were asked to sit in a location of their choosing, so that they could

easily see their computer screen and comfortably reach and manipulate the mouse or

trackpad. They made centre-out movements with either their mouse or on their trackpad

from an on-screen central starting position to targets which appeared on an invisible

circular array surrounding it (Figure 1a). They were told to make one fast and straight

'shooting' movement, aiming to get the on-screen cursor as close as possible to the target.

Prior to starting the task, all participants completed a brief tutorial, which included the task

instructions and aims. At this point, participants were asked to contact a researcher if they

were unclear about any part of the task and/or had any questions relating to the

instructions.

<u>Laboratory</u>

Participants sat in an armless chair in front of a computer monitor (21.5 inch iMac, 60Hz

refresh rate) and used a trackpad (Apple Magic Trackpad) to control the onscreen cursor.

The trackpad measured 0.49-1.09 cm in height, 16 cm in width and 11.49 cm in depth and

was fixed to the desk next to the computer screen. Crucially, the participants received the

same instructions and completed the same tutorial before starting the task. The remaining

task parameters were exactly as the online paradigm. All 20 participants were right-handed

(self-report) and used their right hand to complete the task.

<u>Protocol</u>

At the beginning of every trial the cursor (red filled circle) would be located in the centre of

the screen (grey background). The cursor was surrounded by two larger red annuli, which

formed a bullseye-like formation (Figure 1b). At a set moment, the outer ring disappeared,

followed by the inner ring 0.5 seconds later, and the cursor then changed colour from red to

white after a further 0.5 seconds. Participants were told that this sequence of events should

be treated as a countdown to movement and that they should aim to time their movement

so that it was initiated in synchrony with the cursor changing colour from red to white

(Figure 1b). Depending on the experimental group, the target (green filled circle) would

appear either 2.5 seconds, 1 second or 0.35 seconds before the movement cue - thus

creating three distinct preparation periods. The target could appear at any one of eight

possible locations, equally spaced (separated by 45˚) around an invisible circular array

centred on the start position, and pseudorandomised so that the target appeared at each

location once every cycle of eight trials. The position at which the cursor passed the invisible

perimeter was displayed for 0.5 seconds as static open white circle, providing feedback of

movement accuracy. After an inter-trial interval of 0.5 seconds the cursor would reset to the

central position ready for the next trial. Participants were encouraged to move their hand

back to a comfortable starting position after each trial. All elements of the visual display

were scaled according to the size of the task window and thus were the same relative size

for all participants. Consequently, the physical movement size required varied between

participants depending on their set up and was not recorded beyond input device. If

participants attempted to move 0.15 seconds before or after the go cue, or if movement

time exceeded 0.25 seconds, the message "Response too fast/slow" appeared on the screen

and the trial was aborted. These measures were to encourage fast movements, initiated

correctly with the task instructions.

Figure 1: *The experimental design.* ***a:*** *Participants used either a mouse or trackpad to direct an on-screen cursor towards targets presented radially around a central starting position.* ***b:*** *An example of the cursor countdown sequence and movement cue. At the beginning of each trial the (red) cursor would appear in the centre of the screen, flanked by two larger (red) rings (shown here on the top row). During the trial the two rings would disappear in sequence and the cursor would change colour to white. Participants were required to initiate their movement in synchrony with the cursor colour change, using the disappearing rings as a countdown. The target (shown on the bottom row) would appear either 2.5, 1 or 0.35 seconds prior to the movement cue, depending on group assignment.* ***c:*** *Time course of the study protocol. Participants completed 40 baseline trials, followed by 280 adaptation trials (where either a 30°, 45° or 60° cursor rotation was imposed), then 40 no-feedback trials and finally 40 de-adaptation trials.*

Experimental Design

Participants first performed eight practice trials (one at each target location). These trials were performed with veridical cursor feedback and were used to familiarise the participants with the timing of their version of the task. The main task directly followed the practice trials and included four phases: baseline, adaptation, no-feedback and de-adaptation (Figure 1c). During baseline trials (n = 40) participants received veridical cursor feedback, such that

the on-screen cursor moved in accordance with participants' movements. Adaptation trials

immediately followed, in which the cursor feedback was rotated 30°, 45° or 60° clockwise

(depending on the experimental group, see below) relative to participants' movement. This

block lasted 280 trials, selected to ensure learning approached its asymptotic limit, based on

pilot data collected prior to the present study. While there is some indication that full

asymptotic saturation of learning was not achieved in all conditions, regression analysis of

the last 40 trials of adaptation indicated that there was no significant trend remaining (all p

> 0.19, with all slopes between 0.041 and -0.039) and thus we use the term 'asymptote' to

refer to the final state reached at the end of the 280 adaptation trials. Following adaptation

trials, participants performed no-feedback trials (n = 40). During these trials, participants

were told to stop using any strategies they might have employed to achieve the task

objectives and try to aim directly for the target. The cursor was hidden at all times during

the trial, apart from when located in the central position for the countdown cue. End-point

error was not displayed during the no-feedback phase. Veridical cursor feedback and display

of end-point error were then restored for the final de-adaptation trials (n = 40).

There were ten participant groups (Table 1), to cover all combinations of preparation time

(long: 2.5 seconds, medium: 1 second, short: 0.35 seconds) and the magnitude of cursor

rotation (large: 60°, moderate: 45°, small: 30°), with the 2.5 seconds/45° group repeated in

a laboratory setting. The preparation time was held constant throughout the whole task;

the rotation was applied only during the adaptation phase.

Data Analysis

There were three main outcome variables: reach angle, response time and movement

duration. Our primary dependent variable - reach angle - was the angular difference

between the target location and participants' movement at end-point (i.e., the difference in

angle between the vector linking the starting position and the target marker, and the vector

linking the starting position and the point at which participants' movement crossed the

target circle perimeter). Participants were excluded from analysis if they either failed to

follow task instructions (i.e., ignoring the rotated cursor and not adjusting their aiming

direction) or if they violated the timing limits of the task on four successive trials (indicating

a lack of concentration or distraction). 17 individuals were excluded based on this criterion

and were replaced with new participants in order to achieve the desired sample size. Trials

were deemed outliers and removed if they fell 2.5 standard deviations outside the group

average on each trial. A total of 1.23% of all trials were removed from further analysis. Data

from each participant were then averaged into bins of 4 trials to be used for visual

representation and statistical analysis. Response time was defined as the time period

between target presentation and movement onset (i.e., cursor movement breaking an

invisible line immediately surrounding the starting position) and movement duration was

defined as the time period between movement onset and when movement crossed the

target circle. Reach angle data was not recorded for trials where the response or movement

time limits were violated.

<u>Statistical Analysis</u>

Asymptotic levels of adaptation were defined as the mean error over the last 40 trials of the

adaptation phase and compared between groups in a two-way ANOVA (Rotation Magnitude

= 3 levels (30°/45°/60°) x Preparation Time = 3 levels (0.35 seconds/1 second/2.5 seconds)),

with any significant main effects or interactions followed up with Bonferrroni-corrected

multiple comparisons. Asymptotic differences from the imposed rotation magnitude were

compared using a Wilcoxon Signed Rank test, after data from some groups failed normality

checks (Shapiro-Wilk test). Mean reach angles across all baseline trials and during the first

16 no-feedback trials for each participant were used for baseline and retention

comparisons. Data from the laboratory group were processed and analysed separately from

the online data as this group was not factored into the original study design. In-lab data was

compared to its online counterpart using unpaired t-tests (two-tailed) and from the degree

of imposed rotation using a Wilcoxon Signed Rank test. All statistical analyses were carried

out in MATLAB (R2018b) and SPSS (IBM, version 27). All ANOVAs were run as general linear

models. The threshold for statistical significance was set at $p < 0.05$ and we report W, F, T

and p-values, as well as effect sizes from ANOVAs (partial eta squared (ηp^2)).

Results

Baseline performance does not differ between groups

Differences in reach angle during the baseline phase were assessed in a two-way ANOVA

(Rotation Magnitude x Preparation Time), which revealed no significant main effects for

Rotation Magnitude ($F_{(2, 171)} = 0.071$, $p = 0.93$, $\eta p^2 = 0.001$), Preparation Time ($F_{(2, 171)} =$

0.3, $p = 0.75$, $\eta p^2 = 0.003$), and no significant Rotation Magnitude*Preparation Time

interaction ($F_{(4, 171)} = 0.45$, $p = 0.77$, $\eta p^2 = 0.1$). This result suggests that all groups

performed similarly during baseline trials (Figure 2) and thus, group differences are unlikely

to influence performance later in the task. We felt this analysis important, given the limited

experimenter input associated with online research.

Figure 2: *Mean reach angle and response time for each of the online experimental groups.*
Top panel: Reach error (± standard error, shaded region) is averaged every four trials into
bins for (from left to right) the 30°, 45° and 60° groups, during baseline, adaptation (shaded
grey background), no feedback and de-adaptation trials (shaded grey background). Zero
degrees and the magnitude of imposed rotation are shown by horizontal dashed lines.
Bottom panel: Mean response time (time between target presentation and movement
initiation), ± standard error (shaded region) for each group. Note, preparation times were
predetermined at 0.35, 1 or 2.5 seconds (dotted lines) and were tightly controlled.

The effect of differing preparation time on asymptotic levels of adaptation

A two-way ANOVA comparing asymptotic levels of adaptation revealed significant main

effects for Rotation Magnitude ($F_{(2, 171)} = 121.01$, $p < 0.001$, $\eta p^2 = 0.59$), Preparation Time

($F_{(2, 171)} = 15.17$, $p < 0.001$, $\eta p^2 = 0.15$) and a significant Rotation Magnitude*Preparation

Time interaction ($F_{(4, 171)} = 5.24$, $p < 0.001$, $\eta p^2 = 0.11$). Multiple comparisons revealed

that in the 45° rotation group, there were some differences between learning asymptotes,

with regards to preparation time provided. The 0.35 second preparation time group

displayed impaired adaptation compared to the 1 and 2.5 second groups (both $p < 0.001$),

with no further differences between the latter two conditions ($p > 0.99$). However, contrary

to Langsdorf et al. (2021), all final levels of adaptation significantly differed from 45° (0.35

seconds: W = -210.0, p < 0.001, 95% CI = [-16.72, -11.32]; 1 second: W = -200.0, p < 0.001,

95% CI = [-9.71, -2.50]; 2.5 seconds: W = -210.0, p < 0.001, 95% CI = [-9.33, 3.18]). The 0.35

seconds preparation time group compensated 67.3% for the rotation, with the 1 and 2.5

second groups achieving 85.1% and 86.1% compensation respectively (Figures 2 & 3),

suggesting that additional preparation time allowed for greater compensation but not the

elimination of residual errors.

Similarly, for the 60° rotation condition, shortening planning time to 0.35 seconds

significantly reduced the final level of adaptation compared to both 1 and 2.5 second

preparation periods (0.35 seconds vs 1 second: p = 0.001, 0.35 seconds vs 2.5 seconds: p <

0.001). However, there was no difference between the 1 and 2.5 second groups with

respect to final adaptation levels (p = 0.17). Participants averaged 62.4% compensation with

0.35 seconds preparation time, 75.0% with 1 second preparation time and 81.7% with 2.5

seconds preparation time (Figures 2 & 3). Additionally, all asymptotic levels of adaptation

significantly differed from the imposed 60° rotation (0.35 seconds: W = -210, p < 0.001, 95%

CI = [-31.14, -16.02]; 1 second: W = -210.0, p < 0.001, 95% CI = [-16.27, -10.27]; 2.5 seconds:

W = -206.0, p < 0.001, 95% CI = [-16.76, -6.44]).

In the 30° rotation group, there were no differences in asymptotic error between any of

the different preparation time groups (all p > 0.99, Figure 2). Furthermore, all final levels of

adaptation differed significantly from 30° (0.35 seconds: W = −210.0, p < 0.001, 95% CI = [-

5.35, -2.39]; 1 second: W = -204.0, p < 0.001, 95% CI = [-6.87, -2.98]; 2.5 seconds: W = -

210.0, p < 0.001, 95% CI = [-8.09, -3.25]), with adaptation reaching 84.7%, 82.8% and 82.0%

of the optimum, respectively (Figure 3).

In summary, our results support previous work suggesting that mental rotation

contributes an interval to the planning process which is proportional to rotation magnitude,

and that short periods of preparation interrupt planning, leading the greater residual errors.

However, for the smallest rotation, we found no relationship between preparation time and

error, suggesting that mental rotation was completed within the allowed time. But even in

these circumstances, there were significant residual errors. In fact, in opposition to results

reported by Langsdorf et al. (2021), all groups displayed incomplete adaptation regardless

of the preparation time provided.

Figure 3: *The asymptotic levels of adaptation for each participant in each of the rotation*
magnitude and preparation time groups (online experiment). Filled circles represent the
adaptation asymptote for each participant (defined as the average of the last 40 adaptation
trials), with mean values and standard error depicted by horizontal and vertical lines
respectively. Dashed horizontal lines depict the imposed cursor rotation for each group.
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Restricting motor preparation time resulted in a stronger implicit retention

Implicit retention (mean reach angle in the first 16 no-feedback trials, two cycles of reaches

to each target location) was compared between groups in a two-way ANOVA (Rotation

Magnitude x Preparation Time). Results from the ANOVA revealed a significant main effect

of Rotation Magnitude ($F_{(2, 171)}$ = 6.71, p = 0.002, ηp^2 = 0.07) and Preparation Time ($F_{(2,}$

$_{171)}$ = 18.33, $p < 0.001$, ηp^2 = 0.18), but no significant interaction ($F_{(4, 171)}$ = 1.08, p = 0.37,

ηp^2 = 0.03). Multiple comparisons showed that participants in the restricted 0.35 second

motor preparation time groups displayed greater retention than both the 1 second ($p <$

0.001) and 2.5 second ($p < 0.001$) groups, with no differences between the latter two ($p >$

0.99).

Input device and handedness had no effect on late adaptation levels

In order to determine whether the input device used (trackpad or mouse), or the

handedness of the participant had any effect on our main outcome variable, reach angle, we

ran an additional mixed design ANOVA (Rotation Magnitude x Preparation Time) with

factors for both input device and handedness (online groups only). The ANOVA revealed no

significant main effect of Input Device ($F_{(1, 150)}$ = 0.9, p = 0.35, ηp^2 = 0.006) or Handedness

($F_{(1, 150)}$ = 1.12, p = 0.29, ηp^2 = 0.007). In fact, no interaction that included the term Input

Device revealed significance (Rotation Magnitude*Input Device: $F_{(2, 150)}$ = 0.36, p = 0.7,

ηp^2 = 0.005; Preparation Time*Input Device: $F_{(2, 150)}$ = 0.23, p = 0.79, ηp^2 = 0.003;

Rotation Magnitude*Preparation Time*Input Device: $F_{(4, 150)}$ = 0.3, p = 0.88, ηp^2 = 0.008;

Supplementary Figure 1, see https://doi.org/10.6084/m9.figshare.14797926). Similarly, all

interaction effects with Handedness were also non-significant (Rotation

Magnitude*Handedness: $F_{(2, 150)}$ = 1.55 p = 0.22, ηp^2 = 0.02; Preparation

Time*Handedness: $F_{(2, 150)}$ = 0.75, p = 0.48, ηp^2 = 0.01; Rotation Magnitude*Preparation

Time*Handedness: $F_{(2, 150)}$ = 0.12, p = 0.89, ηp^2 = 0.002). These analyses corroborate our

belief that neither the handedness of the participants, nor the input devices they used,

confound our results.

There were no differences in task performance between the online and in-laboratory

groups

To confirm the validity of our results collected using online methodology, we collected data

from an additional group of participants who performed the experiment in a laboratory with

2.5 seconds of preparation time and a 45° cursor rotation. Data from this additional in-lab

experimental group were compared the equivalent online group using unpaired t-tests

(two-tailed) and revealed no significant differences in baseline, asymptotic or retention

performance ($t(38) = 0.89$, $p = 0.38$; $t(38) = 0.35$, $p = 0.73$; $t(38) = 1.78$, $p = 0.084$,

respectively). Participants in this group compensated 87.2% for the rotation and

importantly, the final level of adaptation was also significantly different from 45° (W = -

196.0, $p < 0.001$, 95% CI = [-8.35, -3.1]), replicating the effect found consistently across our

online groups (Figure 4). We also found no differences in variance between the laboratory

and online groups in each of the experimental phases (F-tests: $F(19, 19) = 1.9$, $p = 0.17$; $F(19,$

$19) = 1.04$, $p = 0.93$; $F(19, 19) = 1.31$, $p = 0.56$).

Figure 4: *Mean reach angle, response time and learning asymptote for the in-laboratory experimental group. **a:** Reach error (± standard error, shaded region) is averaged every four trials into during baseline, adaptation (shaded grey background), no feedback and de-adaptation trials (shaded grey background) for each group. Zero degrees and the magnitude of imposed rotation are shown by horizontal dashed lines. **b:** The asymptotic level of adaptation for each participant. Filled circles represent the adaptation asymptote for each participant (defined as the average of the last 40 adaptation trials), with mean values and standard error depicted by horizontal and vertical lines respectively. Dashed horizontal lines depict the imposed cursor rotation. **c:** Mean response time (time between target presentation and movement initiation), ± standard error (shaded region). Preparation time was predetermined and tightly controlled at 2.5 seconds.*

Discussion

We aimed to test the assumption that increased motor preparation periods may allow for more complete adaptation during visuomotor rotation tasks. As such, we hypothesised that

shorter preparation periods would be sufficient to fully counteract a 30° rotation, as a small

rotation would require less (and therefore quicker) mental rotation before motor execution.

We then predicted that this effect would scale with an increased cursor rotation, so that 45°

and 60° would require greater mental rotation and thus more time to fully compensate.

Indeed, we did find that restricting planning time for moderate and larger rotations resulted

in impaired final adaptation levels and greater implicit retention compared to those groups

with more preparation time. However, contrary to research from Langsdorf et al. (2021), we

found no evidence to suggest that extended motor preparation periods allow for the

elimination of residual errors observed during late stages of adaptation, as all groups

displayed final adaptation performance significantly lower than the imposed cursor

rotation.

Hence, we failed to replicate the results from Langsdorf et al. (2021), who found

that enforcing a 2.5 second planning period between target presentation and reach onset

allowed individuals to fully counteract a 45° visuomotor rotation, leaving no residual mean

error at asymptote. The authors suggested that the extended planning period allowed for

time-consuming cognitive processes, such as mental rotation, to be completed prior to the

go-signal and resulted in complete compensation. This theory, centred around a speed-

accuracy trade-off, seems plausible given that reaction times increase in a linear fashion

when subjects are asked to reach at increasing angles from a target - a relationship that

mimics the behaviour seen in mental rotation tasks (Shepard & Metzler, 1971;

Georgopoulos & Massey, 1987; McDougle & Taylor, 2019). Accordingly, brain regions

activated in both visuomotor adaptation and mental rotation tasks have also been shown to

overlap (Anguera, Reuter-Lorenz, Willingham, & Seidler, 2010), suggesting that mental

rotation contributes to visuomotor adaptation. Recent evidence investigating preparatory

activity in the motor cortex of non-human primates further suggests the necessity for motor

planning time in visuomotor adaptation (Vyas, O'Shea, Ryu, & Shenoy, 2020). In addition,

Langsdorf et al. (2021) found that delaying movement initiation resulted in an

overcompensation of the imposed rotation, similar to the overshoot in reach estimation

shown by Georgopoulos and Massey (1987), suggesting similar cognitive rotation strategies

may have been in play.

Notwithstanding these studies, we found that on average participants' learning plateaued

before eliminating error, with asymptotic learning levels statistically different from the

degree of imposed rotation for all rotational groups (30°, 45°, 60°), regardless of the amount

of preparation time enforced. These findings are consistent with previous reports which

have suggested that sustained errors during visuomotor adaptation are a product of the

implicit learning system; either suppressing alternative learning mechanisms which may be

able to overcome persisting errors (Shmuelof et al., 2012; Vaswani et al., 2015) and/or

modulating the system's sensitivity to errors dependent on their size, variability and history

(Albert et al., 2021). It should be noted however, that despite regression analysis suggesting

the data had reached an asymptote, there is a possibility that with a longer adaptation

session, or with multiple sessions, participants may have been able to reduce their error

further and get closer to complete compensation. Yet, given the degree of error remaining

at the end of these 280 trials, and the non-significant slopes of the regression analyses, it is

unlikely that much greater adaptation would be achieved within the bounds of Langsdorf et

al's. (2012) study protocol (i.e., with an additional 40 trials). In support of this, estimated

asymptotic levels of adaptation modelled from existing mean group data are in close

correspondence with the values calculated in our original analysis and suggest all groups

478 would asymptote below the degree of imposed rotation (Supplementary Figure 2; see

479 https://doi.org/10.6084/m9.figshare.17136857).

480  One factor that may explain the discrepancy between our results and those of Langsdorf

481 et al. (2021), is the level of experimental control. Our study was conducted online, with

482 participants completing the task unsupervised at home, whereas Langsdorf et al. (2021)

483 conducted a laboratory-based study. The disparities associated with these environments

484 may have contributed to small but significant differences in motivation, attention and

485 behaviour. That said, data from our additional in-laboratory group is at odds with this

486 reasoning. We found no difference in adaptive performance at any phase of the task

487 between the in-lab and corresponding online group, with participants in both groups failing

488 to achieve full compensation. This finding supports previous literature which suggests that

489 kinematic data and results from online motor learning studies are analogous with those

490 collected in a controlled lab environment (Tsay, Lee, Ivry, & Avraham, 2021) and that online

491 tasks perform well in terms of accuracy and precision with regards to timing of visual stimuli

492 and response capture (Bridges, Pitiot, MacAskill, & Peirce, 2020). Furthermore, our data are

493 typical of many previous lab-based visuomotor adaptation studies, with comparable levels

494 of final performance (Huberdeau et al., 2015; Morehead, Qasim, Crossley, & Ivry, 2015;

495 Vaswani et al., 2015; Neville & Cressman, 2018; Weightman et al., 2020; Weightman,

496 Brittain, Miall, & Jenkinson, 2021). With all of these results in mind, it seems improbable

497 that the failure to eliminate residual errors (and replicate results from Langsdorf et al.,

498 2021) was a consequence of online data collection methods.

499  An additional difference between the two studies, which may have had some bearing on

500 the results, is the nature of response cueing used. We used a visual countdown sequence

501 which enabled participants to accurately synchronise their movements with the go-signal

and ensured a tight coupling between response times and the preparation time groupings.

In contrast, Langsdorf et al. (2021) displayed the target and instructed participants to wait until they heard a tone before responding. This difference in protocol resulted in response times closer to 3 seconds. One may argue that more than 2.5 seconds are required to fully prepare for a 45° rotated reach. This is unlikely however, as we show that even a 30° angle was not fully compensated, and there was no evidence for a relationship with the preparation interval for those groups. Previous research has also shown that mental rotation and aiming towards angles up to 90° can be achieved in ∼1 second (McDougle & Taylor, 2019). There is perhaps an argument to suggest that attending to the countdown sequence may have interfered with mental rotation and other cognitive planning processes, by, for instance vying for attentional resources and thus contributing to a consistent reach undershoot (Taylor & Thoroughman, 2007; Galea, Sami, Albert, & Miall, 2010). Nevertheless, prior studies using auditory response cueing have not cited attention to the timed-response sequence as a potential confound (Haith et al., 2015; Leow, Gunn, Marinovic, & Carroll, 2017; McDougle & Taylor, 2019).

   Despite participants failing to eliminate residual errors during late adaptation, our data do include some hallmarks of a speed-accuracy trade-off. We found that motor adaptation was impaired in the 45° and 60° rotational groups, during both early and later stages, when planning time was restricted to 0.35 seconds. This result is in line with previous studies who report reduced error compensation when preparation times are limited (Fernandez-Ruiz et al., 2011; Leow, Gunn, et al., 2017; Leow, Marinovic, Riek, & Carroll, 2017; Albert et al., 2021) and may reflect the suppression of explicit re-aiming/cognitive strategies. Additionally, impaired adaptation associated with restricted preparation times was coupled with an increased retention during no-feedback trials, which is consistent with the idea that

learning involved more implicit, procedural processes (Fernandez-Ruiz et al., 2011; Haith et

al., 2015). The greatest retention was seen in the 0.35 seconds / 60° group, which implies

that adaptation in this group may have been weighted more so towards implicit processes –

also highlighted by the larger residual errors at the end of learning. This suggestion is

reinforced by the equal retention seen for the 2.5 second condition, across all three rotation

magnitudes. In this case, the residual errors are approximately equal, because the

preparation time exceeded that required for mental rotation. However, these assumptions

should be treated with some caution after recent commentary on how the dichotomy of

implicit and explicit components of motor adaptation are inferred (Hadjiosif & Krakauer,

2021).

Although not statistically evident, a speed-accuracy trade-off may also be apparent in the

60° rotational group (Figure 3). On average, there was a linear increase in learning

asymptote as preparation time increased, which may reflect how mental rotation of the

intended movement angle increases the accuracy of reaches (McDougle & Taylor, 2019;

Langsdorf et al., 2021). Addition of further adaptation trials might exaggerate these

asymptotic differences, until statistically significant, yet data from our other rotational

groups and previous literature would suggest that errors would still persist. To achieve full

compensation, it is possible that explicit information about the nature of rotation ought to

be provided (McDougle & Taylor, 2019) or strategies primed using methods such as verbal

aiming reports (Bond & Taylor, 2015; Brudner, Kethidi, Graeupner, Ivry, & Taylor, 2016;

Wilterson & Taylor, 2019; Albert et al., 2021; Langsdorf et al., 2021), which are inherently

coupled with increased reaction/plan times.

In summary, our data suggests that extending motor preparation and planning periods

alone is insufficient to eliminate residual errors during visuomotor adaptation, irrespective

of the size of imposed cursor rotation. While increased preparation time may help to

improve error reduction at larger rotation magnitudes, our results suggest there remains a

limit at which learning saturates at asymptote, perhaps only overcome with priming of

explicit strategies, further instruction or changes to experimental variables. We also provide

further support of the use of online data collection methods in the study of motor control

and learning. Understanding why the central nervous system fails to fully adapt movements

in response to environmental changes may be key when aiming to optimise rehabilitation

protocols following brain injury or disease.

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MW, JSB and NJ conceived and designed the study with input from RCM. MW collected the

data. MW, JSB, RCM and NJ analysed and interpreted the data. MW wrote the first draft of

the paper. JSB, RCM and NJ reviewed and edited the paper and all authors agreed with the

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