

1 **Express Arm Responses Appear Bilaterally on Upper-limb Muscles in an Arm Choice**
2 **Reaching Task**

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4
5 Abbreviated title: Express arm responses appear bilaterally

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36 **Abstract**

37 When required, humans can generate very short latency reaches towards visual targets, like
38 catching a cellphone falling off a desk. During such rapid reaches, express arm responses are the
39 first wave of upper limb muscle recruitment, occurring ~80-100 ms after target appearance.
40 There is accumulating evidence that express arm responses arise from signaling along the tecto-
41 reticulo-spinal tract, but the involvement of the reticulo-spinal tract has not been well-studied.
42 Since the reticulospinal tract projects bilaterally, we studied whether express arm responses
43 would be generated bilaterally. Human participants (n = 14; 7 female) performed visually
44 guided reaches in a modified emerging target paradigm where either arm could intercept a target.
45 We recorded electromyographic activity bilaterally from the pectoralis major muscle. Our
46 analysis focused on target locations where participants reached with the right arm on some trials,
47 and the left arm on others. In support of the involvement of the reticulospinal tract, express arm
48 responses persisted bilaterally regardless of which arm reached to the target. The latency of the
49 express arm response did not depend on whether the arm was chosen to reach or not, however
50 the magnitude of the express arm response was correlated to the level of anticipatory activity.
51 The bilateral generation of express arm responses supports the involvement of the reticulo-spinal
52 tract. We surmise that the correlation between anticipatory activity and the magnitude of express
53 arm responses on the reaching arm arises from convergence of cortically derived signals with a
54 parallel subcortical pathway mediating the express arm response.

55

56 **New and Noteworthy:** Express arm responses have been proposed to arise from the tecto-
57 reticulo-spinal tract originating within the superior colliculus, but the involvement of the
58 reticulo-spinal tract has not been well studied. Here, we show these responses appear bilaterally

59 in a task where either arm can reach to a newly appearing stimulus. Our results suggest that the
60 most rapid visuomotor transformations for reaching are performed by a subcortical pathway that
61 lies in parallel with corticospinal circuits.

62

63 Keywords: express arm response, visually-guided reaches, EMG, reticulo-spinal tract

64

65 **Introduction**

66 When time is of the essence, like when catching a cellphone knocked off a desk,
67 visuomotor transformations can occur at times approaching the minimal afferent and efferent
68 conduction delays. A useful marker for these rapid visuomotor transformations is the express
69 arm response. The express arm response, which has also been termed the stimulus locked
70 response (1) or rapid visual response (2), is a burst of upper-limb muscle recruitment that
71 consistently occurs ~100ms after stimulus appearance, regardless of the reach reaction time (1, 3,
72 4). The term express arm response was coined to reflect the shared properties of this aspect of
73 upper-limb muscle recruitment with the visual burst of visuomotor neurons in the intermediate
74 and deep layers of the superior colliculus, and with express saccades (5). Express saccades,
75 express arm responses, and the visual burst of visuomotor neurons are all directed toward the
76 location of a visual stimulus, regardless of instructions to move in the opposite direction (4, 6–8).
77 All three responses are also preferentially evoked by stimuli composed of low spatial frequencies
78 and high contrast (9–12). Further, the magnitudes of both express arm responses and the visual
79 burst of visuomotor neurons are inversely related to the ensuing reaction time (1, 4, 6, 13). These
80 shared properties support the hypothesis that express arm responses are mediated by the superior
81 colliculus (1, 4, 9, 12).

82 In non-human primates (14), the communication between the superior colliculus and
83 spinal cord is likely indirect, with an interface in the reticular formation. Consistent with this
84 potential interface, express arm responses in humans are augmented by non-visual stimuli
85 thought to excite the reticular formation (2). A distinctive feature of the reticular formation is its
86 extensive, almost equal, bilateral projections to upper-limb muscles (15–17). Cortical motor
87 areas also project bilaterally, but the proportion of ipsilateral cortico-spinal motor projections is

88 lower (18, 19), and muscle responses evoked from ipsilateral motor areas tend to have longer
89 latencies and smaller magnitudes (20–22). To date, express arm responses have been studied
90 only in unimanual reaching tasks. The goal of this study is to test whether express arm responses
91 would be expressed bilaterally when either arm can be used to reach to a visual target.

92 Previous work has shown an emerging target paradigm, wherein a moving target
93 transiently disappears and then emerges from behind a barrier, elicits robust express arm
94 responses in the reaching arm in almost every participant (5, 12, 23, 24). Here, we modified this
95 paradigm by increasing the number of potential locations of target emergence and allowing the
96 subject to reach toward the emerging target with either arm. These modifications elicited reaches
97 by either the left or right arm for different target locations, and at certain locations elicited left
98 arm reaches on some trials and right arm reaches on other trials. Muscle recruitment for reaches
99 toward these latter locations is critical for our primary aim, which is to determine whether the
100 expression of express arm responses depended on whether the arm was chosen to reach to the
101 target or not. Further, as our task requires participants to choose which arm to move toward the
102 emerging target, a secondary aim was to determine when limb muscle activity indicated whether
103 the associated arm would reach to the target or not. In doing so, we can assess the presence or
104 absence of any relationship between the commitment to move a particular arm and the express
105 arm response. Overall, we found that express arm responses evolved on both the chosen and non-
106 chosen arm. We also found that the time at which limb muscle recruitment indicated which arm
107 would reach to the target was highly variable and was unrelated to the timing of express arm
108 responses. These findings are consistent with express arm responses being relayed through the
109 reticular formation along a tecto-reticulo-spinal pathway and illustrate a surprising degree of

110 independence between the expression of express arm responses and the decision to commit to
111 moving one arm or the other.

112

113 **Methods and Materials**

114 *Participants*

115 15 participants (8 males, 7 females; mean age: 21.8 years SD: 1.9) provided informed
116 written consent, were paid for their participation, and were free to withdraw from the experiment
117 at any time. All participants had normal or corrected-to-normal vision, with no current visual,
118 neurological, or musculoskeletal disorders. All participants completed the short form Edinburgh
119 Handedness Inventory (25, 26) which indicated 12 participants were right-handed, 2 mixed-
120 handed, and 1 left-handed. All procedures were approved by the Health Science Research Ethics
121 Board at the University of Western Ontario. One participant (left-handed male) was excluded
122 due to a failure to follow task instruction, as they routinely initiated arm movements before target
123 emergence.

124

125 *Apparatus*

126 Participants generated reaching movements with their left and right arms in a bimanual
127 KINARM end-point robot (BKIN Technologies, Kingston, ON, Canada). Movements were
128 generated in the horizontal plane via two handles through shoulder and elbow flexion and
129 extension. A custom built-in projector (ProPixx projector, VPixx, Saint-Bruno, QC, Canada)
130 generated visual stimuli onto an upward facing mirror, located at approximately shoulder height.
131 All visual stimuli were white (110 cd/m^2) presented against a black ($.6 \text{ cd/m}^2$) background
132 (contrast ratio: 183:1). A shield below the mirror occluded direct vision of the hands, but real-

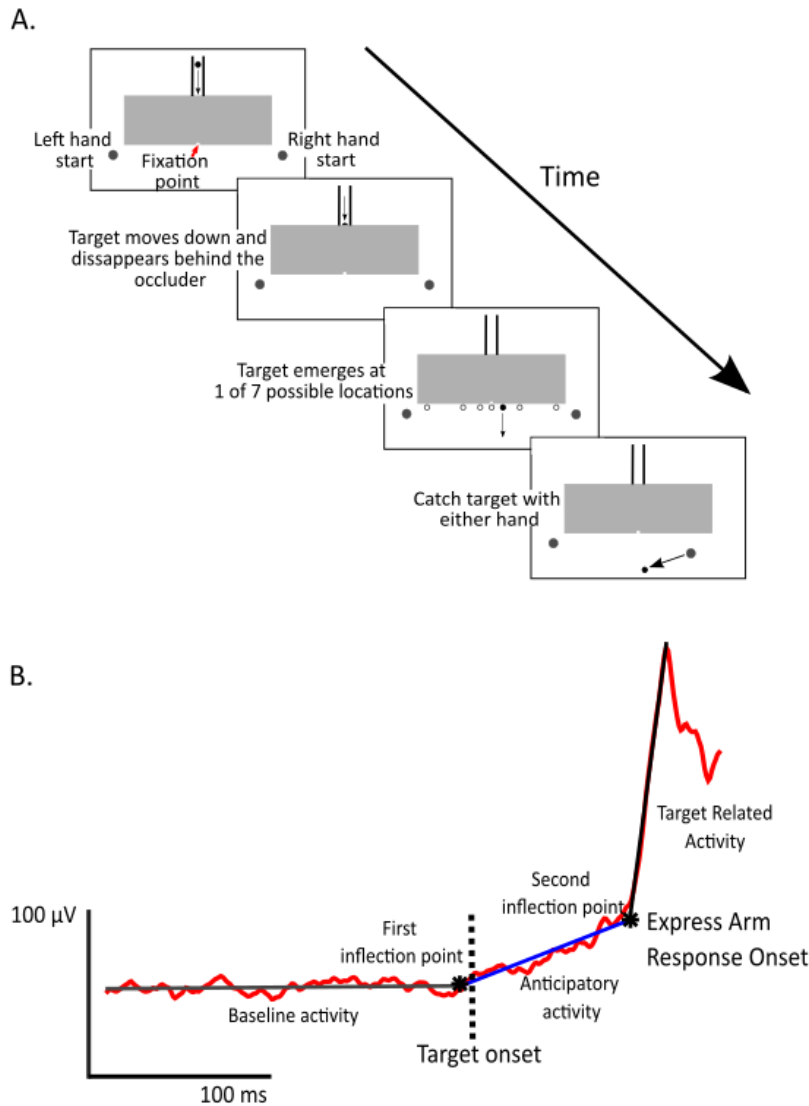
133 time hand positions were represented via two white dots each with a diameter of 1.5 cm (which
134 equates to approximately 1 degree of visual angle). Throughout the experiment, constant forces
135 of 2 N towards the participant and 5N outward for each hand were applied to increase tonic
136 activity in the pectoralis major (PEC) muscle.

137

138 *Experimental Design*

139 Participants completed a modified version of the emerging target paradigm (23) (**Figure**
140 **1A**). Participants initiated each trial by bringing the white dots representing their left and right
141 hands into a round, 2cm diameter white starting position, located 45 cm in front of them, and 23
142 cm to the left and right of center respectively. These starting positions disappeared once the trial
143 was initiated. Simultaneous with the start of the trial, a white target (1.5 cm diameter) located
144 above an occluder began moving toward the participant at 15 cm/s. The target disappeared
145 behind the occluder for a fixed duration of 1.5 s before emerging in motion at 15 cm/s below the
146 occluder at one of 7 locations, appearing either at the horizontal center of the occluder, or 3, 7, or
147 17 cm to the left or right of this central position. Target motion was vertical both before and after
148 disappearance behind the occluder, regardless of where the target emerged. Thus, the time
149 between target disappearance and appearance was fixed at 1.5 s for all target locations. The
150 target was only presented in its entirety after it moved beneath the occluder, preventing the
151 presentation of a half-moon stimulus with a lower overall area. At the time of target emergence,
152 a visual stimulus unseen by the subject was also presented to a photodiode, and all
153 electromyographic (EMG) and kinematic data were aligned to this time.

154



155

156 Figure 1. Modified emerging target paradigm and method for classifying express arm responses.
157 A) At the start of each trial, the target appears above an occluder (grey box), and the participant
158 brings their right and left hands into the start position. The target then moves down the chute,
159 disappears briefly behind the occluder, and then re-emerges below the occluder at one of seven
160 different locations (possible target locations are shown, but these were not presented to the
161 subject). Participants reached to intercept the target with either the right or left arm. B) For this
162 example the muscle activity was fit with a three-piece linear regression, differentiating
163 recruitment during a baseline, anticipatory, and target-related interval. In this case, the time of
164 the second inflection between anticipatory and target-related activity represents the start of the
165 express arm response onset.

166

167 Although eye movements were not measured, participants were instructed to foveate a
168 notch in the center of the occluder, 47 cm in front of them, from the start of each trial until the
169 target re-emerged under the barrier. Upon target emergence, participants were instructed to reach
170 toward the emerging target as quickly as possible and were told that they could use either arm to
171 do so. Participants completed four blocks of 350 trials each, with each block containing 50
172 pseudorandomly intermixed repetitions of each location, yielding a total of 200 trials for each
173 target location.

174

175 *Data acquisition and analysis*

176 Surface EMG activity was recorded from the clavicular head of the right and left
177 pectoralis major muscle (PEC) with double-differential surface electrodes (Delsys Inc. Bagnoli-8
178 system, Boston, MA, USA). To ensure consistency, the same individual placed electrodes on the
179 right and left PEC for all participants, using anatomical landmarking and muscle palpation to
180 determine location. EMG signals were amplified by 1000, sampled by the KINARM data system
181 at 1000 Hz, then full wave rectified off-line. Kinematic data was also sampled at 1000 Hz by the
182 KINARM data system.

183 To allow cross-muscle comparisons, we normalized the EMG activity to baseline,
184 dividing EMG activity on each trial by the average EMG activity between -500 to -100ms before
185 target onset across all trials. Normalized muscle activity was only used when comparing the
186 magnitudes of recruitment across different muscles, otherwise, source EMG voltages were
187 analyzed.

188 Reaction time (RT) was calculated as the time from target appearance below the
189 occluder, indicated by the photodiode, to the initiation of the reaching movement by the arm that

190 intercepted the target. The reach RT for each trial was determined using a custom MATLAB
191 (version 2014b, The MathWorks, Inc., Natick, Massachusetts, United States) script that found
192 the time when the hand exceeded 5% of its peak velocity of the hand after target onset, and then
193 moved backwards in time to find the point at which hand acceleration following target onset
194 exceeded the 95% confidence interval of acceleration data taken from a period of 100 ms before
195 to 50 ms after target onset. The offset of hand motion was the time at which hand velocity fell
196 below 5% of its peak velocity. The onset and offset of movements were confirmed offline by an
197 analyst in a graphical user interface and adjusted if necessary. We excluded trials with RTs less
198 than 100 ms due to presumed anticipation, and trials with RTs exceeding 500 ms due to
199 presumed inattentiveness. 16% of trials were excluded using these RT constraints, primarily due
200 to anticipatory movements. We also excluded trials consisting of multiple movement segments
201 toward the target, excluding ~2% of trials.

202 Arm-choice was defined simply as the arm that intercepted the target. A psychometric
203 function was generated using the proportion of right arm reaches as a function of target location.
204 For each participant a logistic regression was fit to the data, using the ‘logit’ MATLAB function:
205 $f(p) = \log\left(\frac{p}{1-p}\right)$, where p is the proportion of right arm reaches. Using the fitted curve, we
206 estimated the theoretical point where a target would be intercepted with either the left or right
207 arm with equal likelihood. The closest target location to this point, referred to as the target of
208 subjective equality, was then used for further analyses, as this target location permitted the best
209 within-muscle comparison of recruitment when that arm was chosen to reach to the target or not.

210 Previous work examining the express arm response has used a time-series receiver-
211 operating characteristic analysis, contrasting EMG activity for movements into or away from a
212 muscle’s preferred direction (1, 27). Because a given arm only moved in one direction in our

213 study (e.g., all targets lay to the left or right of the right or left arm, respectively), we developed a
214 novel method for detecting and quantifying the express arm response. Our method involves a
215 two- or three-piece linear regression, fitting lines to EMG activity in a baseline, anticipatory
216 (only used for the three-piece linear regression), and post-target interval (see (5, 13) for methods
217 based on a two-piece linear fit). Our rationale for using a three-piece linear regression was based
218 on qualitative observation of mean EMG recruitment, which often started to increase in an
219 anticipatory fashion above baseline before and just after target appearance (**Figure 1B**).

220 To determine the presence or absence of an express arm response, we took the following
221 steps. First, we ensured that there were at least 25 reaches from a given arm to a particular target
222 (only one arm was used to reach to most target locations). Whenever there were enough reaches
223 from a given arm, we further analyzed the muscle activity from both the left and right PEC, as
224 this provides us with EMG activity from both the reaching and non-reaching arm. We then fit the
225 mean EMG activity spanning from 200 ms before target onset to the time of the peak EMG
226 activity within 125 ms after target onset with a two-piece linear regression. This involved finding
227 the inflection point that minimized the sum of error squares (the loss), delineating baseline
228 activity (spanning from -200 ms to the first inflection point), and the target-related interval (from
229 the inflection point to the peak EMG activity). This two-piece regression sufficed for situations
230 where there was no increasing anticipatory activity between baseline and target related activity.
231 To account for situations where anticipatory activity was present, we fit the data with a three-
232 piece linear regression, enforcing a minimum of 10 ms between the first and third pieces. Doing
233 so involved finding two inflections points that minimized the loss, delineating the baseline
234 activity (spanning from -200 ms to the first inflection point), anticipatory activity (spanning from
235 the first to second inflection point), and the target-related interval (spanning from the second

236 inflection point to the peak EMG activity; see **Figure 1B**). As a three-piece linear regression
237 always decreases loss compared to a two-piece linear regression, we determined whether a three-
238 piece regression would be warranted by calculating the ratio of the loss between the two- and
239 three-piece linear regressions. If the ratio was below 0.7, we used the three-piece linear
240 regression. If the ratio was above 0.7, we used the two-piece linear regression. We also
241 calculated the loss ratio between the two-piece linear regression and regular linear regression. A
242 two-piece linear regression was used if the loss ratio was below 0.6, otherwise a linear regression
243 was used.

244 Following these steps, we then determined the presence of an express arm response in the
245 following manner. First, the EMG data had to be fit by either a two- or three-piece linear
246 regression; EMG data fit by a linear regression signified the absence of an express arm response.
247 Second, the target related inflection point had to occur within 70-105 ms, and the slope of the
248 first and second piece for a two-piece linear regression, or the second and third piece for a three-
249 piece linear regression had to be significantly different at $P < 0.05$, as determined by a
250 bootstrapping procedure. If these criteria were met, the latency of the express arm response was
251 defined as the time of the inflection point for the two-piece linear regression, or the second
252 inflection point for the three-piece linear regression. The express arm response magnitude was
253 defined as the difference of the peak EMG activity over the next 15ms to the EMG activity at the
254 onset of the response. We also quantified muscle activity immediately preceding the express arm
255 response (in the results, we term this the “anticipatory activity” for simplicity, although we
256 recognize that anticipatory and baseline activity are equivalent for a two-piece linear regression).

257 In a separate analysis to determine at what point muscle activity reflected arm choice, we
258 used a time-series receiver-operating characteristic (ROC) analysis from EMG activity recorded

259 when participants reach to the target of subjective equality. This target location provided a large
260 sample of EMG activity from a given muscle on trials where the associated arm or the opposite
261 arm reached to the target. We were interested in the time-point when EMG activity from a given
262 muscle diverged depending on whether the arm was chosen to reach to the target or not. We
263 separated EMG activity based on which arm reached to the target, then analyzed at every time
264 sample (1 ms) from 500ms before target onset to the end of the trial. For each time-point we
265 calculated the area under the ROC curve, which is the probability that an ideal observer could
266 discriminate whether the associated arm would reach to the target or not, based solely on the
267 EMG activity. Values of 1 or 0 indicate perfectly correct or incorrect discrimination respectively,
268 whereas a value of 0.5 indicates chance discrimination. We set the threshold discrimination at
269 0.6 because this criterion exceeded the 95% confidence intervals determined previously using a
270 bootstrapping procedure (13). The time of discrimination was defined as the first point in time at
271 which the ROC value exceeded 0.6 for at least eight of ten subsequent time-samples.

272

273 *Statistical Analysis*

274 Statistical analyses were performed in MATLAB. To compare the proportion of
275 participants generating an express arm response (termed express arm response prevalence) as a
276 function of muscle, arm choice, and location, a chi-squared test was used, and Bonferroni
277 corrected when necessary. A paired t-test was used to compare the latency and magnitude of the
278 express arm response within a muscle at the target of subjective equality. We relied on non-
279 normalized EMG for our magnitude analysis for within muscle comparisons, and EMG activity
280 normalized to baseline for across muscle comparisons.

281

282 **Results**

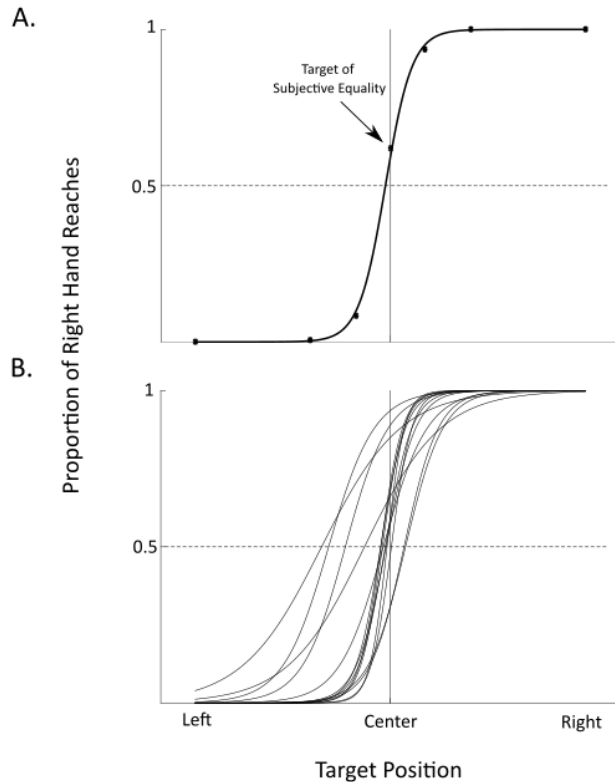
283 The reticular formation is a likely relay in a tectal pathway mediating express arm
284 responses. Given the bilateral projections from the reticular formation, we wondered whether
285 express arm responses would be expressed bilaterally in a task where participants could choose
286 which arm to use to intercept an emerging target. We recorded muscle activity from the right and
287 left PEC muscles as participants completed a modified emerging target paradigm (**Figure 1A**).
288 Targets could emerge at one of seven locations below the barrier, and participants reached to
289 catch the target as fast as possible with either arm. We analysed muscle activity from both the
290 reaching and non-reaching arm to determine the presence of the express arm response. We also
291 examined the time at which muscle activity indicated that the associated arm would reach toward
292 the target or not, relative to the time of the express arm response.

293

294 *Arm-choice as a function of target location, and defining the target of subjective equality*

295 Participants were free to choose which arm to move for all targets, but tended to choose
296 the closer arm (**Figure 2**). We quantified participant behaviour by fitting a psychometric curve to
297 the proportion of right arm reaches expressed as a function of target location. The point of
298 subjective equality defines the theoretical target location where a participant would reach with
299 one arm on half of all trials, and with the other arm on the other half of trials. From the point of
300 subjective equality, we found the closest actual target location, referred to as the target of
301 subjective equality, for each participant (see **Figure 2A** for a representative subject). This
302 location was associated with a high number of reaches from either arm in all participants. Across
303 our sample, the target of subjective equality was at center ($n = 10$), 3 cm left ($n = 2$) or 7 cm left
304 ($n = 2$) of center (**Figure 2B**). The target of subjective equality permits a within-muscle

305 comparison of recruitment when the associated arm was chosen to reach or not. In general,
306 locations other than the target of subjective equality did not generate enough reaches from both
307 arms for within muscle comparisons.



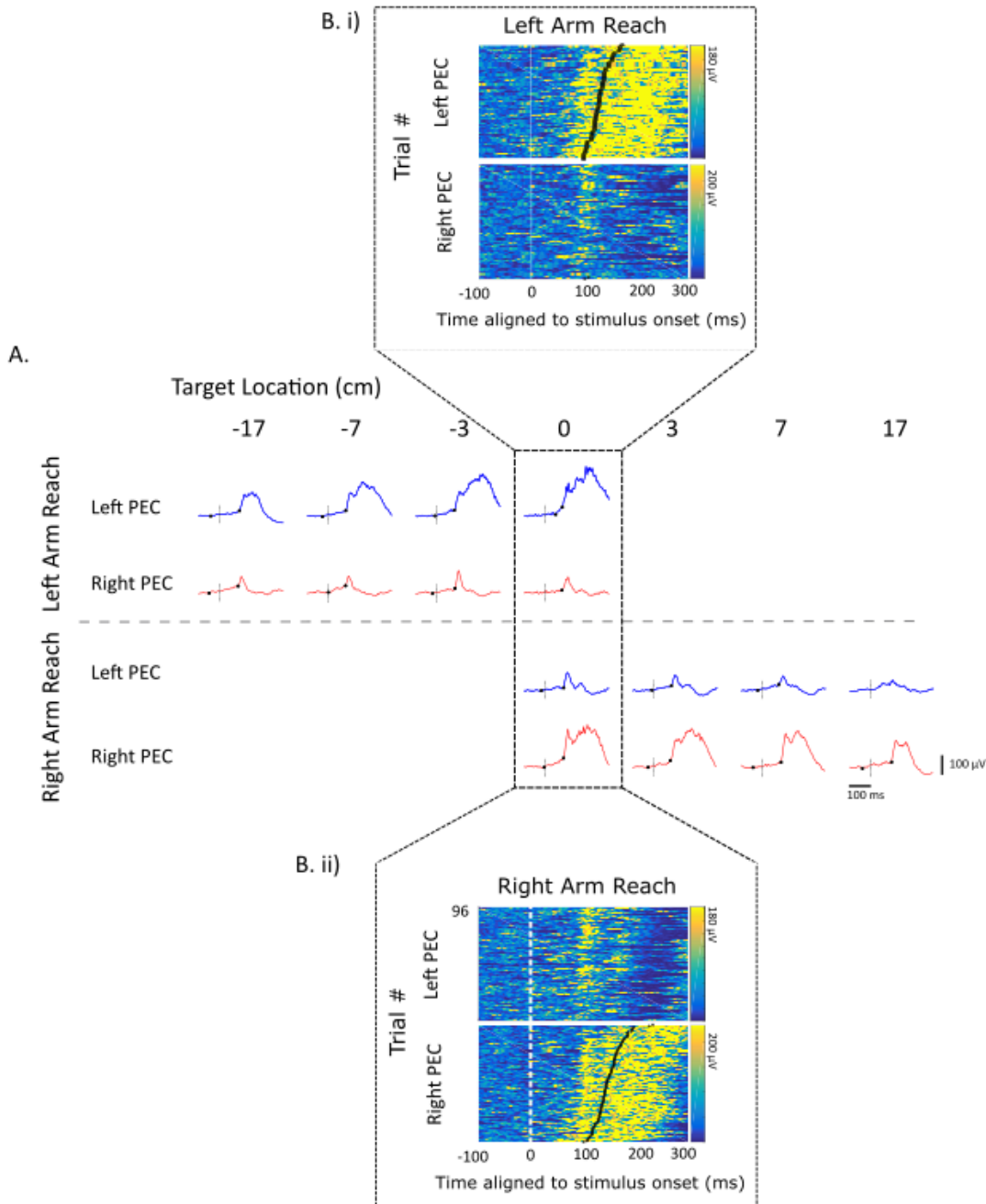
308 Figure 2. Arm Choice as a Function of Target location. A: A single participant example of right
309 arm choice as a function of target location. Each black dot represents a location where the target
310 emerged on a subset of the trials. A psychometric function was fit to the data and the target of
311 subjective equality was chosen as the target closest to the horizontal dash line. B: Psychometric
312 functions for all participants.

314 *Do express arm responses appear bilaterally?*

316 The main question we wanted to address was whether express arm responses evolve
317 bilaterally when either arm could be used to intercept an emerging target. **Figure 3A** shows the
318 average muscle activity from an exemplar participant (same participant as **Figure 2A**), across all
319 positions where at least 25 reaches were made by the associated arm. These data show how
320 participants tended to reach with the arm closest to the target (e.g., note how the right or left arm

321 tended to reach for targets in the right or left hemifield, respectively). Using either a two-piece or
322 three-piece linear regression to determine whether there was an express arm response (**Figure**
323 **1B**, see Methods), we observed express arm responses in both the reaching and non-reaching arm
324 (inflection points are denoted by the black dot; express arm responses in **Figure 3A** are denoted
325 by the first or second dots when a two- or three-piece linear regression was used, respectively) .
326 When detected, express arm responses occurred ~90ms after target appearance in both the
327 reaching and non-reaching arms.

328 Previous reports have emphasized that the trial-by-trial timing of express arm responses
329 is more aligned to stimulus rather than movement onset (1, 4). As shown in **Figure 3B**, we
330 indeed found that the timing of express arm responses was more tied to stimulus rather than
331 movement onset, regardless of whether the associated arm reached or not. This characteristic
332 feature of express arm responses appears as the vertical banding of EMG activity in **Figure 3B**
333 when muscle activity is aligned to stimulus onset, showing a burst of muscle recruitment ~90 ms
334 after target emergence regardless of the ensuing reach RT. Following this bilateral generation of
335 the express arm response, a more prolonged period of increased recruitment was observed only
336 on the muscle associated with the reaching arm.



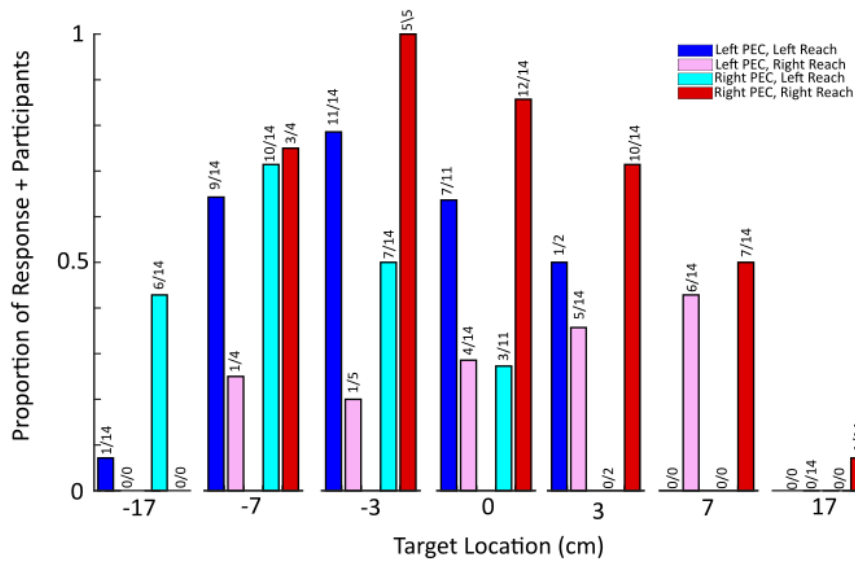
337

338 Figure 3. Bilateral muscle recruitment in a representative participant. A) Average muscle
339 activity (+/- SE) for all reaches as a function of target location. Averages are plotted only if there
340 were at least 25 trials where the given arm reached to the target. The 0 cm location is the target
341 of subjective equality, as this featured many trials where either the right or left arm reached to
342 the target. Stimulus onset indicated by the black vertical dotted line. Black dots represent the
343 inflection points, the first or second of which indicate the time at which an express arm response
344 was detected when using the two- or three-piece linear regression respectively (see methods for
345 further details) B) Depiction of trial-by-trial recruitment from left (top) and right (bottom)

346 pectoralis muscle during left (i) and right (ii) arm reaches. Each row is a different trial, with the
347 intensity of color conveying recruitment magnitude. Trials are aligned to stimulus onset (white
348 vertical dotted line) and sorted by RT (black dots are only shown on the reaching PEC). The
349 express arm response appears as a vertical banding of increased recruitment that is more aligned
350 to stimulus presentation than movement onset.
351

352 The prevalence of express arm responses is known to vary across paradigms and
353 participants (1, 5, 9, 12). We wanted to know whether all participants had express arm responses
354 in general, and further whether the responses were equally prevalent in the reaching and non-
355 reaching arms. As shown in **Figure 4**, the modified emerging target paradigm elicited express
356 arm responses from at least one participant at each location. Further, almost all participants ($n =$
357 13) generated express arm responses follow target presentation at least one location . Compared
358 to the null-hypothesis that the response only occurs in the reaching arm, we found that the
359 response also occurred in the non-reaching arm (Chi-squared test: $p < 0.001$, $c2= 52.3858$, $df=1$).
360 We also compared the prevalence of express arm responses in the reaching and non-reaching arm
361 grouped across all locations, and further at each location individually. Using a chi-squared test
362 we found express arm responses occurred more frequently in the reaching arm compared to the
363 non-reaching arms across all locations ($p= 0.002$, $c2= 9.6671$, $df=1$). Thus, although express arm
364 responses can evolve bilaterally on both upper limbs, they are more likely to occur in the
365 reaching arm.

366 We also examined whether there was a difference in the prevalence of express arm
367 responses as a function of target location. Using a chi-squared test with Bonferroni corrected for
368 multiple comparisons ($\alpha = 0.0083$) and grouping targets based on distance from the center
369 (e.g., combining data for the 17 cm right and 17 cm left targets), we found that express arm
370 responses were significantly less likely for the 17 cm locations ($p < 0.0083$). No other
371 differences were found based on location.



372
373 Figure 4. Proportion of subjects exhibiting an express arm response as a function of arm and
374 target location. At each target location prevalence is determined as the proportion of participants
375 exhibiting an express arm response relative to the number of subjects who generated enough
376 reaches with the given arm at that particular location (recall at least 25 reaches had to be made by
377 a given arm for the analysis of the express arm response).
378

379 *Properties of express arm responses*

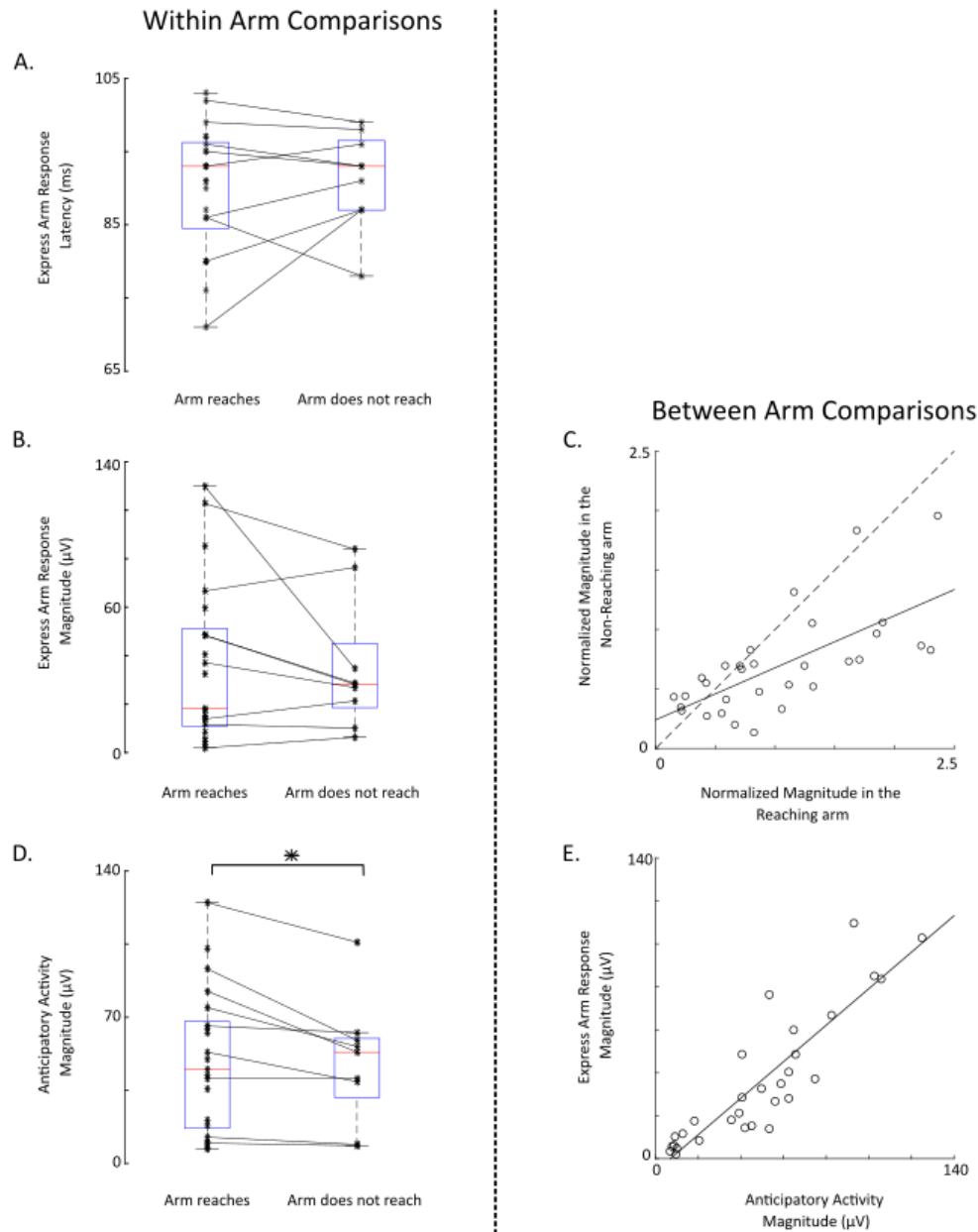
380 Next, we were interested in the latency and magnitude of express arm responses recorded
381 bilaterally, and whether these measures differed depending on whether the associated arm was
382 selected to move or not. Previous work has shown that express arm response latency (9) and/or
383 magnitude (4) may differ depending on stimulus properties and task context. We examined
384 express arm response latency and magnitude within a given muscle at the target of subjective
385 equality, analyzing these properties depending on whether the associated arm was chosen to
386 reach or not (note that this is a within-muscle comparison). Using only paired observations (i.e.,
387 when express arm responses were detected in a given muscle regardless of whether the arm was
388 chosen to move or not) we found no difference in express arm response latency with arm choice
389 (**Figure 5A**; $p = 0.5299$, $t = -0.6565$, $df = 8$). Further, using a single factor ANOVA we found no
390 difference in response latency across target locations ($p > 0.05$). These results reinforce the

391 qualitative observation from **Figure 3A** that the express arm response evolves consistently ~90
392 ms irrespective of arm choice. Along with latency, magnitude was also not significantly different
393 when the arm was chosen or not chosen to reach at the point of equal selection (**Figure 5B**; $p =$
394 0.1485 , $t = 1.5989$, $df = 8$), or across target locations (single factor ANOVA, $p > 0.05$).

395 If mediated by a common source like the reticular formation, we would expect the
396 magnitude of express arm responses on the reaching and non-reaching arm to be correlated
397 across participants and targets (e.g., a larger express arm response on the reaching arm should be
398 associated with a larger express arm response on the non-reaching arm). For this analysis, we
399 identified target locations where an express arm response was observed on both the reaching and
400 non-reaching arm, and found that express arm response magnitudes were indeed positively
401 correlated between the muscles (**Figure 5C**, Pearson correlation, $p < 0.001$, $r = 0.677$; every
402 point represents a unique observation for a participant and target location where express arm
403 responses were observed bilaterally; note magnitudes are normalized here since this is an across-
404 muscle comparison). Thus, larger express arm response magnitudes on the reaching arm tended
405 to be associated with larger express arm response magnitudes on the non-reaching arm.
406 Interestingly, on average, the magnitude of the express arm responses was about twice as large
407 on the reaching versus non-reaching arm. Although this was not seen through the magnitude
408 analysis shown in **Figure 5B**, this may be due to the lower number of paired observations.

409 While the influence of arm choice affected response magnitude when comparing across
410 the muscles, **Figure 5C** shows this was not always the case in all participants, with some
411 observations landing above the line of unity (the dashed line). In our paradigm, participants knew
412 in advance that targets would appear medial relative to the starting position of both the left and
413 right arm, leading us to wonder if participants anticipated which arm to use prior to target

414 emergence. To analyze the potential influence of such anticipation, we examined anticipatory
415 activity on a given muscle as a function of whether the associated arm was chosen to reach or not
416 and found greater anticipatory activity when the associated arm was chosen to reach to the target
417 (**Figure 5D**; paired t-test, $p = 0.0117$, $t = 3.2484$, $df = 8$). This relationship between anticipatory
418 activity and arm choice can be seen in **Figure 3A** on the right PEC at the 0 cm target; note how
419 anticipatory activity preceding the express arm response was greater when the right rather than
420 left arm reached to the target. This level of anticipatory activity related to the magnitude of the
421 ensuing express arm response (n.b., the latter measure quantifies the EMG magnitude above
422 anticipation), as we found a positive correlation between these measures for both the reaching
423 and non-reaching arms (**Figure 5E**; $r = 0.8866$, $p < 0.001$). Thus, the level of anticipatory
424 activity attained just before the express arm response related to the magnitude of the express arm
425 response.



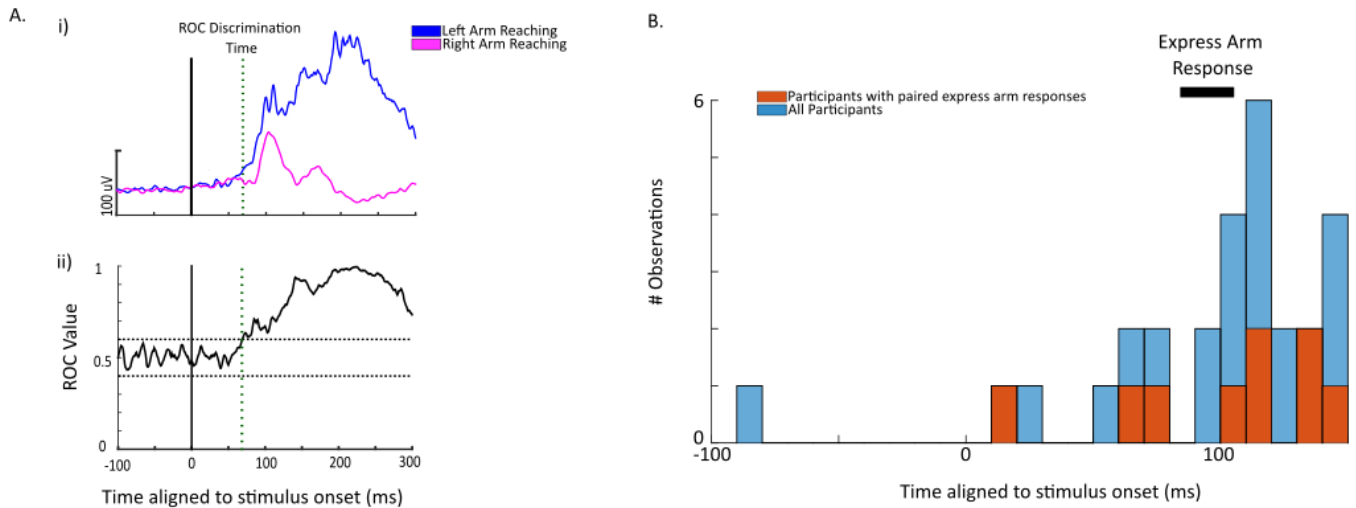
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427 Figure 5. Analyses of the characteristics of express arm response. The latency (A) or magnitude
428 (B) of the express arm response as a function of whether the associated arm reached or not, taken
429 from the target of equal selection. Lines connect within-muscle observations. C) The magnitude
430 of the express arm response in the reaching and non-reaching arm are significantly correlated
431 across participants ($r = 0.677$, $p < 0.001$). Each dot represents a unique combination of target and
432 subject where express arm responses were observed on both the reaching and non-reaching arm.
433 The black line indicates the linear regression fit, and the dashed line represents the line of unity.
434 D) Anticipatory activity, measured as the level of EMG activity just prior to the express arm
435 response. Same format as A. Anticipatory activity was significantly higher when the arm was
436 selected to reach to the target ($p = 0.0117$). E) Correlation of the level of anticipatory activity to
437 the magnitude of the express arm response ($r = 0.8866$, $p < 0.001$). Each dot represents an
438 observation, with the black line indicating the linear regression fit.

439

440 *When, relative to the express arm response, does muscle activity relate to arm choice?*

441 The preceding analyses showed that greater levels of anticipatory muscle recruitment
442 relate to the choice to use the associated arm to reach to the target. These results lead us to
443 wonder when muscle activity predicts which arm was going to move, and whether this time
444 relates in a systematic way to the latency or expression of an express arm response. To address
445 this, we performed a time-series ROC analysis to compare the muscle activity when the arm was
446 chosen to reach or not and searched for the time at which an ideal observer could correctly
447 discriminate arm choice from such EMG activity (see Methods). **Figure 6A** shows one example
448 of this analysis, showing the average activity of left PEC muscle for the exemplar participant
449 (same participant as **Figure 2A** and **Figure 3**) preceding left or right arm reaches to the 0 cm
450 target (top plot, blue or pink traces respectively), as well as the associated time-series ROC
451 (bottom plot). For this example, the discrimination time at which EMG activity reliably predicted
452 which arm would reach was 69 ms after target onset, which preceded the express arm response.
453 Across our entire sample, and regardless of whether participants exhibited an express arm
454 response or not, we observed no systematic relationship between the discrimination time
455 indicating which arm would move and the latency of express arm responses, with discrimination
456 times variably preceding, occurring within, or following the express arm response epoch (**Figure**
457 **6B**). We also observed no obvious relationship between this discrimination time and the
458 generation of express arm responses; subjects exhibited express arm responses regardless of
459 whether the discrimination time occurred earlier or later than the express arm response. This
460 analysis reveals a lack of any relationship between aspects of muscle recruitment reflecting arm
461 choice and the timing and expression of the express arm response.



462

463 Figure 6. Time of arm choice discrimination based on muscle activity. A) data from the
464 exemplar participant, with the top plot (i) depicting mean EMG (+/- SE) from left PEC for
465 reaches using the left (blue) or right (pink) arm, and the bottom plot (ii) showing the time-series
466 ROC analysis used to determine the time at muscle activity predicts arm choice. Green vertical
467 dotted lines in the inset represents the time of discrimination (69 ms). B) Histogram of the
468 discrimination times organized into bins of 10ms. Orange bins depict observations where the
469 participant exhibited an express arm response on a given muscle when the associated arm was
470 selected to reach or not. Blue bins depict observations where express arm responses were not
471 observed.

472

473 *Kinematic Consequences of the Express arm response*

474

The express arm response is a brief period of muscle recruitment that increases muscle

475

force. Previous work with unimanual anti-reach, delay, or stop-signal tasks has shown that

476

express arm responses can produce small, task inappropriate, movements toward a target (4, 28,

477

29). The non-reaching arm provides a further opportunity to study the kinematic consequences of

478

express arm responses in isolation from ensuing reach-related activity. First, we looked at the

479

velocity of both the reaching and non-reaching arm at every location and consistently saw a

480

small movement towards the target in the non-reaching arm. This can be seen in **Figure 7A**

481

where we have plotted horizontal velocity from the exemplar participant (same participant as

482

Figure 2A, Figure 3, Figure 6A) for both the reaching and non-reaching arms at every location.

483

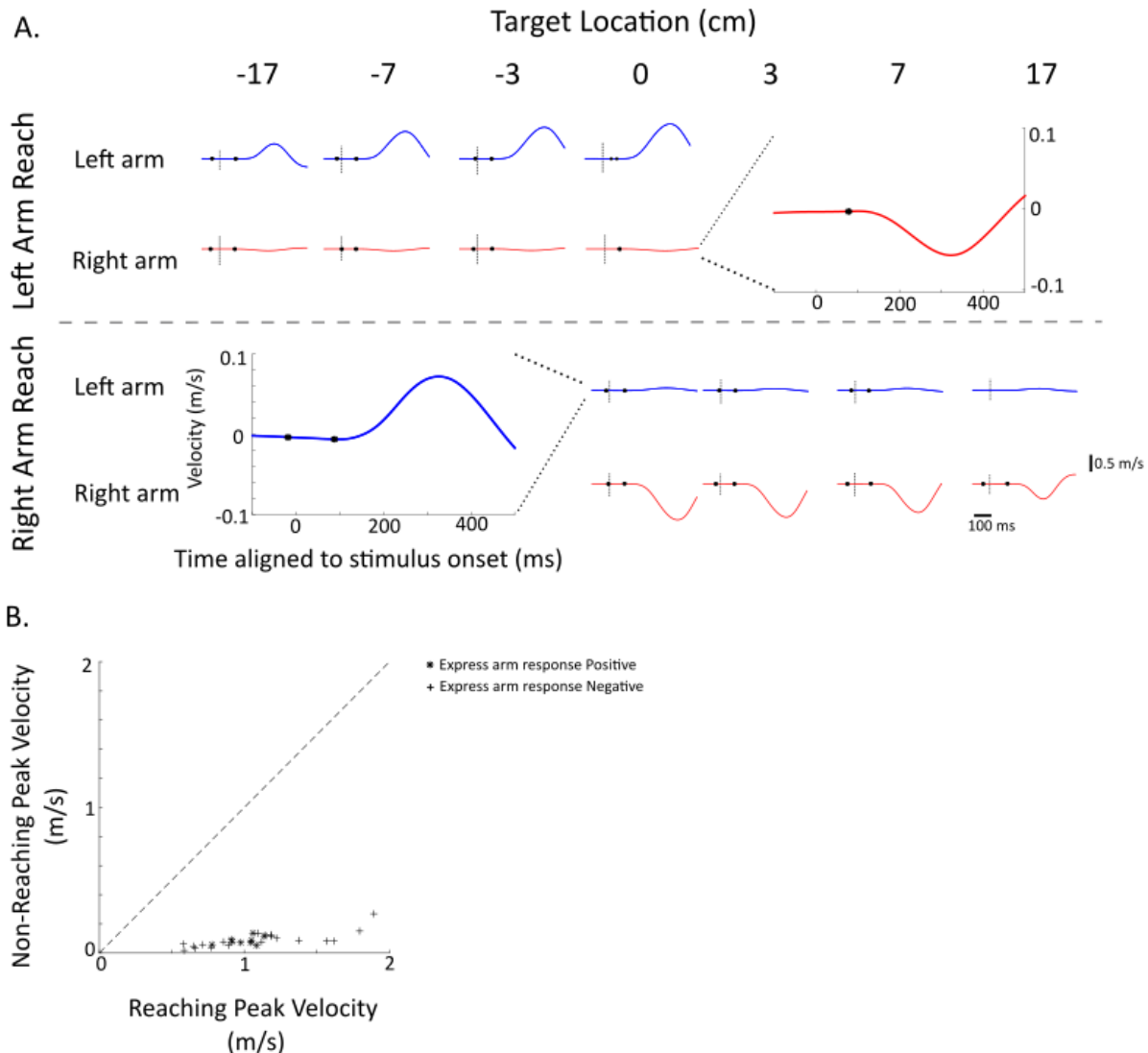
As expected, the velocity is much higher in the reaching arm than in the non-reaching arm, but

484 there is clearly a small deviation of the non-reaching arm toward the target (represented at an
485 increased scale in the insets in **Figure 7A**). To quantify the non-reaching arm's peak velocity and
486 allow cross-participant comparisons, we normalized it by the peak velocity of the reaching arm.
487 We found on average the non-reaching arm had a peak velocity that was $8.11 \pm 2.69\%$ of the
488 reaching arm. Compared to a null hypothesis that no movement occurs in the non-reaching arm,
489 the non-reaching arm did indeed move towards the stimulus (Student's t-test, $p < 0.001$, $t = -$
490 15.9768 , $df = 27$). Next, we compared the peak velocity in the non-reaching arm based on
491 whether an express arm response was observed but did not find any difference in peak velocity
492 based on whether an express arm response was observed (peak velocity: $8.53 \pm 2.15\%$) or not
493 (peak velocity: $7.35 \pm 3.45\%$) (**Figure 7B**; paired t-test, $p > 0.05$). Thus, although the non-
494 reaching arm did move toward the target, the peak velocity of this movement was unrelated to
495 the detection of an express arm response. This is a somewhat surprising result, but we note that
496 our method for detecting express arm responses may have had a high rate of false negatives
497 where the slope of EMG activity during the express arm response epoch did not differ
498 significantly from the slope of EMG activity during the anticipatory interval.

499 Another feature that is apparent in the velocity traces of the non-reaching arm is that the
500 small movement toward the target is followed by a brief reversal in velocity. This reversal
501 reflects a small returning movement of the non-reaching arm back toward the starting position.
502 Interestingly, the EMG correlates of this returning movement on the non-reaching arm are
503 apparent in **Figure 3A**, where recruitment levels after the express arm response drop below the
504 levels of anticipatory recruitment attained just before the express arm response.

505 Given the presence of anticipatory EMG activity, we examined whether the reaching arm
506 drifted slowly inwards, given that all targets appeared medial relative to starting hand positions.

507 To do this, we compared the position of the hand at baseline versus immediately before the
508 express arm response and observed no relationship between the level of anticipatory activity and
509 any change in hand position ($p > 0.05$). This suggests the anticipatory activity did not move the
510 hand, perhaps because any arising forces were insufficient to overcome the inertia of the hand, or
511 because of co-contraction of antagonist muscles.



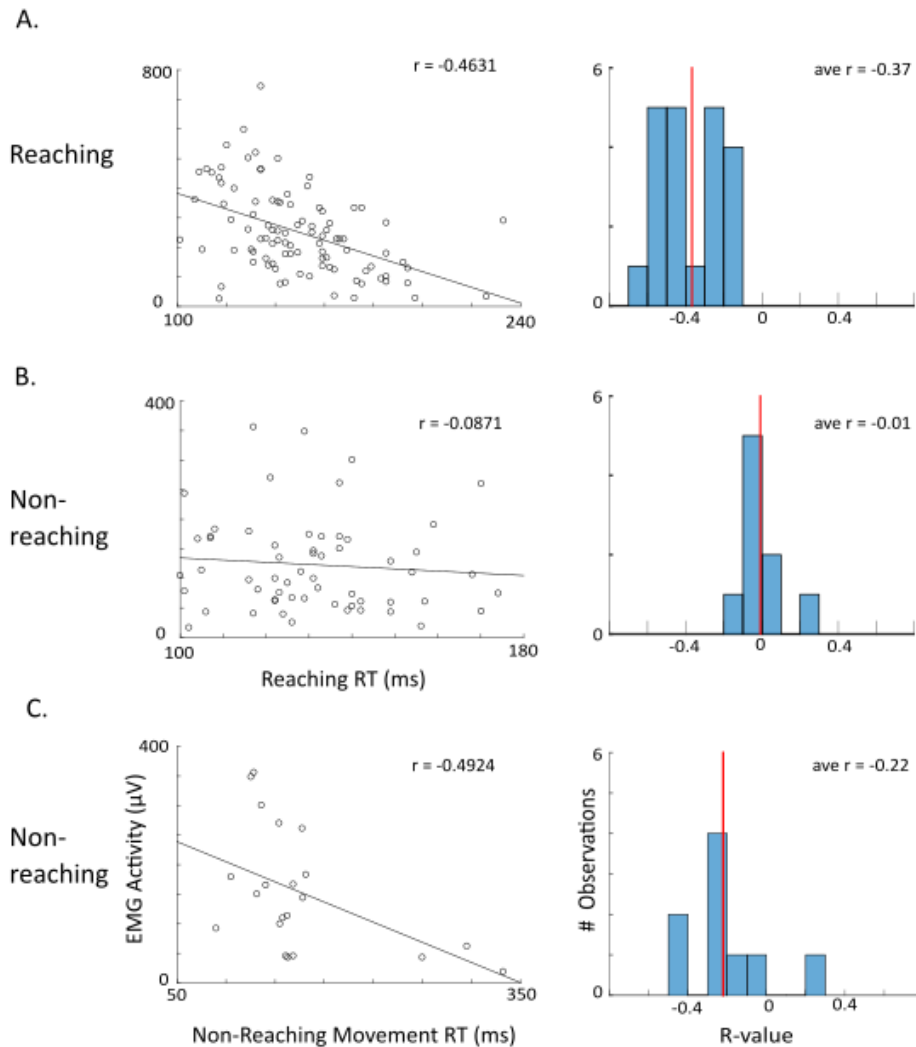
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513 Figure 7. Velocity traces for the exemplar participant. A) Average velocity (+/- SE) for both the
514 reaching and non-reaching arm across locations, with the first or second black dot representing
515 the latency of the express arm response when present when the two- or three-piece linear
516 regression was used to detect the response respectively. Expanded graphs represent the velocity

517 trace from the non-reaching arm at the target of subjective equality, at an enlarged y-axis scale.
518 B) Scatter plot showing the peak velocity of the reaching vs non-reaching arm. Black dashed line
519 shows line of unity and symbols depict whether an express arm response was observed on the
520 non-reaching arm or not.
521

522 A key behavioural correlation seen in previous research using unimanual tasks is that
523 larger express arm responses tend to precede shorter-latency RTs (1, 4). Given that this study is
524 the first to study express arm responses in a bimanual task, we examined our data for the
525 presence of any relationships between express arm responses and RTs. We first confirmed that
526 the express arm response magnitude in the reaching arm is negatively correlated to reach RT (left
527 panel of **Figure 8A** shows trial-by-trial data for the right PEC from the exemplar participant;
528 right panel of **Figure 8A** shows that the r-values across all participants with an express response
529 at the target of equal selection lay significantly below zero; average $r = -0.3672$, $p < 0.001$, $t =$
530 10.4419 , $df = 20$). Next, we examined whether the magnitude of the express arm response on the
531 non-reaching arm related to the RT of the reaching arm, as a common drive mechanism predicts
532 that a larger express arm muscle response on the non-reaching arm should precede shorter
533 latency RTs on the reach arm. However, we found no relationship between the magnitude of the
534 express arm response on the non-reaching arm and the RT of the reaching arm either in the
535 exemplar participant (left panel of **Figure 8B**) or across the sample (the distribution of r-values
536 in right panel in **Figure 8B** does not differ from zero, average $r = -0.0087$, $p > 0.05$, $t = 0.25$, $df =$
537 8). Instead, as we were able to occasionally extract a RT from the movement of the non-reaching
538 arm, we found a weaker albeit significant negative correlation between non-reaching express arm
539 response magnitude and non-reaching movement RT (left panel of **Figure 8C** for exemplar
540 participant; right panel of **Figure 8C** for the sample; average $r = -0.2207$, $p = 0.0119$, $t = 3.2369$,
541 $df = 8$). This final negative correlation does show a relationship between the express arm

542 response on the non-reaching arm and the reaction time for the small movement of that arm,
543 even when the other arm intercepts the target.



544

545 Figure 8. Correlations for express arm response magnitude and reaction time. A) In both the
546 exemplar participant (Left; each point represents data from a single trial) and population (Right)
547 there is a negative trial-by-trial correlation between the magnitude of the express arm response in
548 the reaching arm and the reaction time of the movement. B) No such negative relationship was
549 observed between the magnitude of the express arm response on the non-reaching arm and the
550 reaction time of the reaching arm for either the exemplar participant or across the sample. C) A
551 weaker negative correlation was observed between the express arm response on the non-reaching
552 arm and the reaction time of the non-reaching arm (when a movement was present).

553 **Discussion**

554 We investigated whether the express arm response occurs bilaterally in a task where
555 either arm can be used to intercept a target. We were particularly interested in the prevalence,
556 timing, and magnitude of any express arm responses in the reaching versus non-reaching arm, as
557 well as how these measures related to anticipatory muscle recruitment attained just before the
558 express arm response, and to the kinematics of any associated movement. We found that express
559 arm responses occurred on both the reaching and non-reaching arms, and that express arm
560 response magnitude interacted with the preceding level of anticipatory activity. Express arm
561 responses on the non-reaching arm did relate to aspects of small movements of the non-reaching
562 arm, consistent with this phase of muscle recruitment imparting functional consequences. When
563 integrated with reports in the literature on express arm responses in unimanual tasks, our results
564 are consistent with a reticular transmission of signals arising soon after target onset in the
565 superior colliculus, and the interaction of such signals with pre-existing activity related to the
566 anticipation of target appearance that presumably have a cortical origin. Interactions between
567 cortical and subcortical descending pathways may occur at spinal or supraspinal levels.

568

569 *Comparison to past studies and methodological considerations*

570 The emerging target paradigm (23) has emerged as an efficient means to elicit express
571 arm responses, increasing the prevalence and magnitude of the response (5, 12, 24). Past work
572 has investigated how certainty about the time of target emergence (5), cueing (24), or the
573 properties of the emerging target (5, 12) influence the express arm response. All such work using
574 the emerging target task, as well as all past studies of the express arm response (1, 4, 9)
575 investigated reaches made with one arm. In contrast, in our modified emerging target paradigm,

576 either arm could be used to intercept the target while muscle activity was recorded bilaterally.
577 Further, we increased the number of potential target locations from two used previously to seven.
578 Despite these changes, express arm responses were reliably observed, as all participants
579 exhibited an express arm response to at least one target. We attribute this to the modified
580 paradigm maintaining implied motion behind the barrier and a high degree of certainty about the
581 time of target emergence, which have been suggested to be the main factors increasing express
582 arm response prevalence and magnitude in this paradigm (5, 12, 23).

583 In our study, participants were required to choose which arm reached to the emerging
584 target, doing so as quickly as possible. Previous work has shown that arm choice tends to reflect
585 the hemifield of the target, with a slight bias to use the dominant hand at center (30, 31). In the
586 modified emerging target paradigm used in this study, the logarithmic spacing of the targets
587 under the occluder was chosen to try to find a target location which would elicit reaches from the
588 right arm on some trials and from the left arm on others. Previous versions of a hand-choice task
589 did not instruct participants to reach as fast as possible (30, 31) leading to the possibility that the
590 dominant hand would be used for all targets in this version of the modified emerging target
591 paradigm. Instead, we found that even with the added pressure to be fast, hand choice still
592 largely reflected the hemifield of presentation.

593 Our overall task design was intended to find, for each subject, a target location that
594 elicited reaches with the right arm on some trials, and with the left arm on others; doing so
595 enabled evaluation of muscle activity and express arm responses as a function of whether the
596 associated arm was selected to reach or not, for movements to the exact same visual target. For
597 most participants ($n = 10$), this target of equal selection was the center target. Assuming
598 participants followed task instruction, this center target would be almost (~ 1 degree below) at the

599 fovea. Given that foveal visual stimuli are represented bilaterally in the superior colliculus (32),
600 could this explain our observation of bilateral express arm responses? We think this is unlikely
601 for three reasons. First, equivalent results were obtained for the four participants who had off-
602 centre targets of equal selection (two participants at each of 3 or 7 cm to the left, equating to ~3
603 or 7 degrees of visual angle); such visual targets are represented unilaterally in the superior
604 colliculus. Second, targets that were not the target of equal selection still provoked bilateral
605 responses; it was simply that reaches to these locations were predominantly done by one arm.
606 Third, past work dissociating initial eye and hand position have shown that the express arm
607 responses encode the location of the visual stimulus relative to the current position of the hand,
608 not the eye (3).

609 Our paradigm was not designed to control for the retinal velocity of the moving target. As
610 a consequence of our setup, the retinal image of the central target moved more rapidly than the
611 image of more peripheral targets. That being said, we did not find any influence of target
612 location on the magnitude of express arm responses on either the reaching or non-reaching arm.
613 Previous work has reported that faster moving targets evoke larger express arm responses (12),
614 but the range of actual retinal velocities used in our experiment may not have been large enough
615 to reveal this effect. Related work by Cross and colleagues requiring on-line corrections
616 following a jump in cursor position has also found that the earliest visuomotor responses are
617 invariant for jumps that are greater than 2 cm in magnitude (33). Given these results, the lack of
618 any relationship between target location and express arm response magnitude is not surprising,
619 although future work that more systematically investigates this question may be needed.

620 Another key difference between the current and past studies is the location of potential
621 targets relative to the starting position of the hand. In past work, potential targets were positioned

622 to the left and right of the starting position of the hand, and express arm responses were detected
623 via analysis of increases or decreases in muscle activity following target presentation into or out
624 of the muscle's preferred direction of movement. Here, all targets lay medial to the starting
625 position of the hand, and hence in the preferred direction for pectoralis major. We accordingly
626 developed a new method for detecting express arm responses, which depended on the ratio of the
627 loss (i.e., sum of errors squared) for the two-piece, and three-piece linear regression, and
628 significant differences in the slopes of linear regressions fit to EMG activity during a baseline or
629 anticipatory and express arm response interval. This method appears to be conservative,
630 classifying instances of muscle recruitment as not exhibiting an express arm response despite an
631 inflection being present. This was especially present when there was a higher level of noise in
632 the background activity, and for the non-reaching arm. When express arm responses were
633 detected with this method, they invariably displayed the characteristic trial-by-trial changes in
634 muscle recruitment that were more aligned to target rather than movement onset (e.g., **Figure**
635 **3B**). The lack of specificity of our detection method, which leads to an increased rate of false
636 negatives may partly explain the higher prevalence of responses found in the reaching arm, and
637 the absence of any relationship between the presence or absence of express arm responses and
638 peak velocity on the non-reaching arm (**Figure 7B**)

639 Express arm responses were observed in the reaching and non-reaching arm regardless of
640 whether the dominant or non-dominant arm was chosen to reach. However, all participants
641 included in the analysis were either right hand dominant (n = 12) or ambidextrous (n = 2) as
642 determined by the handedness questionnaire. Previous studies of express arm responses have
643 similarly reported a low number of left-handed participants (1, 5, 12), but there has been no
644 suggestion of any difference in the results of left- and right-handed participants. We speculate

645 that the express arm response would remain bilateral in left-hand dominant participants, but
646 further studies using a larger proportion of left-handed participants would be needed to confirm
647 this assertion.

648

649 *Interactions between anticipatory recruitment, the express arm response, and voluntary reach-*
650 *related activity*

651 In our task, all targets emerged medial to the starting position of the hand. Combined
652 with certainty about the time of target emergence, it is not surprising that participants anticipated
653 target emergence to a degree that influenced muscle recruitment. Such anticipatory recruitment,
654 which we presume has a cortical origin as participants become quite familiar with task structure
655 over repeated trials, influenced the magnitude but not timing of the express arm response;
656 participants with greater levels of anticipatory recruitment tended to have larger express arm
657 responses (**Figure 5E**), and anticipatory recruitment tended to be larger when the associated arm
658 was selected to reach (**Figure 5D**). Although our experiment was not designed to systematically
659 vary the muscle recruitment immediately preceding the express arm response, the relationships
660 between anticipatory recruitment and express arm responses resemble gain scaling seen for the
661 spinal stretch reflex following a mechanical perturbation of the arm (34). Gain scaling likely
662 arises from intrinsic properties at the motoneuron pool from the size-recruitment principle;
663 importantly, recruitment from subsequent longer-loop reflexes may not be gain-scaled, if it were
664 to be counterproductive to the task at hand. A future line of research should investigate whether
665 the express arm response indeed exhibits gain scaling; this could be done by systematically
666 varying the loading force on the muscle of interest and investigating the influence on both the
667 express arm responses and on ensuing phases of recruitment.

668 Regardless of whether the relationship between anticipatory activity and the magnitude of
669 the express arm response arises from gain scaling, anticipatory activity in some participants was
670 significantly greater on the arm that ultimately reached to the target. This is apparent in the time-
671 series ROC analysis in **Figure 7**, where arm choice could frequently be predicted by analyzing
672 muscle activity preceding the express arm response interval. Such anticipatory recruitment
673 suggests that some participants have already committed, to some degree, which arm they were
674 more likely to use to reach to the target. We can only speculate as to why this may be the case; it
675 may be because of trial history or fatigue (e.g., a bias to move one arm if the other arm was used
676 on the previous trials). Development of a bias favoring one arm over the other may explain the
677 lack of a relationship between the magnitude of the express arm response on the non-reaching
678 arm and the reaction time of the reaching arm (**Figure 8B**), as a common bilateral drive to both
679 muscles would predict a negative relationship between the express arm response magnitude of
680 either arm and the reach RT. Instead, since the magnitude of the express arm response is also
681 influenced by anticipatory activity, a bias in anticipatory activity toward the reaching arm and
682 against the non-reaching arm muted the magnitude of the express arm response on the latter
683 further demonstrating the independence of the express arm response from the reach-related
684 activity.

685 A common observation in previous work is that larger express arm responses precede
686 shorter RTs (1, 4), and we observed a similar relationship here. Importantly, this was observed
687 on the muscles of both the reaching and non-reaching arm and the reaction time of the associated
688 arm (when a reaction time for the non-reaching arm could be extracted). A comparison of the
689 evolution of muscle activity on the reaching versus non-reaching arm is quite interesting;
690 whereas express arm responses are readily apparent on both, subsequent phases of more

691 prolonged recruitment are only observed on the reaching arm. The kinematics of movement of
692 the non-reaching arm provides an opportunity to better understand the kinetic consequences of
693 the relatively brief express arm response, and similar to previous results (4, 28, 29), the express
694 arm response is associated with a small movement of the non-reaching arm toward the target
695 followed by a reversal in the voluntary response epoch. This reaffirms that, despite the relatively
696 brief nature of the express arm response, it is not without a kinetic consequence even on the non-
697 reaching arm. Further, an express arm response on the reaching arm may also influence the
698 kinetic consequences of the ensuing phases of voluntary reach-related activity through repeated
699 activation of the same muscle fiber (35).

700

701 *Is the reticular formation involved in the express arm response?*

702 There is considerable circumstantial evidence that express arm responses arise from
703 signalling along a tecto-reticulo-spinal pathway (1, 4, 9, 16, 28). Many of the key response
704 properties of express arm responses resemble those of express saccades, in which the role of the
705 superior colliculus is well understood (36, 37). Further, the related phenomenon of express neck
706 responses has been directly correlated to visual responses in the intermediate superior colliculus
707 of monkeys (38). The interface between the superior colliculus and motor periphery is likely
708 indirect, and our work here adds to a small body of literature that more has considered the
709 potential involvement of other interfaces. For example, Glover and Baker (2019) reported
710 enhanced express arm responses (what they termed rapid visual responses) in a unimanual
711 response task when visual stimuli were combined with other auditory, vestibular, or
712 somatosensory stimuli. Such non-visual stimuli are thought to enhance responses in the reticular
713 formation, hence they attributed the facilitation they observed on express arm responses to the

714 influence of such non-visual stimuli in the reticular formation (2). Further, using an elegant
715 combination of transcranial brain stimulation and electrical stimulation of the median nerve,
716 Nakajima, Suzuki and colleagues proposed that rapid limb responses to changing visual inputs
717 attested to the integration within cervical interneurons of corticospinal inputs with visual
718 information rapidly relayed along a subcortical tectoreticulospinal pathways (39, 40). Whether
719 cervical interneurons are involved in the generation of express arm responses, perhaps in
720 conjunction to the reticular formation, remains to be determined but this seems likely given the
721 broad convergence between descending motor pathways (41).

722 One may wonder whether the express arm response arises from the corticospinal rather
723 than tecto-recticulo-spinal pathway. Our results add to a growing albeit indirect body of literature
724 supporting the involvement of the tecto-recticulo-spinal pathway (1, 4, 9, 12, 16, 28). Although
725 the corticospinal tract does project both contra- and ipsilaterally, ipsilateral projections are more
726 sparse (18, 19) and the latency of ipsilateral versus contralateral motor-evoked potentials are
727 consistently longer (20–22, 42). In contrast, the express arm response occurs at the same latency
728 in the reaching and non-reaching arms.

729 Another area of future research should address how malleable the bilateral distribution of
730 express visuomotor responses would be with changes in body posture, target position, or loading
731 force. Our positioning of targets medial to both hands, with loading forces in the opposite
732 direction, meant that pectoralis major was the only muscle on which the bilateral distribution of
733 express muscle responses could have been assessed. Having established that express arm
734 responses can be distributed bilaterally, future experiments should look at other limb muscles, or
735 configurations where a given target could be reached by contraction of a given muscle in one
736 arm or relaxation of the same muscle on the other arm (e.g., by altering loading forces). Indeed,

737 although there is substantial variability, the most common bilateral recruitment profile evoked by
738 stimulation of the reticular formation is ipsilateral muscle facilitation and contralateral muscle
739 suppression (43). If the pathway mediating the bilateral distribution of express muscle responses
740 is to have any functional benefit, it would seem to be a necessity to be able to flexibly map target
741 locations onto different combinations of bilateral muscle recruitment.

742

743 *Conclusions*

744 Our work here contributes to the understanding of the phenomenology of express arm responses,
745 showing for the first time, to our knowledge, that the underlying pathway distributes the motor
746 signal bilaterally. Our results are largely consistent with the involvement of the reticular
747 formation as an interface between the superior colliculus and motor periphery. Our overall
748 hypothesis is that signalling along the tectoreticulospinal pathway initiates the first wave of limb
749 muscle recruitment in circumstances requiring rapid visually-guided reaching. We are mindful,
750 however, of the possibility of the convergence of cortical inputs into all nodes of this pathway,
751 including the superior colliculus, the reticular formation, spinal interneuron networks, and the
752 motoneuron. Rather than being directly involved in express arm responses, cortical inputs into
753 these subcortical nodes, for example with anticipatory signals that bias arm choice, can dampen,
754 or augment the vigor of the earliest visually-related responses. Further characterization of the
755 properties of express arm responses, and the integration of such signalling with task-relevant
756 information, can more precisely address the underlying neural mechanisms and the integration of
757 such signalling with cortical inputs that initiate and guide our most rapid visually-guided
758 behaviours.

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