gcFront: a tool for determining a Pareto front of growth-coupled

cell factory designs

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ABSTRACT

Motivation: A widely applicable strategy for developing evolutionarily robust cell factories is to knock out (KO)

genes or reactions to couple chemical synthesis with cell growth. Genome-scale metabolic models enable their

rational design, but KOs that provide growth-coupling (gc) are rare in the immense design space, making searching

difficult and slow, and though several measures determine the utility of those strains, few drive the search.

Results: To address these issues we developed a software tool named gcFront - using a genetic algorithm it explores

KOs that maximise key performance objectives: cell growth, product synthesis, and coupling strength. Our measure

of coupling strength facilitates the search, so gcFront not only finds a gc-design in minutes but also outputs many

alternative Pareto optimal gc-designs from a single run - granting users freedom to select designs to take to the lab.

Availability and Implementation: gcFront, with documentation and a workable tutorial, is freely available at

GitHub: https://github.com/lLegon/gcFront, the repository of which is archived at Zenodo, DOI:

10.5281/zenodo.5557756 (Legon *et al.*, 2021).

Supplementary Information: Supplementary notes and data files are available at Bioinformatics online.

INTRODUCTION

Genome-scale constraint-based models (GSMs) are used to explore gene or reaction knockouts (KOs) that rewire cell metabolism for chemical overproduction (Maia *et al.*, 2016). A promising strategy for enabling robust chemical synthesis seeks KO combinations that couple production with cell growth so product synthesis becomes obligatory at maximum cell growth rate (Ohno *et al.*, 2014; Feist *et al.*, 2010). Though KOs can disrupt metabolism, resulting in poorer performance than predicted, growth-coupling allows the selection of higher producing phenotypes through adaptive laboratory evolution, which can even find strains with synthesis and growth rates near the predicted optimal (Tokuyama *et al.*, 2018). Moreover, designs with stronger coupling, where smaller drops in synthesis strongly impair growth, could make synthesis more robust, both with respect to evolution by creating stronger selection pressure to conserve optimal synthesis; and to a heterogeneous growth environment by conserving high synthesis in suboptimally-growing cells. Growth-coupling is a widely applicable strategy (von Kamp and Klamt, 2017), but KOs enabling this are rare, making the search for them difficult and slow (Ohno *et al.*, 2014). Also, fast growth, high synthesis, and strong coupling are desirable characteristics of a strain design, the search for which we address as a multiobjective optimization problem. To solve it, we developed a software tool named gcFront that determines KO sets that predict phenotypes maximal in these three performance objectives, for any chemical and host of interest. Moreover, our proposed measure of coupling strength facilitates the search through the design space, so that gcFront outputs many Pareto optimal designs from a single run, in reasonable time.

THE gcFRONT WORKFLOW

gcFront works in MATLAB, with dependencies on the COBRA toolbox (Heirendt *et al.*, 2019) for analysis of a compatible GSM; and the MATLAB Global Optimization toolbox for solving the multiobjective optimization problem (Supplementary Note 1A). The workflow, detailed in Supplementary Note 1B and Supplementary Fig. 1, entails four fundamental steps.

Inputs. Two interactive windows allow the user to define the GSM and target metabolite product or its exchange reaction, and optional inputs (Supplementary Table 1), like maximum number of KOs and search time.

Preprocessing. To reduce the sets of KOs and search space, dead reactions are removed, unbranched pathways are lumped into composite reactions, and single KOs essential *in silico* for growth or synthesis are excluded.

Solving the optimization problem. To determine growth-coupled (gc-)designs, gcFront solves the multiobjective

optimisation problem defined in Supplementary Note 2A. Our measure of coupling strength shapes the search

landscape; it defines weak and strong coupling but also distinguishes between uncoupled designs (Supplementary

Note 2B, Supplementary Fig. 2a). It assigns higher values to KOs that reduce the cost to growth for increases in the

maximum allowable synthesis, thus driving bias to gc-designs (Supplementary Fig. 2b) to ease the search.

Post-processing and output. On termination (conditions in Supplementary Table 1), many Pareto optimal KO sets

are found from a single run. Genes/reactions that do not affect performance if ignored are removed from each set,

and the Pareto front of designs and their performance is output to an interactive plot, a table in the command

window, and a .csv file. Users can select designs they deem suitable for their chemical and host of interest, based on

bespoke combinations of the performance metrics. A tutorial is given in Supplementary Note 3.

COMPARATIVE PERFORMANCE ASSESSMENT

To test gcFront's performance, we compared it to other MATLAB-based procedures that identify gc-designs,

including RobustKnock (Tepper and Shlomi, 2009) as implemented in OptPipe (Hartmann *et al.*, 2017); gcOpt

(Alter and Ebert, 2019); FastPros (Ohno *et al.*, 2014); and OptGene (Patil *et al.*, 2005) as implemented in COBRA

(Heirendt *et al.*, 2019). We ran each for 6 hours, saved the gc-designs found and the time they needed to find their

first gc-design, repeating this three times for gcFront and OptGene because of the stochastic nature of searching with

a genetic algorithm. For a fair comparison, we ran each algorithm using the *E. coli* GSM model iML1515 (Monk *et*

al., 2017), for non-essential reaction KOs (*in silico* and based on (Goodall *et al.*, 2018)), for synthesis of succinate,

tyrosine, and pyruvate, as example products (detailed in Supplementary Notes 4 and Fig. 1). gcFront found the first

gc-design in 38% less time than gcOpt for succinate synthesis, 98% less time than RobustKnock for tyrosine

synthesis, and orders of magnitude less time than the other methods and products (Fig. 1a, Supplementary Data). Its

power was especially apparent when searching for designs of tyrosine and pyruvate synthesis – still finding designs

in minutes despite these designs, of at least six KOs, being rarer vs three KOs found for succinate (Supplementary

Fig. 3). Furthermore, though the single gc-design found with other methods lay near the Pareto front of gc-designs

from gcFront, gcFront offered many designs that achieved at least higher coupling strength (Fig. 1b, Supplementary

Data).

a. **Time to first** gc-design **b.** **Pareto front** of gc-designs

Fig. 1. gcFront finds many Pareto optimal growth-coupled designs, faster, and with superior performance vs other algorithms. The speed
and designs found from 6-hour runs of gcFront were compared to those of RobustKnock, gcOpt, FastPros, and OptGene (see Supplementary Note
4) on a MacBook Pro (2.3 GHz Quad-Core Intel core i5 processor, 8GB 2133 MHz LPDDR3 RAM). Designs were based on KOs of only non-
essential, gene-associated reactions, for the synthesis of three example products: succinate, tyrosine, and pyruvate from the *E. coli* iML1515 GSM
model, in aerobic, minimal media with glucose. (**a**). Time to identify the first gc-design from each procedure. Due to the stochastic nature of
searching using the genetic algorithm in OptGene and gcFront, the average (bars) and standard deviation (error bars) of times are reported from
three runs (N=3, ±SD). (**b**). Pareto fronts of all gc-designs found from three 6-hour runs.

DISCUSSION

gcFront can find a multitude of Pareto opti

a single run, in a computationally efficient

maximised objectives, the user is free to se

chemical product of interest, e.g. sacrifice growth for stronger coupling and synthesis, for instance for more robust

pyruvate synthesis (Fig. 1b); or sacrifice synthesis for higher growth and stronger coupling, for instance for higher

volumetric productivity with robust synthesis of succinate (Fig. 1b) – making it widely applicable to different

contexts. It is also user friendly, but versatile – the interactive user interface means no coding is required, making

gcFront easy to use out-of-the-box, yet because it is a function in the MATLAB environment it can be easily

integrated within a wider pipeline. For instance, it could complement pipelines automating the construction of

synthetic metabolic pathways (Carbonell *et al.*, 2018) ‑ serving as an input to envisioned robotic labs implementing

KOs (Sinha *et al.*, 2018) and adaptive laboratory evolution (Radek *et al.*, 2017), for evolving optimally performing

phenotypes.

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AUTHOR CONTRIBUTIONS

LL, AAM: developed theory; LL: developed code, ran procedures, plotted results; AAM, DGB: designed and

supervised the research; all authors: wrote the paper.

CONFLICT OF INTEREST

None declared.

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