

1 TreeSearch: morphological phylogenetic analysis in R

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5 *Running head:* Parsimony analysis in R

6

7 *Abstract.*—TreeSearch is an R package for phylogenetic analysis, optimized for morphological
8 datasets. Tree search may be conducted using equal or implied step weights with an explicit
9 (albeit inexact) allowance for inapplicable character entries, avoiding some of the pitfalls
10 inherent in standard parsimony methods. Profile parsimony and user-specified optimality criteria
11 are supported.

12 A graphical interface, which requires no familiarity with R, is designed to help a user to
13 improve the quality of datasets through critical review of underpinning character codings; and to
14 obtain additional information from results by identifying and summarizing clusters of similar
15 trees, mapping the distribution of trees, and removing ‘rogue’ taxa that obscure underlying
16 relationships.

17 Taken together, the package aims to support methodological rigour at each step of data
18 collection, analysis, and the exploration of phylogenetic results.

19 *Key words*

20 phylogenetic software, morphological phylogenetic analysis, implied weights, parsimony,
21 inapplicable characters, rogue taxa, tree space.

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22 Even in the phylogenomic era, morphological data make an important contribution to
23 phylogenetic questions. Phenotypic data improve the accuracy and resolution of phylogenetic
24 reconstruction even when outnumbered by molecular characters, and are the only way to
25 incorporate the unique perspective on historical events that fossil taxa provide (Wiens 2004;
26 Wortley and Scotland 2006; Koch and Parry 2020; Asher and Smith 2022).

27 One challenge with morphological analysis is the treatment of inapplicable character
28 states: for example, ‘tail colour’ cannot logically be ascribed either of the states ‘red’ or ‘blue’ in
29 a taxon that lacks a tail (Maddison 1993). This situation can profoundly mislead phylogenetic
30 analysis, and is not handled appropriately by any standard Markov model or parsimony method.

31 Solutions to this issue have recently been proposed (De Laet 2005; Brazeau et al. 2019;
32 Tarasov 2019; Goloboff et al. 2021; Hopkins and St. John 2021). Where a single ‘principal’
33 character (e.g. ‘tail’) exhibits n ‘contingent’ characters (e.g. ‘tail colour,’ ‘tail covering’), ‘exact’
34 solutions (Tarasov 2019; Goloboff et al. 2021) require the construction of multi-state hierarchies
35 containing $O(2^n)$ entries, meaning that analysis is only computationally tractable for simple
36 hierarchies with few contingent characters. Moreover, these approaches cannot accommodate
37 characters that are contingent on more than one principal character: for example, characters
38 describing appendages on a differentiated head may be contingent on the presence of the two
39 characters ‘appendages’ and ‘differentiated head.’

40 Such situations can be approached using the flexible but approximate parsimony
41 approach proposed by Brazeau et al. (2019). TreeSearch scores trees using the “Morphy” C
42 implementation of this algorithm (Brazeau et al. 2017). Morphy implements tree search under
43 equal step weights. TreeSearch additionally implements implied step weighting (Goloboff 1993),

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44 a method which consistently finds more accurate and precise trees than equal weights parsimony
45 ([Goloboff et al. 2008, 2018a](#); [Smith 2019a](#)).

46 There has been lively discussion as to whether, with the rise of probabilistic approaches,
47 parsimony remains a useful tool for morphological phylogenetics (e.g. [O'Reilly et al. 2016](#);
48 [Puttick et al. 2017](#); [Brown et al. 2017](#); [Sansom et al. 2018](#); [Goloboff et al. 2018b](#)).

49 Notwithstanding scenarios that go beyond the limits of parsimony, such as the simultaneous
50 incorporation of stratigraphic data and other prior knowledge (e.g. [Guenser et al. 2021](#)), neither
51 parsimony nor probabilistic methods consistently recover 'better' trees when gains in accuracy
52 are balanced against losses in precision ([Smith 2019a](#)). Even if probabilistic methods may
53 eventually be improved through the creation of more sophisticated models that better reflect the
54 nature of morphological data ([Goloboff et al. 2018a](#); [Tarasov 2019](#)), parsimony analysis remains
55 a useful tool – not only because treatments of inapplicable character states are presently
56 available, but also because it facilitates a deeper understanding of the underpinning data by
57 emphasizing the reciprocal relationship between a tree and the synapomorphies that it implies.

58 Whatever method is used to find phylogenetic trees, a single consensus tree may fail to
59 convey all the signal in a set of phylogenetic results ([Wilkinson 1994, 1996, 2003](#)). A set of
60 optimal trees can be better interpreted by examining consensus trees generated from clusters of
61 similar trees ([Stockham et al. 2002](#)); by exploring tree space ([Wright and Lloyd 2020](#); [Smith](#)
62 [2022a](#)) and by automatically identifying, annotating and removing 'wildcard' taxa ([Smith 2022b](#))
63 whose 'rogue' behaviour may reflect underlying character conflict or ambiguity ([Kearney 2002](#)).
64 These methods are not always easy to integrate into phylogenetic workflows, so are not routinely
65 included in empirical studies.

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66 TreeSearch provides functions that allow researchers to engage with the three main
67 aspects of morphological phylogenetic analysis: dataset construction and validation;
68 phylogenetic search (including with inapplicable data); and the interrogation of optimal tree sets.
69 These functions can be accessed through the R command-line, as documented within the package
70 and at ms609.github.io/TreeSearch/, or via an integrated graphical user interface (GUI), with
71 options to save outputs in graphical formats or as Nexus or Newick files for further analysis.

72 IMPLEMENTATION

73 *Dataset review*

74 Ultimately, the quality of a dataset plays a central role in determining the reliability of
75 phylogenetic results, with changes to a relatively small number of character codings potentially
76 exhibiting an outsized impact on reconstructed topologies ([Goloboff and Sereno 2021](#)).
77 Nevertheless, dataset quality does not always receive commensurate attention ([Simões et al.](#)
78 [2017](#)). One step towards improving the rigour of morphological datasets is to annotate each cell
79 in a dataset with an explicit justification for each taxon's coding ([Sereno 2009](#)), which can be
80 accomplished in Nexus-formatted data files ([Maddison et al. 1997](#)) using software such as
81 MorphoBank ([O'Leary and Kaufman 2011](#)).

82 TreeSearch presents such annotations alongside a reconstruction of each character's states
83 on an optimal tree, with inapplicable states mapped according to the algorithm of [Brazeau et al.](#)
84 ([2019](#)). Neomorphic (presence/absence) and transformational characters ([Sereno 2007](#)) are
85 distinguished by reserving the token \emptyset to solely denote the absence of a neomorphic character,

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86 with tokens 1 ... n used to denote the n states of a transformational character (Brazeau et al.
87 2019).

88 This visualization of reconstructed character transitions can help to identify cases where
89 the formulation of characters has unintended consequences (Wilkinson 1995; Brazeau 2011);
90 where inapplicable states have been inconsistently applied (Brazeau et al. 2019); where
91 taphonomic absence is wrongly coded as biological absence (Donoghue and Purnell 2009);
92 where previous datasets are uncritically recycled (Jenner 2001); or where taxa are coded with
93 more confidence than a critical evaluation of available evidence can truly support. Insofar as the
94 optimal tree and the underlying characters are reciprocally illuminating (Mooi and Gill 2016),
95 successive cycles of phylogenetic analysis and character re-formulation can improve the integrity
96 of morphological datasets, and thus increase their capacity to yield meaningful phylogenetic
97 results (Hennig 1966).

98 *Tree search*

99 The TreeSearch GUI uses the routine `MaximizeParsimony()` to search for optimal trees using
100 tree bisection and reconnection (TBR) searches and the parsimony ratchet (Nixon 1999). This
101 goes beyond the heuristic tree search implementation in the R package “phangorn” (Schliep
102 2011) by using compiled C code to rearrange trees, accelerating computation; and in supporting
103 TBR rearrangements, which explore larger neighbourhoods of tree space: TBR evaluates more
104 trees than nearest-neighbour interchanges or subtree pruning and regrafting, leading to additional
105 computational expense that is offset by a decreased likelihood that search will become trapped in
106 a local optimum (Goeffon et al. 2008; Whelan and Money 2010).

107 By default, search begins from a greedy addition tree generated by function
108 `AdditionTree()`, which queues taxa in a random order, then attaches each taxon in turn to the

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109 growing tree at the most parsimonious location. Search may also be started from neighbour-
110 joining trees, or the results of a previous search.

111 Search commences by conducting TBR rearrangements – a hill-climbing approach that
112 locates a locally optimal tree from which no tree accessible by a single TBR rearrangement has a
113 better score. A TBR iteration breaks a randomly selected edge in the focal tree, and reconnects
114 each possible pair of edges in the resultant sub-trees to produce a list of candidate trees. Entries
115 that are inconsistent with user-specified topological constraints are removed; remaining trees are
116 inserted into a queue and scored in a random sequence. If the score of a candidate tree is at least
117 as good as the best yet encountered (within the bounds of an optional tolerance parameter ϵ ,
118 which allows the retention of almost-optimal trees in order to improve accuracy (e.g. [Smith](#)
119 [2019a](#))), this tree is used as the starting point for a new TBR iteration. Otherwise, the next tree in
120 the list is considered. TBR search continues until the best score is found a specified number of
121 times; a specified number of TBR break points have been evaluated without any improvement to
122 tree score; or a set amount of time has passed.

123 When TBR search is complete, iterations of the parsimony ratchet ([Nixon 1999](#)) are
124 conducted in order to search areas of tree space that are separated from the best tree yet found by
125 ‘valleys’ that cannot be traversed by TBR rearrangements without passing through trees whose
126 optimality score is below the threshold for acceptance. Each ratchet iteration begins by
127 resampling the original matrix. A round of TBR search is conducted using this resampled matrix,
128 and the tree thus produced is used as a starting point for a new round of TBR search using the
129 original data.

130 After a specified number of ratchet iterations, an optional final round of TBR search
131 allows a denser sampling of optimal trees from the final region of tree space.

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132 During tree search, all trees whose score is within ϵ of the best score are retained, and
133 tagged with the iteration in which they were first identified. This allows the progress of tree
134 search to be visualized in tree space (Fig. 1; after [Whidden and Matsen 2015](#)).

135 More flexible, if less computationally efficient, tree searches can be conducted at the
136 command line using the `TreeSearch()`, `Ratchet()` and `Bootstrap()` commands, which
137 support custom tree optimality criteria (e.g. [Hopkins and St. John 2021](#)).

138 *Tree scoring*

139 Trees may be scored using equal weights, implied weighting ([Goloboff 1993](#)), or profile
140 parsimony ([Faith and Trueman 2001](#)). The function `TreeLength()` calculates tree score using
141 the “Morphy” phylogenetic library ([Brazeau et al. 2017](#)), which implements the Fitch ([1971](#)) and
142 [Brazeau et al. \(2019\)](#) algorithms. Morphy returns the equal weights parsimony score of a tree
143 against a given dataset. Implied weights and profile parsimony scores are computed by first
144 making a separate call to Morphy for each character in turn, passed as a single-character dataset;
145 then passing this value to the appropriate weighting formula and summing the total score over all
146 characters.

147 Implied weighting is an approximate method that treats each additional step in a character
148 as less surprising – and thus requiring less penalty – than the previous step. Each additional step
149 demonstrates that a character is less reliable for phylogenetic inference, and thus more likely to
150 contain additional homoplasy. The score of a tree under implied weighting is $\sum \frac{e_i}{e_i+k}$, where e_i
151 denotes the number of extra steps observed in character i , and is derived by subtracting the
152 minimum score that the character can obtain on any tree from the score observed on the tree in

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153 question (Goloboff 1993). The minimum length of a tree is one less than the number of unique
154 applicable tokens that must be present.

155 Profile parsimony (Faith and Trueman 2001) represents an alternative formulation of how
156 surprising each additional step in a character is (Arias and Miranda-Esquivel 2004): the penalty
157 associated with each additional step in a character is a function of the probability that a character
158 will fit at least as well as is observed on a uniformly selected tree. On this view, an additional
159 step is less surprising if observed in a character where there are more opportunities to observe
160 homoplasy, whether because a character contains fewer ambiguous codings (a motivation for the
161 ‘extended’ implied weighting of Goloboff (2014)) or because states are distributed more evenly
162 in a character, whose higher phylogenetic information content (Thorley et al. 1998) corresponds
163 to a lower proportion of trees in which no additional steps are observed.

164 TreeSearch calculates the profile parsimony score by computing the logarithm of the
165 number of trees onto which a character can be mapped using m steps, using theorem 1 of Carter
166 et al. (1990). As computation for higher numbers of states (Maddison and Slatkin 1991) is more
167 computationally complex, the present implementation is restricted to characters that contain two
168 applicable tokens, and uses the Fitch (1971) algorithm.

169 *Visualization*

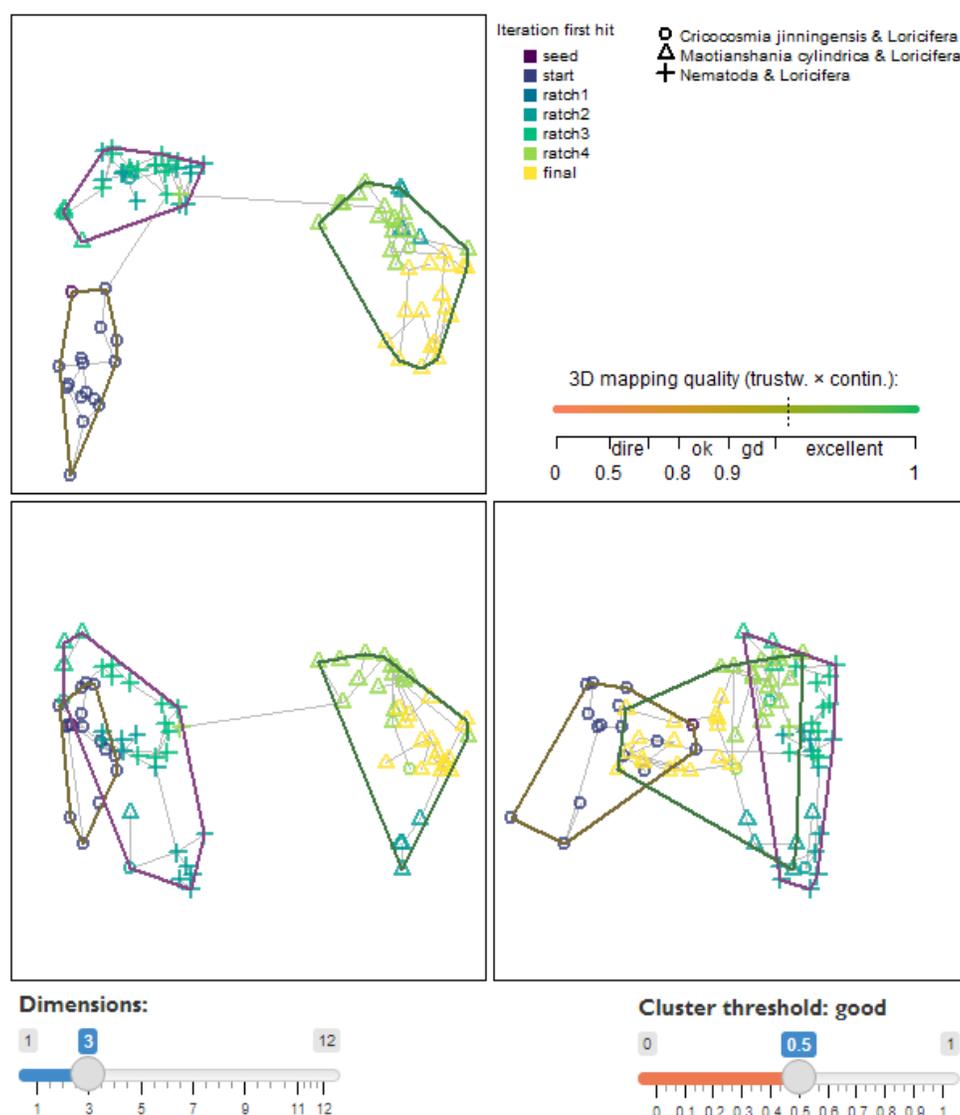
170 The distribution of optimal trees, however obtained, can be visualized interactively through
171 mappings of tree space (Hillis et al. 2005; Smith 2022a) using the TreeSearch GUI.

172 The GUI supports the use of information theoretic distances (Smith 2020a); the quartet
173 distance (Estabrook et al. 1985); or the Robinson–Foulds distance (Robinson and Foulds 1981)
174 to construct tree spaces, which are mapped into 2–12 dimensions using principal coordinates
175 analysis (Gower 1966). The degree to which a mapping faithfully depicts original tree-to-tree

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176 distances is measured using the product of the trustworthiness and continuity metrics (Venna and
177 Kaski 2001; Kaski et al. 2003; Smith 2022a), a composite score denoting the degree to which
178 points that are nearby when mapped are truly close neighbours (trustworthiness), and the degree
179 to which nearby points remain nearby when mapped (continuity). A visualization of stress is
180 provided by plotting the minimum spanning tree (Gower and Ross 1969); contortions in this tree
181 indicate that mapping has distorted original distances (Smith 2022a).

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183 **Figure 1. Three-dimensional map visualizing tree search progress. Optimal trees belong to**
184 **three statistically distinct clusters with good support (silhouette coefficient > 0.5),**
185 **characterized by different relationships between certain taxa (plotting symbols). Although**
186 **multiple ratchet iterations have visited each cluster, limited overlap between ratchet**
187 **iterations suggests that a continuation of tree search may sample novel optimal trees. High**
188 **trustworthiness and continuity values and a simple minimum spanning tree (grey) indicate**
189 **that the mapping does not exhibit severe distortion.**

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190 To relate the geometry of tree space to the underlying trees, each point in tree space may
191 be annotated according to the optimality score of its corresponding tree under a selected step
192 weighting scheme; by the relationships between chosen taxa that are inferred by that tree; and by
193 the search iteration in which the tree was first found by tree search (Fig. 1).

194 The latter feature can be used to evaluate whether a continuation of tree search is likely to
195 yield more optimal trees. For example, if the trees retained are first found only in later rounds of
196 tree search, this recent improvement in tree score suggests that a global optimum may not yet
197 have been reached. Alternatively, if each individual ratchet iteration samples a separate region of
198 tree space, it is likely that the landscape of optimal trees contains isolated ‘islands’ (Bastert et al.
199 2002), some of which may remain to be found. Continuing tree search until additional ratchet
200 iterations no longer locate new clusters of trees will reduce the chance that optimal regions of
201 tree space remain unvisited.

202 As the identification of clusters from mappings of tree space can be misleading (Smith
203 2022a), TreeSearch identifies clusters of trees from tree-to-tree distances using K-means
204 clustering, partitioning around medoids and hierarchical clustering with minimax linkage
205 (Hartigan and Wong 1979; Murtagh 1983; Bien and Tibshirani 2011; Maechler et al. 2019).
206 Clusterings are evaluated using the silhouette coefficient, a measure of the extent of overlap
207 between clusters (Kaufman and Rousseeuw 1990). The clustering with the highest silhouette
208 coefficient is depicted if the silhouette coefficient exceeds a user-specified threshold; the
209 interpretation of the chosen threshold according to Kaufman and Rousseeuw (1990) is displayed
210 to the user. Plotting a separate consensus tree for each cluster often reveals phylogenetic
211 information that is concealed by polytomies in the single ‘plenary’ consensus of all optimal trees
212 (Stockham et al. 2002).

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213 Plenary consensus trees can also lack resolution because of wildcard or ‘rogue’ taxa, in
214 which conflict or ambiguity in their character codings leads to an unsettled phylogenetic position
215 (Wilkinson 1994, 2003; Kearney 2002). TreeSearch detects rogue taxa using a heuristic approach
216 (Smith 2022b) that seeks to maximize the phylogenetic information content (*sensu* Thorley et al.
217 1998) of a consensus tree created after removing rogue taxa from input trees. The position of an
218 excluded taxon is portrayed by shading each edge or node of the consensus according to the
219 number of times the specified taxon occurs at that position on an underlying tree (Fig. 2; after
220 Klopstein and Spasojevic 2019), equivalent to the ‘branch attachment frequency’ of “Phyultity”
221 (Smith and Dunn 2008).

222 Identifying taxa with an unstable position, and splits with low support, can help an
223 investigator to critically re-examine character codings; to this end, each edge of the resulting
224 consensus can be annotated with the frequency of the split amongst the tree set, or with a
225 concordance factor (Minh et al. 2020) denoting the strength of support from the underlying
226 dataset.

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236 `TreeSearch::EasyTrees()`. It has been tested on all widely available operating systems and
237 requires only R packages available from the CRAN repository. Source code is available at
238 <https://github.com/ms609/TreeSearch/>, and is permanently archived at Zenodo
239 (<https://dx.doi.org/10.5281/zenodo.1042590>). Documentation is online at
240 <https://ms609.github.io/TreeSearch/>.

```
241 # Note: A temporary bug in the underlying package 'ape' v5.6 causes  
242 # issues reading trees from Nexus files.  
243 # A patched version should be installed before installing TreeSearch:  
244  
245   install.packages("remotes")  
246   remotes::install_github("ms609/ape@patch-3")  
247   install.packages("TreeSearch")  
248  
249 # The GUI can then be launched with:  
250  
251   library("TreeSearch")  
252   EasyTrees()
```

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256 employs the underlying R (R Core Team 2021) packages `ape` (Paradis and Schliep 2019),
257 `phangorn` (Schliep 2011), `Quartet` (Sand et al. 2014; Smith 2019b), `Rogue` (Smith 2022b), `shiny`
258 (Chang et al. 2021), `shinyjs` (Attali 2020), `TreeDist` (Smith 2020b), and `TreeTools` (Smith 2019c).

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259 DISCLOSURE STATEMENT

260 I am aware of no conflict of interest.

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