Quantitative Mapping of Keratin Networks in 3D

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Abstract

Mechanobiology requires precise quantitative information on processes taking place in specific 3D
microenvironments. Connecting the abundance of microscopical, molecular, biochemical and cell
mechanical data with defined topologies has turned out to be extremely difficult. Establishing such
structural and functional 3D maps needed for biophysical modeling is a particular challenge for the
cytoskeleton, which consists of long and interwoven filamentous polymers coordinating subcellular
processes and interactions of cells with their environment. To date, useful tools are available for the
segmentation and modeling of actin filaments and microtubules but comprehensive tools for the
mapping of intermediate filament organization are still lacking. In this work, we describe a workflow
to model and examine the complete 3D arrangement of the keratin intermediate filament cytoskeleton
in epithelial cells both in vitro and in vivo. Numerical models are derived from super resolution 3D
imaging of fluorescence-tagged keratin filaments. They are interrogated and annotated at different
length scales using different modes of visualization including immersive virtual reality. In this way,
information is provided on network organization at the subcellular level including mesh arrangement,
density and isotropic configuration as well as details on filament morphology such as bundling,
curvature and orientation. We show that the comparison of these parameters helps to identify, in
quantitative terms, similarities and differences of keratin network organization in epithelial cell types
defining subcellular domains, notably basal, apical, lateral and perinuclear systems. The described

approach and the presented data are pivotal for generating mechanobiological models that can be
experimentally tested.

1   Introduction

Quantification of cellular properties is a central task of cell biology (Howard, 2014; Liberali and
Pelkmans, 2012; Lidke, 2017; Lippincott-Schwartz, 2014; Piston, 2014; Roca-Cusachs et al., 2017).
It is necessary for scientific analysis, testing and model building. The structural diversity of
eukaryotic cells supports their complex functions and is essential to provide local
microenvironments, which facilitate and enhance the probability of highly specialized molecular
interactions and reactions. The cytoskeleton is a key determinant of the necessary spatial
organization. It consists of filamentous polymers, which assemble into microtubules, actin filaments
and intermediate filaments. The resulting networks are interlinked and connected to intra- and
extracellular targets, including cytoplasmic organelles and specialized plasma membrane sites. In this
way, they act as structural and mechanical connectors between extra- and intracellular forces. The
participating structures and polypeptides have been referred to as the mechanobiome (Kothari et al.,
2019; Parajón et al., 2021; Wang et al., 2014), which defines the mechanical setting of a cell. The
properties of several mechanobiome components have already been quantified including their
turnover and mechanical features at different levels. Comprehensive quantitative information on
entire cytoskeletal networks, however, is missing for most components and, consequently, only little
is known about the distribution, local composition, mesh size, orientation and mechanical properties
of cytoskeletal networks at the subcellular level. Therefore, there is an urgent need to describe
cytoskeletal network architectures in quantitative terms at subcellular resolution. To this end, we
present a novel approach to create the complete digital representation of keratin intermediate filament
networks in three dimensions (3D), providing maps and quantitative measurements of the entire
keratin network in cultured cells and in cells within their native tissue context.

The intermediate filament cytoskeleton consists of polypeptides, which are expressed in a tissue- and
context-specific manner. The largest group of intermediate filaments, the keratin intermediate
filaments are the main cytoplasmic networks in epithelial tissues. They confer, together with their
associated desmosomal cell-cell and hemidesmosomal cell-extracellular matrix adhesions,
mechanical resilience (Hatzfeld et al., 2017; te Molder et al., 2021). The human genome contains 54
keratin genes, which are expressed in epithelia and epidermal appendages in a cell type-specific
pattern (Jacob et al., 2018). Keratin filaments are highly flexible and extensible (Block et al., 2015).
They form hollow tubes with remarkable variability in local diameter and ultrastructure (Weber et al.,
2021). Keratin filaments generate branched bundles of different thickness forming anisotropic
networks formed (Beil et al., 2005; Martin et al., 2016). The 3D organization of keratin networks
differs profoundly between different epithelia: E.g., the simple epithelial cells lining the intestine
contain a well-defined lateral and apical network, keratinocytes contain a dense 3D network
encompassing the entire cytoplasm, and hepatocytes have a prominent submembraneous network
(Schwarz et al., 2015; Strnad et al., 2008). Network organization is furthermore affected by
mechanical stress (Beriault et al., 2012; Felder et al., 2008; Fois et al., 2013; Karsch et al., 2020; Lutz
et al., 2020; Quinlan et al., 2017) and differentiation-status (Coch and Leube, 2016; Iwatsuki and
Suda, 2010; Leube et al., 2017; Quinlan et al., 2017; Tateishi et al., 2017). In addition, individual
proteins such as Ndel1 and plectin have been shown to regulate keratin network organization (Kim et
al., 2021; Moch et al., 2016; Osmanagic-Myers et al., 2006). Knowledge of the 3D keratin network
organization in single epithelial cells is therefore important to understand and characterize the

particular functional status of a given cell within its complex tissue context under different
conditions.

Segmentation of cellular elements is a key task in biological image analysis. Its application to
specific structures, however, can be quite difficult and requires appropriate adjustment. Networks of
curvilinear objects such as keratin networks are ubiquitous ranging from cytoskeletal filaments at the
micro- to nanoscale to blood vessels or neuronal networks at the tissue and organ level (Özdemir and
Reski, 2021). Filament detection systems have been developed for vascular (Imran et al., 2019;
Moccia et al., 2018; Samuel and Veeramalai, 2020) and neuronal networks (Acciai et al., 2016;
Magliaro et al., 2019; Quan et al., 2016). But these tools have not been optimized for subcellular
structures and are specialized to detect branched, tree-like structures. The fishnet-like organization of
keratin networks poses novel challenges, which are further confounded by the variably spaced
branching points connecting filaments of different thickness and curvature.

A wide range of specialized tools are available for segmentation of cytoskeletal actin (Alioscha-Perez
et al., 2016; Nowak et al., 2020), which also work in 3D (Haspinger et al., 2021). Further tools have
been developed for the segmentation of microtubules (Faulkner et al., 2017) and their prokaryotic
homologue FtsZ (Liu et al., 2019; Özdemir and Reski, 2021). Recently, a tool was described that is
suitable for segmentation of cytoskeletal networks including keratin networks using data obtained by
electron microscopy and super-resolution fluorescence microscopy (Flormann et al., 2021). This tool,
however, lacks 3D capability and does not capture information on filament thickness. Another
segmentation tool for filamentous networks in electronmicroscopic images was also recently reported
(Dimchev et al., 2021). Until now, however, no tools are available that segment 3D fluorescent image
data of keratin filament networks and transform them into a numerical graph model.

To segment keratin filament network and generate a data structure with defined nodes and internodal
regions (= segments) we used the open-source program TSOAX. TSOAX has been used for 3D
segmentation of actin networks using fluorescence images of yeast cells (Xu et al., 2019). It is an
implementation of SOAX (Xu et al., 2015, 2011), which was developed from the Stretching Open
Active Contours (SOAC) algorithm (Li et al., 2010, 2009b, 2009a). SOACs are open curves, which
start at segment tips and delineate the filament centers. We now show that TSOAX can be used to
reliably segment keratin networks in entire cells. TSOAX also provides density information of the
identified keratin filaments. However, the association of nodes and segments is not detected
satisfactorily as the generated TSOAX snakes are not separated consistently at filament nodes and
therefore hinder statistical analysis. We therefore developed additional tools (KerNet) for optimal
network representation on a node-segment structure. The combination of the established
segmentation algorithms (TSOAX) and the additional KerNet analysis tools helped to create accurate
numerical representations of keratin network topology.

The developed image analysis tools were applied to super-resolution fluorescence image stacks of
keratin networks in single cells either in cultured epithelial monolayers or within their native tissue
context. We show that the image analysis tools provide cell type-specific information on filament
mesh characteristics as well as information on filament thickness, directionality and connectivity in
3D. Cinematic rendering and immersive visualization make analysis of network heterogeneity
accessible at a hitherto unknown quality and precision of 3D reconstruction.

2   MATERIALS AND METHODS

2.1   Cell culture

Madin-Darby Canine Kidney (MDCK) cells were stably transfected with a plasmid encoding human full-length keratin 8 with an EYFP tag at its carboxyterminus (Windoffer et al., 2004; recloned into pEYFP-N1 (Clontech) with BamHI and EcoRI). Resulting cell clone H9 was used for the analyses described in this paper. Cells were grown in Dulbecco's Modified Eagle Medium (DMEM, Sigma-Aldrich) with 10% (v/v) fetal calf serum (Pan Biotech) including 700 µg/ml G418 (Sigma-Aldrich) for selection. Vital MDCK cells were imaged after 3 days when the monolayer had reached complete confluence.

Immortalized human HaCaT keratinocyte cell clone B10 expressing EYFP-tagged human keratin 5 (HK5-EYFP) has been described (Moch et al., 2013). The cells were grown in DMEM containing l-alanyl-glutamine (Sigma-Aldrich) supplemented with 10% (v/v) fetal calf serum (SeraPlus; PAN Biotech) and passaged as described (Moch et al., 2013). Vital HaCaT cells were imaged 24 h after.

2.2   Preparation of retinal pigment epithelium

Retinas were prepared from homozygous keratin 8-YFP knock-in mice, which synthesize fluorescence-tagged keratin 8 from the modified endogenous gene locus (Schwarz et al., 2015). Mice were sacrificed by cervical dislocation and eyes were enucleated using curved forceps. Eyeballs were then fixed with 2% paraformaldehyde in rotation at 4°C for 4 h. For retina flat-mount preparation, the eye balls were dissected as previously described (Claybon and Bishop, 2011). Briefly, cornea and lens were removed and the eyecup was cut into a multileaved flower-shape. The neural retina was removed and the remaining tissue was mounted on a microscope slide with Mowiol (Sigma-Aldrich).

2.3   Image recording

To obtain statistically relevant data, ten image data sets were recorded of each cell type with a Zeiss LSM710 using airyscan mode (Carl Zeiss, Jena, Germany). An oil immersion Plan-Apochromat 63x/1.4-NA, DIC M27 objective (Carl Zeiss) was used. Fluorescence was detected with an 488 nm argon laser (module LGK 7872 ML8) and filter set BP 495-550 using 2.5% power. Optimal factory settings for z-stacks were used resulting in a voxel size of xy = 0.044 to 0.065 µm and z = 0.17 to 0.2 µm. No further image optimization was used. To assure that only single cells were analyzed, the fluorescence in individual cells was cropped from confluent MDCK monolayers and retinal pigment epithelium (RPE) using Fiji standard tools. Cell borders were manually defined for each z-slice and the cell exterior was set to a grey value of 0. Wild-type HaCaT and HK5-EYFP producing HaCaT clone B10 cells were mixed prior to prevent overlap of fluorescence signals in neighbouring cells.

2.4   Segmentation of image stacks

TSOAX software (Xu et al., 2019, 2015, 2011) was used for the segmentation of filaments from the recorded 3D image stacks (**Suppl. Figure 1A**). TSOAX facilitates quantitative analysis of network dynamics of multi-dimensional biopolymer networks imaged by various microscopic imaging modalities. The underlying methods of TSOAX include multiple Stretching Open Active Contour (SOAC) models for extraction and a combined local and global graph-matching framework (Li et al., 2010, 2009b, 2009a). For optimal results, the default TSOAX parameters were used, with the exception of 'external-factor' which was set to 2 based on internal testing. Since computation time can be extremely long, TSOAX was executed in parallel instances on the supercomputer CLAIX at RWTH Compute Cluster (https://www.itc.rwth-aachen.de/go/id/eucm).

2.5   Calculation of a segment/node-based network model

To get a perfect network representation it is necessary to divide the network into defined pieces (= segments) that do not cross each other, and can be connected at their ends by nodes. Segmentations using TSOAX defines polygonal chains with *n* vertices (=snakes). Each vertex is defined in x, y, z and has an associated density (= fluorescence intensity). However, the *snakes* are not associated with each other via nodes and may cross each other. (**Suppl. Figure 1B**). To obtain a comprehensive and coherent numerical network definition from *snakes*, KerNet software was developed. It generates a graph representation consisting of segments (~ edges) and nodes. To compute such a connected network representation, vertices of a snake that lie within $\varepsilon = 1.1x$ voxelsize distance of one another are combined to form a node. If more than two vertices are within ε distance, a candidate set is created. Any vertex, which is at most ε away from a vertex in the candidate set, is added to the set until this is no longer possible. Then all vertices in the candidate set are combined to form a single node. Finally, any start or end vertex of a segment is a node. If two nodes are connected by a part of a snake then a segment connects the two nodes in the network. In contrast to classical edges, which are defined as lines connecting the nodes, each segment is a list of vertices (x,y,z) and their associated densities. The segments therefore inform about the trajectory of the snake between its two endpoints and the density progression along the segment. To summarize, nodes represent the first and last vertex of a segment and mark the connection between segments whose endpoints are close (**Suppl. Figure 1C**). All segments and nodes together represent a Euclidean 3D network map of a given cell.

2.6   Validation of segmentation

For validation of the segmentation, the original fluorescence image stacks were compared with the segmented 3D data. All vertices retrieved from KerNet were plotted into the original image stack. The z-values of the vertices were rounded to the nearest z-slice and all segment vertices were drawn as discs with a diameter proportional to their brightness. To simulate the blurriness of the raw images, the vertex stacks were 3D-Gauss filtered using Fiji (values 5,5,3).

2.7   Cinematic rendering of segments

For inspection of the 3D network representation, the xyz-position data of segments were exported into OBJ files (http://www.martinreddy.net/gfx/3d/OBJ.spec), which, in turn, can be imported into 3D rendering programs. For the representation of segment brightness as renderable tubes, density properties of segments were compiled into 3ds Max (Autodesk) script files that translate segment brightness into tube thickness, resulting in renderable splines for each segment. In some instances, random colors were assigned to each segment (**Suppl. Figure 1D**). Finally, 3ds Max rendering was used for the generation of stills and videos.

2.8   Virtual reality

For further visual inspection of the keratin networks, a basic Virtual Reality (VR) application was designed. The VR application was implemented using Unreal Engine 4 (https://www.unrealengine.com/en-US/). It displays the datasets of cells as 3D models. The individual filaments are visualized as tubes. Their brightness is encoded in the tubes' thickness. The resulting structure of interconnected tubes can then be visually inspected in VR, allowing a detailed view on the digitalized subcellular network in any magnification. Individual filaments can be

interactively assigned to one of several distinct classes, pre-defined by the domain expert. Color-
coding is then used to visually differentiate the classes in the immersive visualization.

During our research, we used the HTC Vive Pro headset to manually classify the filaments of a cell.
Afterwards, the aixCAVE at RWTH Aachen University was used to collaboratively discuss and
adjust the classification.

2.9   Numerical analysis and visualization

Matlab routines were used for further analysis of network properties. Up to 150 000 vertices may be
present per cell. Segment length, distance between nodes, bending, curvature and apparent
persistence length of segments were calculated. Bending was defined as the ratio beween the shortest
distance between the segment endpoints and the actual segment length. The curvature was calculated
as the 2nd derivative of the smoothed tangent vector with respect to the arc length (Sternberg, 2012).
Since persistence length can only be calculated in free moving segments and the segments are
restricted in their movement by the nodes in our situation, we calculated an apparent persistence
length as described (Doi and Edwards, 1990).

Statistical analyses were performed with Matlab and GraphPad Prism software. For non-Gaussian
distribution, Mann-Whitney test was used. Values are expressed as the mean $\pm$ SD. * represents a p-
value of $p < 0.05$, ** $p < 0.01$, *** $p < 0.001$ and **** $p < 0.0001$. The differences were considered
significant when $p < 0.05$. Non-significant differences were indicated by n.s.

To visualize segment properties such as length or curvature, the respective values were plotted and
color-coded at the vertex location resulting in heat maps showing the distribution of the selected
property. Here, Fiji scripts were used to plot color-coded properties into xyz coordinates of vertices.

For calculation of cell size, a threshold was used, that separated the background fluorescence inside
and outside of cells.

2.10   Directional vectors

The directionality of segments was calculated for the keratin network of single cells in two ways:

(i) Since the start and end points of segments are randomly orientated, segments with an orientation
difference of 180 degrees were equally orientated. Therefore, normalized histograms were plotted for
azimuth and elevation from 0-180 degrees. Next, we calculated the deviation of the histogram from a
histogram with an even distribution of orientations where each degree has the same frequency.
Finally, the difference between the segment histogram and the even distributed histogram was
calculated as the sum of the differences in each bin.

(ii) Keeping the segments in their original orientation we analyzed the position of segments in
relation to the cell center. The cell center was defined as the mean of the mean positions of all
segments in xyz. It was then determined whether the start point or end point of each segment was
closer to the cell center. The segment was then moved to the cell center such that the closer point was
placed to the cell center. In this way, all segments originate at the cell center and direct outwards. The
resulting radial histograms were plotted to depict the distribution of segments in xy and yz directions.

Treating each segment as a vector extending from the cell center to the segment's end, the sum vector
of all segments was calculated and plotted.

2.11 Software, original and processed data

248 Software, original and processed data are available at http://kernet.rwth-aachen.de/ and
249 https://github.com/VRGroupRWTH/Zytoskelett.

3 RESULTS

3.1 Recording of the keratin intermediate filament network in 3D

In a first step, we wanted to generate high-resolution fluorescence data that would be suitable for
image analysis of single filaments and filament bundles and would represent keratin filament
networks in different epithelial cell types. We selected three non-carcinogenic epithelial cell types: (*i*)
Canine kidney epithelial MDCK cells producing YFP-tagged keratin 8 (subclone H9) were chosen as
representatives of polarized simple epithelial cells. MDCK cells form a one-layered coherent
epithelium with the cuboidal to cylindrical cells attached to each other by highly-organized junctional
complexes. Intracellularly, the keratin filaments have a complex arrangement consisting of a dense
subapical network, perinuclear and radial keratin filaments and interdesmosomal filaments below the
plasma membrane (Quinlan et al., 2017). (*ii*) Spontaneously immortalized human epidermal
keratinocytes expressing YFP-tagged keratin 5 (HaCaT B9) were chosen as representatives of
squamous epithelial cells-(Boukamp et al., 1988) (Moch et al., 2013). They contain pancytoplasmic
keratin filament networks whose 3D organization is only partially elucidated (Moch et al., 2020). (*iii*)
To examine the 3D organization of the keratin intermediate filament network in its native tissue
context, we made use of the recently described knock-in mouse line expressing YFP-tagged keratin
8. Retinal epithelium cells (RPE) were selected for the analysis because of their well-delineated
cytoplasmic network (see below). High resolution airyscan confocal image stacks were prepared
from each cell type.

3.2 Transformation of 3D fluorescence recordings of keratin filaments into digital network models

The recorded image stacks were transformed into Euclidean 3D maps using TSOAX and the KerNet
software (**Figures 1, 2; Suppl. Figure 1**). In these maps, curved segments that are connected by
nodes describe the entire keratin networks of single cells. The segments represent keratin filament
bundles of different thickness and length. These segments are defined as 3D polygonal chains of
vertices, each of which has a specific xyz-position and brightness. The first and last vertices of a
segment are defined as nodes. Nodes are either shared by adjacent connecting segments within a
filament or are positioned at the end of a filament in case of loose ends. Note that keratin filaments
consist of multiple consecutive segments. To validate the quality of the numerical transformation, all
vertices were plotted onto the maximum intensity projection of the fluorescence image stack. **Figure
1A** shows the maximum intensity projection of the fluorescence in an MDCK cell as an example
highlighting selected regions of interest at higher magnification. Separating the regions above and
below the nucleus (apical and basal, respectively) furthermore allowed to distinguish the different
keratin network structures in these subcellular domains. Visual inspection showed a high degree of
overlap between the recorded fluorescence and the derived numerical positions of vertices (dotted
lines) at all subcellular locations.

To obtain more detailed comparisons of the calculated vertices with the fluorescence data, vertices
were first plotted in 3D and their brightness was encoded as filament diameter. The 3D plots were
then convolved by Gaussian blurring to simulate the microscope's point spread function. **Figure 1B**
shows the very good match of the convolved vertices in terms of position and brightness in
comparison to the maximum intensity projection of the fluorescence image. To assess the overall
reliability of the digital transformation, the validation steps were applied to all cells selected for the
study (**Suppl. Figure 2**). Additional slice-by-slice comparisons are presented exemplarily in **Video 1**
further demonstrating the good correlation between the recorded and derived numerical
representation of the keratin filament network in 3D.

For close inspection of the keratin filament network in its subcellular complexity, we used cinematic
rendering. The rendering displays the network as a true 3D model including the brightness of
filaments which are shown as tubes with different degrees of thickness thus providing information on
the segments in a 3D-viewer. To distinguish individual segments, each segment was randomly color-
coded (**Figure 1C**).

3.3 Comparison of 3D cinematic keratin filament renderings in MDCK, HaCaT and RPE
cells

Renderings of keratin filament networks in MDCK, HaCaT and RPE cells are exemplarily shown
from different views in **Figure 2** and **Videos 2-4**. Interactive 3D renderings of all cells are available
at kernet.rwth-aachen.de. Furthermore, immersive visualization was used to provide unrivaled
impressions of the spatial arrangements of the keratin network in stereoscopic 3D (**Figure 3**). The
multidimensional visualizations revealed hallmark features of the different keratin filament networks.

Thus, an apical and a basal keratin filament network domain can be distinguished in MDCK cells
(**Video 2**). The major difference between both domains are the thicker keratin bundles in the basal
domain. Each network is characterized by a regular mesh pattern. The lateral keratin filament
network is more heterogenous and dominated by filaments running between apical and basal.
Circumferential subcortical keratin filaments are mainly restricted to the apical and basal network
domains. In the cell interior, keratin filaments form a network around the nucleus. It is best
developed on the basal side with highly bundled filaments, many of which are rather straight.

HaCaT cells are extremly flat and do not show a clearly seperated apical and basal networks and lack
a distinct lateral network (**Video 3**). A prominent feature of their keratin filament network are long
filament bundles that often run in parallel. They are absent above and below the nucleus but enclose
the nucleus laterally.

The keratin network is less dense in RPE cells than in the other two cell types (**Video 3**). It is
prominent in the cytoplasmatic apical domain, which faces the photoreceptor cells in the retina. It is
also very well developed around the nucleus. In contrast to MDCK cells, the perinuclear network
contains thicker filaments at the apical than the basal side. The basal cytoplasmatic domain is mostly
devoid of keratin filaments. Some filaments run through the cytoplasm from basal to apical.

In conclusion, rendering of the keratin filament networks in three cell types revealed very different
arrangements. The numerical data representation now allows detailed further analyses of distinct
features. Especially with the help of VR, classification of network domains becomes feasable.

3.4 Comparison of keratin filament brightness distribution patterns

The numerical network representations were used to quantify keratin filament properties. A prominent property, which was already graphically encoded in the 3D-models, is filament brightness as a measure of filament thickness. The assumption is that filament thickness is a reliable indicator of filament bundling which can now be easily quantified throughout entire cells. The histograms in **Figure 4A-C** depict the spread of filament segment brightness in MDCK, HaCaT and RPE cells. The quantifications show that filament segments with a medium brightness dominated in MDCK cells with a near Gaussian distribution, whereas thin filaments were prevalent in HaCaT and RPE cells. Thin filaments were most abundant in HaCaT cells.

Maps of filament brightness are shown in **Figure 4D-F** for selected examples of each cell type at low and high magnification. In each case, thin filaments were numerous in the cell periphery. This may be due to the increased *de novo* single filament formation in these regions (Windoffer et al., 2004, 2006, Moch et al., 2013). Some areas, such as those shown at the right margin of the MDCK cell in **Figure 4D**, however, presented rather thick keratin filament bundles, which may represent matured interdesmosomal keratin filaments (Quinlan et al., 2017). The most heterogeneous network in terms of filament thickness was encountered in MDCK cells. The animation in **Video 2** clearly shows that filaments in the basal network of the cell are thicker than that in the apical network. In HaCaT cells, enrichment of thin filaments was visible around the nucleus (**Figure 4E**) whereas thicker filaments were detectable in the cytoplasm, many of which appeared to be arranged in parallel (see also **Video 4**). In contrast, thick filament bundles surrounded the nucleus of RPE cells (**Figure 4F**; **Video 5**). Furthermore, thick bundles were more frequent above the nucleus, i.e., at the part of the cell facing the photoreceptors. Together, the analyses of the digitalized networks revealed major differences in the extent and distribution of keratin filament bundling suggesting that the keratin network is organized to withstand and cope with different types of mechanical stress.

3.5 Number and length of keratin filament segments and overall keratin filament length in single cells

The number and length of individual keratin filament segments are key measurements of network organization. Significantly more segments were detected in HaCaT cells than in the other cell types (**Figure 5A**). The average segment length was shortest in MDCK cells (0.80±0.04 µm), longest in RPE cells (0.88±0.05 µm) and intermediate in HaCaT cells (0.83±0.13 µm) (**Figure 5B**).The combined length of all segments per cell (**Figure 5C**) was similar in MDCK (1.63±0.41 mm) and RPE cells (1.57±0.48 mm) but was more than twice longer in HaCaT cells (4.40±1.53 mm). To see whether this difference was due to different cell dimensions, the cell volumes were determined for all three cell types. Significant differences could be detected, i.e., 4.65±1.13 µm³ for MDCK, 9.16±6.10 µm³ for HaCaT and 2.73±0.95 µm³ for RPE (**Suppl. Figure 3A**). Taking the different cell volumes into account, filament density, i.e. filament length per volume, was comparable in HaCaT (604.82±304.20 µm/µm³) and RPE cells (585.60±63.97 µm/µm³), while it was considerably lower in MDCK cells (355.24±56.49 µm/µm³) (**Figure 5D**). Given that the human body has ~0.14 x 10^{12} epidermal cells (Bianconi et al., 2013), the entire length of epidermal keratin filament bundles in an individual should be ~600 000 km. Assuming a bundling rate of 19 filaments per filament bundle (Hémonnot et al., 2016) there are ~1.14×10^7 km of single filaments keratin filaments in the epidermis of a human body.

3.6   Branching and intersection of keratin filaments

Next, we analyzed branching and intersection of keratin filament bundles. -Different types of
branching could be envisioned depending on the number of segments per node. Three segments per
node would define a Y-shaped branch, whereas four segments would define an X-shaped intersection
of two filaments (**Suppl. Figure 1C**). More than four branches would result in a star-like
configuration. Our analyses show that the Y-shaped organization (three segments per node) was by
far the most frequent configuration (~60%) followed by the X-shaped (four segment per node)
arrangement (~30%) and rarely higher degrees of branching (~10%) (**Figure 6**).

3.7   Bending of keratin filaments

Bending of keratin intermediate filaments is of interest as it may provide information on material
properties of filaments and may indicate whether filaments are under longitudinal compression or
tension. First, we calculated the distance/length ratio of segments (**Figure 7A**). The highest ratios
were observed in MDCK (0.92±0.09) and HaCaT (0.92±0.08), which were significantly higher than
in RPE cells (0.90±0.10) indicating that the filaments in RPE cells are less straight. This
interpretation was confirmed by curvature determination of segments (**Figure 7B**). The mean
curvature of segments was significantly higher in RPE cells (3.30±0.15 µm^{-1}) than in MDCK cells
(2.54±0.11 µm^{-1}) and HaCaT cells (2.97±0.72 µm^{-1}). The curvature distribution in HaCaT cells was
more widely spread than in the other two cell types. Maps of curvature distribution are shown from
two different perspectives in **Figure 7C-E** revealing complex patterns. Finally, we determined the
apparent persistence length of keratin filament segments being aware that the resulting values are
difficult to interpret, since segments are not free to move but are connected to other segments within
the network. **Suppl. Figure 3B** shows that the calculated values (~2.6 µm) do not differ significantly
between the three cell types. As expected, they are higher than the experimentally determined
persistence length of single filaments (cf. (Block et al., 2015)).

3.8   Keratin filament segment orientation

To calculate how evenly the segments are orientated in space, the azimuth (= horizontal orientation)
and the elevation (= vertical orientation) of segments were calculated for each cell. The histograms in
Figure 8A-F show examples of the azimuth and elevation distribution in single MDCK, HaCaT and
RPE cells. Comparing the determined values with the expected values for segments orientated evenly
in all directions, shows that the azimuth distribution is quite even in MDCK and RPE cells but not in
HaCat cells. All cells have an uneven distribution of vertical orientation, indicating that segments are
preferentially oriented horizontally. Compilations of the analyses for all cells (**Figure 8G, H**)
confirmed the single cell data and affirmed that the azimuth distribution in HaCaT is more oriented
than in MDCK or RPE cells. Furthermore, the elevation orientation is more directed in MDCK and
HaCaT cells than in RPE cells. Mapping the horizontal segment orientation in selected cells (**Figure
8I-L**) reveals a random pattern in MDCK and RPE and highlights parallel-arranged filaments in
HaCaT.

To obtain insight about the relationship between segment directionality and cell shape, the orientation
of the segments was analyzed with respect to the cell center. To this end, all segments were
translocated to the cell center and their spatial distribution was plotted in radial 2D histograms. As
expected, MDCK and RPE cells showed a homogenous distribution of horizontal segment orientation
in the x/y plane while HaCaT cells were more polarized (**Figure 9A-C**). In the vertical direction (y/z
plane) horizontally oriented segments predominate in MDCK and HaCaT cells while segments are
more uniformly oriented in RPE cells (**Figure 9D-F**).

To compare the 3D-isotropy of entire keratin filament networks a sum vector of all segments was
constructed for each cell. To this end, the orientation vectors of segments were translocated to the
cell center as described above and mapped with the length of each segment. **Figure 9G-I** shows the
resulting sum vectors in each plane together with corresponding views of the segmented keratin
filament networks. The sum vectors in MDCK and RPE cells are relatively small, indicating an
isotropic orientation of the respective keratin networks. In contrast, the sum vectors in HaCaT cells
are significantly much longer, indicating a higher degree of anisotropy of the keratin network (**Figure
9K**).

4   DISCUSSION

With this work we provide, for the first time, experimentally-derived numerical 3D representations of
entire keratin networks in eukaryotic cells. 3D fluorescence data were used to define segments that
are connected by nodes. This enabled us to compare local properties of keratin intermediate filament
networks such as filament thickness, curvature and orientation in different cell types *in vitro and in*
vivo. It further facilitated comprehensive comparisons of entire networks by quantifying parameters
such as entire filament length, degree of filament connectivity and spatial network orientation.

A critical aspect of the work was evaluation of the quantification process. Since synthetic 3D data of
cellular keratin networks were lacking, the quality of segmentation was evaluated by visual
inspection of superimposed imaging and segmentation data demonstrating that the location and
intensity of filaments were mapped with high precision and reliability. The subsequent allocation of
nodes and segments was visually assessed in rendered 3D models (cinematic rendering) again
revealing very good agreement of the assignments. Nevertheless, the numerical representation has its
limitations in accuracy. Proper segment and node detection was particularly challenging in HaCaT
cells because of their complex network geometry in combination with low filament bundling.
Extreme bending at the single filament level with bending radii of 100 nm (Weber et al., 2021) are
not detected in the present set-up due to the resolution limit of the airyscan. Mapping of keratin
filaments at the cell edges was also difficult in some regions, mostly because of the manual
assignment of cell borders in the confluent cell layers with tightly attached and partially overlapping
neighboring cells. In cultured cells, mixing of fluorescent and non-fluorescent cells could overcome
this problem. Segmentation quality may be further improved in the future by using other and more
powerful super-resolution techniques than the airyscan technology used in the present work.

A major advance of the current report is the fabrication of numerical models of the keratin filament
network in 3D. The rendered 3D models can be thoroughly inspected with the help of 3D display
devices such as 3D screens, virtual reality-headsets (HMDs) or Cave Automatic Virtual
Environments (CAVEs). The benefits of such immersive environments have been demonstrated
(Cruz-Neira et al., 1993; Laha et al., 2013). Three factors thereby improve the domain scientists'
spatial judgment and thus the task performance during the visual analysis: (i) an enlarged field of
regard, compared to standard desktop systems, reduces clutter during the data exploration, (ii)

stereoscopy provides supporting depth cues, and (iii) head tracking provides enhanced motion
parallax.

The derived digital network models furthermore allow comparisons between cells with similar or
dissimilar differentiation status (**Figure 10**). As a proof of concept, we paradigmatically investigated
three different epithelial cell types finding significant differences in filament bundling, segment
length, filament density, filament curvature and filament orientation. These parameters are a crucial
and first step to build mechanical models of keratin filament networks in different cell types and
functional contexts. The following list shows potential implications of the extracted features for our
understanding of keratin filament network properties and functions:

- Brightness of keratin filament segments: Brightness levels correspond to filaments thickness and is
therefore a measure of keratin filament bundling. The observed variation in filament bundling in the
different cell types may therefore be a consequence of differences in the local force balance. This
force balance is the result of intrinsic cell type-specific properties such as cell shape and arrangement
of the actomyosin system and is impacted by forces imposed by neighboring cells and the
extracellular matrix. This is supported by the observed differences in bundling of the apical, basal
and perinuclear keratin filament networks. However, the variation in filament thickness may also
reflect other properties such as the propensity of the network to reorganize, e.g., at different times of
the cell cycle. Correlating the derived image data with information on mechanical keratin filament
properties obtained by laser cutting experiments, force-sensor measurements or traction force
analyses may help to better understand the relationship between filament bundling and mechanics.

- Length of keratin filament segments: Keratin filament segment length is an indirect measure of
mesh size and may therefore describe another crucial mechanical property of the network. We were
surprised to find that the segment length varied only by 10% between the different cell types and thus
showed less variation than filament brightness or curvature. This means that the mesh size is fixed
within a relatively small range, although the number of meshes per volume differed significantly
between the different cell types. A conclusion of this observation is that mesh size may be
determined by intrinsic keratin filament properties such as elastic modulus or branching capacity.
However time-lapse fluorescence analyses (e.g., (Wöll et al., 2005)) have shown that small meshes
can merge and enlarge by the combination of nodes from two segments, forming thicker filament
bundles. Conversely, large meshes are subdivided into small meshes by recruitment of segments into
a node. A self-regulatory mechanism may thus control the balance between enlargement and
reduction of individual meshes.

- Branching of keratin filament segments: Experimental and mechanistic evidence has been provided
for keratin filament branching (Beil et al., 2005; Feng and Coulombe, 2015; Lee et al., 2012; Martin
et al., 2016; Nafeey et al., 2016). The fact that only two types of branching/intersections were
detected in this study, points to a limited repertoire of connectivity. Furthermore, the Y- and X-
shaped configurations may be fundamentally different. The Y-shaped joining of three segments may
be linked to the recently proposed bundling mechanism involving electrostatic and hydrophobic
interactions (Haimov et al., 2020). On the other hand, the X-shaped intersections may be related to
the disulfide bond mediated interactions reported for keratins 5/14 (Lee et al., 2012). In this instance,
preventing these links resulted in altered keratin filament network dynamics and epidermal tissue
homeostasis (Feng and Coulombe, 2015; Guo et al., 2020).

- Curvature of keratin filament segments: Bending of keratin filaments provides important
information on whether keratins are stretched, relaxed or compressed. Keratin intermediate filaments
are highly elastic (Kreplak et al., 2005; Wagner et al., 2007; Yamada et al., 2003). They can be
extended under tension forming straight filaments and buckle under compression (= negative tension)
(Fudge et al., 2008). The measurements of segment curvature can therefore be taken as indicators of
local keratin filament tension. Straight segments were almost completely absent in all cells
suggesting overall negative tension of the keratin networks. The degree of filament bending,
however, differed between the different cell types indicating cell type-specific differences in intrinsic
force balance and may suggest that the different networks retain different degrees of flexibility before
they become stretched to function as mechanical counterbalances to strain. Curvature of keratin
filaments also allowed to estimate the persistence length of network-embedded keratin filaments, i.e.,
the minimum length between two points on the polymer where they become independent of one
another. The value of ~2 µm was only slightly higher than what was reported for other intermediate
filaments including keratin (Block et al., 2015; Wagner et al., 2007). This is low in comparison to
actin filaments (~10 µm) (De La Cruz and Gardel, 2015; Isambert et al., 1995; Takatsuki et al., 2014)
and microtubules ($\sim$5000 µm) (Hawkins et al., 2010). This result emphasizes the maintained high
flexibility of keratin filaments despite their connectivity through nodes.
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- Orientation of keratin filaments: To understand the response of the keratin network to internal and
external forces, it is important to have measures of filament orientation. We suggest that uniformly
radial orientation of keratin filament segments indicates that cells experience mechanical forces that
are homogenous in all directions. In contrast, a preferential orientation in one direction indicates that
keratin filaments align in response to mechanical cues that may be induced by unevenly distributed
cell-cell contacts, polarized cell-extracellular matrix adhesions or contractile activity. Our data
therefore indicate that HaCaT cells are subjected to mechanical strain (uneven azimuth distribution
and large sum vector), whereas MDCK and RPE are subjected to little mechanical (uniform azimuth
distribution and small sum vector). Fine mapping of the distribution patterns of hemidesmosomes and
desmosomes may help to understand the differences and to initiate mechanical modelling, improving
previous models of keratin network, morphogenesis, dynamics and mechanics (Beil et al., 2009;
Dallon et al., 2019; Latorre et al., 2018; Portet, 2013; Portet et al., 2019, 2015).

The observed high degree of segment property variability must be taken as an indication of the
amazing plasticity of the keratin filament system.-The node/segment arrangement provides a unique
3D structure that can be modified in multiple ways affecting bundling, flexibility and local cross-talk.
Keratin isotypes, posttranslational modifications, external and internal forces, and interactions with
other cytoskeletal and cellular components may determine these properties and thereby act as
modulators of network structure at different length and time scales.

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6   Conflict of Interest

777 The authors declare that the research was conducted in the absence of any commercial or financial
778 relationships that could be construed as a potential conflict of interest.

7   ETHICS STATEMENT

780 n.a.

8   Author Contributions

• Conceptualization: RW, JDR, REL
• Methodology: RW
• Software: RW, MS, JS, AB
• Validation: RW
• Formal analysis: RW
• Investigation: RW, NS, SY, TP
• Resources: RW

• Writing—original draft: RW, REL
• Writing—review & editing: RW, REL
• Visualization: RW, AB
• Supervision: RW
• Project administration: RW, REL
• Funding acquisition: RW, REL

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10.1 Figure Legends

FIGURE 1 Evaluation of 3D keratin filament network segmentation. The pictures show three
different numerical representations of the same fluorescence data set detecting the keratin filament
network in an MDCK cell expressing fluorescently labelled keratin 8. The cell is part of a confluent
monolayer and the fluorescence of the single cell shown was manually excised from an image stack
consisting of 32 slices (voxel size: $xy = 66$ nm, $z = 182$ nm). This cropped fluorescence was used to
calculate the vertex positions and intensity of all keratin filaments. **(A)** The top picture shows an
overlay of the recorded fluorescence in red as a maximum intensity projection (mip) and the
corresponding calculated xy positions of vertices of all segments as green dots. The enlargements
below (corresponding regions demarcated by boxes) show maximum intensity projections of focal
planes above and below the nucleus (apical and basal) at left and two regions of interest (roi 1, roi 2)
depicting maximum intensity projections of all focal planes in the cell periphery. **(B)** presents an
overlay of the keratin fluorescence and corresponding vertices that were plotted in 3D with a
diameter relative to their brightness and were subsequently subjected to 3D Gaussian blurring to
simulate the microscope's blur. The enlargements correspond to those shown at left in **(A)** presenting
the same regions of interest and focal planes. The top panel of **Video 1** presents an animated
comparison of the fluorescence recording, segmentation and overlay in each focal plane. **(C)** depicts
a cinematic rendering of segments. Each calculated segment is rendered in 3D with a thickness
corresponding to the brightness of the original filament. The color-coding helps to identify and
distinguish individual segments. The regions of interest correspond to the same single planes as those
shown in **(A)**. White arrows demarcate thin filaments, blue arrows thick filaments.

FIGURE 2 Comparison of 3D cinematic rendering of keratin filaments in three different epithelial
cell types. The position and intensity of fluorescence recordings were transferred into a numerical
3D-representation of individual segments. The thickness of the segments corresponds to the
fluorescence brightness in the original data. (**A**) shows cinematic rendering of keratin filaments of an
MDCK cell expressing fluorescently labelled keratin 8. **Video 2** presents the 3D-animation of the
cell. (**B**) Depicts the cinematic rendering of keratin filaments in a HaCaT keratinocyte expressing
fluorescently labelled keratin 5 (animation in **Video 3**). (**C**) Illustrates cinematic rendering of keratin
filaments in a single RPE cell of a homozygous keratin 8-YFP knock-in mouse (animation in **Video
4**).

FIGURE 3 Visual inspection of the keratin network of a single cell in a virtual reality environment.
The viewer can move freely within the network which appears to her/him as a true 3D stereoscopic
structure. Classification of segments is done interactively in this environment by color coding.

FIGURE 4 Mapping of keratin filament brightness in MDCK, HaCaT and RPE cells. **(A-C)** The
histograms display the distribution of relative segment brightness for each cell type. The maximum
brightness was normalized to 100 in all cases. For each segment, the mean brightness was calculated
and the determined brightness levels of all segments in 10 cells were pooled for each diagram. **(D-F)**
The maps depict the segment brightness in a representative MDCK (left), HaCaT (middle) and RPE
(right) cell (top panel; enlarged boxed area in bottom panel). The colour code represents relative
brightness.
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FIGURE 5 Measurements of keratin filaments in MDCK, HaCaT and RPE cells. **(A-D)** The whisker
box plots depict the number of segments per cell (A), the mean segment length (B), the entire length
of the keratin filament network within a single cell **(C)** and the filament length per µm³ **(D)**. 10 cells
were analyzed for each cell type. **(E-G)** show color-coded keratin filament segment lengths for each
cell type. The top panel presents the results for entire cells, the bottom panel the results for the boxed
areas at higher magnification.

FIGURE 6 Calculation of keratin filament node types based on segment/node ratios in MDCK,
HaCaT and RPE cells. A segment/node ratio of 3 refers to Y-shaped branching, a ratio of 4 to X-
shaped branchings. Higher values refer to star-like branchings. The histograms depict the relative
distribution of node types.

FIGURE 7 Measurements of keratin filament segment bending in MDCK, HaCaT and RPE cells.
(A). The whisker box plot shows the distance/length ratio of keratin segments. **(B)** The curvature of
keratin filaments in the three cell types is shown as a whisker box plot. **(C-E)** Color-coded
representation of the keratin network depicting the curvature of keratin filament segments in entire
cells (top) and selected regions of interest (boxed areas) at higher magnification (bottom).

FIGURE 8 Orientation of keratin filament segments in MDCK, HaCaT, and RPE cells. **(A-C)** The
histograms show the normalized distribution of azimuth (= horizontal orientation) of keratin filament
segments in single cells. Since the segments have no defined start and end point, the histogram is
restricted to 180 degrees. The horizontal line represents the expected histogram levels if all angles
were equally distributed. **(D-F)** The histograms show the elevation (= vertical orientation) of keratin
filament segments. The horizontal line demarcates the expected histogram values, if elevation of
keratin filament segments would be uniform. **(G, H)** Whisker box plot depicting the deviation of
segment orientations from uniform unbiased distributions. The differences in azimuth **(G)** and
elevation **(H)** were calculated for 10 MDCK, 10 HaCaT and 10 RPE cells. **(I-L)** The color-coded

maps depict the azimuth of segments in entire cells (top; MDCK, left; HaCaT, middle; RPE, right)
and selected regions of interest (boxed areas; bottom).

FIGURE 9 Analysis of segment orientation in MDCK, HaCaT and RPE cells. **(A-F)** The blue
polygons represent radial histograms of the orientation of keratin filament segments in relation to the
cell center of single cells. Horizontal orientation **(A-C)** and the vertical orientation **(D-F)** are shown.
Each keratin segment in each cell was moved to the cell center and vectors pointing in the same
directions were added. Thus, the longer the blue lines are, the more vectors point in that direction.
(G-I) The red arrows represent the sum vectors of the direction and length of all segments in each
cell. **(K)** Whisker box plots depicting the length of the main vectors in all three cell types.
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883   **FIGURE 10** Schematic drawing of the reconstructed keratin network in the three cell types
884   investigated.
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11   Figures

11.1   Figure 01

11.2   Figure 02

898 **11.3   Figure 03**

11.4 Figure 04

907   **11.5 Figure 05**

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11.6 Figure 06

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11.8 Figure 08

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924   **11.9   Figure 09**

927 **11.10 Figure 10**