Title

Spatially Periodic Computation in the Entorhinal-Hippocampal Circuit During Navigation

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Keywords

Entorhinal cortex, Hippocampus, Cognitive map, Neural periodicity, fMRI

Abstract

To enable navigation in both physical and mental spaces, the human brain employs a cognitive map constructed from the global metrics of the entorhinal cortex and the local representations of the hippocampus. However, how these two regions coordinate to enable navigation remains poorly understood. Here, we designed an object-matching task where human participants unknowingly manipulated object variants arranged in a ring-like structure around a central prototype. Functional MRI revealed a 3-fold spatial periodicity in the hippocampal activity that tracked navigation directions from object variants to the central prototype. This hippocampal periodicity was phase-locked with the well-documented 6-fold periodicity of the entorhinal cortex, suggesting hierarchical interaction between these regions. Consistent with this neural pattern, a corresponding 3-fold periodicity was observed in behavioral performance, which was synchronized with hippocampal activity. Finally, an EC-HPC PhaseSync model reproduced this phenomenon, in which the 6-fold activity periodicity of entorhinal grid cells across directions projects vectorial representations to the hippocampus, and the collection of these vectors exhibits 3-fold periodicity to represent conceptual directions. Together, these findings reveal a periodic mechanism through which entorhinal grid codes structure hippocampal vector representations.

Introduction

The cognitive map, initially introduced by Tolman (Tolman, 1948) and later supported by the discovery of place cells in the hippocampus (HPC) (O'Keefe and Dostrovsky, 1971), has served as a framework for spatial navigation. Grid cells in the upstream entorhinal cortex (EC), known for their hexagonal firing pattern to provide the metric for space (Hafting et al., 2005), have also been found to represent conceptual space beyond the physical reference frame (Constantinescu et al., 2016; Bao et al., 2019; Raithel et al., 2023). These findings suggest that the EC-HPC circuit fundamentally organizes spatial and non-spatial knowledge (Epstein et al., 2017; Behrens et al., 2018; Bottini and Doeller, 2020; Park et al., 2020), and to guide flexible behaviors such as retrieving knowledge from the past and making decisions for the future (Addis et al., 2007; Hassabis and Maguire, 2007; Schacter et al., 2012).

Flexible navigation requires the mental simulation of prospective pathways on a cognitive map, which is defined by essential cues such as self-location, goal location, direction, and distance (Nyberg et al., 2022). This process necessarily involves dynamic representations of the external world relative to self-location. Converging evidence indicates that the HPC binds spatial cues into vectorial representations, providing activity gradients that reflect potential pathways toward goals. In bats, a subpopulation of CA1 neurons exhibited conjunctive tuning to both direction and distance, with activity gradually decaying within 10–15 minutes after the goal is displaced (Sarel et al., 2017). In rats, similar findings were observed for neurons tuned to featureless goal locations distributed across space (Ormond and O'Keefe, 2022). These neurons fire maximally when the animal is oriented toward the goal and rapidly reorganize following goal shifts. Consistently, the neural representation of prospective pathways in the human brain is affected by goal locations (Muhle-Karbe et al., 2023). The neural geometry derived from the BOLD signals in the HPC is distorted by goals, reflecting the successful learning of goal-directed navigation. Collectively, these findings suggest that the formation of prospective pathways relies on memory-based vectorial representations in the HPC. However, these studies raise the question of how grid cells in the EC contribute to this process.

We hypothesize that projections from EC grid cell populations provide a coherent

cognitive-map framework in the HPC that embeds a three-fold periodic structure across

spatial directions to support vectorial representations and simulating the prospective

pathways. Grid cells exhibit hexagonal firing patterns with nearly invariant orientations

(Hafting et al., 2005; Sargolini et al., 2006; Krupic et al., 2012; Gardner et al., 2022).

These properties may support the formation of vector-like representations of pathways by

coactivation of grid cell populations. In the simplest case, when one mentally simulates a

straight pathway aligned with the grid orientation, a subpopulation of grid cells would be

sequentially activated, and the resulting population activity would manifest a near-perfect

vectorial representation with constant activity strength along the pathway. In contrast,

when the pathway is misaligned with the grid orientation, the corresponding grid cell

population yields a distorted vectorial code. Consequently, simulating straight pathways

spanning 0°–360° yields only half the number of unique activity patterns. This arises

because the hexagonal grid's 180° rotational symmetry makes orientations separated by

180° indistinguishable. We therefore speculate that the vectorial representations

embedded in grid cell activity are periodic across spatial orientations and are transmitted

through the EC–HPC circuit to bind prospective path directions. Consistent with this idea,

reorientation paradigms in both rodents and young children demonstrate that subjects

search equally at two opposite directions, reflecting successful orientation encoding but a

failure to integrate spatial direction (Hermer and Spelke, 1994; Julian et al., 2015;

Gallistel, 2017; Julian et al., 2018).

This hypothesis is supported by evidence from anatomical, functional, computational,

and physiological findings on the EC–HPC circuit. Anatomically, the EC serves as one of

the major sources of input to the downstream HPC (Witter and Amaral, 1991; van Groen

et al., 2003; Garcia and Buffalo, 2020). Functionally, grid cells in the medial EC

exhibited multiplexed and heterogeneous responses corresponding to position, direction,

and speed before they are integrated in the HPC (Sargolini et al., 2006; Hardcastle et al.,

2017). Computationally, grid cells have been proposed as the foundation of hippocampal

place field formation by integrating multiple grid modules (Solstad et al., 2006; De

Almeida et al., 2009; Bush et al., 2014; Bush et al., 2015; Bicanski and Burgess, 2019).

Physiologically, EC lesions disrupt the precision and stability of place fields (Hales et al.,
2014), leading to reduced discharge rates and field sizes (Van Cauter et al., 2008). If our
hypothesis is correct, a 3-fold periodicity aligned with the three principal grid axes should
emerge in the HPC, phase-locked with EC activity along path directions. Because
simultaneous population-level recordings from the EC and HPC remain technically
challenging, we employed fMRI, which has previously revealed 6-fold periodicity in the
EC (Doeller et al., 2010; Constantinescu et al., 2016; Bao et al., 2019; Wagner et al.,
2023; Raithel et al., 2023), to test for periodicity in the HPC.

A novel 3D object, named Greeble (Fig. 1a) (Gauthier and Tarr, 1997), was used to
create a conceptual Greeble space. Within this space, locations were represented by
Greeble variants characterized by two features ("Loogit" and "Vacso"). The feature
length defined the two dimensions of the space. The central Greeble served as the
prototype. Participants were instructed to morph Greeble variants to match this target
prototype (Fig. 1b). This process generated a sequence of Greebles that resembled
movements along navigational path in a two-dimensional conceptual space (Fig. 1c),
although participants were unaware of the underlying Greeble space. To ensure a
comprehensive exploration of the Greeble space for detecting hippocampal periodicity,
Greeble variants were pseudo-randomly sampled at the periphery of space. This ensured
a high-resolution sampling of conceptual directions ranging from 0° to 360° (i.e., the
orange locations in Fig. 1c), while controlling for distance. As a result, we observed a 3-
fold periodicity in hippocampal activity, cross-validated using sinusoidal modulation and
spectral analyses. The spatial phase of the HPC was coupled with a 6-fold periodicity in
the EC, no spatial offset was identified. In addition, we identified a 3-fold periodicity in
participants' behavioral performance that was phase-locked with hippocampal activity.
Finally, the EC–HPC PhaseSync model, developed to simulate EC projections into the
HPC, reproduced the emergence of 3-fold activity periodicity across directions under
randomized goal locations. Together, these empirical findings highlight a periodic
representation of conceptual directions within the HPC, suggesting that vectorial
representations in the hippocampus may arise through projections from periodic grid
codes in the EC.

Fig. 1. Experimental design. a) Depiction of the Greeble prototype (Gauthier and Tarr, 1997) and its two defining features, namely "Loogit" and "Vacso." b) Inside the MRI scanner, participants adjusted the length of Loogit and Vacso to match the prototype by stepwise button presses, within a 10-s time limit. c) Conceptual object space. Each orange dot within the ring-shaped area represents a Greeble variant, while the central blue dot indicates the Greeble prototype (i.e., the goal location). The red dots denote exemplar intermediate locations along the navigational path (i.e., the black line). d) Density distribution of participants' ending locations indicated an overall superior behavioral performance for detecting the periodic activity of the HPC.

Results

Behavioral results

Participants adjusted Greeble features using two response boxes inside the MRI scanner. Each response box controlled one feature, with two buttons used to stretch and shrink the

feature, respectively. To prevent a "horizontal–vertical movement" strategy, in which
participants navigate primarily along the cardinal directions (e.g., repeatedly adjusting
one feature towards North and then East), participants were encouraged to adjust both
features simultaneously to promote directional variability in path directions for detecting
neural periodicity. This strategy, referred to as "Radial Adjustment" involved making a
one-unit adjustment to one feature with the left hand followed by a one-unit adjustment to
the other feature with the right hand.

To examine participants' movement strategy, we first calculated the number of unique
directions across every three consecutive steps within their original movement paths (Fig.
S1). Participants showed an average of 3.8 directions per path, which was significantly
higher than the two directions predicted under the "horizontal–vertical movement"
strategy ($t(32) = 15.76$, $p < 0.001$, two-tailed; Cohen's $d = 2.78$). Next, we examined the
uniformity of directional distributions across all generated paths spanning 0°–360°. No
significant deviation from uniformity was observed (Fig. S2; $p > 0.05$, Rayleigh test for
circular uniformity). These results confirm that the "Radial Adjustment" strategy was
stably adopted by participants during navigation in the conceptual Greeble space,
ensuring that subsequent analyses were not biased by directional sampling.

To eliminate potential learning effect on potential BOLD signal periodicity, all
participants completed a training task one day prior to the MRI scanning to familiarize
themselves with Greebles morphing (see methods for details). Behavioral performance
was defined as a composite score combining path length and error size, with superior
performance characterized by smaller scores. Learning effects were observed during the
practice experiment on day 1 (Fig. S3; $t(32) = -2.46$, $p = 0.019$, two-tailed; Cohen's $d =$
0.44), but were no longer present during the MRI experiment on day 2 ($t(32) = -0.74$, $p =$
0.462, two-tailed; Cohen's $d = 0.13$). These results suggest that participants maintained
stable task accuracy across experimental sessions during MRI scanning. (Fig. 1d; Paths of
individual participants are shown in Fig. S4).

a

6-fold modulator

Misligned bins

Aligned bins

180° 0°

b

6-fold
neural correlates

ERC

x = 30

y = -7

c

ROI analysis

Sagittal plane
x = 30

**

Beta value

0.50

0.25

0.00

3-fold 4-fold 5-fold 6-fold 7-fold

d

Reconstructed BOLD activity

Beta value

0.5

0.0

-0.5

0° 60° 120° 180° 240° 300°

180°

0°

Fig. 2. 6-fold periodicity in the EC. a) Schematic defining path directions in the 6-fold modulation. Participants' path directions (Top) were extracted from the original paths (Left) by connecting the starting and ending locations, with 0° arbitrarily set to the East as the reference, and were then classified as "aligned" or "misaligned" (Right & Bottom). The original paths of each participant were referred to Fig. S4. b) Voxel-based sinusoidal modulation revealed significant 6-fold periodicity within the right EC (Voxel-based analysis: initial threshold: $p = 0.05$, two-tailed; cluster-based small volume correction (SVC) for multiple comparisons: $p < 0.05$; Cohen's $d = 0.63$; Peak MNI coordinate: 32, -6, -30). Volumetric results are displayed in radiological orientation; numbers below the brain slices indicate MNI coordinates. c) ROI-based analysis, using a functional mask derived from the significant right EC cluster and constrained within the anatomical EC, confirmed a significant 6-fold periodicity ($t(32) = 3.56$, $p = 0.006$, two-tailed, corrected for multiple comparisons across rotational symmetries; Cohen's $d = 0.62$). The black line indicates the boundary of the EC. d) Schematic illustrating the 6-fold directional tuning curve reconstructed from sinusoidal modulation (Left) and its representation in the 2D Greeble space (Right).

6-fold periodicity in the EC

Using sinusoidal modulation, the grid orientation, reflecting the allocentric direction of the grid axes, was calculated for each voxel within the bilateral EC using half of the dataset (Experimental session 1, 3, 5, 7). Participants' path directions were determined by the 2D position of Greeble variants relative to the ending locations, with 0° arbitrarily defined as movement from the East (Fig. 2a). Significant deviations from uniformity were observed in 30 out of 33 participants (Fig. S5, $p < 0.05$; Rayleigh test of uniformity and pairwise phase consistency (PPC), Bonferroni-corrected across participants), indicating that voxelwise grid orientations in the EC were consistent for the majority of participants.

Hexagonal 6-fold activity was examined using the other half of the dataset (Experimental session 2, 4, 6, 8), with path directions calibrated according to participant-dependent grid

orientations. This analysis identified a significant cluster in the right EC (Fig. 1b; initial

threshold: p = 0.05, two-tailed; cluster-based SVC correction for multiple comparisons: p

< 0.05; Cohen's d = 0.63; Peak MNI coordinate: 32, -6, -30). Four ROI-based control

analyses were performed using rotationally symmetric parameters (3-, 4-, 5-, and 7-fold)

to validate the robustness of the cluster in representing the 6-fold periodicity. The ROI

was defined as a functional mask of the right EC identified in the voxel-based analysis

and further restricted within the anatomical EC. These analyses revealed significant

periodic modulation only at 6-fold (Fig. 2c; t(32) = 3.56, p = 0.006, two-tailed, corrected

for multiple comparisons across rotational symmetries; Cohen's d = 0.62). In contrast, no

significant effects were observed for 3-fold periodicity (120° periodicity; t(32) = 1.10, p

= 0.28, Cohen's d = 0.19), 4-fold periodicity (90° periodicity; t(32) = 0.31 , p = 0.76,

Cohen's d = 0.05), 5-fold periodicity (72° periodicity; t(32) = -0.21, p = 0.83, Cohen's d

= -0.04), or 7-fold periodicity (51.4° periodicity; t(32) = 0.88, p = 0.39, Cohen's d =

0.16).

We further examined the fluctuation of hexagonal activity across the angular domain of

path directions, following the approach reported in previous studies (Doeller et al., 2010;

Constantinescu et al., 2016; Bao et al., 2019; Wagner et al., 2023; Raithel et al., 2023). In

these studies, EC activity exhibited six peaks as a function of path direction. To do so, we

reconstructed the BOLD signals using sinusoidal modulation for each path direction and

each participant. To account for individual difference in spatial phase, path directions

were calibrated by subtracting the participant-specific grid orientation estimated from the

odd sessions. The directional tuning curve was then derived by averaging the

reconstructed BOLD signals across voxels within a hand-drawn bilateral EC mask and

across participants. A stable 6-fold periodicity was observed (Fig. 2d, left; p < 0.05,

permutation corrected for multiple comparisons), characterized by stronger activity when

path directions were aligned with the calibrated grid axes and weaker activity when they

were misaligned, confirming a 60° periodicity of EC activity across conceptual directions

in the Greeble space (Fig. 2d, right).

Fig. 3. 3-fold periodicity in the HPC. a) Schematic illustration of the spectral analysis

procedure. b-c) Voxel-based spectral analysis revealed significant 3-fold periodicity in

the bilateral HPC and 6-fold periodicity in the bilateral EC (initial threshold: $p = 0.05$,

two-tailed; Cluster-based SVC correction for multiple comparisons: $p < 0.05$; For the

HPC: Cohen's $d = 1.06$; Peak MNI coordinate: -24, -20, -18; For the EC: Cohen's $d =$

1.27; Peak MNI coordinate: -22, -14, -30). The black lines indicate the boundaries of the

HPC and EC. d-e) 3-fold periodicity in the bilateral HPC identified using sinusoidal

modulation (initial threshold: $p = 0.05$, two-tailed; cluster-based SVC correction: $p <$

0.05; Cohen's $d = 0.68$; peak MNI coordinate: $-24, -18, -12$). ROI-based analysis using

a functional mask of this cluster within the anatomical HPC confirmed the effect ($t(32) =$

3.94, $p = 0.002$; Cohen's $d = 0.70$). Volumetric results are displayed in radiological

orientation; numbers below the brain slices indicate MNI coordinates. f) Schematic

illustrating the 3-fold directional tuning curve reconstructed from sinusoidal modulation

(Left) and its representation in the 2D Greeble space (Right).

3-fold periodicity in the HPC

Potential neural periodicity in the HPC was assessed using a Fast Fourier Transform

(FFT)-based spectral analysis. FFT was employed to permit unbiased identification of

multiple candidate periodicities (e.g., from 3- to 7-fold), independent of any a priori

assumptions regarding spatial phase (orientation). Unlike the EC where a 6-fold

periodicity is well established, the periodic structure of the HPC was not known a priori.

FFT was thus applied as a phase-invariant approach to detect potential periodicities.

Moreover, FFT was employed as an independent analysis to cross-validate the sinusoidal

modulation results, thereby offering complementary evidence for the 6-fold periodicity in

EC and the 3-fold periodicity in HPC. Accordingly, BOLD signals from all eight

experimental sessions were modeled using a GLM to estimate direction-dependent

activity. Participants' path directions were down-sampled into 10° bins, resulting in a

total of 36 directional bins (e.g., 0°, 10°, 20°, etc.). These bins were entered into the GLM

as binary regressors. The resulting direction-dependent parametric maps were sorted in

ascending order of spatial directions, and FFT was applied to extract spectral magnitude

maps for periodicities ranging from 3- to 7-fold (Fig. 3a; see Methods for details).

A significant cluster of 3-fold periodicity was observed in the bilateral HPC (Fig. 3b;

initial threshold: p = 0.05, two-tailed; Cluster-based SVC corrected for multiple

comparisons: p < 0.05; Cohens' d = 1.06; Peak MNI coordinate: -24, -20, -18). Moreover,

a significant cluster of 6-fold periodicity was identified in the right EC (Fig. 3c; initial

threshold: p = 0.05, two-tailed; Cluster-based SVC-corrected for multiple comparisons: p

< 0.05; Cohen's d = 1.27; Peak MNI coordinate: -22, -14, -30), thereby replicating the

finding from the sinusoidal modulation. No significant periodic activity was observed for

the other folds (P > 0.05).

The hippocampal 3-fold periodicity has not been previously reported in the spatial

domain by either neurophysiological or fMRI studies. To validate its reliability, we

conducted additional analyses. First, sinusoidal modulation confirmed significant 3-fold

clusters in the bilateral HPC (Fig. 3d; initial threshold: p = 0.05, two-tailed; Cluster-based

SVC-corrected for multiple comparisons: p < 0.05; Cohen's d = 0.68; Peak MNI

coordinate: -24, -18, -12). ROI analysis, using a functional mask of the HPC identified in

the spectral analysis and further restricted within the anatomical HPC, indicated that HPC

activity selectively fluctuated at 3-fold periodicity (Fig.3e; t(32) = 3.94, p= 0.002,

corrected for multiple comparisons across rotational symmetries; Cohen's d = 0.70),

whereas no significant activity periodicity was observed at other spatial fold (4-fold

periodicity: t(32) = 0.09, p = 0.93, Cohen's d = 0.02; 5-fold periodicity: t(32) = 0.31, p =

0.76, Cohen's d = 0.05; 6-fold periodicity: t(32) = 2.36, p = 0.12, Cohen's d = 0.42; 7-

fold periodicity t(32) = 1.21, p = 0.24, Cohen's d = 0.21). The reconstructed BOLD

signals, direction-calibrated for each participant based on their spatial phase estimated

from sinusoidal modulation, showed a significant 3-fold periodic pattern in the bilateral

HPC (Fig. 3f, left; p < 0.05, corrected for multiple comparisons). In sum, both the

spectral and sinusoidal modulation confirmed a 3-fold periodic activity in the HPC across

the conceptual directions within the 2D Greeble space (Fig. 3f, right), which was distinct

from the 6-fold periodicity observed in the EC.

Second, the 3-fold HPC periodicity was not affected by the precision of directional

sampling, as consistent findings were observed when 20° bins were applied (Fig. S6;

initial threshold: $p = 0.05$, two-tailed; Cluster-based SVC corrected for multiple

comparisons: $p < 0.05$; Cohen's $d = 1.18$; Peak MNI coordinate: 22, -24, -14). Third, we

independently analyzed HPC and EC periodicity using spectral analysis for each of the

three site-dependent experimental groups (See methods for details). These analyses

showed reliable activity periodicities in both brain areas across experimental groups (Fig.

S7; initial threshold: $p = 0.05$, two-tailed. Cluster-based SVC corrected for multiple

comparisons: $p < 0.05$). Fourth, we further examined the whole brain representation of

both 3- and 6-fold activity periodicity, respectively (Fig. S8). The 3-fold periodicity

revealed significant involvement of the medial prefrontal cortex (mPFC), precuneus

(PCu), and parietal cortex (PC)(initial threshold: $p = 0.05$, two-tailed. Whole brain

correction for multiple comparisons: $p < 0.05$), suggesting engagement of the default

mode network (DMN). In contrast, the 6-fold periodicity highlighted the Salience

network, including the anterior cingulate cortex (ACC) and insular cortex (INS), in

addition to the EC (initial threshold: $p = 0.05$, two-tailed; Whole brain cluster-based

correction for multiple comparisons: $p < 0.05$). These results demonstrated distinct

functional networks involved in integrating spatial metric (6-fold periodicity) and in

judging self-motion within conceptual space (3-fold periodicity).

Fig. 4. Phase synchronization between the HPC and EC activity in the directional domain. a) Cross-participant circular–circular correlation analysis revealed a significant coupling between the EC and HPC phases (r = 0.42, p < 0.001). The green (outer ring) and purple (inner ring) dots denote HPC and EC phases, respectively. Each line connecting the EC and HPC phases represents one participant, with its color indicating the HPC phase (0–120°). b) Schematic illustration of a hypothetical peak-overlapping pattern (blue ellipse) between the HPC and EC activity in corresponding to spatial phase (one-cycle). c) Amplitude-phase modulation analysis revealed significant coupling between the 3-fold HPC activity and 6-fold EC activity in the bin centered at phase 0 (t(32) = 2.57, p = 0.02, Bonferroni-corrected across tests; Cohen's d = 0.45). The coupling strength was computed as the difference between the observed modulation index (M) and the mean surrogate modulation index (M'). No significant coupling was observed in the control analyses testing phase synchronization between the 3-fold HPC

and the 9-fold or 12-fold EC periodicities (p > 0.05). The error bars indicate SEM. ***: p < 0.001.

Phase synchronization between the HPC and EC activity

To examine whether the spatial phase structure in one region could predict that in another, we tested whether the orientations of the 6-fold EC and 3-fold HPC periodic activities, estimated from odd-numbered sessions using sinusoidal modulation with rotationally symmetric parameters (in radians), were correlated across participants. A cross-participant circular–circular correlation was conducted between the spatial phases of the two areas to quantify the spatial correspondence of their activity patterns (EC: purple dots; HPC: green dots) (Jammalamadaka & Sengupta, 2001). The analysis revealed a significant circular correlation (Fig. 4a; r = 0.42, p < 0.001), as reflected by the continuous color progression across the participants (i.e., the colored lines connecting each pair of the EC and HPC dots in Fig.4a), suggesting that participants with smaller hippocampal phases (green, outer ring) tended to have smaller entorhinal phases (purple, inner ring), and vice versa.

In addition to the across-participant phase correlation, we further examined the spatial alignment between the 6-fold EC and 3-fold HPC activity patterns. Given that the spatial phase of the HPC depends on EC's projections as we hypothesized, particularly along the three primary axes of the hexagonal codes, we examined whether the periodic activities of the EC and HPC were peak-overlapped? Notably, unlike previous studies that examined temporal coherence of neural oscillations (Buzsaki, 2006; Maris et al., 2011; Friese et al., 2013), our analysis focused on the periodic coupling of brain areas in spatial direction domain. To test this, a cross-frequency spatial coupling analysis (adapted from the amplitude–phase coupling framework; Canolty et al., 2006) was employed to identify at which HPC phase the EC exhibited maximal amplitude modulation, quantified by a modulation index M (Canolty et al., 2006). If the activities of both areas were peak-overlapped (i.e., no peak offset), a strong coupling at phase 0 of the HPC would be expected as shown by the one-cycle-based schema in Fig. 4b.

The BOLD signals of both regions were first reconstructed using sinusoidal modulation

based on participants' path directions, without calibrating their spatial phase estimated

from rotationally symmetric parameters. The 6-fold EC and 3-fold HPC activity were

then converted into analytic representations using the Hilbert transform to extract their

instantaneous phase of the HPC (ϕ_{HPC}) and amplitude envelope of the EC (A_{ERC}). The

phases of the HPC were classified into nine bins. The composite analytic signal, defined

as $z = A_{ERC}e^{i\phi_{HPC}}$, was then used to compute the modulation index M, defined as the

absolute value of the mean of z values within each bin, quantifying the scalar coupling

strength between EC amplitude and HPC phase. To assess statistical significance, a

surrogate dataset, a null distribution of the modulation indices (M'), was generated by

spatially offsetting the EC amplitude relative to the HPC phase across all possible spatial

lags. This procedure preserved the within-region structure while disrupting inter-regional

alignment. The mean of this surrogate distribution was used as the baseline reference

against which the observed coupling strength was compared. As the result, significant

coupling was observed in the bin centered at phase 0 of the HPC (Fig.4c; t(32) = 2.57, p

= 0.02, Bonferroni-corrected across tests; Cohen's d = 0.45). In contrast, no significant

coupling was found in other bins (p > 0.05). To rule out the possibility that the observed

coupling was driven by the integer multiple (harmonic) relationship between the 3-fold

and 6-fold periodicities, we additionally conducted control analyses using 9-fold and 12-

fold EC components. However, no significant coupling was observed in these controls

(Fig.4c; P > 0.05). Together, these results confirmed selective alignments of spatial peaks

between the 6-fold EC and 3-fold HPC periodicity in the conceptual direction domain.

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Fig. 5 3-fold periodicity in behavioral performance. a) Schematic illustration of
visuospatial task performance potentially inheriting HPC's 3-fold periodicity. b)
Participants' behavioral performance, measured by a composite index of path length and
deviation from the goal to ending locations, fluctuated as a function of path directions.
The shaded area denotes SE. c) Spectral analysis revealed significant power at the 3-fold
of participants' behavioral performance ($p < 0.05$, corrected for multiple comparisons).
The red dashed line represents the baseline derived from permutation. d) Significantly
higher phase-locking values were observed between participants' behavioral performance

and HPC activity compared to surrogate dataset (t(32) = 8.10, p < 0.001; Cohen's d =
1.14).

3-fold periodicity in human behavior

Considering the reciprocal connectivity between the medial temporal lobe (MTL), where

the EC and HPC reside, and the parietal cortex implicated in visuospatial perception and

action, together with the observed 3-fold periodicity within the DMN (including the PC

and PCu; Fig. S8), we hypothesized that the 3-fold periodic representations of path

directions extend beyond the MTL to the egocentric cortical areas, such as the PC,

thereby influencing participants' visuospatial task performance (Fig. 5a). To test this

hypothesis, we assessed participants' behavioral performance using two metrics: (1) path

length and (2) the deviation (i.e., error size) between the actual ending location and the

goal location per trial, since participants rarely stopped exactly at the goal. This

procedure yielded, for each participant, a performance vector in the directional domain

(Fig. 5b), with superior performance indexed by a composite score reflecting shorter path

and smaller error size.

Using spectral analysis, we identified a significant periodicity in participants' behavioral

performance, with spectral power peaking at a 3-fold symmetry (Fig. 5c; p < 0.05,

permutation corrected for multiple comparisons), demonstrating that participants'

visuospatial perception performance fluctuated as a function of path directions. In

contrast, no significant spectral power was observed at other spatial folds, including 6-

fold behavioral periodicity (p > 0.05). As a control, we also examined behavioral

periodicity along each individual metric, path length and error size. A significant 3-fold

periodicity was observed for path length (Fig. S9; p < 0.05, permutation-corrected for

multiple comparisons), whereas no significant modulation was found for error size, likely

reflecting a residual 4-fold bias inherent to the four cardinal-direction movement

structure. To further investigate the causal relationship in brain-behavior coupling, we

calculated the phase-lag index between the 3-fold behavioral periodicity and HPC

activity for each participant (Stam et al., 2007). This analysis revealed a significantly

higher phase-locking value (PLV) compared to surrogate dataset (Fig. 5d; t(32) = 8.10, p

< 0.001; Cohen's d = 1.14), confirming phase coupling between the 3-fold HPC activity

and the 3-fold behavioral performance. Contrary to the commonly held assumption of

isotropic task performance across path directions, these results demonstrated a biased

behavioral pattern influenced by HPC and EC activity periodicity, with superior

navigational performance (i.e., shorter path length and smaller error size) observed when

path directions aligned with grid axes compared to when they were misaligned.

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Fig. 6. The EC-HPC PhaseSync Model. a) Schematic illustrating the population activity
of grid cells during mental planning. The simulated grid cell population was activated by
visiting discrete locations (the black circles in the right panel) in the Greeble space along

directions either aligned (purple) or misaligned (grey) relative to the grid axes. b) The 3-

fold periodicity of the path code V represented in the HPC. A path code V is symmetrical

for path direction ϕ and $\phi+180°$, representing a unique spatial orientation ψ ranging

from 0° to 180°. The δ value (y-axis) indicates the degree to which the spatial orientation

ψ of a path code V aligns with the grid axes, with larger δ values (e.g., the spatial

orientation (1, 3, and 5)) indicating a perfect match between ϕ and grid axes. c)

Simulated vectorial representation of the HPC for centered-goal-based navigation. The 3-

fold periodicity is driven by vectorial gradients inherited from δ. d) Random-goal-based

navigational simulation. Significant spectral power of model performance was observed

at 3-fold across 100 randomly selected goal locations (the blue dots and gray lines)

(P<0.05, corrected for multiple comparisons). The red dashed line indicates the

significance threshold derived from permutation. The blue shaded areas denote the

standard error. Grey lines represent the spectral powers of goal-dependent simulations.

The "EC-HPC PhaseSync" Model

The above empirical results elucidate that the vectorial representations of the HPC,

characterized by 3-fold activity periodicity, were spatially coherent with EC population

activity across the directional domain. To mechanistically explain how the 6-fold EC

code gives rise to a 3-fold HPC representation, we constructed a cognitive model, termed

the "EC-HPC PhaseSync" model (Fig. 6), which demonstrates the possible computational

mechanism of the EC-HPC circuit, through simulating how the periodic representations

emerged in the HPC influences spatial movements toward the center of Greeble space, as

well as qualifying the reliability of the 3-fold periodic performance, particularly when

goal locations are randomly distributed across the conceptual space.

The EC grid code G was simulated using a cosine grating model (O'keefe and Burgess,

2005; Burgess et al., 2007; Blair et al., 2007; Bush and Schmidt-Hieber, 2018; see

methods for details). A population of 45-by-45 grid cells were generated to tessellate the

space (Fig. 6a, left), with spatial orientations kept constant while spatial phases varied

across locations. The population activity in the EC, associated with movements from a

start location, was termed the path code V, simulated by summing the grid codes across

locations along the path (Fig. 6a, right). Notably, the path code V is exactly identical for

path direction ϕ and $\phi + 180°$, naturally reflect the spatial orientation $\psi \in [0, \pi)$ across

the space.

The downstream HPC activity was simulated using a two-dimensional $\boldsymbol{\delta}$ vector to

represent spatial orientation. Each δ value, encoded by a single HPC neuron, was

obtained by linearly summing EC activity across locations along the path code V (Fig. 6b,

black dots). The spatial periodicity and spatial phase of $\boldsymbol{\delta}$ depend on the number of

primary axes and orientation of grid codes, while the magnitude of $\boldsymbol{\delta}$ indicates the degree

of alignment between the path orientation ψ and the grid axes. Therefore, the 3-fold

structure of $\boldsymbol{\delta}$, projected from the EC grid cells, initially represents environmental

orientations when self-location is not integrated. When self-location is anchored into

space, this 3-fold $\boldsymbol{\delta}$ structure embeds allocentric directions so that the preferred directions

can be distinguished. The amplitude of $\boldsymbol{\delta}$ reflects the directional modulation strength and

the phase specifies the angular offset of the 3-fold pattern. The goal-directed vector

representation C in the HPC was next simulated by integrating the $\boldsymbol{\delta}$ vector with a

Gaussian-based distance vector centered at the goal location, thereby driving movements

toward the goal (Fig. 6c).

During simulations, 100 goal locations were randomly generated within the space, each

paired with 120 starting locations, arranged in a ring-shaped pattern near the boundary.

At each simulation step, a vector of HPC activity was extracted from the locations

surrounding the current location, and the next movement was determined by the strongest

activity of adjacent locations, following winner-take-all dynamics. The step size,

initialized as 1 pixel, was dynamically adjusted using a stepwise approach, with a

maximum limit of 5 pixels; for example, the step size increased by 1 pixel if no stronger

activity was found among the surrounding locations compared to the activity of self-

location. Model performance was defined by the path length, calculated as the sum of

Euclidean distances between consecutive locations, with superior performance

corresponding to shorter path length. The model performance of all directions was sorted

in ascending order before spectral analysis, and the mean spectral powers, calculated

across 100 navigations tasks, was compared with a permutation-based significant

threshold. The simulations revealed a significant 3-fold periodicity in path length across

100 navigation tasks (Fig. 6d; $P < 0.05$, corrected for multiple comparisons). No other

periodicities reached significance ($P > 0.05$). These results demonstrate that projections

from grid cell populations can reproduce the 3-fold behavioral periodicity observed in

humans during goal-directed navigation.

Discussion

Spatial navigation, the cognitive process of retrieving spatial relationships from one

moment to the next in both conceptual (Epstein et al., 2017; Behrens et al., 2018; Bottini

and Doeller, 2020; Park et al., 2020) and physical spaces (Tolman, 1948; Sargolini et al.,

2006; Gardner et al., 2022; Ormond and O'Keefe, 2022), relies on the EC-HPC circuit.

These two areas are known to have distinct functions. The EC encodes continuous space

with a metric representation (Hafting et al., 2005), while the HPC represents localized

spatial locations (O'Keefe and Dostrovsky, 1971). A longstanding puzzle is how they

collaborate to encode spatial navigation. In the present study, we modulated the EC and

HPC activity using conceptual directions, and identified 6-fold periodicity from EC

activity and 3-fold periodicity from HPC activity. The periodic activities of both areas

were synchronized and peaked-overlapped. Additionally, 3-fold periodicity was also

observed in participants' behavioral performance, which was synchronized with the HPC

activity, suggesting a direct influence of periodic brain activity on visuospatial perception.

Our findings provide a potential explanation for the observation of the hippocampal

vector field (Sarel et al., 2017; Ormond and O'Keefe, 2022; Muhle-Karbe et al.,2023).

In addition to the HPC and EC, whole-brain spectral analysis revealed involvement of the

DMN and salience network for the 3- and 6-fold periodicity, respectively, suggesting that

concept-dependent periodic neural activity is supported by distinct networks and extends

beyond the EC–HPC circuit. These results do not imply that grid cell's hexagonal code is

the origin of the spatially selective periodic activity observed in these brain networks.

Rather, these large-scale activity dynamics more likely reflect hierarchical computations

across the brain. In upstream visual areas, neurons encode position-specific features and

provide egocentric cues when an allocentric map is unavailable, as seen in the feature-selective neurons in V1 that represent locations across visual space, as described by Hubel and Wiesel (1959, 1962). Moreover, spatial attention has been shown to operate through rhythmic sampling in the temporal domain. Neural activity in the frontoparietal attention networks oscillates at 3–8 Hz and predicts trial-by-trial performance in spatial discrimination tasks (Fiebelkorn et al., 2018). This finding parallels our observed 3-fold behavioral periodicity, indexed by task performance, suggesting that neural representation in both the temporal and spatial domains may rely on periodic computations, potentially reflecting a shared mechanism by which the brain organizes perception and guides goal-directed behavior.

The EC–HPC PhaseSync model demonstrates how a vectorial representation may emerge in the HPC from the projections of populations of periodic grid codes in the EC. The model was motivated by two observations. First, the EC intrinsically serves as the major source of hippocampal input (Witter and Amaral, 1991; van Groen et al., 2003; Garcia and Buffalo, 2020), and grid codes exhibit nearly invariant spatial orientations (Hafting et al., 2005; Gardner et al., 2022). Second, mental planning, characterized by "forward replay" (Dragoi and Tonegawa, 2011; Pfeiffer, 2020), has the capacity to activate populations of grid cells that represent sequential experiences in the absence of actual physical movement (Nyberg et al., 2022). We hypothesize that an integrated path code of sequential experiences may eventually be generated in the HPC, providing a vectorial gradient toward the goal location. The path code exhibits regular, vector-like representations when the path direction aligns with the orientations of grid axes, and becomes irregular when they misalign. This explanation is consistent with the band-like representations observed in the dorsomedial EC (Krupic et al., 2012) and the irregular activity fields of trace cells in the HPC (Poulter et al., 2021).

In sum, our study identifies a 3-fold hippocampal code that complements the 6-fold EC metrics, potentially supporting flexible navigation. Extending previous cognitive models based on grid- and place-cell simulations of navigation (Bicanski and Burgess, 2019; Whittington et al., 2020; Edvardsen et al., 2020), our findings highlight a potential

hierarchical periodic architecture of neurons within the MTL, particularly in representing

spatial directions. Moreover, considering that the task space was simplified to an

idealized square layout. In more complex, real-world environments, hippocampal three-

fold periodicity may interact with other spatial variables such as distance, movement

speed, and environmental boundaries. Future studies should aim to characterize how the

periodic activity of the EC–HPC circuit interacts with the external environment to

support real-world navigation.

Methods

Participants

Thirty-three right-handed university students with normal or corrected-to-normal vision participated in the experiment. Participants were recruited in three separate batches: 10 from Tsinghua University (Group 1: mean age = 23.9 [SD = 3.51], 5 females, 5 males), 10 from Peking University (Group 2: mean age = 22.10 [SD = 2.23], 5 females, 5 males), and 13 from Tsinghua University (Group 3: mean age = 20.85 [SD = 3.08], 2 females, 11 males). All participants had no history of psychiatric or neurological disorders and gave their written informed consent prior to the experiment, which received approval from the Research Ethics Committee of both universities.

Greeble space

The Greebles (Gauthier and Tarr, 1997) were generated based on the modified codes of the TarrLab stimulus datasets (http://www.tarrlab.org/) using Autodesk 3ds Max (version 2022, http://www.autodesk.com). A Greeble's identity was defined by the lengths of two distinct features, represented by two nonsense words, "Loogit" and "Vacso" (Fig. 1a). These nonsense names were arbitrarily assigned and carried no semantic relevance to the task. The generated Greebles were arranged in a 45-by-45 matrix, forming a two-dimensional space, with each Greeble representing a "location". The feature 'Loogit' corresponded to the y-axis, while the feature 'Vacso' represented the x-axis (Fig. 1c). The prototype Greeble, positioned at the center of the Greeble space (Fig. 1c; blue dot), served as the target (i.e., "goal location"), with Loogit and Vacso having equal lengths. The length ratios of Greebles' feature relative to the Greeble prototype ranged from 0.12 to 1.88, with a step size of 0.04, providing a smooth morphing experience as participants adjusted the lengths of the Greeble features.

Experimental design.

The object matching task was programmed using Pygame (version 2.0, https://www.pygame.org/; Python version 3.9). Each trial began with a 2.0-s fixation screen, followed by a pseudo-randomly selected Greeble variant presented at the center of the screen (Fig. 1b). These variants were sampled from those near the boundary of the

feature space (Fig. 1c; orange dots). Participants were instructed to adjust the features of

the Greeble variant by pressing buttons to match the Greeble prototype as quickly as

possible. Two response boxes enabled participants to stretch or shrink the two features.

These boxes were counterbalanced between the left and right hands of participants. To

mitigate the impact of learning effects on BOLD signals, participants completed a

training task one day prior to MRI scanning. On the training day, participants completed

the task in a self-paced manner. They first familiarized themselves with the task and then

performed at least 10 practice trials before the main training session, freely adjusting

Greeble features and pressing the return key to end each trial. Feedback was provided

during the first 7 sessions (e.g., "Loogit: 5 percent longer than the target"), while no

feedback was given in the final session. Day 2's MRI experiment procedure mirrored day

1, except that 1) participants were required to complete a trial within 10 seconds. A timer

was presented on top of screen (Fig. 1b), and 2) no feedback was provided for all

experimental sessions. Based on the present design, the "path" from a Greeble variant

towards the prototype can be interpreted as forming a conceptual direction. To ensure an

even distribution of conceptual directions, we arbitrarily defined the "movement" from

the East as 0°. For each 30° bin, 24 Greeble variants were pseudo-randomly selected

from the boundary of the feature space with an angular precision of 1.25°, resulting in a

total of 288 Greeble variants distributed in 8 experimental sessions. Each session

contained 36 object matching trials and 4 lure trials. The lure trial presented a blank

screen after the fixation for 10 seconds. The MRI experiment lasted approximately 1

hour. Participants were incentivized to perform accurately with exponentially increasing

monetary rewards based on their performance. After the scan, participants were

debriefed, shown their performance results, and asked to discuss their subjective feeling

as well as any perceived reasons for any performance issues. Importantly, participants

were unaware of the existence of the Greeble space or the spatial features such as the

location and direction during the task.

Behavioral performance

The behavioral performance score was calculated for each trial as $T - T' + E/0.04$,

where T and T' denote the participants' actual and the objectively optimal path length,

respectively. The term $E/0.04$ quantified the error size, the Euclidean distance (in pixels)

between the participant's ending locations (final adjusted Greeble) and the goal location

(Greeble prototype). The constant "0.04" represents the step size of the Greeble feature

ratio, and was used to convert the ratio-based error to pixel units. The actual path length

T was defined as the number of movement steps (in pixels) recorded from the

participant's paths, whereas the optimal path length T' was determined by the number of

pixels in the shortest possible path between the Greeble variants and Greeble prototype.

Subtracting T' from T thus normalized each participant's performance relative to the

optimal path. The rationale for this correction was to eliminate the systematic difference

in path length between cardinal (i.e., "East", "South", "West", and "North") and

intercardinal (e.g., "Southeast") directions, which arises from the restricted movements

along the horizontal and vertical axis of the squared Greeble space. In this design,

movements along cardinal directions inherently result in shorter paths, while those along

intercardinal directions become longer. Although this normalization effectively reduced

the directional bias in path length, it did not remove the residual 4-fold bias in error size.

Nevertheless, because path length and error size capture complementary aspects of task

performance—navigational efficiency and positional accuracy—we incorporated both

terms in quantifying behavioral performance. Superior performance was represented by

shorter paths and smaller errors, corresponding to lower performance scores.

fMRI data acquisition

Imaging data were collected using a 3T Siemens Prisma scanner, equipped with a 64-and

20-channel receiver head coil at Tsinghua University and Peking University Imaging

Center, respectively. Functional data were acquired with a Multi-band Echo Planer

imaging (EPI) sequence with the following parameters: Acceleration Factor: 2, TR =

2000 ms, TE = 30 ms, matrix size = 112 × 112 x 62, flip angle = 90°, resolution = 2 × 2 ×

2.3 mm³, 62 slices with a slice thickness of 2 mm and a gap of 0.3 mm, in a transversal

slice orientation. Additionally, high-resolution T1-weighted three-dimensional

anatomical datasets were collected for registration purposes using MPRAGE sequences,

detailed as follows: TR = 2530 ms, TE = 2.98 ms, matrix size = 448 x 512 x 192, flip

angle = 7°, resolution = 0.5 × 0.5 × 1 mm³, 192 slices with a slice thickness of 1 mm, in

the sagittal slice orientation. At Tsinghua University, stimuli were presented through a Sinorad LCD projector (Shenzhen Sinorad Medical Electronics) onto a 33-inch rear-projection screen. At Peking University, stimuli presentation was managed using a visual/audio stimulation system (Shenzhen Sinorad SA-9939) and an MRI-compatible 40-inch LED liquid crystal display, custom-designed by Shenzhen Sinorad Medical Electronics Co., Ltd. The screen resolution for both sites was 1024 x 768. Participants viewed the stimuli through an angled mirror mounted on the head coil.

fMRI data preprocessing

The BOLD signal series of each scanning session was preprocessed independently using the FSL FEAT toolbox from the FMRIB's Software Library (version 6.0, https://fsl.fmrib.ox.ac.uk/fsl/fslwiki)(Smith et al., 2004; Woolrich et al., 2009; Jenkinson et al., 2012). For each scanning sessions, the BOLD signals were corrected for motion artifacts, slice time acquisition differences, geometrical distortion using fieldmaps, and were applied with a high-pass filter with a cutoff of 100 seconds. Spatial smoothing was performed using a Gaussian kernel with a full width at half maximum (FWHM) of 5 mm. For group-level analysis, the preprocessed BOLD signals were registered to each participant's high-resolution anatomical image and subsequently normalized to the standard MNI152 image using FSL FLIRT (Jenkinson and Smith, 2001). During normalization, the functional voxels were resampled to the resolution of 2 x 2 x 2 mm.

Sinusoidal modulation

A GLM with sinusoidal regressors was employed to investigate the periodic neural activity in the EC and HPC, following previously established protocols (Doeller et al., 2010; Constantinescu et al., 2016; Bao et al., 2019; Wagner et al., 2023; Raithel et al., 2023). First, the grid orientation in each voxel within the EC from each participant was calculated using half of the dataset (odd-numbered sessions: 1, 3, 5, 7). Specifically, a GLM was created for each session to model the BOLD signals of the EC with two parametric modulators: $\sin(6\theta)$ and $\cos(6\theta)$, convolved with the Double-Gamma hemodynamic response function. θ represents the path directions, derived from drawing a line between the starting and the ending location, as each raw adjustment step was limited

to four cardinal directions. Defining direction by start–end vectors thus allowed full 0–

360° coverage, consistent with previous grid-like coding studies (e.g., Constantinescu et

al., 2016). The factor "6" represents the rotationally symmetric 6-fold neural activity. The

factors "3", "4", "5" and "7", misaligned with the primary axes of grid cells, were used as

control parameters. The estimated weights β_{sine} and β_{cosine} were then used to compute

the grid orientation φ, ranging from 0° to 59°, where $\varphi = [\arctan(\frac{\beta_{sine}}{\beta_{cosine}})]/6$. The φ

maps of each participant were averaged across the voxels of a hand-drawn bilateral EC

mask and odd-numbered sessions to represent the grid orientation. Second, the neural

representation of hexagonal activity, modulated by path directions in Greeble space, was

examined by another GLM using the other half of the dataset (even-numbered sessions:

2, 4, 6, 8), with path direction calibrated by the participant-specific grid orientation. The

GLM was specified with a cosine parametric modulator, $\cos(6[\theta - \Phi])$. Third, the

hexagonal activity maps were averaged across the even-numbered sessions for each

participant before entering second-level analysis. The same procedure was applied to the

bilateral HPC to test for 3-fold periodicity. Specifically, voxel-wise phase estimates were

obtained from odd sessions using $\sin(3\theta)$ and $\cos(3\theta)$ regressors, and the participant-

specific 3-fold phase was obtained by averaging voxel-wise estimates across the bilateral

HPC, using a mask derived from the AAL template. In the even sessions, path directions

were rotationally calibrated by subtracting this participant-specific phase, and a GLM

with $\cos(3[\theta - \Phi])$ was fitted. The resulting maps of 3-fold periodic modulation were

averaged across even sessions for each participant and then submitted to group-level

analysis. To present the directional tuning curves of EC and HPC activity in the angular

domain of path directions, we reconstructed the BOLD signals for each participant using

parameters estimated from sinusoidal modulation. Functional masks derived from

significant subregions identified in the voxel-wise analyses were employed to capture

their tuning profiles with maximum sensitivity.

Spectral analysis of MRI BOLD signals

Spectral analysis was employed to examine the spatial periodicity of BOLD signals. This

procedure consisted of three stages: First-level analysis. A GLM was constructed to

estimate direction-dependent activity maps. Participants' path directions were down-

sampled into 36 bins of 10° each (e.g., path directions between 0° and 10° were assigned

to the 0° bin, whereas those between 350° and 360° were assigned to the 350° bin). These

bins were entered as regressors in the GLM, yielding activity estimates associated with

each directional bin for every participant. Second-level analysis. The direction-dependent

activity maps were sorted in ascending order (from 0° to 360°), detrended, and processed

with a Hanning window. They were then transformed from the spatial to the frequency

domain using FFT (implemented in the stats package of R, version 4.0; https://www.r-

project.org/) (Landau and Fries, 2012). The absolute values of the complex FFT outputs

were used to generate spectral magnitude maps for each participant, covering

periodicities from 0- to 18-fold. Third-level analysis. For group inference, the 95th

percentile (two-tailed) of the pseudo-t distribution, computed as the mean spectral

magnitude divided by the standard error across participants, was used as the initial

threshold for family-wise error correction in multiple comparisons.

Anatomical masks

The mask of the bilateral EC was manually delineated on the MNI T1 brain with 1 mm

resolution packaged by FSL, using established protocols (Insausti et al., 1998), and the

delineation software ITK-SNAP (Version 3.8, www.itksnap.org). The EC mask was then

resampled to a 2 mm resolution. The anatomical mask of the bilateral HPC and the MTL

were derived from the AAL atlas, an automated anatomical parcellation of the spatially

normalized single-subject high-resolution T1 volume provided by the Montreal

Neurological Institute (Version: AAL 3v2; https://www.gin.cnrs.fr/en/tools/aal/)(Rolls et

al., 2020).

Spectral analysis of human behavior

FFT analysis was employed to examine participants' behavioral periodicity, following

the same procedure used to detect activity periodicity in the EC and HPC. For each

participant, a performance vector was constructed from their paths. These vectors were

down-sampled into 10° bins from the original 288 conceptual directions (from 0° to

360°), sorted in ascending order, detrended and processed with a Hanning window. This

procedure yielded a resampled vector of 36 data points, which was then entered into the

FFT analysis. The two-tailed 95th percentile of the spectral magnitude distribution was

used as the initial threshold for the family-wise error correction across multiple

comparisons.

The "EC-HPC PhaseSync" model

The EC grid-cell spatial code G was simulated using the cosine grating model (O'keefe

and Burgess, 2005; Burgess et al., 2007; Blair et al., 2007; Bush and Schmidt-Hieber,

2018) in Python (version 3.9). At each Greeble location $r = (x, y)$, three cosine gratings,

oriented 60° apart, were generated by rotating around the anchor point r according to the

rotation vector k, and then linearly summed (Equation 1). The parameter A represents the

amplitude of the cosine gratings, $c = (c_x, c_y)$ denotes the spatial phase offset of the

grating pattern, and ω indicates the scale ratio (i.e., grid modules). This procedure

generated a 45-by-45 grid cell population, with a constant grid orientation maintained

across the population.

779
$$G_r = \sum_{i=1}^{3} A \cos(\omega_i(k_{i,x}(r_x - c_x) + k_{i,y}(r_y - c_y))) \qquad (1)$$

781 The path code V of grid cell population was defined as the linear summation of

782 grid codes across locations along the path (Equation 2), where r and q denote the starting

783 location (i.e., Greeble variant) and the ending location (Greeble prototype), and r'

784 indexes the intermediate locations along the path from r to q.

785
$$V_r = \sum_{r' \in trajectory(r,q)} G_{r'} \qquad (2)$$

V exhibited a "planar wave" pattern (Welday et al., 2011; Krupic et al., 2012)

when the allocentric direction ϕ_r, defined by $\arctan2\left(\frac{q_y - r_y}{q_x - r_x}\right)$, aligned with the primary

axes of grid cells (i.e., orientation $\boxed{1}\boxed{3}\boxed{5}$; aligned conditions). In contrast, when the

allocentric direction ϕ_r deviated from the grid axes (i.e., orientation $\boxed{2}\boxed{4}\boxed{6}$; misaligned

conditions), irregular activity patterns emerged from the path code V. Note that the path

code V is exactly identical between the allocentric direction ϕ and $\phi + 180°$. In other

words, the Greeble space can be tessellated by a vector of orientations over $\psi \in [0, \pi)$ in

the orientation domain (Equation 3).

$$\psi_r = \left(\arctan2\left(q_y - r_y, q_x - r_x\right)\right) mod \ \pi \tag{3}$$

The neural representations of spatial orientation ψ can be simplified as a two-

dimensional vector $\boldsymbol{\delta}$, where each δ_r, representing activity in the 2D orientation space,

was derived from the path code V_r by linearly summing the activity of a set of locations R

along the path (Equation 4). The magnitude of δ_r indexed the degree of alignment

between the orientation ψ and the grid axes, with larger values indicating closer

alignment. In the orientation domain, the $\boldsymbol{\delta}$ vector was expected to exhibit a 3-fold

periodicity across environmental orientations, characterized by a repeating "aligned-

deviated" pattern driven by the periodic structure of the path codes $V(\psi)$ projected from

grid cell population, with the spatial phase inherited from grid orientation.

$$\delta_r = \sum_{r \in R_\psi} V_{r,\psi} \tag{4}$$

To construct the goal-directed vector representation C of the HPC for driving

movements from self-location towards goal-location, the allocentric directions Φ between

the location vector R and the goal location were encoded by the $\boldsymbol{\delta}$ periodic structure, with

the spatial fold and spatial phase denoted by δ_c and δ_ε, respectively (Equation 5). Then,

C was the linearly summation between $\boldsymbol{\delta}$ and a Gaussian-based distance term centered at

the goal location q (Equation 5). The distance term is invariant to spatial directions but

encodes spatial proximity to the goal. The parameter σ represents the spatial spread,

defined by the radius of the Greeble space.

$$C(R) = \cos\left(\delta_c \times \Phi_R + \delta_\varepsilon\right) + \exp\left(-\frac{\|R - q\|^2}{2\sigma^2}\right) \tag{5}$$

Statistical analysis

Voxel-wise clusters from the sinusoidal modulation and spectral analyses were first

identified using a cluster-defining threshold of $p < 0.05$ (two-tailed t-test). Cluster

significance was determined with cluster-based permutation (5,000 iterations) using FSL

randomise (v2.9; Nichols & Holmes, 2002), with small-volume correction (SVC) applied

within the bilateral MTL. Clusters exceeding the 95th percentile of the maximal

suprathreshold cluster size were deemed significant. The directional tuning reliability was

assessed via a label-shuffling permutation, in which directional labels were randomly

permuted 5,000 times to derive a null distribution of spectral power. The 95th percentile

of surrogate power defined the uncorrected threshold, and the across-fold 95th percentile

served as the FWE–corrected threshold. For the PPC (Vinck et al., 2010), significance

was tested using 5,000 permutations of uniformly distributed random phases (0–2π) to

generate a null distribution for comparison with the observed PPC. For behavioral

periodicity, both human and EC–HPC PhaseSync model data were evaluated against

shuffled null distributions (5,000 iterations). Multiple comparisons across folds (0–18)

were controlled using the maximum-statistic approach. Finally, coherence analyses were

performed for EC–HPC and behavior–HPC coupling. Direction-domain signals were

band-pass filtered at the 3- and 6-fold using a two-way least-squares FIR filter (eegfilt.m,

EEGLAB; Delorme & Makeig, 2004). EC–HPC coherence was quantified using

amplitude–phase coupling (Canolty et al., 2006), and behavior–HPC coherence was

quantified using the phase-lag index (PLI; Stam et al., 2007). The relationship between

EC and HPC phases was evaluated using the circular–circular correlation

(Jammalamadaka & Sengupta, 2001) implemented in the CircStat MATLAB toolbox. For

all coherence and phase-coupling analyses, statistical significance was assessed using a

non-parametric permutation test. Surrogate datasets were generated by circularly shifting

the signal series along the direction axis across all possible offsets (Canolty et al., 2006),

thereby preserving the within-domain phase structure while disrupting consistent phase

alignment between signals. Each surrogate dataset underwent identical filtering and

coherence computation to obtain a null distribution. The observed coherence strength was

then compared with this distribution using paired t-tests across participants.

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Acknowledgments

We sincerely thank Yue Wu, Yuannan Li, and Ao Li for their thoughtful discussions that greatly contributed to our data analysis. We are also grateful to Russell Epstein for his insightful feedback on the fMRI analysis and computational modeling, and to Dr. Michael Tarr for generously sharing the code used for generating the Greeble stimuli. This work was supported by the High-Performance Computing Platform of Peking University and the Resnick High Performance Computing Center of California Institute of Technology.

Funding

The work was supported by the following funding sources: National Key R&D Program of China 2020AAA0105200 (J.L.), China Postdoctoral Science Foundation 2022M710470 (B.Z.), Beijing Municipal Science & Technology Commission & Administrative Commission of Zhongguancun Science Park Z221100002722012 (J.L.), Tsinghua University Guoqiang Institute 2020GQG1016 (J.L.), and Beijing Academy of Artificial Intelligence (J.L.).

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Supervision: J.L.

Competing interests

1053 None declared

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Data and code availability

The analyses in the present study were carried out using custom scripts written in Python

(version 3.9), Pygame (version 2.0), Matlab (version 2019b), R (version 4.0), and GNU

Bash (version 3.2.57). The neuroimaging and machine learning toolkits employed include

FreeSurfer (version 7.1, https://surfer.nmr.mgh.harvard.edu/), FSL (version 6.0,

https://fsl.fmrib.ox.ac.uk/fsl/fslwiki), and Torch (version 1.9, https://pytorch.org/). The

MRI dataset, behavioral data, and our manually delineated EC mask are available via the

Science Data Bank (https://www.scidb.cn/s/NBriAn). The original code for the "EC-HPC

PhaseSync" model is openly available at (https://github.com/ZHANGneuro/The-E-H-

PhaseSync-Model). Additional scripts are available upon request from the corresponding

author   (J.L.).

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1068 **Supplemental information**

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1070 **Spatially Periodic Computation in the Entorhinal-Hippocampal Circuit**

1071 **During Navigation**

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Fig. S1. The averaged number of path directions across all paths (i.e., trial). The original

path directions towards East (e.g., key 1 on the response box), West (e.g., key 2), North

(e.g., key 3), and South (e.g., key 4) were identified based on three consecutive

movement steps within each path. On average, participants moved in 3.8 directions,

suggesting a "Radial Adjustment" strategy and excluding the possibility of the

"horizontal-vertical movement" strategy, which would result in 2 path directions (black

dashed line) per path (t(32) = 15.76, p < 0.001; two-tailed; Cohen's d = 2.78). The error

bars indicate SEM.

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Fig. S2. Histograms of path directions for each participant. Path directions were binned into 36 bins of 10° each. The uniformity of the distributions was assessed using the Rayleigh test. For all participants, no significant deviations from uniformity were observed (all p > 0.05, Bonferroni-corrected across participants). Bar height indicates the number of samples per bin.

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Fig. S3. Learning effect of the object matching task. The two-day design effectively
eliminated the learning effect from the MRI experiment. On day 1, participants'
behavioral performance increased as a function of experimental sessions, resulting a
significantly negative slope (grey bar, t(32) = -2.46, p = 0.019, two-tailed; Cohen's d =
0.44). In contrast, no significant learning effect was found on day 2 (red bar, t(32) = -
0.74, p = 0.462, two-tailed; Cohen's d = 0.13). The dots indicate individual participants.
The error bars indicate SEM.

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1126 Fig. S4. Movement paths of human participants during Greeble morphing in the MRI

1127 experiment. Orange and red dots represent the starting and ending locations, respectively.

1128 The black lines indicate the movement paths. Participants' behavioral performance,

1129 calculated as the sum of path length and error size, is shown in the title, with smaller

1130 score indicating better performance.

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Fig. S5. Distribution of grid orientations in the EC. Grid orientations ranging from -30° to 30° were estimated for each voxel. The uniformity of grid orientations was assessed using both the Rayleigh test and PPC. Significantly clustering was observed in 30 out of 33 participants, indicated by * (* p < 0.05, ** p < 0.01, *** p < 0.001, Bonferroni-corrected across participants). Bar length indicates the number of voxels. Black line denotes the mean orientation.

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Fig. S6. 3-fold periodicity of the HPC examined using 20° bin. Significant clusters were

revealed in the right HPC (initial threshold: $p = 0.05$, two-tailed; clustered based SVC

correction for multiple comparisons: $p < 0.05$; Cohen's $d = 1.18$; Peak MNI coordinate:

22, -24, -14). The black lines indicate the outline of the HPC and EC. Volumetric results

are displayed in radiological orientation; numbers above the brain slices indicate MNI

coordinates.

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3-fold effect   6-fold effect

Group 1

(-30, -34, -10)   (-16, -8, -28)

Group 2

(-30, -20, -22)   (28, -12, -34)

Group 3

(-24, -20, -18)   (20, -8, -32)

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Fig. S7. 3- and 6-fold periodicity of participant groups revealed by spectral analysis. All

individual groups showed significant clusters of 3- and 6-fold periodicity in the HPC and

EC, respectively (initial threshold: p = 0.05, two-tailed. Cluster-based SVC correction for

multiple comparisons: p < 0.05). The peak MNI coordinates are shown on the bottom (3-

fold: Group 1-3, t(9) = 8.0, t(9) = 7.6, t(12) = 10.8, Cohen's d= 0.67, 0.87, 1.21; 6-fold:

Group 1-3, t(9) = 13.8, t(9) = 8.7, t(12) = 6.7; Cohen's d= 0.83, 0.63, 0.96). The black

lines indicate the outline of the HPC and EC. Volumetric results are displayed in

radiological orientation; numbers below the brain slices indicate MNI coordinates.

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Fig. S8. Whole brain representations of 6- and 3-fold periodicity revealed by spectral

analysis. Significant clusters (Red) within the DMN were identified as representing 3-

fold periodicity, whereas 6-fold periodicity revealed clusters within the Salience

Network, including the ACC and INS (initial threshold: $p = 0.05$, two-tailed. Whole brain

cluster-based correction for multiple comparisons: $p < 0.05$). The grey lines represent the

cortical parcellation based on the DKT Atlas.

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 Fig. S9. Spectral analysis of human behavior. a & b) Behavioral periodicity of path

 length and error size (deviation from the goal to ending locations). The shaded areas

 denote SE. c & d) Spectral analysis revealed significant 3-fold power for path length ($p <$

 0.05, corrected for multiple comparisons), whereas no significant periodicity was

 observed for error size ($p > 0.05$). The red dashed line indicates the permutation-based

 baseline.