Adaptive brain changes to virtual lesions interfering with visual processing

Short title: BOLD correlates of virtual lesions in the visual system

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Highlights:

- TMS-induced perturbation of the early visual areas (EVA) or the mediotemporal area (hMT+/V5) area selectively impairs motion direction discrimination.

- The TMS perturbation is associated with a local down-scaling of BOLD activity in both areas, potentially specific to task-related neuronal populations during motion discrimination.

- The two visual areas display distinct topological networks' adaptations in response to TMS, reflecting different levels of networks resilience to a focal lesion.

- TMS-fMRI coupling can be used to assess 'disconnectomics' and to precisely map how a local perturbation propagates to large-scale behavioural deficits.

Graphical abstract

Abstract:

Understanding the causal relationship between a focal lesion and network (re)organization is crucial to accurately predict the resulting large-scale symptoms of a lesion. In this study, we applied short trains of 10 Hz TMS to healthy participants over the early visual areas (EVA) or the medio-temporal area (hMT+/MT) during a motion discrimination task and at rest, while concurrent fMRI was acquired. TMS applied in the early stage of motion processing induced a specific deficit in judging motion direction in both sites, while global motion perception was preserved. This was associated with a common suppression of local brain activity and network activity. In contrast, we report distinct topological network properties depending on the disrupted site. Networks associated with EVA perturbation displayed a more robust and efficient functional reorganization, suggesting that EVA might be more resilient to focal perturbations. While contributing to a better understanding of the impact and potential mechanisms of TMS perturbation, these results provide a model for focal lesions in the visual motion processing system.

1. Introduction:

Brain networks dynamically adjust their spatiotemporal organization to changing contexts and ongoing demands (Telesford et al., 2011) (Papo et al., 2014). Such adaptive networks can be characterized by their topological transformation, their state-dependency and/or their state transition. The adaptive nature of brain networks is likely important for maintaining an optimal balance of information segregation and integration, allowing functional stability, communication via long-range connections, all while maximizing the efficiency of local processing. This process might support functional networks resilience in case of progressive neurodegeneration or focal lesions (Bullmore and Sporns, 2012) (Bassett and Bullmore, 2009) (Fornito et al., 2015). Today, a comprehensive understanding of the causal relationship between a focal lesion and brain network organization is still missing despite the fact that lesion-based brain disorders are network disorders, leading to the inability to accurately predict resulting symptoms and recovery processes.

Directly testing the systematic association between a focal lesion and brain reorganization in humans is challenging, because of the difficulties inherent in selectively altering activity *in vivo* to dissect causal impact on brain networks. An emerging approach is to combine non-invasive brain stimulation (e.g., transcranial magnetic stimulation, TMS) with neuroimaging techniques (in particular functional magnetic resonance imaging (fMRI)) (Ozdemir et al., 2020) (Vink et al., 2018) (Bergmann et al., 2021). The combination of TMS with fMRI provides a unique opportunity to temporarily "knock out" a brain region and assess the changes in local brain activity and inter-areal functional connectivity that may underlie changes in task performance (Ruff et al., 2006) (Bestmann S., 2008) (Ricci et al., 2012) (Leitão et al., 2015) (Cocchi et al., 2016) (Beckers and Hömberg, 1992). The first use of the so-called "TMS-induced virtual

lesion" concept was in early visual cortex, to impair visual targets' detection (Amassian

et al., 1989). Later, several attempts have been made to combine fMRI with TMS to

capture the impact that TMS can have on patterns of functional connectivity in

specialized, large-scale, brain systems (Ruff et al., 2008) (Jung et al., 2020). However, the

nature and functional relevance of the local brain responses to TMS induced virtual

lesions and network changes are still unclear. This lack of knowledge prevents the use of

TMS perturbation as a proper model to precisely map how a local perturbation

propagates to large scale behavioural deficits and establish it as a model for lesion-

based neurological disorders.

Whether single pulse TMS actually modulates local BOLD activity is currently

debated in the field (Rafiei and Rahnev, 2022). In the context of virtual lesions or TMS

perturbations, diverging hypotheses have been suggested. Virtual lesions are classically

associated with a temporary inactivation of a population of neurons (Ruzzoli et al., 2010)

(Perini et al., 2012) (Schwarzkopf et al., 2011) (Wahlbom et al., 2019). Prior studies using

concurrent or interleaved TMS and fMRI have described a localized decreased BOLD

signal as being the neural signature of TMS-induced virtual lesions (Sack et al., 2007)

(Ruff et al., 2008) (Harris et al., 2008) (Mullin and Steeves, 2013) (Mason et al., 2014). In

contrast, proponents of the *random noise activity* hypothesis state that TMS actually

acts by inducing random neuronal activity that is unrelated to the ongoing activity

(Pascual-Leone et al., 1999) (Silvanto and Muggleton, 2008) (Ruzzoli et al., 2010)

(Schwarzkopf et al., 2011) (Solomon-Harris et al., 2016), suggesting that TMS

preferentially recruits populations of neurons that are not involved in the on-going

cognitive process. This theory received support from behavioral and modeling studies

(Bancroft et al., 2014), but so far no neuroimaging data have reported correlates of this

TMS-induced random noise activity. Prior literature on online homeostatic regulation of

brain activity (Billman, 2020), would rather suggest that TMS preferentially acts on the

neural populations that are pre-activated by a task for instance, hereby achieving higher

functional selectivity of targeted populations. Here we hypothesized that pre-activating

a given population of neurons locally through a behavioural task would make them more

sensitive to TMS effects.

Beside local effects, substantial evidence have shown that TMS can modulate

connected remote brain areas (Bestmann et al., 2004) (Denslow et al., 2005) (Solomon-

Harris et al., 2016) (Tik et al., 2017) (Jung et al., 2020). It is also very likely that signal

propagation, interareal interactions are context dependent and shaped by the

hierarchical level of the brain area that is targeted. In an elegant modelling study, Gollo

and collaborators compared the impact of an inhibitory rTMS protocol when applied to

a brain hub region or to a peripheral region (Gollo et al., 2017). Their results revealed

that brain hubs, where activity is integrated and further distributed appear to be

functionally less affected by focal perturbations. In contrast, perturbations of peripheral

and more associative areas, might have greater impact on acute network activity. To test

it in vivo, we compared the level of network activity in different behavioural contexts

and the topological features of brain networks in response to a virtual lesion of the early

visual areas (EVA) and of the extrastriate, motion-sensitive visual area hMT+/V5. These

two regions were chosen because they allowed us to compare the whole brain

consequences of a virtual lesion affecting a primary integrative brain region, acting as a

gateway to other 'higher' visual areas, and in contrast, a more functionally specialized

brain region (Grossberg et al., 1999; Mineault et al., 2012; Rust et al., 2006; Simoncelli

and Heeger, 1998). Hierarchical models have been used to explain motion processing in

the dorsal stream of the visual cortex (Giese and Poggio, 2003; Grossberg et al., 1999;

Mineault et al., 2012; Rust et al., 2006; Simoncelli and Heeger, 1998). Most of these

models assume that V1 measures motion inaccurately while hMT+/V5 performs certain

calculations on the V1 output to obtain the correct direction and speed (Pack and Born,

2010). Hence, hMT+/V5 is thought to belong to a second order region, which conversely

to V1, only receives specialized motion signals (see also (Zhang and Tadin, 2019)). We

applied ICA and graph analyses to provide a qualitative and quantitative framework and

compared whole brain functional networks under different conditions of TMS induced

perturbation. We anticipated that the degree of distributed networks underlying TMS

effects would explain differences in robustness to EVA or to hMT+/V5 disruption (Das et

al., 2012) (Gollo et al., 2017) (Tu et al., 2021). More precisely, we hypothesized that EVA,

as a primary integrative brain region, would show a more robust network organization in

response to TMS, as measured with network topology metrics, namely higher degrees of

small-world networks with shorter characteristic path length and larger clustering

compared to hMT+/V5.

In sum, we compared the behavioural consequences, as well as the local and network

activation associated with TMS-induced perturbation applied to the EVA or to hMT+/V5

at rest and during a motion direction discrimination task with different TMS timings. We

expected TMS perturbations to selectively alter neuronal populations involved in the

task for both stimulated regions in proportion with behavioral impairments. If our

expectations are verified, we would provide neuroimaging evidence supporting the use

of active tasks to improve selectivity of TMS effects (Romero et al., 2019). Furthermore,

we anticipated that signal propagation would differ depending on the hierarchical

network level of the stimulated area, providing an *in vivo* model to study differences in

the resulting large-scale behavioral deficits of a focal brain lesion depending on lesion

site.

2. Methods

Participants

In total, thirty healthy subjects (seventeen males: mean age 28.8 years, range 19–39

years) were recruited in the experiment. All participants provided informed written

consent prior the experiment and none of them met the MRI or TMS exclusion criteria

(Rossi et al., 2021). This study was approved by the local Swiss Ethics Committee (2017-

01761) and performed in accordance with the Declaration of Helsinki.

Experimental Design and Task Procedure

Sixteen participants (nine males, mean age 26.5 years, range 19-32 years) performed

two TMS-fMRI sessions (except one drop-out for the second session). During the first

session, TMS was applied to the right EVA (TMS$_{(EVA)}$: mean(±SD) MNI coordinate: 8(5);-

76(4);9(6)) using phosphenes perception when possible (in 9/16 participants) or the O2

position based on the 10-20 EEG system; during the second session, TMS was applied to

the functionally defined right hMT+/V5 (TMS$_{(hMT+/V5)}$: mean MNI coordinates (SD): 46(4);

-83(6); 11(5)) (Figure 1A). We chose this study design to maximize our chances to

optimally target the individual hMT+/V5 area through a dedicated MT localizer acquired

during the first session (see online supplementary materials for a description of the

hMT+/V5 functional localizer). For the two online TMS-fMRI sessions, TMS was applied

during a *motion direction discrimination (MDD) Task* and at *Rest*. These sessions had the

same content except the anatomical T1-MPRAGE sequence and the hMT+/V5 functional

localizer sequence, which were only performed during the first session. A short offline

session prior the hMT+/V5 session was needed to locate the individual hMT+/V5 cluster

using a neuro-navigation system (Localite GmbH, Bonn, Germany).

An offline control experiment was performed to control for TMS non-specific effects on

additional fifteen participants (seven males, mean age 28.9 years, range 22-39 years).

We repeated the *MDD task* with TMS using the same setup (neuronavigation and eye-

tracking systems) and the same task parameters (see below) but stimulating the right

motor cortex (TMS$_{(M1)}$, mean(SD) MNI coordinates: 53(7);-4(2);54(3), corresponding to

the motor hotspots of the participants), outside the MRI scanner. Figure 1B summarizes

the study timeline.

For the three sessions, the *MDD task* consisted in rating subjective perceptual

experience of visually presented motion stimuli and in performing a forced-choice

direction discrimination task on the same moving stimuli (Koivisto et al., 2021). The

visual stimuli involved a group of static or moving dots coherently to the right or to the

left. During the familiarization phase outside the scanner, the duration of stimulus

presentation was individually defined (either 50, 67 or 84 ms, corresponding to 3, 4 or 5

frames) to ensure approximatively 70% accuracy in the *noTMS* trials. The stimulus

duration was then kept constant throughout the experiment (see Figure 1D for an

illustration of the task).

Just after the stimulus presentation, participants were asked to rate their perception

using a response box with their right hand using a 1 to 4 scale (see Figure 1's caption for

more details). In the main experimental conditions, TMS bursts were given to EVA when

visual signals first reach the target region 60 ms after the onset of the visual stimulus

(TMS$_{(EVA)}$) (Lamme, 2001) and 30 ms after stimulus onset (TMS$_{(hMT+/V5)}$) for hMT+/V5 to

account for the direct thalamic-extrastriate pathway (Lamme and Roelfsema, 2000)

(Beckers and Homberg, 1992) (d'Alfonso et al., 2002) (Koivisto et al., 2010). This ensured

similar perturbation of the feed-forward thalamic inputs to the two regions. Later TMS

onsets were also tested in half of the trials, 100ms for EVA and 130ms for hMT+/V5

selectively interfering with late processing stages. The total direction of the TMS bursts

was 200ms to cover the full window of visual processing in the two regions. TMS

intensity was set to ≈ 80% [range: 75 to 90%] maximal stimulator output (MSO) for the

HighTMS condition. Intensity was individually adjusted prior the measurement to ensure

phosphene sub-threshold stimulation and progressively increased until participants

report pain or discomfort. The intensity was then chosen to get reliable BOLD signal

while preserving participant's comfort. For the M1 control experiment, the same EVA

timings were used and TMS was given sub-threshold to avoid motor evoked potentials

elicitation.

Conditions randomly alternated between TMS versus noTMS trials, moving versus static

trials throughout the task, 50 trials each, giving a total of 300 trials. An inter-trial interval

(ITI) of approximatively 1.5 sec was used. The task was displayed in the scanner through

a 44cm x 27cm LCD monitor at a 2.5m distance via a mirror mounted on the head coil,

on a frame on top of the TMS-fMRI setup (Figure 1B). For the offline M1 control

experiment, the task was displayed on a mid-grey background LCD projector (1024 x

768, 144 Hz). To exclude bad performance due to TMS-induced blinking and to make

sure that participants were constantly looking at the fixation point, gaze and pupils'

movements were controlled in real time with an EyeLink 1000 Plus Eye Tracking System

(SR Research Ltd., Canada) in the scanner and in the behavioral room, sampling at a

frequency of 1000 Hz. Trials were aborted and redone if deviation exceeded 1° from the

fixation point. The duration of the *MDD Task-TMS* sequence was on average 16.5

minutes (SD = 4.30 minutes) depending on individual reaction times.

- A *Rest-TMS* sequence, during which an event-related design was used to map the

effect of TMS bursts composed of three pulses at alpha (10Hz) frequency. Three

conditions were pseudorandomized and counterbalanced across the run: high-intensity

TMS (*HighTMS*), low-intensity TMS *(LowTMS)* and no TMS *(noTMS),* with 25 repetitions

of each condition with an inter-trial interval (ITI) of 6 seconds (covering 3 repetition

times). *HighTMS* intensity corresponded to the intensity used during the MDD Task

while *LowTMS* was set to ≈38 % [35 to 43%] MSO. Participants were asked to look at a

fixation cross throughout the acquisition. Note that the LowTMS data are not reported

in this manuscript. The duration of the *Rest TMS* sequence was 9 minutes.

Figure 1.A: TMS targeting*. TMS targets were determined by the functional localizer of EVA*
and hMT+/V5 for precise TMS positioning (see online materials for further details about
the motion processing localizer). The two images on the right part show the T2 image of a
representative subject with the oil capsules placed on the TMS-MRI coil casing to monitor
the coil position located on the TMS coil for V1 and V5. These markers formed a "T-like
shape" indicating the center of the coil as well as the coil orientation as seen on a T2
HASTE image acquired with the two TMS-compatible MRI coil arrays (56 axial slices, slice
thickness = 0.8 mm, TR = 1500 ms, TE = 135 ms, FOV = 216 mm, flip angle = 140°). Coil
*positions were readjusted if needed. **B: MRI setup**. The MRI-TMS coil was positioned over*
the occipital area while the MR-receiving coil was positioned over the frontal lobe. Both
were maintained via a vacuum pillow to ensure the absence of movement or vibration and
*to ensure a comfortable position for the participant. **C: Study timeline**: Description of the*
*two experimental sessions; **D: One single trial of the motion discrimination task**. The*
visual stimuli involved a group of white dots in a 5˚ diameter circular aperture centered in
the middle of the screen. The dots were either static or moving coherently to the right or to
the left at a density of 2.6 dots per degree. Dots were displayed for 50, 67 or 84 ms
(corresponding to 3, 4 or 5 frames). This duration was individually adjusted prior the fMRI
measurement to ensure approximatively 70% accuracy in the noTMS trials. Just after the
stimulus presentation, participants were asked to subjectively rate their perception using
a response box on their right hand with a 1 to 4 scale, 1 being "I clearly saw the motion"
(Seeing), 2 being "I sensed the motion" (Sensing), 3 being "I saw something moving but
I'm unable to judge the direction" (No Direction) and 4 being "I didn't see any motion" (No
Motion) (Koivisto et al., 2010) (Grasso et al., 2018). When the participants pressed the
three first options, they were then asked to judge whether the dots moved to the right or
to the left with a response box on their left hand. If participants pressed 4, the task moved
to the next trial. ***E: Schematic of the BOLD sequence allowing artefact free combination of***
alpha TMS bursts.

Magnetic Resonance Imaging & Transcranial Magnetic Stimulation

MRI images were acquired at the Magnetic Resonance Imaging facility of the Human

Neuroscience Platform of the Fondation Campus Biotech Genève (FCBG, Biotech

Campus, Geneva, Switzerland), using a Siemens Prisma 3 Tesla scanner (Siemens

Healthineers, Germany).

Standard MRI sequences acquisition

Anatomical images were acquired with a 64-channel head and neck coil using a 3D

MPRAGE sequence (TR/TE = 2300/2.96 ms, flip angle 9°, 192 sagittal slices, matrix = 256,

$1x1x1 \text{ mm}^3$ resolution) covering the whole head. For retrospective distortion correction,

static field mapping was performed with a double-echo spoiled gradient echo sequence

(TR= 652 ms, TE1/TE2=4.92/7.38 ms, resolution $2.2x2.2x2.2 \text{ mm}^3$, whole head coverage),

generating two magnitude images and one image representing the phase difference

between the two echoes.

Combined TMS-fMRI sequences acquisition

For combined TMS-fMRI images, two dedicated coil arrays were used (Navarro de Lara

et al., 2017). This setup consisted of an ultra-slim 7-channel receive-only coil array,

which was placed between the subject's head and the TMS coil (MRi-B91, MagVenture,

Farum, Denmark) and connected to a MagPro XP stimulator (MagVenture, Farum,

Denmark). A second, receive-only MR coil was positioned over Cz in the EEG 10-20

system to allow a full coverage of the participant's brain.

The *Rest-TMS* and MDD *Task-TMS* sequences were acquired with a GE-EPI sequence

using the same parameters: 40 axial slices, slice thickness = 2.2 mm, in-plane resolution

= 2.2 mm, TR = 2000 ms, TE = 30 ms, FOV = 242 mm, flip angle = 67°, GRAPPA = 2,

Multiband Factor (MB) = 2. A gap was introduced between consecutive EPI volumes in

order to guaranty artefact free MR images after TMS stimulation (Navarro de Lara et al.,

2015). For both rest and task TMS sequence, a single repetition time (TR=2000 ms) was

therefore composed of 40 slices acquired during 1430 ms followed by a gap of 570 ms

before the next volume acquisition. The synchronization of TMS pulse was carried out

with an in-house script using Matlab (R2019).

Static field mapping was also performed with the TMS-MRI coils using the same double-

echo spoiled gradient echo sequence (TR = 652 ms, TE = 4.92 and 7.38 ms, slice

thickness: 2.2 mm, in-plane resolution = 2.2 mm, flip angle = 60°) that generates two

magnitude images and one image representing the phase difference between the two

echoes.

Preprocessing of fMRI images

Statistical Parametric Mapping software (SPM12, Wellcome Department of Imaging

Neuroscience, UK) was used for data pre-processing and analysis of the four datasets

(*Rest TMS* and *Task TMS* datasets, on both EVA and hMT+/V5). Spatial distortions due to

field inhomogeneities were removed from all EPI images using the Fieldmap toolbox

from SPM12 (Andersson et al., 2001). Subsequently, all time-series were motion-

corrected to the first volume using 6 degrees of freedom (3 rotations, 3 translations) and

drifts in signal time courses were corrected as well. To improve the normalization

procedure, two intermediate steps were added (see online materials for further details

about the additional sequences used for coregistration purposes). A first co-registration

was performed between the mean realigned and slice timing corrected image and the

SSFP sequence acquired with the same MR coil (and thus the same spatial coverage).

The resulting, co-registered image was once more co-registered to the SSFP sequence

acquired with the MR coil integrated into the scanner (i.e., the body coil, thus preserving

the contrast). The latter could then be easily co-registered to the high resolution T1

image acquired with the 64-channel head coil that covered the whole brain, and later

transformed into standard MNI space using a segmentation-based normalization

approach (Ashburner and Friston, 2005). Finally, the normalized images were spatially

smoothed using a Gaussian kernel (4 mm, Full-width half-maximal). The realignment

parameters estimated during spatial pre-processing for the *Rest TMS* and *Task TMS*

dataset were introduced in the design matrix as regressors of no interest in order to

prevent confounding activations related to minor head movements during scanning. The

experimental event-related designs were convolved with the canonical hemodynamic

response function, and the resulting models described in the following section were

estimated using a high-pass filter at 128 s to remove low-frequency artefacts.

fMRI Univariate Analysis

EVA and hMT+/V5 datasets were similarly analyzed using general linear models (GLM) to

calculate individual contrasts. For the *Task TMS* sequence, a design matrix with TMS

conditions (*TMS, noTMS*) and visual state (*Moving, Static*) was constructed using the

correct trials only. Note that to allow proper comparison between the TMS and noTMS

conditions, the noTMS correct trials were shuffled at the individual level. There were on

average 25(+/- 6) (correct) moving trials for each of the TMS and noTMS condition and

31(+/- 8) (correct) static trials for each of the TMS and noTMS condition. For the group

analysis, paired-t-tests were conducted to assess the effect of TMS (*TMS* versus *noTMS*),

and the visual state (Moving versus *Static)*.

For the *RestTMS* sequence, we defined a design matrix comprising three conditions

(*HighTMS, LowTMS* and *noTMS*). T-contrasts for each TMS condition were established

for all participants. For the purpose of this study, we only contrasted *HighTMS* versus

noTMS using a paired-t-test at the group level. The statistical significance threshold was

set to a height threshold of p < 0.001 uncorrected, at the voxel level and to that of p <

0.05 at the cluster level after false-discovery rate (FDR) correction. Group analyses were

conducted   using   the   GLMFlex   Fast2   toolbox

(https://habs.mgh.harvard.edu/researchers/data-tools/glm-flex-fast2/).

To explore the effects of TMS across conditions within the stimulated regions

EVA and hMT+/V5, mean beta values were extracted from regions of interest (ROIs)

defined as a 8 mm radius sphere based on the results of the group-level analysis of the

motion processing localizer described above using the MarsBaR toolbox (Brett et al.,

2002)(right EVA: 6, -83, 11 and right hMT+/V5: 58, -66, -3). For each site of stimulation

(EVA and hMT+/V5) in the *Task TMS* condition, repeated measure ANOVAs were built

with TMS and visual stimulus as within-subject factors. Planned comparisons between

TMS and noTMS were conducted if significant interactions were reported in order to

clarify the directionality of the results. For the *Rest TMS* condition, paired-t-tests were

applied between TMS and noTMS conditions.

fMRI Multivariate Analysis:

Independent Component Analysis (ICA) was used on the motion discrimination task data

to estimate independent spatiotemporal functional networks from the data and to

visualize networks specifically modulated by TMS. ICA uses fluctuations in BOLD signal to

split it into maximally independent spatial maps or components, each explaining a

unique part of variance from the 4D fMRI data. Then, all components have their specific

time course related to a coherent neural signal potentially associated with intrinsic brain

networks, artifacts, or both. The group ICA of fMRI Toolbox (GIFT version 3.0b; (Calhoun

et al., 2001)) was used. First, it concatenates the individual data followed by the

computation of subject-specific components and time course. Maximum Description

Length (MDL) and Akaike's criteria were applied to estimate the number of ICs in our

data. Using principal component analysis, individual data was reduced. Then, the

informax algorithm (Bell and Sejnowski, 1995) was applied for the group ICA and

estimated 16 components. In order to improve the IC's stability, the ICASSO was applied

and run 20 times (Himberg et al., 2004). Over the 16 extracted network components, we

focused on the TMS specific networks defined by the overlap between the activated

clusters and the coordinates of the stimulation target. Based on these independent

components, we then examined how each condition (Moving or Static) covaries with the

TMS networks using the *temporal sorting* option in the GIFT toolbox. Temporal sorting

consists in regressing the fMRI specific time course for each individual against the design

matrix for the experimental conditions. The resulting betas weights represent the

degree to which network was recruited by the conditions. For a network, positive and

negative b weights indicate the level of network recruitment in each experimental

condition. Paired-sample t-tests were used to identify networks that were significantly

modulated by TMS at rest and during motion discrimination using $p < 0.05$.

Brain Networks generation and Graph Theoretical Analysis

In addition to ICA, we used the graph theoretical network analysis toolbox GRETNA to

image connectomics and construct the functional brain networks derived from the full

TaskTMS$_{(EVA)}$ and TaskTMS$_{(hMT+/V5)}$ dataset *comprising all the conditions of interest (e.g.,*

noTMS, TMS, motion or static stimuli)." (Wang et al., 2015). The whole brain was

divided into 90 cortical and subcortical regions according to Automated Anatomical

Labeling (Tzourio-Mazoyer et al., 2002), and the mean time series for each of the 90

regions was extracted. Pearson's correlation coefficients for each pair of regions were

calculated for the mean time series of all of the 90 regions, and z-transformed using

Fisher's Z transformation. Subsequently, a positive binary undirected connection

functional network was constructed according to a range of selected threshold of the

relation matrix. As there is no defined standard for threshold selection in the

construction of a binary connection brain functional network, sparsity was used as a

range of correlation coefficient thresholds for correlation metrics. It was defined as the

existing number of edges in a graph divided by the maximum possible number of edges.

In accord with previous studies, we set both the sparsity and Pearson correlation

threshold of the functional network to range from 0.05 to 0.5 (in 0.05 steps), resulting in

a more efficient functional network than a random network with the number of artificial

edges minimized (Achard and Bullmore, 2007) (Zhao et al., 2017). Graph theoretical

analysis was applied to assess the topological and organizational properties focusing on

3 graph theoretical metrics (Rubinov and Sporns, 2010). These metrics were: the

clustering coefficient (λ), which measures how much neighbors of a node are connected

to each other and is closely related to local efficiency; characteristic path length (γ),

which is the average number of edges needed to get from any node in the network to

any other node in the network and is inversely related to global efficiency; small

worldness (δ), which reflects whether the network balances global integration and local

segregation for efficient information processing (Latora and Marchiori, 2001). To

compare graph theoretical network properties between EVA and hMT+/V5, integration

of the topological metric over all selected ranges of sparsity values was calculated using

GRETNA. Paired t-tests corrected for FDR ($p < 0.05$) were performed between the

topological measures of EVA and hMT+/V5 networks.

3. Results

We used online TMS-fMRI coupling in healthy participants in order to perturb and map

the right EVA (TMS$_{(EVA)}$) and the right hMT+/V5 (TMS$_{(hMT+/V5)}$) during a motion direction

discrimination task (MDD-Task) and at rest. An additional offline experiment targeted

the right primary motor cortex (TMS$_{(M1)}$) in another subgroup of healthy participants

(Figure 1A-D).

2.1 TMS over EVA and hMT+/V5 deteriorates motion direction discrimination, but not

motion perception

Figure 1E shows the mean and individual motion perception accuracy (+/- SEM),

reflecting how well participants could distinguish between moving and static stimuli

when a TMS burst was applied over EVA (top row), hMT+/V5 (middle row) and over the

control region M1 (bottom row). A mixed ANOVA revealed no main effect of Site ($F_{(2,30)}$ =

2.99, p = 0.07, η^2 = 0.107), TMS ($F_{(1,15)}$ = 1.43, p = 0.24, η^2 = 0.009) and no significant TMS

by Site interaction ($F_{(2,15)}$ = 0.8,   p = 0.462, η^2 = 0.023), suggesting that TMS has no

consequence on motion perception in these three regions. In contrast, the same model

on motion direction discrimination performances revealed a significant TMS effect ($F_{(1,15)}$

= 27.46, p < 0.001, η^2 = 0.251) and Site effect ($F_{(2,30)}$ = 10.3, p < 0.001, η^2 = 0.13). There

was also a TMS by Site interaction ($F_{(2,30)}$ = 13.85, p < 0.001, η^2 = 0.14), driven by an

absence of TMS effect for M1 (t(15) = -0.2, p = 1) compared to marked decays in

performance when TMS was applied to EVA (t(15) = 5.6, p < 0.001) and hMT+/V5 (t(15) =

5.4, p < 0.001) (Figure 1F). Importantly, baseline performance (noTMS conditions) was

similar across sites (F(2,30) = 0.112, p = 0.894).

We next examined the relationship between awareness and accuracy by taking into

account motion awareness ratings (Figure 1G). Without TMS, motion direction

discrimination increased (moved away from chance level) as subjective awareness of

motion increased. This indicates that without TMS, performance is tied to conscious

motion awareness. The rmANOVA with TMS and Rating as within subject factors

revealed a significant interaction only for $TMS_{(EVA)}$ ($F(3,45) = 8.21$, $p < 0.001$, $\eta^2 = 0.129$)

and $TMS_{(hMT+/V5)}$ ($F(3,45) = 3.4$, $p = 0.026$, $\eta^2 = 0.069$) compared to $TMS_{(M1)}$ ($F(3,12) =$

1.18, $p = 0.36$, $\eta^2 = 0.049$).

Figure 2: A: Individual data, box plots and smoothed density histograms of motion perception
with and without TMS *for $TMS_{(EVA)}$ (top row),$TMS_{(hMT+/V5)}$ middle row) and $TMS_{(M1)}$ (bottom*
row); B: Individual, group average and distribution of motion direction discrimination with
and without TMS *for $TMS_{(EVA)}$ (top row), $TMS_{(hMT+/V5)}$ (middle row) and $TMS_{(M1)}$ (bottom row); C:*
Relationship between behavioural accuracy and awareness of motion *with TMS (in green) or*
without TMS (in orange) for $TMS_{(EVA)}$ (top row), $TMS_{(hMT+/V5)}$ (middle row) and $TMS_{(M1)}$ (bottom
row).

Noteworthily, when comparing TMS at early versus late onsets, performances were

significant different for $TMS_{(EVA)}$ ($t_{(9)} = -3.15$, $p = 0.034$) but not for $TMS_{(hMT+/V5)}$ ($t_{(9)} = -1.6$,

$p = 1$), suggesting that interfering with recurrent feedbacks loops only impaired motion

direction discrimination in hMT+/V5. Performances for $TMS_{(M1)}$ were unchanged ($t_{(9)} = -$

0.64, $p = 1$) (Supplementary Figure S1).

2.2 Local brain effects of TMS

2.2.1 TMS induces negative BOLD responses at rest

At rest, the fMRI contrast *TMS$_{-RS}$* versus *noTMS$_{-RS}$* revealed local suppressive effects for

both EVA (Figure 2A, left panel) and hMT+/V5 stimulation (Figure 2B, left panel). Regions

of Interest (ROI) created from the functional localizer, confirmed the local deactivation

underneath the coil (*TMS$_{-RS}$* versus *noTMS$_{-RS}$* EVA: $t_{(15)}$ = 4.47, p = 0.0004, Cohen's d: -

1.12, Figure 2C, left panel, hMT+/V5: $t_{(15)}$ = 2.06, p = 0.049, Cohen's d: -0.6, Figure 2D,

left panel). Note that whole-brain analysis for TMS$_{(EVA)}$ showed additional decreased

regional activity in the ipsilateral hMT+/V5 and positive activation in the supplementary

motor area (SMA) and the frontal eye field (FEF). TMS$_{(hMT+/V5)}$ also revealed a negative

cluster in the ipsilateral EVA, and in the frontal eye field (FEF) (see Supplementary Tables

S1 and S2).

2.1.3 TMS suppresses BOLD activity during motion processing

When participants were presented with moving stimuli, both TMS sites induced a

significant local decrease in BOLD activity (Figure 3A, middle panel for EVA and Figure

3B, middle panel for hMT+/V5, and see Supplementary Tables S3 and S4). Interestingly,

the same contrast on the correct static trials did not reveal any significant TMS effect

(Figure 3A for EVA and Figure 3B for hMT+/V5, right panels).

The rmANOVA modeling the beta estimates for TMS$_{(EVA)}$ showed a main effect of TMS

($F_{(1,12)}$ = 6.32, p = 0.03, η^2 = 0.102) and a significant TMS by Visual stimulus (moving or

static) interaction ($F_{(1,12)}$ = 10.82, p = 0.006, η^2 = 0.113), while no main effect of Visual

stimulus was found ($F_{(1,12)}$ = 3.93, p = 0.07, η^2 = 0.115). Post hoc comparisons between

TMS and noTMS for the two visual conditions revealed a significant decrease in beta

estimates for moving stimuli only (moving: $t_{(12)}$ = 7.03, p < 0.001, Cohen's d = 1.88 ,

static: $t_{(12)}$ = -0-079, p = 0.94, Cohen's d = -0.02). The same rmANOVA for TMS$_{(hMT+/V5)}$

only revealed a significant TMS by Visual stimulus interaction ($F_{(1,14)}$ = 6.1, p = 0.03, η^2 =

0.08). The main effects were not significant (TMS: $F_{(1,14)}$ = 3, p = 0.11, η^2 = 0.071; Visual

stimulus: $F_{(1,14)}$ = 1.11, p = 0.31, η^2 = 0.025). Post hoc comparisons between TMS and

noTMS in the two visual conditions confirmed a significant decrease in beta weights for

the TMS condition associated with moving stimuli ($t_{(14)}$ = -3.73, p = 0.002, Cohen's d = -

0.964) , but not with static stimuli ($t_{(14)}$ = 0.058, p = 0.954, Cohen's d = 0.015).

Finally, to investigate the link between the TMS-induced impairments in motion

direction discrimination and the reduction in local activation, we performed planned

correlation analyses. We found no significant correlation in EVA (r = -0.41, p = 0.14), but

a significant positive association between the amount of task impairment and the

strength of the deactivation in hMT+/V5 (r = 0.82, p<0.001) (Figure 3E & 2F).

Figure 3: Local effects of TMS: A: *Activation maps corresponding to the TMS > noTMS contrast at*
rest (right panel), simultaneously to moving visual stimuli (middle panel), simultaneously to static
visual stimuli (right panel) for TMS(EVA); **B**: *Activation maps corresponding to the TMS > noTMS*
contrast at rest (right panel), simultaneously to moving visual stimuli (middle panel),
simultaneously to static visual stimuli (right panel) for TMS(hMT+/V5); **C**: *ROI analysis associated with*

the TMS$_{(EVA)}$ > noTMS$_{(EVA)}$ contrast at rest, while presenting moving stimuli and static visual
*stimuli; **D**: ROI analysis associated with the TMS$_{(hMT+/V5)}$ > noTMS$_{(hMT+/V5)}$ contrast at rest, while*
*presenting moving stimuli, while presenting static visual stimuli; **E**: Relationship between impaired*
motion direction discrimination and deactivation in EVA for TMS$_{(EVA)}$; TMS$_{(hMT+/V5)-Mov}$ >
*TMS$_{(hMT+/V5)-Stat}$ ROI analysis; **F**: Relationship between impaired motion direction discrimination*
and deactivation in hMT+/V5 for TMS$_{(hMT+/V5)-Mov}$. Please note the strong correlation between
TMS$_{(hMT+/V5)}$ related changes in behavior and TMS$_{(hMT+/V5)}$ -related changes in BOLD activity (r =
0.82, p<0.001).

3.2 Multivariate and graph theory-based network analysis

We further investigated whether and how long-range brain activity was modulated by

TMS over *EVA* or *hMT+/V5* during motion direction discrimination. We first applied an

independent component analysis to extract hidden spatiotemporal components

contained within the TMS$_{(EVA)}$ and TMS$_{(hMT+/V5)}$ task data. Second, we applied a graph

theoretical analysis to assess the topological and organizational properties of these

networks.

3.2.1 TMS$_{(EVA)}$ networks

The ICA applied to the TMS$_{(EVA)}$ data at rest revealed 16 components, among

which 13 were considered as functional brain networks and three components

considered as noise. Three networks (IC1, IC3 and IC14) were labelled as TMS-related

networks because they overlapped with the stimulation site and were significantly

modulated by TMS (Figure 4A, Supplementary Figure S2 for all the other functional brain

networks and Supplementary Table S5 for the MNI coordinates). Interestingly, those

three networks only encompassed the stimulated EVA area. The temporal regression

analysis applied to the components' time courses showed that they were significantly

down regulated by TMS$_{(EVA)}$ only when considering moving stimuli (IC1: t$_{(15)}$ =4.9, p$_{cor}$ =

0.006, Cohen's d: 1.02, IC3: t$_{(15)}$ = 2.41, p$_{cor}$ = 0.039, Cohen's d: 0.6, IC14: t$_{(15)}$ = 2.25, p$_{cor}$

= 0.051, Cohen's d: 0.56, Figure 3A). In contrast, IC14 was over-expressed when

associated with static stimuli (IC14: $t_{(15)}$=3.6, p_{cor} = 0.005, Cohen's d: 0.45). The other two

IC were not significantly modulated by TMS during static stimuli (IC1: $t_{(15)}$ = 0.89, p_{cor} = 1,

Cohen's d: 0.09, IC3: $t_{(15)}$ = 1.3, p_{cor} = 0.21, Cohen's d: 0.32).

3.2.2 TMS$_{(hMT+/V5)}$ networks

Among the 14 (out of 16) components representing functional brain networks for

TMS$_{(hMT+/V5)}$ (see Supplementary Figure S3 and Supplementary Table S6), three

corresponded to TMS networks (IC5, IC7, IC13, Figure 4B). Compared to TMS$_{(EVA)}$, these

networks were more diffused, comprising the stimulated right hMT+/V5 area, the

bilateral or contralateral left FEF (IC5 and IC7), the medial prefrontal cortex and pre-

supplementary motor area (preSMA) (IC5) and the posterior parietal cortex (PPC) (IC13).

The temporal regression analysis applied to the components' time courses showed that

IC5 and IC13 were suppressed by TMS when associated with moving stimuli (IC5: $t_{(14)}$ =

2.5 p_{cor} = 0.07, Cohen's d: 0.63, IC7: $t_{(14)}$ = 0.35 p_{cor} = 0.73, Cohen's d: 0.7, IC13:$t_{(14)}$ = 2.6

p_{cor} = 0.048, Cohen's d: 0.62, Figure 4B) and IC7 showed a trend toward an up-regulated

with static stimuli (IC7: $t_{(14)}$ = 2.2 p_{cor} = 0.07, Cohen's d: 0.57, IC5: $t_{(14)}$ = 1.3 p_{cor} = 0.315,

Cohen's d: 0.33, IC13: $t_{(14)}$ = 0.47 p_{cor} = 0.774, Cohen's d: 0.12).

3.2.3 Graph-based network analysis

We applied a graph theory approach to compare the topological organization of the

functional connectivity networks, when EVA or hMT+/V5 was perturbed during motion

discrimination. We first investigated small-world topological properties especially

because networks with high small-world properties are believed to play a role in

protecting the brain from local perturbation or damage. Both EVA and hMT+/V5

networks exhibited small-world properties ($\lambda \approx 1$ and $\sigma > 1$) among the selected

sparsity values (see Methods section). Interestingly, there was a significant difference in

the small-world network parameters (σ) between EVA networks and hMT+/V5 networks

with higher σ for EVA networks at the sparsity values 0.3, 0.4, 0.45 and marginally at

0.35 (see supplementary Table S7 for all paired t-tests), also considering the mean

across all spasticity values ($t_{(14)}$ = 2.9, p = 0.034, Cohen's d: -0.67) (Figure 4C). There was

no significant difference in normalized clustering coefficient (λ) between the two

networks ($t_{(14)}$ = 0.42, p = 0.68, Cohen's d: 0.12). Finally, characteristic path length (γ)

showed a significant increase at sparsity thresholds of 0.2, 0.25 and marginally at 0.15

(Figure 4D and see Supplementary Table S8 for all paired t-tests). The difference

between EVA and hMT+/V5 networks was also significant across all sparsities ($t_{(14)}$ = 2.9,

p = 0.012, Cohen's d: 0.75) (Figure 4E and see supplementary Table S9 for all paired t-

tests).

Figure 4A: *TMS$_{(EVA)}$-specific component networks that are modulated by TMS during motion*
discrimination and temporal regression analysis for the noTMS and TMS$_{(EVA)}$ conditions associated
with moving or static stimuli; **B**: *TMS$_{(hMT+/V5)}$-specific component networks that are modulated by*
TMS during motion discrimination and temporal regression analysis for the noTMS and TMS$_{(EVA)}$
conditions associated with moving or static stimuli; **C**: *Small-worldness properties for TMS$_{(EVA)}$ and*
TMS$_{(hMT+/V5)}$ along the sparsity threshold of 0.05-0.50 (top row) and mean values (bottom row); **D**:
Clustering coefficient for TMS$_{(EVA)}$ and TMS$_{(hMT+/V5)}$ along the sparsity threshold of 0.05-0.50 (top
row) and mean values (bottom row); **E**: *Characteristic Path Length properties for TMS$_{(EVA)}$ and*
TMS$_{(hMT+/V5)}$ along the sparsity threshold of 0.05-0.50 (top row) and mean values (bottom row); *
p(FDR) < 0.05.

4. Discussion

This study used short bursts of 10Hz TMS to disrupt either a low-level visual area (EVA) or a highly specialized, motion sensitive, visual area (hMT+/V5) during concurrent fMRI. We first confirmed targets causal engagement with significant TMS task impairments that were specific to motion direction discrimination. We also describe a local context-dependent BOLD deactivation common to both areas, but only predictive of task impairment when TMS was applied to hMT+/V5. Finally, our results revealed distinct topological networks' adaptations in response to TMS perturbation of the EVA or hMT+/V5, possibly reflecting different levels of networks resilience to the focal lesion.

In line with the concept of "virtual lesion" described in the literature (Pascual-Leone et al., 1999), the TMS bursts applied to either EVA and hMT+/V5, resulted in a selective and transient deterioration of performance of a left/right motion direction discrimination task. This was interpreted to reflect successful causal and selective disruption of brain functioning. Interestingly, participants remained able to dissociate moving from static stimuli. This dissociation is likely supported by the existence of independent substrates supporting unspecific motion processing versus global motion direction integration in EVA and hMT+/V5 (Simoncelli and Heeger, 1998). There is evidence showing that a sub-population of neurons in hMT+/V5 focuses on the processing of local motion signals similar to that in EVA, and some other neuronal populations rather process global motion (Born and Tootell, 1992). Our TMS disruption might have specifically impacted on the neurons in charge of the decoding of motion directions. Furthermore, other areas of the motion processing network, not directly impaired by the focal perturbation, such as the medial superior temporal area (MST) (Sclar et al., 1990) might be involved in unspecific motion processing, explaining the lack of impairment. Considering now the relationship between motion awareness and

motion direction discrimination, we found that the direction of the moving trials that

were judged as "moving", were not correctly guessed when both areas were stimulated.

In contrast, "unaware" trials were unchanged. We can speculate that this residual,

unconscious ability of detecting changes in the dots' positions might be at least partially

supported by the activation of the fast, direct geniculo-extra-striate pathway (Abed

Rabbo et al., 2015) (Bridge et al., 2008) (Ajina et al., 2015).

Locally, motion direction discrimination was associated with an increase in EVA

and hMT+/V5 BOLD activity, probably representing the populations of neurons tuned to

the presented direction of motion since only the correct trials were considered. In

contrast, the selective behavioral impairment induced by TMS was associated with a

local loss of BOLD signal strength only when participants were judging motion direction.

This *signal suppression* effect fits with the traditional use of temporary virtual lesions in

a healthy brain, where TMS would inhibit the activity of active neuronal populations,

specifically in this study, the neurons coding for on-axis directions. Consequently, the

signal-to-noise ratio for properly integrating the encoding properties of the remaining

active motion sensitive neurons got significantly worsened, explaining the deterioration

of performance. This is further supported by the significant correlation between the

level of impairment and the amount of hMT+/V5 BOLD suppression. Finally, this finding

is perfectly in line with extracellular recordings in monkeys showing strong associations

between neuronal responses and accuracy depending on the difference between the

stimulus motion and the preferred direction of a neuron (Purushothaman and Bradley,

2005) (Cohen and Newsome, 2009). Therefore, we conclude that our findings provide

neuroimaging evidence that active rescaling of local BOLD activation makes TMS more

likely to specifically suppress the active neurons.

This BOLD suppression occurred locally on the targeted region, but also

remotely via functional coupling at the network level. TMS networks were specifically

down-regulated when participants were presented with moving stimuli for both TMS(EVA)

and TMS(hMT+/V5). Conversely to local activation, the static condition led to an up-

regulation of some TMS networks, confirming that multivariate network analyses might

be more sensitive to contextual changes than classical univariate analyses (Hebart and

Baker, 2018) (Brauchli et al., 2019) and might be associated with attentive

compensatory mechanisms (Parks and Madden, 2013).

Another observation arising from the ICA analysis was that TMS networks'

configurations were significantly different whether TMS was applied to EVA or hMT+/V5.

We found that the TMS(hMT+/V5) networks were spatially more distributed, including

additional associative areas, such as the frontal eye field (FEF), the posterior parietal

cortex (PPC) or the medial prefrontal cortex (mPFC). In comparison, the independent

components forming the TMS(EVA) networks were restricted to the stimulated EVA. To

quantify these observations, we used graph-based theory analyses and found that

whole-brain functional networks were different whether EVA or hMT+/V5 was

perturbed. Specifically, EVA networks showed higher small-worldness values,

characterized by local clustering of elements and short path lengths, compared to

TMS(hMT+/V5) networks. The TMS(EVA) networks configuration appears to support efficient

parallel information processing, which typically maximizes information transfer

efficiency at a relatively low wiring cost (Achard and Bullmore, 2007). Then, it is possible

that the clustered TMS(EVA) networks enable flexible redistribution of network activity, to

maintain an orchestrated network stability despite various internal and external

perturbations (Wu et al., 2019). In contrast, the existence of the scattered functional

TMS(hMT+/V5) networks adaptation might reflect propagation of task-specific suppression

that is distributed over higher visual brain regions (FEF, PPC or mPFC). These suppressed,

broader effects might prevent compensation or re-balancing of network activity in

response to a lesion or a focal perturbation.

Although this difference in network adaptation between $TMS_{(EVA)}$ and

$TMS_{(hMT+/V5)}$ did not translate into a behavioural difference using these TMS and task

parameters, our results are in congruence with a modelling study, showing that brain

hubs, where activity is integrated and further distributed (like EVA in our case) operate

in a slower regime and appear to be functionally less affected by focal perturbations

(Gollo et al., 2017). In contrast, perturbations of peripheral or more associative areas

(e.g., hMT+/V5), might have greater impact on acute network activity. Lesion studies

also provided evidence that damage to the homologue of hMT+/V5 in behaving cats

impairs more relearning of motion discrimination and learning transfer than lesions to

EVA (Das et al., 2012). Our control experiment using later TMS onsets also shows

detrimental behavioural effects only for hMT+/V5 stimulation. To sum up, the network

analyses revealed differences between the two disrupted areas, not observable with

classical activation analyses. Perturbating a highly specialized region such as hMT+/V5 in

this case, led to more widespread effect, leading to the conclusion that this region is

more vulnerable to focal perturbation.

In conclusion, despite growing interest and extensive computational modelling

contributions, the causal mechanisms underlying neural network dynamics after a

lesion, remain elusive. In the present study, we used concurrent TMS-fMRI coupling as a

tool to probe neural mechanisms underlying functional reorganization of whole-brain

dynamics using a "virtual-lesion" approach. First, we provide neuroimaging evidence for

task selectivity of TMS effects, which is more prompt to act on active neurons

specifically. We also demonstrate that selective, focal virtual lesions can result in distinct

dis-regulations in visual network activity, depending on which hierarchical level is

perturbed. Complementarily to lesion studies (Das et al., 2012), these findings motivate

the use of TMS-fMRI coupling as an additional tool to assess 'disconnectomics' and their

network and behavioural effects after brain lesions (Egger et al., 2021). This technique

could be leveraged to precisely map how a local perturbation propagates to large-scale

behavioural deficits by comparing the neural impact of TMS-induced virtual lesion

during different active cognitive processes.

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Supplementary online Materials

1. **Motion processing localizer**: A standard h*MT+/V5* localizer task was acquired during

the first fMRI session and used to accurately and individually target the h*MT+/V5* area.

The screen displayed radially moving dots alternating with stationary dots (see e.g., [81]). A

block design alternated six 15 s blocks of radial motion with six blocks featuring

stationary white dots in a circular region on a black background. This region subtended

25° visual angle, with 0.5 dots per square degree. Each dot was 0.36° diameter. In the

motion condition the dots repeatedly moved radially inward for 2.5 s and outward for

2.5 s, with 100% coherence, at 20°/s measured at 15° from the center. Participants were

passively looking at the screen and were asked to focus on a fixation point located in the

middle of the screen. The motion processing localizer was acquired using a GE-EPI

sequence with 56 axial slices, slice thickness = 2.2 mm, in-plane resolution = 2.2 mm, TR

= 2000 ms, TE = 30 ms, FOV = 242 mm, flip angle = 60°, GRAPPA = 2, Multiband Factor

(MB) = 2.

2. Additional MRI sequences for coregistration of TMS-fMRI data

Functional and structural MR data, respectively acquired with the TMS-MRI coils and the

64-channel head coil, were found difficult to co-register due to different coil coverage,

sensitivity and contrast. Therefore, two additional rapid high signal-to-noise, balanced,

steady-state free precession (SSFP) sequences [82] (96 axial slices, slice thickness = 2 mm,

(gap 0.4 mm), in-plane resolution = 2 mm, TR = 5.24 ms, FOV = 256 mm, flip angle = 28°)

were acquired with both the TMS-MRI coils and the body coil integrated into the

scanner bore in order to resolve based on the same SSFP contrast the coil coverage

mismatch within the registration processing pipeline.

Figure S1: *Individual, group average and distribution of motion*
direction discrimination without TMS, with TMS and TMS-late for
TMS(EVA) (top left), TMS(hMT+/V5) (top right) and TMS(M1) (bottom row).

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1004   ***Figure S2***: *Independent component analysis (ICA) results of TMS$_{(EVA)}$ at rest. Spatial*
1005   *distribution of 13 networks, grouped into functional groups. See Supplementary*
1006   *Table S5 for the Montreal Neurological Institute (MNI) coordinates;*

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Figure S3: Independent component analysis (ICA) results of the motion discrimination task with TMS(EVA). Spatial distribution of 13 networks, grouped into functional groups. See Supplementary Table S6 for the Montreal Neurological Institute (MNI) coordinates;

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1016 **Supplementary Table S1** (GLM analysis Rest EVA)

Brain region	Cluster extent	Z score	Peak MNI coordinate		
			x	y	z
noTMS>TMS					
EVA (right hem.)	516	4.43	6	-80	15
hMT+/V5 (right hem.)	419	3.31	51	-52	10
TMS>noTMS					
SMA	219	4.48	1	2	61
FEF	384	3.91	23	8	61

1017 *Bilat.: bilateral; hem.: hemisphere; FEF: Frontal Eye Field; EVA: early visual areas; hMT+/V5:*
1018 *motion-sensitive medio-temporal visual area; SMA: supplementary motor area.*

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1021 **Supplementary Table S2** (GLM analysis Rest hMT+/V5)

Brain region	Cluster extent	Z score	Peak MNI coordinate		
			x	y	z
noTMS>TMS					
hMT+/V5 (right hem.)	609	4.62	39	-70	-5
EVA (right hem.)	213	3.47	6	-64	-7
FEF (right hem.)	205	4.05	12	2	50

1022 *Hem.: hemisphere; FEF: Frontal Eye Field; EVA: early visual areas; hMT+/V5: motion-sensitive*
1023 *medio-temporal visual area.*

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1026 **Supplementary Table S3** (GLM analysis Task EVA on correct moving trials)

Brain region	Cluster extent	Z score	Peak MNI coordinate		
			x	y	z
TMS>noTMS					
EVA (bilat.)	502	3.34	-2	-88	20
SMA (bilat.)	1843	3.21	2	-11	60

1027 *Bilat.: bilateral; EVA: primary visual areas; SMA: supplementary motor area;*

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1029 **Supplementary Table S4** (GLM analysis Task hMT+/V5 on correct moving trials)

Brain region	Cluster extent	Z score	Peak MNI coordinate		
			x	y	z
noTMS>TMS					
hMT+/V5 (Right hem.)	462	4.73	37	-61	-5
EVA	351		8	-66	-2

1030 *Hem.: hemisphere; EVA: early visual areas; hMT+/V5: motion sensitive medio-temporal visual*
1031 *area.*

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1034 **Supplementary Table S5** (MNI coordinates of the 13 IC networks Task EVA)

Component	Cluster region	Cluster extent	Peak MNI coordinate		
			x	y	z
TMS-specific Networks					
IC1*	EVA (Bilat.)	1843	21	-93	-6
IC3*	EVA (Bilat.)	1557	-5	-85	2
IC14*	EVA (Bilat.)	1243	-1	-81	8
Visual Networks					
IC4	EVA (Right hem.)	763	28	-89	5
IC6	EVA (Left hem.)	587	-14	-93	18
IC7	EVA (Right hem.)	634	30	-93	-5
IC9	EVA (Bilat.)	1476	3	-97	9
IC11	EVA (Left hem.)	423	-24	-86	18
IC12	EVA (Bilat.)	764	5	-88	-8
IC13	EVA (Bilat.)	984	-7	-92	16
IC15	EVA (Right hem.)	478	27	-89	17
Frontal Network					
IC2	FEF (Right hem.)	642	28	-2	52
	FEF (Left hem.)	897	-31	-1	51
	SMA (Bilat.)	598	8	-5	66
Default Mode Networks					
IC5	Pre Frontal	2534	6	43	45
	Pre Cuneus	1243	2	-66	43

1035 *Bilat.: bilateral; hem.: hemisphere; FEF: Frontal Eye Field; EVA: early visual areas; SMA:*
1036 *supplementary motor area;* Networks significantly modulated by TMS*

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 Supplementary Table S6 (MNI coordinates of the 14 IC networks Task hMT+/V5)

Component	Cluster region	Cluster extent	Peak MNI coordinate		
			x	y	z
TMS specific Networks					
IC5*	hMT+/V5 (Right hem.)	1343	58	-48	1
	FEF (Right hem.)	187	54	-18	45
	FEF (Left hem.)	218	-32	-24	58
	PreSMA (bilat.)	138	4	15	61
IC7*	hMT+/V5 (Right hem.)	348	43	-73	16
	PPC (bilat.)	3577	26	-59	56
	PreFrontal (Left hem.)	298	9	-21	57
	PPC (bilat.)	2232	30	-69	60
IC13*	V5 (Right hem.)	1687	9	3	45
	PPC (Right hem.)	587	39	-21	20
Visual Network					
IC3	EVA (Right hem.)	4420	-3	-78	2
	PPC (Right hem.)	221	34	-45	61
IC6	hMT+/V5 (Right hem.)	122	51	-48	5
	PreCuneus (bilat.)	283	-3	-19	12
	FEF (Right hem.)	934	27	12	653
	FEF (Left hem.)	189	-31	17	65
IC8	hMT+/V5 (Right hem.)	132	56	-58	4
Sensorimotor Network					
IC14	SM1 (bilat.)	4286	25	-20	63
Frontal Network					
IC16	Frontal lobe (bilat.)	3984	-4	29	55
Default Mode Networks					
IC10	FEF (Right hem.)	234	38	20	59
	PPC (Right hem.)	1384	40	-50	59
	PPC (Left hem.)	984	45	-46	54
	mPFC (bilat.)	346	3	51	42
IC11	PPC (Right hem.)	1583	40	-50	59
	PFC (Left hem.)	219	46	28	44
IC15	PPC (Right hem.)	1032	50	-59	44
	PPC (Left hem.)	783	-43	-53	44
	PCC	2984	1	-54	42
	PFC	2439	2	36	46

Auditory Networks

IC1	STG	274	57	-52	6
IC2	TPJ	355	54	-57	21
IC4	STG	254	60	-43	7

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1040 *Bilat.: bilateral; hem.: hemisphere; hMT+/V5: motion-sensitive medio-temporal visual area; FEF:*
1041 *Frontal Eye Field; EVA: early visual areas; mPFC: medial prefrontal cortex; PCC: posterior cingulate*
1042 *cortex; ACC: anterior cingulate cortex; SMA: supplementary motor area; LGN: lateral geniculate*
1043 *nucleus; S1: preimary somatosensory cortex.*

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1046 **Supplementary Table S7** (paired t-tests for Sigma compared between TMS$_{(EVA)}$ and
1047 TMS$_{(hMT+/V5)}$ networks)

Sparcity thresholds	t	df	p
0.05	0.084	14	0.23
0.1	0.121	14	0.24
0.15	0.31	14	0.45
0.2	0.52	14	0.26
0.25	0.84	14	0.16
0.3*	2.01	14	0.03
0.35	1.89	14	0.06
0.4*	2.01	14	0.03
0.45*	2.02	14	0.04
0.5	1.45	14	0.17

1048 *: Significant difference in smallworldness (Sigma) between EVA and hMT+/V5 networks.

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1052 **Supplementary Table S8** (paired t-tests for Lambda compared between $TMS_{(EVA)}$ and
1053 $TMS_{(hMT+/V5)}$ networks)

Sparcity thresholds	t	df	p
0.05	0.237	14	0.82
0.1	0.175	14	0.86
0.15	0.128	14	0.9
0.2	0.26	14	0.8
0.25	0.5	14	0.62
0.3	0.713	14	0.5
0.35	0.845	14	0.42
0.4	0.946	14	0.36
0.45	1.089	14	0.2
0.5	1.089	14	0.28

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1055 **Supplementary Table S9** (paired t-tests for Gamma compared between TMS$_{(EVA)}$ and
1056 TMS$_{(hMT+/V5)}$ networks)

Sparcity thresholds	t	df	p
0.05	0.452	14	0.66
0.1	-0.72	14	0.49
0.15(*)	-1.9	14	0.08
0.2*	-2.03	14	0.05
0.25*	-2.16	14	0.04
0.3	-1.45	14	0.17
0.35	-1.2	14	0.25
0.4	-0.75	14	0.47
0.45	-0.8	14	0.43
0.5	-0.77	14	0.46

1057 *: Significant difference in Path Length (Gamma) between EVA and hMT+/V5 networks.

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