G-matrix stability in clinally diverging populations of an annual weed.

Abstract

How phenotypic and genetic divergence among populations is influenced by the genetic

architecture of those traits, and how microevolutionary changes in turn affect the within-

population patterns of genetic variation, are of major interest to evolutionary biology. Work on

Ipomoea hederacea, an annual vine, has found genetic clines in the means of a suite of

ecologically important traits, including flowering time, growth rate, seed mass, and corolla

width. Here we investigate the genetic (co)variances of these clinally varying traits in two

northern range-edge and two central populations of *Ipomoea hederacea* to evaluate the influence

of the genetic architecture on divergence across the range. We find 1) limited evidence for clear

differentiation between Northern and Southern populations in the structure of **G**, suggesting

overall stability of **G** across the range despite mean trait divergence and 2) that the axes of

greatest variation (g_{max}) were unaligned with the axis of greatest multivariate divergence.

Together these results indicate the role of the quantitative genetic architecture in constraining

evolutionary response and divergence among populations across the geographic range.

Keywords: G-matrix, multivariate evolution, clinal divergence, *Ipomoea hederacea*, constraint
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Introduction

A major goal in evolutionary biology is to understand the relationship between genetic variation within populations and phenotypic divergence between populations (Antonovics 1976, Endler 1977, Walsh & Blows 2009). Range-edge populations provide an interesting setting in which to investigate this relationship. Populations existing on the margin of species' ranges are expected to have smaller population sizes (Brown et al. 1995), which are more susceptible to drift, and limited gene flow compared to more central populations (Sexton et al. 2009). Environmental gradients will often additionally create different selective pressures across the geographic range, favouring phenotypic and genetic divergence among populations (Endler 1977, Slatkin 1978, Barton 2001). Here we examine the divergence and evolutionary potential of four populations of an annual plant, *Ipomoea hederacea*, sampled from the center and northern edge of its range with respect to five clinally varying traits.

The evolutionary response to selection is dependent not only on local selection, but on the underlying genetic architecture of the traits undergoing selection. The ability to adapt to the local environment depends on both standing genetic variation and covariation, represented as a genetic covariance matrix, **G** (Antonovics 1976, Lande 1979, Lande & Arnold 1983, Falconer & Mackay 1996, Agrawal & Stinchcombe 2009). **G** shapes evolutionary responses to selection, as the relationships among traits lead to correlated responses (Lande 1979, Lande & Arnold 1983). Divergence among populations in response to local selection may thus be constrained or facilitated by trait (co)variances. The multivariate trait combination with the greatest amount of genetic variation, dubbed the "genetic line of least resistance" by Schluter (1996) has been shown to influence macroevolutionary responses by deflecting the response to selection toward trait combinations with the most genetic variation (Schluter 1996).

Exactly how G-matrices will change with divergence in trait means across latitudinal

ranges is not clear, although there are numerous reasons to predict that they will. For example,

while some work suggests that G-matrices are expected to exhibit stability over various

evolutionary timescales (Lande 1979, Schluter 1996, Arnold et al. 2008), this assumes genes

underlying traits are from an infinite-sites model with a gaussian distribution (Lande 1979). **G**

may be unstable through time if the distribution of the alleles underlying traits is skewed (Barton

& Turelli 1987, Turelli 1988). Additionally, **G** among populations may differ if a population is

small and subject to substantial genetic drift or inbreeding (Lande 1979, Phillips et al. 2001,

Jones et al. 2004, Doroszuk et al. 2008), has experienced recent population bottlenecks (Shaw et

al. 1995, Roff 2000), or is under strong selection due to novel conditions (Turelli 1988, Roff

2000, Conner et al. 2011, Uesugi et al. 2017), which are all features often associated with range-

edge populations. Recent theory by Chantepie and Chevin (2020) suggests that in finite

populations subject to drift, genetic correlations will more closely reflect mutational

(co)variances as effective population sizes become smaller. Chantepie and Chevin (2020) note

that colonizing populations (which may be similar to range-edge populations) often experience

reduced Ne and strong selection, and thus **G** will be more reflective of mutational covariances,

and stronger genetic constraints. Taken together, we might predict less overall genetic variance

(Johnson & Barton 1995), or different patterns of genetic covariance, which may in turn lead to

evolutionary constraint in range-edge populations.

There are, however, some scenarios in which **G** might be predicted to be similar among

populations. If range-edge populations frequently experience swamping gene flow from the

center of the range (Kirkpatrick & Barton 1997; Garcia-Ramos & Kirkpatrick 1997), their **G**

might show few differences compared to core populations, with populations diverging along the

homogenized axis of maximal (co)variation (Guillaume & Whitlock 2007). Some theory also

suggests that dispersal into peripheral populations can enhance genetic variance (counteracting

the effects of drift), facilitating adaptation to range-edge conditions (Polechova 2015, Polechova

2018).

Empirical assessment of divergence among population G-matrices in natural populations

has led to mixed results. Some studies find that **G** is fairly stable (Roff & Mousseau 1999,

Puentes et al. 2016, Delahaie et al. 2017, McGoey & Stinchcombe 2021) with most divergence

among populations occurring along g_{max} (Silva e Costa et al. 2020, Royaute et al. 2020). In

Australian populations of *Drosophila melanogaster* sampled along a broad environmental

gradient, Hangartner et al. (2019) estimated G-matrices for size, desiccation, and thermal traits.

They found no differentiation among population G-matrices, demonstrating the robustness of **G,**

despite diverging local selection. In contrast, Hine et al. (2009) evaluated the divergence in the

G-matrices for cuticular hydrocarbons of nine *Drosophila serrata* populations along the same

gradient, and found significant divergence among **G**s. Wood and Brodie (2015) showed that

environmental effects on **G** (e.g., due to novel habitats) were often as large, or larger, than

population differentiation, suggesting that environmental sensitivity in the expression of **G** can

have effects as large as the accumulated effects of drift, selection, and mutation between

diverging populations. Similarly, some studies have found remarkable shifts in **G** through time

and/or across environments (Cano et al. 2004, Doroszuk et al. 2008, Bjorklund et al. 2013).

Collectively, this diverse body of theory and empiricism suggests numerous reasons why

G from range-edge and populations from the interior of a species range should differ. Under a

wide range of biologically plausible assumptions about genetic architecture, inbreeding, drift,

effective population size, bottlenecks, dispersal, and strong selection—all of which are expected

to be relevant to range-edge populations and those adapting to a gradient—lead to the prediction

of differences in G. However, alternative theoretical assumptions about genetic architecture or

divergence could lead to predictions of no or little change in **G**. Past empirical work likewise

offers contrasting guidance: **G** might show minimal or alternatively strong changes due to

temporal or environmental effects. Consequently, whether range-edge populations that have

diverged along a gradient show altered **G** – and thus potentially altered evolutionary potential

and constraint – remains an unanswered empirical question.

Ipomoea hederacea, an annual plant which grows across the eastern U.S.A. from

Pennsylvania to Florida, has latitudinal genetic clines in a variety of quantitative traits

(Klingaman and Oliver 1996, Stock et al. 2014) and leaf shape (Bright-Emlen 1998, Campitelli

& Stinchcombe 2013), a Mendelian trait. These clines do not appear to be due to drift, but rather

a response to selection, as no latitudinal patterns in neutral loci have been found (Campitelli &

Stinchcombe 2013; Campitelli & Stinchcombe 2014). Previous work by Stock and colleagues

(2014) focused on among-population patterns found evidence of significant clinal divergence.

Briefly, Stock et al. (2014) grew individuals in a common greenhouse environment from 20

populations, spanning the gradient sampled by Campitelli and Stinchcombe (2013) . They used

selfed seeds from 10 maternal lines sampled per population and up to 8 individuals per matriline.

They performed redundancy analysis using the matriline means of five focal traits (seed mass,

early growth rate, flowering time, corolla width, and anther-stigma distance) regressed on

latitude of origin. Flowering time, anther-stigma distance, and corolla width exhibited significant

latitudinal clines, while seed mass and growth rate had marginally significant divergence. Stock

et al. (2014) estimated the axis of greatest multivariate divergence, the mean trait combination

that is most different between populations of *I. hederacea* across latitudes, which we use here

alongside more deeply sampled populations to compare within-population trait organization to

among-population trait divergence.

Our research aims were: 1) to determine whether Northern and Southern populations

differed in the overall heritability and genetic variance of the focal traits, 2) evaluate how genetic

variation within populations was aligned relative to the axis of multivariate genetic divergence,

and 3) assess population level divergence of the G-matrices. To do so, we estimated trait

heritability and genetic variance-covariance matrices of four populations of *Ipomoea hederacea*;

collected from the northern range-edge and the core of the range. We expected the axis of trait

divergence between populations to be biased toward the axis of greatest variation within

populations, the genetic line of least resistance (Schluter 1996).

Methods

Propagation and trait measurements

We harvested seed from populations from the edge of agricultural fields in Pennsylvania

(40.116611°N, 76.398889°W), Maryland (39.581861°N, 77.816861°W), Hoffman, North

Carolina (35.074139°N, 79.556694°W) and Ellerbe, North Carolina (35.091722°N,

79.742722°W). We sampled seed pods haphazardly from vines 1-2 m from one another to

minimize repeat sampling of maternal plants, which served as the founders of the matrilines we

used in our experiment. We grew one seed from 50 randomly chosen matrilines per population in

a common greenhouse environment and allowed these individuals to self-fertilize. One death

prior to seed set resulted in 49 matrilines from Ellerbe, NC. We harvested selfed seeds from each

maternal plant and grew ~11 focal individuals (range: 2-11, mean = 10.7) from each line,

resulting in a total sample of 2,133 plants. While our use of selfed progeny precludes estimating

additive genetic variance, selection acts on the broad-sense variation rather than just the additive

components of variation in mainly selfing species (Roughgarden 1979), making this design

appropriate for *I. hederacea*.

We grew plants in cone-tainers (Stuewe & Sons, Oregon, USA) filled with Pro-Mix soil

in a glasshouse from April-October 2018. All plants received a dilute fertilizer solution (N-P-K:

10-52-10) every 2 weeks. Day length was initially 16 hours at 28°C, reduced to 12 hours at 25°C

on day 32, and 8 hours at 22°C on day 38 to promote flowering.

Trait measurements followed Stock et al. (2014). Prior to planting, we weighed each seed

and recorded individual mass. We counted leaves at 17 days after planting and again on the 26th

or 27th day after planting; we estimated growth rate as the difference in leaf counts divided by

the number of days, and as such it is in units of new leaves/day. We measured corolla width and

anther-stigma distance on the first flower of each individual using digital calipers. We measured

the distance from the lowest and highest anthers to the stigma and calculated the mean of the

absolute distance to characterize anther-stigma distance.

Data preparation

Four of the five focal traits, (seed mass, early growth rate, corolla width and anther-

stigma distance) were standardized to mean = 0 and standard deviation = 1 using the grand mean

and standard deviation across populations to allow for meaningful comparison of differences

(Hine et al. 2009, Hansen & Houle 2008). We elected to use this standardization to eliminate

differences in the scale and units of our traits (e.g., anther-stigma distance in mm, growth rate in

leaves per day, and flowering time in days) and because mean standardization can be difficult to

apply to traits like flowering time, which have an arbitrary rather than natural zero (Hansen &

Houle 2008, Houle et al. 2011). During the experiment the shift from lengthening to shortening

days interrupted the flowering schedule. The glasshouse in which the plants were grown was

exposed to ambient light, and the change in artificial light used to induce flowering was largely

overwhelmed by the natural photoperiod. For this reason, we transformed the number of days

until the first flower using ordered quantile normalization (ORQ), which preserves the order of

flowering but results in a gaussian distribution (Peterson and Cavanaugh 2019). The ORQ

normalization results in a distribution centered on zero with a standard deviation of one, which is

the same scale as all other traits.

Univariate analysis

To determine broad-sense heritabilities of the traits we fit Bayesian generalized linear

mixed-effect models for each trait across all populations. We estimated the models using

MCMCglmm in R (Hadfield 2010) using the mixed model,

$y = \mathbf{X}\boldsymbol{\beta} + \mathbf{Z}_1\mathbf{u}_1 + \mathbf{Z}_2\mathbf{u}_2 + \mathbf{e}$ **(1)**

For each trait, y, we ran a separate model. In (1), $\mathbf{X}$, $\mathbf{Z}_1$ and $\mathbf{Z}_2$ represent design matrices for the

fixed effect of population, and random effects of matriline and greenhouse block, respectively. $\boldsymbol{\beta}$

and $\mathbf{u}$ are vectors of the related parameters. We included the environmental block to control for

the effect of microenvironmental differences within the glasshouse. For seed mass, we used the

greenhouse block of the maternal plant. Residual error is represented by $\mathbf{e}$.

We tested six priors and summed the Deviance Information Criteria value for each of the

five univariate models. We used the prior with the lowest summed DIC score, although due to

the amount of data in the model, the prior was not very influential. The effective size of the

samples was greater than 85% of the total number of samples and the autocorrelation was below

0.05 for all parameters (Hadfield 2010). To evaluate whether there was meaningful broad-sense

heritability, we ran models within each population with and without the matriline variable and

compared DIC values, per Puentes et al. (2016). We considered models where the matriline

reduced the DIC score >2 to have a "significant" genetic component and thus H^2 was significant.

We constructed comparable models for validation, using REML, which are presented in the

Supplemental Material. Heritability estimates were similar, with the greatest difference in

Heritability of 5.2%, and an average absolute difference of 1.7%. The 95% Highest Posterior

Density (HPD) intervals from Bayesian models overlapped REML heritability estimates in all

cases, and as such Bayesian estimates are presented in the main text.

Multivariate Analyses

We estimated the total genetic variance-covariance matrices separately for each

population using Bayesian generalized linear mixed-effect models through *MCMCglmm* in R

(Hadfield 2010). We again used the mixed model,

$$\mathbf{y} = \mathbf{X\beta} + \mathbf{Z}_1\mathbf{u}_1 + \mathbf{Z}_2\mathbf{u}_2 + \mathbf{e} \tag{3}$$

where $\mathbf{X}$, $\mathbf{Z}_1$ and $\mathbf{Z}_2$ represent design matrices for the vectors of trait means $(\mathbf{\beta})$, the total genetic

effects $(\mathbf{u}_1)$ and the greenhouse block effects $(\mathbf{u}_2)$. The residual error is represented by the term $\mathbf{e}$.

We used weakly informative inverse-Wishart priors for estimating the variance and

covariances where the distribution was described by the variance (V) and the belief parameter

(nu) and the default prior for the fixed effect estimates, $N(0,10^8)$. We tested a variety of priors to

determine the robustness of estimates and selected the model with the best fitting prior,

determined by the lowest average Deviation Information Criteria score to use for our analyses

(see Supplementary Materials). The final prior for the residual variance was given by a diagonal

matrix of 1's with the degree of belief slightly above *n*-1, for *n* traits (V=diag(5), nu = 4.001).

The best prior for the random effects was a matrix of 1/6 the phenotypic variance-covariance

matrix and a belief parameter slightly above *n*-1 (V = (**P**/6)×100, nu=4.001, where **P** is the

phenotypic (co)variance matrix). All the response variables in the model were multiplied by a

factor of 10, which improves the estimation of small variances (and is subsequently factored out

of the genetic variance-covariance matrix). To account for this factor of 10 in the response

variables, the Phenotypic variance-covariance matrix (**P**) was multiplied by a factor of 100 in the

priors.

We ran full models for 5,005,000 iterations, with a burn in of 5,000 and a thinning

interval of 1,000, resulting in 5000 iterations sampled from the posterior distribution. As with

our univariate models, the effective size of the samples were greater than 85% of the total

number of samples and all parameters had <0.05 autocorrelation (Hadfield 2010).

Null Models

For some analyses a null model was necessary, as MCMC methods can only estimate

variance greater than zero (matrices must be positive definite). We constructed randomized G-

matrices where the values only reflected sampling error as a point of comparison to our actual

estimates. Following Walter et al. (2018) and McGoey and Stinchcombe (2021), we randomly

assigned individuals to matrilines within populations, without replacement, resulting in G-

matrices that are only due to sampling error, as any phenotypic similarity among individuals is

only due to random sampling, rather than true genetic ancestry. Our design includes significant

fixed effects, which Morrissey et al. (2019) note will make these null distributions larger than

they should be, which should make our approach conservative. We also note that because each

randomized G-matrix only reflects sampling variation, the expectation of a large number of G-

matrix comparisons should be near 0 (as each population only reflects sampling variation), but

the distribution of these comparisons reflects the range of potential outcomes one can obtain if

each **G** only reflects sampling, making it a sensible null model. The within-population

randomization approach also allows us to compare whether each estimated **G** differs from

expectations due to sampling (Sztepanacz and Blows 2017).

We fed each randomized "population" into the same models as the observed data, run for

20,000 iterations with a burn in of 5,000 and a thinning interval of 100. We iterated the

randomization and model estimates 1000 times. We combined the final posterior sample of each

of the randomized models within populations to be used as a composite posterior. We assessed

chains visually for stability and with Gelman and Rubin convergence diagnostic criteria.

G-matrix comparisons

We used several metrics to compare G-matrices, each of which has different strengths

and weaknesses (Krzanowski 1979, Kirkpatrick 2009, Hine et al 2009, Aguirre et al. 2014,

Teplitsky et al. 2014, Puentes et al. 2016, Walter et al. 2018). In general, our goal was to use a

variety of metrics to compare G-matrix size, concordance between patterns of genetic variance

and clinal divergence, and similarity in the responses to selection that each G-matrix would

produce.

G-matrix size

We calculated the trace of the G-matrices to determine the total amount of genetic

variance in each population. The trace then describes the overall size of the G-matrices, or the

total amount of quantitative genetic variation they contain, which may be smaller in populations

affected by recent bottlenecks or strong selection as genetic variation is lost or eroded. We tested

our hypotheses using the mean of the posterior distributions and the 95% HPD intervals, to

examine whether there were differences in quantitative genetic variance. We also utilized the

posterior distribution of **G** to retrospectively evaluate how different they would need to be to

detect differences in the trace. To do so, we multiplied the posterior distribution of the Northern

populations by successive fractions to determine how much shrinkage would be required for the

95% HPD interval of a Northern population to not overlap that of the Southern populations. Our

logic was that if only minor reductions in **G** were required (e.g., the fraction is 0.95), any

conclusion of similarity would be relatively weak, and suggest a combination of low power, and

sampling or estimation error. In contrast, if detecting a difference between Northern and

Southern **G** required dramatic shrinkage of the matrix (e.g., the fraction is 0.25), it would suggest

that any conclusion about trace similarity was robust.

Genetic variation in the direction of maximum clinal divergence

To evaluate the alignment between the axis of greatest genetic variation (g_{max}) of each

population, and between g_{max} and the vector of greatest multivariate divergence ($Cline_{max}$ from

Stock et al. 2014) we calculated the correlation coefficient between these vectors. We used

random unit vectors as a null comparison. We note that Stock et al. (2014) used and presented

results from mean-standardized data; we re-analyzed their data to estimate the vector of greatest

clinal divergence using standard deviation standardized data, to match our use of standard

deviation-standardized data from the greenhouse experiment.

We projected the vector of maximum clinal divergence through each G-matrix (using

$b^T\mathbf{G}b$, where b is the vector of clinal divergence; see Lin and Allaire 1977) to calculate the

genetic variance in direction of clinal divergence. To estimate the proportion of genetic variance

along the direction of maximum clinal divergence, we estimate $b^T\mathbf{G}b/\boldsymbol{\lambda}_1$, where $\boldsymbol{\lambda}_1$ is the first

eigenvalue of **G**, representing the vector of maximum genetic variance in each population. Given

that the G-matrices had different shapes, the maximum amount of genetic variation in any

direction differed between the populations. To allow for fair comparison, we standardized by the

proportion of variance associated with g_{max}, the first eigenvector of **G**, in each population.

Random skewers

We performed a random skewers analysis (Cheverud & Marriog 2007, Aguirre et al.

2014) following Aguirre et al. 2014. Briefly, 1000 randomly generated normal vectors were

projected through each population's **G**. We compared the response from each projection between

populations to determine which random vectors which produced response differences. We then

calculate the variance-covariance matrix of the skewers which result in response differences

between populations and performed eigenanalysis to generate the **R** matrix. The **R** matrix

describes the trait space where differences in the response to skewers exist between populations,

with the first eigenvector describing the axis with the greatest differences between populations.

Krzanowski's subspace analysis

Krzanowski's subspace analysis provides a method of evaluating the similarity in

geometry of multiple variance-covariance matrices. The approach works by examining whether

the subspaces containing most of the genetic variation (e.g., the leading PCs) in each population

are shared, or in common. We first determine the shared space (**H**) of all populations, from a

subset of the leading PCs (eigenvectors) of each population, using:

$$\mathbf{H} = \sum_{t=1}^{p} \boldsymbol{A}_t \boldsymbol{A}_t^{T} \qquad\qquad (4)$$

where superscript T indicates transposition, and a subset t of PCs of each G-matrix are included

in **A**, and summation is to p populations ($p = 4$ in our case; Krzanowski 1979; Aguirre et al.

2014). As per Aguirre et al. 2014, the number of eigenvectors used for each population were

those which explained >90% of the total variation to account for differences in the shape of the

population G-matrices. The eigenvalues of **H** can range from 0 to p, which indicates common

sub-spaces to the matrices being compared (i.e., the leading PCs describe similar directions of

multivariate space). If the eigenvalues of **H** are less than p (4 in our case), this indicates that

genetic variation described by that eigenvector differs among the populations. To evaluate which

populations are most similar we determine the smallest angle between the mean posterior

subspace of each population and the mean shared subspace **H**, as per Aguirre et al. 2014.

Tensor analysis

Differences between matrices can be evaluated by calculating the 4th-order covariance

tensor, describing the variances and covariances between matrices (Hine et al. 2009). We used

the 4th-Order Genetic Covariance Tensor analysis developed by Hine et al. (2009), and outlined

by Aguirre et al. (2014), and Walter et al. (2018). We refer interested readers to these papers for

full details (especially Fig. 2 of Walter et al. 2018), and only provide a brief overview here. The

fourth-order tensor of the matrices describes the variance and covariances among the population

G-matrices. The tensor can be represented as a symmetric ($n(n+1)/2$) matrix (**S**) (Basser &

Pajevic 2007), where n is the number of traits, with elements describing the variances and

covariances of genetic variances and covariances among the four populations. The matrix **S** can

then be subject to eigenanalysis followed by scaling and rearrangement, such that the

eigenvalues and eigentensors describe how the G-matrices vary. Eigentensors with larger

eigenvalues (which explain a larger percentage of variance) describe dimensions of greater

variation in the G-matrices; the eigentensors can themselves be subjected eigenanalysis, to

determine the linear combination of traits (eigenvectors) that lead to the difference in G-matrices

captured by the eigentensors. The covariance tensor analysis can thus be used to evaluate axes of

differences among the genetic variance-covariance structure of the populations.

Results

Univariate Analyses

We estimated broad-sense heritability of each trait within populations using a Bayesian

model (Table S1, Figure S1), and confirmed results with REML (Table S2). All traits had

heritability greater than zero in at least 3 of the 4 populations (Table S1). The Pennsylvania

population lacked significant heritability for anther-stigma distance (Table S1). The mean of all

the heritability estimates was 0.213 (ranging from 0.011 to 0.535). There was no significant

difference between Northern and Southern populations, although Northern populations tended to

have lower heritability estimates than Southern populations (Table S1).

G-matrix size

We present population G-matrices, 95% HPD intervals, and null expectations due to

sampling variation in the Supplemental Material (Table S3, Table S4), and focus here on

comparisons of the matrices. The G-matrices all contain variances with HPD intervals that do not

overlap the 95% HPD intervals of the null G-matrices, although some traits in some populations

did have overlapping 95% HPD intervals, indicating that the variation may be very small (Table

S3). Two traits, corolla width and anther-stigma distance, have variation indistinguishable from

sampling variation in all populations except Hoffman (Table S3); we nonetheless retained these

traits in our analyses to allow comparisons of **G** to divergence in trait means, which requires

these traits.

We found that Hoffman, NC had significantly greater total genetic variation than either

Northern population, estimated as the trace of the G-matrices. Hoffman had approximately 57%

greater genetic variation than populations from Ellerbe, NC, 84% greater variation than

Maryland, and 142% greater variation than Pennsylvania. The 95% HPD intervals of Hoffman

did not overlap with either Northern population, but did overlap slightly with the other Southern

population, Ellerbe, NC.

Table 1: The total amount of genetic variation in each population estimated as the trace of **G**. Low and
high values demarcate the 95% highest posterior density interval (HPD). The trace of the randomized null
G-matrices are included for comparison.

Population	Trace of G	Lower HPD	Upper HPD	Random Trace	L. HPD	U. HPD
Pennsylvania	0.708	0.524	0.896	0.137	0.078	0.195
Maryland	0.930	0.689	1.178	0.138	0.085	0.209
Hoffman, NC	1.716	1.311	2.181	0.153	0.093	0.232
Ellerbe, NC	1.091	0.799	1.386	0.148	0.092	0.216

We next manipulated the posterior distribution to determine the proportional change

required to eliminate the overlap of the 95% HPD intervals between Northern and Southern

populations (taking advantage of the fact that posterior distributions remain valid for operations

performed on them: Wilson et al. 2010). As the trend was for smaller trace values in the north,

which we expect in recently bottlenecked populations or those eroded by selection, we calculated

the necessary reductions in the trace for Northern populations. Hoffman, NC was already

detectably different from the Northern populations, and so Ellerbe was the contrast for this

assessment. A reduction of 15% of the trace from the estimated trace of Pennsylvania and 50%

reduction of Maryland were sufficient to allow for differentiation between those populations and

Ellerbe. These analyses suggest that the Pennsylvania population may in fact have a reduced

trace but that estimation and sampling error, and power, preclude us detecting it. In contrast, the

trace for the Maryland population appears to be robustly similar to Southern populations.

Genetic variation in the direction of maximum clinal divergence

Overall, the proportion of genetic variation in the direction of maximum clinal

divergence was small, roughly on par with the third eigenvalues of each population, and there

were no significant differences between any populations (Table 2). To fairly compare between

populations, which differ in their total amount of genetic variation (Table 1) and the variation

along g_{max} (Table S5), we standardized the genetic variance in the direction of clinal divergence

by the genetic variance associated with g_{max}, so the values are relative to the linear combination

of traits with the maximum possible genetic variance in each population. The standardized

projections of the Northern populations were slightly larger than the Southern populations, but

there were no significant differences between them. In general, genetic variance in the direction

of clinal variation was ~30-50% of the genetic variance associated with g_{max}.

Table 2: Genetic variance in the direction of maximum clinal divergence for each population. In the
standardized column (Variance (std)), the variances are standardized by the eigenvalue of the leading
eigenvector of each population, to express this relative to the direction of greatest genetic variation.
Lower and higher HPD values demarcate the 95% highest posterior density interval.

Population	Variance	Lower HPD	Higher HPD	Variance (std)	Lower HPD	Higher HPD
Pennsylvania	0.155	0.076	0.241	0.505	0.258	0.782
Maryland	0.212	0.111	0.326	0.492	0.274	0.721
Hoffman, NC	0.247	0.130	0.380	0.321	0.139	0.523
Ellerbe, NC	0.283	0.151	0.436	0.591	0.319	0.869

The correlation between g_{max} from each of the G-matrices and direction of maximum

clinal divergence is not significantly different from the expected correlation between g_{max} and a

random vector (Figure 1). Although we might expect the direction of maximum clinal divergence

to be aligned with directions of genetic variation, this does not appear to be the case for any

population. The correlation between PC2 through PC5 of the population G-matrices and

direction of maximum clinal divergence followed the same pattern (Figure S2).

Figure 1: The correlation between the g_{max} of each population G-matrices and the vector of greatest
multivariate clinal divergence (Observed, in blue) compared to the correlation between the g_{max} of each
population G-matrices and randomized vectors (Randomized, in, in gray). Error bars represent the 95%
HPD intervals. "Penn" is Pennsylvania, "Mary" is Maryland, "Hoff" is Hoffman, NC and "Ellr" is
Ellerbe, NC.

Random skewers

The considerable fraction of the random vectors produced some difference in response

between populations, with 350 of 1000 resulting in responses where at least one pairwise

comparison had 95% HPD intervals which did not overlap. Following Aguirre et al. (2014), we

took this subset of vectors which resulted in response differences and created a variance-

covariance matrix of the vectors. We then performed eigenanalysis to evaluate the trait space

which describes differences among populations. The highest trait loading of the first eigenvector

is corolla width, followed by seed mass and flowering time (table 3). These differences in

response are largely attributable to Hoffman, NC. Projecting the eigenvectors of the R-matrix

through each population's G-matrix, we found that Hoffman had significantly more genetic

variation along this eigenvector than the other three populations (Figure 2). In other words, the

response difference we detected with random skewers appears to be due to the Hoffman

population having more genetic variation for a linear combination of traits made up primarily of

corolla width, flowering time and seed mass, with lesser contributions of growth rate and anther

stigma distance, than the other three populations.

Table 3: Eigenanalysis of the R-matrix from the Random Skewers analysis which resulted in difference
in response when projected through populations. The R-matrix summarized the trait combinations which
resulted in differences to the projected response. Each eigenvector (RSe1 through RSe5) describes an
independent combination of traits which capture differences among populations. The eigenvalues describe
the proportion of variation of each eigenvector within **R**, larger values indicate more of the variation in
the skewers are explained.

Trait	RSe1	RSe2	RSe3	RSe4	RSe5
Seed mass	-0.471	-0.153	0.402	-0.404	0.656
Growth	-0.041	-0.045	0.811	-0.069	-0.578
Flow time	-0.513	-0.525	-0.034	0.676	-0.053
Corolla	-0.655	0.158	-0.388	-0.429	-0.459
AS dist.	-0.292	0.821	0.172	0.436	0.145
Eigenvalues	**0.419**	**0.230**	**0.177**	**0.106**	**0.068**

The second and third eigenvalues of **R** are of similar magnitude, and when projected

through the G-matrices, reveal similar patterns. The second axis of **R** captures trait combinations

with opposing and larger values for anther-stigma distance and flowering time (Table 2); we

observed that Hoffman had more genetic variation for this combination of traits than

Pennsylvania. Collectively, these data indicate that the differences in the G-matrices detected by

random skewers were primarily driven by the Hoffman population, and it having more variation

in the linear combinations of traits measured (*RSe1*: corolla width, flowering time and seed mass

in concert; *RSe2*: flowering time and anther stigma distance in opposition).

Figure 2: Genetic variance (Vg) in the direction of each eigenvector of the **R** matrix, where the **R** matrix
is composed of vectors which resulted in response differences between populations.

Krzanowski's subspace analysis

To construct **H**, the shared subspace, we used the number of eigenvectors which

explained at least 90% of the variation in each population. The first four eigenvectors of each

population satisfied this condition. Lambda, which ranges from 1 to 4, approaches 4 in the first

eigenvector of **H** (Table 4, Figure 4). A lambda value nearing 4 means the populations all

contain the variation sufficient to recreate the shared trait space. Thus, the populations contain

considerable shared trait space in the first dimension of **H**. The second through fourth

eigenvalues are lower but similar to the randomized comparison (Figure 4). Overall, there is no

evidence of divergence among populations in the shared subspace.

Table 4: Eigenvalues (lambda) for each eigenvector of the shared subspace **H** with the 95% HPD
intervals. A value of 4 would indicate that all the populations have the variation in their subspaces
required to recreate the respective eigenvalue of **H**, lower values indicate that populations do not and thus
lack similarity.

Eigenvector	Lambda	Lower HPD	Higher HPD
h1	3.776	3.528	3.964
h2	2.909	2.184	3.679
h3	2.378	1.515	3.305
h4	2.021	0.994	3.089

To evaluate any population level divergence from the shared subspace we calculated the

angle between the axes of **H** and the subspaces of the populations ($A_tA_t^T$), which capture at least

90% of the genetic variation in each population. Larger angles indicate that populations differ in

some manner along that axis of shared subspace. The first four eigenvectors of Pennsylvania,

Hoffman, and Ellerbe, and Maryland were used to generate the shared subspace. Overall, the

angles between **H** and the population subspaces are similar and small with increasing uncertainty

for higher eigenvectors (Figure S3), meaning differences between the populations and the shared

trait subspace are minimal.

Figure 3: Eigenvalues (lambda) for each eigenvector of the shared subspace **H**, (where h > min k).
Higher values of lambda indicate greater similarity of population subspaces.

Covariance tensor analysis

451  We calculated the fourth order covariance tensor for the population G-matrices to assess

452 areas of divergence between the populations. We used the randomized G-matrices, which

453 represent sampling variation within populations, as a null contrast. For observed G-matrices, we

454 estimated three non-zero eigentensors for tensor **S**. Of these three eigentensors, the first two have

455 eigenvalues significantly different from a null expectation based on sampling variation creating

456 each G-matrix independently (Table S6, Figure 4).

Figure 4: A) Eigenvalues (**α**) for each non-zero eigentensor from the observed and randomized G-matrices. Note that the upper and lower bounds of the randomized data, reflecting only sampling variation, are small and hard to distinguish on the figure. B) Coordinates of each population in the first non-zero eigentensor of **S**, E1. C) Coordinates of each population in the second non-zero eigentensor of **S,** E2.

To determine the contributions of each population to the eigentensor, we estimated the coordinates of the populations within each eigentensor. The greater the absolute value of the coordinate the greater the contribution a population has. In the first eigentensor (E1, which explains 78.4% of the variation across all non-zero eigentensors), Hoffman again stands out from the other populations and has the greatest contribution. Thus, the first eigentensor, which describes the greatest amount of variation among the population G-matrices, is largely driven by differences between Hoffman, NC and all the other populations. In contrast, Ellerbe, NC has the largest coordinate value in the second eigentensor (E2), which explains 14.4% of the variation among G-matrices.

Table 5: Eigenvectors of each non-zero eigentensor of observed **S**. The variance explained by each non-zero eigentensor of **S** is given, along with the eigenvalues of each eigentensor in the direction of each eigenvector. These values describe the contribution of the independent trait combinations described by the eigentensors. The proportion of variance is the proportion of variance of the eigentensors explained by each eigenvector. The trait loadings for eigenvalues of each of the three eigentensor are given, along with the eigenvalue of the eigentensors.

Eigenvector	σ of E_x	Eigenvalue	Prop. of σ	Seed mass	Growth	Flow time	Corolla	AS dist.
e1.1	0.784	-0.914	0.581	-0.618	-0.134	-0.372	-0.607	-0.306
e1.2		-0.301	0.191	-0.255	-0.530	0.648	0.201	-0.440
e1.3		-0.260	0.166	0.536	0.327	0.113	-0.338	-0.692
e1.4		0.072	0.046	0.513	-0.770	-0.306	-0.207	0.085
e1.5		-0.026	0.016	0.056	0.037	0.579	-0.659	0.476
e2.1	0.144	0.840	0.471	0.677	-0.642	-0.309	-0.105	0.150
e2.2		0.395	0.221	0.646	0.607	0.235	-0.385	-0.104
e2.3		-0.303	0.170	0.088	-0.292	0.892	0.154	0.295
e2.4		0.216	0.121	-0.220	0.104	-0.129	-0.503	0.819
e2.5		-0.028	0.016	0.261	0.351	-0.191	0.751	0.457
e3.1	0.071	0.675	0.355	0.948	-0.092	0.001	0.288	-0.102
e3.2		-0.590	0.310	0.057	-0.687	-0.514	-0.473	-0.193
e3.3		-0.334	0.176	0.209	0.346	-0.434	-0.310	0.744
e3.4		-0.291	0.153	-0.153	-0.597	0.083	0.520	0.585
e3.5		0.011	0.006	-0.179	0.209	-0.736	0.572	-0.238

Eigenanalysis of the eigentensors reveals that the first eigenvector of E1, (*e11*) which explains 45.6% of overall variation (58.11% of variation within E1), is most heavily weighted by seed mass and corolla width (similar to *RSe1* of the R-matrix, as analyzed by Random Skewers), with all trait loadings being of the same sign (Table 5). The first eigenvector of E2 *(e21)*, which explains 6.88% of overall variation among populations (47.17% of variation in E2), describes a dimension most heavily weighted by the seed mass and growth rate of opposing signs (Table 5). Thus these two eigentensors describe population differences in the relationship between seed mass and other traits, especially with respect to the Southern populations.

Figure 5: Genetic variation in the direction of eigenvectors of the fourth-order covariance tensor **S**. *e11* is the first eigenvector of the first eigentensor, *e12* is the second eigenvector of the first eigentensor, *e21* is the first eigenvector of the second eigentensor, *e22* is the second eigenvector of the second eigentensor. The vectors were projected through each of the G-matrices to determine the amount of genetic variation that exists in that dimension.

We next projected these eigenvectors through the population G-matrices, as we did for

the random skewers, to assess how much variation each population has along these axes. Not

unexpectedly, Hoffman, NC has significantly greater genetic variation along the first and second

eigenvector of E1 (Figure 5). Ellerbe has greater variation than the other population along the

first eigenvector of E2, although the HPD intervals overlap all other populations. The second

eigenvector of E2 similarly has overlapping 95% HPD intervals for all populations but the

Southern populations have slightly more genetic variation in this direction than the Northern

populations.

Similarity between skewers and tensors

Given the similarities between the first eigenvector of E1 of **S** and the results from the

random skewers R-matrix projection we calculated the correlation between the two vectors and

found that they are almost perfectly correlated (corr = 0.97). This congruence between two

vectors of differentiation calculated with entirely different methods provides additional support

for this axis describing considerable differences among populations.

Discussion

Understanding patterns of genetic variation within populations, and how they relate to

phenotypic differentiation among them, is a central goal in evolutionary biology. Our analyses of

genetic (co)variance matrices and divergence of four natural populations of *Ipomoea hederacea*

point to three main results. First, despite the variety of evolutionary forces that could produce

differences in **G** between Northern and Southern populations—including strong selection, drift,

and bottlenecks—we found remarkably similar patterns of **G** and genetic variation. Our results

add to a growing body of cases in which differences in **G** are predicted *a priori*, but not detected.

Second, contrary to a variety of theoretical predictions, we failed to detect a relationship between

the axis of greatest multivariate clinal divergence and the axes of greatest genetic variation

within populations. Below, we discuss these results in light of how genetic constraints and

reduced dimensionality of **G** influence phenotypic divergence, and divergence in **G** these

populations.

Evolutionary potential and divergence of G

Our study of **G** within these four populations allows both an evaluation of the

evolutionary potential within each population, and the divergence (or lack thereof) of **G** itself

between range-edge populations and central populations. Using a variety of approaches,

including estimating trace of **G**, and three methods for comparing **G** among populations, we

found a consistent pattern of results. These populations all appear to be of reduced rank, have

similar amounts of total genetic variance, and there do not appear to be appreciable differences

between range-edge populations and core populations in the structure, size, or orientation of **G**.

We first assessed the total amount of genetic variation among populations and found that

there was a trend along latitude for decreased genetic variation in the Northern populations,

although the 95% HPD intervals of one of the Southern populations overlapped, making this

trend slight. Hoffman, NC, one of the Southern populations, stood out among others as

possessing significantly greater variation than all other populations. Similarly, one of the

Northern populations, Pennsylvania, had the lowest trace, and if it had been estimated as slightly

smaller (15% reduction), its trace would not have overlapped with the Southern populations.

However, while we detected one Southern population with increased genetic variation, and

possibly one Northern population with reduced variation, the remaining two populations have

robustly similar amounts of quantitative genetic variation. In like fashion, trait heritabilities

tended to be higher in Southern populations (Table S1), albeit again with overlapping HPD

intervals. Thus, it appears that the Hoffman population is distinct from the rest, rather than

Southern populations overall strongly differing from Northern populations.

Two of the traits, corolla width and anther-stigma distance, had very small variances

indistinguishable from sampling variance in three of the populations (Hoffman being the

exception). The lack of variation in these traits in **G** make observing differences among

populations impossible with respect to corolla width and anther-stigma distance. In Cline$_{max}$ both

corolla width and anther-stigma distance showed significant among-population divergence of the

means, which suggests that the paucity of within-population variation for these traits is likely due

to selection. We retained these traits in our G-matrices to allow for comparison with the axis of

greatest multivariate divergence, Cline$_{max}$ (from Stock et al. 2014).

Our results are suggestive of the overall stability of the G-matrices across populations,

and add to a handful of cases in which **G** remains similar despite adaptation to gradients,

differences in selective regimes, and altered patterns of gene flow. Given the *a priori* expectation

that drift and population bottlenecks should introduce stochastic changes in **G** (Lande 1979,

Shaw et al. 1995, Roff 2000, Phillips et al. 2001, Jones et al. 2004, Doroszuk et al. 2008) and

that populations of *Ipomoea hederacea* likely have low effective populations sizes and may

frequently experience bottlenecking (Campitelli & Stinchcombe 2014) and thus are expected to

be susceptible to drift, the degree of stability we found is surprising. In this regard, our results are

similar to McGoey and Stinchcombe (2021), who found little difference in G-matrices between

introduced and native populations of ragweed (*Ambrosia artemisiifolia*) despite expectations to

the contrary. More generally, our results add to other findings of **G** being relatively stable across

geography (Arnold et al. 2008; Delahaie et al. 2017), even in cases in which theoretical guidance

suggests a strong expectation of divergence in G. In Scandinavian populations of *Arabidopsis*

thaliana, Puentes et al. (2016) expected to find divergence in **G** due to differences in selective

environments and limited gene flow. While the populations had univariate differences the G-

matrices of all populations demonstrated overall similarity in shape and orientation. Similarly,

Hangartner et al. (2019) estimated **G** in locally adapted populations along a broad climatic

gradient with disparate selective regimes and found that **G** had minimal changes across eastern

Australian populations of *Drosophila melanogaster*. In island and mainland populations of the

blue tit (*Cyanistes caeruleus*) where two distinct, heterogenous landscapes produce divergent

selection and gene flow between populations is expected to be low to effectively absent (in the

case of island-mainland) Delahaie et al. (2017) found weak overall differentiation in **G**.

Although **G** can evolve under certain conditions, and empirical studies have in some cases

detected remarkable differences, ours is one of the growing number of studies that have failed to

detect changes in **G** despite strong expectations.

Both the covariance tensor and random skewers analysis suggest that the Hoffman, NC

population differed from the others (this population also had the most genetic variation overall

and in the direction of clinal divergence). The covariance tensor and skewers approaches are

complementary, in that the tensor reflects patterns of variation and covariation among **G**, while

the skewers analysis is insensitive to differences in the total amount of genetic variance and

magnitude of the response (as it uses the correlation between response vectors, but not their

magnitude; Hansen and Houle 2008). These differences are not simply due to Hoffman's greater

overall genetic variation. The first eigenvector of the first eigentensor (*e11*), the first eigenvector

of the random skewers analysis (*RSe1*), and g_{max} within the Hoffman population were all highly

correlated, with heavy loading from flowering time, corolla width, and seed mass. The Hoffman,

NC population site did not differ substantially from the others: all were collected from roadsides

adjacent to agricultural fields and were reasonably large to allow for sampling from 70-100

individuals. Hoffman was, however, the only population where we observed both leaf shape

genotypes (leaf shape is a simple Mendelian polymorphism in this species; Bright-Emlen 1998).

Some speculative possibilities are that it was founded by heterozygous individuals, multiple

founders of opposite leaf shape genotypes, or is subject to balancing selection on the leaf shape

locus (as has been shown by Bright and Rausher 2008), and thus has more variation for any of

these reasons.

Collectively, our diverse set of analyses points to a single population being qualitatively

different from the others, with divergence driven by a handful of traits in that population, rather

than range-edge populations having any inherent differences in the structure of **G**. At face value,

these findings might suggest that range-edge populations of *Ipomoea hederacea* are not small

enough to experience substantial genetic drift that could reduce genetic variance compared to

central populations; alternatively, it may be that all populations experience frequent extinction

and colonization dynamics, across the range, and that this does not have differential effects on

genetic variance. We suspect the latter possibility is more likely, especially when taken together

with the population genetic work of Campitelli and Stinchcombe (2014), in which they suggested

that metapopulation dynamics with high extinction and dispersal rates may explain the patterns

of neutral genetic diversity.

Clinal divergence and G

In general, phenotypic divergence is expected to be aligned with **G** under three overall

conditions. First, under genetic drift, we expect that phenotypic divergence in a suite of traits

should be related to the overall amount of standing quantitative genetic variance in those traits

(Lande 1979, Phillips et al. 2001). Second, when G-matrices are ill-conditioned, or of reduced

rank, we expect short-term evolutionary responses to be biased towards directions of multivariate

trait space with genetic variance (Chenoweth et al. 2010). In other words, once a G-matrix differs

from spherical, evolutionary responses will be dominated by the directions containing the most

variance. In the third scenario, when $\beta = g_{max}$, divergence, Δz, proceeds along g_{max}, and we

expect the maximal evolutionary response (Gaydos et al. 2013). Hangartner et al. (2019) found

that G-matrices of range-edge populations of *Drosophila melanogaster* were in fact aligned with

clinal divergence and that the trait covariances improved the adaptive potential of peripheral

populations. Work on the cuticular hydrocarbons of *Drosophila serrata* population by Hine and

colleagues (Hine et al 2009, Chenoweth et al. 2008) found patterns in mean trait divergence,

reduction in associated variation in g_{max}, and divergence among populations along g_{max}.

Similarly, Aguirre et al (2014) found that those populations share considerable trait space,

although there were axes of divergence among the populations. In contrast, phenotypic

divergence does not have to be aligned with **G** if selection has been strong and persistently

favoring alternative combinations of traits, or consistent selection over long evolutionary

timescales. For example, McGuigan et al. (2005), found that hydrodynamic adaptation in

rainbow fish was only weakly associated with g_{max}, and was primarily aligned with the trailing

eigenvectors of **G**; they interpreted this as a result of long-term selection towards a new

phenotypic optimum.

With this context in mind, many of our results suggest that we should have observed a

relationship between clinal divergence and **G**: the traits are genetically variable, both

individually (Table S1) and as a linear combination (Table 2). It also seems unlikely that the

phenotypic divergence detected is a result of long-term selection, similar to McGuigan et al.

(2005), as *I. hederacea* currently inhabits (and was collected from) ephemeral, disturbance-prone

habitats such as roadsides, agricultural fields, and cleared areas. Consequently, many of the

conditions that can produce a relationship between **G** and divergence appear to be met.

Two potential explanations for why we do not see such a relationship between **G** and

divergence occur to us. The first is that previous work on *Ipomoea hederacea* (Simonsen and

Stinchcombe 2010; Campitelli and Stinchcombe 2013; Stock et al. 2014) and this study

inadvertently omitted an ecologically important, correlated trait. For this scenario to explain the

lack of relationship between divergence and **G**, there would have to be an omitted trait that is

both highly variable within populations, and highly diverged between populations, such that its

inclusion would predominate both g_{max} and any estimate of a divergence vector. The problem of

missing traits is inherent to studies of phenotypic evolution; while the traits we measured capture

aspects of size, growth, phenology, and floral morphology, it is possible that other traits related

to ecophysiology, seed bank dynamics, or other aspects of the life cycle are more important.

Second, it may be that natural selection is acting in a direction that is nearly orthogonal to

g_{max}, thus leading to the divergence that is at a substantial angle from g_{max}. If this were the case,

it would be possible for the G-matrices we estimated to produce evolutionary responses that

could lead to the observed divergence. One clue in support of this hypothesis is that flowering

time appears to load relatively weakly on g_{max} in the Pennsylvania population, but in the past has

been detected to be under very strong directional selection in this species (Simonsen and

Stinchcombe 2010; Campitelli and Stinchcombe 2013). Similarly, Campitelli and Stinchcombe

(2013) found selection favoring decreased flowering time and increased early and mid-season

growth rates (i.e., β elements of opposite signs), while we found that growth rate and flowering

time load in the same direction (i.e., are positively correlated) of g_{max} in three of four

populations. As such, there are past observations of selection acting strongly on traits with

relatively little genetic variance, or in opposite directions on positively correlated traits, both of

which could lead to β being orthogonal to g_{max}. Indeed, Simonsen and Stinchcombe (2010) found

strong natural selection almost orthogonal to g_{max} in a field study of size traits and flowering

time, due to size traits being highly variable and under weak selection, and flowering time being

less variable but under very strong selection. The divergence observed may thus be the product

of selection, but without requiring recourse to long-term selection towards a single optimum.

While there are field studies of natural selection on some of the traits we studied, an overall

study of all of them is necessary to distinguish between the missing trait explanation and **β** being

orthogonal to g_{max}.

Conclusions and Future Directions

Determining the relationship between **G** and phenotypic divergence, or divergence of G-

matrices themselves, is a challenging empirical and statistical endeavor. Practical constraints

make constructing well estimated G-matrices for dozens of populations nearly impossible

(Arnold et al. 2008) is certainly the case for *I. hederacea*. The most tractable and testable

hypothesis to emerge from our work is that natural selection on these five traits is poorly aligned

with g_{max}. Future field studies will be required to further elucidate the action of natural selection

on this species, and the ecological mechanisms behind selection for this suite of traits and others.

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