OptoRheo: Simultaneous *in situ* micro-mechanical sensing and

imaging of live 3D biological systems.

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Abstract

Biomechanical cues from the extracellular matrix (ECM) are essential for directing many

cellular processes, from normal development and repair, to disease progression. To better

understand cell-matrix interactions, we have developed a new instrument named 'OptoRheo'

that combines light sheet fluorescence microscopy with particle tracking microrheology.

OptoRheo lets us image cells in 3D as they proliferate over several days while

simultaneously sensing the mechanical properties of the surrounding extracellular and

pericellular matrix at a sub-cellular length scale. OptoRheo can be used in two operational

modalities (with and without an optical trap) to extend the dynamic range of microrheology

measurements. We corroborated this by characterising the ECM surrounding live breast

cancer cells in two distinct culture systems, cell clusters in 3D hydrogels and spheroids in

suspension culture. This cutting-edge instrument will transform the exploration of drug

transport through complex cell culture matrices and optimise the design of the next-

generation of disease models.

Introduction

Cells sense and respond to the mechanical properties of the extracellular matrix (ECM) at a

cellular length scale, using traction forces to probe stiffness [1], steer migration [2,3] and

influence cell fate [4]. Simultaneously, the ECM is continuously remodelled by cells as they

exert these traction forces [5] during cell migration and morphological re-arrangement [6].

Anomalies in the mechanical properties of the ECM play significant roles in the development

of pathologies such as cancer [7] and fibrosis [8], often establishing barriers to therapeutic

intervention [9]. Modelling and understanding cellular influence on ECM biomechanics is

challenging given the wide range of mechanical environments experienced in health and

disease. In healthy tissues, the elastic modulus has been reported to range from tens of Pa

(e.g., brain, lung) to well above 10 KPa (e.g., skeletal muscle, bone), with disease states

such as cancer and fibrosis showing a significant change in stiffness (e.g., from 800 Pa for

normal breast to more than 4 KPa in breast cancer) [10]. Moreover, the full mechanical

characterisation of the ECM also contains a viscous component that may influence cell

behaviour [11]. The recent development of engineered hydrogels with tuneable mechanical

properties [12,13] have made it possible to recreate elements of the ECM micro-architecture *in*

vitro and reveal the influence of ECM viscoelasticity on cell processes [14,15]. Despite these

advances and their importance, the mechanistic processes of cell-matrix interactions remain

poorly understood. For instance, do cells 'prime' their local environment prior to migrating or

do they exploit existing weaknesses in the ECM and migrate accordingly? These

unanswered questions call for minimally invasive optical approaches to monitor changes in

the microscopic mechanical properties of the ECM, *in situ* and in real time*,* local to

proliferating cells over many days.

To address this aim, OptoRheo combines three different microscopy techniques, light sheet

microscopy, multiplane microscopy and optical trapping into a single instrument. This

approach enables live fluorescence imaging deep in 3D cell cultures and microrheology

measurements of the ECM within the same region of interest, local to and far from the cells.

3D fluorescence imaging is achieved using a new version of reflected light sheet

fluorescence microscopy (LSFM) [16–19] built on a commercial inverted microscope body to

image hundreds of microns deep from the coverslip, within live 3D cell cultures and with sub-

cellular resolution. The sample is kept completely stationary during z-scanning, with no

perturbation or contamination risk from dipping lenses, both crucial for ensuring that

observation does not influence the mechanical or biological properties of the sample. This

novel configuration allows for delicate samples such as hydrogel scaffolds to be imaged

simply in off-the-shelf chambered coverslips. To extract the viscoelastic properties of the

ECM, OptoRheo tracks the thermally driven Brownian motion of micron-sized beads, acting

as rheological probes across a wide time-window. The inert bead probes can be embedded

in the hydrogel during encapsulation [6,20–22] or even internalised into cells [23] to probe intra-

cellular viscoelasticity. In suspension cultures, an optical trap can be used to hold the probe

in the field of view within the cells' microniche during the measurement extending the range

of materials the instrument can characterise [24]. Finally, OptoRheo incorporates optional

multiplane imaging that can be used to extend microrheology to 3D in a configuration similar

to the one developed for OptiMuM [25], to achieve a full 3D characterisation of the extracellular

microenvironment.

To highlight the capability of OptoRheo, we present data obtained from the analysis of two

systems seeded with human-derived MCF-7 and/or MDA-MB-231 breast cancer cells, either

(I) encapsulated as clusters in 3D hydrogels or (II) as spheroids maintained in suspension

culture. In the case of hydrogel scaffolds, matrix stiffness was measured using passive

particle tracking microrheology without the use of an optical trap or multiplane imaging,

whereas in the case of suspension cultures, the optical trap was implemented along with

multiplane imaging. Imaging and microrheology were performed sequentially at multiple

regions within the samples at depths of 150 µm - 400 µm from the coverslip. In the case of

the hydrogels, the samples were monitored over three days to reveal microscale variations

in the elastic properties of the ECM near to and away from cells. When studying spheroids in

suspension the optical trap was used to place and hold the probes in user-defined locations

and extract the relative viscosity of the media near the spheroids. Notably, in both the cases

our measurements were found to be sensitive to local spatio-temporal variations in the

biomechanical properties of the culture medium. As demonstrated in this study, our

multimodal and minimally invasive approach opens a wide range of future opportunities for

physiologically relevant, long-time course investigations and time-lapse videos of cell-ECM

interactions in fragile live cell culture samples. We anticipate that this approach will be

applied to increasingly complex and relevant *in vitro* models, providing an essential insight

into the previously opaque mechanistic control of cell behaviour by the ECM in health and

disease.

Results

3D imaging deep in live cell cultures

A schematic representation of OptoRheo can be seen in Figure 1. 3D light sheet

fluorescence microscopy (LSFM) is achieved by projecting a thin, planar excitation

beam limited to the detection plane of the microscope and collecting the emitted

fluorescence at a 90° angle to the illumination plane [26,27]. For deep imaging of live 3D cell

cultures, the light sheet illumination was introduced using a 10 mm 90:10 (Reflectance:

Transmittance) beam splitter cube placed in the sample chamber prior to casting the gel

alongside it (Figs 1, 2 and S1). This LSFM approach has multiple advantages; deep and fast

fluorescence imaging with low phototoxicity [28] and minimal sample perturbation during

imaging, while being cost-effective and modular. The glass beam splitter cube can be

sterilized for reuse and placed either inside or outside the sample chamber to provide

flexibility to adapt to different experimental conditions.

Unlike some other prism or mirror based LSFM solutions [16,29,30], 3D image generation was

achieved here by scanning the light sheet and not the sample. Notably, this allows the

sample to be kept stationary and undisturbed throughout data collection, which is essential

for imaging delicate samples prepared in soft hydrogels (Fig 2A) or liquid suspension media

over multiple days. The light sheet itself was generated using a cylindrical lens, the

properties of which set the thickness of the light sheet and influence the axial resolution and

optical sectioning capabilities of the microscope. In the presented configuration, the

measured axial resolution of the detection optics of the LSFM on OptoRheo was 1.09 µm for

$\lambda_{ex} \backslash \lambda_{em}$ = 532 nm \ 580 nm which agrees closely with theory (1.1 µm) (Fig S2).

A scanning galvanometer mirror was placed conjugate to the cylindrical lens using a 4f

system, so that tilting the galvanometer mirror translated to a Z-shift in position of the light

sheet at the sample (Fig 1). Acquiring Z-stacks involved synchronisation of the galvanometer

mirror with a piezoelectric objective scanner that moved the objective lens, ensuring that the

illumination and imaging planes remained co-aligned and synchronised throughout the scan.

The light sheet remained at optimal thickness (~3 µm for all three colour channels, see

Methods) over a field of view of ~100 µm. However, image tiling could be achieved within a

region 4 - 6 mm from the beam splitter cube to increase the field of view. This required

shifting the light sheet focus laterally by moving the position of the cylindrical lens. The

shifted position of the beam splitter was compensated by tilting the galvanometer mirror to

image the new focal position.

Figure 1: **A schematic representation of the OptoRheo instrument**. Components: Lasers

– 473 nm, 532 nm and 640 nm lasers provide the light sheet illumination while a 1064 nm

laser is used for optical trapping. M1- M3 – mirrors; D1-D3 – dichroic mirrors; L1-L6 –

achromatic doublets, L1 and L2 form a 8.3 x beam expander and are part of a 4f system with

the galvanometer mirror (GM) and a beam splitter (BS2); CY1, CY2 – cylindrical lenses;

BS1, BS2 – beam splitter cubes; OBJ – objective lens; OBJ S – piezoelectric objective

scanner; F1– fluorescence emission filter; TL – tube lens, QG – quadratic gratings and CAM

– camera. Yellow arrows indicate synchronised motion of (i) the galvanometer mirror, (ii) the

projected light sheet and (iii) the objective lens (using a piezoelectric objective scanner). The

quadratic gratings slide in and out of the optical path to enable 2D and 3D particle tracking.

The quadratic gratings are removed for the LSFM imaging.

The current configuration of OptoRheo uses a 60x objective lens with a 1.5 mm working

distance and a numerical aperture (NA) of 1.1, selected to image deep into a sample, but

with a high enough NA for optical trapping. For the data presented in this work, z-scans were

typically recorded 150 μm - 400 μm from the coverslip (Fig 2B). To extend the field of view

for larger objects, LSFM images could be tiled and stitched together as detailed above. The

multiplane grating breaks up the field of view into nine planes to enable 3D tracking of the

rheological probe [25] and therefore, is not required for LSFM imaging and can be easily

removed by means of a slider. Additionally, the multiplane gratings used were optimised for

a particular wavelength (543 nm) making them unsuitable for multicolour imaging. OptoRheo

is fitted with a stage-top incubator that regulates temperature, CO_2 and humidity around the

sample, allowing long time-course experiments spanning over hours (Fig 2C and

Supplementary Videos VS1 and VS2) and days.

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Figure 2: **Light sheet fluorescence microscopy (LSFM) with OptoRheo.** A. Schematic of

light sheet microscopy on the OptoRheo. Sample consists of cell clusters (represented by

red circles with blue centres) and collagen (purple lines). B. Multicolour imaging of a co-

culture of MCF-7 (top left corner of montage) and MDA-MB-231 (bottom right corner) in

hydrogel supplemented with Cy-5 labelled collagen I (bottom right corner) on the OptoRheo

with three colour channels. Images in montage are maximum intensity projections. Scale bar

= 20 µm. C. Single planes from time lapse movie (supplementary video VS1) taken on the

OptoRheo of a MDA-MB-231 cell changing morphology. Scale bar = 10 µm. D. 3D rendering

of the same region of interest in panel B.

Microrheology of gels and suspension cultures

The viscoelastic properties of biomaterials can be extracted non-invasively using particle

tracking microrheology as developed by this group and others [24,25,31]. This involves a

statistical analysis of the residual Brownian motion of micron-sized spherical probes, whose

temporal behaviour can be described by means of a Generalised Langevin equation [31]. For

this purpose, polystyrene microsphere probes were seeded in the cell culture samples under

sterile conditions (Fig 3A). For hydrogel-based cell culture systems, the diameter of the

microsphere probes (6 µm) was selected so that the Brownian motion of the probes were

constrained by the hydrogel polymer network. A small field of view (typically 14 µm x 14 µm)

was recorded around the microsphere probe (Fig 3B) to track the trajectory of each probe

(Fig 3C) at a relatively high frame rate (~ 300 Hz - 5 kHz) to achieve broadband

microrheology. This was done while switching the illumination to transmission mode using a

LED source to avoid introducing fluorescence bleaching-related errors in particle tracking

(Fig 1). A second cylindrical lens (CY2 in Fig 1) was placed in the LED light path to

compensate for the presence of the light sheet forming cylindrical lens (CY1 in Fig 1) and

produce uniform illumination. An analysis of the mean squared displacement (MSD) of the

confined microspheres (Fig 3D) gives the elastic ($G'(\omega)$) and viscous ($G''(\omega)$) moduli of the

surrounding gel (Fig 3E), see methods section for further details.

Figure 3: **Passive microrheology without optical trapping.** A. A schematic representation

of passive microrheology measurements. B. Microsphere probes (6 μm diameter) were

seeded in the hydrogel and small regions of interest (typically 14 μm x 14 μm as shown)

around them were imaged at a high frame rate (5 kHz in this example). C. Particle trajectory

in a 2D plane with individual positions depicted in orange (down sampled here for clarity

from a total of 1.5×10^6 frames). D-E. The mean squared displacement (MSD) provides a

measure of gel compliance, which is then used to compute the elastic ($G'(\omega)$) and viscous

($G''(\omega)$) moduli of the gel over a wide range of frequencies as shown in panel E (for more

details on the analysis see Methods).

In liquid media and suspension cultures, microsphere probes sediment to the coverslip over

time with a rate dependent on the gravitational force, the buoyancy of the microsphere and

the viscosity of the medium [32]. In aqueous liquids, this sedimentation rate is about 20 μm/s

for microspheres with a 3 μm radius, thus preventing long-term (i.e. tens of minutes) tracking

of the probe trajectories, which are needed for broadband microrheology calculations.

Therefore, when working with liquids we used an optical trap (Fig 4A) to hold the probe in

the field of view and at the required location relative to the cell/s of interest during the

measurement time. The trapping force acting on the microsphere was kept very low (<10^{-6}

N/ m) by controlling the laser power, to maximise the amplitude of the residual Brownian

motion, increasing the sensitivity of the microrheology measurement and the frequency

range. The confined Brownian motion of the microsphere could then be recorded at ~300 Hz

in 3D by inserting a removable pair of quadratic gratings (QG) in the detection path before

the sCMOS camera to achieve multiplane detection of the particle position [25,33] (Fig 1 and

4B). In particular, the quadratic grating pair focus light from nine object-planes as an array

onto the camera sensor for instantaneous 3D imaging without the need of any mechanical

moving parts [25,33] (Fig 4B). This method allows tracking of the microsphere motion in all

three dimensions simultaneously (Fig 4C), revealing spatial variation of the sample's

viscoelastic properties. However, the smallest variance in particle position we could reliably

measure with the present configuration was 30 nm in z, compared to 15 nm in x and y.

Therefore, tracking in z was unreliable for our gel samples where the motion is typically less

than 50 nm (see Fig 3C).

We validated our microrheology measurements from the 3D particle tracking mode of

OptoRheo by using water, a well characterised Newtonian fluid. We extended our previous

work [25] by measuring the 3D trajectories of microsphere probes from 50 to 400 μm away

from the coverslip, without the use of any aberration correction, thus enabling microrheology

measurements at the same sample depths as our light-sheet imaging experiments. It is

important to note that most studies employing optical trapping report measurements taken at

<100 μm from the coverslip [34]. The use of water immersion and a correction collar allowed

us to achieve trap stiffness k values of k_x= 3.2 x 10^{-7} ± 0.3 x 10^{-7} N/m along the x axis, k_y =

3.2 x 10^{-7} ± 0.5 x 10^{-7} N/m along the y axis and k_z = 6.7 x 10^{-8} ± 1.2 x 10^{-8} N/m along the z

axis (mean ± standard deviation) over this large range of distances from the coverslip.

Relative viscosity (ratio of viscosity of an aqueous solution to the viscosity of water at the

same temperature) could be evaluated in 3D by analysing the normalised position

autocorrelation function (NPAF) for x, y and z at depths ranging from 50 µm to 400 µm from

the coverslip. In particular, the relative viscosity can be read "*at a glance*" from the abscissa

of the NPAF intercept e^{-1}, when the NPAF is plotted versus a dimensionless lag-time $\tau^* =$

$k\tau/(6\pi a \eta_s)$; where k is the trap stiffness, τ is the lag-time (or time interval), a is the probe

radius, and η_s is the Newtonian viscosity expected for the pure solvent [35] (Fig 4D). Figure 4E

shows the mean x, y and z relative viscosity ± standard deviation, performed at different

depths (see Methods). Over the range of recorded measurements, the measured mean

relative viscosity (over x, y and z) remained stable with depth (i.e., 1 ± 0.05).

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Figure 4: **Microrheology with an optical trap and multiplane detection** (3D particle

tracking mode) in an aqueous solution. A. An optically trapped microsphere is imaged in 9

planes simultaneously (planes represented by dashed lines). B. Captured image of nine

separate Z planes (Δz = 0.79 µm). The planes (labelled from number -4 to +4) are

simultaneously recorded at the camera sensor to extract the 3D trajectory. C. The resulting

3D trajectory of optically trapped microsphere in water with individual positions depicted as

blue circles (down sampled for clarity from a total of 2×10^5 frames). D. The normalised

position autocorrelation function (NPAF) versus a dimensionless time, τ^*. E. The mean ±

standard deviation of the relative viscosity measured at each position over a range of

depths.

Monitoring ECM stiffness in hydrogel-encapsulated 3D cell culture

In order to test the ability of OptoRheo to evaluate biomechanical properties of the ECM in

real time, clusters of human-derived MCF-7 cancer cells expressing the tdTomato

fluorescent protein were grown in a hydrogel-encapsulated cell culture matrix [12,36]. Echoing

what is known from patients, changes in the ECM stiffness around these cells have been

correlated with cancer progression and metastasis, and have been shown to alter drug

resistance [37,38]. Complementary multi-colour 3D LSFM imaging allowed cells and labelled

matrix components (i.e. collagen I) from the same locations to be captured in separate

colour channels. These volume images could be overlaid and combined with microrheology

measurements to map the changing biomechanical properties to the changing morphology

of the sample, at the microscale. This approach was used to compare four different complex

systems made of hydrogels with and without (i) collagen and (ii) cells.

The curves of the elastic ($G'(\omega)$) and the viscous ($G''(\omega)$) moduli of all the hydrogel

preparations show a pattern characteristic of viscoelastic polymer gels [39] with a rubbery

elastic plateau G'_0 (where $G'(\omega) > G''(\omega)$) at low frequencies transitioning to a high

frequency glassy state (Figs 3E and 5A). Environmental control on OptoRheo allowed the

gel samples to be kept under physiological conditions over multiple days, making it possible

to re-visit selected microsphere probes multiple times over the duration of the experiment

(three days) to follow the changing ECM properties over time. This was performed in

triplicate.

In the absence of cells, the height of the elastic plateau - G_0', is greater for plain gels (n = 11)

as compared to gels supplemented with collagen I (n = 11) (p = 0.0014, Kruskal-Wallis test;

Fig 5A) at the start of the experiments (day 1), indicating stiffer gels and may point to

differences in the cross-linked network [40]. The high frequency glassy response which can be

attributed to local monomer relaxation [41] is similar for the gels (Fig 5A) which have the same

polymer hydrogel base at the same concentration. We therefore focus our analysis on the

G_0' values.

The presence of cells brings about complex changes in the gels which become more

apparent over time and when taking into account the proximity to cell clusters (Fig 5 B-F).

Over time, as cell clusters proliferated and changed their relative distance from the probes,

this information could be extracted from LSFM images. Our data show that the presence of

collagen makes the gels more compliant (p = 0.0008 Generalised Mixed Effects Model).

There was a significant difference in the proportional change in $\Delta G_0'$ (between day 3 and day

1) in the presence and absence of cells in gels supplemented with collagen (p = 0.007,

Kruskal-Wallis test; Fig 5B). Moreover, the G_0' values change with distance from the nearest

cell cluster both in the presence and absence of collagen. In the presence of collagen, the

gel was most compliant within 50 µm from the edge of the nearest cell cluster. This region

near the cell clusters was much more heterogeneous with measurements spanning over

three orders of magnitude as compared to farther away (two orders of magnitude at regions

> 50 µm) (Fig 5F) hinting at a gel remodelling front.

Figure 5: **Local stiffness measured in live 3D cell cultures with different compositions**.

A. Complex moduli of plain gel in orange and gel supplemented with collagen in purple at

day 1 (averaged with 95% confidence intervals shown as shaded regions). B. Proportional

change in the height of the low frequency elastic plateau G'_0 at individual bead probes over

three days of observation in plain gel (G), gel with collagen (GCol), gel seeded with cells

(GCell) and gel with collagen and cells (GColCell). The dashed line represents no change,

negative values indicate more compliant gels. C-D. Biomechanical maps produced by

OptoRheo of MCF-7 clusters expressing tdTomato (shown in purple) encapsulated in

hydrogels and D. MCF-7 clusters from the same cell line in hydrogel supplemented with

collagen I labelled with Cy5 (shown in green) monitored over three days. Spheres depict

microsphere probes (not to scale) assigned a colour to reflect the local stiffness (G_0'). E. & F.

Spatiotemporal changes in G_0' values with relative distance from the edge of the cell clusters

in gel in the absence (E) and presence (F) of collagen over three days.

Mapping relative viscosity local to spheroids in suspension culture

The second scenario tested as a proof-of-concept, was to acquire 3D images and

microrheology measurements near spheroids in suspension culture. Spheroids were grown

from the same MCF-7 cancer cell line as in the peptide hydrogel cultures and were used two

days after seeding at a size of ~1 mm in diameter. As both 3D imaging and microrheology

on OptoRheo do not involve moving the sample, these spheroids could be maintained in

liquid media without the need to immobilise them in agarose or any other hydrogel matrix –

an advantage over most conventional LSFM instruments. Volume images near the edges of

spheroids were acquired by tiling multiple overlapping imaging volumes of 200 µm x 200 µm

x 200 µm (between 150 µm – 350 µm from the coverslip) (Fig 6A). Once the images were

acquired, the instrument was switched from LSFM modality to 3D particle tracking mode by

sliding the quadratic gratings into the optical path and with illumination in transmission (QG

in Fig 1). The optical trap enabled microsphere probes to be individually trapped and

positioned in 3D with the XY stage and the piezoelectric objective scanner to make

measurements at selected locations near the edge of the spheroids (Fig 6A inset).

Our measurements show an apparent increase in relative viscosity with decreasing distance

(4 μm, n = 4; 6 μm, n = 4; 12 μm, n = 3 and 30 μm, n = 7) between the centre of the

microsphere and the surface of the spheroid (n = 2 spheroids) (Fig 6A, 6B and 6C).

Viscosities could be extracted in 3D by resampling the recorded 3D trajectories along any

desired axis, calculating the MSD, and then using Fick's Law (see methods). Such angle-by-

angle analysis reveals higher relative viscosity values perpendicular to the surface of the

spheroid as compared to parallel to the surface, with the anisotropy increasing as the probe

approaches the surface (Fig 6B). This trend is in agreement with predictions from Faxén's

law which describes the increased hydrodynamic drag experienced by objects near solid

surfaces and manifests itself as an increase in apparent viscosity, albeit our measured

values are lower than the predictions [42] (dashed black line in Fig 6C). The lower values could

potentially be attributed to the spheroid surface being irregular and not completely inelastic.

Additionally, the presence of salts in the nutrient medium may screen charge-charge

interactions between the microsphere probes and the cell surface, reducing the force

required to move the probe closer to the spheroid surface [43] as corroborated by control

measurements at corresponding distances from the inert glass coverslip in the same

medium without the presence of the spheroids (red line in Fig 6C).

Figure 6: **Viscosity near spheroid**. A. 3D rendering of a section of a spheroid of MCF-7

cells expressing td-Tomato (relative dimensions: 200 μm x 400 μm x 100 μm (150-250 μm

from the coverslip)). The inset shows one of the areas where viscosity (relative to the

solvent) measurements were acquired at incremental distances from the spheroid surface –

three measurements (4 μm, 12 μm and 30 μm from the spheroid surface) are depicted as

spheres (not to scale). The colour gradient for each sphere represents the relative viscosity

sampled by angle at each measurement position. A fourth position (6 μm) has not been

shown to aid visualisation. B. Relative viscosity measurements in a plane perpendicular to

the spheroid surface, passing through the highest and lowest measured viscosity at the

probe position. C. Mean ± standard deviation of relative viscosity measurements of the

nutrient media at each position for a direction perpendicular to the spheroid surface (blue)

and glass (red), showing increased apparent viscosity at positions closer to the surface but

lower than values predicted from Faxén's law (black dashed line).

Discussion

To understand how cells interact with and remodel their surrounding matrix, it is crucial not only to visualise cell clusters in 3D, but also to map these images to the changing micro-mechanical properties of the matrix local to and distant from the cells. In this study, we have introduced an integrated instrument – OptoRheo, that combines light sheet fluorescence microscopy (LSFM) with non-invasive microrheology to enable a more complete understanding of cell-matrix interactions. The new LSFM configuration presented here is straightforward to implement and does not require the use of bespoke, expensive optics. This reflected configuration allows for samples to be prepared and mounted as on any commercial inverted microscope, using off-the-self sample chambers and a stage-top incubator to control temperature, humidity and CO_2 throughout experiments, enabling delicate hydrogel-based cell culture samples to be studied over multiple days. With the ability to optically trap microrheological probes when required, we have demonstrated the capability of the instrument to study aqueous (suspension culture) as well as soft solid (hydrogel) environments. This modular functionality with a gratings-based approach allows OptoRheo to transition from 2D to 3D particle tracking without difficulty. We provide experimental evidence of this approach by following changes in matrix viscoelasticity in 2D in hydrogel-encapsulated cell cultures over three days and viscosity in 3D near spheroids in suspension. Our localised rheological measurements reveal heterogeneities at the microscale in hydrogel-encapsulated cell cultures.

OptoRheo provides broadband microrheology measurements, covering 5 - 6 decades of frequency in our data. These broadband measurements provide valuable insight into the frequency-dependent mechanical properties of biological materials. As can be seen in Figure 5, OptoRheo is sensitive to mechanical changes arising from changes in matrix composition and from cell-driven re-organisation of the local environment, detectable over a broad range of frequencies. This is in contrast to Brillouin scattering – another emerging technique that is

being used to quantify the mechanical properties of biological systems [44], but which is limited

to a narrow range of frequencies in the gigahertz regime. It is possible that the narrow

frequency range of Brillouin scattering measurements will miss some of the mechanical

changes we report here. Furthermore, compared to previously published methods for optical

trapping based stiffness measurements [45,46], OptoRheo can characterise samples at depths

of hundreds of microns from the coverslip making it particularly suited to cell cultures grown

in 3D. OptoRheo has the additional benefit that the mechanical characterisation is paired

with multi-channel 3D fluorescence light sheet imaging allowing the changing morphology of

the cells to be monitored at the same time.

Extending the rheological measurements to 3D and sampling viscosity in 360 °, as shown in

our experiments with spheroids in suspension (Fig 6B), increases the capability of our

measurements to extract heterogeneities, not just between probe positions, but for different

directions at a single probe position. Currently, this 3D approach is restricted to computing

viscosity in liquids due to limited spatial sensitivity when tracking probe position in z

(Methods). This is not an issue when the extent of the Brownian motion of the probe is large,

such as the ~1 μm (Fig 4B) observed in a weak optical trap in suspension culture, but is of

concern when motion is very small ($\leq$ 50 nm) such as that observed in stiff gels (Fig 3B). In

future, the sensitivity and measurement range of the 'sharpness' metric used for particle

tracking in z could be tuned by changing the plane spacing selected with the multiplane

grating pair, the probe size, the illumination levels and the signal to noise ratio of the images

[25]. Efforts to extend these 3D analyses to gels in the future would be highly valuable as

biophysical properties in the ECM are likely to vary in 3D, as apparent in the images of

labelled collagen present in the gel samples (Fig 5B).

The outputs from these proof-of-concept experiments are very data-rich. Different locations

of interest in the sample can be programmed to be revisited multiple times over a multi-day

experiment. As such, OptoRheo enables researchers to track numerous variables over time,

so that the relative cell and probe position, and cell behaviour (change in shape or size,

migration, apoptosis) can be related to viscous and elastic components of the matrix

biophysical properties. In future, it would be relatively straight forward to include additional

probes into the sample (either genetically engineered reporters in the cells or sensors

embedded in the gel/ matrix) to track the coordinated impact of chemical, biological and

mechanical cues.

As highlighted in recent publications [4,47], the control of cell behaviour by mechanical forces

exerted through the ECM remains poorly understood, even as researchers take advantage

of ECM control to create more complex, physiologically relevant models of development and

disease, that better represent the *in vivo* micro-environment. The ability to integrate read-

outs of cell behaviour with the microrheology of pericellular and distant matrix will be critical

in further improving these models and using them to uncover the mechanistic basis of the

phenomena they imitate. In addition, for development of therapeutics, there remains a

significant gap in our understanding of the environments that drugs and delivery vehicles

encounter in the body. The simultaneous observation of material transport together with

rheological measurements will enable us to build detailed structure-function relations of drug

delivery pathways, which in turn, will enable more efficient screening of candidate

therapeutics and better predictive models of *in vivo* activity and efficacy.

Online Methods

Light sheet fluorescence microscopy (LSFM)

OptoRheo uses a reflected light sheet configuration where light sheet illumination is

introduced into the imaging plane of an inverted microscope (Olympus IX-73) using a right-

angle optic (90:10 RT beam splitter cube, 10 mm; Thorlabs Inc.). Z-scanning was achieved

by moving the light sheet through the sample using a galvanometer scanning mirror

(dynAXIS 3S; SCANLAB Gmbh) whilst simultaneously moving the

objective lens (LUMFLN60XW 60x 1.1 NA 1.5 mm WD; Olympus) via a

motorised piezo objective scanner (P-725.4CD; Physik Instrumente Ltd.) to keep the light

sheet in focus. Lateral positioning was achieved using a XY microscope stage (MS-2000,

ASI) and a zoom-mount attached to the cylindrical lens forming the light sheet. The

fluorescence image was detected using an sCMOS camera (Hamamatsu ORCA Flash 4.0

V2). Environmental control was achieved using an Okolab stage-top incubator (H301-K-

FRAME) supplied with pre-mixed CO_2 gas.

Multi-colour fluorescence imaging was made possible by using three lasers separately to

form the light sheet; 473 nm (SLIM-473; Oxxius), 532 nm (BWN-532-2OE; B&W Tek) and

640 nm (OBIS; Coherent). These laser lines were coupled to each other in the illumination

beam path using dichroic mirrors. A cylindrical lens (f = 50 mm, Thorlabs) was used to

generate the light sheet with a beam waist of 2.6 μm for λ_{ex} 473 nm, 2.4 μm for λ_{ex} 532 nm

and 3.3 μm for λ_{ex} 640 nm. The light sheet was aligned and characterised by imaging it in

reflection using two beam splitters (90:10 RT beam splitter cube, 5 mm; Thorlabs Inc.) in

tandem. The relationship between voltage applied to the galvanometer mirror and position of

the light sheet was characterised using this double beam splitter set up and keeping the

detection objective stationary while scanning the light sheet in z. The slope of the linear fit to

the measured position of the light sheet against the voltage applied gave the pixel to voltage

step size for synchronised movement.

When imaging samples, an autofocus step is first performed to ensure the illumination and

detection optics, primarily the objective, are aligned. This involves recording a stack of

images while keeping the imaging objective stationary and scanning the light sheet with a

sub-beam-waist step size. The frame with the highest mean intensity value denotes where

the light sheet waist coincides with the imaging plane and so the position of the light sheet

for this frame is synchronised with the height of the objective.

Standard off-the-shelf beam splitter cubes have a blunt edge that make the bottom 150 μm

unsuitable for reflecting the light sheet illumination. These regions can be illuminated by

tilting the light sheet at BS1 (Fig 1) or by using a bespoke cube with a sharp edge.

The mechanical components of the OptoRheo including the light sheet parts were controlled

in LabVIEW (2018, 64bit; National Instruments Inc.). Image volumes were saved as '.tiff'

files. Automation of the laser lines through camera-controlled remote triggering and a

motorised filter turret enabled overnight time lapse imaging.

Image processing

Contrast adjustment and background subtraction was performed on image volumes in

ImageJ/ Fiji [48] and volume tile stitching was performed using the BigStitcher [49] plugin for Fiji.

3D rendering for Figure 6A was done in FluoRender (v 2.26.3) [50] and for Figure 2B was done

in Imaris (10.0.0, Oxford Instruments).

To calculate the distance between microspheres and the nearest cell clusters, the centre

positions of the microspheres in image coordinate space were extracted from the LSFM

images. Although the microspheres (Polybead® Microspheres 6.00 μm; PolySciences) were

not fluorescently labelled, they are identifiable in the 3D LSFM images due to light scattering.

Mesh renderings of the corresponding cell clusters were exported from FluoRender and

these meshes along with positions of the microspheres from the same image volume were

used as inputs in the point2trimesh.m [51] code in MATLAB which computes the shortest

distance between a given point and the outer edge of a triangular mesh.

Figures 5C and 5D and the inset within 6A were prepared in MATLAB using mesh

renderings generated in FluoRender overlaid with rendered spheres to depict the

microsphere probes with a colour gradient to show the low frequency plateau in the elastic

modulus (G_0') (Fig 5C and 5D) or viscosity (Fig 6A inset) at each probe.

Optical Tweezers

The beam path from a continuous wave 1064 nm 5 W DPSS laser (Opus, Laser Quantum)

was directed into the inverted microscope body and focused in the image plane using the

same objective lens used for imaging in the LSFM set up. This objective lens was also used

to image a small region of interest (14 µm x 14 µm), required for high frame rate imaging,

around the trapped polystyrene microspheres in wide-field with illumination in transmission

for fast (300 Hz for multiplane 3D rheology) tracking of thermal fluctuations.

Multiplane detection

3D imaging of the microrheology probes was made possible by multiplane detection similar

to the OpTIMuM instrument [25] and its predecessors [33,52]. Here, a multiplane grating pair was

formed using two quadratically distorted diffraction gratings etched into a quartz substrate

(bespoke production by Photronics UK Ltd). A single grating generates three sub-images,

corresponding to the m = 0, ± 1 diffraction orders while two gratings with orthogonal etch

patterns, can generate nine different sub-images, each corresponding to a different image

depth which can be captured simultaneously on a single camera sensor (Hamamatsu ORCA

Flash 4.0 V2) (Fig 4A). A 4f image relay system consisting of two 300 mm lenses was set up

in the detection path between the camera and the inverted microscope body to enable the

multiplane grating pair to be placed in the telecentric position. This set up ensured a

consistent level of magnification in each of the imaging focal planes. The grating is on a

slider and easily removable allowing the user to switch between standard full field of view

imaging and multiplane imaging of a small region of interest with no adverse side effects. In

our system we have used a relay and grating combination that gives plane separation of Δz

= 0.79 μm with the nine images spanning 7.11 μm, designed to show the extent and position

of our 6 μm diameter probe. Grating combinations can be chosen to suit the diameter of the

probe such that the total span in z covers the extent of the trajectory of the probe with the

minimum plane separation for optimal resolution [25].

Microrheology

Particle tracking microrheology was performed using polystyrene microspheres as probes

(Polybead® Microspheres 6.00 μm diameter; PolySciences). In hydrogel cultures, the

microspheres were encapsulated during the gelation process at a final density of 3×10^5

particles/ mL. In suspension cultures, the microspheres were added to a final dilution of

1:200,000 from concentrate product, the probes were individually optically trapped using ~4

mW of laser power (at the sample) and moved to a position of interest. The Brownian motion

of the microspheres, was recorded over 300,000 frames at ~300 frames per second for

experiments in Figures 4 and 5, and for 1.5×10^6 frames at 5 kHz for Figure 3 and the

measurements depicted in the time lapse videos (VS1 and VS2) using OptoRheo with

illumination in transmission from an LED light source (Fig 1). Videos of the microsphere

probes were acquired using Micro-Manager (version 1.4) [53] and Micro-Manager (version 2.0)

for Figure 3 and the measurements corresponding to the time lapse videos.

The time-dependent trajectories of the microspheres were extracted from these videos in

MATLAB (2019b; MathWorks, Nattick, MA). For 2D trajectories along the image plane a

centre-of-mass detection method following Otsu's method of multiple thresholding (with two

levels) was used. Out-of-plane Z motion of the probe was tracked by computing a

'Sharpness' metric as detailed in our OpTIMuM publication [25]. Particle tracking with these

methods gives us a minimum sensitivity of ~ 15 nm (FWHM) in the xy plane and ~ 30 nm

(FWHM) in z for a particle with diameter of ~ 6 µm, using a 60x objective and a plane

spacing of ~ Δz = 0.79 µm [25]. A calibration step is performed for each microsphere before

taking a measurement by translating a lens (L4 in Fig 1) in the beam expander in the optical

path as described previously [25].

In the case of hydrogels, the Brownian motion of the microsphere confined within the gel

was recorded in 2D without the use of the optical trap or multiplane imaging. For these data,

an analysis of the mean squared displacement (MSD) gave the storage (elastic) and loss

(viscous) moduli of the gel. To acquire the viscoelastic measurements for each probe, first

each experimentally acquired trajectory was detrended to remove long-term drift and a

filtering step was performed to remove instrument noise. For the noise filtering, a Fourier

transform of each trajectory was used to identify sharp noise peaks characterised by a single

frequency width and using an amplitude threshold of 2×10^{-10} m. These noisy peaks,

attributed to electrical noise from the laboratory, were then removed from the data using a

custom multiband filter in MATLAB. The MSD values for each filtered trajectory was then fit

with a stretched bi-exponential of the form

585
$$MSD(t) = \left(A_1\, exp\left(-\left(\frac{t}{\tau_1} \right)^{B_1} \right) \right) + \left(A_2\, exp\left(-\left(\frac{t}{\tau_2} \right)^{B_2} \right) \right) \tag{1}$$

586 A_1, A_2, B_1, B_2, τ_1 and τ_2 are fitting parameters. This approach mitigates any error generated

587 by the inherently finite nature of the measurements that affects the accuracy to which the

588 MSD is calculated especially at short-time scales (Fig 3). The MSD relates to the gel's time

589 dependent compliance J(t) [54] as follows,

590
$$MSD(t) = \frac{k_B T}{\pi a} J(t) \tag{2}$$

591 where k_B is the Boltzmann's constant, T is the absolute temperature, and a is the radius of

592 the microsphere. The materials' complex shear modulus can be computed from the

593 materials' compliance by means of its Fourier transform ($\hat{J}(\omega)$)

$$594 \qquad G^*(\omega) = \frac{1}{i\omega \hat{J}(\omega)} \; . \qquad\qquad (3)$$

We used a new MATLAB based graphical user interface named π-Rheo (see code

availability statement) for evaluating Equations 2 & 3, to compute the Fourier transform of

the particles' MSD and the materials' complex modulus for passive microrheology

measurements. π-Rheo is underpinned by the algorithm introduced in i-RheoFT [55]. The real

and imaginary parts of the complex modulus give the elastic ($G'(\omega)$) and viscous ($G''(\omega)$)

moduli of the gel.

The elastic plateau of the gels G'_0 (equivalent to $G'(\omega)$ at low frequencies) can be calculated

simply from the particles' time-independent variance $\langle r^2 \rangle$ using the formula:

$$604 \qquad G'_0 = \frac{k_B T}{\pi a \langle r^2 \rangle} \qquad\qquad (4)$$

For aqueous solutions, where 3D positions of the probe are tracked, the viscosity may be

extracted by fitting an exponential decay against the normalised position autocorrelation

function [35]. This method is highly effective for data aligned with the principal axes of the

optical trap (see Fig 4D). However, when calculating viscosity along vectors not aligned with

these axes using this method, the significant trap anisotropy along the z-axis introduces

artefacts as outlined in detail previously [56]. Alternatively, if the material under investigation is

purely viscous, then at very early times the MSD of the bead should behave as if the bead is

not trapped. Under these conditions, Fick's Law for unconstrained diffusion can be used to

extract viscosity in any arbitrary direction rather than just x, y, z at these early times. Fick's

law for motion in 1D is given by,

$$615 \qquad MSD_{(t,\theta,\varphi)} = 2D_{(\theta,\varphi)} t \qquad\qquad (5)$$

616 where θ and ψ define the direction being probed and D is the diffusion coefficient for a

617 sphere of radius a in a liquid with viscosity η. From the Stokes-Einstein relation

$$618 \qquad D = \frac{k_B T}{6\pi \eta_{(\theta,\varphi)} a} \; . \qquad\qquad (6)$$

619 This approach was used to compute viscosity in 3D as shown in Figure 4E and Figure 6A.

Cell culture

The breast cancer cell lines MCF-7 and MDA-MB-231 expressing tdTomato or eGFP were

produced by lentiviral transduction of cells originally obtained under MTA from NCI as part of

the NCI-60 panel. These cell lines were maintained in high glucose DMEM (MCF-7

tdTomato; Life Technologies, 21969-035) or phenol red free RPMI (MDA-MB-231 tdTomato

and MCF-7 eGFP; Sigma, D5671) with 10 % foetal bovine serum (Life Technologies, 10500-

064), 1 % L-glutamine (Life Technologies, 25030-024). To maintain the tdTomato protein

expression, the medium was supplemented with Puromycin (Gibco, A11138-03) at 1:1000

every passage (MCF-7 tdTomato) or every 3 weeks at 1:500 (MCF-7 eGFP) or 1:250 (MDA-

MB-231 tdTomato). Cells were maintained at 37 °C and 5 % CO_2 in a humidified atmosphere

during cell culture and measurements on the OptoRheo. All cell lines were subjected to

monthly mycoplasma testing and none of the lines used in this study tested positive at any

point.

Peptide gel precursor preparation

The precursor and gel preparation method was followed as previously published [57]. A

commercially available peptide preparation in powder form was used as the source of the

octapeptide gelator (Pepceuticals UK, FEFEFKFK, Phe-Glu-Phe-Glu-Phe-Lys-Phe-Lys). To

form the precursor, a mass of 10 mg peptide preparation was dissolved in 800 µL sterile

water (Sigma, W3500), using a 3 min vortex step followed by centrifugation (3 min at 1000

rpm) and a 2 hour incubation at 80 °C. After incubation, 0.5 M NaOH (Sigma, S2770) was

added incrementally to the gel until optically clear. The gel was vortexed, buffered by

addition of 100 µL 10x PBS (Gibco, 70011), and incubated at 80 °C overnight. The resulting

precursor could be stored at 4 °C until required.

Peptide gel formation with collagen I supplementation

Prior to peptide gel formation, the precursor was heated at 80 °C until liquid to ensure

homogeneity, before transferring to a 37 °C water bath. Cy5 labelled (in-house preparation,

see method below) rat tail Collagen I was neutralised directly before use with 1 M NaOH

according to manufacturer instructions, and diluted with sterile water and 10x PBS to a

concentration of 1 mg/ mL while keeping on ice at all times to prevent polymerisation.

Peptide gel formation was then induced by pH neutralisation on addition of cell culture

medium (with or without cell suspension) to the gel precursor. A final volume of 1.25 mL was

obtained from a preparation by adding 125 µL of cell suspension and 125 µL Cy5 collagen I

to a precursor volume of 1 mL. The end concentration of peptide preparation was 8 mg/ mL

and collagen I concentration was 100 µg/ mL. Polystyrene microspheres (Polybead®

Microspheres 6.00 µm; PolySciences) were added at final density of approx. 3×10^5

particles/ mL. The medium / cell suspension was thoroughly mixed with the precursor and

Collagen-I by gentle (reverse) pipetting, before plating at 100 µL per well into a 4 µ-well

glass bottom chambered coverslips (IBIDI, 80427) pre-mounted with a beamspliter cube

(ThorLabs, BS070). The wells were then flooded with cell culture medium and incubated at

37 °C and 5 % CO_2 in a humidified atmosphere. Sequential media changes (at least two)

over the next 2 hours ensured complete neutralisation and therefore gelation.

For cell encapsulation, the 125 µL volume of cell culture medium was prepared as a cell

suspension at 10x the intended final seeding density, to allow for the dilution factor on mixing

with the gel precursor. Trypsin-EDTA (0.25%; Life Technologies, 25200056) was used to

detach cells from 2D culture at sub-confluence. 1.25×10^5 cells were re-suspended in 125

µL cell culture medium, giving final seeding density in the peptide gel 1×10^5 cells/ mL. For

data in Figure 2B, a co-culture of MCF-7 (eGFP) and MDA-MB-231 (tdTomato) were at a

final seeding density of 1×10^6 cells/ mL for each cell type. 24 hrs post encapsulation culture

medium was replenished, with the addition of HEPES buffer (Life Technologies, 15630-056)

at 10 mM final concentration and 0.5 - 1 % penicillin/ streptomycin (Gibco, 15140122).

Prior to casting the gel, the beam splitter cubes were sterilised in absolute ethanol. Cubes

were soaked for 1 hour, then left to dry on a paper tissue inside the class 2 safety cabinet.

To minimise movement and consequently damage to delicate structure of a hydrogel, the

cubes were secured in place with glass coverslips.

Collagen labelling with Cy5

Rat tail collagen type 1 solution (10 mL; Gibco, A1048301) was mixed with 0.1 M sodium

bicarbonate buffer (10 mL, pH 8.5) and 110 µL Cy5 NHS ester solution (10 mg/ mL, DMSO)

added. The reaction mixture was stirred at 4 °C overnight. The reaction mixture was purified

via the dialysis method at 4 °C to remove the unreacted dye and yield the Cy5 labelled

collagen. It was then lyophilised and reconstituted in 20 mM acetic acid buffer.

Spheroid preparation

Corning 7007 Ultra-low attachment (ULA) 96-well round-bottom plates were used to culture

the 3D spheroids. 80 % confluent tdTomato MCF-7 monolayer cells were detached,

collected and the cell number determined using an automated cell counter (Biorad TC20). A

single-cell suspension was diluted in culture medium and cells seeded at 6000 cells/ well to

generate the spheroids (final volume of cell suspension in each well was 100 µL). The plates

were then centrifuged at 300 RCF for 5 min and cultured for 3 days until visible spheroid

formation.

For experiments on the OptoRheo, spheroids were placed in 4 µ-well glass bottom

chambered coverslips (IBIDI, 80427) using a P1000 pipette with the pipette tip cut off at the

end. Each spheroid was placed alone in 500 μL of phenol red-free culture media (1:1

DMEM:F12 supplemented with 10% FBS), ~ 5 mm away from the edge of a 10 mm beam

splitter cube (ThorLabs, BS070) (Fig S1A) in each well to enable LSFM imaging. Similar to

the peptide gel sample preparation protocol, beam splitter cubes were sterilised between

uses and secured in place in the chambered coverslips by wedging glass coverslips

between the cube and the chamber side wall.

Time lapse experiment

Time lapse videos were generated of MDA-MB231 cells expressing tdTomato fluorescent

protein seeded in peptide gel and supplemented with unlabelled collagen type I (Gibco,

A1048301) and bead probes (Polybead® Microspheres 6.00 μm; PolySciences). TrypLE

(Gibco, 12604) was used to detach cells from 2D culture at sub-confluence. The gels were

prepared in ibidi 4-well chambered coverslips with a beam splitter cube inserted at one end,

similar to the gel rheology experiments described above but with final cell seeding density

increased to 2×10^6 cells/ mL for video VS1 and 1×10^6 cells/ mL for video VS2, collagen I

increased to 150 μg/ mL and bead density increased to 3×10^5 / mL for samples in both

videos. The samples were kept at 37 °C and supplied with humidified 5 % CO_2 using cell

culture incubators prior to imaging and then the Okolab stage-top incubator during the

experiment.

Single channel image volumes were acquired at 10 minute time intervals with light sheet

illumination at 532 nm using an automated LabVIEW program on the OptoRheo. Acquired

image volumes were subjected to 3D deconvolution using the Wiener Filter Preconditioned

Landweber (WPL) method in the Parallel Iterative Deconvolution plugin in Fiji. The 4D videos

were rendered in Imaris (10.0.0, Oxford Instruments).

The time lapse videos were halted at regular intervals to acquire microrheology

measurements within the same field of view by recording the Brownian motion of 6 µm bead

probes at 5 kHz for 1.5×10^6 frames. The bead trajectories were analysed as described in

the microrheology section above and depicted as spheres (to scale) in the videos by creating

volume objects in a separate colour channel with a colour shade corresponding to the local

measurement at the time.

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Competing Interests

The authors declare no conflicts of interest.

Supplementary Information

1. Sample preparation

Fig S1: Sample set up: A. Side view of the 4 μ-well chambered coverslip with a 10 mm

beam splitter cube inserted with the reflective surface facing the empty half of the chamber.

B. Top view of a sample with the gel cast next to the beam splitter cube. C. Side view of the

peptide hydrogel topped up with medium next to the beam splitter cube.

2. Light sheet properties

Fig S2: Lateral (left) and axial (right) point spread functions (PSFs) of the system along the

XY (0.36 μm FWHM) and YZ (1.09 μm FWHM) planes measured using fluorescent sub-

diffraction sized microspheres (diameter = 200 nm, λ_{ex} / λ_{em} = 532 nm / 580 nm) at ~200 µm

from the coverslip.

Supplementary videos:

VS1: **MDA-MB-231 (tdTomato) cells changing morphology** in 3D within a hydrogel

matrix supplemented with collagen I (unlabelled). The video was acquired over ~7 hours with

a 10 min time interval between frames. Changes in ECM rheology and cell morphology

appear related as a more compliant gel at the start of the video (see table S1 below)

precedes cell elongation while an increase in stiffness around 6 hours into the experiment

corresponds with a retracted cell morphology.

Time	Measurement location 1 (G_0' [Pa])	Measurement location 2 (G_0' [Pa])	Measurement location 3 (G_0' [Pa])
0 min	2.3×10^{-2}	2.0×10^{-2}	1.5×10^{-2}
120 min	1.5×10^{-2}	0.7×10^{-2}	0.4×10^{-2}
240 min	1.2×10^{-2}	2.2×10^{-2}	3.2×10^{-2}
360 min	20.2×10^{-2}	22.9×10^{-2}	24.0×10^{-2}

Table S1: Microrheology measurements depicted in supplementary video VS1 clockwise

from bottom over the time course of the experiment.

VS2: **MDA-MB-231 (tdTomato) cells migrating** in 3D within a hydrogel matrix

supplemented with collagen I (unlabelled). The video was acquired over 4 hours with a 10

min time interval between frames. Rheology measurements showed a more compliant

region (2×10^{-2} Pa) near (~ 50 µm) the migratory path depicted as a dark pink sphere as

opposed to farther away (6×10^{-2} Pa at ~80 µm away) depicted as a bright pink sphere.