

1 Auditory spatial analysis in reverberant audio-visual multi-talker
2 environments with congruent and incongruent visual room information

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4 Axel Ahrens

5 Hearing Systems Section, Department of Health Technology, Technical University of Denmark,

6 2800 Kgs. Lyngby, Denmark

7 aahr@dtu.dk

8

9 Kasper Duemose Lund

10 Hearing Systems Section, Department of Health Technology, Technical University of Denmark,

11 2800 Kgs. Lyngby, Denmark

12 kasperduemose@gmail.com

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20 Date: 13 February 2022

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22 Running Title: Auditory scene analysis

23 Abstract

24 In multi-talker situation, listeners have the challenge to identify a target speech source out of a
25 mixture of interfering background noises. In the current study it was investigate how listeners
26 analyze audio-visual scenes with varying complexity in terms of number of talkers and
27 reverberation. Furthermore, the visual information of the room was either coherent with the
28 acoustic room or incoherent. The listeners' task was to locate an ongoing speech source in a
29 mixture of other speech sources. The 3D audio-visual scenarios were presented using a
30 loudspeaker array and virtual reality glasses. It was shown that room reverberation as well as the
31 number of talkers in a scene influence the ability to analyze an auditory scene in terms of accuracy
32 and response time. Incongruent visual information of the room did not affect this ability. When
33 few talkers were presented simultaneously, listeners were able to quickly and accurately detect a
34 target talker even in adverse room acoustical conditions. Reverberation started to affect the
35 response time when four or more talkers were presented. The number of talkers became a
36 significant factor for five or more simultaneous talkers.

37

38 Keywords: Speech perception; Virtual Reality; Localization

39

40 I. Introduction

41 The human auditory system has the ability to focus on a speech stream in the presence of
42 interfering speech stimuli. Such a multi-talker scenario has been termed the cocktail-party situation
43 (Bronkhorst, 2000; Cherry, 1953). Many factors are known to reduce the ability to understand
44 speech in such a cocktail-party situation, e.g., the level of the target speech relative to the
45 interferers, the number of talkers, or the type of listening room. These effects are commonly
46 measured by asking the listeners to repeat a word or a sentence or to write down the perceived
47 stimulus. However, in our daily life the task in a cocktail-party situation is usually different, where
48 it is necessary to follow a conversation and to identify a certain topic or continuous speech stream
49 out of an interfering speech mixture. In the current study we investigated the ability of listeners to
50 analyze an acoustic scene with varying complexity in terms of number of interfering talkers, room
51 reverberation and coherency of visual room information.

52 The number of interfering talkers has been shown to influence the intelligibility of a target talker.
53 (S. A. Simpson & Cooke, 2005) showed that the intelligibility decreases when increasing the
54 number of interfering speech sources for up to eight interfering talkers, as the ability to listen into
55 speech gaps is reduced and at the same time the interfering speech remains intelligible and can be
56 confused with the target speech. When further increasing the number of interfering talkers, the
57 intelligibility was shown to improve as the interferers become more noise-like and therefore do
58 not contain understandable speech.

59 Reflections and reverberation are present in nearly all communication scenarios. Room
60 reverberation has been shown to negatively affect speech perception in a number of studies (Best
61 et al., 2015; Bronkhorst & Plomp, 1990; Moncur & Dirks, 1967; Nabelek & Mason, 1981; Nábělek
62 & Pickett, 1974). Particularly, the diffuse reverberation, i.e., the late reverberant tail, has been
63 shown to reduce speech intelligibility, while early reflections do not seem to harm, or might even

64 improve speech perception (Arweiler et al., 2013; Arweiler & Buchholz, 2011; Warzybok et al.,
65 2013).

66 Previous studies have investigated the ability of listeners to identify and locate speech in the
67 presence of other speech sources. (Kopčo et al., 2010) measured the localization accuracy of a
68 digit spoken by a female talker in the presence of words spoken by male interfering talkers. The
69 target and the interferers were all presented in the frontal area of the listener. They found that the
70 presence of the interferers reduced the localization accuracy. (Buchholz & Best, 2020) measured
71 localization accuracy with a similar target digit as in (Kopčo et al., 2010) but with a more realistic
72 background noise scene. The interfering signals were seven paired conversations (both male and
73 female) at various locations in a simulated cafeteria. Results showed that the localization accuracy
74 was only affected by the noise when the target source was distant but not when it was nearby. This
75 finding suggests an interaction with reverberation, as farther sources have more reverberant energy
76 relative to the direct sound compared to nearby sources.

77 While these studies focused on the ability to locate a speech signal in a speech background,
78 (Hawley et al., 1999) investigated both the localization accuracy of speech as well as the
79 intelligibility. They showed that the inability to correctly locate a source did not limit the ability
80 to correctly understand it. However, the number of interfering sources was limited to three.

81 (Weller et al., 2016) presented a novel method to evaluate the ability to analyze a complex acoustic
82 scene. They asked their listeners to judge the location of all talkers presented in a virtual cocktail-
83 party situation by indicating the gender of the talkers. When varying the number of simultaneously
84 presented talkers, they found that normal-hearing listeners were able to correctly locate and count
85 the number of talkers for up to four sources. When six talkers were presented, the accuracy
86 decreased.

87 Most of the beforementioned studies focused on the ability to localize speech but less to
88 comprehend the speech. However, in a real-world cocktail party, listeners need to perform both
89 tasks to successfully communicate. In the current study, we asked listeners to locate a talker
90 speaking about a certain topic, while presenting a varying number of other simultaneous talkers.
91 Thus, the primary task was to understand the speech and the secondary task to locate the talker.
92 The experiment was conducted in an audio-visual virtual environment using a loudspeaker array
93 and virtual reality glasses. The listeners' task was to indicate a semi-transparent avatar at the
94 location of an acoustic source talking about a topic indicated by an icon. The sources were located
95 at one of fifteen possible locations with 15° horizontal separation. The number of simultaneous
96 speech sources was varied between two and eight. Three virtual rooms were simulated visually
97 and acoustically. Furthermore, a condition with incongruent audio-visual cues was presented by
98 visually showing the anechoic room and acoustically presenting the reverberant room or vice
99 versa.

100

101 II. Methods

102

103 A. Participants

104

105 Thirteen Danish native speaking normal-hearing listeners aged 20-26 years participated in the
106 experiment (7 female and 6 male). Participants were paid on an hourly basis and gave consent to
107 an ethics agreement approved by the Science-Ethics Committee for the Capital Region of Denmark
108 (reference H-16036391).

109

110 B. Material

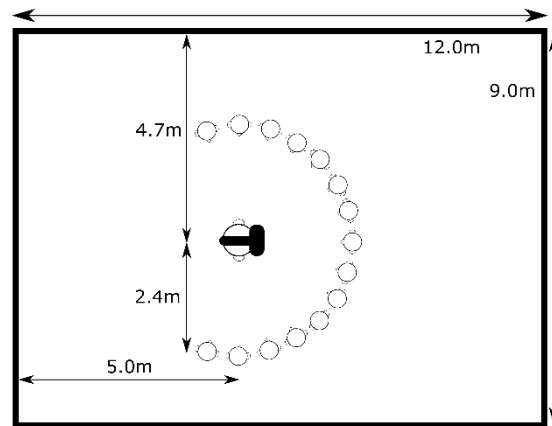
111
112 The speech material for target and interferers was taken from a database of anechoically recorded
113 monologues in Danish (see (Lund et al., 2019) for details¹). Each monologue was designed with
114 characteristic features in mind, ensuring significant difference of the content. The database consists
115 of ten monologues each spoken by ten native Danish speakers.

116

117 C. Audio-visual rooms

118
119 Three different acoustic and visual rooms were used in this study, a high-reverberant room, a mid-
120 reverberant room and an anechoic room. The dimensions of all three rooms remained constant as
121 shown in Figure 1, both acoustically and visually. However, the surface materials differed.

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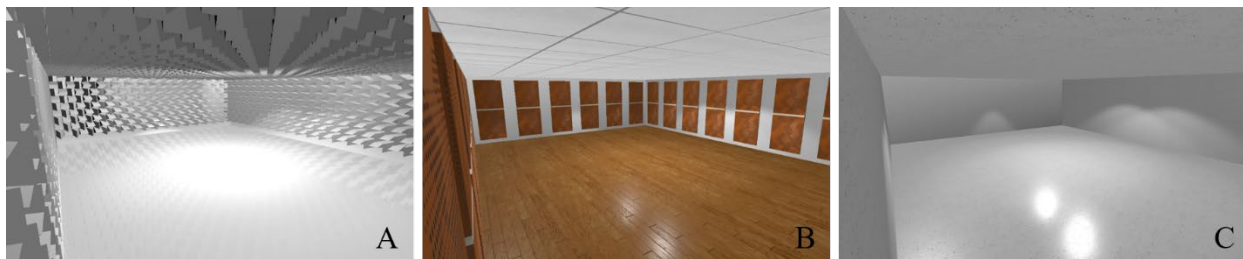
124 Figure 1: Top view of the virtual audio-visual room. The listener is wearing VR glasses with a
125 visual simulation of the room including 15 potential talker positions at 2.4m distance in the frontal
126 hemisphere visualized by the head icons. The height of the room is 2.8m.

¹ Data available: https://data.dtu.dk/articles/Recordings_of_Danish_Monologues_for_Hearing_Research/9746285

127

128 Figure 2 shows the visual appearances of the three rooms. Figure 2A shows the anechoic room
129 with foam wedges as commonly seen in anechoic chambers. For the acoustic reproduction of this
130 room only the direct sound was reproduced from single loudspeakers. In Figure 2B the mid-
131 reverberant room can be seen. The visual as well as the acoustical properties were similar to a large
132 living room. The highly reverberant room is shown in Figure 2C. It was modelled with bare
133 concrete surfaces to simulate a highly reverberant, yet realistic environment.

134



136 Figure 2: Visual appearance of the three virtual rooms. A: anechoic, B: mid-reverberant, C: high-
137 reverberant. The dimensions in the rooms are identical, while the surface materials differ.

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139 The rooms were simulated using the room acoustic simulation software Odeon (Odeon A/S, Kgs.
140 Lyngby, Denmark) with the materials and surface absorption coefficients as shown in Table 1. For
141 the anechoic room, only the direct sound was considered. In Figure 3 the reverberation time, clarity
142 and direct-to-reverberant ratio of the three rooms are shown. The reverberation time as well as the
143 clarity were calculated using the ITA-toolbox (Berzborn et al., 2017), the direct-to-reverberant
144 ratio was calculated as the ratio between the direct sound and the reflections. Mind that for the
145 anechoic condition the clarity and direct-to-reverberant ratio are infinite as no reflections are
146 present which is indicated with arrows.

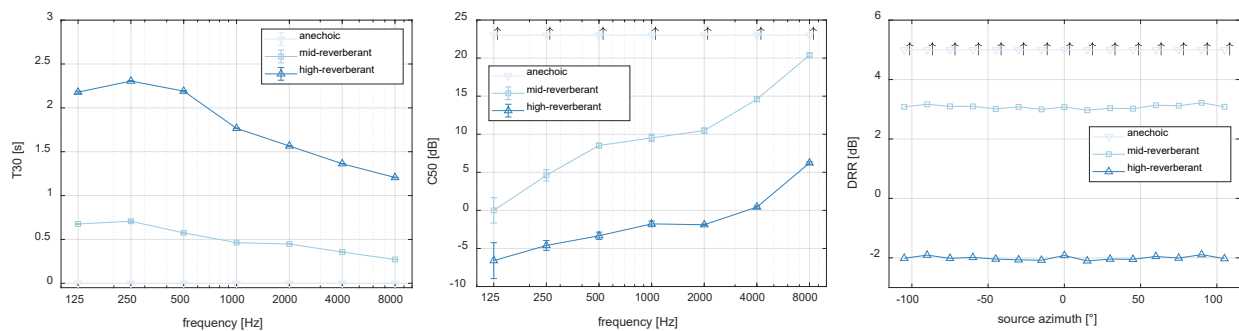
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148 Table 1: Absorption coefficients (α) of the surfaces in the mid-reverberant and high-reverberant room.

α (mid-rev/high-rev)	63 Hz	125 Hz	250 Hz	500 Hz	1 kHz	2 kHz	4 kHz	8 kHz
Side walls Wooden panels/Brick	0.2/0.06	0.2/0.06	0.2/0.06	0.3/0.07	0.4/0.07	0.4/0.07	0.5/0.08	0.5/0.09
Floor Parquet/Concrete	0.2/0.05	0.2/0.05	0.15/0.05	0.1/0.05	0.1/0.07	0.05/0.07	0.1/0.07	0.1/0.07
Ceiling Gypsumboard/Concrete	0.3/0.05	0.3/0.05	0.35/0.05	0.4/0.05	0.4/0.07	0.4/0.07	0.5/0.07	0.55/0.07

149

150



152 Figure 3: Reverberation time (T30), Clarity (C50) and the direct-to-reverberant ratio (DRR) for
 153 the three rooms. The T30 and the C50 are shown with respect to octave frequency bands. The DRR
 154 is shown with respect to the source azimuth angle. The arrows indicate that the measure is infinite.

155

156 D. Task

157

158 The listeners' task was to identify the location of a talker amongst concurrent talker(s) in a virtual
 159 audio-visual room according to the story in the monologue. Accuracy and completion time of the
 160 task was emphasized by advising the listeners to "find the correct story as fast as possible". The
 161 number of concurrent talkers varied between two and eight, thus the number of interfering talkers
 162 varied between one and seven. An icon visualizing the target story content was displayed on the
 163 backwall in the visual virtual room. The 15 possible talker positions were always represented by

164 semi-transparent humanoid shapes independent of the actual number of concurrent talkers. Figure
165 1 visualizes the possible talker locations between -105° to 105° separated by 15° in the frontal
166 hemisphere at a distance of 2.4 m. The task was performed by pointing at the position where the
167 target talker was perceived. The participants were using a virtual reality controller that included
168 the visual appearance of a laser pointer in the virtual room.

169 For each scene a unique talker, story and position was randomly chosen as the target. Between one
170 and seven masking talkers were included in a similar way. No talker, story or position could occur
171 twice at the same time. For each trial, the acoustic talkers were presented for 120 seconds. The
172 stories were started at a random point in time and were repeated from the beginning after finishing.
173 Thus, no bias towards the beginning of each story was introduced. The listener could indicate the
174 perceived target talker position at any time, even after the audio had stopped. Each individual
175 talker was presented at a sound pressure level of 55 dB SPL.

176 Three congruent audio-visual rooms were used as described above, an anechoic, a mid-reverberant
177 and a high-reverberant room. In addition to the conditions with congruent audio and visual room
178 information, two conditions with incongruent audio-visual cues were considered. These were
179 anechoic acoustics with the appearance of a highly reverberant room and high-reverberant
180 acoustics with the visuals of the anechoic room. Thus, five room conditions were tested. Each of
181 the conditions was repeated three times resulting in 105 trials, five audio-visual conditions and
182 between two and eight concurrent talkers.

183 Prior to the experiment, the listeners performed a familiarization phase, where they were
184 familiarized with the speech material and the story content but not with the task itself. The anechoic
185 version of the ten stories were played back via headphones in a randomized order. Each talker was
186 randomly assigned to one of the stories. Thus, listeners heard each story and each talker once. For

187 the training, listeners were instructed to focus on unique content features or passages of the stories.
188 After completed training listeners were seated in the loudspeaker environment and introduced to
189 the listening task and the interaction method using the VR controller.

190

191 E. Virtual audio-visual setup

192

193 The virtual visual scenes were rendered on the head-mounted display (HMD) of an HTC Vive Pro
194 Eye (HTC Vive system, HTC Corporation, New Taipei City, Taiwan). This system allowed to
195 track the listeners motion and record eye gaze and pupil dilation from inside the HMD with a
196 sampling frequency of up to 120 Hz and an accuracy between 0.5° and 1.1° . The visual virtual
197 scenes were modeled and displayed using Unity (Unity Technologies, San Francisco, California,
198 USA).

199 The acoustic scenes were reproduced on 64-channel spherical loudspeaker array housed in an
200 anechoic chamber (see (Ahrens, Marschall, et al., 2019) for details). The loudspeaker signals were
201 generated using the room acoustic simulation using the LoRA-toolbox (Favrot & Buchholz, 2010).
202 For the loudspeaker playback the nearest loudspeaker mapping was applied, where the direct sound
203 as well as the early reflections are mapped to the nearest loudspeaker. The late reverberant tail is
204 reproduced using 1st order ambisonics to achieve a diffuse acoustic field (Favrot & Buchholz,
205 2010).

206 F. Outcome measures and statistical analyses

207

208 To evaluate the listeners' ability to successfully analyze a cocktail-party scenario, two outcome
209 measures were evaluated. First, the ability to correctly identify and locate the target talker. This

210 allows for a binary right/wrong analysis as well as a localization error in degrees. Second, the
211 response time of the listener from audio onset to decision.

212 The outcome measures were analyzed using an analysis of variance of mixed linear models. The
213 computational analyses were done using the statistical computing software R(R Core Team, 2020)
214 and the lmerTest (Kuznetsova et al., 2017) package. Within factor analyses were conducted using
215 marginal means implemented in the emmeans package (Lenth, 2020) with Tukey correction for
216 multiple comparisons.

217III. Results

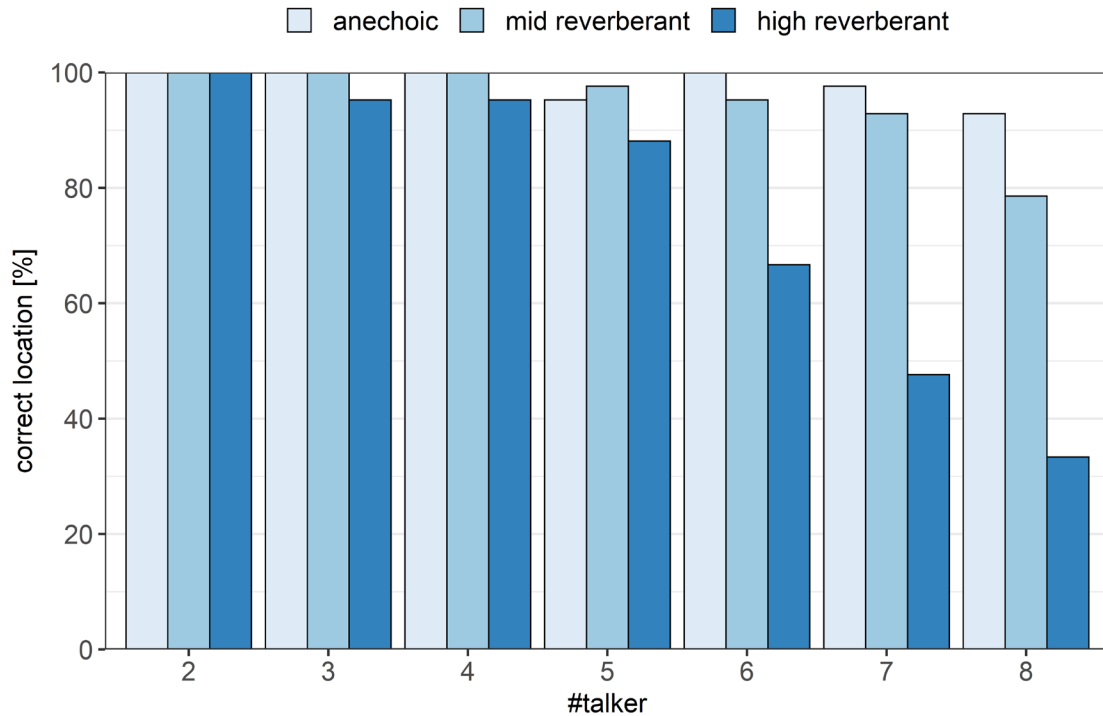
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219 A. Coherent audio-visual room information

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221 Figure 4 shows the percentage of correctly located stories. Each bar contains 42 datapoints across
222 the 14 participants and three repetitions. When few talkers are in a scene, the participants were
223 able to accurately locate the correct story in all reverberation conditions. In scenes with more than
224 five talkers, the accuracy in the high-reverberant condition (dark blue) decreases. In the mid-
225 reverberant condition such a decrease can only be observed when eight talkers are in a scene. In
226 the anechoic condition, the participants were able to accurately locate the target story for all
227 numbers of talkers.

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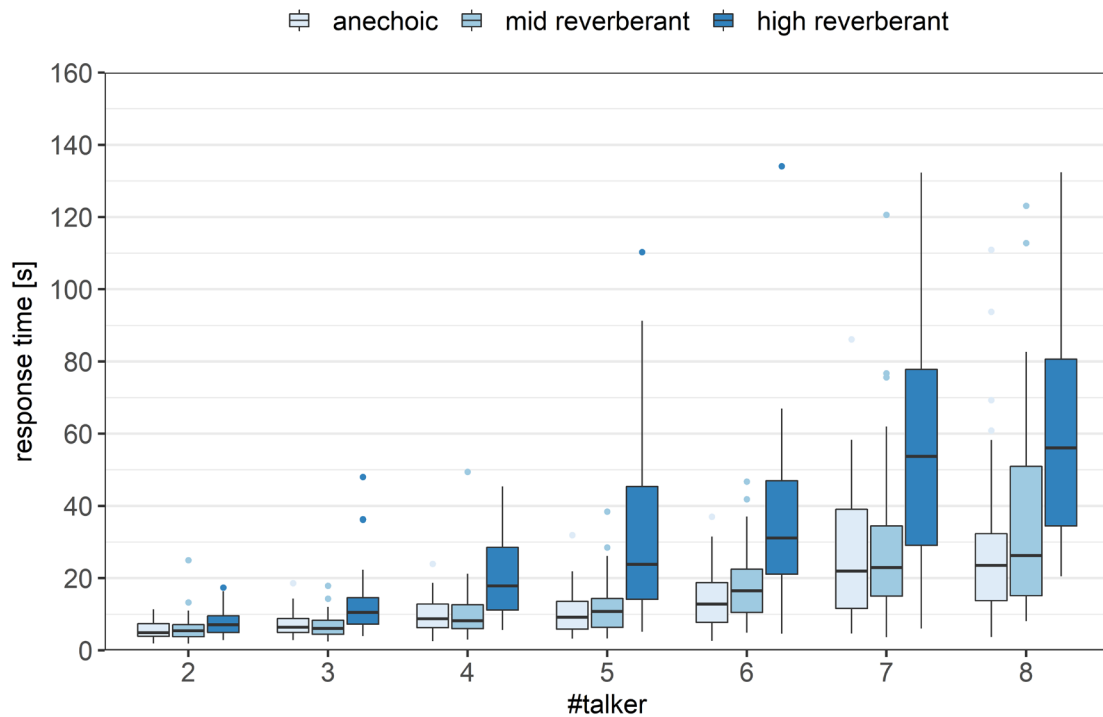
230 Figure 4: The percentage of correct response locations. Each bar contains 42 datapoints across
231 subjects and repetitions. The three colors indicate the room conditions.

232

233 Figure 5 shows the response time of the correct responses when two to eight talkers were presented
234 simultaneously. The response time is displayed for the audio-visually coherent room conditions
235 with varying reverberation times indicated with the different colors. With an increasing number of
236 simultaneous talkers, the time needed to identify the target talker increased [$F(6,755.2)=73.1$,
237 $p<0.0001$]. The response time was also found to be dependent on the reverberation time
238 [$F(2,755.6)=83.1$, $p<0.0001$]. Furthermore, the interaction term between the number of talkers and
239 the reverberation time was found significant [$F(12,754.8)=5.4$, $p<0.0001$]. Specifically, the high-
240 reverberant condition was found to lead to a higher response time when four or more talkers were
241 presented [$p<0.05$] but not with less than four talkers [$p>0.5$]. The differences between the high-
242 reverberant condition and the anechoic/mid-reverberant condition increases with larger numbers

243 of talkers. No significant differences between the anechoic and the mid reverberant condition was
244 found [$p > 0.1$] across all number of talkers.

245



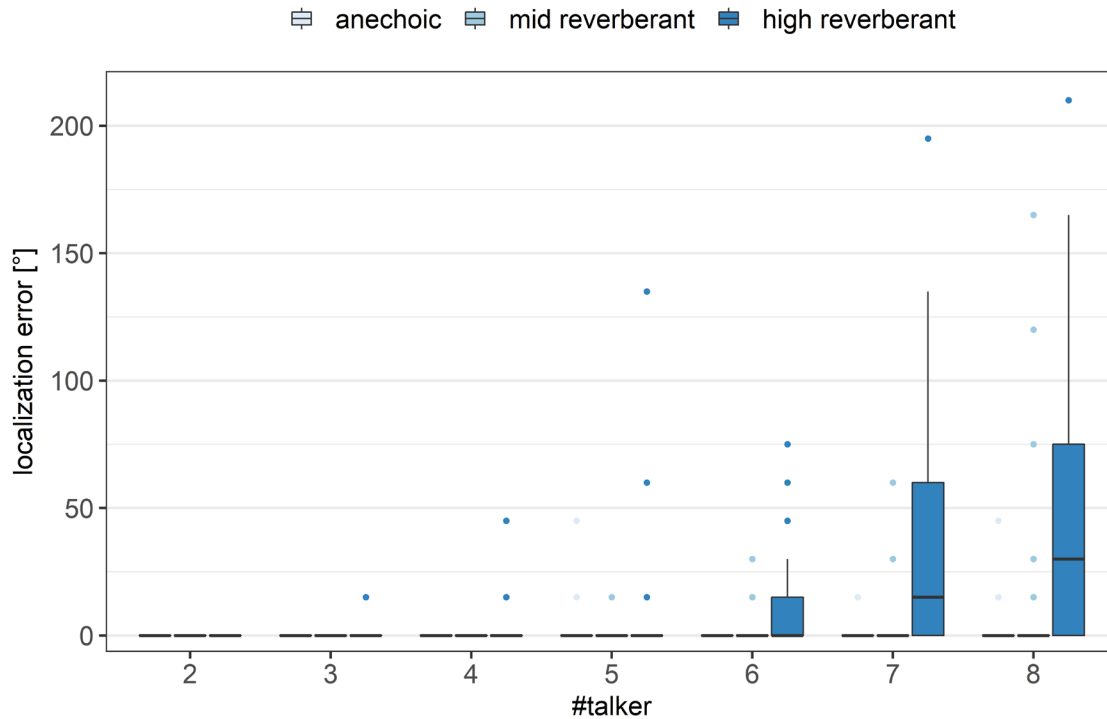
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247 Figure 5: Response time with respect to the number of talkers in a scene of all correct responses.
248 The colors indicate the room reverberation conditions. The boxes cover the range between the 25th
249 and the 75th percentile. The horizontal line in the boxes indicates the median. The whiskers extend
250 to 1.5 times the inter-quartile range. Outliers are indicated as dots.

251

252 In Figure 6 the localization error is shown. In the high-reverberation condition an increasing mean
253 localization error was found for six and more talkers, with the eight-talker setting resulting in a
254 median error of 30° , i.e., two potential positions error from the target location. In the anechoic and
255 mid-reverberant conditions only few errors were found, indicated as outliers in Figure 6.

256



258 Figure 6: Localization error with respect to the number of talkers. The three colors indicate the
259 room conditions. The boxes cover the range between the 25th and the 75th percentile. The
260 horizontal line in the boxes indicates the median. The whiskers extend to 1.5 times the inter-
261 quartile range. Outliers are indicated as dots.

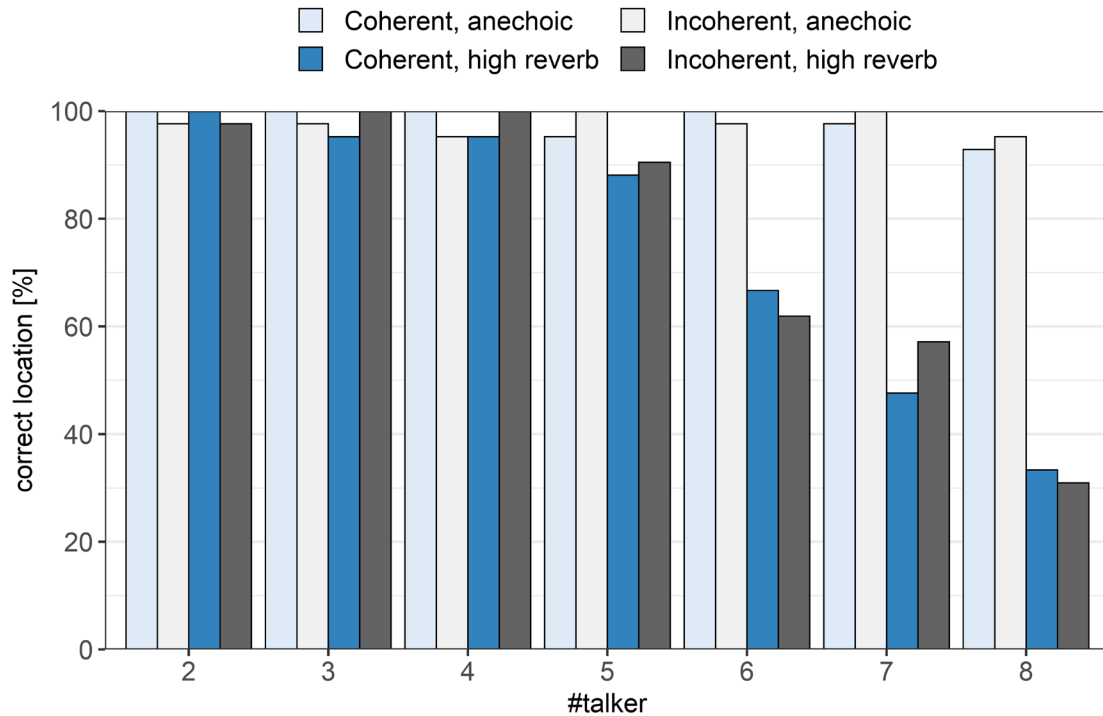
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263 B. Incoherent audio-visual room information

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265 Figure 7 shows the percentage of correctly identified stories, comparing the coherent and the
266 incoherent audio-visual conditions with and without reverberation. The light blue/grey bars
267 indicate the acoustically anechoic conditions and the dark bars the acoustically reverberant
268 conditions. No differences arise from the audio-visual incongruency.

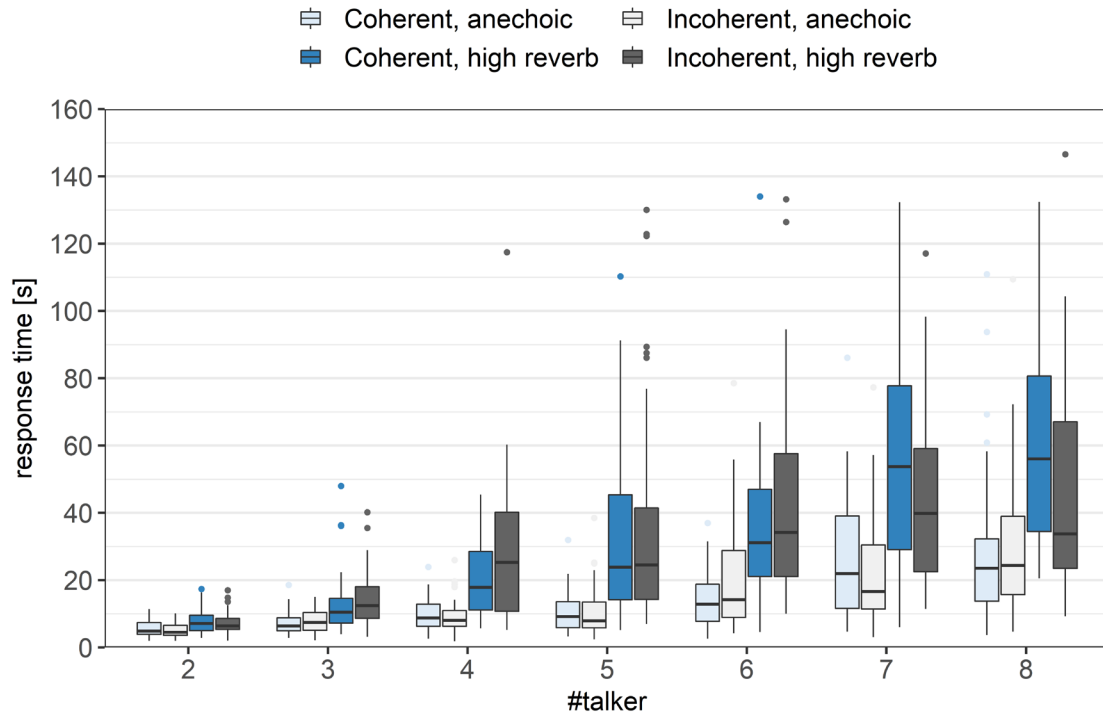
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271 Figure 7: The percentage of correct response locations comparing the coherent and incoherent
272 audio-visual conditions. Each bar contains 42 datapoints across subjects and repetitions. The three
273 colors indicate the room conditions.

274

275 Figure 8 shows the response times for the incongruent audio-visual conditions (grey boxes), i.e.,
276 the conditions with anechoic acoustic stimuli and the visuals of the reverberant room (light grey)
277 and with high acoustic reverberation and the visuals of the anechoic room (dark grey).
278 Additionally, the response times from the coherent anechoic and reverberant conditions are shown
279 (blue boxes, as in Figure 5). No significant difference was found between the congruent and the
280 incongruent condition [$p > 0.12$].



281

282 Figure 8: Response time with respect to the number of talkers in a scene. The light-blue and light-
283 grey boxes indicate the anechoic room acoustic condition with coherent and incoherent visual
284 information, respectively. The dark-blue and dark-grey boxes indicate the high reverberant room
285 acoustic condition. The boxes cover the range between the 25th and the 75th percentile. The
286 horizontal line in the boxes indicates the median. The whiskers extend to 1.5 times the inter-
287 quartile range. Outliers are indicated as dots.

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296 IV. Discussion

297

298 In the current study we investigated the ability of normal-hearing listeners to identify and locate a
299 story in the presence of other stories. The task of the listeners was to locate a target story in the
300 presence of a varying number of simultaneous interfering talkers. Furthermore, the effect of audio-
301 visual room information was investigated, by testing different audio-visually coherent and
302 incoherent reverberant environments. The data showed that the localization accuracy and the
303 response time are affected by the number of simultaneous talkers as well as by reverberation. With
304 an increase of number of interfering talkers and an increase of reverberation time the performance
305 of the listeners decreased. Presenting incoherent audio-visual room information did not affect the
306 outcome measures.

307 A. Effect of number of talkers

308 Several factors are likely to affect the increase in response time with increasing number of talkers.

309 In the present study the speech level of each talker was kept constant independent of the number
310 of talkers, and therefore, the signal-to-noise ratio (SNR) decreases. Thus, the intelligibility is
311 expected to drop with the number of simultaneous talkers. However, the effective SNR is
312 constantly changing with head-motion and fluctuations in the signals (Grange & Culling, 2016).
313 The head-motion introduces a variation of the target and interferer angles relative to the head and
314 thus head-shadow and interaural time differences vary. Both head-shadow and interaural time
315 differences have been shown to be utilized to separate target and interfering speech sources
316 (Bronkhorst, 2000; Culling et al., 2004). Fluctuations in the speech signals allow for dip-listening
317 which can significantly improve the SNR in some time-frequency bins. Such glimpses can help to
318 better understand speech (Glyde et al., 2013; Miller & Licklider, 1950). When many speech
319 sources are presented, such glimpses are usually reduced (Cooke, 2006; Freyman et al., 2004).

320 Another effect that likely influences the response time is the amount of informational masking,
321 i.e., confusions between the target and the interferers (Carhart et al., 1969; Durlach et al., 2003;
322 Kidd et al., 2008; Watson, 2005). Previous studies have argued that the amount of informational
323 masking decreases with increasing number of simultaneous talkers (Carhart et al., 1975; Freyman
324 et al., 2004; S. A. Simpson & Cooke, 2005). However, in the current study the target speaker needs
325 to be identified by understanding the speech and to do so, listeners also need to understand the
326 content of the interferers. Thus, the listener needs to employ a strategy to search through the
327 auditory scene and while performing the search an interfering talker becomes a temporary target
328 talker. Therefore, the definition of informational masking that was already controversial in classic
329 speech perception tasks (Durlach et al., 2003; Kidd et al., 2008; Watson, 2005) becomes even more
330 complex. How the listeners perform this task and which search strategies they employ, remains an
331 open question and is out of the scope of the current study.

332 B. Effect of Reverberation

333 Reverberation was found to affect the response time only between the mid-reverberation and the
334 high-reverberation conditions, and when there were four or more talker in a scene. In literature, it
335 is reported that reverberation affects speech intelligibility more with few interfering talkers
336 because potential speech gaps and pauses get ‘filled’ with the reverberant energy (Bolt &
337 MacDonald, 1949; Xia et al., 2018). Such gaps generally do not exist with many overlapping
338 speech sources (Cooke, 2006; Freyman et al., 2004). A potential explanation for the disagreement
339 is that the task remains fairly easy with additional reverberation when few talkers are in a scene
340 and thus, the effect of reverberation is masked.

341 No difference in response time was observed between the anechoic and the mid-reverberant
342 conditions. The inexistent difference between the anechoic and the mid-reverberant condition
343 contradicts results from previous studies where differences in speech perception between mildly

344 reverberant conditions and anechoic conditions were found (Ahrens, Marschall, et al., 2019;
345 Duquesnoy & Plomp, 1980; Plomp, 1976). The reason for this discrepancy could be that the test
346 paradigm might not be as sensitive to capture small differences in reverberation time, as traditional
347 speech tests. However, (Kopčo et al., 2010) discussed a similar finding that mild reverberation
348 does not affect the speech localization in background speech by comparing their study with data
349 from (B. D. Simpson et al., 2006). This raises the question if there is an effect of mild reverberation
350 on speech intelligibility in everyday situations or if this effect can only be observed in artificial
351 listening scenarios in the laboratory.

352

353 C. Experimental paradigm

354 The spatial scene analysis method employed in this study was similar to (Weller et al., 2016). The
355 most significant difference between the approaches is that in the current study the target speech
356 stimulus needed to be understood while the task in (Weller et al., 2016) was to judge the gender
357 of all talkers presented in a scene. Consequently, they used the total number of perceived talkers
358 as their main outcome measure, while we used the response time. Furthermore, in their study the
359 participants needed to translate the spatial percept from an egocentric auditory perception onto a
360 top-down view interface. This translation was not needed in the current study as virtual reality was
361 employed as a user interface.

362 While the use of virtual reality can allow for a more user-friendly interface, virtual reality could
363 also introduce issues to an experiment. For example, the auditory percept might be affected by the
364 physical presence of the headset which has been shown to be negligible for setups with far spaced
365 sources (Ahrens, Lund, et al., 2019; Gupta et al., 2018). Furthermore, virtual reality glasses might
366 alter the participant's behavior due to their physical appearance but also because the visual world

367 is not an exact copy of the real world. However, the influence is likely negligible in this
368 experimental setup.

369 Contrary to classical speech perception studies where a %-correct or a reception threshold is
370 determined, in the present study the response time was used as the main outcome measure.
371 (Drullman & Bronkhorst, 2000) used a similar speech localization/identification paradigm with
372 sentences and words instead of ongoing speech. They showed that the trend of change in
373 intelligibility with increasing number of talkers was similar to the trend of the response times, i.e.,
374 with more interfering talkers the intelligibility decreases, and the response time increases. While
375 the material and the task were not fully comparable between these studies, one can expect a
376 correlation between speech intelligibility and response time.

377

378 D. Effect of incoherent AV

379 Visual information is known to affect speech perception (McGurk & MacDonald, 1976). However,
380 the effect of visual room information on auditory perception remains unclear. Previous studies
381 showed that visual information of the room can improve auditory distance perception (Calcagno
382 et al., 2012) and incongruent audio-visual cues can disrupt distance or externalization percepts
383 (Gil-Carvajal et al., 2016). However, visual information has been shown to not affect the percept
384 of reverberation (Schutte et al., 2019), which is in line with the results from the current study.

385

386 E. Limitations

387 The speech material (10 stories spoken by 10 talkers) was recorded specifically for this study with
388 the aim to have distinctly different content that can be visualized with an icon. Furthermore, we
389 aimed for natural speech as opposed to highly controlled recordings with professional speakers.
390 This approach also comes with disadvantage; for example some stories or talkers might be easier

391 to understand than others. However, as stories and talkers were chosen randomly, their influence
392 is likely to be little over the sufficiently large number of iterations.

393 One aim of this study was to develop a test paradigm that is more like real-life listening than most
394 current speech intelligibility tests. While the task of understanding and locating a speech stream
395 out of interfering speech is more similar to traditional speech tests, it is by no means a replications
396 of a realistic cocktail-party situation. Firstly, all talkers are located at the same distance and with
397 the same speech level and face the listener. This decision was made to not give any level,
398 directional or direct-to-reverberant energy cues other than the information from the room
399 reflections and the talkers themselves. Secondly, the visual avatars are highly conceptualized
400 human bodies. Technology does not yet allow to visualize highly realistic human avatars with
401 conventional computational power and effort. When using avatars that share similarities with real
402 humans but evidently are not, viewers might get distracted (compare uncanny valley, (Diel et al.,
403 2022)). Thirdly, lip-movements have not been included in this study. This choice was made
404 because lip-movement simulations are not, as to the knowledge of the authors, evaluated for
405 hearing research purposes. Additionally, the aim of the avatars was more to be a ‘response-box’
406 than an actual simulation of a human talker.

407

408 V. Conclusions

409 In the present study we investigated the ability of listeners to analyze a spatial scene with multiple
410 talkers. A varying number of simultaneously spoken stories was presented in different reverberant
411 environments and listeners were asked to locate a target story. Results showed that the number of
412 simultaneous talkers affected the correct identification as well as the response time. Reverberation

413 only affected the outcome measures when the reverberation time was high but not with moderate
414 reverberation.

415

416 Acknowledgement

417 We would like to thank Marton Marschall, Valentina Zapata Rodriguez and Jakob Nygard
418 Wincentz for their valuable feedback regarding the plausibility of the virtual audio-visual rooms
419 and Torsten Dau for the feedback on the experimental design.

420

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