

Binding and unbinding pathways of peptide substrate on SARS-CoV-2 3CL protease

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Abstract

Based on many crystal structures of ligand complexes, much study has been devoted to understanding the molecular recognition of SARS-CoV-2 3C-like protease (3CL^{pro}), a potent drug target for COVID-19. In this research, to extend this present static view, we examined the kinetic process of binding/unbinding of an eight-residue substrate peptide to/from 3CL^{pro} by evaluating the path ensemble with the weighted ensemble simulation. The path ensemble showed the mechanism of how a highly flexible peptide folded into the bound form. At the early stage, the dominant motion was the diffusion on the protein surface showing a broad distribution, whose center was led into the cleft of the Chymotrypsin fold. We observed a definite sequential formation of the hydrogen bonds at the later stage occurring in the cleft, initiated between Glu166 (3CL^{pro}) and P3_Val (peptide), followed by binding to the oxyanion hole and completed by the sequence-specific recognition at P1_Gln.

Introduction

The 3C-like protease (3CL^{pro}, also called the main protease) of SARS-CoV-2 is a cysteine protease of the C30 family (1) and it plays a critical role in viral replication by cleaving the polyprotein of SARS-CoV-2 at 11 distinct sites to release functional proteins (Fig. 1a; 2). Thus, 3CL^{pro} is a potent drug target that has been widely investigated for preventing the COVID-19 pandemic (2-4). A number of crystal structures complexed with the substrate peptides have been solved for the atomic-level understanding of the proteolytic mechanism of 3CL^{pro} (5-12) and it has been shown that the substrate recognition of 3CL^{pro} can be outlined by the classic subsite model of proteases (13,14). This knowledge has been the basis for the inhibitor design (3,4), particularly for the peptidomimetic inhibitors (15,16).

In our previous study (17), the structural changes of 3CL^{pro} upon ligand binding were discussed collectively by accumulating all available crystal structures of 3CL^{pro} including both ligand-bound and ligand-free forms (more than 300 PDB entries, including homologous 3CL^{pro} of SARS-CoV, comprising a broad range of the conformations). We call the assembled crystal structures ‘*crystal structure ensemble*’ (17,18). It was found in the ‘*crystal structure ensemble*’ that the structural responses upon ligand binding exclusively occurred at the ligand binding flexible loops on the rigid Chymotrypsin fold to finely regulate the catalytic activity (Fig. 1b; 17).

In this research, we extend the scope of the study on 3CL^{pro} from thermodynamics to kinetics to obtain the atomic details of the binding/unbinding process by employing the path sampling simulations (19-21). The kinetic view offers a significantly larger amount of information describing the entire process of the molecular recognition compared to the thermodynamic view focusing only on the initial (ligand-free) state and the final (ligand-bound) state. Recently, the kinetic information has attracted considerable attention because the drug efficacy *in vivo* was found to be more relevant to the kinetics rather than the thermodynamics in the equilibrium condition (22,23).

The kinetics of the peptide binding process is sensitively modulated by different factors, not only the peptide’s fluctuations but also the protein’s structural changes and desolvation in the interface. Then, the path sampling of binding and unbinding processes must be conducted in a sufficiently comprehensive manner to produce a trajectory covering all events occurring in all

degrees of freedom, including those of solvent molecules. Since such a molecular simulation is computationally highly demanding, we used the weighted ensemble (WE) simulation (24-26), which runs a number of short-time unconstrained all-atom MD simulations to evolve a diverse set of continuous paths of the protein structural change efficiently. The path ensemble of the binding/unbinding process thus obtained offers the essential information of the molecular recognition to show the atomistic details of the binding/unbinding process.

We chose the eight-residue peptide (TSAVLQ↓SG, ↓ indicating the cleavage site, see Methods for details) from the 11 cleavage sites of SARS-CoV-2 (2) for the target substrate in the simulations. This is a model for the native substrate as well as for the flexible peptidomimetic compounds (mostly Mw > 500) that are found in the majority of the ligand molecules in the complex crystal structures (17). This computer simulation study elucidates how 3CL^{pro} induces the folding and binding of the highly flexible eight-residue peptide from the fully random conformation in the bulk solvent to the peptide-bound structure uniquely determined at the 3CL^{pro} recognition site, and answers a question as to how the structural changes in the flexible loops of 3CL^{pro} contribute to the peptide recognition process.

Results

Structural dynamics of 3CL^{pro} in peptide-bound and peptide-free forms.

Prior to the WE simulation, conventional MD simulations of the SARS-CoV-2 3CL^{pro} dimer were conducted with the peptide-bound and peptide-free forms to describe the structural dynamics characteristics for the two terminal states of the path ensemble. This procedure aims at finding the definite structural changes upon ligand binding and identifying the native atom contacts with the peptide under the thermal fluctuation, that are useful for the subsequent analysis of the path ensemble.

To detect the structural difference seen in the two MD simulations, the Motion Tree was constructed from the difference between the two snapshot structures near each average structure obtained from the trajectories of the peptide-bound and peptide-free simulations (27; Fig. S1). The Motion Tree reveals the structural differences between the two termini of the path ensemble

that mostly occurs in the ‘moving clusters’ (the segments showing large structural changes) originally defined by the crystal structure ensemble (17), i.e. ‘H-loop’ (residues 38–64), ‘E-loop’ (residues 166–178), ‘Linker’ (residues 188–196) and ‘domain III’ (residues 200–300) (these clusters were named the same as in ref. 17). ‘C-loop’ (residues 138–143) was another major moving cluster observed in the crystal structure ensemble, while in Fig. S1, it is not a major cluster but is found in a part of the rigid core region with a small MT score less than 1 Å. This is because the crystal structure ensemble contains both the active and collapsed (inactive) structures of the C-loop, whose pairwise C α RMSD exceeds 3Å, corresponding to the MT score between nodes 3 and 4 in Fig. 2. However, the present simulations started with the same crystal structure in the active state (PDB: 2q6g) and the active structure remained stable in the simulation condition even when the peptide was removed. The C-loop’s stability can also be confirmed by the five hydrogen bonds (HBs) between the C-loop and other parts of the protein, found in the crystal structures (Table S1; in the crystal structures, these HBs were formed in the active state but not in the collapsed state; 17); the C-loop will be intrinsically in active form because collapsed C-loop is found only in the crystal structures with mutations at the important sites or appended amino acids at the N-terminus (17). The HBs in the simulations are independent of peptide binding, seen in almost the same probability of occurrence (the average probabilities are 0.74 and 0.77 for the peptide-bound and peptide-free simulations, respectively).

The dynamic fluctuation of the peptide-bound state and that of the peptide-free state were then compared in the Motion Trees (Fig. S2), which were constructed from the variance of the inter-residue distances (28). As shown in Fig. S2, the H-loop, Linker and domain III fluctuate most largely both in the peptide-bound and peptide-free states. Thus, the structural differences between the peptide-bound and peptide-free structures of these clusters illustrated in Fig. S1 were not attributed to the influence of peptide binding, but were rather caused by the large fluctuations. Domain III is distant from the peptide binding sites, and the H-loop and Linker have no substantial interactions with the peptide. However, the E-loop is the cluster that was strongly influenced by peptide binding; the E-loop was stiffened by peptide binding (the MT score decreased from 2 Å to 0.4 Å upon binding; Fig. S2). The E-loop’s role in peptide recognition is discussed below. It was also found in the MD simulations that these moving clusters fluctuated independently of each other as in the crystal structure ensemble (Table S2; 17).

The interactions with the peptide were analyzed by measuring the probability of occurrence of the HBs (Table 1). Most of the HBs found in the simulation were those found in the crystal structure ensemble (17), but the HBs with the Linker, HB #8 and #9, have very low values of the probability of occurrence in the simulation; their probabilities are smaller than 0.1. As shown in Fig. S2, where the Linker maintained a large fluctuation even after peptide binding, the large fluctuation of the Linker in the simulation may prevent the peptide from forming stable HBs, while the crystal structure reflects the one with a low level of fluctuation measured at a low temperature. These HBs are employed below in the description of the binding/unbinding pathway.

Peptide binding and unbinding kinetics observed in WE simulations.

The WE simulations were conducted to obtain the kinetic information and the path ensemble of the peptide binding and unbinding processes. The root-mean-square deviation (RMSD) of the non-hydrogen atoms of the substrate residues VLQS from the crystal structure after superimposing the protein's core region of the protein, $\text{RMSD}_{\text{VLQS}}$, was taken as the reaction coordinate (see Methods for details). As summarized in Fig. S3, the unbinding paths were computed starting from the position of the crystal structure (Fig. S3a). The peptide dissociated from the binding site to different directions and finally arrived at the peptide-free state in the bulk solvent region (Fig. S3b). The binding WE runs were conducted to obtain the binding paths reaching the binding site, starting from three distinct peptide-free structures taken from the terminal bin of the unbinding WE simulation (Fig. S3c). Finally, the structures in the peptide-bound state were successfully sampled in the terminal bin of the binding WE runs (Fig. S3d).

The key quantity provided by the WE simulation is the probability flow, p_{flow} , from the peptide-free state to the peptide-bound state and in the reverse direction. Fig. 2a illustrates the time evolution of p_{flow} that allows us to assess the mean first passage time (MFPT) from the approximately linear ranges ($5 \leq t \leq 7.5$ ns for the binding simulation and $7.5 \leq t \leq 10$ ns for the unbinding simulation), while latent periods appeared in small t ($< \sim 2-4$ ns) due to finite numbers of copies in the WE simulation. The kinetic constants, k_{on} and k_{off} , calculated with the estimated peptide concentration, turned out to be $k_{\text{on}} = 6.7 \pm 0.71 \times 10^4 \text{ M}^{-1}\text{sec}^{-1}$ and $k_{\text{off}} = 63 \pm 9.2 \text{ sec}^{-1}$ (Eqs. 1 and 2, see Methods). This result also shows that the binding process started from the

three structures (see Fig. S3c) is faster (larger probability flow) than the unbinding process that directly corresponds to the binding affinity, or the dissociation constant: $K_D = k_{\text{off}} / k_{\text{on}} \sim 900 \mu\text{M}$. Although no experimental K_D value of the substrate is available, the Michaelis constant K_M is cited as a reference (Table S3; K_M is a reasonable reference, as the k_{cat} values are small). The experimental K_M values (5–170 μM) are at least five-fold smaller than the calculated K_D value. This difference is due to the large k_{off} value. Several reasons are supposed, such as the smaller chain length of the substrate adopted in the simulation, and such that the fixed force field did not produce a sufficient affinity in the peptide-bound form. The Michaelis complex related to K_M is a pre-transition state complex containing the charge and proton transfer between the substrate and the protein, which may yield stronger affinity (29). In a neutron diffraction structure (PDB:7jun; 30), the proton transfers from S γ in Cys145 to N ϵ in His41 to produce Cys145⁻ and His41⁺.

To view in details the binding/unbinding kinetics along the reaction coordinate, the probability flow, p_{flow} , was computed for each bin of the WE simulations, and the MFPT as a function of RMSD_{VLQS} was evaluated similarly as in Fig. 2a. Fig. S4 shows that the evolution curves of MFPT along RMSD_{VLQS} for unbinding and binding processes are reasonably approximated by the power-law type relation as $\text{MFPT}(r) \sim r^d$ (unbinding) and $\text{MFPT}(r) \sim \frac{1}{\alpha} (r_{\text{max}} - r)^d$ (binding), where $r := \text{RMSD}_{\text{VLQS}}$ with $2.5 \text{ \AA} \leq r \leq 25.5 \text{ \AA}$ and $r_{\text{max}} = 28 \text{ \AA}$. The power d is the effective dimension, which was evaluated here to be ~ 7 for both processes and α ($= 1.5\text{--}2.2$) is a scaling factor to the absolute values of the MFPT for the two processes.

We can refer to the formulation of the scale-free network (31) for the interpretation of the power-law type behavior, in which the recurrent diffusion occurring in an equilibrium system has the MFPT of the form, $\text{MFPT}(r) \sim r^{d_w}$, where d_w represents the walk dimension related to the mean square displacement as, $\langle \Delta r^2 \rangle \sim t^\beta$ with $\beta = 2/d_w$. According to the formulation, the effective dimension, d , evaluated above can be interpreted as the walk dimension d_w , thus $\beta = 0.3$. Therefore, the dynamics of the binding/unbinding process of the peptide are subdiffusion with $\beta < 1$. The extensive slowness of the dynamics may come from the flexible torsional motions of the peptide (32) and the interplay with the protein surface restraining the peptide motions.

Path ensemble of peptide binding and unbinding.

Along the binding/unbinding pathways, there are two stages of the process experienced, each of which is described by a different reaction coordinate: the region distant from the binding site, where the peptide moves randomly on the protein surface, is outlined by $\text{RMSD}_{\text{VLQS}}$ and the region near the binding site, completing the peptide recognition, is explained by the fraction of the native atom contacts between the protein and the peptide, Q (see the caption of Fig. 2 for the definition). Fig. 2b illustrates the relation between $\text{RMSD}_{\text{VLQS}}$ and Q . The native contacts occur only in the vicinity of the binding site, $\text{RMSD}_{\text{VLQS}} < 5\text{--}7 \text{ \AA}$, where Q can be employed as the reaction coordinate.

First, the peptide binding and unbinding processes are outlined along the reaction coordinate of $\text{RMSD}_{\text{VLQS}}$. The structural indices characterising the processes are the number of atom contacts between the protein and the peptide, n_c , and the number of hydrated water molecules of the peptide, n_w (see the caption of Fig. 2 for the definitions). Fig. 2c illustrates a gradual, almost linear increase in n_c starting from the non-zero value at $\text{RMSD}_{\text{VLQS}} = 20 \text{ \AA}$, showing that at the remote region ($\text{RMSD}_{\text{VLQS}} > 5\text{--}7 \text{ \AA}$) the peptide has already had plenty of non-specific, non-native interactions with the protein. This observation indicates that the kinetics in this region is regulated by diffusion on the protein surface. Fig. 2d shows that the peptide is fully solvated in the region of $\text{RMSD}_{\text{VLQS}} > 10 \text{ \AA}$. On approaching the peptide-bound state beyond this region, n_w gradually decreases with $\text{RMSD}_{\text{VLQS}}$. At the end of this section, it is demonstrated that at $\text{RMSD}_{\text{VLQS}} \sim 10 \text{ \AA}$, the binding mode is divided into the inside ($< 10 \text{ \AA}$) and the outside ($> 10 \text{ \AA}$) of the cleft of the Chymotrypsin fold in which the binding site exists (see Fig. 1b). Entering the cleft thus accompanies a certain level of desolvation.

As a whole, Figs. 2b-d show that the binding and unbinding processes follow an identical pathway within the margin of error. Thus, we calculated all structural indices without distinguishing the binding and unbinding processes or by mixing up the ensembles of the two processes in the following discussion.

In Fig. 3, we go into detail about the peptide binding process. Fig. 3a illustrates the peptide's spatial distribution in terms of the translation and rotation degrees of freedom; the vector from the center of C α atoms of the protein residues, Met165 and Cys145, to the center of C α atoms of the peptide residues, P2_Val and P0_Ser, is described in the polar coordinates, (d, θ, ϕ) . The

three-dimensional coordinates are further reduced to the two dimensions, $(d, |\Delta\theta| + |\Delta\phi|)$, where Δ shows the difference from the values in the peptide-bound state. The resultant two-dimensional free energy landscape in Fig. 3a shows that when $d > 10\text{--}12\text{ \AA}$, the peptide's rotation is not hindered by the protein but allowed freely as in the bulk solvent region. When $d < 10\text{--}12\text{ \AA}$, the rotation began to be restricted by the protein surface and was finally reduced to the fluctuation level observed in the peptide-bound simulation. Since d is well correlated with $\text{RMSD}_{\text{VLQS}}$ (see the caption of Fig. 3), the position of $d \sim 10\text{--}12\text{ \AA}$ corresponds to $\text{RMSD}_{\text{VLQS}} \sim 10\text{--}12\text{ \AA}$ where the peptide starts to enter the cleft of the Chymotrypsin fold and its overall rotation starts to be constrained. However, as illustrated in Fig. 3b, even after the peptide enters the cleft, the peptide's conformation, depicted by $\text{C}\alpha\text{-RMSF}_{\text{int}}$ ($\text{C}\alpha$ -root-mean-square fluctuation after superimposing the residues VLQS), remains largely fluctuating. It converges to the peptide-bound structure only after the native contacts are formed ($\text{RMSD}_{\text{VLQS}} < 5\text{ \AA}$). It is concluded that the peptide's conformation is solely determined by the native interactions with the protein. These results are also observed in the peptide's representative structures (Fig. S5).

Now let us look into the evolution of the path ensemble from the standpoint of the shift of the peptide distribution. Fig. 3c shows the $\text{C}\alpha\text{-RMSF}$ of the residues VLSQ after superimposing the protein's core region against $\text{RMSD}_{\text{VLQS}}$. The breadth of the distribution increases with increasing $\text{RMSD}_{\text{VLQS}}$, with the linear relation, $\text{C}\alpha\text{-RMSF} \sim 3/4 \text{ RMSD}_{\text{VLQS}}$. Two extreme scenarios of the binding process can be supposed: (1) the distribution approaching the binding site along a definite pathway and (2) the distribution simply shrinking in size to converge to the binding site without a substantial shift of the distribution center. The first scenario will give a small change in RMSF with $\text{RMSD}_{\text{VLQS}}$, while the latter gives a substantial change in RMSF. The relation in Fig. 3c may be better suited to the second scenario. This is seen in the distribution of the contact residues in the protein (Fig. 3e), which reveals a shrink of the distribution size along the binding process or with decreasing $\text{RMSD}_{\text{VLQS}}$. For all ranges of $\text{RMSD}_{\text{VLQS}}$, the residues surrounding the native binding site are most frequently contacted with the peptide.

It is then possible to scrutinise how the center of the peptide distribution moves with $\text{RMSD}_{\text{VLQS}}$. Fig. 3d illustrates the evolution, which was monitored separately by the positions of two atoms, $\text{C}\alpha$ atoms of P1_Gln and P3_Val, as a function of $\text{RMSD}_{\text{VLQS}}$. The center approaches the binding site along the peptide's longitudinal axis in the peptide-bound state from the P2' side.

It is most notable that the two positions of P1_Gln and P3_Val merge after $\text{RMSD}_{\text{VLQS}} > 10 \text{ \AA}$ and diverge to each binding position when $\text{RMSD}_{\text{VLQS}} < 10 \text{ \AA}$. This indicates that the region of $\text{RMSD}_{\text{VLQS}} \sim 10 \text{ \AA}$ separates the inside and outside of the cleft of the Chymotrypsin fold, and at the outside of the cleft, the peptide's overall rotation mixes up the positions of the two C α atoms. Once the peptide goes into the cleft, the rotation becomes restricted and the two C α atoms are aligned to the cleft.

Finally, in this section, the ligand-induced structural changes in the protein are discussed. Fig. 3f illustrates the C α -RMSD value of the E-loop and C-loop. As in the Motion Tree of Fig. S1, the E-loop has a definite structural change, while the C-loop shows only a small change. At $\text{RMSD}_{\text{VLQS}} \sim 6.5 \text{ \AA}$, the E-loop's RMSD value starts to decrease, indicating that the E-loop's structure is affected mostly by the native contact with the peptide. A more detailed discussion is presented in the next section in terms of the Q dependence. However, the H-loop and Linker maintain large fluctuations and exhibit almost no effect on the $\text{RMSD}_{\text{VLQS}}$ values from peptide binding (Fig. S6a, see also Fig. S2). However, the Linker's n_C value increases with a decrease in $\text{RMSD}_{\text{VLQS}}$ (Fig. S6b). Since the Linker does not have any native contact counted in Q (see also Table 1), it was concluded that the large fluctuating Linker makes a substantial number of non-specific contacts with the peptide (corresponding to 25%–35% of the total number of contacts shown in Fig. 2c), which certainly contributes to not only the binding affinity but also the substrate peptide's kinetics. The same type of non-specific interaction may occur in the recognition of the peptide-mimic compound with the Linker.

Completion of the peptide binding to 3CL^{pro}

The binding/unbinding process near the binding site was studied in detail along the reaction coordinate of Q , the fraction of the native contacts. The structural indices focused here is the peptide recognition by the HBs defined in the peptide-bound simulation (see Fig. 1b and Table 1). In terms of the peptide's binding sites, the HBs were classified into four groups: (1) P3_Val, (2) P1_Gln (main-chain; the carbonyl oxygen is the target of the oxyanion hole), (3) P1_Gln (side-chain; the origin of the sequence-specific recognition) and (4) P2_Leu and P4_Ala. Group 4 is not discussed here because of the low probability of occurrence in the simulation. The average number of the HBs in each group, n_{HB} , illustrated in Fig. 4a, indicates that there exists a

definite sequence of the formation of the HBs during the peptide binding/unbinding process; the groups 1, 2 and 3 in the ascending order of Q . It is again noted that the binding and unbinding processes are mixed for the calculation of n_{HB} . The difference between the two processes along Q is small enough for both processes to keep the sequence of the HB formation (Fig. S7).

Based on the observation in Fig. 4a, the structural basis of the peptide recognition was further elucidated by relating the sequential formation of the HBs to the protein structural change and the peptide folding toward the peptide-bound state (Figs. 4b-d). A series of snapshots of the peptide binding process along Q -value ($Q = 0, 0.35, 0.6$ and 1) were employed to illustrate the derived findings (Fig. 4e).

At the initial stage of the HB formation at $Q \sim 0.2$, one of the HBs in the group 1 between Glu166 (main-chain) and P3_Val (main-chain) is firstly formed (Fig. 4a), where Glu166 is at the position of the peptide-free state (because the $C\alpha$ distance of Glu166 from the peptide-bound state, d_{E166} , was evaluated to be 1.9 ± 0.4 Å in the peptide-free MD; Fig. 4b). This HB triggers the peptide's folding to form the peptide-bound structure, or initiates the decrease of the $C\alpha$ -RMSD for the peptide VLQS residues from ~ 2 Å (Fig. 4c).

Glu166 is then more attracted to the peptide when the two HBs in the group 1 between Glu166 (main-chain) and P3_Val (main-chain) are complete at $Q \sim 0.35$ (Figs. 4b and 4e), accompanying the increase of d_{E166} (fig. 4d). This overshoot of Glu166 appears as if the E-loop goes out of the cleft to catch the peptide located outside the binding site. This dynamic behavior of the E-loop reminds us of the fly-casting mechanism (33), in which the unfolded and highly flexible region in a protein is used to bind a ligand to form the complex structure (though the E-loop does not unfold). Glu166 starts to cause a significant motion toward the peptide-bound state when Q -value becomes greater than 0.35 (Arrow 2 of Fig. 4e), seen in the decrease of d_{E166} to the level in the peptide-bound state ($d_{E166} = 1.1 \pm 0.3$ Å calculated in the peptide-bound MD; Fig. 4b) and thus leads the peptide into the binding site buried inside of the cleft (Arrow 3 of Fig. 4e). These binding dynamics of Glu166 are mostly due to the E-loop's structural change (residues 166–171) (Fig. 4c; Arrow 1 of Fig. 4e). Since in the peptide-free simulation the E-loop was highly flexible (see Fig. S2), the E-loop susceptibly responds to the interactions with the peptide to lead the peptide to the bound state. In our previous study, the E-loop was found to make a

ligand-size dependent conformational change (17). This finding in the crystal structure ensemble corroborates the susceptible response to the peptide interactions observed in the WE simulation.

At $Q \sim 0.6$, the peptide motion led by the E-loop further causes the residues in the group 2 to form the HBs with P1_Gln (Figs. 4a and 4e). These HBs are formed during a slight shift of the C-loop at Gly143 and Cys145 toward the peptide (Arrow 4 of Fig. 4e), seen in the decrease of the C-loop C α -RMSD (Fig. 4d). However, at $Q \sim 0.6$, the side-chain of P1_Gln still largely fluctuates (Fig. 4d) not allowing to fix it at the binding conformation.

Finally, at $Q \sim 1$, the final stage of the binding process, the conformational fluctuation of the P1_Gln side-chain is gradually converged to the peptide-bound form (Fig. 4d) and the HBs in the group 3 are formed to complete the binding process (Arrow 5 of Fig. 4e). The binding of the side-chain of P1_Gln with Phe140 accompanies a further shift of the C-loop at Phe140 (Arrow 6 of Fig. 4e).

Discussion

The path sampling simulations of the eight-residue peptide binding/unbinding process to/from SARS-CoV-2 3CL^{pro} were conducted using the WE method (24-26). The binding kinetics was successfully quantified in terms of the MFPT. The obtained MFPT showed reversible kinetics in the peptide binding/unbinding process except for the free energy difference favouring the peptide-bound state. It also underwent an extensive slowdown relative to simple diffusion along the reaction coordinate, RMSD_{VLQS}. Thus, the kinetics was categorised as subdiffusion, which is supposed to be one of the common behavior of flexible peptides (32).

The path ensemble obtained in the WE simulations enabled us to explain the details of the peptide binding/unbinding process. The initial stage of the binding process starts with the diffusion on the protein surface that allows the overall rotation and a considerable conformational change of the peptide. The diffusion is directed toward the cleft region between the two domains in the Chymotrypsin fold to increase the number of non-specific contacts. This cleft plays a crucial role in leading the highly flexible peptide to the peptide-bound form: aligning the peptide to the cleft to restrain the overall rotation, increasing the number of contacts and enhancing the peptide's desolvation.

After the peptide enters the cleft, the specific native contacts start to be formed first at the main-chain of Glu166, where the E-loop's dynamics play a critical role. The E-loop is intrinsically flexible and shows a large conformational change upon ligand binding. The E-loop responds to the approaching peptide and causes a large shift toward the peptide to form the HBs of Glu166 (group 1 in Table 1), like the fly-casting mechanism (33). These HBs trigger the sequential formation of the HBs to P1_Gln main-chain (group2) to lead the peptide more deeply into the cleft. The last event to complete the binding process occurs in the side-chain of P1_Gln (the HBs in group 3). This is because the side-chain flexibility can be constrained only after the peptide's residues and the protein surrounding the side-chain is fixed by the native contacts. During the binding process, first the cleft of the Chymotrypsin fold and then the specific native contacts gradually restrain the flexible peptide conformation to form the peptide-bound state. Thus, it is concluded that the peptide binding is the process of gradual damping of the motions of both the peptide and protein that is highly regulated by the non-specific and specific peptide-protein interactions.

Methods

Model construction and MD simulations

Conventional MD simulations were performed for the SARS-CoV-2 3CL^{pro} dimer with and without the bound peptide to study the dynamics at the termini of the path ensemble calculated by the subsequent WE simulation. The simulation model was taken from the SARS-CoV crystal structure (PDB: 2q6g; 34), which binds the peptide substrate (residues 3258–3265 of P0DTC1 or P0DTD1, TSAVLQ↓SG capped with the terminal acetyl and N-methyl groups (Mw = 816.9); the C-terminal 6 residues of nsp4 and the N-terminal 2 residues of nsp5 (3CL^{pro}) in the polyprotein of SARS-CoV-2; '↓' indicates the substrate cleavage site and thus the peptide corresponds to P6-P1↓P1'P2'; the three C-terminal residues in 2q6g were excluded from the model). The 12 SARS-CoV-specific amino acids with the mutated Ala41 in 2q6g were converted into those of SARS-CoV-2 employing MODELLER (35). This model was selected because it has a unique structure representing the non-covalent interaction between Cys145 and the substrate (17,34). The other complex crystal structures with non-covalent interactions with the substrate peptide (PDB:1z1j, 5b6o, 6xoa and 7joy) have mutations, C145A or C145S. Recently, the structure of the 3CL^{pro}

(H41A) complexed with the same peptide was released (PDB:7dvp;12). The structure of 7dvp was discovered to be very similar to that of 2q6g; C α -RMSD (residues 1–200) = 0.38 Å and RMSD (non-hydrogen atoms of the eight residues of the peptide after superposition of the protein) = 0.70 Å.

Rectangular simulation boxes were constructed with a margin of 12 Å to the boundary of the simulation box and fully solvated by 25,955 TIP3P water molecules (36) and eight sodium ions to neutralise the simulation systems, resulting in 89,501 atoms. The molecular recognition and the proteolytic reactions occur seamlessly, and the substrate peptide forms a covalently bound intermediate between Cys145 S γ of 3CL^{pro} and P1_Gln O during the proteolysis reaction (14). However, due to the limitation of the MD simulation, 3CL^{pro} and the peptide interact with each other in a non-covalent manner throughout the simulations. The peptide-unbinding simulation was conducted with the same system after removing the peptides.

AMBER ff14SB (37) was employed for the potential energy of the protein. The MD simulations were conducted using AMBER 16 (38) under the constant temperature and pressure (NPT) condition at $P = 1$ atm and $T = 300$ K, using Berendsen's barostat and Langevin dynamics to control the temperature with 1.0 ps^{-1} as the collision frequency. The particle mesh Ewald method (39) was used for the electrostatic interactions. The time step was 2 fs with the constraints of bonds involving hydrogen atoms via the SHAKE algorithm (40). For each of the peptide-bound and peptide-free systems, the simulation was performed for 1 μs and three times starting with different initial velocities. The trajectories were recorded at 10 ps intervals.

Construction of Motion Tree

In the analysis of the trajectories derived in the MD simulations of the peptide-bound and peptide-free states, protein dynamics were analyzed as a set of collective motions among residue clusters behaving as rigid structural units. These clusters were defined by the hierarchical clustering of the fluctuations of inter-residue distances to construct a dendrogram named '*Motion Tree*' (27,28). Each node of the Motion Tree shows a pair of clusters mutually fluctuating with the magnitude represented by the node height. In previous studies, the Motion Tree was applied to the analyses of the trajectories of MD simulations (28,41,42) and crystal structure ensemble (17,18).

The metric of the hierarchical clustering for the Motion Tree comparing two structures (snapshots near the average structures of the peptide-bound and peptide-free simulations) was defined by $D_{mn} = |d_{mn}^{\text{bound}} - d_{mn}^{\text{free}}|$, where d_{mn} represents the distance between the C α atoms of residues m and n (27). Structural fluctuations of the peptide-bound structure or the peptide-free structure during the simulation were described by employing the metric of $D_{mn} = \langle \Delta d_{mn}^2 \rangle^{1/2}$, where $\langle \Delta d_{mn}^2 \rangle$ represents the variance of the structural ensemble obtained in the simulation (28). Since 3CL^{pro} forms a homodimer, D_{mn} was symmetrized by averaging the duplicated structures of AB and BA, where AB represents the original dimer of protomers A and B, and BA is the exchanged dimer. The C-terminal segment (residues 301–306) was excluded in the analysis since it is highly flexible and irrelevant to 3CL^{pro} function.

WE simulations

The path ensembles of the binding and unbinding processes were obtained using the WE simulation (26). The WE simulation carries out a number of short-time unbiased MD runs repeatedly, whose trajectories are then connected to construct full continuous paths progressing along a pre-defined reaction coordinate. The original Huber-Kim algorithm (24,26) of the WE simulation was employed for the binding/unbinding simulation to/from protomer A, while the peptide on protomer B was kept in the peptide-bound form (see Fig. 1a). It was confirmed in the preliminary simulations that there was no detectable cooperativity between the two binding sites. As the one-dimensional reaction coordinate in the WE simulation, we chose the root-mean-square deviation (RMSD) of the non-hydrogen atoms of the substrate residues VLQS (corresponding to P3-P1') from the crystal structure after superimposing the protein's core region (17; hereinafter designated as RMSD_{VLQS}). Thus, RMSD_{VLQS} reflects not only the peptide internal conformation but also the peptide's overall translation and rotation. The discretization of the reaction coordinate for the WE simulation was conducted as follows: RMSD_{VLQS} < 2 Å is defined as the peptide-bound state, RMSD_{VLQS} > 25 Å is the peptide-free state, and 40 bins are set between 2 and 12 Å with the interval of 0.25 Å and 26 bins between 12 and 25 Å with the interval of 0.5 Å; the number of bins, M_{bin} , is thus 68. The peptide-bound state corresponds to the range of thermal fluctuation seen in the MD simulation of the peptide-bound form, while the peptide-free form is the peptide position sufficiently distant from the binding site with no

interaction with the protein. As the initial condition for the simulation, the configuration was set at bin 1 (the peptide-free state for the binding simulation and the peptide-bound state for the unbinding simulation), i.e. $\rho_1(0) = 1$, where $\rho_I(t)$ represents the probability of the occupancy at bin I ($I = 1, 2, \dots, M_{\text{bin}}$) at time t . To evolve $\rho_I(t)$, 16 unbiased MD simulations of τ ($= 25$ ps in this study) were performed starting from a representative set of 16 copies of the system involved in bin I when $\rho_I(t) > 0$. Thus, at time t , 1088 ($= 16 \text{ copies} \times 68 \text{ bins}$) MD simulations were conducted. This procedure was repeated L times ($= 300$ for the binding simulation and 400 for the unbinding simulation) iteratively to evolve $\rho_I(t)$, i.e. the time interval of $\rho_I(t)$ is thus $L\tau = 7.5$ ns and 10 ns for binding and unbinding simulations, respectively. In this research, the unbinding paths were first computed by starting at a structure taken randomly from the trajectories of the MD simulation of the peptide-bound form and then the computation of the binding paths was performed starting from each of the three separate structures of the peptide-free form generated by the unbinding WE runs (see Fig. S3). The WE runs were repeated three times for the error estimation of the rate constants. In total, the simulation time amounts to 24.5 μs ($25 \text{ ps} \times 16 \text{ copies} \times 68 \text{ bins} \times 300 \text{ iterations} \times 3 \text{ runs}$) for the binding simulation and 32.6 μs ($25 \text{ ps} \times 16 \text{ copies} \times 68 \text{ bins} \times 400 \text{ iterations} \times 3 \text{ runs}$) for the unbinding simulation.

The MFPT, or the inverse of the rate constant k , was calculated from the probability flow, p_{flow} , as follows:

$$p_{\text{flow}}(t) := p_{M_{\text{bin}}}(t) \simeq \frac{t}{\text{MFPT}} = kt, \quad (1)$$

where the approximation is for a sufficiently small t . First, $\rho_I(t)$ was time-averaged with a timestep of 100 ps to reduce fluctuating noise. Then, the averaged $\rho_I(t)$ at the terminal bin ($I = M_{\text{bin}}$), corresponding to p_{flow} , was employed for the calculation of gradient by linear regression in the range of $5 \leq t \leq 7.5$ ns for the binding simulation and $7.5 \leq t \leq 10$ ns for the unbinding simulation (see Fig. 2a). The binding rate constant k_{off} and k_{on} were calculated respectively, using

$$k_{\text{off}} = \frac{1}{\text{MFPT}_{\text{off}}}, \quad k_{\text{on}} = \frac{1}{\text{MFPT}_{\text{on}}[\text{peptide}]}, \quad (2)$$

where MFPT_{on} and MFPT_{off} represent the values of MFPT obtained in the binding and unbinding simulations, respectively and $[\text{peptide}]$ is the peptide's concentration in the simulation box, $[\text{peptide}] = (1 \text{ molecule})/(\text{the volume of the simulation box}) = 1.9 \times 10^{-3} \text{ M}$. The peptide-bound

state in the computation of the MFPT was redefined according to the HBs based on Table 1, instead of the $\text{RMSD}_{\text{VLQS}}$ value, i.e. by using the conditions that the HBs #3 and #5 in the group 2 and more than one HB (#6 or #7) in the group 3 are formed.

Data availability

The data that support the findings of this study are available from the corresponding author upon reasonable request.

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Author contributions

K.M., T.E., M.I. and A.K. designed research; K.M. performed research; K.M. and A.K. analyzed data; K.M., T.E., M.I. and A.K. wrote the paper.

Competing interests

The authors declare that they have no conflict of interest.

Additional information

Supplementary information is available for this paper at ...

Table 1. Probability of hydrogen-bond formation p_{HB} between 3CL^{pro} and peptide.

Group ^a	No ^b	3CL ^{pro}	Peptide ^c	$p_{\text{HB,crystal}}^{\text{d}}$	$p_{\text{HB,MD}}^{\text{e}}$
1	1	Glu166N	P3 ValO	0.77	1.00
	2	Glu166O	P3 ValN	0.74	1.00
2	3	Gly143N	P1 GlnO	0.56	0.98
	4	Cys145N	P1 GlnO	0.96	0.79
	5	His164O	P1 GlnN	0.87	0.97
3	6	Phe140O	P1 GlnN _ε	0.63	0.67
	7	His163N _ε	P1 GlnO _ε	0.78	0.73
4	8	Gln189O _ε	P2 LeuN	0.55	0.09
	9	Thr190O	P4 AlaN	0.28	0.07

^a ‘Group’ is the classification of the HBs occurring sequentially along the pathway (see text).

^b HBs formed in the crystal structures of the complexes with a peptide or a peptide-mimic compound (17).

^c The position of the amino acid is for the peptide of TSAVLQ↓SG (‘↓’ indicates the substrate cleavage site).

^d $p_{\text{HB,crystal}}$ is the probability of occurrence of HBs in the crystal structure ensemble (17).

^e $p_{\text{HB,MD}}$ for the probability of occurrence of HBs observed in the peptide-bound MD simulations.

Figures and Figure Captions

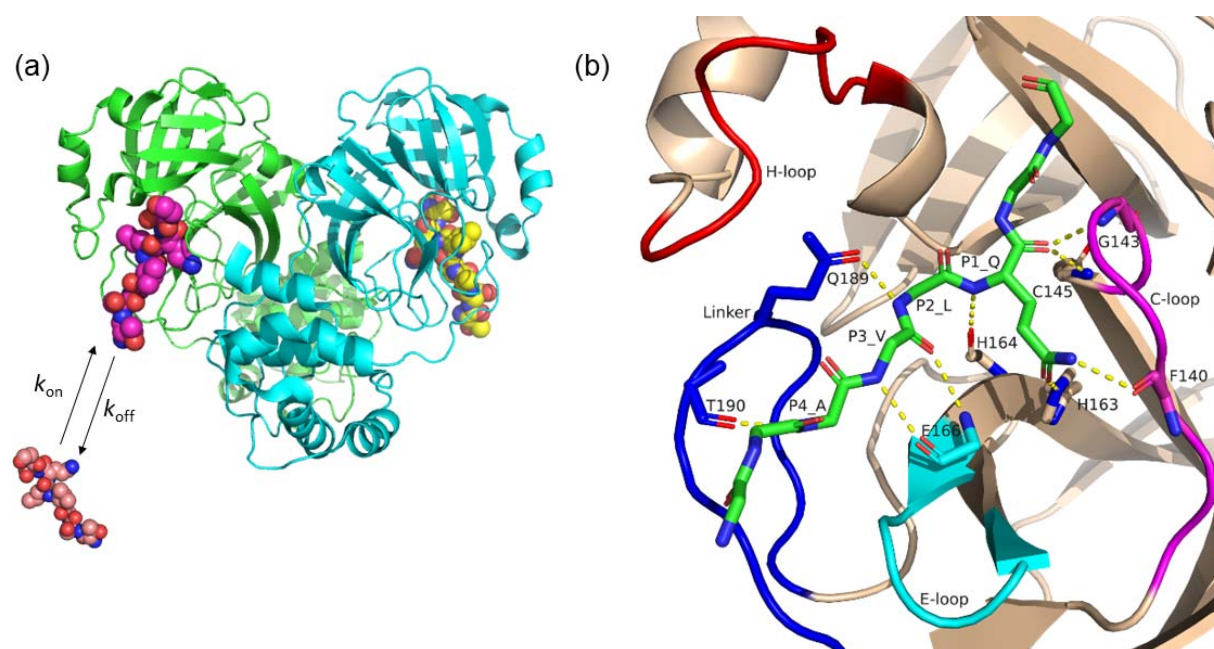


Fig. 1. SARS-CoV-2 3CL^{pro} structure. (a) The 3CL^{pro} dimeric structure in complex with the eight-residue peptide (sphere) bound on each protomer (PDB: 2q6g, 34), where the peptide's three C-terminal residues are excluded in the simulation model. The peptide is coloured magenta (bound on protomer A, by green) and yellow (bound on protomer B, by cyan). The peptide binding/unbinding process to/from protomer A (k_{on} and k_{off} are the associated rate constants, respectively) were simulated while protomer B was kept in the peptide-bound state. (b) A close-up view indicates hydrogen bonds between 3CL^{pro} and the peptide (Table 1) by dashed yellow lines together with the peptide by stick representation. The moving clusters defined in the Motion Tree (see Figs. S1 and S2) are also shown: H-loop (43–51: red), C-loop (138–144: magenta), E-loop (166–171: cyan) and Linker (184–197: blue). Domains 1 and 2 are in wheat and grey, respectively. The peptide is bound at the cleft between the two domains.

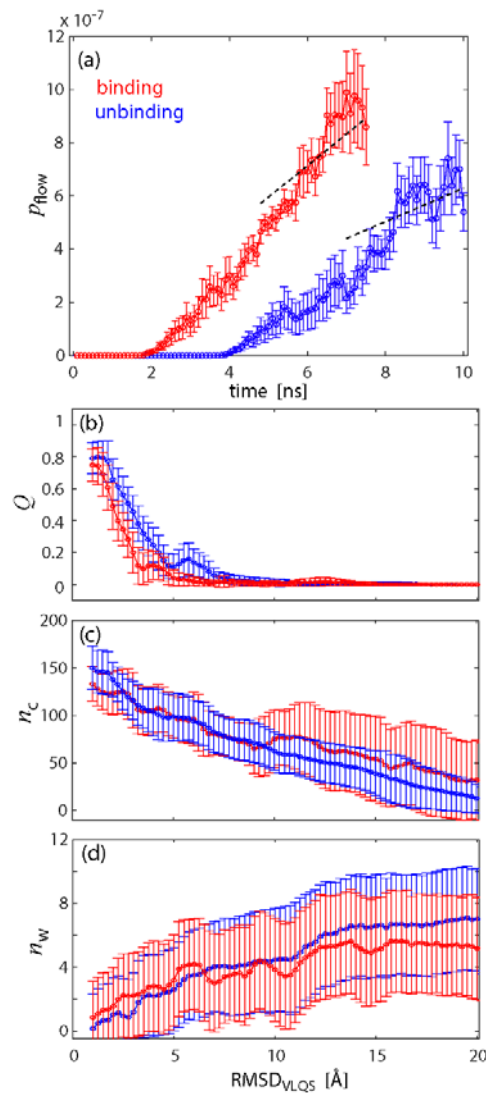


Fig. 2. Peptide binding and unbinding WE simulations. (a) Probability flows, p_{flow} , between the peptide-bound and peptide-free states during the WE simulations of the peptide binding (red) and unbinding (blue). Linear regression lines for the MFPT estimation are shown by dashed lines. The peptide-bound state in this figure was redefined by the conditions that the two HBs in group 2 and more than one HB in group 3 in Table 1 are formed. The error bars were calculated for the three runs of the WE simulations starting at different initial conditions. (b) The ratio of the native contacts formed, Q , which was defined by the 43 native atom contacts with a distance less than 4 Å and more than 70% probability of occurrence in the peptide-bound MD simulation. (c) The number of atom contacts with the peptide, n_c , is calculated for the pairs of non-hydrogen atoms with $r < 4$ Å between the protein and the residues VLQS of the peptide. (d) The amount of hydrated water in the residues VLQS of the peptide in the form of the increment to the average number of hydrated water molecules during the peptide-bound simulation, i.e. $n_w - \langle n_{w(\text{bound})} \rangle$, where $\langle n_{w(\text{bound})} \rangle = 8.1$. Binding (red) and unbinding (blue) processes. The mean and the standard deviation were calculated using all the simulation data.

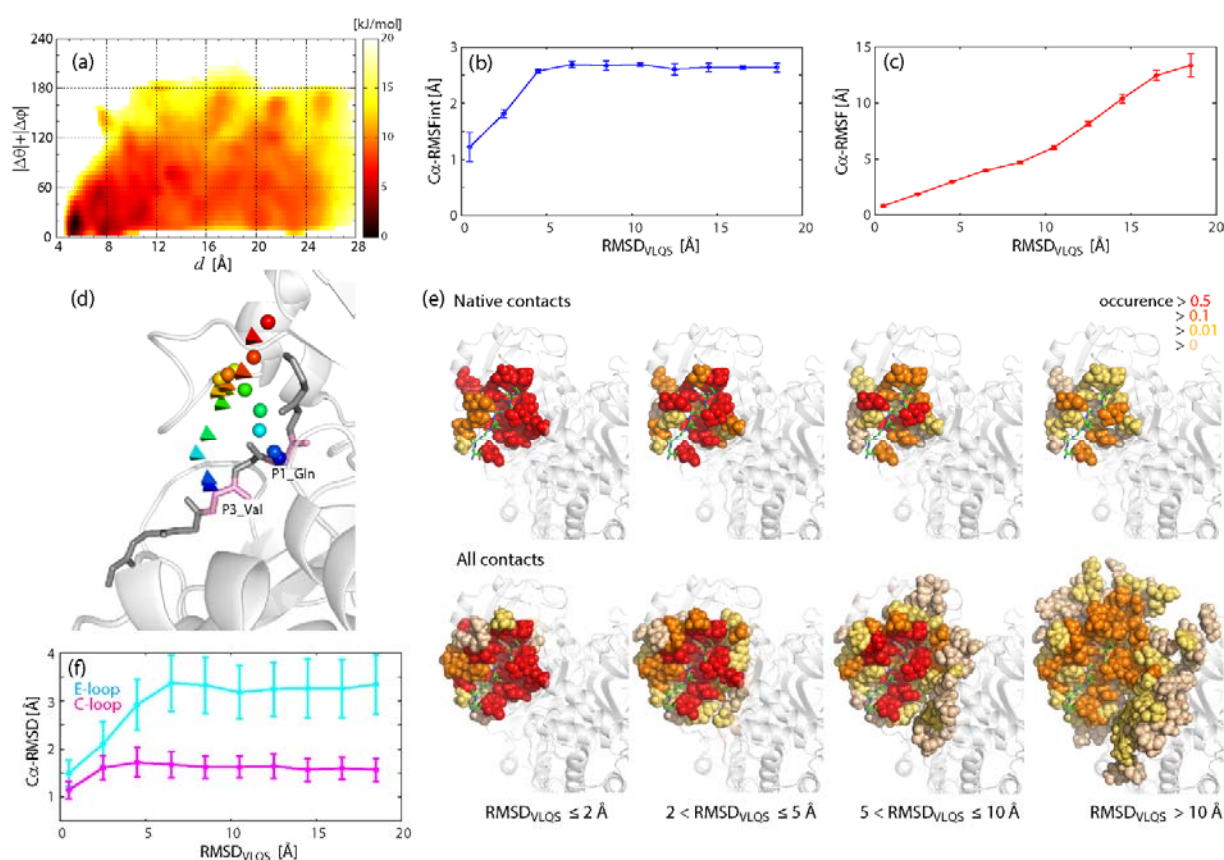


Fig. 3. Peptide binding and unbinding processes. (a) Free energy landscape plotted in the plane describing the peptide configuration, represented by the polar coordinates (d , θ , ϕ) of the vector connecting the center of Cα of Cys145 and Met165 to the center of Cα of P2_Val and P0_Ser. The horizontal axis d is the distance between the peptide and the protein (d is related to $\text{RMSD}_{\text{VLQS}}$ by $d \approx (0.93\text{RMSD}_{\text{VLQS}} + 2) \pm 2.5 \text{ Å}$ for $d \geq 5 \text{ Å}$) and the vertical axis is $|\Delta\theta| + |\Delta\phi|$ representing the rotation of the peptide evaluated by the sum of the absolute deviations of two angles from that of the peptide-bound structure. (b) The peptide's internal flexibility calculated by the root-mean-square fluctuation (RMSF) of the Cα atoms of the residues VLQS after superimposing VLQS, plotted against $\text{RMSD}_{\text{VLQS}}$. (c) The width of the distribution of the peptide configuration, calculated by the Cα-RMSF of the peptide residues VLQS after superimposing the core domain as a function of $\text{RMSD}_{\text{VLQS}}$. In (b) and (c), the error bars were calculated as the standard deviations of the five groups that were generated randomly from the trajectories of the WE simulation. (d) The paths of the Cα atoms on P1_Gln (sphere) and P3_Val (tetrahedra), calculated as their average positions over the simulated peptide structures with a specified range of $\text{RMSD}_{\text{VLQS}}$. Ten marks are drawn with the colours changing from blue to red, respectively corresponding to the ranges of $\text{RMSD}_{\text{VLQS}} = 0.5 + 2n \pm 1 \text{ Å}$ ($n = 0, \dots, 9$), or $0-1.5 \text{ Å}$ (blue), $1.5-3.5 \text{ Å}$, ..., $17.5-19.5 \text{ Å}$ (red). (e) The 3CL^{PRO} residues interacting with the peptide are represented by spheres, separately for each $\text{RMSD}_{\text{VLQS}}$ range. The colours indicate the ratio of occurrences in the WE simulations. The peptide in the peptide-bound form is shown by green sticks. (f) The Cα-RMSD of the E-loop (cyan) and the C-loop (magenta), plotted against $\text{RMSD}_{\text{VLQS}}$.

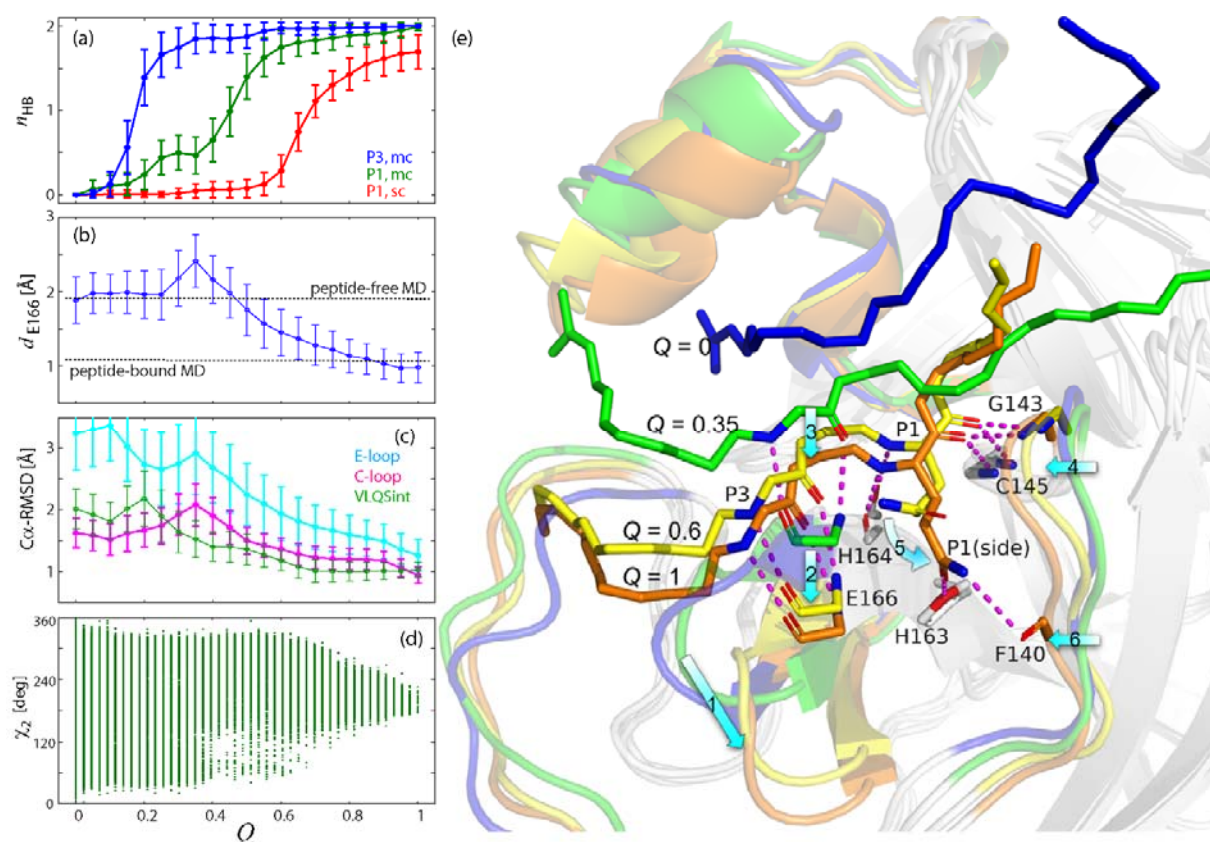


Fig. 4. Peptide recognition process along native contact formations. (a) The number of hydrogen-bond n_{HB} as a function of Q for group1 (the main-chain of P3_Val; HB #1 and #2 in Table 1; blue), group2 (the main-chain of P1_Gln; #3 and #5; green) and group3 (the side-chain of P1_Gln; #6 and #7, red). (b) The distance of the Glu166 Cα atom from that of the peptide-bound state, d_{E166} . (c) The Cα-RMSD values of the E-loop (cyan) and the C-loop (red) after the superimposition to the core region, and the Cα-RMSD of the peptide VLQS residues (green). (d) The sampled χ_2 angle in P1_Gln indicated by dots. (e) Representative structures during the peptide binding at $Q = 0$ (blue), 0.35 (green), 0.6 (yellow) and 1 (orange). The main-chain of the peptide and side-chain of P1_Gln ($Q = 0.6$ and 1) are shown on the stick. The C-loop, E-loop and Linker are drawn by a coloured cartoon and the other part of the protein by a white cartoon. The HBs listed in Table 1 are indicated by magenta broken lines. The structural changes during the binding process are marked by cyan arrows with the numbers 1–6: Glu166 catches P3_Val at the outer region of the cleft ($Q = 0.35$) to form the HBs in group 1 (see Table 1), and the E-loop's motion toward active form (Arrow 1) leads Glu166 (Arrow 2) and P3_Val (Arrow 3) to the binding site. This change accompanies the motion of P1_Gln toward the HB site of group 2 (including the oxyanion hole) causing the shift of the C-loop (Arrow 4; $Q = 0.6$). Finally, the fluctuation of the P1_Gln side-chain is converged to the peptide-bound form and the formation of the HBs in group 3 are complete (Arrow 5; $Q = 1$), which accompany the motion of the C-loop at Phe140 (Arrow 6).