

1 **Title: Applications of a Novel Reciprocating Positive Displacement Pump in the Simulation**
2 **of Pulsatile Arterial Blood Flow**

3

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13 **Abstract**

14 Pulsatile arterial blood flow plays an important role in vascular system mechanobiology,
15 especially in the study of mechanisms of pathology. Limitations in cost, setup time, sample size,
16 and control across current in-vitro and in-vivo methods prevent future exploration of novel
17 treatments. Presented is the verification of a novel reciprocating positive displacement pump
18 aimed at resolving these issues through the simulation of human ocular, human fingertip and skin
19 surface, human cerebral, and rodent spleen organ systems. A range of pulsatile amplitudes,
20 frequencies, and flow rates were simulated using pumps made of 3D printed parts incorporating
21 a tubing system, check valve and proprietary software. Volumetric analysis of 430 total readings
22 across a flow range of 0.025ml/min to 16ml/min determined that the pump had a mean absolute
23 error and mean relative error of 0.041 ml/min and 1.385%, respectively. Linear regression of
24 flow rate ranges yielded R^2 between 0.9987 and 0.9998. Waveform analysis indicated that the
25 pump could recreate accurate beat frequency for flow ranges above 0.06ml/min at 70BPM. The
26 verification of accurate pump output opens avenues for the development of novel long-term in-
27 vitro benchtop models capable of looking at fluid flow scenarios previously unfeasible, including
28 low volume-high shear rate pulsatile flow.

29 **Keywords**

30 Low volume flow, In Vitro Modelling, Human ocular blood flow, Human fingertip blood flow,
31 Human cerebral blood flow, Splenic blood flow, Rodent blood flow

32 **Background**

33 Pulsatile arterial blood flow has been shown to have inherent properties that are integral to the
34 normal function of specific organ and tissue systems[1,2]. The ability to generate pulsatile flow
35 is important in the development of in-vitro models to simulate real-life conditions. However,
36 many modern fluidic devices resort to utilizing constant or harmonic-based fluid flow. This is
37 especially true in low volume conditions due to limitations in producing physiologically accurate
38 low volume flow[3].

39 While extremely useful when studying systemic impact, animal studies are limited in their ability
40 to directly and simultaneously mimic human physiologic arterial blood flow. These studies are
41 also usually very time-intensive to setup and are limited in the range of physiologic and
42 pathophysiologic scenarios that can be measured and tested dynamically. In-vitro models
43 maintain control and dynamic recording potential. However, significant cost and time investment
44 required to build, verify, and validate a test setup prior to conducting flow based biomechanistic
45 in-vitro studies limits their usage.

46 This study presents the testing and verification of a novel positive displacement pump and
47 operating program through the simulation of literature-based blood flow data of organ systems
48 spanning human ocular, human fingertip and skin surface, human cerebral, and rodent spleen.
49 These blood flow data span arbitrarily defined low (0ml/min – 0.4ml/min), mid (0.4ml/min –
50 1.3ml/min) and high (3ml/min – 16ml/min) flow rate ranges aimed to provide flow rate
51 performance for different flow applications. The use of a syringe-based positive displacement
52 method of driving fluid flow in conjunction with the precise control of programmable input
53 variables through a user interface allow for the generation of a wide-range of pulsatile low
54 volume fluid flow rates and waveforms. Furthermore, the incorporation of a robust check valve
55 system enables the ability for the pump to automatically reset back to its original position
56 allowing the pump to function in long term fluid flow experiments.

57 **Materials and Methods**

58 **Reciprocating Positive Displacement Pump**

59 The body of each reciprocating positive displacement pump is comprised of 3D printed parts
60 made of polylactic acid plastic (PLA) manufactured using an Anycubic I3 Mega printer
61 (Anycubic Technology CO., Limited, HongKong)[4]. The design consists of five 3ml syringes
62 per pump, allowing flow output from five total channels per pump (Fig 1.). A stepper motor,
63 linear bearings, motor coupler, and lead screw assembled in line with each channel allow for the
64 conversion of rotational motion into linear movement.

65 **Fig 1. Reciprocating Positive Displacement Pump.** Front view (a) and rear view (b) of fully
66 assembled reciprocating positive displacement pump

67 A proprietary software allowing for the direct input through a simple user interface of user
68 profile variables consisting of output bulk volume rate, pulsation frequency, and pulsation
69 amplitude was developed using Python. Based on user input per profile, rotational speed and
70 duration were calculated by the software. Mechanical inefficiencies of the pump and other
71 components were account for through the program. This information is then sent to an Arduino-
72 based board which is then interpreted and used to drive stepper motor movement. Each Arduino-
73 based board is capable of simultaneously running three pumps, a total of 15 channels per board.
74 An automatic sterilization function was also built within the program consisting of a constant

75 reciprocating action of the pump for a total of 20 minutes, cycling 99% isopropyl alcohol
76 throughout the duration of the cleaning function. This is followed by three cycles of deionized
77 water to expel any remaining isopropyl alcohol from the tubing system.

78 Once the syringes have reached their fully compressed state, the program then automatically
79 resets the pump back to its original position, extending the syringes fully. The use of individual
80 check valves immediately after the output from the syringes enables this retracting motion of the
81 pump to automatically refill the syringes. This retraction time takes a total of approximately
82 eight seconds. Each check valve limits the chances of cross-contamination between sample
83 outputs and between input and output within each channel. Luer locking fittings used by the
84 check valves and syringes allowed for simple and robust fluidic connections between all
85 components. Input and output for each individual channel consisted of 50cm 3mm inner diameter
86 silicone tubing into their respective check valves.

87 **Systolic Time Interval**

88 An important variable in the accuracy of individual pulsations is systolic time interval. An
89 analogous representation of ventricular systolic time interval is created through the
90 implementation of the systole time user input variable. This allows for direct control over beat
91 cycle length independent of volume rate or frequency. Ideally, beat cycle duration can be
92 approximately equal to two times the input systole time, although external variables such as
93 system compliance may affect this.

94 **Amplitude**

95 Amplitude of individual pulsations is based on the multivariable user input per profile.
96 Amplitude is directly correlated to volume rate and compliance of the tubing and flow system,
97 and inversely correlated to both systole time and beat frequency. The dampening factor is a
98 representation of compliance of the entire tubing system, and refers to the tubing system itself,
99 attached chambers to the tubing and fluid viscosity. All these variables such as tubing diameter
100 can be manipulated to better fit the intended modelling parameters. The full relationship between
101 these variables and their effects on amplitude can be seen in Equation 1:

$$102 \quad \blacktriangleright \text{Amplitude} \left(\frac{\text{ml}}{\text{min}} \right) = \frac{\text{Volume rate} \left(\frac{\text{ml}}{\text{min}} \right) \times \frac{60 \text{ seconds}}{\text{min}}}{\text{Systole time (seconds)} \times \text{Heart rate} \left(\frac{\text{Beats}}{\text{min}} \right)} \times \text{Dampening Factor}$$

103 The incorporation of a method of simply and directly manipulating pulsatile amplitude allows for
 104 the freedom to explore domains of clinical applications previously unexplored.

105 **Testing Parameters**

106 In our previous study, the accuracy of the reciprocating positive displacement pump was
 107 demonstrated across a range of 0.01ml/min to 0.7ml/min with an R² value of 0.9998[5]. To
 108 expand the verified flow rate range and investigate the capabilities of the pump in novel
 109 applications of arterial blood flow in organ systems, a literature search was conducted collecting
 110 flow rate data spanning three ranges; low (0ml/min – 0.4ml/min), mid (0.4ml/min – 1.5ml/min)
 111 and high (3ml/min – 16ml/min) bulk flow rates. The organ systems used to populate these
 112 arterial blood flow ranges are human ocular, human fingertip, human cerebral, and rodent spleen
 113 (Table 1). Unless otherwise noted, an input of 70BPM and 0.1 second systolic time were used for
 114 all human simulations and 380BPM and 0.054 second systolic time for all rat-based
 115 simulations[6–8]. While any heartrate within physiologic domain could have been selected, an
 116 average resting 70BPM for humans and 380BPM for rats was chosen unless otherwise specified.
 117 Systolic time was not provided in any study simulated throughout the flow ranges, therefore
 118 requiring the use of arbitrary systolic times of 0.1 seconds for human and 0.054 seconds for rat-
 119 based simulations.

120 **Table 1. Organ systems scenarios and corresponding flow rate, beat rate, and systolic time**
 121 **input profiles into reciprocating positive displacement pump**

Input Flow Profile for each organ system, measuring device and condition	Flow Rate (ml/min)	Beat Rate (BPM)	Systolic Time (seconds)	Reference
Low Flow Range (0ml/min – 0.4ml/min)				
Fingertip blood flow autoregulation (post-caffeine)	0.029±0.004	71	0.1	[9]
Retinal Blood Flow by Laser Doppler Velocimetry	0.033	70	0.1	[10,11]
Fingertip Blood Flow by Venous-occlusion volume plethysmography (lower)	0.056	70	0.1	[12]

Fingertip blood flow autoregulation (pre-caffeine)	0.067±0.009	74	0.1	[9]
Retinal Blood Flow by Laser Doppler Velocimetry	0.08 ±0.012	70	0.1	[13]
Fingertip blood flow autoregulation (baseline)	0.088±0.015	76	0.1	[9]
Fingertip Blood Flow by Venous-occlusion volume plethysmography (Critical vasoconstriction Temperature)	0.2	70	0.1	[12]
Retinal Blood Flow by Phase Contrast MRI	0.261±0.087	70	0.1	[14]
Mid Flow Range (0.4ml/min – 1.4ml/min)				
Fingertip Blood Flow by Venous-occlusion volume plethysmography	0.42	70	0.1	[12]
Total Pulsatile Ocular Blood Flow by MRI (lower)	0.444	70	0.1	[14]
Rat Splenic Arteriovenous Flow Differential in Rats (<i>pre-caudal ligation</i>)	0.6±0.1	380	0.054	[15]
Splenic Arteriovenous Flow Differential in Rats (<i>pre-caudal ligation</i>)	0.8±0.3	380	0.054	[15]
Total Pulsatile Ocular Blood Flow by MRI (upper)	0.803	70	0.1	[14]
Ocular Choroidal Blood Flow by MRI	0.917±0.281	70	0.1	[14]
Total Pulsatile Ocular Blood Flow by Langham Pneumotonometer	1	70	0.1	[16,17]
Splenic Arteriovenous Flow Differential in Rats (<i>post-caudal ligation</i>)	1.0±0.2	380	0.054	[15]
Splenic Arteriovenous Flow Differential in Rats (<i>post-rostral ligation</i>)	1.2±0.1	380	0.054	[15]
High Flow Range (3ml/min – 16ml/min)				
Middle Meningeal Artery	6±3	70	0.1	[18]
Ophthalmic Artery	11±5	70	0.1	[18]

123 These systolic times are used as a representation of true systolic time, however changes in
124 systolic times can be made for direct manipulation of pulsatile amplitude independent of flow
125 volume rate and beat rate. Degassed, deionized water, measured and verified at 1 gram/milliliter
126 of water at room temperature, was used to measure the accuracy and precision of pump output. A
127 total of 10, ten-minute weight measurements were performed across 10 pump channels using the
128 pump and tubing setup schematic seen in Fig 2. per input user profile. The sterilization function
129 described earlier was used to properly clean and prime pumps before each testing session.
130 Individual beakers were used per channel, weighed after the time period of each test was
131 completed. Weight measurements were conducted using a Mettler Toledo AT261 DeltaRange
132 Analytical Balance (Mettler-Toledo, LLC, USA).

133 **Fig 2. Schematic diagram of testing setup.** Illustrates flow of fluids and data collection
134 locations of user input verification

135 Each individual profile tested also had flow data obtained from a flow sensor placed at the
136 immediate output of a channel check valve for each individual profile tested. The flow sensor
137 used to collect flow data was Sensirion SLF06 series flow sensor (Sensirion AG, Switzerland).
138 Flow data was used to determine consistency of amplitude and volume rate within the same test,
139 accurate beat rate throughout the duration of each test, and differences of volume rate and
140 amplitude across different profiles.

141 **Results**

142 **Volumetric Analysis**

143 The pump was able to simulate the volumetric flow rates for the low, mid, and high bulk flow
144 rate ranges spanning a total range of 0.025ml/min to 16ml/min for the organ systems of the
145 human eye, human fingertip and skin surface, rat spleen and human cerebral blood flow rates
146 (Fig 3, Table 2).

147 **Fig 3. Expected vs. Measured low, mid, and high bulk flow rate ranges.** Illustrates the
148 expected versus mean of measured volume rate across 10 channels for low flow ranges (0ml/min
149 – 0.4ml/min) (a), mid flow ranges (0.4ml/min – 1.4ml/min) (b), and high flow ranges (3ml/min –
150 16ml/min) (c) with a linear function showing a regression and R^2 value for each plot

151 **Table 2 – Verified organ systems explored in this paper within achievable range of**
 152 **reciprocating positive displacement pump**

Organ System	Minimum Input Flow Rate ($\frac{ml}{min}$)	Maximum Input Flow Rate ($\frac{ml}{min}$)	Pump Achieves Physiologic Flow
Retinal Blood Flow	0.033	0.348	Yes
Ocular Choroidal Blood Flow	0.636	1.198	Yes
Total Pulsatile Ocular Blood Flow	0.444	1	Yes
Fingertip Blood Flow	0.025	0.42	Yes
Splenic Arteriovenous Flow Differential in Rats	0.5	1.3	Yes
Ophthalmic Artery	6	16	Yes
Middle Meningeal Artery	3	9	Yes

153
 154 Across the entire range of flow rates, a total of 430 ten-minute weight measurements taken from
 155 the pumps had a mean absolute error and mean relative error of 0.040854 ml/min and
 156 1.385164% respectively. The linear regression of the low, mid, and high flow rate ranges (Fig 3,
 157 a-c, respectively) tested yielded R² values 0.9998, 0.9988 and 0.9987, respectively. The standard
 158 deviation across the total range of 0.025ml/min to 16ml/min was 0.00151ml/min to
 159 0.14196ml/min presented in Fig 4(a). Relative standard deviation indicates the pumps' precision
 160 across the range of tested flow rates (Fig 4(b)). A novel verified range for pump input parameters
 161 can be seen in Table 3.

162 **Fig 4. Standard Deviation across full bulk flow rate range.** Illustrates the standard
 163 deviation(a) and relative standard deviation(b) across full range of tested flow ranges

164 **Table 3 – Verified pulsation rate, volume rate and amplitude range achievable by the**
 165 **reciprocating positive displacement pump**

Category	Minimum	Maximum	Capable of Achieving?
Pulsation Rate ($\frac{Beats}{min}$)	1	400	Yes
Output Volume Rate ($\frac{ml}{min}$)	0.01	16	Yes
Amplitude ($\frac{ml}{min}$)	0.02	65	Yes

166

167 **Pulsatile Flow**

168 Flow measurements from the pump illustrated accurate pulsatile flow according to beat rate and
 169 volume rate in humans and rats (Fig 5-7). Flow rates under 0.06ml/min with an input of 70BPM
 170 were too small and were unable to simulate accurate 70BPM pulsatile waveform flow.

171 Therefore, waveforms presented in Fig 5 (a-c) do not have the correct beat counts in the relative
 172 time frames, although the pump remains volumetrically correct due to inbuilt catchup functions
 173 within the proprietary program. However, A total of ~23 total beats were counted across the 20
 174 seconds displayed for all other displayed flow patterns, equating to the input value of ~70BPM.

175 **Fig 5. Low flow range pulsatile waveform patterns.** Visual representation of flow waveform
 176 pattern of mean flow in order from lowest to highest bulk volume rate simulated in low flow rate
 177 range; effects of caffeine on fingertip blood flow autoregulation (post-caffeine) (a), retinal blood
 178 flow by laser doppler velocimetry (b), fingertip blood flow by venous occlusion
 179 plethysmography (c), effects of caffeine on fingertip blood flow autoregulation (pre-caffeine)
 180 (d), retinal blood flow by laser doppler velocimetry (e), effects of caffeine on fingertip blood
 181 flow autoregulation (baseline) (f), critical vasoconstriction temperature for fingertip blood flow
 182 (g), retinal blood flow by phase contrast MRI (h)

183 **Fig 6. Mid flow range pulsatile waveform patterns.** Visual representation of flow waveform
 184 pattern of mean flow in order from lowest to highest bulk volume rate simulated in mid flow rate
 185 range; fingertip blood flow by venous occlusion plethysmography (a), total pulsatile ocular blood
 186 flow by phase contrast MRI (b), splenic arteriovenous flow differential in rats (pre-caudal
 187 ligation) (c), splenic arteriovenous flow differential in rats (pre-rostral ligation) (d), total pulsatile
 188 ocular blood flow by phase contrast MRI (e), ocular choroidal blood flow by phase contrast MRI
 189 (f), total pulsatile ocular blood flow by Langham pneumotonometer (g), splenic arteriovenous
 190 flow differential in rats (post-caudal ligation) (h), splenic arteriovenous flow differential in rats
 191 (post-rostral ligation) (i)

192 **Fig 7. High flow range pulsatile waveform patterns.** Visual representation of flow waveform
193 pattern of mean flow in order from lowest to highest bulk volume rate simulated in high flow
194 rate range; Middle meningeal Artery (a), Ophthalmic Artery (b)

195 To better illustrate the effects of input volume changes on individual pulsation amplitude and
196 pattern, Fig 8 (a-d) illustrates a 1 second, single beat comparison of mean, upper and lower flow
197 rate limits of standard deviation of measurement in ocular choroidal, total pulsatile ocular, and
198 retinal blood flow rates. One second, single beat comparisons were not shown for organ system
199 simulations where flow rates dropped below 0.06ml/min, waveform amplitudes exceeded the
200 flow rate limit of the flow sensor used (65ml/min), or similarity in single beat waveforms made
201 the subsequent graph unclear. Fig 9 illustrates the direct simulation done using the reciprocating
202 pump of retinal blood flow rates patterns from previous literature, matching fluid rise times, peak
203 amplitude, and total beat time similar to the Figure presented by Rebhan et. al[19].

204 **Fig 8. Visualization of single second pulsatile waveform patterns.** Visual Representation of
205 comparison of lower, mean, and upper limits of flow waveform patterns across 1 second for
206 choroidal blood flow rates (a), total pulsatile ocular blood flow measurements (b), retinal blood
207 flow gathered through MRI (c), retinal blood flow gathered using Laser Doppler velocimetry (d)

208 **Fig 9. Waveform pattern simulation.** Visual representation of simulation using reciprocating
209 pump of one-second flow waveform patterns of retinal blood flow in a healthy, diabetic, and
210 glaucoma patient scenarios generated from a computational framework

211

212 In the simulation seen in Fig 7 (b), very high flow rates (above 6ml/min) were high enough to
213 require the use of the reciprocating action of the pump before the full 20 seconds has elapsed,
214 requiring the pump to return to its original, fully retracted position state and explains the lack of
215 pulsatile flow across the full 20 seconds.

216 **Discussion**

217 Using the testing setup, volumetric analysis of pump output was accurate within a standard
218 deviation range of 0.00151ml/min to 0.14196ml/min through the low (0ml/min – 0.4ml/min),
219 mid (0.4ml/min – 1.3ml/min) and high (3ml/min – 16ml/min) bulk flow rate ranges within the
220 organ systems tested (Fig 3). Through this, the pump has shown to provide accurate flow in
221 ranges in which the development of mechanistic in-vitro models and products requires. Although
222 specific organ systems were used to define the flow ranges tested, these simulations for organ

223 systems are used as example vascular bodies and the versatility of the pump expands beyond
224 these examples. This versatility is also created through the implementation of the reciprocating
225 action of the pump once syringe limits have been reached. The reciprocating action of the pump
226 takes approximately eight seconds and stops flow for that duration of time. However, the total
227 bulk flow output, beat frequency and time input of flow are not affected.

228 This is one way in which the reciprocating positive displacement pump system distinguishes
229 itself, making it ideal for use in long term fluid modeling scenarios where output variables from
230 the model are dependent on input pulsatile flow. The use of the proprietary program along with
231 its ability to take in user input for heart rate, volume rate and amplitude, also employs a user-
232 input time variable where the program can calculate the exact number of pulsations within the
233 input time frame and executing them, excluding time of retraction. This in turn, allows for
234 precision in long term applications of the pump and makes the versatility of pump applications
235 span much wider than the organ systems described throughout this paper, although the
236 applications within the organ systems are vast in themselves.

237 **Human Ocular and Retinal Blood Flow**

238 Unlike previous pump flow systems, non-harmonic pulsatile flow can be achieved, through the
239 manipulation of volume rate, beat rate and amplitude. This means that low volume pulsatile flow
240 simulations are no longer limited by the method of simulating them, but rather the accuracy of
241 the measurement method itself and its application, assuming it is within the achievable range of
242 the pump. This can be seen through the successful simulation of multiple methods of measuring
243 retinal and total pulsatile ocular blood flow seen in Table 1 and Fig 3. Individual pulsations
244 utilizing our reciprocating pump are also capable of being simulated at low flow rates, through
245 the manipulation of BPM and amplitude input. This allowed the pump to reproduce the
246 individual pulsations of blood flow through the human retina seen in Fig 9. Previous literature
247 has shown that flow shear stress is an important indicator of vascular disease[20,21]. Our pump,
248 with its ability to directly manipulate flow amplitude, a key component to shear stress in arteries,
249 provides an avenue in which its incorporation into a flow based in-vitro model can provide
250 comprehensive insight into the role shear stress plays in retinal disorders. The use of this system
251 in conjunction with an integrated in-vitro model of the human eye does not need to be confined
252 within the domain of the retina. The successful simulation of choroidal blood flow rates and

253 waveforms makes the pump ideal to be integrated into an in-vitro model, an example an in-vitro
254 investigation of retinal detachment. Retinal detachment has been shown to be correlated to
255 central ocular choroidal blood flow with atrophy of the retinal pigment epithelium[22]. Because
256 of current limitations in the simulation of low volume fluid flow models, static in-vitro models
257 with short perfusion times are often resorted to when looking at this phenomenon[23]. The
258 pumps implementation in in-vitro models can provide a more comprehensive understanding of
259 the effects of blood flow on retinal detachment and other diseases. Innovations in vascular
260 development and perfusion methods for future in-vitro models can further increase model
261 accuracy and applicability of the pump. One early possibility can be seen through the
262 development of optical vascular structures developed using optical coherence tomography[24].
263 The pulsatile nature of the fluid flow has yet to be accounted for in an in-vitro setup involving
264 the human eye, although waveform dynamics have been shown to affect patient outcome in
265 specific scenarios[25].

266 **Human Fingertip and Skin Surface Blood Flow**

267 The reciprocating positive displacement pump is also capable of simulating fingertip and skin
268 surface blood flow under varying physiologic and pathophysiologic scenarios. An example
269 application within this specific vascular domain is in the bioprinting of skin grafts for burn
270 victims, where functional vascular endothelial cells require perfusion with a peristaltic
271 pump[26]. The use of peristaltic pumps has been compared to harmonic wave flow because of its
272 low peak-to-peak amplitude per pulse and lack of a significant flow drop between pulsations[27].
273 Pulsatile shear rate has been shown to increase the proliferation of vascular endothelial cells,
274 meaning the implementation of the reciprocating positive displacement pump in a cell perfusion
275 setup used for 3D printed cells can perhaps improve the rate and complexity at which vasculature
276 develops, and in turn accelerate the progression towards a viable bio-printed skin-graft[23,28].
277 Not only can the increased shear rates of output fluid flow affect the rate at which vascular tissue
278 develops, but also the contents of the fluids used to perfuse the cellular structure. In our setup,
279 the simple silicone tubing system used alongside the reciprocating positive-displacement pump
280 allows for a vast array of fluids with physiologic or pathophysiologic makeup. An example fluid
281 explored in the previous literature is cerebrospinal fluid (CSF), where the reciprocating positive
282 displacement pump can be used to model pulsatile flow, shear rate, shear stress, and amplitude

283 simultaneous to variations in CSF composition as this is directly relevant to pathologic states like
284 those in hydrocephalus[5,29].

285 **Splenic Blood Flow in Rats**

286 Non-human simulations using our pump are presented because of possible limitations in the
287 collection of flow data in humans in-vivo and in turn, limitations of data for a range of organ
288 systems. Animal models are the main alternative to in-vitro modeling; although useful in their
289 ability to model systemic effects and device compatibility, are time-intensive to setup, limited in
290 the range of conditions testable, and whose flow conditions may not map to humans linearly.
291 Modeling animal flow rates gives us flexibility to eliminate unknown variables, and perhaps may
292 reflect on human data if there are anatomical similarities between species. An example of this
293 within this organ system domain are splenic baroreceptors and their control over splenic afferent
294 nerve activity[30]. Novel developments in carbon-based organic semiconductors can be
295 implemented as an afferent nerve substitute where their efficacy relative to the original nerve in a
296 rat-based in-vitro model with pulsatile fluid flow can be modeled by the reciprocating positive
297 displacement pump[31].

298 **Human Cerebral Arterial Blood Flow**

299 The ability to isolate flow from different sources provides further versatility of the reciprocating
300 positive displacement pump, as seen in the ophthalmic artery simulation as well as the total
301 pulsatile ocular and retinal blood flow simulations presented in Table 1 and Fig 3. The use of
302 anticancer chemotherapy drugs has been shown to have complications with many organs in the
303 human body, one being the induction of ocular toxicity and other complications with the eye and
304 retina[32,33]. Past in vitro models of the human eye used primary human retinal endothelial
305 cells, employing relatively short perfusion times of chemotherapeutic agents[34]. The pump can
306 act as a method to perfuse the cells over a much longer period and can be a more comprehensive
307 in-vitro test with more accurate flow shear rates throughout treatment. The isolated effects of a
308 chemotherapeutic drug can also be measured, through the pumps ability to isolate specific flow
309 rates of different vascular systems and arteries and get a much more tailored flow modelling
310 setup. The simulation of the middle meningeal artery has fewer applications for the simulation in

311 and of itself, although this additional application confirms that the pump is capable of simulating
312 flow rates necessary for the study of disease not well implemented to date.

313 **Limitations of the Reciprocating Positive Displacement Pump**

314 The pump is required to retract back to its initial state and reset after a set time simulating
315 pulsatile fluid flow depending on the volume flow rate input profile used. This retraction time,
316 and in turn pause time on the induction of fluid flow, lasts around eight seconds in the current
317 setup. Although this is a minimal pause in fluid flow production, future iterations of the pump
318 and proprietary program design can significantly reduce this time to near zero ensuring a
319 constant pulsatile fluid flow is delivered to a fluid setup or model being investigated. The current
320 syringe volume of 3ml in the pump limits the range of higher flow rate models that can be
321 simulated, something a peristaltic pump can achieve through the sequential addition of peristaltic
322 pump outputs in series. This can be addressed in future iterations of the pump by increasing
323 syringe volume or using the same approach as a sequential peristaltic pump system where
324 combining channels of the same pump and channels from multiple pumps would deliver a
325 significantly larger volume of pulsatile fluid flow.

326 **Conclusion**

327 In conclusion, the verification of the reciprocating positive displacement pump determined it was
328 accurate in the simulation of arterial blood flow in human ocular, human fingertip and skin
329 surface, human cerebral, and rodent spleen organ systems. This provides new freedom in the
330 development of novel in-vitro benchtop models involving pulsatile fluid flow and can accelerate
331 the development of translatable treatments to improve patient outcome.

332 **Declarations**

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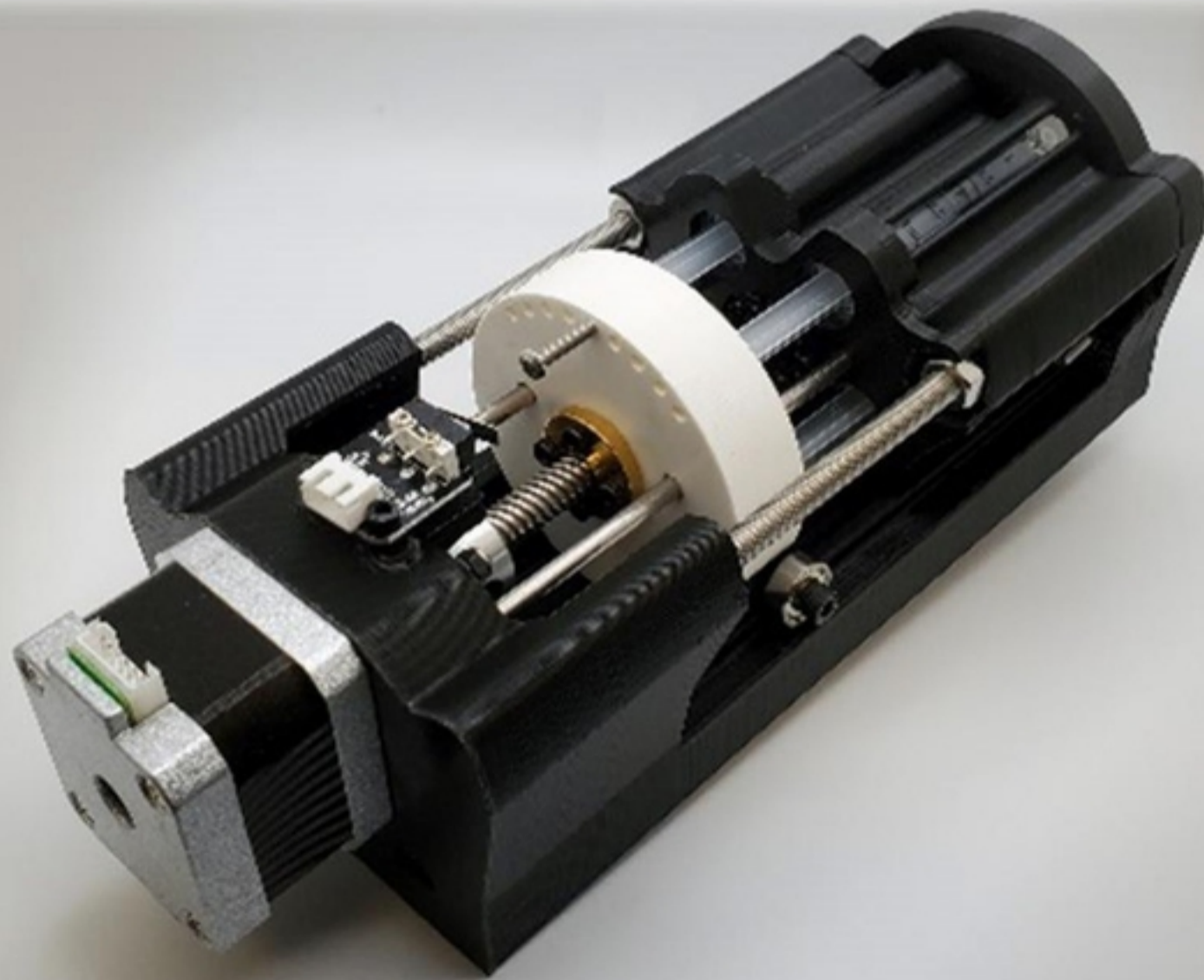
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(a)



(b)

Figure 1

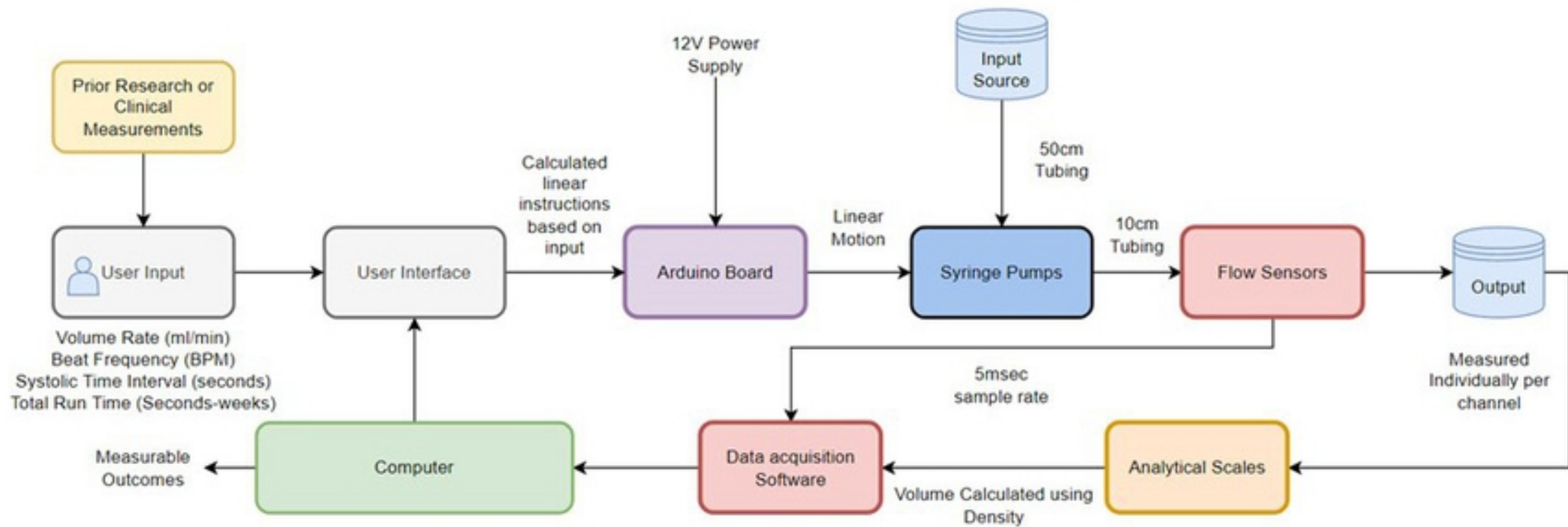
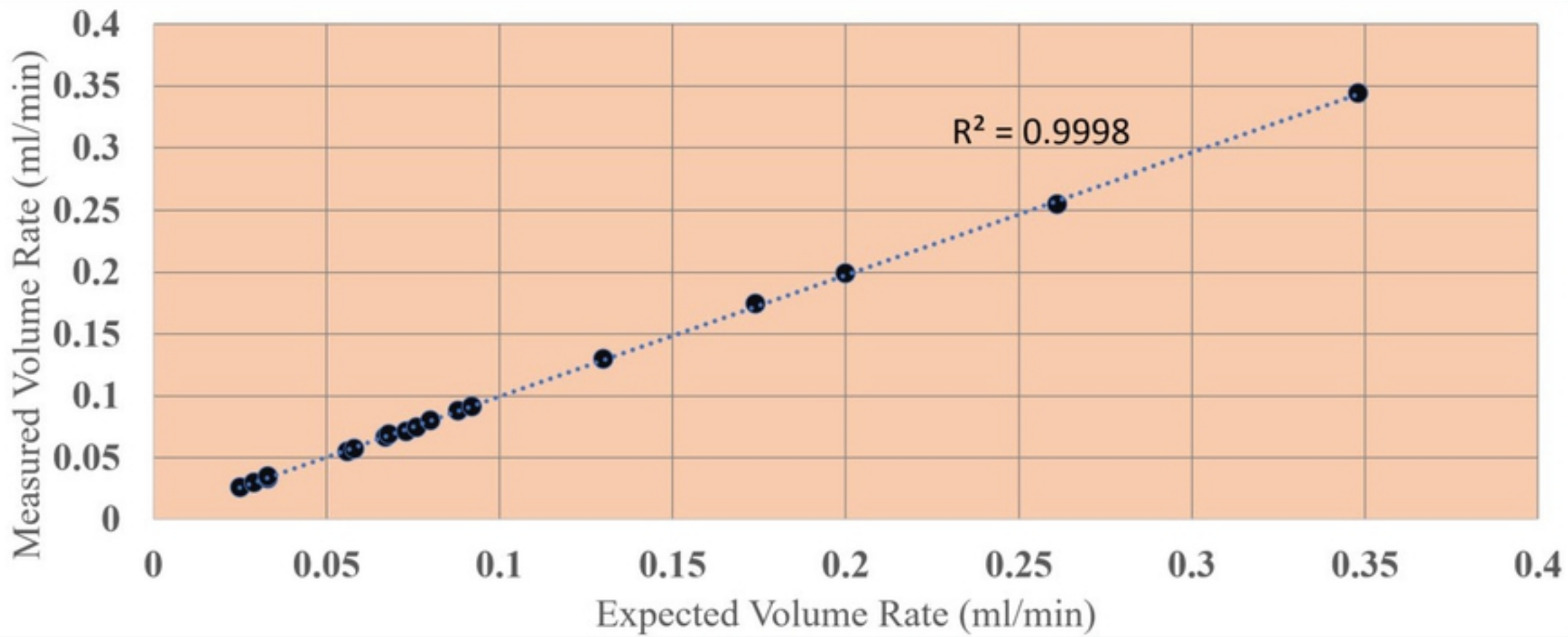
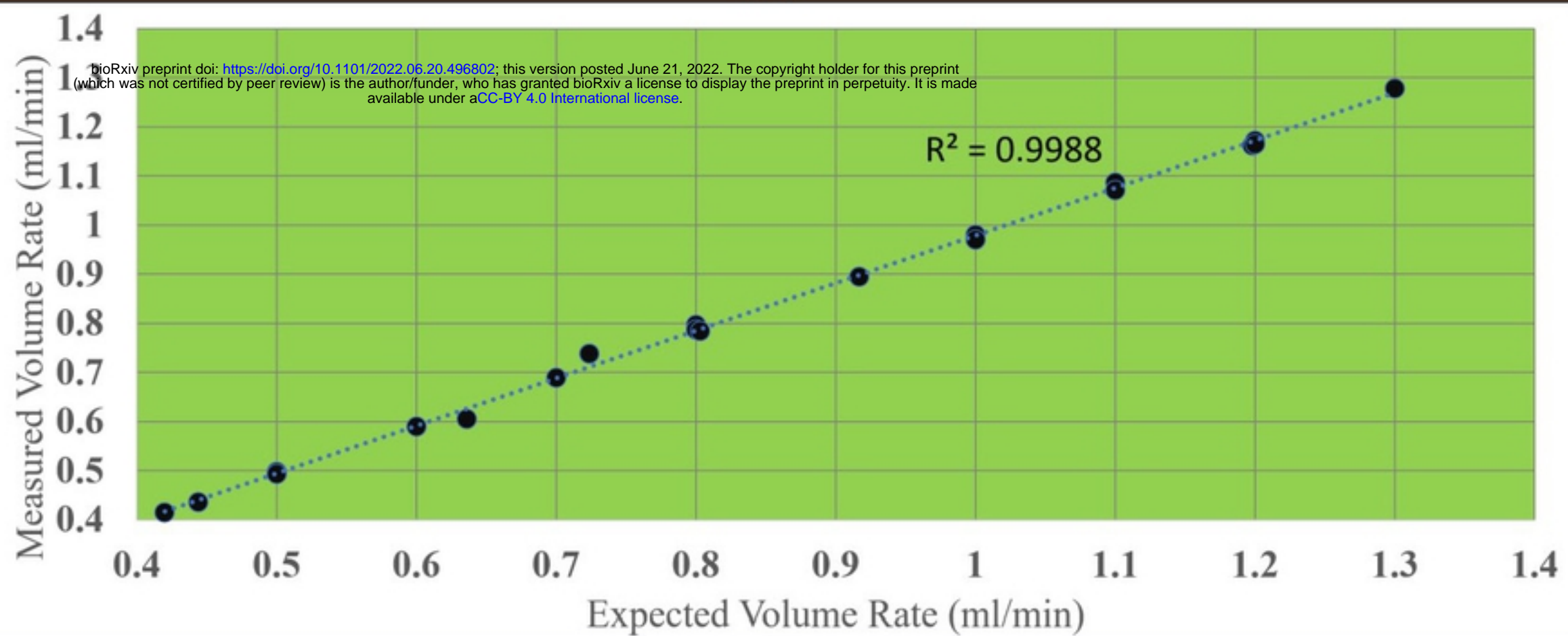


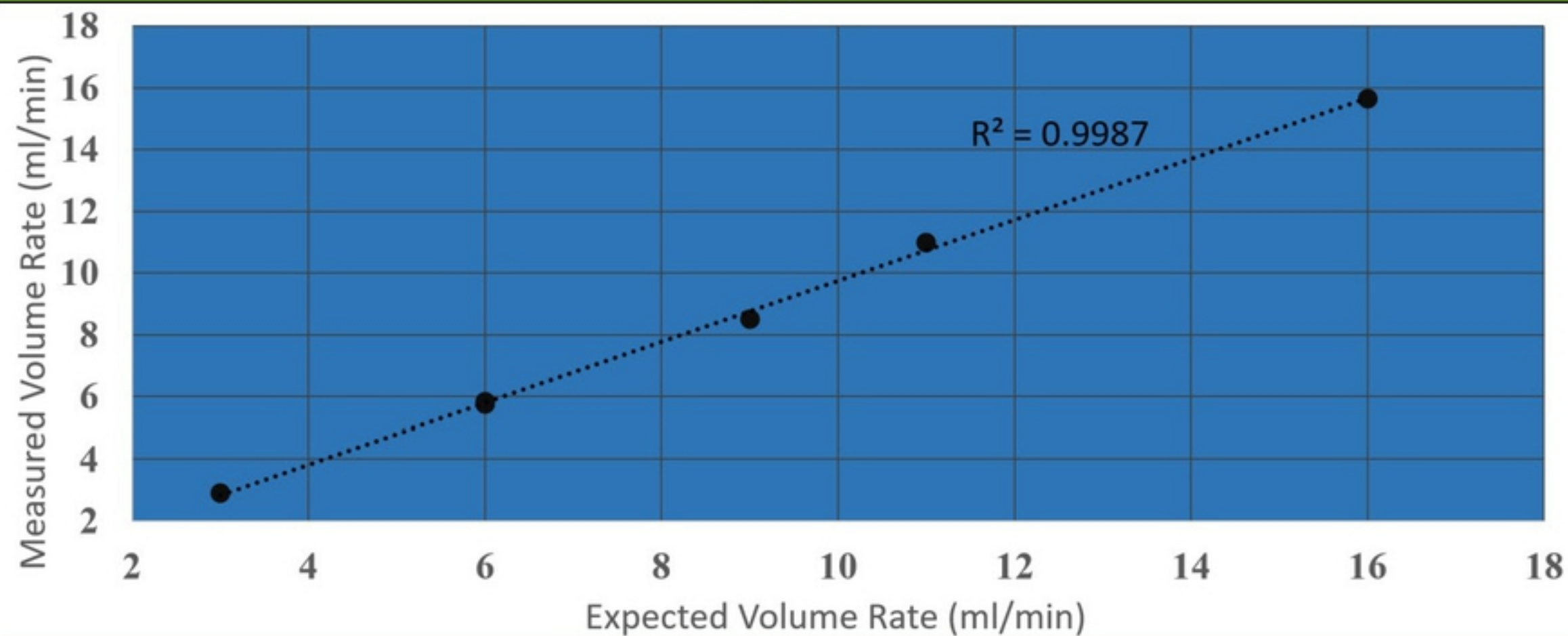
Figure 2



(a)



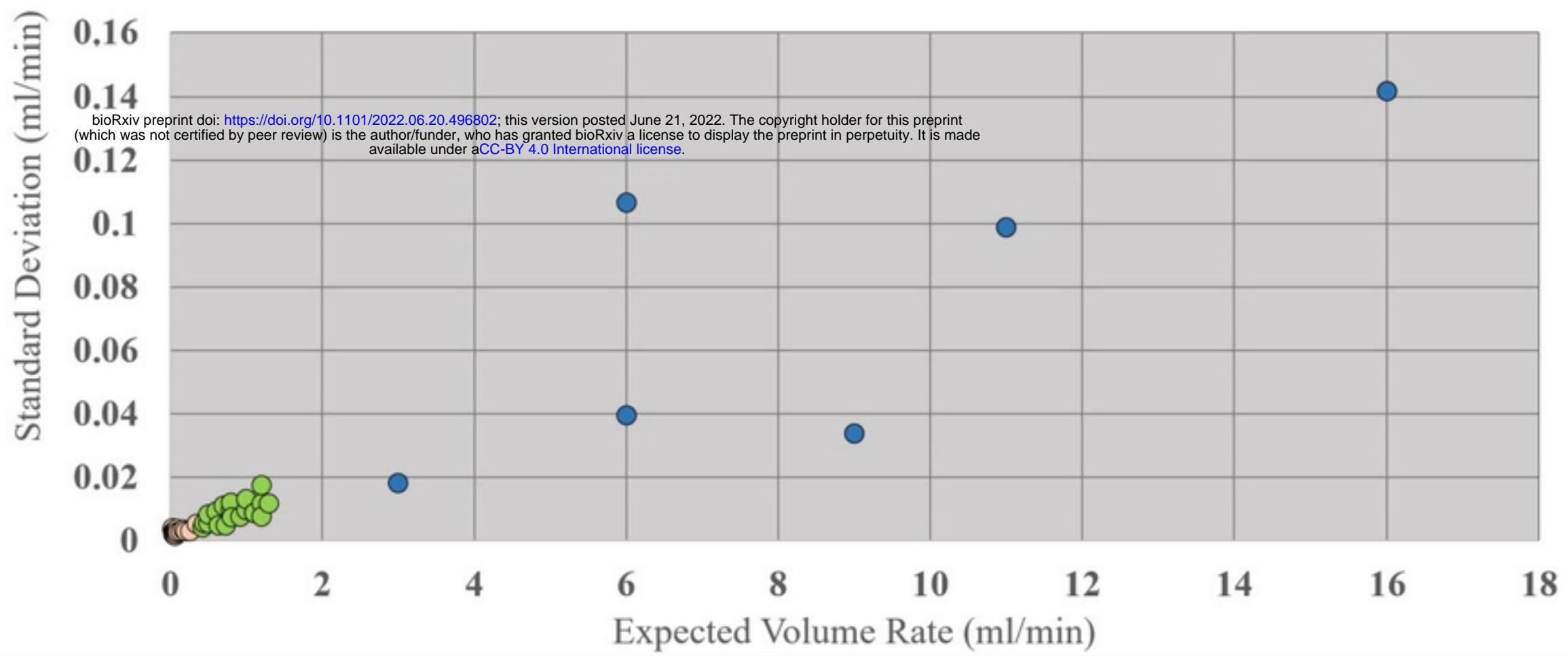
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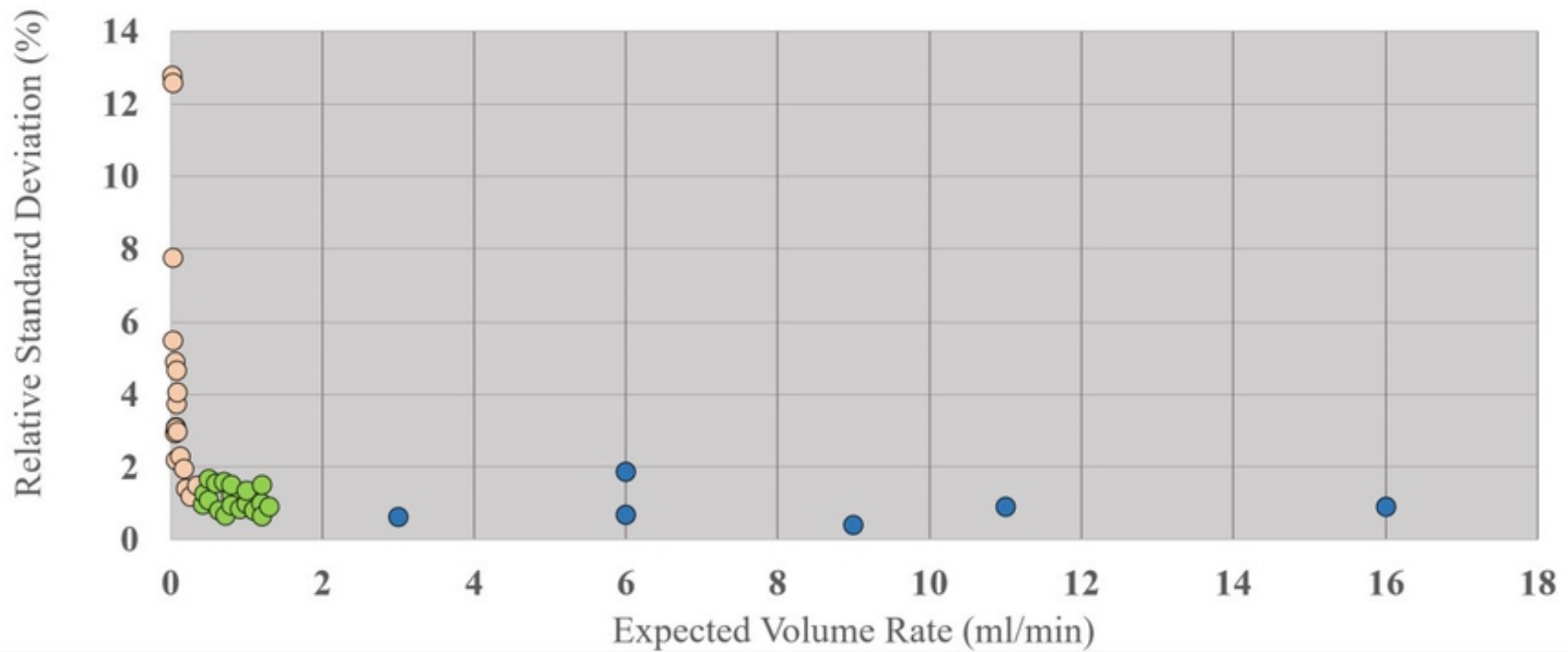
(c)

Figure 3

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(a)

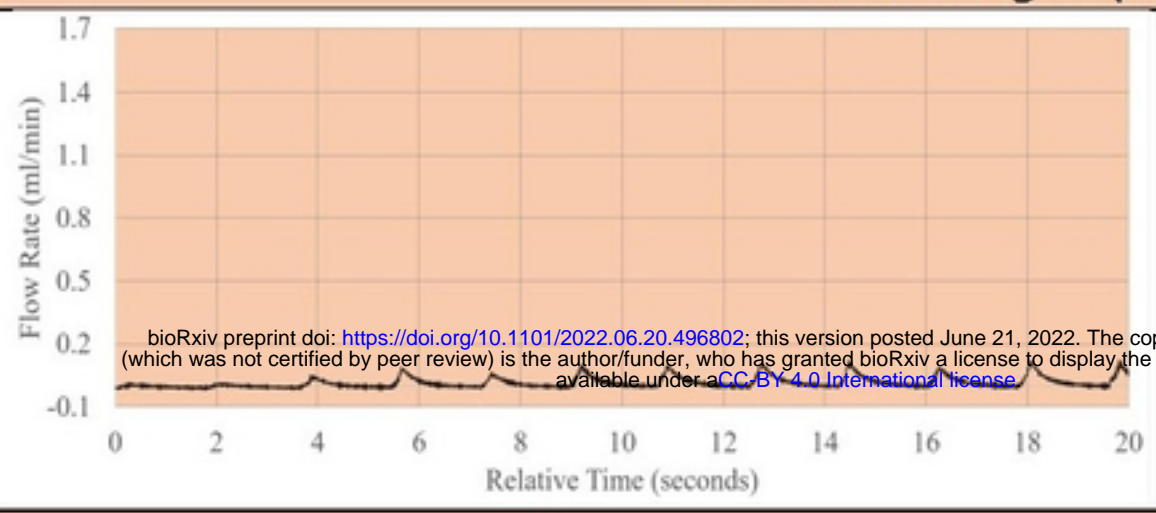


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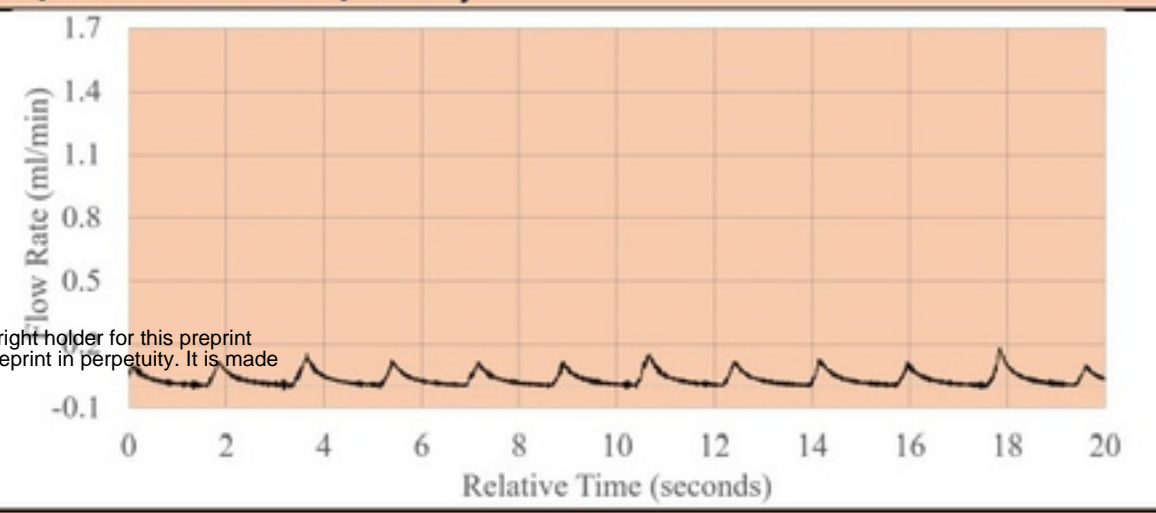
Figure 4

Low Flow Ranges (0ml/min - 0.4ml/min)

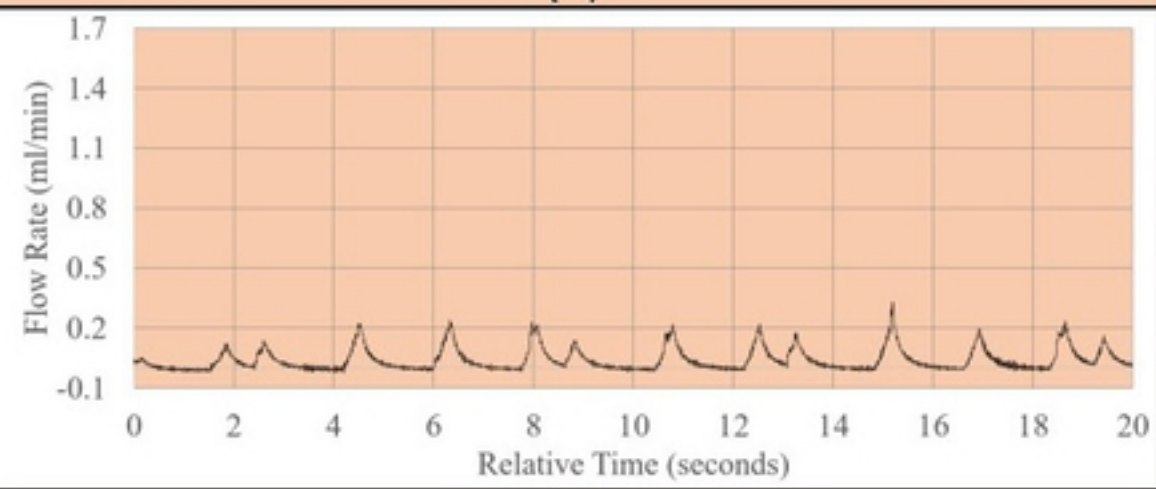
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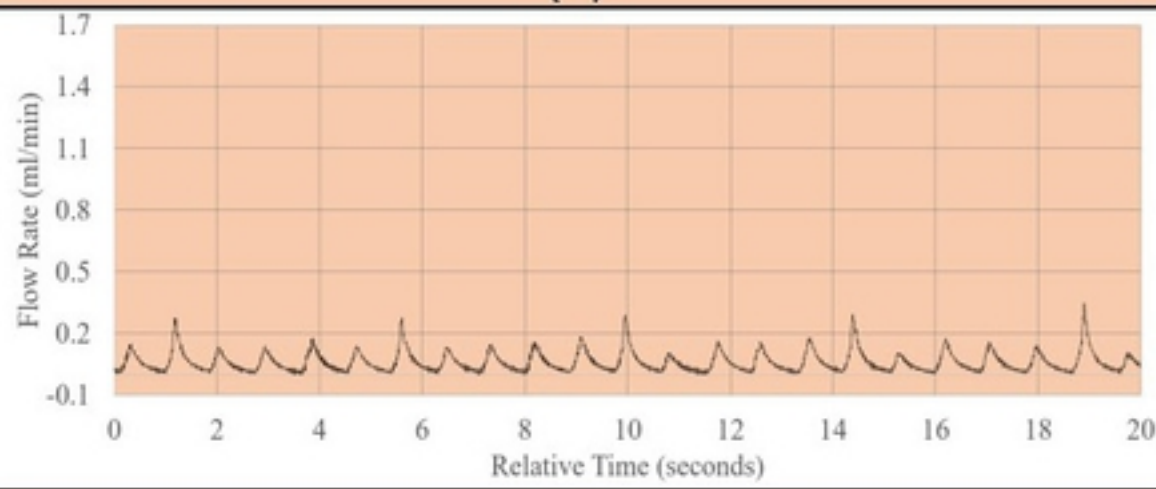
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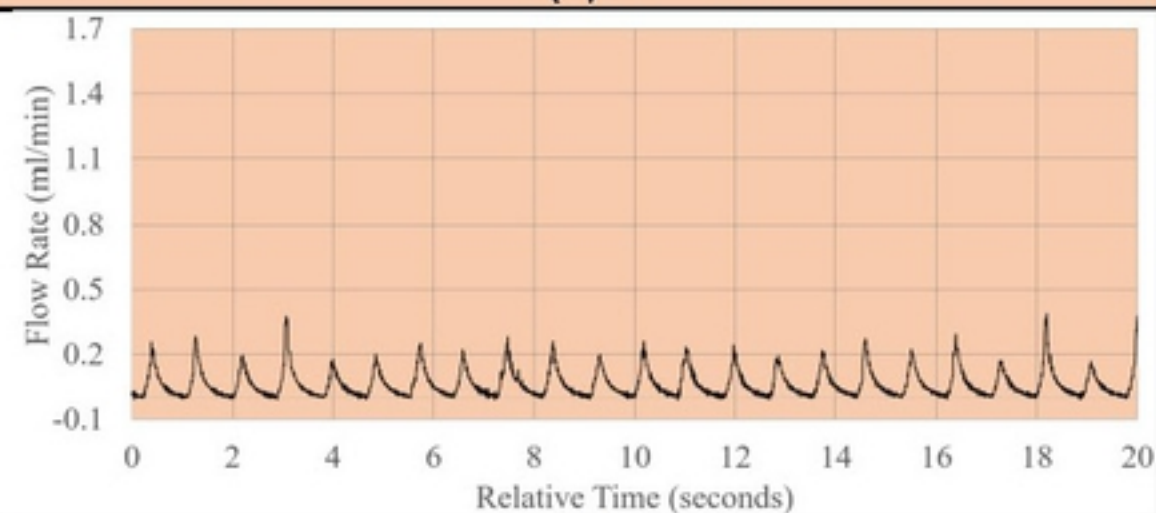
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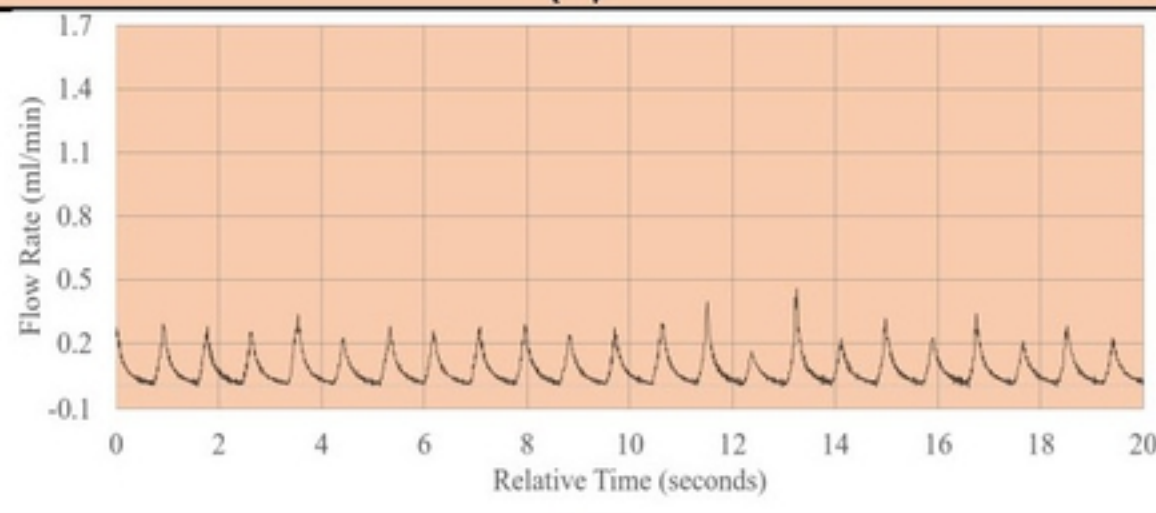
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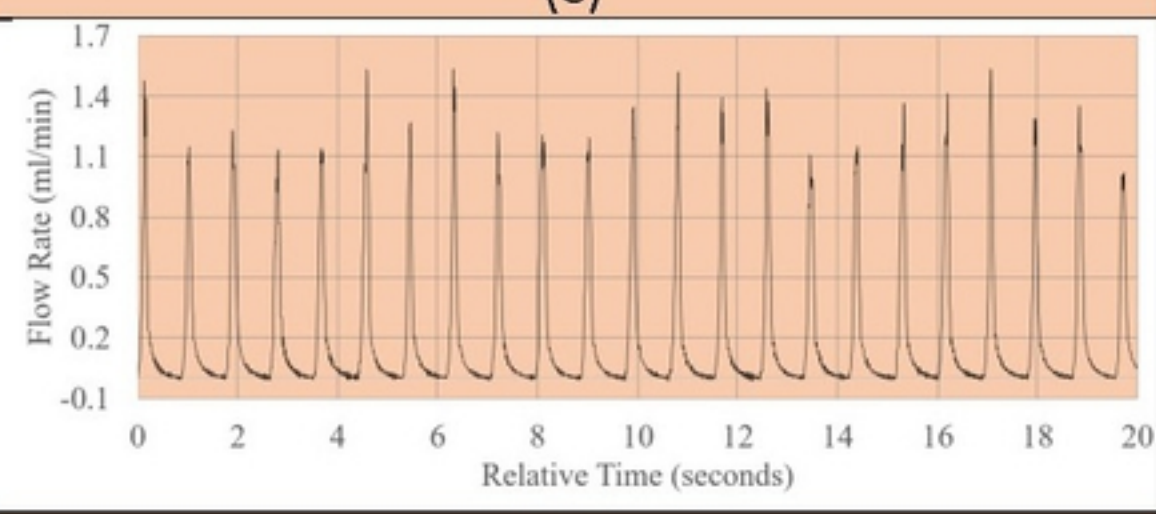
(d)



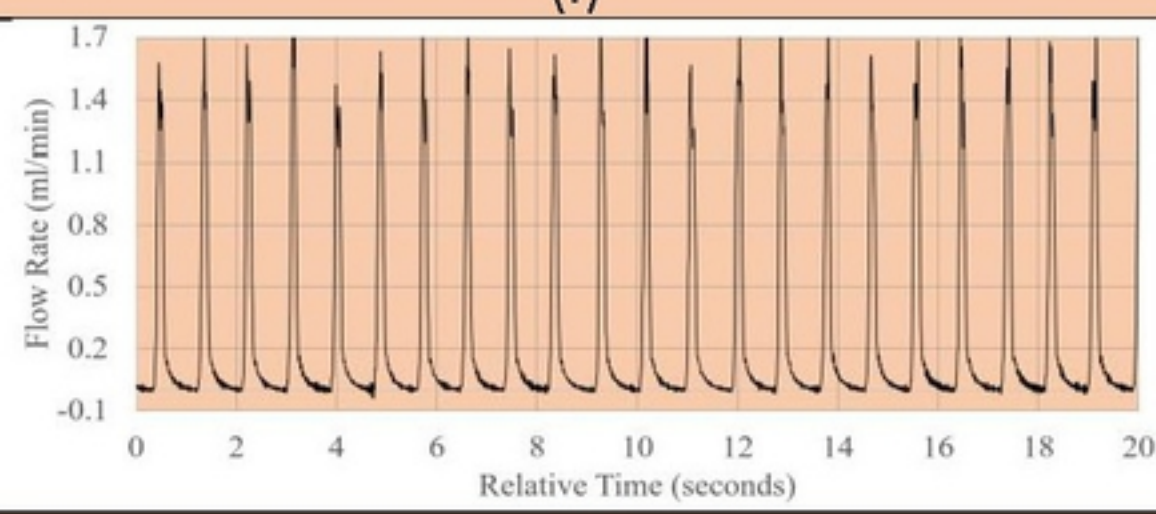
(e)



(f)



(g)



(h)

Figure 5

Mid Flow Ranges (0.4ml/min – 1.4ml/min)

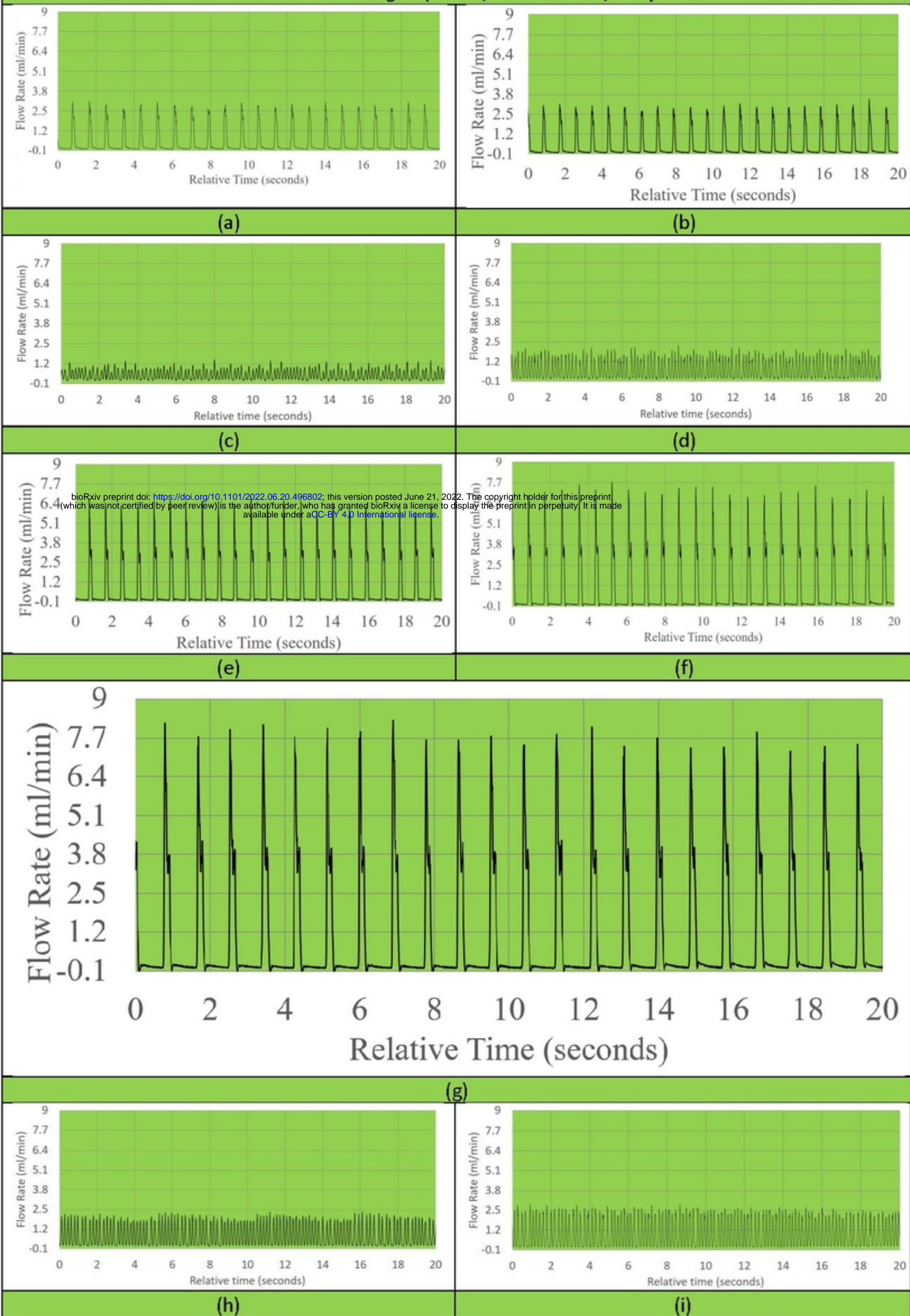
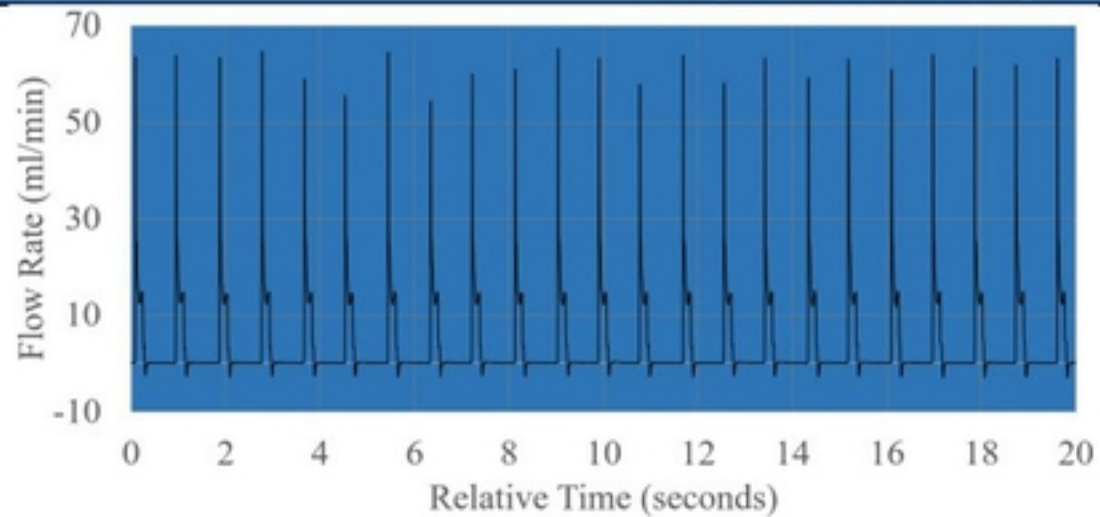
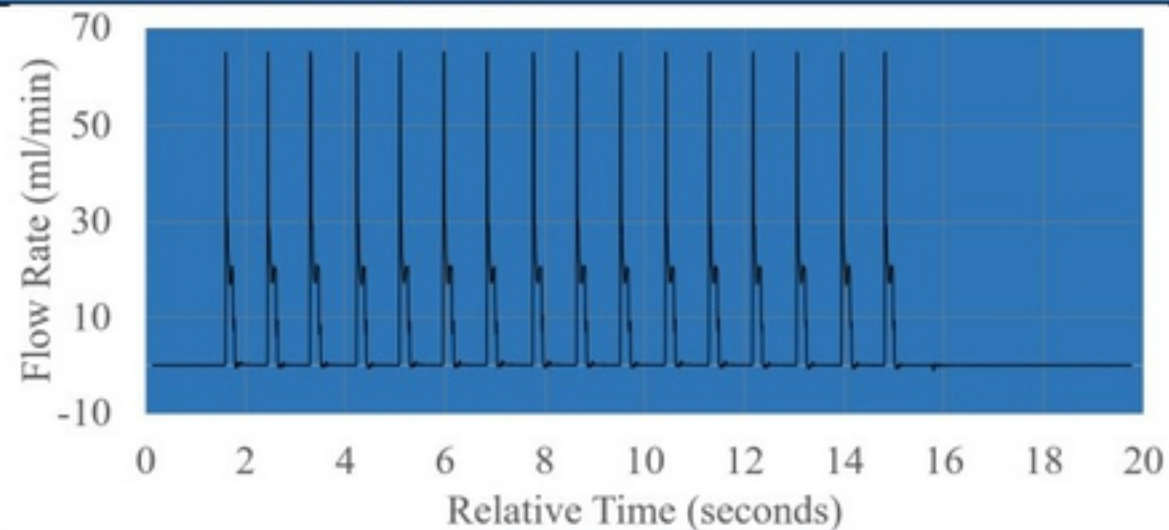


Figure 6

High Flow Ranges (3ml/min – 16ml/min)

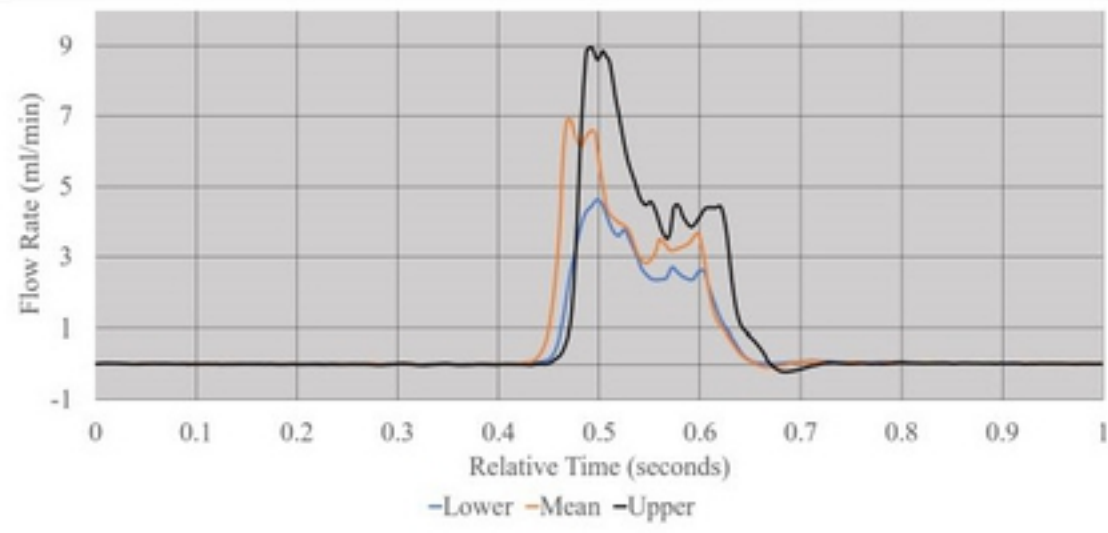


(a)

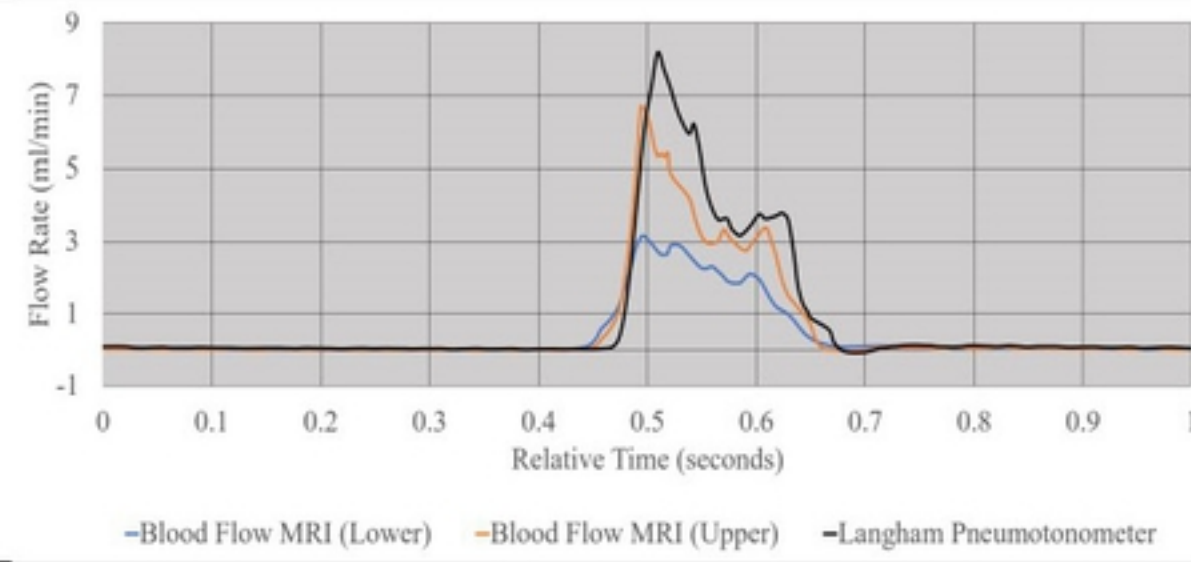


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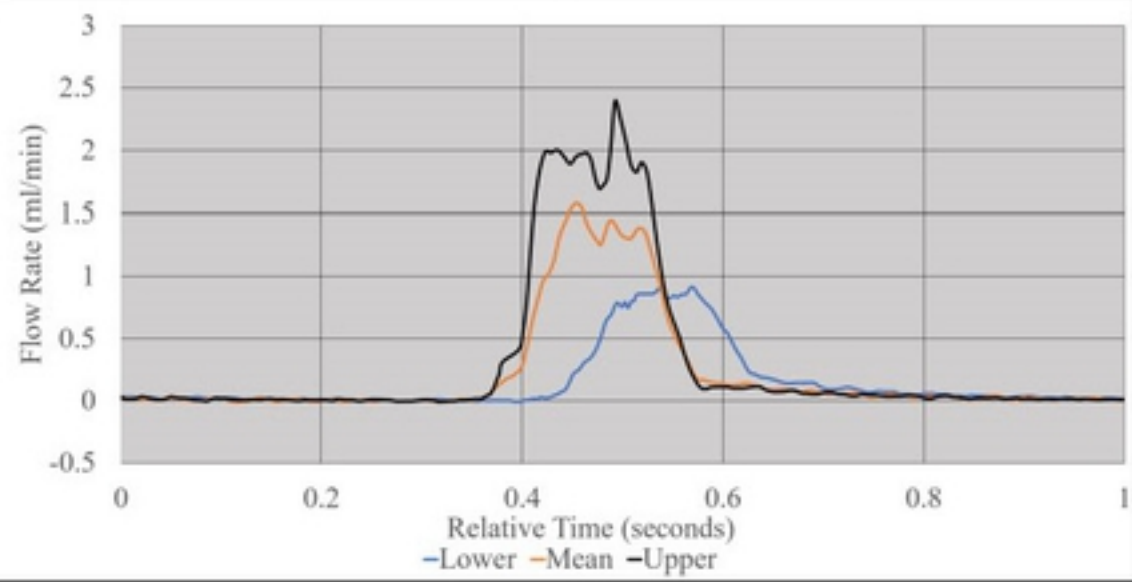
Figure 7



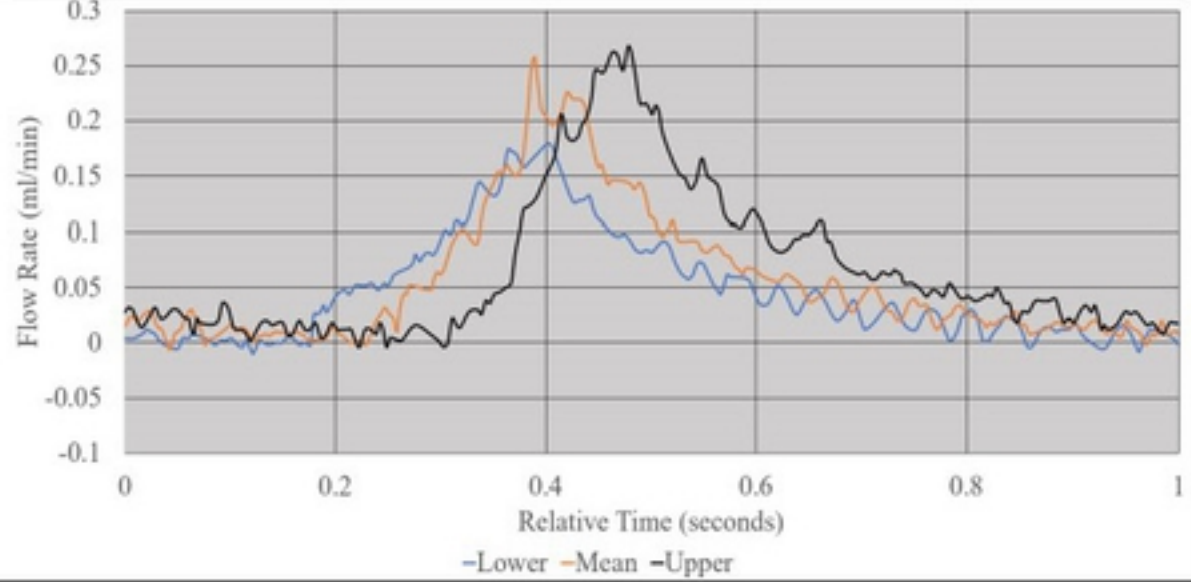
(a)



(b)



(c)



(d)

Figure 8

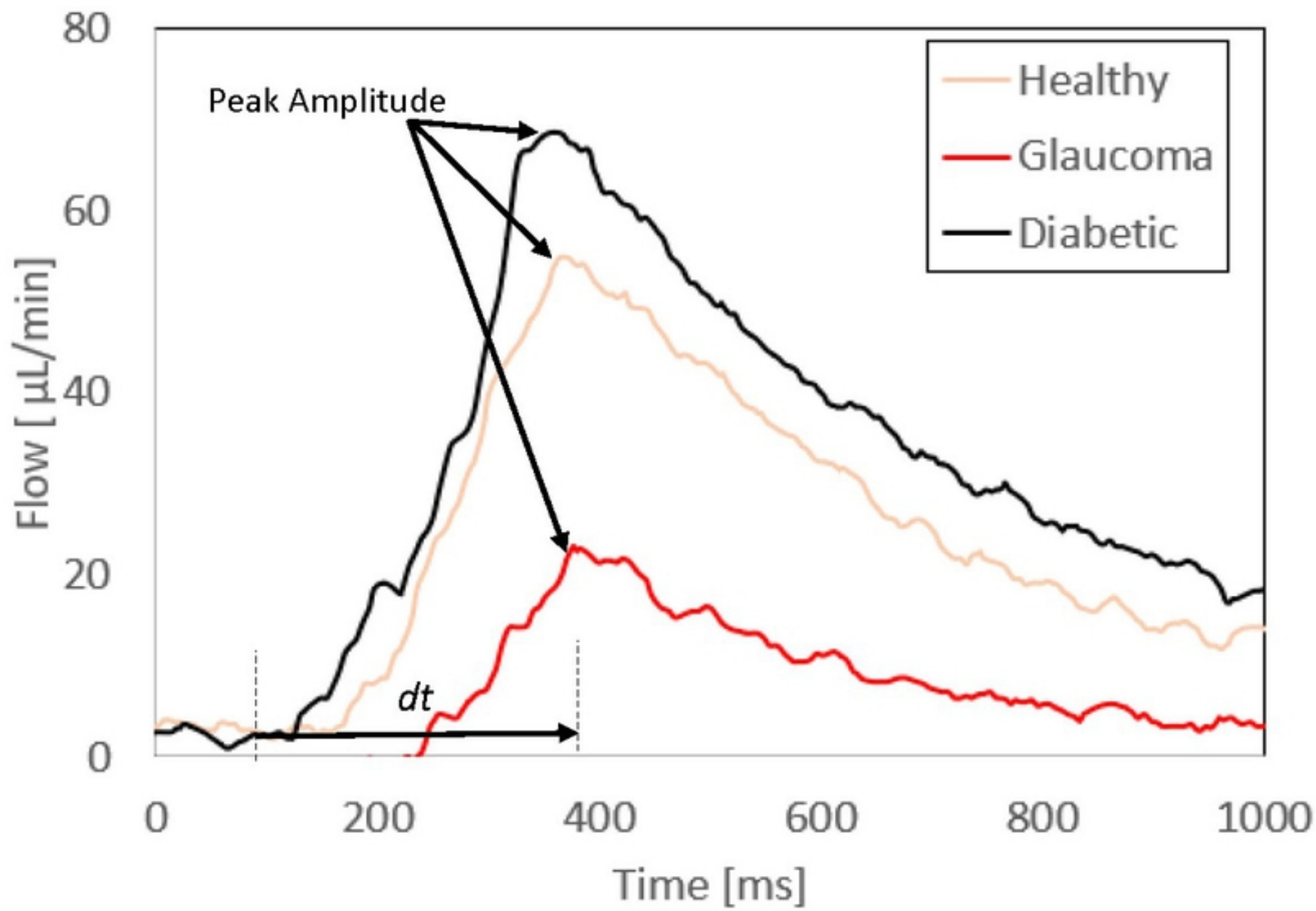


Figure 9