Intrinsic and extrinsic inhibition of cortical flow underlies

symmetry breaking during unilateral cytokinesis

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Short title

Symmetry breaking in unilateral cytokinesis

Summary

Non-concentric closure of the contractile ring, known as unilateral cytokinesis, often

orients along the body axis to maintain tissue integrity in various animals. Despite the

identification of unilateral cytokinesis regulators, the mechanism of initial symmetry

breaking remains elusive. Here, we report that intrinsic and extrinsic inhibition of cortical

flow breaks cytokinesis symmetry in *Caenorhabditis elegans*. By coupling high-

resolution 4D imaging with an *in vitro* cell contact reconstitution assay, we found that

unilateral cytokinesis of the zygote P_0 and the two-cell stage blastomere AB are regulated

by actin-dependent and adhesion-dependent mechanisms, respectively. Intracellular

compression and intercellular adhesion in P_0 and AB, respectively, locally inhibit both

furrow-directed cortical flow and cleavage furrow ingression, resulting in eccentric ring

closure. Our study demonstrates that local mechanical suppression of ring-dependent cell

cortex pulling is a common symmetry-breaking cue underlying distinct modes of

unilateral cytokinesis.

Keywords: Cytokinesis, cortical flow, C. elegans, Contractile ring, Coronin, Anillin,

Actin, Myosin, Cell division

1 Introduction

The contractile ring is a supramolecular structure critical for the physical partitioning of

dividing cells, but its function is not limited to cell proliferation. In animal zygotes and

epithelial tissues, contractile ring closure is often non-concentric and is termed unilateral

or asymmetric cytokinesis (Rappaport, 1996; Sugioka, 2021; Thieleke-Matos et al.,

2017). This phenomenon is ubiquitously observed from invertebrates to vertebrates,

including humans (Ferguson, 1988; Jinguji and Ishikawa, 1992; Maddox et al., 2007;

Vogetseder et al., 2005; Ziegler, 1903), and its disruption is associated with cytokinesis

failure and epithelial sheet and tube morphogenesis defects (Herszterg et al., 2013;

Maddox et al., 2007; Taulet et al., 2017). Despite its developmental significance, the

mechanism of unilateral cytokinesis remains unclear on several points.

A classically-known symmetry-breaking cue of unilateral cytokinesis is mitotic

spindle positioning, which is critical for specifying contractile ring assembly at the

equator of the cell cortex (Rappaport, 1986; Rappaport and Conrad, 1963). Central to

contractile ring formation is the activation of the small GTPase RhoA (Figure 2A)

(Basant and Glotzer, 2018). Upon anaphase onset, the chromosome passenger complex

recruits centralspindlin to the spindle midzone and activates its oligomerization (Basant

et al., 2015; Douglas et al., 2010). Centralspindlin then activates Ect2 RhoGEF, which in

turn facilitates the formation of the active GTP-bound form of RhoA at the equatorial cell

cortex (Gómez-Cavazos et al., 2020; Somers and Saint, 2003; Tatsumoto et al., 1999;

Yüce et al., 2005). RhoA then stimulates downstream Rho-kinase and the actin

nucleating/polymerizing factor formin to promote myosin II activation and F-actin

assembly, respectively, to initiate the ring formation (Matsumura, 2005; Otomo et al.,

2005). Pioneering studies have shown that the asymmetric positioning of the mitotic

spindle, with the spindle midzone closer to one side of the equatorial cortex, is sufficient

to induce unilateral cleavage in ctenophore zygotes and normally symmetrically dividing

sea urchin embryos (Rappaport and Conrad, 1963; Yatsu, 1912). The off-center spindle

induces asymmetric activation of RhoA in the adjacent cell cortex (Bement et al., 2005).

Thus, the geometric relationship between the equatorial cortex and mitotic spindle is a

symmetry-breaking cue of unilateral cytokinesis in some animals, hereafter called

spindle-dependent unilateral cytokinesis. However, spindle-cortex proximity does not

explain unilateral cytokinesis in many tissues as described below.

Epithelial cells undergo adherens junction-dependent unilateral cytokinesis. In

both invertebrate and vertebrate epithelial cells, mitotic spindle is slightly nearer to the

apical cell cortex, but the furrow is usually formed from the basal side (Fleming et al.,

2007; Morais-de-Sá and Sunkel, 2013; Nakajima et al., 2019; Woolner and Papalopulu,

2012). Inhibition of contractile ring components such as anillin and septin does not affect

ring eccentricity, but knockdown of adherens junction components results in concentric

contractile ring closure in *Drosophila* embryonic and follicular epithelia (Guillot and

Lecuit, 2013; Morais-de-Sá and Sunkel, 2013). Although it has been reported that the

mechanical resistance imposed by adherens junctions anchors the contractile ring at the

apical cortex (Guillot and Lecuit, 2013), the relationship between junctions, cell-cortex

dynamics, and furrow ingression remains elusive.

In contrast with the systems described above, *Caenorhabditis elegans* zygotes

undergo adhesion-independent unilateral cytokinesis. Mitotic spindle positioning is not

particularly off-center, while cortical components, including myosin, anillin, and septin,

are enriched in the fast-closing furrow, forming a structurally asymmetric ring (Maddox

et al., 2007). Unlike in *Drosophila* epithelial cells, anillin and septin are required for

structural asymmetry and unilateral cleavage (Maddox et al., 2007). Recent studies have

also revealed the significance of the concerted movement of cell-cortex material, or

cortical flow, during this process (Figure 2A). Furrow-directed cortical flow compresses

the cell cortex along the axis perpendicular to the contractile ring and facilitates myosin

enrichment and F-actin alignment along the circumferential axis of the contractile ring

(Khaliullin et al., 2018; Reymann et al., 2016). Formin also reinforces F-actin alignment

through a filament-guided filament assembly mechanism (Li and Munro, 2021).

Importantly, ring constriction further pulls the cell cortex toward the equator, producing a

positive-feedback loop between cortical flow and ring constriction (Khaliullin et al.,

2018). Because asymmetric myosin enrichment, eccentric closure, and asymmetric cell

cortex compression have been reported to occur simultaneously (Khaliullin et al., 2018;

Maddox et al., 2007), the initial symmetry-breaking mechanism remains unknown.

In this study, we performed a comparative analysis of adhesion-dependent and

adhesion-independent unilateral cytokinesis using *C. elegans* as a model system, to gain

insights into a unified mechanism underlying these seemingly very distinct division

modes. Although implicated in the previous studies, there was no concrete evidence

supporting adhesion-dependent unilateral cytokinesis in *C. elegans* (Bourdages et al.,

2014; Koyama et al., 2012). We found that the two-cell stage AB cell underwent

adhesion-dependent unilateral cytokinesis. Using blastomere isolation assays, high-

resolution 4D imaging, and *in vitro* cell-contact reconstitution assays, we have identified

symmetry-breaking cues underlying both modes of unilateral cytokinesis.

1   Results

2   High-resolution 4D imaging and quantitative analysis of contractile ring dynamics

To understand the symmetry-breaking mechanism of unilateral cytokinesis, we

performed high-resolution 4D imaging of GFP-fused non-muscle myosin II (NMY-2)

(Figure 1A, Figure S1A). Imaging methods widely adopted in the *C. elegans* cytokinesis

field slightly compress embryos to facilitate visualization of the cell cortex (Khaliullin et

al., 2018; Li and Munro, 2021; Reymann et al., 2016). However, these methods are not

optimal to analyze early symmetry-breaking events, because compression is known to

induce global cortical rotation along the short axis of the cell (Schonegg et al., 2014;

Singh et al., 2019) (Figure S1B). The compression-induced cortical rotation alters the

positioning of fast- and slow-closing (leading and lagging, respectively) cortical sides

between pre- and mid-cytokinesis, preventing the analysis of initial symmetry breaking.

To avoid compression, we used cell-sized polystyrene beads as spacers between the

coverslip and slide. Furthermore, we used a refractive index-matching medium and a

silicone-immersion objective to reduce spherical aberration to increase spatial and

temporal resolutions (Xiong and Sugioka, 2020) (Figure S1A).

These improvements enabled us to capture complete uncompressed embryonic

volumes every 5.6 sec at a 1-µm step size (a total of 31 Z slices) (Figure 1A, Movie S1).

To our knowledge, this is the first example of near-synchronous 4D imaging of both

cortical and ring dynamics, at a sufficient time-resolution with which one can estimate

the cortex movements. As expected, we did not observe cortical rotation owing to the

lack of compression (Figure S1B, Movie S1). We developed an image analysis pipeline

that efficiently measured the centroid and radius of the contractile ring at a given time

from thousands of raw images (Figure. 1B, Figure S1A, S1C). From these data, we

calculated ring closure indices (0–100%, 100% represents complete closure) and ring

eccentricities (off-center tendency). Using an initial ring radii R_0 and at a given time Rt,

the ring closure index $f(t)$ was defined as:

5
$$f(t) = (R_0 - R_t)/R_0 \qquad (1)$$

6   We defined ring eccentricity $g(t)$ using Q_t, the distance between the centroids of the

7   initial ring (C_0) and the ring at time t (C_t), as:

8
$$g(t) = Q_t/R_0 \quad (Q_t \leq R_0 - R_t) \quad (2)$$

9   The upper limit of the eccentricity at a given time point $s(t)$ was limited by Rt, as:

10
$$s(t) = \frac{R_0 - R_t}{R_0} = f(t) \qquad (3)$$

Because $s(t)$ is equal to $f(t)$, eccentricity cannot exceed the ring closure index at any time

(Figure 1C and Movie S1). After analyzing multiple embryos, individual ring constriction

curves versus time were aligned relative to the time at which the ring closure first

exceeded 2% (Figure S1D); this allows us to detect differences in sub-percentage ring

closure indices around cytokinesis onset. We defined cytokinesis onset as the 17 sec

before 2% ring closure, based on the extrapolation of a line passing two data points

before the 2% ring closure to 0 (Figure S1D). Our data alignment method was set to

understand early symmetry-breaking events, and our data include 50–80 sec preceding

cytokinesis onset, which was not reported before. Thus, our method allows analysis of

early cortical dynamics of the uncompressed embryo at high temporal resolution while

preserving the initial positioning of both leading and lagging cortices, which is necessary

to understand the symmetry-breaking mechanism.

Intrinsic and extrinsic control of unilateral cytokinesis in P_0 and AB blastomeres

We found that the P_0 contractile ring initially underwent nearly the upper limit of eccentric closure (Figure. 1C, *f(t) = g(t)*; Movie S1). The observed maximum ring eccentricity represents dominant furrow ingression from the leading cortex. Unilateral furrow ingression continued until approximately 89 sec after the cytokinesis onset (Figure. 1B, C; left panel). After this time point, the lagging cortex gradually started ingression, reducing eccentricity (Figure 1C, *f(t) > g(t)*; Movie S1).

Next, to compare the difference between adhesion-dependent and -independent unilateral cytokinesis, we sought an adhesion-mediated unilateral cytokinesis in *C. elegans* embryo. We focused on the two-cell stage AB blastomere that undergoes unilateral cytokinesis (Figure 1A) (Ozugergin et al., 2022). In intact embryos, the AB contractile ring initially exhibited low eccentricity, resulting in more symmetric ring closure (Figure. 1B, C; middle panel). However, as the ring constricted, eccentricity gradually increased. The distinct contractile ring dynamics in P_0 and AB indicated a qualitative difference in the unilateral cytokinesis mechanisms. To test the requirement for adhesion in AB unilateral cytokinesis, we isolated the AB cell by mechanically separating it from the neighboring P_1 cell. Obtained isolated AB cells exhibited symmetric ring closure, suggesting that AB unilateral cytokinesis is adhesion-dependent, as in *Drosophila* epithelial cells (Guillot and Lecuit, 2013; Morais-de-Sá and Sunkel, 2013).

Lack of asymmetries in mitotic spindle positioning, RhoA activity, and myosin level at the beginning of P_0 and AB cytokinesis

To address symmetry-breaking mechanisms in P_0 and AB cells, we first tested the

asymmetric regulations of known contractile ring assembly pathways (Figure. 2A). First,

we tested asymmetry in mitotic spindle positioning, a known symmetry-breaking cue in

ctenophore zygotes (Rappaport and Conrad, 1963; Yatsu, 1912). A previous study

reported symmetric spindle positioning in P_0 (Maddox et al., 2007). To analyze both P_0

and AB cells, we measured distances between centrosomes and leading (LE) and lagging

cortices (LG), calculating ratios of LE to LG (Figures 2B, 2C, and S2A). In both P_0 and

AB cells, the LE/LG ratio was close to 1.0, indicating mitotic spindle position symmetry

relative to leading and lagging cortices. These results confirm that the geometric

relationship between the mitotic spindle and cell cortex is not a symmetry-breaking cue

in these cell types.

Next, we examined asymmetries of RhoA activity and myosin enrichment. To

monitor the former, we used a RhoA biosensor with a GFP fused to the C-terminus of

anillin containing conserved region (AH) and pleckstrin homology (PH) domains (Tse et

al., 2012). Ratios between leading and lagging cortices were quantified as shown in

Figure S2B. Both kymographs of the equatorial cortex and leading/lagging ratios (Figure

2D and E) show that both myosin enrichment and RhoA activity started to become

asymmetric after at least 50 sec from the onset of cytokinesis. Since both were symmetric

at the beginning of P_0 and AB cytokinesis, asymmetric myosin enrichment and RhoA

activity do not appear to cause early symmetry breaking.

Actin alignment asymmetry specifies ring closure direction in P_0 cells

To test for actin alignment asymmetry in P_0 cells, we imaged whole Lifeact::mKate2-

expressing embryos as described above (Figure 3A). For the analysis of actin filament

orientation, we selected embryos that underwent furrow ingression perpendicular to the

imaging plane, to have either a leading or lagging cortex at the surface of the image stack.

For each embryo, ten surface slices closest to the objective lens were flattened by

summation; only a central 9×9-μm region was analyzed to avoid deformation of the

filament structure at the high-curvature surface (white dotted box in Figure 3A). Actin

filament orientations were estimated based on the gradient structure tensor in a local area,

using a method described before (Figure 3B, yellow lines) (Püspöki et al., 2016). We

defined the circumferential axis of the ring and axis perpendicular to it as ring-axis and

perpendicular-axis, respectively (Figure 2A, schematic ii). We found that the circular

means of actin filament orientation at the lagging cortex were significantly higher than

those at the leading cortex, indicating more ring-axis actin alignment at the lagging side

(Figure 3C; $p = 0.036$ at -50 sec using Welch's t-test). The asymmetry was first observed

approximately 55 sec before cytokinesis onset. As reported previously, actin orientation

in both leading and lagging cortices were increasingly aligned along the ring-axis over

time (Figure 3C), presumably due to the perpendicular-axis cortical compression and

filament-guided filament assembly (Figure 2A) (Li and Munro, 2021; Reymann et al.,

2016). In contrast, the actin signal intensities were not asymmetric at the beginning of

cytokinesis (Figure 3D). These results suggest that actin alignment asymmetry specifies

leading and lagging cell cortices in P_0 cells.

To examine a requirement for actin regulations in unilateral cytokinesis, we

inhibited actin and actin binding proteins. A pioneering study has shown that ANI-

1/anillin is essential for unilateral cytokinesis (Maddox et al., 2007). We confirmed that

ani-1(RNAi) caused concentric ring closure (Figure 3E-G; ring closure and eccentricity

curves separate in early cytokinesis as shown in 3F). However, as anillin is a scaffold

protein that interacts with F-actin, myosin II, RhoA, phosphatidylinositol, and

microtubules (Liu et al., 2012; van Oostende Triplet et al., 2014; Piekny and Glotzer,

2008), the significance of anillin-dependent F-actin regulation in unilateral cytokinesis is

unclear. Partial knockdown of the actin nucleator and polymerizing factor CYK-1/formin

has also been reported to result in symmetric cytokinesis at the end of contractile ring

closure, based on 2D analyses of compressed embryos (Chan et al., 2019), but we did not

observe early unilateral cytokinesis defects in our 4D analysis of uncompressed embryos

(Figure 3G).

　　　　To further investigate a requirement for actin organization in unilateral

cytokinesis, we inhibited or knocked down additional actin regulators. The Arp2/3

complex mediates actin nucleation from existing filaments, leading to branched network

assembly (Goley and Welch, 2006). POD-1/coronin is a negative regulator of Arp2/3 that

promotes actin debranching by removing Arp2/3 from F-actin (Xie et al., 2021). Finally,

we used a semi-dominant negative, temperature-sensitive mutant of one of *C. elegans*

actin encoding genes, *act-2*. *act-2(or295ts)* is a missense G14R mutation near the

conserved ATP-binding pocket, which causes abnormal actin distribution (Willis et al.,

2006). We found that both *pod-1(RNAi)* and *act-2(or295ts)* resulted in more symmetric

contractile ring closure (Figure 3E-G). In contrast, knockdown of the Arp2/3 complex did

not affect cytokinesis asymmetry, consistent with a previous report in compressed

embryos (Chan et al., 2019). Ring eccentricity has been shown to be insensitive to the

reduction of myosin activity (Maddox et al., 2007). Consistently, the knockdown of LET-502/Rho kinase did not cause unilateral cytokinesis defects (Figure 3E-G). However, a strong reduction in myosin activity by the knockdown of myosin light chain MLC-4 resulted in symmetric closure (Figure 3E, G). Thus, regulation of both actin and myosin is required for unilateral cytokinesis.

Compression of the lagging cortex along the circumferential axis of the contractile ring in P_0 cells

We hypothesized that the cell cortex with asymmetric actin alignment underwent anisotropic contraction. To test this hypothesis, we measured cortical flow using particle image velocimetry (PIV) (Thielicke and Sonntag, 2021) (Figure 4A). We analyzed the maximum projection of the top 15 slices seen from the leading, lateral, and lagging cortices of embryos expressing NMY-2::GFP (Movie S2, Figure S3). To quantify cortical dynamics, we calculated the convergence of PIV vectors per area along the ring and perpendicular axes (Figure 4B). This represents an advantage of uncompressed imaging since previous studies did not report ring axis convergence, presumably due to the compression-dependent cortical rotation. Positive and negative convergence indicated the influx and efflux of cortical material per unit area, respectively (Figure 4B: arrows, cortical flow; boxes, unit area). It is important to note that cortical convergence can be interpreted as cortical compression before furrow ingression (Figure 4C, left). After furrow ingression onset, convergence indicates both compression and ingression (cortical material moving away vertically from the imaging plane) (Figure 4C, right). We used the lateral cortex view to produce average flow vector and convergence maps (Figure 4D and

Movie S3) and the leading and lagging cortex views to quantify convergence at the cell

equator (Figure 4E).

First, we compared perpendicular axis convergence between leading and lagging

cortices (Figure 4D, bottom row; Figure 4E, left graph; Movie S3). Before and until 11

sec following cytokinesis onset, perpendicular-axis convergence was positive at both the

leading and lagging cortices, indicating that they are being compressed symmetrically

along this axis (Figure 4D and E, -75–11 sec). At 16 sec after cytokinesis onset,

perpendicular axis convergence started to increase at the leading cortex, owing to

compression and ingression (Figure 4D and 4E, 16–84 sec). These results are in

agreement with those from slightly compressed embryos (Khaliullin et al., 2018). The

same study showed that the contractile ring pulls on the cortical surface from a relatively

polar area at a rate proportional to the amount of ring myosin. Consistently, the elevation

of the perpendicular-axis convergence at the lagging cortex coincides with its ingression-

onset (Figure 4E; left graph). Because initial asymmetry in perpendicular axis

convergence emerged after cytokinesis onset, it is less likely to be an ingression

symmetry-breaking cue.

Next, we compared ring axis convergence between the leading and lagging

cortices. We found that it was higher at the lagging cortex before cytokinesis onset, with

positive convergence persisting until after furrow ingression onset of the lagging cortex

(Figure 4E; right graph, -75–125sec, and Figure 4F). These results suggest that the

lagging equatorial cortex is compressed along the contractile-ring axis in P_0 cells. The

ring-axis compression at the lagging cortex may be specified by the biased F-actin

orientation along the ring axis, while we do not claim causal relationships.

Ring axis compression limits cleavage furrow ingression in P_0 cells

Positive ring-axis cortical convergence was observed in the lagging cortex before and

during cytokinesis. Thus, we hypothesized that ring-axis cortical compression inhibits

furrow ingression during cytokinesis. To test this, we employed the *act-2(or295ts)*

mutant, which occasionally exhibits the ring oscillation phenotype (67%, n = 15) while

retaining the normal contractile ring closure rate (Figure 5A). We found that *act-*

2(or295ts) exhibited higher cortical contractility than the control, as determined by the

pronounced repetition of coalescence and dissipation of myosin clusters (Figure 5B). We

then compared the relationship between cortical compression and furrow ingression using

the maximum projection image of the focal planes closest to the objective lens (Figure 5C

and 5D, top surface) and the ring en face view (Figure 5C and 5E) from the same

embryo. We found that contraction at the top surface coincided with the immobilization

of the top furrow (Figure 5D-F; 73–84 sec and 106–117sec; Movie S4). In contrast,

cortical relaxation coincided with furrow ingression from the top (Figure 5D-F, 95 sec;

Movie S4). We measured the correlation between ring velocity and ring convergence

(Figure 5G, time series of one sample; Figure 5H, five embryos). We found that

perpendicular axis convergence did not correlate with ring ingression. In contrast, ring

axis convergence was negatively correlated with ring ingression from the top surface

(Figure 5G-H). These results suggest that local ring-axis compression locally inhibits

furrow ingression without affecting the rate of overall ring constriction.

Theoretical and experimental studies have shown that the contractile ring, with its

higher cortical tension, pulls in the cell cortex from the more relaxed polar region (Bray

and White, 1988; Greenspan, 1978; Khaliullin et al., 2018; Wolpert, 1960; Zinemanas

and Nir, 1987, 1988). Thus, we hypothesized that the ingression rate is determined by a

tug-of-war between cortical compression and contractile ring-dependent cell cortex

pulling. To test this, we measured myosin cluster displacement with respect to the timing

of peak compression (Figure 5I). We found that cortical myosin underwent isotropic

contraction while migrating toward the furrow during relaxation (Figure 5I, left two

panels). After cytokinesis, myosin clusters did not show biased movement toward the

furrow (Figure 5I, right panel). The similar negative correlation between ring-axis

convergence and the furrow-directed cortical flow is also observed at the lagging cortex

of wild-type embryos (Figure 5D, 33 sec; Figure 5E, 0–75 sec). These results suggest that

cortical compression inhibits furrow ingression by suppressing furrow-directed cortical

flow at the lagging cortex.

Adhesion leads to resistance of cleavage furrow ingression in AB cells

Next, we investigated the mechanisms underlying unilateral AB cytokinesis. First, we

tested whether different molecular mechanisms are required in AB cells than in P_0 cells.

We tested *act-2(or295ts)*, *ani-1(RNAi)*, and *pod-1(RNAi)*, all of which resulted in

symmetric P_0 cytokinesis (Figure 3B). Interestingly, the contractile rings underwent

eccentric closure in all three conditions, with proximity to the cell-cell boundary as in

wild-type controls (Figure 6A). Although *pod-1(RNAi)* embryos exhibited the lowest ring

eccentricity in P_0 cells (Figure 3G), they exhibited wild-type level eccentricity in AB

cells (Figure 6B, C). These results suggest that AB unilateral cytokinesis is not sensitive

to alternations in actin dynamics and is regulated by a different mechanism.

The AB cell underwent symmetric cytokinesis after removing the neighboring P_1

cell (Figure 1). There are two possible mechanisms underlying this type of unilateral

cytokinesis. First, junctional proteins may suppress furrow ingression from the lagging

cortex by controlling downstream intracellular signaling (e.g., RhoA inhibition). Second,

adhesion may prevent furrow ingression mechanically. We tested the latter possibility

using protein-free adhesive polystyrene beads.

We attached one or two adhesive beads to the isolated AB cell before anaphase

onset to test the effects of different adhesion strengths on the contractile ring dynamics.

After attaching one adhesive bead, the AB contractile ring initially underwent symmetric

closure but gradually increased eccentricity in the middle of cytokinesis (Figure 6C-D).

The contractile ring eventually returned to the cell center by the end of ring closure

(Figure 6C, right graph; 6D). When attaching two adhesive beads, the contractile ring

also initially underwent symmetric closure, but ring eccentricity steadily increased until

the end of cytokinesis (Figure 6C and 6E). The dynamics in the AB cells attached by two

beads were similar to that of intact AB cells, wherein the ring initially closed

symmetrically but later steadily increased eccentricity until it plateaued (Figure 6B).

These results suggest that adhesion is sufficient to induce unilateral cytokinesis. We also

found that ring eccentricity was higher when a bead was attached to the equatorial cortex

rather than in the polar region (Figure 6F). Because the polar cortex undergoes relaxation

and actively loses actomyosin (Chapa-Y-Lazo et al., 2020), these data suggest the

importance of physical connectivity between adhesion, the plasma membrane, and the

cell cortex for the regulation of furrow ingression.

Finally, we measured angles of ingression at sites with and without an adhesive

bead, to assess the mechanical resistance of the cell cortex (Figure 6G). Ingression angles

were initially symmetric (Figure 6G, i). As the ring constricted, the angle of ingression

became overtly asymmetric, with higher and slower reduction rates at the adhesion-free

and adhering sites, respectively (Figure 6G, ii). When the ring further constricts, the cell

surface near it was locally detached from the adhesion site, leading to a rapid decrease in

the angle of ingression (Figure 6G, iii). These dynamics suggest three stages of the

adhesion-cortex relationship. First, adhesion imposes weak resistance against ring-

dependent cortex bending during the initial concentric closure observed in intact embryos

and in all *in vitro* experiments (Figure 6G, schematic i). Second, adhesion imposes

stronger resistance as the ring constricts, leading to eccentric closure in all the tested

cases (Figure 6G, schematic ii). Third, ring-dependent cell cortex pulling and a sudden

adhesion rupture resulted in the quick bending of the cortex and the ring returning to the

cell center when one adhesive bead was used (Figure 6G, schematic iii). Strong adhesion

in intact and isolated AB cells attached by two beads prevented the premature release of

ring anchoring, allowing eccentric ring positioning at the end of cytokinesis.

Adhesion limits furrow-directed cortical flow

We hypothesized that adhesion would inhibit ring-dependent cell cortex pulling. If this

hypothesis is correct, the furrow-directed cortical flow should be limited by adhesion.

Indeed, in our previous study on AB cell division axis orientation, we observed bead

attachment-dependent suppression of furrow-directed cortical flow (Sugioka and

Bowerman, 2018). However, in previous experiments, we did not rule out the possibility

that physical contact, rather than adhesion, limits furrow-directed cortical flow.

Therefore, we measured furrow-directed cortical flow in the regions distal and proximal

to the bead contact site using beads of different sizes (Figure 7A). The bigger the bead

diameter, the larger the adhesion area and the number of adhesion bonds. We found that

furrow-directed cortical flow was reduced at the cortex proximal to the contact site in a

bead diameter-dependent manner (Figure 7B, C). Taken together, these results indicate

that adhesion limits furrow-directed cortical flow by suppressing ring-dependent cell

cortex pulling.

10   Discussion

Unilateral cytokinesis is widely conserved in animal development. Although

spindle off-centering is a known symmetry-breaking cue for unilateral cytokinesis in

ctenophore zygotes and manipulated sea urchin embryos (Bement et al., 2005; Rappaport

and Conrad, 1963; Yatsu, 1912), the mechanism underlying spindle-independent

symmetry breaking was unclear before this study. The two important model systems, i.e.,

C. elegans P_0 and *Drosophila* epithelial cells, have very distinct molecular requirements:

the former is adhesion-independent but anillin-septin-dependent, while the latter is

adhesion-dependent but anillin-septin-independent (reviewed in (Sugioka, 2021). In this

study, we identified adhesion-dependent unilateral cytokinesis in *C. elegans* AB cells and

performed a comparative analysis of adhesion-dependent and adhesion-independent

unilateral cytokinesis.

Based on our analyses, we propose a unified symmetry-breaking mechanism

underlying adhesion-independent and adhesion-dependent unilateral cytokinesis (Figure

7D). Since both ring-axis compression and adhesion suppressed the furrow ingression as

well as furrow-directed cortical flow, it is likely that they inhibited ring-dependent cortex

pulling (Figure 7D, middle box). During migration from the cell surface into the division

plane, the cell cortex changes its curvature (Figure 7D, top-right diagrams). Ring-axis

compression likely increases cortical stiffness by requiring more energy for the ring to

deform and pull in the cell cortex. In contrast, adhesion externally inhibits ring-dependent

cortex pulling by imposing mechanical resistance. Adhesion also induces myosin

inhibition in this cell type and may prevent furrow-directed cortical flow (Sugioka and

Bowerman, 2018). This mechanical suppression model is consistent with that proposed

for *Drosophila* embryonic epithelial cells (Guillot and Lecuit, 2013), but our study

further characterized the spatiotemporal ring-cortex interaction and expanded its utility to

nonadhesive and nonepithelial cells. In summary, our findings indicate that intrinsic and

extrinsic regulation of local cortical stiffness is a symmetry-breaking cue for distinct

modes of spindle geometry-independent unilateral cytokinesis.

This intrinsic and extrinsic control of local cortical stiffness can explain the

distinct contractile ring trajectories observed *in vivo* and *in vitro* (Figure 7D, bottom-right

panels). In P_0 cells, the cell cortex is already stiffer than the other areas before cytokinesis

onset (preconditioning), leading to maximum eccentricity from the early phase of

cleavage (Figure 7D, schematic i). The subsequent suppression of ring-axis compression

allows lagging cortex ingression and a reduction in eccentricity (Figure 4E). The

oscillatory ring trajectory in *act-2(or295ts)* is likely due to oscillatory cortical

compression, as shown in Figure 5 (Figure 7D, schematic ii). In the AB cell, adhesion

does not impose strong mechanical resistance at the beginning, presumably owing to the

typical strain-stress relationship of a cell-cell junction and synthetic adhesives (Esfahani

et al., 2021; Gent et al., 1969), then gradually increases resistance to cause eccentric

closure (Figure 7D, schematic iii). When adhesion is weak, adhesion rupture reduced ring

eccentricity (Figure 7D, schematic iv). Taken together, these few simple rules can

generate diverse ring trajectories; therefore, this knowledge will be useful for estimating

spatial cytokinesis control in more complex tissues.

One notable difference among tissues undergoing spindle-independent unilateral

cytokinesis is the spatial organization of the contractile ring. Asymmetric myosin

enrichment at the leading edge has been observed in *C. elegans* P_0 and AB cells and

Drosophila pupal dorsal thorax epithelial cells (this study; (Founounou et al., 2013;

Herszterg et al., 2013; Maddox et al., 2007) but not in *Drosophila* embryonic epithelia,

follicular epithelia, and pupal wing epithelia (Guillot and Lecuit, 2013; Herszterg et al.,

2013; Morais-de-Sá and Sunkel, 2013). Importantly, cortical stiffness-dependent

suppression of ring-dependent cortex pulling can account for the asymmetric ingression

of both structurally asymmetric and symmetric contractile rings (this study; (Guillot and

Lecuit, 2013). This observation is consistent with our model, in which mechanical

suppression occurs upstream of compression-dependent feedback (Figure 7D). We

speculate that the above-described tissues are only different in terms of their downstream

myosin enrichment mechanisms: structurally asymmetric and symmetric rings rely more

on compression feedback and RhoA pathways, respectively.

By integrating our results and the above discussion, we predict that the ring-

dependent cortex pulling is tuned differently in different tissues to execute tissue-specific

morphogenic cytokinesis. Three important parameters are the strength of compression-

dependent myosin recruitment to the ring, RhoA-dependent myosin recruitment to the ring, and cortical stiffness. Compression-dependent myosin enrichment should translate subtle cortical stiffness asymmetry into increased ingression rate difference by forming a structurally asymmetric contractile ring. For a compression-dependent feedback mechanism to effectively create a structurally asymmetric contractile ring, RhoA-dependent myosin recruitment should be limited. Conversely, excessive RhoA-dependent myosin enrichment suppresses ring-dependent mechanosensing of subtle cortical stiffness asymmetry. Understanding the tissue-specific ring-cortex relationship and its local tuning by RhoA activity or tissue mechanics is necessary to further delineate the role of cytokinesis in animal morphogenesis.

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Author contributions

3 **C.R.H.**: Formal analysis, Investigation, Writing-Original Draft, Validation,

4 Visualization. **G.S.**: Formal analysis, Investigation. **W.F.**: Formal analysis, Investigation.

5 **J.Z.**: Formal analysis, Investigation. **K.S.**: Conceptualization, Formal analysis,

6 Investigation, Methodology, Software, Validation, Writing-Original Draft, Writing-

7 Review & Editing, Supervision, Funding acquisition.

Declaration of interests

10 The authors declare no competing interests.

STAR Methods

Key Resource Table

Provided as a separate file.

Contact for Reagent and Resource Sharing

Lead contact information:

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Lead contact holds responsibility for responding to requests and providing reagents and

information.

Experimental Model and Subject Details

All *C. elegans* strains were cultured using the standard method (Brenner, 1974). A

temperature sensitive-actin mutant *act-2(or295)* was cultured at 15˚C until the L4 larval

stage and incubated at 25˚C overnight before imaging. Lifeact::mKate2 strain was

cultured at room temperature. The following transgenes were used: *cp13*[*nmy-2*::GFP +

LoxP] (non-muscle myosin II) (Dickinson et al., 2013), *cp69*[*nmy-2*::mKate2 + LoxP]

(non-muscle myosin II) (Dickinson et al., 2017), *or1940*[GFP::*sas-7*] (centriole marker)

(Sugioka et al., 2017), *itIs37* (mCherry::histone H2B), *ruIs32*[*pie*-1p::GFP::H2B::*pie-1*

3'UTR + *unc-119*(+)], *sybIs2855*[*mex-5*p::lifeact::mKate2::*tbb-2* 3'UTR] (F-actin

marker; made by SunyBiotech), *xsSi5*[*pie*-1p::GFP::*ani-1*(AH+PH)::*pie-1* 3'UTR + *Cbr-*

unc-119(+)] (RhoA biosensor) (Tse et al., 2012).

RNAi

Feeding RNAi was performed at 25˚C using the standard method (Ahringer, 2006). For control RNAi, a bacterial strain carrying an empty vector (L4440) was used. For *cyk-1*, *arx-2*, *ani-1* and *let-502*, the L2 stage larvae were cultured on freshly prepared feeding RNAi plates on day 1. The L4 larvae were then transferred to new feeding RNAi plates on day 2 and imaged on day 3. For *pod-1* and *mlc-4*, L4 larvae were cultured on feeding RNAi plates and used for imaging on the next day.

Blastomere isolation

Blastomeres were isolated as described before (Hsu et al., 2019). We cut the gravid adult worms in egg salt buffer (Edgar and Goldstein, 2012) and treated them with hypochlorite solution [75% Clorox (Clorox) and 2.5N KOH] for 50 seconds. After washing twice with Shelton's growth medium (Shelton and Bowerman, 1996), embryos were transferred to fresh Shelton's growth medium. Eggshell and permeability barrier were removed by mouth pipetting with hand-drawn microcapillary tubes (10 microliters, Kimble Glass Inc.). The two-cell stage eggshell-free embryos were further pipetted to remove the cell-cell contact.

Adhesive polystyrene bead preparation

The detailed method is described in our previous papers (Hsu et al., 2019; Sugioka and Bowerman, 2018). 10 mg carboxyl-modified polystyrene beads with diameters of 30 µm (Kisker Biotech GmbH & Co.), 20 µm, 10 µm, and 4.5 µm (Polysciences) were washed

twice with 100 mM 2-(N-morpholino) ethanesulfonic acid (MES) buffer (pH6.5) and

incubated with 1 mL MES buffer containing 10 mg 1-Ethyl-3-(3-dimethylaminopropyl)

carbodiimide (EDAC) for 15 mins at room temperature. We washed the beads twice with

phosphate buffered saline (PBS) and incubated them with 0.5 mL PBS containing 0.05

µg Rhodamine Red-X succinimidyl ester (ThermoFisher Scientific) for 5 minutes. The

appropriate concentration was also determined by treating the beads with a series of

serially diluted Rhodamine Red-X solution (Hsu et al., 2019). The beads were washed

twice with PBS and stored in PBS at 4˚C. Adhesiveness of the beads was confirmed by

attaching them to the isolated blastomere using the mouse pipette. If successful, the

adhesion is firmly established and cells do not dissociate spontaneously.

Live-imaging sample preparation

To obtain embryos, gravid adults were dissected on a coverslip, in a droplet of 10-12 µl

of refractive index-matching medium (30% iodixanol diluted in egg salt buffer,

supplemented with 30 µm diameter plain polystyrene beads) as described before (Xiong

and Sugioka, 2020). After placing the coverslip gently onto a slide glass, three edges of

coverslip were sealed with petroleum jelly (Vaseline), with one edge remaining open to

the air. We realized that this method improved the success rate of imaging for

inexperienced users. Inexperienced users may observe cell death due to the acute

compression during the sample preparation and requires training using control strains. If

all the processes were performed gently, the imaging condition does not have adverse

effects on the embryonic viability, as judged by the normal cell division in the next cell

cycle.

Microscopy

Intact embryos were imaged using a microscope Olympus IX83 (Olympus), equipped

with a spinning-disk confocal unit CSU-W1 (Yokogawa), a scientific CMOS camera

Prime 95B (Photometrics), a piezoelectric stage NANO-Z (Mad City Labs), a silicon

immersion objective UPLSAPO60XS2 (NA1.3, 60X; Olympus), and a beam splitter

Optosplit II (Cairn Research), which is controlled by Cellsense Dimension (Olympus). A

silicone immersion oil (Z81114; refractive index: 1.406 at 23˚C; Olympus) was used as

an immersion medium. Samples were illuminated by diode-pumped lasers with 488 nm

and 561 nm wavelengths, and the simultaneous two color-imaging was performed with

150 msec camera exposure time, 1-μm Z-step size with a total of 31 slices per frame, 5.6

sec interval, and the duration of 15 mins. Isolated blastomeres were imaged using a

microscope Leica DMi8 (Leica Microsystems), equipped with a spinning-disk confocal

unit CSU-W1 with Borealis (Andor Technology), dual EMCCD cameras iXon Ultra 897

(Andor Technology), and an oil-immersion PL APO objective lens (NA1.4, 63X; Leica),

and controlled by Metamorph (Molecular Devices). Data in Figure 6D-G were imaged

with 1.5 μm Z-step size and 15 sec intervals. Data in Figure 7 were imaged with 1.5 μm

Z-step size and 10 sec intervals, with only the half volume closure to the objective lens

were imaged.

Quantification of the P_0 contractile ring dynamics

Obtained 4D data were deconvoluted using a constrained iterative and advanced

maximum likelihood algorithm (iteration: 5), using Olympus Cellsens software

(Olympus, Inc). Each 4D tiff stack file was processed using Fiji (Schindelin et al., 2012)

(Figure S1). The deconvoluted images were processed using Gaussian blur (sigma = 2)

and an image J plug-in "attenuation correction" (opening =3, reference =15) (Biot et al.,

2008). A 10 µm W x 32 µm H boxed region corresponding to the contractile ring was

selected and adjusted for the fluorescence intensity so that the signal will not be saturated

in the next step, and rotated by 3D projection (Brightest point, interpolation on). After

selecting a plane of en face ring view, the images were segmented and quantified using

an Image J plug-in Morpholib J (Legland et al., 2016). The segmented contractile ring

areas were measured for ring radius, ring centroid, and ring angle. The radius of the

segmented area was estimated using ellipsoid fitting and derived by calculating the

average of major and minor radii of the ellipsoid. Data were aligned relative to the time

point first exceeded 2% ring closure. The ring trajectory images were obtained with an

in-house image J macro using same data.

Quantification of the AB contractile ring dynamics

Since the AB cell undergoes rotation during its division, the precise quantification is

challenging. We first selected samples undergoing unilateral cleavage roughly in parallel

to the imaging plane, and corrected for cell rotation using Stackreg plug-in of Image J

using chromosome signal (polar bodies were deleted using a brush tool to avoid abnormal

image registration) (Thévenaz et al., 1998). The rotation-corrected images were then

processed by the same pipeline used for the P_0 cell.

3D visualization and quantification of contractile ring dynamics in isolated

blastomeres

The oblique view of cells in Figure 1A, Figure 6A, and Figure 6D were generated using

an Image J plug-in Clear Volume (Royer et al., 2015). The analysis of the contractile ring

dynamics in isolated blastomeres is challenging since the cell is rotated along different

axes, and not all the planes were captured during imaging. Thus, we made en face ring

view images for each time point using Clear Volume, and estimated the cell and ring

contours, centroids, and diameters, by selecting more than four points along the cell and

ring perimeter, respectively, using an Image J macro "Smallest Enclosing Circle"

(Schindelin et al., 2012). The ring closure rate and eccentricity were calculated using the

method described above for other cells. Measurements were performed three times per

sample, and average values were used to mitigate the relatively higher error rate

compared to the automatic segmentation method used for intact embryos.

Kymographs

Kymographs in Figure 2D were generated by stacking 1.5 µm W x 32 µm H rectangular

regions at a given time along a user defined line passing the equatorial cortex or furrow

using an in-house image J macro. Kymographs in Figure 5B were generated by stacking

49 µm W x 1.8 µm H boxes using Fiji (built-in function, Make Montage). Kymographs in

Figure 5I were generated by stacking 11 µm W x 3.7 µm H rectangular regions

corresponding to a myosin cluster. The timing is adjusted so that the peak myosin cluster

intensity comes the 4th out of total 8 frames, using an in-house image J macro.

Quantification of centrosome positioning

For the P_0 cell, obtained 4D images were rotated so that the angle of unilateral closure, at

5% ring closure, is accurately in parallel to the imaging plane (Figure S2A). The

distances between a centrosome and leading and lagging cortices were measured using an

in-house image J macro. For the AB cell, we only used samples undergoing unilateral

cleavage roughly in parallel to the imaging plane (Figure S2A). The distance between a

centrosome and a line passing the both ends of the AB-P_1 cell boundary was measured to

calculate the centrosome-lagging cortex distance. We then drew a line passing a

centrosome, and being perpendicular to the above-described AB-P_1 boundary line. The

intersection of this line and a line in parallel to the leading cortex was used to calculate

the centrosome-leading cortex distance. Data were aligned relative to cytokinesis onset

defined by the 4D ring dynamics data described above.

Quantification of signal intensities

To accurately measure the signal intensities within a thin layer of leading and lagging

cortices, we selected embryos undergoing unilateral furrow ingression roughly in parallel

to the imaging plane (Figure S2B). We selected a Z slice containing the center of

contractile ring at about 200 second after cytokinesis onset, and calculated the summation

of three Z slices around the ring center. We then measured signal intensities in 1.83 μm x

0.55 μm boxes, corresponding to the cell cortex and the tip of the cleavage furrow before

and after cleavage onset, respectively.

Quantification of the F-actin alignment

The obtained 4D data sets of lifeact::mKate2-expressing embryos were deconvoluted and

analyzed to quantify ring closure dynamics by the above-described method using

Morpholib J. We selected embryos showing leading or lagging cell cortex closest to the

objective lens. For each data, ten slices at the cell surface closer to the objective lens were

flattened by summation using Fiji, and central 9 μm x 9 μm rectangular regions were

analyzed to avoid deformation of filament structure at the high-curvature surface. The

orientations of actin filaments were estimated based on the gradient structure tensor in a

local area using an Image J plug-in Orientation J (Gradient: Cubic Spline, local window:

2 pixel) (Püspöki et al., 2016). Circular mean was calculated using Scipy (Virtanen et al.,

2020) and the timings of data were aligned relative to cytokinesis onset.

Visualization of F-actin alignment

To visualize F-actin alignment in Figure 3A-B, the above-described flattened images

were processed using an unsharp mask (Image J built-in function) and an Image J plug-in

Feature J (Edges:, smoothing scale 1.0) (Meijering). The orientation vectors in Figure 3B

were generated using Orientation J.

Particle Image Velocimetry

A detailed image preprocessing pipeline is shown in Figure S3. Briefly, 4D data sets of

NMY-2::GFP and GFP::-SAS-7-expressing embryos were processed with Gaussian Blur

(sigma =1) and unsharp mask (radius =1, mask = 0.6) using Fiji. Centriole signals were

deleted by filling zero values. After intensity adjustment to avoid signal saturation, half

volume of image stack was filled with zero values to avoid projecting cortical myosin

from opposite cortical sides. Obtained images were projected using an Image J function

"3D projection." We rotated 3D projected data relative to angle of cleavage at 5% closure

and generated leading, lagging, and lateral cortex views. Note that not always both

lagging and leading cortices were clearly visible, so that in some embryos, either the

leading or lagging cortex was used. Using these flattened cell cortex images, Particle

Image Velocimetry was performed using MATLAB software PIV LAB (Algorithm: FFT

window deformation, Interrogation area: 5.8 μm, Step size: 2.9 μm, Sub-pixel estimator:

Gauss 2x3 point, Correlation robustness: Standard) (Thielicke and Sonntag, 2021). We

rejected vectors exceeding 0.25 μm/sec to remove estimation errors (the setting was

visually confirmed to reflect the myosin foci movement). Obtained 3D matrix data (2D x

time) were used for downstream analyses. The PIV matrix data were aligned relative to

cytokinesis onset, centered relative to the cell center corresponding to the furrow

position, and resized to contain an entire embryo using Numpy and Pandas (Harris et al.,

2020; McKinney, 2010). Mean PIV vectors were calculated and plotted using Matplotlib

(stream plot) (Hunter, 2007).

Estimation of cortical convergence

Cortical convergence was derived using the PIV vector matrix and a NumPy gradient

function (Harris et al., 2020). When we define perpendicular-axis and ring-axis cortical

flow velocities in an i x j matrix as $u_{i,j}$ and $v_{i,j}$, respectively, $u_{i+h,j}$, $u_{i-h,j}$, $v_{i,j+h}$, $v_{i,j-h}$ can be

defined as follows using Taylor series (Quarteroni et al., 2010):

22
$$u_{i+h,j} = u_{i,j} + h\frac{\partial u_{i,j}}{\partial i} + \frac{h^2}{2!}\frac{\partial^2 u_{i,j}}{\partial i^2} + \mathcal{O}(h^3) \qquad (4)$$

$$u_{i-h,j} = u_{i,j} - h\frac{\partial u_{i,j}}{\partial i} + \frac{h^2}{2!}\frac{\partial^2 u_{i,j}}{\partial i^2} + \mathcal{O}(h^3) \quad (5)$$

$$v_{i,j+h} = v_{i,j} + h\frac{\partial v_{i,j}}{\partial j} + \frac{h^2}{2!}\frac{\partial^2 v_{i,j}}{\partial j^2} + \mathcal{O}(h^3) \quad (6)$$

$$v_{i,j-h} = v_{i,j} - h\frac{\partial v_{i,j}}{\partial j} + \frac{h^2}{2!}\frac{\partial^2 v_{i,j}}{\partial j^2} + \mathcal{O}(h^3) \quad (7)$$

4   And we will obtain the followings by subtraction:

$$u_{i+h,j} - u_{i-h,j} = 2h\frac{\partial u_{i,j}}{\partial i} + \mathcal{O}(h^3) \quad (8)$$

$$V_{i,j+h} - V_{i,j-h} = 2h\frac{\partial v_{i,j}}{\partial j} + \mathcal{O}(h^3) \quad (9)$$

7   Thus, the cortical flow gradients at the interior points can be defined as follows:

$$\frac{\partial u_{i,j}}{\partial i} = \frac{u_{i+h,j} - u_{i-h,j}}{2h} + \mathcal{O}(h^2) \approx \frac{u_{i+h,j} - u_{i-h,j}}{2h} \quad (10)$$

$$\frac{\partial V_{i,j}}{\partial j} = \frac{v_{i,j+h} - v_{i,j-h}}{2h} + \mathcal{O}(h^2) \approx \frac{v_{i,j+h} - v_{i,j-h}}{2h} \quad (11)$$

10   At the boundary, first order one-sided differences were achieved as follows:

$$\frac{\partial u_{i,j}}{\partial i} = \frac{u_{i+h,j} - u_{i,j}}{h} + \mathcal{O}(h) \approx \frac{u_{i+h,j} - u_{i,j}}{h} \quad (12)$$

$$\frac{\partial v_{i,j}}{\partial j} = \frac{v_{i,j+h} - v_{i,j}}{h} + \mathcal{O}(h) \approx \frac{v_{i,j+h} - v_{i,j}}{h} \quad (13)$$

13   Perpendicular-axis and ring-axis cortical convergence $p_{i,j}$, $q_{i,j}$, respectively, were

14   calculated as follows, where a is the PIV step size:

$$p_{i,j} = -\frac{1}{a}\frac{\partial u_{i,j}}{\partial i} \approx -\frac{1}{a}\frac{(u_{i+1,j} - u_{i-1,j})}{2} \quad (at\ the\ interior\ points)\ (14)$$

$$p_{i,j} = -\frac{1}{a}\frac{\partial u_{i,j}}{\partial i} \approx -\frac{1}{a}(u_{i\pm1,j} - u_{i,j}) \quad (at\ the\ boundary)\quad (15)$$

$$q_{i,j} = -\frac{1}{a}\frac{\partial v_{i,j}}{\partial j} \approx -\frac{1}{a}\frac{\left(v_{i,j+1} - v_{i,j-1}\right)}{2} \quad (at\ the\ interior\ points)\ (16)$$

$$q_{i,j} = -\frac{1}{a}\frac{\partial v_{i,j}}{\partial j} \approx -\frac{1}{a}\left(v_{i,j\pm1} - v_{i,j}\right) \quad (at\ the\ boundary)\quad (17)$$

Mean convergence of embryos was calculated for each grid, and plotted in Figure 4D

using Matplotlib (stream plot). To quantify leading and lagging cortex convergence at the

equatorial region in Figure 4E, we calculated mean convergence within a 6x3 grid (14.6

μm W x 5.9 μm H) around the center of the furrow position.

Myosin foci tracking

Before the analysis of myosin foci, cell position was registered using image J plug-in

Stackreg, to eliminate the movement of myosin foci caused by the movement of cell

body. Myosin foci in Figure 7B were tracked using Manual Tracking plug-in of Image J.

Statistical analysis

For multiple comparisons, one-way ANOVA with the Holm-Sidak's method was used.

The comparison of two data was performed using the Mann-Whitney U-test or Welch's t-

test. No statistical method was used to predetermine the sample size. Error bars or bands

are corresponding to the 95% confidence interval. Pearson's coefficients were calculated

in multiple 95 sec windows in Figure 5G. In Figure 5I, a 95 sec window corresponding to

the ring oscillation period was used. The experiments were not randomized. The

investigators were not blinded to the study. Statistical analyses were performed using

either SciPy or Prism 9 (Graphpad). Symbols such as "****", "***", "**", and "*"

indicate $p < 0.0001$, $p < 0.001$, $p < 0.01$, and $p < 0.05$, respectively.

Figure legends

Figure 1. Intrinsic and extrinsic control of unilateral cytokinesis in *C. elegans*

embryos.

(**A**) Eccentric and concentric contractile ring closure of *C. elegans* embryonic

blastomeres shown by volumetric 4D imaging of NMY-2::GFP (green, non-muscle

myosin II), GFP::SAS-7 (green, centriole) and histone H2B::mCherry (magenta,

chromosome) in the zygote P_0, 2-cell stage AB, and isolated AB. In this and subsequent

figures, anterior and posterior are to the left and right, respectively. (**B**) Trajectory of ring

constriction. Outlines of the contractile ring during cytokinesis are plotted for single P_0,

AB, and isolated AB cells. Color coding indicates time relative to cytokinesis onset. (**C**)

Mean ring closure and eccentricity. Times are relative to cytokinesis onset. Error bands

indicate 95% confidence intervals. Scale bars, 10 µm.

Figure 2. Mitotic spindle positioning, RhoA activity, and myosin enrichment are not

asymmetric at the beginning of the P_0 and AB cytokinesis.

(**A**) Contractile ring assembly mechanism in *C. elegans* zygotes. (i) Mitotic spindle

positioning determines the active RhoA zone where centralspindlin activates ECT-2-

RhoGEF and RhoA; RhoA-GTP then activates myosin and actin assembly ("RhoA

pathway"). (ii) At the cell surface, cortical flow compresses the equatorial cell cortex,

producing actin alignment and myosin enrichment. Ring constriction further pulls the cell

cortex to induce pole-to-equator cortical flow to form a positive feedback loop

("compression-feedback pathway"). (**B, C**) Centrosome positions relative to the axis of

contractile ring constriction. LE and LG indicate distances between the centrosome and

cell cortex, respectively. (**D**) Kymographs of myosin and active RhoA localization at the

equatorial cell cortex (ROI shown in B) using intensity-based color-coding. (**E**) Ratios of

myosin and active RhoA signal intensities between leading and lagging cortices. Times

are relative to cytokinesis onset. Error bands and bars indicate 95% confidence intervals.

Scale bars, 10 μm.

Figure 3. Actin alignment asymmetry specifies leading and lagging cell cortices of P_0

cells.

(**A**) F-actin distribution in leading and lagging cortices at 50 seconds before cytokinesis

onset. White dotted boxes show F-actin alignments in B. Bottom panels show edge-

enhanced images. (**B**) F-actin orientation at leading and lagging cell cortices. Yellow

lines in the second and fourth columns indicate estimated F-actin orientations. Each box

is 12 × 9 μm. (**C**) Circular means of F-actin orientation during P_0 cytokinesis. (**D**) Ratios

of F-actin intensities between leading and lagging cortices. (**E**) Contractile ring

trajectories after perturbation of key actin and myosin regulators. (**F**) Mean ring closures

and eccentricities. Control data are the same as for Fig. 1C. (**G**) Eccentricities at 50% ring

closure. Times are relative to cytokinesis onset. Error bands and bars indicate 95%

confidence intervals. P-values were calculated using one-way ANOVA followed by

Holm-Sidak's multiple comparison test. Scale bars, 10 μm.

Figure 4. Lagging equatorial cortex is compressed along the contractile ring axis in

P_0 cells.

(**A**) Cortical flow of a single embryo visualized from multiple angles. Yellow arrows

indicate the movement of myosin foci from particle image velocimetry. (**B, C**) Concept

of cortical convergence. Net influx and efflux of cortical flow within a certain area were

calculated for the axes in parallel and perpendicular to the contractile ring (B). Cortical

convergence indicates the degree of cortex compression before cleavage onset. After

cleavage onset, convergence indicates both compression and the loss of cell surface from

the focal plane due to invagination (C). (**D**) Mean cortical convergences and cortical

flows calculated using the lateral cortex view. Arrow size scales with the cortical flow

velocity. Convergence in the local area is shown by the color code. Dotted boxes indicate

the equatorial regions of leading (top) and lagging (bottom) cortices. (**E**) Mean

convergences at equator (boxes in schematic) calculated using leading and lagging cortex

views. (**F**) Ring-axis convergences before cytokinesis onset. P-values were calculated by

the Mann-Whitney U-test. Times are relative to cytokinesis onset. Error bands and bars

indicate 95% confidence intervals. Scale bars, 10 μm.

Figure 5. Ring axis compression inhibits the furrow ingression and furrow-directed

cortical flow.

(**A**) Contractile ring trajectory of a single *act-2(or295ts)* mutant (left panel) and the

average of ten embryos (graph). (**B**) Kymographs of the cortical NMY-2::GFP with

intensity-based color coding. (**C**) Planes shown in (D-F). (**D**) NMY-2::GFP localization

at the top surface during cytokinesis. Yellow and light blue dotted circles indicate the

area exhibiting contraction and relaxation, respectively. (**E**) Ring en face view of the

same embryo shown in panel D. Dotted lines indicate top and bottom limits of the

contractile ring. Arrows indicate the movement of the ring limit. (**F**) Ring trajectories of

the contractile ring shown in (E). Top- and bottom-oriented movements are shown in

yellow and blue, respectively. (**G**) Relationship between ring velocity and cortical

convergence. Ring centroid velocities of one embryo were plotted with ring axis

convergences at the top surface. Positive ring velocity represents ring ingression from the

top and vice versa. Pearson's correlation coefficients in 95 sec windows are also shown.

(**H**) Pearson's correlation coefficients between ring velocity and cortical convergence

from five embryos. (**I**) Furrow-directed movement of myosin clusters during relaxation.

Kymographs of individual and averaged clusters are shown relative to the time of peak

signal intensity. Except for I, times are relative to cytokinesis onset. Error bands indicate

95% confidence intervals. Scale bars, 10 μm.

Figure 6. Adhesion results in resistance of cleavage furrow ingression in AB cells.

(**A**) Eccentric ring closure in AB cells. In addition to myosin II (green), cells are labeled

with centriole (green) and histone-H2B (magenta), except for *act-2(or295ts)* mutants.

White dotted lines indicate the AB-P_1 boundary. (**B**) Mean ring closure and eccentricity

in *pod-1(RNAi)*. (**C**) Ring eccentricity in intact embryos (control vs. *pod-1(RNAi)*), and in

isolated AB blastomeres with or without the attachment of adhesive beads. p-values were

calculated by Welch's t-test for the left graph and one-way ANOVA with Holm-Sidak's

multiple comparison test for the remaining data set. (**D, E**) Oblique view of contractile

rings in the bead attached AB cell. Ring trajectory and mean eccentricity are shown in D'

E' and D'' E'', respectively. (**F**) Ring eccentricity as a function of bead contact site. (**G**)

Angle of ingression during adhesion-dependent unilateral cleavage. Insets in the top

panels show the ring-bead interface. The graph at the right shows angles of ingression

from three experiments. Times are relative to cytokinesis onset. Error bands and bars

indicate 95% confidence intervals. Scale bars, 10 µm.

Figure 7. Adhesion inhibits furrow-directed cortical flow.

(**A**) Isolated AB cells attached to adhesive beads of different diameters. (**B**) Furrow-

directed cortical flow proximal (P) and distal (D) to bead attachment sites. (**C**) Myosin

movement with a bead attached. Arrowheads indicate myosin foci. Arrows below

micrographs indicate total displacements over 15 sec. (**D**) Working hypothesis for

symmetry-breaking in unilateral cytokinesis. Ring-axis compression and cell-cell

adhesion inhibit cortical ingression and furrow-directed cortical flow by suppressing ring-

dependent cortex pulling (left diagram). Perpendicular-axis compression in wild-type

embryos is a result of furrow-directed cortical flow that induces myosin enrichment at the

equatorial cortex through compression-dependent feedback. Suppression of cell cortex

pulling induces unilateral cytokinesis with and without the compression-dependent

feedback. Cortical stiffness asymmetry induced by intrinsic cortical dynamics and

external adhesion is the symmetry-breaking cue (right diagram). Differences in ring

trajectories can be explained by differences in the timing of stiffness change (diagrams i-

iv, lower right panel). Error bars indicate 95% confidence intervals. Scale bars, 10 µm. p-

values were calculated by one-way ANOVA with Holm-Sidak's multiple comparison

test.

Figure S1. Imaging and contractile ring analysis methods.

(**A**) Imaging conditions and analytical flow charts. For intact embryos, we used refractive

index matching medium and polystyrene beads as spacers. For isolated AB blastomeres,

we used a normal growth medium and a different analytical pipeline to estimate ring size

and position because of the cells' movement and rotation. Isolated AB cells were

measured three times, and average values were analyzed. (**B**) Temporal color-coded

image of 20 frames around cytokinesis onset showing that compression-free embryos do

not exhibit global cortical rotation. (**C**) Ring en face view after the rotation of 3D

projected data and ring segmentation. (**D**) Contractile ring closure data after alignment of

time series data relative to 2 % ring closure. Error bars indicate 95% confidence intervals.

Figure S2. Measurement of centrosome positioning and signal intensity.

(**A**) Image analysis pipelines for P0 (left) and AB (right) spindle positioning. All

processes were performed semi-automatically using in-house image J macros. (**B**) Image

analysis pipeline for active RhoA and myosin signal intensities. White boxes in the insets

of images on the right show the areas of measurement.

Figure S3. Generation of cortical myosin data used for PIV analysis.

(A) An image preprocessing pipeline used to generate cortical myosin data for Particle

Image Velocimetry analyses. See also Methods section. At the quality control step, very

noisy or dim images were not selected for PIV analyses. These images are usually from

image planes furthest from the objective lens.

Movie S1. Dynamics of cortical myosin and contractile ring of a single embryo

Left top: maximum projection of cell surface NMY-2::GFP. Bottom left: ring en face

view of NMY-2::GFP. Bottom middle: segmented ring. Bottom right: reconstructed ring

trajectory. Right graph: Contractile ring dynamics of the same embryo. Note that an

identical embryo was used to generate all data.

Movie S2. Cortical flow and flow vector map using Particle Image Velocimetry

The cell surface NMY-2::GFP of leading (left), lateral (middle), and lagging cortex views

(right). Yellow arrows are generated by Particle Image Velocimetry. Times are relative to

cytokinesis onset.

Movie S3. Average cortical flow and convergence map using lateral view

Perpendicular-axis (left) and ring-axis convergences (right) are shown. The color code is

the same as Figure 4D (warm colors: positive, cool colors: negative values). Times are

relative to cytokinesis onset.

Movie S4. Dynamics of cortical compression and cortical ingression

Cell surface (top) and ring en face view (bottom left) of NMY-2::GFP. Ring outlines and

centroid trajectory were color coded as in Figure 5F (yellow: movement towards the

contraction site, blue: movement away from the relaxation site).

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Figure 1. Intrinsic and extrinsic control of unilateral cytokinesis in *C. elegans* embryos.
(A) Eccentric and concentric contractile ring closure of *C. elegans* embryonic blastomeres shown by volumetric 4D imaging of NMY-2::GFP (green, non-muscle myosin II), GFP::SAS-7 (green, centriole) and histone H2B::mCherry (magenta, chromosome) in the zygote P_0, 2-cell stage AB, and isolated AB. In this and subsequent figures, anterior and posterior are to the left and right, respectively. **(B)** Trajectory of ring constriction. Outlines of the contractile ring during cytokinesis are plotted for single P_0, AB, and isolated AB cells. Color coding indicates time relative to cytokinesis onset. **(C)** Mean ring closure and eccentricity. Times are relative to cytokinesis onset. Error bands indicate 95% confidence intervals. Scale bars, 10 μm.

Figure 2. Mitotic spindle positioning, RhoA activity, and myosin enrichment are not asymmetric at the beginning of the P0 and AB cytokinesis.
(**A**) Contractile ring assembly mechanism in *C. elegans* zygotes. (i) Mitotic spindle positioning determines the active RhoA zone where centralspindlin activates ECT-2-RhoGEF and RhoA; RhoA-GTP then activates myosin and actin assembly ("RhoA pathway"). (ii) At the cell surface, cortical flow compresses the equatorial cell cortex, producing actin alignment and myosin enrichment. Ring constriction further pulls the cell cortex to induce pole-to-equator cortical flow to form a positive feedback loop ("compression-feedback pathway"). (**B, C**) Centrosome positions relative to the axis of contractile ring constriction. LE and LG indicate distances between the centrosome and cell cortex, respectively. (**D**) Kymographs of myosin and active RhoA localization at the equatorial cell cortex (ROI shown in B) using intensity-based color-coding. (**E**) Ratios of myosin and active RhoA signal intensities between leading and lagging cortices. Times are relative to cytokinesis onset. Error bands and bars indicate 95% confidence intervals. Scale bars, 10 µm.

Figure 3. Actin alignment asymmetry specifies leading and lagging cell cortices of P0 cells.
(**A**) F-actin distribution in leading and lagging cortices at 50 seconds before cytokinesis onset. White dotted boxes show F-actin alignments in B. Bottom panels show edge-enhanced images. (**B**) F-actin orientation at leading and lagging cell cortices. Yellow lines in the second and fourth columns indicate estimated F-actin orientations. Each box is 12 × 9 μm. (**C**) Circular means of F-actin orientation during P0 cytokinesis. (**D**) Ratios of F-actin intensities between leading and lagging cortices. (**E**) Contractile ring trajectories after perturbation of key actin and myosin regulators. (**F**) Mean ring closures and eccentricities. Control data are the same as for Fig. 1C. (**G**) Eccentricities at 50% ring closure. Times are relative to cytokinesis onset. Error bands and bars indicate 95% confidence intervals. P-values were calculated using one-way ANOVA followed by Holm-Sidak's multiple comparison test. Scale bars, 10 μm.

Figure 4. Lagging equatorial cortex is compressed along the contractile ring axis in P0 cells.
(**A**) Cortical flow of a single embryo visualized from multiple angles. Yellow arrows indicate the movement of myosin foci from particle image velocimetry. (**B, C**) Concept of cortical convergence. Net influx and efflux of cortical flow within a certain area were calculated for the axes in parallel and perpendicular to the contractile ring (B). Cortical convergence indicates the degree of cortex compression before cleavage onset. After cleavage onset, convergence indicates both compression and the loss of cell surface from the focal plane due to invagination (C). (**D**) Mean cortical convergences and cortical flows calculated using the lateral cortex view. Arrow size scales with the cortical flow velocity. Convergence in the local area is shown by the color code. Dotted boxes indicate the equatorial regions of leading (top) and lagging (bottom) cortices. (**E**) Mean convergences at equator (boxes in schematic) calculated using leading and lagging cortex views. (**F**) Ring-axis convergences before cytokinesis onset. P-values were calculated by the Mann-Whitney U-test. Times are relative to cytokinesis onset. Error bands and bars indicate 95% confidence intervals. Scale bars, 10 µm.

Figure 5. Ring axis compression inhibits the furrow ingression and furrow-directed cortical flow.
(**A**) Contractile ring trajectory of a single *act-2(or295ts)* mutant (left panel) and the average of ten embryos (graph). (**B**) Kymographs of the cortical NMY-2::GFP with intensity-based color coding. (**C**) Planes shown in (D-F). (**D**) NMY-2::GFP localization at the top surface during cytokinesis. Yellow and light blue dotted circles indicate the area exhibiting contraction and relaxation, respectively. (**E**) Ring en face view of the same embryo shown in panel D. Dotted lines indicate top and bottom limits of the contractile ring. Arrows indicate the movement of the ring limit. (**F**) Ring trajectories of the contractile ring shown in (E). Top- and bottom-oriented movements are shown in yellow and blue, respectively. (**G**) Relationship between ring velocity and cortical convergence. Ring centroid velocities of one embryo were plotted with ring axis convergences at the top surface. Positive ring velocity represents ring ingression from the top and vice versa. Pearson's correlation coefficients in 95 sec windows are also shown. (**H**) Pearson's correlation coefficients between ring velocity and cortical convergence from five embryos. (**I**) Furrow-directed movement of myosin clusters during relaxation. Kymographs of individual and averaged clusters are shown relative to the time of peak signal intensity. Except for I, times are relative to cytokinesis onset. Error bands indicate 95% confidence intervals. Scale bars, 10 µm.

Figure 6. Adhesion results in resistance of cleavage furrow ingression in AB cells.
(**A**) Eccentric ring closure in AB cells. In addition to myosin II (green), cells are labeled with centriole (green) and histone-H2B (magenta), except for *act-2(or295ts)* mutants. White dotted lines indicate the AB-P1 boundary. (**B**) Mean ring closure and eccentricity in *pod-1*(RNAi). (**C**) Ring eccentricity in intact embryos (control vs. *pod-1*(RNAi)), and in isolated AB blastomeres with or without the attachment of adhesive beads. p-values were calculated by Welch's t-test for the left graph and one-way ANOVA with Holm-Sidak's multiple comparison test for the remaining data set. (**D, E**) Oblique view of contractile rings in the bead attached AB cell. Ring trajectory and mean eccentricity are shown in D' E' and D'' E'', respectively. (**F**) Ring eccentricity as a function of bead contact site. (**G**) Angle of ingression during adhesion-dependent unilateral cleavage. Insets in the top panels show the ring-bead interface. The graph at the right shows angles of ingression from three experiments. Times are relative to cytokinesis onset. Error bands and bars indicate 95% confidence intervals. Scale bars, 10 μm.

Figure 7. Adhesion inhibits furrow-directed cortical flow.
(**A**) Isolated AB cells attached to adhesive beads of different diameters. (**B**) Furrow-directed cortical flow proximal (P) and distal (D) to bead attachment sites. (**C**) Myosin movement with a bead attached. Arrowheads indicate myosin foci. Arrows below micrographs indicate total displacements over 15 sec. (**D**) Working hypothesis for symmetry-breaking in unilateral cytokinesis. Ring-axis compression and cell-cell adhesion inhibit cortical ingression and furrow-directed cortical flow by suppressing ring-dependent cortex pulling (left diagram). Perpendicular-axis compression in wild-type embryos is a result of furrow-directed cortical flow that induces myosin enrichment at the equatorial cortex through compression-dependent feedback. Suppression of cell cortex pulling induces unilateral cytokinesis with and without the compression-dependent feedback. Cortical stiffness asymmetry induced by intrinsic cortical dynamics and external adhesion is the symmetry-breaking cue (right diagram). Differences in ring trajectories can be explained by differences in the timing of stiffness change (diagrams i-iv, lower right panel). Error bars indicate 95% confidence intervals. Scale bars, 10 μm. p-values were calculated by one-way ANOVA with Holm-Sidak's multiple comparison test.

Figure S1. Imaging and contractile ring analysis methods.
(**A**) Imaging conditions and analytical flow charts. For intact embryos, we used refractive index matching medium and polystyrene beads as spacers. For isolated AB blastomeres, we used a normal growth medium and a different analytical pipeline to estimate ring size and position because of the cells' movement and rotation. Isolated AB cells were measured three times, and average values were analyzed. (**B**) Temporal color-coded image of 20 frames around cytokinesis onset showing that compression-free embryos do not exhibit global cortical rotation. (**C**) Ring en face view after the rotation of 3D projected data and ring segmentation. (**D**) Contractile ring closure data after alignment of time series data relative to 2 % ring closure. Error bars indicate 95% confidence intervals.

Figure S2. Measurement of centrosome positioning and signal intensity.
(**A**) Image analysis pipelines for P0 (left) and AB (right) spindle positioning. All processes were performed semi-automatically using in-house image J macros. (**B**) Image analysis pipeline for active RhoA and myosin signal intensities. White boxes in the insets of images on the right show the areas of measurement.

A

Zygote P0 cell

Deconvoluted
4D data set

Ring dynamics
measurement
(Fig. S1)

Gaussian Blur
sigma = 1

Unsharp mask
radius =1
mask = 0.6

Centriole/cytoplasmic
signal deletion
(Small areas around
centrioles were
filled with zero
values for 10 slices

Intensity
adjustment
to avoid saturation

Deletion of near-half
volume
to avoid projection
of two oppsite
cortical sides

3D projection

Orientation
relative to
ring closure angle
at 5% closure

Lateral
cortex
view

Leading
cortex
view

Lagging
cortex
view

Quality control
(very noisy or dim images
were not used for analysis)

Cleavage
angle information

mid-plane

NMY-2::GFP
(myosin II)

SAS-7::GFP
(centriole)

1) When cleavage angle at 5% closure is horizontal
to the imaging plane (less than 50˚ or more than 130˚):
>> Entire area of near-half slices (12 slices) closest or
furthest to the objective lens were deleted.

2) When cleavage angle at 5% closure is perpendicular
to the imaging plane (between 50˚ and 130˚):
>> Near-half area (48%) across 31 slices were deleted
(images shown above)

Lagging cortex view

Leading cortex view

QC passed

Did not pass QC

Figure S3. Generation of cortical myosin data used for PIV analysis.
(**A**) An image preprocessing pipeline used to generate cortical myosin data for Particle Image Velocimetry
analyses. See also Methods section. At the quality control step, very noisy or dim images were not selected
for PIV analyses. These images are usually from image planes furthest from the objective lens.