Variability of visual field maps in human early extrastriate cortex challenges
the canonical model of organization of V2 and V3

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Abstract

Visual field maps in human early extrastriate areas (V2 and V3) are traditionally

thought to form mirror-image representations which surround the primary visual cortex

(V1). According to this scheme, V2 and V3 form nearly symmetrical halves with

respect to the calcarine sulcus, with the dorsal halves representing the lower

contralateral quadrants, and the ventral halves representing the upper contralateral

quadrants. This arrangement is considered to be consistent across individuals, and

thus predictable with reasonable accuracy using templates. However, data that

deviate from this expected pattern have been observed, but mainly treated as

artifactual. Here we systematically investigate individual variability in the visual field

maps of human early visual cortex using the large-scale 7T Human Connectome

Project (HCP) retinotopy dataset. Our results demonstrate substantial and principled

inter-individual variability in early visual retinotopy. Visual field representation in the

dorsal portions of V2 and V3 was more variable than in their ventral counterparts,

including substantial departures from the expected mirror-symmetrical patterns.

Surprisingly, only one-third of individuals had maps that conformed to the expected

pattern. In addition, retinotopic maps in the left hemisphere were more variable than

those in the right hemisphere. Our findings challenge the current view that inter-

individual variability in early extrastriate cortex is negligible, and that the dorsal

portions of V2 and V3 are roughly mirror images of their ventral counterparts.

Keywords

human connectome project, retinotopy, high-resolution fMRI, 7T, vision, hemispheric

differences, V3

Introduction

Non-invasive imaging has been instrumental in mapping the topographic organization of human visual cortex (Wandell and Winawer, 2010). The visual field maps in early visual areas (V1, V2, and V3) have been reported to be remarkably consistent across people, and predictable with reasonable accuracy using a template (Benson et al., 2014, 2012; Schira et al., 2010). While V1 contains a complete, first-order (continuous) representation of the contralateral visual hemifield, areas V2 and V3 form second-order (discontinuous) representations (Rosa, 2002). In these areas, a field discontinuity near the horizontal meridian splits the maps into upper and lower field representations that are only connected at the foveal confluence (Figure 1a,b). Accordingly, in parcellation schemes (Glasser et al., 2016; Wang et al., 2015), early visual areas form concentric bands, arranged in nearly symmetrical halves with respect to the calcarine sulcus. These bands, each containing the representation of a contralateral visual field quadrant, are referred to as the dorsal and ventral portions of V2 and V3 (Figure 1a). However, observations originating in several laboratories has indicated departures from this pattern, particularly in the dorsal region (Allen et al., 2021; Arcaro and Kastner, 2015; Benson and Winawer, 2018; Van Essen and Glasser, 2018). Even so, small-sized datasets, variability in acquisition sites and protocols, and methodological constraints have limited the investigation of this variability. As a result, no consensus exists about deviations from the canonical mirror-symmetrical organization of V2 and V3.

Figure 1 – Visual field mapping in the human early visual cortex. a, Coarse scale visual field mapping in the early visual cortex. The left (L) hemisphere maps the right visual field, and the right (R) hemisphere maps the left visual field. The dorsal portion of early visual areas maps the lower hemifield, and the ventral portion the upper field. **b,** Fine scale visual field mapping with visual field maps represented in polar angles (0-360º). The vertical (90º or 270º) and horizontal meridians (0º for the left and 180º for the right hemispheres) delineate boundaries between visual areas. **c,** Three "typical" polar angle maps, obtained from the left hemispheres of three individuals in the HCP retinotopy dataset, which conform to the traditional model. **d,** Three polar angle maps that deviate from this pattern, obtained from left hemispheres of three other individuals in the HCP retinotopy dataset. In the latter, the isopolar bands representing the anterior borders of dorsal V3 (V3d) and dorsal V2 (V2d) do not follow the proposed borders of V2 and V3 (dashed lines).

In humans, empirical visual field mapping using functional MRI (fMRI) is the primary means of delineating precise visual area boundaries in individuals. Visual field maps are typically defined in polar coordinates, resulting in two maps: one representing polar angle (or clock position) and the other eccentricity (or distance away from the fixation point) (Wandell and Winawer, 2010). In primates, isoangle bands representing the vertical and the horizontal meridians are thought to delineate boundaries between V1 and V2, V2 and V3, and V3 and higher-order visual areas (Figure 1b). Particularly, in human probabilistic maps, boundaries between the dorsal portions of early visual areas are roughly mirror images of their ventral counterparts (Figure 1c). Nevertheless, boundaries that deviate from the expected ones exist, but these have been mainly treated as artifactual, with researchers often overlooking the irregularities by simply drawing the boundaries to resemble that of a typical map as best as possible (Figure 1d). Here, it may be important to remark that the border between the dorsal parts of V2 and V3 is well known to be variable in other mammals, and that it typically does not coincide with the representation of the horizontal meridian (see Rosa and Manger, 2005 for review).

Although previous reports of individual variability in the dorsal portion of human early visual cortex were primarily anecdotal (Allen et al., 2021; Arcaro and Kastner, 2015; Benson and Winawer, 2018; Van Essen and Glasser, 2018), a recently developed deep learning model predicts that individual variability in retinotopy exists, and that this is correlated with variations in gross anatomy (e.g., the pattern of sulci and gyri) (Ribeiro et al., 2021). Moreover, studies modelling the formation of retinotopic maps in non-human primates also indicate that different variants could develop based on application of similar rules (Yu et al., 2020).

Motivated by these findings, here we systematically investigate individual variability in

visual field maps of human early visual cortex using a recently released, large-scale

dataset: the 181 participants, 7T Human Connectome Project (HCP) retinotopy

dataset (Benson et al., 2018). Our aims were to quantify the level of individual

variability throughout early visual cortex (V1-V3) and to determine whether there are

common modes of retinotopic organization that differ from the established view (i.e.,

whether individual retinotopic maps differ from a template in similar ways). Our results

challenge the current view that individual differences in retinotopic organization reflect

experimental artifacts that may be dismissed for practical purposes. In particular, they

demonstrate that the dorsal portions of human early visual areas are more

heterogeneous than previously acknowledged.

Materials and Methods

Dataset

We used the Human Connectome Project (HCP) 7T Retinotopy dataset (Benson et

al., 2018) to investigate individual variability in retinotopic maps of human early visual

cortex. This dataset consists of high-resolution functional retinotopic mapping and

structural data from 181 participants (109 females, age 22-35) with normal or

corrected-to-normal visual acuity. Participant recruitment and data collection were led

by Washington University and the University of Minnesota. The Institutional Review

Board (IRB) at Washington University approved all experimental procedures (IRB

number 201204036; "Mapping the Human Connectome: Structure, Function, and

Heritability"), and all participants provided written informed consent before data

collection (Van Essen et al., 2013). Additionally, the acquisition protocol has been

described in previous work (Benson et al., 2018; Van Essen et al., 2013).

Structural data were acquired at 0.7 mm isotropic resolution in a customized Siemens

3T Connectome scanner (Van Essen et al., 2013). Briefly, cortical surfaces were

reconstructed from T1w structural images using FreeSurfer and aligned to the 32k

fs_LR standard surface space. This standard 32k fs_LR cortical surface consists of

32,492 vertices sparsely connected, forming triangular faces. Functional data were

later aligned with this standard surface space.

Functional retinotopic mapping data were acquired using a Siemens 7T Magnetom

scanner at 1.6 mm isotropic resolution and 1 s TR. Data were preprocessed following

the HCP pipeline (Glasser et al., 2013), which included correction for head motion and

EPI spatial distortion, alignment of the fMRI data with the HCP standard surface space,

and denoising for spatially specific structured noise. Retinotopic mapping stimuli

comprised rotating wedges, expanding and contracting rings, and bars of different

orientations moving across different directions in the visual field. A population

receptive field (pRF) modeling procedure was then used to reconstruct visual field

maps (Benson et al., 2018; Dumoulin and Wandell, 2008; Kay et al., 2013), which

encompasses estimating the spatial preference of cortical surface vertices to different

locations of the visual field (i.e., its receptive field) defined in polar coordinates – for

more, see Benson et al, (2018). Hence, polar angle maps are retinotopic maps

reflecting the polar angle (angle relative to the horizontal vertical meridian) in the visual

field to which a vertex is most responsive, while eccentricity maps reflect the distance

from the center of the visual field (i.e., the fixation point). The combination of a polar

angle map and an eccentricity map completely specifies a map of the visual field.

Region of Interest

Early visual areas were defined by a surface-based probabilistic atlas (Wang et al.,

2015). This probabilistic atlas includes the dorsal and ventral portions of V1, V2 and

V3, not including the foveal confluence. For the clustering analysis, we slightly

modified the atlas by extending the dorsal border of V3 and including V1/V2/V3 foveal

confluence (Schira et al., 2009), in line with our previous work (Ribeiro et al., 2021).

Individual variability

We determined individual variability in visual field maps to quantify how variable these

maps were across visual areas (V1, V2, and V3), portions (dorsal and ventral), and

hemispheres (left and right) in human early visual cortex. First, we computed the

average retinotopic maps across all 181 individuals from the HCP retinotopy dataset

for both left and right hemispheres. Then, we iteratively calculated the vertex-wise

difference between an individual's retinotopic map and the average map. The

difference between two angles is given by:

$$\text{MIN} \left(\left| \hat{\theta} - \theta \right|, \left| \hat{\theta} - \theta + 2\pi \right|, \left| \hat{\theta} - \theta - 2\pi \right| \right) \tag{1}$$

for $0 < \theta < 2\pi$.

Finally, vertex-wise difference scores were averaged over vertices in the range of 1-

8º of eccentricity within the dorsal and ventral portions of early visual areas, resulting

in one scalar value per individual per visual area, which we refer to as the individual

variability. The eccentricity mask was defined using the group-average eccentricity

map. This range of eccentricity values was chosen because, in the original population

receptive field mapping experiment of the HCP, the visual stimulus extended to 8° of

eccentricity (Benson et al., 2018). Additionally, due to the inherent difficulty in mapping

the foveal confluence (Schira et al., 2009), we constrained our comparison to

eccentricity values above 1°. According to studies in non-human primates, this

corresponds approximately to half of the expected extent of V1, V2 and V3 (Gattass

et al., 1988, 1981).

Linear mixed-effects model

We determined whether there were main effects and interactions of hemispheres (left,

right), visual areas (V1, V2, V3), and portions (dorsal, ventral) on individual variability

of retinotopic maps using linear mixed-effect (LME) models. Standard ANOVAs and t-

tests assume statistical independence of individuals' data (Yu et al., 2022), which is

often not the case. For example, the 7T HCP retinotopy dataset includes data from 50

monozygotic and 34 dizygotic twins, totaling 168 individuals out of 181. Therefore, to

meet the statistical independence criterion, many data points would have to be

disregarded for standard statistical inference. However, LME models allow us to take

full advantage of the dataset by explicitly modeling cluster-specific means (random

intercepts). Indeed, individual variability from different visual areas is naturally

clustered by individuals (Magezi, 2015). Therefore, using this statistical model, we can

appropriately model individual-specific effects (Magezi, 2015; Yu et al., 2022).

In our linear mixed effect model, the dependent variable is the individual variability (Y),

which is modeled as a function of the fixed effects (β) of three factors (x) and their

interactions. These three factors are: hemisphere, visual area, and portion.

Additionally, we also consider the random effects (γ_i) associated with the individual (i

= 1, …, 181), and the random effects of each factor nested within the individual (γ_{ij},

with j = 1, 2, and 3). This model is expressed as:

$$Y_i = \beta_0 + \sum_{j=1}^{3} \beta_j x_j + \beta_{12}x_1x_2 + \beta_{13}x_1x_3 + \beta_{23}x_2x_3 + \beta_{123}x_1x_2x_3 + \sum_{j=1}^{3} \gamma_{ij} + \gamma_i + \varepsilon_i$$

where β_0 is the intercept and ε is the residual random error. We built two separate

models for individual variability associated with polar angle and eccentricity maps

using Jamovi ("The jamovi project (2021)," n.d.).

Individual variability in retinotopic maps and potential cofounds

Other potential sources of individual variability in retinotopic maps can be readily

included as covariates in LME models after their appropriate standardization by

computing z-scores. Here, we consider the effect of potential cofounders, including

curvature, normalized mean BOLD signal, and intra-individual variability in pRF

estimates. These factors are known to be correlated with retinotopy and could explain

part of the variability found across visual areas.

Curvature maps highlight the geometry of folding patterns of individuals' cortical

surfaces, with negative values representing sulci and positive gyri (as per the HCP

dataset). In V1, the horizontal and vertical meridian representations of the visual field

correlate with underlying sulcal patterns (Hinds et al., 2009; Holmes and Lister, 1916;

Horton and Hoyt, 1991; Inouye, 1909; Rajimehr and Tootell, 2009). This tight structure-

function relationship was further leveraged for individual-level predictions of retinotopy

from underlying anatomy, using atlas-fitting algorithms (Benson et al., 2014, 2012), a

Bayesian model (Benson and Winawer, 2018), and deep learning (Ribeiro et al.,

2021b). Therefore, although curvature is a good predictor of retinotopy, it is unclear if

it is sufficient to explain the systematic differences in individual variability across visual

areas. Here, we consider the individual variability in curvature maps as a covariate.

Individual variability in curvature was operationalized as the mean absolute difference

between an individual's curvature map and the corresponding average map over

vertices in the range of 1-8º of eccentricity within the dorsal and ventral portions of

early visual areas, resulting in one scalar value per individual per visual area.

The mean pre-processed BOLD signal is used as a proxy for the location of large veins

(Boyd Taylor et al., 2019; Kurzawski et al., 2022), which are known to affect pRF

estimates. Voxels near large veins show lower mean BOLD signal, a phenomenon

known as the venous eclipse, which systematically affects pRF estimates, for

example, in area hV4 (Boyd Taylor et al., 2019; Winawer et al., 2010). As such,

deviations in the expected mean BOLD signal could lead to deviations from the

expected retinotopic organization. Therefore, we considered individual variability in the

mean BOLD signal as another covariate. To do so, we first normalized the mean BOLD

signal (over the time course) by dividing the value of each vertex by the mean

maximum intensity (Boyd Taylor et al., 2019). Then, we computed the individual

variability as previously described for curvature maps.

Finally, different levels of individual variability in retinotopic maps could also reflect

variations in their reliability across visual areas. For example, in the HCP dataset,

despite pRF estimates being highly consistent between two model fits (Benson et al.,

2018), there was still some intra-individual (between-fit) variability. Thus, we

considered intra-individual variability in pRF estimates as a covariate. Intra-individual

variability was operationalized as the difference in pRF estimates from two pRF model

fits of half splits of the retinotopic mapping data (fit 2 and 3; Supplementary Table 1),

which were provided and determined using the first and second half of the temporal

data from each run (Benson et al., 2018). By using these two other fits, it is possible

to assess the reliability of the pRF parameter estimates (Supplementary Figure 1);

hence, the difference in pRF estimates is a proxy for the reliability of individuals'

retinotopic maps and can be included as a covariate in the linear mixed effects model.

Clusters of spatial organization

Lastly, we performed an exploratory clustering analysis to determine whether

retinotopic maps differ from the average map in similar ways, particularly in the dorsal

portion of early visual cortex. Specifically, we investigated the spatial overlap between

retinotopic maps as an unambiguous indicator of the similarity between two maps.

First, to obtain such a measure of the spatial overlap, the continuous polar angle maps

were converted into discrete maps, such that each vertex was categorized into one

out of four possible labels:

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$$\theta_{discrete} = \begin{cases} 0°, for\ 0° \leq \theta_{continuous} \leq 45° \\ 90°, for\ 45° < \theta_{continuous} \leq 180° \\ 270°, for\ 180° \leq \theta_{continuous} < 315° \\ 360°, for\ 315° \leq \theta_{continuous} < 360° \end{cases}$$

249   these categories were chosen because they highlight the location of visual area

250   boundaries. Discrete eccentricity maps were determined by:

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$$\theta_{discrete} = \begin{cases} 0°, for\ 0° \leq \theta_{continuous} \leq 2° \\ 2°, for\ 2° < \theta_{continuous} \leq 4° \\ 4°, for\ 4° < \theta_{continuous} \leq 6° \\ 6°, for\ 6° < \theta_{continuous} \end{cases}$$

Next, the spatial overlap between discrete maps from all possible pairs of individuals

was estimated using the Jaccard similarity coefficient (Levandowsky and Winter, 1971;

Taha and Hanbury, 2015). The Jaccard index estimates similarity between two maps

by taking the size of the intersection (in number of vertices) divided by the size of the

union of two label sets. Hence, the Jaccard score ranges from 0 to 1; the closer to 1

the score is, the more similar the two maps are. For our data and each pair of

individuals, the Jaccard index is determined from the two possible individuals'

combinations (i.e., individual 1 *vs.* individual 2 and individual 2 *vs.* individual 1) since

the order of the maps determines which map is the reference one. For each

combination, we estimated the Jaccard index for each label, and their weighted

average was determined using the number of labels' instances in the reference map

to account for label imbalance. Then, these two estimates were averaged, resulting in

one estimate of the spatial overlap between two individuals' discrete retinotopic maps.

To assess whether inter-individual differences fell into stereotyped patterns, we

applied a spectral clustering algorithm from Scikit-learn (Abraham et al., 2014;

Pedregosa et al., 2011). This algorithm operates on the low-dimensional embedding

of the affinity matrix (our Jaccard index-based similarity matrix), followed by K-means

clustering of the components of the eigenvectors in the low-dimensional space. This

low dimensional space is determined by selecting the most relevant eigenvectors of

the graph Laplacian of the affinity matrix, of which corresponding eigenvalues reflect

important properties of the affinity matrix that can be used to partition it (Luxburg,

2007). In implementing the spectral clustering algorithm, we set the number of clusters

to 6 and fixed the random state for replication purposes. We selected this number of

clusters as there are at least five different models of third-tier visual cortex organization

in non-human primates (Angelucci and Rosa, 2015), with a sixth cluster intended to

capture noisy or unclear retinotopic organization. After clustering, we computed each

cluster's mean map by averaging the continuous retinotopic maps across individuals

within each cluster.

Data and code availability

The data used in this study is publicly available at BALSA
(https://balsa.wustl.edu/study/show/9Zkk). All accompanying Python source code will
be available upon publication on GitHub.

Results

Individual variability in retinotopy

We defined an individual variability metric to quantify how variable visual field maps
are across visual areas (V1, V2, and V3), portions (dorsal and ventral), and
hemispheres (left and right) in human early visual cortex. First, we computed the
average visual field maps across all 181 individuals from the HCP retinotopy dataset
for both left and right hemispheres. Then, we iteratively calculated the difference
between an individual's visual field map and the average map. Finally, these
differences were averaged over all vertices within the dorsal and ventral portions of
early visual areas, resulting in one scalar value per individual per visual area, which is
our individual variability metric. Figure 2 shows the distribution of individual variability
scores across all participants.

Figure 2 – Individual variability in visual field maps of early visual areas. a, Hypothetical diagram of symmetrical distributions of individual variability across visual areas. Empirical distributions of individual variability of polar angle (**b** and **c**) and eccentricity (**d** and **e**) maps for both dorsal (dark shades) and ventral (lighter shades) portions of early visual areas in left (purple) and right (green) hemispheres.

We built a linear mixed effect model (Yu et al., 2022) to test the fixed effects of hemispheres, visual areas, and portions on individual variability of polar angle (Table 1) and eccentricity (Table 2) maps. Table 1 shows statistically significant main effects of all factors on individual variability of polar angle maps. Specifically, polar angle maps of the left hemisphere show higher individual variability than those found in the right hemisphere (mean difference = 3.35, p<.001). The dorsal portions of early visual areas are also more variable than the ventral portions (mean difference = 3.30, p<.001). Finally, post-hoc comparisons of visual areas indicated that V3 has higher

individual variability than V2 (mean difference = 1.60, p<.001) and V1 (mean difference

= 3.99, p<.001); V2 also has higher individual variability than V1 (mean difference =

2.38, p<.001). For brevity, we only show the main effects in Table 1, although we also

found statistically significant interactions. Briefly, each visual area in the left

hemisphere has significantly higher individual variability than its analogous area in the

right hemisphere. In addition, the dorsal portion of each visual area of the left

hemisphere is significantly more variable than its dorsal analogue in the right

hemisphere and the ventral analogue of both the left and right hemispheres (for more,

see the Supplementary Material). These findings suggest that individual variability in

polar angle representations varies across hemispheres, visual areas, and according

to dorsal/ventral locations.

Table 1 - Fixed effects parameter estimates for the linear mixed effect model of
individual variability of polar angle maps. SE – standard error; CI – confidence
interval.

Names	Effect	Estimate	SE	95% CI		df	t	p
				Lower	Upper			
Intercept	Intercept	18.58	0.30	17.99	19.17	180	61.86	<.001
Hemisphere	RH-LH	-3.35	0.32	-3.97	-2.72	181	-10.47	<.001
Visual area (1)	V2-V1	2.38	0.29	1.81	2.95	210	8.21	<.001
Visual area (2)	V3-V1	3.99	0.32	3.36	4.61	187	12.54	<.001
Portion	ventral - dorsal	-3.30	0.29	-3.86	-2.74	181	-11.50	<.001

Note: The table is titled "Polar angle" with a "95% CI" spanning header over Lower and Upper columns.

Moreover, Table 2 shows statistically significant main effects of the hemisphere, visual

area, and the visual area portion on individual variability of eccentricity maps. Like

polar angle maps, eccentricity maps of the left hemisphere show higher individual

variability than those in the right hemisphere (mean difference = 0.14, p<.001). The

dorsal portion of early visual areas is also more variable than the ventral portion (mean

difference = 0.13, p<.001). For visual areas, post-hoc comparisons indicated that the

only statistically significant difference was that of V3 versus V1, with V3 having higher

individual variability than V1 (mean difference = 0.05, p<.004). In addition, statistically

significant interactions were also found (Supplementary Material). Each visual area in

the left hemisphere has significantly higher individual variability than analogous areas

in the right hemisphere, except for V3. Eccentricity maps of each visual area's dorsal

portion in the left hemisphere are significantly more variable than the dorsal

counterpart in the right hemisphere, and the ventral analogues in both the left and the

right hemispheres.

Table 2 – Fixed effects parameters estimates for the linear mixed model of
individual variability of eccentricity maps. SE – standard error; CI – confidence
interval.

		Eccentricity						
				95% CI				
Names	Effect	Estimate	SE	Lower	Upper	df	t	p
Intercept	Intercept	0.81	0.02	0.77	0.85	180	41.86	<.001
Hemisphere	RH-LH	-0.14	0.01	-0.16	-0.11	181	-10.91	<.001
Visual area (1)	V2-V1	0.01	0.01	-0.01	0.04	402	0.98	0.326
Visual area (2)	V3-V1	0.05	0.01	0.02	0.08	182	3.24	0.001
Portion	ventral - dorsal	-0.13	0.03	-0.18	-0.07	180	-4.64	<.001

Influence of covariates on individual variability of retinotopic maps

Other potential sources of individual variability in retinotopic maps include covariates,

such as cortical curvature and mean BOLD signal. As mentioned in the Materials and

Methods section, these factors are known to be correlated with retinotopy and could

explain part of the variability found across visual areas. In Figure 3, we show pair-wise

correlations among polar angle, eccentricity, curvature, and normalized mean BOLD

signal for both V1-3 (main plots) and each visual area separately (inset plots). Across

V1-3 (Figure 3, main plots), polar angle was significantly correlated with curvature and

the mean BOLD signal in both the right and left hemispheres; eccentricity was

correlated with the mean BOLD signal in both hemispheres and curvature in the right

hemisphere. Moreover, the correlation between these maps varied across visual

areas. Specifically, correlations between polar angle and curvature, polar angle and

mean BOLD signal, and curvature and mean BOLD signal decreased from V1 to V2

to V3.

Figure 3 – Retinotopic maps correlation with covariates. Pair-wise correlations

among polar angle, eccentricity, curvature, and normalized mean BOLD signal for

early visual areas (V1-3; main plot) and each visual area separately (inset plots). Polar

angle maps were converted such that 0º corresponds to the horizontal meridian and

90º corresponds to the upper and lower vertical meridians (Kurzawski et al., 2022).

Finally, data were concatenated across all participants (n=181). * p < .001.

Given the meaningful correlation between some of these variables and their varying

degree of association across visual areas, we further include individual variability in

curvature and mean BOLD signal maps and the intra-individual variability in pRF

estimates (a proxy for the reliability of the retinotopic maps) as covariates in the LME

model (Tables 3 and 4). Our findings indicate that the main effects found here were

not a mere reflection of variation in the reliability of the individual maps and other

covariates. For example, we found that the main effects of all factors (hemispheres,

visual areas, and portions) on individual variability of polar angle maps persisted, but

the estimated effects were slightly reduced (Table 3). For eccentricity, we found the

main effects of hemisphere and portion but not visual area after accounting for these

covariates (Table 4). Crucially, these findings suggest that individual variability in polar

angle representations varies as a function of hemispheres, visual areas, and

dorsal/ventral locations. These effects are not simply due to trivial intra-individual

variability in pRF estimates or individual variability in curvature and the mean BOLD

signal.

Table 3 - Fixed effects parameter estimates for the linear mixed effects model of

individual variability of polar angle maps using covariates. The covariates

included in the model were intra-individual variability in pRF estimates, and individual

variability in curvature and the mean BOLD signal. SE – standard error; CI –

confidence interval.

		Polar angle		95% CI				
Names	**Effect**	**Estimate**	**SE**	**Lower**	**Upper**	**df**	**t**	**p**
Intercept	Intercept	18.58	0.27	18.06	19.11	179	69.58	<.001
Hemisphere	RH-LH	-2.44	0.28	-2.99	-1.89	189	-8.71	<.001
Visual area (1)	V2-V1	1.93	0.33	1.29	2.57	323	5.90	<.001
Visual area (2)	V3-V1	3.54	0.32	2.92	4.16	288	11.22	<.001
Portion	ventral - dorsal	-2.12	0.29	-2.69	-1.54	207	-7.20	<.001
Intra-individual variability	Intra-individual variability	2.90	0.16	2.58	3.22	1364	17.81	<.001
Individual variability in curvature	Individual variability in curvature	0.40	0.14	0.12	0.68	1812	2.82	0.005
Individual variability in mean BOLD signal	Individual variability in mean BOLD signal	0.21	0.19	-0.16	0.57	597	1.11	0.268

Table 4 - Fixed effects parameter estimates for the linear mixed effects model of individual variability of eccentricity maps using covariates. The covariates included in the model were intra-individual variability in pRF estimates, and individual variability in curvature and the mean BOLD signal. SE – standard error; CI – confidence interval.

				95% CI				
Names	**Effect**	**Estimate**	**SE**	**Lower**	**Upper**	**df**	**t**	**p**
Intercept	Intercept	0.81	0.01	0.78	0.84	179	54.64	<.001
Hemisphere	RH-LH	-0.07	0.01	-0.09	-0.05	201	-6.40	<.001
Visual area (1)	V2-V1	-0.02	0.01	-0.05	0.01	506	-1.52	0.128
Visual area (2)	V3-V1	-0.02	0.02	-0.05	0.01	262	-1.20	0.231
Portion	ventral - dorsal	-0.07	0.02	-0.11	-0.03	186	-3.24	.001
Intra-individual variability	Intra-individual variability	0.21	0.01	0.20	0.23	1982	26.51	<.001
Individual variability in curvature	Individual variability in curvature	0.01	0.01	-0.00	0.02	1829	1.52	0.128
Individual variability in mean BOLD signal	Individual variability in mean BOLD signal	0.02	0.01	0.00	0.03	489	2.34	0.020

The table is headed "Polar angle".

Common modes of variability

Next, we performed an exploratory analysis to determine whether polar angle maps differ from the average map in similar ways, particularly in the dorsal portion of early

visual cortex of the left hemisphere. Note that an analogous analysis was performed

for eccentricity maps, but in agreement with our statistical models we did not find

meaningful differences across eccentricity map clusters (Supplementary Figure 2). We

computed the extent of overlap between discrete polar angle maps from all possible

pairs of individuals using the Jaccard index, resulting in a similarity matrix (Figure 4a).

Next, we applied a spectral clustering algorithm with a fixed number of clusters equal

to 6 (Figure 4b). Finally, we averaged the continuous polar angle maps across

individuals within each cluster to visualize common patterns of retinotopic organization

in the dorsal portion of early visual cortex (Figure 4c).

Figure 4 - Clusters of retinotopic organization in the dorsal portion of early visual cortex. a, Continuous polar angle maps were converted into discrete maps, such that each vertex would be categorized into one out of four possible labels. Spatial overlap between discrete maps was estimated using the Jaccard similarity coefficient from all possible pairs of individuals, resulting in a 181×181 similarity matrix. **b,** Then, we applied a spectral clustering algorithm – setting the number of clusters to 6. **c,** An average map (discrete and continuous) was calculated for each cluster by averaging the continuous polar angle maps across all individuals within each cluster.

Our findings clearly indicate shared patterns of retinotopic organization that deviate from the typical polar angle representation in the dorsal portion of early visual cortex

(Figure 1c). Specifically, average maps from clusters 1 and 5 capture nearly a third of

individuals and show typical polar angle representations, with clear boundaries

between V1/V2 and V2/V3 (Figure 1c and Figure 4c). However, clusters 2, 3, and 4

capture nearly two thirds of individuals and deviate from this typical polar angle

representation (Figure 4c). The average map from cluster 2 shows that the boundaries

between V1 and V2, and the most anterior portion of V3 and higher-order visual areas,

merge to form a Y-shaped (or forked) lower vertical representation. Clusters 3 and 4

show a truncated V3 boundary, indicating that dorsal V3 does not cover the entire

quarter visual field (i.e., from 360º to 270º) either throughout its length or only in its

most anterior portion. Finally, cluster 6 reflects unclear retinotopic organization, with a

handful of individuals' retinotopic maps showing overall low correspondence with the

typical retinotopic organization.

Qualitatively, individual maps seem to agree with their corresponding average cluster

map, but there are some exceptions (Figure 5, Supplementary Figure 3). Figure 5

shows the average cluster maps from each cluster and examples of individuals' maps

that are qualitatively similar and dissimilar to their corresponding average cluster map.

While most polar angle maps correspond well with their average cluster maps (as seen

in the middle row of Figure 5), there is also an apparent mismatch between a few maps

and their corresponding cluster average (bottom row in Figure 5). For example,

individual #132118 was assigned to Cluster 4, but their polar angle map is qualitatively

more similar to Cluster 5. These mismatches are likely due to the extensive overlap

between within-cluster and between-clusters distributions of pairwise Jaccard scores

(Figure 6). Note in Figure 6 that the within-cluster distributions highlighted in grey are

generally shifted to the right compared to the between-clusters distributions, indicating

their higher Jaccard scores. However, the overlap between these distributions is

substantial. For example, the between cluster 1 and 5 distribution overlaps with within-

cluster 1 distribution throughout its entirety, which is justified by the significant

similarity between their average maps. Despite this, we found that the average within-

cluster Jaccard score is 0.54 (SD = 0.07), while the average between-clusters score

is 0.46 (SD = .08), showing that pairs of maps within a cluster are, on average, more

similar than between-clusters.

Figure 5 - Qualitative evaluation of clusters. Average cluster maps are shown in

the top row. The middle row shows examples of maps from each cluster with a similar

retinotopic organization to the corresponding average map. Finally, in the bottom row,

examples of those with dissimilar organizations are shown.

Within and between-clusters
distributions of pairwise Jaccard scores

449

450 Figure 6 - Distributions of pairwise Jaccard scores. Within and between-clusters

451 distribution of Jaccard scores across all pairs of individuals. Within-cluster distributions

452 are highlighted in grey. Between-clusters distributions are the same regardless of the

453 order of the clusters, i.e., the Jaccard score distribution between cluster 1 and cluster

454 2 ('between 1 and 2') is the same as the one between cluster 2 and 1. Black vertical

455 lines indicate distributions' means.

456 Discussion

457 We systematically investigated individual variability in visual field representation of

458 human early visual cortex using the HCP 7T retinotopy dataset. We found that

459 retinotopic maps in the left hemisphere were more variable than those in the right

hemisphere. Moreover, in the left hemisphere the dorsal portions of early visual areas

were more variable than their ventral counterparts. Additionally, we found that these

effects are not merely due to trivial intra-individual variability in pRF estimates or

individual variability in curvature and the mean BOLD signal. Thus, we investigated

whether there were common motifs in the observed individual variability in retinotopic

maps. This analysis showed that deviations from the canonical model of continuous,

alternating bands of vertical and horizontal meridian representation in V2 and V3 exist

in the majority of individuals. Overall, our findings challenge the current view that the

dorsal portions of early visual areas form retinotopic maps which are consistent

between individuals as roughly mirror images of their ventral counterparts.

Although previous evidence for the variability seen across dorsal early visual cortex in

humans has been mostly anecdotal, a number of studies have indicated a complex,

retinotopic organization of dorsal early visual areas in non-human primates, using both

electrophysiological recordings and high-resolution fMRI (Angelucci and Rosa, 2015;

Gattass et al., 1988; Sereno et al., 2015; Zhu and Vanduffel, 2019). Accordingly, there

is a long-standing debate about the number of visual areas – and their boundaries –

in the third-tier visual cortex of New and Old-World monkeys (Angelucci and Rosa,

2015; Hadjidimitrakis et al., 2019). However, the question of whether the areal

boundaries in this region show significant individual variability has not been studied

systematically in non-human primates. Only Gattass et al. (1988) reported, in the

macaque monkey, that the representation of the lower vertical meridian in dorsal V3

varied across individuals, but firm conclusions could not be drawn due to the small

sample. These authors indicated that some animals showed a continuous

representation of this meridian along the rostral border of this area, whereas in others

additional field discontinuities created a discontinuous representation. Notably, the

same discontinuities in the anterior border of dorsal V3 were also found in our

systematic investigation of individual variability in human polar angle maps. It is also

significant that the same pattern of variation (relatively simple and reproducible

representations of the upper contralateral quadrant, and complex and variable

representations of the lower quadrant) characterize V2 and V3 in at least one non-

primate, the cat (Rosa and Manger, 2005; Tusa et al., 1979). Overall, our findings in

humans demonstrate that the organization of dorsal early visual areas is more

heterogeneous than previously acknowledged and suggest that this may be a common

feature of mammals with developed vision.

Although different models of third-tier visual cortex organization in non-human

primates (Angelucci and Rosa, 2015) also suggest unusual eccentricity mapping, we

did not find meaningful differences in clusters of eccentricity maps. This may be

associated with the limited extent of the visual stimulus (up to 8° of eccentricity)

(Benson et al., 2018) and remains to be further investigated. Another alternative is

having a complex pattern of polar angle representation coexisting with a preserved

eccentricity gradient, as demonstrated by previous work in areas V2 and V3 of cats

(Tusa et al., 1979), flying foxes (Rosa, 1999), ferrets (Manger et al., 2002) and tree

shrews (Sedigh-Sarvestani et al., 2021).

Our investigation provides firm evidence for individual variability in the retinotopic

organization across parts of early visual areas in the human visual cortex. Moreover,

the exploratory analysis indicates the presence of shared patterns of retinotopic

organization that deviate from the typical polar angle representation in the dorsal

portion of early visual cortex. Future work could extend these insights through

additional analyses – for example, by employing different similarity metrics, using

different features, or changing the number of clusters. Here, we limited our analysis to

the spatial overlap of discrete polar angle maps, which means that a pair of

qualitatively similar but spatially misaligned polar angle maps, for example, might have

a low Jaccard score. If another more suitable metric can consider the topographic

organization of polar angle maps regardless of the spatial location, it would be possible

to increase the consistency between an individual's map and their cluster average

map. It would also be possible to estimate the similarity between two individuals'

retinotopic maps from specific features extracted from the maps (such as linear

magnification along isoeccentricity lines), to provide insights into changes in these

properties as a function of cortical location (Schira et al., 2010). Finally, it is important

to note that selecting the ideal number of clusters depends on the similarity metric

employed, prior knowledge, and the clustering algorithm. Therefore, future work could

be performed to explore the effect of the number of clusters on clustering quality

(perhaps as indicated by within- vs. between-cluster similarity measures).

Given the presence of individual variability across early visual cortex in humans,

another potential line of investigation involves the origin of this variability. Pertinently,

we recently developed a deep learning model of retinotopy able to predict this

individual variability from anatomical information (including curvature) (Ribeiro et al.,

2021; Ribeiro et al., 2022), suggesting that it is, to some extent, a structure-related

variation. Accordingly, here we modelled individual variability in curvature as an

anatomy-related covariate, which significantly affected the individual variability of polar

angle maps. Additionally, to determine if our findings were not merely due to other

covariates, we included the normalized mean BOLD signal and intra-individual

variability in pRF estimates as additional covariates. The former is an important proxy

for the location of large veins (Boyd Taylor et al., 2019; Kurzawski et al., 2022), which

are known to affect pRF estimates systematically (Boyd Taylor et al., 2019; Winawer

et al., 2010); the latter is a proxy for the reliability of individuals' retinotopic maps, which

could vary across visual areas. While we found a significant effect of intra-individual

variability, the main effects of all factors (hemispheres, visual areas, and portions) on

individual variability of polar angle maps persisted. This finding indicates that these

effects were not merely due to the covariates included in the model.

These results raise many questions regarding how retinotopic maps develop. For

example, studies modelling the formation of retinotopic maps in development have

suggested that multistable solutions may occur depending on factors such as the

degree of elongation of the area (Sedigh-Sarvestani et al., 2021; Wolf et al., 1994) and

adjacency with other areas (Yu et al., 2020), which do not violate the need to minimize

the length of connections (Durbin and Mitchison, 1990; Swindale, 1996). Therefore,

future work could evaluate whether there is an overlap between function- and

anatomy-based clusters to help elucidate the developmental mechanisms underlying

the variability of human dorsal extrastriate cortex.

Finally, another finding that requires consideration is the interhemispheric difference

revealed in our data: retinotopic maps in the left hemisphere showed more variation

than those in the right hemisphere. To date, there has been no report of

interhemispheric differences in early visual cortex of other mammals, including non-

human primates. In part, this may be traced to the relatively small samples in these

studies compared to those possible using human fMRI. However, another possibility

is that such differences may arise more frequently in human brains due to the scaling

of callosal connections with brain size (Rilling and Insel, 1999), which may promote a

higher degree of connectional independence during development.

In conclusion, using a large-scale brain imaging dataset, we provide new insights into

the variability in the topographical organization of human visual cortex. These insights

may prove crucial in guiding further experimental investigations and theories about

retinotopic organization differentiation across species, development, and individuals.

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Competing financial interests

The authors declare no competing financial interests.

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