A cautionary note on quantitative measures of phenotypic convergence

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ABSTRACT

1. Tests of phenotypic convergence can provide evidence of adaptive evolution, and the popularity of such studies has grown in recent years due to the development of novel, quantitative methods for identifying and measuring convergence. These methods include the commonly applied $C1$–$C4$ measures of Stayton (2015), which measure morphological distances between lineages in phylomorphospace, and Ornstein-Uhlenbeck evolutionary model-fitting analyses to test whether lineages have convergently evolved toward adaptive peaks.

2. We test the performance of C-measures and other convergence measures under various evolutionary scenarios. We reveal critical issues with C-measures, which we help to address by developing novel convergence measures ($Ct1$–$Ct4$-measures) that measure distances between lineages at specific points in time.

3. The most substantial issue with *C*-measures is that they will often misidentify divergent lineages as convergent; this is most common when focal taxa are

morphological outliers. In contrast, our new *Ct*-measures minimize the possibility of misidentifying divergent taxa as convergent. *Ct*-measures are most appropriate

when putatively convergent lineages are of the same or similar geologic ages (e.g., extant taxa), meaning that all or most of the evolutionary histories of the lineages

overlap in time. Beyond *C*-measures, we demonstrate issues with other convergence measures. We find that all distance-based convergence measures are

influenced by the position of putatively convergent taxa in morphospace, with morphological outliers often statistically more likely to be categorized as convergent

by chance. Further, we demonstrate that multiple-regime Ornstein-Uhlenbeck models often outperform simpler models when fit to divergent lineages, highlighting

that model support for multiple-regime models should not always be assumed to reflect convergence among focal lineages.

4. The issues with convergence measures highlighted here are especially relevant because they influence the degree of inferred convergence in many past studies,

raising the concern that many lineages have been mistakenly identified as convergent. Our new convergence measures provide researchers with an improved

comparative tool for future studies. Nonetheless, we emphasize that all available convergence measures are imperfect, and researchers should recognize the

limitations of these methods and use multiple lines of evidence when inferring and measuring convergence.

KEYWORDS: adaptive evolution, convergent evolution, evolutionary models, Ornstein-Uhlenbeck models, phylomorphospace

INTRODUCTION

Phenotypic convergence among distantly related taxa is commonly associated with adaptive evolution (e.g., Darwin 1859, Losos 2011), but it can also occur stochastically (Stayton 2008) or as a byproduct of shared developmental constraints (Losos 2011, Speed and Arbuckle 2016). Evidence for adaptive convergence is strengthened when the magnitude of convergence is greater than expected by chance, and also when the convergent phenotypes are shown to be tied to similar ecological or functional roles. Thus, quantitative examinations of phenotypic convergence are important; they assist researchers in identifying adaptive morphological changes that are driven by shared selective pressures and/or developmental constraints. Novel methods for identifying and measuring convergence have recently been developed (Mahler et al. 2013, Arbuckle et al. 2014, Ingram and Mahler 2013, Stayton 2015A, Speed and Arbuckle 2017, Castiglione et al. 2019), and these methods are often accompanied by statistical tests for comparing the measured convergence to that which is expected from a null model-fitting hypothesis or random data permutations. This has increased the accessibility of quantitative tests for phenotypic convergence, leading to a flood of recent studies on that topic (e.g., Friedman et al. 2016, Zelditch et al. 2017, Baliga and Mehta 2018, Da Silva et al. 2018, Arbour and Zanno 2020, Button and Zanno 2020, Grossnickle et al. 2020, Martinez et al. 2020, Serio et al. 2020, Rincon-Sandoval et al. 2020, Spear and

76   Williams 2020, Baumgart et al. 2021, Huie et al. 2021, Rovinsky et al. 2021, Tamagnini

et al. 2021, Alfieri et al. 2022, Bennion et al. 2022, Canale et al. 2022, Law 2022).

78   Phenotypic convergence is often defined as lineages evolving to be more

similar to one another than were their ancestors (Losos 2011, Stayton 2015A, Mahler et

80   al. 2017), and we follow that definition here. Thus, a signature of convergence is

phylogenetic tips that are phenotypically more similar to one another than expected

82   based on assumptions of random change over time; the degree of this similarity of tips

is often quantified by convergence measures (Speed and Arbuckle 2017). However, a

84   confounding issue is that multiple types of evolutionary trajectories can result in

lineages that are more similar to one another than expected by chance but are not

86   convergent (as defined above). This includes lineages that retain a shared ancestral

morphology (see discussion on 'conservatism' below) and lineages that have parallel

88   evolutionary trajectories from a similar ancestral trait condition.

          The C1–C4 measures (hereafter, 'C-measures') developed by Stayton (2015A)

90   have emerged as an especially popular means of quantifying phenotypic convergence

(e.g., Friedman et al. 2016, Zelditch et al. 2017, Baliga and Mehta 2018, Da Silva et al.

92   2018, Arbour and Zanno 2020, Button and Zanno 2020, Grossnickle et al. 2020,

Martinez et al. 2020, Rincon-Sandoval et al. 2020, Spear and Williams 2020, Baumgart

94   et al. 2021, Huie et al. 2021, Rovinsky et al. 2021, Tamagnini et al. 2021, Alfieri et al.

2022, Bennion et al. 2022, Canale et al. 2022, Law 2022). C-measures are calculated

96   using geometric distances in phylomorphospace between focal lineages, relying on

ancestral reconstructions for morphologies at ancestral nodes. The underlying feature of

98   the C-measures is the comparison of two measurements: the maximum phenotypic

distance between lineages at any points in their evolutionary histories (D_{max}) and the

100   phenotypic distance between phylogenetic tips (D_{tip}). More specifically, D_{max} is the

greatest distance between any two points along the lineages in phylomorphospace, with

102   candidate distances including any points between the lineages' most recent common

ancestor and the tips (Fig. 1A). $C1$ is the primary C-measure and calculated as $1 -$

104   (D_{tip}/D_{max}), with the resulting value representing "the proportion of the maximum

distance between two lineages that has been 'closed' by subsequent evolution" (Stayton

106   2015A). In our conceptual illustration (Fig. 1A), two focal lineages have convergently

evolved such that their tips are 70% closer to each other than their D_{max}, resulting in a

108    $C1$ score of 0.7.

One reason for the popularity of C-measures is that they can distinguish between

110   convergence and conservatism, which both result in distantly-related phylogenetic tips

with similar phenotypes. The key difference between convergence and conservatism

112   centers on the ancestral morphologies of the lineages. Whereas convergence involves

ancestors that were less morphologically similar to each other than their descendant

114   tips are to one another (Losos 2011, Stayton 2015A, Mahler et al. 2017), conservatism

is the lack of substantial phenotypic divergence from ancestral morphologies relative to

116   what is expected from random processes (Losos 2008, Moen et al. 2013, McLean et al.

2018). The 'blue' lineages in Figure 1B could be considered an example of

118   conservatism; they have not evolved far from the ancestral morphology. C-measures

account for ancestral patterns via the D_{max} measurement (Fig. 1A). Alternative distance-

120   based methods for testing for convergence (e.g., Wheatsheaf index, Arbuckle et al.

2014, Arbuckle and Minter 2015; θ, Castiglione et al. 2019) cannot adequately

122   differentiate between convergence and conservatism (or parallelism) because

phenotypic distances between ancestral morphologies are not considered or, in the

124   case of θ, only partially integrated (Castiglione et al. 2019).

In addition to distance-based measures, researchers often use evolutionary

126   model-fitting analyses to test for convergence, relying on strong fits of multiple-regime

Ornstein-Uhlenbeck (OU) models (Hansen 1997, Butler and King 2004) to

128   morphological data for evidence of convergence (e.g., Mahler et al. 2013, Ingram and

Mahler 2013, Friedman et al. 2016, Mahler et al. 2017, Baliga and Mehta 2018,

130   Grossnickle et al. 2020, Martinez et al. 2020). An OU process involves 'attraction'

toward an 'attractor' or trait optimum (commonly interpreted as the location of an

132   adaptive peak), and this attraction and any resulting convergence is often assumed to

be due to selective pressures toward adaptive peaks (Fig. 1B). Convergence is

134   identified when the best-supported model indicates that two or more focal lineages have

independently evolved toward the same trait optimum. Convergence can be tested by

136   examining model support for multiple-regime OU models in which focal taxa are

classified into regimes *a priori* or by examining whether focal taxa are independently

138   identified (i.e., without *a priori* classifications) as shifting toward shared adaptive peaks.

The latter method can be implemented using functions in the *SURFACE R* package

140   (Ingram and Mahler 2013; but see Adams and Collyer 2018 for a critique), which was

developed specifically for identifying convergence, or with other *R* packages designed

142   to identify peak shifts (e.g., *Bayou*, Uyeda and Harmon 2014; *l1ou*, Khabbazian et al.

2016; *phyloEM*, Bastide et al. 2018). However, an OU process does not require that

144   independent lineages shifting toward a peak come from more dissimilar ancestors and

thus may not meet the criteria of convergence used in this paper, and interpreting

146   convergence from model support for multiple-regime OU models should be made with

caution because OU models are prone to overfitting to data (Cooper et al. 2016, Adams

148   and Collyer 2018). Further, when focal taxa exhibit the ancestral morphology, it may be

challenging to use OU model-fitting analyses to determine whether the lineages exhibit

150   the morphology due to convergence or conservatism; both scenarios reflect

expectations of an OU process (i.e., selection toward a shared morphology).

152   Nonetheless, a benefit of OU model-fitting analyses is that the magnitude of the

attraction parameter allows an estimate of selective strength toward adaptive peaks,

154   therefore providing valuable information about the evolutionary process that may be

driving convergence.

156   Here, we test the performances of *C*-measures and other convergence measures

by applying the methods to simulated data in which a subset of lineages are modeled as

158   truly convergent or truly divergent. Our results highlight a critical concern with the *C*-

measures: in some circumstances they may lead to misclassification of divergent

160   lineages as convergent, and this is more common when those lineages are outliers in

morphospace. We find that θ (i.e., the angle between phenotypic vectors; Castiglione et

162   al. 2019) is also biased toward misclassifying morphological outliers as convergent,

whereas the Wheatsheaf index (Arbuckle et al. 2014, Arbuckle and Minter 2015) is

164   biased but in the opposite direction, indicating greater convergence among lineages that

retain their shared ancestral morphology. Further, we find that multiple-regime OU

166   models can outperform simpler models as fits to divergent lineages, highlighting that

model support for multiple-regime OU models should not be assumed to always be

168   indicative of convergence. Finally, we present an improved method for calculating *C*-

    measures that minimizes the possibility of erroneously measuring divergent lineages as

170   convergent.

172   **METHODS**

    Evolutionary simulations

174   We generated a series of simulated trait datasets to ascertain how frequently

    convergence measures correctly identify *convergent* lineages and misclassify *divergent*

176   lineages as convergent. Simulated datasets are intended to reflect typical empirical

    datasets, but we include some unrealistically extreme morphological outliers to help

178   identify trends. Thus, we simulated traits for 201 species included in a recent

    phylogenetic treatment of extant mammals, resulting in taxon sampling and

180   phylogenetic structure comparable to many recent comparative studies (Chen and

    Wilson 2015, Grossnickle et al. 2020, Weaver and Grossnickle 2020, Pevsner et al.

182   2022). We obtained 1000 randomly chosen phylogenetic trees from the posterior

    distribution of Upham et al.'s (2019) 'completed trees' analysis. We then used

184   *TreeAnnotator* (Drummond et al. 2012) to generate a maximum clade credibility tree,

    which was pruned to the species in our sample. The sample includes 13 gliding-

186   mammal species representing five independent evolutionary origins of gliding behavior.

    We treated the gliders as the focal lineages (*sensu* Grossnickle et al. 2020); they were

188   the subject of manipulation in our simulations (as such, we refer to those simulated

    glider data as 'gliders'). The five 'glider' clades are spread across the mammalian

190   phylogeny and have varying evolutionary origin ages, making them ideal for

representing typical empirical datasets.

192   Each simulated dataset included six morphological traits. In the non-glider (i.e.,

'base') parts of the tree, all six traits were simulated to evolve via Brownian motion

194   (BM). In 'glider' clades, between three to six of these traits were simulated to evolve via

an OU process (except for drift-based divergence simulations in which all traits were

196   BM-evolved; see descriptions below), with optima varying to produce convergent or

divergent trajectories. The BM component of the simulation ('base simulation') was

198   performed using the *SimulateContinuousTraitsOnTree* function in the *Phylogenetics for*

Mathematica package (Polly 2019). The ancestral value for each trait was arbitrarily set

200   to 0.0 and the step rate, σ^2, was set at 1.0 per million years. (Note that the phylogenetic

tree was the same for each simulation, but the BM trait values were re-simulated with

202   every 'base simulation.') In 'gliders,' traits evolving via an OU process toward trait

optima (see below) were simulated using the *LineageEvolution* function in

204   *Phylogenetics for Mathematica* (ancestral trait values were those generated via BM at

the base of each clade). Phylogenetic branches of 'gliders' were those tipped by one of

206   the 13 'glider' species, plus the subtending branches below clades whose tips were all

'gliders.'

208   We generated four types of simulations: 1) convergence of 'gliders' via selection

(OU-evolved traits), 2) divergence of 'gliders' via drift (BM-evolved traits), 3)

210   'constrained divergence' of 'gliders' via selection (OU-evolved traits, limited to positive

values), and 4) 'unconstrained divergence' of focal taxa via selection (OU-evolved traits;

212 no limits on traits). The following text describes these four types of simulations, and

Figure S1 provides a graphical summary.

214 *Convergence simulations.* For the convergence simulations, we systematically

altered 1) the number of traits (of the six total traits) that were subjected to convergent

216 selection (three through six) and 2) their optimum values (or 'targets') (Fig. S1).

Convergent traits were evolved via selection (i.e., OU-evolved) toward the same trait

218 optimum (target). The convergent traits were subjected to directional OU-selection for

their full branch lengths, which allowed most 'glider' tips (besides those with the shortest

220 branches) to arrive at the adaptive peak. Traits not subject to convergent evolution

continued to evolve by BM. Note that the OU-parameters for all simulations were the

222 same, and the 'strength' of convergence was represented by the number of traits

subject to convergence rather than the strength of selection per se. Six of six traits

224 being convergent thus represents very strong convergence, whereas three of six traits

being convergent represents weaker convergence. Further, we alter the number of

226 convergent traits because it is likely that in empirical datasets some traits are

convergent whereas other traits are not convergent (e.g., see the discussion on long

228 bone lengths versus long bone widths in Grossnickle et al. 2020).

By changing the values of trait optima ('targets') we systematically controlled the

230 morphological distance of 'gliders' from their ancestral condition, allowing us to test how

morphospace position influences the results of applied convergence measures (Fig.

232 S1). We used a series of nine trait optima positioned at successively greater distances

from the ancestral point in morphospace, starting at zero (convergence toward the

234 ancestral trait values) and successively increasing by 10 to a distance of 80 trait units

from the ancestral value. For example, in a simulation with four convergent traits and an

236   optimum of 30, the first four traits all evolved toward an optimum trait value of 30 and

the two remaining traits evolved by BM. The range of tip values in the 'base' portion of

238   the tree (BM-evolved 'non-gliders') has a radius of about 15 trait units, so the first two

optima in this iteration (zero and 10) lie within the morphospace occupied by 'non-glider'

240   taxa and the last seven lie increasingly outside the range of morphology of 'non-gliders.'

The farthest tested optima (i.e., ~60–80) result in the 'gliders' being unrealistically far

242   from 'non-gliders' in morphospace and thus unlikely to reflect empirical scenarios, but

we include them here to help infer trends in how morphospace position influences

244   convergence measures. Each simulation with all of its iterations was repeated with 15

unique 'base simulations,' and we report results for the means and standard errors of

246   these 15 replicates.

Divergence simulations. To simulate divergence via drift (i.e., BM-evolved

248   'gliders'), we simulated six traits using the *fastBM* function of the *phytools* package

(Revell 2012) for *R* (*R* Core Team 2020). Ancestral trait values were set at zero, and, to

250   mimic natural variation, the rate parameter (σ^2) was sampled from a log-normal

distribution with log-mean and standard deviation 0 and 0.75, respectively. This was

252   repeated to produce 15 replicate datasets. In contrast to all other simulations, gliders in

these datasets did not possess any OU-evolved traits.

254   For the selection-based (OU-evolved) methods for generating divergence, we

simulated divergence as selection of the individual 'glider' lineages each toward a

256   different trait optimum. We used a procedure that is as similar as possible to that used

in the convergence simulations. Between three and six traits were selected toward the

258   clade-specific trait optimum with a series of target distances ranging from 30 trait units

from the ancestral morphology (which extends the lineages past the periphery of the

260   base BM tree and thus ensures that the targets are divergent) to 100 units in steps of

10. This choice, however, means that the divergence simulations are limited to cases in

262   which the lineages are morphological outliers, whereas the drift-based divergence

simulations include non-outlying lineages. A different target was randomly selected for

264   each 'glider' clade by choosing a random trait value for each of the traits under selection

with the condition that their sum of squares equal the squared target distance (i.e., that

266   the target lies at a distance of 30, 40, etc. units from the ancestral trait values). The

selected lineages are allowed to fully reach their trait optima.

268   For our primary selection-based divergence simulations, we limited the OU-

evolved 'glider' traits to positive values. Choosing only positive trait values ensures that

270   the trait optima ('targets') are divergent yet lie within the same quadrant (or hyper-

quadrant) of multidimensional space. This constriction of adaptive peaks to one region

272   of morphospace helps to better mimic empirical datasets in which lineages exhibit some

morphological similarities but are still geometrically divergent (e.g., Grossnickle et al.

274   2020, Collar et al. 2014). Further, researchers are most likely to apply convergence

measures to lineages that share some similarities, making these simulations more

276   applicable to empirical research. Nonetheless, we also simulated 'unconstrained

divergence' for a smaller subset of evolutionary scenarios (see discussion on subset

278   analyses below) in which the 'glider' trait optimum values were not limited to positive

values. The results of convergence measures applied to these simulations are provided

280   in the Supplemental Results.

In total, we generated and analyzed 960 simulated datasets: 540 that simulated

282   trait convergence and 420 that simulated trait divergence.

284   **C-measures**

We applied the *C*-measures (Stayton 2015A) to focal lineages ('gliders') in the

286   simulated datasets. The primary measure, *C*1, is the distance between phylogenetic tips

of focal taxa (D_{tip}) divided by the maximum distance between any tips or ancestral

288   nodes of those lineages (D_{max}). The resulting proportion is subtracted from one; the *C*1

value is one for complete convergence zero for divergence (i.e., D_{max} is D_{tip}). *C*2 is the

290   difference between D_{max} and D_{tip}, and it captures the absolute magnitude of convergent

change. *C*3 and *C*4 are standardized versions of *C*2 that are calculated by dividing *C*2

292   by the phenotypic change along branches leading to the focal taxa (*C*3) or the total

amount of phenotypic change in the entire clade (*C*4). See Stayton (2015A) for full

294   descriptions of *C*1–*C*4. To calculate *C*-measure scores, we used functions in the *R*

script from Zelditch et al. (2017), which are computationally faster than the functions in

296   the *convevol R* package (Stayton 2015A, Stayton 2018). *C*1–*C*4 scores were calculated

for all simulated datasets, but due to computational limits of analyzing a large number of

298   simulated datasets, we only calculated simulation-based *p*-values for a smaller subset

of datasets used for subsequent analyses (see the following subsection).

300   *C*-measures quantify phenotypic convergence between individual phylogenetic

tips, not between clades with multiple tips (Stayton 2015A). Thus, we calculated

302   average phenotypes for taxa of focal clades. For example, one glider clade includes six

flying squirrel species, so for each of the six simulated traits we calculated mean values

304   for the six species. The averages were then used as the representative flying squirrel

lineage. Thus, *C*-measures were measured for five 'glider' lineages, each representing

306   an independent evolution of gliding. The species' traits were not averaged prior to the

other types of convergence analyses described below.

Additional measures of convergence

310   *Subset of simulated datasets.* We applied additional measures of convergence (OU

model-fitting, θ, and Wheatsheaf index) to a smaller subset of 165 simulated datasets.

312   This subset only includes datasets in which four of six traits were simulated to converge

on a specific trait optimum or diverge toward multiple optima, with the remaining two

314   traits evolved by BM (see Evolutionary simulations subsection for more details). We did

not use datasets in which all six traits are convergent because this leads to nearly

316   complete convergence on a trait optimum, and complete convergence appears to be

very rare among empirical analyses (Grossnickle et al. 2020). Nonetheless, four of six

318   traits being convergent on an optimum often results in strong convergence (i.e.,

statistically significant distance-based measures of convergence and strong fits of

320   multiple-peak OU models) among lineages, especially when trait optima are outliers in

morphospace (see Results & Discussion). For convergence simulations, we used the 15

322   simulated datasets each from the sets of simulations where trait optima were set at 0,

20, 40, 60, and 80. These represent simulations in which focal lineages evolve toward

324   the ancestral morphology (optimum = 0), evolve just beyond the outer edge of the

morphospace region of BM-evolved lineages (optimum = 20), and evolve far into

326   outlying morphospace (optima = 40, 60, and 80). For selection-based divergence

simulations (both 'constrained' and 'unconstrained'), we used the 15 simulated datasets

328   with optima of 40, 60, and 80. (Using trait optima of 0 or 20 could mistakenly simulate

convergence toward ancestral morphologies.) Thus, the subset of datasets includes 75

330   convergence simulations (15 datasets each for five trait optima) and 45 simulations

each for unconstrained and constrained divergence simulations (15 datasets each for

332   three optima). The following methods were only applied to this subset of datasets.

Evolutionary model-fitting analyses. We fit four multivariate models to all six

334   simulated traits using functions within the *mvMORPH R* package (Clavel et al. 2015).

The first three models were a single-rate multivariate BM model (mvBM1) that assumes

336   trait variance accumulates stochastically but proportionally to evolutionary time, a

single-optimum Ornstein-Uhlenbeck model (mvOU1) that modifies the BM model to

338   constrain each trait to evolve toward a single optimum, and an early burst model

(mvEB) that modifies the BM model to decrease evolutionary rate with time. Model

340   support for any of these three models would indicate a lack of strong convergence

among the taxa simulated as convergent or divergent, due to the lack of evidence for a

342   distinct adaptive peak associated with 'gliders.' In all model-fitting analyses, the mvEB

model collapsed to a mvBM model (i.e., the change-in-rate parameter was zero). Thus,

344   we did not report the mvEB results, and we did not include it when calculating Akaike

weights.

346   We then fit a multivariate OU model with two selective regimes (mvOU2) that

allowed 'gliders' and 'non-gliders' to exhibit different trait optima (θ). Support for mvOU2

348   would provide evidence of convergence by indicating that selective forces are driving

'glider' lineages to a shared adaptive peak (Fig 1B). Note that in the simulations 'non-

350   gliders' evolved via BM, and thus any support for the mvOU2 model is likely to be driven

by the 13 'glider' lineages. Relative support for each of the three models was assessed

352   through computation of small-sample corrected Akaike weights (AICcW; Akaike 1974;

Hurvich and Tsai 1989). We calculated AICcW for each of the 15 trees, and we report

354   the mean values for these trees. Prior to fitting the mvOU2 model, we mapped the

gliding regime character state onto the 'glider' branches of the phylogeny (including the

356   subtending branches below 'glider' clades) using the *paintSubTree* function in the

phytools R package (Revell 2012).

358   In addition to fitting models to multivariate data, we fit models to univariate data

(PC1 scores) using functions in the *OUwie R* package (Beaulieu et al. 2012). Although

360   fitting evolutionary models to PC scores may generate biased results (Uyeda et al.

2015, Adams and Collyer 2018), we performed these analyses because they allowed us

362   to fit multiple-regime OU models with varying evolutionary rates (σ) and/or attractions to

optima (α) between regimes, which is not a feature of the multivariate *mvMORPH*

364   models. See the Supplemental Methods for additional information.

Additional distance-based convergence measures. We applied two other

366   measures of convergence to the subset of 30 simulated datasets (using all six traits):

Wheatsheaf index, which was implemented via the *R* package *windex* (Arbuckle et al.

368   2014, Arbuckle and Minter 2015), and θ_{real}, which was implemented using the *RRphylo*

package (Castiglione et al. 2018, Castiglione et al. 2019). The Wheatsheaf index

370   measures pairwise morphological distances between putatively convergent taxa, with

distances corrected for the degree of phylogenetic relatedness of lineages. These

372   distances are compared to pairwise distances between other lineages in the sample to

determine whether putatively convergent lineages are more similar to each other than

374   expected. The θ measurement is the angle between the phenotypic vectors of putatively

convergent lineages (note that this θ is different from the θ parameter of OU models),

376   and it is based upon phylogenetic ridge regression. We report the angle obtained by all

pairwise comparisons between putatively convergent clades (θ_{real}), standardized by the

378   phylogenetic distance separating them (i.e., expected divergence under a BM model).

Significance tests compare standardized θ_{real} values of putatively convergent taxa to

380   values computed for randomly selected tip pairs.

382   **RESULTS & DISCUSSION**

***C*-measure issues**

384   Our analysis of the *C*-measure calculations reveals that the measures do not always

perform as intended (Stayton 2015A), especially when putatively convergent lineages

386   are outliers in morphospace. This critical problem can manifest in at least three ways,

which we illustrate in Figure 2. First, the more outlying the morphologies are in

388   phylomorphospace (and all else being equal), the greater the *C* scores, indicating

stronger convergence. We demonstrate this with a conceptual illustration in Figure 2A

390   (note that D_{tip} remains constant in both scenarios). This does not align with our working

definition of convergence and in Stayton (2015A); the distances between ancestral

392   nodes and the distances between descendants are unchanged between the scenarios,

and thus we could expect *C* scores to be the same for both scenarios. The pattern of

394   greater convergence in outliers is also demonstrated by results of applying *C*-measures

to evolutionary simulations (Figs. 3 and S2); taxa evolving to trait optima farther from

396 the ancestral morphology have greater $C1$–$C4$ scores. The only exception is the $C1$ set

  of results when all six simulated traits are convergent. In this case, $C1$ scores remain

398 consistently around 0.8 regardless of the position of trait optima (Fig. 3C).

   The second and third issues with the C-measures are more problematic:

400 divergent and parallel lineages can have $C1$ scores that are greater than zero,

  incorrectly indicating that the lineages are convergent (Fig. 2B, C). In Figure 2B we

402 illustrate lineages that are diverging morphologically (in univariate and multivariate

  morphospace), but they have a $C1$ score of 0.3, incorrectly suggesting that the lineages

404 have experienced substantial convergence (i.e., closing about 30% of the maximum

  distance between lineages). To further test this issue, we measured $C1$ in lineages

406 simulated to have divergent traits (Fig. 3B), and $C1$ values are consistently greater than

  zero (and statistically significant) when applied to the 'constrained divergence'

408 simulations (Fig. 3C; Table 1), incorrectly indicating strong convergence instead of

  divergence.

410   Similarly, outlying lineages evolving along parallel phylomorphospace trajectories

  from a similar ancestral condition have extremely strong $C1$ scores (Fig. 2C). This is

412 unexpected because the ancestral nodes of both lineages are the same morphological

  distance from one another as the distance between tips; this is not convergence

414 according to the definition of convergence adopted here or in Stayton 2015A (see

  Introduction; Losos 2011, Mahler et al. 2017).

416   Although the second and third issues with C-measures may be more common

  when at least one focal lineage has diverged rapidly from other focal taxa and is likely to

418 be a morphological outlier (e.g., see examples in Figures 2B and 2C), these issues are

not limited to outliers. For instance, the scenarios for focal ('maroon') lineages in

420   Figures 2B and 2C could occur in any region of morphospace. Thus, these issues have

major implications for many empirical studies (see discussion of examples below);

422   divergent or parallel lineages may often be incorrectly interpreted to be convergent, no

matter their position in morphospace.

424   The possibility of diverging and parallel lineages having $C1$ scores that

incorrectly indicate convergence (i.e., are greater than zero) stems from the D_{max}

426   measurement (as defined by Stayton 2015A and calculated in versions 1.0 through 1.3

of the *convevol R* package), which can be erroneously inflated, especially when

428   lineages are morphological outliers. D_{max} can be measured between ancestral nodes

(e.g., see the illustration in Figure 1A), between tips, or between a node and a tip (which

430   is the case in all examples in Figure 2). For converging lineages, D_{max} is expected to be

longer than D_{tip} (Stayton 2015A). For diverging lineages, in contrast, D_{max} is expected to

432   be the morphological distance between the tips, meaning that D_{max} equals D_{tip} (and $C1$

= 0). However, this is not always the case; divergent lineages can have a D_{max} length

434   that is not between tips, as illustrated in Figure 2B. Thus, D_{max} can be greater than D_{tip}

(indicating convergence) even when lineages are divergent. Although we illustrate this

436   issue using diverging phylogenetic tips (Fig. 2B), the problem could also arise if there

are internal nodes that are similarly divergent and outlying in morphospace (and

438   branching lineages from those nodes do not converge on other focal lineages); thus,

this issue is not solely due to allowing D_{max} to be measured to tips.

Other measures of convergence show biased results

442   To test whether other convergence measures also experience similar issues as those of

the *C*-measures, we applied two other 'distance-based' metrics (Wheatsheaf index

444   [Arbuckle et al. 2014, Arbuckle and Minter 2015] and θ [Castiglione et al. 2019]) and OU

model-fitting analyses to a subset of simulated datasets (Table 1).

446   *Distance-based convergence measures*. Consistent with the *C*-measures, the

$θ_{real}$ results (standardized to phylogenetic distance between clades) indicate greater

448   convergence in morphological outliers (Table 1). That is, the angle between phenotypic

vectors, $θ_{real}$, decreases when lineages evolve toward optima that are farther from the

450   ancestral morphology. This is unsurprising because a relatively farther trait optimum

results in greater trait values in the lineages simulated to be convergent, and, all other

452   variables being equal, greater trait values should result in smaller angles between

phenotypic vectors. However, unlike the *C*-measures, $θ_{real}$ does not consistently identify

454   simulated divergent lineages as convergent (Tables 1 and S3), although many

'constrained divergence' simulations (~40%) still returned significant results.

456   In contrast to the *C*-measures and standardized $θ_{real}$, the Wheatsheaf index

measures less convergence in outliers relative to non-outliers; values decrease when

458   convergent taxa are farther from the ancestral morphology in morphospace. The

Wheatsheaf index compares the distances between putatively convergent taxa to

460   distances between other tips. Our simulations did not allow all convergent lineages to

completely reach trait optima (Fig. 3A), and for the subset of datasets used for

462   Wheatsheaf index analyses, two of the six simulated traits evolved via BM. Together,

these two factors mean that simulated convergent lineages did not completely converge

464   on a morphology, and the pairwise distances between many tips of simulated

convergent lineages are farther apart from each other than are the pairwise distances

466 between other, BM-evolved lineages (see the phylomorphospace in Figure 3A, but note

that the plot is for data in which all six traits were convergent). If we allowed simulated

468 lineages to completely reach trait optima, then this trend of less convergence in outliers

(as measured by the Wheatsheaf index) might disappear. However, complete

470 convergence on morphologies seems especially rare in empirical datasets (Grossnickle

et al. 2020); thus, we believe that the Wheatsheaf index is likely to show reduced

472 measures of convergence in morphological outliers of most empirical samples, in line

with our simulation results.

474 *Evolutionary model-fitting analyses*. The simulated datasets used in model-fitting

analyses include lineages that were evolved by both BM ('non-gliders') and by a mix of

476 OU and BM processes ('gliders'; two traits BM-evolved and four traits OU-evolved),

meaning that we do not expect any of the four tested models (mvBM1, mvOU1, mvEB,

478 mvOU2) to be good fits to the data because they do not include a mix of BM and OU

processes. Nonetheless, we fit these models because our goal is to mimic how

480 researchers are likely to test for convergence if given the simulated morphological data

without prior knowledge of the underlying evolutionary processes (e.g., Friedman et al.

482 2016, Baliga and Mehta 2018, Grossnickle et al. 2020, Martinez et al. 2020, Rincon-

Sandoval et al. 2020). We have assigned the 'gliders' to one regime and the 'non-

484 gliders' to a second regime, and then use model support for multiple-regime OU models

(e.g., mvOU2 in this study) as evidence for convergence (Fig. 1B). Support for multiple-

486 regime OU models could suggest that lineages of one or both regimes have

convergently shifted toward a shared adaptive peak.

488   Our results for 'constrained divergence' simulations highlight a potential pitfall of

the assumption that model support for multiple-regime OU models is indicative of

490 convergence (Fig. 1B). Contrary to this assumption, the two-regime OU models

outperformed simpler models when fit to data in which lineages of both regimes

492 ('gliders' and 'non-gliders') are divergent (via the 'constrained divergence' simulations;

Table 2). Although the divergent focal lineages ('gliders') are partially constrained to one

494 region of morphospace in the simulations (see Methods and further discussion below),

they still show considerable divergence in phylomorphospace (Fig. 3C) rather than

496 convergent or parallel attraction toward a shared optimum (a presumptive adaptive

peak), which is an assumption of the OU process (Fig. 1B). Further, taxa representing

498 the second regime ('non-gliders') were evolved by BM, not an OU process. Thus, taxa

of neither selective regime are expected to be well-fit by by an OU model, and yet the

500 two-regime OU model is a substantially better fit to the data than the null, BM1 model

(AICcW for mvOU2 is 1.0 when 'glider' trait optima are 40, 60, and 80; Table 2). These

502 results are also supported by the univariate model-fitting results, with the two-regime

OU2VA model being the best-fitting model (Table S1). This indicates evidence of two

504 adaptive peaks, one for 'gliders' and one for 'non-gliders,' even though neither of those

groups were simulated as evolving toward an adaptive peak.

506   That the two-regime OU model is the best fit to our divergence data, despite the

expectation that none of our fitted models fit the simulated data, may simply reflect that

508 two-regime OU models are the best-fitting of bad-fitting models. Further, multiple-regime

OU models are often incorrectly favored over simpler models (Ho and Ané 2014,

510 Cooper et al. 2016), especially when sample sizes are small, and this may be the case

with our divergence datasets. The strength of an OU process can be assessed by

512 examining the phylogenetic half-lives ($\ln(2)/\alpha$) of traits (Ho and Ané 2014, Cooper et al.

2016). To examine half-lives for our datasets, we used the univariate, two-regime OU

514 models (via the *OUwie R* package) because, unlike the multivariate models (via the

mvMORPH R package), they permit the α value parameter to vary between regimes

516 (see Supplemental Methods), which then allows us to calculate the phylogenetic half-life

specifically for the 'glider' regime. For simulations with divergent trait optima of 40, the

518 fitted α value (mean of 15 trees) of the best-fitting univariate model (OU2VA; Table S1)

to PC1 scores indicates a phylogenetic half-life for the simulated 'gliders' of 46 million

520 years. Four of the five glider clades originated less than 46 million years ago. Thus, the

relatively long half-life suggests an especially poor fit of the OU2VA model to the data,

522 despite this model being a better fit than the BM1 and OU1 models according to the

AICcW comparisons.

524   Considering that empirical datasets often include complex evolutionary patterns

and small sample sizes for some regimes, researchers should be cautious both when

526 choosing models to fit to data and when interpreting results (Cooper et al. 2016).

Although not explored in this study, multiple-regime BM (BMM) models may offer

528 alternative options that complement multiple-regime OU models (e.g., Grossnickle et al.

2020, Martinez et al. 2020, Rincon-Sandoval et al. 2020). BMM models allow varying

530 phylogenetic means among regimes and can be fit using functions within some *R*

packages, including *mvMORPH* (Clavel et al. 2015). Because BMM models do not

532 model selection toward an optima, support for BMM models over OUM models may

suggest that there is limited or no convergence among lineages of interest (e.g.,

534 Grossnickle et al. 2020), and in some cases a BMM model might serve as a more

appropriate null model than BM1.

536   An additional OU model-fitting approach involves testing for convergent shifts

toward shared adaptive peaks without *a priori* regime classifications for focal lineages

538 (e.g., using the *SURFACE R* package; Ingram and Mahler 2013). We did not apply this

method in part because results are challenging to interpret across many simulated

540 datasets, especially when peak shifts are likely to be identified in taxa that evolved via

BM (Adams and Collyer 2018), and because the method may be less appropriate than

542 our method (with *a priori* regime classifications for 'gliders' and 'non-gliders') for testing

the specific hypothesis of this study. Nonetheless, this method provides a valuable

544 research tool for examining convergence, especially for analyses that are exploratory

(i.e., without hypotheses for specific lineages), and we recommend applying it to

546 empirical datasets as a supplement to other convergence measures (e.g., Grossnickle

et al. 2020, Rincon-Sandoval et al. 2020).

548   Our goal with divergence simulations was to mimic empirical samples with

lineages that might share some similarities and thus be tested for convergence. Thus, in

550 our primary divergence simulations (i.e., 'constrained divergence'), the divergent focal

lineages ('gliders') were partially constrained to one region of morphospace (e.g., all

552 divergent lineages are in negative PC2 space in Figure 3B) because we limited the

randomized optima to be positive values for the four OU-evolved divergent traits (the

554 other two traits were evolved by BM and could be negative; see Methods). This

methodological decision helps to explain the relatively strong fits of the two-regime OU

556 models to the simulated divergence datasets. Because 'glider' lineages are shifting in

similar directions (e.g., all divergent lineages are in negative PC2 space in Figure 3B),

558 the 'gliders' may be modeled as evolving toward an especially broad adaptive peak that

occupies a large region of one side of morphospace, especially because an OU process

560 does not require that independent lineages shifting toward a peak come from more

dissimilar ancestors. Figure 2B provides a conceptual illustration of this scenario; the

562 focal lineages ('maroon') are diverging but still evolved toward a broad adaptive peak,

which is broader than the adaptive peak of the ancestral ('blue') lineages. This could be

564 a similar scenario to the divergent outlier lineages in our simulated dataset (Fig. 3C).

For 'unconstrained divergence' simulations, we allowed the 'gliders' to diverge in

566 all directions in morphospace, and all convergence measures, including OU model-

fitting analyses, correctly identify the taxa as being divergent (Supplemental Results;

568 Table S3). Thus, the issues highlighted here for OU model-fitting analyses are likely

limited to scenarios in which focal taxa share some morphological similarities.

570 Our results highlight a second potential issue with using the fits of multiple-

regime OU models to measure convergence: OU model-fitting analyses may struggle to

572 identify convergence when lineages converge on a morphology that is similar to the

ancestral morphology (Table 2). This is reflected by the strong performance of mvBM1

574 (a uniform BM model) when optima are zero (AICcW = 0.991). Similarly, model-fitting

analyses may be biased toward measuring stronger convergence when lineages evolve

576 farther from the ancestral morphology, consistent with C-measures and standardized

θ_{real}. This is demonstrated by model support for mvOU2, which strengthens when

578 lineages evolve farther from the ancestral morphology (Table 2).

However, the aforementioned issue can be addressed in part by fitting more

580   appropriate multiple-regime OU models to the data, such as models that allow for

parameters to vary between regimes. This is demonstrated by our univariate results; the

582   OU2VA allows the selection and rate parameters to vary between regimes, and it is the

best-fitting model to PC1 scores at all trait optima values (Table S1). The results

584   correctly identify different underlying evolutionary processes for the two regimes, with

'gliders' showing stronger evidence of convergence via an OU process (i.e., greater

586   selection and rate parameters compared to those of the non-glider regime). Thus, for

robust analyses of convergence via model-fitting analyses, we recommend that

588   researchers include models that allow parameters to vary across regimes.

Although results of both *C*-measures and OU model-fitting analyses can

590   incorrectly suggest that divergent lineages are convergent, the reasons for this issue

are different for the two methods; they are fundamentally different in how they test for

592   convergence. Stayton (2015A, 2015B) highlighted that distance-based measures rely

on a pattern-based definition of convergence that does not assume a specific

594   mechanism is driving convergence (although see Mahler et al. 2017 for an opposing

view), whereas OU model-fitting analyses assume that a specific mechanism, selective

596   pressure (modeled as the α parameter), is driving convergence, and thus rely on a

process-based definition of convergence. A further distinction between these types of

598   convergence measures is that distance-based measures assess *morphological*

convergence of lineages (i.e., the focus is on whether lineages are evolving toward

600   each other), whereas OU model-fitting analyses test for *convergence on a morphology*

(i.e., the focus is on whether lineages are evolving toward a trait optimum or adaptive

602 peak, not toward each other). This distinction between these two types of convergence

measures is important: OU model-fitting analyses are not testing for similarities of

604 lineages but rather similarities of lineages to a morphology; thus, they are less directly

testing for convergence compared to distance-based measures, and instead are testing

606 for occupation of similar adaptive zones, which may permit greater morphological

variation than strict convergence towards a shared morphology.

608 *Summary of issues with convergence measures.* The most critical issue

uncovered by our results is that C-measures often misidentify divergent lineages as

610 being convergent (Fig. 2B, Fig. 3C, Table 1). However, all convergence measures show

some bias, especially when examining morphological outliers, albeit for different

612 underlying reasons for each method. C-measures, θ_{real}, and some OU model-fitting

analyses (those in which parameters are not allowed to vary between regimes) all result

614 in stronger measures of convergence when simulated convergent taxa evolve toward

relatively farther trait optima. In contrast, the Wheatsheaf index shows weaker

616 convergence in outliers, although the magnitude of this bias may be influenced by our

simulation methods (Table 1). Further, model support for multiple-regime OU models,

618 which is often interpreted as support for convergent shifts toward shared adaptive

peaks, should be considered with caution because in some scenarios these models

620 may be the best fits to divergent lineages (Table 2). To help address this issue, we

recommend that researchers fit a broad range of models that allow parameters to vary

622 among regimes, examine the phylogenetic half-lives measured by OU models to

evaluate model fit, and perform model-fitting analyses in conjunction with distance-

624 based convergence measures.

Measuring convergence through time via *Ct*-measures

Despite any shortcomings, *C*-measures have benefits over other convergence measures, including the ability to distinguish between convergence and conservatism (Stayton 2015A). Thus, our objective is not to discourage the use of distance-based metrics like *C*-measures but rather to identify issues and encourage the development of improved measures.

We help to address the *C*-measure issues by presenting novel distance-based convergence measures that are derived from the *C*-measures. The new measures are calculated using the same equations as those for *C*1–*C*4 (except with a change to *C*4; see below and Supplemental Methods), but we limit the candidate D_{max} measurements to distances between lineages at synchronous 'time slices' coinciding with internal phylogenetic nodes. We refer to the new measures as *Ct*-measures (or *Ct*1–*Ct*4) and D_{max} as $D_{max.t}$ because time (*t*) is incorporated when measuring morphological distances between lineages, unlike the *C*-measures. *Ct*1 scores can be interpreted in the same way as *C*1 scores were intended to be interpreted (Stayton 2015A): positive *Ct*1 scores represent a proportion of the maximum morphological distance between lineages that has been covered by convergent evolution, with a result of one representing complete convergence. Like *C*-measures, statistical significance for *Ct*-measures is based on comparison with expectations for evolution proceeding entirely on a BM model, with simulations used to generate the expectations.

By limiting the candidate $D_{max.t}$ measurements to time slices, the *Ct*-measures minimize the possibility of $D_{max.t}$ being erroneously inflated by divergent tips. This is

648   conceptually illustrated in Figures 4A and 4B, which are the same scenarios as in

Figure 2A and 2B. Whereas the $C1$ score in Figure 2B incorrectly indicates

650   convergence (i.e., $C1$ is greater than zero), the $Ct1$ score in Figure 4B correctly

indicates divergence (i.e., the value is negative; unlike the C-measures, the Ct-

652   measures allow divergence results to be negative).

Unlike the D_{max} measurement, the D_{tip} measurement has not been altered from

654   its original implementation in C-measures (Stayton 2015A) and is not limited to a

synchronous time slice, thus allowing for distances between tips to be compared even if

656   the tips vary in geologic age (e.g., comparison of an extinct taxon and an extant taxon).

However, unlike the C-measures, the Ct-measures do not allow $D_{max.t}$ to be measured

658   between tips (i.e., $D_{max.t}$ cannot equal D_{tip}). This means that divergent taxa will have

negative Ct scores, whereas C-measures (as they were initially intended) will measure

660   divergent taxa as having scores of zero (i.e., D_{max} equals D_{tip}). See the Supplemental

Methods for more information on the Ct-measures.

662   In addition to developing the Ct-measures, we added several new features to the

convevol R package (Stayton 2018). This includes allowing Ct-measures to compare

664   clades that contain multiple lineages, whereas the C-measures are limited to

comparisons of individual lineages (see Methods; Stayton 2015A). Clade comparisons

666   are enabled by 1) excluding pairwise comparisons between within-clade lineages (e.g.,

two flying squirrel species) and 2) weighting of Ct scores and p-values based on the

668   number of pairwise comparisons between focal clades (see Supplemental Methods).

Further, Ct-measures can be measured using single traits (C-measures only permitted

670   measures of multivariate distances, although they were adapted for univariate analyses

in some studies; Spear and Williams 2020, Law 2022), and we updated the $C4$ (now

672   $Ct4$) calculation to better match the original description of that measure. See the

Supplemental Methods for additional information on these updates. We used an R script

674   written by Jonathan S. Mitchell and published in Zelditch et al. (2017) as a foundation

for the updated functions. The run times for the revised R functions (*convrat.t* and

676   *convratsig.t*) are approximately ten times faster than the original functions of Stayton

(2015A) when using our simulated datasets. We did not revise $C5$, which is a

678   frequency-based convergence measure that tallies the number of times lineages enter a

region of morphospace (Stayton 2015A), because it is not influenced by the issues

680   highlighted here.

We have also developed a new R function, *plot.C*, that produces a plot of the

682   distances between lineages through time. This type of plot is conceptually illustrated in

Figure 4, and Figure 5B includes a phylogeny and plot produced by the *plot.C* function

684   for an example dataset from our convergence simulations, showing pairwise distances

between three 'glider' lineages. An additional example output of *plot.C* is provided in

686   Figure S6 for the 'twig' ecomorphotype lineages of anoles, although we separated

convergent and non-convergent pairwise comparisons for ease of interpretation. These

688   plots allow researchers to visualize when the measured $D_{max.t}$ occurred during the

evolutionary history of the lineages, and they may be useful for applications beyond

690   studies of convergence. The candidate $D_{max.t}$ measurements at time slices are provided

as an output of the *convrat.t* function.

692   We tested the performance of Ct-measures by applying them to the simulated

datasets using the same methodology as that for C-measures. Unlike the C-measures

694   (Fig. 3C), the *Ct*-measures do not consistently misidentify divergent lineages as being

convergent (Figs. 5A and S3); most of the simulated divergence datasets (via both

696   drift/BM and selection/OU) exhibit *Ct*1 scores that are negative, correctly indicating

divergence. Like *C*-measures, the *Ct*-measures do measure more convergence in

698   morphological outliers (Figs. 4A and 5A), but this pattern appears to be less pronounced

than with *C*-measures (Figs. 2A and 3C). Although in some cases the *Ct*1 score is

700   greater than zero (indicating convergence; Fig. 5A), the *Ct*1 scores are not statistically

significant when applied to divergence datasets (Table 1), which is in contrast to the

702   strongly significant *C*1 scores for divergence simulations. Further, the greater-than-zero

*Ct*1 results could be due in part to convergence occasionally occurring by chance in our

704   simulated-divergence datasets (e.g., BM-evolved 'glider' lineages evolving toward each

other by chance). This indicates the importance of researchers considering the *p*-values

706   associated with *Ct*-measures when evaluating convergence in their samples.

        Different origination ages of convergent clades might also inflate *Ct* scores in

708   morphological outliers, especially if the oldest lineage evolves rapidly into outlying

morphospace and away from other putatively convergent lineages. This is illustrated in

710   Figure S4 and discussed in the Supplemental Results. To help address this issue, we

added an optional feature to the *convrat.t* function that limits candidate $D_{\text{max.t}}$

712   measurements to the time prior to the evolution of the focal lineages (e.g., prior to the

evolution of the earliest glider clade). We recommend that researchers use this option

714   as a supplement to regular *Ct*-measures when their clades of interest have very

different origination ages (see Supplemental Results).

Empirical examples – *C*1 vs *Ct*1

718   The *C*-measure issues highlighted here are relevant to the many studies that have

employed (or will employ) the *C*-measures. In many cases, erroneous *C*-measure

720   results may have led researchers to either infer convergence in lineages that are

divergent or infer inflated degrees of convergence. For instance, Grossnickle et al.

722   (2020) tested for convergence among gliding mammal lineages using limb

measurements, and they observed conflicting results. Statistically significant *C*-measure

724   scores indicated strong convergence, but other analyses (evolutionary model-fitting,

morphological disparity, phylomorphospace trajectories) suggested parallel evolutionary

726   patterns. The authors concluded that the conflicting lines of evidence indicated weak,

incomplete convergence. But considering the issues highlighted here, the strong *C*-

728   measure results in Grossnickle et al. (2020) are probably misleading. For instance, the

C-measure scores were likely inflated due to the outlying morphologies of some gliders

730   (e.g., dermopterans), meaning that the gliders are probably less convergent than the

authors concluded. We re-analyzed the data from Grossnickle et al. (2020) using the *Ct*-

732   measures, and in contrast to strong *C*-measure scores, we found that all glider

comparisons have negative *Ct*1 scores, indicating divergence instead of convergence.

734   In some instances, the *Ct*1 scores are only slightly negative and have significant *p*-

values (e.g., *Ct*1 = -0.01 and $p < 0.01$ for the comparison of scaly-tailed squirrels and

736   flying squirrels), which is congruent with the other lines of evidence examined in

Grossnickle et al. (2020) that suggested parallel evolutionary changes rather than

738   convergence for most glider groups.

Huie et al. (2021) and Stayton (2015A; using data from Mahler et al. 2013)

740   independently analyzed *Anolis* lizard morphologies using distinct datasets, and both

found that the ecomorphotypes with the greatest $C1$ scores are those in the outermost

742   regions of morphospace ('crown-giant,' 'grass-bush,' and 'twig'; see Figure 3 of Huie et

al. 2021). The $C1$ values for these ecomorphotypes ranged from 0.31 to 0.43 in these

744   studies, whereas other, non-outlying ecomorphotypes had $C1$ values ranging from 0.09

to 0.25 (Stayton 2015A, Huie et al. 2021). The relatively large $C1$ scores of outlying

746   ecomorphotypes, in addition to the positive $C1$ scores for all pairwise comparisons, may

be due in part to the biases in the C-measures. We evaluated this possibility by applying

748   *Ct*-measures to one of the outlying ecomorphotypes ('twig') from the anole dataset of

Mahler et al. (2013; ten standardized measurements of body dimensions, e.g., tail

750   length). We found that, although the overall $Ct1$ score was statistically significant, it was

near zero (Table S2), in contrast to the $C1$ score being 0.36 (Stayton 2015A).

752   Interestingly, there was considerable disparity in the pairwise *Ct* results for the five twig

lineages, with $Ct1$ scores ranging from 0.346 (*A. paternus* vs. *A. valencienni*) to -0.763

754   (*A. occultus* vs. *A. paternus*) and six of ten pairwise comparisons not significant. (See

Figure S6 and Table S2 for full results and plotted pairwise distances through time.)

756   Thus, these results highlight not only the issues with the C-measures, namely the

inflation of C scores among outliers, but also the importance of considering pairwise

758   comparisons when evaluating convergence among multiple focal lineages.

760   **_Ct_-measures – recommendations and limitations**

In contrast to *C*-measures, the *Ct*-measures are influenced by the timing of evolutionary

762 change because they limit candidate $D_{max.t}$ measurements to specific time slices. This

feature should be considered by researchers who apply the *Ct*-measures because it

764 may alter expectations about the degree of measured convergence. For instance, if

different focal lineages evolve toward a specific morphology (or adaptive peak) at

766 different points in time, then the $D_{max.t}$ measurement may not measure the

morphologically farthest distances between the lineages, possibly resulting in lower-

768 than-expected *Ct* scores. Conversely, and as noted above, if the putatively convergent

taxa evolve toward outlying regions of morphospace, then the asynchronous origins of

770 the clades could inflate the *Ct*-measures (Supplemental Results; Fig. S4). To help

mitigate this issue, we recommend that researchers generate and assess

772 phylomorphospace and distances-between-lineages-through-time plots, and compare

default *Ct* results to those generated when using the alternative option of the *convrat.t*

774 function that limits candidate $D_{max.t}$ measurements to the period in which lineages of

interest overlap in time (see Supplemental Methods).

776   The *Ct*-measures can be applied to taxa of varying geologic ages (assuming

there is an internal node for a $D_{max.t}$ measurement), but they may perform poorly when

778 the tips of focal taxa are very different in geologic age because candidate $D_{max.t}$

measurements are restricted to the period in which the evolutionary histories of the

780 lineages overlap in time. For instance, the evolutionary histories of ichthyosaurs and

dolphins overlap from their most recent common ancestor (MRCA; early amniotes) to

782 the ichthyosaur tips, providing considerable time (more than 200 million years) for

candidate $D_{max.t}$ measurements. However, there are no candidate $D_{max.t}$ measurements

784   between the extinction of ichthyosaurs and extant dolphins, and if this is the period in

which the ancestral dolphin lineages shows the greatest divergence from ichthyosaurs,

786   then $D_{max.t}$ will not capture the maximum divergence of the lineages. That is, much of

the evolutionary history of dolphins (and placental mammals more broadly) would be

788   excluded by Ct-measures, likely resulting in smaller-than-expected Ct scores. (Note,

however, that D_{tip} ignores time and would measure the morphological distance between

790   ichthyosaur and dolphin tips.) In these types of cases, alternative methods for

measuring convergence (e.g., OU model-fitting analyses) may be more appropriate.

792   The restriction of candidate $D_{max.t}$ measurements to coincide with internal nodes

exacerbates an issue inherent to many phylogenetic comparative methods: the reliance

794   on inferred ancestral states. $D_{max.t}$ is the critical value that enables the Ct-measures to

diagnose convergence, and it is drawn entirely from ancestral state data, which are

796   estimated from tip values assuming a BM model of evolution. The consequence is that

ancestral reconstructions are likely to reflect average morphologies of the sampled taxa,

798   decreasing the chance of measuring convergence via the Ct-measures because $D_{max.t}$

estimates may be artificially shorter than the 'real' $D_{max.t}$ values. For instance, despite

800   simulating extremely strong convergence on a trait optimum for all six traits, the greatest

$Ct1$ scores are around 0.7, indicating that about 70% of $D_{max.t}$ has been closed by

802   convergent evolution. Based on the simulation methods, we expected $Ct1$ values to be

closer to 1.0. We tested this issue by applying $Ct1$ measures to simulations in which we

804   used the generated ('true') ancestral traits. For 'glider' trait optima of 50, the $Ct1$ score is

0.67 when using estimated node reconstructions and it increases to 0.78 when using

806   the generated ancestral values (Table S4). This helps to confirm that the convergence

signal of *Ct*-measures might often be diluted due to the assumption of a BM model of

808   evolution.

      The aforementioned issue is likely to be exacerbated under conditions where

810   there are relatively few intervening nodes between putatively convergent lineages (i.e.,

there is a small sample of candidate $D_{max.t}$ measurements), when those putatively

812   convergent lineages are subtended by long branches (i.e., distances from which to draw

$D_{max.t}$ are biased toward deeper nodes), and when only contemporary tips are included

814   (i.e., there is a lack of fossil data informing reconstructions at internal nodes). Therefore,

the *Ct*-measures may be most appropriate for well-sampled study systems that include

816   a substantial number of internal nodes and relatively few long branches, and

researchers should include fossil taxa whenever possible to improve ancestral

818   reconstructions at internal nodes.

      The number of phenotypic traits used to assess convergence is likely of

820   increased importance when using *Ct*-measures. In multivariate datasets, some traits

may be convergent and others non-convergent (i.e., divergent, parallel, or

822   conservative). While including a greater number of non-convergent traits in analyses is

expected to decrease the overall convergence signal of any convergence measure, it

824   may also exacerbate the *Ct*-related issues raised in this section. In general, adding

traits increases the measured distances between tips and internal nodes. However,

826   ancestral inference via BM tends to average variation at internal nodes; thus, D_{tip}

typically increases at a higher rate than $D_{max.t}$ for each non-convergent trait that is

828   added to a dataset. This pattern is illustrated in Figure S5, highlighting that increasing

the number of BM-evolved traits (which are expected to be mostly non-convergent) in

830   simulations results in relatively greater increases of D_{tip} scores compared to $D_{max.t}$

scores. Therefore, an increased number of traits in analyses (with all else equal) could

832   result in a relative decrease in Ct scores compared to datasets with fewer traits, unless

the additional traits are strongly convergent. We recommend that researchers carefully

834   choose traits (or landmarks if using geometric morphometrics) based on the specific

hypothesis being tested, and analyze individual traits or subsets of traits whenever

836   feasible to tease apart unique patterns among traits.

Many of the aforementioned factors that influence Ct-measures, especially the

838   assumption of a BM mode of evolution in ancestral lineages, could contribute to the Ct-

measures being conservative in their measures of convergence. This should be

840   considered by researchers who use the Ct-measures.

As highlighted throughout this study, convergence measures can be biased

842   based on the location of taxa in morphospace, with outliers tending to show greater

convergence when using the C-measures, Ct-measures (although to a lesser degree

844   than C-measures), θ, and some OU-model-fitting analyses (when model parameters are

limited to being constant across regimes), and less convergence when using the

846   Wheatsheaf index (Figs. 2A and 4A, Tables 1 and 2). We consider the greater observed

convergence in morphological outliers via most methods to be an issue (Fig. 2A)

848   because it is inconsistent with our working definition of convergence, which has the

precision that allows for quantitative comparisons. However, under looser definitions of

850   convergence this pattern could be interpreted as a reflection of the amount of

evolutionary change of the convergent lineages. Outliers have undergone greater

852   morphological change, evolving farther from the ancestral morphology, and thus their

tendency to appear 'convergent' could be an emergent property of the evolution of

854   outlying morphologies (e.g., see Collar et al. [2014] for a discussion of 'imperfect

convergence' in divergent, outlying lineages). This, however, is not what the measures

856   of convergence have been defined to test, and we emphasize that researchers should

ensure that their chosen convergence metrics and interpretations of results align with

858   their *a priori* definition of convergence. For instance, researchers should think critically

about whether they are trying to measure convergence toward a shared morphology or

860   a shared trajectory toward a broad adaptive zone. In any case, researchers should

expect to observe relatively stronger evidence of convergence in outliers when using

862   most convergence measures.

864   **Summary**

The *C*-measures are a popular means of identifying and quantifying phenotypic

866   convergence, in part because they can differentiate between convergence and

conservatism. However, we highlight a critical issue with *C*-measures: they can

868   misidentify divergent lineages as convergent (Figs. 2 and 3, Table 1). To help address

this issue, we developed improved convergence measures (*Ct*-measures) that quantify

870   distances between lineages at time slices at internal phylogenetic nodes, minimizing the

possibility of divergent taxa being mistakenly measured as convergent. We have also

872   developed new features (available in the *convevol R* package), such as a function to

produce distances-between-lineages-through-time plots and the ability to compare

874   clades that include multiple taxa. Although *Ct*-measures improve on *C*-measures,

researchers should recognize their limitations. For instance, *Ct*-measures may be

876   unreliable if convergent evolutionary change is asynchronous between lineages of

interest (e.g., fossils of very different geologic ages), especially when lineages are

878   morphological outliers. More broadly, we find that multiple methods (including *Ct*-

measures) are biased by the location of taxa in morphospace, with most methods

880   measuring greater convergence in morphological outliers. OU model-fitting analyses are

a valuable tool for investigating convergence, but we urge caution when applying and

882   interpreting the results of the analyses. Model support for multiple-regime OU models is

not always indicative of convergent shifts toward shared adaptive peaks, especially

884   when all of the fitted models are poor fits to the data (Table 2). Because all available

methods for identifying and measuring phenotypic convergence are imperfect, we

886   recommend that researchers use multiple convergence methods. Researchers should

also recognize the benefits and drawbacks of their chosen methods when interpreting

888   results, and they should put greater focus on methods that are most appropriate for the

data being analyzed and the hypotheses being tested.

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FIGURES

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1058   **Figure 1**. Conceptual illustrations of two methods for assessing phenotypic convergence of

focal lineages (maroon): *A*, *C*1 of Stayton (2015A) and, *B*, multiple-regime Ornstein-Uhlenbeck

1060   (OU) model-fitting. The *C*1 score of 0.7 indicates that lineages have evolved toward each other

to cover 70% of the maximum distance (D_{max}) between their lineages. D_{max} can be measured at

1062   any point along the evolutionary histories, including the dashed branches in *A*, and D_{tip} is the

morphological distance between phylogenetic tips. Although time is a variable in the univariate

1064   illustration in *A*, the *C*-measures do not incorporate time. *B*, OU models include fitting a trait

optimum parameter that is often interpreted as the location of an adaptive peak and an

1066   'attraction' parameter that is commonly interpreted as the strength of selection. Abbreviation:

MRCA, most recent common ancestor.

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1072 **Figure 2**. Conceptual illustrations of C-measure issues. $C1$ scores are greater than zero for the
divergent (B) and parallel (C) focal lineages ('maroon'), incorrectly indicating that the lineages

1074 are convergent. See the main text and Figure 1 for more information on $C1$, D_{max}, and D_{tip}. The
C-measure issues highlighted here also apply to evolutionary model-fitting analyses. The

1076 distribution curves in univariate illustrations could represent adaptive peaks, and OU model-
fitting analyses are more likely to identify unique adaptive peaks when a peak is farther from the

1078 ancestral morphology (Table 1).

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Figure 3. PCA phylomorphospaces for example datasets that simulate convergence (*A*) and divergence (*B*) of all six traits of five focal clades ('gliders'). Traits were selected toward optima

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via an OU process, with all traits of convergent taxa selected toward a value of 20 and traits of divergent taxa selected toward varying values that result in evolutionary change equal to that of

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convergent taxa (see Methods). (*C*) *C*1 scores for simulated convergent lineages (solid lines) and divergent lineages (dashed lines), using datasets in which focal taxa have varying numbers

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of convergent/divergent traits (of six total) and trait optima positions. Any traits and lineages not selected to be convergent/divergent were evolved by Brownian motion (BM). Focal taxa evolved

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toward trait optima after they originated. Divergent trait optima are randomized, but they are limited to being positive numbers (whereas BM-evolved traits can be positive or negative),

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resulting in divergent lineages evolving in the same direction along PC1 (e.g., *B*) but otherwise being divergent (unless convergence occurs by chance). *C*1 values above zero indicate

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convergence, and a value of one would reflect complete convergence (i.e., phenotypically identical tips). We did not simulate divergence to trait optima of 0, 10, and 20 because the

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simulations might mistakenly generate convergent lineages near the middle of morphospace. As a second means of simulating divergence, we allowed the focal lineages to evolve via BM, and

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these results are displayed as a box-and-whisker plot in *C*. *C*1 results are means and standard

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errors of 15 simulated datasets.

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Figure 4. Conceptual illustration of our new $Ct1$ convergence measure, which is calculated like
1106 $C1$ of Stayton (2015A) but candidate $D_{max.t}$ measurements are limited to 'time slices' at internal
phylogenetic nodes. The plots on the right show the three candidate $D_{max.t}$ measurements and
1108   the distance between lineages at the tips (D_{tip}). The scenarios in A and B are the same as those
in Figures 2A and 2B, respectively. In contrast to $C1$, $Ct1$ correctly identifies divergence
1110   (negative score) in the scenario in B. Although the $Ct1$ score is greater when lineages are
outliers (A), note that the $Ct1$ scores (0.3 for non-outliers and 0.4 for outliers) are more similar to
1112   each than are the $C1$ scores in the same scenarios (0.4 and 0.7; Fig. 2A), indicating that Ct-
measures are less influenced by positions of taxa in morphospace compared to C-measures.

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Figure 5. (*A*) *Ct*1 scores for simulated convergent lineages (top results in plot) and divergent

1122 lineages (bottom) under varying evolutionary scenarios. See the Methods and Figure 3 caption

for more information. Although in some cases the divergence *Ct*1 results are greater than zero

1124 (indicating convergence), these results were not statistically significant when we calculated

simulation-based *p*-values for a subset of datasets (Table 1). *C*1 results are means and

1126 standard errors of 15 simulated datasets. (*B*) An example output from the *plot.C R* function that

shows the pairwise distances between lineages with time. Note that although only three 'glider'

1128 lineages are highlighted in the plot, five lineages were used for *Ct1* measurements.

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1142 **TABLES**

1144 **Table 1.** Tests of convergence among focal lineages ('gliders') of the simulated datasets using distance-based measures. Results are means of the 15 simulated datasets for each optimum. For θ results, we report θ_{real} standardized to phylogenetic distance between clades. Note that relatively smaller θ_{real} values (i.e., smaller angles between phenotypic vectors) suggest greater convergence, whereas relatively larger Wheatsheaf index, $C1$, and $Ct1$ values indicate greater convergence. Statistical significance (*, $p \leq 0.05$; **, $p \leq 0.01$; ***, $p \leq 0.001$) for $C1$ and $Ct1$ is based on comparisons to results of 100 simulations via a BM model, and for the Wheatsheaf index it is based on bootstrapping with 1000 replicates. Significance of standardized θ_{real} values is based on bootstrapping with 1000 replicates for each pairwise comparison between the five 'glider' clades (except the monospecific clade). In all cases, the reported significance is based on means of 15 analyses for a given trait optimum. The 'constrained divergence' simulations limited the simulated traits of 'gliders' to be positive values, thus constraining them to one region of morphospace (see Methods).

Simulations	Convergence measure	Trait optimum				
		0	20	40	60	80
Convergence	θ (*RRphylo*)	0.393	0.126*	0.071**	0.044**	0.040**
	Wheatsheaf index	1.976***	1.715***	1.314	0.905	0.626
	$C1$	0.350*	0.526***	0.685***	0.751***	0.769***
	$Ct1$	0.176*	0.233**	0.367***	0.497***	0.483***
Divergence	θ (*RRphylo*)	–	–	0.220	0.242	0.229
('constrained')	Wheatsheaf index	–	–	0.826	0.581	0.434
	$C1$	–	–	0.363**	0.325**	0.310**
	$Ct1$	–	–	0.035	0.011	-0.003

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1164   **Table 2.** Tests of convergence among lineages of the simulated datasets using evolutionary model-fitting analyses. Model-fitting results for each trait optimum are the mean AICcWs of
1166   15 simulated datasets. Model support for the two-regime model (mvOU2) represents support for convergence because this model reflects evolution of focal lineages toward a shared
1168   adaptive peak. The 'constrained divergence' simulations limited the simulated traits of focal taxa ('gliders') to be positive values, thus constraining them to one region of morphospace
1170   (see Methods). See the Supplemental Results for 'unconstrained divergence' results. Abbreviations: AICcW, small-sample corrected Akaike weights; mvBM, multivariate
1172   Brownian motion model; mvOU, multivariate Ornstein-Uhlenbeck model.

Simulations	Model	Trait optimum of focal taxa				
		0	20	40	60	80
Convergence	mvBM1	1.000	0.000	0.000	0.000	0.000
	mvOU1	0.000	0.000	0.000	0.000	0.000
	mvOU2	0.000	1.000	1.000	1.000	1.000
Divergence	mvBM1	–	–	0.000	0.000	0.000
('constrained')	mvOU1	–	–	0.000	0.000	0.000
	mvOU2	–	–	1.000	1.000	1.000

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SUPPORTING INFORMATION

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A cautionary note on using quantitative measures of phenotypic convergence

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1202   Roston, Spencer K. Pevsner, C. Tristan Stayton, P. David Polly, Chris J. Law

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SUPPLEMENTAL METHODS

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Simulations

1208   We produced a graphical summary of our simulations to help clarify the various types and

iterations of simulations used in this study (Fig. S1). The four types of simulations include 1)

1210   convergence of focal taxa via selection (OU-evolved traits), 2) divergence of focal taxa via drift

(BM-evolved traits), 3) 'constrained' divergence of focal taxa via selection (OU-evolved traits,

1212   limited to positive values), and 4) 'unconstrained' divergence of focal taxa via selection (OU-

evolved traits; no limits on traits). Each set of simulations used six traits per lineage, but for the

1214   convergence and 'constrained divergence' simulations the number of traits simulated to be

convergent (or divergent) for focal taxa ('gliders') was systematically altered between three and

1216   six. Non-convergent traits were evolved via Brownian motion (BM). Varying the number of

convergent traits helps to toggle the strength of convergence, with simulations of three

1218   convergent traits representing relatively weak convergence. Further, systematically altering the

trait optimum values allows us to examine the performance of convergence measures when

1220   focal taxa are evolved to different distances from ancestral morphologies (i.e., varying positions

in morphospace). See the Methods for more information on each of these types of simulations.

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Figure S1. A graphical summary of the simulated datasets used in this study. See the

1226 Methods for full descriptions. Abbreviations: BM, Brownian motion; OU, Ornstein-

Uhlenbeck.

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1230 **Univariate model-fitting analyses**

One limitation of the *mvMORPH* multivariate models, which are used for our primary model-

1232 fitting analyses, is that they do not permit the evolutionary rate (σ) or strength of attraction to

optima (α) to vary between the two selective regimes ('gliders' and 'non-gliders'). This likely

1234 results in poor model performance because the datasets were simulated such that 'gliders' and

'non-gliders' should have different rates and attraction strengths. For example, the 'non-gliders'

1236 are evolved by BM, and thus they are not expected to exhibit attraction to a trait optimum,

whereas the convergent 'glider' lineages are expected to exhibit strong attraction due to being

1238 simulated by an OU process. Further, the phylogenetic half-life (ln(2)/α) of the 'glider' regime

cannot be calculated independent of the 'non-glider' regime if the α parameter is uniform across both regimes, which is the case with the multivariate models.

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Thus, we also fit seven univariate evolutionary models to the subset of simulated datasets, including several multiple-regime OU models that permit σ and α to vary between regimes. Using functions in the *OUwie R* package (Beaulieu et al. 2012), we fit these models to the first principal component (PC1) scores of a principal components analysis of the six simulated traits. The univariate models include uniform (or single-regime) BM and OU models, as well as a suite of multiple-regime OU models (i.e., 'OUM' models of Beaulieu et al. 2012). The OU2 model keeps α and σ constant for both regimes, the OU2A model allows α (but not σ) to vary between regimes, the OU2V model allows σ^2 (but not α) to vary between regimes, and the OU2VA model allows both σ and α to vary between regimes. As with the multivariate analyses, all models were fitted across 10 'simmaps' for each of the 30 datasets and relative support for models was measured using AICcW.

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We recognize that fitting models to PC scores can lead to biased results (Uyeda et al. 2015, Adams and Collyer 2018), and thus our univariate results should be considered with caution. However, we feel that using PC1 scores here is justified for two reasons. First, the alternative option is to fit models to each of the six simulated traits individually, but four of the traits are evolved via a strong OU process and two traits are evolved via BM (in our subset of datasets used in model-fitting analyses; see Methods), and thus the model-fitting results are expected to vary considerably between those two types of traits. PC1 provides a single value for which results can be more easily interpreted compared to results for the six traits. Second, our conclusions concerning the use of model-fitting analyses for testing for convergence are based entirely on the multivariate model-fitting analyses (see Results & Discussion), and thus the results of the univariate model-fitting analyses (which are congruent with the multivariate results; Tables 2 and S1) do not influence the broad conclusions of this study. The univariate model-fitting analyses are simply a supplemental analysis that provide a fitted α value and phylogenetic half-life for the 'glider' regime.

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Ct-measures

1268   We used the *R* script from Zelditch et al. (2017) as a foundation for the updated functions for

calculating *Ct*1–*Ct*4 and simulation-based *p*-values because they are computationally faster

1270   than the original *R* functions in the *convevol R* package (Stayton 2015, Stayton 2018). Note that

the relevant *R* functions are titled *calcConv* (*C* calculations) and *convSig* (significance testing) in

1272   the *R* code of Zelditch et al. (2017), *convrat* and *convratsig* in the original *convevol R* package,

and *convrat.t* and *convratsig.t* for our updated measures.

1274 $D_{max.t}$ *measurement*. The primary change made by the *Ct*-measures in comparison to

Stayton's (2015) original *C*-measures is the way in which D_{max} is defined. *Ct*-measures were

1276   designed to ensure D_{max} (now referred to as $D_{max.t}$) was obtained from comparisons of

synchronous time points along the evolutionary paths leading to the putatively convergent taxa

1278   of interest. In this way it prevents the inflation of $D_{max.t}$ that resulted from comparison of

asynchronous nodes (e.g., tips and internal nodes) which often occurred when using the

1280   original metrics on lineages with outlying morphologies (Figs. 3C and 4). Several modifications

to the source *R* code were made to facilitate this change. Candidate $D_{max.t}$ measurements for

1282   putatively convergent lineages are now measured at each internal node along the branch paths

from the most recent common ancestor (MRCA) of the lineages (e.g., see Figures 4 and 5B). At

1284   each of these points we extracted the phenotypic distance between lineages as the euclidean

distance between the ancestral reconstruction at the focal node and the coincident

1286   reconstruction along the branch path of the other lineage. Where this corresponds to a point

along a branch (which is most cases) the ancestral state is estimated using formula [2] from

1288   Felsenstein (1985), which allows ancestral states to be interpolated at any point along a given

branch from reconstructions at the branch's ancestral and descendant nodes. The code for this

1290   was largely repurposed from the *contMap* function of the *phytools R* package (Revell 2012). If

no contemporaneous point exists on the opposite path for a given internal node (e.g., when

1292   comparing extinct and extant taxa), then a measurement is not taken at that node. All distances

measured between paths are stored for each pair of user defined tips. $D_{max.t}$ is the maximum of

1294   these distance values, but it is restricted to predate either focal tip (i.e., $D_{max.t}$ cannot equal

D_{tip}).

1296   Restriction of $D_{max.t}$ to predate the focal tips means the minimum $Ct1$ value is no longer

set to zero as in the original $C1$-measure. This allows for some degree of divergence to be

1298   captured (i.e., relatively more negative $Ct1$ values may represent greater divergence). However,

users are cautioned from using this to test the magnitude of divergence between clades. This is

1300   because in divergent clades $D_{max.t}$ will almost always be the last time point before the oldest

focal tip. The method will thus reflect only a small portion of the period when lineages were

1302   undergoing divergent evolution. Degree of divergence will then be a function of both

phenotypic rates of evolution and of subtending branch length. The latter will in many practical

1304   situations be a function of sampling, with long subtending branches due to poor sampling likely

to inflate divergence measures substantially since they will provide the best scenario for a large

1306   time difference between D_{max} and D_{tip} (and thus capture the greatest proportion of divergent

evolution).

1308   The changes to D_{max} were the most consequential of those made to modify the original

C-measures. However, a number of other new options were also included. These are briefly

1310   described below. Full documentation of these options will be available as part of the next

update to the *convevol R* package (Stayton, 2018).

1312   *User-defined groups*. The first new option is for users to provide grouping assignments

to the tips being tested, thus allowing comparisons of clades with multiple lineages, whereas

1314   the original C-measures are limited to comparisons of individual lineages. This option removes

pairwise comparison between tips within the same group (e.g., two flying squirrels would not

1316   be compared if all flying squirrels are defined as one group) and returns results for each unique

comparison between groups in addition to overall results. This option is useful if it is

1318   hypothesized that two (or more) clades converged, and relieves the user from needing to

average tip values of a clade or manually define all of the desired comparisons. When using this

1320   option, the overall (for all pairwise comparisons) and comparison-specific Ct and p values are

returned. Overall results are provided as both raw values (means of all pairwise comparisons,

1322   excluding within-group comparisons) and weighted values. The latter allows each inter-group

comparison to impact the overall average equally, so that larger within group sample sizes

1324   don't skew overall results. For instance, if there are three putatively convergent groups (Group

A, Group B, and Group C), and Groups A and B both include a single lineage and Group C

1326 includes 10 lineages, then there would be 21 total pairwise comparisons among groups (one for

A-B, 10 for A-C, and 10 for B-C). Although constituting one third of the unique inter-group

1328 comparisons, Ct measurements taken from comparison of Groups A and B constitute less than

5% of those used to compute overall (average) Ct values. Thus, Groups A and B have a relatively

1330 smaller impact than Group C on the overall Ct scores and p-values. The weighted output scales

the Ct results (and associated p-values) so that each unique inter-group comparison contributes

1332 equally to the overall results, whereas the raw overall result simply reports the mean value for

all 21 pairwise comparisons. Both weighted and unweighted values are reported in the default

1334 output printed by the updated $convratsig.t$ function, but we recommend the weighted result be

used by default when comparing groups. Nevertheless, the raw result may be preferable in

1336 cases in which researchers believe that the more heavily sampled group(s) should have a larger

impact on overall results.

1338   Note that it is possible to define groups even when those consist of a single tip. While

doing so will not change which pairwise comparisons the model considers, it will provide the

1340 user with unique Ct scores and p-values for each comparison. This can be especially useful

when the degree of convergence varies across the lineages of interest (e.g., see the pairwise

1342 results for anole species in Figure S6 and Table S2).

Conservative $D_{max.t}$ option. When providing user-defined groups, a conservative $D_{max.t}$

1344 option is available that limits candidate $D_{max.t}$ measurements to a time point predating the

origination of both focal groups (i.e., the nodes of the MRCAs of each group). This is to prevent

1346 $D_{max.t}$ being skewed by an early transition of one lineage toward a shared adaptive optimum

that is outlying in morphospace, which can result in inflated Ct scores, especially when the

1348 origins of the clades are very different in age. This issue is discussed in the Supplemental

Results and illustrated in Figure S4. Note that this option is only meaningful when user defined

1350 groups are provided. When one of those groups consist of a single lineage the node

immediately ancestral to the tip is used. Using this method, long branches can substantially

1352 alter inferred $D_{max.t}$ values. We have provided the option to print relevant information about

the restrictions put on $D_{max.t}$ when using this method (by setting VERBOSE = TRUE in $convrat.t$).

1354   We strongly suggest that users investigate the impact of using the conservative $D_{max.t}$ option

before committing to significance tests.

1356   *Updated Ct4 computation.* In addition to changes to $D_{max.t}$, we also altered the way in

which the *C*4-measure is computed. The new version (called *Ct*4) redefines $L_{tot.clade}$, which is the

1358   value used to standardize the *C*2 value (D_{max} subtracted by D_{tip}) to obtain *C*4. $L_{tot.clade}$ is

described by Stayton (2015) as reflecting the total amount of morphological evolution which

1360   occurs in the clade originating with the MRCA of two putatively convergent tips. In the original

C-measures, $L_{tot.clade}$ values were obtained as a sum of the phenotypic distances from all

1362   pairwise comparisons between nodes in the clade, but this does not fully account for

phylogenetic structure and is heavily influenced by sampling intensity. We have updated this to

1364   now be the sum of the phenotypic distances accumulated along each branch in the clade of

interest. This change brings *C*4 closer to the original description of the metric.

1366   *Measuring convergence of single traits.* By default, the original *C*-measures do not

support investigation of convergence in a single trait (although see Spear and Williams, 2020;

1368   Law, 2022). To circumvent this limitation we have added code to the *convrat.t* function which

appends an invariant trait (with value zero) to datasets consisting of a single trait. This

1370   approach was taken due to ease of integration with existing code, and although crude will

provide the same phenotypic distances as would be obtained from the single trait.

1372   *Model output.* Additional changes were made to increase the amount of information

returned to the user and facilitate plotting of results. This includes the addition of the novel

1374   *plot.C* function, which is described in the 'Measuring convergence through time via Ct-

measures' section of the main text (with example output in Figure 5B).

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SUPPLEMENTAL RESULTS

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Univariate model-fitting analyses

1380   For univariate models fit to PC1 scores the OU2VA model, which allows varying rates and

attraction strengths between regimes, is the best fitting model at all trait optimum values for

1382   both convergence and divergences datasets (Table S1). However, for convergence datasets, the

null model (BM1) is the second best-fitting model when the trait optimum is zero and 20, and

1384   the total AICcW values for the OU2VA model increases with greater optima values. This pattern

is consistent with the results of the multivariate evolutionary models (Table 2), suggesting a

1386   potential bias toward better fits of multiple-regime models when focal taxa are morphological

outliers. This potential bias should be considered by researchers who use fits of multiple-regime

1388   OU models to test for convergence.

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Table S1. Tests of convergence among lineages of the simulated datasets using evolutionary
1394   models fit to univariate data (PC1 scores) via functions in the *OUwie R* package. Model-
fitting results for each trait optimum are the mean AICcWs of 15 simulated datasets (see
1396   Methods). Model support for the two-regime models (any variation of the OU2 model)
could be interpreted as support for convergence because this model reflects evolution of
1398   the putatively convergent lineages toward a shared adaptive peak (but see the Results &
Discussion). Abbreviations: AICcW, small-sample corrected Akaike weights; BM, Brownian
1400   motion; OU, Ornstein-Uhlenbeck.

Simulations	Model	Trait optimum of focal taxa				
		0	**20**	**40**	**60**	**80**
Convergence	BM1	0.087	0.051	0.000	0.000	0.000
	OU1	0.032	0.022	0.000	0.000	0.000
	OU2	0.045	0.023	0.000	0.000	0.000
	OU2A	0.024	0.010	0.001	0.000	0.000
	OU2V	0.038	0.040	0.000	0.000	0.000
	OU2VA	0.773	0.854	0.999	1.000	1.000
Divergence	BM1	–	–	0.000	0.000	0.000
('constrained')	OU1	–	–	0.000	0.000	0.000
	OU2	–	–	0.000	0.000	0.000
	OU2A	–	–	0.105	0.079	0.214
	OU2V	–	–	0.046	0.000	0.000
	OU2VA	–	–	0.849	0.921	0.786

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$C1$–$C4$ and $Ct1$–$Ct4$ applied to simulated data

1408   In the main text we only present results for $C1$ (Fig. 3C, Table 1) and $Ct1$ (Fig. 5A, Table 1), which

were applied to both the simulated convergence datasets and the simulated divergence

1410   datasets. However, Stayton (2015) developed four distance-based convergence measures ($C1$–

$C4$) and one frequency-based measure ($C5$), with $C1$ being the primary measure, and we altered

1412 $C1$-$C4$ to produce the $Ct1$–$Ct4$ measures. Here, we provide full results for $C1$–$C4$ (Fig. S1) and

$Ct1$–$Ct4$ (Fig. S2), which are also applied to both the convergence and divergence datasets. See

1414   the Methods and Stayton (2015) for descriptions of the four convergence measures, and see

the Methods for information on the simulated datasets. Note that the $Ct4$ measure is

1416   calculated differently than the $C4$ measure (see Supplemental Methods). For $C1$–$C4$, all results

for divergence simulations are greater than zero (Fig. S2), incorrectly indicating convergence,

1418   whereas the $Ct1$–$Ct4$ scores for divergence datasets are generally at or below zero (Fig. S3).

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Figure S2. Plots of means and standard errors of *C*1–*C*4 scores for simulated convergent
1424   lineages (solid lines) and divergent lineages (dashed lines). Datasets varied in the number of
convergent/divergent traits (represented by the different colored lines) and in the distance
1426   of trait optima from the ancestral morphology (approximated as the center of
morphospace). Means and standard errors are computed from 15 simulated datasets.
1428   Greater *C*1–*C*4 values indicate greater convergence. We did not simulate divergence for
trait optima of 0, 10, and 20 because at these optima our simulation methods may have
1430   inadvertently generated convergence patterns (see Methods and Figure 3). As a second
means of simulating divergence, we allowed the lineages of interest ('gliders') to evolve via
1432   BM. These are provided as box-and-whisker plots, summarizing 15 simulated datasets of six
traits (see Methods). Note that the divergence results are all greater than zero, incorrectly
1434   indicating convergence.

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Figure S3. Plots of means and standard errors of *Ct*1–*Ct*4 scores for simulated convergent lineages (solid lines) and divergent lineages (dashed lines). Datasets varied in the number of convergent/divergent traits (represented by the different colored lines) and in the distance of trait optima from the ancestral morphology (approximated as the center of morphospace). Means and standard errors are each computed from 15 simulated datasets. Greater *Ct*1–*Ct*4 values indicate greater convergence. We did not simulate divergence for trait optima of 0, 10, and 20 because at these optima our simulation methods may have inadvertently generated convergence patterns (see Methods and Figure 3). As a second means of simulating divergence, we allowed the lineages of interest ('gliders') to evolve via BM. These are provided as box-and-whisker plots, summarizing 15 simulated datasets of six traits (see Methods). Note the differences in the scaling of the vertical axes of the *Ct*2 and *Ct*3 plots relative to the *C*2 and *C*3 plots (Fig. S1), respectively. (The scaling for *C*4 and *Ct*4 is different because these measures are calculated differently.) Also, note the different position of zero relative to results in the *Ct*1–*Ct*4 plots versus the position in *C*1–*C*4 plots (Fig. S1), as well as the overlap in the *Ct*1–*Ct*4 plots of divergence data simulated by both BM and OU processes.

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_Ct_-measures – the influence of origination times on results

As discussed in the main text, the _Ct_-measures limit candidate $D_{max.t}$ measurements to specific

time slices at internal nodes, and thus the timing of evolutionary change among putatively

convergent lineages can influence the results of _Ct_-measures. For instance, if different lineages

of interest evolve toward (or away from) a specific morphology at different points in time, then

the $D_{max.t}$ measurement may not measure the morphologically farthest distances between the

lineages. This issue may be magnified when convergence is expected to be linked to adaptive

changes (e.g., adaptations for gliding behavior) that evolved at specific times. For instance, if

colugos (i.e., Dermoptera or 'flying lemurs') evolved traits associated with gliding behavior

approximately 60 Ma, and flying squirrels (Pteromyini) evolved traits associated with gliding

approximately 25 Ma (e.g., Grossnickle et al. 2020), then most of the candidate $D_{max.t}$

measurements will be comparisons of dermopterans with gliding traits to stem flying squirrels

without gliding traits (from 60 to 25 Ma). If the older lineage (colugos) has already undergone

considerable evolutionary change by the time that the younger lineage (flying squirrels)

originated, then much of the convergent evolutionary change of the older lineage is not

captured by the morphological distances measured at 'time slices,' which are limited to the

time period in which the lineages overlap. Ideally, most candidate $D_{max.t}$ measurements would

be comparisons of non-gliding stem colugos and non-gliding stem flying squirrels that lack the

adaptive traits associated with gliding. This issue might lead to candidate $D_{max.t}$ measurements

being smaller than expected, or at least smaller than those calculated by measures that ignore

time (e.g., _C_-measures).

Conversely, if the putatively convergent taxa evolve toward outlying regions of

morphospace, then the asynchronous origins of the clades could inflate the _Ct_-measures. We

illustrate this in Figure S4. Note that the orange arrows, which represent the origins of the focal

lineages (and positions of candidate $D_{max.t}$ measurements), are the same morphological (x-axis)

distance apart in each panel if time (the y-axis) is ignored. In the conceptual illustrations, the

_Ct_1 score is consistently 0.3 when convergent lineages originate at the same time and/or when

lineages evolve toward the ancestral morphology. However, when lineages originate at

1488   different times and evolve toward an outlying region of morphospace, then the $Ct1$ score is 0.7

due to an inflated $D_{max.t}$ value (bottom right panel). Thus, researchers should be cautious when

1490   applying Ct measures to datasets with outlying taxa of various origination ages, and we offer

some suggestions in the main text for mitigating this issue. It is also worth noting that this latter

1492   scenario assumes that the convergent lineages can reach adaptive zones; if the later-evolving

convergent lineage is still evolving toward outlying morphospace (i.e., it has yet to reach an

1494   adaptive peak or zone) then the aforementioned issue may have less of an influence on Ct

results.

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Figure S4. Conceptual illustrations demonstrating how $Ct1$ results can be influenced by a

1502   combination of outlying morphologies and varying origination times among convergent
lineages. The $Ct1$ score is 0.3 in three of the scenarios but inflates to 0.7 when lineages both

1504   originate at different times and are outliers in morphospace (bottom right). To help mitigate
this issue, we have included an option as part of the *convrat.t* function that allows users to

1506   limit candidate $D_{max.t}$ measurement to the time period prior to the origination of the focal
        lineages (see Supplemental Methods). See the main text for descriptions of $Ct1$, $D_{max.t}$, and
1508 D_{tip}.

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Influence of the number of traits on *Ct* results

1514   As discussed in the main text (see Results & Discussion), the number of traits used in analyses

       (with all else equal) can bias the *Ct* scores. Inference of ancestral states via BM tends to average

1516   variation at internal nodes; thus, D_{tip} typically increases at a higher rate than $D_{max.t}$ for each non-

       convergent trait that is added to a dataset. (Here, we use "non-convergent traits" to refer to

1518   BM-evolved traits that are not selected to evolve toward a trait optimum via an OU process.

       These are often divergent, although it should be noted that BM-evolved traits could still be

1520   convergent by chance.) This is illustrated in Figure S5. The effect of this pattern is that an

       increased number of traits in analyses (with all else equal) could result in a relative decrease in

1522   *Ct* scores, unless those added traits are strongly convergent.

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Figure S5. Illustration of how the number of traits used in analyses can influence *Ct*-measures, demonstrating the increased rate at which D_{tip} values increase relative to $D_{max.t}$ as additional non-convergent traits are included in analyses. (Here, 'non-convergent traits' refers to BM-evolved traits, which are expected to be divergent in most cases.) The left panel shows D_{tip} and $D_{max.t}$ measured between two 'glider' lineages with two simulated convergent traits (optimum = 100) and varying number of additional traits simulated via BM. The right panel shows the ratio between the D_{tip} and $D_{max.t}$ values.

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Empirical example - *Anolis* **'twig' ecomorphotype**

1538   To test the novel *Ct*-measures and compare *Ct* results to those of *C*-measures (see the *Empirical*
        examples subsection of the Results & Discussion), we re-analyzed a classic example of

1540   convergence among *Anolis* lizards (Mahler et al. 2013), focusing specifically on five 'twig'
        ecomorphotype lineages. We chose this ecomorphotype because the taxa are morphological

1542   outliers that occupy a unique region of *Anolis* morphospace (Huie et al. 2021), and they have
        especially strong *C*-measure scores (Stayton 2015, Huie et al. 2021), although we believe that

1544   this is due in part to the lineages being morphological outliers (see Results & Discussion).
        Following the methods of Mahler et al. (2013), we size-corrected the traits via PGLS regression

1546   of each trait against the snout-to-vent length via PGLS. The *Ct*-measure results for this analysis
        are provided in Figure S6 and Table S2. Whereas the *C*1 score is 0.36 (Stayton 2015), we find the

1548   overall *Ct*1 score to be near zero for both the raw and weighted results (Table S2). This helps to
        highlight the inflated *C*-measure results due to the issues highlighted in the Results &

1550   Discussion. However, note that there is considerable diversity in the results among the ten
        pairwise comparisons; four are strongly statistically significant, whereas some (e.g., *Anolis*

1552   *occultus* and the *A. paternus* clade) show considerable divergence (*Ct*1 = -0.763; Table S2). To
        highlight the differences between convergent and non-convergent (or not significant

1554   convergence) pairwise comparisons, we separate those comparisons in Figure S6. Thus, we
        recommend that researchers examine and report results for pairwise comparisons whenever

1556   examining more than two putatively convergent lineages.

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Figure S6. Summary of empirical tests of convergence in *Anolis* species belonging to the 'twig ecomorph' (Mahler et al. 2013). We size-corrected (via PGLS regression) and then analyzed the ten skeletal traits of the dataset of Mahler et al. (2013), with taxa assigned to groups based upon unique origins of the 'twig' ecomorphotype (see the *Ct-measures* section of the Supplemental Methods). The plots are the output of the *plot.C* function of the convevol R package, although the distance-through-time plot has been split to show statistically significant (left) and not significant (right) pairwise comparisons separately (see also Table S2). Significant pairwise comparisons are also indicated in bold in the key. Note that two of the 'non-convergent' comparisons in the right panel do have a positive *Ct*1 value, but they are statistically not significant (Table S2). There are 50 null simulations (light gray lines).

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Table S2. *Ct*-measure values obtained for analyses run using the anole dataset of Mahler et al. (2013; ten standardized skeletal traits). Values are reported for overall comparison of ten 'twig ecomorph' species in five groups (corresponding to each independent origin of the ecomorph; Fig. S6). Pairwise comparisons of groups are also illustrated in (Fig. S6). See the Supplemental Methods for an explanation of the difference between 'overall raw' and 'overall weighted' results. Note that 'pat' refers to a five-species clade that includes *Anolis paternus* and four closely related specie*s*, whereas all other 'twig' taxa include a single lineage (Fig. S6); see the Methods for updates to the *convevol R* package that allow for comparisons among taxa with more than one lineage. Asterisks denote values returned as significantly different from null simulations (. - p < 0.1, * - p < 0.05, ** - p < 0.01). Abbreviations: *dar, Anolis darlingtoni*; *ins, Anolis insolitus*; *occ, Anolis occultus*; *pat, Anolis paternus*; *val, Anolis valencienni*.

	Overall		Pairwise comparisons									
	Raw	Weighted	*dar - pat*	*ins - pat*	*pat - val*	*occ - pat*	*dar - ins*	*dar - val*	*dar - occ*	*ins - val*	*ins - occ*	*occ - val*
Ct 1	-0.01**	-0.057**	0.147**	0.323**	0.346**	-0.763	0.083 .	0.161 .	-0.521	-0.527	0.237**	-0.055
Ct 2	0.072**	0.022**	0.086**	0.254**	0.261**	-0.216	0.027 .	0.042 .	-0.241	-0.127	0.179**	-0.039
Ct 3	0.039**	0.012**	0.047**	0.111**	0.140**	-0.090	0.013 .	0.023 .	-0.117 .	-0.063	0.071*	-0.018
Ct 4	0.002**	-0.006 .	0.003**	0.019**	0.011**	-0.007	0.001 .	0.001 .	-0.089	-0.005	0.006**	-0.001

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Unconstrained divergence

For our primary selection-based divergence simulations, we 'constrained' the focal lineages ('gliders') to one region of morphospace by limiting the OU-evolved divergent trait optima to be positive values, whereas all BM-evolved traits (of both 'gliders' and 'non-gliders') could be positive or negative (see Methods and Figure S1). We believe that the 'constrained divergence' simulations help to mimic empirical datasets in which lineages exhibit some morphological similarities but are still geometrically divergent.

Nonetheless, we also simulated 'unconstrained divergence' for a smaller subset of evolutionary scenarios (see discussion on subset analyses in the Methods) in which the 'glider' trait optimum values were not limited to positive values. The results of convergence measures applied to these simulations are provided in Table S3. The results indicate that all convergence measures correctly identify the 'gliders' to be divergent. For instance, the two-regime OU model (mvOU2) is out-performed by the single-regime mvBM1 and mvOU1 models, indicating a

lack of evidence for 'glider' lineages converging on a shared adaptive peak. The mean $C1$ results

1618 are greater than zero, indicating a small amount of convergence. However, in contrast to Ct-measures, C-measures are not permitted to be less than zero (see Methods). Thus, the mean $C1$

1620 results are biased toward being greater than zero because none of the 15 simulations can have values less than zero, and the small positive value is likely due to the occasional convergence of

1622 the 'glider' lineages by chance.

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1628 **Table S3**. Convergence measures applied to 'unconstrained divergence' simulations in which focal taxa ('gliders') were permitted to evolve in any direction (see Methods and Figure S1). Results are the means of 15 simulated datasets for each trait optimum value.

1630 The Akaike weights are small-sample corrected Akaike weights. None of the results for the distance-based convergence measures are statistically significant. For θ results, we report

1632 θ_{real} standardized to phylogenetic distance between clades. See Tables 1 and 2 for more information.

		Trait optimum of focal taxa		
		40	60	80
Model-ftting analsyes (Akaike weights)	mvBM1 model	1.000	1.000	1.000
	mvOU1 model	0.000	0.000	0.000
	mvOU2 model	0.000	0.000	0.000
Distance-based convergence measures	θ (*RRphylo*)	0.509	0.468	0.530
	Wheatsheaf index	0.840	0.640	0.481
	*C*1	0.056	0.064	0.037
1634	*Ct*1	-0.101	-0.081	-0.108

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1640 **Influence of ancestral state reconstructions**

As discussed in the main text, the assumption of a BM model of evolution for ancestral state

1642 reconstructions may often dilute Ct scores. We tested this assumption by comparing Ct scores obtained using our revised metric (with ancestral reconstructions via a Brownian motion model

1644 of evolution) to those obtained using a similar approach but employing the generated ('true') ancestral morphologies. The latter method used saved node values for each simulated

1646   morphological trait. Comparison between these two approaches was conducted using 15

simulated datasets, with all six traits of 'gliders' converging to an optimum trait value of 50 (see

1648   Fig 5). Group-weighted *Ct* values showed consistently stronger convergence when true

ancestral states were used in calculations (Table S4). However, differences were comparatively

1650   small (e.g., differences smaller than those between datasets containing five and six convergent

traits; Fig 5). Nevertheless, these results indicate that the assumption that focal traits evolved

1652   via Brownian motion used to calculate *Ct* (and original *C*) scores can in some cases result in an

underestimate of the degree to which lineages converge.

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Table S4. We compared *Ct* values obtained using our revised metric (with ancestral
1658   reconstructions estimated via a BM model of evolution) to those obtained using the
generated ('true') ancestral morphologies. Comparison between these two approaches was
1660   conducted using 15 simulated datasets, with all six 'glider' traits converging to an optimum
trait value of 50. The standard errors (SEs) for the 15 datasets are also reported.

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Ancestral traits	*Ct* 1	*Ct* 2	*Ct* 3	*Ct* 4
Estimated	0.67	32.63	0.14	0.04
SE	0.003	0.961	0.003	0.001
Generated	0.78	63.09	0.2	0.07
SE	0.002	1.536	0.003	0.002

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