Challenges and advances in measuring phenotypic convergence

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14 **ABSTRACT**

Tests of phenotypic convergence can provide evidence of adaptive evolution, and the

16 popularity of such studies has grown in recent years due to the development of novel,

quantitative methods for identifying and measuring convergence. These methods include the

18 commonly applied $C1$–$C4$ measures of Stayton (2015), which measure morphological distances

between lineages, and Ornstein-Uhlenbeck (OU) evolutionary model-fitting analyses, which test

20 whether lineages convergently evolved toward adaptive peaks. We test the performance of C-

measures and other convergence measures under various evolutionary scenarios and reveal a

22 critical issue with C-measures: they often misidentify divergent lineages as convergent. We

address this issue by developing novel convergence measures—$Ct1$–$Ct4$-measures—that

24 measure distances between lineages at specific points in time, minimizing the possibility of

misidentifying divergent taxa as convergent. Ct-measures are most appropriate when focal

26   lineages are of the same or similar geologic ages (e.g., extant taxa), meaning that the lineages'

      evolutionary histories include considerable overlap in time. Beyond C-measures, we find that all

28   convergence measures are influenced by the position of focal taxa in phenotypic space, with

      morphological outliers often statistically more likely to be measured as strongly convergent by

30   chance. Further, we mimic scenarios in which researchers assess convergence using OU models

      with *a priori* regime assignments (e.g., classifying taxa by ecological traits), and we find that

32   multiple-regime OU models with phenotypically divergent lineages assigned to a shared

      selective regime often outperform simpler models. This highlights that model support for these

34   multiple-regime OU models should not be assumed to always reflect convergence among focal

      lineages of a shared regime. Our new $Ct1$–$Ct4$-measures provide researchers with an improved

36   comparative tool, but we emphasize that all available convergence measures are imperfect,

      and researchers should recognize the limitations of these methods and use multiple lines of

38   evidence when inferring and measuring convergence.

40
      INTRODUCTION

42   Phenotypic convergence is commonly associated with adaptive evolution (e.g., Darwin 1859,

      Losos 2011), but it can also occur stochastically (Stayton 2008) or as a byproduct of shared

44   developmental constraints (Losos 2011, Speed and Arbuckle 2016). Evidence for adaptive

      convergence is strengthened when the convergent phenotypes are tied to similar ecological or

46   functional roles, and when the magnitude of convergence is greater than expected by chance.

      Thus, quantitative examinations of phenotypic convergence are important; they assist in 1)

48   identifying convergence and 2) inferring whether evolutionary change is adaptive. Novel

methods for identifying and measuring convergence have recently been developed (Mahler et

50   al. 2013, Arbuckle et al. 2014, Ingram and Mahler 2013, Stayton 2015A, Speed and Arbuckle

2017, Castiglione et al. 2019) and are often accompanied by statistical tests for comparing

52   observed convergence to that which is expected by chance. The increased accessibility of

quantitative tests for phenotypic convergence has led to a flood of recent studies on that topic

54   (e.g., Friedman et al. 2016, Zelditch et al. 2017, Baliga and Mehta 2018, Da Silva et al. 2018,

Arbour and Zanno 2020, Button and Zanno 2020, Grossnickle et al. 2020, Martinez et al. 2020,

56   Serio et al. 2020, Rincon-Sandoval et al. 2020, Spear and Williams 2020, Baumgart et al. 2021,

Huie et al. 2021, Rovinsky et al. 2021, Tamagnini et al. 2021, Alfieri et al. 2022, Bennion et al.

58   2022, Canale et al. 2022, Law 2022).

Phenotypic convergence is often defined as lineages evolving to be more similar to

60   one another than were their ancestors (Losos 2011, Stayton 2015A, Mahler et al. 2017), and we

follow this definition here. This definition is pattern-based, and thus is consistent with any

62   number of evolutionary processes or scenarios which might lead to increased phenotypic

similarity among evolving lineages, making it an ideal framework for identifying and quantifying

64   convergence (Stayton 2015A, Stayton 2015B). Further, this definition aligns with the underlying

operational definitions of convergence used in recent studies that developed convergence

66   measures (Losos 2011, Arbuckle et al. 2014, Stayton 2015A, Mahler et al. 2017, Castiglione et

al. 2019). This strict definition of convergence excludes some patterns that some authors

68   consider forms of convergence (e.g., evolution along parallel trajectories). Thus, we

reemphasize here that the chosen definition can significantly influence conclusions of

70   convergence studies, including this study. For instance, relying on a relatively broad definition

of convergence that permits focal species to have greater morphological variation than their

72   ancestors (e.g., see 'imperfect convergence' of Collar et al. 2014) would increase the chance of

concluding that focal taxa are convergent. Moreover, finding a pattern of convergence

74   according to our definition can be used to support a hypothesis of lineages evolving in response

to the same adaptive peak; 'imperfect convergence', although possible under such a scenario,

76   will not provide evidence for shared selection in response to the same adaptive peak. For more

information on the definition of convergence, see multiple reviews on the topic, including

78   Moore and Willmer (1997), Stayton (2006), Stayton (2008), Stayton (2015A), Stayton (2015B),

Pontarotti (2016), Speed and Arbuckle (2017), Mahler et al. (2017), and Bels and Russell (2023).

80   The $C1$–$C4$ measures (hereafter, 'C-measures') developed by Stayton (2015A) are an

especially popular means of quantifying morphological convergence (e.g., Friedman et al. 2016,

82   Zelditch et al. 2017, Baliga and Mehta 2018, Da Silva et al. 2018, Arbour and Zanno 2020,

Button and Zanno 2020, Grossnickle et al. 2020, Martinez et al. 2020, Rincon-Sandoval et al.

84   2020, Spear and Williams 2020, Baumgart et al. 2021, Huie et al. 2021, Rovinsky et al. 2021,

Tamagnini et al. 2021, Alfieri et al. 2022, Bennion et al. 2022, Canale et al. 2022, Law 2022). C-

86   measures are calculated using geometric distances in phenotypic space between focal lineages,

relying on ancestral reconstructions for morphologies at ancestral nodes. The underlying

88   feature of C-measures is the comparison the maximum phenotypic distance between focal

lineages at any points in their evolutionary histories (D_{max}) and the phenotypic distance

90   between phylogenetic tips (D_{tip}) (Fig. 1A). $C1$ is the primary C-measure and calculated as $1 -$

(D_{tip}/D_{max}), with the resulting value representing "the proportion of the maximum distance

92   between two lineages that has been 'closed' by subsequent evolution" (Stayton 2015A). In our

conceptual illustration (Fig. 1A), two focal lineages have convergently evolved such that their

94   tips are 70% closer to each other than their D_{max}, resulting in a $C1$ score of 0.7.

Figure 1. Conceptual illustrations of two methods for assessing phenotypic convergence of focal

98   lineages (maroon): *A*, *C*1 of Stayton (2015A) and, *B*, multiple-regime Ornstein-Uhlenbeck (OU)

model-fitting. The *C*1 score of 0.7 indicates that lineages have evolved toward each other to cover

100   70% of the maximum distance (D_{max}) between their lineages. D_{max} can be measured at any point

along the evolutionary histories, starting from the most recent common ancestor (MRCA). D_{tip} is the

102   morphological distance between phylogenetic tips. Univariate plots are illustrated as bivariate

because there is a time axis, although note that *C*-measure calculations do not incorporate time. *B*,

104   OU models include fitting parameters for trait optima (often interpreted as locations of adaptive

peaks) and 'attraction' strengths (often interpreted as selection strengths).

108   One reason for the popularity of *C*-measures is that they can distinguish between

convergence (as defined here) and alternative evolutionary patterns that result in distantly

110   related taxa with similar phenotypes, such as conservatism and parallel evolutionary

trajectories (referred to as 'parallelism' in some contexts). Conservatism is the lack of

112   substantial phenotypic divergence from ancestral morphologies relative to what is expected

from various processes (Losos 2008, Moen et al. 2013, McLean et al. 2018); thus, unlike

114   convergence, it does not involve ancestors being less morphologically similar to each other than

are their descendants (e.g., see the 'blue' lineages in Figure 1B). Similarly, parallelism results in

116   lineages with shared traits, but the lineages' ancestors never diverged and thus do not reflect

convergence as defined here. C-measures account for ancestral patterns via the D_{max}

118   measurement (Fig. 1A). Alternative distance-based methods for testing for convergence (e.g.,

Wheatsheaf index, Arbuckle et al. 2014, Arbuckle and Minter 2015; θ, Castiglione et al. 2019)

120   cannot adequately differentiate between convergence and either conservatism or parallelism

because phenotypic distances between ancestral morphologies are not considered or, in the

122   case of θ, only partially integrated (Castiglione et al. 2019).

In addition to distance-based measures, evolutionary model-fitting analyses are used to

124   assess convergence, with strong fits of multiple-regime Ornstein-Uhlenbeck (OU) models

(Hansen 1997, Butler and King 2004) to morphological data often interpreted as evidence of

126   convergence (e.g., Mahler et al. 2013, Ingram and Mahler 2013, Friedman et al. 2016, Mahler et

al. 2017, Baliga and Mehta 2018, Grossnickle et al. 2020, Martinez et al. 2020). An OU process

128   involves 'attraction' toward an 'attractor' (i.e., trait optimum), which may be due to selective

pressures toward adaptive peaks (Fig. 1B). Convergence is sometimes inferred when the best-

130   supported model indicates that two or more focal lineages independently evolved toward the

same trait optimum (or adaptive peak). Implementations of these multiple-regime OU models

132   either classify focal taxa into selective regimes *a priori* (e.g., based on a shared ecological trait)

or examine whether focal taxa are independently identified (i.e., without *a priori* classifications)

134   as shifting toward a shared adaptive peak. The latter method can be implemented using

functions in *R* libraries such as *SURFACE* (Ingram and Mahler 2013; but see Adams and Collyer

136   2018 for a critique) and *l1ou* (Khabbazian et al. 2016). Other *R* packages can also identify peak

shifts (e.g., *Bayou*, Uyeda and Harmon 2014; *phyloEM*, Bastide et al. 2018) but do not include

138   functions specifically designed to identify convergence.

However, an OU process does not require that independent lineages shifting toward a

140   peak (as evidenced by support for OU models) come from more dissimilar ancestors and thus

these lineages may not meet the criteria of convergence used in this paper. As such, it may be

142   challenging to use OU model-fitting analyses to differentiate convergence from conservatism;

focal taxa may share a given morphology with their common ancestor, but lacking information

144   about ancestral states, it may be difficult to determine whether this is because the taxa

retained the ancestral morphology (conservatism) or converged on this ancestral morphology.

146   Nonetheless, a benefit of OU model-fitting analyses is that the magnitude of attraction

parameters provides estimates of selective strengths toward adaptive peaks, therefore

148   providing valuable information about underlying evolutionary processes.

We test the performances of *C*-measures and other means of assessing phenotypic

150   convergence using simulated multivariate datasets in which a subset of lineages are modeled as

truly convergent or truly divergent. Although our results uncover potential concerns with

152   multiple convergence measures (Wheatsheaf index, θ, and OU model-fitting analyses), the

most critical concern is with the *C*-measures: in many circumstances, *C*-measures may lead to

154 misclassification of divergent lineages as convergent. To address this issue, we present an

improved method for calculating *C*-measures that minimizes the possibility of erroneously

156 measuring divergent lineages as convergent.

METHODS

158 **Evolutionary simulations**

We generated simulated trait datasets to ascertain how frequently convergence measures

160 correctly identify *convergent* lineages and misclassify *divergent* lineages as convergent.

Simulated datasets are intended to reflect typical empirical datasets. We simulated traits for

162 201 species included in a recent phylogenetic treatment of extant mammals, resulting in taxon

sampling and phylogenetic structure comparable to recent comparative studies (Grossnickle et

164 al. 2020, Weaver and Grossnickle 2020, Pevsner et al. 2022). The phylogeny is a pruned

maximum clade credibility tree produced using 1000 randomly chosen trees from the posterior

166 distribution of Upham et al.'s (2019) 'completed trees' analysis. The sample includes 13 gliding-

mammal species representing five independent evolutionary origins of gliding behavior. We

168 treated the gliders as the focal lineages (*sensu* Grossnickle et al. 2020); they were the subject of

manipulation in our simulations (as such, we refer to those simulated glider data as 'gliders').

170 The five 'glider' clades are spread across the phylogeny and have varying evolutionary origin

ages, making them ideal for representing typical empirical datasets.

172 Each simulated dataset included six morphological traits, which typically had ranges

between 40 and -40 trait units. These are meant to mimic independent linear measurements of

174 an empirical dataset. In the non-glider (i.e., 'base') portion of the tree, all six traits were

simulated to evolve via Brownian motion (BM). In 'glider' clades, between three to six of these

176   traits were simulated to evolve via an OU process (except for drift-based divergence

        simulations; see descriptions below), with optima varying to produce convergent or divergent

178   trajectories. The BM component of the simulation ('base simulation') was performed using the

        SimulateContinuousTraitsOnTree function in the *Phylogenetics for Mathematica* package (Polly

180   2019). The ancestral value for each trait was arbitrarily set to 0.0 and the step rate (σ^2) was set

        at 1.0 per million years. In 'gliders,' traits evolving via an OU process toward trait optima (see

182   below) were simulated using the *LineageEvolution* function in *Phylogenetics for Mathematica*

        (ancestral trait values were generated via BM at the base of each clade), with variable optima

184   (θ), a step rate (σ^2) of 0.01, and selection strength (α) of 0.01. See the Supplemental Methods

        for a description of how these simulations can be replicated using the *OUwie R* library (Beaulieu

186   et al. 2012). Phylogenetic branches of 'gliders' were those tipped by one of the 13 'glider'

        species, plus the subtending branches below clades whose tips were all 'gliders.'

188   We generated four types of simulations: 1) convergence of 'gliders' via selection (OU-

        evolved traits), 2) divergence of 'gliders' via drift (BM-evolved traits), 3) 'constrained

190   divergence' of 'gliders' via selection (OU-evolved traits, limited to positive values), and 4)

        'unconstrained divergence' of focal taxa via selection (OU-evolved traits; no limits on traits).

192   The following text describes these types of simulations, and Figure S1 provides a graphical

        summary. In total, we generated and analyzed 960 simulated datasets.

194   *Convergence simulations.* We systematically altered 1) the number of traits (of six total)

        subjected to convergent selection (three through six) and 2) their optimum values (or 'targets')

196   (Fig. S1). Convergent traits were evolved via selection (i.e., OU-evolved) toward the same trait

        optimum (target). The convergent traits were subjected to directional OU-selection for their full

198   branch lengths, allowing most 'glider' tips (besides those with the shortest branches) to arrive

at the adaptive peak. Traits (and taxa) not subject to convergent evolution continued to evolve

200   by BM. Note that the OU parameters, apart from the target optimum (i.e., θ), were kept

constant (σ^2 = 0.01, α = 0.01) for all simulations involving OU-evolved traits, and variation in the

202   'strength' of convergence was represented by the number of traits subject to convergence

rather than the strength of selection per se. Six of six traits being convergent represents

204   extremely strong convergence, whereas three of six traits being convergent represents weaker

convergence. Further, we altered the number of convergent traits because empirical datasets

206   often include both convergent and divergent traits (e.g., Grossnickle et al. 2020).

By systematically altering trait optima ('targets'), we controlled the morphological

208   distance of 'gliders' from their ancestral condition, allowing us to test how morphospace

position influences results of applied convergence measures (Fig. S1). We used a series of nine

210   trait optima at successively greater distances from the ancestral point in morphospace, starting

at zero (convergence toward the ancestral trait values) and successively increasing by 10 trait

212   units to a distance of 80. For example, in a simulation with four traits (of six) being convergent

and an optimum of 30, four traits evolved toward an optimum trait value of 30 and the two

214   remaining traits evolved by BM. For simulations using the smallest optima values (zero and 10),

the 'gliders' generally lie within the morphospace occupied by 'non-gliders.' In contrast, the

216   farthest tested optima (i.e., ~60–80) result in the 'gliders' being very far from 'non-gliders' in

morphospace. The extreme outliers are unlikely to reflect empirical scenarios but are included

218   to help infer trends. Each simulation with all iterations was repeated with 15 unique 'base

simulations,' and we report means and standard errors of these 15 replicates.

220   *Divergence simulation*s. Because divergence may result from both selective and non-

selective processes, and because the expected patterns among focal groups varies with these

222   generating processes, we generated two types of divergence simulations. These were drift-

based via BM-evolved traits and selection-based via OU-evolved traits. In addition, drift-based

224   simulations involve divergence of lineages that remain relatively closer to the ancestral

morphology (i.e., within the morphospace region occupied by non-gliders), which is more

226   difficult to replicate in our OU-evolved divergence simulations (see below). To simulate

divergence via drift (i.e., BM-evolved 'gliders'), we simulated six traits using the *fastBM* function

228   of the *phytools* package (Revell 2012) for *R* (*R* Core Team 2020). For both 'gliders' and 'non-

gliders,' ancestral trait values were set at zero, and, to mimic natural variation, the rate

230   parameter (σ^2) was sampled from a log-normal distribution with log-mean and standard

deviation 0 and 0.75, respectively. This was repeated to produce 15 replicate datasets.

232   For selection-based (OU-evolved) divergence, the five 'glider' clades each evolved

toward a different trait optimum. Between three and six traits were selected toward the clade-

234   specific trait optimum with a series of target distances ranging from 30 trait units from the

ancestral morphology (which extends the lineages past the periphery of the base BM tree and

236   thus ensures that the targets are divergent) to 80 units in steps of 10. This means that these

divergence simulations are limited to cases in which focal lineages are morphological outliers. A

238   different target was randomly selected for each 'glider' clade by choosing a random trait value

for each of the traits under selection with the condition that their sum of squares equal the

240   squared target distance (i.e., that the target lies at a distance of 30, 40, etc. units from the

ancestral trait values). The focal lineages were allowed to fully reach their trait optima.

242   For our primary selection-based divergence simulations, we 'constrained' the OU-

evolved 'glider' traits to positive values, ensuring that trait optima are divergent yet lie within

244   the same quadrant (or hyper-region) of multidimensional space. This constraint mimics

empirical datasets in which lineages exhibit some morphological similarities but are

246   geometrically divergent (e.g., Collar et al. 2014). Nonetheless, we also simulated 'unconstrained

divergence' (see discussion on subset analyses below) in which the 'glider' trait optimum values

248   were not limited to positive values.

        Convergence tests applied to simulated data, except some model-fitting analyses, were

250   multivariate, incorporating all six simulated traits. Although our simulated data mimic

independent linear measures, all convergence measures tested here could be applied to other

252   data types, including higher-dimensional trait data (e.g., geometric morphometrics data),

although long computational times for some analyses might first require data reduction via

254   principal components analyses (PCAs).

256   ***C*-measures**

We applied *C*-measures (Stayton 2015A) to focal lineages ('gliders') in the simulated datasets.

258   The primary *C*-measure, *C*1, is calculated as $1 - (D_{tip}/D_{max})$, with D_{tip} representing the distance

between phylogenetic tips of focal taxa and D_{max} representing the maximum distance between

260   any tips or ancestral nodes of those lineages (Fig. 1A). The *C*1 value is one for complete

convergence and zero for divergence (i.e., D_{max} is D_{tip}). *C*2 is the difference between D_{max} and

262   D_{tip}, and it captures the absolute magnitude of convergent change. *C*3 and *C*4 are standardized

versions of *C*2, with *C*2 divided by the phenotypic change along branches leading to the focal

264 taxa (*C3*) or the total amount of phenotypic change in the entire clade (*C4*). See Stayton (2015A)

for full descriptions of *C*1–*C*4. To calculate *C*-measure scores, we used *R* script functions from

266 Zelditch et al. (2017), which are computationally faster than the functions in v1.0 through v1.3

of the *convevol R* package (Stayton 2015A, Stayton 2018). *C*1–*C*4 scores were calculated for all

268 simulated datasets, but due to computational limits, we only calculated simulation-based *p*-

values for a smaller subset of datasets (see the following subsection).

270   *C*-measures quantify phenotypic convergence between individual tips, not between

clades with multiple tips (Stayton 2015A). Thus, we calculated average phenotypes for each

272 focal clade and applied *C*-measures to the five 'glider' lineages, each representing an

independent evolution of gliding. For example, one glider clade includes six species, so for each

274 simulated trait we calculated mean values for the six species, with the averages used as the

representative flying squirrel lineage. These clade averages were only used for *C*-measures.

Additional measures of convergence

278 *Subset of simulated datasets*. We applied additional measures of convergence (OU model-

fitting, θ, and Wheatsheaf index) to a smaller subset of simulated datasets. This subset only

280 includes datasets in which four of six traits were simulated to converge on a specific trait

optimum or diverge toward multiple optima, with the remaining two traits evolved by BM. Four

282 of six traits being convergent results in focal lineages being strongly convergent (e.g.,

statistically significant distance-based measures of convergence; see Results & Discussion) but

284 not completely convergent. For convergence simulations, we used 15 simulated datasets from

sets of simulations where trait optima were set at 0, 20, 40, 60, and 80. These represent

286   simulations in which focal lineages evolve toward the ancestral morphology (optimum = 0), just

beyond the morphospace region of BM-evolved lineages (optimum = 20), and far into outlying

288   morphospace (optima = 40, 60, and 80). For selection-based divergence simulations, we used

the 15 simulated datasets with optima of 40, 60, and 80. (Using trait optima of 0 or 20 could

290   mistakenly simulate convergence toward ancestral morphologies.) The following methods were

only applied to this subset of datasets.

292   *Evolutionary model-fitting analyses*. We performed evolutionary model-fitting analyses

using both multivariate models via functions in the *mvMORPH R* package (Clavel et al. 2015)

294   and univariate models via functions in the *OUwie R* package (Beaulieu et al. 2012). The

multivariate models offer the benefit of incorporating all six traits, whereas the univariate

296   models can be set to allow rate (σ^2) and attraction (α) parameters to vary between selective

regimes (i.e., 'gliders' and 'non-gliders') and therefore better represent the underlying

298   simulated data, which include both BM-evolved and OU-evolved lineages.

We fitted four multivariate models to all six simulated traits. The first three models were

300   a single-rate multivariate BM model (mvBM1) that assumes trait variance accumulates

constantly and homogeneously on the phylogeny, a single-optimum Ornstein-Uhlenbeck model

302   (mvOU1) that modifies the BM model to constrain each trait to evolve toward a single

optimum, and an early burst model (mvEB) that modifies the BM model to decrease

304   evolutionary rate with time. These models do not model 'gliders' as evolving to a distinct

adaptive peak and thus are not expected to reflect convergence of 'gliders' on an adaptive peak

306   (e.g., Fig. 1B). The mvEB model always collapsed to a mvBM model (i.e., the change-in-rate

parameter was zero), and thus we did not report mvEB results.

308   We fitted a two-regime multivariate OU model (mvOU2) that allowed 'gliders' and 'non-

gliders' to exhibit different trait optima (θ). Support for mvOU2 could provide evidence of

310   convergence by indicating that selective forces are driving 'glider' lineages to a shared adaptive

peak (Fig. 1B). Note that in the simulations 'non-gliders' evolved via BM (intended to simulate

312   lineages with traits not under strong directional selection or constraint), and thus any support

for the mvOU2 model is likely to be driven by the 13 'glider' lineages. Relative support for

314   models was assessed through computation of small-sample corrected Akaike weights (AICcW;

Akaike 1974; Hurvich and Tsai 1989). We calculated AICcW for each of the 15 base simulations

316   and report mean values. Prior to fitting the mvOU2 model, we mapped the gliding regime

character state onto the 'glider' branches of the phylogeny (including the subtending branches

318   below 'glider' clades) using the *paintSubTree* function in the *phytools R* package (Revell 2012).

        We fitted models to univariate data (PC1 scores) using *OUwie* functions (Beaulieu et al.

320   2012). Although fitting evolutionary models to PC scores may generate biased results (Uyeda et

al. 2015, Adams and Collyer 2018), we fitted these models because, unlike multivariate

322   *mvMORPH* models, they permit evolutionary rates (σ^2) and/or attraction strengths (α) to vary

between regimes. We fitted seven univariate models, including single-regime models (BM1 and

324   OU1) and a suite of two-regime OU models (i.e., 'OUM' models of Beaulieu et al. 2012). The

OU2 model keeps α and σ constant for both 'glider' and 'non-glider' regimes, OU2A allows α to

326   vary between regimes, OU2V allows σ^2 to vary between regimes, and OU2VA allows both σ^2

and α to vary between regimes (see the Supplemental Methods).

328   *Additional distance-based convergence measures*. We applied two other convergence

measures to the subset of simulated datasets (using all six traits): the Wheatsheaf index, which

330   was implemented via the *R* package *windex* (Arbuckle et al. 2014, Arbuckle and Minter 2015),

and θ_{real}, which was implemented using the *RRphylo* package (Castiglione et al. 2018,

332   Castiglione et al. 2019). The Wheatsheaf index measures pairwise morphological distances

between focal taxa, with distances corrected for the degree of phylogenetic relatedness of

334   lineages. These distances are compared to pairwise distances between other lineages in the

sample to determine whether focal lineages are more similar to each other than expected. The

336   θ_{real} measurement (which is different than the θ parameter of OU models) is the angle between

the phenotypic vectors of focal lineages (note that these are not vectors of evolutionary

338   change), and it is based upon phylogenetic ridge regression (Castiglione et al. 2018, Castiglione

et al. 2019). Smaller angles indicate greater phenotypic similarity, which may reflect

340   convergence of taxa toward a common morphology (Castigione et al. 2019). We report the

angle obtained by all pairwise comparisons between focal clades (θ_{real}), standardized by the

342   phylogenetic distance separating them (i.e., expected divergence under a BM model).

Significance tests compare standardized θ_{real} values of focal taxa to values computed for

344   randomly selected tip pairs.

346   **RESULTS & DISCUSSION**

***C*-measure issues**

348   The *C*-measures do not always perform as intended (Stayton 2015A), especially when focal

lineages are morphological outliers. This critical problem can manifest in at least two ways (Fig.

350   2). First, the more outlying the morphologies are in phylomorphospace (and all else being

equal, including D_{tip}), the greater the *C* scores, indicating stronger convergence. We

352 demonstrate this with a conceptual illustration in Figure 2A. Here, the distances between

ancestral nodes and the distances between descendants are unchanged between the scenarios,

354 and thus the *C* scores should be the same for both scenarios. The pattern of greater

convergence in outliers is also demonstrated by results of applying *C*-measures to evolutionary

356 simulations (Figs. 3 and S2).

Figure 2. Conceptual illustrations of *C*-measure issues. *C*1 scores are greater than zero for the

364 divergent (*B*) and parallel (*C*) focal lineages ('maroon'), incorrectly indicating convergence. See the

main text and Figure 1 for more information on $C1$, D_{max}, and D_{tip}. The C-measure issues may also

366   apply to evolutionary model-fitting analyses because model support for multiple-regime models

(often interpreted as evidence for convergence) may be strongest when lineages of different

368   regimes are divergent, such as in *B* (see Results and Discussion).

Figure 3. PCA phylomorphospaces for example datasets that simulate convergence (*A*) and

374   divergence (*B*) of all six traits of five focal clades ('gliders'). After focal clades originated, their traits

were selected toward optima via an Ornstein-Uhlenbeck (OU) process, with convergent clades

376   selected toward the same optimum (20 in *A*) and divergent clades selected toward varying optima

values (see Methods). (*C*) $C1$ scores (means and standard errors of 15 datasets) for focal lineages,

378   with varying numbers of convergent/divergent traits (of six total) and trait optima positions. Non-

convergent/divergent traits and lineages were evolved by Brownian motion (BM). Divergent trait

380   optima are randomized but limited to positive numbers (whereas BM-evolved traits can be

negative), resulting in divergent lineages occupying the same region of morphospace (e.g., negative

382   PC2 space in *B*). We did not simulate OU-evolved divergence to trait optima of 0–20 because it often

mistakenly generates convergent lineages near the middle of morphospace. But we also simulated

384   divergence via BM evolution, with results as a box-and-whisker plot in *C*.

386   The second issue with the C-measures is more problematic: divergent and parallel

lineages can have $C1$ scores greater than zero, incorrectly indicating convergence. In Figure 2B

388   we illustrate lineages that are diverging morphologically but have a $C1$ score (0.3) indicating

substantial convergence (closing about 30% of the maximum distance between lineages).

390   Similarly, lineages evolving along parallel trajectories from a similar ancestral condition (Fig. 2C)

have an extremely strong $C1$ score (0.7), which is unexpected because the lineages' ancestral

392   nodes are the same morphological distance from one another as the distance between tips.

Further, we measured $C1$ in lineages simulated to be divergent (Fig. 3B), and $C1$ values are

394   consistently greater than zero (and statistically significant) for the 'constrained divergence'

simulations (Fig. 3C; Table 1), incorrectly indicating convergence. $C1$ scores for divergent focal

396   lineages remain around 0.3 at all morphospace positions (Fig. 3B), although the lack of an

increase in outliers (like with convergence simulations) may be due in part to methodological

398   choices (see the Supplemental Results and Figure S4).

Table 1. Distance-based convergence measures applied to focal lineages ('gliders') of simulated
convergence and 'constrained' divergence datasets (see Methods). Results are means of 15 datasets
for each optimum. For θ, we report $θ_{real}$ standardized to phylogenetic distance between clades.
Relatively smaller $θ_{real}$ values (i.e., smaller angles between phenotypic vectors) suggest greater
convergence, whereas larger Wheatsheaf index, $C1$, and $Ct1$ values indicate greater convergence.
Statistical significance (*, $p \leq 0.05$; **, $p \leq 0.01$; ***, $p \leq 0.001$) for $C1$ and $Ct1$ is based on
comparisons to 100 BM simulations, for the Wheatsheaf index it is based on bootstrapping with
1000 replicates, and for standardized $θ_{real}$ it is based on bootstrapping with 1000 replicates for each
pairwise comparison between the five 'glider' clades (except the monospecific clade).

Simulations	Convergence measure	Trait optimum				
		0	20	40	60	80
Convergence	θ (*RRphylo*)	0.393	0.126*	0.071**	0.044**	0.040**
	Wheatsheaf index	1.976***	1.715***	1.314	0.905	0.626
	$C1$	0.350*	0.526***	0.685***	0.751***	0.769***
	$Ct1$	0.176*	0.233**	0.367***	0.497***	0.483***
Divergence	θ (*RRphylo*)	–	–	0.220	0.242	0.229
('constrained')	Wheatsheaf index	–	–	0.826	0.581	0.434
	$C1$	–	–	0.363**	0.325**	0.310**
	$Ct1$	–	–	0.035	0.011	-0.003

The issues with *C*-measures may commonly occur when at least one focal lineage

rapidly diverged from other taxa, which can often generate morphological outliers (e.g., see

'maroon' lineages in Figure 2B). However, these issues are not limited to outliers and could

occur in any region of morphospace. Thus, they have major implications for many empirical

studies that rely on *C*-measures (see discussion of examples below); divergent or parallel

lineages may often be incorrectly interpreted to be convergent.

The possibility of diverging and parallel lineages having $C1$ scores greater than zero

(incorrectly indicating convergence) stems from problematic D_{max} measurementss. D_{max} can be

measured between ancestral nodes (e.g., see Figure 1A), between tips, or between a node and

432   a tip (e.g., see Figure 2). For converging lineages, D_{max} is expected to be longer than D_{tip}

(Stayton 2015A). For diverging lineages, by contrast, D_{max} is expected to be the morphological

434   distance between the tips, meaning that D_{max} equals D_{tip} (and $C1 = 0$). However, this is not

always the case; divergent lineages can have a D_{max} length that is not between tips, as

436   illustrated in Figure 2B. Thus, divergent lineages can have a D_{max} that is greater than D_{tip},

incorrectly indicating convergence. Although we illustrate this issue using diverging

438   phylogenetic tips (Fig. 2B), the problem could also arise if internal nodes are similarly divergent

and outlying in morphospace (and branching lineages from those nodes do not converge on

440   other focal lineages); thus, this issue is not solely due to allowing D_{max} to be measured to tips.

442   **Other measures of convergence**

To test the performances of other convergence measures, we applied two 'distance-based'

444   metrics (Wheatsheaf index [Arbuckle et al. 2014, Arbuckle and Minter 2015] and θ [Castiglione

et al. 2019]) and OU model-fitting analyses to a subset of simulated datasets (Table 1).

446   *Distance-based convergence measures.* Consistent with the *C*-measures, $θ_{real}$ results

(standardized to phylogenetic distance between clades) indicate greater convergence in

448   morphological outliers (Table 1). That is, the angle between phenotypic vectors, $θ_{real}$, decreases

when lineages evolve toward optima that are farther from the ancestral morphology. This is

450   unsurprising because all other variables being equal (e.g., phenotypic distance between tips),

trait values farther from the origin should result in smaller angles between phenotypic vectors.

452   However, unlike the *C*-measures, $θ_{real}$ does not consistently identify simulated divergent

lineages as convergent (Tables 1 and S), although many 'constrained divergence' simulations

454   (~40%) returned significant results. In contrast to *C*-measures and standardized θ_{real}, the

Wheatsheaf index measures less convergence in outliers relative to non-outliers; values

456   decrease when convergent taxa are farther from the ancestral morphology in morphospace.

Evolutionary model-fitting analyses. For datasets with simulated convergent 'gliders,'

458   multiple-regime OU models (with a 'glider' regime) are the best-fitting models (Table 2),

correctly suggesting that 'gliders' are converging on a shared adaptive peak (Fig. 1B). However,

460   results are similar when 'gliders' are simulated to be divergent – multiple-regime OU models

outperform simpler models even though the 'gliders' are not evolving toward a shared adaptive

462   peak (Table 2).

480   **Table 2.** Evolutionary model-fitting analyses in which multivariate models were fitted to all six

simulated traits (via *mvMORPH* functions) and univariate models were fitted to PC1 scores (via

482   *OUwie* functions). Results for each trait optimum are mean AICcWs of 15 simulated datasets. Model

support for two-regime models (mvOU2 and all OU2 models) could be interpreted as evidence for

484   convergence because these model evolution of focal lineages toward a shared adaptive peak

(although see the Results & Discussion for cautionary notes on this assumption). The 'constrained

486   divergence' simulations limited the simulated traits of focal taxa ('gliders') to be positive values, thus

constraining them to one region of morphospace (see Methods). See the Supplemental Results for

488   'unconstrained divergence' results, and see the Methods for descriptions of the models.

Simulations		Model	Trait optimum of focal taxa				
			0	20	40	60	80
Multivariate	**Convergence**	mvBM1	1.000	0.000	0.000	0.000	0.000
(via *mvMORPH*)		mvOU1	0.000	0.000	0.000	0.000	0.000
		mvOU2	0.000	1.000	1.000	1.000	1.000
	Divergence	mvBM1	–	–	0.000	0.000	0.000
	('constrained')	mvOU1	–	–	0.000	0.000	0.000
		mvOU2	–	–	1.000	1.000	1.000
Univariate	**Convergence**	BM1	0.087	0.051	0.000	0.000	0.000
(via *OUwie*)		OU1	0.032	0.022	0.000	0.000	0.000
		OU2	0.045	0.023	0.000	0.000	0.000
		OU2A	0.024	0.010	0.001	0.000	0.000
		OU2V	0.038	0.040	0.000	0.000	0.000
		OU2VA	0.773	0.854	0.999	1.000	1.000
	Divergence	BM1	–	–	0.000	0.000	0.000
	('constrained')	OU1	–	–	0.000	0.000	0.000
		OU2	–	–	0.000	0.000	0.000
		OU2A	–	–	0.105	0.079	0.214
		OU2V	–	–	0.046	0.000	0.000
		OU2VA	–	–	0.849	0.921	0.786

492   Our model-fitting analyses mimic an empirical scenario in which researchers test an *a*

priori hypothesis that specific focal taxa (i.e., 'gliders'; *sensu* Grossnickle et al. 2020) are

494   converging on an adaptive peak. We assigned 'gliders' to one selective regime and 'non-gliders'

to a second regime, and then used model support for multiple-regime OU models as evidence

496   for convergence on adaptive peaks (Fig. 1B). In this type of analysis, support for multiple-regime

OU models could suggest that the focal lineages (assigned to a single regime) have convergently

498   shifted toward a shared adaptive peak for that regime. This procedure is prevalent in the

literature (e.g., Collar et al. 2014, Friedman et al. 2016, Baliga and Mehta 2018, Grossnickle et

500   al. 2020, Rincon-Sandoval et al. 2020, Law 2022), although other studies assess convergence

using model-fitting procedures without *a priori* regime assignments (e.g., Ingram and Mahler

502   2013, Khabbazian et al. 2016), which are not examined here.

    The simulated datasets include lineages evolved by both BM ('non-gliders') and a mix of

504   OU and BM processes ('gliders'; two traits BM-evolved and four traits OU-evolved). Therefore,

we do not expect any of the tested multivariate *mvMORPH* models (mvBM1, mvOU1, mvEB,

506   mvOU2) to be good fits because they do not include a mix of BM and OU processes. Although

OUwie models are expected to provide relatively better fit by allowing a greater number of

508   parameters to vary between regimes, their limitation to only univariate data means they cannot

model our full dataset (instead PC1 scores were used).

510   For convergence simulations, univariate OU model-fitting analyses (i.e., those using

OUwie models) correctly identify convergence of focal lineages at any optima values (i.e., at any

512   position in morphospace): the OU2VA model is the best-fitting model to PC1 scores and it

allows the selection (α) and rate (σ^2) parameters to vary between regimes (Table 2). The results

514   correctly identify different underlying evolutionary processes for the two regimes, with 'gliders'

showing stronger evidence of convergence via an OU process (i.e., greater α values and smaller

516   σ^2 values than those of non-gliders). This highlights that evaluating parameter values of fitted

OU models can assist researchers in evaluating the strength of convergence (and overall fit of

518   the OU model; Boettiger et al. 2012, Ho and Ané 2014, Cooper et al. 2016, Grabowski et al.

2023), with stronger convergence expected to be reflected by relatively larger α values and

520   relatively smaller σ^2 values (e.g., Collar et al. 2014).

However, in multivariate model-fitting analyses (i.e., those using *mvMORPH* models),

522   where rate and attraction parameters cannot vary between regimes, mvBM1 out-performs

mvOU2 (suggesting a lack of convergence) when focal lineages converge on a morphology that

524   is similar to the ancestral morphology (i.e., in the middle of morphospace; Table 2). This is

expected because there was not a strong shift in morphology from the ancestral morphology,

526   but it highlights that researchers should use caution when applying model-fitting analyses to

scenarios in which focal lineages are not morphological outliers. Thus, we recommend including

528   models that allow all parameters to vary among regimes when testing for convergence,

because they are more likely to identify convergence when focal lineages converge on ancestral

530   morphologies.

Results for 'constrained divergence' simulations highlight a potential pitfall of the

532   assumption that model support for multiple-regime OU models is indicative of convergence

(Fig. 1B). Two-regime OU models (both multivariate and univariate) outperformed simpler,

534   single-regime models when fit to data in which lineages of both regimes ('gliders' and 'non-

gliders') are divergent (via 'constrained divergence' simulations; Table 2). In these simulations,

536   'gliders' do not evolve toward a shared optimum, and are in fact considerably divergent in

phylomorphospace (Fig. 3C). Further, 'non-gliders' evolved by BM, not an OU process. Thus,

538   taxa of neither selective regime are expected to be well-fit by an OU model, and yet the two-

regime OU models are substantially better fits to the data than other models (Table 2). In

540   univariate analyses, the best-fitting model is OU2VA, which allows α and σ² to vary between

'glider' and 'non-glider' regimes – this is the most appropriate model, considering the

542   generating processes of the simulations (i.e., divergent BM and OU processes). However,

OU2VA is still a multiple-regime OU model, and its performance could be interpreted as

544   evidence for the presence of two adaptive peaks, one for 'gliders' and one for 'non-gliders,'

even though lineages of each regime were not simulated as evolving toward regime-specific

546   adaptive peaks. This result is consistent with the model-fitting results of Collar et al. (2014) for

eel morphology – durophagous eels appear to be divergent in phylomorphospace, but OU

548   models with two regimes (i.e., durophagous and non-durophagous) were the best-fitting

models.

550   That the two-regime OU model is the best fit to divergence data, despite the

expectation that none of our fitted models fit the simulated data, may simply reflect that two-

552   regime OU models are the best-fitting of mostly bad-fitting models (with the univariate OUMVA

model as a possible exception for some simulated scenarios). Knowing the underlying processes

554   that generated the simulated data, we recognize that the multiple-regime OU models are a

poor representation of the data. Nonetheless, we are mimicking specific empirical scenarios in

556   which researchers use *a priori* regime assignments (e.g., based on shared gliding behavior) and

do not know the evolutionary processes that generated their trait data. Our results highlight

558   that even if multiple-regime OU models are best-fitting to data, it does not necessarily indicate

that the lineages of those regimes experienced convergence (as defined here).

560   Despite our results, we do not intend to discourage the use of OU model-fitting to test

for convergence; they offer a valuable complement or alternative to distance-based metrics.

562   Nonetheless, our results highlight that researchers should be cautious both when choosing

models to fit and when interpreting results, especially considering that empirical datasets often

564   include complex evolutionary patterns and small sample sizes, which could influence the fits of

OU models (Boettiger et al. 2012, Ho and Ané 2014, Cooper et al. 2016, Grabowski et al. 2023).

566   For robust tests of convergence using an OU-modeling approach, we recommend using models

that allow rate (σ^2) and attraction (α) parameters to vary between regimes (e.g., *OUwie*

568   models), with close examination of resulting parameter values. For example, in our univariate

model-fitting analyses, although two-regime models had the strongest support in all scenarios,

570   'glider' regimes of divergence simulations have considerably greater σ^2 values compared to

those of the 'glider' regimes of convergence simulations (Table S2). Thus, in empirical studies,

572   relatively elevated rates be indicative of very weak or no convergence among focal lineages.

       We also recommend fitting a broader set of models than those fitted here. For instance,

574   multiple-regime BM models that allow phylogenetic means to vary between regimes, which can

be fit using *mvMORPH* functions (Clavel et al. 2015; smean = "FALSE"), may offer more

576   appropriate null models than BM1, and they may complement multiple-regime OU models

(e.g., Law et al. 2018, Grossnickle et al. 2020, Martinez et al. 2020, Rincon-Sandoval et al. 2020).

578   Because these models do not model selection toward optima, support over OUM models may

suggest limited or no convergence among focal lineages (e.g., Grossnickle et al. 2020). Further,

580   models can be fit that allow for a shift in mode of evolution in focal clades or at a specific point

in time (Slater 2013, Clavel et al. 2015), and these may be especially appropriate when different

582   lineages are suspected to have evolved via different evolutionary processes, such as in our

simulated datasets, and/or when only one regime is expected to have undergone convergence

584   (reflected by a strong fit of an OU model). If sample size permits, researchers may also consider

fitting models that separate focal taxa into multiple regimes. Comparing support for these

586   models, relative to those uniting focal taxa into a shared regime, may aid in identifying false

positives like those observed in our simulated divergent datasets.

588   An additional OU model-fitting approach involves testing for convergent shifts toward

shared adaptive peaks without *a priori* regime classifications (e.g., using *SURFACE* functions,

590   Ingram and Mahler 2013; and *l1ou* functions, Khabbazian et al. 2016). We did not apply this

method because results are challenging to interpret across many simulated datasets, especially

592   when peak shifts are likely to be identified in BM-evolved taxa (Adams and Collyer 2018), and

our approach (using *a priori* regime classifications) may be more appropriate for testing specific

594   hypotheses for focal taxa. Nonetheless, this method provides a valuable research tool,

especially for exploratory convergence analyses or as a supplement to other convergence

596   measures (e.g., Rincon-Sandoval et al. 2020).

        To mimic empirical samples with focal lineages that share some similarities, our primary

598   divergence simulations (i.e., 'constrained divergence') partially constrained 'gliders' to one

region of morphospace by limiting the randomized optima to be positive values for four

600   divergent traits (the other two traits were BM-evolved and could be negative). This helps to

explain the relatively strong fits of the two-regime OU models to the simulated divergence

602   data. Because 'gliders' are shifting in similar directions (e.g., all divergent 'gliders' are in

negative PC2 space in Figure 3B), they may be modeled as evolving toward a broad adaptive

604   peak in one region of morphospace, especially because an OU process does not require that

        independent lineages shifting toward a peak come from more dissimilar ancestors. Figure 2B

606   provides a conceptual illustration of this scenario; focal lineages ('maroon') are diverging but

        still evolving toward a broad adaptive peak. Further, the eels examined by Collar et al. (2014)

608   may provide an empirical example of this scenario; durophagous eel lineages are

        morphologically divergent but appear 'constrained' to one region of morphospace, and a two-

610   regime OU model is best-fitting to durophagous and non-durophagous eels.

        For 'unconstrained divergence' simulations, 'gliders' diverged in all directions in

612   morphospace, and all convergence measures, including OU model-fitting analyses, correctly

        identified divergence (Supplemental Results; Table S3). Thus, the central issue for OU model-

614   fitting analyses (i.e., that multiple-regime OU models are best-fitting to divergent lineages) is

        likely limited to scenarios in which divergent focal taxa share some morphological similarities.

616   *Summary of issues with convergence measures.* All convergence measures correctly

        identified convergence among lineages simulated to be convergent (Tables 1 and 2, Figs. 3C and

618   5A), although results are often influenced by the positions of focal taxa in morphospace. *C*-

        measures, θ_{real}, and OU model-fitting analyses (especially those in which rate and attraction

620   parameters are constant among regimes) show stronger measures of convergence when focal

        taxa are morphological outliers. In contrast, the Wheatsheaf index shows weaker convergence

622   in outliers (Table 1). For divergence analyses, our most critical finding is that *C*-measures often

        misidentify divergent lineages as being convergent (Fig. 2B, Fig. 3C, Table 1). In addition, model

624   support for multiple-regime OU models, which is often interpreted as evidence for convergent

shifts toward shared adaptive peaks, should be considered with caution because in some

626   scenarios these models may be the best fits to divergent lineages (Table 2).

628   **Measuring convergence through time via *Ct*-measures**

Despite any shortcomings, *C*-measures have benefits over other convergence measures,

630   including being designed to distinguish between convergence and conservatism (Stayton

2015A). Thus, our objective is not to discourage the use of distance-based metrics like *C*-

632   measures but rather to identify issues and encourage the development of improved measures.

We address the *C*-measure issues by presenting novel distance-based convergence

634   measures that are derived from the *C*-measures. The new measures are calculated using the

same equations as those for *C*1–*C*4 (except with a change to *C*4; see Supplemental Methods),

636   but we limit candidate D_{max} measurements to distances between lineages at synchronous 'time

slices' coinciding with internal phylogenetic nodes (Fig. 4). We refer to the new measures as *Ct*-

638   measures and D_{max} as $D_{max.t}$ because time (*t*) is incorporated when measuring morphological

distances between lineages. *Ct*1 scores can be interpreted in the same way as *C*1 scores were

640   intended to be interpreted (Stayton 2015A): positive *Ct*1 scores represent a proportion of the

maximum morphological distance between lineages that has been closed by convergent

642   evolution, with *Ct*1 = 1 representing complete convergence. Like *C*-measures, statistical

significance for *Ct*-measures is based on comparison with expectations for evolution proceeding

644   entirely on a BM model, using simulations to generate the expectations.

Figure 4. Conceptual illustration of the $Ct1$-measure, which is calculated like $C1$ of Stayton (2015A) but candidate $D_{max.t}$ measurements are limited to 'time slices' at internal phylogenetic nodes. Plots on the right show the three candidate $D_{max.t}$ measurements and the distance between lineages at the tips (D_{tip}). The scenarios in A and B are the same as those in Figures 2A and 2B, respectively. In contrast to $C1$, $Ct1$ correctly identifies divergence in B (negative score). Although the $Ct1$ score in A is greater when lineages are outliers (0.4) versus non-outliers (0.3), the $Ct1$ scores are more similar to each than are the $C1$ scores in the same scenarios (0.7 versus 0.4; Fig. 2A), indicating that Ct-measures are less influenced by morphospace positions compared to C-measures.

By limiting candidate $D_{max.t}$ measurements to time slices, Ct-measures minimize the possibility of $D_{max.t}$ being erroneously inflated by divergent tips. This is conceptually illustrated in Figures 4A and 4B, showing the same scenarios as in Figures 2A and 2B. Whereas the $C1$ score in Figure 2B incorrectly indicates convergence (i.e., $C1$ is greater than zero), the $Ct1$ score in Figure 4B correctly indicates divergence (i.e., the value is negative).

The D_{tip} measurement has not been altered from its original implementation in C-

664 measures (Stayton 2015A) and is not limited to a synchronous time slice, thus allowing for D_{tip}

to be measured even when tips vary in geologic age (e.g., an extinct taxon and an extant taxon).

666 However, unlike C-measures, the Ct-measures do not allow $D_{max.t}$ to be measured between tips

(i.e., $D_{max.t}$ cannot equal D_{tip}). This results in divergent taxa having negative Ct scores (D_{tip} is

668 greater than $D_{max.t}$), whereas C-measures (as initially intended) measure divergent taxa as

having scores of zero (D_{max} equals D_{tip}). See the Supplemental Methods for more information on

670 the Ct-measures.

The Ct-measures include four new features to enhance functionality, which are available

672 via functions (*calcConvCt* and *convSigCt*) in version 2.0.1 of the *convevol R* package (Brightly and

Stayton 2023). First, Ct-measures can compare clades that contain multiple lineages, whereas

674 the original routines were limited to comparisons of individual lineages (Stayton 2015A). Clade

comparisons are enabled by 1) excluding pairwise comparisons between within-clade lineages

676 (e.g., two flying squirrel species) and 2) weighting of Ct scores and p-values based on the

number of pairwise comparisons between focal clades (see Supplemental Methods). Second,

678 Ct-measures can be measured using single traits (the original routines only permitted

multivariate analyses, although they were adapted for univariate analyses in some studies;

680 Spear and Williams 2020, Law 2022). Third, users can now specify ancestral states for

calculations of Ct scores. This is especially useful if a BM model (the default model for inferring

682 ancestral states) is expected to be a poor fit to the data, or if additional constraints should be

placed on the traits of interest (e.g., based on fossil evidence). Fourth, we updated the Ct4

684   calculation to better match the original description of that measure. See the Supplemental

Methods for additional information on these features.

686   We used an *R* script written by Jonathan S. Mitchell and published in Zelditch et al.

(2017) as a foundation for the updated functions. Run times for the revised *R* functions are

688   approximately ten times faster than the original functions of Stayton (2015A) when using our

datasets. We did not revise *C*5, which is a frequency-based convergence measure that tallies

690   the number of times lineages enter a region of morphospace (Stayton 2015A) because it is not

influenced by the issues highlighted here.

692   We have also developed a new *R* function, *plotCt*, that plots pairwise distances between

lineages through time. (These distances are also provided as an output of the *calcConvCt*

694   function.) This type of plot is illustrated conceptually (Fig. 4) and in two examples: simulated

'glider' lineages (Fig. 5B) and anole 'twig' ecomorphotype lineages (Fig. S7; Mahler et al. 2013).

696   These plots allow researchers to visualize when $D_{\text{max.t}}$ occurred during the evolutionary history

of focal lineages and may be useful for applications beyond convergence studies.

Figure 5. (*A*) *Ct*1 scores for simulated convergent and divergent lineages under varying evolutionary scenarios. See the Methods and Figure 3 caption for more information. Although in some cases the divergence *Ct*1 results are greater than zero (indicating convergence), these results were not statistically significant via simulation-based *p*-values for a subset of datasets (Table 1). *Ct*1 results are means and standard errors of 15 simulated datasets. (*B*) An example output from the *plotCt R* function that shows pairwise distances between lineages with time. Note that although only three 'glider' lineages are highlighted in the plot, five lineages were used for *Ct1* measurements.

We tested the performance of *Ct*-measures by applying them to the simulated datasets using the same methodology as that for *C*-measures. Unlike the *C*-measures (Fig. 3C), the *Ct*-measures do not consistently misidentify divergent lineages as being convergent (Figs. 5A and S3); most of the simulated divergence datasets exhibit *Ct*1 scores that are negative, correctly indicating divergence. Although in some cases the *Ct*1 score is greater than zero when applied

to divergence datasets (incorrectly indicating convergence; Fig. 5A), these $Ct1$ scores are not

716   statistically significant, which contrasts with the strongly significant $C1$ scores for divergence

simulations (Table 1). Further, the greater-than-zero $Ct1$ results could be due in part to

718   convergence occasionally occurring by chance in our simulated-divergence datasets (e.g., BM-

evolved 'glider' lineages evolving toward each other).

720   Although both $C1$ and $Ct1$ have a maximum value of one (complete convergence), the

two measures scale differently and thus their values should not be directly compared. For

722   instance, when applied to the 'constrained' divergence simulations, $C1$ = ~0.3 (Fig. 3C) and $Ct1$ =

~0 (Fig. 5A). Positive $C1$ values reflect both convergence and some degree of divergence (due to

724   the D_{max} issue highlighted in this study), and their values are expected to be greater than those

of $Ct1$ for the same scenario.

Relatively greater convergence in morphological outliers

728   Like C-measures and θ_{real}, the Ct-measure scores are often greater when focal lineages are

morphological outliers (Figs. 4A, 5A, and S8). This pattern is more pronounced in C-measures

730   compared to Ct-measures (Figs. 2A, 3C, and S8), likely due to the C-measure issues highlighted

in this study (Fig. 2). Further, this trend may occur in Ct-measures (despite the C-measure-

732   related issues being eliminated) when focal taxa evolve toward outlying regions of phenotypic

space, in which case the asynchronous origins of the clades could inflate the Ct-measures (see

734   the Supplemental Results and Figure S5 for an explanation of this issue). To help address this

issue for Ct-measures, we added an optional feature to the *calcConvCt* function that limits

736   candidate $D_{max.t}$ measurements to the time prior to the evolution of the focal lineages (e.g.,

prior to the evolution of the earliest glider clade). We recommend using this option as a

738   supplement to regular *Ct*-measures when focal clades have very different origination ages (see

Supplemental Results).

740   The trend of greater convergence in outliers largely disappears for *C*- and *Ct*-measures

when all six simulated traits are OU-evolved to trait optima (i.e., all six traits are convergent) –

742   the *C*1 and *Ct*1 values remain relatively constant at any optimum values (Figs. 3C and 5A).

Conversely, the trend is more distinct when a greater number of traits are BM-evolved. This

744   indicates that the pattern of greater convergence in outliers is influenced by the types of

simulated traits (BM-evolved or OU-evolved). We believe that trait type influences this pattern

746   because the relative amount of morphological evolution in OU-evolved traits (vs BM-evolved

traits) varies depending on the value of trait optima. For instance, when OU-evolved traits are

748   evolved toward optima near the ancestral morphology (i.e., toward zero), those traits may

undergo less morphological change relative to the BM-evolved traits. Thus, there is a relatively

750   greater influence of BM-evolved traits (i.e., divergent traits) on *C*- and *Ct*-measures at smaller

optima values, resulting in weaker convergence signals via *C*- and *Ct*-measures. Conversely, OU-

752   evolved traits (i.e., convergent traits) of outliers have undergone relatively greater

morphological change, evolving farther from the ancestral morphology, and therefore the

754   outlying OU-evolved traits have a relatively larger influence on *C*- and *Ct*-measures. This pattern

likely reflects empirical scenarios because the strength of natural selection is expected to vary

756   among traits (e.g., Grossnickle et al. 2020). Thus, when different traits have undergone varying

amounts of adaptive morphological change, researchers should expect to observe relatively

758   stronger evidence of convergence in outliers when using most convergence measures.

Empirical examples – *C*1 vs *Ct*1

In some cases, erroneous *C*-measure results may have led researchers to infer convergence in

lineages that are divergent or infer inflated degrees of convergence. For instance, Grossnickle

et al. (2020) tested for convergence among gliding mammal lineages using limb measurements

and recovered statistically significant *C*-measure scores, indicated strong convergence. But

considering the issues highlighted here, the strong *C*-measure scores in Grossnickle et al. (2020)

were likely inflated due to the outlying morphologies of some gliders (e.g., dermopterans)

because outliers produce greater *C* scores (Figs. 2A and 3C). This suggests that the gliders are

probably less convergent than the authors concluded. We applied *Ct*1 to the data from

Grossnickle et al. (2020), and in contrast to strong *C*1 scores, we found that all glider

comparisons have negative *Ct*1 scores, indicating divergence instead of convergence. In some

instances, *Ct*1 scores are only slightly negative and have significant p-values (e.g., *Ct*1 = -0.01

and $p < 0.01$ for the comparison of scaly-tailed squirrels and flying squirrels), which is congruent

with other lines of evidence explored in Grossnickle et al. (2020) that suggested glider limbs

experienced parallel evolutionary changes rather than convergence.

Huie et al. (2021) and Stayton (2015A; using data from Mahler et al. 2013)

independently analyzed *Anolis* lizard morphologies using distinct datasets and found that

ecomorphotypes with the greatest *C*1 scores are those in the outermost regions of

morphospace ('crown-giant,' 'grass-bush,' and 'twig'; see Figure 3 of Huie et al. 2021). The *C*1

values for these ecomorphotypes ranged from 0.31 to 0.43 in these studies, whereas other,

non-outlying ecomorphotypes had *C*1 values ranging from 0.09 to 0.25 (Stayton 2015A, Huie et

al. 2021). The relatively large $C1$ scores of outlying ecomorphotypes, in addition to the positive

782    $C1$ scores for all pairwise comparisons, may be due in part to the biases in the C-measures. We

applied Ct-measures to one of the outlying ecomorphotypes ('twig') from the anole dataset of

784   Mahler et al. (2013; ten standardized measurements of body dimensions). We found that,

although the overall $Ct1$ score was statistically significant, it was near zero (Table S1), in

786   contrast to the $C1$ score being 0.36 (Stayton 2015A). Interestingly, there was considerable

disparity in the pairwise Ct results for the five twig lineages, with $Ct1$ scores ranging from 0.346

788   (*A. paternus* vs. *A. valencienni*) to -0.763 (*A. occultus* vs. *A. paternus*) and six of ten pairwise

comparisons not significant. (See Figure S7 and Table S1 for full results and plotted pairwise

790   distances through time.) Thus, these results highlight not only the inflation of C scores among

outliers, but also the importance of considering individual pairwise comparisons when

792   evaluating convergence among multiple focal lineages.

794   **Ct-measures – recommendations and limitations**

In contrast to C-measures, the Ct-measures are influenced by the timing of evolutionary change

796   because they limit candidate $D_{max.t}$ measurements to specific time slices. This feature should be

considered when applying Ct-measures because it may alter expectations about the degree of

798   measured convergence. For instance, if different focal lineages evolve toward a specific

morphology (or adaptive peak) at different points in time, then the $D_{max.t}$ measurement may

800   not measure the morphologically farthest distances between the lineages, possibly resulting in

lower-than-expected Ct scores. Conversely, and as noted above, if focal taxa evolve toward

802   outlying regions of morphospace, then asynchronous origins of clades could inflate Ct-measure

scores (Supplemental Results; Fig. S5). To help mitigate this issue, we recommend assessing

804   phylomorphospace and distances-between-lineages-through-time plots, and comparing default

Ct results to those generated when using the alternative option of the $calcConvCt$ function that

806   limits candidate $D_{max.t}$ measurements to the period in which lineages of interest overlap in time

(see Supplemental Methods).

808   Ct-measures can be applied to taxa of varying geologic ages (if there is an internal node

for a $D_{max.t}$ measurement), but they may perform poorly when tips of focal taxa are very

810   different in geologic age because candidate $D_{max.t}$ measurements are restricted to the period of

evolutionary overlap among focal lineages. For instance, the evolutionary histories of

812   ichthyosaurs and dolphins overlap from their most recent common ancestor (early amniotes) to

the ichthyosaur tips, providing considerable time (more than 200 million years) for candidate

814    $D_{max.t}$ measurements. However, there are no candidate $D_{max.t}$ measurements between the

extinction of ichthyosaurs and the origin of extant dolphins (a period that includes most of

816   placental mammal history). If this is the period in which the ancestral dolphin lineages show the

greatest divergence from ichthyosaurs, then $D_{max.t}$ will not capture the maximum divergence of

818   the lineages, resulting in smaller-than-expected Ct scores. (Note that D_{tip} ignores time and

would measure the morphological distance between ichthyosaur and dolphin tips.) In these

820   types of cases, alternative methods for measuring convergence (e.g., OU model-fitting analyses)

may be more appropriate.

822   Restricting candidate $D_{max.t}$ measurements to coincide with internal nodes exacerbates

an issue inherent to many phylogenetic comparative methods: the reliance on inferred

824   ancestral states. $D_{max.t}$ is the critical value that enables the Ct-measures to diagnose

convergence, and it is drawn entirely from ancestral state data, which, by default, are

826   estimated from tip values assuming a BM model of evolution (although users may specify

ancestral states obtained by other means). Thus ancestral reconstructions likely reflect average

828   morphologies of the sampled taxa, decreasing the chance of measuring convergence via the Ct-

measures because $D_{max.t}$ estimates may be artificially shorter than the 'real' $D_{max.t}$ values. We

830   tested this issue by applying $Ct1$ (and $C1$) measures to simulations in which we used the

generated ('true') ancestral traits, and comparing them to scores obtained using the default BM

832   ancestral state reconstructions and those obtained via alternate methods. $Ct1$ scores are

consistently greater when 'true' ancestral states are used in calculations (Fig. S8), suggesting

834   the convergence signal of Ct-measures might often be diluted due to the assumption of a BM

model of evolution. Although different methods for inferring ancestral state values may

836   outperform BM, of those we tested, none consistently reproduced the "true" $Ct1$ scores (Fig.

S9). This issue is likely exacerbated when there are relatively few intervening nodes between

838   focal lineages (i.e., there are few candidate $D_{max.t}$ measurements), when focal lineages are

subtended by long branches (i.e., limiting $D_{max.t}$ to deeper nodes), and when using extant-only

840   samples (i.e., there is a lack of fossil data informing ancestral node reconstructions). Therefore,

Ct-measures may be most appropriate for well-sampled study systems that include a

842   substantial number of internal nodes and relatively few long branches, and researchers should

include fossil taxa whenever possible.

844   The number of phenotypic traits used to assess convergence can influence Ct scores. In

multivariate datasets, some traits may be convergent and others non-convergent (i.e.,

846   divergent, parallel, or conservative). While including a greater number of non-convergent traits

in analyses is expected to decrease the overall convergence signal of any convergence measure,

848   it may also exacerbate *Ct*-related issues raised in this section. In general, adding traits increases

the measured distances between tips and internal nodes. However, ancestral inference via BM

850   tends to average variation at internal nodes; thus, D_{tip} typically increases at a higher rate than

$D_{max.t}$ for each non-convergent trait that is added to a dataset. This pattern is illustrated in

852   Figure S6, highlighting that increasing the number of simulated BM-evolved traits (expected to

be mostly divergent) results in relatively greater increases of D_{tip} scores compared to $D_{max.t}$

854   scores. Thus, an increased number of traits in analyses (with all else equal) could result in a

relative decrease in *Ct* scores compared to datasets with fewer traits. We recommend choosing

856   traits based on the specific hypothesis being tested (e.g., functional morphological traits that

are linked to ecological or behavioral traits of interest) and analyzing individual traits or subsets

858   of traits whenever feasible to tease apart unique patterns among traits.

Given the issues with convergence measures, how should researchers interested in

860   convergence proceed? In general, we believe the newly described *Ct*-measures are the

preferred option among distance-based convergence measures, in part because they are largely

862   robust to the biases discussed in this study and can distinguish convergence from conservatism.

However, *Ct*-measures may not be ideal in all scenarios, such as when lineages are of very

864   different geologic ages, and alternative methods, including OU model-fitting analyses, may be

more appropriate. Further, in cases in which researchers are interested in comparing the

866   degree of similarity among focal taxa, regardless of the mechanism in which lineages evolved

similarities (conservatisms, convergence, or parallelism), then alternative geometric methods

868   such as Wheatsheaf index and θ_{real} may be more informative. The OU-approach may be ideal

when researchers are interested in the underlying strength of selection that may be driving

870   convergent change, rather than simply measuring convergence. Nonetheless, for OU model-

fitting analyses to indicate convergence, the available evidence should go beyond support for a

872   multiple-regime OU model. For instance, researchers should include appropriate null models

and examine model parameters for evidence of convergence (e.g., a relatively strong α value is

874   more likely to reflect convergence). Finally, for exploratory analyses of convergence, we

recommend researchers implement multiple convergence measures.

Summary

878   *C*-measures are a popular means of identifying and quantifying phenotypic convergence, in part

because they can differentiate between convergence and conservatism. However, we highlight

880   a critical issue: *C*-measures can misidentify divergent lineages as convergent (Figs. 2 and 3,

Table 1). Thus, we developed improved convergence measures (*Ct*-measures) that quantify

882   distances between lineages at time slices at internal phylogenetic nodes, minimizing the

possibility of divergent taxa being mistakenly measured as convergent. We also developed new

884   features (available in the updated *convevol R* package; Brightly and Stayton 2023), such as a

function to plot distances between lineages through time. Although *Ct*-measures improve on *C*-

886   measures, they have limitations. For instance, *Ct*-measures may be unreliable if convergent

evolutionary change is asynchronous between lineages of interest (e.g., fossils of very different

888   geologic ages). More broadly, we find that multiple methods (including *Ct*-measures) are biased

by the location of taxa in phenotypic space, with most methods measuring greater convergence

890   in phenotypic outliers. OU model-fitting analyses are a valuable tool for investigating

convergence, but we urge caution when applying and interpreting their results. Model support

892   for multiple-regime OU models is not always indicative of convergent shifts toward shared

adaptive peaks (Table 2). Because all available convergence measures are imperfect,

894   researchers should consider the benefits and drawbacks of various measures when choosing

methods and interpreting results.

DATA ARCHIVING

Upon publication, all simulated datasets will be archived in Dryad (https://doi.org/XXXXXXX).

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