Large differences in target-flanker depth increase crowding-evidence from a multi-depth plane display

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Abstract

Crowding occurs when the presence of nearby features causes highly visible objects to become unrecognizable. Although crowding has implications for many everyday tasks and the tremendous amounts of research reflect its importance, surprisingly little is known about how depth affects crowding. Most available studies show that stereoscopic disparity reduces crowding, indicating that crowding may be relatively unimportant in three-dimensional environments. However, most previous studies tested only small stereoscopic differences in depth in which disparity, defocus blur, and accommodation are inconsistent with the real world. Using a novel multi-depth plane display, this study investigated how large (0.54 - 2.25 diopters), real differences in target-flanker depth, representative of those experienced between many objects in the real world, affect crowding. Our findings show that large differences in target-flanker depth increase crowding, contrary to previous work showing reduced crowding in the presence of small depth differences. Furthermore, when the target was at fixation depth, crowding was more pronounced when the flankers were behind the target as opposed to in front of it. However, when the flankers were at fixation depth, crowding was more pronounced when the target was behind the flankers. These findings suggest that crowding from clutter outside the

23 limits of binocular fusion can still have a significant impact on object recognition and visual

24 perception in the peripheral field.

Introduction

Visual crowding is a phenomenon in which a peripherally viewed object, that is easily

identifiable in isolation, becomes harder to recognize or identify when it is surrounded by other

objects, despite still being clearly visible (Bouma, 1970; Herzog et al., 2015; Levi, 2008; Pelli,

2008; Whitney and Levi, 2011). The importance of crowding is reflected by the tremendous

amount of research on the topic and it has been extensively reviewed over the years (e.g., Coates

et al., 2021; Herzog et al., 2015; Manassi and Whitney, 2018; Pelli, 2008; Strasburger et al.,

2011; Whitney and Levi, 2011). This high level of interest is not surprising given that the natural

environment is usually cluttered and mostly viewed in the peripheral visual field. Consequently,

it is assumed that crowding has a large impact on our daily lives with implications for many

everyday visual tasks including driving (Xia et al., 2020), reading (Legge, 2007) and face

recognition (Kalpadakis-Smith et al., 2018; Louie et al., 2007). Crowding also has important

clinical implications for people with glaucoma (Ogata et al., 2019; Shamsi et al., 2022), as well

as for other disorders including central vision impairment (e.g., macular degeneration),

amblyopia and dyslexia (Whitney and Levi, 2011). Through this body of research, we have been

able to build a good understanding of the factors that mediate and moderate crowding and

develop unifying theories (e.g., Balas et al., 2009; Harrison and Bex, 2015; Keshvari and

Rosenholtz, 2016; van den Berg et al., 2012, 2010). However, despite the large body of

literature, one area that remains surprisingly understudied is how depth affects crowding. This is

important because we live in a three-dimensional environment and so to understand the

significance of crowding in the real world it is essential to understand the role of depth

information.

Kooi et al. (1994) were the first to investigate how depth influences crowding. The

authors found that compared to when a peripheral target and flankers were at the same depth,

there was a release from crowding when the target and flankers were stereoscopically presented

in crossed (front) and uncrossed (behind) disparities (Kooi et al., 1994). Sayim et al. (2008)

found that when flankers were at fixation depth, there was less foveal crowding when the target

was stereoscopically presented in front or behind the flankers. Felisberti et al. (2005) also found

an effect of depth on crowding in the parafovea, but to a more limited extent. They reported a

release from crowding in two out of three subjects when the target appeared behind the flankers,

but only in one of the three subjects when the target was in front of the flankers (Felisberti et al.,

2005). Astle et al. (2014) extended on previous research by testing the effect of depth on

crowding over a range of stereoscopically produced target-flanker disparities (±800 arcsec). In

line with previous studies, Astle et al. (2014) found that when the target was at fixation depth,

increasing target-flanker disparity systematically reduced crowding. They also found that the

release from crowding was asymmetric whereby crowding was greater when the flankers were in

front of the target compared to behind it (Astle et al., 2014).

Taken together these studies appear to paint the picture that a difference in depth between

a target and flankers reduces crowding. This could challenge the concept that crowding is

ubiquitous in three-dimensional natural environments (Whitney and Levi, 2011) because it

implies that depth differences between natural objects could prevent crowding from being a

problem (Figure 1). However, all the above studies tested only small depth differences between

target and flankers that do not reflect the often-large differences in depth between objects in the

real world. Furthermore, the generalizability of these studies to real world depth is also limited

by the fact that depth cues were generated stereoscopically. One potential problem with stereo

displays is that disparity information often does not match with accommodation or defocus blur

which can detrimentally affect depth perception (Hoffman et al., 2008; Watt et al., 2005).

Figure 1: Example of crowding in a simulated everyday scene. (A) When fixating on the red dot above
the horizon, it is relatively easy to spot and recognize the person crossing on the right. However, it is
more difficult, or impossible, to recognize the person about to cross the road on the left because of the
presence of nearby signs. Images like this one are often used to illustrate how crowding is ubiquitous in
everyday natural scenes. **(B)** However, in real life the two signs and the person on the right may be

several meters apart and so each would appear at a different depth from the observer. Currently, little is

known about how large, real differences in depth between objects affects crowding. See

acknowledgments for image attributions.

To our knowledge, four studies have investigated the effect of depth on crowding using a

real depth display. All four studies used two orthogonally positioned screens viewed through a

half-transparent mirror allowing stimuli to be displayed on two different depth planes

simultaneously (Eberhardt et al., 2021; Eberhardt and Huckauf, 2019, 2017, 2020). Eberhardt

and Huckauf (2017) kept a target and flankers at the same depth and presented them 0.06

diopters (i.e., 1/focal length in meters), in front, behind or at the same depth as fixation. The

authors found that this small difference in depth between the stimuli and fixation planes had no

effect on the amount of crowding compared to when everything was presented at the fixation

plane (Eberhardt and Huckauf, 2017). Eberhardt and Huckauf (2019) repeated and expanded on

this work with the addition of a ± 0.1 diopter depth difference between fixation and the stimuli in

addition to the ± 0.06 diopter condition. The results showed that crowding was greater when the

stimuli were furthest from fixation compared to when they were closer to fixation, regardless of

whether the stimuli were in front or behind the fixation plane (Eberhardt and Huckauf, 2019).

More recently, Eberhardt and Huckauf (2020) used the same approach to investigate the effect of

depth on crowding when the target and flankers were separated in depth. When flanker depth

was varied while the target was at fixation depth, crowding increased with increasing target-

flanker depth difference (Eberhardt and Huckauf, 2020). This result is the opposite to the

findings of other studies in which small differences in depth between the target and flankers were

introduced with stereoscopic disparity (Astle et al., 2014; Felisberti et al., 2005; Kooi et al.,

1994; Sayim et al., 2008). Furthermore, the authors also found that when flanker depth was

varied while the target was at fixation depth, crowding was greater when the flankers were

behind the target and fixation compared to in front of it (Eberhardt and Huckauf, 2020). When

target depth was varied while the flankers were at fixation, there was more crowding when the

target was in front of the flankers and fixation compared to when it was behind them (Eberhardt

and Huckauf, 2020).

In light of the above discrepancies, and the prevalence of depth information in real world

scenes, there is a pressing need for a better understanding of how visual crowding is affected by

depth differences representative of those experienced between objects in the real world.

Therefore, using a novel multi-depth plane display consisting of screens at 0.4 m, 1.26 m, and 4

m viewing distances, we investigate how crowding is affected by large, real differences in target-

flanker depth.

Methods

Subject recruitment

A total of 110 naïve subjects were recruited from the Northeastern University undergraduate

population in exchange for course credit as compensation for their time. Of these, seven were

excluded immediately following screening because they did not meet the inclusion criteria of

normal or corrected-to-normal vision. An additional five subjects were excluded because of

issues with the experimental code (N=3), calibration issues (N=1) or because they did not follow

the task instructions (N=1). Thus, a total of 98 subjects (32 males, 66 females; mean age = 18.86

years) contributed usable data across five separate experiments (22 in Experiment 1, 19 in

Experiment 2, 21 in Experiments 3 and 4, and 15 in Experiment 5). All subjects read and signed

an informed consent form approved by the Northeastern University Ethics Board before the

experiment began. The experimental procedure was approved by the institutional review board at

Northeastern University, and the experiments were performed in accordance with the tenets of

the Declaration of Helsinki.

Setup

We developed a multi-depth plane display consisting of three screens at 0.4 m (near screen), 1.26

m (mid screen) and 4 m (far screen) from the observer (Figure 2). These distances were chosen

because 4 m is close to optical infinity while 0.4 m is the clinical standard for near distance, with

1.26 m being in the middle of these two extremes in log units. Given in diopters, the near, mid,

and far screens were at 2.5 diopters, 0.79 diopters and 0.25 diopters receptively. For the far

screen we used an ultra-short throw projector (Bomaker Polaris 4K Laser Projector) projected

onto a 240 cm x 250 cm white wall at the end of the room. The mid and near screens were made

from 101.5 cm x 76 cm and 46 cm x 36.5 cm clear 5 mm acrylic respectively held in position by

a frame constructed from extruded aluminum rails. The transparent acrylic was covered on one

side with ClearBright transparent display film (Lux Labs Inc., Boston, MA, USA). This

nanoparticle film enabled us to display images from two projectors (InFocus IN3116) onto the

near and mid screens while preserving their transparency (Hsu et al., 2014), thus allowing

observers to simultaneously view adjacent stimuli presented on all three depth planes at the same

time. The screens were temporally synchronized and spatially aligned to ensure display timing

and position were consistent across the three depth planes. All experiments were conducted in

Python using PsychoPy (v2021.2.3) (Peirce et al., 2019).

Figure 2: Illustration of the multi-depth plane display setup used for this study.

Spatial calibration

Each observer performed a subjective spatial calibration at the start of Experiments 1-4 to ensure

that the angular positions of the stimuli and fixation point relative to primary gaze were the same

(or as close as realistically possible) across all three depth planes. The center of the far screen

(which was at primary gaze when the observers head was positioned in the chin and head rest)

was used as the fixed reference against which all three screens were calibrated. With their head

in the chin and head rest, observers were instructed to sequentially position a series of targets so

that they were in the same position as a fixed reference target that was displayed on the reference

screen. The calibration was performed under monocular conditions using the observer's

dominant eye as determined by the Miles test (Miles, 1929). The calibration was performed

monocularly because during a preliminary experiment subjects reported finding the task too

difficult to complete under binocular conditions (e.g., because of diplopia, an issue that is

considered further in the Discussion section). For Experiment 5, the spatial calibration was

performed by the experimenter prior to the experiment using a webcam positioned at the

observer's cyclopean point. The main experiment was conducted under binocular viewing

conditions and observers were asked to maintain the same head position within the chin and head

rest throughout the experiment.

Stimuli and experimental conditions

The target and flankers were inspired by those used in previous studies (Harrison and Bex, 2017,

2015). The target was a white Landolt-C displayed against a black background at 10˚ eccentricity

to the right or left of the fixation point at primary gaze. Following the structure of a Landolt-C

optotype, the target was 1˚ in diameter with a 0.25˚ line width and a 0.25˚ opening. The opening

orientation of the target was random each trial, drawn from a uniform 360˚ distribution. The

target was surrounded by a white flanker ring formed of four circular arcs (Figure 3). In each

depth combination described below, the outer edge of the target was separated from the inner

edge of the flanker ring by 5˚, 2.5˚, 1.25˚ or 0.625˚. These distances of separation represented

1/2, 1/4, 1/8 and 1/16 of the target eccentricity respectively. The line width and size of the four

gaps in the flanker ring were kept constant (0.25˚). For each target depth, a control condition

with no flanker ring was also included. The fixation point consisted of a 1˚ white circle with a

black cross (Figure 3). This design was used because it has been reported to elicit more stable

fixation compared to a plain circle or cross hair alone (Thaler et al., 2013). The background on

all screens was always set to the lowest RGB (i.e. R=G=B=0) value which was transparent on

the near and mid screens, and black on the far screen. Since the mid screen was dimmest

(R=G=B=255, white=13.56 cd/m^2), the luminance of stimuli displayed on the near and far

screens were calibrated to match the luminance of the mid screen using a Photo Research PR-

650 spectroradiometer (Photo Research, Chatsworth, CA, USA). The room lights were switched

off for the duration of the experiment.

Figure 3: Schematic illustration of experimental stimuli and fixation marker. In all conditions, except the
no-flanker condition, the randomly orientated target (a white Landolt-C) was surrounded by a white
flanker ring at one of four possible target-flanker distances. The stimuli were viewed against a black
background.

A summary of the stimulus conditions tested in each experiment is provided in Table 1.

Briefly, in Experiments 1 and 2 the target was always presented at fixation depth while the depth

of the flanker was varied. In Experiment 1 the target and fixation point were always on the mid

screen while each flanker was displayed in front, behind or at fixation depth. In Experiment 2 the

target and fixation point were presented on the near or far screen while the flanker was presented

at one of the three depths across trials for each fixation distance. Experiments 3 and 4 were the

same as Experiments 1 and 2 except that the flanker ring was presented at fixation depth while

the target depth was varied. In Experiment 3, the flanker and fixation point were always on the

mid screen while the target was displayed on one of the three depth planes across trials. In

Experiment 4, the flankers and fixation point were presented on the near or far screen while the

target was presented at each of the three depths across trials for each fixation distance. For

Experiment 5, the target, flanker ring and fixation were presented together on the same screen at

three different depths. This was to investigate whether there was an effect of absolute viewing

distance on crowding. Each condition was repeated 10 times in Experiments 1, 2, 3 and 5 and

eight times in Experiment 4, with equal number of repeats on either side of the fixation point.

The order of testing was randomized.

227 **Table 1:** Summary of the stimulus conditions in each experiment. The same color scheme is used to
228 represent the near (0.4 m), mid (1.26 m) and far (4 m) screens throughout the manuscript. Note that for
229 target-flanker spacing, 'infinity' = no flanker ring.

Experiment	Fixation depth (m)	Target depth (m)	Flanker depth (m)	Target-flanker spacing (degrees)	No. of stimulus conditions	Total no. presentations	Sample size
Exp 1	Mid (1.26)	Mid (1.26)	Near (0.4)	0.625°, 1.25°, 2.5°, 5°	13	130 (10 reps per stimulus)	N = 22
	Mid (1.26)	Mid (1.26)	Mid (1.26)	0.625°, 1.25°, 2.5°, 5°, infinity			
	Mid (1.26)	Mid (1.26)	Far (4)	0.625°, 1.25°, 2.5°, 5°			
Exp 2	Near (0.4)	Near (0.4)	Near (0.4)	0.625°, 1.25°, 2.5°, 5°, infinity	26	260 (10 reps per stimulus)	N = 19
	Near (0.4)	Near (0.4)	Mid (1.26)	0.625°, 1.25°, 2.5°, 5°			
	Near (0.4)	Near (0.4)	Far (4)	0.625°, 1.25°, 2.5°, 5°			
	Far (4)	Far (4)	Near (0.4)	0.625°, 1.25°, 2.5°, 5°			
	Far (4)	Far (4)	Mid (1.26)	0.625°, 1.25°, 2.5°, 5°			
	Far (4)	Far (4)	Far (4)	0.625°, 1.25°, 2.5°, 5°, infinity			
Exp 3	Mid (1.26)	Near (0.4)	Mid (1.26)	0.625°, 1.25°, 2.5°, 5°, infinity	15	150 (10 reps per stimulus)	N = 21
	Mid (1.26)	Mid (1.26)	Mid (1.26)	0.625°, 1.25°, 2.5°, 5°, infinity			
	Mid (1.26)	Far (4)	Mid (1.26)	0.625°, 1.25°, 2.5°, 5°, infinity			
Exp 4	Near (0.4)	Near (0.4)	Near (0.4)	0.625°, 1.25°, 2.5°, 5°, infinity	30	240 (8 reps per stimulus)	N = 21
	Near (0.4)	Mid (1.26)	Near (0.4)	0.625°, 1.25°, 2.5°, 5°, infinity			
	Near (0.4)	Far (4)	Near (0.4)	0.625°, 1.25°, 2.5°, 5°, infinity			
	Far (4)	Near (0.4)	Far (4)	0.625°, 1.25°, 2.5°, 5°, infinity			
	Far (4)	Mid (1.26)	Far (4)	0.625°, 1.25°, 2.5°, 5°, infinity			
	Far (4)	Far (4)	Far (4)	0.625°, 1.25°, 2.5°, 5°, infinity			
Exp 5	Near (0.4)	Near (0.4)	Near (0.4)	0.625°, 1.25°, 2.5°, 5°, infinity	15	150 (10 reps per stimulus)	N = 15
	Mid (1.26)	Mid (1.26)	Mid (1.26)	0.625°, 1.25°, 2.5°, 5°, infinity			
	Far (4)	Far (4)	Far (4)	0.625°, 1.25°, 2.5°, 5°, infinity			

An example trial is illustrated in Figure 4. Briefly, at the start of each trial, observers

were instructed to focus on the central fixation point. The fixation point appeared on the fixation

screen 1 sec before stimulus onset in Experiments 1, 3 and 5, and 1.5 sec before stimulus onset in

Experiments 2 and 4. The fixation point was displayed for slightly longer before stimulus onset

in Experiments 2 and 4 to ensure that observers had adequate time to refocus on the fixation

point when it switched between the near and far screens. The target and flanker ring (if present)

were displayed for 0.25 sec. The fixation point remained on the screen for 1 sec before being

replaced by a randomly oriented Landolt-C that was the same size as the target Landolt-C. The

observer used the mouse to rotate this Landolt-C until it matched the perceived orientation of the

target and then clicked to report the orientation.

Due to the nature of the experimental set up, and the large distances being tested, it is

possible that head movements, diplopia, or local suppression (see Discussion) could have

resulted in differences in the perceived position of the target relative to the flanker ring.

Therefore, in all experiments except Experiment 5, observers were also asked to report the

perceived location of the target relative to the position of the flanker ring. There were 5 options

to choose from, "target in center of ring", "target inside ring but not in the center", "ring

obstructs target", "target outside ring", and "unsure or no ring". Observers were instructed to

select the option that most closely matched how they perceived the stimulus. If an observer

missed the stimulus or they were unsure of the targets' location relative to the flanker ring, e.g.,

because of confusion caused by diplopia, they were instructed to select the "unsure or no ring"

option. Collecting data on the perceived target-flanker location enabled us to examine how

difference in target-flanker depth influenced the perception of the stimulus and investigate the

potential effect that factors such as target misalignment and possible diplopia may have had on

perceptual error (see Discussion). Following this selection, the next trial started immediately.

Before starting an experiment, all participants underwent training during which they

completed as many practice trials as they needed to familiarize themselves with the task. The

main experiment only began once the researcher running the study was confident that the

participant understood the task and were able to perform it correctly. These practice trials did not

contribute to the collected data.

Figure 4: A step-by-step example of a single trial. Note that in the actual experiments a text description of each of the five options in step five was also included within the option boxes. The text descriptions for the different options were: "Target in center of ring" (top left), "Target inside ring but NOT in the center" (top right), "Ring obstructs target" (middle left), "Target outside ring" (middle right), and "Unsure or no ring" (bottom center). Step five was not included in Experiment 5 as all parts of the stimulus were always presented at the same depth.

Data processing and statistical analysis

<u>Perceptual error</u>

To quantify crowding for each stimulus condition we first calculated the report error for each presentation, i.e., the angular difference between the reported gap orientation of the target and the actual gap orientation. For each subject, this generated 10 report errors per stimulus condition in Experiments 1, 2, 3 and 5, and eight per stimulus condition in Experiment 4. We then used these report errors to calculate the circular standard deviation for each stimulus condition using

the Circular Statistics Toolbox (Berens, 2009) in MATLAB R2022a (MathWorks Inc., Natick,

MA, USA). We refer to this measure as perceptual error, which is reported in degrees.

The effect of target/flanker depth and target-flanker spacing on perceptual error was

analyzed using mixed effects multiple linear regression, fitted using the lme4 package (Bates et

al., 2015) in R (R Core Team, 2022). Perceptual error was used as the response (dependent)

variable after being natural log transformed to correct for positive skew. For all five experiments,

we included target-flanker spacing as a fixed effect. We also included flanker depth for

Experiments 1 and 2, target depth for Experiments 3 and 4 or target-flanker-fixation depth for

Experiment 5. Target-fixation depth or flanker-fixation depth were also included as a third fixed

effect for Experiment 2 and 4 respectively. All possible pairwise interactions of fixed effects

were fitted in the full model. Subject identification (ID) was included as a random effect in all

experiments to control for repeated measures. We first used model simplification, whereby

models were compared with one another using a likelihood ratio test (LRT), to remove non-

significant interactions sequentially. This enabled us to test the effect of individual fixed effects

that were not involved in an interaction. We then used the minimum model (i.e., model

containing all fixed effects of interest plus any significant two-way interactions) to report the

significance of each main effect or significant interaction(s) by using a LRT to compare the

minimum model with the same model but with the effect/interaction of interest removed.

Individual main effects that were part of a significant interaction where not tested in this way

because their effect was dependent on another variable. Note that data for the control condition

(i.e., no flanker ring) were excluded from statistical analysis. This was to ensure that a) the fixed

effects remained independent and b) the effect of having no flanker ring did not mask the effect

of flanker and target depth.

<u>Perceived target position relative to flanker ring</u>

We used the observers' perceived target position relative to the flanker ring to calculate the

proportion of trials in which observers reported seeing the target inside the flanker ring (i.e., they

chose either "target in center of ring" or "target inside ring but not in the center"). For statistical

analysis, these data were treated as a binary response variable whereby trials in which observers

reported seeing the target inside the flanker ring were assigned a value of 1 while all other trials

(i.e., those for which the observer chose "ring obstructs target", "target outside ring" or "unsure

or no ring") were assigned a value of 0.

These data were then analyzed using mixed effects binary logistic regression, fitted using

the lme4 package (Bates et al., 2015) in R (R Core Team, 2022). We used the DHARMa package

(Hartig, 2022) to run residual diagnostics that are often overlooked in logistic regression.

Perceived target position was used as the binary response variable (i.e., 1 = target inside ring and

0 = target not inside ring). The fixed effect, and pairwise interaction for each experiment were

the same as those described above for the analysis of perceptual error. Subject ID was included

as a random effect in all experiments to control for repeated measures. Model simplification (to

remove non-significant interactions) and significance testing was the same as described above

for the analysis of perceptual error. Data for the control condition (i.e., no flanker ring) were

excluded from statistical analysis for the same reasons as those outlined above. The separate

results showing the number of times observers chose each of the five choices for perceived target

position relative to the flanker ring can be found in Supplementary Figures S1-S4.

Results

Perceptual error

<u>Target always at fixation depth with variable flanker depth</u>

Experiment 1: Target and fixation at 1.26 m with flanker ring presented at each depth

(Figure 5A). Perceptual error was higher when the flanker ring was displayed in front of, or

behind, the target and fixation plane (mixed effects multiple linear regression models compared

via LRT for effect of flanker depth: $\chi^2_{(2)} = 20.67$, p <0.001). As expected, perceptual error

decreased as target-flanker spacing increased (effect of target-flanker spacing: $\chi^2_{(1)} = 31.71$, p

<0.001). There was no significant interaction between flanker depth and target-flanker spacing

($\chi^2_{(2)} = 5.56$, p=0.062).

Experiment 2: Target and fixation at 0.4 m or 4 m with flanker ring presented at each

depth (Figure 5B). Perceptual error tended to increase with increasing flanker depth when the

flanker ring was behind the target and fixation plane, however, the effect of flanker depth was

much weaker when the flanker ring was in front of the target and fixation (interaction between

target-fixation depth and flanker depth: $\chi^2_{(2)} = 17.18$, p<0.001). Perceptual error decreased with

increasing target-flanker spacing, in a manner corresponding to target-fixation depth (interaction

between target-flanker spacing and target-fixation depth: $\chi^2_{(1)} = 9.2$, p=0.002). There was no

significant interaction between target-flanker spacing and flanker screen and ($\chi^2_{(2)} = 4.52$,

p=0.104).

Figure 5: Perceptual error results for Experiments 1 (A) and 2 (B) in which flanker depth was varied while the target was always at fixation depth. Box plots show medians plus the interquartile range (IQR), whiskers are the lowest and highest values that are within 1.5 times the IQR from the upper and lower quartiles. Points show the perceptual error for each individual observer. The visual aid below each graph shows the depth of the flanker ring (based on the same color key as the box plot) relative to the depth of the fixation point and target (shown in black) for each stimulus condition. The relative sizes of, and distances between, the fixation point, target, and flanker ring are to scale. Note that the fixation point is only shown for the 0.625° target-flanker spacing due to limited space within the figure.

<u>Flanker ring always at fixation depth with variable target depth</u>

Experiment 3: Flanker ring and fixation at 1.26 m with target presented at each depth

(Figure 6A). Overall, perceptual error was higher when the target was displayed in front of, or behind, the flanker ring and fixation (effect of target depth: $\chi^2_{(2)} = 36.93$, p <0.001), with the greatest perceptual error occurring when the target was behind the flanker ring and fixation. Perceptual error decreased as target-flanker spacing increased (effect of target-flanker spacing: $\chi^2_{(1)} = 45.99$, p <0.001). There was no significant interaction between target depth and target-flanker spacing ($\chi^2_{(2)} = 3.55$, p=0.17).

364 **Experiment 4: Flanker ring and fixation at 0.4 m or 4 m with target presented at each**

365 **depth (Figure 6B).** Perceptual error was greatest when the target was displayed behind the

366 flanker ring and fixation, while the effect of depth was less prominent when the target was

367 displayed in front of the flanker ring and fixation (interaction between flanker-fixation depth and

368 target depth: $\chi^2_{(2)} = 61.87$, p<0.001). Perceptual error decreased as target-flanker spacing

369 increased (effect of target-flanker spacing: $\chi^2_{(1)} = 29.92$, p<0.001). There was no significant

370 interaction between flanker-fixation depth and target-flanker spacing ($\chi^2_{(1)} = 0.14$, p=0.71) nor

371 between target depth and target-flanker spacing ($\chi^2_{(2)} = 1.43$, p=0.488).

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374 **Figure 6**: **Perceptual error results for Experiments 3 (A) and 4 (B) in which target depth was varied**

375 **while the flanker ring was always at fixation depth.** Box plots show medians plus the interquartile

376 range (IQR), whiskers are the lowest and highest values that are within 1.5 times the IQR from the upper

377 and lower quartiles. Points show the perceptual error for each individual observer. The visual aid below

378 each graph shows the depth of the target (based on the same color key as the box plot) relative to the

379 depth of the fixation point and flanker ring (shown in black) for each stimulus condition. The relative

380 sizes of, and distances between, the fixation point, target, and flanker ring are to scale. Note that the

381 fixation point is only shown for the 0.625° target-flanker spacing due to limited space within the figure.

382

<u>Target and flanker ring at fixation depth</u>

Experiment 5: Target and flanker ring always at fixation depth (Figure 7). Perceptual error

decreased as target-flanker spacing increased (effect of target-flanker spacing: $\chi^2_{(1)} = 64.8$,

p<0.001). There was also a significant effect of target-flanker-fixation depth ($\chi^2_{(2)} = 8.75$,

p=0.013) resulting from a higher perceptual error for stimuli displayed at 4 m. There was no

significant interaction between target-flanker-fixation depth and target-flanker spacing ($\chi^2_{(2)} =$

1.72, p=0.424).

Figure 7: **Perceptual error results for Experiment 5 in which the target and flanker were always**

presented at the same depth as the fixation point. Box plots show medians plus the interquartile range

(IQR), whiskers are the lowest and highest values that are within 1.5 times the IQR from the upper and

lower quartiles. Points show the perceptual error for each individual observer. The visual aid below the

graph shows the depth of the target, flanker, and fixation point (based on the same color key as the box

plot) for each stimulus condition. The relative sizes of, and distances between, the fixation point, target,

and flanker ring are to scale. Note that the fixation point is only shown for the 0.625˚ target-flanker

spacing.

Perceived target position relative to the flanker ring

Target always at fixation depth with variable flanker depth

Experiment 1: Target and fixation at 1.26 m with flanker ring presented at each depth

(Figure 8A and Supplementary Figure S1). In Experiment 1, most observers consistently

reported seeing the target inside the flanker ring. However, when the flanker ring was away from

target-fixation depth there was a reduction in the proportion of observers who consistently

reported seeing the target within the flanker ring when the target-flanker spacing was small

(mixed effects binary logistic regression models compared via LRT; interaction between target-

flanker spacing and flanker depth: $\chi^2_{(2)} = 36.12$, p <0.001). This effect was greatest when the

flanker ring was displayed behind the target and fixation.

Note that in all four experiments, the response to the control (i.e., no flanker condition)

indicates the probability of an observer making an inaccurate report (e.g., they selected the

wrong option by mistake or missed the stimulus and reported a guess rather than selecting the

"Unsure" option).

Experiment 2: Target and fixation at 0.4 m or 4 m with flanker ring presented at each

depth (Figure 8B and Supplementary Figure S2). As with the previous experiments, when the

flanker ring was away from target-fixation depth, there was a reduction in the overall proportion

of trials in which observers reported seeing the target within the flanker ring (interaction between

target-fixation depth and flanker depth: $\chi^2_{(2)} = 374.26$, p < 0.001). The greatest reduction

occurred when target-flanker spacing was smaller (effect of target-flanker spacing: $\chi^2_{(1)} = 178.65$,

p < 0.001). There was no significant interaction between flanker depth and target-flanker spacing

($\chi^2_{(2)} = 0.24$, p=0.886) nor between target-fixation depth and target-flanker spacing ($\chi^2_{(1)} = 1.64$,

p=0.2)

Figure 8: **Proportion of trials in which observers reported seeing the target inside the flanker ring**

for Experiments 1 (A) and 2 (B). In both experiments flanker depth was varied while the target was

always at fixation depth**.** Box plots show medians plus the interquartile range (IQR), whiskers are the

lowest and highest values that are within 1.5 times the IQR from the upper and lower quartiles. Points

show the proportion of trials for each individual observer. The visual aid below each graph shows the

depth of the flanker ring (based on the same color key as the box plot) relative to the depth of the fixation

point and target (shown in black) for each stimulus condition. The relative sizes of, and distances

between, the fixation point, target, and flanker ring are to scale. Note that the fixation point is only shown

for the 0.625˚ target-flanker spacing due to limited space within the figure.

<u>Flanker ring always at fixation depth with variable target depth</u>

Experiment 3: Flanker ring and fixation at 1.26 m with target presented at each depth

(Figure 9A and Supplementary Figure S3). When the target was away from flanker-fixation

depth, observers were less likely to report seeing the target within the flanker ring. This effect

was greatest when target-flanker spacing was smaller and when the target was displayed in front

of the flanker ring and fixation (interaction between target-flanker spacing and target depth: $\chi^2_{(2)}$

$= 100.38$, p <0.001).

Experiment 4: Flanker ring and fixation at 0.4 m or 4 m with target presented at each

depth (Figure 9B and Supplementary Figure S4). As with the previous experiment, the greater

the difference between target depth and flanker-fixation depth, the less likely observers were to

report seeing the target within the flanker ring (interaction between flanker-fixation depth and

target depth: $\chi^2_{(2)} = 779.49$, $p < 0.001$), particularly when target-flanker spacing was small

(interaction between target-flanker spacing and target depth: $\chi^2_{(2)} = 23.27$, $p < 0.001$). However,

target-flanker spacing had a weaker effect on the proportion of trials in which observers reported

seeing the target within the flanker ring when the flanker ring and fixation were near compared

to far (interaction between target-flanker spacing and flanker-fixation depth: $\chi^2_{(1)} = 56.23$, p <

0.001).

Figure 9: **Proportion of trials in which observers reported seeing the target inside the flanker ring**

for Experiments 3 (A) and 4 (B). In both experiments target depth was varied while the flanker ring was

always at fixation depth. Box plots show medians plus the interquartile range (IQR), whiskers are the

lowest and highest values that are within 1.5 times the IQR from the upper and lower quartiles. Points

show the proportion of trials for each individual observer. The visual aid below each graph shows the

depth of the target (based on the same color key as the box plot) relative to the depth of the fixation point

and flanker ring (shown in black) for each stimulus condition. The relative sizes of, and distances

between, the fixation point, target, and flanker ring are to scale. Note that the fixation point is only shown

for the 0.625° target-flanker spacing due to limited space within the figure.

Discussion

In all experiments, perceptual error decreased as the target-flanker spacing increased, which is in

line with previous crowding research (Bouma, 1970; Pelli, 2008). Overall, perceptual error was

higher when the target or flanker ring were presented at a different depth from the other and from

fixation. The greatest differences in perceptual error among the different depth conditions

occurred when the target or flanker ring were presented behind fixation depth. In contrast, when

the target or flanker ring were presented in front of fixation depth, the differences in perceptual

error among depth conditions were notably smaller. The results also show that when the target,

flanker ring and fixation were all at the same depth plane, crowding tended to increase with the

absolute distance of the stimuli from the observer.

The main finding that a depth difference between the flankers and the target led to an

increase, rather than a decrease, in perceptual error is different from the findings of several

previous studies that investigated the effect of depth on crowding using a stereoscopic

presentation (Astle et al., 2014; Felisberti et al., 2005; Kooi et al., 1994; Sayim et al., 2008). For

example, Astle et al (2014) found that when the target was presented at fixation depth

(comparable to Experiments 1 and 2 in our study), increasing the disparity between the target and

flankers resulted in less crowding, and ultimately a complete release from crowding. The authors

also reported that crowding was greater when flankers were presented in crossed disparity (in

front of the target and fixation), compared to uncrossed disparity (behind the target and fixation)

(Astle et al., 2014). Similarly, when the flankers were presented at fixation depth (comparable to

Experiments 3 and 4 in our study), Sayim et al (2008) found that foveal crowding was lower

when the target was presented in front of or behind the flanker and fixation.

Several explanations for crowding have been proposed in which crowding occurs because

target and flanking features are inappropriately grouped (Banks et al., 1979; Herzog and

Manassi, 2015; Pachai et al., 2016). Consistent with this explanation, crowding can be alleviated

when the flankers are grouped together and segmented from the target (Herzog and Manassi,

2015). One piece of evidence in support of this account is the reduction of crowding that can

occur when flankers are presented at a different depth from the target (Astle et al., 2014;

Felisberti et al., 2005; Kooi et al., 1994; Sayim et al., 2008). Our results challenge this view of

crowding because it would predict that increasing the depth difference between target and

flankers would decrease the probability of them being inappropriately grouped and increase the

probability of the flankers being segmented from the target, thereby decreasing crowding, the

opposite of our finding. Other models of crowding, such as texture processing and feature

integration (Balas et al., 2009; Freeman and Simoncelli, 2011; Parkes et al., 2001; van den Berg

et al., 2012, 2010; Wallis and Bex, 2012), sampling errors (Ester et al., 2015, 2014; Harrison and

Bex, 2017, 2016, 2015), attentional resolution limits (He et al., 1996) or saccade properties

(Nandy and Tjan, 2012) are agnostic concerning the influence of depth differences among targets

and flankers. Therefore, each of these models would require modification to explain the increase

in crowding that we observe with large real depth differences between a target and its flankers.

In contrast with studies that controlled depth with small stereoscopic disparities, our

results do agree with the findings of Eberhardt and Huckauf (2020) who also used a real-depth

display and tested larger differences in depth between the target and flankers than previous

studies had examined, though depth differences were still much smaller than those tested in our

current study. When the target was at fixation depth (comparable to Experiments 1 and 2 in our

study), Eberhardt and Huckauf (2020) found that crowding increased with increasing target-

flanker depth difference. The authors also found that crowding was greater when the flankers

were behind the target and fixation compared to in front of it (Eberhardt and Huckauf, 2020).

Our findings from Experiments 1 and 2 are consistent with these results. However, when the

flankers were at fixation depth (comparable to Experiments 3 and 4 in our study), Eberhardt and

Huckauf (2020) found that crowding was higher when the target was in front of the flankers and

fixation compared to when it was behind them. In contrast, in Experiments 3 and 4 we found that

perceptual error was greatest when the target was presented behind the flanker ring and fixation

rather than in front of it. This difference is likely due to a combination of high defocus blur when

the target was behind fixation combined with the finding from Experiment 5 which found that in

our study a larger absolute distance from the observer resulted in higher perceptual error.

Why the inconsistencies across studies? It is important to consider that most of the

previous studies used very small depth differences, the largest being 0.1 diopters in Eberhardt

and Huckauf (2019, 2020). In comparison, the depth difference in our study ranged from 0.54

diopters (between the mid and far screens) to 2.25 diopters (between the near and far screens).

Our results, together with those from previous studies, suggest that small differences in depth

between the target and flankers reduce crowding (Astle et al., 2014; Felisberti et al., 2005; Kooi

et al., 1994; Sayim et al., 2008), while larger differences in depth increase it (Eberhardt and

Huckauf, 2020; and results from our study). Although this pattern is quite surprising, there is

precedent for non-linear effects of depth on perceptual processing outside the crowding

literature. In a multiple object tracking task, when the targets and distractors were distributed

equally on two depth planes, tracking accuracy was better than the accuracy during trials in

which targets and distractors appeared on a single depth plane when the depth difference

between planes was small (~6 cm) (Ur Rehman et al., 2015; Viswanathan and Mingolla, 2002),

but worse when the depth difference between planes was large (50 cm) (Ur Rehman et al., 2015).

How could depth affect perception in this nonlinear way? The geometry of the eyes and

the 3D environment create interocular disparity differences between the images in each eye.

When corresponding features in the images in each eye can be identified, the images can be

fused to generate a binocular perceptual experience of depth (for review see Nityananda and

Read, 2017). There is a horizontal and vertical spatial limit to the interocular disparity difference

over which the visual system attempts to identify corresponding retinal points in order to fuse

different 2D interocular images as a single 3D object (Westheimer, 1979). This 2D spatial

correspondence limit creates a 3D volume along the horopter known as Panum's Fusional Area

(Panum, 1858). Outside Panum's Fusional Area, there is a loss of stereoscopic depth perception

and either double vision (diplopia) may be experienced, or single vision may occur if the image

from one eye is partly suppressed (Georgeson and Wallis, 2014; Ono et al., 1977; Spiegel et al.,

2016; Stidwill and Fletcher, 2010). The spatial extent of Panum's Fusional Area depends on the

spatial frequency of the stimuli (Maiello et al., 2020; Pulliam, 1981; Reynaud and Hess, 2017;

Wilcox and Allison, 2009; Yang and Blake, 1991) and increases with eccentricity (Hampton and

Kertesz, 1983; Harrold and Grove, 2019; Qin et al., 2006).

It is likely that differences between fusion and depth perception within Panum's Fusional

Area versus diplopia, and/or local suppression for single vision, outside of it can explain the

patterns of results observed between studies. Small disparity differences between target and

flankers create differences in perceived depth that can alleviate the effects of crowding,

potentially through ungrouping of target and flanking elements (Herzog et al., 2015; Herzog and

Manassi, 2015; Manassi et al., 2012) or by independent processing of target and flankers in

different depth-selective channels (Norcia et al., 1985; Pulliam, 1981; Reynaud and Hess, 2017;

Tyler et al., 1994; Wilcox and Allison, 2009; Yang and Blake, 1991) by any of the computational

models of crowding based on texture processing and feature integration (Balas et al., 2009;

Freeman and Simoncelli, 2011; Parkes et al., 2001; van den Berg et al., 2012, 2010; Wallis and

Bex, 2012), sampling errors (Ester et al., 2015, 2014; Harrison and Bex, 2017, 2016, 2015)

attentional resolution limits (He et al., 1996) or saccade properties (Nandy and Tjan, 2012).

Large interocular disparity differences on the other hand can induce diplopia that could increase

the perceived number of flankers (Eberhardt and Huckauf, 2019). In theory, this perceived

increase in the number of flanking elements could result in higher perceptual error because

increasing the number of flankers is known to increase crowding under certain conditions

(Chanceaux et al., 2014; Manassi et al., 2012; Pluháček et al., 2021). It is however worth noting

that the opposite can occur, i.e. reduced crowding with increasing number of flankers, in cases

where the additional flankers are grouped together (Manassi et al., 2013, 2012). Surprisingly,

when asked, only a few observers reported experiencing diplopia, and those that did reported

only experiencing it in a minority of presentations for which they selected the 'unsure or no ring'

option (as instructed) when reporting the perceived location of the target (Supplementary Figures

S1E, S2E, S3E and S4E). However, it is worth noting that as mentioned in the Methods sections,

observers did report experiencing diplopia when trying to perform the spatial calibration task

under binocular conditions during a pilot experiment. It is possible that the short presentation

time of the stimulus was too fast for observers to notice diplopia consciously (i.e., diplopia did

not enter awareness), or that diplopia was suppressed entirely by local suppression to maintain

single vision. Attention effects such as inattentional blindness (Bredemeier and Simons, 2012;

Simons and Chabris, 1999) could also play a role in explaining why so few observers reported

diplopia in the main experiments. There is conflicting evidence as to whether conscious

awareness of a flanker is necessary for it to induce crowding (compare Ho and Cheung, 2011 vs

Wallis and Bex, 2011), and thus whether 'unconscious diplopia' could have increased crowding

in this study due to the reason highlighted above is a matter for debate and beyond the scope of

our findings. In addition, it is worth noting that due to the lack of binocular fusion of stimulus

areas outside Panum's Fusional Area, we can't rule out the possible involvement of binocular

rivalry which has been shown to interfere with object recognition not just in isolation but also

when combined with crowding (Kim et al., 2013).

Another explanation for higher perceptual error with increasing target-flanker depth

differences could be perceived target misalignment. Recall that to avoid diplopia during the

spatial calibration, the screens were calibrated monocularly with the dominant eye. This means

that the screens were imperfectly aligned for the non-dominant eye. Therefore, as in the real

world, at certain flanker sizes and separations there may be occlusions between target and

flanker features that could affect target report accuracy, which is not the same mechanism as

crowding. In our study, such misalignment could result from local suppression of the calibrated

eye to maintain single vision, and/or head movements following the spatial calibration. To

examine how target misalignment (i.e., target obstructed ring, target was outside ring, or they

were unsure, e.g., due to diplopia) affected the overall results, we recalculated perceptual error

using only trials in which the observer reported seeing the target inside the flanker ring. We then

reanalyzed these data the same way as for perceptual error calculated from the full data set.

Apart from Experiment 2, the effect of flanker and/or target depth remained statistically

significant (see Supplementary Figures S5 and S6). Therefore, across the majority of

experiments, misalignment or occlusion of the target by the flanker ring is not enough to explain

the overall results. This supports the suggestion that the increase in perceptual error when the

target and flanker are at different depths is being driven by an increase in crowding.

This current study is the first to investigate how crowding is affected by large, real

differences in depth between a target and flanking features. This is important because objects in

the real world are often flanked by visual features that vary greatly in their distance from an

observer, and many will fall outside the limits of Panum's Fusional Area. A limitation of our

approach is that the use of relatively simple stimuli in a tightly controlled experiment limits the

generalizability of our finding to the real world where clutter is abundant and more complex.

Future research should therefore aim to utilize stimuli that better capture the complexity and

heterogeneity of natural scenes. Future work should also investigate if the reported effects of

depth on crowding in our study hold at different target eccentricities, particularly given that the

range of Panum's Fusional Area changes with eccentricity (Hampton and Kertesz, 1983; Harrold

and Grove, 2019; Qin et al., 2006). Nevertheless, our findings still show that crowding from

clutter outside Panum's Fusional Area has the potential to significantly impact object recognition

and visual perception in the peripheral field. Our findings therefore do not support the view that

depth differences between targets and flankers necessarily reduce crowding, instead the effect of

depth on crowding appears to be more complex than originally thought. Our results, alongside

those of previous studies, suggest that small differences in depth between targets and flankers do

not have the same effect on crowding as larger differences in depth in which either the target or

flankers are presented outside the limits of binocular fusion. This finding confirms the potential

importance of crowding in three-dimensional scenes.

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Renderpeople (https://skfb.ly/6SO7F) and "American Road Intersection" by jimbogies

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Author Contributions

650 S.P.S. and P.J.B. conceived the study and the idea of the multi-depth plane display and designed

651 the experiments. S.P.S. designed and built the multi-depth plane display, wrote all code, and

652 performed analyses. S.P.S., Y.S., and J.A. conducted the experiments. S.P.S. and P.J.B. wrote the

653 manuscript with input from all authors.

Data Availability

656 All data and code required to replicate the analyses in this paper will be made available on an

657 online repository at the stage of publication. It will also be made available to reviewers during

658 peer review.

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Supplementary figure legends

Supplementary Figure S1: **Proportion of trials in Experiment 1 in which observers reported seeing the target in the center of the flanker ring (A), within the flanker ring but not in the center (B), partly or fully obstructed by the flanker ring (C), outside the flanker ring (D), or they were unsure or there was no flanker ring (E).** Flanker depth was varied while the target was always at fixation depth. Box plots show medians plus the interquartile range (IQR), whiskers are the lowest and highest values that are within 1.5 times the IQR from the upper and lower quartiles. Points show the number of trials for each individual observer. There were 10 repeats per stimulus condition.

Supplementary Figure S2: **Proportion of trials in Experiment 2 in which observers reported seeing the target in the center of the flanker ring (A), within the flanker ring but not in the center (B), partly or fully obstructed by the flanker ring (C), outside the flanker ring (D), or they were unsure or there was no flanker ring (E).** Flanker depth was varied while the target was always at fixation depth. Box plots show medians plus the interquartile range (IQR), whiskers are the lowest and highest values that are within 1.5 times the IQR from the upper and lower quartiles. Points show the number of trials for each individual observer. There were 10 repeats per stimulus condition.

Supplementary Figure S3: **Proportion of trials in Experiment 3 in which observers reported seeing the target in the center of the flanker ring (A), within the flanker ring but not in the center (B), partly or fully obstructed by the flanker ring (C), outside the flanker ring (D), or they were unsure or there was no flanker ring (E).** Target depth was varied while the flanker was always at fixation depth. Box plots show medians plus the interquartile range (IQR), whiskers are the lowest and highest values that are within 1.5 times the IQR from the upper and lower quartiles. Points show the number of trials for each individual observer. There were 10 repeats per stimulus condition.

Supplementary Figure S4: **Proportion of trials in Experiment 4 in which observers reported seeing the target in the center of the flanker ring (A), within the flanker ring but**

not in the center (B), partly or fully obstructed by the flanker ring (C), outside the flanker

ring (D), or they were unsure or there was no flanker ring (E). Target depth was varied while

the flanker was always at fixation depth. Box plots show medians plus the interquartile range

(IQR), whiskers are the lowest and highest values that are within 1.5 times the IQR from the

upper and lower quartiles. Points show the number of trials for each individual observer. There

were eight repeats per stimulus condition.

Supplementary Figure S5: Perceptual error for Experiments 1 (A) and 2 (B) calculated

only from trials in which the observer reported seeing the target inside the flanker ring. In

both experiments flanker depth was varied while the target was always at fixation depth. Box

plots show medians plus the interquartile range (IQR), whiskers are the lowest and highest

values that are within 1.5 times the IQR from the upper and lower quartiles. Points show the

perceptual error for each individual observer. The visual aid below each graph shows the depth

of the flanker ring (based on the same color key as the box plot) relative to the depth of the

fixation point and target (shown in black) for each stimulus condition. The relative sizes of, and

distances between, the fixation point, target, and flanker ring are to scale. Note that the fixation

point is only shown for the 0.625˚ target-flanker spacing due to limited space within the figure.

Experiment 1: Target and fixation at 1.26 m with flanker ring presented at each depth. The effect

of flanker depth relative to target-fixation depth ($\chi^2_{(2)}$ = 15.69, p <0.001) and target-flanker

spacing ($\chi^2_{(1)}$ = 20.03, p <0.001) both remained significant. There was no significant interaction

between flanker depth and target-flanker spacing ($\chi^2_{(2)}$ = 1.92, p=0.384).

Experiment 2: Target and fixation at 0.4 m or 4 m with flanker ring presented at each depth.

When perceptual error was calculated using only trials in which the observer reported seeing the

target inside the flanker ring, flanker depth had no significant effect on perceptual error ($\chi^2_{(2)}$ =

5.7, p = 0.058). In contrast, when perceptual error was calculated from the full data set there was

a significant interaction between target-fixation depth and flanker depth (see Results section).

The interaction between target-flanker spacing and target-fixation depth remained significant

($\chi^2_{(1)}$ = 7.32, p=0.007). There was no significant interaction between target-fixation depth and

flanker depth ($\chi^2_{(2)}$ = 3.44, p=0.179) nor between flanker depth and target-flanker spacing ($\chi^2_{(2)}$ =

4.85, p=0.088).

Supplementary Figure S6: **Perceptual error for Experiments 3 (A) and 4 (B) calculated only**

from trials in which the observer reported seeing the target inside the flanker ring. In both

experiments target depth was varied while the flanker was always at fixation depth. Box plots

show medians plus the interquartile range (IQR), whiskers are the lowest and highest values that

are within 1.5 times the IQR from the upper and lower quartiles. Points show the perceptual error

for each individual observer. The visual aid below each graph shows the depth of the target

(based on the same color key as the box plot) relative to the depth of the fixation point and

flanker ring (shown in black) for each stimulus condition. The relative sizes of, and distances

between, the fixation point, target, and flanker ring are to scale. Note that the fixation point is

only shown for the 0.625˚ target-flanker spacing due to limited space within the figure.

Experiment 3: Flanker ring and fixation at 1.26 m with target presented at each depth. The effect

of target depth relative to flanker-fixation depth ($\chi^2_{(2)}$ = 36.98, p <0.001) and target-flanker

spacing ($\chi^2_{(1)}$ = 50.63, p <0.001) both remained significant. There was no significant interaction

between target depth and target-flanker spacing ($\chi^2_{(2)}$ = 3.59, p=0.166).

Experiment 4: Flanker ring and fixation at 0.4 m or 4 m with target presented at each depth. The

interaction between flanker-fixation depth and target depth ($\chi^2_{(2)}$ = 8.7, p = 0.013), and the effect

of target-flanker spacing ($\chi^2_{(1)}$ = 7.58, p = 0.006) both remained significant. There was no

significant interaction between flanker-fixation depth and target-flanker spacing ($\chi^2_{(1)}$ = 0.64,

p=0.425) nor between target depth and target-flanker spacing ($\chi^2_{(2)}$ = 0.98, p=0.612).