Label-free Identification of Protein Aggregates Using Deep Learning

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Abstract

Protein misfolding and aggregation play central roles in the pathogenesis of various neurodegenerative diseases (NDDs), including Huntington's disease, which is caused by a genetic mutation that leads to a polyglutamine repeat length > 35 in exon 1 of the Huntingtin protein (Httex1). Current research on protein aggregation often involves the use of fluorescent labels to visualize and monitor the dynamics of protein expression, which can alter the biophysical properties of proteins and the final ultrastructure, composition, and toxic properties of the formed aggregates. To overcome this limitation, we present a method for label-free identification of NDD-associated aggregates (LINA). Our approach utilizes deep learning to detect unlabeled and unaltered Httex1 aggregates in living cells from transmitted-light images, without the need for fluorescent labeling. We developed pixel-classification and pixel-regression models, which are robust across imaging conditions, and validated them on aggregates formed by different constructs of Httex1. Our results reveal that Httex1 proteins with shorter polyglutamine repeat lengths form aggregates with a higher average dry mass and area, highlighting the differences in their ultrastructure and aggregation mechanisms. LINA enables the dynamic identification of label-free aggregates and measurement of their dry mass and area changes during their growth process. Our highly-robust models offer high speed, specificity, and simplicity to analyze label-free protein aggregation dynamics and obtain high-fidelity information.

Introduction

Neurodegenerative diseases (NDDs), such as Alzheimer's disease (AD), Parkinson's disease (PD), and Huntington's disease (HD), are major global health concerns afflicting tens of millions of patients worldwide and are currently incurable[1,2]. They are characterized by progressive damage to the structure and function of neurons and the accumulation of misfolded proteins in specific brain regions and neuronal populations[3–6]. Although these misfolded protein aggregates represent the hallmark of several NDDs, including AD, PD, and HD, our understanding of their mechanisms of formation and role in the disease pathogenesis remains incomplete. While some studies suggest that their formation is a major driver of neurodegeneration, other studies propose that they represent neuroprotective mechanisms that lead to inactivation of toxic aggregates[7–12]. Furthermore, the nature of toxic species remains unknown. One primary reason for this knowledge gap is the lack of tools and methods that allow for direct monitoring of the different phases of protein misfolding and aggregation, leading to the formation of the pathological hallmarks found in the brains of affected individuals.

To enable monitoring protein aggregation in living cells or animals, fluorescent proteins (FPs), such as GFP, YFP, mCherry, and others, are usually fused to the C- or N-terminus of the protein of interest. Protein aggregation is usually seen as the transition from diffuse signal to the formation of puncta or foci structures. However, as useful and valuable as FPs can be, they also have limitations. Several studies have shown that fluorescently-tagged proteins exhibit altered biochemical, biophysical or cellular properties[13–22]. In the context of protein aggregation linked to NDDs, the addition of fluorescent proteins to proteins of different sizes has been shown to alter not only the kinetics of aggregation and the final size of the aggregates, but also the interactome of the aggregate and their ultrastructural organization in the final inclusions that accumulate in cells or brain tissues. This discrepancy has been observed in several NDD-associated proteins, including alpha-synuclein[18,19], tau[20], amyloid beta[21,22] (Aβ), and exon1 of the Huntingtin (Htt) protein[14–17] (Httex1), one of the primary components of intracellular protein aggregates found in Huntington's disease post-mortem brains[23–25]. Httex1 overexpression in multiple cellular and animal models of HD recapitulates many of the

key features of HD human pathology, including Htt aggregation and inclusion formation,
neurodegeneration, and brain atrophy[8,26–30].

In a recent study[14], we compared the biochemical and ultrastructural properties of
cellular inclusions formed by mutant Httex1, with expanded polyglutamine (polyQ) repeats
of 16-72Q, in the absence or presence of GFP on the C-terminus of the protein. Our
results showed that the addition of GFP to mutant Httex1 not only altered the biochemical
and ultrastructural properties of the inclusions but also their toxic properties and
interactions with cellular organelles. For example, the inclusions formed by unlabeled
mutant Httex1 displayed distinctive core and shell structures that contain lipids and
membranous organelle and within which the Htt fibrils colocalize with and interact with
the endoplasmic reticulum (ER) structure and membranous structures. In contrast, mutant
Httex1-GFP formed a mesh of cytoplasmic fibrils that exhibited minimal interactions with
cellular organelles (Fig. 1a). These observations are consistent with previous studies
showing that fusion of large proteins to mutant Httex1, such as GFP, alter their
dimensions as well as their mechanical and surface properties. GFP-labeled fibrils were
approximately 3 nm thicker[15] and exhibited increased stiffness[16] compared to the
unlabeled Httex1 fibrils. Using coarse-grained simulations, we recently showed that
fluorescent tags like GFP cause a size-dependent surface occlusion and thus alter the
fibril's interactome[17]. These observations could explain the distinct interactome observed
for untagged and GFP-tagged mutant Htt inclusions in mammalian cells and primary
neurons[14]. While it is tempting to attribute these changes in the biophysical and
biochemical properties to the large size of fluorescent proteins, it has been shown that
even the fusion of small peptide tags like HA to different N-terminal Htt fragments could
markedly change their aggregation and toxic properties[31]. Altogether, these observations
underscore the critical importance of developing label-free methods that enable
investigation of the mechanisms of protein aggregation and inclusion formation of the
native proteins.

Although recent studies have suggested using label-free methods, such as Raman
microscopy[32], to monitor protein aggregation in cells, these methods lack the specificity
and contrast needed to analyze them sufficiently, often lack the needed temporal
resolution, or require deuterium labeling. Quantitative phase imaging (QPI)[33–35] is an

attractive label-free microscopy modality that produces a quantitative image of an
unlabeled biological specimen based on the phase shift at each pixel in the field of view
(FOV), enabling the extraction of quantitative parameters, such as the dry mass or
morphology. Since low-intensity illumination can be used, quantitative information can be
obtained from live specimens with minimal photodamage and photobleaching (compared
to fluorescence imaging) at rapid time scales. However, the lack of a specific label
complicates distinguishing between different structures inside cells. In recent years, the
concept of virtual staining has emerged[36–39], in which a deep learning model is taught to
map between a label-free imaging modality (e.g., brightfield, QPI, or auto-fluorescence)
and fluorescence imaging, such that the model can predict the fluorescence signal strictly
from the label-free input, yielding the necessary contrast and specificity. A recent
technique called VISTA uses sample expansion to achieve super-resolved Raman
imaging and virtual labeling of Aβ plaques and mutant Htt aggregates[40]. However, this
technique was not validated on label-free Htt aggregates, was not quantitatively validated
on any Htt aggregates, had a large variation in Aβ-plaque model performance (roughly
between 30-90%), requires substantial sample manipulation and perturbation during
expansion, and is fundamentally incompatible with live-cell imaging.

In this work, we employ the concept of virtual labeling[36–39] on a well-characterized
cellular model of mutant Httex1 aggregation and inclusion formation by training a neural
network on data collected using widely available imaging modalities (brightfield/QPI and
widefield fluorescence) to generate label-free identification of NDD-associated
aggregates (LINA) models (Fig. 1b). We quantitatively validate the LINA models and
demonstrate that they can be used to accurately identify unlabeled mutant Httex1
aggregates with areas as small as 3 μm^2 and at exposure times as low as 3 ms. By
applying our neural network models to identify aggregates formed by different label-free
mutant Httex1 constructs, we are able to measure and compare their dry masses. We
can also identify aggregates from live-cell imaging data and are able to measure the dry
mass and area of aggregates as they form. We experimentally validate the models'
robustness to different acquisition settings and cell lines, showing the high applicability of
the method. The aforementioned issues related to labeling illustrate the need for label-
free techniques for identifying and analyzing native neurodegenerative protein

aggregates to avoid tag-induced alterations. The label-free method we have developed
to visualize and analyze protein aggregates demonstrates, for the first time to our
knowledge, the applicability of virtual labeling on unlabeled and unaltered protein
aggregates in living cells, with rapid speed, high accuracy, and relative simplicity. LINA
paves the way for more accurate analysis of NDD-associated protein aggregates, better
recapitulating their true neurobiological nature and offering higher-fidelity information.

Figure 1: Label-free identification of NDD-associated aggregates (LINA). (a) The NDD-associated
Httex1 protein forms aggregates in cells within 48 hours. When the protein is unlabeled, these aggregates
have a core and shell ultrastructure. Labeled Httex1 (e.g., with GFP) forms altered aggregates that lack this
structure, instead resembling a mesh of fibrils, and have altered biochemical and biophysical properties
(e.g., different proteome composition, stiffness, and fibril length). (b) To enable label-free imaging of
unaltered Httex1 aggregates, we trained a neural network to map between label-free transmitted-light
(brightfield or quantitative phase) image inputs (single or multiple planes) and fluorescence images, such
that the network is then able to identify aggregates using only the label-free input. Dashed arrows represent
training-only steps.

Results

Label-free identification of aggregates formed by different Httex1 constructs with high accuracy

The choice of a well-controlled biological model system is crucial for the development of robust and reproducible image analysis tools. To apply virtual labeling on NDD-associated aggregates and develop LINA models, we chose to use a cellular model of HD that is well-characterized. As reported previously, when a mutant Httex1 construct with a polyQ repeat length ≥ 39 is overexpressed in HEK 293 (HEK) cells, aggregates are formed within a period of 48 hours. With our custom-built, multi-modal, multi-plane microscope[41], it is possible to acquire ultrafast 4D brightfield and fluorescence images using an image-splitting prism that introduces path length differences in the detection path. This prism allows the acquisition of an image stack consisting of 8 z-planes simultaneously. An algorithm is then used to retrieve phase information from the brightfield image stack using Fourier filtering, transforming it into a QPI stack. We used this microscope to collect a dataset of over 1,000 8-plane brightfield and fluorescence pairs of images of fixed HEK cells overexpressing a mutant Httex1 construct with a polyQ repeat length of 72, fused to GFP (Httex1-72Q-GFP).

We processed the dataset to obtain pixel-registered 8-plane QPI (which we also refer to as 'phase' images) and fluorescence images. We then used a subset of the dataset (the training and validation sets) to train a convolutional neural network (CNN) (with a U-Net architecture[42], more information is provided in the Methods) and produce LINA models for both pixel regression and pixel classification (Fig. 2a). Here, each ground truth label is generated as the maximum z-projection of each 8-plane image stack so that it incorporates information from the 8 planes, reducing the complexity of the mapping. We aim to achieve 2D, rather than 3D, identification of the aggregates, for several reasons. A major reason is that this lowers the memory constraints considerably and enhances the accessibility of the method. 3D prediction is a challenging task as described in similar prior work[36]. Using our 2D-identification models, an aggregate can be identified in 2D space first and then its position within the other planes can be inferred from the QPI images afterwards. The pixel classification model is trained on segmentation masks

generated from the maximum z-projection images, and it classifies the pixels into either
1's or 0's, i.e., part of an aggregate or not. The pixel regression model is more general in
that it is trained directly on the maximum z-projection fluorescence images, and can
predict intensity values rather than just 1's or 0's. In Fig. 2a, the phase image is a color-
coded maximum z-projection, where each z-plane is represented using a different color,
illustrating the spread of information available in the 8 planes. The network outputs were
observed to match the ground truths quite well, as can be verified further in Fig. 2b. The
phase images are represented in this figure and other figures by one of the central planes,
i.e., plane 4 or 5. Further visual test-set examples for both model types are shown in
Supplementary Fig. 1 and Supplementary Fig. 2.

Figure 2: Validation of deep learning models for label-free identification of Httex1 protein aggregates. (a) Convolutional neural networks for both pixel classification and regression have been trained using pixel-registered pairs of 8-plane quantitative phase images and maximum-projected 8-plane fluorescence images or corresponding segmented masks. The 8-plane input images are represented by a color-coded maximum *z*-projection image; the aggregate in the image is highlighted by the dashed square and is shown magnified. The phase signal was thresholded (T = 0 rad) prior to color-coding to enhance the contrast. The labels used are generated as the maximum z-projection of the fluorescence images in the 8 planes for the pixel regression network and the corresponding segmented masks (Otsu thresholding) for pixel classification. (b) Test set prediction example, with images of the phase, fluorescence, network output, and a merge of all three, showing where the three images colocalize in white. (c) Quantitative validation of the pixel regression model using the Pearson correlation coefficient (r), showing high correlation with the

ground truth (~0.96 mean). (d) The regression network was further validated on label-free Httex1
aggregates. Despite being trained only on a 72Q-GFP construct of Httex1, the model works well on label-
free constructs of different polyQ repeat lengths (39Q, 72Q) and types (72Q with a truncated Nt17 domain).
Scale bars: 5 µm.

To precisely quantify how well the LINA pixel-regression model performs, we
measured the Pearson correlation coefficient (r) between the network output and the
ground truth (Fig. 2c). The correlation coefficient is consistently high (0.959 mean) over
the entire test set, a set of images which the model had never seen before, illustrating the
high reliability of the model. We further evaluated the quantitative performance of the
model by measuring r and the normalized mean squared error (NMSE), the quantity used
for training (unnormalized), computed only within the regions where there are aggregates
(Supplementary Fig. 3a, b), thereby more precisely measuring the degree of true
positives/false negatives (Methods). The correlation remains very high (0.955 mean), and
the NMSE also consistently shows relatively low errors (0.106 mean). The pixel-
classification model also performs well, achieving an F1-score of 0.9 and a mean Jaccard
index of 0.78. The pixel-regression model is slightly more accurate when segmentations
are produced from its regression predictions (using Otsu thresholding), with a mean
Jaccard index of 0.81 and a mean Dice loss of 0.89 (Supplementary Fig. 3c, d). Therefore,
we focus on the regression model for our following experiments and quantifications. We
used the Pearson correlation coefficient to compare the total intensity within the
aggregates in the prediction images versus the ground truth, which was computed as
0.91, suggesting very high correlation in this regard as well. Supplementary Fig. 4 shows
LINA's performance on two negative controls (cells expressing 16Q-GFP and eGFP,
respectively), where aggregates are not produced. LINA successfully predicts the
absence of aggregates in both cases.

To determine if the models work on the unlabeled protein aggregates and if they
generalize to other constructs than the one it was trained on, we sought to validate the
network on different label-free constructs of mutant Httex1. The constructs we tested are
unlabeled mutant Httex1 with a polyQ repeat length of 39 (Httex1-39Q), unlabelled mutant
Httex1 with a polyQ repeat length of 72 (Httex1-72Q), and unlabelled mutant Httex1 with
a polyQ repeat length of 72 with a truncated Nt17 domain (Httex1-ΔNt17-72Q). These

constructs, which either have a shorter polyQ repeat length or have a truncated Nt17
domain, have been shown to influence the kinetics of aggregation, as well as the
ultrastructural properties of Httex1 inclusions when comparing 39Q and 72Q[14]. Therefore,
it was important to verify if LINA can identify aggregates formed using these constructs
despite the differences in aggregate properties. To obtain a ground truth, we performed
immunocytochemistry (ICC) on the three constructs and labeled the aggregates with an
anti-Htt antibody raised against the Proline-rich domain (PRD) (MAB5492, Millipore). We
acquired QPI images of the same cells before and after ICC, using grid-marked
coverslips, to ensure that LINA works well in both cases. Fig. 2d shows the input, ground
truth and network output for each construct. For all three constructs, the network correctly
identifies the aggregates, whose peripheries are shown in the ground truth images; this
is because the antibody we used is known to show a strong immunoreactivity to the
periphery of the aggregate rather than the core[14], while the network was trained solely on
GFP-labeled protein aggregates. Although the CNN was only trained on images of
Httex1-72Q-GFP, the model is nonetheless generalizable to different kinds of label-free
Httex1 constructs. For Httex1-ΔNt17-72Q, the model is able to discern between rather
small closely-neighboring aggregates (areas of around 3 μm^2), instead of seeing them as
one larger aggregate.

Robustness and generalizability of LINA

Testing the robustness of LINA in various image acquisition, input type, label quality, and
cell line configurations is vital to ensure the models' robustness and generalizability to
different kinds of data, and to facilitate the usability of the models by new users.
Supplementary Note 1 provides a more extensive discussion of the robustness and
generalizability of LINA. We observed, in test-set examples that are being seen by the
network for the first time, that the pixel-classification model can identify aggregates that
are missing in the label due to segmentation errors (Supplementary Fig. 5a). The model
outputs outperform direct segmentation from the ground truth, showing that it can learn
very well what constitutes an aggregate despite some erroneous labels.

The signal-to-noise ratio (SNR) of microscopy images is a key determinant of how
well image analysis pipelines and models perform. Increasing amounts of noise can

reduce the accuracy and precision of segmentation and classification models, leading to

incorrect or inconsistent results. All our models were trained on images taken at a 50 ms

exposure time and a fixed illumination, so we wanted to test whether it is possible to

identify aggregates from images taken at lower SNRs. We verified LINA's robustness to

noise both using simulated noise and experimentally (Supplementary Fig. 5b-h). Through

a simple pre-filtering step, we show that it is possible to identify aggregates even at

excessive amounts of noise (variance of 0.48 rad^2) where nothing can be visually

identified in the image anymore. By adding noise specifically to the aggregate regions

and with the same pre-filtering step, we show that LINA has high potential to be applied

on aggregates of varying optical properties. We observe, both visually and quantitatively,

that the performance degrades when noise is added that is larger than or equal to 0.5

rad^2, so we consider this the acceptable range for our model, though it can be extended

in the future through transfer learning. We then experimentally verified the model's

robustness to different SNRs, as we measured a consistently-high SSIM at various

exposure times, as low as 3 ms, without the need for pre-filtering, despite the model being

solely trained on images acquired at a 50 ms exposure time.

Another aspect we wanted to assess was the models' generalizability to different

cell lines than what we used for training (HEK). Therefore, we quantified LINA's ability to

identify Httex1-72Q-GFP aggregates expressed in HeLa cells, and the model consistently

produced highly-accurate predictions, as quantified by measuring the Pearson correlation

coefficient and the NMSE between the network outputs and the ground truth images (Fig.

3a, b). Fig. 3c, d show example images with the highest and lowest correlation

coefficients, respectively. The lowest-correlation example still shows excellent

performance, as both aggregates can be identified by the model. The reason for the

slightly lower correlation could possibly be that having two aggregates in one FOV

complicates the prediction of the true intensity levels for both aggregates at the same

time, as we observed that the example with the highest NMSE (worst performance) also

had two aggregates in the FOV, though this was also accurately predicted. These results

indicate the high potential for LINA to be applied in other cell lines, greatly enhancing its

generalizability.

Figure 3: Generalizability of LINA to a different cell line. (a) Pearson correlation coefficient (r) computed only on the regions where there are aggregates. The metric is computed for the 8-plane-QPI pixel-regression model. (b) Normalized mean squared error computed only on the regions where there are aggregates. The metric is computed for the 8-plane-QPI pixel-regression model. Both metrics show that LINA is able to accurately recognize aggregates expressed in a different cell line (HeLa). (c, d) Example images visualizing the model's performance on aggregates expressed in HeLa cells. (c) The example with the best r value is shown. (d) The example with the lowest r value is shown. Scale bars: 5 μm.

To test the potential of generalizing LINA to various kinds of protein aggregates involved in other NDDs, which could vary in terms of circularity and heterogeneity, we simulated a non-circular, chimeric test set and tested LINA's performance on it. This was done by replacing parts of aggregates in the test set by images of cells/background (for both the input and label), and then testing the ability of the pixel-regression model to correctly identify the heterogeneous aggregates (Supplementary Fig. 6). The Pearson correlation coefficient (mean 0.89) and NMSE (mean 0.08) show excellent performance even with these perturbations, demonstrating the high potential of generalizing LINA to different kinds of protein aggregates, of varying morphologies and structure.

We also evaluated LINA's dependence on the number of planes of the input by training new pixel-regression models using QPI inputs with one, two and four planes, respectively. Supplementary Fig. 7a quantifies and compares the performance of the 8-plane model to these three new models. We found that all three new configurations perform very well. We expected to possibly need transfer learning using a small set of new data to be able to identify aggregates correctly at much lower SNRs or for different cell lines, however, we found LINA to be highly robust to these changes, promising high generalizability to different kinds of imaging conditions. It is important to note that our QPI phase-retrieval algorithm yields better results with increasing numbers of planes. Therefore, it is possible that the model could perform even better if our training set had even more planes than eight. For our experiments, we settled on the standard 8 planes while acquiring our dataset as a good trade-off between image quality and speed. This is because the 8 planes are acquired simultaneously using an image-splitting prism, whereas more planes would require a z-stack. Here, we tested the different number of planes after all 8 were processed together into QPI images. Since the output image quality our QPI method is dependent on the number of planes of the input, it could possibly be interesting in the future to also study the effect of having the QPI images themselves being generated by fewer planes.

Our method to produce quantitative phase images[41] is widely adoptable; as previously mentioned, the phase information can be extracted using an algorithm from a z-stack of images. However, the simplest and most basic label-free technique is brightfield microscopy. How well would LINA perform on the simplest and most widely-available label-free technique? To answer this question, we trained pixel-regression models using only brightfield inputs, first with 8 planes then with a single plane (Supplementary Fig. 7b). We quantitatively compared both these models' performance with the model trained on 8-plane QPI images, and we found that both brightfield models perform very well on the test set. The 8-plane brightfield model yielded very similar results to the QPI model, with a slightly larger variance and the drawback of not having the possibility to extract the dry mass from the images.

To confirm LINA's generalizability and ease of use, we tested it on a completely different imaging setup with different illumination and a lower numerical aperture (NA)

microscope objective (Supplementary Fig. 7c). We were able to identify aggregates from images acquired using this different setup and the 1-plane brightfield LINA model, without the need to rely on transfer learning. Next, we tested LINA on a commercial, confocal setup (Leica TCS SP8). We used a similar magnification (63X versus 60X) and NA (1.4 versus 1.2) objective, but the illumination, setup type (confocal versus widefield) and detectors were completely different. Here, we acquired 8-plane stacks and used our QPI algorithm[41] to produce 8-plane QPI stacks. We tested LINA's performance using these QPI inputs (Supplementary Fig. 8a), as well as using the simplest possible inputs, 1-plane brightfield (Supplementary Fig. 8b), and both types of inputs yielded highly-accurate network predictions. Based on these results, we expect LINA to work well for new users acquiring images at different conditions, perhaps needing some transfer learning, or as shown here, likely not even requiring it.

We further tested LINA on the same commercial setup, with a lower-magnification (20X versus 60X) and NA (0.85 versus 1.2) objective (Supplementary Fig. 9). A lower-magnification objective means the FOV will be larger and, therefore, would enable users of our method to have a higher imaging throughput of cells containing aggregates. Since the network expects 352 pixels x 352 pixels inputs, we first cropped regions of that size around the aggregate images and used those as inputs to the network. We also directly tested the model on the 1024 pixels x 1024 pixels images. In both cases, the network performs very well and accurately identifies the aggregates. Here, again, we expected to possibly need transfer learning so that the network learns to expect smaller features (due to the lower magnification), yet the model works very well directly, illustrating the high generalizability and robustness of our method. These results using QPI inputs generated from images acquired on the commercial setup also demonstrate the ease of use and the accuracy of using our QPI algorithm on a setup that is different from our own. For quantitative analysis of these images, a calibration should first be done to ensure the accuracy of the phase retrieval, based on the optical properties of the setup that is used.

Dataset size requirements

What is the minimal amount of data needed to successfully train a LINA model? To answer this question, we first computationally estimated this by taking increasingly-sized

samples from our complete dataset, which consists of over 1,000 8-plane phase and fluorescence image stacks. We calculated the mean aggregate area and circularity for each sample size, repeated the sampling 100,000 times, and took the average. We plotted the discrepancy from the ground truth standard deviation to indicate the sample size at which we obtain a similar distribution as that of the ground truth (Supplementary Fig. 10); here, we consider the ground truth standard deviation to be that of the entire dataset, since it leads to well-performing models and should be large enough to capture the diversity of the different kinds of aggregates. Supplementary Fig. 11 shows the morphological distribution of the entire dataset. The simulation showed a saturation at around 30-50% of the size of the complete dataset, indicating that there could be diminishing returns past this point.

We then aimed to answer this question experimentally by attempting to train models with varying amounts of data (10%, 20%, 30%, and 50% of the entire dataset). It is possible to train LINA models even with only 10% of our dataset (Supplementary Fig. 12). However, performance does degrade slightly for the models trained with lower amounts of data, except for the model trained with 50% of the data, which yields very similar results to our standard model trained with 90% of the data (the remaining 10% is used as the test set), in agreement with our simulation results. While it is possible to train a LINA model with just 10% of the data, we visually observed this model to not do as well as the 90% model on some test set images. It is crucial that the training and validation datasets capture the diversity of the subject of the data to ensure high generalizability and accuracy of the trained model, and, therefore, more data will very often lead to better results. However, care should be taken to only provide high quality, useful data to the CNN, as low-quality data can actually confuse the network and lead to hallucinations[43]. The quality of the dataset is just as important as its quantity, making data curation a crucial step in successfully training a deep learning model.

Automatic scanning and image acquisition

We enhanced our image acquisition throughput by implementing an automatic image-scanning method, called xy-scan mode, to scan an arbitrary number of fields of view (FOV) across the sample (Fig. 4a). The xy-scan mode permits us to set the step size and

the number of steps in the x and y directions. The illumination source remains stationary while a piezo nano-positioning stage moves under the control of the software. This allows us to acquire images of thousands of FOVs, for cells expressing different Httex1 constructs, which our LINA models can then process to determine the presence or absence of aggregates (Fig. 4b).

Using the automatic xy-scan mode, we efficiently collected images of cells overexpressing mutant Httex1-39Q, Httex1-72Q, Httex1-ΔNt17-72Q and Httex1-72Q-GFP, then processed them to determine which FOVs contain aggregates. To minimize the occurrence of false positives, we combined the predictions from multiple models. While this approach may result in a higher chance of false negatives, our priority is to ensure for the analysis results to consider only true aggregates. The output of our model, which indicates the label-free images that contain aggregates, can then be used to extract their dry masses.

Figure 4: Automatic image acquisition, identification, and dry mass quantification of different kinds of label-free Httex1 aggregates. (a) A motorized piezo nano-positioning stage is controlled using software to scan the sample in the x and y directions and collect images at various fields of view (FOVs) for different label-free constructs of Httex1 (39Q, 72Q, ΔNt17-72Q) and a GFP-labeled construct (72Q-GFP). (b) The images are post-processed and our trained model is used to identify FOVs that contain aggregates. (c) The dry mass of aggregates produced by different constructs of Httex1 is extracted from the quantitative phase images, as shown in the inset image (n = 39 for 39Q, n = 29 for 72Q, n = 30 for ΔNt17-72Q, and n = 64 for 72Q-GFP). ΔNt17-72Q and 72Q had similar dry mass distributions (unpaired, two-sided t-test resulted in a p-value of 0.40), however, both label-free constructs had smaller dry masses on average than 39Q (unpaired, two-sided t-test p-values of 0.0008 and 0.0085 for 72Q and ΔNt17-72Q, respectively), and all three had smaller dry masses than the labeled 72Q-GFP (unpaired, two-sided t-test p-value = 0.00012 for 39Q, 2.8e-12 for 72Q, and 2.1e-10 for ΔNt17-72Q). ns: $p > 0.05$, **: $p \leq 0.01$, ***: $p \leq 0.001$, ****: $p \leq 0.0001$. White dots represent the medians, thick bars represent the interquartile ranges, and thin lines represent 1.5x the interquartile ranges. Scale bars: 5 μm.

Dry mass quantification and comparison between aggregates of different Httex1 constructs

The dry mass of a biological specimen can be extracted from a QPI image through a proportional relation (Methods)[35]. For this relation, we used a constant value of 0.19 for the refractive increment α, as recommended in the literature, due to α having an extremely narrow distribution[35,44]. The quality of the QPI images, e.g., in terms of resolution or SNR, determines the accuracy and precision of the dry mass measurement[35]. After the QPI image is translated into a dry mass density map, the dry mass of an aggregate can be measured by integrating over its area in the image (more details in Supplementary Fig. 13). To compare the dry mass of the different Httex1 constructs, we used the model outputs from the automatic xy-scan images to curate images with aggregates, producing segmentation masks that were then multiplied by the corresponding dry mass images. This allows for efficient and accurate measurement of the dry mass of the different kinds of aggregates (Fig. 4c).

Our findings indicate that there is no statistically-significant difference between the mean dry masses of mutant Httex1-72Q and Httex1-ΔNt17-72Q. Both of these constructs have been shown to form inclusions with the same core-and-shell ultrastructure[14]. Thus, they likely have a similar mechanism of aggregation, which explains their similar dry masses. We observed that fewer aggregates were detected for Httex1-39Q (8% of automatically-scanned FOVs) compared to the other two constructs, which had similar rates (~12% of automatically-scanned FOVs). This is in agreement with the literature, as increasing polyQ repeat length is known to accelerate aggregation and toxicity[45–47]. However, interestingly, we found that Httex1-39Q, which lacks the core-and-shell ultrastructural arrangement[14], produced aggregates with a larger average area (16.9 ± 7.6 μm^2), compared to Httex1-72Q (11.5 ± 4.7 μm^2) and Httex1-ΔNt17-72Q (12.7 ± 4.9 μm^2), and consequently a larger average dry mass. The difference in ultrastructure, and therefore the aggregation mechanism, leads to fewer aggregates being produced overall, yet at the same time, a fraction of the aggregates that are produced grow to larger final sizes.

We also compared the mean dry masses of the three unlabeled constructs with
that of the labeled one (Httex1-72Q-GFP) and found around a two-fold increase in the
mean dry mass of the labeled construct compared to the two constructs with the same
polyQ repeat length, as well as a 1.5-fold increase compared to Httex1-39Q. Similar to
Httex-39Q, Httex1-72Q-GFP aggregates have been shown to lack the core-and-shell
ultrastructural arrangement[14], which for both constructs leads to increasing the size of the
formed aggregates. The considerable increase in size of Httex1-72Q-GFP aggregates is
likely due to a mixture of the large size of the GFP tag and its effect on the size of the
fibrils, the difference in ultrastructure, and the difference in properties (e.g., proteome
composition) that it is known to cause, supporting previous studies' results and
demonstrating why such label-free methods are needed.

Live, label-free identification and analysis of an aggregate as it forms

Capturing the growth dynamics of NDD-associated protein aggregation is crucial to
deciphering the role of different stages and intermediates on the pathology formation
pathways in the pathogenesis of NDDs and potentially identifying new targets for
therapeutic intervention. For example, if the aggregate growth rate is controlled by a
particular cellular mechanism, drugs that target this mechanism may slow or stop the
disease development and progression. Furthermore, a better understanding of the
characteristics of different aggregates on the pathway to pathological inclusions should
facilitate the development of new molecular probes and diagnostic tools for monitoring
early oligomerization events that are thought to contribute to and correlate with early
stages of disease development. LINA enables the live identification, imaging, and
analysis of native aggregates as an important step toward reaching these goals.

Fig. 5a shows our LINA pixel-regression model's performance on dynamic, live-
cell, time-lapse images, taken every 2 minutes, of Httex1-72Q-GFP in a HEK cell, starting
from a diffuse protein state and aggregating over time. LINA can distinguish between the
diffuse protein and the aggregated state, as it only starts to predict an aggregate at the
time-point where the aggregate begins to form, as verified visually from the ground-truth
fluorescence images. It is able to correctly detect the aggregate as it grows in size from
then on, and as it moves along different subcellular localizations. Fig. 5b illustrates the

normalized mean intensity of the output images along time. As the aggregate grows and
more pixels are predicted as parts of an aggregate, the mean intensity of the output image
increases. The mean intensity follows the expected sigmoidal behavior and can be
divided into three regimes. First, for diffuse protein, the prediction intensities are very low,
which shows successful predictions that there are no aggregates. Then, for aggregate
formation, the intensity starts increasing gradually while the aggregate grows, until the
third regime is reached, where the intensity stabilizes into a steady state and the
aggregate stops growing.

The dry mass of aggregates can be extracted from the phase images and the
segmentation masks of the network output images in the same fashion as described
previously for the fixed cells. Furthermore, the area can also be extracted from the mask
of the identified aggregate. Both the dry mass and area are plotted in Fig. 5c, and they
are highly correlated to each other and to the normalized mean intensity. Once again,
they can be split into three regimes: diffuse protein, aggregate formation, and stabilizing
to a steady state. The ability to measure the dry mass and area of living aggregates as
they grow opens up many possibilities for dynamics studies.

Figure 5: Live, label-free identification and analysis of Httex1 protein aggregation. (a) Time-lapse
images, acquired every 2 minutes, of Httex1-72Q-GFP in a HEK cell, starting from a diffuse protein state
and aggregating over time. LINA is able to distinguish between the diffuse protein and the aggregated state,
correctly predicting the aggregate as it grows in size and moves along different subcellular localizations.
Scale bar: 5 μm. (b) Normalized mean intensity of the network output images as the aggregate grows,
following a three-regime sigmoidal behaviour. (c) Dry mass and area changes extracted from the network
output images, split into the same three regimes. (b, c) Error bars represent the standard deviation in each
image.

Discussion

LINA is a label-free method for virtually labeling and identifying protein aggregates using a trained deep-learning CNN, enabling more accurate analysis of the native aggregates, and avoiding label-induced alterations. We have validated LINA quantitatively, showed its applicability on different constructs of Httex1, and verified the models' consistently-accurate performance over various imaging conditions, including varying SNR, cell line, and input type, illustrating the universality of our method. Furthermore, LINA is fully compatible with long-term live-cell imaging, circumventing the issues of photobleaching and phototoxicity, and can be used to identify aggregates and analyze their quantitative parameters (e.g., area, dry mass, morphology, and interaction dynamics). In support of prior studies[14,16,17,48], our characterization and comparison of the dry masses of unlabeled and labeled aggregates further demonstrate the need for using label-free methods to study protein aggregation and inclusion formation in NDDs. We found that mutant Httex1 with a truncated Nt17 domain and a polyQ repeat length of 72Q forms aggregates of the same dry mass on average as the construct with the same polyQ repeat length but maintaining the Nt17 domain. We found that the aggregates formed by Httex1 with a polyQ repeat length of 39Q, which lack the core-and-shell ultrastructural arrangement of the two other constructs, are larger on average, despite a reduction in the number of formed aggregates. This is likely due to the different ultrastructure and aggregation mechanism of Httex1-39Q. Further analysis and comparisons of the characteristics of different label-free Httex1 constructs will be possible using LINA, which could lead to new discoveries into the pathological mechanisms of Huntington's disease and uncover possible therapeutic targets.

Nowadays, artificial intelligence (AI), particularly machine learning, is extensively being used in microscopy for various purposes, including denoising, image-to-image translation, segmentation, classification, and even medical diagnosis[36–39,49–54]. There have also been developments aiming to ease the adoption of these models and democratize their use[55–57]. As with any new technology, there can be mistrust and a reluctance to rely on it, especially when it is a "black box" that is difficult to interpret – fortunately, there has been considerable progress in deciphering how deep learning

models make their predictions[43]. In the case of AI-enhanced microscopy, concern can be
warranted because of the field's fundamental nature and it being a basis for biomedical
discoveries, which makes it truly important for any results to be unequivocally true, as this
affects future studies and research directions which, depending on their success, can
either facilitate or delay the treatment of devastating illnesses. This is especially the case
when it comes to unsupervised learning using generative models, such as those using a
generative adversarial network (GAN). GANs create highly-plausible outputs that can be
hard to distinguish from real data, and it can be difficult to determine if biological
phenomena identified by such a model are true or a hallucination. To mitigate such
concerns, it is important to validate the AI model as much as possible and to discuss the
kind of problem that it excels at solving, as well as the model's limitations. That is why we
validated our models as much as possible, quantitatively, on different protein constructs
and at different conditions.

The detection limit of LINA depends on several factors, notably the size distribution
of the training dataset and the limitations in the images resulting from the microscope
(contrast, SNR, resolution) and the sample (transparency, refractive index heterogeneity).
In our training dataset, we focused on late-stage aggregates, making sure to include
images of aggregates of varying morphologies and sizes, such that the network can be
as general as possible. We show that LINA works well for varying image SNRs, aggregate
sizes and shapes, protein constructs, cell lines, and in live-cell imaging conditions. The
current version of LINA can detect aggregates with areas as small as 3 μm^2. To further
enhance LINA's capabilities for kinetics studies, we aim in future work to expand the
training dataset to include early and intermediate stage aggregates, which would enable
the detection of even smaller aggregates than what is currently possible. This can be
accomplished by re-training a new model on the expanded dataset, or through transfer
learning on a dataset consisting of the earlier-stage aggregates.

We believe that our method has significant potential for characterizing protein
aggregates and inclusions associated with other NDDs. This could be achieved by
following a similar approach of training a CNN from scratch on a new dataset, or by simply
performing transfer learning on our trained model with the new data. Methods to increase
the throughput of the data acquisition, such as the automatic XY-scan mode we use here,

are useful for collecting new data for transfer learning or re-training. Another possibility

would be to image at a lower magnification, increasing the yield from one image, which

we showed is a possibility using our method (Supplementary Fig. 9). However, this comes

at a cost of resolution and information, which will likely complicate the identification of

small aggregates from transmitted-light images, which could be particularly problematic

for live-cell imaging of aggregates as they form. Our method has the advantage of not

requiring manual annotations, as the training labels are directly obtained from the

fluorescence images. Therefore, researchers who are interested in extending our

approach using new data only need access to a microscope capable of imaging in a label-

free modality and any kind of fluorescence microscopy. Additionally, LINA could

potentially be extended in the future to virtually label aggregates from electron microscopy

images. LINA paves the way for studying the molecular interaction dynamics of protein

aggregates and the evaluation of the cellular state in cells containing aggregates, without

the need to rely on labels. It can be extended to virtually label other cellular components,

such as organelles or cytoskeletal proteins, which are known to interact with NDD-

associated protein inclusions, and several studies have already shown their capability to

be virtually labeled[36,37,58]. Moreover, LINA can be further developed to classify the cellular

state[36] of label-free cells containing aggregates to elucidate the mechanisms that disrupt

cellular viability or introduce toxicity. We also envisage several possibilities for LINA to be

correlated with other imaging techniques, opening up new avenues for correlative

microscopy of neurodegenerative diseases.

Methods

Sample preparation

HEK 293 cells were cultured at 37 °C and 5% CO_2 using DMEM high glucose without phenol red (Gibco, Thermo Fisher Scientific), supplemented with 10% fetal bovine serum, 1% penicillin-streptomycin and 4 mM L-glutamine (all three from Gibco, Thermo Fisher Scientific). Cells were plated at a density of 120,000 per dish either on high precision #1.5 25 mm coverslips (Marienfeld) or on FluoroDish Sterile Culture Dishes 35 mm, 23 mm well (World Precision Instruments), coated with fibronectin. Cells were transfected one day after plating using polyethylenimine (PEI) transfection. 2 µg of DNA are mixed in 100 µl of OptiMEM Reduced-Serum Medium (Life Technologies), 6 µl of PEI are mixed in 100 µl of OptiMEM, and then both mixtures are mixed and incubated for 5 minutes at room temperature (RT), then added drop-wise and carefully distributed over the cells. Cells were then returned to the incubator and left either for 48 hours before fixation or for shorter durations before live-cell imaging followed by fixation at 48 hours post-transfection. For fixation, cells were washed twice with PBS pH 7.4 (1X) (Life Technologies, Switzerland) and fixed in 3.7% formaldehyde (Sigma-Aldrich, Switzerland) in PBS (PFA) for 15 min at room temperature (RT). Cells were then washed in PBS then mounted in PBS.

For immunocytochemistry, after a blocking step with 3% BSA (Sigma-Aldrich, Switzerland) diluted in 0.1% Triton X-100 (Applichem, Germany) in PBS (PBST) for 30 min at RT, cells were incubated with the primary antibody (anti-Htt raised against the Proline-rich domain (PRD) (MAB5492, Millipore) at a dilution of 1/500 in PBST for 2 h at RT. Cells were then rinsed five times in PBST and incubated for 1 h at RT with the secondary donkey anti-mouse Alexa488 (Life Technologies, Switzerland) used at a dilution of 1/800 in PBST. Cells were then washed five times in PBST, and finally washed once in double-distilled H2O, before being mounted in PBS.

Data acquisition and processing

All imaging was performed with a custom-built microscope (Supplementary Fig. 14) equipped with a temperature and CO_2 controlled incubator for live cell imaging, as described in previous work from our group[41]. Live-cell imaging was performed in DMEM

without phenol red at 37 °C and 5% CO_2. The microscope is controlled using custom

LabVIEW software. For fluorescence imaging, a 120 mW, 488 nm laser (iBeam smart,

Toptica), is focused into the back focal plane of an Olympus UPLSAPO 60XW 1.2 NA

objective for wide-field epi-fluorescence illumination. The fluorescence light was filtered

using a combination of a dichroic mirror (zt405/488/532/640/730rpc, Chroma) and an

emission filter. For phase imaging, we used the white-light Koehler illumination module of

a Zeiss Axiovert 100 M microscope equipped with a halogen lamp to collect brightfield

images which are later processed into QPI images. The detection path is arranged as a

sequence of four 2-f configurations to provide image–object space telecentricity. The

image splitter placed behind the last lens directs the light into eight images, which are

registered by two synchronized sCMOS cameras (ORCA Flash 4.0, Hamamatsu; back

projected pixel size of 111 nm). For translating the sample, the microscope is equipped

with piezoLEGS stage (3-PT-60- F2,5/5) and Motion-Commander-Piezo controller

(Nanos Instruments GmbH). While collecting our dataset, we acquired any FOV that had

an aggregate, not filtering for particular sizes or shapes, to have a dataset which is as

general as possible. For all imaging experiments and data collection, multiple samples

from at least 3 independent experiments were used for data acquisition.

We used custom MATLAB (R2021a) (Mathworks) scripts (available here) to

retrieve the phase information from the brightfield images and produce quantitative phase

images. These scripts are also used for pixel-registration in the 8 z-planes for both phase

and fluorescence images. The images are cropped to a size of 352 pixels x 352 pixels.

We used Fiji[59] (v2.9.0) scripts to produce maximum z-projection fluorescence

images, to segment these images using Otsu thresholding and produce the labels for

pixel classification, to prepare the color-coded maximum z-projection phase image shown

in Fig. 2a, and for the image processing in Fig. 2b. Fiji was also used to segment network

predictions and produce masks which are used to measure the area, circularity or dry

mass of aggregates.

Python (v3.7) was used for data analysis and plotting. This includes the

quantitative metric calculations and cropping the regions of interest (ROIs), i.e. the

aggregate regions within the images. This was done using Otsu thresholding to produce

a mask from the ground truth image, which is then used to crop the ROIs. The Pearson

correlation coefficient was calculated using the function 'pearsonr' in the scipy library

(v1.7.3), and the MSE was calculated using the mean_squared_error function in the

Scikit-learn library (v1.0.2), then normalized by the square of the sum of the label images,

as defined in the literature[60].

Neural network training

Our models are trained on a deep CNN with a U-Net[42] architecture (Supplementary Fig.

15). Compared to the original architecture, we reduced the number of feature maps by a

factor of 4 which led to a reduction in the trainable parameters by a factor of 15. This

notably reduces GPU memory usage and training time, while still enabling excellent

performance. We used TensorFlow (v2.8.0) and Keras (v2.8.0) to build our network, and

training was done on a workstation equipped with an NVIDIA GeForce RTX 3090 GPU.

We used the adaptive moment estimation (Adam) optimizer with a learning rate of 1e-4

and a mean squared error loss function. Before training our models, we normalize both

the phase and fluorescence images by rescaling each image to be between 0 and 1. We

used 10% of our dataset as the test set and split the rest of the dataset into training and

validation sets with 20% being used for validation. We used the 'EarlyStopping' (on the

validation loss) and 'ModelCheckpoint' callbacks to avoid overfitting and to save the best,

most general models.

Dry mass quantification

664 Supplementary Fig. 13 summarizes the dry mass extraction process. To map between

665 phase information and dry mass, we use the following equation[35]:

$$\sigma(x, y) = \frac{\lambda}{2\pi\alpha} \phi(x, y)$$

667 where σ and ϕ are the dry mass and the phase, respectively, at the location defined by

668 the x and y coordinates, λ is the wavelength of the illumination (here chosen as the

669 average wavelength of our white-light source), and α is the refractive increment, treated

670 as a constant value of 0.19 $\mu m^3 \cdot pg^{-1}$, as recommended in the literature, due to α having

671 an extremely narrow distribution[35,44].

Data Availability

The data provided in the article and the supplementary information are available from the corresponding authors on reasonable request. Source data are provided with this paper.

Code Availability

The Python codes for training a model, using a pre-trained model, and for transfer learning on a pre-trained model are available at:

https://github.com/kibb/LINA/

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Author contributions

K.G. conceived the idea and initiated the project, which was driven by the observations of N.R.; K.A.I., H.A.L., and A.R. designed the experiments; K.A.I., L.F., and N.R. prepared the samples; K.A.I. performed the experiments, acquired, analyzed, and visualized the data, developed and optimized the neural network training pipeline, validated the trained models, and developed the pipeline to extract the dry mass and area measurements; K.A.I. and H.A.L. wrote the paper, with input from all authors. H.A.L. and A.R. supervised the project; All authors discussed the results and commented on the manuscript.

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