ExMove: An open-source toolkit for processing and exploring

animal tracking data in R

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Keywords: Animal movement, Tracking data, Reproducibility, Code sharing, User guide, GPS,

geolocator, ARGOS

Abstract

1.   Ongoing technological advances have led to a rapid increase in the number, type, and scope of animal tracking studies. In response, many software tools have been developed to analyze animal movement data. These tools generally focus on movement modelling, but the steps required to clean raw data files from different tracking devices have been largely ignored. Such pre-processing steps are often time-consuming and involve a steep learning curve. Moreover, decisions made at this early stage can substantially influence subsequent analyses.

2.   Here we present an open-access, reproducible toolkit written in the programming language R for processing raw data files into a single cleaned data set for analyses and upload to online tracking databases. Additionally, we provide a Shiny app to enable appropriate parameter determination during data cleaning.

3.   The toolkit is generalizable to different data formats and device types, uses modern 'tidy coding' practices, and has minimal dependencies. We provide a set of key principles and transparent, flexible code to flatten the learning curve associated with animal movement data processing, and produce robust, reproducible datasets.

4.   Overall, we envision our resource as a time-saving approach that provides a reproducible pipeline from data collection to archiving, useful for anyone conducting animal movement analyses.

1 Introduction

We live in a golden age of animal-tracking data. Recent technological advancements have reduced the size and cost of telemetry devices and improved their capacities, with more species and individuals tracked over longer periods, allowing researchers to expand the frontiers of ecological research (Wilmers et al. 2015; Kays et al. 2015; Bodey et al. 2017). These studies have generated a rapidly expanding volume of data (Kays et al. 2021; Gupte et al. 2021), from an increasing range of device types, with associated formats and errors. This proliferation has complicated the workflow from raw files to a cleaned data set suitable for analysis and sharing, with knock-on impacts for reproducibility. Such pre-analysis steps are universal when working with animal movement data and involve the determination of key filtering parameters to remove data that can strongly influence the conclusions drawn from subsequent analysis. Moreover, these steps are time consuming, often involving a steep learning curve, and large amounts of time and associated grant funding are lost as unacquainted researchers re-run these steps and, in many cases, attempt to re-invent what should be a standardized and reproducible process. Numerous software tools have been developed to facilitate animal movement research (Joo et al. 2019). However, these tools largely focus on conducting movement analyses of cleaned and collated data, and the upstream filtering and processing steps required to generate an appropriate data set have been given scant attention (however see Gupte et al. 2021). The value of transparent data pre-processing and the accessibility of authentic data sets is being realised amid the push towards open and reproducible science. Software tools to facilitate this move are urgently required.

There has been progress in developing tools for pre-processing. Gupte *et al*. (2021) provides an

informative framework outlining the key pre-processing steps involved in processing high-

throughput animal tracking data, alongside a pipeline to implement these steps. However, the

associated atlastools R package wraps these steps up into opaque functions, which may be

challenging for less-experienced analysts to de-bug. Additionally, bespoke functions, whilst

convenient in many instances, essentially constitute a black box and may provide an

impediment to learning. Over-reliance on existing functions may hinder researchers in their

effort to develop a foundational understanding of their animal tracking data and the steps

required to process it. MoveApps (Kölzsch et al. 2022) takes an alternative approach to the

problem, providing an online user interface where researchers can upload and explore their

own tracking data. This provides a tool to rapidly visualize animal tracking data, especially for

researchers who lack programming experience, however the background code is not

immediately apparent to users, which again limits the scope for learning. Moreover, MoveApps

does not allow upload of raw data from tags, requiring pre-processing into specific formats.

Existing approaches demonstrate the need for resources that integrate data processing goals

with user learning and development, alongside trends towards open and reproducible science

(Brunsdon and Comber 2020).

We fill this gap by providing a toolkit of foundational code to process raw tracking files into

clean data sets providing a reproducible starting point for animal movement analysis.

Moreover, we format these data sets for upload to two widely used online tracking databases;

Movebank (Kays et al. 2021) and the Seabird Tracking Database (www.seabirdtracking.org). Our

methods focus on accessible and robust data processing and thorough interrogation of user-

defined parameters, both of which have important downstream consequences for biological

inference. By sharing transparent code, we equip users with tools to learn from and adapt for

their own analyses. This will make processing tracking data accessible to a wider audience,

breaking down financial barriers associated with expensive training courses, while

simultaneously flattening the learning curve for ecologists everywhere. Limited learning

opportunities and confidence in code quality have contributed to historically low uptake of

journal-mandated code archiving (Baker 2016), and this will further contribute towards more

open-access attitudes in science (Potts and Börger 2022; Barnes 2010)

82 2 Aims and objectives

Given the increase in animal movement research, and current gaps in availability and

accessibility of data processing tools, we have developed a toolkit in the programming language

R with the following aims and objectives:

1.   Create a foundational clean data set upon which researchers can build their own

bespoke animal movement analyses.

2.   Provide a flexible pipeline able to process data from a range of tracking devices

including GPS, GLS and Argos.

3.   Streamline the path from data collection to sharing of cleaned datasets in online

repositories to facilitate open-access and reproducibility requirements of funders,

journals, and institutions.

4.   Enable appropriate parameter determination by providing a shiny app for data

visualization, further improving the efficiency of processing.

5.   Generate a learning tool for users to develop skills in animal movement analysis. We

provide code organized into annotated code chunks which prioritize user understanding

rather than wrapping code up in opaque functions.

6.   Limit dependencies and maximize stability by using a well-maintained set of core R

packages, including *here*, *tidyverse* and *sf*. This is timely given the widespread adoption of

tidy-style coding and deprecation of *sp* (Müller 2020; Wickham et al. 2019a; Pebesma

2018).

7.   Provide a suite of tools that can be adapted to process data that contains a timestamp

from any biologging device

105   3 Best practices

106   Producing open-access and reproducible analyses is now a common goal for scientific research

107   (McKiernan et al. 2016; Culina et al. 2020), and there are various ways to version and publicly

108   share code (such as git & GitHub). Here, we outline the core best practices that we have

109   followed to help to ensure that the code itself is reliable and can be reproduced by others.

110   3.1 Directory structure

Directory structure relates to how folders and sub-folders are arranged. We recommend

following the directory structure outlined by Figueiredo *et al.* (2022), which suggests that all

data required for a project should be inside a single directory, with separate sub-folders for raw

data, processed data, and outputs (such as tables and figures). Folders are best named in

snakecase format (e.g., "raw_data") to avoid issues with encoding spaces in filepaths (Trisovic

et al. 2022). For R Studio users, this folder structure is enhanced with the use of R Studio

projects, whose location denotes the 'top' of the directory allowing for shorter, reproducible

filepaths. We also use the here package to maximise reproducibility between operating systems

that use different file path delimiters (Müller 2020). When used in combination, these best

practices ensure that when sharing or archiving a single project folder, other users have all the

data required to recreate your analyses, and results will be reproducible regardless of their

machine.

3.2 Data structure

Raw animal tracking data should be saved into a "raw_data" folder in the exact format they are

downloaded or decompressed from devices (i.e., completely unaltered). These files should be

considered read-only and must not be opened with other software (such as Excel) which can

cause problems in changing data formats. Data from different devices will usually arrive in

separate files and as such there should be one file per individual (though some cases and data

sources may mean that data are combined in some way). Metadata files are generally also

saved in raw_data and are usually a single file per dataset containing all additional data for each

tag deployment, for example individual ID, tag ID, tagging location/time or location of central

place.

3.3 Code structure

The tidyverse is an increasingly used approach for coding in R, with a collection of core

packages that use consistent grammar and data structures that allows user to quickly create

analyses that can be easily understood by others (Wickham et al. 2019b). To follow tidyverse

coding practices, data should adhere to three core rules: i) every variable must have its own

column, ii) every observation must have its own row, and iii) every value must have its own cell

(Wickham 2014). Tracking data inherently follow this tidy structure, with rows as observations,

with at minimum require a column for time, plus additional columns for variables associated

with each time point (e.g., latitude and longitude, depth, temp etc.). Finally, focusing on using

core *tidyr* packages (specifically *tidyverse* and *sf*), helps to maximise code longevity.

4 Overview of the workflow structure

Here, we provide an outline of the data workflow structure and methods (Figure 1) that enable

a user to import raw tracking data and metadata, perform basic to advanced cleaning, filtering

and processing steps, ready for further scientific analysis. We will introduce the required data

structure and outline the flexibility and utility of the workflow for anyone undertaking analysis

of animal movement data.

Figure 1: Diagram of workflow used for analysing movement data (thick line denotes core path of workflow)

Key principles of clean data

By following this workflow, the user will achieve the following minimum requirements for clean

data:

1. Standardise date and time formats across time zones

2. Remove rows with corrupted timestamps

3. Include relevant metadata

4. Remove no data values (e.g., "NA", "0,0" in lat/longs or other erroneous sensor values)

5. Remove duplicates

6. Remove undeployed locations (e.g., before tag attachment)

7. Standardise spatial projections

8. Remove erroneous speeds and locations

9. Remove locations at start of tracking period when behaviour is influenced by capture

4.1 Import data, metadata, and combine

The workflow starts with reading in raw tracking data and metadata files. Raw tracking data

refers to data downloaded directly from biologging tags, which fundamentally must contain a

time stamp and sensor data (e.g., location, light levels, immersion). We also provide alternative

code for data that have already been partially processed, for example data downloaded from

an existing repository that contains multiple tags and/or individuals. Metadata provide essential

technical, biological and ecological context for the raw data, such as the tag deployment period,

sex, age and population. Metadata should contain one row for each tag deployment per

individual, with ID numbers corresponding to those in the raw data. The ID numbers are used to

match each row of the raw data to the corresponding metadata. Additional code is provided to

handle scenarios where a single individual has carried multiple tags in its lifetime, or a single tag

has been deployed on multiple individuals. Example data are saved as .csv files (see

supplementary files), and guidance is provided for importing data in other text-based formats

(e.g., such as .txt or .tsv.).

Figure 2. Example mutating join of raw GPS tracking data file (red) and metadata file (green) using left_join, with "animal_id" as the index column. Note that accuracy of latitude and longitude data has been reduced for clarity.

4.2 Cleaning

The cleaning step removes data that are incorrect based on deployment periods and technical

tag information. This includes limiting data to the deployment period (i.e., for loggers

programmed to start ahead of deployment or not turned off immediately following retrieval),

removing duplicate rows, and removing NA's or known values that correspond to missing data

based on tag manufacturer guidance. Some tags record a specific 'no data' value when sensor

information cannot be derived (e.g., "0,0" for latitude and longitude).

4.3 Processing

During the processing step we calculate spatial and temporal metrics to allow downstream

analyses and filtering of data based on ecological knowledge. These include metrics pertaining

to distance traveled, net displacement, time steps, travel speed and turning angle (relative to

previous trajectory) and travel bearing (relative to true north). For central place foragers, we

calculate distance and bearing to the central place.

All spatial data possess a coordinate reference system (CRS) that refers to the 2D projection of

the earth's surface used to represent locations. The most common CRS used for biologging

devices is WGS84 (units: latitude and longitude). During the processing step the user must

define the CRS of their data. We recommend transforming to a 'equal area projection' for

spatial calculations (e.g., distance between points), particularly when tracking data spans a

large geographic range.

D

E

F

Figure 3. Processed metrics derived from animal tracking data. Plot A depicts a movement track of a Greenland White-fronted Goose with three different metrics labelled: i) step length, ii) turning angle and iii) travel bearing. The net displacement (plot B) and speed (plot C) over time is shown for the movement track plot A. Plot C depicts a single foraging trip of a Red-footed Booby from a central place (grey filled diamond). Two metrics are labelled here: iv) distance to central place and v) bearing to central place. The distance to colony (plot D) and cumulative distance traveled (plot E) are shown for the track in Plot C.

4.4 Enter the Shiny app

The Shiny app is designed to determine user-input parameters throughout the workflow by

exploring their downstream effects on the resulting data frames. When processing animal

tracking data, prior to analysis, users often select rather arbitrary values by which to filter data,

i.e., to eliminate erroneous speeds users often remove points creating speeds above a selected

threshold. The app allows users to explore the implications of these arbitrary decisions via

interactive manipulation of threshold values and subsequent visualizations that include, data

summary tables, histograms of the variable of interest and maps. This app workflow is designed

to be iterative. Allowing users to explore threshold choice at multiple points in the workflow,

between processing and filter steps and prior to post-processing steps. There are multiple tabs

to navigate within the app after users have read in their own data, in each there are a series of

interactive user input threshold values and a number of plots and tables detailing the

consequences of the user selected values (Fig 4). There are tabs for basic data filters

(e.g., speed, post-deployment period and date), calculating foraging trips for central placed

foragers, sub-sampling location frequency, segmenting movement tracks and finally visualizing

the locations in an interactive leaflet map. To facilitate integration with the main workflow

there are code chunks output at the bottom of each shiny tab that contain the selected

parameter values, which can be copied into the workflow.

Figure 4. Shiny app to explore and visualise tracking data and test the influence of parameter selection on filtering and post-processing. The data filters tab is depicted here, and each labelled element is described in more detail here. Data upload: search the users system for a file to upload to the app, this should be the equivalent of df_diagnostic. Toggle tab: toggle between different tabs in the app, for each tab the user input box and outputs will change. Info Boxes: summary information of the tracking data that is calculated automatically for the tracking uploaded by the user. User Values: Values that the user can alter that specify the parameters in filtering or post-processing steps. These maybe be sliders, buttons, dropdown menus or calendar date selectors Help; Click to access a pop-up help page that guides users through each tab. Action; press this button to apply the current user value selection to the data. Plot Controls: change whether all or a single individuals is depicted in a map. The specific

individual visualised can be chosen using a dropdown menu

4.5 Filter

The filter step allows users to remove erroneous locations based on three derived variables: 1)

speed, 2) net displacement and 3) time since tag deployment. Each of these are calculated

during the processing step. The threshold values selected by the user to remove data can be

explored within the shiny app. Ecological knowledge can help inform the thresholds used, for

instance a species' maximum travel speed or likely displacement from tagging location. We

encourage users to explore a range of values in the shiny app and consider the resulting

implications for the data retained.

4.6 Summarise

This step provides a full summary of the data that the user has retained after the filtering step.

This is an important opportunity to scrutinize the integrity of the data and determine if further

filtering is required. The user selects grouping variables for the data — we suggest initially

grouping by individual but broader groupings may be required depending on the type of

analysis to be undertaken (e.g., year and population). For each level of the grouping variable

the following summary statistics are provided: number of locations, number of unique tracking

days, start and end dates of tracking period, and the sampling frequency locations.

4.7 Visualisation

Visualisations are an essential part of exploring and understanding a dataset. As such, we

provide code for a series of figures and maps for the user to view the data, validate previous

steps and inform future steps. This may elucidate erroneous data that have been overlooked.

We also provide code to map the data, providing an initial spatial visualisation of animal

movements. Plots of speed and step length offer a further opportunity to screen data for

errors. Plots can be visualised with all individuals at once or faceted by individual. It should be

noted that there are numerous visualisations in the shiny app that serve much the same

purpose, including an interactive map to aid data visualisation and parameter determination.

4.8 Post-processing (optional)

Some types of animal movement analyses require additional processing to prepare data, such

as defining segments (e.g., separating tracks into bursts of continuous data to avoid over-

interpolation across large gaps), sub-sampling (e.g., to down sample tracking data to facilitate

comparisons among datasets with different sampling regimes), and identifying distinct trips

made by central place foragers. Additional scripts are provided to perform these analyses,

designed to follow on from the main code workflow. Scripts can be run iteratively if additional

post-processing steps are required. Each script contains tools to summarise, visualise, and save

the post-processed data. The shiny app can also be used here to aid parameter determination.

Figure 5. Example of sub-sampling GPS tracking data using an optional processing step. The data used are from two Greenland White-fronted Geese migrating from the United Kingdom to Iceland. Panel a depicts a histogram of sampling intervals present in the data, clearly there is a mixture of data collected at one- and two-hour resolution. Therefore, to make sampling intervals consistent the data were sub-sampled to 2 hours (dashed vertical line). In panel b the output of this sub-sampling is visualized and retained (red) and removed (grey) GPS fixes are shown. The individual starting from a more southerly location was originally collected at a 1-hour resolution hence roughly every other fix is removed.

4.9 Standardising output for tracking databases

Many users may need to archive their data on an online database, which often require data to be in a specific format before files can be uploaded (Kays et al. 2021b). As such, we provide code for users to format and save their data, processed within the workflow, in the required format of two common tracking databases: (1) MoveBank, and (2) the Seabird Tracking Database.

5 Tools and additional practical resources

5.1 Preparing your machine

In order to make use of the included materials, users need to have downloaded R and the
RStudio IDE (Ihaka and Gentleman 1996). Our code is compatible with R versions 4.0.3 - 4.2.1.
In general, it is recommended that users are not more than two sub-versions behind the most
recent release of R.

5.2 Updating packages

We make use of the most recent releases of core packages in the *tidyverse* (Wickham et al.
2019), which is composed of *ggplot2* (v3.4.0), *dplyr* (v1.0.10), *tidyr* (v1.2.1), *readr* (v2.1.2), *purrr*
(v1.0.1), *tibble* (v3.1.8), *stringr* (v1.5.0) and *forcats* (v0.5.1), as well as *lubridate* (v1.8.0). We also
use *sf* (v1.0-9) for spatial analyses, and the *here* package (v1.0.1) for making reproducible file
paths (Pebesma 2018; Müller 2020).

5.3 Using GitHub

ExMove GitHub repository can be utilised in a variety of ways, accessible to all levels of
experience and desired user outcomes. Users can either: i) 'clone' an updatable version of the
ExMove repository via git, ii) download a static copy of the entire repository by navigating to <>
Code > Download ZIP, or iii) view and download individual scripts as required. To maximise
reproducibility and future functionality, our recommended approach would be to set up
R/RStudio with git version control, set up and connect a personal GitHub account, then clone

the ExMove repository. Additional information and links for on getting set up with GitHub and

RStudio can be found in the ExMove repository readme (https://github.com/ExMove/ExMove).

5.4 User guide

We also provide a browser-based user guide that follows each step of the workflow, with

worked examples in baseR and tidy code. This guide also contains example outputs of data

frames and plots produced for each step

(https://github.com/ExMove/ExMove/tree/main/Documentation)

5.5 Shiny app

The shiny app is available online at the following link:

https://lukeozsanlav.shinyapps.io/exmove_explorer/. There is an upload limit so users can

either explore the app with examples data sets we provide or a subset of their own data. If the

user wants to run the app on their full data set, then we recommend that they fork the

repository and then run the app locally on their own machine.

5.6 FAQ's

Some important principles of movement and spatial analyses can be a common source of

confusion (for example: understanding data projections). Given ExMove's goal as a learning

tool, we provide information to help facilitate better understanding of these core concepts, and

links to useful materials made available by others (FAQ page can be found here:

(https://github.com/ExMove/ExMove/tree/main/Documentation).

6 Try it yourself

Within the GitHub repo we provide four road-tested example datasets for users to familiarise

themselves with running the pipeline. These datasets are from Trindade Petrels (*Pterodroma*

arminjoniana, panel A) breeding on Round Island, adult and immature Red-footed boobies (*Sula*

leucogaster, panel B & D) breeding in the Chagos Archipelago and Greenland white-fronted

goose (*Anser albifrons flavirostris*, panel C) migrating from Ireland and Scotland to Greenland

(see Figure 6).

Figure 6. Visualisation of the three example datasets provided as part of the pipeline. A: Trindade petrel. B: Immature red-footed booby. C: Greenland white-fronted goose. D: Adult red-footed booby.

6.1 Trindade petrel data set

GLS data from one Trindade petrel tracked during its non-breeding migration in 2011. Devices

were deployed and retrieved when the individual was resting on Round Island Nature Reserve

(19.85° south; 57.78° east), situated 23 km off the North coast of Mauritius, Indian Ocean. Full

methods and ethics are detailed in Nicoll *et al.* (2016).

6.2 Red-footed booby data sets

GPS data from three adult red-footed boobies tracked during 2016 and 2016 using igotU

loggers (Figure 6B). Data represent central-place foraging trips of breeding adults from two

colonies, Diego Garcia and Nelsons Island in the Chagos Archipelago, central Indian Ocean.

Tagging methodology and ethical considerations can be found in Trevail *et al.* (In review,

MEPS).

Argos data from two immature red-footed boobies tracked during 2022 using Microwave

Telemetry Solar Argos/GPS PTT loggers (Figure 6D). Data represent movements of individuals

that have not yet recruited into a breeding population, tagged whilst roosting on East Island in

the Chagos Archipelago, central Indian Ocean. Tagging was conducted under ethics approval as

in Trevail *et al.* (In review, MEPS).

6.3 Greenland white-fronted geese data set

GPS data from four Greenland White-fronted Geese tracked during spring 2018 and 2019

(Figure 6C). These data cover the entire spring migration from Ireland and Scotland to

Greenland with a stopover in southern Iceland. Two individuals originate from Islay, Scotland

and two from Wexford, Ireland. Tagging methodology and ethical considerations can be found

in Ozsanlav-Harris *et al.* (2022).

Acknowledgments

Alice Trevail was funded by the Bertarelli Programme in Marine Science, who also funded collection of adult and immature red-footed booby data. We thank the Wildfowl and Wetlands Trust for providing tracking data from Greenland White-fronted Geese. We thank Malcolm Nicoll for valuable comments on an earlier version of the manuscript, and for providing tracking data from a Trindade petrel. The Trindade petrel tracking programme (Round Island, Mauritius) was supported by NERC (Grant NE/H5081500) and Research England, with thanks to Mauritian Wildlife Foundation (MWF) and the National Parks and Conservation Service (NPCS). We also thank Evelyn Alexander, Jacqueline Glencross and Tess Handby for providing valuable feedback on the code, workflow and Shiny app.

Author contributions

All authors contributed equally to the manuscript.

Data availability statement

All data and code presented in this manuscript can be found in the following public GitHub repository: https://github.com/ExMove/ExMove. All tracking data sets used are cited appropriately in the 'Try it yourself' section.

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