Influence of visual information on sniffing behavior in a routinely trichromatic primate

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ABSTRACT

Most catarrhine primates are considered to be strongly visually oriented, obtaining

information about conspecifics and their environment from a diversity of visual cues. Other

sensory modalities may provide information that is redundant and/or complimentary to visual

cues. When cues from multiple sensory modalities are available, these may reinforce or

suppress each other, as shown in several taxa ranging from insects to humans. Here, we tested

how the presence and ambiguity of visual information affects the use of olfactory cues when

exploring food and non-food items in semi-free ranging Barbary macaques at Affenberg Salem,

Germany. We presented monkeys with pipes containing food (peanuts, popcorn), non-food

(stones, feces) or no items in transparent or opaque containers, and assessed whether animals

looked, sniffed and/or grabbed into the pipes depending on visibility of the contents

(experiment 1). Visual information had no robust effect on sniffing probability, but it did affect

sniffing behavior with respect to the timing of olfactory inspections (i.e. whether sniffing

occurred first). Both visual and olfactory information affected, whether or not monkeys

attempted to retrieve the items from the pipes. Furthermore, we manipulated the visual

appearance of familiar food items (popcorn) with food colorant (experiment 2), which resulted

in substantially increased olfactory inspections compared to unmanipulated popcorn. Taken

together, reliance on the olfactory sense was modulated by the available visual information,

emphasizing the interplay between different sensory modalities for obtaining information

about the environment.

Keywords: multimodal information, olfaction, vision, food assessment, Barbary macaques

INTRODUCTION

Animals gain information about their physical and social environment using different sensory

channels. Information can be conveyed via vision, audition, olfaction or other sensory

modalities either by a single or multiple sensory channels in combination. In fact, sensory

information is frequently multi-modal (i.e. encompassing more than one modality) in nature

and integrating information from multiple modalities is widespread throughout the animal

kingdom (e.g. Rushmore et al. 2012; Higham and Hebets 2013). Well-known examples include

aposematically colored insects, which typically also emit an odor or sound when approached

by a predator, or courtship signals encompassing combinations of visual, acoustic, tactile

and/or chemical elements in a range of taxa (e.g. insects, fish, birds, see review in Hebets and

Papaj 2005). The different modalities may thereby provide redundant or complimentary

information simultaneously or sequentially, which may reinforce or in other ways interact with

each other, and/or act at different spatial or temporal scales (Hebets and Papaj 2005). As a

result, multimodal information may be more accurate, salient or diverse, more robust to noise,

more memorable or available across a larger range than information conveyed via a single

modality (Hebets and Papaj 2005; Higham and Hebets 2013; Leonard and Masek 2014).

Many multimodal studies focus on relatively easily recordable modalities like vision

and audition, but an increasing number of studies show multimodal interactions involving

olfaction as well (reviewed in Hebets and Papaj 2005). The interplay of olfaction with other

senses has been studied relatively well in insects and insect-plant interactions (reviewed for

bees in Leonard and Masek 2014), but rather little in vertebrates (see Melin et al. 2019).

Nonetheless, there is evidence that the availability and salience of information in one modality

may affect to what extent vertebrates attend to other sensory modalities, including olfaction,

in various contexts (e.g. communication in lizard *Liolaemus pacha,* Vicente and Halloy 2017;

foraging bats *Artibeus watsoni* and *Vampyressa pusilla*, Korine & Kalko 2005; odor detection in

humans, Gottfried and Dolan 2003).

Among primates, vision and olfaction have been suggested to be the main senses in

foraging ecology (e.g. Dominy 2004; Rushmore et al. 2012; Veilleux et al. 2022). Most primates

are strongly visually oriented animals (Kawamura 2016). They have three-dimensional vision

and are the only eutherian mammals to have developed trichromatic vision, albeit not in all

taxa (Jacobs 2009; Kawamura 2016). More specifically, catarrhine primates (Old World

monkeys and apes) and howler monkeys have evolved routine trichromacy, while many

platyrrhine species (New World monkeys) show a polymorphism that results in heterozygous

females being trichromatic and homozygous females as well as all males being dichromatic

(Kawamura 2016). Primates in all taxa also routinely rely on olfaction in foraging, social and

sexual contexts (e.g. Drea 2015; Vaglio et al. 2016; Jänig et al. 2018; Kücklich et al. 2019).

Importantly, the reliance on olfaction has been suggested to be related to visual capabilities, as

dichromatic white-faced capuchins (*Cebus imitator*) sniffed fruits more often than trichromatic

conspecifics (Melin et al. 2019). However, no clear relationship between sniffing and chromacy

was found in black-handed spider monkeys (*Ateles geoffroyi*, Hiramatsu et al. 2009). Similarly,

the sense of smell was reported to have higher subjective value in blind than sighted humans

and olfactory bulb size was found to be larger in early blind people (reviewed in Sorokowska et

al. 2019), although there is no robust evidence for a behavioral difference in olfactory abilities

between blind and sighted people when corrected for publication bias (Sorokowska et al.

2019).

Reliance on olfaction in primates has further been suggested to be related to feeding

ecology and the sensory cues provided by food items (Nevo and Heymann 2015). For instance,

black-handed spider monkeys (Hiramatsu et al. 2009), but not white-faced capuchins (Melin et

al. 2019), were found to sniff more at visually less conspicuous fruits. An interplay between

different senses in foraging success was shown in nocturnal grey mouse lemurs (*Microcebus*

murinus), which were able to detect their insect prey using either visual, acoustic or olfactory

cues in isolation but performed best when cues from all three modalities were available

together (Piep et al. 2008). Similarly, folivore Coquerel's sifakas (*Propithecus coquereli*)

required visual and olfactory cues together to reliably identify more nutritious food, while

generalist ring-tailed lemurs (*Lemur catta*) could use either modality alone, and frugivore

ruffed lemurs (*Varecia variegata*) could use olfactory, but not visual, cues alone to select the

more nutritious food items (Rushmore et al. 2012). Hence, current evidence points towards

olfaction in primate feeding ecology being relevant primarily for food selection and when

visual information about food quality is lacking or ambiguous, although the overall evidence is

mixed and data are still too scarce for robust conclusions (Hiramatsu et al. 2009; Nevo and

Heymann 2015). Furthermore, with the exception of a few studies in humans, data on the

interplay between vision and olfaction are lacking for species that are routinely trichromatic.

Barbary macaques (*Macaca sylvanus*) are feeding generalists (Fooden 2007) with

trichromatic vision (Niimura et al. 2018). They use olfaction in a range of contexts but direct

the majority (~80%) of sniffs at food (Simon, Widdig & Weiß, bioRxiv 2022.08.08.503203).

Within a project on the role of olfaction in this catarrhine primate, we here investigated the

interplay between visual information and olfaction in two experimental feeding contexts. In

experiment 1, we provided Barbary macaques with food or non-food items in either a visible

or non-visible condition to assess i) if visibility affected the propensity to sniff at the setup

during any stage of exploring it, ii) if visibility affected at what stage of the exploration

monkeys used olfaction, and iii) the interplay between visual condition, olfaction and the

(attempted) retrieval of items from the setup. We expected monkeys to be more likely to sniff,

and use sniffing as the first type of inspection if visual information was absent. We further

expected that they use olfactory information gained in the non-visible condition to inform

subsequent behavior (i.e. attempting to retrieve the content or not). In experiment 2, we

manipulated the visual appearance of a familiar food item, i.e. popcorn, with food dye to

assess how the salience in visual information affected sniffing behavior. We expected that

popcorn with unfamiliar visual appearance (i.e. dyed popcorn) would be sniffed more

frequently than naturally colored popcorn. We initially also intended to assess whether sniffing

and visual appearance jointly affected whether or not items would be discarded or eaten, but

restrictions in the experimental design as well as a very low prevalence of discarded popcorn

prevented us from explicitly testing this.

METHODS

Study population

The study was conducted at Affenberg Salem, Germany in February and March 2021.

Affenberg Salem is home to ~ 200 Barbary macaques in three naturally formed social groups

that range freely year-round within a 20ha forested enclosure. The park is open to visitors

from spring to autumn, and is an active site of research year-round. Visitors are restricted to a

designated path, while researchers have access to the entire park area. As a result, the

monkeys are well-habituated to human presence (see de Turckheim and Merz 1984 for details

on the park). The monkeys feed on plants and insects found naturally within the park and are

supplemented daily with fruit, vegetables and grain. Water is available ad libitum in ponds and

water troughs throughout the park. Individuals are identifiable from natural markings such as

facial pigmentation patterns, coat color and stature as well as an alphanumeric code tattooed

on the inner thigh. Individual life histories, group memberships and maternal relatedness are

known from near-daily monitoring by staff.

Experiment I: transparent *vs.* opaque pipes

Setup

We experimentally presented the monkeys with different food and non-food items in a visible

and non-visible condition at 12 sites throughout the park. Hence, experiments took place in a

near-natural environment without spatial or temporal restrictions of access. For logistic

reasons, we split the experiment into three blocks, during each of which four sites were active

simultaneously. In each block, the four active sites were distributed across the home ranges of

all three groups. Sites were set up in locations routinely used by the monkeys but not directly

at the feeding areas.

At each site we fixed a grey drainage pipe (11cm diameter) with a 90° angle to the bottom of a

tree. One, open end of the pipe faced upwards, the other to the right (when viewed from the

front) as depicted in Fig. 1. The end pointing to the right was closed with a transparent or an

opaque food storing can (made of hard plastic, 11cm diameter) using cable ties. The opaque

storing can was identical to the transparent one but coated with a layer of grey duct tape

(without appreciable odor to the human observers) on the inside. While we cannot fully

exclude that monkeys may have been able to smell the tape inside the can, this should have no

effect on whether or not monkeys sniffed, or when monkeys sniffed first (see description of

response variables below), because any potential odor of the tape would only have become

available after already having sniffed. Due to the angle and dimensions of the pipe, items

placed into the can were not visible (as assessed separately by 3 different human

experimenters) from the top opening of the pipe, but only through the walls of the can if this

was transparent (Fig. 1). All cans were punctured three times at the bottom to allow the odors

of the content to be perceivable not only from the top opening of the pipe but also when

sniffing the bottom of the can (see Fig. 1). Pipes were fixed to trees with black belt straps

(38mm width, polypropylene), with the opening at a height of 30-40cm. The dimension and

height of the setup allowed monkeys to inspect the setup and also to grab into it from the top

to retrieve items from the can.

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Figure 1: Setup for the pipe experiment with a transparent (left) or an opaque (right) storage

can affixed to a drainage pipe. In the example shown, both cans are baited with popcorn, but

the popcorn is only visible from the outside when the can is transparent. The setup is open at

the top; and storage cans are punctured at the bottom to allow for olfactory investigation from

either the top or the can.

At each site, approaches to and interactions with the setup were continuously monitored with

two wildlife cameras (Crenova 4K 20 MP) mounted to neighboring trees to cover the setup

from two different angles. Cameras were set to record a full HD video (avi format with

1920x1080p resolution) for 1min without sound whenever detecting movement with their

motion detectors (see Supplement S1 for details). Cameras were equipped with a night mode

which used infrared light, allowing for 24/7 monitoring.

Experimental design

At each site we first conducted a 2d habituation phase to familiarize the monkeys with the

setup and its location. During the entire habituation phase a transparent can was attached to

the pipe, and the pipe was filled with food items (3-6 pieces of peeled peanuts or popcorn) at

random intervals 6-8 times per day.

The habituation phase was followed by a 7d test phase. In the test phase, the transparent can

was exchanged with an opaque can every few hours and the can was filled with different food

or non-food items or was pretended to be filled but left empty (see details below). At each

site, the setup was filled 6x/d using the following semi-randomized manner: we divided

daylight hours (7 a.m. to 7 p.m.) into six 2h time slots. In each slot, a given setup was filled

once within the first hour of the slot, whereby we randomly determined the start time (0, 15,

30 or 45 min of the first hour) for filling the first setup and the order in which the four sites

deployed simultaneously were visited. This ensured that the experiment covered the different

daytimes evenly without making the visits to the respective setups easily predictable. In this

way there further was at least one hour between consecutive visits to the same site, thereby

increasing chances that one or several monkeys passed the setup while filled with a given

content.

At each visit, the can was filled with one of 7 possible contents (5 types of contents, 2 of them

in two different quantities as described below). To provide an incentive for exploring the setup

with different senses rather than grabbing inside by default, we did not only fill the setup with

food items but also non-food of similar size to the food items or nothing at all. As food items

we either used pieces of peeled peanuts or popcorn, which were provided in two different

quantities (3 or 6 pieces) to vary the intensity of their odor. As non-food items we either used

3 stones or 3 small pieces of Barbary macaque feces. We chose stones as presumably neutral,

odorless items (i.e. neither particularly desirable nor undesirable for the monkeys). Stones

with an approximate size of the peanut pieces were collected within the park area, washed

with a neutral soap and water, and then rinsed with distilled water before use in the

experiment. In contrast, feces were used as a potentially aversive item, as contact with feces

may increase the risk of contracting infections and is avoided in numerous species (e.g. Case et

al. 2020; Lopes et al. 2022). Feces were collected opportunistically whenever individually

identified, adult monkeys were seen to defecate. Feces were stored in 30ml glass vials with

screw top sealed with parafilm and were frozen at -20°C within 2h after collection. Feces were

defrosted ~30min before use and sized to approximately match the size of the peanut pieces.

We used feces from both sexes but from other groups than the group using the area of the

experimental site. As the experiment was conducted in a near-natural environment without

spatial or temporal restrictions in access to the setup, monkeys could potentially observe the

filling of the setup. To better disentangle whether a filling event or the items in the setup

affected exploratory behavior, we therefore included a 7th possible content, for which the can

was pretended to be filled by reaching into it, but was left empty. All items were handled with

disposable gloves, and the experimenter wore a medical mouth-nose cover. At each visit

potential remains of the previous filling were removed, the inside of the setup was wiped first

with 70% Ethanol (Carl Roth) and then with distilled water to remove residues of the ethanol

before being refilled.

Over the course of the 7 test days, each of the 7 possible contents was presented once in the

transparent and once in the opaque condition in three of the six 2h time slots: one of the first

two, one of the middle two and one of the last two slots of the day (i.e. 7 contents x 2

conditions x 3 daytimes = 42 times). The order of these 42 filling events was randomized

conditional on the following rules: a maximum of 3 consecutive fillings without edible items

and no empty conditions twice in immediate succession at a given site (to keep the incentives

up), and at least one but a maximum of three changes between transparent and opaque cans

per day and site (to balance randomization with feasibility). This randomization procedure was

done separately for each site, so that the order of conditions and contents was also

randomized across sites.

Coding

We first screened all recorded videos and discarded the "false alarms", in which the cameras

were triggered by movement in the background or other animals than the monkeys (e.g. mice

at night). We kept a total of 6570 videos in which one or more monkeys approached (i.e.

interacted with or passed within 1m of) the setup. This number comprises the videos recording

the same approach(es) from both angles by different cameras, whereby we only coded one of

the simultaneously recorded videos if all behaviors were discernible from a single angle. It

further comprises 181 videos recorded in the early morning hours after the end of the 7d test

phase but before the setup was dismantled.

From the videos we scored each individual monkey's approach. Videos could encompass

multiple approaches per video or multiple, successive videos per approach, if the monkey

remained at the setup for more than 1 minute. For each approach we scored from the video

the date and start time as well as whether or not the individual looked, sniffed or grabbed into

the setup (see sample videos in Supplements S2a-c). Looking was scored when the

approaching animal oriented its eyes towards or into the opening or can of the setup. This was

typically accompanied by a clearly noticeable movement and re-orientation of the head from a

distance of less than 50cm, with the eyes closest to the setup while the snout and nose were

pulled back towards the neck. Sniffing was scored when an animal placed its nose within 5cm

of the opening or can, with the snout and nose stretched forward and placed closest to the

setup. For both looking and sniffing we differentiated whether the behavior was directed at

the opening of the pipe and/or can. Grabbing was defined as moving the hand (and arm) into

the opening of the pipe so that at least the entire hand was inside the pipe. If a grab occurred,

we also scored whether the monkey successfully retrieved anything from the setup. We scored

any other interactions of the monkeys with the setup (e.g. climbing, tugging, biting into it) as

"other", and further coded the order of the respective behaviors. The manipulation of the

setup by the monkeys sometimes led to a slight shift in the pipe's orientation. As a

counterclockwise shift could potentially dislodge items from the can towards the bend, where

it might have been visible from the opening irrespective of whether the can was transparent or

opaque, we also scored the orientation of the pipe's opening to statistically take into account

the possibility that items may have become visible from the top opening (see Supplement S1

for details). All individual identities were scored from video by an observer with 2yrs

experience in identifying the study animals. Behaviors were coded from video by a total of 6

different observers blind to the content of the setup, at least in the opaque condition (see

Supplement S1 for details and inter-observer reliability).

Based on the experimental schedule and field notes, we determined information on condition

(transparent or opaque), the exact time and content of the preceding filling for each approach

at each site. By combining information on what was filled into the setup when, what was

visible in the can on the video, what monkeys retrieved at a given visit to the setup and what

was left in the setup at the next filling event, we were able to confidently deduce the actual

content of the setup at the time of each individual approach.

For 7 of the 12 sites, the coded videos encompassed all monkey approaches to the setup

(viewed from one or both angles) over the entire test phase. Hence, this also encompassed all

approaches after (other) monkeys had already retrieved the items, which represents

additional cases of an empty setup similar to when the setup was only pretended to be filled.

At the remaining 5 sites, coding all approaches was not feasible because they were visited too

frequently. For these sites we coded no more than the first 7 approaches after a given filling

event and discarded the remaining videos (and thereby those approaches in which the setups

were likely no longer baited). Overall, we analyzed 3590 videos, which corresponded to 1556

different approaches. All approaches took place during full daylight (98%) or late dawn (2%).

Statistical analysis

To assess the role of visibility on sniffing behavior as well as the consequences of olfactory

inspection for further interactions of monkeys with the experimental setup, we constructed

four generalized linear mixed models (GLMMs) in R (version 4.2.2, R Core Team 2022) using

the function glmer in package lme4 (version 1.1-31, Bates et al. 2015). All 4 models were run

with binomial error structure with logit link function. For these analyses, we only considered

approaches in which the animals interacted with the setup (1431 of 1556 scored approaches,

i.e. excluding those in which animals just passed by), all of which took place during daylight

hours. To be able to account for repeated observations of the same individuals, we further

used only those approaches for which we could identify the involved individual, i.e. 1399

approaches by 126 different individuals (which interacted with the setup 1-84 times). The

sample sizes actually used differed between models for analytical reasons as described below.

As only food, but none of the other items were supplied in different quantities and a

preliminary analysis suggested no differences in sniffing or grabbing behavior in relation to the

quantity of items (Roderer 2021), we did not differentiate between quantities in the main

analyses (models 1-4) to allow fitting all types of contents (peanuts, popcorn, stones, feces or

nothing) in the same model. Details and results of a model investigating a potential effect of

quantity on grabbing behavior when the setup contained peanuts or popcorn are presented in

Supplement 1.

Model 1 was formulated to investigate the influence of the visibility condition (i.e. transparent

or opaque can) on the propensity to sniff at the setup during any stage of exploring it. This

model tested the prediction that visibility affects sniffing behavior. We fitted the model with

sniff (yes/no) observed as response variable, using 1354 approaches which represented 853

cases with and 501 cases without sniffs by a total of 97 different individuals. As fixed effects

test predictors, we modelled the visibility condition (transparent vs. opaque can), the actual

content of the setup at the time of the approach (i.e. peanuts, popcorn, stones, feces or

nothing) and the interaction between visibility condition and content to account for the

possibility that different items were more or less likely to elicit sniffs in the transparent

condition. We also fitted interactions between visibility condition and two control predictors:

cohort (i.e. birth year of approaching individual) to account for age-dependent differences in

the use of sensory modalities, and the number of days a given site was already active to

account for a potential learning effect across time. As fixed effects control predictors, we

further included sex (male/female), group (C, F or H), the experimental block (1-3, fitted as a

covariate), the time (in min) since the last filling, the orientation of the pipe's opening (see

Supplement S1) and, to account for potential differences in activity patterns, the hour of the

day. We further fitted the identity of the coder, the monkey ID, the date and the site as

random intercepts to account for repeated measures and the random variation imposed by

these grouping factors.

Model 2 used only data for the 7 sites for which all approaches had been coded (973

approaches by 80 different individuals of which 609 were with and 364 without sniffs). Coding

of all approaches allowed us to also determine the time (min) since the previous approach to

the setup by the approaching or other individuals, as well as to number the times the

approaching individual had previously been at the setup. The motivation of this model was to

take into account some of the individual information monkeys may have had available (from

own experience or observing others at the setup) in addition to visibility of the content to

guide their (olfactory) exploration of the setup. The model was constructed like model 1, but

additionally included as fixed effects predictors the time (min) since approach by another

monkey (delta other), time (min) since own previous approach (delta self) and n^{th} approach to

the setup as well as the two-way interactions of these terms with the main test predictor, i.e.

visibility condition. For the very first approach of an individual to a setup, we imputed the data

by using the average time between approaches as time since own previous approach (delta

self).

Model 3 was formulated to investigate whether the visibility condition affected if the monkeys

used olfaction at the beginning of the exploration or later. Specifically, we expected the

monkeys to sniff first when the content was not visible but later during the exploration if it was

visible. Hence, this model used only those approaches in which the monkeys did sniff. As

binary response variable, we fitted whether a sniff occurred first or later in the exploration

sequence. Hence, 813 approaches by 71 individuals were used in this analysis. These

represented 158 cases in which sniffs were the first behavior and 655 cases with sniffs at later

stages of the exploration. Similar to model 1, we fitted the visibility condition, the content of

the setup and their interaction, as well as the interaction between visibility condition and the

control predictor day (i.e. number of days the site had already been active) as fixed effects test

predictors. As fixed effects control predictors, we further included sex, cohort, group, block

and the hour of the day. We further fitted the identity of the coder, the monkey ID, the date

and the site as random intercepts.

Model 4 specifically investigated the interplay between visual condition, olfaction and the

(attempted) retrieval of items from the setup. We expected that in the transparent condition

vision will primarily guide the decision as to whether individuals would grab or not, while in

the opaque condition olfaction should do so, and that in either case the decision would

depend on the content. We therefore fitted grab (yes/no) as binary response variable, using

the same 1354 cases as in model 1. These comprised 510 approaches with, and 844 without

grabs. We fitted the visibility condition, the content of the setup, whether or not monkeys first

sniffed (yes/no), and their 2-way and 3-way interactions as test predictors. In this model, "sniff

first" referred to the order of a sniff relative to the first grab to assess whether olfactory

information may have guided the decision to grab. Hence, approaches with sniffs before the

first grab, or sniffs not followed by a grab, would be denoted as "yes", and approaches with

sniffs after the first grab, or without any sniffs as "no". As fixed effects control predictors, we

further included sex, cohort, group, block, the day of the experiment, the time since the last

filling of the setup and the hour of the day. We also fitted the interaction between orientation

of the pipe and content to account for the possibility that food items (but not non-food items)

having shifted into the bend could elicit more grabs. As in the other models, we further fitted

the identity of the coder, the monkey ID, the date and the site as random intercepts.

General model procedures

To achieve reliable estimates for fixed effects predictors, we fitted all (model 1) or most

(models 2-4) theoretically identifiable random slopes of fixed effects within the grouping

factors (Schielzeth and Forstmeier 2009; Barr 2013, see Supplements S1 & S3). We did not fit

any random correlations between random slopes terms to maintain an adequate balance

between sample size and model complexity. We further excluded cases from the analyses that

represented rare levels of grouping factors (i.e. fewer than 3 observations per level, see

supplement S1) to facilitate accurate estimation of random variation.

For all models, we z-transformed covariates to a mean of 0 and an SD of 1 prior to fitting the

model to facilitate convergence and interpretation of model estimates (Schielzeth 2010). To

facilitate comparisons between studies, means and SDs of the untransformed covariates are

provided in supplement S4. As the time since the last filling (delta fill) and since approach by

another monkey (delta other) were strongly right-skewed, we log-transformed these variables

after adding the constant 1 (to avoid 0-values) to improve model fitting. In these cases, the

log-transformation was performed first and the z-transformation last. Furthermore, we

manually dummy-coded categorical fixed effects predictors if involved in model interactions to

be able to include their respective random slopes.

We checked for collinearity between predictors by using the function vif of the package car

(version 3.1-1, Fox & Weisberg 2019). There were no issues with collinearity in any of the

models (largest VIF in model 1: 1.15, model 2: 1.36, model 3: 1.25, model 4: 1.32). We further

assessed the stability of models 1-3 by excluding each grouping factor level one at a time and

comparing model estimates, using a function provided by R. Mundry. With a few exceptions

(see Supplement S1), model estimates were generally stable. Because of the long computation

time, we did not assess model stability for model 4 (estimated to take >60 days).

For inference, we compared the full models comprising all predictors with the corresponding

null models, which excluded the test predictors but included all control predictors and all

random intercepts and slopes. Hence, full-null model comparisons are indicative of whether

one or more test predictors, but not whether control predictors significantly affect the

response. Full-null model comparisons were conducted with Likelihood Ratio Tests (LRTs) using

the R function anova. Only if the full-null model comparison was significant ($p < 0.05$), we

assessed significance of the individual (test and control) predictors with LRTs using the

function drop1. In case of non-significant full-null model comparisons we assessed significance

of control predictors using Wald statistics provided by the glmer function, but did not consider

results of test predictors. Accordingly, in contrast to test predictors, results of individual

control predictors are not controlled for cryptic multiple testing. If a model contained non-

significant interactions involving test predictors, we excluded the non-significant interactions

from the model to facilitate interpretation of the main terms. For these models we present

final models (after removal of non-significant interactions) in the main text and full models

(including non-significant interactions) in supplement S5.

Experiment II: colored popcorn

In the second experiment, conducted after the pipe experiment, we manipulated the visual

appearance of a familiar food item, i.e. popcorn. This experiment was conducted with 32 adult

focal animals of both sexes (16 males with ages of 7 to 21 years, 16 females with ages of 6 to

21 years) from two of the three study groups. All focal animals were already habituated to

retrieving peanuts from a shallow plastic container in the course of another study.

With each of these individuals, we conducted two sessions (with 1-3d between sessions), in

which popcorn was offered in a grey plastic container (the socket plug of a drainage pipe with

7.5cm diameter and 3 cm height) fixed to a horizontal branch or wooden rail with a belt strap.

Each session consisted of a warm-up and a test trial. In the warm-up trial, a single piece of un-

manipulated, white popcorn was offered in the container. If the animal participated in the

warm-up trial, the container was filled with 4 pieces of popcorn simultaneously, 2 of which

were white and the other 2 blue. Blue popcorn was obtained by dissolving a drop of viscous

food dye (Dr. Oetker) in the same amount of water. The diluted dye was soaked up with a

paper towel and softly dabbed over the entire surface of the popcorn, then left to dry. As we

were unable to obtain white food coloring of the same brand, the white pieces of popcorn

were left unmanipulated. In blind tastings of dyed and undyed popcorn, three experimenters

(each tasting 3 pieces) were not able to distinguish between dyed and undyed popcorn, but we

cannot exclude minor differences in smell or taste resulting from the dying process. To avoid

interference by other monkeys, sessions were conducted when the respective focal animal had

voluntarily separated from group members and was either out of sight or was at least 3m away

from other monkeys and all individuals in the vicinity were lower-ranking than the focal

animal. All sessions were conducted by the same experimenter and recorded with a handheld

video camera (Panasonic HC-V180), with the experimenter commenting the observed

behaviors and colors of the retrieved popcorn pieces while recording. All 32 focal animals

could be successfully tested in this manner.

From the videos, we scored for each session the date and time, and for each piece of popcorn

the order of retrieval, its color, whether or not it was sniffed at and/or eaten. All videos were

coded by the same observer.

Statistical analysis

We analyzed the effect of popcorn color on sniffing behavior by fitting a GLMM with sniff

(yes/no) as the binomial response variable with logit link. The unit of analysis was each single

piece of popcorn offered to the 32 focal individuals in the test trials (N = 32 individuals x 4

pieces per session x 2 sessions = 256). As fixed effects test predictor, we fitted the color of the

popcorn (white/blue). To account for the possibility that monkeys might get used to the novel

coloration over the course of the experiment, we further fitted the interaction between color

and the nth piece of popcorn retrieved (continuous variable from 1 to 8). We controlled for sex

(male/female), cohort, hour of the day and group (C or F) by fitting these terms as fixed effects

control predictors, and for monkey ID and date by fitting them as random intercepts. We

further fitted all identifiable random slopes of fixed effects predictors within ID and date (see

Supplement S3), but no random correlations, as this caused non-convergence of the model.

Checks of model assumptions and stability as well as determination of p-values for the full

model and individual predictors were conducted as described in experiment 1. There were no

issues with collinearity (largest VIF 1.31). Estimates for the effect of nth piece of popcorn were

rather wide and overlapped 0, but the model was stable with respect to the test predictor and

the other control predictors.

Ethical note

Experiments were approved by Affenberg Salem. As all procedures were non-invasive and

participation was voluntary, we required no further animal ethics approval.

RESULTS

Experiment 1: transparent vs. opaque pipes

We first addressed if visibility affected the propensity to sniff at the setup during any stage of

exploring. In the 1399 approaches with interactions by identified individuals, monkeys sniffed

in 439 (59.1%) of 743 approaches when the transparent can was attached to the pipe, and in

443 (67.5%) of 656 approaches when the can was opaque. However, although the proportion

of sniffs in the opaque condition was slightly higher, the visibility condition had no significant

impact on the propensity to sniff when the other predictors were controlled for (Model 1 on

1354 approaches by 97 individuals: full-null model comparison, LRT, $\chi2 = 11.747$, df = 11, P =

0.383, see Tab. 1). This remained qualitatively the same when accounting for potential

additional information on the contents from own or others' prior approaches to the setup

(Model 2 on 973 approaches by 80 individuals: full-null model comparison, LRT, $\chi2 = 17.807$, df

= 17, P = 0.401, see Tab. 1). While not addressed by the full-null model comparison, model

results were suggestive of a significant effect of certain control predictors, namely cohort, with

younger individuals being more likely to sniff than older ones in Model 1 (Wald test, z = 3.032,

P = 0.002) and an interaction between cohort and visibility condition in Model 2 (Wald test, z =

2.015, P = 0.044), although the latter result was not very stable across models with different

random level effects included (see details on model stability in the methods).

Table 1: Estimates of the GLMMs investigating the propensity to sniff for all experimental sites

(Model 1, N = 1354 approaches) and for fully-coded experimental sites only (Model 2, N = 973

approaches).

	Model 1		Model 2	
Term	*Estimate*	*SE*	*Estimate*	*SE*
Intercept	1.137	0.407	1.156	0.577
Content				
(feces)	0.119	0.411	0.000	0.541
(nothing)	-0.301	0.347	-0.417	0.484
(popcorn)	-0.664	0.406	-1.085	0.523
(stones)	-0.384	0.415	-0.580	0.544

condition (transparent)	-0.485	0.426	-0.572	0.599
delta_other			-0.117	0.125
delta_self			-0.222	0.138
n^{th}_approach			-0.054	0.302
Cohort	0.328	0.108	0.287	0.129
Day	0.131	0.164	0.351	0.150
sex (male)	-0.128	0.179	-0.045	0.200
Group				
(F)	-0.114	0.265	0.185	0.410
(H)	0.164	0.327	0.125	0.578
Block	-0.079	0.102	-0.084	0.140
delta_fill	-0.159	0.124	-0.128	0.121
Orientation	-0.081	0.071	0.008	0.081
hour of day	-0.102	0.080	-0.165	0.101
content:condition				
(feces:transparent)	-0.138	0.547	-0.108	0.725
(nothing:transparent)	0.148	0.461	0.318	0.621
(popcorn:transparent)	0.691	0.584	0.927	0.836
(stones:transparent)	0.304	0.554	0.190	0.745
condition (transparent):cohort	0.172	0.136	0.351	0.174
condition (transparent):day	-0.131	0.149	-0.245	0.227
condition (transparent):delta_other			0.271	0.183
condition (transparent):delta_self			0.232	0.195
condition (transparent):n^{th}_approach			0.120	0.190

Values in parenthesis indicate levels relative to the respective reference level (content peanuts,

condition opaque, sex female, group C). SE = standard error. P-values not shown because full-null model

comparisons were non-significant.

We further assessed, if visibility affected at what stage of the exploration monkeys used

olfaction. n the 882 approaches during which the monkeys were observed to sniff, sniffing was

the very first behavior directed towards the setup in 172 (19.5%) of cases, while the majority

of sniffs occurred at later stages of exploring the setup. More specifically, monkeys inspected

the setup first by sniffing in 76 (17.3%) of 439 cases in the transparent condition, and in 96

(21.7%) of 443 cases in the opaque condition, whereby both content and visibility condition

significantly affected the propensity to sniff first (Model 3 on 815 approaches by 71 individuals,

full-null model comparison LRT, $\chi 2 = 24.782$, $df = 10$, $P = 0.006$, see Tab. 2). Specifically,

monkeys were slightly more likely to sniff first if the can was opaque, irrespective of content,

and were more likely to sniff first when non-food items or nothing was in the pipe (Fig. 2).

Figure 2: Proportion of approaches with sniffs in which the first interaction with the setup was

a sniff depending on content and visibility condition (white symbols: transparent, grey

symbols: opaque). Symbols are scaled by sample size (range 38 − 205 approaches with sniffs).

Lines depict model estimates (dashed: opaque, dotted: transparent condition) when all other

predictors are at their average.

Table 2: Estimates of the GLMM investigating the propensity to sniff first (N = 882 approaches

with sniffs).

term	Estimate	SE	χ^2	df	P
Intercept	-3.061	0.787			
content			14.061	4	**0.007**
(feces)	1.582	0.536			
(nothing)	1.529	0.507			
(popcorn)	0.766	0.574			
(stones)	1.025	0.566			
condition (transparent)	-0.458	0.209	4.213	1	**0.040**
cohort	-0.283	0.185	1.735	1	0.188
day	0.101	0.141	0.482	1	0.487
sex (male)	-0.408	0.231	2.933	1	0.087
group			3.569	2	0.168
(F)	-0.013	0.354			
(H)	0.622	0.409			
block	-0.209	0.150	1.837	1	0.175
hour of day	0.084	0.163	0.281	1	0.596

Values in parenthesis indicate levels relative to the respective reference level (content peanuts,

condition opaque, sex female, group C). SE = standard error. χ^2 and P values are derived from LRTs to

determine the significance of the individual test predictors. Significant effects are marked in bold.

Finally, we investigated the interplay between visual condition, olfaction and the (attempted)

retrieval of items from the setup. In the 1399 approaches with interactions of identified

individuals, the monkeys grabbed into the setup in 516 (36.9%) of cases. Whether or not the

monkeys did grab was affected by the content, the visibility condition and whether or not the

monkeys had sniffed at the setup (Model 4 on 1354 approaches by 97 individuals: full-null

model comparison, LRT, $\chi2$ = 94.424, df = 23, P < 0.001). In particular, the effect of the visibility

condition depended on the content of the setup (Tab. 3). Specifically, monkeys showed a

similar propensity to grab for food items irrespective of the visibility condition, but a reduced

propensity to grab for non-food items or into an empty pipe in the transparent versus the

opaque condition (Fig. 3). When the monkeys did grab, they actually retrieved peanuts and

popcorn in almost all instances of grabbing (peanuts: 95 out of 96 times, popcorn 115 out of

119 times), but only in half of the 80 cases in which they grabbed stones and never in the 24

grabs when feces were inside the can. Sniffing generally decreased the propensity to grab into

the setup (Tab. 3). Although this decrease appeared to be more pronounced in the opaque

condition (Fig. 3), the interaction between sniffing and visibility condition or content was not

significant. Furthermore, the propensity to grab inside was higher in younger animals and later

in the experiment (Tab. 3). The quantity of the provided food items did not significantly affect

grabbing behavior (Supplement S1).

Figure 3: Proportion of grabs into the setup depending on content, visibility condition (white

symbols: transparent, grey symbols: opaque) and whether or not monkeys had sniffed first

(yes: circles, no: diamonds). Symbols are scaled by sample size (range 18 – 201). Lines depict

model estimates (dashed: sniffed first, dotted: no prior sniff) when all other predictors are at

their average.

Table 3: Estimates of the GLMM investigating the propensity to grab into the setup (N = 1354

approaches).

term	Estimate	SE	χ²	df	P
Intercept	0.522	0.647			
content					*
(feces)	-4.687	0.766			
(nothing)	-2.622	0.521			
(popcorn)	-0.424	0.613			
(stones)	-1.917	0.596			
condition (transparent)	0.294	0.630			*
sniff first (no)	0.568	0.274	4.348	1	**0.037**
cohort	0.971	0.230	10.366	1	**0.001**
sex (male)	0.186	0.375	0.248	1	0.619
group			2.134	2	0.344
(F)	0.492	0.451			
(H)	0.789	0.579			
day	0.243	0.139	3.125	1	0.077
block	0.713	0.147	14.216	1	**< 0.001**
z.delta_fill	-0.163	0.099	2.695	1	0.101
orientation	0.073	0.142	0.269	1	0.604
hour of day	-0.152	0.102	2.140	1	0.144
content:condition			15.018	4	**0.005**
(feces:transparent)	-2.173	1.009			
(nothing:transparent)	-1.791	0.688			
(popcorn:transparent)	0.124	0.886			
(stones:transparent)	-1.047	0.781			

Values in parenthesis indicate levels relative to the respective reference level (content peanuts,

condition opaque, sniff first yes, sex female, group C). SE = standard error. χ^2 and P values are derived

from LRT to determine the significance of the individual test predictors. Significant effects are marked in

bold.

* not presented because terms comprised in significant interaction and thus having a very limited

interpretation

Experiment 2: colored popcorn

The 32 focal animals retrieved all of the 256 pieces of popcorn and sniffed at 58 (22.7%) of

them. The color of the popcorn had a clear impact on the probability of sniffing (full-null model

comparison, LRT, $\chi2 = 10.77$, df = 2, P = 0.005). More specifically, blue popcorn was sniffed at

significantly more often (50 out of 128 times) than white one (8 out of 128 times), irrespective

of how many pieces had already been retrieved (see Tab. 4). Furthermore, females generally

sniffed at a higher proportion of popcorn than males (Tab.4, 5). Finally, the sniffing frequency

appeared to decrease slightly over the course of the experiment irrespective of color, but this

was only a statistical trend and not very robust (see details on model stability in the methods).

Table 4: Number (N) and fitted values for proportion (prop. fit) of white and blue popcorn
pieces sniffed by female and male Barbary macaques.

	white		blue	
	N	prop. fit	N	prop. fit
female	6	0.044	34	0.490
male	2	0.008	16	0.148

543   The total number of popcorn pieces per sex and color was 64 (16 individuals x 2 pieces x 2 sessions).

545 Table 5: Estimates of the GLMM investigating the propensity to sniff at popcorn (N = 256

546 pieces of popcorn).

term	estimate	SE	χ^2	P
Intercept	-3.274	0.729		
color (blue)	3.037	0.675	9.550	**0.002**
popcorn_nr	-0.829	0.507	3.325	0.068
sex (male)	-1.709	0.637	7.894	**0.005**
group (F)	0.334	0.584	0.314	0.576
cohort	0.043	0.347	0.015	0.902
hour of day	0.006	0.259	0.001	0.982

Values in parenthesis indicate levels relative to the respective reference level. SE = standard error. χ^2

and P values are derived from LRTs to determine the significance of the individual test predictors.

Significant effects are marked in bold.

The monkeys ate the vast majority of popcorn pieces (232) and only discarded 24 of them (23

blue, 1 white). They had sniffed at 13 of the discarded blue and at the one piece of white,

discarded popcorn. Due to the low number of discarded pieces (especially white ones) and the

lack of a positive control for the dye, we did not assess the interplay between visual and

olfactory cues on the decision to eat or discard the popcorn statistically.

DISCUSSION

The present study provides evidence that visual information affects the use of olfaction (i.e.

sniffing) and subsequent exploratory behavior of Barbary macaques, whereby patterns

differed depending on whether the presence or salience of visual information was

manipulated in experimental feeding situations.

Experiment 1: Effects of visual information on olfactory behavior (models 1-3)

Sniffing probabilities in experiment 1 were generally rather high and only little affected by the

visibility condition: monkeys sniffed in more than half of the approaches even if the content

was visible through the transparent can. Notably, sniffing occurred throughout all phases of

interacting with the setup. While an initial assessment of the setup using olfaction was slightly

more pronounced when cans were opaque than when they were transparent, the majority of

sniffs in either visibility condition occurred after the monkeys had actively looked, grabbed or

in other ways interacted with the setup. Hence, as suggested for various strepsirrhine and

platyrrhine primates (reviewed in Nevo and Heymann 2015) and other mammals (e.g. swamp

wallabies, *Wallabia bicolor*, Stutz et al. 2017), sniffing in Barbary macaques may be more

relevant *after* an item is located through other sensory modalities (like vision), and thus may

function primarily as quality assessment and food selection process rather than in the search

for food.

The degree to which vision and olfaction interplay in food search and assessment has

been associated with evolutionary adaptations to aspects such as diet or sensory abilities of

foragers. In procellariform ("tube-nosed") sea birds, for instance, differences in light exposure

in early development have been related to the degree of dependence on visual and/or

olfactory cues during foraging at sea, with burrow-nesting species depending more on

olfactory and surface-nesting species more on visual or multimodal cues (Van Buskirk and

Nevitt 2008). Similarly, the sensory cues provided by food items and the sensory capabilities of

individuals may interact in an intricate manner in primate food selection. In spider monkeys,

sniffing decreased from 40-45% in fruit species with rather cryptic coloration to 0 for the

visually most conspicuous fruit species, irrespective of individual color vision abilities

(Hiramatsu et al. 2009). In contrast, Melin et al. (2019) found that dichromatic capuchin

monkeys sniffed more at fruits than trichromatic ones irrespective of the conspicuity of the

visual cues provided by the fruits, although chromacy-related differences in sniffing rates

varied greatly between fruit species and the overall difference was small (8% vs. 7% sniffing in

di- vs. trichromatic individuals). Our study animals presumably all had highly similar visual

capabilities with the one known exception of a subadult male with one blind eye from birth on.

He sniffed in 70% of 37 approaches to the transparent and 73% of 22 approaches to the

opaque setup and thus more frequently than the average. However, younger individuals were

generally more likely to sniff (and grab into) the setup, and with just one case we are unable to

assess whether the high sniffing rates were related to visual impairment, young age or just

chance. Further studies incorporating a wider range of species are needed to address how

aspects such as dynamic vs. stable differences in visual information, diet and other aspects of

species ecology or individual differences in sensory capabilities affect to what extent vision

affects olfactory behavior.

Experiment 1: Effects of sensory information on grabbing for items (model 4)

Monkeys grabbed into the setup in a little more than one third of the approaches. As

expected, whether or not monkeys grabbed was modulated by the content and its visibility.

They were most likely to grab for peanuts and least for feces in either visibility condition, but

the differences in grabbing between contents were less pronounced in the opaque condition.

This suggests that the absence of visual information limited the monkeys' ability to distinguish

the contents of the setup, but also that they did have other sensory information than the

items' visibility available to guide the decision as to whether or not to grab inside. Our

prediction that olfaction would mediate further exploration of the setup in the absence of

visual information, however, was only partly supported. Results indeed indicated a significant

effect of prior sniffing on the propensity to grab. Based on grabbing rates (see Fig. 3), this

effect appeared to be more pronounced in the opaque condition, particularly when feces,

nothing or popcorn was inside. However, statistically an interaction between sniffing, visibility

condition and content could not be confirmed; model results rather suggest that monkeys that

had sniffed the setup were generally less likely to grab inside irrespective of content or

visibility condition. Although we scored well over 1000 approaches, the study design was

complex and the number of actual approaches to a given content and condition as well as the

(sniffing) behavior shown by the monkeys upon approach was not controllable by us, so that

for particular combinations of predictors, cases may have still been too rare to detect

statistically robust patterns. Another explanation could be that some residues of fecal odor

remained in the setup even if other contents were inside, although we took great care to

thoroughly clean the setup between fillings. Given the much lower propensity to grab for feces

than for other items, this could explain a generally lower propensity to grab after sniffing

irrespective of visibility condition and content, but if this was the case, we would have

expected a much more pronounced decrease in grabs after sniffing than actually observed. We

also consider it unlikely that a potential smell of the duct tape in the opaque condition affected

grabbing, because sniffing the setup reduced grabbing irrespective of the visibility condition.

Notably, even if monkeys had not sniffed, grabbing rates differed between contents in

the opaque condition (see Fig. 3), suggesting that the monkeys may have had other sources of

information about the contents than anticipated. One possibility is that the odors of the

contents may have been perceivable from a greater distance and without requiring the active

sniffing movement that we scored, so that we may have underestimated the number of

approaches in which olfactory information was available and used by monkeys. Although the

majority of studies point towards primates primarily using olfaction for the close-up

assessment of food items (Nevo and Heymann 2015), at least some species of strepsirrhines

and platyrrhines appear to be able to detect and locate food sources from up to several meters

distance using olfactory cues (Bicca-Marques and Garber 2004; Cunningham et al. 2021).

Monkeys also sometimes pulled at the setup, which may have dislodged items from the tip of

the can into a position visible from the top opening of the pipe. We statistically controlled for

this possibility by including the orientation of the pipe into the models, but could not

unambiguously determine for each approach whether or not monkeys could have seen the

contents even in the opaque condition. Sound is unlikely to have provided salient information

about the contents (other than maybe that there is something inside). Touch, on the other

hand, has been suggested to be an important sense for evaluating food quality in primate

feeding ecology (Dominy 2004; Veilleux et al. 2022). For instance, results by Dominy et al.

(2016) suggest that the ingestion of green figs, *Ficus sansibarica*, by chimpanzees was elicited

by fig toughness rather than their color or size. Along similar lines, the Barbary macaques in

the present study may have grabbed inside the setup to gather tactile information about the

item. The fact that the monkeys, in case of a grab, almost always retrieved food, but only half

of stones and none of the feces supports the idea that monkeys may have also used tactile

cues, but this possibility would need to be assessed systematically in a future study.

Finally, the food items used in the experiment are highly favored by the monkeys, and

peanuts, in particular, are not routinely provided by the park. Hence, the incentive of gaining a

favorite food item may have been higher than costs for an unsuccessful grab revealing no food

or even an item like feces, so that at least some individuals may have pursued the strategy to

grab inside as long as there was no obvious cue suggesting feces or other non-food content.

Furthermore, monkeys not having encountered feces in the setup in previous approaches may

have been more prone to grab inside irrespective of visual or odor cues to the content.

However, taking into the account the prior setup experience of each individual would have

required a much more detailed investigation including coding every single video, which was

not feasible in the present study. Taken together, Barbary macaques appeared to depend

more on visual than olfactory information to distinguish between items, although question

marks remain as to whether or how visual and olfactory information interact to guide

exploratory behavior in an experimental feeding context.

Experiment 2

The second experiment addressed a different aspect of visual information. By presenting blue

and white pieces of popcorn, visual information was constantly available but while size and

shape were familiar, the color of dyed popcorn was not and thus represented a source of

ambiguity. Indeed, monkeys sniffed popcorn in a novel (blue) color considerably more often

than the familiar, white popcorn. This matches results in spider monkeys and squirrel

monkeys, who used olfaction and other non-visual senses more when presented with novel

food (i.e. entirely unfamiliar or with unfamiliar color or scent), while relying primarily on vision

for assessing familiar food items (Laska et al. 2007). The unfamiliar visual appearance of the

dyed popcorn also appeared to be particularly salient for sniffing behavior in Barbary

macaques and elicited stronger changes in olfactory inspections than the presence or absence

of visual cues in experiment 1.

Unfamiliar colors have also been shown to affect the acceptance and manipulation of food

items (e.g. zebra finches: Kelly and Marples 2004; spider monkeys and squirrel monkeys: Laska

et al. 2007). In our popcorn experiment, 23 of the 24 discarded pieces were dyed, but the

monkeys consumed such a large proportion of the popcorn pieces (91%) overall that we did

not have a sufficient number of discarded pieces to statistically assess how the interplay

between visual information and sniffing behavior affected consumption. Furthermore, our

inference about the role of visual appearance on food consumption was limited by the fact

that we had no white food coloring of the same brand as the blue one available and thus

compared dyed with undyed popcorn. Although different experimenters were not able to

detect a difference in smell or taste of the dyed and undyed popcorn, we cannot exclude that

the monkeys may have been able to perceive a difference. If that was the case though, this

information should only have become available after sniffing or tasting the popcorn.

Accordingly, a potential difference in the smell or taste of dyed popcorn should have been of

little relevance for the question if an unusual color elicits olfactory investigation, but might

have had an effect on the consumption of the popcorn. Follow-up studies should therefore

incorporate different colors as well as combinations with odors (as done in e.g. Kelly and

Marples 2004; Laska et al. 2007) to get a better understanding how unfamiliar visual

appearance and olfactory information interact in catarrhine primate food choice.

Conclusions

The present study provides evidence that Barbary macaques used visual and olfactory

information to guide exploratory and feeding behavior in experimental feeding contexts. As a

highly visually oriented species with acute color vision it comes as no surprise that the

presence or absence as well as the salience of visual information clearly affected how monkeys

responded to different food and non-food items. Monkeys also routinely used olfaction to

inspect items, particularly if visual information was ambiguous (i.e. familiar food in an

unfamiliar color), while the presence/absence of visual information had only minor effects on

sniffing behavior. Olfactory inspection affected subsequent behavior to some degree, albeit

less than vision. As such, this study adds to the increasingly comprehensive evidence that

olfaction plays a prominent role in the lives of catarrhine primates, which were historically

regarded to rely only little on the sense of smell. Importantly, by taking a multimodal approach

we were able to show that the availability and salience of information in one sensory modality

may affect the use of other sensory modalities, potentially leading to a complex, multisensory

interplay affecting behavior. As also pointed out by various authors (e.g. Smith and Evans

2013; Leonard and Masek 2014; Valenta et al. 2015; Wilke et al. 2017; Veilleux et al. 2022), our

results highlight the importance of a multimodal perspective, as examining single modalities

may be insufficient to explain behavioral decisions. How such multisensory interactions guide

behavior in a feeding or other contexts requires further studies and across a wider range of

species to understand how (socio)ecological traits shape sensory ecology.

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