Multiscale mechanisms driving tissue rupture by invading cells.

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Summary

Cells migrate and invade tissues during development, immune responses, and cancer.
Collective invasion is generally understood to be driven by invading cells unjamming and
pushing through barriers such as the extracellular matrix and surrounding tissues. Whether
these barriers actively contribute to invasion remains unclear. Using ovarian adenocarcinoma

spheroids invading mesothelium derived from benign pleural effusions as an experimental
model, combined with modelling, we examine invasion across molecular to multicellular
scales. We identify intercellular integrin adhesions linking invasive leader cells to the tissue
barrier, triggering apical constrictions within the barrier. This constriction shrinks cell-cell
contacts, leading to barrier rupture. Thus, the tissue barrier plays a mechanically active role in
invasion. Rather than cells pushing through, we find that coordinated subcellular contractility
between the invading leader cell and the barrier drives barrier tensile rupture and invasion,
independent of a jamming transition. Together, our findings challenge prevailing paradigms
of collective cell invasion.
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46 **Introduction**
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48 Cell migration and invasion into tissues and the extracellular matrix are fundamental for the
49 development and maintenance of organisms and are rampant in diseases such as cancer[1,2].
50 During cancer, tumour cells traverse into foreign tissues during metastasis[2], while in
51 development, undifferentiated cells move into tissues to form different tissue types[3].
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A variety of microenvironments contain the extracellular matrix and closely packed cells
adherent to one another[4,5]. Whether these mechanical barriers actively contribute to
mammalian tissue invasion and whether cell-matrix adhesion receptors, such as integrins, are
involved remains unclear. Since tumour cell clusters are more capable of forming secondary
metastases than single cells[6]. Another key challenge is to identify the changes in subcellular
dynamics that link molecular mechanisms to cellular and multicellular rearrangements in
collective invasion of tissues.
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Our current understanding of how cells collectively invade tissues stems from the study of
angiogenesis, neural crest migration and border cell migration. Landmark studies in
Drosophila showed that the microtopography of barrier tissue provides an energetically
favourable path of least resistance for border cell cluster migration, and cell-cell adhesion
contributes to the traction of border cells[7]. Notably, mechanical feedback by E-cadherin-
based Rac signalling promotes direction sensing of border cells through nurse cells[8]. Despite
these insights, a deep understanding of collective invasion into mammalian tissues is lacking.

An interdisciplinary approach to achieve a multiscale understanding[9,10] of collective tissue

invasion in cancer remains largely unexplored.

We use three-dimensional co-cultures mimicking ovarian tumour invasion of the

mesothelium as a model system in our experiments. Previously studies suggested that integrin

and talin-dependent activation of non-muscle myosin-II was required for spheroids to

displace the mesothelial cells apart during invasion[11,12]. Here, we study the interplay between

fracture mechanics and cell invasion across molecular to multicellular scales. First, we have

identified a material-based phenomenon of tissue rupture by collective invasion and the

patterns of motion driving invasion. Then, we worked out the cellular and molecular

mechanisms underlying the patterns of motion driving invasion and the role of multicellular

dynamics during spheroid invasion. Finally, our theoretical modelling predicts the

quantitative basis of the invasion process. We conclude that instead of the widely accepted

model of invading cells pushing through the tissue barrier or jamming transition-mediated

cell invasion, a coordinated patterning of subcellular contractility by invading cells and the

tissue barrier drives tissue invasion. Thus, our findings challenge the existing paradigm of

how cells invade tissues.

Results

We study how cells migrate and invade the ECM and tissue barrier through experiments and

theory. Our experiments used three-dimensional co-cultures that mimic ovarian tumour

invasion of the mesothelium[11-14]. The mesothelium is a monolayer of simple squamous

epithelium[15] covering the human peritoneum's stroma (Fig. 1a). In peritoneal metastasis[16],

the mesothelium is cleared by ovarian tumours, eventually leading to the absence of the

mesothelium underneath the tumour and indentation of the stroma (Fig. 1b,b').

Our modified 3D culture systems can phenocopy our clinical observations (Fig. 1c). Human

ovarian adenocarcinoma OVCA433 epithelial cells were cultured to form spheroids in

suspension, bearing a grape cluster-like morphology (Fig. 1d)[17]. These spheroids were

introduced onto the ZT mesothelia[13] that form a laminin-rich basement membrane when

grown on Matrigel (Fig. 1c). The E-cad GFP expressing spheroid invaded and cleared the

underlying mesothelium (Fig. 1c), mimicking our clinical observations. Additionally,

multicellular assemblies migrating into tissues can also occur as a general morphogenetic

process that is not just specific to tumour invasion. This is because spheroids formed from

mesothelial cells can also migrate into mesothelium grown on Matrigel (Supplementary Fig.

1a).

Rupture initiation of the mesothelium during spheroid invasion

We first study tissue invasion at high resolution. As spheroids invade the mesothelium, a

phenomenon resembling crazing is observed at mesothelial cell-cell junctions (Fig. 1d' and

Video 1). Crazing is a unique feature when thermoplastic polymer materials rupture[18],

characterized by a network of fine cracks within the material. It occurs when excessive

tensile stress or stretching is applied to a polymer, producing gaps termed microvoids

between fibrillar bridges that are thought to help sustain some stress (Supplementary Fig. 1b).

At the mesothelium, we observed the pulling of cell-cell junctions leading to the elongation

of fibrillar bridges linked by the intercellular adhesion molecule, E-cadherin, and the

formation of microvoids before mesothelial rupture (Fig. 1d'' and Video 1). Mesothelial

rupture initiation was also characterised by the elongation of E-cadherin puncta, and we did

not observe any dramatic reduction of E-cadherin at intact regions of the mesothelial cell-cell

contacts during rupture initiation (Fig. 1d''', Video 1). These E-cadherin fibrillar bridges are

not specific to mesothelium cultured on glass, as we observe fibrillar bridges at sites of

spheroid invasion when mesothelium is grown on Matrigel (Video 2). Notably, fibrillar

bridges and microvoids in polymer crazing are ~10-20 nanometres, much smaller than the E-

cadherin fibrillar bridges and microvoids between cells we observed (Fig. 1d'' and Video 1).

Thus, instead, we termed the formation of E-cadherin fibrillar bridges and microvoids during

the initiation of cell-cell junction rupture as cell-cell contact crazing.

We weakened cell-cell contacts to test if these E-cadherin fibrillar bridges help resist rupture.

(Fig. 1d, Video 1 & 2). RhoA-Myosin-II mediated contractility supports E-cadherin cell-cell

adhesion strength[19-22]. We reduced E-cadherin adhesiveness of the mesothelium by

expressing a dominant negative RhoA mutant T19N fused to E-cadherin (Fig. 1e and

Supplementary Fig. 1c-f). Strikingly, the E-cadherin fibrillar bridges formed during spheroid

invasion were reduced in the mesothelium expressing E-cad-RhoA-T19N mutant (Fig. 1f,g).

Although the rate of mesothelial rupture remains unchanged in mesothelium expressing E-

cad-RhoA-T19N mutant (Supplementary Fig. 1g), more extensive mesothelial clearance by

spheroid invasion was observed (Fig. 1h). Thus, these mesothelial E-cadherin linked fibrillar

bridges may resist invasion. Taken together, we observe features of material-based fracture

during cell invasion of the mesothelium.

Tensile fracture of the mesothelium by spheroid engagement

Next, we identify the underlying patterns of motion and mode of mesothelium rupture

involved in invasion. To analyze the mesothelium fracturing process, we tagged its apical

surface with fluorescent microbeads[23] and imaged it undergoing spheroid invasion. 500nm

beads were coated with wheat-germ-agglutinin for cell surface binding[23].

A material's fracture response can be classified as brittle or more ductile according to the

extent of its deformation during fracture[24]. A ductile fracture is seen in readily deformable

materials and is characterized by extensive plastic deformation before the material finally

breaks apart[25]. By contrast, a brittle fracture exhibits little or no plastic deformation before its

fracture[25]. Velocity magnitude quantification from particle image velocimetry (PIV) of the

WGA-coated beads on the mesothelium apical surface showed significant deformation of the

mesothelium (Fig. 1i, Supplementary Fig. 1h). This suggests that the tearing of the

mesothelium is akin to ductile rupture.

Generally, there are three principal modes by which fracture/rupture occurs, namely tensile

fracture[26,27] (mode I), shear fracture (mode II) and out-of-plane tearing (mode III) (Fig. 1j).

Since cell-cell contact crazes typically form at the plane normal to tensile stress, spheroid

invasion should likely induce mesothelial tensile fracture.

Indeed, PIV of the beads on the mesothelium apical surface after spheroid invasion showed a

constriction zone next to the region where the crack was initiated (Fig. 1i, Supplementary

Fig. 1h). After being pulled from both sides, the small crack opened a hole in the middle of

the mesothelium, an indication of a tensile fracture.

Given that cells did not slide past each other upon fracture, it is unlikely that in-plane shear is

an important driver of fracture initiation (Fig. 1d). To quantify the deformation nature of the

mesothelium, we examined both the normal strain rate and shear strain rate of the

mesothelium undergoing fracture (Fig. 1i,k, Supplementary Fig. 1h). Here, the normal strain

rate represents the strength of the velocity gradient in the direction of the local velocity, and

the shear strain rate represents the strength of the velocity gradient perpendicular to the local

velocity[28]. We did not observe a high shear rate near the initial fracturing site (Fig. 1i,k,

Supplementary Fig. 1h). Instead, we observed a low shear rate with high expansion velocity,

thus corresponding to tensile fracture (Fig. 1i,k, Supplementary Fig. 1h, Methods).

Finally, using lattice light sheet microscopy to achieve a clear cross-section view, we did not

observe any out-of-plane tearing (mode III) of the mesothelium caused by the spheroid (Fig.

1l). Protrusions penetrating the mesothelium E-cadherin junctions preceding mesothelial

fracture were only observed in ~6% of the invading spheroids (Supplementary Fig. 1i). While

in most of the spheroids, their protrusions were formed after mesothelial fracture. Indeed,

lattice light sheet imaging showed that mesothelial cells were forced apart from the apical

side first, and such separation then propagated to the basal side, leading to a complete rupture

of the mesothelium. Thus, spheroid invasion induces tensile rupture, and we have ruled out

other modes of tissue rupture.

Spheroid leader cell attachment initiates apical constriction and tensile fracture of the

mesothelium

We then investigated the cellular mechanism underlying tension-induced mesothelial fracture

by spheroids. A large displacement at one side of the microvoid (Fig. 1i) may reflect an

apical constriction starting from a mesothelial cell beneath the spheroid as the mesothelium

begins to fracture (Fig. 2a). By contrast, such aggressive apical constriction is not detected in

other areas of the intact mesothelium away from the fracture site as shown by a more constant

cell apical area (Fig. 2b). It is conceivable that apical constriction of a cell could stretch its

junctions with neighbouring cells and eventually result in the aforementioned tensile fracture

(Fig. 1i). Apical constriction is a cell shape deformation mechanism, promoting tissue

remodelling during development[29-32], that is triggered by increased activation of myosin-II at

the apical cortex[21,31,33,34]. Structured illumination super-resolution imaging of myosin-

regulatory-light-chain (MRLC)[35] showed a myosin-II network extending across the apical

region of the mesothelial cells (Fig. 2c, c'). In quantitative live-imaging, MRLC intensifies at

the junctional and apical cortex region of a mesothelial cell beneath the interacting spheroid

(Fig. 2a,d and Video 3). Such intensification of MRLC precedes junction constriction and

fracture (Fig. 2d). These observations support the notion that constriction of apical

mesothelial myosin-II cortex pulls on E-cadherin junctions, eventually leading to initiation of
mesothelial fracture.
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Besides the apical constriction mechanism, we use traction force microscopy (TFM) to
analyse the contribution of in-plane traction-mediate-migration of mesothelial cells during
fracture[23,26]. First, we find that the spheroid leader cell tends to contract the
Polydimethylsiloxane (PDMS) substrate in the absence of mesothelium (Fig. 2e). Such
inward contraction from spheroid cells is well poised to activate the inward contraction/apical
constriction on contacting mesothelial cells.
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Next, we introduced a spheroid on the mesothelium grown on PDMS but failed to detect an
enhancement in the mesothelial cell traction force on the PDMS substrate (Fig. 2f,g) or any
change in radial traction stress of mesothelial cells upon fracture initiation (Fig. 2f,
Supplementary Fig. 2a). Unexpectedly, in contrast to previous qualitative observations, we
did not observe traction-mediated lateral migration of mesothelial cells away from the
invading spheroid during fracture initiation[11]. Notably, our finding reinforces the conclusion
that mesothelial fracture ductility has absorbed and dissipated forces exerted by the spheroid
(Fig. 1j,k,l), preventing any obvious changes in the patterns of mesothelium traction forces.
Although obvious changes in the patterns of mesothelium traction forces are undetected,
Bayesian inversion stress microscopy analysis[36] identifies an increase in supracellular
mesothelial tensile stresses surrounding the spheroid before invasion (Fig. 2h,i,
Supplementary Fig. 2b). The increase in mesothelial tensile stresses is likely due to the
reorganization of apical actomyosin filaments (Supplementary Fig. 2c-g). Taken together,
this reinforces that tensile stresses, likely due to apical constriction of the mesothelium, are
responsible for invasion-induced fracture.
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228 **Intercellular and apical integrins trigger mesothelial fracture and collective cell**
229 **invasion.**
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We then look deeper into the molecular mechanisms underlying the forces driving invasion.
We hypothesize that the spheroid-mesothelium interactions trigger mesothelial apical
constriction. It was shown that mesothelial clearance is initiated by ovarian tumour
attachment to the mesothelium via integrin alpha-5[11,12], but the organization of intercellular
integrin-matrix complexes in a 3D microenvironment remains unclear. We imaged Paxillin -

a key component of the integrin matrix adhesion at the spheroid-mesothelium contact region

to visualise the intercellular integrin-matrix complexes. Strikingly, when they attached to the

mesothelium, spheroids expressing Paxillin-GFP exhibited strands of Paxillin at the spheroid-

mesothelium interface (Fig. 3a, Supplementary Fig. 2h), which grew from smaller initial

spots (Fig. 3b). The mesothelium tends to rupture after a spheroid's leader cell spreads on a

mesothelial cell (Supplementary Fig. 2i). These strands of Paxillin morphologically resemble

the integrin adhesion complexes seen when cells spread on glass[37]. We observed that

mesothelial rupture occurred after spreading of a spheroid's leader cell on the mesothelium in

~70% of invasion cases (Supplementary Fig. 2j).

As E-cadherin interactions between the epithelial assemblies[8,19,22,33,38-43] were undetected

with co-localization analysis between E-cad GFP spheroid and E-cad tdT mesothelium (Fig.

3c,d), we continued to analyse the role of intercellular integrin instead. Knocking down α5

integrin and using a thrombospondin-1 (TSP-1) peptide[44] to specifically block fibronectin-

based integrin adhesion of cells successfully blocked mesothelial fracture by the spheroid

(Fig. 3e-g, Supplementary Fig. 2j,k), validating the role of α5 integrin in the spheroid-

mesothelium attachment.

Adhesion receptors such as integrins could be present at the apical surface of mesothelial

cells, mediating their attachment to the spheroid. This is supported by our finding that

mesothelial cells detached from the adhesive (i.e. fibronectin-coated) round micropattern can

be associated with the spheroid at non-adhesive region of the substrate (Fig. 3h). Whereas in

controls, mesothelial cells remained attached on the adhesive round micropattern

(Supplementary Fig. 2l). Additionally, this observation was consistent with our TFM data,

together suggesting that mesothelial cell's outward migration away from the spheroid by

basal traction is dispensable for mesothelial fracture.

Strikingly, strands of Paxillin were localized at the apical side of mesothelial cells and

exhibited co-localization with immunostained fibronectin (Fig. 3i). Even in the absence of

spheroid attachment to the apical side of the mesothelium, α5 integrin and other binding

partners of the integrin complex, including Paxillin, kank2, tensin1, fibronectin and vinculin,

co-localized at sites of apically localized integrin-based adhesions (Fig. 3j). Notably, the

mesothelial apical integrin that we have identified here, although not visualised previously, is

reported to functionally mediate apical constriction in the embryonic Drosophila
epithelium[45,46].

It was suggested that integrin and Talin-dependent activation of non-muscle myosin-II was
required for an uncoupling mechanism to separate the mesothelial cells from fibronectin
fibrils to drive mesothelial cell migration away from the spheroid during invasion[11,12].
However, instead of such an uncoupling mechanism, the mesothelial apical fibronectin
network undergoes fracture as the spheroid invades (Video 4). Thus, our data shows that
ECM and mesothelium barrier fracturing mechanism is the dominant invasion mechanism.

Furthermore, mesothelial α5 integrin or mesothelial/spheroid fibronectin knockdown was
sufficient to block spheroid-induced fracture (Fig. 3k,l, Supplementary Fig. 2m-p and Video
5). Whereas fibronectin from the media is not required for invasion, as invasion remains
robust in serum-free media experimental condition (Fig. 3k, Supplementary Fig. 2n). Of note,
knockdown of α5 integrin primarily depleted apical integrins with a subtle reduction of basal
integrins (Supplementary Fig. 2o). Thus, the mesothelium's apical integrin adhesion complex
and spheroid fibronectin are required for spheroid invasion.

Our evidence suggests that mesothelial apical constriction from intercellular integrin
engagement initiates the mesothelial tensile fracture. To directly test this notion, we blocked
spheroid-induced mesothelial apical constriction by linking a dominant-negative RhoA
mutant to α5 integrin (Fig. 3m and Supplementary Fig. 2q-t). This significantly reduced
spheroid-induced mesothelial fractures (Fig. 3n,o, Supplementary Fig. 2u,v, and Video 5).
Although RhoA inhibition reduces mesothelial apical fibronectin fibril assembly
(Supplementary Fig. 2w,x), the restoration of fibronectin fibrils by introducing exogenous
fibronectin-1 fails to rescue the reduction of invasion caused by RhoA inhibition (Fig. 3n,o,
Video 6). Thus, intercellular integrin engagement induces mesothelial fracture, in part by
apical myosin-II activation, is the key molecular mechanism driving invasion.

Spheroid invasion of the mesothelium did not involve induction of jamming transition

We then addressed how spheroid multicellular dynamics affect invasion. Invading spheroids
break through the mesothelium and then attach to the submesothelial substrate to prevent
anoikis of spheroid cells[47](Fig. 4a). Thus, we assess the critical relationship between spheroid

cell dynamics and mesothelial fracture. We quantitatively compared the cellular movement

pattern in (1) invading spheroids with (2) non-invading spheroids due to ITGA5 knockdown

in the mesothelium. We obtained tracking data of the spheroid's cell nuclei by deep-learning

segmentation[48,49] and IMARIS tracking (Fig. 4b,c, Supplementary Fig. 3a). In invading

spheroids, there was a spreading of cells at the bottom layer, as well as an overall bias in cell

movement towards the mesothelium base even before mesothelial fracture (Fig. 4c,d, Video

7). By contrast, the cell movement in non-invading spheroids has no particular direction (Fig.

4d,e). We then assess whether directed cell motion is involved in spheroid invasion by

quantifying the persistency of cell velocity (Methods). Our results suggest that cells in non-

invading spheroids move less persistent than those in invading spheroids (Fig. 4f).

Jamming transition is a common trigger of collective cell migration, involving the transition

of multicellular assemblies from a jammed to fluid state[50-53]. To quantify the involvement of

jamming transition, we then quantify the mean-square displacement (MSD) of cell nucleus

centroids obtained from AI segmentation and cell tracking. To exclude the effect of a global

drift of the spheroids, we adopted pair-wise MSD for our system (see Methods). We found

that at a small timescale of about 10 mins, both non-invading and invading spheroids show

roughly diffusive movement with MSD linearly growing with lag time, while on the

timescale larger than 50 minutes, MSD grows with lag time super-linearly for invading and

free-spreading spheroids and sub-linearly in non-invading spheroid (Fig. 4g,h). The short-

time diffusive movement of cells suggests that the spheroid is in a fluid state[36,37,38] even when

the spheroid cannot invade due to the lack of ITGA5 expression in the mesothelium. Our 3D

cell tracking and MSD analysis indicate that cancer cells are in an unjammed state even when

confined as a spheroid with intact E-cadherin adhesion. Thus, the triggering of jamming

transition is not a key driver for cancer spheroid invasion and spreading.

Instead, the whole spheroid could be considered as a multicellular droplet held by an

effective tensile surface. The long-time sub-linearity of MSD with non-invading spheroids

indicates the caging effect brought by the boundary of this effective surface, whereas, in

invading spheroids, the super-linearity of MSD on the larger timescale implies the existence

of some external force that guides cells in persistent and directed movement. Thus, this

external force likely originates from wetting at the intercellular integrin cell-cell contact

between the spheroid leader cell and the mesothelium. Indeed, α5 integrin and fibronectin are

required for the invasion. Moreover, the spreading of the spheroid leader cell coincides with

the shrinkage of the underlying mesothelial cell-cell junction preceding mesothelium fracture

(Fig. 4i). Unexpectedly, spheroid invasion is independent of jamming transition induction.

Theoretical modelling of migration and tissue invasion

To elucidate the underlying physical mechanisms behind the observed experimental

phenomena, we developed a theoretical framework grounded in the concept of active wetting

(Methods). Specifically, we modelled the spreading and invasion of leader spheroid cells as a

wetting-driven interfacial displacement process, in which the system's free energy is

determined by interfacial energy and polarization work (Eq. 1). The interfacial energy, in turn,

evolves dynamically according to interfacial adhesion and cortical tension, as governed by

Eqs. (2~4).

Our theoretical model predicts the critical conditions under which spheroid cell invasion

occurs. A physical process can only proceed spontaneously when the change in free energy is

negative (Fig. 5a), thereby providing a clear boundary between invasive and non-invasive

regimes (Fig. 5b,c). The theoretical analysis indicates that the critical condition for

spontaneous invasion is characterized by a 1/2 power law (Eq. 8) between the spheroid-

mesothelial integrin adhesion strength (W_{I0}, Methods) and the activated contractility of

mesothelial cells (described by the coupling strength β, Methods). Moreover, due to the

apical constriction of mesothelial cells, the effective adhesion length between the two cell

types is substantially reduced, which in turn increases the required integrin-mediated

adhesion strength for effective invasion. As expected, the critical condition also shows that

polarization of the spheroid cells toward the mesothelial layer lowers the energy barrier and

facilitates invasion, while an increase in the thickness of the barrier cell layer impedes it (Fig.

5b,c).

To directly compare theoretical predictions with experimental results, we conducted

numerical simulations of the invasion process using the proposed theoretical framework in

conjunction with the active foam model[54] (Supplementary Fig. 3b, Methods). Key simulation

parameters were informed by experimental observations and cortical tension measurements

by atomic force microscopy (AFM) (Supplementary Fig. 3c,d, Methods).

The simulations (Fig. 5d-k) reproduced all key experimental observations, including the

integrin-mediated extension of the spheroid-mesothelial interface, enhanced cortical tension

due to active mesothelial contraction, E-cadherin junction fracture between mesothelial cells

in contact with spheroid cells, and internal cellular rearrangements within the invading

spheroid cell (Fig. 5d,e, Video 8, top left). The accuracy of our model was further validated

by comparing simulated and experimentally observed apical constriction areas and apical

tension in mesothelial cells (Fig. 5f,g). In particular, by tracking the changes in spheroid cell

shape (quantified by the shape index I_s, a key descriptor of cell morphology and intercellular

junction lengths (Fig. 5h), our simulation identified that spheroid cells undergo prominent T1

transition during initiation of mesothelial invasion. This leads to super-diffusive motion of

the spheroid mass (Fig. 5i,j), consistent with experimental observations (Fig.4d,e,g).

Numerical modelling enabled us to quantitatively control the parameters of invasion; thus, we

seek to identify key factors affecting the invasion process. As a direct driver of invasion,

weakened integrin adhesion between cells slowed down spheroid rearrangement and

ultimately abolished the spheroid's ability to invade the barrier layer (Fig. 6a-e; Video 8, top

right). Conversely, increasing integrin adhesion promoted rapid internal rearrangement of

spheroid cells and accelerated rupture of the mesothelium (Fig. 6f-j; Video 8, bottom left).

We did not observe an obvious effect of reduced E-cadherin strength in mesothelial cells on

collective invasion (Supplementary Fig. 3e-h, Video 8, bottom right). Nonetheless, this

reduction caused greater deformation of neighboring mesothelial cells during invasion (Fig.

5k, Supplementary Fig. 3i), which may explain the experimentally observed increased

mesothelial clearance upon E-cadherin adhesion weakening (Fig. 1h).

Finally, we performed simulations to evaluate the impact of mesothelial cell contractility and

summarized the results alongside those involving intercellular adhesion strength in phase

diagrams (Fig. 6k,l,m, Supplementary Fig. 3j). Specifically, moderate enhancement of apical

constriction in barrier cells accelerated invasion, whereas overtly high constriction effectively

suppressed both spheroid invasion and junctional rupture (Fig. 6k). Therefore, invasion

occurs only within a defined region of the phase diagram characterized by high integrin

adhesion strength and low-to-moderate barrier cell contractility. Moreover, consistent with

apical constriction without tissue fracture during embryonic development, our theory and

numerical simulations predict that when the intercellular integrin-mediated adhesion strength

is weak (or absent), apical constriction alone does not drive the rupture of the barrier cell

monolayer (Fig. 5b,c, Fig. 6k,l). The invasion–non-invasion boundary predicted by

simulations aligned closely with theoretical predictions (Fig. 6k,l), further confirming that

spheroid cell invasion is governed by an interfacial displacement process driven by active

tissue wetting. Similarly, due to the competition between integrin adhesion–mediated wetting

and mesothelial apical constriction–driven dewetting, the spheroid cells exhibited

morphological transitions between wetting and dewetting states, as evidenced by a significant

difference in shape index between the invasion and non-invasion regions in the phase figures

(Fig. 6m, Supplementary Fig. 3j).

Discussion

Prevailing models have attributed collective invasion to unjamming. We challenge this

interpretation. Our analyses show that spheroid cells maintaining E-cadherin–mediated

contacts are already in an unjammed state, as indicated by mean squared displacement

measurements. Although similar dynamic signatures have been reported in other collective

invasion studies and interpreted within a jamming framework,[52,55-57] such interpretations are

imprecise because a solid-to-fluid state transition is not evident. In condensed matter physics,

unjamming refers specifically to a glass-like solid becoming fluid as packing constraints are

relieved. By contrast, the longer-timescale (~50 mins) dispersal dynamics observed here,

likely reflecting multicellular spheroid spreading, indicates a liquid-to-gas–like transition

rather than a solid-to-liquid unjamming.

Moreover, spreading of a single leader cell is sufficient to initiate collective invasion and

barrier fracture, indicating that invasion does not require a multicellular phase transition such

as unjamming. Taken together, these observations demonstrate that unjamming neither

precedes nor drives tissue invasion.

What, then, initiates tissue invasion?

A previous model proposed that spheroid protrusion and dissociation of surface fibronectin

fibrils from the mesothelium drive outward mesothelial migration to facilitate invasion.[11] By

contrast, higher-resolution quantitative imaging shows that invasion is initiated through

contractility-driven fracture of the mesothelial barrier, resembling material "crazing".[25] This

barrier failure arises from RhoA-dependent forces transmitted through spheroid integrins to

mesothelial apical integrins via the intervening fibronectin matrix, triggering mesothelial

apical constriction and ultimately tensile rupture of cell–cell junctions. Together, these results

indicate that invasion is driven not by protrusive pushing, fibronectin uncoupling, or jamming

transitions, but by contractility-induced tensile fracture of the barrier, enabling subsequent
spheroid spreading and mesothelial clearance.

To establish a quantitative framework for this process, we applied wetting theory to model
spheroid–tissue interactions. While classical wetting describes passive interfacial energy
balance, our findings show that barrier cell contractility actively modulates interfacial energy
beyond fluctuations arising from junctional dynamics.[58] Mesothelial apical constriction,
coordinated with intercellular integrin mediated adhesion, exerts dual effects on invasion:
moderate integrin based contractility promotes invasion, whereas excessive contractility
suppresses it through negative feedback that limits further integrin-mediated adhesion growth.
Thus, invasion dynamics are governed not solely by properties of the invading spheroid but
by active mechanical regulation from the barrier tissue. This active wetting framework
quantitatively predicts interfacial invasion behavior and highlights the tissue barrier as a
critical mechanical regulator of tissue invasion. Notably, this conclusion is consistent with
prior work demonstrating that myoepithelial barrier cells can restrain and recapture invasive
breast cancer spheroids[59].

In conclusion, rather than invasion driven by protrusive pushing or induction of a jamming
transition, we demonstrate that coordinated subcellular contractility in both invading cells and
the tissue barrier drives invasion through tensile fracture. These findings challenge prevailing
paradigms and establish the tissue barrier as an active mechanical regulator of tissue invasion.

Limitations of the study

First, whether the mechanism we identify is a key driver of metastatic colonization in cancer
patients remains to be determined. Second, consistent with the inward contraction observed at
the mesothelial surface prior to invasion, we show that spheroid leader cell spreading induces
inward contraction of the TFM PDMS substrate. However, the PDMS substrate used for
traction force microscopy does not necessarily recapitulate the mechanical behavior of the
mesothelial apical surface.

Resource availability

Lead contact

Further information on resources reported in this study should be directed to Yuan Lin

(theory)   (ylin@hku.hk)   and   the   lead   contact,   Selwin   K.   Wu

(selwin_wu@mail.dfci.harvard.edu)

Materials availability

Plasmids generated in this study are available on request. Immortalized non-GFP expressing

ZT cells created for this study are available on request. Request and information on the

resources and equipment used and reported in this study should be directed to Celestine Z. Ho

(celestineho@u.nus.edu) and will be fulfilled by Boon Chuan Low (dbslowbc@nus.edu.sg).

Data and code availability

The scripts generated in this study have been deposited at our GitHub repository:

https://github.com/selwinwu/morphogenesis.git and are publicly available as of the date of

publication. The specific version of this resource is also archived in Zenodo under DOI

10.5281/zenodo.16737385.

Data availability

The authors declare that the data supporting this study's findings are available within the

paper and its supplementary files. The raw data generated in this study are available from the

corresponding authors upon reasonable request.

Code availability The scripts generated in this study are available from

https://github.com/selwinwu/morphogenesis.git

Figures

Figure 1. Spheroid-induced mesothelial tensile fracture.

(a,b) Ovarian tumour metastasis. Hematoxylin and eosin-stained human peritoneal surface

without metastatic tumour implantation (a) and a microscopic tumour implant on the omental

surface from a patient with metastatic serous ovarian carcinoma (b). Mesothelium (green

arrow, a) lines the abdominal surface but is not detected beneath the invading ovarian

tumour (b & b'). Representative images from 4 ovarian cancer patients with different layers

of tissue are indicated. Inset from b' with arrows indicating the invading tumour/stroma interface without the mesothelium.

(c) An E-cadherin GFP-expressing spheroid invades and clears the mesothelium with a basement membrane.

(d) Mesothelial cell-cell contact forms E-cadherin fibrillar bridges and microvoids upon spheroid invasion. Representative time-lapse images of the mesothelium under a spheroid (colour-coded in hot orange). d'-d''' with detailed views. d''' shows a cadherin fibrillar bridge being extended as crazing proceeds. Red arrows point towards a fibrillar extension, and green arrows point towards a microvoid.

(e) Schematic of E-cad-GFP-RhoA-T19N fusion protein.

(f,g) Reduction of E-cad fibrillar bridges during mesothelial fracture when E-cad-based contractility is reduced. Representative images with arrows indicating fibrillar bridges (f) and quantification (g) of the percentage of mesothelium E-cad fibrillar bridges when either RhoA-T19N mutant is fused to E-cad or in controls.

(h) Increased size of mesothelial clearance when E-cadherin adhesion is compromised. Quantitative comparison of the mesothelial clearance size when either RhoA-T19N mutant is fused to mesothelial E-cad or in controls.

(i) Tension-induced fracture. PIV analysis of fluorescent microbeads on top of the mesothelium expressing E-cad tdTomato. The heatmaps of shear strain rate (s^{-1}) or normal strain rate (s^{-1}) or velocity($\mu m/s$) from the PIV analysis. Right magnified view (white dotted rectangle) of the velocity PIV heatmap shows outward vectors (red dotted circles) away from the fracture initiation site (grey dotted circle).

(j) Diagram of three different modes of fracture which the mesothelium may undergo (modified from modes of material fracture). The modes are Mode I: Opening (stress orthogonal to the local plane of the crack surface), Mode II: In-plane-shear (stress parallel to the crack surface but orthogonal to the crack front), and Mode III: Out-of-plane shear (stress parallel to the crack surface and the crack front). The arrows indicate the direction of stress, and asterisks indicate the crack point.

(k) Tension-induced fracture is the dominant initiating mode of fracture. Comparison between the fold changes of the shear strain rate and normal strain rate with velocity magnitude analysis during fracture initiation and fracture.

(l) Mode III: Out-of-plane shear fracture is not detected when the spheroid begins to invade

the mesothelium. XZ views of time-lapse lattice light-sheet microscopy images of E-cad GFP

spheroid invading E-cad tdT mesothelium. Grey arrows indicate the opening of mesothelial

cell-cell contacts.

All data are means ± SEM from at least n=2 independent experiments, except for (g), which

are from n=8 independent experiments, ns, not significant, *p < 0.05, **p < 0.01, ****p <

0.0001; analysed with unpaired t-test. Scale bars, 5µm.

Figure 2. Initiation of fracture from apical constriction of the mesothelial cell.

(a,b,c,d) Apical constriction precedes fracture initiation of the mesothelium. (a) Time-lapse

images of the spheroid (brightfield, top right) invading mesothelium expressing E-cad tdT

and MRLC-GFP. Intensification of MRLC filaments is observed as apical constriction of the

mesothelial cell led to subsequent fracture initiation of the mesothelium. (b) Variance

quantification of mesothelial apical cell area beneath spheroid during fracture compared to

areas not undergoing fracture. (c) Network of myosin-II filaments spans the apical region of

the mesothelium. Structured illumination microscopy of mesothelium expressing MRLC-

GFP, with a detailed view in (c') (d) Myosin-II filaments intensification precedes apical

constriction. Representative temporal changes in myosin-II filaments intensity at the apical

cortex and size of mesothelial cell apical area.

(e) Spheroid leader cell contracts basal substrate inwards. Time-lapse images of radial

traction stress of E-cad GFP expressing spheroid leader cell attaching onto the PDMS

substrate.

Heat maps in (e,f) shows the direction and magnitude of radial traction stress. The colour

scale bar indicates the magnitude of the outward (red) and inward (blue) radial traction stress

from the mesothelial fracture site.

(f,g) Traction force of mesothelial cells did not exhibit obvious changes upon fracture. Time-

lapse images (f) and quantification of fracture site average cellular traction stress (g) of E-cad

tdT expressing mesothelium when invaded by spheroid expressing E-cad GFP. The

discontinuous line in (f) indicates the area of the fracture.

(h,i) An increase in mesothelial tensile stresses at regions surrounding the invading spheroid

prior to invasion. Comparison of isotropic tensile stress at a 10-micron boundary (h, red)

surrounding invading spheroids prior to invasion and control which are spheroids that fail to

invade (i). For green regions highlighted in (h), refer to Supplementary Fig. 2b.

All data are means ± SEM from n=7 cells from at least 3 independent experiments, except for

(b), which is from 4 independent experiments, *p < 0.05, analysed with Mann-Whitney U

test. Scale bars, 5µm.

Figure 3. Intercellular integrin adhesion and fibronectin matrix complexes connect the

spheroid to the mesothelium.

(a) Strands of integrin adhesion clusters at the spheroid-mesothelium interface from spheroid

expressing Paxillin GFP with indicated XZ representative views (bottom).

(b) The spheroid leader cell's Paxillin GFP clusters grow gradually at the spheroid-

mesothelium interface. The cell that is first attached to the mesothelium is defined as the

invasion leader cell. Time-lapse imaging of Paxillin GFP at the spheroid-mesothelium

interface.

(c) Cadherin at the interface between spheroid (top left, brightfield) expressing E-cad GFP

and mesothelium expressing E-cad tdTomato does not co-localize, with detailed views of c'

in c'' and c'''.

(d) Representative fluorescence line-scan analysis of spheroid E-cad GFP and mesothelium

E-cad tdTomato in c''' shows a lack of homophilic E-cadherin interactions.

(e) Thrombospondin-1 peptide treatment, blocking integrin-based fibronectin attachment,

prevents spheroid-induced mesothelial fracture. Rate of spheroid-induced fracture in control

compared to thrombospondin-1 peptide treated cultures.

(f,g) Spheroid integrin knockdown blocks fracture. Representative images (f) and

quantification of the spheroid (g) invading the mesothelium in control compared to ITGA5

knockdown in the spheroid.

(h) Mesothelial cells associating with spheroids at non-adhesive regions of micropatterned

glass. Time-lapse images of spheroid displacing mesothelial doublets from round adhesive

fibronectin patterns into non-adhesive zones.

(i)   Co-localization   of   fibronectin   with   apical   mesothelial   integrin   clusters.

Immunofluorescence images of immunostained fibronectin and mesothelium expressing

Paxillin-GFP with detailed views (bottom).

(j)   Mesothelial   apical   integrin   adhesion   complex   without   spheroid   engagement.

Immunofluorescence images of mesothelium apical region immunostained for Paxillin,

ITGA5, FN1, Kank-2 and Vinculin.

(k,l) FN1 and ITGA5 from the mesothelium and spheroid are required for spheroid-induced

mesothelial fracture. Rate of spheroid-induced fracture in control compared to either

mesothelium FN1 knockdown, spheroid FN1 knockdown, serum-free media condition (k) or ITGA5 knockdown (l).

(m) Design of ITGA5-GFP fused to RhoA dominant negative T19N mutant for expression in the mesothelium.

(n,o) Spheroid-induced fracture requires activation of contractility at sites of mesothelial ITGA5 adhesion. Representative images (n) and quantification (o) of spheroid-induced mesothelial fracture rate in control mesothelium expressing ITGA5 knockdown with reconstitution of ITGA5-GFP compared to the reconstitution of ITGA5-GFP fused to RhoA dominant negative T19N mutant in the mesothelium.

All data are means ± SEM from at least with ~50 spheroid from n=3 independent experiments, *p < 0.05, **p < 0.01; analysed with unpaired t-test. Scale bars, 5µm.

Figure 4. Jamming transition did not induce the spheroid invasion of the mesothelium.

(a) Model for spheroid-induced mesothelial tensile fracture

(b) Representative images of an OVCA433 spheroid labeled with H2B-mNeon segmented by 3D StarDist (left) and a 3D rendering of the segmented nuclei.

(c) Representative 2D projection of a 3D cell trajectories in spheroid invading the mesothelium over time: (left) in XY axis, projected from the top, (middle) map in XZ axis projected from the side and (right) map in Radial Z (RZ) axis, a radial projection of spheroid assuming the rotational symmetry around the axis at the in-plane center of the spheroid.

(d) Spheroid cells exhibit motility bias towards the mesothelium prior to mesothelial fracture. Representative XZ and RZ side view velocity maps of a spheroid 6 and 3 minutes before mesothelial fracture compared to spheroids that will not induce fracture due to ITGA5 knockdown of the mesothelium.

(e) Mesothelium ITGA5 is required for spheroid cells motility bias towards the mesothelium. The ratio of spheroid cells Z velocity mean over standard deviation of XY velocities distribution of spheroid cells on control mesothelium compared to spheroid cells on ITGA5 knockdown mesothelium.

(f) Persistency of directed spheroid cell migration (see Methods) is higher in spheroid invading the mesothelium compared to spheroid without invasion due to ITGA5 knockdown in the mesothelium. Quantification of spheroid cells velocity auto-correlation persistency in spheroid with or without invasion.

(g, h) Pair-wise mean square displacement (MSD) (g) (see Methods) of representative

samples for spheroid with or without invasion. (h) Local slope of MSD value obtained from

the pair-wise mean square displacement graph for six selected regions from top to base of

spheroids (see Methods) for two different conditions.

(i) Shrinkage of mesothelial cell-cell junctions and spreading of leader cell on mesothelium

precedes fracture. Representative temporal changes in leader cell spreading area at

mesothelial and sub-mesothelial regions is in green, and mesothelial junction length is in red.

Dotted line indicates the onset of mesothelial cell-cell contact rupture.

(j,k) Spheroids expressing higher levels of E-cadherin have reduced rate of invasion.

Representative E-cad GFP expressing spheroid images (j) and quantification of the spheroid

(k) invading the mesothelium in control compared to higher E-cadherin levels expressing

spheroid.

All data are means ± SEM from at least n=4 independent experiments, *p < 0.05, **p < 0.01,

****p < 0:0001; analysed with Mann-Whitney U test. Scale bars, 5μm.

Figure 5. Theoretical predictions and numerical simulations of wetting-induced invasion.

(a-c) Theoretical predictions for spontaneous fracture initiation and spheroid invasion. (a)

Schematics for the relationship between active wetting (increasing δL_{in}) and free energy

change, where a spontaneous invasion sets the condition as $\Delta G_{\text{m}} \leq 0$. (b) Increasing

mesothelial monolayer thickness (represented by increasing L_{m0}) significantly pushes the

critical invasion conditions toward higher intercellular integrin adhesion. (c) Spheroid

polarization promotes cell invasion and lowers the requirements of W_{I0} for complete fracture

initiation.

(d-k) Simulated invasion process agrees with experimental results when the intercellular

adhesion is comparable to the mesothelial E-cadherin adhesion, i.e. when $W_{\text{I0}}/W_0 = 0.9$,

$W_0/T_0 = 1.2, \beta/T_0 = 1.5$. (d) Intercellular integrin adhesion drives spheroid invasion and

mesothelial fracture. Stages of collective invasion include [i] initial state, [ii] establishment of

contact between the leader spheroid cell and the 2nd mesothelium cell, [iii] invasion, and [iv]

complete mesothelial fracture. To make a direct comparison with experimental results, we set

the initial time as -3 mins. (e) Complete fracture occurs ~10 mins after the spheroid leader

cell comes into contact with the 2nd mesothelial cell. The right interface refers to the interface

between the leader spheroid cell #1 and the #3 mesothelial cell, the left interface refers to the

interface between the leader spheroid cell #1 and the #2 mesothelial cell, and the fracturing

junction refers to the junction between #2 and #3 mesothelial cells labelled in (d). (f)

Simulated apical tension of the #2 mesothelial cell is in qualitative agreement with the

observed MRLC results. The computed tension is normalized by the static mesothelial

tension T_0 . (g) Simulated apical area of the #2 mesothelial cell fits well with the

experimentally measured apical cell area. The apical area is calculated by the square of the

simulated apical cell length and is normalized by the initial area. (h) Spheroid cells show T1

transition during the invasion process. The shape index (individual and average) of the

spheroid cells is used to quantitively evaluate the rearrangement of the spheroid. (i)

Simulated collective spheroid cell motion towards the direction of the mesothelium (negative

Z direction). (j) Central spheroid junction shrinkage indicates striking deformation and

intercalation of spheroid cells. (k) Longitudinal strain of the mesothelial cells. Longitudinal

strain is computed by the dynamic change of cell length.

Figure 6. Extensive simulations show apical constriction level and adhesion strength as key

factors affecting invasion dynamics.

(a-e) Low integrin adhesion strength ($W_{I0}/W_0 = 0.3, W_0/T_0 = 1.2, \beta/T_0 = 1.5$) prevents

spheroid T1 transition and leads to incomplete mesothelial fracture. (a) Process of incomplete

fracture includes [i] initial state, [ii] contacting between the leader spheroid cell and the 2nd

mesothelium cell, [iii] further invasion, and [iv] complete mesothelial fracture nucleation.

The initial time is set as -3 mins. (b) Fracturing junction reaches its minimal length ~25

minutes after contacting the 2nd mesothelial cell, indicating an incomplete fracture at low

integrin adhesion strength. The right interface refers to the interface between the leader

spheroid cell (#1) and the #3 mesothelial cell, the left interface refers to the interface between

the leader spheroid cell (#1) and the #2 mesothelial cell, and the fracturing junction refers to

the junction between #2 and #3 mesothelial cells. (c) Low integrin adhesion strength prevents

T1 transition of spheroid cells during invasion. (d) Low integrin adhesion strength results in

slow central junction shrinkage and thus prevents T1 transition in the spheroid. (e) Low

integrin adhesion strength changes the distribution of mesothelial strain in adjacent cells.

(f-j) High integrin adhesion strength ($W_{I0}/W_0 = 1.5, W_0/T_0 = 1.2, \beta/T_0 = 1.5$) results in

striking spheroid T1 transition and mesothelial fracture. (f) Dynamic process of rapid fracture

includes [i] initial state, [ii] contacting between the leader spheroid cell and the 2nd

mesothelium cell, [iii] further invasion, and [iv] complete mesothelial fracture nucleation.

The initial time is set as -3 mins. (g) Complete fracture occurs ~6 mins after the leader cancer

cell comes into contact with the 2nd mesothelial cell. The right interface refers to the interface

between the leader spheroid cell #1 and the #3 mesothelial cell, the left interface refers to the

interface between the leader spheroid cell #1 and the #2 mesothelial cell, and the fracturing

junction refers to the junction between #2 and #3 mesothelial cells. (h) High intercellular

integrin adhesion strength leads to striking T1 transition of spheroid cells during invasion. (i)

High integrin adhesion strength results in quick central junction shrinkage and, thus, striking

T1 transition in the spheroid. (j) Slightly smaller mesothelial deformation was observed by

increasing intercellular integrin adhesion strength.

(k-m) Mesothelial fracture and spheroid rearrangement are strongly interrelated during

invasion. The simulated critical boundary for the occurrence of mesothelial fracture agrees

well with the prediction (black curves) given by Eq. (5). Complete mesothelial fracture and

spheroid rearrangement only occur at low to medium apical contractility and high integrin

adhesion. Low integrin adhesion strength or high apical contractility leads to lower spheroid

T1 transition and incomplete fracture. (k) Complete fracture time as a function of the integrin

adhesion strength and apical contractility. Rapid invasion occurs at medium apical

contractility and strong integrin adhesion strength. No data is at the bottom right corner since

no complete mesothelial fracture occurs in this region. The time taken for fracture is

calculated as the period between the contact of the leader spheroid cell with the 2nd

mesothelial cell and the complete rupture of the mesothelial junction. (l) High apical

contractility with low intercellular integrin adhesion strength leads to incomplete fracture, i.e.,

a non-vanishing minimal junction length (in the lower right region) between #2 and #3

mesothelial cells labeled in (Fig. 5d). The minimal fracturing junction length is normalized

by its initial length. (m) Spheroid cell rearrangement is regulated by intercellular integrin

adhesion and apical contractility. The shape index reflects the deformation of the leader

spheroid cell with respect to different intercellular integrin adhesion strength and apical

contractility. Here, the shape indices are taken when the fracturing junction length reaches 0

(for cases where mesothelium is completely fractured) or when the fracturing junction length

reaches its minimum for cases where there is no complete mesothelial fracture.

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Author Contributions

S.K.W. conceived the project with input from Yuting Lou and A.S.Y. C.Z.H. and S.K.W.
performed all experiments except traction force microscopy and immunoblotting, which were
shared with J.X. and C.B.H. D.L. and D.S.T. provided cancer pathology specimens and
performed pathological analysis. F.Q.S. and Yuan Lin developed the theoretical model and
conducted simulations and quantitative analyses for fracture dynamics and actomyosin fiber
alignment. T.H. and Yuting Lou performed spheroid velocity and jamming transition
analyses. P.M. provided the BISM code and assisted with BISM analysis. M.H. Nai, Yuting
Lou, and C.T. Lim contributed to AFM-based tension measurements. C.B.H., I.Y., and M.S.
performed traction force analysis and 3D StarDist AI–based nuclear segmentation. S.V. and
A.S.Y. provided input on cadherin and myosin experiments. S.K.W. wrote the manuscript,
with F.Q.S. writing the modelling sections. C.B.H., Yuan Lin, C.Z.H., Yuting Lou, and
A.S.Y. edited the manuscript. J.C. contributed to imaging and microscope setup. All analyses
were led by S.K.W., with assistance from C.Z.H. All authors provided feedback on the
manuscript. S.K.W. supervised the study.

Declaration of interests

768 A.S.Y. is a member of the Advisory Board of Developmental Cell.

770 STAR⬚Methods

Key resources table

REAGENT or RESOURCE	SOURCE	IDENTIFIER
Antibodies		
Mouse anti-Fibronectin	BD Transduction	Cat# 610077
Mouse anti-CD49e/Integrin α5 Chain	BD Pharmingen	Cat# 555614
Mouse anti-Integrin alpha-5	EMD Millipore	Cat# MABT201
Rabbit anti-Paxillin alpha, beta, and gamma isoforms	Abcam	Cat# ab32084
Mouse anti-GAPDH	Santa Cruz	Cat# sc-32233
Rabbit anti-non-muscle myosin heavy chain IIA	Sigma-Aldrich	Cat# M8064
Rabbit anti-laminin	Novus Biologicals	Cat #NB300-144
Mouse anti-GFP	Invitrogen	Cat# MA5-15256
Chemicals, peptides, and recombinant proteins		
10X Phosphate Buffered Saline (PBS)	1st BASE	Cat# BUF-2040-10X1L
Fetal Bovine Serum, heat inactivated, certified, One Shot™, United States	Gibco	Cat# A3840001
Bovine Serum Albumin (BSA)	Sigma-Aldrich	Cat#A9647
Glycine	1st BASE	Cat#BIO-2085
Triton™ X-100	Sigma-Aldrich	Cat# 1.08603
Human Plasma Fibronectin Purified Protein	Sigma-Aldrich	Cat#FC010
MCDB 105 Medium	Sigma-Aldrich	Cat#117-500
Medium 199, no phenol red	Thermo Fisher	Cat#11043023
TrypLE™ Express Enzyme (1X), no phenol red	Gibco	Cat# 12604039
Cell Dissociation Buffer, enzyme-free, PBS	Thermo Fisher	Cat#13151014
Geltrex™ LDEV-Free, hESC-Qualified, Reduced Growth Factor Basement Membrane Matrix	Gibco	Cat#A1413301
Experimental models: Cell lines		
Human ovarian adenocarcinoma OVCA433 epithelial cells (RRID:CVCL_0475)	Laboratory of Michael Sheetz	-

ZT human benign pleural effusion mesothelial cells	Laboratory of Tan A. Ince	
Immortalized non-GFP expressing ZT human benign pleural effusion mesothelial cells	Derived from ZT human benign pleural effusion mesothelial cells obtained from the laboratory of Tan A. Ince	
Oligonucleotides		
siRNA against human ITGA5 5'-GGACCAGGATGGCTACAATGA-3'	IDT	N/A
siRNA against human FN1 (5'-GCAGCACAACUUCGAAUUA-3' ; 5'-GAAAUAGAUGCAACGAUCA-3'; 5'-GAGGAAAUCUGCACAACCA-3'; 5'-CCUAAAGACUCCAUGAUCU-3')	Dharmacon ON-TARGETplus SMARTpool	#2335
Recombinant DNA		
pLL5.0 Myosin Regulatory Light Chain-GFP	Addgene	Cat# 187260
pLL5.0 human E-cadherin shRNA knockdown reconstituted with mE-cadherin-tdTomato	Addgene	Cat# 101278
pLL5.0 E-cadherin shRNA/mEcad–GFP	Addgene	Cat# 101285
pLL3.7 human Paxillin shRNA knockdown reconstituted with gallus gallus Paxillin GFP. pLL3.7 Paxillin shRNA/gallus gallus Paxillin-GFP	This paper	N/A
pLL5.0 human ITGA5 shRNA knockdown reconstituted with shRNA resistant human ITGA5-GFP -- pLL5.0 human ITGA5 shRNA/shRNA resistant human ITGA5-GFP	This paper	N/A
pLL5.0 human ITGA5 shRNA knock down reconstituted with siRNA resistant human ITGA5-GFP fused to a linker and RhoA-T19N pLL5.0 human ITGA5 shRNA/shRNA resistant human ITGA5-GFP-RhoA-T19N	This paper	N/A
pLL5.0 human E-cadherin shRNA knockdown reconstituted with mE-cadherin-GFP fused to a linker and RhoA-T19N pLL5.0 E-cadherin shRNA/mEcad–GFP-RhoA-T19N	This paper	N/A
Software and algorithms		
Fiji (ImageJ)	Schneider et al., 2012	RRID:SCR_002285 https://imagej.net/software/fiji/downloads
MATLAB	MathWorks	https://ww2.mathworks.cn/products/matlab.html

PIVlab	PIVlab	https://www.pivlab.de/
JPK instrument software	JPK Instruments	JPK SPM software
3D StarDist	Martin Weigert et al.	https://github.com/stardist/stardist
MetaMorph Microscopy 7.10.5.476	Molecular Devices	RRID:SCR_002368
Other		
Nikon ECLIPSE Ti-2 Inverted Microscope Systems	Nikon	Eclipse Ti2-U
Iwaki 12mm Glass Base Dishes	AGC Techno Glass (Iwaki)	Cat# 3911-035
Falcon® 15 mL High Clarity PP Centrifuge Tube, Conical Bottom, with Dome Seal Screw Cap, Sterile	Falcon	Cat# 352096

Experimental models and study participant details

Cell culture OVCA433 ovarian serous adenocarcinoma cell line and the ZT mesothelial cells

were cultured in a 1:1 ratio of medium MCDB 105 (Cell Applications Inc.) and Medium 199

(GIBCO) supplemented with 10% FBS (GIBCO). The OVCA433 cell lines were obtained

from Michael Sheetz's laboratory. ZT mesothelial cells were obtained from a benign pleural

effusion, a gift from Ince Tan's laboratory. These cells were immortalized by ectopic

expression of SV40 T antigen and overexpression of human telomerase (fused to GFP), as

previously described [13]. Non-GFP expressing ZT cells were obtained by sorting out non-

fluorescence ZT cells, and they were subsequently immortalized by transfecting them with

SV40 T-antigen expressing plasmid (Addgene). Cells were tested negative for mycoplasma

with MycoStrip (Invivogen).

Human tissue sections

Hematoxylin and eosin (H&E)-staining sections of human ovarian cancer sections were

obtained from archived patients in the National University Hospital, Singapore. All samples

were obtained with approval by Singapore National Healthcare Group's Domain Specific

Review Board under the reference number 2013/00705. A senior pathologist reviewed the

specimens to identify the ovarian tumour invading the peritoneum.

Plasmids, siRNA and shRNA For the expression of fluorescence transgenes we subcloned

shRNA-resistant transgene fused with the fluorescence tag into the multiple cloning site of

either lentiviral pLL3.7 or pLL5.0 vectors by recombination. The shRNA targeting the

corresponding endogenous proteins is cloned into the lentiviral pLL vectors between the

XhoI and HpaI restriction sites to prevent overexpression artefacts. The fluorescent

transgenes are designed to be shRNA resistant by using a non-human transgene or codon

change with site-directed mutagenesis. The lentiviral constructs generated are 1. pLL3.7

human Paxillin shRNA knockdown reconstituted with gallus gallus Paxillin GFP. pLL3.7

Paxillin shRNA/gallus gallus Paxillin-GFP, 2. pLL5.0 human ITGA5 shRNA knockdown

reconstituted with shRNA resistant human ITGA5-GFP -- pLL5.0 human ITGA5

shRNA/shRNA resistant human ITGA5-GFP. Additionally, a linker (5′ -

GGGTCTACATCTGGATCTGGGAAGCCGGGTTCTGGTGAGGGTTCT-3′) is fused

between fluorescence transgenes and the RhoA dominant negative mutants for the following

constructs. 3. pLL5.0 human ITGA5 shRNA knock down reconstituted with siRNA resistant

human ITGA5-GFP fused to a linker and RhoA-T19N pLL5.0 human ITGA5 shRNA/shRNA

resistant human ITGA5-GFP-RhoA-T19N, 4. pLL5.0 human E-cadherin shRNA knockdown

reconstituted with mE-cadherin-GFP fused to a linker and RhoA-T19N pLL5.0 E-cadherin

shRNA/mEcad–GFP-RhoA-T19N.

The following constructs were published previously. 1. pLL5.0 Myosin Regulatory Light

Chain-GFP, 2. pLL5.0 human E-cadherin shRNA knockdown reconstituted with mE-

cadherin-tdTomato and 3. pLL5.0 E-cadherin shRNA/mEcad–GFP used was as previously

described[19], 4. Lentiviral H2B-mNeon is a gift from Rong Li's lab.

Fibronectin 1 and Integrin alpha-5 were silenced by siRNA directed against human ITGA5

5'-GGACCAGGATGGCTACAATGA-3' and Dharmacon Smartpool siRNA directed against

human FN1(5'-GCAGCACAACUUCGAAUUA-3' ; 5'-GAAAUAGAUGCAACGAUCA-

3'; 5'-GAGGAAAUCUGCACAACCA-3'; 5'-CCUAAAGACUCCAUGAUCU-3')

respectively.

<u>Method details</u>

Heterotypic spheroid-monolayer coculture IWAKI 35mm dishes (12mm glass diameter)

were coated with 1:100 Human Fibronectin plasma (Sigma-Aldrich) in PBS and incubated at

4°C overnight. For Matrigel conditions, 20µl of Geltrex was added to the glass base and

evenly spread. Subsequently, ZT mesothelial cells were seeded and incubated overnight at

37°C to form a confluent monolayer.

Spheroids of OVCA433 were prepared by dissociating cells with trypsin-free Cell
Dissociation Buffer, PBS (Gibco), and incubated in suspension in 2ml of 1:1 ratio of medium
MCDB 105 (Cell Applications Inc.) and Medium 199 (Gibco) with 10% FBS (Gibco) for 30
mins twice at 37°C to remove trace amounts of cell dissociation buffer and promote spheroid
formation. Spheroids of approximately 50µm size were imaged and analysed. Spheroids were
transferred to a dish containing a confluent monolayer and incubated for 15 min to allow
spheroids to settle before live imaging. Imaging was performed using Nikon W1 Spinning
Disk confocal microscope with the integrated Perfect Focus System on a 60x water-
immersion magnification objective. Brightfield, GFP, and RFP images were captured every 3
min for 12 h. After live imaging, spheroids that invaded the monolayer were quantified by
viewing data obtained using MetaMorph Microscopy Automation and Image Analysis
Software. To quantify the mesothelial clearance area, the non-fluorescent area created by the
invading spheroid in the GFP mesothelial monolayer images was measured at 24 h and
divided by the initial area of the cancer spheroid 2D size at time 0. All measurements were
taken using ImageJ software.

Protein coupling of microbeads PolyLink Protein Coupling Kit (Polysciences, Inc) was
used to prepare 50µl of fluorescence beads solution. 200µg of Wheat Germ Agglutinin was
added to the activated beads suspension and incubated for 2 hr at room temperature.
Subsequently, the beads suspension was sonicated for 15 min and immediately added to a
dish containing a confluent monolayer and centrifuged until no floating beads could be
observed. Prepared OVCA433 spheroids were transferred to the dish and incubated for 15
min to allow spheroids to settle before live imaging.

Multicellular spheroids of OVCA433 were prepared by dissociating cells with trypsin-free
Cell Dissociation Buffer, PBS (Gibco) and incubated in suspension in 2ml of 1:1 ratio of
medium MCDB 105 (Cell Applications Inc.) and Medium 199 (Gibco) with 10% FBS
(Gibco) for 30 mins twice at 37°C to remove trace amounts of cell dissociation buffer and
promote spheroid formation. Spheroids were transferred to a dish containing a confluent
monolayer and incubated for 15 min to allow spheroids to settle before live imaging. Imaging
was performed using Nikon W1 Spinning Disk confocal microscope with the integrated
Perfect Focus System on the 60x water-immersion magnification objective. Brightfield, GFP,
and RFP images were captured every 3 min for 12 h. Spheroids that invaded the monolayer
were quantified with MetaMorph.

Plasmids, siRNA and shRNA For the expression of fluorescence transgenes we subcloned
shRNA-resistant transgene fused with the fluorescence tag into the multiple cloning site of
either lentiviral pLL3.7 or pLL5.0 vectors by recombination. The shRNA targeting the
corresponding endogenous proteins is cloned into the lentiviral pLL vectors between the
XhoI and HpaI restriction sites to prevent overexpression artefacts. The fluorescent
transgenes are designed to be shRNA resistant by using a non-human transgene or codon
change with site-directed mutagenesis. The lentiviral constructs generated are 1. pLL3.7
human Paxillin shRNA knockdown reconstituted with gallus gallus Paxillin GFP. pLL3.7
Paxillin shRNA/gallus gallus Paxillin-GFP, 2. pLL5.0 human ITGA5 shRNA knockdown
reconstituted with shRNA resistant human ITGA5-GFP -- pLL5.0   human ITGA5
shRNA/shRNA resistant human ITGA5-GFP. Additionally, a linker (5′ -
GGGTCTACATCTGGATCTGGGAAGCCGGGTTCTGGTGAGGGTTCT-3′) is fused
between fluorescence transgenes and the RhoA dominant negative mutants for the following
constructs. 3. pLL5.0 human ITGA5 shRNA knock down reconstituted with siRNA resistant
human ITGA5-GFP fused to a linker and RhoA-T19N pLL5.0 human ITGA5 shRNA/shRNA
resistant human ITGA5-GFP-RhoA-T19N, 4. pLL5.0 human E-cadherin shRNA knockdown
reconstituted with mE-cadherin-GFP fused to a linker and RhoA-T19N pLL5.0 E-cadherin
shRNA/mEcad–GFP-RhoA-T19N.

The following constructs were published previously. 1. pLL5.0 Myosin Regulatory Light
Chain-GFP, 2. pLL5.0 human E-cadherin shRNA knockdown reconstituted with mE-
cadherin-tdTomato and 3. pLL5.0 E-cadherin shRNA/mEcad–GFP used was as previously
described[19], 4. Lentiviral H2B-mNeon is a gift from Rong Li's lab.

Fibronectin 1 and Integrin alpha-5 were silenced by siRNA directed against human ITGA5
5'-GGACCAGGATGGCTACAATGA-3' and Dharmacon Smartpool siRNA directed against
human FN1(5'-GCAGCACAACUUCGAAUUA-3' ; 5'-GAAAUAGAUGCAACGAUCA-
3';   5'-GAGGAAAUCUGCACAACCA-3';   5'-CCUAAAGACUCCAUGAUCU-3')
respectively.

Computational fracture analysis of microbeads Analysis of microbeads at regions of
mesothelial fracture was performed as previously described with minor modifications and
additional quantifications[23]. Particle image velocimetry (PIV) analysis (PIVlab package[60] in
MATLAB) was used to quantify the flow fields in the top-viewed cell layer microbeads time-

lapse datasets. The PIV analysis was carried out for specific duration segments of these

datasets where the field of view was fixed. The time interval of each slice is 30 seconds. We

then carry out the PIV analysis by dividing the images into 64×64 pixel interrogation

windows with 50% overlap on the first pass, 32×32 pixel interrogation windows with 50%

overlap for the second pass, and 16×16 pixel interrogation windows with 50% overlap for the

third pass. Next, we select velocity threshold limits for post-processing the resulting velocity

vector fields, smooth the data, and use bicubic interpolation for missing vectors. After

calibrating the results, velocity magnitude ($v = \sqrt{v_x^2 + v_y^2}$), normal strain rate [$\dot{\varepsilon} = \partial_x v_x -$

$\partial_y v_y$][28] and shear strain rate [$\dot{\gamma} = \partial_x v_y + \partial_y v_x$] were calculated, where x and y are the

directions of vectors while v_x and v_y represent the corresponding mesothelium velocity

components[23].

Traction force microscopy TFM substrate was prepared as previously described [61] with

minor modifications. Briefly, PDMS with an average stiffness of 15 kPa was prepared by

dispensing 40 µL of 1:1 CyA and CyB mixture on the 14 mm well of the 35 mm glass bottom

dish (Cellvis), spin-coating the dish at 1000 rpm for 1 min and letting it cure at 80°C for 2 h.

PDMS surface was then silanised with 5% APTES in absolute ethanol, functionalised with

filtered and sonicated 0.2% (v/v) 0.2 µm dark red fluorescent carboxylate-modified

microspheres (FluoSpheres). Beads were inactivated by 0.1M Tri's treatment for 10 min. The

substrate was coated with 100 µg/mL of poly-D-lysine for 1 hour, followed by the adding 50

µg/ml (1:100) of human plasma fibronectin (Sigma-Aldrich) for overnight incubation at 4°C.

Subsequently, ZT mesothelial cells were seeded and incubated at 37°C to form a confluent

monolayer. Multicellular spheroids of OVCA433 were prepared and transferred to the

confluent monolayer and incubated for 15 min to allow spheroids to settle before live

imaging. Imaging was performed using Nikon W1 Spinning Disk confocal microscope with

the integrated Perfect Focus System on the x60 water magnification objectives. After 12 h,

10% SDS was added to remove cells, and the substrate was left alone to recover to the resting

state for an hour before acquiring reference images.

TFM Analysis The fluorescent bead images were maximum projected for each timepoint and

subsequently contrast-enhanced and registered to the maximum projected reference images

using MultiStackReg. PIVlab[62] add-on for MATLAB was used to calculate the displacement

field from the registered bead images using three passes of cross-correlation with the
interrogation windows as follows: 128(64), 64(32), and 32(16). Outlier vectors with
abnormally large values were removed post-processing. FTTC, an ImageJ plugin for a
Fourier transform-based, semi-infinite half-space method, was used to reconstruct the force
field from the displacement field[63]. Customised codes were written to generate the force map
or superimpose the traction force over the cell image. For downstream analysis requiring
quantification for each cell, a code was customised to import ImageJ ROIs into MATLAB to
calculate the parameters for each ROI. Radial traction stress is analysed as previously
described, with the middle of initially spreading cells or fracture site being the point of
reference[64]. Statistical analysis was performed using one-way ANOVA in GraphPad Prism.

Bayesian inversion stress microscopy and spheroid surrounding border analysis of
tensile stresses BISM analysis was performed on traction force microscopy data as
previously described[26,36]. Next, we identified the spheroid's outline from brightfield live
imaging and created masks for a 10-micron border around spheroids that invaded or did not
invade with a MATLAB script. Stress values from the BISM analysis in each 10-micron
region bordering the spheroid are obtained to calculate the average stress.

Immunofluorescence and microscopy Cells were fixed at 4 ∘ C with either −20 $^{\circ}$C methanol
on ice for 5 min or with 4% paraformaldehyde in cytoskeleton stabilization buffer (10 mM
PIPES at pH 6.8, 100 mM KCl, 300 mM sucrose, 2 mM EGTA and 2 mM MgCl2) on ice for
20 min and subsequently permeabilized with 0.2% Triton-X in PBS for 5 min at 4 $^{\circ}$C[65-69].

For structured illumination microscopy, spinning-disc confocal microscopy (Yokogawa)
coupled with the Live SR module (GATACA Systems), Nikon Eclipse Ti-E inverted
microscope with Perfect Focus System, controlled by MetaMorph software (Molecular
device) supplemented with a 100x oil 1.45 NA CFI Plan Apo Lambda oil immersion
objective and sCMOS camera (Prime 95B, Photometrics).
945
946 For lattice light sheet microscopy, Zeiss Lattice Lightsheet 7 is equipped with a 10x 0.4 NA
947 illumination objective at a 30-angle to cover glass and a 48x 1.0 NA detection objective at a
948 60-angle to cover glass. Pre-defined Sinc3 beams with 30mm length x 1000nm thickness
949 were used for image acquisition. Images were captured with Pco.edge 4.2 CLHS sCMOS
950 camera and processed with Lattice Lightsheet 7 Processing Module.

Antibodies and blocking peptide Primary antibodies in this study were: mouse monoclonal antibody against human Fibronectin (1:100; BD Transduction Laboratories; catalogue number 610077); mouse monoclonal antibody against human CD49e/Integrin α5 Chain (1:1000 for western blotting; BD Pharmingen; catalogue number 555614); mouse monoclonal antibody against human Integrin alpha-5 (1:100 for immunofluorescence; EMD Millipore; catalogue number MABT201, clone number SNAKA51); rabbit monoclonal antibody [Y113] against mouse and human Paxillin alpha, beta, and gamma isoforms (1:200 for immunofluorescence; Abcam; catalogue number ab32084); mouse monoclonal antibody against GAPDH (1:1000 for western blotting; Santa Cruz Biotechnology; catalogue number sc-32233); rabbit polyclonal antibody against non-muscle myosin heavy chain IIA (1:200 for immunofluorescence; Sigma-Aldrich; catalogue number M8064); rabbit polyclonal antibody against laminin (1:100 for immunofluorescence; Novus Biologicals; catalogue number NB300-144); Mouse monoclonal antibody against native and denatured forms of GFP (1:1000 for western blotting; Invitrogen; catalogue number MA5-15256, clone number GF28R).

Generation of micropatterned substrates Micropatterned substrate was fabricated by stencil patterning. Polydimethylsiloxane (PDMS) (Sylgard 184 kit, Dow Corning) was applied onto a photoresist mould, containing circular micropatterns. A mixture of elastomer to crosslinker in a 10:1 ratio (w/w) was used, followed by curing at 80°C for 2 hours. The resulting crosslinked PDMS layer was carefully detached, and stamps were manually crafted. Inverting the PDMS stamp, it was positioned on an uncoated 35mm μ-dish (ibidi GmbH) with hydrophobic properties. Next, Norland Optical Adhesive 73 (NOA-73, Norland Inc.) was applied along one edge of the stamp. Through capillary action, NOA-73 flowed into the gaps between the PDMS stamp and the dish, effectively sealing the stamp on all sides. Curing the NOA-73 stencil took place under ultraviolet light for 15 seconds. Following removal of the PDMS stamp, the stencil and dish were subjected to incubation with fluorescence fibrinogen mixed fibronectin at 50 μg/ml concentration in PBS. This incubation occurred overnight at 4°C following a brief degassing at 10 mbar. After the incubation, the fibronectin solution was removed, and the stencil was detached. The dish's printed bottom was treated with 0.2% Pluronic acid-H2O for 30 minutes as a passivation step. Finally, the passivated dishes underwent three washes with PBS before cell seeding.

Spheroid nucleus segmentation with StarDist 3D deep learning model and cell tracking

by IMARIS The spheroids' image stacks underwent manual labelling using the Labkit plugin

in ImageJ. These labels were subsequently employed as the ground truth masks for the

StarDist 3D segmentation (cite Weigert). A subset of the labelled stacks, selected randomly,

was allocated for training (N_{train}=19) and testing (N_{test}=2) datasets. To augment the data,

various techniques, including random flips, rotations, and intensity modifications, were

applied during training to expand the pool of training examples. The initial model parameters

were set using the pre-trained StarDist model weights.

Throughout the training process, the last five Conv3D layers of the model were reinitialized

and trained over 100 epochs. A learning rate of 10^{-4} was employed, along with a patch size of

8x96x96. All other training parameters were kept consistent as previously described.

Following this, the best-performing model, determined by the lowest test dataset loss,

underwent further fine-tuning for an additional 10 epochs. During this fine-tuning phase, a

reduced learning rate of 10^{-6} was employed. All training and fine-tuning procedures were

executed on a shared Jupyter notebook server equipped with an NVIDIA RTX 6000 GPU.

After model training, the trained model was deployed for predictions on new spheroid

images. This inference step was carried out using a Google Colab notebook with GPU

acceleration (Google, Google Colaboratory. Retrieved from https://colab.google (2025)).

After executing the prediction code, the resultant labels were compared with the original

image stack to assess segmentation accuracy. Following this evaluation, the autoregressive

motion algorithm was applied to enable automated tracking of the segmented H2B mNeon

nuclei time-lapse images in IMARIS to generate nuclei tracks. These tracks were then

subjected to manual refinement across all frames to accurately capture the movement of

spheroid cells.

Pair-wise mean square displacement (MSD) analysis of cell nucleus Given a time t, the

distance of two nuclei i and j is denoted as $dx_{i,j}(t)$. The displacement of this distance over an

time interval dt is $dx_{i,j}(t, dt)= dx_{i,j}(t+dt)-dx_{i,j}(t)$. Then, the pair-wise MSD $<dx^2>(dt)$ is the

squared distance averaged over all time points and all nuclei pairs. MSD increases

with dt with a power s such that $<dx^2> \sim dt^s$, where $s(dt)$ is referred to as local slope of MSD

power in the main text. A local slope of 1 across all timescale dt indicates a random diffusion

of particles.

Cell migration persistency analysis Let x_i be the position of cell nuclei i in the XYZ
(Cartesian) coordinate space, where the origin of the space x_0 is the averaged positions of all
cells in spheroids. Then, the velocity of nucleus i is calculated as the distance of the nucleus
between two consecutive frames: $v_i(t)=x_i(t+dt)-x_i(t)$, where $dt=$ 3 minutes, the time
resolution of tracking. The direction of the velocity is $v^l_i =v_i(t)/|v_i(t)|$, from which the auto-
correlation of velocity directions $C(dt)= <v^l_i(t)v^l_i(t+dt)>$ could be obtained. The decay
of C with the lag time dt follows an exponential form as $C \sim exp(-dt/T)$, where T is the
persistent timescale.

Z-stacks of spheroid Let S be the total number of stacks to be sliced, and each stack is
enumerated as integer s ranging from 1 (top) to S (base). We first calculate the cumulative
distribution M of the cell nuclei in the spheroid along the Z direction, then $M=0$ corresponds
to the top surface and $M=1$ at the bottom surface. Next, we determine the upper bound z_s and
lower bound z'_s of a stack s in such a way that $M(z_s)= (s-1)/S$ and $M(z'_s)= min(1, (s-1)/S + h)$,
where h is a predefined effective thickness $(0 < h < 1)$. Note that a fixed h imposes a similar
number of cells within each stack and excludes the bias from the population number in the
statistics. Finally, we select the cells with their vertical position z within the range of $[z_s, z'_s]$
for a stack s. In the main text, the total number of stacks S is 6, and the effective thickness h
is 0.3.

Interface Energy Formulation During spheroid wetting and invasion into the cell
monolayer, the free energy change (ΔG) of the system is due to variations in the interface
energies and cell polarization energy, i.e.,

1035
$$\Delta G = \Delta \gamma_i + \Delta \gamma_m + \Delta \gamma_c + \phi_p, \tag{1}$$

in which $\Delta \gamma_i$, $\Delta \gamma_m$ and $\Delta \gamma_c$ represent changes in the cadherin-mediated spheroid cell-cell,
mesothelial cell-cell, and integrin-based spheroid-mesothelium interface energies,
respectively. ϕ_p is the work done by the polarization force in spheroid cells. Physically, these
aforementioned interface energies depend on mesothelial cell cortical tension T_0, spheroid
cell tension T_c, mesothelial adhesion strength W_0, spheroid adhesion strength W_c and integrin-
based adhesion energy W_I between spheroid leader cell and mesothelial cells.

1042

1043   During wetting, i.e. when the spheroid leader cell is in contact with the mesothelium, integrin
1044   is recruited to the interface (Fig. 3a,b) and increases the adhesion strength W_I. Here, such

1045   gradual enhancement of adhesion is described by

1046
$$\tau_I \partial_t W_I = W_{I0} - W_I, \tag{2}$$

1047   where τ_I represents the timescale for integrin recruitment, W_{I0} is the maximum interface

1048   adhesion energy density that can be achieved.

1049

1050   It is widely reported that active contraction of cells could be triggered by mechanical signals

1051   such as local stretching and indentation [46,70]. To incorporate this important feature into our

1052   model, a first-order coupling between the cortical tension T and the length L_{in} of spheroid-

1053   mesothelium adhesive interface [71,72]was adopted as

1054
$$\tau_A \partial_t T = T_0 - T + \frac{\beta L_{in}}{L_0}, \tag{3}$$

where T_0 is the static mesothelial cortical tension, L_0 is a reference length, τ_A characterizes

the reaction timescale for myosin recruitment and activation, and β is the tension provided by

the myosin recruitment per unit length of integrin adhesion. Evidently, under a fixed interface

length, the maximum mesothelium contractility that can be induced by myosin recruitment is

simply $T_0 + \frac{\beta L_{in}}{L_0}$.

During wetting, formation or elongation of intercellular junctions would bring in free energy

change in the system. Since active constriction is only found at the apical side of the

mesothelium, the interface energy changes are $\Delta\gamma_m = -W_0 \delta L_m$, $\Delta\gamma_c = -W_c \delta L_c$ and

1063
$$\Delta\gamma_i = (T_{act} - T_0 - W_{I0})\delta L_{in} \tag{4}$$

1064   where T_{act} is the increased mesothelium apical tension in the equilibrium state. Considering

1065   the steady-state solution of Eq. (3), the apical tension change is simply $T_{act} - T_0 = \frac{\beta L_{in}}{L_0}$. At

1066   the same time, as spheroid cells move towards the mesothelium, free energy change induced

1067   by polarization work is $\phi_p = -F_p \delta L_m$.

1068

1069   At steady-state, the change of system free energy according to Eqs. (1-4) is

1070
$$\Delta G = \frac{\beta}{L_0} \delta L_{in}^2 - W_{I0}\delta L_{in} + F_p\delta L_m - W_0\delta L_m - W_c\delta L_c, \tag{5}$$

where δL_{in}, δL_m and δL_c are the length change of spheroid-mesothelial integrin junction,

mesothelial E-cad junction and spheroid E-cad junction, respectively, F_p is the polarization

force in spheroid cells (Supplementary Fig. 3b). For the spheroid itself, the free energy

change reduces to $\Delta G_c = -W_{I0}\delta L_{in} - W_c\delta L_c$, which shows a competition between the

integrin interface energy and spheroid E-cad interface energy. This implies that the shortening

of spheroid E-cad junction due to the favoring of spheroid-mesothelial junctions lengthening,

promotes the wetting of spheroid on the mesothelium[73]. Indeed, experiments with spheroids

sorted for higher E-cadherin expression, which prevents cell-cell contact shrinkage[74]and

reduces spheroid invasion (Fig. 4j,k, Supplementary Fig. 3k,l). In the scenario of single-cell

wetting, we have $\delta L_c = 0$. Under such circumstances, the mesothelial free energy change is

$\Delta G_m = \frac{\beta}{L_0} \delta L_{in}^2 - W_{I0} \delta L_{in} + F_p \delta L_m - W_0 \delta L_m$, indicating the fracture of mesothelial E-cad

junction (represented by the vanishing mesothelial junction length due to δL_m) is regulated

by mesothelial apical constriction, spheroid-mesothelium adhesion, and spheroid cell

polarization. Specifically, considering the complete rupturing condition $\delta L_m \leq -L_{m0}$ (with

L_{m0} being the initial length of the mesothelial junction), the critical condition for spontaneous

mesothelium fracturing (Fig. 5a) is

1087
$$\Delta G_m \leq \frac{\beta}{L_0} \delta L_{in}^2 - W_{I0} \delta L_{in} - F_p L_{m0} + W_0 L_{m0} \leq 0. \tag{6}$$

1088   For this equation to have a solution, we must have

1089
$$W_{I0}{}^2 - \frac{4\beta(W_0 - F_p)L_{m0}}{L_0} \geq 0. \tag{7}$$

1090   Then, the critical condition for mesothelium fracture (Fig. 5a) can be obtained as

1091
$$\frac{W_{I0}}{W_0} \geq \left[4\left(1 - \frac{F_p}{\zeta T_0}\right)\frac{L_{m0}}{\zeta L_0}\right]^{1/2} \left(\frac{\beta}{T_0}\right)^{1/2}, \tag{8}$$

1092   where $\zeta = \frac{W_0}{T_0}$ defines the initial mesothelial tissue state.

1093

1094   **Active Foam Formulation** In our model, cell movement and deformation are captured by the

1095   position change of a set of vertices, describing the shape of each cell as

1096
$$\eta_R \frac{dR_\alpha}{dt} = \sum_{i,j \in F(\alpha)} \left(T_{ij} + N_{ij} + P_{ij}\right) \tag{9}$$

where R_α is the position vector of vertex α, t represents the time, η_R is the friction

coefficient associated with vertex movement, $F(\alpha)$ represents the set of junctions sharing

vertex α, N_{ij} is the normal force (due to osmotic pressure [54]) acting on the junction ij, T_{ij} is

the active cortical tension along the tangential direction of junction ij (Supplementary Fig.

3b). P_{ij} is the polarization force within the spheroid leader cell. Note that the effective

tension on adherent junctions is affected by the strength of cell-cell adhesion. For example,

the magnitude of effective junctional tension ij between cell a and cell b is expressed as

$T_{ij}^a + T_{ij}^b - W_{ij}^{ab}$, where W_{ij}^{ab} is the adhesion strength on segment ij between two cells. The

asymmetry of surface forces induced by cell adhesion elongates the interface and drives the

 spreading of the spheroid leader cell on the mesothelium. The physical meaning and adopted

 value of different parameters are summarized in Table S1.

 Initial Configuration Four spheroid cells that formed a cell cluster and were designated near

 a mesothelium cell layer were used to study the dynamic invasion process.   Periodic

 boundary conditions are applied to the left and right sides of the mesothelium monolayer

 during the simulation. As the cancer cells are supposed to form a spheroid, a relatively high

 adhesion energy among themselves is adopted (Table S1).

     On the other hand, a very weak interface adhesion between cancer spheroid and

 mesothelial cells (i.e., $W_{I0}/T_0 = 0.05$) is applied at the beginning of the simulation, given

 that stable spheroid-mesothelial attachment takes time to form (after their initial contact). A

 slightly lower E-cadherin adhesion energy (i.e., $0.8W_0$) between mesothelial cells is also

 adopted. Before the actual simulation, the system was allowed to relax the steady state.

     Once the simulation starts, a dynamic spheroid-mesothelium adhesion strength (given by

 Eq. (3)) is invoked. Driven by the increased spheroid-mesothelial adhesion, the spheroid

 leader cell spreads more on the mesothelium, triggering its apical contraction and junction

 rupture and eventually leading to spheroid invasion into the mesothelial layer.

     Based on our experimental observations, L_0 and T_0 are taken to be 20 mm and 5 nN,

 respectively. According to previous studies [72,75], the friction coefficient η_R could vary from

 0.01 to 0.1 N·s·m^{-1}; here, we take a high friction coefficient (0.1 N·s·m^{-1}) for mesothelial cells

 as they are attached to the substrate and a low friction coefficient (0.05 N·s·m^{-1}) for the

 floating spheroid cells. Since the integrin adhesion timescale is believed to be significantly

 shorter than that for apical constriction [72,76,77], we choose $\tau_I = 20$ s and $\tau_A = 100$ s in the

 simulation. The values of all dimensionless parameters are listed in Table S1.

                         Table S1 Description of dominating parameters

Parameter	Physical description	Range	Data Estimation
$\dfrac{L_c}{L_0}$	Characteristic spheroid size	1	Measurement
$\dfrac{T_c}{T_0}$	Spheroid cortical tension	0.5	Measurement
$\dfrac{\beta}{T_0}$	Integrin-based apical tension strengthening	0.5~5	Literature[71,72]
$\dfrac{W_0}{T_0}$	Mesothelial adhesion strength	1.2	Shape estimation
$\dfrac{W_c}{T_c}$	Spheroid adhesion strength	1.1	Shape estimation

$\dfrac{P_0 L_0}{T_0}$	Static osmotic pressure	8000	Literature[78]
$\dfrac{F_\mathrm{p}}{T_0}$	Cell polarization force	0.72	Literature[79]

1131

Onset of Tissue Fracture At the early stage of spheroid cell invasion, the mesothelial

junction below spheroid cells is shortened by activated apical contraction. In our simulation,

we set a mesothelial junction to be completely ruptured when its length is below a small

threshold value (i.e., $\leq L_0/100$), corresponding to the onset of tissue fracture in our

experiments. In this situation, the remaining central vertices are copied and divided equally

between the cells on both sides.

1138

Vertex Motion and Contact Formation Movements of vertices in our model are governed

by Eq. (1). To maintain the accuracy of the simulation; automatic re-meshing is adopted

where a new vertex is added to the middle of the boundary segment when its deformed length

is above a critical value (i.e., $L_0/20$).

To capture the growth of adhesive contact between cells in our simulation, vertices in front of

each contact tip are checked at every time step. Once a segment from one cell is close enough

to the other cell boundary, the two segments (as well as vertices) are combined. In this way,

elongation of the contacting spheroid-mesothelial interface is realized.

The shape index of the cell is calculated as $I_\mathrm{s} = \dfrac{L_\mathrm{P}}{\sqrt{S}}$ where L_P is the perimeter of the cell

and S is the area.

1149

Cell stiffness and surface tension measurement by atomic force microscopy (AFM) The

stiffness of the mesothelial cells and spheroids was measured using a Nanowizard IV

BioAFM system (JPK Instruments, Germany). Confluent mesothelial cell monolayers were

cultured on a glass bottom petri dish while the spheroids were adhered to a poly-d-lysine

(PDL) coated glass bottom petri dish. Indentations for surface tension measurements were

performed on randomly selected cells with a silicon nitride pyramidal tip (MLCT-D, Bruker;

nominal cantilever spring constant k = 0.03 N/m; nominal tip radius 20 nm) using a force of 3

nN at a speed of 5 µm/s. The force curves from more than nine mesothelial cells and multiple

cells from nine ovarian cancer spheroids were analysed to evaluate the surface tension. The

calculation of cell surface tension was performed as recently described[80-83]. In brief, the cell

membrane is assumed to be a thin tensile shell. With an AFM indentation range much larger

than cell membrane thickness, the formula used is T = K/2pi, where K is fitted from the linear

coefficient of force vs. indentation ranging from 50nm to 300 nm.

Quantification and statistical analysis

Image Processing and Analysis The images presented were processed with ImageJ

(http://rsb.info.nih.gov/ij/). For quantification of apical fluorescent density and line-scan

analysis, the mean intensity of the selected apical region was measured from the microscopy

images. Line-scan analysis was performed according to the published protocol[67]: A line of

standardized length was drawn perpendicular to and centered on cell-cell contacts, and

fluorescence intensity of all pixels along the drawn line was determined using the PlotProfile

feature on ImageJ. The resulting data was imported into Excel for average calculation. For

statistical analysis, raw fluorescence intensity data was used in Prism to analyze co-

localization between E-cad GFP spheroid and E-cad tdT mesothelium.For quantification of

the phosphoMLC intensity at E-cadherin cell-cell contacts and apical integrin adhesions,

segmented lines were drawn on immunostained E-cadherin cell-cell contacts (line width 20)

and apical integrin adhesions to obtain multiple regions of interest with FIJI. The

corresponding phosphoMLC intensities were measured at these regions of interest.

For quantification of apical mesothelial paxillin intensity, an image mask was created by

subtracting the background intensity with the rolling ball radius set to 50 pixels with FIJI,

followed by the Gaussian blur with a sigma of 2. Particles with an area larger than 0.1 μm^2

were considered and segmented for the final mask to measure Paxillin intensity. The area of

each focal adhesion was recorded as a region of interest (ROI) in ImageJ, and the mean

intensity of the focal adhesions was calculated by subtracting the background intensity

obtained from an area of the image without paxillin. For quantifying mesothelial apical F-

actin orientation, we measured the alignment of F-actin bundles in cell fluorescence images at

10-degree intervals, using the Directionality Function in Fiji (v. 1.54p).

For quantification of the abundance of fibronectin fibrils at the apical regions of the

mesothelium, an intensity threshold mask was created to outline the fibronectin fibrils with

FIJI. Their intensity multiplied by the area of these fibronectin fibrils are then compared

between the different experimental groups.

For quantification of cell-cell contact crazing, time-lapse image stacks of mesothelial
monolayers were analysed using Metamorph with Z-projection. Mesothelial monolayers were
first visually verified to be intact before tearing. Timeframes showing the initial cell-cell
contact breakdown were determined after playing through each movie and visually assessed
for multiple fibrillar bridges and microvoids indicative of crazing.

Statistical analysis

All data are represented as mean ± SD, unless otherwise stated. Each experiment was
independently performed at least 3 times. All statistical analyses were performed in
GraphPad Prism. Student's t test was used to compare datasets with 2 groups; depending on
the number of variables, one-way or two-way ANOVA was used to compare 3 or more
groups.

Supplemental information

<u>Supplementary videos</u>
1203
1204 Video 1. Formation of fibrillar bridges and microvoids at mesothelial E-cadherin (hot orange)
1205 cell-cell contacts during spheroid invasion, related to Figure 1.
1206
1207 Video 2. Formation of fibrillar bridges (E-cad tdTomato, red) and microvoids at mesothelium
1208 (GFP, green) grown on matrigel during spheroid invasion, related to Figure 1.
1209
1210 Video 3. Apical constriction of a mesothelial cell expressing myosin regulatory light chain
1211 (MRLC-GFP, green) and E-cadherin tdTomato (red) during the spheroid invasion, related to
1212 Figure 2.
1213
1214 Video 4. Mesothelial apical fibronectin GFP and mesothelium (E-cad tdTomato, red) undergo
1215 fracture induced by an invading spheroid, related to Figure 3.
1216
Video 5. Representative multipanel videos of spheroid invasion of the mesothelium in the
three following experimental conditions, related to Figure 3.

1) Fibronectin-1 and 2) α5 integrin siRNA mediated knockdown in mesothelium compared to
controls. 3) Mesothelium expressing α5 integrin GFP fused with RhoA-T19N compared to
control mesothelium expressing wild-type α5 integrin GFP. Arrows indicate four ends of the
mesothelial fracture propagation.

1223

Video 6. Representative multipanel videos of spheroid invasion of the mesothelium in the
three following experimental conditions, related to Figure 3.
1) Control mesothelium expressing wild-type α5 integrin GFP, 2) mesothelium expressing
α5 integrin GFP fused with RhoA-T19N, and 3) mesothelium expressing α5 integrin GFP
fused with RhoA-T19N with addition of exogenous FN1. Arrows indicate four ends of the
mesothelial fracture propagation.

1230

1231 Video 7. Representative multipanel video of spheroid expressing H2B-mNeon invading E-
1232 cad tdT expressing mesothelium and the corresponding XZ and RZ velocity maps on the
1233 right, related to Figure 4.

1234

1235 Video 8. Computational vertex results of spheroid cell invasion and mesothelial fracture with
1236 medium intercellular integrin adhesion, related to Figures 5 and 6.
1237 Top left: ($W_{I0}/W_0 = 0.9$), top right: ($W_{I0}/W_0 = 0.3$), bottom left: ($W_{I0}/W_0 = 1.5$), bottom
1238 right: ($W_0/T_0 = 0.6$).

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1240

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Figure 1

a Without metastatic tumour implantation
Mesothelium
Peritoneum Space
Stroma
Adipose tissue

b Invading ovarian tumour

b'

c Mesothelium
Ecad Spheroid
Laminin basement membrane

d Mesothelial E-cadherin tdT
Spheroid
Mesothelium
d' 0 mins | 45 mins | 93 mins | 300 mins
d''' 0 mins | 6 mins | 12 mins | 18 mins | 24 mins
High Intensity Low

d''
Cell 1 | Cell 3 | Cell 2 | Cell 4
27 mins | 45 mins | 93 mins | 300 mins

e E-cad
GFP
Linker
RhoA T19N

f Mesothelium Ecad
Spheroid | WT
+RhoA T19N

g % of 'Craze' at microfracture (%)
Ecad | Ecad +RhoA T19N
****

h Mesothelial Clearance (a.u)
Ecad | Ecad +RhoA T19N
****

i Mesothelial
Ecad 0 mins
Spheroid
Ecad 81 mins
Shear strain rate (s⁻¹) −0.04 to 0.04
Normal strain rate (s⁻¹) −0.04 to 0.04
Velocity (µm/s) 0.01 to 0.05
0 mins | 81 mins
Initial fracture
Constriction
Beads displacement

j Mesothelium
Fracture Modes
I: Opening | **II**: In-plane shear | **III**: Out-of-plane shear

k Fold change
Initial fracture
Shear Strain rate * | Normal Strain rate ** | Velocity magnitude

l Spheroid Ecad GFP
Mesothelial Ecad tdT
XZ view
0 min | 12 mins | 24 mins | 63 mins

Figure 2

a Mesothelial E-cad tdT MRLC GFP

Spheroid

0 min   9 mins   12 mins   21 mins   60 mins

b Mesothelial apical cell area variance

***

W/O Invasion   With Invasion

c Mesothelial medioapical MRLC-GFP

High
Intensity
Low

c'

d Onset of Mesothelial E-cad contact Rupture

Apical cortex MRLC mean intensity(a.u)
Mesothelial cell apical area (μm²)
Time (minutes)

e Spheroid   Traction Vectors

Ecad-GFP spheroid cell

Radial Traction

(Pa)
300
200
100
0
-100
-200
-300

0 min   10 mins   20 mins

f Spheroid E-cad GFP Basal Mesothelial E-cad tdT

Spheroid

Traction vectors

Radial Traction

(Pa)
300

-300

0 min   15 mins   30 mins

g Average Traction Stress (Pa)

-9mins -6mins -3mins Initial Fracture 3mins 6mins 9mins

h Spheroid

Region Quantified (BISM)

i Bayesian Inversion Stress Microscopy

Tension (kPa μm)

*

Control   3 minutes before Spheroid Invasion

Figure 3

a Spheroid Paxillin-GFP Mesothelial E-cad tdT

XY

Spheroid

XY

XZ view of integrin adhesion on mesothelium

Spheroid Paxillin-GFP

b Spheroid cell Pax-GFP

0 min
5 mins
10 mins
15 mins
20 mins

c Spheroid E-cad GFP Mesothelial E-cad tdT

Spheroid

c'
c''
c'''

d
Spheroid Ecad GFP intensity (a.u)
Mesothelia Ecad mean intensity (a.u.)
Distance(microns)

e
Rate of Invasion (%)
Cont   TSP-1
**

f Mesothelial E-cad tdT
Control
Spheroid
Spheroid ITGA5 KD

g
Rate of Invasion (%)
Control   Spheroid ITGA5 KD
*

i Mesothelial Pax-GFP FN1
Spheroid

h Mesothelial E-cad tdT
Spheroid
0 min   240 mins   339 mins   387 mins   603 mins

j Mesothelial cells apical region
Paxillin ITGA5   Paxillin FN1   Tensin-1 Vinculin   Kank-2 Vinculin

k
Rate of Invasion (%)
Control   Mesothelial FN1 KD   Spheroid FN1 KD   Serum free
**   **   ns

l
Rate of Invasion (%)
Control   Mesothelial ITGA5 KD
**

m
ITGA5
GFP
RhoA T19N
Linker

n Mesothelial
ITGA5 KDR E-cad tdT
Spheroid
ITGA5 KDR + RhoA T19N

o
Rate of Invasion (%)
ITGA5 KDR   ITGA5 KDR+RhoA T19N   ITG5A KDR with FN1   ITG5A KDR+RhoA T19N with FN1
**   **

Figure 4

Figure 5

Figure 6