Ocular dominance-dependent binocular combination of monocular neuronal responses in macaque V1

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Abstract

Primates rely on two eyes to see depth, while keeping a stable vision when one eye is closed. Although psychophysical and modeling studies have investigated how monocular signals are combined to form binocular vision, the corresponding neuronal mechanisms, especially in V1 where most neurons become binocular but with different eye preferences, are not well understood. Here we used two-photon calcium imaging to compare monocular and binocular responses of thousands of V1 superficial-layer neurons in three awake macaques. Under monocular stimulation, neurons preferring the stimulated eye responded substantially stronger than those preferring both eyes. However, under binocular stimulation, the responses of neurons preferring either eye were suppressed, and those preferring both eyes were enhanced, so that neuronal responses became similar regardless of eye preferences. A neuronally realistic model of binocular combination, which includes ocular dominance-dependent divisive interocular inhibition, and binocular summation, is proposed to account for these observations.

Introduction

Human and non-human primates often use binocular disparity, or the differences

between the retinal images of two eyes, to perceive depth (stereopsis). In the meantime,

the brain maintains a stable perception of the visual world when one eye closes and the

incoming light is halved. Much has been known regarding the neural foundations of

stereopsis (Barlow, Blakemore, & Pettigrew, 1967; Henriksen, Tanabe, & Cumming, 2016;

Parker, Smith, & Krug, 2016; Welchman, 2016; Read, 2021). Nevertheless, whether and how

the neurons respond differently to monocular and binocular stimulations is less studied

(Prince, Pointon, Cumming, & Parker, 2002; Dougherty, Cox, Westerberg, & Maier, 2019;

Mitchell et al., 2022). Adding to the complexity is the fact that many V1 neurons, although

responding to stimulations in both eyes, have various degrees of eye preferences (Hubel &

Wiesel, 1962, 1968). Thus, a more complete picture of binocular combination of monocular

responses would illustrate monocular and binocular responses of neurons at different eye

preferences, which is the purpose of the current study.

It has been reported that overall the binocular responses of macaque V1 neurons are

lower than the sum of monocular responses to each eye (Prince et al., 2002; Mitchell et al.,

2022), but are stronger than monocular responses either when one eye was stimulated

(Prince et al., 2002; Mitchell et al., 2022), or when neurons' preferred eye was stimulated

(Mitchell et al., 2022). Further, Dougherty et al. (2019) reported that the responses of

monocular neurons are found to be more likely suppressed than facilitated by binocular

stimulation. As our results will suggest later, this conclusion is valid when the monocular

baseline is either the sum of monocular responses, or the monocular responses of either

eye. Dougherty et al. (2019) also reported similar responses of neurons with monocular and

binocular preferences, as well as similar responses of binocular neurons to monocular and

binocular stimulations, which are not supported by our data.

A big and more complete picture of the binocular combination of monocular

responses, as well as the impacts of eye preferences, would come from large samples of

neurons, so that the data can be quantitatively described with sufficient statistical power,

and analyzed with computational modeling. Two-photon calcium imaging is capable of

recording thousands of neurons simultaneously at the single-neuron resolution, which is

especially suitable for this task. In this study, we used a two-photon imaging setup, which

had been adapted for recording with awake macaques (Li, Liu, Jiang, Lee, & Tang, 2017), to

measure responses of V1 superficial-layer neurons to monocular and binocular stimulations.

Furthermore, a neuronally realistic binocular combination model, which considers ocular

dominance-dependent interocular divisive inhibition, as well as binocular summation, is

proposed to explain the data.

Results

We recorded responses of V1 superficial-layer neurons to monocular (contralateral

and ipsilateral) and binocular stimulations in three awake, fixating macaques. The stimulus

was a high-contrast (0.9) Gabor grating at various orientations and spatial frequencies (SFs).

The recording was performed at two cortical depths of the same response field of view

(FOV) in first two monkeys (MA & MB), and at one depth in the third monkey (MC) as the

first two monkeys displayed similar results at two depths (Fig. 1A). Imaging processing

identified a total of 10,168 neurons. Among them, 9,390 (92.4%) were tuned to orientation,

SF, or both. Results from these orientation- and/or SF-tuned neurons were used in the

following data analysis.

V1 superficial-layer neurons exhibited various degrees of eye preferences, consistent

with the classical findings of Hubel and Wiesel (1962, 1968). An ocular dominance index

(ODI) was calculated to characterize each neuron's eye preference: ODI = $(R_i - R_c)/(R_i + R_c)$, in

which R_i and R_c were the neuron's respective peak responses to ipsilateral and contralateral

stimulations on the basis of data fitting (see Methods). Here ODI = -1 and 1 would indicate

complete contralateral and ipsilateral eye preferences, respectively, and ODI = 0 would

indicate equal preferences to both eyes. The ocular dominance functional maps at single-

neuron resolution, especially those of Monkeys A and C, showed regions of neurons

preferring either the contralateral (blue) or the ipsilateral eye (red), and transitional zones

where neurons preferring both eyes (white) (Fig. 1B). The ocular dominance maps were

similar at two cortical depths in Monkeys A and B, indicating possible ocular dominance

columns (Fig. 1B). The frequency distributions of ODIs suggest more binocular neurons than

monocular neurons in V1 superficial layers (Fig. 1C), similar to the normal distribution of

ocularity index in Dougherty et al. (2019).

Figure 1. Eye preferences of V1 superficial-layer neurons in three macaques. **A**. Two-photon

imaging. Average 2-photon images over a recording session for each response FOV.

MA_200: Monkey A at a 200-μm cortical depth. **B**. Ocular dominance functional maps of

each FOV/depth at single-neuron resolution. **C**. Frequency distributions of neurons of each

FOV/depth as a function of ocular dominance index.

91   The responses of individual neurons were plotted against the ocular dominance

index (ODI) when monocular stimulation was through the contralateral eye (Fig. 2A) or the

ipsilateral eye (Fig. 2B). As expected, neurons with more negative ODIs responded stronger

when the contralateral eye was stimulated, and those with more positive ODIs responded

stronger when the ipsilateral eye was stimulated. The responses declined as neurons

became more binocular. However, when both eyes were stimulated, the response

differences among neurons of different eye preferences became not obvious (Fig. 2C).

These trends can be better appreciated when the difference between binocular and

monocular responses are presented for each FOV/depth in Fig. 2D: Under monocular

stimulation, if only the neuronal responses to the preferred eye were taken into

consideration (i.e., a neuron's higher response to ipsilateral vs. contralateral stimulations),

more monocular neurons (ODIs farther from 0) tended to have stronger responses than

more binocular neurons (ODIs closer to 0). However, under binocular stimulation, the

responses of more monocular neurons were suppressed, and those of more binocular

neurons were enhanced, by binocular stimulation. These trends are best appreciated in

pooled data over five FOVs/depths (Fig. 2E). Further, linear regression confirmed a significant

dependence of binocular modulation on absolute ODI ($y = -0.41x + 0.16$, $p < 0.001$) (Fig. 2E).

That is, responses of neurons with lower absolute ODI (i.e., binocular neurons) tended to be

more enhanced, and responses of neurons with higher absolute ODI (i.e., monocular

neurons) tended to be more suppressed.

Figure 2. A comparison of neuronal responses to monocular and binocular stimulations. **A**.

Responses of individual neurons against their ocular dominance indices with contralateral

stimulation. **B**. Responses of the same neurons against their ocular dominance indices with

ipsilateral stimulation. **C**. The binocular responses of the same neurons. **D**. The difference

between binocular and monocular responses ($R_b - \max(R_i, R_c)$). Each vertical line represents

one neuron. To summarize the results, neurons of each FOV/depth are evenly divided into 60

bins in the order of the ocular dominance index. White dots represent the median responses

of respective bins and are connected with a black line. **E**. The differences between binocular

and monocular responses of individual neurons pooled over five FOVs/depths. **F**. Binocular

modulation index as a function of absolute ODI and the linear fit. The binocular modulation

index of each neuron was defined as $(R_b - \max(R_i, R_c))/(R_b + \max(R_i, R_c))$.

Modeling monocular and binocular responses

To model the monocular and binocular neural responses, monocular and binocular

data of each FOV/depth, as well as the pooled data, were first normalized by the respective

median of the binocular responses and then divided into 60 bins in the order of the ocular

dominance index (Fig. 3A-C).

<u>Monocular responses</u>

A neuron's monocular responses to contralateral and ipsilateral stimulations could be

respectively described by a divisive gain control model:

$$R_c = \frac{w_c^{m_c} \cdot S_c}{k} \quad \text{and} \quad R_i = \frac{w_i^{m_i} \cdot S_i}{k} \qquad \text{(Eq. 1)}$$

Here S_c and S_i were stimulus contrasts, w_c and w_i were linear transformations of a neuron's

ocular dominance index from [-1 1] to [0 1]: $w_c = (ODI + 1)/2$ and $w_i = 1 - w_c$, m_c and m_i

represented monocular nonlinearity, and k represented divisive gain control. Because S_c and

S_i in our experiments were 0.9, which were about equal to 1 (full contrast) due to neuronal

response saturation, the above equations were simplified as

$$R_c = \frac{w_c^{m_c}}{k} \quad \text{and} \quad R_i = \frac{w_i^{m_i}}{k} \qquad \text{(Eq. 2)}$$

Eq. 2 was used to fit the binned median contralateral and ipsilateral data (Figs. 3A &

B), with the parameter k being equal for contralateral and ipsilateral responses. The fitting

revealed that m_c and m_i were negative and close to -1, which resulted in a quick decline of

$w_c^{m_c}$ and a quick increase of $w_i^{m_i}$ as a function of the ocular dominance index since w_c and

$w_i \in [0, 1]$. The fit quality indices (Busse, Wade, & Carandini, 2009) ranged 0.85-0.95 for the

contralateral condition (Fig. 3A) and 0.90-0.93 for the ipsilateral condition (Fig. 3B),

suggesting adequate goodness of fit. The fitting parameters are listed in Fig. 3D.

Binocular responses

Fig. 2D-F earlier has indicated that neuronal responses to binocular stimulation

change from suppression to enhancement as neurons' ocular dominance changes from

monocular to binocular, which may reflect the ocular dominance-dependent net effect of

interocular suppression and binocular summation. To model interocular response

suppression, responses from each eye in Eq. 2 were further normalized by an interocular

suppression factor w_i^b or w_c^b, whose strength was decided by the linearly transformed ODI

with a nonlinear exponent b. Then the normalized responses from two eyes were summed

to model binocular summation and the final binocular responses of neurons R_b (Eq. 3).

155
$$R_b = \frac{w_i^{m_i}}{kw_i^b} + \frac{w_c^{m_c}}{kw_c^b} \qquad\qquad \text{(Eq. 3)}$$

156   During data fitting, the parameters m_i, m_c, and k were inherited from earlier

157   monocular data fitting and remained fixed. Only b was allowed to change. Data fitting

158   resulted in flat binocular response functions (Fig. 3C) with satisfactory goodness-of-fit (fit

159   quality index = 0.86 to 0.94).

	m	k		m	k		b
A_200	-0.981	3.717		-1.008	3.717		0.302
A_300	-0.868	3.380		-0.936	3.380		0.302
B_140	-1.074	2.582		-0.984	2.582		0.825
B_250	-0.967	2.299		-1.036	2.299		0.935
C_210	-0.585	2.005		-0.532	2.005		0.622
Pooled	-0.672	2.270		-0.665	2.270		0.578

Figure 3. Modeling monocular and binocular responses. **A & B**. Median neuronal responses

to contralateral and ipsilateral stimulations as a function of ocular dominance index and

respective data fitting with Eq. 2. Neurons are evenly divided into 60 bins in the order of the

ocular dominance index, with each bin containing 28-33 neurons that varied among

different FOVs/depths (156 neurons for the pooled data). Each datum represents the median

response of a bin. Free parameter k was kept equal during contralateral and ipsilateral data

fitting. **C**. Binocular responses as a function of ocular dominance index and data fitting with

Eq. 3 for the same bins of neurons. During binocular data fitting, parameters k, m_i, and m_c

were inherited from monocular data fitting, and only b was the free-changing parameter. **D**.

The values of free parameters from monocular and binocular data fitting.

The behaviors of interocular suppression and binocular summation in the model, as

well as their contributions to the binocular response, may be better appreciated in Fig. 4. Fig.

4A uses Eqs. 2 and 3 and the parameters from fitting of pooled data (Fig. 3D) to simulate the

contralateral (blue curve with label R_c), ipsilateral (red curve with label R_i), and binocular

(black curve) response functions against the ocular dominance index. The arithmetic sum of

contralateral and ipsilateral response functions was also simulated (grey dashed curve

labeled $R_i + R_c$). In addition, neuronal responses to preferred eye stimulation would consist of

the higher branches of contralateral and ipsilateral response functions. It is apparent that

binocular responses can be described by neither the sum of monocular responses, nor the

responses to the preferred eye. Instead, the median of the binocular response function

(black arrow) in each data set is close to but still more or less higher than the median of the

contralateral (blue arrow) or ipsilateral response function (red arrow), which is consistent

with previous reports (Prince et al., 2002; Mitchell et al., 2022).

Fig. 4B plots the interocular suppression factor w_c^b (dotted blue curve) for the

contralateral response R_c (solid blue curve from 4A), and w_i^b (dotted red curve) for the

ipsilateral response R_i (solid red curve from 4A). The suppression factors w_c^b and w_i^b are

larger with neurons that are more monocular than with neurons that are more binocular. The

R_c and R_i are divided by the respective interocular suppression factor, producing the

normalized contralateral responses (dashed blue curve labeled R_c/w_c^b) and ipsilateral

responses (dashed red curve labeled R_i/w_i^b). These normalized curves are lower than original

monocular responses, especially for neurons that are more monocular (ODIs farther from 0),

showing interocular suppression.

Then the normalized monocular curves are summed up in Fig. 4C, which represents

binocular summation and produces the final binocular responses (R_b). Therefore, as a result

of combined interocular suppression and binocular summation, the final curve for binocular

responses becomes nearly flat within the data range.

Figure 4. Monocular and binocular responses modeled with binocular suppression and

binocular summation. **A.** The solid blue, red, and black curves are simulations of the

contralateral, ipsilateral, and binocular responses on the basis of fitting of pooled data (Fig.

3D). The grey dashed curve simulates binocular responses as the arithmetic sum of

contralateral and ipsilateral responses. The higher branches of contralateral and ipsilateral

response functions represent monocular responses with preferred eye stimulation. The black,

blue, and red arrows indicate the median binocular, contralateral, and ipsilateral responses,

respectively, from pooled data. The shadowed area indicates the region where actual

neurons existed on the basis of the ocular dominance index. **B.** Interocular suppression. The

contralateral and ipsilateral responses (R_c & R_i) are divided by respective interocular

suppression factors W_c^b and W_i^b to produce interocular-suppressed responses R_c/w_c^b and

R_i/w_i^b. **C.** Binocular summation. R_c/w_c^b and R_i/w_i^b are summed to produce the final binocular

responses R_b.

Discussion

The current study compared the responses of large samples of V1 superficial-layer

neurons to monocular and binocular stimulations in three macaques. The monocular

response functions show steep changes as a function of the ocular dominance index, but

binocular response functions are largely flat, regardless of neurons' eye preferences.

Modeling efforts indicated that when signals from two eyes are combined, interocular

divisive suppression, which is more prominent with neurons preferring one eye, and

binocular summation, which is more prominent with binocular neurons, together produce

the nearly flat binocular response function within a broad range of ocular dominance indices.

As shown in Fig. 4A, the median of binocular neuronal responses is slightly higher

than that of monocular responses of either eye (black vs. red/blue arrows), consistent with

earlier reports (Prince et al., 2002; Mitchell et al., 2022). However, individually, compared to

monocular responses, responses of monocular neurons more preferring the stimulated eye

are actually suppressed, and only responses of binocular neurons are increased by binocular

stimulation. Furthermore, overall stronger binocular than monocular responses in V1, even

with a small amount, would suggest that the binocular neuronal responses must be further

modulated by additional mechanisms to achieve stable vision, regardless of whether the

world is viewed with one or two eyes.

In Dougherty et al. (2019), the responses of monocular and binocular neurons are

similar under monocular stimulation, and only monocular neurons, but not binocular

neurons, are significantly suppressed by binocular stimulation. In contrast, our results show

that monocular neurons respond to stimulation in the preferred eye much more strongly

than binocular neurons do to the same monocular stimulation (Fig. 2C). Moreover, although

confirming interocular suppression of monocular neurons responding to the preferred eye,

our results also indicate enhanced responses of binocular neurons to binocular stimulation.

Considering the large diversity of binocular responses of neurons with similar eye

preferences (Fig. 2C), it is very possible to obtain inaccurate statistical estimates with small,

and possibly biased, samples of neurons in electrode recording experiments.

Binocular combination of monocular signals has long been recognized to involve both

interocular suppression and binocular summation (DeSilva & Bartley, 1930; Cohn & Lasley,

1976; Li & Atick, 1994). Most more recent models use divisive normalization to explain

interocular suppression (e.g., Cogan, 1987; Anderson & Movshon, 1989; Ding & Sperling,

2006; Moradi & Heeger, 2009; Huang, Zhou, Zhou, & Lu, 2010; Ding, Klein, & Levi, 2013). Our

modeling effort shows that a similar divisive interocular suppression and binocular

summation model can account for neuronal response changes under monocular and

binocular stimulations, with the distinction that the divisive interocular suppression is

additionally controlled by a neuron's ocular dominance. The latter also controls the

responses of individual neurons to monocular stimulation, as shown in Figs. 3A-B. The critical

roles of ocular dominance have been largely overlooked by extant binocular vision models to

our knowledge, except that Anderson and Movshon (1989) demonstrated that a model

consisting of multiple ocular dominance channels can better explain their psychophysical

adaptation data. We hope that our two-photon imaging results can be incorporated into

future neuronally plausible models of binocular vision.

On the basis of current findings, future two-photon imaging work shall compare

neural responses to monocular and binocular stimulations with uneven effective stimulus

contrasts due to physical contrast differences (Anderson & Movshon, 1989), monocular

adaptation (Anderson & Movshon, 1989), and short-term monocular deprivation (Lunghi,

Burr, & Morrone, 2011), as well as the relevant roles of ocular dominance of individual

neurons. These results would help understand abnormal binocular vision in patients with

strabismus and amblyopia. In addition, under current zero-disparity stimulus conditions,

neuronal responses to binocular stimulation appear no longer affected by ocular dominance

of individual neurons (Fig. 2D). Therefore, another interesting question is whether the same

is true when disparity is present in the stimuli. These future results would enrich and refine

our current simplified but neuronally realistic model.

Materials and Methods

Monkey preparation

Monkey preparations were identical to those reported in a previous study (Guan, Ju,

Tao, Tang, & Yu, 2021; Ju, Guan, Tao, Tang, & Yu, 2021). Three rhesus monkeys (*Macaca*

mulatta) aged 4 to 6 years, respectively, were each prepared with two sequential surgeries

under general anesthesia and strictly sterile condition. In the first surgery, a 20-mm diameter

craniotomy was performed on the skull over V1. The dura was opened and multiple tracks of

100-150 nL AAV1.hSynap.GCaMP5G.WPRE.SV40 (AV-1-PV2478, titer 2.37e13 (GC/ml), Penn

Vector Core) were pressure-injected at a depth of ~350 μm. Then the dura was sutured, the

skull cap was re-attached with three titanium lugs and six screws, and the scalp was sewn up.

After the surgery, the animal was returned to the cage, treated with injectable antibiotics

(Ceftriaxone sodium, Youcare Pharmaceutical Group, China) for one week. Postop analgesia

was also administered. The second surgery was performed 45 days later. A T-shaped steel

frame was installed for head stabilization, and an optical window was inserted onto the

cortical surface. Data collection could start as early as one week later. More details of the

preparation and surgical procedures can be found in Li et al. (2017). The procedures were

approved by the Institutional Animal Care and Use Committee, Peking University.

Behavioral task

After a ten-day recovery from the second surgery, monkeys were seated in primate

chairs with head restraint. They were trained to hold fixation on a small white spot (0.1°)

with eye positions monitored by an ISCAN ETL-200 infrared eye-tracking system (ISCAN Inc.)

at a 120-Hz sampling rate (Monkeys A & B) or an Eyelink-1000 (SR Research) at a 1000-Hz

sampling rate (Monkey C). During the experiment, trials with the eye position deviated 1.5°

or more from the fixation before stimulus offset were discarded as ones with saccades and

repeated. For the remaining trials, the eye positions were mostly concentrated around the

fixation point, with eye positions in over 95% of trials within 0.5° from the fixation point. The

viewing was binocular.

Visual stimuli

For Monkeys A and B, visual stimuli were generated by the ViSaGe system (Cambridge

Research Systems) and presented on a 21'' Sony G520 CRT monitor (refresh rate = 80 Hz,

resolution = 1280 pixel × 960 pixel, pixel size = 0.31 mm × 0.31 mm). Because of the space

limit, the viewing distance and the monitor position varied depending on the stimulus spatial

frequency (30 cm at 0.25, 0.5, and 1 cpd, 60 cm at 2 cpd, and 120 cm at 4 and 8 cpd). For

Monkey C, visual stimuli were generated by Psychotoolbox 3 (Pelli & Zhang, 1991) and

presented on a 27'' Acer XB271HU LCD monitor (refresh rate = 80 Hz native, resolution =

2560 pixel × 1440 pixel native, pixel size = 0.23 mm × 0.23 mm). The viewing distance was 50

cm for lower frequencies (0.25 - 1 cpd) and 100 cm for higher frequencies (2 - 8 cpd). For

both monitors, the screen luminance was linearized by an 8-bit look-up table, and the mean

luminance was ~47 cd/m^2.

A drifting square-wave grating (SF = 4 cpd, contrast = full, speed = 3 cycles/s, starting

phase = 0°, and size = 0.4° in diameter) was first used to determine the location, eccentricity

(3.4^o for Monkey A, 1.7^o for Monkey B, and 1.1^o for Monkey C) and size (0.8 - 1°) of the

population receptive field associated with a recording field of view (FOV), as well as ocular

dominance columns when monocularly presented to confirm the V1 location. This fast

process used a 4 × objective lens mounted on the two-photon microscope and revealed no

cell-specific information.

Neuronal responses were then measured with a high-contrast (0.9) Gabor grating

(Gaussian-windowed sinusoidal grating) drifting at 2 cycles/s in opposite directions

perpendicular to the Gabor orientation. The starting phase of the drafting Gabors was always

0°. The Gabor grating varied at 12 orientations from 0° to 165° in 15° steps, and 6 spatial

frequencies from 0.25 to 8 cpd in 1-octave steps. In addition, three stimulus sizes (with

constant stimulus centers) were used at each spatial frequency, for two purposes. First, our

pilot measurements suggested very strong surround suppression with larger stimuli.

Therefore, comparing the responses to different stimulus sizes helped approximate the RF

size of each neuron that produced maximal response and least surround suppression.

Second, for neurons whose RF centers and the stimulus center were misaligned, the RFs of

some misaligned neurons might be better covered by larger stimuli. Still the RFs of additional

neurons might have less overlap with the stimuli. These neurons would have weaker and less

orientation-tuned responses because of the Gaussian-blurred stimulus edge, and would most

likely be filtered out during our multiple steps of selection of orientation tuned neurons (see

below). Specifically, the σ of the Gaussian envelope of the Gabor were 0.64λ and 0.85λ at all

spatial frequencies, and was additionally smaller at 0.42λ when spatial frequencies were

0.25 - 1 cpd, and larger at 1.06λ when spatial frequencies were 2 - 8 cpd (λ: wavelength;

Gabors with the same σ in wavelength unit had the same number of cycles). Here at the

smallest σ (0.42λ), the Gabors still had sufficient number of cycles (frequency bandwidths =

1 octave) (Graham, 1989), so that the actual stimulus spatial frequencies were precise at

nominal values. In terms of visual angle, σ = 1.68°, 2.56°, and 3.36° at 0.25 cpd; 0.84°, 1.28°,

and 1.68° at 0.5 cpd; 0.42°, 0.64°, and 0.85° at 1 cpd; 0.34°, 0.42°, and 0.53° at 2 cpd; 0.17°,

0.21°, and 0.26° at 4 cpd, and 0.08°, 0.11°, and 0.13° at 8 cpd, respectively.

Each stimulus was presented for 1000 ms, with an inter-stimulus interval (ISI) of 1500 ms that

is sufficient to allow the calcium signals back to the baseline level (Guan, Zhang, Zhang, Tang,

& Yu, 2020). Each stimulus condition was repeated 12 times with six repeats for each

opposite direction. When a stimulus was presented monocularly to one eye, the other eye

was covered with a translucent eye patch to reduce the impacts of short-term monocular

deprivation. For Monkey A, binocular recording preceded monocular recording in separate

days. During monocular recording contralateral and ipsilateral stimulations alternated in

blocks of trials with at least 10-minute breaks, during which the eye mask was taken off.

Recording at a specific viewing distance was completed with all trials at relevant SFs pseudo-

randomly presented before proceeding to the next distance. For Monkeys B and C, binocular

and monocular recordings were mixed and completed in two daily sessions. At a specific

viewing distance, all binocular trials at relevant SFs were completed first, then contralateral

and ipsilateral trials were completed in alternating blocks of trials with at least 10-minute

eye-patch-off breaks. Again, recordings at a specific viewing distance were completed before

proceeding to a different distance. Each block of trials typically lasted 20-25 minutes, but for

Monkeys A & B some blocks involving three SFs could last up to 45 minutes. The strength of

fluorescent signals (mean luminance of a small area) was monitored and adjusted if

necessary for drift of fluorescent signals. We compared the response ratios of the last 2 trials

over the first 2 trials for each stimulus condition in these extended blocks with ipsilateral and

contralateral stimulations. The respective mean ratios were 0.94 and 0.86, suggesting that

the recorded neuronal responses remained largely stable over extended blocks of trials.

Two-photon imaging

Two-photon imaging was performed with a Prairie Ultima IV (In Vivo) two-photon

microscope (Prairie Technologies) on Monkeys A and B, or a FENTOSmart two-photon

microscope (Femtonics) on Monkey C, and a Ti:sapphire laser (Mai Tai eHP, Spectra Physics).

One FOV of 850 x 850 μm^2 was selected in each animal and imaged using a 1000-nm

femtosecond laser under a 16 × objective lens (0.8 N.A., Nikon) at a resolution of 1.6

μm/pixel. Fast resonant scanning mode (32 frames per second) was chosen to obtain

continuous images of neuronal activity (8 frames per second after averaging every 4 frames).

Recording was first performed at a shallower depth, and some neurons with high brightness

or unique dendrite patterns were selected as landmarks. In the next daily session, the same

FOV at the same depth was located before recording with the help of landmarks, and the

depth plane was lowered if recording was performed at a deeper depth (Monkeys A & B).

Because of the time limit, recordings at a specific FOV/depth with monocular and binocular

stimulations were completed in 2-3 consecutive daily sessions, but the same neurons could

be precisely tracked over multiple recording sessions with the use of multiple landmark cues.

Imaging data analysis: Initial screening of ROIs

Data were analyzed with customized MATLAB codes. A normalized cross-correlation

based translation algorithm was used to reduce motion artifacts (Li et al., 2017). Then

fluorescence changes were associated with corresponding visual stimuli through the time

sequence information recorded by Neural Signal Processor (Cerebus system, Blackrock

Microsystem). By subtracting the mean of the 4 frames before stimuli onset (*F0*) from the

average of the 6th-9th frames after stimuli onset (*F*) across 5 or 6 repeated trials for the

same stimulus condition (same orientation, spatial frequency, size, and drifting direction),

the differential image (*ΔF = F - F0*) was obtained.

For a specific FOV at a specific recording depth, the regions of interest (ROIs) or

possible cell bodies were decided through sequential analysis of 216 differential images in

the order of spatial frequency (6), size (3), and orientation (12) (6 x 3 x 12 = 216). The first

differential image was filtered with a band-pass Gaussian filter (size = 2-10 pixels), and

connected subsets of pixels (>25 pixels, which would exclude smaller vertical neuropils) with

average pixel value > 3 standard deviations of the mean brightness were selected as ROIs.

Then the areas of these ROIs were set to mean brightness in the next differential image

before the bandpass filtering and thresholding were performed (This measure gradually

reduced the SDs of differential images and facilitated detection of neurons with relatively

low fluorescence responses). If a new ROI and an existing ROI from the previous differential

image overlapped, the new ROI would be on its own if the overlapping area OA < 1/4 ROI_{new},

discarded if 1/4 ROI_{new} < OA < 3/4 ROI_{new}, and merged with the existing ROI if OA > 3/4

ROI_{new}. The merges would help smooth the contours of the final ROIs. This process went on

through all 512 differential images twice to select ROIs. Finally, the roundness for each ROI

was calculated as:

$$Roundness = \frac{\sqrt{4\pi \times A}}{P}$$

where *A* was the ROI's area, and *P* was the perimeter. Only ROIs with roundness larger than

0.9, which would exclude horizontal neuropils, were selected for further analysis.

Imaging data analysis: Orientation tuning, SF tuning, and ocular dominance

407   The ratio of fluorescence change (*ΔF/F0*) was calculated as a neuron's response to a

specific stimulus condition. For a specific cell's response to a specific stimulus condition, the

$F0_n$ of the n-th trial was the average of 4 frames before stimulus onset, and F_n was the

average of 5th-8th frames after stimulus onset. $F0_n$ was then averaged across 12 trials to

obtain the baseline F0 for all trials (for the purpose of reducing noises in the calculations of

responses), and $\Delta F_n/F0 = (F_n-F0)/F0$ was taken as the neuron's response to this stimulus at

this trial. For a small portion of neurons (e.g., ~3% in Monkeys A, ~8% in monkey B and ~2%

in Monkey C) showing direction selectivity as their responses to two opposite directions

differed significantly ($p < 0.05$, Friedman test), the 6 trials at the preferred direction was

considered for calculations of $\Delta F_n/F0$ as the cell's responses to a particular stimulus. F0 was

still averaged over 12 trials at two opposite directions.

418   Several steps were then taken to decide whether a neuron was tuned to orientation

and/or spatial frequency, and if so, its ocular dominance index. For each monocular

condition, first the orientation, SF, and size (σ) producing the maximal response among all

conditions were selected. Then responses to other 11 orientations and 5 SFs were decided at

the selected SF and size. Second, to select orientation and/or SF tuned neurons, a non-

parametric Friedman test was performed to test whether a neuron's responses at 12

orientations or 6 SFs were significantly different from each other at least under one

monocular stimulation. To reduce Type-I errors, the significance level was set at $\alpha = 0.01$.

Third, for those showing significant orientation difference, the trial-based orientation

responses of each neuron were fitted with a Gaussian model with a MATLAB nonlinear least-

squares function: lsqnonlin:

$$R(\theta) = a_1 2^{-(\frac{\theta - \theta_0}{\sigma})^2} + b$$

where R(θ) was the response at orientation θ, free parameters a_1, θ_0, σ, and b were the

amplitude, peak orientation, standard deviation of the Gaussian function, and minimal

response of the neuron, respectively. Only neurons with goodness of fit $R^2 > 0.5$ at least

under one stimulation condition were finally selected as orientation tuned neurons. Fourth,

for those showing significant SF difference, the trial-based SF responses of each neuron were

further fitted with a Difference-of-Gaussian model.

$$R(sf) = a_1 e^{-(\frac{sf}{\sigma_1})^2} - a_2 e^{-(\frac{sf}{\sigma_2})^2} + b$$

where R(sf) was a neuron's response at spatial frequency sf, free parameters a_1, σ_1,

a_2, and σ_2 were amplitudes and standard deviations of two Gaussians, respectively, and b

was the minimal response among 6 spatial frequencies. Only those with goodness of fit $R^2 >$

0.5 at least under one monocular stimulation were selected as SF tuned neurons.

The ocular dominance index (ODI) was calculated to characterize each orientation

and/or SF tuned neuron's eye preference: ODI = $(R_i - R_c)/(R_i + R_c)$, in which R_i and R_c were the

neuron's respective peak responses at the best orientation and SF to ipsilateral and

contralateral stimulations on the basis of data fitting. Here ODI = -1 and 1 would indicate

complete contralateral and ipsilateral eye preferences, respectively, and ODI = 0 would

indicate equal preferences to both eyes.

Model fitting

Monocular and binocular data in Fig. 4 were fitted by Eqs. 2 and 3, respectively. The

goodness-of-fit was indicated by a fit quality index q with a range of 0-1, which is the root

mean square deviation between the observed responses and the model normalized by the

observed response mean (Busse et al., 2009):

453
$$q = 1 - \frac{\sqrt{\frac{\sum_{i=1}^{n}(r_i - m_i)^2}{n}}}{\bar{r}}$$

where i indicates the i_{th} bin, r indicates median response of a specific bin, and m indicates

the corresponding model predictions.

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Competing interests

None.

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