Plasticity-led and mutation-led evolutions are discrete modes of the same developmental gene regulatory network.

Eden Tian Hwa Ng[a] **and Akira R. Kinjo**[a,1]

[a]**Department of Mathematics, Faculty of Science, Universiti Brunei Darussalam, Jalan Tungku Link, Gadong, BE1410, Brunei Darussalam**

Corresponding author:
Akira R. Kinjo[1]

Email address: akira.kinjo@ubd.edu.bn

ABSTRACT

The standard theory of evolution proposes that mutations cause heritable variations, which are naturally selected, leading to evolution. However, this mutation-led evolution (MLE) is being questioned by an alternative theory called plasticity-led evolution (PLE). PLE suggests that an environmental change induces adaptive phenotypes, which are later genetically accommodated. According to PLE, developmental systems should be able to respond to environmental changes adaptively. However, developmental systems are known to be robust against environmental and mutational perturbations. Thus, we expect a transition from a robust state to a plastic one. To test this hypothesis, we constructed a gene regulatory network (GRN) model that integrates hierarchical developmental regulation and environmental cues. We then simulated its evolution over different magnitudes of environmental changes. Our findings indicate that this GRN model exhibits PLE under large environmental changes and MLE under small environmental changes. Furthermore, we observed that the GRN model is susceptible to environmental or mutational fluctuations under large environmental changes but is robust under small environmental changes. This indicates a breakdown of robustness due to large environmental changes. Before the breakdown of robustness, the distribution of phenotypes is biased and aligned to the environmental changes, as though the population is preparing for rapid adaptation. These observations suggest that the evolutionary transition from mutation-led to plasticity-led evolution is due to a developmental transition from robust to susceptible regimes over increasing magnitudes of environmental change. Therefore, the GRN model can reconcile these conflicting theories of evolution.

INTRODUCTION

Plasticity-led evolution (PLE) is a process in which novel adaptive phenotypes initially induced by a new environment are genetically accommodated over generations (West-Eberhard, 2003; Levis and Pfennig, 2016, 2021). The ability to respond to environmental cues by changing the phenotype without changing the genotype is called phenotypic plasticity (West-Eberhard, 2003; Pfennig, 2021; Gilbert and Epel, 2009). PLE has been

proposed to remedy the problem of gradualism implied by the Modern Evolutionary Synthesis (Laland et al., 2014; Ehrenreich and Pfennig, 2016; Nishikawa and Kinjo, 2014, 2018; Pfennig, 2021).

In contrast, mutation-led evolution (MLE) refers to evolution initiated by a mutation that induces a novel adaptive phenotype (Gilbert and Epel, 2009). Since mutations are random, an adaptive mutation is expected to appear only after a long time, assuming the population has not yet gone extinct. While the Modern Evolutionary Synthesis is necessarily a form of MLE, MLE itself encompasses more general concepts, particularly hierarchical developmental process (Gilbert and Epel, 2009; Parsons et al., 2020). Our previous work shows that, even without environmental cues, the developmental process is still essential for adaptive evolution in a plausible time scale (Ng and Kinjo, 2023). In comparison, it has been observed that quantitative genetics models, not incorporating developmental processes, evolve far more slowly even with environmental cues (Lande, 2009; Scheiner and Levis, 2021). In this work, we consider a model for MLE that incorporates hierarchical developmental processes.

In our previous work (Ng and Kinjo, 2023), we proposed a gene regulatory network (GRN) model that exhibits behaviors compatible with PLE upon large environmental changes (Levis and Pfennig, 2016). However, this model is highly robust against mutations and environmental noises in already adapted environments (Wagner, 1996; Espinosa-Soto et al., 2011; Watson et al., 2014; Ng and Kinjo, 2023). How can the same system be robust in one environment yet exhibit a plastic response to another? This observation suggests there should be a transition from a robust to a plastic regime, depending on the magnitude of environmental change. In the following, we show that this transition manifests as a breakdown of robustness. Furthermore, we demonstrate that the system undergoes MLE under the robust regime and PLE under the plastic regime, thereby unifying two conflicting evolutionary schemes as two modes of the same developmental system.

MATERIALS AND METHODS

Here, we briefly describe our evolutionary models based on gene regulatory networks. For the details, see our previous paper (Ng and Kinjo, 2023).

Environment

In plasticity-led evolution, the environment plays two roles: selector and inducer of phenotypes (West-Eberhard, 2003). We assume that these two roles of the environment are highly correlated (Ng and Kinjo, 2023).

We model the environment-as-selector as a 200-dimensional vector $\mathbf{e}$ of ± 1. This vector is also the optimal phenotype used to calculate the fitness of each individual's phenotype (also modeled as a 200-dimensional vector; see the following subsection). We model the environment-as-inducer as each individual's environmental cue e. This vector is obtained by randomly flipping 5% of the elements of $\mathbf{e}$.

Development

In the following, we compare two variants (Ng and Kinjo, 2023) of the gene regulatory network (GRN) model introduced by Wagner (1996). In these models, the phenotype

is a vector, and the genome is a set of interaction matrices. The first model, the *Full* model, incorporating environmental cues, developmental processes, and hierarchical regulation, exhibits PLE under large environmental changes. The environmental cue serves as the environmental input to the network. The developmental process is a recursive process that updates the system's internal state, integrating environmental and genetic information into the phenotype. The hierarchical regulation reflects the multilayered nature of biological regulation.

In our developmental GRN models, let $p(s)$ be the phenotype expressed at the s-th stage of development and $\tilde{p}(s)$ (and $v(s)$) be the exponential moving average (and variance) of the phenotype. To reflect the hierarchical regulation of GRN elements (such as epigenetic marks, RNAs, and proteins), we introduce layers of 200-dimensional vectors $f(s), g(s)$, and $h(s)$ to represent epigenetic marks, gene expression and higher-order complexes (such as proteins, supramolecular complexes, etc.), respectively. For the Full model, we assume the following mutually recursive equations:

$$f_i(s) = \sigma_f \left(\sum_{j=1}^{200} G_{ij} g_j(s-1) + \sum_{j=1}^{200} E_{ij}(e_j - \tilde{p}_j(s-1)) \right),$$

$$g_i(s) = \sigma_g \left(\sum_{j=1}^{200} F_{ij} f_j(s) \right),$$

$$h_i(s) = \sigma_h \left(\sum_{j=1}^{200} H_{ij} g_j(s) + \sum_{j=1}^{200} J_{ij} h_j(s-1) \right), \tag{1}$$

$$p_i(s) = \sigma_p \left(\sum_{j=1}^{200} P_{ij} h_j(s) \right),$$

$$\tilde{p}_i(s) = \alpha p_i(s) + (1-\alpha)\tilde{p}_i(s-1),$$

$$v_i(s) = (1-\alpha)\{v(s-1) + \alpha[\tilde{p}_i(s-1) - p_i(s)]^2.\}$$

where E is a matrix that represents environmental regulation of epigenetic marks, F is a matrix representing epigenetic regulation of gene expression levels, G is a matrix representing genetic regulation of epigenetic marks, H is a matrix representing genetic regulation of higher-order complexes, J is a matrix representing interactions among higher-order complexes, P is a matrix representing regulation of the phenotype. The matrix ensemble E, F, G, H, J, P represents the individual's genome. All matrices are sparse with density 0.02. $\sigma_f, \sigma_g, \sigma_h, \sigma_p$ are activation functions (Ng and Kinjo, 2023). The initial conditions are $f(0) = \mathbf{0}$, $g(0) = \mathbf{1}$, $h(0) = \mathbf{0}$ and $p(0) = \mathbf{0}$ where $\mathbf{0}$ is the zero vector and $\mathbf{1}$ is a vector where all elements are equal to 1. We recursively compute the state vectors $f(s), g(s), h(s), p(s)$ for $s = 1, 2, \cdots$ until the total phenotypic exponential moving variance $\sum_i v_i(s) < 10^{-5}$ for some $s \leq 200$ (i.e., the phenotype has converged) and take the adult phenotype as $\tilde{p}_i(s)$. Otherwise, we say that the phenotype does not converge.

The other model, the *NoCue* model, is identical to the Full model, except it uses the following for $f_i(s)$ instead:

$$f_i(s) = \sigma_f \left(\sum_{j=1}^{200} G_{ij} g_j(s-1) - \sum_{j=1}^{200} E_{ij} \tilde{p}_j(s-1) \right). \tag{2}$$

The NoCue model does not take in environmental cues (e_j). As a result, it does not exhibit phenotypic plasticity and, therefore, serves as a model for MLE.

We note that these models are mathematically equivalent to artificial recurrent neural networks, so they have generic learning capabilities. In this context, adaptive evolution can be viewed as a process of learning the environment by changing the genome (network weights) (Watson and Szathmáry, 2016). Notably, the Full model can adaptively respond to environmental cues through development.

Evolution

We simulate evolution by applying a genetic algorithm (Mitchell, 1998) to a population of 1000 individuals (Ng and Kinjo, 2023). We impose the role of the environment-as-selector by evaluating the fitness of each individual by matching the macro-environment **e** with the adult phenotype p (assuming that p converges). In other words, the macro-environment **e** is the optimal phenotype. We also included the number of developmental steps up to convergence into the calculation of fitness such that individuals with a lower number of developmental steps are favored. We define the raw fitness of the i-th individual as:

$$\omega_i = \exp(-(\alpha\|p - \mathbf{e}\|_1 + \beta N_{\text{step}})) \tag{3}$$

where $\|p - \mathbf{e}\|_1$ is the absolute (L1) distance between the first 40 (out of 200) elements of the adult phenotype p and the corresponding elements of the macro-environment **e**, N_{step} is the number of developmental steps until convergence, $\alpha = 20$ and $\beta = \frac{1}{20}$. Only 40 traits (elements of the phenotype vector) are subject to selection, and other $160(= 200 - 40)$ traits are allowed to evolve freely. In this paper, we call the value of $\|p - \mathbf{e}\|_1$ *mismatch*. Individuals whose phenotype $p(s)$ does not converge before a pre-specified number (200) of steps are given a fitness of zero. The population in which all individuals have completed the developmental process is called the adult population in the following. The normalized fitness of the i-th individual of the adult population is given by

$$\Omega_i = \frac{\omega_i}{\max_j\{\omega_j\}} \tag{4}$$

where $\max_j\{\omega_j\}$ is the maximum raw fitness of the adult population. As such, Ω_i represents a probability of being selected for reproduction.

To generate the offsprings, individuals are randomly sampled from the adult population with replacement with probability Ω_i. Selected individuals are paired to become parents. For each pair of parents, two offsprings are produced by randomly shuffling the corresponding rows of the genome matrices with probability 0.5 between the parents. The genome matrices of the offsprings are randomly mutated. The adaptive evolution of a population in an environment is, therefore, modeled by repeated cycles of development, selection, and reproduction.

We let the population adapt to a constant environment **e** for 200 generations. This duration is called an *epoch*. Before simulating for another epoch, we change the environment **e** by flipping a specified proportion of the elements of this vector. We iterate this procedure for many epochs. Before the production runs given in the Results section,

we ran 40 epochs of preparatory runs under 40 completely uncorrelated environments to equilibrate the randomly initialized population and to let the system learn how to respond to environmental changes (Ng and Kinjo, 2023). In the following, the novel and ancestral environments refer to current and previously adapted environments.

Singular Value Decomposition of Cross-Covariance Matrices

We use cross-covariance matrices to study the correlation between selected phenotypes and environmental noise or mutations. We define the Pheno-Cue or Pheno-Geno cross-covariance matrices as

$$C_{ij} = \frac{1}{N} \sum_{k=1}^{N} (p_{ik} - \overline{p}_i)(x_{jk} - \overline{x}_j) \tag{5}$$

where p_{ik} is the i-th trait of the phenotype vector of the k-th individual, $\overline{p}_i$ is the population average of the i-th trait, x_{jk} is the j-th environmental factor (for Pheno-Cue) or the j-th element of the vectorized genome (for Pheno-Geno) of the k-th individual and $\overline{x}_j$ is the corresponding population average value.

We apply singular value decomposition (Yanai et al., 2011) to the cross-covariance matrix C to obtain orthonormal components as follows (Navarra and Simoncini, 2010):

$$C = \sum_i \sigma_i u_i v_i^\top \tag{6}$$

where the superscript $\top$ indicates transpose. In Eq. (6), u_i and v_i are the i-th left and right singular vectors, interpreted as the i-th principal axis of phenotypic variation (the left singular vectors) in response to the corresponding principal axis (the right singular vectors) of environmental noises (or mutations); σ_i is the i-th singular value, arranged in decreasing order, which represents the cross-covariance between the left and right principal components.

To quantify developmental bias, we used the proportion of the (squared) first singular value to the total cross-covariance:

$$\frac{\sigma_1^2}{\sum_i \sigma_i^2}. \tag{7}$$

The alignment between the first principal axis of phenotypic variation and environmental change is measured by the magnitude of the normalized dot product:

$$\frac{|u_1 \cdot (\mathbf{e}_n - \mathbf{e}_a)|}{\|\mathbf{e}_n - \mathbf{e}_a\|} \tag{8}$$

where $\mathbf{e}_n$ is the novel environment and $\mathbf{e}_a$ is the ancestral environment.

RESULTS

In the following, we study evolution over various magnitudes of environmental change. We show that the Full model exhibits characteristics consistent with plasticity- or mutation-led evolution when the environmental change is large or small, respectively. We then demonstrate that a breakdown in robustness due to large environmental changes

induces adaptive plastic responses and uncovers cryptic mutations in the Full model. We show that developmental bias, the skew in phenotype distribution induced by environmental changes, precedes the onset of PLE and is already aligned with environmental changes.

The Full model exhibits plasticity-led evolution under large environmental changes

Figure 1. Evolution under large environmental changes. A large environmental change is modeled by flipping 50% of the ancestral environment vector **e**. The genotype-phenotype plot of an arbitrary epoch of the **(a)** Full and **(b)** NoCue model. Trajectories of **(c)** Mismatch and **(d)** Genetic Variance for ten different consecutive epochs. These results were reproduced from our previous work (Ng and Kinjo, 2023).

This subsection briefly summarizes our previous results (Ng and Kinjo, 2023) to introduce fundamental notions describing PLE and MLE. We simulated evolution under large environmental changes for ten epochs, flipping 50% of the elements of the environment vector at the end of each epoch. We visualized evolutionary trajectories using the genotype-phenotype plots (Fig. 1 **a,b**) (Ng and Kinjo, 2023). Phenotypic values of 0 and 1 correspond to phenotypes perfectly adapted to the ancestral and novel

environments, respectively. Similarly, genotypic values of 0 and 1 correspond to the average genotypes adapted to the ancestral and novel environments. Generally, the evolution proceeds from the lower left corner to the upper right corner of the genotype-phenotype plot.

For the Full model (Fig. 1 **a**), phenotypic values are greater in the novel environment than in the ancestral environment on average, indicating an adaptive plastic response. This response is also called phenotypic accommodation (West-Eberhard, 2003, 2005). The standard deviation in the phenotypic values in the ancestral environment is minimal, indicating the robustness of adapted phenotypes. The standard deviation in the phenotypic values in the novel environment is much greater than that in the ancestral environment in the first generation, indicating the uncovering of cryptic mutations. The phenotypic and genotypic values in the novel environment increase somewhat quickly, indicating rapid genetic accommodation. These features of the genotype-phenotype plot assert that the Full model exhibits plasticity-led evolution under large environmental changes.

The NoCue model (Fig. 1 **b**) exhibits neither adaptive plastic response nor uncovering of cryptic mutations (by design). The cluttered distribution of points in the lower left corner demonstrates that the early adaptation stage of these trajectories is prolonged. The sparse distribution of points around the center of the plot indicates a rapid change in genotype once adaptive mutations are found.

We next tracked the trajectories of mismatch (Fig. 1**c**). Recall that the mismatch measures the adaptedness using the distance between the phenotype and environment (see the subsection **Evolution** in **Materials and Methods**). The mismatch of the Full model decreases immediately and rapidly. In contrast, the NoCue model exhibits a delay of around 20–30 generations before the mismatch decreases rapidly, a manifestation of gradualism.

Finally, we checked the trajectories of genetic variance (Fig. 1**d**). Here, the genetic variance is computed as the sum of the variance in each element of the genome matrices. For the Full model, the genetic variance decreases immediately and rapidly to a minimum before gradually increasing again. The initial rapid decrease corresponds to a purifying selection of uncovered cryptic variations, whereas the later increase indicates the accumulation of cryptic mutations. This behavior contrasts the NoCue model, for which the genetic variance gradually increases at the start of each epoch before decreasing to a minimum. The initial increase in the genetic variance coincides with the initial delay of mismatch (Fig. 1**c**), which is attributed to the time taken to find adaptive mutations in the novel environment. We identify these initial behaviors of the NoCue model as a key signature of MLE.

The Full model exhibits mutation-led evolution under small environmental changes

We simulated evolution under small environmental changes for ten epochs, flipping 5% of the elements of the environment vector at the end of each epoch. The evolutionary trajectories of the Full and NoCue models (Figs. 2 **a,b**) are nearly identical under small environmental changes. That is, the Full model (Fig. 2 **a**) exhibits neither adaptive plastic response nor uncovering of cryptic mutations. The NoCue model exhibits similar evolutionary trajectories under small (Fig. 2 **b**) and large (Fig. 1 **b**) environmental

Figure 2. Evolution under small environmental change. A small environmental change is modeled by flipping 5% of the ancestral environment vector **e**. Genotype-Phenotype plots in an arbitrary epoch of the **(a)** Full and **(b)** NoCue model. Trajectories of **(c)** Mismatch and **(d)** Genetic Variance for ten different consecutive epochs.

changes. Therefore, under small environmental changes, both the Full and NoCue models exhibit the characteristics of MLE. This observation is consolidated by the trajectories of mismatch and genetic variance (Fig. 2 **c,d**).

The Full model undergoes a phase transition from MLE to PLE

We have seen that the Full model exhibits PLE or MLE under large or small environmental changes. This observation suggests a transition from MLE to PLE as environmental change increases. To see how this transition occurs, we examined the mean projected phenotype (Fig. 3**a**) in the first generation after environmental changes of different magnitudes. The mean projected phenotypic value suddenly increases (indicating adaptive plastic response) at 30% environmental change. The variance in projected phenotype (Fig. 3**b**) also suddenly increases (indicating the uncovering of cryptic mutations) at 30% environmental change.

Figure 3. Transition from MLE to PLE. **(a)** Projected phenotype in the first generation. **(b)** Variance in projected phenotype in the first generation. **(c)** First singular value of phenotype-environmental cue (Pheno-Cue) cross-covariance matrix. **(d)** First singular value of phenotype-genome (Pheno-Geno) cross-covariance matrix.

To further analyze the phenotypic variation under various environmental changes, we examined the cross-covariance matrix between phenotype and environmental cue (Pheno-Cue cross-covariance) or mutations (Pheno-Geno cross-covariance). These cross-covariance matrices quantify how phenotypic variation is affected by environmental noise or mutations. In particular, we only consider the first singular value of the Pheno-Cue (Fig. 3**c**) and Pheno-Geno (Fig. 3**d**) cross-covariance matrices as it explains most phenotypic variation. We found that the first singular values also suddenly increase at 30% environmental change. This observation indicates that the phenotypes become susceptible to environmental noise or mutations at this transition point, suggesting a breakdown of environmental and mutational robustness.

Developmental bias precedes PLE

The cross-covariance matrices introduced in the previous subsection contain various information about phenotype distribution, particularly the extent of phenotypic diversity

Figure 4. Developemental bias under various environmental changes. Percentage contribution of the first singular value of the Pheno-Cue (**a**) and Pheno-Geno (**b**) cross-covariance matrices. Alignment (normalized dot product) between environmental change and the first phenotype singular vector of the Pheno-Cue (**c**) and Pheno-Geno (**d**) cross-covariance matrices.

and the skew in phenotype distribution (Noble et al., 2019). There, we studied the extent of phenotypic diversity measured by the first singular values. We now study the skew in phenotype distribution, also called the developmental bias (Uller et al., 2018). In the previous work, we observed large developmental biases aligned with large environmental changes, whereas such biases were absent in adapted environments (Ng and Kinjo, 2023).

To study the transition in developmental bias, we measured the proportion of the first singular value of the Pheno-Cue (Fig. 4**a**) and Pheno-Geno (Fig. 4**b**) cross-covariance matrices over environmental changes of different magnitudes. There is an increase in both proportions at around 25% environmental change. Compared to the transition from MLE to PLE (Fig 3), this increase in bias is less abrupt and occurs at smaller environmental changes. Thus, the developmental bias is more susceptible to environmental changes than the extent of phenotypic diversity. Still, it does not

manifest as adaptive plastic responses or increased phenotypic variance due to the system's robustness when the environmental changes are small. When the bias becomes sufficiently large, the system's robustness breaks down, as indicated by an abrupt increase in the cross-covariances (Fig 3**c,d**).

We next examined the orientation of the developmental bias. Specifically, we measured the alignment between the environmental change and the first phenotype singular vector of the Pheno-Cue (Fig. 4**c**) or Pheno-Geno (Fig. 4**d**) cross-covariance matrices over different magnitudes of environmental changes. The alignment is small for less than 25% environmental changes. Above 25% environmental change, developmental bias is well-aligned with environmental change. Thus, the emergent developmental bias facilitates selection by magnifying the difference between the most and least fit individuals. Note that the transition in alignment also happens before the increase in phenotypic variance (see Fig 3**c,d**). Thus, the population seems "ready" for rapid adaptive evolution before selection, although plastic responses are invisible.

DISCUSSION

From an evolutionary perspective, the Full model exhibits plasticity-led evolution (PLE) under large environmental changes and mutation-led evolution (MLE) under small environmental changes. From a developmental perspective, the Full model is susceptible to environmental noise and mutations under large environmental changes but is robust under small environmental changes. When the Full model is susceptible to perturbations, adaptive plastic phenotypes are induced, cryptic mutations are uncovered, and developmental bias is aligned with environmental change, enabling PLE. When it is robust against environmental and genetic fluctuations, phenotypic variation is suppressed, cryptic mutations accumulate, and developmental bias is minimal, necessitating an extensive search for favorable mutations to adapt to small environmental changes, which leads to MLE. Thus, the developmental transition from a robust regime to a susceptible one underlies the evolutionary transition from MLE to PLE.

The developmental transition from robust to susceptible regimes may be considered as the switching of an evolutionary capacitor from the "charging" (accumulating cryptic mutations) to "discharging" (purifying uncovered variations) states (Masel, 2013). Indeed, evolutionary capacitance has been suggested to be a generic feature of the GRNs, which are non-linear multi-body feedback systems with gene-environment interactions (Bergman and Siegal, 2003). The present work suggests that the switching of the evolutionary capacitor also switches the evolutionary regimes from MLE to PLE.

The transition from robust to susceptible regimes over environmental changes implies the existence of a force opposing robustness. According to the Theory of Facilitated Variation (Gerhart and Kirschner, 2007), robustness and *adaptability* are (apparently) competing properties of the developmental process. Here, adaptability means the ability of the developmental process to respond to environmental changes adaptively. In our results, adaptability manifests in two ways: (1) adaptive plastic response (Fig. 3) and (2) developmental bias favorably aligned with environmental change (Fig. 4). In the robust regime, the adaptive plastic response is not visible (Fig. 3), but the developmental bias is already aligned with environmental change (Fig. 4**c,d**). As the magnitude of environmental change increases, the induced adaptability overwhelms the system's

robustness, manifests as adaptive plastic responses, and triggers PLE (Fig. 3).

The adaptability of the Full model is a consequence of its learning capability, as it is mathematically equivalent to an artificial recurrent neural network (Watson et al., 2014; Watson and Szathmáry, 2016; Kouvaris et al., 2017; Ng and Kinjo, 2022, 2023). Many studies attempted to explain adaptive plastic response in terms of this learning capability of GRNs (Watson et al., 2014; Watson and Szathmáry, 2016; Kouvaris et al., 2017; Szilágyi et al., 2020; Ng and Kinjo, 2022). However, these works assume that the novel environment should be sufficiently similar to one of the ancestral environments to exhibit adaptive plastic response. In other words, this "developmental memory" of past environments enables adaptive plastic responses. This type of plasticity is genetically encoded because it has been selected through evolution (Parsons et al., 2020), and we still face the problem of gradualism if the novel environment is entirely different from any of the ancestral environments. Furthermore, with genetically encoded plasticity, the plastic responses are expected to be uniform across the population. This implies that there will not be a wide range of variations for selection to act upon (Riley et al., 2023), hence limiting the efficiency of genetic accommodation. In contrast, our results show that the GRNs (the Full model) can exhibit adaptive plastic responses even in entirely new environments (Fig. 3). Since the novel environments in our simulations have no correlations to any of the ancestral environments, such adaptive plastic responses cannot be (entirely) genetically encoded but must be an emergent property of the GRNs (Ng and Kinjo, 2023). This type of plasticity may be called developmental plasticity instead of genetically encoded plasticity. Furthermore, the adaptive plastic response caused by developmental plasticity compromises the robustness of the developmental system to expose a wide range of variations under large environmental changes for selection to act upon, hence accelerating genetic accommodation. In summary, the adaptability of GRNs can manifest not only as genetically encoded plasticity but also as developmental plasticity, but it is the latter plasticity that is the key to rapid adaptation to large environmental changes.

CONCLUSIONS

We have demonstrated that the gene regulatory network (GRN) model incorporating hierarchical developmental regulation and environmental cues can exhibit plasticity-led evolution (PLE) or mutation-led evolution (MLE) depending on the magnitude of environmental changes. The evolutionary transition between MLE and PLE is driven by the developmental transition between a robust state and a susceptible state of the developmental GRN. The GRN model presented here may serve as a theoretical basis for studying evolution, development, and environmental changes in an integrated manner.

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Author contributions

ARK conceived the models and ran preliminary simulations. ETHN ran large-scale simulations and collected the data. ETHN and ARK designed the work plan, wrote the

computer programs, analyzed the data, and wrote the manuscript.

Competing interests

The authors declare no competing interests.

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