1   **Polarised Moonlight Guides Nocturnal Bull Ants Home**
2

3   Cody A Freas*, Ajay Narendra; Trevor Murray; Ken Cheng
4
5   School of Natural Sciences, Macquarie University, Sydney, NSW Australia

21   * Corresponding Author
22
23
Address for correspondence:
Cody A Freas
School of Natural Sciences
Macquarie University
Sydney, NSW 2113 Australia
Email: cody.freas@mq.edu.au

Abstract
For the first time in any animal, we show that nocturnal bull ants use the exceedingly dim
polarisation pattern produced by the moon for overnight navigation. The sun or moon can
provide directional information via their position; however, they can often be obstructed by
clouds, canopy or the horizon. Despite being hidden, these bodies can still provide compass
information through the polarised light pattern they produce/reflect. Sunlight produces
polarised light patterns across the overhead sky as it enters the atmosphere, and solar
polarised light is a well-known compass cue for navigating animals. Moonlight produces an
analogous pattern, albeit a million times dimmer than sunlight. Here we show evidence that
polarised moonlight forms part of the celestial compass of navigating nocturnal ants.
Nocturnal bull ants leave their nest at twilight and rely heavily on the overhead solar
polarisation pattern to navigate. Yet many foragers return home overnight when the sun
cannot guide them. We demonstrate that these bull ants use polarised moonlight to
navigate home during the night, by rotating the overhead polarisation pattern above homing
ants, who alter their headings in response. Furthermore, these ants can detect this cue
throughout the lunar month, even under crescent moons, when polarised light levels are at
their lowest. Finally, we show long-term incorporation of this moonlight pattern into the
ants' path integration system throughout the night for homing, as polarised sunlight is
incorporated throughout the day.

81   **Keywords:** ant navigation, lunar cues, route maintenance, cue detection, polarised light,
82   vector

Introduction

Many navigating animals use the position of the sun or moon to guide their movement (Jander 1957; Koltz and Reid 1993; Perez et al. 1997; Dacke et al. 2014; Warrant and Dacke 2016; Freas and Cheng 2022). Yet these celestial bodies are not always directly visible, often obscured by clouds, the canopy or after passing below the horizon, resulting in gaps for navigation relying solely upon direct visual detection. Animals hence rely on the pattern of polarised skylight, which is accessible even when the celestial bodies are occluded to some extent (Horváth et al. 2014). When the electromagnetic field of light oscillates in a directionally predictable manner, it is defined as polarised. The type of polarisation describes the pattern of this oscillating electromagnetic field. When this oscillation is in a single plane, this light is defined as linearly polarised. The electric field of light can form other patterns, such as circular polarisation, with the field spiralling in three dimensions as a plane wave propagates. Linearly polarised sunlight comprises light waves which occur along a single plane produced as a by-product of light passing through the upper atmosphere (Horváth & Varjú 2004; Horváth et al. 2014). The scattering of this light creates an e-vector pattern in the sky, which is arranged in concentric circles around the sun or moon's position with the maximum degree of polarisation located 90° from the source. Hence when the sun/moon is near the horizon, the pattern of polarised skylight is particularly simple with uniform direction of polarisation approximately parallel to the north-south axes (Dacke et al. 1999, 2003; Reid et al. 2011; Zeil et al. 2014). The pattern's stability makes the sky's polarisation a useful directional cue for orientation (Wehner and Müller 2006; Reid et al. 2011; Lebhardt and Ronacher 2013; Warrant and Dacke 2016; Freas et al. 2017a, 2019; Freas and Spetch 2023), which insects detect through specialised photoreceptors located in the dorsal rim area of their eyes (Labhart and Meyer 1999; Homberg and Paech 2002; el Jundi et al. 2015). Like solar polarisation, though a million times weaker, the moon reflects sunlight, producing a polarised moonlight pattern emanating from the moon's position in the night sky (Gál et al. 2001). Given that the moon creates a much dimmer version of the polarisation pattern formed around the sun, only night-navigating insects with eyes highly specialised for low-light detection may be able to rely on this pattern to orient and navigate to goals.

Currently, only dung beetles (the nocturnal *Scarabaeus satyrus* and *S. zambesianus* and the diurnal *Scarabaeus (Kheper) lamarck*) are known to attend to moonlight polarisation patterns during their movement (Dacke et al. 2003, 2004, 2011; Smolka et al. 2016; Foster et al. 2019). Yet interestingly, these beetles do not use moonlight to navigate, instead relying on this pattern to keep moving straight in order to roll their dung balls expeditiously away from a central dung pile. As such, this cue has only been documented for heading maintenance over short periods. While it has been theorised that this ability to detect the much dimmer polarisation pattern produced by the moon may be present across nocturnal insects more broadly, including nocturnal bees and crickets (Herzmann and Labhart 1989; Greiner et al. 2007; Rost and Honegger 1987), there is currently no behavioural evidence for its use in goal-directed navigation. We sought such evidence in nocturnal bull ants.

The large-eyed *Myrmecia* ants have several species that restrict the majority of their
navigation to evening twilight (outbound) and morning twilight (inbound) respectively
(Narendra et al. 2017). We know that two well-studied nocturnal ant species, *Myrmecia*
pyriformis and *Myrmecia midas*, use the overhead solar polarised light pattern, which is still
visible during the twilight period to derive compass information (Reid et al. 2011; Freas et al.
2017ab; Freas and Cheng 2018). Because the information required for visual navigation
degrades beyond twilight, it has been suggested that animals tend to be less active at night.
However, a small proportion of *M. pyriformis* foragers leave the nest (10.7% of daily foraging
force) or return home during night (13.3% of daily foraging force) (Reid et al. 2013). In *M.*
midas, this nocturnal activity is even more pronounced with the majority of the foraging
force returning during night (62.8% of daily foraging force) along with a minority of foragers
leaving the nest during night (26.2% of daily foraging force) (Freas et al. 2017a).
Nocturnal bull ants navigate using a combination of learned visual cues (Freas and
Cheng 2018; Islam et al. 2020; Deeti et al. 2023) and homing vectors obtained by integrating
pedometric and celestial compass information (Wittlinger et al. 2006; Wehner 2020). This
'true nocturnal navigation' is likely aided by the increase in the light intensity provided by
the moon's presence. In *M. pyriformis*, on 'full-moon' nights there was a significantly greater
proportion of foragers leaving the nest at night compared to a 'new-moon' night (Reid et al.
2013). This additional light at night may enhance terrestrial visual features foragers have
learned and therefore assist in visual guidance. In addition, the moon and the lunar
polarisation pattern also likely provide compass information, allowing foragers acquire or
follow a homing vector. Several arthropods, including ants and bees, directly track the
moon's position to obtain compass information (Jander 1957; Koltz and Reid 1993; Dacke et
al. 2004; Ugolini et al. 2003). But given the moon may be occluded by clouds or overhanging
canopy we aim to identify here whether the lunar polarised skylight can also be used by ants
for homing.
In the current study, we studied foraging ants' ability to orient during lunar twilight,
by placing and rotating a linear polarising filter over them as they returned to the nest
(Figure 1A). We also explored whether these navigators weigh their attendance to polarised
moonlight across the lunar cycle, since during quarter-moon and crescent-moon nights,
smaller portions of the moon's surface reflect sunlight (as well as moonless nights when no
ambient e-vector is present). Finally, we characterised changes in weighting that these ant
navigators give polarised moonlight, as a function of the moon's overnight consistency in the
sky (waxing vs. waning) and the length of their accumulated path integrator, which should
increase the weight given to celestial compass portion of the path integrator when in conflict
with terrestrial visual cues (Burkhalter 1972; Narendra 2007; Wystrach et al. 2015; Freas and
Cheng 2019).
160
Methods
Study site

Experiments were conducted from April through October 2023 on two *Myrmecia midas*
nests on the Macquarie University Wallumattagal campus in Sydney, Australia (33°46 11S,
151°06 40E). *M. midas* nests are typically located within stands of *Eucalyptus* trees with the
nest entrance located near (<30cm) a tree (Deeti et al. 2024). *M. midas* is nocturnal, with
foraging onset occurring ~20min after sunset when foragers leave the nest to travel to and
up one of several surrounding foraging trees overnight (Freas et al. 2018). Inbound
navigation is more variable, with foragers returning to the nest entrance overnight and into
morning twilight (Freas et al. 2017a). For this study, we chose two nests under open
canopies to ensure foragers had at least partially unobstructed visual access to the overhead
sky (Figure 1B). The understory of these areas is naturally barren of vegetation, and we
cleared the foraging column of debris to aid visual tracking.
174
Apparatus: Polarisation filter
For each condition, we altered the pattern of polarised moonlight by rotating a linear
polarisation filter (Polaroid HN22, 30cm diameter) above each ant along their inbound
journey. This rotation blocks the ambient e-vector direction of the sky above the navigator,
replacing it with an artificial e-vector of polarisation that is rotated ±45° off the ambient
pattern. This filter was held by a circular 1cm thick ring and lifted 10cm off the ground by
four equally spaced thin metal legs (Figure 1). All testing was conducted overnight before
morning solar twilight, during the lunar twilight for each tested lunar phase. For each night
we obtained the moon's position as it reached the horizon based on the Astronomical
Almanac (http://asa.usno.navy.mil) and set the ambient lunar e-vector perpendicular from
the moon's position at moonset. We relied on a digital compass mobile application (Apple™)
confirmed by an analogue compass to locate the ambient e-vector and rotated the linear
polariser by ±45° from this direction for each ant.
188
Across all conditions, we recorded four positions: the ant's release point, position
when the filter was placed overhead, the filter exit point, and reorientation after ~1m, taking
care to slowly follow the ant and mark their positions so as to not disturb their travel. These
positions determine each forager's initial orientation, exit orientation and reorientation
directions (Figure 1). After testing, each forager was marked with acrylic paint (Tamiya™) to
prevent retesting. Testing was conducted at distinct lunar phases which predicably occur
throughout the lunar month cycle (29.5 days).
196
Full moon
For full moon testing we chose nights during which the waxing moon's lunar phase was near
full but with clear separation between solar and lunar twilights. Testing on true full moon
nights is problematic as solar and lunar twilights fully overlap and the solar polarised light
pattern would overpower the lunar counterpart. Testing during the nights preceding the full
moon (waxing phase) ensured the moon's presence in the night sky overnight and testing

occurred on nights in which the lunar twilight (1am – 4am) was clearly separated from the
start of morning solar twilight (5:22am) with illumination above 80% of the lunar surface.
Outbound *M. midas* foragers from two nests were followed as they left the nest
during evening twilight and collected as they climbed onto their foraging tree, (Nest 1: 6.0m;
Nest 2: 3.1m from the nest entra). Each forager was provided a small amount of honey and
held within a clear plastic phial on the ground 5m from the foraging tree with an
unobstructed view of the sky (Figure 1B). Foragers were held in these phials overnight until
the moon's position was within ±10° of the horizon (large stands of trees and buildings near
the western horizon occluded the moon's position during all testing; Figure 1B).
212
Waxing lunar phase
We observed clear shifts in forager headings at both nests under *Full Moon* conditions, yet
nights with over 80% lunar illumination only account for nine nights per lunar cycle. To
assess if polarised moonlight can be used throughout the lunar month, we tested Nest 1
foragers in three further conditions representing distinct lunar phases: a *Waxing Quarter*
Moon, a Waxing Crescent Moon, and a *No Moon* control. For the *Quarter Moon* and
Crescent Moon conditions, we tested ants identically to full moon conditions; for overnight
testing, however, the moon has a different temporal period when it is positioned near the
horizon (12am and 9pm, respectively).
The procedure was slightly modified for *No Moon* testing as we did not test these
foragers on the new moon night (the new moon is only present during the day). We
hypothesised that foragers with no available ambient polarisation and suddenly presented
with an e-vector pattern might fall back on a memory of the morning solar e-vector as many
foragers return during morning twilight and this direction remains consistent across nights.
In order to test on a night when there were distinct directional differences between the
lunar and morning solar e-vectors (Lunar e-vector: 329°; Morning solar e-vector: 7°; Evening
Solar e-vector: 353°), we chose to test on a quarter moon night when the moon was well
below the horizon. Testing commenced at 9:00pm, when the moon was 30° below the
horizon and we rotated the filter around to the future lunar e-vector direction (moonrise at
12:39am). If foragers were relying on a solar e-vector memory, we expected to see unequal
shifts between ±45° (smaller shifts in the +45° condition and larger shifts in the −45°
condition).
235
Waning lunar phases
While there is a consistent presence of polarised light during the waxing phase, during
waning lunar phases there is a gap which may impede this pattern's use as a compass cue.
Testing during the waxing lunar phase, as the moon's illuminated surface increases,
corresponds with periods in which the moon rises prior to sunset and sets overnight. This
creates a consistent presence of polarised light (solar then lunar) that foragers could use to
continuously update their celestial compass and path integrator. In contrast, the waning
lunar phase corresponds with the moon rising overnight, leading to a gap in this cue as solar

twilight ends. We hypothesised that the absence of the moon's presence as a cue overnight
might decrease its weighting or degrade its integration into the celestial compass. We added
two conditions to test this hypothesis: a *Waning Full Moon* and *Waning Quarter Moon*
conditions. Foragers were tested identically to previous conditions; only, they were tested
during moonrise (10pm and 1am) overnight rather than moonset.
249
Vector testing
After noticing differences in heading shift magnitude between nests which correlated with
path integration derived vector lengths, we tested the hypothesis that, similar to solar
polarisation (Freas et al. 2017b), the navigator's accumulated vector length impacts
orientation to rotated lunar polarised light. While foragers at Nest 1 (6.0m vector) reoriented
almost fully, those at Nest 2 (3.1m vector) only altered their headings by about half of the
45° e-vector shift (25.2°± 3.7°), despite being tested on near-full-moon nights.
To test this hypothesis, we tested a separate group of foragers at Nest 1 on near
(waxing) full moon nights at the same spatial location, but with diverging remaining vectors
(Figure 6A). In the first test (called *Halfway Collect & Release*), outbound foragers were only
allowed to travel half the distance (~3m) to their foraging tree before being collected and
were then released back at this spot to be tested under the ±45° filter rotations at ~2m from
the nest with a small remaining vector (Figure 6A). In contrast, the second testing group
(*Halfway Release)* were allowed to accumulate their full 6m vector by collecting outbound
foragers as they reached their foraging tree. When these foragers were released, we placed
them at the halfway point, 3.0m from the nest and tested them with a larger remaining
vector near (~2m) to the nest. We followed outbound foragers to their foraging tree,
collected and held them until lunar twilight (2-4am) identically to previous full moon
conditions. In both conditions, we again recorded the initial orientation, filter exit
orientation and post-filter reorientation of each forager. These conditions tested if vector
state (near zero vs. near full) or the test site underlies the observed heading shift differences
271
Statistical analysis
Data were analysed with circular statistics with the statistics package Oriana Version
4 (Kovach Computing Services). Each ant had a slightly different inbound heading due to
their stereotypical route along the foraging corridor and we corrected this variance by
designating the initial headings (pre-filter) as 0° for calculating shift magnitudes under the
filter. To assess shift magnitude between −45° and +45° foragers within conditions, we
calculated the mirror of the shifts in each −45° condition, allowing shift magnitude
comparisons between conditions within each test. Mirroring the −45° conditions was
calculated by mirroring each individual forager's shift across the 0° to 180° plane. This
mirrored data set was then compared to the corresponding unaltered +45 condition. As
mirrored −45° shifts were not significantly different from +45° shifts in any condition
(Watson–Williams F-tests), they were combined for between condition comparisons. Within-
individual comparisons (Initial Orientation vs. Filter Exit and Filter Exit vs. Reorientation)

were analysed using Moore's Paired Tests. Across-condition shift magnitudes were analysed
using Watson–Williams F-tests. In the lunar phase comparisons where full, quarter and
crescent shift magnitudes, as well as Waning and Waxing phases were compared, Holm-
Bonferroni corrections were applied to the p-value to account for multiple comparisons.
Given Watson–Williams F-tests can be sensitive to difference in spread, when differences
between conditions were significant, we further analysed these conditions with Var tests to
assess if these differences were due to variance (Wystrach et al. 2014; Freas and Cheng
2017; Freas and Spetch 2019). Here, the absolute angular error from the mean vector were
calculated for each condition and this error magnitude between conditions was compared
using Mann-Whitney u tests.
295

Results
Full moon testing
Under a (waxing) *Full Moon* with lunar illumination above 80%, when the linear polariser
was rotated clockwise (+45°), exit orientations were shifted to the right of initial headings
(mean ± s.e.m. Nest 1: 38.4±4.8°; Nest 2: 23.4±4.2°; Figure 2A, B), and these changes were
significant (Moore's Paired Test, Nest 1: R=1.639, p<0.001; Nest 2: R=1.592, p<0.001).
Forager headings also changed predictably when the filter was rotated counter-clockwise (−
45°) with exit orientations to the left of initial headings (Nest 1: −41.1±5.5°; Nest 2: −
27.1±7.4°; Figure 2A, B), and these changes were significant (Moore's Paired Test, Nest 1:
R=1.794, p<0.001; Nest 2: R=1.310, p<0.01). After exiting the +45° or −45° rotated filter,
foragers reoriented significantly to the left (Moore's Paired Test, Nest 1: R=1.598, $p < 0.001$;
Nest 2: R=1.383, p<0.005) or right respectively (Moore's Paired Test, Nest 1: R=1.604,
p<0.001; Nest 2: R=1.328, p<0.005). Shift magnitudes did not differ between +45° and −45°
conditions (Watson–Williams F-test, Nest 1: $F_{(1,23)}$=0.155, p=0.697; Nest 2: $F_{(1,20)}$=0.234,
p=0.634). Shift magnitudes were significantly larger at Nest 1 compared to Nest 2 (Watson–
Williams F-test, $F_{(1,45)}$=8.672, p=0.005), exhibiting shifts near the full e-vector change
(39.8±3.2°) while foragers at Nest 2 only exhibited shift magnitudes at about half the 45°
rotation (25.2±3.7°). A Var test showed no significant difference in circular variance between
nests (Var Test; Z=−0.09; p=0.530).
315

Waxing lunar phases
Under a *Waxing Quarter Moon* (lunar illumination ~50%), when the e-vector was
rotated clockwise (+45°), exit orientations were again significantly shifted (Moore's Paired
Test, R=1.787, p<0.001) to the right of their initial heading (mean ± s.e.m.; 37.6±4.1°; Figure
3A). Forager headings were similarly significantly altered (Moore's Paired Test, R=1.734,
p<0.001) when the overhead e-vector was rotated counter-clockwise (−45°) with exit
orientations to the left of initial headings (mean ± s.e.m. −38.5±6.4°; Figure 3A). After exiting
the filter in both conditions, foragers reoriented significantly back to the ambient lunar e-
vector either to the left (+45°: Moore's Paired Test, Nest 1: R=1.616, p<0.001) or right (−45°:
Moore's Paired Test, Nest 1: R=1.664, p<0.001) of their filter exit heading direction.

Foragers continued to show evidence of attending to the lunar polarisation pattern
even under a *Waxing Crescent Moon* (lunar illumination ~20%). Here, when the e-vector was
rotated clockwise (+45°), exit orientations were again significantly shifted (Moore's Paired
Test, R=1.175, p<0.025) to the right of their initial heading (mean ± s.e.m.; 24.3±15.5°; Figure
3B). Forager headings were similarly significantly altered (Moore's Paired Test, R=1.39,
p<0.005) when the overhead e-vector was rotated –45° counter-clockwise, with exit
orientations to the left of initial headings (mean ± s.e.m.; –25.1±6.3°; Figure 3B). After exiting
the filter in both conditions, foragers reoriented significantly back toward the ambient lunar
e-vector either to the left (+45°: Moore's Paired Test, Nest 1: R=1.324, p<0.005) or right (–
45°: Moore's Paired Test, Nest 1: R=1.223, p<0.025) of their filter exit heading direction. Shift
magnitudes were not significantly different between ±45° conditions (Watson–Williams F-
test, $F_{(1,20)}$=0.03, p=0.863).
When no ambient lunar e-vector was present (*No Moon*) and the polariser was
rotated either clockwise (+45°) or counter-clockwise (–45°), foragers did not significantly
alter their paths under the filter (+45°: Moore's Paired Test, R=0.226, p>0.50; mean ± s.e.m.:
–5.4±7.4°; –45°: Moore's Paired Test, R = 0.650, p > 0.10; mean ± s.e.m.: 1.5±2.4°; Figure 3C).
Foragers also did not significantly reorient after exiting the filter (+45°: Moore's Paired Test,
R=0.294, p>0.50; mean ± s.e.m.: –7.1±5.6°; –45°: Moore's Paired Test, R=0.611, p>0.10;
mean ± s.e.m.: 3.1±5.8°). Shift magnitudes were not significantly different between ±45°
conditions (Watson–Williams F-test, $F_{(1,24)}$=0.016, p=0.899).
When comparing shift magnitudes across lunar phases, *Full Moon f*oragers were not
significantly different from either the *Waxing Quarter Moon* or *Waxing Crescent Moon*
(Watson–Williams F-test, p>0.05; see Figure 5).
349
Waning lunar phases
Under a *Waning Full Moon*, when the polarisation e-vector was rotated clockwise (+45°), exit
orientations were shifted significantly to the right of initial headings (mean ± s.e.m. =
16.5±5.3°; Moore's Paired Test, R=1.468, p<0.005; Figure 4A). Headings also shifted
significantly to the left of initial headings (mean ± s.e.m.: –15.4±5.1°; Moore's Paired Test,
R=1.513, p<0.001; Figure 4A) when the overhead e-vector was rotated –45° counter-
clockwise. After exiting the filter in both conditions, foragers reoriented significantly back to
the ambient lunar e-vector either to the left (+45°: Moore's Paired Test, Nest 1: R=1.548,
p<0.001) or right (–45°: Moore's Paired Test, Nest 1: R=1.247, p<0.025) of their filter exit
heading direction. Shift magnitudes were not significantly different between the ±45°
conditions (Watson–Williams F-test, $F_{(1,30)}$=0.022, p=0.884).
Under a *Waning Quarter Moon* (lunar illumination ~50%), when the e-vector was
rotated clockwise (+45°), exit orientations were shifted to the right of initial headings
(mean ± s.e.m. = 20.5±8.4°; Figure 4B), and these changes were significant (Moore's Paired
Test, R=1.33, p<0.005). Headings also changed significantly (Moore's Paired Test, R=1.31,
p<0.01) when the overhead e-vector was rotated counter-clockwise (–45°) with exit
orientations to the left of initial headings (mean ± s.e.m.: –25.0±9.9°; Figure 4B). After

exiting the filter in both conditions, foragers reoriented significantly back to the ambient lunar e-vector either to the left (+45°: Moore's Paired Test, Nest 1: R=1.504, $p<0.001$) or right (−45°: Moore's Paired Test, Nest 1: R=1.246, $p<0.025$) of their filter exit heading direction. Shift magnitudes were not significantly different between the ±45° conditions (Watson–Williams F-test, $F_{(1,18)}=0.154$, $p=0.700$).

When comparing shift magnitudes between Waxing and Waning phases, shift magnitude was significantly higher in both *Waxing Full Moon* and *Waxing Quarter Moon* foragers when compared to their *Waning* counterparts (39.8° vs. 16.0° and 38.1° vs. 22.7° respectively; Full Moon: Watson–Williams F-test, $F_{(1,55)}=21.62$, $p<0.001$; Quarter Moon: Watson–Williams F-test, $F_{(1,44)}=5.889$, $p=0.038$; Figure 5). Var tests showed no significant difference in circular variance between Waxing and Wanning phase shift magnitudes (Full Moon: Var Test; $Z=−0.50$; $p=0.625$; Quarter Moon: Var Test; $Z=−0.38$; $p=0.716$).

Vector testing

Both forgers with a long ~6m remaining vector (*Halfway Release),* or a short ~2m remaining vector (*Halfway Collection & Release),* tested at the same location, exhibited significant shifts (*Halfway Release*: Moore's Paired Test, $R=1.728$, $p<0.001$; *Halfway Collection & Release:* Moore's Paired Test, $R=1.380$, $p<0.005$) to the right of initial headings (mean ± s.e.m.: 41.9±4.9° and 16.8±4.3°; Figure 6B, C) when the e-vector was rotated clockwise (+45°). Forager headings also significantly shifted (*Halfway Release*: Moore's Paired Test, $R=1.664$, $p<0.001$; *Halfway Collection & Release:* Moore's Paired Test, $R=1.07$, $p<0.05$) when the overhead e-vector was rotated counter-clockwise (−45°) with exit orientations to the left of initial headings (mean ± s.e.m.: −46.4±6.3° and −12.7±8.5°; Figure 6B, C). After exiting the filter in both conditions, foragers reoriented significantly back to the ambient lunar e-vector either to the left (+45°: *Halfway Release*: Moore's Paired Test, R=1.692, $p<0.001$; *Halfway Collection & Release:* Moore's Paired Test, $R=1.600$, $p<0.001$) or right (−45°: *Halfway Release*: Moore's Paired Test, R=1.604, $p<0.001$; *Halfway Collection & Release:* Moore's Paired Test, $R=1.274$, $p<0.01$) of their exit heading direction. Shift magnitude was significantly higher in *Halfway Release* foragers compared to *Halfway Collection & Release* foragers tested at the same location 2m from the nest entrance (44.1° and 14.8° respectively; Watson–Williams F-test, $F_{(1,40)} = 29.105$, $p < 0.001$; Figure 6B, C). Var tests showed no significant difference in circular variance of shift magnitudes when foragers had a long or short vector (Var Test; $Z=−1.34$; $p=0.188$).

Discussion

These results constitute the first instance of polarised moonlight use for homing and only the second reported instance of its use for orientation in any animal. *Myrmecia midas* foragers predictably altered their heading directions in response to experimental rotations in the overhead lunar polarisation pattern. This ability to detect and use of polarised moonlight persisted throughout the lunar cycle, with foragers attending to the pattern even under a crescent moon with ~20% lunar illumination. This indicates that polarised moonlight is

detectable across the lunar month, making it a stable cue these ants can use when moving
or updating their path integrator overnight.
While they can utilise the lunar polarisation pattern through the lunar cycle, foragers
exhibited reduced heading shifts during the waning lunar phases, during which the moon's
absence for a portion of the night leads to a cue gap overnight (Figure 7). These reductions
in observed shifts are likely due to either decreased weighting or a degradation in the
celestial compass due to periods when no celestial cues are available. The shift magnitude
differences between conditions also point to moonlight polarisation being continuously
tracked throughout the overnight period, in line with this celestial cue being integrated into
the navigator's path integrator. Further evidence of this cue's integration into the path
integrator is illustrated in our vector length testing conditions. Here, foragers with longer
home vectors under a full moon responded almost fully to e-vector changes regardless of
their distance to the nest, while foragers with shorter vector distances led to less than half
the e-vector shift, corresponding with decreases in vector cue strength at small distances
(Wystrach et al. 2015). These changes align with how *M. midas* uses polarised sunlight as
part of its vector-based homing during evening and morning twilight (Freas et al. 2017b;
Figure 7), suggesting that polarised moonlight is detected and integrated into its path
integrator along the same visual pathways as sunlight.
426
Moonlight vs. sunlight
The nocturnal bull ants *Myrmecia pyriformis* and *Myrmecia midas* are known to use the
solar polarised light pattern during the twilight periods (Reid et al. 2011; Freas et al.
2017ab), yet both species are active after twilight, when solar polarisation cues are absent
(Reid et al. 2011, 2013; Freas et al. 2017ab). The observed true nocturnal navigation in these
animals could be driven by the moon's presence with *M. pyriformis*, which show more
foraging activity on full moon nights (Reid et al. 2013). *M. midas* exhibits a high level of
overnight activity, with almost half of foragers returning before the morning solar twilight.
M. midas also navigates through heavily canopied forest habitat where the moon may be
occluded but its polarisation pattern across the sky remains unobstructed. Thus, *M. midas*
makes for an interesting species to characterise lunar and solar polarised light detection.
While we cannot compare solar and moonlight polarisation navigation in outbound
ants (outbound foraging is highly correlated with evening twilight when the solar light would
overpower any moonlight polarisation pattern), striking similarities occur when comparing
solar and moonlight polarisation navigation in ants homing to the nest (Figure 7). In the solar
polarisation study (Freas et al. 2017b), inbound foragers tested during morning twilight at 4–
6 m from their nest altered their paths under the filter for almost the full 45° solar e-vector
manipulation (−45° rotation: −41.16°/ +45° rotation: 34.13°; Figure 7) but only compensated
for around half of the rotation when tested 1–2 m from the nest (−45° rotation: −24.86°/
+45° rotation: 19.73°). We see the same pattern with polarised moonlight with foragers
exhibiting near full shifts 5 m from Nest 1 (−45° rotation: −41.4°/ +45° rotation: 38.4°) and
half shifts 2 m from Nest 2 (−45° rotation: −27.1°/ +45° rotation: 23.4°; Figure 7).

We also observed consistent slight under-estimation in the shifts even when foragers
had a long vector. Observations of ants after the filter was placed overhead suggest that
heading updates are not immediate, occurring only after the ant travels along its original
heading a few centimetres (~5cm). This means that even if the ant fully shifts its heading,
the delay will cause our measurements at filter exit to slightly underestimate each
individual's position since we measure the angle from where the lunar cue changes (as the
filter was placed overhead) and not the position at which the ant altered its heading.
456
Moonlight and the path integrator
We also see the same full heading changes to both solar- and moonlight-polarisation-
pattern rotations when foragers were released halfway to the nest and tested 2m with a
longer 6m vector (Solar: –45° rotation: –35.77°/ +45° rotation: 39.42°; Moonlight: –45°
rotation: –46.4°/ +45° rotation: 41.9; Figure 7). In the *Halfway collect & Release* condition,
when vector length was 2m, this shift significantly decreased at the same testing location,
indicating that the vector length and not the testing site dictated this adjustment in cue
weighting. These findings suggest that under the filter, foragers use any available celestial
and terrestrial cues that are still visible, yet the weighting of the polarisation pattern appears
to change in accordance with the vector state (Burkhalter 1972; Narendra 2007) and not its
test location close to the nest tree, which could be a potentially highly salient landmark. This
leads to several interesting implications. First, these ants weight the polarisation cue more
highly and perform larger heading shifts when their current path integrator distance is
longer. These increased shift magnitudes align with the hypothesis that with longer
accumulated vectors, ants increase the weighting given this cue (Burkhalter 1972; Narendra
2007; Wystrach et al. 2015; Freas et al. 2017b). Secondly, these ants are using polarised
moonlight precisely the same way they use solar polarisation, meaning polarised moonlight
is likely integrated into the forager's path integrator throughout the night. Polarised
moonlight is likely processed through the same visual pathways as polarised sunlight,
meaning that these ants can use the same underlying neural architecture for polarised solar
light and polarised moonlight cues. The limiting factors to lunar cue use for navigation would
instead be the ant's detection threshold for either absolute light intensity, polarization
sensitivity or spectral sensitivity. In addition to being dimmer, moonlight is less UV-rich
compared to direct sunlight and its spectrum changes across the lunar cycle (Palmer and
Johnsen 2015), with sensitivity to green spectrum within polarised moonlight of potential
importance for orientation (Yilmaz et al. 2024).
483
Polarised moonlight and lunar phase
Foragers showed clear evidence of detecting and employing polarised moonlight when
homing to the nest across the lunar cycle, even on waxing crescent moon nights. This aligns
with polarised moonlight's use in dung beetles, with individuals able to maintain their
straight-line paths under quarter and crescent moon e-vectors (Dacke et al. 2004).
Furthermore, the lack of a shift-magnitude reduction between full and crescent nights

suggests no reduction in detection. While we could have continued to test with smaller
portions of the moon surface illuminated, a reduction in shift magnitude could result from
either physiological limits in detection or 'decisional' processes in how much weight to
accord the cue. Behavioural responses and physiological limits cannot be untangled
behaviourally, and detection thresholds would require intracellular recordings under dim
polarised light. Finally, the lack of shifts with *No Moon* foragers indicates that these
navigators do not fall back on memories of the evening or morning solar e-vector when
presented one overnight.
One unexpected finding was the reduction in shift magnitude under waning moons
relative to waxing moons. When we first tested foragers under *Waning Full Moons* and
Waning *Quarter Moons* they showed clear evidence of attending to the polarisation cue, but
shift magnitudes were significantly smaller compared to the *Waxing Moon* conditions. This
reduction in shift magnitude suggests that polarised moonlight was being detected but it
was weighted weakly, perhaps due to the incorporation of the celestial compass into the
path integrator being interrupted. This observed reduction in shift magnitude likely results
from the period overnight in which the waning moon was absent from the night sky,
meaning foragers could not attend to a consistent polarisation pattern throughout the night.
The moonlight pattern only becomes visible in the sky once the moon reaches −18° below
the horizon; thus, waning-moon nights present periods when there are neither solar nor
lunar cues available to maintain the compass, potentially degrading the compass portion of
the vector estimate. This suggests that when the moon is waxing and present throughout
the overnight period (at least until moonset), *M. midas* foragers are continuously tracking it
and integrating this compass cue into their path integrator. When there are periods
overnight when the moon and its polarisation pattern are absent, it is either weighted
weakly or the path integrator may become degraded with cues having been interrupted
during overnight periods with no detectable celestial cues.
In this vein, it remains unknown if these ants are tracking their lunar polarisation
compass by using a time-compensated lunar compass, or if the compass is updated with
reference to other cues, such as the panorama, throughout the night. It is possible that
these ants form a lunar ephemeris function or time compensator for the moon's position.
Solar ephemeris functions are well demonstrated in insect navigators (Mouritsen and Frost
2002; Massy and Wonton 2023), including honeybees (Dyer and Dickinson 1994) as well as
desert ants (Wehner and Lanfranconi 1981). This study cannot untangle these possibilities as
ants had a continuous view of both the sky and surrounding terrestrial cues throughout the
night before testing. However, the shift reductions on nights where there was no access to
the lunar polarisation cue until just prior to tests (lunar twilight before moonrise), suggests
these foragers may need some set period of exposure to the moon's polarisation pattern to
employ it fully during inbound homing. Future work could tackle if a lunar ephemeris
function is employed by these ants through exposing or blocking access to the sky and
familiar panorama for set time periods when the moon is naturally visible overnight, during
waxing gibbous phases.

531
Conclusions

Inbound *M. midas* foragers detect and respond predictably to rotations of the moonlight e-
vector orientation under a filter and reorient back to the ambient e-vector after filter exit.
This ability occurs across lunar phase, suggesting that polarised moonlight is a detectable
cue throughout the lunar month. Heading changes due to polarised moonlight align with
responses to polarised sunlight as part of the path integrator during solar twilight. This
indicates that polarised moonlight is likely detected and integrated into the ant's path
integrator for inbound homing along the same visual pathways as polarised sunlight.
Reductions in heading shifts due to differences in PI vector lengths, and periods without
access to polarised light patterns suggest that these animals can weight the information
provided by celestial polarised light. In so doing these foragers can cater their navigational
decisions proportionate to closely match the reliability of available navigational information.
544

Acknowledgments
Funding

This project was funded by a Macquarie University Research Fellowship (MQRF0001094), by

Macquarie University, and by an ARC Discovery Grant (DP200102337).

Land Acknowledgment

This work was conducted upon the Wallumattagal campus of Macquarie University. We

acknowledge the traditional custodians of the land on which Macquarie University sits, the

Wallumattagal clan of the Dharug Nation. Their culture and customs have nurtured and

sustained this land since the Dreamtime and continue to do so. We pay our respects to their

Elders, past, present, and future.

Conflicts of interest

The authors declare no conflicts of interest associated with this work.

Ethics

There are no state or federal governmental regulations guiding the research of

invertebrates in Australia.

Data Availability

All data, documentation and code will be made available online at osf.io

References
Burkhalter, A. (1972). Distance measuring as influenced by terrestrial cues in *Cataglyphis*
bicolor. In Information Processing in the Visual System of Arthropods (ed. R. Wehner),
pp. 303-308. Berlin: Springer.

Dacke, M., Byrne, M. J., Baird, E., Scholtz, C. H., & Warrant, E. J. (2011). How dim is dim? Precision of the celestial compass in moonlight and sunlight. Philosophical Transactions of the Royal Society B: Biological Sciences, 366(1565), 697-702.

Dacke, M., Byrne, M. J., Scholtz, C. H., & Warrant, E. J. (2004). Lunar orientation in a beetle. Proceedings of the Royal Society of London. Series B: Biological Sciences, 271(1537), 361-365.

Dacke, M., Nilsson, DE., Warrant, E. et al. Built-in polarizers form part of a compass organ in spiders. Nature, 401, 470–473 (1999). https://doi.org/10.1038/46773

Dacke, M., Nilsson, D. E., Scholtz, C. H., Byrne, M., & Warrant, E. J. (2003). Insect orientation to polarized moonlight. Nature, 424(6944), 33-33.

Dacke, M., el Jundi, B., Smolka, J., Byrne, M., & Baird, E. (2014). The role of the sun in the celestial compass of dung beetles. Philosophical Transactions of the Royal Society B: Biological Sciences, 369(1636), 20130036.

Deeti, S., Islam, M., Freas, C., Murray, T., & Cheng, K. (2023). Intricacies of running a route without success in night-active bull ants (*Myrmecia midas*). Journal of Experimental Psychology: Animal Learning and Cognition, 49(2), 111.

Deeti, S., Tjung, I., Freas, C., Murray, T., & Cheng, K. (2024). Heavy rainfall induced colony fission and nest relocation in nocturnal bull ants (*Myrmecia midas*). Biologia, 79(5), 1439-1450.

Dyer, F. C., & Dickinson, J. A. (1994). Development of sun compensation by honeybees: how partially experienced bees estimate the sun's course. Proceedings of the National Academy of Sciences, 91(10), 4471-4474.

el Jundi, B., Warrant, E. J., Byrne, M. J., Khaldy, L., Baird, E., Smolka, J., & Dacke, M. (2015). Neural coding underlying the cue preference for celestial orientation. Proceedings of the National Academy of Sciences, 112, (36), 11395–11400.

Foster, J. J., Kirwan, J. D., El Jundi, B., Smolka, J., Khaldy, L., Baird, E., & Dacke, M. (2019). Orienting to polarized light at night–matching lunar skylight to performance in a nocturnal beetle. Journal of Experimental Biology, 222(2), jeb188532.

Freas, C. A., & Cheng, K. (2017). Learning and time-dependent cue choice in the desert ant, *melophorus bagoti*. Ethology, 123(8), 503-515.

Freas, C. A., & Cheng, K. (2019). Panorama similarity and navigational knowledge in the nocturnal bull ant *Myrmecia midas*. Journal of Experimental Biology, 222(11), jeb193201.

Freas, C. A., & Cheng, K. (2022). The basis of navigation across species. Annual Review of Psychology, 73, 217-241.

Freas, C. A., & Spetch, M. L. (2019). Terrestrial cue learning and retention during the outbound and inbound foraging trip in the desert ant, *Cataglyphis velox*. Journal of Comparative Physiology A, 205(2), 177-189.

Freas, C. A., & Spetch, M. L. (2023). Varieties of visual navigation in insects. Animal cognition, 26(1), 319-342.

Freas, C. A., Narendra, A., & Cheng, K. (2017a). Compass cues used by a nocturnal bull ant, *Myrmecia midas*. Journal of Experimental Biology, 220(9), 1578-1585.

Freas, C. A., Narendra, A., Lemesle, C., & Cheng, K. (2017b). Polarized light use in the nocturnal bull ant, *Myrmecia midas*. Royal Society Open Science, 4(8), 170598.

Freas, C. A., Plowes, N. J., & Spetch, M. L. (2019). Not just going with the flow: foraging ants attend to polarised light even while on the pheromone trail. Journal of Comparative Physiology A, 205(5), 755-767.

Freas, C. A., Wystrach, A., Narendra, A., & Cheng, K. (2018). The view from the trees: nocturnal bull ants, Myrmecia midas, use the surrounding panorama while descending from trees. Frontiers in Psychology, 9, 16.

Gál, J., Horváth, G., Meyer-Rochow, V. B., & Wehner, R. (2001). Polarization patterns of the summer sky and its neutral points measured by full–sky imaging polarimetry in Finnish Lapland north of the Arctic Circle. Proceedings of the Royal Society of London A, 457(2010), 1385-1399.

Greiner, B., Cronin, T. W., Ribi, W. A., Wcislo, W. T., & Warrant, E. J. (2007). Anatomical and physiological evidence for polarisation vision in the nocturnal bee *Megalopta genalis*. Journal of Comparative Physiology A, 193, 591-600.

Herzmann, D., & Labhart, T. (1989). Spectral sensitivity and absolute threshold of polarization vision in crickets: a behavioral study. Journal of Comparative Physiology A, 165, 315-319.

Homberg, U., & Paech, A. (2002). Ultrastructure and orientation of ommatidia in the dorsal rim area of the locust compound eye. Arthropod Structure & Development, 30(4), 271-280.

Horváth, G., & Varjú, D. (2004). Polarized light in animal vision: polarization patterns in nature. Springer Science & Business Media.

Horváth, G. Lerner, A., & Shashar, N. (2014). Polarized light and polarization vision in animal sciences (Vol. 2,). G. Horváth (Ed.). Berlin: Springer.

Islam, M., Freas, C. A., & Cheng, K. (2020). Effect of large visual changes on the navigation of the nocturnal bull ant, *Myrmecia midas*. Animal Cognition, 23, 1071-1080.

Jander, R. (1957) Die optische Richtungsorientierung der Roten Waldameise (Formica rufa L.) Zeitschrift tiir vergMehende Physiologie Bd, 40, 162-238.

Klotz, J. H., & Reid, B. L. (1993). Nocturnal orientation in the black carpenter ant Camponotus pennsylvanicus (DeGeer)(Hymenoptera: Formicidae). Insectes Sociaux, 40, 95-106.

Labhart, T., & Meyer, E. P. (1999). Detectors for polarized skylight in insects: a survey of ommatidial specializations in the dorsal rim area of the compound eye. Microscopy research and technique, 47(6), 368-379.

Lebhardt, F., & Ronacher, B. (2014). Interactions of the polarization and the sun compass in path integration of desert ants. Journal of Comparative Physiology A, 200, 711-720.

Massy, R., & Wotton, K. R. (2023). The efficiency of varying methods and degrees of time compensation for the solar azimuth. Biology Letters, 19(11), 20230355.

Mouritsen, H., & Frost, B. J. (2002). Virtual migration in tethered flying monarch butterflies reveals their orientation mechanisms. Proceedings of the National Academy of Sciences, 99(15), 10162-10166.

Narendra, A. (2007). Homing strategies of the Australian desert ant *Melophorus bagoti II*. Interaction of the path integrator with visual cue information. Journal of Experimental Biology, 210(10), 1804-1812.

Narendra A, Kamhi JF & Ogawa Y. 2017. Moving in dim light: behavioural and visual adaptations in nocturnal ants. Integrative and Comparative Biology, 57, 1104-1116.

Palmer G, Johnsen S. 2015.Downwelling spectral irradiance during evening twilight as a function of the lunar phase. Appl Opt. 54(4):B85-92. doi: 10.1364/AO.54.000B85.

Perez, S., Taylor, O. & Jander, R. 1997. A sun compass in monarch butterflies. Nature, 387, 29. https://doi.org/10.1038/387029a0

Reid, S. F., Narendra, A., Hemmi, J. M., & Zeil, J. (2011). Polarised skylight and the landmark
panorama provide night-active bull ants with compass information during route
following. Journal of Experimental Biology, 214(3), 363-370.
Reid SF, Narendra A, Taylor RW & Zeil J. 2013. Foraging ecology of the night-active bull
ant, Myrmecia pyriformis. Australian Journal of Zoology, 61, 170-177.
Rost, R., & Honegger, H. W. (1987). The timing of premating and mating behavior in a field
population of the cricket *Gryllus campestris L*. Behavioral Ecology and Sociobiology, 21,
279-289.
Smolka, J., Baird, E., el Jundi, B., Reber, T., Byrne, M. J., & Dacke, M. (2016). Night sky
orientation with diurnal and nocturnal eyes: dim-light adaptations are critical when
the moon is out of sight. Animal behaviour, 111, 127-146.
Ugolini, A., Galanti, G., & Mercatelli, L. (2013). Do sandhoppers use the skylight polarization
as a compass cue?. Animal Behaviour, 86(2), 427-434.
Warrant, E., & Dacke, M. (2016). Visual navigation in nocturnal insects. Physiology, 31(3),
182-192.
Wehner R. 2020. Desert Navigator. Cambridge, MA: Belknap Press
Wehner, R., & Müller, M. (2006). The significance of direct sunlight and polarized skylight in
the ant's celestial system of navigation. Proceedings of the National Academy of
Sciences, 103(33), 12575-12579.
Wehner, R. and Srinivasan, M.V. (2003). Path integration in insects. In: Jeffery KJ (ed) The
neurobiology of spatial behaviour. Oxford University Press, Oxford, pp 9–30.
Wittlinger, M., Wehner, R., & Wolf, H. (2006). The ant odometer: stepping on stilts and
stumps. science, 312(5782), 1965-1967.
Wystrach, A., Mangan, M., & Webb, B. (2015). Optimal cue integration in ants. Proceedings
of the Royal Society B, 282(1816), 20151484.
Wystrach, A., Schwarz, S., Schultheiss, P., Baniel, A., & Cheng, K. (2014). Multiple sources of
celestial compass information in the central Australian desert ant *Melophorus bagoti.*
Journal of Comparative Physiology A, 200, 1–11.
Yilmaz, A., Belušič, G., J Foster, J., Tocco, C., Khaldy, L., & Dacke, M. (2024). Polarisation vision
in the dark: green-sensitive photoreceptors in the nocturnal ball-rolling dung beetle
Escarabaeus satyrus. Journal of Experimental Biology, 227(4).
Zeil J, Ribi WA, Narendra A. 2014 Polarization vision in ants, bees and wasps. In Polarized
light and polarization visionin animal sciences, 2nd edn (ed.Gábor Horváth), pp. 41–60.
Berlin, Germany:Springer Series in Vision Research.

736   **Figure Captions**

A — Ambient Angle of Lunar Polarization

Initial Heading · Filter Polarization · 45°

1m · a · Initial Heading · a° · b · b° · 15cm · c · Exit Heading · Reorientation · 1m · d · c°

B — Foraging Tree · N · Nest 1 · Foraging Tree · N · Nest 2

C

Lunar Phases Southern Hemisphere (Sydney, AU)

New Moon · Waxing Crescent · Waxing Quarter · Full Moon · Waning Quarter · Waning Crescent · New Moon

Figure 1. Diagram of the polarisation filter and changes to the overhead lunar polarisation pattern. (A) During the inbound journey, a linear polarisation filter was placed over the forager, rotating the overhead e-vector by ±45°. Panel depicts the positional measurements recorded during testing. Initial orientation routes were measured from the foraging tree release point (a) to when the polarisation filter was placed over each forager (b). Exit orientations were measured from the filter centre (b) to the forager's exit location at the filter edge (c). Route directions under the filter (b°) were calculated from the forager's initial route direction zeroed. Reorientations were measured from the forager's exit location from the polarisation filter (c) to the forager's path 1m after exit (d). Reorientation directions (c°) were calculated from the under-filter route direction zeroed. (B) Images of the sky and canopy cover at both nests. Photos were taken at the on-route midpoint between the foraging and nest trees. Both Nests were located on the edge of tree stands. However, Nest 1 was in a more barren area of the field site, with less vegetation both along the horizonal plane and in the overhead canopy. (C) Lunar phases denote the sunlit part of the moon's surface and where this area is increasing (Waxing) or decreasing (Waning). The lunar phase cycle repeats every 29.5 days. moon images are public domain art accessed through wiki commons (https://commons.wikimedia.org/).

Figure 2. Circular distributions of headings during the original full moon conditions. In both conditions, testing occurs in the nights preceding the full moon (illumination > 80%) with the moon waxing. Circular plot shifts show the exit orientations of individual foragers relative to initial headings while the reorientation represents the change in headings 1m after exiting the filter. Triangles denote the ±45° e-vector rotation. The arrow denotes the length and direction of the mean vector. (*A*) Nest 1 foragers, 5m from the nest (6.0m foraging route). (*B*) Nest 2 foragers, 2m from the nest (3.1m foraging route). *n*, number of individuals; *b*°, mean vector of shift; *c*°, mean vector of reorientation; *r*, length of the mean vector.

Figure 3. Circular distributions of headings during (A) Waxing *Quarter Moon,* (B*) Waxing Crescent Moon* and (C) *No Moon* conditions. Circular plot shifts show the exit orientations of individual foragers relative to initial headings while the reorientation represents the change in headings 1m after exiting the filter. Triangles denote ±45° e-vector rotation. The arrow denotes the length/direction of the mean vector. *n*, number of individuals; *b*°, mean vector of shift; *c*°, mean vector of reorientation; *r*, length of the mean vector.

774
Figure 4. Circular distributions of headings during (A) Waning Full *Moon,* (B) *Waning Quarter*
Moon conditions. Circular plot shifts show the exit orientations of individual foragers relative
to initial headings while the reorientation represents the change in headings 1m after exiting
the filter. Triangles denote ±45° e-vector rotation. The arrow denotes the length/direction of
the mean vector. n, number of individuals; $b°$, mean vector of shift; $c°$, mean vector of
reorientation; r, length of the mean vector.
781

782
783 **Figure 5.** Shift magnitudes for lunar phase conditions at Nest 1. Each circular plot shows the
784 ±45° combined shifts for each condition. Triangles denote +45° e-vector rotation; data from
785 −45° were mirrored and combined). The arrow denotes the length and direction of the mean
786 vector. n, number of individuals; $b°$, mean vector of shift; $c°$, mean vector of reorientation; r,
787 length of the mean vector.

Figure 6. Diagram of collection procedures and circular distributions of *M. midas* headings during *Released Halfway, Collected & Released Halfway* conditions. (A) Foragers in both conditions were tested at 2m from the nest with (B) *Released Halfway* foragers having a long 6.0m vector and (C) *Collected & Released Halfway* foragers having a 3.1m vector. Circular plot shifts show the exit orientations of individual foragers relative to their initial headings while the reorientation represents the change in headings 1m after exiting the filter. Triangles denote ±45° e-vector rotation. The arrow denotes the length and direction of the mean vector. *n*, number of individuals; *b*°, mean vector of shift; *c*°, mean vector of reorientation; *r*, length of the mean vector.

801
802 **Figure 7.** Mean shift magnitudes, +45° and –45° combined, reported as percentages of the
803 45° e-vector rotation (100% = 45°). Vector data for solar polarised light is reported from
804 Freas et al. 2017, Royal Society Open Science. Sun and moon images are public domain art
805 accessed through wiki commons (https://commons.wikimedia.org/).