1 Distributed and convergent representations of tools in human parietal and anterior temporal
2   regions revealed by fMRI-RSA
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Abstract

Classical models of tool knowledge and use are centred on dorsal and ventral parietal
pathways. Theories of semantic cognition implicate a "hub-and-spoke" network, centred on
the anterior temporal lobe (ATL), that underpins all concepts including tools. Despite their
prominence, the two theoretical frameworks have never been brought together and the large
discrepancy in the functional neuroanatomy addressed. We undertook a multiple-regression
Representational Similarity Analysis (RSA) of task fMRI data with four (motor action, broad
function, mechanical function, object structure) feature-based models. The motor action
model correlated with the activation patterns in bilateral superior parietal lobules (SPL), while
the models of broad function and mechanical effect aligned with the activation patterns in
bilateral ATLs. The object-structure model correlated with activation patterns in bilateral
middle occipital gyri. The results also showed that the ventral ATL activation patterns
corresponded simultaneously with all RDM models except object structure. Furthermore, a
standard univariate analysis using tool-familiarity ratings for parametric modulation revealed
that the classical tool-network regions (frontal, inferior parietal, and posterior middle
temporal cortices) were increasingly active as the tool familiarity reduced. These results
demonstrate that parietal and ATL regions are both crucial, and motivate a major extension
and revision of the neuroanatomical framework for tool use.

INTRODUCTION

The ability to understand and use tools is a crucial human ability. When it goes wrong, patients have significant disabilities and everyday challenges. Classical and contemporary frameworks for tool knowledge and use are still centred on the parietal lobe. Utilising multiple methods, convergent evidence has increasingly implicated the anterior temporal lobe (ATL) as a crucial neural area for semantic memory (including knowledge about tools). This area is, however, notable by its absence in most models of praxis and tool use. By utilising dual-echo fMRI that ensures ATL BOLD coverage and representational similarity analysis (RSA), the current paper explored, for the first time, how multiple aspects of tool knowledge are represented in the healthy brain. The results not only reinforce the importance of classical dorsal parietal regions but also heavily implicate the ATL as a major representational hub for multiple aspects of tool knowledge.

The importance of the parietal lobe for tool use was first highlighted in the 19th century via reports of stroke patients with action and pantomime deficits following parietal damage (apraxia; Jackson 1866; Liepmann 1900). The parietal lobe is now widely acknowledged as a critical cortical region for human object use, as revealed by contemporary investigations using neuropsychology, neuroimaging or stimulation methods (Boronat et al., 2005; Canessa et al., 2008; Gross & Grossman, 2008; Ishibashi et al., 2011; Pelgrims et al., 2011). Recent theories implicate two major pathways from visual to motor regions residing in the parietal lobe (Binkofski & Buxbaum, 2013; Buxbaum & Kalénine, 2010; Buxbaum & Randerath 2018). The "dorso-dorsal" pathway is located in the superior parietal lobule (SPL) and the intraparietal sulcus (IPS), and is supposed to compute object-directed actions based on the structural configuration of the object and body. The "ventro-dorsal pathway" streams from the visual MT region and runs through the inferior parietal lobule towards the supramarginal gyrus (SMG), and is argued to be important for more indirect planning of actions incorporating the known function of the objects/tools. This neuropsychologically-derived framework receives some support from fMRI which has shown that the SPL and the anterior IPS are engaged when participants make decisions about the manipulation of tools. In addition, a large number of neuroimaging studies indicate that the left SMG activates for tasks requiring tool recognition and naming (Lewis, 2006; Ishibashi et al., 2016).

In contrast to the two well-studied "dorsal" pathways, the ventral route (i.e. the temporal lobe) has received less attention in human tool use research. Though the left posterior middle temporal gyrus (pMTG) shows consistent activation in tool cognition studies, most of the anterior temporal lobe remains enigmatic (Boronat et al., 2005; Kellenbach et al., 2000; Ishibashi et al., 2016). Therefore, the human brain's "tool network" (Cabrera-Álvarez et al., 2020; Chao & Martin, 2000; Gallivan et al., 2013) often emphasizes the dorsal parietal regions

for computing praxis and the posterior portion of the left temporal cortex for the possible storage of the tool-function knowledge (Reynaud et al., 2016; Lesourd et al., 2021). There are, however, clear indications that the parietal-centric perspective may need substantial revision to incorporate more anterior temporal involvement in tool knowledge and use. First, moving beyond a parietal-stroke model, studies of semantic dementia (SD) from 20 years ago showed not only that knowledge about tools (alongside all other concepts) becomes degraded as a result of the bilateral ATL atrophy, but also that the patients become unable to demonstrate the use of these tools, with degradation of knowledge and declining tool use strongly coupled (Bozeat et al 2003). Comparisons with cortico-basal syndrome (CBS) form a double dissociation between object knowledge and motor skills, as poor knowledge and use of meaningful tools are observed in SD, while ideomotor-type dysfunction is prominent in CBS patients (Hodges et al., 1999). These patient results are mirrored by studies using repetitive transcranial magnetic stimulation (rTMS) in healthy participants (Pobric et al., 2010; Ishibashi et al., 2011) with ATL stimulation leading to transient semantic impairment for all concepts and object-function knowledge, while IPS stimulation generates poorer performance in praxis/tool-specific cognition. Despite these striking results, these past studies are limited in number and have had little impact on theoretical frameworks of tool knowledge and use, and their disorders.

Interestingly, an equivalent situation emerged in the parallel literature on the neural bases of language and its impairments. For many years, the framework for language function was built upon insights from post-stroke aphasia, which highlighted the importance of Wernicke's and Broca's regions and the dorsal pathways between them (though see Weiller et al., 2011). Over the past twenty years, convergent data from functional MRI, cortical electrode explorations, TMS, computational modelling and semantic dementia studies have extended these language frameworks to include ventral pathways and key regions such as the ATL (Ueno et al., 2014; Saur et al., 2008; Lambon Ralph et al., 2017; Mesulam, 2023; Shimotake et al., 2015). Accordingly, the central thesis of this paper is that an equivalent, significant expansion of the framework for human praxis is overdue.

Motivated by these lines of research, we investigated how neural encoding tool-representations extends beyond the parietal-centric regions in neurologically healthy brains. We were especially interested in whether the more anterior parts of temporal lobes are involved in representing any aspects of tool information. The current study made use of two critical technical developments. First, multi-echo EPI techniques for fMRI improve sensitivity within the ATL, which is challenged by multiple factors including its higher magnetic-susceptibility artefact (Halai et al., 2014; Poser and Norris, 2009; Poser et al., 2006; Visser et al., 2009). Secondly, Representational Similarity Analysis (RSA) allows the researcher to go

beyond univariate analysis to investigate local neural coding of different types of
representations from their multi-voxel pattens of activation. We used these opportunities to
tackle, for the first time, the following questions: (a) which brain regions are implicated in
different aspects of tool knowledge such as the body movements for use and their functions
(whole-brain analysis); (b) which aspects of tool knowledge are represented in the classical
parietal-centred 'tool-network' regions (i.e. SPL, SMG and pMTG) and which aspects of tool
knowledge, if any, are supported by the ATL (region-of-interest analyses); and (c) are there
any areas that integrate multiple types of different tool information? Our findings reveal that
(*a*) superior parietal (SPL) and anterior temporal (ATL) regions predominantly represent
tool "action" and "function" information, respectively; (*b*) except for the SPL, the classical
tool-network regions (i.e. SMG and pMTG) do not correlate with any of the examined tool
information; and (*c*) the ventral part of ATL, the acknowledged "semantic hub" region,
integrates various tool-relevant information including both function and action knowledge. In
addition, our data revealed that (*d*) the activation in tool network increases for less common
tools, with the activation pattern exhibiting significant overlap with the semantic-control
network observed in our previous studies.
These findings are in alignment with the semantic hub-and-spoke model where the ATL
'hub' area combine information from other modality-specific 'spoke' regions in the brain
(Lambon Ralph et al., 2017). Considering SPL as the essential spoke area for processing the
motor actions, the current results draw out the comprehensive tool-representative network
on the firm ground of the recent information-based analysis of brain activations for the
recognition and use of common tools.
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RESULTS

Functional-MRI Results: Whole-brain searchlight analysis and ROI analysis

The analysed data were collected in a tool-viewing fMRI experiment designed for this
study. Ninety colour photographs depicting familiar tools (mechanical tools, office/kitchen
utensils, gardening tools, and personal grooming items) were presented to participants during
the fMRI scan (Fig. 1-A). They judged whether each tool is typically used indoors or outdoors.
This task served two purposes: 1) to prevent participants from falling asleep during the scan
and 2) to ensure that the task decision was orthogonal to the tool-information models used in
the Representational Similarity Analysis (RSA). They also rated familiarity of the tools on a
5-point Likert scale (1 = not familiar at all, 5 = very familiar) after scanning. We employed a
multi-regression RSA approach (Kriegeskorte et al., 2008; Nili et al., 2014; Tucciarelli et al.,
2019). Four models were used to represent different types of tool information: broad function
(bF), mechanical function (mF), motor action (A), and object structure (Str). The models
were created based on a normative object use feature study which was part of a previous
investigation of tool knowledge in patients with semantic dementia (Bozeat et al., 2002). The
broad-function model encodes the possible situations that the tools can be used in (e.g.,
gardening, cooking, etc.). The mechanical-function model includes features of the mechanical
purpose each tool can be used for (e.g., cutting, making a hole, etc.). The motor-action model
consists of the elements of hand and arm movements when using each tool (e.g., gripping,
pinching, striking down, etc.). The object-structure model consists of the visible structural
properties of the tool (e.g., rod-shaped, round-shaped, having a joint, etc.). This last model
was expected to serve as a 'control' model to validate the analytical methods by examining the
visuo-perceptual representation in visual cortex. For each of the four models, representational
dissimilarity matrices (RDMs) were calculated and used as predictors of corresponding
dissimilarities in neural activation patterns. We used searchlight method with a mixed-effect
multiple regression model including all the four predictors. Analytic procedure for the whole-
brain searchlight analysis is illustrated in Fig.1-B. The region of interest (ROI) analysis was
conducted in the same way, except that limited number of anatomically defined ROIs were
used to calculate neural RDMs. See Methods for further details of the experimental
procedures and the precise pipeline of the analysis.

Figure 1-A. Schematic image of the behavioural task within the scanner.

Figure 1-B. Illustration of a multiple-regression RSA step for a given searchlight. The
estimated standardized regression coefficients were recorded for the location (centre) of the
searchlight. Note that the actual analysis was conducted on the combined activation-based
RDMs from all the participants. This mixed-effect regression analysis was repeated moving
the searchlight across the whole brain to yield the coefficient map for each model.

Fig.2 shows the results of the whole-brain searchlight analysis. The two function-
knowledge model, broad-function as indicated in green and mechanical-function shown in
light blue, had high correlations mostly within the bilateral temporal lobes, with largest
clusters at the anterior temporal lobes. The motor-action model (yellow) highlighted some
parietal areas including bilateral superior parietal lobules and the right inferior parietal lobule.

It also had high correlation with the activation patterns in the right inferior temporal gyrus
and the left ATL. The object-structure model had high correlation in the bilateral occipital
regions, roughly corresponding to the secondary visual cortex. The local maxima of the
significant clusters for the four feature models are listed in Supplementary Tables 1A-D.

The ROI analyses built on the searchlight results and allowed us to focus on key areas
implicated in the classical praxis frameworks as well as the hub-and-spoke semantic model.
Fig.3 show the results of the ROI analyses, dividing the ROIs by existence/absence of a
significant effect of any of the four models. Fig.3-A shows that bilateral SPLs (involving the
upper bank of IPS) had significant similarities with the motor-action model, the ATLs had
correspondence with broad-/mechanical-function models, and the middle occipital gyri
activates in high similarity with the object-structure model. The right SMG also had a
significant correspondence with the structure model. The left SMG and the bilateral pMTGs,
as indicated in Fig.3-B, had no significant similarity in their activation patterns with any of
the four feature models.

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Figure 2. Results of the whole-brain searchlight analysis. Voxel-wise threshold was set at
uncorrected p<0.001. Cluster-extent threshold was applied for each model map with an FDR-
corrected threshold for p<.05. The minimum size of significant cluster was 43, 46, 49, and 42
voxels for the broad-function, mechanical-function, motor-action, and object-structure
models, respectively.

While the strongest contrast was observed between action and function models, the
distribution of the significant clusters for each model gives important additional insights.
Motor-action information was not exclusively represented in the parietal regions of the brain,
but also represented in the bilateral temporal lobes. Some bilateral temporal areas also showed
similarity to the motor-action model, making anterior parts of bilateral ATL the most probable
overlapping areas across models. Accordingly, we conducted a conjunction analysis to confirm
if any area represents both function and action types of tool knowledge (i.e., similarity to the
first three models). Four clusters were found significant (Fig.4-A, Supplementary Table 2).

The largest cluster locates within the left ATL extending into left inferior frontal gyrus (see
Fig.4-B for the confirmation of regression results at the peak-ATL searchlight). The right ITG
(covering the caudal ATL and fusiform gyrus), left insula and cerebellum were also detected
as showing significantly similar activation patterns across the three tool-knowledge models.
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213 Figure 3-A. Regression coefficients for anatomical ROIs with significant positive effect by at
214 least one of the four models. (bF: broad function, mF: mechanical function, Act: motor action,
215 Str: object structure. ***:p<.001, **:p<.01.*:p<.05)
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Figure3-B. Regression coefficients for anatomical ROIs with no significant positive effect by

any of the four models. (bF: broad function, mF: mechanical function, Act: motor action,

Str: object structure. All ps>.05)

Figure 4. A) Areas with representational similarities to all three types of tool information.

Cluster-extent threshold was applied for each cluster with the FDR-corrected threshold for

p<.05. The minimum size of significant cluster was 39 voxels. The white dot and circle

indicate the location of the voxel with the peak T value and its corresponding searchlight in

the left ventral ATL. B). Estimated weights of the four regressors at the peak searchlight

from the conjunction analysis. Grey stars at the top indicate the level of statistical

significance. Note that significant tendency at the level of p<.10 is obvious for the first three

regressors by the nature of this analysis. The bar plot and the statistical results are presented

here for confirmatory purpose. ***: p<.001, **: p<.01

bF: broad function, mF: mechanical function, Act: motor action, Str: object structure.

Functional-MRI Results: effects of tool familiarity across the tool-network activation

The univariate task-related activations (Fig. 5-A top row, left) revealed the typical fronto-
parietal and occipito-temporal 'tool-network' areas found in previous studies and ALE meta-
analyses (Chao & Martin. 2000; Federico et al., 2023; Ishibashi et al., 2016; Lewis 2006; Wang
et al., 2018). These same areas were also observed in the map of areas where activation
correlated with the degree of unfamiliarity with each tool (i.e. more activation for less familiar
tools; Fig. 5A second row, left). As these same areas have been implicated in semantic-
executive control, we compared them directly with the results from previous work on semantic
and domain-general control (Humphreys et al., 2017). There was striking resemblance
including the left pMTG/occipito-temporal cortex, SMG, and bilateral frontal/prefrontal
regions (Fig. 5-B, left). The overlap in the posterior pMTG also corresponded to the location
of common activation for semantic activation and tool cognition indicated by a recent large-
scale meta-analysis (Hodgson et al., 2023; Fig.5-B in the enlarged view).

The reverse contrasts indicated that the regions positively correlated with tool familiarity
were the dorsal medial prefrontal cortex (mPFC), posterior cingulate cortex (PCC), and
bilateral angular gyri (AG) —typical task-negative areas which deactivate in various cognitive
tasks, including the current fMRI task (Fig. 5-A right). There were also some familiarity-
correlated activations in bilateral lateral ATLs, which are also sometimes a subcomponent of
the task-negative network (Buckner et al., 2008; 2019; Jackson et al., 2019; Menon et al.,
2023) and tend to show enhanced deactivation in line with increasing task demands
(Humphreys et al., 2015). In line with this result, there was a strong correspondence (Fig. 5-
B, right) of the familiarity-positive activation correlation map from this study with the task-
negative activation for non-semantic tasks observed in a previous multi-experiment study
(Humphreys et al., 2015), including overlap in the medial prefrontal-parietal regions (mPFC,
PCC), bilateral AG, and bilateral lateral ATLs.

Figure 5. Mass-univariate activation maps. A) task-related base activation (top) and its

parametric modulation by unfamiliarity of the presented tool (bottom); B) Overlays of the

parametric modulation maps with other results from previous studies on general/semantic

executive demands (left) and on the task-negative activation.

Maps in panel A are all thresholded at a cluster-forming threshold of p<.001 and then small

clusters were removed based on FWE-corrected cluster-extent threshold of p<.05. In panel

B, the activation maps were thresholded at p<.05 for exploratory purpose. The Rest>Non-

Semantic contrast was thresholded at p<.005 for its relatively large sample size (N=69).

Clusters smaller than 25-voxel size are not shown for the sake of brevity. TN: Task-Negative.

DISCUSSION

Classical and contemporary frameworks for tool knowledge and use are still centred on the
parietal lobe. By utilising contemporary fMRI acquisition methods and analytics, the current
study was able to investigate, for the first time, how multiple aspects of tool knowledge are
represented in the healthy brain. The results not only reinforce the importance of classical
dorsal parietal regions in human praxis but also heavily implicate the ATL as a major
representational hub for multiple aspects of tool knowledge, and suggest that a significant
extension of the classical model of object use is necessary; changes that parallel those found
in contemporary models of language and semantics. We consider below how the relationship
of the current results to: (i) classical models of praxis in the dorsal parietal cortex; (ii) the
striking multifaceted contributions of the ATL to tool knowledge and use; and (iii) the role of
posterior lateral temporal and inferior parietal regions in object tool use.

SPL and the dorso-dorsal pathway: Consistent with the classical dual-route theory, we found
that SPL/IPS activation was correlated with the motor action RDM. This region is known as
the where/how pathway in visual information processing, and is thought to perform planning
of hand-object interactions from visual information (Goodale & Milner, 1992; Goodale et al.
2005). Cortical damage in SPL/IPS causes deficient object-directed actions including
dysfunctional reaching and grasping (Binkofski et al., 1998; Cavina-Pratesi et al., 2013;
Karnath & Perenin, 2005; Perenin & Vighetto, 1988). As the motor action RDM consists of
features of the grip and arm movements for tool use, the present results suggest that body-
movement for tool use is indeed calculated/represented in the bilateral SPL/IPS regions.
Corroborating this view, a recent study found successful decoding of planned grasp type from
activation in both right and left anterior IPS (Michalowski et al., 2022), and activity in bilateral
IPS during planning tool-use has been found to increase with the complexity of manipulating
each tool (Ras et al., 2022). Some clinical studies also suggest that the SPL contributes tool-
manipulation knowledge, as SPL-damaged patients struggle to show canonical manipulation
of common tools without agnosia on the tools (Valério et al., 2021; Peigneux et al., 2001).

The importance of the ATL semantic hub: perhaps the most striking aspect of the current
study was the importance of the ATL in the representation not only of two forms of tool
function knowledge but also of motor actions (indeed, only visual form similarity did not
engage the ATL). Furthermore, the ATL was also one of the only regions that jointly
represented these three different aspects of tool knowledge. Though the ATLs have never
been explicitly integrated into the models of human tool use, our results provide clear evidence
that the integration is necessary; in the same way that the ATL has been integrated into

contemporary models of language and semantics (Chen et al., 2017; Frisby et al., 2022;
Lambon Ralph et al., 2017; Mesulam, 2023; Patterson et al., 2007). The absence of the ATLs
from models of praxis (and previously language) probably reflects the neuropsychological
origins of the classical models which were founded on the study of patients after MCA stroke.
The middle-to-inferior aspects of the ATLs are in the watershed between the MCA and PCA
(Lambon Ralph et al., 2017; Phan et al., 2005; Zhao et al., 2020), and thus unlikely to be
damaged after embolic stroke (and even less likely to produce bilateral ATL damage, which is
the atrophy distribution in semantic dementia: Ding et al., 2020; Rouse et al., 2024). The RSA
results fit precisely with previous investigations of ATL and IPL using TMS (Ishibashi et al.,
2011: Pobric et al., 2010) and most directly with past explorations of tool knowledge and use
in SD patients, which showed parallel degradation of semantic knowledge of tools (as a part
of their generalised semantic deficits) and impaired object use (Bozeat et al., 2000; 2002;
Coccia et al., 2004; Hodges et al., 1999; 2000).

The discovery of ATL involvement in tool-representation is also consistent with the
semantic hub-and-spoke model of semantic cognition (Lambon Ralph, 2017). The framework
posits that the bilateral ATLs serve as a modality-general 'hub', integrating multimodal
information over time to build generalisable conceptual knowledge (Lambon Ralph et al.,
2010; Jackson et al., 2021). Indeed, the convergence of multiple forms of tool knowledge into
the ATL also fits with recent decoding results from cortical grid electrode recordings which
showed that the ATL does not simply represent various semantic dimensions separately but
actually encodes them simultaneously to form a unified semantic space (Cox et al., 2024).

Neuroanatomically, ATL involvement in praxis may also seem somewhat surprising given
its distance from other tool-related cortical areas. Although the cortical distances between
ATL and SPL are large (almost as large as they can be within the same hemisphere), they have
direct white-matter connectivity allowing fast, efficient communication and emergent
functional interactions. Human and non-human primate tractography studies have found that
the superior ATL and inferior parietal cortices are connected along the middle longitudinal
fasciculus (Menjot de Champfleur et al., 2013), then extending beyond AG up to the SPL
(Wang et al., 2013; Markis et al., 2013). In parallel, the inferior longitudinal fasciculus (ILF)
not only connects the temporal pole with occipital visual areas (Tusa & Ungerleider, 1985;
Catani et al., 2003) but also branches at the ventral occipito-temporal area to ascend, medially,
into the dorsal parietal cortex, in both non-human primates (Selzer & Panja 1984;
Schmahmann & Pandya, 2009) and humans (Lang et al., 2017). Whether this ascending
parietal branch should be regarded a part of ILF remain controversial (Mandonnet et al., 2018;
Bullock et al., 2022), however it is quite possible that neurons in the SPL and ATL are
connected directly via midLF, or through a single intermediating region at the occipito-

temporal region.

Temporoparietal and ventro-dorsal pathway contributions: The null RSA results for the left
pMTG and SMG are potentially puzzling given that these regions are frequently noted in tool-
use/recognition (univariate) fMRI studies, as well as being a key area of damage in ideational
apraxia (Goldenberg & Spatt, 2009; Goldenberg & Randerath, 2015; Hodgson et al., 2023;
Ishibashi et al., 2016). There are at least two possible explanations. The first is insufficient
statistical power in the MVPA analysis, although the additional univariate analysis with the
same data revealed two important findings: (1) both the pMTG and SMG were activated by
the tool decision task, and (2) these two regions, along with the inferior frontal gyrus (IFG),
responded more strongly to the least familiar tools. In keeping with these results, the second
possible explanation is that these regions (along with PFC) support semantic control (Jackson
et al., 2021; Jackson, 2021; Lambon Ralph et al., 2017); a conclusion supported by convergent
evidence from fMRI, rTMS and neuropsychology (Hallam et al., 2016; Jefferies, 2013;
Whiteney et al., 2011; 2012). In fact, patients with damage to these brain regions not only
show multimodal semantic control deficits (semantic aphasia: Jefferies & Lambon Ralph,
2006; Jefferies et al., 2008; Noonan et al., 2013; Thompson et al., 2022) but also present with
ideational apraxia (Corbett et al., 2009a, 2009b; 2011; 2015).

The reason why tool cognition and semantic control align in these same regions (see Fig.
5; and also recent large-scale ALE examinations: Hodgson et al., 2023) is not fully understood.
It is possible that some executive planning is required or automatically triggered in the
recognition of tools. Multiple recent reviews on the neural mechanisms of human tool use
argue that tool use is not simply the recall of movement information stored for each tool, but
rather a compositional process for integrating relevant physical information of the tool and
expected target objects for a desired goal state (technical-reasoning hypothesis; Jarry et al.,
2013; Osiurak & Badets, 2016; Lesourd et al., 2021). Although this account has focussed on
the role of left SMG, the required executive process for tool-use 'reasoning' is likely to require
contributions from multiple multi-demand and semantic control areas beyond SMG alone.

Conclusion: the adoption of RSA and multi-echo fMRI shows that the cortical areas implicated
in human tool cognition and use go beyond the classical parietal-centric dorso-dorsal and
ventro-dorsal pathways. A more comprehensive account is needed, in which the classical
framework is extended to include the ATLs' essential role in representation of multiple aspects
of tool knowledge, plus the support of the FTP semantic-control network for controlled, goal-
directed tool-use actions.

METHODS

Materials

We based our selection of tool stimuli on the neuropsychological study by Bozeat et al. (2002). The study examined tool-relevant cognitive performance of patients with semantic dementia utilizing a set of 90 different tools. We collected visual photo images of the corresponding 90 tools and used them for the present experiment (see Supplementary Table 3). Each collected image was converted to a 24-bit bmp file and then scaled to fit into the same image dimensions (400 × 300 pixels) using Windows Paint software.

Participants

We recruited 22 graduate/undergraduate students in the University of Manchester. Their age range was 18-30 years (Mean 21.9; SD = 3.2). All had normal or corrected-to-normal vision and were right-handed (mean score in Edinburgh Handedness Inventory was +89.0). They gave their informed consent before taking part in this study and were reimbursed for their time. Two of them had to cancel their participation during the experiment (one at their will, another for a technical problem with the MRI scanner). Data from another participant had irreversible error (mixed-up slices) detected right after the recording. We therefore used data from the other 19 participants in the following analyses.

Experimental Procedure

Participants were engaged in visual recognition of tools while lying supine in the MRI scanner (Fig.1). The stimuli were presented with a projector system and seen in a mirror attached to the head coil. To make sure that the participants attend to the meaning of each stimulus, they were asked to judge whether the tool is used indoors or outdoors, and reported their decisions by pressing a button on a response box in their right hand. The responses were made using their right index and middle fingers. The assignment of buttons to the two (indoor/outdoor) categories was counterbalanced across participants. Each of the 90 stimuli appeared only once in a session and stayed on the screen for 1.2 seconds regardless of their responses. A fixation cross on a grey background was presented when no stimulus is presented. The interval time between stimulus presentations were determined in advance using Optseq program (Dale, 1999; https://surfer.nmr.mgh.harvard.edu/optseq/) for each session. The intervals were set to range between 3.5-9.3 seconds by the minimum steps of 250ms and to have the mean of 4.8 seconds. The average stimulus onset asymmetry (SoA) was hence 6.0 seconds. A 16-second interval was added at the beginning and the end of each session to accommodate extra margins for the baseline. We used E-Prime software (Psychology Software Tools inc.) to implement the presentation of stimuli and the recording of the participants' responses.

Participants performed the task in 5 sessions (approximately 55 minutes in total with in-

scanner breaks between sessions) with functional scanning, following an initial scanning of

the structural T1 data of their brain (about 5 minutes). Before entering the scanner, they

practised the task on a laptop PC. All stimuli appeared just once in the practice session with

the tool name shown below the image. This was to enhance their correct recognition of these

images. After all sessions in MRI scanner, the participants were asked to provide a familiarity

rating for each tool on a Likert scale between 1 ("not at all") and 5 ("very"). This rating task

was conducted to confirm the familiarity of the tools across participants and to establish

inclusion/exclusion of the tools in the main analysis: only tools with a familiarity rating>4.0

(on average) were included in the later RSA analysis in order to ensure that representational

analyses were based on items that participants knew well. The rating resulted in 22 of 90 items

having the mean familiarity <4.0. We used all items in a subsequent parametric-modulation

analysis of the effect of familiarity in these task fMRI data (see below). The accuracy of the

indoor/outdoor judgments on the included 68 items (58 indoor, 10 outdoor tools) was very

high: 91.8% (SD=2.8). The mean response time was 749.9ms (SD=48.6).

Image Acquisition with Dual-Echo fMRI sequence

We used a dual-echo sequence with 12ms and 35ms echo times for data acquisition (Halai

et al., 2014; 2015). This method helps to reduce the effect of signal-dropouts at the basal parts

of anterior temporal lobes and orbitofrontal cortex. Because tissues with heterogeneous

magnetic susceptibility (e.g. cortex, bone, air) lie in close vicinity in these areas, canonical

fMRI protocols with single echo time of around 35ms create large distortions in these regions.

Given that signal dropout increases with echo time, the shorter of the dual echoes provides

better signal recovery in these challenging areas, whilst the greater SNR of the longer echo

time for other brain areas is retained (Halai et al., 2014; 2015). Thus we adopted this

acquisition method for our experiment.

Preprocessing

The preprocessing steps followed the method established in previous dual-echo fMRI

studies (Halai et al., 2014; 2015). The short-echo and long-echo images were re-aligned to

the first volume in each session and then the signals were combined using a simple average at

each voxel. The combined data were then passed to the subsequent pre-processing steps on

the Statistical Parametric Mapping software (SPM8, https://www.fil.ion.ucl.ac.uk/spm/),

which included slice-timing correction to the first (bottom) slice in each volume,

coregistration of the first EPI volume with individual T1 image, and normalisation using

DARTEL algorithm (Ashburner, 2007). No smoothing was applied to the data as the main

purpose of this study is to explore multi-voxel patterns.

Preparation for RSA: Univariate Analysis for Estimating Tool-Wise Activation Patterns

Voxel-wise GLM analysis was conducted using SPM8. We adopted a Condition-Rich

design (Kriegeskorte et al., 2008) to model the BOLD signals at each voxel, setting each of

the 90 stimulus as a different condition. Participants' key-presses were modelled as an

additional single 'responses' condition. Six volume-realignment parameters (6 parameters)

from the preprocessing were also added to regress out the head-motion noise. We also applied

a high-pass filter of 128 seconds to remove low-frequency noise at each voxel. After estimating

weights for all regressors, we calculated subject-wise contrast images for each of the 90 stimuli

versus implicit rest. Excluding activation maps for the low-familiarity tools, a set of 68 × 19

contrast images were created as the target data for the following RSA analysis.

Multi-Voxel RSA with Linear Mixed-Effect Regression

We adopted a multi-regression RSA approach (Kriegeskorte et al., 2008; Nili et al., 2014;

Tucciarelli et al., 2019). Four models were used to represent different types of tool

information: broad function (bF), mechanical function (mF), motor action (A), and object

structure (Str). The models were created based on a normative object use feature study which

was part of a previous study on investigation of tool knowledge in patients with semantic

dementia (Bozeat et al., 2002). These models consisted of codes on the existence (1) or

absence (0) of certain features on each of the 90 tool stimuli, providing a binary-code vector

for each tool concept. The "broad function" of tools indicated the possible situations each tool

can be used in. The "mechanical function" model (mF) involves a short description of

mechanical purpose which each tool can be used for. The "motor action" model consists of

the types of hand and arm movements involved in using each tool. The "object structure"

model consists of visible structural properties of the tool. For each of the four models, cosine

similarity was calculated for each pair of tools and then 1-cos was used as the model's

representational dissimilarity matrix (RDM). The object structure model was involved in the

analysis as a 'control' regressor. It was expected to prove the quality of the data and validity of

the analytical procedure by showing high correlation in the occipital visual cortex.

We conducted both whole-brain and region-of-interest (ROI) analyses. In the whole brain

analysis, we used a searchlight method with a linear mixed effect model (LME) analysis. The

group-level mask image calculated from DARTEL processing was used as the area to explore.

A spherical searchlight with 9mm radius (involving 123 voxels) around each voxel was used

to extract the multi-voxel patterns. Pearson's correlation coefficients (r) across the tool stimuli

were calculated and 1-r was used as the activity-based RDM. We conducted a mixed effect

multiple-regression analysis with the upper triangular part of the activation-based RDM as

the dependent variable and those of model RDMs as explanatory variables (see Fig.2).

Weighting of the four regressors were thus estimated for each searchlight location. This step

was repeated for the search light across the whole brain. We created four T-value maps for the

four model regressors, truncated them with uncorrected voxel-wise threshold of $p<.001$ and

applied cluster-extent thresholding of p<.05 corrected for FDR to detect significant clusters.

Only positive values were mapped and considered legitimate targets of significance tests in

this RSA.

In the ROI analysis, we examined five anatomical ROIs in both hemispheres: two ROIs in

parietal lobe (SPL, SMG), two in temporal lobe (ATL, pMTG), and one at the middle

occipital gyrus (MOG). The parietal ROIs were chosen as the representative parts in the

dorsal (dorso-dorsal and ventro-dorsal)pathways and the temporal ROIs as the representative

parts along the ventral pathway. The MOG was chosen as a control region to examine the

correspondence between low-level visual features (i.e. object-structure model) and the

activation patterns in the visual cortex. We used WFU pick atlas (Maldjian et al., 2003) and

AAL3 (Rolls et al., 2020) toolboxes to define four of the five ROIs. The ATL mask for a

previous meta-analysis for temporal-lobe activation in fMRI studies (Rice et al., 2015) was

utilised as the ATL-ROI. Regression analysis was conducted on the activation-based RDMs

in each ROI. As in our searchlight analysis, only positive weights were considered targets of

significance tests in this analysis.

Following these two analyses, we also conducted a conjunction analysis on the results of

the models in the searchlight analysis. As we were interested in where the various semantic

components are combined, the conjunction analysis was applied for the results of the first

three models excluding the object structure (i.e., broad function, mechanical function and

motor action) excluding the control model (object structure). The three T-maps were

combined taking the minimum T statistics at each voxel. Significance tests were performed

the same way as in the searchlight analysis. A voxel-wise threshold of α <.001 was first applied

on each voxel (equivalent to p<.001 for the combined T map, i.e. p<.10 for each model).

Cluster-extent threshold of p<.05 was then applied with FDR correction for the number of

detected clusters.

Univariate Analysis with Tool-Familiarity as Parametric Modulator

To examine the general task-related activation in this study and its correlation with the

level of the participants' tool knowledge (i.e., rated familiarity on the stimuli), we also

conducted a univariate activation analysis on the same pre-processed data using each tool's

mean familiarity as a parametric modulator. All tool-presentation events were combined into

a single "Stimulus" condition. Stimulus-wise mean familiarity values were added into the

design matrix as a parametric modulator of the stimulus-evoked activation. The participants'

key-presses were also included in the model as a regressor of no interest. Both positive and

negative contrasts were calculated for the base activation (task-positive/task-negative) maps

and for the parametric-modulation (familiarity-/unfamiliarity-correlated) maps. The group-

level activation maps were computed for each contrast and voxel-wise significance was tested

using one-sample t test. Images were thresholded at a cluster-forming threshold of p<.001

and then small clusters were removed based on FWE-corrected cluster-extent threshold of

p<.05. The results were compared with the results of our previous fMRI/meta-analysis studies

reporting Semantic-/Executive-Control and Task-Negative networks (see also the caption of

Fig.5).

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Notes on FWHM estimation:

The FWHM for cluster-extent thresholding was estimated based on a simulation of

spatial auto-correlation between neighbouring voxels. We utilised the ratio of shared

number of voxels between two neighbouring searchlights in the current setting (94 of 123

voxels in a single searchlight). On a MATLAB-R2022b platform, we first generated random

Gaussian noise in an array of 123 $\times$ 68 cells. For each array, 29 $\times$ 68 cells were updated

by another Gaussian-noise simulation keeping 94 $\times$ 68 of them unchanged. The 68-by-68

RDM was calculated for the original and the updated arrays, and then the upper-triangle

part was extracted as a vector from each. These steps were repeated 19 times to simulate the

noise data from 19 virtual participants. Then, the vectors were concatenated to create a

single error vector for the original and updated vectors, respectively. This was to simulate

the number of datapoints for the current multiple-regression RSA. The correlation between

the original and updated error vectors were then calculated as an index of simulated pure-

noise-based autocorrelation between a pair of neighbouring searchlights. The entire above

procedure was repeated 10,000 times to simulate distribution of correlation values in

multiple pairs of searchlights, and the average $r=0.761$ (SD=0.0031) was taken as the

theoretical spatial autocorrelation between neighbouring datapoints in the current whole-

brain analysis. The in-house script for this simulation is available upon request to the

corresponding author.

Supplementary materials

Supplementary Table 1: Clusters with significant extent with p<.05 corrected for the

number of detected clusters. Labelling is based on AAL3 atlas (Rolls et al., 2020). In the

cases where the coordinates do not precisely locate within the labelable volume in AAL3, the

closest anatomical structure was judged by the authors.

Supplementary Table 1-A. Broad Function

cluster no.	size	p-val (cluster)	label	MNI coordinates			T-Val	p-val (voxel)
				x	y	z		
1	684	1.25E-12	PHG, R	21	3	-30	7.035695	2.01E-12
			ATLsup, R	51	9	-12	6.021222	1.74E-09
			OFCpost, R	36	24	-27	5.896813	3.73E-09
2	406	3.91E-09	ATLmid, L	-36	12	-33	6.277258	3.48E-10
			Insula, L	-24	12	-18	4.90693	9.28E-07
			ATLsup, L	-45	6	-15	4.627445	3.71E-06
3	213	3.40E-06	SFGmedial, R	9	33	39	7.338632	2.20E-13
			SFG, R	15	42	57	4.457818	8.30E-06
4	193	7.57E-06	STG, L	-51	-18	3	5.851103	4.92E-09
			Insula, L	-33	-21	3	4.710975	2.47E-06
5	172	1.81E-05	Cerebellum, L	-18	-54	-66	7.491916	6.92E-14
			Cerebellum, R	3	-51	-66	4.80879	1.52E-06
6	104	0.0004064	MFG, R	36	27	39	6.198857	5.74E-10
7	97	0.0005793	OFCmed, L	-3	72	-3	6.416437	1.41E-10
8	80	0.0014226	Cerebellum, R	12	-93	-27	5.897382	3.72E-09

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 Supplementary Table 1-B. Mechanical Function

cluster no.	size	p-val (cluster)	label	MNI coordinates			T-Val	p-val (voxel)
				x	y	z		
1	353	2.19E-08	MTG, L	-57	-3	-21	5.224254	1.76E-07
			PHG, L	-30	-3	-30	5.020742	5.17E-07
			OFCpost_L	-24	18	-21	4.765473	1.89E-06
2	234	1.50E-06	Cerebellum, L	-9	-54	-54	5.755369	8.70E-09
			Cerebellum, R	12	-54	-60	4.866502	1.14E-06
3	145	5.86E-05	ATLmid, R	57	12	-30	5.341671	9.26E-08
			ATLmid, R	39	-3	-27	4.518193	6.25E-06
4	132	0.0001059	MTG,L	-48	-36	-3	5.050767	4.42E-07
			OCCinf, L	-39	-60	-9	4.741597	2.13E-06
			ITG, L	-60	-48	-18	3.744445	0.000181
5	109	0.000317	CaudNuc. R	18	3	18	4.70877	2.50E-06
			thalamus, R	15	-21	12	4.242927	2.21E-05
6	95	0.000642	SMA, L	-6	24	66	4.900668	9.59E-07
7	86	0.0010291	ITG,R	42	-45	-9	5.254866	1.49E-07
8	60	0.0044661	Ptamen, R	27	-15	-6	4.624924	3.76E-06
9	55	0.0060587	Cerebellum, L	-33	-42	-42	4.661304	3.15E-06
10	51	0.0077847	PostCentral, R	18	-33	78	4.115608	3.87E-05
			SMA, R	9	-15	72	3.612443	0.0003037
11	48	0.0094357	SN, R	9	-9	-9	5.507887	3.65E-08

570 Supplementary Table 1-C. Motor Action

cluster no.	size	p-val (cluster)	label	MNI coordinates			T-Val	p-val (voxel)
				x	y	z		
1	360	1.74E-08	SPL, R	27	-51	66	6.242261	4.35E-10
			AG, R	60	-66	33	5.464899	4.66E-08
			SPL, R	27	-69	63	5.126224	2.97E-07
2	328	5.10E-08	Precuneus, L	-18	-45	48	6.694631	2.19E-11
			Precuneus, R	12	-54	45	5.128943	2.93E-07
			CingulateMid, R	9	-24	39	4.996337	5.87E-07
3	228	1.89E-06	ATLinf, R	57	-15	-33	6.552504	5.72E-11
			ITG, R	45	-18	-15	4.797225	1.61E-06
4	157	3.45E-05	MFG, R	42	48	-6	6.203247	5.58E-10
5	145	5.86E-05	ATLinf, R	30	6	-48	9.301928	1.44E-20
6	100	0.0004971	OFCmed, L	-15	24	-18	6.723004	1.80E-11
			ATLsup, L	-21	12	-33	4.793944	1.64E-06
7	93	0.000712	SFG, L	-21	27	45	6.206962	5.45E-10
8	86	0.0010291	Cerebellum, R	24	-57	-30	5.062486	4.16E-07
			Cerebellum, R	39	-42	-30	4.858799	1.19E-06
9	77	0.0016777	Cerebellum, L	-48	-45	-45	6.156934	7.48E-10
			Cerebellum, L	-30	-42	-45	5.167318	2.39E-07
10	76	0.0017734	PreCentral, R	15	-15	78	5.796587	6.81E-09
11	57	0.0053572	Cerebellum, R	54	-63	-39	5.649143	1.62E-08
12	50	0.0082966	SPL, L	-18	-48	78	4.767743	1.87E-06

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573   Supplementary Table 1-D. Object Structure

cluster no.	size	p-val (cluster)	label	MNI coordinates			T-Val	p-val (voxel)
				x	y	z		
1	701	7.94E-13	OCCmid, L	-36	-78	0	10.11955	4.81E-24
			Fusiform, L	-36	-30	-27	6.557123	5.55E-11
			Lingual, L	-24	-63	-9	6.539894	6.22E-11
2	403	4.31E-09	Fusiform, R	33	-69	-3	7.547999	4.51E-14
			OCCmid, R	36	-69	27	7.218718	5.33E-13
3	270	3.93E-07	SMG, R	54	-33	42	7.911361	2.61E-15
			IPL, R	36	-45	51	6.253668	4.05E-10
4	164	2.55E-05	SFG, L	-24	0	45	8.479464	2.33E-17
			PreCentral, L	-42	3	45	6.734239	1.67E-11
			SMA, L	-9	-18	57	4.992063	6.00E-07
5	105	0.0003866	Insula, L	-30	21	0	6.701249	2.09E-11
6	98	0.0005504	PostCentral, R	18	-39	51	5.963926	2.48E-09
7	93	0.000712	MTG, R	48	-39	-9	6.563608	5.31E-11
8	91	0.0007903	STG, R	48	-54	21	7.118374	1.11E-12
9	87	0.0009758	SPL, L	-21	-57	42	7.238483	4.61E-13
10	58	0.0050402	ParsTri, R	57	39	15	5.137714	2.79E-07
11	52	0.0073075	ParsOper, L	-48	15	18	6.000751	1.98E-09
12	51	0.0077847	PreCentral, L	-33	-21	57	6.417862	1.40E-10

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576   Supplementary Table 2. Conjunction across three models (broad/mechanical function,
577   motor action)

cluster no.	size	p-val (cluster)	label	MNI coordinates			T-Val	p-val (voxel)
				x	y	z		
1	146	5.603E-05	OFCpost, L	-24	21	-27	3.273167	0.0010643
			ATLinf, L	-42	6	-33	3.025974	0.0024798
			Putamen, L	-15	9	-12	2.501458	0.012372
2	88	0.0009254	Cerebellum, R	9	-51	-60	2.804335	0.0050443
3	73	0.0020974	ITG, R	57	-18	-24	3.382253	0.0007196
4	58	0.0050402	Putamen, R	36	-9	0	3.597909	0.0003211

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580   Supplementary Table 3.

581   FeatureModels.xlsx: Bozeat's semantic features for the 90 common tools

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