Trait genetic architecture and population structure determine model selection for

genomic prediction in natural *Arabidopsis thaliana* populations

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Article summary

Machine learning and linear models were tested for genomic prediction of multiple traits in the

model plant *Arabidopsis thaliana*. We associate the performance of genomic prediction models

to trait ontology, finding machine learning approaches applicable to biochemical traits, and linear

models best for macroscopic traits. We link this result to the genetic architecture of each trait and

patterns of selection in the association panel's ancestral population, thus underscoring the

relevance of these two sensitivities to genomic prediction in plant breeding.

Abstract

Genomic prediction applies to a wide range of agronomically relevant traits, with distinct ontologies and genetic architectures. Selecting the most appropriate model for the distribution of genetic effects and their associated allele frequencies in the training population is crucial. Linear regression models are often preferred for genomic prediction. However, linear models may not suit all genetic architectures and training populations. Machine Learning approaches have been proposed to improve genomic prediction owing to their capacity to capture complex biology including epistasis. However, the applicability of different genomic prediction models, including non-linear/non-parametric approaches, have not been rigorously assessed across a wide variety of plant traits in natural outbreeding populations. This study evaluates genomic prediction sensitivity to trait ontology and the impact of population structure on model selection and prediction accuracy. Examining 36 quantitative traits measured for 1000+ natural genotypes of the model plant *Arabidopsis thaliana*, we assessed the performance of penalised regression, random forest, and multilayer perceptron at producing genomic predictions. Regression models were generally the most accurate, except for biochemical traits where random forest performed best. We link this result to the genetic architecture of each trait – notably that biochemical traits have simpler genetic architecture than macroscopic traits. Moreover, complex macroscopic traits, particularly those related to flowering and yield, were strongly correlated to population structure, while molecular traits were better predicted by fewer, independent markers. This study highlights the relevance of machine learning approaches for simple molecular traits and underscores the need to consider ancestral population history when designing training samples.

1.   Introduction

In plant breeding, genomic prediction can apply to any agronomically relevant traits form yield, to phenology, metabolite concentrations or the response to stresses, which all have different genetic basis. Heritable traits, whether simple and controlled by a few loci, or complex and controlled by many variants, can be predicted based on the information from dense, genome-wide markers. Genomic prediction models are often fitted to training populations designed to maximise diversity, including genotypes with varying levels of co-ancestry and different evolutionary histories (Fodor et al., 2014). Therefore, critical in genomic prediction is the choice

of a model that most adequately factors population's allele frequencies and the distribution of

genetic effects for each particular trait.

The number of genome-wide markers (p) being typically much larger than the number of

individual observations (n), overfitting is a major challenge in genomic prediction. A common

solution is to use penalised linear regression models (Meuwissen et al., 2001). Penalised

regression reduces overfitting by shrinking the effect of each marker. Most penalisation

functions assume a prior distribution of the marker effects, which relates to the trait's assumed

genetic architecture. Linear models also assume that genetic factors influence the phenotype

additively. This simplification allows many predictors to be incorporated parsimoniously but

excludes interactive effects such as dominance and epistasis. Indeed, an additive model with a

fixed prior distribution may not be optimal when the development and regulation of the focal

trait are a complex function of genetic and environmental factors (Meuwissen, 2009; Morgante et

al., 2018; Putra et al., 2023).

Machine learning has been proposed as a means to better accommodate biological complexity in

genomic prediction (Carlborg & Haley, 2004). Non-linear, non-parametric models can account

for dominance and epistasis and have fewer assumptions about the distribution of genetic effects.

It is thus hypothesised that machine learning should be effective for genomic prediction under

increased model complexity, as is the case for other biological problems like predicting protein

structure (Jumper et al., 2021). However, the performance of non-linear machine learning models

has been largely underwhelming in genomic prediction. Multiple studies have shown machine

learning techniques to be no more accurate than linear regression for complex polygenic traits

(Abdollahi-Arpanahi et al., 2020; Azodi et al., 2020; Bellot et al., 2018). One explanation for the

under-performance of machine learning models is that the number of genetic variants used as

predictors is too high compared to the number of genotypes observed in the training set. There

might be many genetic interactions contributing to the development of a complex trait such as

crop yield; if the effect of each interaction is small, it is difficult to parameterise them with low

statistical power. Simulation studies have shown that machine learning models might rather be

suited to simpler traits controlled by a small number (<100) of causal loci (Abdollahi-Arpanahi

et al., 2020). Indeed, non-linear models have been most successful for predicting the occurrence

of human autoimmune diseases, where most of the genetic variance can be attributed to a

discrete set of loci from the major histocompatibility complex (Ohta et al., 2024). As such, rather

than attempting to apply machine learning to genomic prediction generally, machine learning

models might be specifically suited to simpler traits controlled by a few loci with strong epistatic

effects (Abdollahi-Arpanahi et al., 2020; Farooq et al., 2023). This hypothesis is agronomically

relevant. In crops, it can be desirable to breed for biochemical traits, for example the

concentration of minerals or metabolites (Šimić et al., 2012), which often have simple genetic

architectures (Riedelsheimer et al., 2012). On the other hand, macroscopic traits such as those

related to yield often combine many endophenotypes and tend to be more complex.

In addition to biological complexity, different evolutionary histories and patterns of selection in

the ancestral populations of training panels could also affect model selection (Fodor et al., 2014;

Guo et al., 2014). Population-specific selection on a trait leads to covariance between trait value

and population structure, confounding variants causally affecting a trait and background genomic

variations captured by neutral markers. Thus within one training panel, traits may be confounded

to a different degrees by historical patterns of selection. Moreover, the level of selection on a

trait, the trait's phenotypic ontology, and its architecture are likely to be linked, making it

extremely arduous to obtain independent estimates of each factor (Zhang, 2018). For example,

flowering time in *A. thaliana* is known to be both complex in genetic architecture and selected

along environmental clines (Zan & Carlborg, 2019; Fournier-Level et al., 2022).

The design and tuning of genomic prediction studies requires an understanding of how genetic

architectures and evolutionary histories interact to produce trait variation in the training

population considered. However, there has been very limited sensitivity analyses comparing

linear and machine learning models across a wide range of genetic architectures in natural,

outbreeding plant populations. Our study aims to address this gap by comparing the accuracy of

machine learning and linear models for the prediction of 36 *Arabidopsis thaliana* traits. We

specifically test the sensitivity to the phenotypic ontology of each trait, the genetic architecture

of each trait and finally assess how population structure and demography affect predictions. We

investigate how intertwined these three factors are, testing the hypothesis that linear models

would perform best for macroscopic traits, with complex genetic architecture that is structured

along environmental gradients. On the other hand, machine learning approaches are expected to

improve prediction accuracy for biochemical traits, which usually have a simple genetic

architecture, and are less heterogeneously selected across environments.

2.   Methods

2.1   Data Set

We used 10,709,466 molecular markers genotyped across 2029 inbred homozygous *Arabidopsis*

thaliana accessions from the 'K2029' public data set (Arouisse et al., 2020) which combines

genotypes from the RegMap Panel (Horton et al., 2012) and the 1001 genome project (Alonso-

Blanco et al., 2016). We downloaded all available phenotypes measured in all or a subset of

these accessions from the AraPheno database (Seren et al., 2017). In addition to the traits listed

in the AraPheno database, we also included 22 metabolic traits, which are the concentration of

glucosinolates involved in *Arabidopsis thaliana*'s herbivory stress response (Brachi et al., 2015).

No phenotype was measured across all genotyped accessions, meaning experiments always had

less than 2029 observations. For traits where measures were replicated within an accession, we

used the breeding value estimated across the replicates as the trait value for our genomic

prediction experiments. We estimated these breeding values using the best linear unbiased

predictor (BLUP). Using a phenotypic value derived from replicated measures of the same

accession minimises the effect of the environment in the study. From all traits available in the

AraPheno database, we retained only studies with 150 or more phenotyped accessions. When

two traits were correlated with Pearson's correlation $r^2 > 0.75$, we arbitrarily retained one, and

subsequently only considered traits where at least one genomic prediction model could explain

20% of the phenotypic variance. This filtering process reduced the set of traits from 551 to 36.

We then grouped these 36 traits by their associated trait ontology terms (Cooper et al., 2024).

The total number of molecular markers was filtered to keep computation time within a practical

range. For each trait, markers with minor allele frequencies (MAF) lesser than 5% were

discarded. We used 'plink thin' to prune correlated markers within a sliding window along the
genome, using a window size of 200 kbp, removing one of each pair of markers with linkage
disequilibrium $r^2 > 0.6$. Due to each trait having a different set of phenotyped accessions, we
conducted this filtering strategy independently for each trait. The total number of markers used
for the final set of 36 traits ranged from 218,128 to 366,534.

2.2 Analysis of Genetic Architecture

We investigated the genetic architecture of each trait using genome-wide association studies
(GWAS). GWAS were conducted using the 'VCFtoGWAS' function (Vogt et al., 2022)
implementing a 'GEMMA' model (Zhou & Stephens, 2012), where the effect of pairwise
relationships (estimated as identity-by-state-based kinships) is modelled as random, and the
effect of individual markers are modelled as fixed and tested using a Wald test. Polygenic traits
were defined when showing a high heritability while lacking substantial GWAS peaks;
oligogenic traits where defined as displaying multiple GWAS peaks; and monogenic traits were
defined when displaying a single associated locus (Atwell et al., 2010). The trait complexity
classification defined above was determined quantitatively by the kurtosis of the distribution of
GWAS p-values, and qualitatively validated through the inspection of Manhattan plots.

2.3 Prediction Models

2.3.1 Penalised Linear Regression

For the linear models, we implemented Ridge regression/GBLUP (genomic best linear unbiased
predictor), Lasso, and Elastic-net. Briefly, these models fit a weighted linear combination of
regression coefficients for the predictors (denoted $\boldsymbol{\beta}$) by minimising the following objective
function:

$$\hat{\beta} \equiv \underset{\beta}{argmin}\{\|y - \hat{y}\|^2 + \lambda(\alpha\|\beta\|_1 + (1-\alpha)\|\beta\|_2^2)\} \ (1)$$

Where y is a vector of observed phenotypes and $\hat{y}$ is the predicted phenotype, λ controls the
penalisation and α weights L_1 and L_2 penalisation. When α is null, the model is equivalent to

Ridge regression, when α is 1 the model is equivalent to Lasso regression, and when $0 < \alpha < 1$

the model is termed Elastic-net regression (Tibshirani, 1996; Zou & Hastie, 2005).

In our implementation of these models, the meta-parameters λ, and α in the case of Elastic-net,

were chosen through five-fold cross-validation in the training partition of the dataset searching

the following domains: $\lambda \in \{1.5^{-30}\ldots1.5^{30}\}$, $\alpha \in \{0.01, 0.1, 0.5, 0.85, 0.9, 0.97, 0.99, 0.995\}$. Ridge

and Lasso regressions were implemented using the 'RidgeCV' and 'LassoCV' functions of the

scikit-learn package (Pedregosa et al., 2011). Elastic-net regression was implemented using

'glmnet' with the coordinate descent algorithm (Friedman et al., 2010). All other parameters

were kept to default values.

2.3.2 Multilayer Perceptron

A Multilayer Perceptron (MLP) is a simple ANN model where perceptrons are organised in fully

connected layers. In our implementation, we used a rectified linear unit (ReLU) activation

function. Preliminary tests showed that other sigmoidal activation functions (such as *tanh*) had

similar prediction accuracy. We optimised {1,2,3} hidden layers in the network, where the

number of perceptrons in each hidden layer was set to two-thirds of the number of input

predictors. We also incorporated L2 penalisation where λ is a scalar optimised over {0, 0.01, 0.1,

1}. Weights were fitted iteratively using the Adam optimiser (Kingma & Ba, 2014). To

determine when to cease the training of the neural network model, we used an early stopping

approach (Prechelt, 1998). Briefly, we held out 10% of observations, and training was stopped

when either out of sample mean squared error did not decrease by at least the tolerance value for

10 consecutive epochs (iterations over the dataset), or 250 epochs were reached. The tolerance

value was optimised over {0.05, 0.01, 0.005}, noting here that each phenotype was standardised

to have a variance of 1. We also added dropouts (Srivastava et al., 2014). Dropouts are a type of

regularisation specifically designed for ANNs which randomly deactivate, or drop out, a certain

percentage of weights between layers during each training iteration. This prevents the model

from becoming too reliant on any specific perceptron or connection. We optimised the network

either using no dropout or dropping out 10% of the network connections during training. Due to

the computationally heavy requirement of fitting ANNs, we applied an additional filtering to the

number of markers used to fit this model. For this filtering, we fitted a linear Lasso regression

then filtered out markers with a regression coefficient equal to 0. Here, the penalty terms were

determined via five-fold cross-validation alongside the other meta-parameters specified in this

section.

2.3.3 Random forest

Random forest is an ensemble model that fits decision trees to bootstrapped samples of the data,

then makes predictions by averaging the output of each tree. We implemented the

'RandomForest' sci-kit learn function (Pedregosa et al., 2011). Five-hundred decision trees were

used across experiments; increasing the number of decision trees did not affect performance.

Each of these trees was fitted to the full set of predictors, randomness between trees being

introduced through bootstrapping of the accessions. All other parameters were kept as default.

2.3   Model benchmarking and meta-parameter selection

We compared the accuracies and residual errors of each of the models described using nested 10-

fold cross validation. This framework consists of an inner loop and an outer loop. The outer loop

is a canonical ten-fold cross-validation and measures generalizability. The inner loop takes each

training partition from the outer loop and uses five-fold cross validation to evaluate each meta-

parameter configuration of the tested model.

2.4   Analysis of Spatial Clines

To analyse the effect of differential selection across genotypes having evolved across distant

environments, we quantified the strength of spatial clines for each trait. To do this, we used the

following model of the phenotypic values in terms of the latitude and longitude of where each

accession was originally sampled from.

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$$y = \beta_0 + lat + \beta_2 long + \beta_3 lat \cdot long + \beta_4 lat^2 + \beta_5 long^2 \quad (2)$$

221 We quantified the strength of a spatial cline based on the phenotypic variance that was captured

222 by this model. We applied this model only to accessions sampled within Europe (latitude -40–60,

223 longitude 20–70), excluding the small number of accessions sampled from North America.

 2.5   Code Availability

All code and the corresponding analysis used in this paper can be found on the following

repository:

https://github.com/Patrick-Gibbs/Trait-genetic-architecture-and-population-structure-genomic-

prediction

3.   Results

3.1   Optimal genomic prediction model is associated with trait ontology

Of the 551 publicly available traits, 36 traits were independent (correlation between traits $r^2 <$

0.75) and sufficiently heritable to be predicted with an accuracy $r^2 > 0.2$ by one of the genomic

prediction models. Of this filtered set of traits, 23 were macroscopic and 13 were biochemical

(Supplementary Table S1). Penalised regression yielded the most accurate predictions for all 23

macroscopic traits; 20 through Ridge regression and three through Lasso. In contrast, no single

model was superior at predicting the 13 biochemical traits (Supplementary Table S2).

Noticeably, Random Forest improved prediction above linear models for 7 biochemical traits

(Figure 1a). The increase in accuracy was particularly large for allyl concentration, a

glucosinolate involved in preventing herbivory, and molybdenum concentration, an essential

micronutrient (Figure 1b, paired t-test $p = 2.87 \times 10^{-4}, p = 3.28 \times 10^{-5}$ respectively).

Figure 1: Genomic prediction accuracy depends on trait ontology class. (a) Most accurate genomic

prediction model for each trait ontology term. (b) Prediction accuracy of the best linear model compared to

Random Forest contrasting for a pair of biochemical traits (the concentration of allyl and molybdenum)

and macroscopic traits (number of days to flowering at 10°C and average seed weight). Here, the ten data

points are the prediction accuracy (measured as r^2) for each partition of the ten-fold cross-validation.

250   3.2   The genetic architecture is associated with genomic prediction model choice.

To test the hypothesis that random forest out-performance over penalised regression is due to the

specific genetic architecture of biochemical traits, we analysed each trait through GWAS.

Biochemical traits had stronger individual associations compared to macroscopic traits (Fig. 2A;

Suppl. Fig. S1). Macroscopic traits generally displayed fewer association peaks despite high

heritability, indicative of polygenicity. This observation was reflected in the kurtosis of the

distribution of p-values, which was on average higher for biochemical traits compared to

macroscopic traits (t-test, t=5.54, p=3.34e-06; Fig. 2a). Moreover, among the biochemical traits

best predicted by Random Forest, six out of seven were most accurately predicted by linear

models that assume sparsity (Elastic-net or Lasso). Only one of these seven traits was most

accurately predicted by Ridge regression, which assumes polygenicity (Supplementary Table

S2).

262   3.3   The Effect of genetic architecture and population structure differ across trait

263   ontology.

To better understand how population structure affects prediction accuracy, we used principal

components (PCs) computed from genome-wide marker data as predictors instead of the markers

themselves. We considered traits that could be well predicted by a small number of PCs to be

structured. As a quantitative metric of structure we divided the r^2 prediction accuracy of the best

model that used markers by the r^2 of the best model using PCs. Under this metric, macroscopic

traits were more structured than biochemical traits. When we fitted each model to the PCs

explaining 30% of marker variance, the best genomic prediction model fitted to these PCs

produced an r^2 value on average 90% as high as the best marker-based model for macroscopic

traits, compared to 69% for biochemical traits (t-test, t=2.48, p=0.0178; Fig. 3b).

Finally, we investigated the effect of large spatial gradients. In general, macroscopic traits tended

to covary more strongly with latitude and longitude than biochemical traits. A quadratic function

of latitude and longitude (Eqn. 2) explained on average 25% of phenotypic variance for

macroscopic traits compared to 14% of variance in microscopic traits (t-test, t=2.55, p=0.0153).

Notable were the extremes: the quadratic spatial model could explain as much as 48% of

flowering time traits, yet as little as 1% of variation in biochemical traits (Fig. 3c). Critically, the

traits with a distribution of genetic effects with a low kurtosis were best predicted by a Ridge

regression model and explained well by population structure and spatial distribution. In turn, the

traits with high kurtosis were best predicted by Lasso or Random Forest and explained poorly by

population structure and geography (Fig. 2a-c).

Figure 2: Sensitivity of best genomic prediction model to genetic architecture, population structure

and geography. (a) The kurtosis of GWAS log(p-values) for each of the 36 traits analysed in this study.

(b) the ratio between prediction accuracy (r^2) of the best performing model fit to the principal

components of the genome (30% variance explained), to the best model fit to genome-wide markers. (c)

The proportion of phenotypic variance explained by the geographic location of origin of genotypes (r^2),

given by equation 2 for each class of trait.

Figure 3: Example of the relationship between genetic architecture, genomic prediction model, population structure and geography. (a) Manhattan plots for GWAS illustrating the genetic architecture of 3 traits with contrasted genetic architectures. (b) Sensitivity to dimensionality reduction conducted through principal component (PC) analysis. The x-axis shows the cumulative variance explained by the set of PCs retained in the untransformed feature set. The last tick on the x-axis corresponds to the accuracy achieved using the markers, equivalent to using all PCs. RF: Random Forest; MLP: multilayer perceptron model which uses a single hidden layer. (c) Sensitivity between the phenotype and the latitude of origin of the accessions. *Note* figure shows only the 78 accessions with phenotype data for all 3 traits.

4.   Discussion

Genomic prediction is an expanding field of research initially motivated by the opportunity of conducting molecular breeding in animals and plants. Genomic selection can apply to any heritable trait, with very diverse genetic architectures and evolutionary histories. As such, we expected that genomic prediction would rely on different, specific methodologies for each trait. Among the 36 *Arabidopsis thaliana* traits tested, the most accurate genomic prediction model depended on trait ontology, genetic architecture and population structure. These components are interconnected and collectively determine the most suitable prediction model. Specifically, we observed that biochemical traits have sparser genetic architectures and are less influenced by population structure. As a result, different approaches were optimal for biochemical and macroscopic traits. Linear regression was best suited for macroscopic traits, while sparse linear regression or Random Forest generally yielded more accurate predictions for biochemical traits.

Model selection depends on the genetic architecture of the trait

We found that Random Forest specifically outperformed linear models for biochemical traits which showed a monogenic to oligogenic architecture. These findings challenge previous work which has argued that for polygenic traits determined by a complex network of genes, non-linear models have potential to outperform linear models (Azodi et al., 2019; Farooq et al., 2023; Momen et al., 2018; Morgante et al., 2018). Instead, we support that non-linear models are best suited to traits with a small number of effects with strong epistasis (Abdollahi-Arpanahi et al., 2020). Our results also suggest that for training panels gathering broad sources of natural variation, non-linear, non-parametric models can improve predictions when targeted to specific sparse traits. We argue this is a more effective strategy than developing generalised machine learning frameworks aimed at improving genomic prediction across all traits. Our findings are consistent with recent studies that linked the success of ensemble approaches to evidence of strong epistasis in specific mice traits (Perez et al., 2022; Zingaretti et al., 2020), or a recent study finding non-linear approaches to improve prediction of MHC related human disease (Ohta et al., 2024). Our results also expand on a study by Riedelsheimer and colleagues (2012), which

compared linear models between molecular and macroscopic traits in maize. Their study found
that molecular traits have a simple genetic architecture, and showed that linear models with a
sparse prior best predicted them. Consistent with these findings, we generally observed that for
biochemical traits the best performing linear models had sparse priors, although random forest
delivered higher accuracy for a few of the biochemical traits. Earlier motivation for testing
machine learning in complex traits was to capture phenotypic variance underpinned by epistasis.
We believe non-parametric models worked specifically well for sparser traits because the
presence of interaction effects is stronger when fewer genomic regions underpin a trait.
Moreover, when a trait is sparse, the prior distribution of effect sizes is more difficult to
determine, which is advantageous to non-parametric models such as Random Forest which rely
on fewer assumptions about the prior distribution of genetic effects. The development and
regulation of complex traits may well be underpinned by epistasis, but the effect size of each
interaction is likely to be small, or underpinned by very rare variants. As noticed in previous
studies, this would make the effect size of each interaction small, and difficult to learn from data
(Azodi et al., 2019).
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In line with previous works, we found artificial neural networks of any design tested to have
lower out of sample prediction accuracy than linear models (Abdollahi-Arpanahi et al., 2020;
Azodi et al., 2020; Bellot et al., 2018). MLPs make predictions by building increasingly abstract
representations from all the predictors. They have the implicit assumption that every predictor is
meaningful, and likely interacts with other predictors. These assumptions work well for
computer vision tasks, where each pixel contains a small but meaningful amount of information,
and an image is best understood from a collection of many pixels. We believe the poor results
from MLP in genomic prediction is because the way genomic information maps to phenotypic
variation poorly matches the assumptions of MLPs. Genomic data typically exhibit a very low
signal-to-noise ratio with respect to trait determinism. For simpler traits, many SNPs may have
no signal, and of those that do, there may only be a small number of effective interactions. For
complex traits, that are hypothesised to be underpinned by a complex network of genes
(Carlborg & Haley, 2004), complex models like MLPs suffer from the aforementioned problem
of low statistical power and rare variants (Azodi et al., 2019; Bellot et al., 2018).

Effect of the trait evolutionary history on genomic prediction

We found that population demography and the evolutionary history of the trait is also an

important determinant of genomic prediction model selection. Particularly, biochemical traits

were less correlated with population structure than the macroscopic traits. The principal

component analysis of the population genomic data captures the major axis of genomic variation,

and thus provides a concise summary of population structure (Ma & Amos, 2012; Novembre &

Stephens, 2008). For example, a linear combination of PCs explaining 30% of genomic variants

predicted flowering time as well as any marker based model. On the other hand, the most

accurate model that used PCs as predictors only predicted the concentration of metabolite

M130T666 with an $r^2 = 22\%$ as high as the best marker based model. Thus in the training

population examined, individual markers are informative for the prediction of simple, typically

biochemical, traits while for complex, macroscopic traits, causal variants are confounded by

population structure. Indeed a complex trait like flowering time may be underpinned by many

epistatic effects, but could be obfuscated by population structure, favouring simpler linear

models. We tested a population of natural, unrelated accessions sampled at a large geographic

scale, which is different to most genomic prediction studies working with inbred lines generated

from crossing designs. Genomic prediction in genetically diverse training populations is relevant

at the prebreeding step where the aim is often to characterise germplasm as broadly as possible.

As a consequence, the effect of population structure we observed might be less pronounced in

study with crossing designs. However, simulation studies using genotypic data from crosses have

also shown that factoring the effect of populations structure can improve the prediction accuracy

of complex traits if the testing partition of the data captures similar variation to the training

partition (Fodor et al., 2014).

Our findings suggest that the varying degree of correlation between traits and population

structure observed in this study is explained by heterogeneous levels of ancestral selection across

traits. We observed that macroscopic traits on average had stronger biological clines across

longitudinal and latitudinal gradients compared to biochemical traits. We thus expect that such

biological clines are established in response to selection pressures that differ between
environments. It is well established that flowering time is adaptive to specific environments in
Europe (Fournier-Level et al., 2022). The weaker clines in biochemical traits supports the neutral
theory of molecular evolution, which posits that selection occurs mostly at the organismal level
and that molecular traits are generally more neutral than macroscopic traits (Fig. 2c; Kimura,
1985). When considering the hierarchical organisation of traits that establish the whole
phenotype, it follows that a mutation affecting a trait at a high level will also influence traits at
lower levels. Macroscopic traits which are under direct selection combine many endophenotypes.
However, individual biochemical traits might not affect the organism at a macroscopic level and
thus are inherently under more relaxed selection (Zhang, 2018). We argue that in addition to
genetic architecture, ensemble approaches were effective for specifically biochemical traits
because these traits are more neutral, and thus less confounded by population structure.
Importantly, our research suggests that within the same population, ancestral patterns of selection
affect the inference of causal variants and the choice of genomic prediction model. As a
consequence, the magnitude of this effect in a natural population can be understood in terms of
the hierarchical organisation of trait ontology.
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Conclusion
In light of our results, we suggest that future implementation of genomic prediction should lean
towards ensemble models in addition to linear statistical models when the genetic architecture is
sparse. We also caution that the confounding effect of population structure can vary between
traits within the same population, likely due to selection history. This has the potential to hamper
the generalisation and biological interpretability of genomic prediction models. Non-linear
approaches have a role in genomic prediction, however only for specific genetic architectures,
with strong associations that are not confounded by population structure, or after strong
differential selection in the ancestral populations. Previous work has focused on benchmarking a
wide range of genomic prediction models across select complex traits without focusing on their
organisational hierarchy. Future work would certainly benefit from expanding genomic
prediction methodology through the exploration of the phenome, linking trait ontologies, genetic
architectures, and population histories to modelling strategies.

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Statements & declarations

Conflict of interest

On behalf of all authors, the corresponding author states that there is no conflict of interest.

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Author contributions

PMG, JFP and AFL designed the study, PMG and JFP prepared the material, PMG analysed the data, PMG and AFL wrote the manuscript.

Data availability

All code and the corresponding analysis used in this paper can be found on the following repository:

https://github.com/Patrick-Gibbs/Trait-genetic-architecture-and-population-structure-genomic-prediction

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(a) Best Performing Model

Trait Ontology
- biochemical trait
- flowering time trait
- plant morphology trait
- seed dormancy trait
- shoot system growth and develpoment trait
- yeild trait

(b)

(a)

(b)

(c)