Trait genetic architecture and population structure determine model selection for

genomic prediction in natural *Arabidopsis thaliana* populations

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Abstract

Genomic prediction applies to a wide range of agronomically relevant traits, with distinct

ontologies and genetic architectures. Selecting the most appropriate model for the distribution of

genetic effects and their associated allele frequencies in the training population is crucial. Linear

regression models are often preferred for genomic prediction when the number of genome-wide

markers is much greater than the number of observations. However, linear models may not suit

all genetic architectures and training populations. Machine Learning was proposed as an

improvement for genomic prediction owing to its capacity to capture complex biology including

epistasis, but its performance over parametric regression is yet to be widely assessed. This study

evaluates genomic prediction sensitivity to trait ontology and the impact of training population

structure on model selection and prediction accuracy. Examining 36 quantitative traits measured

for 1000+ natural genotypes of the model plant *Arabidopsis thaliana*, we assessed the

performance of penalised regression, random forest, and multilayer perceptron at producing

genomic predictions. Regression models were generally the most accurate, except for

biochemical traits where Random Forest performed best. We link this result to the genetic

architecture of each trait – notably that biochemical traits have simpler genetic architecture than

macroscopic traits. Moreover, complex macroscopic traits, particularly those related to flowering

and yield, were strongly correlated to population structure, while molecular traits were better

predicted by fewer, independent markers. This study highlights the relevance of machine

learning approaches for simple molecular traits and underscores the need to consider ancestral

population history when designing training samples.

1.   Introduction

In plant breeding, genomic prediction can apply to any agronomically relevant traits form yield,

to phenology, metabolite concentrations or the response to stresses, which all have different

genetic basis. Heritable traits, whether simple and controlled by a few loci, or complex and

controlled by many variants, can be predicted based on the information from dense, genome-

wide markers. Genomic prediction models are often fitted to training populations designed to

maximise diversity, including genotypes with varying levels of co-ancestry and different

evolutionary histories (Fodor et al., 2014). Therefore, critical in genomic prediction is the choice

of a model that most adequately factors population's allele frequencies and the distribution of

genetic effects for each particular trait.

The number of genome-wide markers (p) being typically much larger than the number of

individual observations (n), overfitting is a major challenge in genomic prediction. A common

solution is to use penalised linear regression models (Meuwissen et al., 2001). Penalised

regression reduces overfitting by shrinking the effect of each marker. Most penalisation

functions assume a prior distribution of the marker effects, which relates to the trait's assumed

genetic architecture. Linear models also assume that genetic factors influence the phenotype

independently and additively. This simplification allows many predictors to be incorporated

parsimoniously but excludes interactive effects such as dominance and epistasis. Indeed, an

additive model with a fixed prior distribution may not be optimal when the development and

regulation of the focal trait are a complex function of genetic and environmental factors

(Meuwissen, 2009; Morgante et al., 2018; Putra et al., 2023).

Machine learning has been proposed as a means to better accommodate biological complexity in genomic prediction (Carlborg & Haley, 2004). Non-linear, non-parametric models can account for dominance and epistasis and have fewer assumptions about the distribution of genetic effects. It is thus hypothesised that machine learning should be effective for genomic prediction under increased model complexity, as is the case for other biological problems like predicting protein structure (Jumper et al., 2021). However, the performance of non-linear machine learning models has been largely underwhelming in genomic prediction. Multiple studies have shown machine learning techniques to be no more accurate than linear regression for complex polygenic traits (Abdollahi-Arpanahi et al., 2020; Azodi et al., 2020; Bellot et al., 2018). One explanation for the under-performance of machine learning models is that the number genetic variants used as predictors is two high compared to the number of genotypes observed in the training set. There might be many genetic interactions contributing to the development of a complex trait such as crop yield; if the effect of each interaction is small, it is difficult to parameterise them with low statistical power. Simulation studies have shown that machine learning models might be suited to simpler traits controlled by a small number (<100) of causal loci (Abdollahi-Arpanahi et al., 2020). Indeed, non-linear models have been most successful for predicting the occurrence of human autoimmune diseases, where most of the genetic variance can be attributed to a discrete set of loci from the major histocompatibility complex (Abraham et al., 2014). As such, rather than attempting to apply machine learning to genomic prediction generally, machine learning models might be specifically suited to simpler traits controlled by a few loci with strong epistatic effects (Abdollahi-Arpanahi et al., 2020; Farooq et al., 2023). This hypothesis is agronomically relevant. In crops, it can be desirable to breed for biochemical traits, for example the concentration of minerals or metabolites (Šimić et al., 2012), which often have simple genetic architectures (Riedelsheimer et al., 2012). On the other hand, macroscopic traits such as those related to yield often combine many endophenotypes and tend to be more complex.

In addition to biological complexity, different evolutionary histories and patterns of selection in the ancestral populations of training panels could also affect model selection (Fodor et al., 2014; Guo et al., 2014). Population-specific selection on a trait leads to covariance between trait value and population structure, confounding causal variants with demographic history and neutral

markers. Thus within one training panel, traits may be confounded to a different degrees by

historical patterns of selection. Moreover, the level of selection on a trait, the trait's phenotypic

ontology, and its architecture are likely to be linked, making it extremely arduous to obtain

independent estimates of each factor (Zhang, 2018). For example, flowering time in *A. thaliana*

is known to be both complex in genetic architecture and selected along environmental clines

(Zan & Carlborg, 2019; Fournier-Level et al., 2022).

The design and tuning of genomic prediction studies requires an understanding of how genetic

architectures and evolutionary histories interact to produce trait variation in the training

population considered. However, there has been very limited sensitivity analyses comparing

linear and machine learning models across different genetic architectures in natural, outbreeding

plant populations. Our study aims to address this gap by comparing the accuracy of machine

learning and linear models for the prediction of 36 *Arabidopsis thaliana* traits. We specifically

test the sensitivity to the phenotypic ontology of each trait, the genetic architecture of each trait

and finally assess how population structure and demography affect predictions. We investigate

how intertwined these three factors are, testing the prediction that linear models would perform

best for macroscopic traits, with complex genetic architecture that is structured along

environmental gradients. On the other hand, machine learning approaches are expected to

improve prediction accuracy for biochemical traits, expected to have a simple genetic

architecture, and less heterogeneously selected across environments.

2.   Methods

2.1   Data Set

We used 10,709,466 molecular markers genotyped across 2029 inbred homozygous *Arabidopsis*

thaliana accessions from the 'K2029' public data set (Arouisse et al., 2020) which combines

genotypes from the RegMap Panel (Horton et al., 2012) and the 1001 genome project (Alonso-

Blanco et al., 2016). We downloaded all available phenotypes measured in all or a subset of

these accessions from the AraPheno database (Seren et al., 2017). In addition to the traits listed

in the AraPheno database, we also downloaded 22 metabolic traits, which are the concentration

of glucosinolates involved in *Arabidopsis thaliana*'s herbivory stress response (Brachi et al., 2015). No phenotype was measured across all genotyped accessions, meaning experiments always had less than 2029 observations. For traits where measures were replicated within an accession, we used the breeding value estimated across the replicates as the trait value for our genomic prediction experiments. We estimated these breeding values using the best linear unbiased predictor (BLUP). Using a phenotypic value derived from replicated measures of the same accession minimises the effect of the environment in the study. From all traits available in the AraPheno database, we retained only studies with 150 or more phenotyped accessions. When two traits were correlated with Pearson's correlation $r^2 > 0.75$, we arbitrarily retained one, and subsequently only considered traits where at least one genomic prediction model could explain 20% of the phenotypic variance. This filtering process reduced the set of traits from 551 to 36. We then grouped these 36 traits by their associated trait ontology terms (Cooper et al., 2024).

The total number of molecular markers was filtered to keep computation time within a practical range. For each trait, markers with minor allele frequencies (MAF) lesser than 5% were discarded. We used 'plink thin' to prune correlated markers within a sliding window along the genome, using a window size of 200 kbp, removing one of each pair of markers with linkage disequilibrium $r^2 > 0.6$. Due to each trait having a different set of phenotyped accessions, we conducted this filtering strategy independently for each trait. The total number of markers used for the final set of 36 traits ranged from 218,128 to 366,534.

2.2   Analysis of Genetic Architecture

We investigated the genetic architecture of each trait using genome-wide association studies (GWAS). GWAS were conducted using the 'VCFtoGWAS' function (Vogt et al., 2022) implementing a 'GEMMA' model (Zhou & Stephens, 2012), where the effect of pairwise relationships (estimated as identity-by-state-based kinships) is modelled as random, and the effect of individual markers are modelled as fixed and tested using a Wald test. Polygenic traits were defined when showing a high heritability while lacking substantial GWAS peaks; oligogenic traits where defined as displaying multiple GWAS peaks; and monogenic traits were defined when displaying a single associated locus (Atwell et al., 2010). The trait complexity

classification defined above was determined quantitatively by the kurtosis of the distribution of

GWAS p-values, and qualitatively validated through the inspection of Manhattan plots.

2.3   Prediction Models

2.3.1   Penalised Linear Regression

For the linear models, we implemented Ridge regression/GBLUP (genomic best linear unbiased

predictor), Lasso, and Elastic-net. Briefly, these models fit a weighted linear combination of

regression coefficients for the predictors (denoted β) by minimising the following objective

function:

$$\hat{\beta} \equiv \underset{\beta}{argmin}\{\|y - \hat{y}\|^2 + \lambda(\alpha\|\beta\|_1 + (1 - \alpha)\|\beta\|_2^2)\}\ (1)$$

Where y is a vector of observed phenotypes and $\hat{y}$ is the predicted phenotype, λ controls the

penalisation and α weights L$_1$ and L$_2$ penalisation. When α is null, the model is equivalent to

Ridge regression, when α is 1 the model is equivalent to Lasso regression, and when $0 < \alpha < 1$

the model is termed Elastic-net regression (Tibshirani, 1996; Zou & Hastie, 2005).

In our implementation of these models, the meta-parameters λ, and α in the case of Elastic-net,

were chosen through ten-fold cross-validation in the training partition of the dataset searching

the following domains: $\lambda \in \{1.5^{-30}, 2^{19}...1.5^{30}\}$, $\alpha \in \{0.01, 0.1, 0.5, 0.85, 0.9, 0.97, 0.99, 0.995\}$. Ridge

and Lasso regressions were implemented using the 'RidgeCV' and 'LassoCV' functions of the

scikit-learn package (Pedregosa et al., 2011). Elastic-net regression was implemented using

'glmnet' with the coordinate descent algorithm (Friedman et al., 2010). All other parameters

were kept to default values.

2.3.2   Multilayer Perceptron

A Multilayer Perceptron (MLP) is a simple ANN model where perceptrons are organised in fully

connected layers. In our implementation, we used a rectified linear unit (ReLU) activation

function. Preliminary tests showed that other sigmoidal activation functions (such as *tanh*) had

similar prediction accuracy. We optimised {1,2,3} hidden layers in the network, each width

equal to two-thirds of the number of input predictors. We also incorporated L2 penalisation

where λ is a scalar optimised over $\{0, 0.01, 0.1, 1\}$. Weights were fitted iteratively using the

Adam optimiser (Kingma & Ba, 2014). To determine when to cease the training of the neural

network model, we used an early stopping approach (Prechelt, 1998). Briefly, we held out 10%

of observations, and training was stopped when either out of sample MSE did not decrease by at

least the tolerance value for 10 consecutive epochs (iterations over the dataset), or 1000 epochs

were reached. The tolerance value was optimised over $\{0.05, 0.01, 0.005\}$, noting here that each

phenotype was standardised to have a variance of 1. We also added dropouts (Srivastava et al.,

2014). Dropouts are a type of regularisation specifically designed for ANNs which randomly

deactivate, or drop out, a certain percentage of weights between layers during each training

iteration. This prevents the model from becoming too reliant on any specific perceptron or

connection. We optimised the network either using no dropout or dropping out 10% of the

network connections during training. Due to the computationally heavy requirement of fitting

ANNs, we applied an additional filtering to the number of markers used to fit this model. For this

filtering, we fitted a linear Lasso regression then filtered out markers with a regression

coefficient equal to 0. Here, the penalty terms were determined via five-fold cross-validation

alongside the other meta-parameters specified in this section.

2.3.3   Random forest

Random forest is an ensemble model that fits decision trees to bootstrapped samples of the data,

then makes predictions by averaging the output of each tree. We implemented the

'RandomForest' sci-kit learn function (Pedregosa et al., 2011). Five-hundred decision trees were

used across experiments; increasing the number of decision trees did not affect performance.

Each of these trees was fitted the full set of predictors, randomness between trees being

introduced through bootstrapping of the accessions. All other parameters were kept as default.

2.3   Model benchmarking and meta-parameter selection

We compared the accuracies and residual errors of each of the models described using nested 10-

fold cross validation. This framework consists of an inner loop and an outer loop. The outer loop

is a canonical ten-fold cross-validation and measures generalizability. The inner loop takes each

training partition from the outer loop and uses five-fold cross validation to evaluate each meta-

parameter configuration of the tested model.

2.4   Analysis of Spatial Clines

To analyse the effect of differential selection across genotypes having evolved across distant

environments, we quantified the strength of spatial clines for each trait. To do this, we used the

following model of the phenotypic values in terms of the latitude and longitude of where each

accession was originally sampled from.

$$y = \beta_0 + lat + \beta_2 long + \beta_3 lat \cdot long + \beta_4 lat^2 + \beta_5 long^2 \quad (2)$$

We quantified the strength of a spatial cline based on the phenotypic variance that was captured

by this model. We applied this model only to accessions sampled within Europe (latitude -40–60,

longitude 20–70), excluding the small number of accessions sampled from America.

2.5   Code Availability

213   All code and the corresponding analysis used in this paper can be found on the following

214   repository:

215   https://github.com/Patrick-Gibbs/Trait-genetic-architecture-and-population-structure-genomic-

216   prediction

3.   Results

3.1   Optimal genomic prediction model is associated with trait ontology

Of the 551 publicly available traits, 36 traits were independent (correlation between traits $r^2 <$

0.75) and sufficiently heritable to be predicted with an accuracy $r^2 > 0.2$ by one of the genomic

prediction models. Of this filtered set of traits, 23 were macroscopic and 13 were biochemical

(Supplementary Table S1). Penalised regression yielded the most accurate predictions for all 23

macroscopic traits; 22 through Ridge regression and two through Lasso. In contrast, no single

model was superior at predicting the 13 biochemical traits (Supplementary Table S2).

Noticeably, Random Forest improved prediction above linear models for 7 biochemical traits

(Figure 1a). The increase in accuracy was particularly large for allyl concentration, a

glucosinolate involved in preventing herbivory, and molybdenum concentration, an essential

micronutrient (Figure 1b, paired t-test $p = 2.87 \times 10^{-4}$, $p = 3.28 \times 10^{-5}$ respectively).

Figure 1: Genomic prediction accuracy depends on trait ontology class. (a) Most accurate genomic prediction model for each trait ontology term. (b) Prediction accuracy of the best linear model compared to Random Forest contrasting for a pair of biochemical traits (the concentration of allyl and molybdenum) and macroscopic traits (number of days to flowering at 10°C and average seed weight). Here, the ten data points are the prediction accuracy for each partition of the ten-fold cross-validation.

3.2 The genetic architecture is associated with genomic prediction model choice.

To test the hypothesis that random forest out-performance over penalised regression is due to the specific genetic architecture of biochemical traits, we analysed each trait through GWAS. Biochemical traits had stronger individual associations compared to macroscopic traits (Fig. 2A; Suppl. Fig. S1). Macroscopic traits generally displayed fewer association peaks despite high heritability, indicative of polygenicity. This observation was reflected in the kurtosis of the distribution of p-values, which was on average higher for biochemical traits compared to macroscopic traits (t-test, t=5.54, p=3.34e-06; Fig. 2a). Moreover, among all biochemical traits best predicted by Random Forest, the most accurate linear model was either Elastic-net or Lasso, which assume sparsity, and never Ridge regression, which assumes polygenicity.

3.3 The Effect of genetic architecture and population structure differ across trait ontology.

To better understand how population structure affects prediction accuracy, we used principal components (PCs) computed from genome-wide marker data as predictors instead of the markers themselves. We classified as structured traits that were well predicted by a small number of principal components. As a quantitative metric of structure we divided the r^2 prediction accuracy of the best model that used markers by the r^2 of the best model using principal components. Under this metric, macroscopic traits were more structured than biochemical traits. When we fitted each model to the PCs explaining 30% of marker variance, the best genomic prediction model fitted to these PCs produced an r^2 value 90%, as high as the best marker-based model for macroscopic traits, compared to 69% for biochemical traits (t-test, t=2.48, p=0.0178; Fig. 3b).

Macroscopic traits were more correlated with this PC-based measure of population structure than

biochemical traits. For example, when we fitted models using the PCs explaining 30% of marker

variance, the best PC-based genomic prediction model for macroscopic traits produced an r^2

value of 90%, as high as the best marker based model, compared to 69% for biochemical traits

(t-test, t=2.48, p=0.0178; Fig. 3b).

Finally, we investigated the effect of large spatial gradients. In general, macroscopic traits tended

to covary more strongly with latitude and longitude than biochemical traits. A quadratic function

of latitude and longitude explained on average 25% of phenotypic variance for macroscopic

traits compared to 14% of variance in microscopic traits (t-test, t=2.55, p=0.0153). Notable were

the extremes: the quadratic spatial model could explain as much as 48% of flowering time traits,

yet as little as 1% of variation in biochemical traits (Fig. 3c). Critically, the traits with a

distribution of genetic effects with a low kurtosis were best predicted by a Ridge regression

model and explained well by population structure and spatial distribution. In turn, the traits with

high kurtosis were best predicted by Lasso or Random Forest and explained poorly by population

structure and geography (Fig. 2a-c).

Figure 2: Sensitivity of best genomic prediction model to genetic architecture, population structure

and geography. (a) The kurtosis of GWAS log(p-values) for each of the 36 traits analysed in this study.

(b) the ratio between prediction accuracy (r^2) of the best performing model fit to the principal

components of the genome (30% variance explained), to the best model fit to genome-wide markers. (c)

The proportion of phenotypic variance explained by the geographic location of origin of genotypes (r^2), given by equation 2 for each class of trait.

Figure 3: Example of the relationship between genetic architecture, genomic prediction model, population structure and geography. (a) Manhattan plots for GWAS illustrating the genetic architecture of 3 traits with contrasted genetic architectures. (b) Sensitivity to dimensionality reduction conducted through principal component (PC) analysis. The x-axis shows the cumulative variance explained by the set of PCs retained in the untransformed feature set. The last tick on the x-axis corresponds to the accuracy

289   achieved using the markers, equivalent to using all PCs. RF: Random Forest; MLP: multilayer perceptron

290   model which uses a single hidden layer. (c) Sensitivity between the phenotype and the latitude of origin of

291   the accessions. *Note* figure shows only the 78 accessions with phenotype data for all 3 traits.

4.   Discussion

Genomic prediction is an expanding field of research initially motivated by the opportunity of

conducting molecular breeding in animals and plants. Genomic selection can apply to any

heritable trait, with very diverse genetic architectures and evolutionary histories. As such, we

expected that genomic prediction would rely on different, specific methodologies for each trait.

Among the 36 *Arabidopsis thaliana* traits tested, the most accurate genomic prediction model

depended on trait ontology, genetic architecture and population structure. These components are

interconnected and collectively determine the most suitable prediction model. Specifically, we

observed that biochemical traits have sparser genetic architectures and are less influenced by

population structure. As a result, different approaches were optimal for biochemical and

macroscopic traits. Linear regression was best suited for macroscopic traits, while sparse linear

regression or Random Forest generally yielded more accurate predictions for biochemical traits.

Model selection depends on the genetic architecture of the trait

We found that Random Forest specifically outperformed linear models for biochemical traits

which showed a monogenic to oligogenic architecture. These findings challenge previous work

which has argued that for polygenic traits determined by a complex network of genes, non-linear

models have potential to outperform linear models (Azodi et al., 2019; Farooq et al., 2023;

Momen et al., 2018; Morgante et al., 2018). Instead, we support that non-linear models are best

suited to traits with a small number of effects with strong epistasis (Abdollahi-Arpanahi et al.,

2020). Our results also suggest that for training panels gathering broad sources of natural

variation, non-linear, non-parametric models can improve predictions when targeted to specific

sparse traits. We argue this is a more effective strategy than developing generalised machine

learning frameworks aimed at improving genomic prediction across all traits. Our findings are

consistent with recent studies that linked the success of ensemble approaches to evidence of

strong epistasis in specific mice traits (Perez et al., 2022; Zingaretti et al., 2020). Our results also

expand on a study by Riedelsheimer and colleagues (2012), which compared linear models

between molecular and macroscopic traits in maize. Their study found that molecular traits have

a simple genetic architecture, and showed that linear models with a sparse prior best predicted

them. Consistent with these findings, we generally observed that for biochemical traits the best

performing linear models had sparse priors, although random forest delivered higher accuracy

for a few of the biochemical traits. Earlier motivation for testing machine learning in complex

traits was to capture phenotypic variance underpinned by epistasis. We believe non-parametric

models worked specifically well for sparser traits because the presence of interaction effects is

stronger when fewer genomic regions underpin a trait. Moreover, when a trait is sparse, the prior

distribution of effect sizes is more difficult to determine, which is advantageous to non-

parametric models such as Random Forest which rely on fewer assumptions about the prior

distribution of genetic effects. The development and regulation of complex traits may well be

underpinned by epistasis, but the effect size of each interaction is likely to be small, or

underpinned by very rare variants. As noticed in pervious studies, this would make the effect size

of each interaction small, and difficult to learn from data (Azodi et al., 2019).

In line with previous works, we found artificial neural networks of any design tested to have

lower out of sample prediction accuracy than linear models (Abdollahi-Arpanahi et al., 2020;

Azodi et al., 2020; Bellot et al., 2018). MLPs make predictions by building increasingly abstract

representations from all the predictors. They have the implicit assumption that every predictor is

meaningful, and likely interacts with other predictors. These assumptions work well for

computer vision tasks, where each pixel contains a small but meaningful amount of information,

and an image is best understood from a collection of many pixels. We believe the poor results

from MLP in genomic prediction is because the way genomic information maps to phenotypic

variation poorly matches the assumptions of MLPs. Genomic data typically exhibit a very low

signal-to-noise ratio with respect to trait determinism. For simpler traits, many SNPs may have

no signal, and of those that do, there may only be a small number of effective interactions. For

complex traits, that are hypothesised to be underpinned by a complex network of genes

(Carlborg & Haley, 2004), complex models like MLPs suffer from the aforementioned problem

of low statistical power and rare variants (Azodi et al., 2019; Bellot et al., 2018).

Effect of the trait evolutionary history on genomic prediction

We found that population demography and the evolutionary history of the trait is also an

important determinant of genomic prediction model selection. Particularly, biochemical traits

were less correlated with population structure than the macroscopic traits. The principal

component analysis of the population genomic data captures the major axis of genomic variation,

and thus provides a concise summary of population structure (Ma & Amos, 2012; Novembre &

Stephens, 2008). For example, a linear combination of PCs explaining 30% of genomic variants

predicted flowering time as well as any marker based model. On the other hand, the most

accurate model that used PCs as predictors only predicted the concentration of metabolite

M130T666 with a 22% accuracy, as well as most accurate model that uses markers as predictors.

Thus in the training population examined, individual markers are informative for the prediction

of simple, typically biochemical, traits while for complex, macroscopic traits, causal variants are

confounded by population structure. Indeed a complex trait like flowering time may be

underpinned by many epistatic effects, but could be obfuscated by population structure,

favouring simpler linear models. Although we do note that we tested an inbred population

sampled at a large geographic scale, which is a point of difference to most genomic prediction

studies. Thus, the effect of population structure we observed might be less pronounced in crossed

study designs. Genomic prediction is genetically diverse training populations is relevant at the

prebreeding step where the aim is often to characterise germplasm as broadly as possible.

Nonetheless, simulation studies using genotypic data from crossed populations have also shown

that structure can benefit the prediction of complex traits if the testing partition of the data

captures similar variation to the training partition (Fodor et al., 2014).

Our findings suggest that the varying degree of correlation between traits and population

structure observed in this study is explained by heterogeneous levels of ancestral selection across

traits. We observed that macroscopic traits on average had stronger biological clines across

longitudinal and latitudinal gradients compared to biochemical traits. We thus expect that such

biological clines are established in response to selection pressures that differ between

environments. It is well established that flowering time is adaptive to specific environments in

Europe (Fournier-Level et al., 2022). The weaker clines in biochemical traits supports the neutral

theory of molecular evolution, which posits that selection occurs mostly at the organismal level

and that molecular traits are generally more neutral than macroscopic traits (Fig. 2c; Kimura,

1985). When considering the hierarchy of phenomes in the biological organisation, it follows

that a mutation affecting a trait at a high level will also influence traits at lower levels.

Macroscopic traits which are under direct selection combine many endophenotypes. However,

individual biochemical traits might not affect the organism at a macroscopic level and thus are

inherently under more relaxed selection (Zhang, 2018). We argue that in addition to genetic

architecture, ensemble approaches were effective for specifically biochemical traits because

these traits are more neutral, and thus less confounded by population structure. Importantly, our

research suggests that within the same population, ancestral patterns of selection affect the

inference of causal variants and the choice of genomic prediction model. As a consequence, the

magnitude of this effect in a natural population can be understood in terms of the hierarchical

organisation of trait ontology.

Conclusion

In light of our results, we suggest that future implementation of genomic prediction should lean

towards ensemble models in addition to linear statistical models when the genetic architecture is

sparse. We also caution that the confounding effect of population structure can vary between

traits within the same population, likely due to selection history. This has the potential to hamper

the generalisation and biological interpretability of genomic prediction models. Non-linear

approaches have a role in genomic prediction, however only for specific genetic architectures,

with strong associations that are not confounded by population structure, or after strong

differential selection in the ancestral populations. Previous work has focused on benchmarking a

wide range of genomic prediction models across select complex traits without focusing on their

organisational hierarchy. Future work would certainly benefit from expanding genomic

prediction methodology through the exploration of the phenome, linking trait ontologies, genetic

architectures, and population histories to modelling strategies.

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Statements & declarations

Conflict of interest

On behalf of all authors, the corresponding author states that there is no conflict of interest.

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Author contributions

PMG, JFP and AFL designed the study, PMG and JFP prepared the material, PMG analysed the

data, PMG and AFL wrote the manuscript.

Data availability

All code and the corresponding analysis used in this paper can be found on the following

repository:

https://github.com/Patrick-Gibbs/Trait-genetic-architecture-and-population-structure-genomic-

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