Title: Motor sequence-specific learning-induced corticospinal plasticity is biased towards

sensorimotor mu rhythm peak phases

Abbreviated title: Mu phase-dependent corticospinal plasticity

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Abstract

Motor cortical (M1) transcranial magnetic stimulation (TMS) interventions increase

corticospinal output and improve motor learning when delivered during sensorimotor mu

rhythm trough but not peak phases, suggesting that the mechanisms supporting motor

learning may be most active during mu trough phases. Based on these findings, we

predicted that motor sequence learning-related corticospinal plasticity would be most evident

when measured during mu trough phases. Healthy adults were assigned to either a

sequence or random group. Participants in the sequence group practiced the implicit serial

reaction time task (SRTT), which contained an embedded, repeating 12-item sequence.

Participants in the random group practiced a version of the SRTT that contained no

sequence. We measured mu phase-independent and mu phase-dependent MEP amplitudes

using EEG-informed single-pulse TMS before, immediately, and 30 minutes after the SRTT

in both groups. All participants performed a retention test one hour after SRTT acquisition. In

both groups, mu phase-independent MEP amplitudes increased following SRTT acquisition,

but the pattern of mu phase-dependent MEP amplitude increases after SRTT acquisition

differed between groups. Relative to the random group, the sequence group showed greater

increases in peak-specific corticospinal output 30 minutes after SRTT acquisition. Contrary

to our original hypothesis, results revealed that motor sequence learning recruits peak-

rather than trough-specific neurophysiological mechanisms. These findings suggest that mu

peak phases may provide protected time windows for motor memory consolidation and

demonstrate the presence of a mu phase-dependent motor learning mechanism in the

human brain.

Keywords: sensorimotor rhythms, motor learning, brain stimulation, phase, motor cortex

Introduction

The sensorimotor cortex is a hub within brain networks controlling human motor skill acquisition. Human sensorimotor cortical activity dynamically oscillates in the mu (8-13 Hz) frequency range, with distinct phases of this rhythm reflecting brief windows of relative excitation and inhibition (Bergmann et al., 2019; Hussain et al., 2019; Suresh & Hussain, 2023; Zrenner et al., 2018). In non-human primates, motor cortical (M1) neuronal spiking rates are highest during mu rhythm trough phases and lowest during opposing peak phases (Haegens et al., 2011). In humans, corticospinal output (Bergmann et al., 2019; Hussain et al., 2019; Suresh & Hussain, 2023; Wischnewski et al., 2022; Zrenner et al., 2018) and interhemispheric communication between homologous M1 subregions (Stefanou et al., 2018) are also increased during sensorimotor mu rhythm trough relative to peak phases.

In addition to shaping single-neuron spiking rates, corticospinal output, and inter-hemispheric communication, sensorimotor mu rhythm phase also determines the likelihood of inducing long-term potentiation-like (LTP-like) corticospinal plasticity in humans. For example, transcranial magnetic stimulation (TMS) interventions applied to M1 during mu rhythm trough phases preferentially induce LTP-like corticospinal plasticity, measured as increases in corticospinal output (Baur et al., 2020; Zrenner et al., 2018). In contrast, identical TMS interventions applied during mu rhythm peak phases induce weak long-term depression-like (LTD-like) corticospinal plasticity, measured as decreases in corticospinal output (Baur et al., 2020; Zrenner et al., 2018). These findings suggest that corticospinal plasticity induction is causally related to sensorimotor mu rhythm phase, with LTP-like and weak LTD-like corticospinal plasticity occurring preferentially during mu rhythm trough and peak phases, respectively. Given that LTP-like plasticity processes have been proposed to support human motor learning (Cantarero et al., 2013a; Cantarero et al., 2013b), and TMS interventions preferentially enhance motor learning when applied during mu rhythm trough phases (Hussain et al., 2021), the neurophysiological mechanisms underlying human motor learning may thus be most active during sensorimotor mu rhythm trough phases.

Outside of the motor system, brain oscillatory activity is thought to rhythmically control

various attentional (Busch & VanRullen, 2010; VanRullen et al., 2011), perceptual

(Baumgarten et al., 2015; Busch et al., 2009; Dugué et al., 2011), and memory processes

(Kerrén et al., 2018; Siegel et al., 2009). For example, the formation and retrieval of

declarative memories has been proposed to occur during opposing hippocampal oscillatory

phases (Hasselmo et al., 2002; Kerrén et al., 2018), object memory formation preferentially

occurs during distinct prefrontal oscillatory phases (Siegel et al., 2009), and replay of whole-

brain neuronal activity patterns associated with working memory are phase-locked to the

theta rhythm (Fuentemilla et al., 2010). These findings suggest that oscillatory phase-

dependent memory processing may be a widespread learning mechanism present across

neural domains (Watrous et al., 2015). If so, phase-dependent neurophysiological signatures

of motor learning should also be detectable within the human motor system.

Here, we reasoned that, if motor learning relies on a sensorimotor mu phase-dependent

mechanism, then learning-related corticospinal plasticity should be more evident during

some mu rhythm phases than others. That is, expression of learning-related corticospinal

plasticity should vary significantly across mu phases. Based on previous studies showing

that corticospinal output (Hussain et al., 2019; Suresh & Hussain, 2023; Zrenner et al.,

2018), interhemispheric communication (Stefanou et al., 2018), corticospinal plasticity (Baur

et al., 2020; Zrenner et al., 2018), and the effects of TMS interventions on motor sequence

learning (Hussain et al., 2021) are all enhanced during mu rhythm trough relative to peak

phases, we predicted that motor sequence learning-related changes in corticospinal output

would be more evident when measured during mu rhythm trough than peak phases.

To test this possibility, we measured sensorimotor mu phase-independent and phase-

dependent corticospinal output using single-pulse, real-time EEG-informed TMS immediately

before and after healthy adults practiced a serial reaction time task (SRTT) that included

either an embedded, repeating 12-item motor sequence (sequence group) or a variation of

the same task that included no sequence (random group). We predicted that mu phase-

dependent corticospinal plasticity would be more prominent for the sequence than the

random group, with motor sequence learning-related corticospinal plasticity being stronger

when measured during mu trough than peak phases. As expected, our results show that

participants in the sequence group exhibited greater sequence-specific learning than those

in the random group. While both groups showed increased mu phase-independent

corticospinal output following SRTT performance, each group exhibited a distinct pattern of

mu phase-dependent corticospinal plasticity. Relative to the random group, the sequence

group showed greater increases in peak- than trough-specific corticospinal output.

Surprisingly, these findings indicate that corticospinal plasticity induced by motor sequence

learning is more prominent during mu rhythm peak than trough phases. Findings highlight

the mechanistic role of mu rhythm phase in behaviorally-relevant corticospinal plasticity

within the human motor system.

Methods

Participants

Thirty-six naïve right-handed healthy adult participants (age = 20.9 ± 0.52, 25 F and 11 M)

participated in a single-session study that involved single-pulse transcranial magnetic

stimulation (TMS), electroencephalography (EEG), electromyography (EMG), and behavioral

testing. Right-handedness was confirmed using the Edinburgh Handedness Inventory

(Oldfield, 1971). This study was approved by the Institutional Review Board at the University

of Texas at Austin and all participants provided their written informed consent. Participants

were randomly assigned to either the sequence group (N = 18, age = 20 ± 0.37 years, 13 F

and 5 M) or the random group (N=18, age = 21.8 ± 0.94 years, 12 F and 6 M) prior to

beginning experimental procedures. This sample size was chosen based on previous

studies that identified significant mu phase-dependent variation in corticospinal output and

corticospinal plasticity, as well as phase-dependent enhancement of motor sequence

learning (N = 12-23, Zrenner et al., 2018; Bergmann et al., 2019; Hussain et al., 2019;

Suresh & Hussain, 2023; Hussain et al., 2021).

Experimental design and timeline

After EEG and EMG preparation, the scalp hotspot for the right first dorsal interosseous

muscle (FDI) and the stimulation intensity needed to elicit motor-evoked potentials (MEPs)

within this muscle were empirically determined for each subject. Participants then performed

a choice reaction time task (cRT), after which parameters for real-time targeting of

sensorimotor mu rhythm phases were individually optimized. Phase targeting accuracy was

assessed during EEG recordings while participants rested quietly with their eyes open.

Then, single-pulse TMS was delivered over the scalp hotspot during sensorimotor mu

rhythm peak, trough, and random phases. Participants subsequently practiced one of two

versions of the serial reaction time task (SRTT; see below for details). Immediately and 30

minutes after task completion, single-pulse TMS was again delivered during mu peak, trough

and random phases. One hour after completing the SRTT, both groups performed a brief

retention test that involved the same SRTT version performed during practice. After retention

testing, all participants completed the Process Dissociation Procedure (PDP; Wilkinson &

Shanks, 2004). The PDP was used to evaluate the development of explicit sequence

awareness, given that corticospinal plasticity following motor sequence learning under

implicit and explicit task conditions may differ (Tunovic et al., 2014). Data from the cRT are

not reported in this manuscript. See Figure 1 for experimental design and timeline.

152
153
Figure 1. Experimental timeline and serial reaction time task. A) Experimental design
and timeline. Real-time EEG analysis algorithm parameters were individually optimized
during resting EEG recordings. After acquisition of phase-independent (random) and phase-
dependent (peak and trough) MEPs at baseline, subjects in both groups performed the
SRTT. Post-SRTT phase-independent and phase-dependent MEPs were recorded
immediately and 30 minutes after SRTT acquisition. SRTT retention was evaluated 1 hour
after SRTT acquisition. **B)** Depiction of implicit SRTT. During acquisition, participants
completed 14 blocks (120 trials per block). During retention, participants completed 7 blocks
(120 trials per block). During sequence blocks, the sequence group practiced the SRTT with
an embedded 12-item sequence, while during these blocks the random group practiced the
task with no sequence (all random blocks).
165

Data acquisition

<u>EEG and EMG recording.</u> 64-channel EEG and bipolar EMG signals were recorded using

TMS-compatible amplifiers (NeurOne Tesla with real-time digital out option, Bittium

Biosignals, Finland). EEG impedances were maintained below 10 kΩ. EMG signals were

recorded from the right FDI using disposable adhesive electrodes placed in a belly-tendon

montage. EEG and EMG were recorded at a sampling rate of 5 kHz, with low-pass hardware

filtering at 1250 Hz and a resolution of 0.001 μV.

Transcranial magnetic stimulation. We empirically determined the motor hotspot as the scalp

site at which suprathreshold, single-pulse TMS elicited a reliable, focal twitch within the right

FDI as well as a peak-to-peak motor evoked potential (MEP) amplitude of at least 50 μV.

After hotspot identification, resting motor threshold (RMT) was determined using an

automatic threshold-tracking algorithm (Borckardt et al., 2006). On average, RMT was 64.3 ±

3.8% of maximum stimulator output for the sequence group and 61.2 ± 3.1% for the random

group. All TMS procedures were performed using a figure-of-eight coil held at ~45° relative

to the midsagittal line (DuoMAG XT-100, Deymed Diagnostic, biphasic pulse shape). Coil

position accuracy was monitored online using frameless neuronavigation (BrainSight, Rogue

Research) during hotspot identification, RMT determination, and mu phase-independent and

mu phase-dependent single-pulse TMS.

Real-time EEG analysis. Real-time EEG-triggered TMS was performed using an established

method (Zrenner et al., 2018; Shirinpour et al., 2020; Hussain et al., 2021; Suresh &

Hussain, 2023). The EEG system was configured to stream data from 5 pre-selected EEG

channels overlying the left sensorimotor cortex (C3, FC3, FC5, CP3 and CP5) using a local

wired network connection (packet rate = 1 kHz, 5 packets per sample) between the EEG

system and a dedicated PC for signal processing (Microsoft Windows 10, 10 cores, Intel i9

processor, 16 GB RAM) using Lab Streaming Layer software (Kothe, 2014) in real-time.

Custom MATLAB scripts were used to receive EEG data, process it, and send TTL triggers

to the TMS device upon detection of the desired mu rhythm phase. During data streaming,

EEG data was first downsampled to 1 kHz. To attenuate the effects of volume conduction,

the Hjorth transformation was applied by subtracting the mean of the surrounding electrodes

(FC3, FC5, CP3 and CP5) from the center electrode (C3; Hjorth 1975). The resulting signal

was then buffered to create overlapping 500 ms windows for real-time analysis. At each time

step, the current data window was zero-phase bandpass filtered using a Finite Impulse

Response (FIR) filter (8-13 Hz, order = 128) and 64 ms data segments at the beginning and

end of the 500 ms window were removed to eliminate edge effects. The remaining 372 ms

data window was then used to fit an autoregressive model (Yule-Walker method, order: 30) that forward predicted the bandpass filtered signal 128 ms into the future. After forward prediction, the Hilbert transform was used to generate an estimated phase angle timeseries signal. The phase estimation algorithm was also configured to trigger TMS only when each participant's sensorimotor mu power exceeded a predefined threshold. To calculate this threshold, resting state EEG data was divided into non-overlapping 500 ms segments, bandpass filtered using a Finite Impulse Response (FIR) filter (8-13 Hz, order = 128), Hjorth transformed, downsampled to 1 kHz and then spectrally decomposed (Welch's method, 4-100 Hz with 0.25 Hz resolution excluding frequencies between 57.75 – 62 Hz to reduce the influence of line noise). For each participant, the median of the resulting frequency-domain signal between 8 and 13 Hz was defined as the power threshold. When the estimated instantaneous phase angle at the time point of interest matched the pre-determined mu phase condition and mu power exceeded each participant's threshold, a single TTL pulse was sent to the TMS system and the EEG system to trigger single-pulse TMS and mark the time of TMS delivery, respectively.

Phase targeting accuracy and real-time EEG-informed single-pulse TMS. Prior to delivering real-time EEG-informed TMS, we first evaluated the accuracy of phase targeting in the absence of TMS delivery in each participant. 25 TTL pulses were sent to the EEG system at mu peak, trough and random phases, but no TMS was delivered (minimum inter-stimulus interval = 5 s + random jitter). During mu phase-independent single-pulse TMS, blocks of 25 TMS pulses were delivered to the scalp hotspot for the right FDI during random mu phases (120% RMT, inter-stimulus interval = 5 s + random jitter). During mu phase-dependent single-pulse TMS, blocks of 25 TMS pulses were delivered during mu peak and trough phases (120% RMT, minimum inter-stimulus interval = 5 s + random jitter). Real-time EEG-informed single-pulse TMS was delivered at baseline, immediately after SRTT acquisition, and 30 minutes after SRTT acquisition. The order of phases targeted per block (i.e., random, peak, and trough) was counterbalanced across participants in both groups.

<u>Serial Reaction Time Task</u>. Participants in both the sequence and random groups were

seated in front of a computer monitor with their right arm resting on a tabletop and their right

hand positioned atop a serial response box (Chronos Response Device, Psychology

Software Tools, see Figure 1). Participants performed one of two modified versions

(sequence or random) of the SRTT (Nissen & Bullemer, 1987; Perez et al., 2007)

programmed using E-prime 3 (Psychology Software Tools). The random group was included

in this study to experimentally account for non-specific effects of motor task engagement

(including repeated keypresses) on corticospinal plasticity. During the SRTT, the monitor

displayed four equally-spaced green dashes against a black background. On each trial, one

of these dashes was replaced by a circle. Prior to beginning the task, participants were

instructed to respond to the presentation of the circle as fast and accurately as possible by

pressing one of the four keys with the corresponding finger of their right hand, as shown in

Figure 1. When the participant pressed the correct key, the circle disappeared, and the trial

was complete. If an incorrect key was pressed, the circle remained on the monitor and the

trial continued until the correct key was pressed. 500 ms elapsed between trials. No

feedback on keypress accuracy or keypress latency was provided.

Participants became familiarized with the task during a practice block that included 10 trials.

During SRTT acquisition, participants in the sequence group performed 14 blocks of

keypresses, with one minute of rest between blocks. Each block was composed of 10

repetitions of a 12-item sequence, amounting to a total of 120 keypresses per block. Blocks

3-7 and 9-13 included a pre-determined, embedded 12-item sequence (2-3-1-4-3-2-4-1-3-4-

2-1). Blocks 1, 2, 8 and 14 were random blocks that contained no embedded sequence.

During SRTT retention, participants in the sequence group performed 7 blocks of 120

keypresses each, again resting for one minute between blocks. Blocks 1 and 7 were random

blocks while blocks 2-6 were sequence blocks.

Random blocks contained no consecutive item repeats and each item had approximately the

same frequency of appearance. Participants in the random group experienced keypresses

that were randomized. Participants were not informed about the presence or absence of the

sequence or its length.

Process Dissociation Procedure. After SRTT retention, participants completed the PDP. The

PDP assesses conscious control over sequence knowledge that may develop during implicit

SRTT paradigms (Destrebecqz et al., 2005; Wilkinson et al., 2009, 2015; Wilkinson &

Jahanshahi, 2007; Wilkinson & Shanks, 2004) and is based on the rationale that conscious

knowledge is both reportable upon request and under intentional control. The PDP consists

of an inclusion and exclusion test, each of which involve 12 unique three-item fragments of

the 12-item sequence that were embedded within the sequence version of the SRTT (e.g., 2-

3-1, 3-1-4, 1-4-3, etc.).

The inclusion test evaluates reportable, consciously accessible knowledge. During the

inclusion test, participants were presented with two elements of each of 12 three-item

fragments and were asked to produce the next element in the fragment by pressing the

corresponding button. The exclusion test evaluates intentional control. During the exclusion

test, participants were again presented with two elements of each of 12 three-item fragments

and were asked to *avoid* producing the next element in the fragment by pressing any button

other than the one that corresponded to the next element in the fragment. At the beginning

of the inclusion and exclusion tests, participants were informed that repeated element

sequences (i.e., a 2 immediately after a 2) were not allowed. For each trial of the inclusion

test, there was a 1/3 probability of pressing the correct key by chance. For each trial of the

exclusion test, there was a 2/3 probability of pressing the correct key by chance. The order

of inclusion and exclusion tests was counterbalanced across participants in both groups.

Data analysis

<u>Serial Reaction Time Task.</u> Reaction times (RTs) were averaged within each block. We

defined acquisition and retention skill as the difference between the mean RT of the last

random block and last sequence block during SRTT acquisition and the difference between

the mean RT of the first random block and first sequence block during SRTT retention,

respectively. We also defined offline changes in skill as the difference between acquisition

skill and retention skill. Here, positive values reflect offline losses while negative values

reflect offline gains.

$$Acquisition\ skill = RT_{Acquisition\ block\ 14} - RT_{Acquisition\ block\ 13}$$

$$Retention\ skill = RT_{Retention\ block\ 1} - RT_{Retention\ block\ 2}$$

$$Offline\ skill\ changes = Acquisition\ skill - Retention\ skill$$

<u>Process Dissociation Procedure.</u> Keypresses during inclusion trials were considered

accurate when the participant correctly completed the 3-element fragment by pressing the

correct key in the sequence. Keypresses during exclusion trials were considered accurate

when the participant correctly avoided the next element in the fragment by pressing one of

the two other key choices. The total number of accurate trials in the inclusion and exclusion

conditions were compared to the corresponding chance levels (i.e., 4/12 for the inclusion test

and 8/12 for the exclusion test) to test for explicit awareness of the embedded sequence.

<u>EEG analysis.</u> EEG signals were processed using a combination of Fieldtrip (Oostenveld et

al., 2010) and custom-written MATLAB scripts. To evaluate phase targeting accuracy, we

segmented EEG data into 6 s segments (± 3 s relative to the targeted phase), and then

demeaned and detrended these segments. To ensure that all offline data analysis

procedures mimicked those applied during real-time phase targeting, we applied the Hjorth

transformation to the EEG data by subtracting the mean of four surrounding sensorimotor

electrodes (FC3, FC5, CP3 and CP5) from the center sensorimotor electrode (C3). Resulting

data segments were zero-phase bandpass filtered using an FIR filter (8-13 Hz). The

instantaneous phase of the filtered signal at the time of phase targeting was identified using

the Hilbert transformation. We then combined phase angles across all subjects per group.

To calculate pre-stimulus sensorimotor mu rhythm power, continuous EEG data obtained

during TMS delivery were segmented into 500 ms segments (0.51 to 0.01 seconds prior to

each TMS pulse), demeaned, linearly detrended and Hjorth transformed (center = C3,

surround = FC1, FC5, CP1, CP5; Hjorth, 1975; Zrenner et al., 2018; Hussain et al., 2021;

Suresh & Hussain, 2023). The resulting Hjorth-transformed signals were then spectrally

decomposed (Welch's method, 4-50 Hz with 0.25 Hz resolution, Suresh & Hussain, 2023).

Each trial's power values were averaged in the mu (8-13 Hz) range to generate a mixed mu

power estimate (i.e., the combination of aperiodic and periodic components of mu power;

Donoghue et al., 2020). Mixed mu power was calculated instead of periodic mu power as our

previous work demonstrated that statistical models including mu rhythm phase and mixed

mu power explain MEP amplitude variation better than those including mu phase and

periodic mu power (Suresh & Hussain, 2023).

<u>MEP analysis</u>. Pre-stimulus EMG activity was filtered with a discrete Fourier transform filter

to reduce line noise. All trials were visually inspected, and those that precluded reliable

calculation of peak-to-peak MEP amplitudes were rejected (3.3% of all trials). We calculated

background EMG as the root-mean-square of pre-stimulus EMG activity between 100 and

25 ms before each TMS pulse. Peak-to-peak MEP amplitudes were calculated as the

maximum voltage deflection between 20 and 40 ms after each TMS pulse. MEP amplitudes

for rejected trials were treated as missing data during statistical analysis. MEP amplitudes

were log-transformed to reduce positive skew and improve statistical model fits (Hussain et

al., 2019; Suresh & Hussain, 2023).

Statistical analysis

<u>Phase targeting accuracy.</u> Phase angle distributions at the time of phase targeting were

evaluated for deviations from a circular uniform distribution in the 90° (peak phases) and

270° (trough phases) directions using separate V-tests for each group. For random phases,

general deviations from circular uniformity were tested using Rayleigh's test. For each group,

mu peak and trough phase angle distributions were compared using the Watson-Williams

test. Phase angle distributions for each condition (peak, trough, and random) were also

compared across groups using the Watson-Williams test.

<u>SRTT acquisition and retention.</u> To evaluate changes in mean RT during SRTT acquisition

and retention, we fit separate linear mixed-effects models (LMMs) for data acquired during

SRTT acquisition and retention periods. These included mean RT as the response variable,

BLOCK (categorical variable: acquisition blocks 1-14, retention blocks 1-7), GROUP

(categorical variable: sequence, random), and BLOCK x GROUP interactions as fixed

effects. PARTICIPANT was included as random intercept. To evaluate changes in skill from

SRTT acquisition to retention, we fit an LMM that included the change in mean RT as the

response variable, TASK (categorical variable: acquisition, retention, offline change),

GROUP (categorical variable: sequence, random), and TASK x GROUP interactions as fixed

effects. Post-hoc pairwise comparisons were used to compare SRTT acquisition and

retention between groups (sequence versus random). To evaluate offline skill, we compared

offline changes to zero using separate single-sample t-tests for the sequence and random

groups.

<u>Process dissociation procedure (PDP).</u> To assess explicit sequence awareness, we

compared fragment completion accuracy to chance using separate single-sample right-tailed

t-tests for the inclusion and exclusion tests. One participant in the random group did not

complete the PDP.

MEP analysis. We first examined the influence of SRTT acquisition on phase-independent

MEP amplitudes using an LMM with GROUP (categorical variable: sequence, random),

TIME (categorical variable: baseline, immediately after SRTT acquisition, 30 minutes after

SRTT acquisition), and the GROUP x TIME interaction as fixed factors, natural log-

transformed POWER (continuous variable) and background EMG (continuous variable) as

covariates, and natural log-transformed MEP amplitudes elicited during random mu phases

as the response variable. The random intercept of PARTICIPANT was also included

(Hussain et al., 2019; Hussain et al., 2021; Suresh & Hussain, 2023).

Next, we evaluated the influence of SRTT task performance on phase-dependent MEP

amplitudes by fitting an LMM that included fixed effects of GROUP (categorical variable:

sequence, random), PHASE (categorical variable: peak, trough), TIME (categorical variable:

baseline, immediately after SRTT acquisition, 30 minutes after SRTT acquisition) and the

GROUP x PHASE x TIME interaction as fixed factors, the PHASE x natural log-transformed

POWER interaction and background EMG (continuous variable) as covariates, and natural

log-transformed MEP amplitudes as the response variable. PARTICIPANT was included as

the random intercept. This LMM revealed a significant three-way interaction (see *Results*).

To further characterize this three-way interaction, we fit separate LMMs for each group.

These post-hoc LMMs included PHASE (categorical variable: peak, trough), TIME

(categorical variable: baseline, 30 minutes after SRTT acquisition), and the PHASE x TIME

interaction as fixed factors, as well as the PHASE x log transformed POWER interaction and

background EMG as covariates. Natural log-transformed mu MEP amplitudes were the

response variable, and PARTICIPANT was included as the random intercept.

Given the mu PHASE x POWER interaction identified in our previous work and that of others

(Bigoni et al., 2024; Hussain et al., 2019; Ozdemir et al., 2022; Suresh & Hussain, 2023) and

our primary interest in evaluating mu phase-dependent corticospinal plasticity, we included

the PHASE x natural log-transformed POWER interaction as a covariate in all our LMMs to

control for this known interaction effect (Hussain et al., 2019; Suresh & Hussain, 2023).

Furthermore, it is well established that pre-stimulus voluntary muscle activation can increase

MEP amplitudes (Hess et al., 1996). To account for any variation in MEP amplitudes caused

by pre-stimulus muscle activation, we also included pre-stimulus background EMG activity

as a covariate in our LMMs. The significance of fixed effects was determined using likelihood

ratio tests. All reported β-coefficients represent the difference in estimates between groups

and phases.

All statistical analyses were performed in R (version 4.3.1). Model fits were visually

inspected using histograms of residuals and quantile-quantile plots. Alpha was equal to 0.05

for all comparisons and p-values were corrected using the Tukey's Honestly Significant

Difference test for multiple comparisons where appropriate. Data are expressed as mean ±

standard error of the mean.

Results

Phase targeting accuracy

Real-time EEG analysis accurately identified and targeted mu peak (Figure 2, target phase =

90°, observed mean phase for sequence group = 85.7° [95% confidence interval {CI} =

80.27°− 91.12°], V = 237.9, p < 0.001; observed mean phase for random group = 86.93°

[95% CI = 80.77°− 93.10°], V = 217.52, p < 0.001) and mu trough phases (target phase =

270°, observed mean phase for sequence group = 271.72° [95% CI = 266.17° − 277.25°], V

= 56.01, p < 0.001; observed mean phase for random group = 269.66° [95% CI = 263.99° −

275.31°], V = 45.71, p = 0.001). As expected, targeted phases differed significantly between

peak and trough conditions in both the sequence group (F = 1687.0, p < 0.001) and the

random group (F = 1495.8, p < 0.001). For random phases, we observed a deviation from

circular uniformity in the 20° direction in the sequence group (R = 5.56, p = 0.003, observed

mean phase = 19.05° [95% CI = 343.15° − 54.95°]) and no significant deviation from

uniformity in the random group (R = 2.47, p = 0.08, observed mean phase = 12.93° [95% CI

= 311.2° − 74.66°]). However, we observed no significant differences in phase targeting

accuracy between the sequence and random groups for any phase (peak: F = 0.11, p =

0.741; trough: F = 0.341, p = 0.559; random: F = 0.188, p = 0.665).

Figure 2. Phase targeting accuracy. A, B) Group-averaged raw and filtered (8-13 Hz) EEG
signals recorded over left sensorimotor cortex during evaluation of mu phase targeting
accuracy in the sequence (A) and random (B) groups. Black vertical lines reflect the time
point at which the real-time EEG analysis algorithm identified mu peak, trough, and random
phases. Shading represents mean ± 1 SEM. **C, D)** Circular histograms indicate the phase
angle of the sensorimotor mu (8-13 Hz) rhythm at the time of phase targeting for peak,
trough, and random phases in the sequence (C) and random (D) groups. **E, F)** Scalp
distribution of C3-Hjorth transformed and band-pass filtered EEG activity during mu peak,
trough and random phases at the time of phase targeting for each phase condition in the
sequence (E) and random (F) groups. Topographical plots reflect average scalp-recorded
EEG signals (filtered between 8-13 Hz) within a 5 ms window centered on the time of phase
targeting. Bolded channels indicate those used to calculate C3-Hjorth transformed EEG
data. Asterisks reflect significance at p < 0.05.

SRTT

During SRTT acquisition, participants in both the sequence and random groups decreased

their mean RTs across blocks (Figure 3, main effect of BLOCK: F = 12.96 and p < 0.001).

RTs did not differ between groups for random blocks, but participants in the sequence group

tended to show faster mean RTs during the sequence blocks than the random group during

the corresponding blocks (BLOCK x GROUP interaction: F = 9.37 and p < 0.001; no main

effect of GROUP: F = 0.63 and p = 0.42). However, post hoc pairwise comparisons did not

identify any significant differences in mean RTs between groups during these blocks (i.e.,

blocks 3-7 or 9-13, see Figure 3). For both groups, mean RTs were not statistically

distinguishable between the first and last random blocks (blocks 1 vs. 14, t < 0.165, p =

0.99). For the sequence group, mean RTs were faster during the last sequence block than

the last random block (block 13 vs. 14, t ratio = -8.51, p < 0.001), but this was not the case

for the random group (t ratio = 0.16, p = 0.99). Finally, acquisition skill was significantly

greater in the sequence than random group (Figure 3, t ratio = 5.94, p < 0.001). Thus, as

expected, participants in the sequence group experienced sequence-specific learning.

During SRTT retention, participants in both groups decreased their mean RTs across blocks

(Figure 3, main effect of BLOCK: F = 18.91 and p < 0.001) and mean RTs were overall

faster for the sequence group than the random group (main effect of GROUP: F = 6.04, p =

0.01). Mean RTs were not statistically distinguishable between groups during random blocks

but were significantly faster for the sequence group than the random group during sequence

blocks (GROUP x BLOCK interaction: F = 21.14, p < 0.001). Post hoc pairwise comparisons

revealed that mean RTs were faster for the sequence group than for the random group

during blocks 4-6 (t > 3.59, p values < 0.03). In addition, retention skill was significantly

greater in the sequence group than the random group (Figure 3, t ratio = 5.17, p < 0.001).

Thus, participants in the sequence group retained sequence-specific skill obtained during

SRTT acquisition. Finally, participants in the sequence group showed significant offline

losses (t = 5.23 p < 0.0001, mean = 98.17 ms [95% CI = 58.61 ms - 137.72 ms] while those

in the random group did not (t = -0.51, p = 0.616, mean = -1.95 ms [95% CI = -10.01 ms -

6.11ms]). However, direct comparison of the magnitude of offline changes revealed no

significant difference between groups (Figure 3, t = 0.76, p = 0.97).

Figure 3. **Serial reaction time task performance. A)** Participants in the sequence group showed sequence-specific decreases in mean RTs during SRTT acquisition and retention. Vertical dotted lines indicate random blocks during the SRTT (practice block not shown). Colored asterisks reflect significance at p < 0.05 for post hoc pairwise comparisons between blocks 13 and 14 during SRTT acquisition and blocks 1 and 2 during retention (green for sequence group). Shading represents the mean ± 1 SEM. **B)** Sequence-specific skill acquisition and retention were greater in the sequence group than in the random group. Asterisks reflect significance at p < 0.05 for post hoc comparisons of acquisition, retention and offline skill changes between groups. Note that for offline changes, positive values reflect offline losses while negative values reflect offline gains. For boxplots, black lines represent median, white dots represent mean, black dots represent individual participants, and error bars represent upper and lower inter-quartile ranges.

Explicit sequence awareness

In the sequence group, mean fragment completion accuracies exceeded chance for the

inclusion test (6 ± 0.66 [SEM], t = 3.02, p = 0.007, chance = 4) but not the exclusion test

(7.72 ± 0.54, t = -0.51, p = 0.61, chance = 8). In the random group, fragment completion

accuracies did not exceed chance for either the inclusion or exclusion tests (Figure 4,

inclusion = 3.88 ± 0.45, exclusion = 7.7 ± 0.54, t < -0.52 for both, p > 0.59 for both). Given

that explicit awareness requires both conscious knowledge of the sequence and the ability to

intentionally control sequence production, there was no strong evidence of explicit sequence

awareness in either group.

Figure 4. Process Dissociation Procedure. Mean number of fragments completed or avoided during the inclusion and exclusion portions of the PDP, respectively. The dashed lines reflect chance performance (4/12 for inclusion and 8/12 for exclusion). For boxplots, black lines represent group median, white dots represent group mean, black dots represent individual participants, and error bars represent upper and lower inter-quartile ranges.

Phase-independent changes in MEP amplitudes

We first characterized the effects of SRTT acquisition on phase-independent MEP

amplitudes elicited during random mu phases. In both groups, MEP amplitudes increased

following SRTT acquisition (significant main effect of TIME; $F = 27.05$, $p < 0.001$, no main

effect of GROUP; $F = 0.67$, $p = 0.41$, no GROUP x TIME interaction, $F = 1.25$, $p = 0.28$).

Post hoc pairwise comparisons revealed that random, phase-independent MEP amplitudes

increased from baseline to immediately after SRTT acquisition ($\beta = -0.08$, t ratio = -2.47, $p =$

0.03), from baseline to 30 minutes after SRTT acquisition ($\beta = -0.24$, t ratio = -7.24, $p <$

0.0001), and from immediately to 30 minutes after SRTT acquisition ($\beta = -0.16$, t ratio = -

4.76, $p < 0.001$). Thus, phase-independent MEP amplitudes increased similarly following

SRTT acquisition in both groups.

Phase-dependent changes in MEP amplitudes

We next evaluated the effects of SRTT acquisition on phase-dependent MEP amplitudes

elicited during mu peak and trough phases. We found a significant three-way GROUP x

TIME x PHASE interaction (Figure 5, likelihood ratio test: $F = 8.53$, $p = 0.0001$). However,

this three-way interaction was only present when comparing changes in MEP amplitudes

from baseline to 30 minutes after SRTT acquisition (no GROUP x TIME x PHASE interaction

for immediately after SRTT: $t = -1.691$, $p = 0.09$, significant GROUP x TIME x PHASE

interaction for 30 minutes after SRTT: $t = 2.42$, $p = 0.01$), indicating that the magnitude of

MEP amplitude changes from baseline to 30 minutes after SRTT acquisition more strongly

differed across mu phases in one group than the other. Given the significant three-way

GROUP x PHASE x TIME interaction present from baseline to 30 minutes after SRTT

acquisition, we evaluated mu phase-dependent changes in MEP amplitudes across these

two time points separately for each group. For the sequence group, this post-hoc analysis

revealed a significant effect of PHASE ($F = 4.14$, $p = 0.04$) and TIME ($F = 69.85$, $p <$

0.0001), but no PHASE x TIME interaction ($F = 3.09$, $p = 0.07$). Post-hoc pairwise

comparisons further revealed that MEP amplitudes were significantly larger during mu trough

than peak phases (t ratio $= -2.15$, $p = 0.03$), while MEP amplitudes elicited during both

phases were significantly larger 30 minutes after SRTT acquisition than baseline (t ratio $= -$

8.35, $p < 0.0001$). For the random group, post-hoc analysis revealed a significant effect

PHASE ($F = 25.67$, $p < 0.0001$), TIME ($F = 97.58$, $p < 0.0001$) and a significant PHASE x

TIME interaction ($F = 4.74$, $p = 0.02$). Post-hoc pairwise comparisons additionally showed no

differences between peak and trough MEP amplitudes at baseline (t ratio $= -1.68$, $p = 0.33$),

but MEP amplitudes were larger during trough than peak phases 30 minutes after SRTT

acquisition (t ratio $= -4.76$, $p < 0.0001$).

Figure 5. Mu phase-independent and phase-dependent changes in corticospinal output. A) Group-level linear mixed-effects model coefficients depicting relationships between mu phase-independent MEP amplitudes and group at baseline, immediately and 30 minutes after SRTT acquisition. **B)** Group-level linear mixed-effects model coefficients depicting relationships between mu phase-dependent MEP amplitudes and group at baseline, immediately, and 30 minutes after SRTT acquisition. For A and B, dots represent model coefficients and error bars indicate SEM. For A, black asterisks reflect significant post hoc pairwise comparisons across time points. For B, text above each panel indicates results of the PHASE x TIME interaction, and the black asterisk reflects significant GROUP x PHASE x TIME interaction for the random group.

To visualize differences in mu phase-dependent MEP amplitude changes between groups

(i.e., in the sequence group relative to the random group) identified by the GROUP x PHASE

x TIME interaction, we subtracted random group model-fitted MEP amplitudes from

sequence group model-fitted MEP amplitudes (Figure 6). This subtraction illustrated that

sequence-specific learning-related corticospinal plasticity was significantly greater during mu

rhythm peak than trough phases thirty minutes after SRTT acquisition.

Figure 6. Effects of motor sequence-specific learning on mu phase-dependent corticospinal plasticity. At each time point, group-level model fitted MEP amplitudes obtained during mu peak and trough phases in the random group were subtracted from corresponding group-level model fitted MEP amplitudes in the sequence group. Asterisk reflects significant 3-way interaction of GROUP x PHASE x TIME.

Discussion

Based on our previous work showing that mu phase-dependent TMS interventions coupled

to sensorimotor mu rhythm trough but not peak phases improve motor sequence learning,

we predicted that sequence learning-related corticospinal plasticity would be more evident

when measured during sensorimotor mu rhythm trough than peak phases. To test this

hypothesis, we delivered single-pulse, real-time EEG-informed TMS during mu rhythm peak,

trough, and random phases immediately before and after healthy adults performed a version

of the implicit SRTT that included either an embedded, repeating motor sequence (sequence

group) or no sequence (random group). Behaviorally, participants in the sequence group

acquired greater sequence-specific knowledge than participants in the random group and

also retained this knowledge over time. Physiologically, participants in both groups showed

mu phase-independent increases in corticospinal output following SRTT acquisition,

reflecting the occurrence of significant mu phase-independent corticospinal plasticity that did

not differ between participants who did and did not acquire sequence-specific knowledge.

However, we identified differences in mu phase-dependent changes in corticospinal output

between groups. In the sequence group, SRTT acquisition elicited corticospinal plasticity

that was similar in magnitude across mu peak and trough phases. However, in the random

group, SRTT acquisition elicited corticospinal plasticity that was greater during mu trough

than peak phases. Direct comparisons between groups showed that participants in the

sequence group exhibited greater peak-specific corticospinal plasticity than those in the

random group. These findings strongly suggest that performance of each SRTT variant

elicits phase-independent corticospinal plasticity, while sequence learning *per se* elicits

stronger corticospinal plasticity during mu peak than trough phases.

Motor learning potentiates corticospinal output (Pascual-Leone et al., 1994; Perez et al.,

2007) and occludes subsequent induction of LTP-like corticospinal plasticity (Cantarero et

al., 2013a; Cantarero et al., 2013b). This occlusion is thought to support retention of newly-

acquired motor skills, such that its experimental reversal significantly diminishes retention

(Cantarero et al., 2013a). Thus, LTP-like corticospinal plasticity and its occlusion both play

key mechanistic roles in motor learning. Like motor learning, repetitive TMS interventions

can also induce corticospinal plasticity. Specifically, recent studies using real-time EEG-TMS

have shown that both low- and high-frequency repetitive TMS interventions preferentially

induce LTP-like corticospinal plasticity when applied during sensorimotor mu trough but not

peak phases (Baur et al., 2020; Zrenner et al., 2018). Such mu phase-dependent

corticospinal plasticity could therefore reflect a common neurophysiological mechanism

underlying the effects of repetitive TMS interventions and motor learning. If mu phase-

dependent corticospinal plasticity does support motor learning, then TMS interventions

should more strongly affect motor learning when delivered during specific mu phases. We

previously evaluated this possibility by measuring the effects of a low-frequency mu phase-

dependent repetitive TMS intervention on offline changes in explicit motor sequence task

performance (Hussain et al., 2021). In that study, repetitive TMS delivered during mu trough

but not peak phases enhanced offline gains in motor sequence performance. These findings

raised the intriguing possibility that the neurophysiological mechanisms underlying motor

learning may be most active and thus most susceptible to modification during sensorimotor

mu trough phases. However, in the current study, mu phase-dependent corticospinal

plasticity was biased towards mu peak phases in the sequence group relative to the random

group.

What could explain these surprising findings? Our experimental design directly compared

changes in MEP amplitudes following performance of one of two related motor tasks. In the

sequence group, participants performed repeated keypresses while also acquiring

knowledge of an embedded sequence, while in the random group, participants performed

repeated keypresses in the absence of any embedded sequence. To isolate the effects of

sequence learning on mu phase-dependent corticospinal plasticity, we therefore subtracted

random group model-fitted MEP amplitudes from sequence group model-fitted MEP

amplitudes. This direct contrast revealed that sequence learning, after accounting for the

effects of repeated keypresses, induced mu phase-dependent corticospinal plasticity that

was biased towards mu peak phases. We previously proposed that mu rhythm peak phases

reflect a neutral excitability state that is not strongly affected by synchronization of

corticothalamic inputs to layer V pyramidal cells (Hussain et al., 2019). Specifically, M1

single neuron spiking rates are lower during mu rhythm peak than trough phases in non-

human primates (Haegens et al., 2011), which may correspond to the decreased

corticospinal output observed during mu peak relative to trough phases in humans

(Bergmann et al., 2019; Hussain et al., 2019; Suresh & Hussain, 2023). Indeed, Bergmann

et al. (2019) showed that mu peak phases reflect a lack of pulsed excitation rather than

pulsed inhibition of corticospinal output. Together, these previous findings suggest that mu

peaks reflect brief quiescent windows during which corticospinal and sensorimotor network

communication is diminished relative to mu troughs. As a result, neural activity should only

weakly propagate through an extended sensorimotor network during mu peak phases. We

and others previously provided empirical support for this possibility by showing that (1) TMS-

related whole-brain broadband power, an indirect marker of population-level neuronal

spiking (Gao et al., 2017; Manning et al., 2009), is weaker when M1 TMS delivery coincides

with mu rhythm peak than trough phases (Hussain et al., 2021), and (2) interhemispheric

communication between bilateral motor cortices is lower during mu peak than trough phases

(Stefanou et al., 2018). The decreased network communication that occurs during mu peak

phases may prevent motor sequence memories from being disrupted by task-irrelevant

sensory information carried by thalamocortical projections, such that sequence memories

can be replayed and consolidated by sensorimotor and hippocampal networks without

interference (Buch et al., 2021; Jacobacci et al., 2020; Robertson & Genzel, 2020). This idea

aligns with previous work showing that wakeful rest after motor sequence learning supports

consolidation and retention of the learned sequence (Bönstrup et al., 2019, 2020; Buch et

al., 2021; Robertson, 2019; Robertson et al., 2004; Walker et al., 2003). Mu peak phases

could therefore provide a protected time window during which replay and consolidation of

motor sequence memories may occur. Such a scenario could explain why sequence-specific

learning-related corticospinal plasticity was more pronounced during mu peak phases in the

current study. Future work could directly evaluate this possibility by examining sensorimotor

mu phase-dependency of motor sequence replay or altering mu peak phase properties

immediately following motor sequence learning using closed-loop neurofeedback paradigms.

Although we previously suggested that the neurophysiological mechanisms underlying motor

sequence learning may be most active during sensorimotor mu trough phases (Hussain et

al., 2021), here we report that corticospinal plasticity following motor sequence-specific

learning is more strongly expressed during mu peak than trough phases. Two key

differences between our previous work and the current study could explain these diverging

results. First, the current study used the implicit SRTT, while our previous work used the

explicit motor sequence learning task. Although both tasks involve acquisition of sequential

knowledge, they rely on dissimilar sensorimotor networks. Specifically, the implicit SRTT

likely more heavily recruits corticostriatal circuits (Grafton et al., 1995; Hazeltine et al., 1997),

while the explicit motor sequence learning task may more strongly engage prefrontal and

premotor areas (Pinsard et al., 2019; Yokoi & Diedrichsen, 2019). Given the fundamental

role of oscillatory phase in inter-regional neural communication (Fries, 2005, 2015;

Womelsdorf et al., 2007), these two brain networks may optimally interact with sensorimotor

cortical neuronal populations during different mu rhythm phases. Second, the current study

directly assessed within-session phase-dependent neurophysiological changes induced by

motor sequence learning, whereas our previous work examined the influence of a phase-

dependent TMS intervention on between-session behavioral changes in motor sequence

performance. Thus, corticospinal plasticity supporting motor sequence-specific learning may

be most evident during mu peak phases, while TMS interventions may best improve motor

sequence learning during mu trough phases. Along these lines, it is possible that the

neurophysiological mechanisms supporting motor sequence-specific learning are maximally

active during mu peak phases, such that peak-specific TMS interventions cannot further

upregulate them. If so, the same neurophysiological mechanisms may be only partially

active during mu trough phases, allowing them to be further enhanced by trough-specific

TMS interventions. Regardless, our current findings and previous work both support the

notion that the neurophysiological mechanisms underlying motor sequence learning are

sensorimotor mu phase-dependent, although the precise contributions of mu peak and

trough phases to different aspects of such learning require further investigation.

Unexpectedly, we observed that mu phase-dependent variation in corticospinal output

associated with non-sequence-specific learning emerged 30 minutes after SRTT acquisition

in the random group. One possible explanation for this observation is that the repetitive

keypress movements performed during the random version of the SRTT induced use-

dependent plasticity that is biased towards mu rhythm trough phases. Given that acquiring

real-world motor skills involves multiple learning mechanisms, sequence-dependent learning

mechanisms that are most evident during mu peak phases could co-occur with use-

dependent plasticity mechanisms that may be biased towards mu trough phases. Although it

is tempting to interpret the mu phase-dependent MEP differences identified in the random

group as direct evidence of non-sequence-specific learning-related plasticity, our study was

not specifically designed to address this possibility. Future work aimed at establishing

relationships between use-dependent plasticity and sensorimotor rhythm phase should

directly examine phase-dependent directional biases of TMS-evoked movements (Bütefisch

et al., 2000; Mawase et al., 2017).

Our findings may also have implications for motor learning after stroke. Stroke-related brain

lesions can either directly or indirectly alter sensorimotor rhythms by disrupting their cortical

sources (Salmelin & Hari, 1994), their subcortical pacemaker cells (Hughes & Crunelli,

2005), or anatomical connections between them. For example, sensorimotor mu rhythms

weaken and slow after stroke (Hussain et al., 2020; Johnston et al., 2023). Given the role of

sensorimotor mu rhythm phase in the sequence-specific learning-related corticospinal

plasticity identified here, stroke-related changes in mu rhythm properties could interfere with

the neurophysiological mechanisms underlying motor learning, limiting motor skill

(re)acquisition and retention during neurorehabilitation. Accordingly, the presence or

absence of mu phase-dependent corticospinal plasticity in stroke survivors could predict

each individual's capacity for rehabilitation-related motor recovery, and strategically

delivering mu phase-specific TMS interventions prior to rehabilitative training could enhance

rehabilitation's effects in individuals with intact sensorimotor mu rhythm-generating circuits.

Indeed, the combined effects of mu phase-dependent TMS interventions and motor

rehabilitation on poststroke upper extremity motor recovery are currently being evaluated via

a multi-center randomized controlled trial (Lieb et al., 2023). However, nearly all studies

evaluating sensorimotor mu phase-dependency within the human motor system have

focused on neurotypical adults (Baur et al., 2020; Bergmann et al., 2019; Stefanou et al.,

2018; Suresh & Hussain, 2023; Zrenner et al., 2018), and whether similar mu phase-

dependent mechanisms support TMS-induced and learning-related corticospinal plasticity

after stroke is still unknown.

Several strengths of this study exist. First, our experimental design included two groups: one

that experienced sequence learning and one that did not. This design allowed us to

dissociate the effects of sequence-specific and non-sequence-specific learning on mu

phase-independent and phase-dependent corticospinal plasticity. Of note, non-specific

effects of motor task engagement are often not considered in motor sequence learning

studies, including our own previous work (Hussain et al., 2021; Bönstrup et al., 2019, 2020;

Perez et al., 2007; Walker et al., 2003). However. without directly contrasting phase-

dependent corticospinal plasticity between the sequence and random groups, the current

study would have failed to identify any role of mu phase-dependent corticospinal plasticity in

sequence learning. Second, we quantified both mu phase-independent and phase-

dependent corticospinal plasticity. This quantification showed that mu phase-independent

corticospinal plasticity can be elicited by repeated keypresses even in the absence of

sequence learning itself. Third, participants were not required to meet any pre-defined

neurophysiological criteria to participate in this study; our results are likely to be more

generalizable across diverse groups of participants than previous studies using similar

techniques (Baur et al., 2020; Zrenner et al., 2018). Finally, rather than inferring the

existence of a phase-dependent learning mechanism from an interventional study (Hussain

et al., 2021), here we specifically quantified phase-dependent neurophysiological changes

induced by sequence-specific and non-sequence-specific learning. Thus, the results of the

current study can be directly attributed to sequence learning *per se* rather than the combined

effects of sequence learning and a phase-dependent TMS intervention.

While our study provides novel insights into phase-dependent mechanisms of motor

learning, it is not without limitations. First, previous studies have shown that mu rhythm

phase and power interdependently influence corticospinal output at rest (Hussain et al.,

2019; Ozdemir et al., 2022; Suresh & Hussain, 2023), but here we evaluated only mu phase-

dependent changes in corticospinal output. Although this was achieved by introducing a

covariate into our statistical models that controlled for mu phase-power interactions, this

approach does not capture more complex learning-related changes in mu phase-power

interactions. Second, we did not measure changes in corticospinal output during other mu

phases (Wischnewski et al., 2022; Zrenner et al., 2023), other sensorimotor rhythms

(Hussain et al., 2019; Wischnewski et al., 2022) or broadband activity (Davis et al., 2022).

Experimental designs using phase-independent measures of corticospinal excitability and

post hoc trial sorting approaches may be better suited to explore the contribution of other

brain rhythms and phases to learning-related corticospinal plasticity. Finally, the SRTT

requires participants to activate several intrinsic and extrinsic hand muscles, and we only

recorded MEP amplitudes from the FDI. Future studies that record MEPs from multiple task-

relevant muscles could provide richer information on sequence learning-related corticospinal

plasticity.

In conclusion, we report that corticospinal plasticity elicited by motor sequence-specific

learning is biased towards sensorimotor mu rhythm peak phases, providing first direct

evidence that motor learning induces mu phase-dependent corticospinal plasticity in

humans. Overall, these findings suggest that mu peak phases may provide brief protected

time windows for motor sequence memory consolidation and establish the mechanistic role

of sensorimotor mu rhythm phase in behaviorally-relevant corticospinal plasticity.

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