A hybrid approach to invertebrate biomonitoring using computer vision and DNA metabarcoding

Jarrett D. Blair [1,2], Michael D. Weiser [3], Cameron Siler [3,4], Michael Kaspari [3,5], Sierra N. Smith [3,4,6], Jessica F. McLaughlin [3,4], Katie E. Marshall [1]

[1] Department of Zoology, University of British Columbia, Vancouver, BC V6T 1Z4, Canada

[2] Department of Ecoscience, Aarhus University, 8000 Aarhus C, Denmark

[3] School of Biological Sciences, University of Oklahoma, Norman, OK 73019-0235, USA

[4] Sam Noble Oklahoma Museum of Natural History, University of Oklahoma, Norman, OK 73072-7029, USA

[5] Conservation Ecology Center, Smithsonian's National Zoo and Conservation

[6] Department of Biology Institute, Front Royal, VA 22630, University of Texas at Arlington, Arlington, TX, 76019, USA.

Corresponding author: Jarrett Blair, Department of Ecoscience, Aarhus University, C.F. Møllers Allé 8, 8000 Aarhus C, Denmark, jarrett@ecos.au.dk

<u>Abstract</u>

1. Automated invertebrate classification using computer vision has shown significant

potential to improve specimen processing efficiency. However, challenges such as

invertebrate diversity and morphological similarity among taxa can make it difficult to

infer fine-scale taxonomic classifications using computer vision. As a result, many

invertebrate computer vision models are forced to make classifications at coarser levels,

such as at family or order.

2. Here we propose a novel framework to combine computer vision and bulk DNA

metabarcoding specimen processing pipelines to improve the accuracy and taxonomic

granularity of individual specimen classifications. To improve specimen classification

accuracy, our framework uses multimodal fusion models that combine image data with

DNA-based assemblage data. To refine the taxonomic granularity of the model's

classifications, our framework cross-references the classifications with DNA

metabarcoding detections from bulk samples. We demonstrated this framework using a

continental-scale, invertebrate bycatch dataset collected by the National Ecological

Observatory Network. The dataset included 17 taxa spanning three phyla (Annelida,

Arthropoda, and Mollusca), with the finest starting taxonomic granularity of these taxa

being order-level.

3. Using this framework, we reached a classification accuracy of 79.6% across the 17 taxa

using real DNA assemblage data, and 83.6% when the assemblage data was "error-free",

resulting in a 2.2% and 6.2% increase in accuracy when compared to a model trained

using only images. After cross-referencing with the DNA metabarcoding detections, we

improved taxonomic granularity in up to 72.2% of classifications, with up to 5.7%

reaching species-level.

4. By providing computer vision models with coincident DNA assemblage data, and

refining individual classifications using DNA metabarcoding detections, our framework

has the potential to greatly expand the capabilities of biological computer vision

classifiers. This framework allows computer vision classifiers to infer taxonomically

fine-grained classifications when it would otherwise be difficult or impossible due to

challenges of morphologic similarity or data scarcity. This framework is not limited to

terrestrial invertebrates and could be applied in any instance where image and DNA

metabarcoding data are concurrently collected.

1. Introduction

Computer vision has the potential to transform invertebrate ecology by automating estimations of invertebrate abundance, biomass, and diversity (Høye *et al.*, 2021; Schneider *et al.*, 2022). However, accurately classifying invertebrate species using computer vision is challenging. This is partly due to the sheer diversity of invertebrates, as there are an estimated 7.5 million (~1.5 million named) terrestrial invertebrates species globally (Stork, 2018). This has led most invertebrate classification models to opt for coarser taxonomic granularity (e.g. order-level instead of species-level classifications) with relatively few unique classification groups (usually <50; (Ärje *et al.*, 2020; Blair *et al.*, 2022; Schneider *et al.*, 2022). However, ecology studies can involve hundreds or thousands of species, which poses a challenge for simpler machine vision techniques.

One way computer vision models have overcome the challenge of handling many thousands or millions of classification labels is by including additional data modalities such as contextual metadata (e.g. collection location) in computer vision models. The mobile app iNaturalist uses this spatiotemporal data in combination with user-submitted photos to classify nearly 80,000 taxa across the tree of life (Leary *et al.*, 2023). Other studies conducted on a smaller scale have also found substantial improvements to classification accuracy with multimodal models that include both metadata and images compared to image-only models (Berg *et al.*, 2014; Terry, Roy and August, 2020; Blair *et al.*, 2022). However, despite the potential improvements in accuracy, there are several pitfalls to consider when including spatiotemporal metadata in a computer vision model. For one, spatiotemporal metadata is a lagging indicator of species habitat occupancy (i.e. the presence or absence of a species at a given place and time), and as such it is susceptible to data drift over time (Friedland, 2024). That is, spatiotemporal distributions of taxa

change over time, but computer vision models can only learn from past data. Unless a computer

vision model is updated frequently with more recent data, the species range distributions it has

learned may quickly become outdated. Finally, when dealing with many machine learning

classes, spatiotemporal metadata does not solve the challenge of gathering enough training data

to sufficiently train a computer vision model (Beery, Van Horn and Perona, 2018; Beery *et al.*,

2020). In short, studies that incorporate spatiotemporal metadata have shown that supplemental,

non-visual data can improve ecological computer vision models, but spatiotemporal metadata

itself has several potential drawbacks. In this study, we leverage an alternative data stream that

does not pose the same challenges associated with spatiotemporal metadata: DNA

metabarcoding.

DNA metabarcoding is an established tool in ecological research that allows for multiple species

to be identified from a single sample using high-throughput sequencing (Deiner et al., 2017; Liu

et al., 2020; Taberlet et al., 2012). Using this method, DNA can be collected from the

environment (eDNA) or from preservative media (e.g. ethanol in insect bycatch samples),

sequenced, and then used to infer ecological metrics such as species richness and community

composition (Wood *et al.*, 2017; Marquina *et al.*, 2019; Weiser *et al.*, 2022). Due to its improved

cost-effectiveness, DNA metabarcoding is becoming more frequently used in large-scale studies

where traditional morphological identification techniques cannot keep up financially or

logistically (Liu et al., 2020). However, despite being an excellent tool for detecting occurrence

at fine taxonomic granularity (even below species-level; Stewart & Taylor, 2020; Wilcox et al.,

2015), DNA metabarcoding cannot be used to reliably estimate species abundance or biomass

(Bista *et al.*, 2018; Lamb *et al.*, 2019). Instead, eDNA metabarcoding is more suitable for binary

presence/absence detections of species. Additionally, while DNA metabarcoding is generally

reliable for taxonomic identifications, it is not exempt from false positive and false negative

detections (Guillera-Arroita *et al.*, 2017). Some examples of how this may occur include DNA

contamination and primer mis-priming (false-positives), or DNA degradation and insufficient

sampling effort (false-negatives) (Guillera-Arroita *et al.*, 2017; Liu *et al.*, 2020). Therefore,

while DNA metabarcoding offers considerable advantages for biodiversity assessment (e.g.,

species inventories, species richness) its limitations often necessitate the use of complementary

indicators such as visual observations for other metrics (e.g., abundance, biomass) (Schneider et

al., 2022).

Given DNA metabarcoding's ability to produce reliable fine-scale community composition data,

and computer vision's ability to measure abundance and biomass at coarse taxonomic

granularity, several studies have called for a synergistic classification pipeline that takes

advantage of the strengths of each tool (Badirli et al., 2023; Schneider et al., 2022; Sys et al.,

2022). In theory, such a pipeline could leverage DNA metabarcoding's fine taxonomic

granularity against computer vision's ability to infer specimen-level characteristics (identity,

morphology, etc.) to make ecological inferences that would not be possible using either data

stream on their own. DNA might also be a favourable alternative to spatiotemporal metadata, as

it is a more direct and coincident indicator of species habitat occupancy, likely making it more

resistant to data drift over time (Taberlet *et al.*, 2018). Despite the potential benefits of

multimodal image-DNA classification models for ecological research, few studies have explored

this approach. Additionally, proposed hybrid classification pipelines either leave the DNA and

image data streams separate (Sys *et al.*, 2022), or sequence specimens individually, and thus do

not take advantage of metabarcoding's ability to process bulk samples (Badirli *et al.*, 2023).

Here we present a novel approach for identifying and classifying invertebrate taxa which

integrates DNA metabarcoding and computer vision. The objective of this hybrid approach is to

improve the accuracy and taxonomic granularity of computer vision classifications by adding

concurrent community assemblage data derived from DNA metabarcoding into a bulk specimen

classification pipeline (Figure 1). The combination of DNA and image data occurs twice

throughout the pipeline: first during classification inference in the computer vision model, and

then again as a post-processing step for the model's classifications. While developing this

approach, we ask two primary questions: (1) How does error in DNA metabarcoding data affect

the accuracy of the computer vision classification model? (2) What are the strengths and

limitations of different taxonomic granularity refinement methods? In addition to the case study

we present here, we have also developed a GitHub repository to allow this framework to easily

be adapted to other study systems (Blair, 2024).

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Figure 1: Our framework for combining computer vision and DNA metabarcoding to improve the
accuracy and taxonomic granularity of classifications. (a) Images and DNA metabarcoding data are
collected concurrently from bulk samples. (b) Images and DNA assemblage data are used as input for a
multimodal classification model. The features of the image input are extracted using a convolutional
neural network. The DNA assemblage data provides presence/absence information for the model's known
classes and is input as a binary vector into a dense neural network. The image features and the DNA
features are concatenated and processed to produce a final classification. (c) By interpreting the DNA
metabarcoding detections hierarchically and cross-referencing them with the model's classifications, the
taxonomic granularity of the classifications can be refined.

2. Methods

2.1 Data collection

2.1.1 Specimen collection

Each year, the National Ecological Observatory Network (NEON) performs standardized pitfall

trap array sampling across the United States, including Alaska, Hawaii, and Puerto Rico

(Hoekman et al. 2017). The focal taxa of the pitfall trap array project are ground beetles

(Coleoptera: Carabidae), which are collected, identified, and counted by NEON staff members

once every two weeks during the growing season (defined as "the weeks when average minimum

temperatures exceed 4 °C for 10 days and ending when temperatures remain below 4 °C for the

same period", Kaspari et al., 2022). The remaining pitfall trap contents are set aside as

'Invertebrate Bycatch' and archived in 95% ethanol-filled 50 mL falcon tubes. Hereon, a single

collection period from a pitfall trap plot is referred to as a "sampling event".

The invertebrate bycatch specimens used in this research were taken from 56 NEON trap plots

from 27 sites (usually two plots per site; Figure 2, Figure S.1). Generally, we used three

sampling events per plot, selected at the beginning, middle, and end of each site's growing

season. This resulted in a total of 150 sampling events. All sampling events used here were

collected in 2016 and processed in 2019. The focus of this project was to classify the invertebrate

bycatch, so ground beetles and non-invertebrate specimens were not considered.

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Figure 2: Map of the 27 NEON sampling sites used in this study. The sites are labelled with their
abbreviated names.

<u>2.1.2 Imaging</u>

The contents of each 50mL falcon tube were spread out across a 20.32 cm ✖ 30.48 cm (8" ✖

12") white ceramic tile and photographed at a resolution of 729 pixels per mm^2, as described by

Weiser et al., 2021 (Figure S.2). Using the FIJI implementation of ImageJ (Schindelin et al.,

2012), each specimen was detected and cropped to its bounding box to produce a final image.

<u>2.1.3 DNA extraction and metabarcoding</u>

The DNA metabarcoding data used in this study was collected for Weiser et al., 2022, which

used the same sampling events described in Section 0. In brief, DNA metabarcoding was

conducted on a per-tube basis (Figure S.1). Ethanol from each falcon tube was filtered

individually (i.e., one filter per tube) and DNA was extracted from the filters using established

protocols (Weiser et al., 2022). The cytochrome c oxidase I (COI) barcode region (141-254 base

pairs) was then amplified using a two-step polymerase chain reaction (PCR) protocol and

sequenced on an Illumina MiSeq. Three COI primers were used: 157, LCO, and Lep (Rennstam

Rubbmark et al., 2018; Hajibabaei et al., 2019; Weiser et al., 2022). Sequences were clustered

into Operational Taxonomic Units (OTUs) and each OTU was assigned a taxonomic

classification using NCBI BLASTn (Altschul *et al.*, 1990) and Integrated Taxonomic

Information System (ITIS) (U.S. Geological Survey, 2013). Only sequences with $\geq 97\%$

similarity between the OTU consensus sequence and the BLASTn search were used. See Weiser

et al., 2022 for the full DNA extraction and metabarcoding methods.

In total, across all sampling events, there were 10,212 DNA metabarcoding detections. To align

the DNA data with the imaging data, we removed any DNA detections from sampling events not

included in the image dataset, as well as duplicate detections (i.e. multiple detections of the same

taxon in a single sampling event, for example due to amplification using multiple primers). This

yielded a final DNA metabarcoding dataset with 3,361 detections and 1,212 unique taxa,

primarily consisting of family (369 detections; 85 unique), genus (468 detections; 183 unique),

and species-level (2,471 detections; 922 unique) detections.

2.2 Data and labelling

2.2.1 Computer vision class labels

The taxonomic scope of the image and DNA metabarcoding data spanned three invertebrate phyla: Annelida, Arthropoda, and Mollusca. The specimen images were labelled by a single technician to the best of their ability (as described in Blair *et al.*, 2022). The final labels used for our study ranged from order to phylum-level. Classes with a taxonomic granularity coarser than order-level but with no subtaxa present in the dataset (e.g. Phylum: Annelida) were included. Specimens labelled as nested classes at a taxonomic granularity coarser than order-level (Phylum: Arthropoda, Class: Insecta, and Class: Arachnida) were excluded. Classes with fewer than 100 specimens in the dataset were also excluded. This resulted in a final image dataset with a total of 36,988 specimens across 17 classes (13 orders and one subclass, class, subphylum, and phylum; Figure 3).

Annelida
Acari
Araneae
Opilioacarida
Opiliones
Collembola
Blattodea
Coleoptera
Diptera
Hemiptera
Hymenoptera
Lepidoptera
Orthoptera
Zygentoma
Isopoda
Myriapoda
Gastropoda

5 mm

Figure 3: Collage of photographs of all invertebrate classes used in the training dataset (n = 17). The
taxonomic granularity of the classes ranges from order to phylum. Specimens were cropped from their
original photographs, and the background was removed. Relative scale of each specimen is conserved.

<u>2.2.2 Hierarchical labels</u>

Hierarchical labels containing taxonomic information at multiple levels and were assigned to

images and sampling events. Image-based hierarchical labels contained information at six levels

from phylum to order-level for individual specimens (Table 1). DNA-based hierarchical labels

contained information at 13 levels from phylum to species for all DNA detection in each

sampling event (Table 2). The levels in the DNA-based hierarchical labels were phylum,

subphylum, class, subclass, superorder, order, suborder, infraorder, superfamily, family,

subfamily, genus, and species. We used these labels as part of the taxonomic granularity

improvement process detailed in Section 2.5.

Table 1: Three examples image-based hierarchical labels (a,b,c). (a) The hierarchical label for Blattodea
with all taxonomic levels between phylum and order filled. (b) Some taxa do not have names for every
taxonomic sub-level. In these cases, the name from the preceding, finer-grain level is used. In this
example, Coleoptera does not belong to any superorder, so "Coleoptera" is used as a placeholder
superorder name. (c) Classes with a taxonomic granularity above order-level used indeterminate ("indet.")
labels at all remaining taxonomic levels. In this example, "Annelida indet." is used for all levels below
phylum.

Example	Phylum	Subphylum	Class	Subclass	Superorder	Order
(a)	Arthropoda	Hexapoda	Insecta	Pterygota	Polyneuroptera	Blattodea
(b)	Arthropoda	Hexapoda	Insecta	Pterygota	*Coleoptera*	Coleoptera
(c)	Annelida	*Annelida indet.*	*Annelida indet.*	*Annelida indet.*	*Annelida indet.*	*Annelida indet.*

203 Table 2: Simplified example of a DNA multi-class hierarchical label for a sampling event. Our DNA
204 hierarchical labels used 13 taxonomic levels from phylum to species, but for the sake of space only major
205 taxonomic levels are shown here.

Phylum	Class	Order	Family	Genus	Species
Arthropoda	Insecta	Diptera	Culicidae	*Aedes*	*A. vexans*
				Culex	*C. salinarius*
		Orthoptera	Gryllidae	*Gryllus*	*G. veletis*
	Arachnida	Araneae	Lycosidae	*Schizocosa*	*S. humilis*

2.2.3 Binary assemblage data

Two sets of binary assemblage data were recorded for each sampling event: one using detections

from the image labels and one using detections from the DNA class labels. DNA class labels

were based on the same 17 classes used by the computer vision model, and followed the same

naming scheme described in Section 0. The assemblage data was multi-hot encoded

(Goodfellow, Yoshua and Courville, 2016). That is, each sampling event was assigned a 17

element long binary vector where each element corresponded to a computer vision class. If the

class was detected in the sampling event, its element was assigned a score of 1, whereas it was

assigned a score of 0 if it was not detected. This data was used as input for some classification

models described in Section 0.

2.3 Training and testing data split

Quasi-replication occurs in machine learning datasets when the same or very similar data occur

in both the training and testing datasets. This violates the assumption of independence between

training and testing data and should be avoided to make valid inferences on the test data. The

DNA-based assemblage data presented a quasi-replication risk, as specimens from the same

sampling event would have the same assemblage data. To avoid quasi-replication, we split the

training and testing such that all specimens from a given sampling event were only included in

either the training or testing data. We set our target training:testing ratio to 85:15, and we

randomly added sampling events to the test dataset until the test dataset contained >15% of the

total number of specimens. The final train:test split was 31,381: 5,617 specimens and 122:28

sampling events.

2.4 Classification models

The objective of all the classification models was to accurately classify the class labels of

individual specimen photos. Classification masks (Section 0) and data fusion approaches

(Section 0) were used to assess how classification accuracy changes when DNA-based

assemblage data was added to the specimen classification pipeline. Performance of each

classification model was assessed using the original image labels as a ground truth. All code

required for running these models can be found in the "Model_Scripts" subdirectory of our

GitHub repository (Blair, 2024).

<u>2.4.1 Baseline model</u>

To evaluate model performance in the absence of DNA-based assemblage data, we trained a

ResNet-50 (He et al., 2016) as a baseline model using only image data. The model was pre-

trained using the ImageNet weights from He et al. (2016), and then fine-tuned using the NEON

invertebrate bycatch image data. The ImageNet classification layer was removed and replaced

with a new classification layer for our 17 classes.

2.4.2 Classification masks

2.4.2.1 Naïve mask

For our first experiment in combining the image and DNA-based assemblage data, we used what

we call a "naïve mask" on the baseline model's test data softmax classification layer outputs.

Using the naïve mask, the softmax layer values for each test data specimen were multiplied by

their sampling event's binary DNA-based assemblage data. Thus, any classes not detected by the

DNA metabarcoding in a given sampling event had their respective softmax values set to 0,

whereas the remaining classes were unaffected. After applying the mask, the class label with the

highest softmax value was used as the classification for a given specimen.

2.4.2.2 Weighted mask

"Hard" masks like the naïve mask, which set the softmax values of undetected classes to 0,

assume the DNA metabarcoding data is error-free. However, in reality, DNA metabarcoding can

have false positive and/or false negative detections (Taberlet *et al.*, 2018). To create a "softer"

version of the naïve mask, we also created a "weighted mask", which allows classes not detected

by the DNA metabarcoding to still be classified.

The weights for the weighted mask were calculated using the DNA's true positive rate

(precision) and false negative rate (1 - recall) for each class. The DNA metabarcoding precision

and recall were calculated by comparing the DNA-based assemblage labels to the image-based

assemblage labels, using the image-based assemblage labels as a ground truth. To create the

weighted mask, we assigned a class's precision for positive DNA detections, and the class's false

negative rate for negative detections. The application of the weighted mask was the same as the

naïve mask: The softmax values for each test data specimen were multiplied by their sampling

event's weighted mask values, and the new top-1 class was used as the classification.

2.4.2.3 Image-based mask

To simulate a scenario where the DNA detections were in perfect alignment with the image-

based detections, we applied the image-based binary assemblage data to the softmax values of

the baseline model. We did this to provide an upper-bound for the classification mask accuracy,

and to understand how DNA detection accuracy impacts specimen classification accuracy when

using classification masks.

2.4.3 Multimodal fusion

To allow the classification models to learn patterns from the DNA data, we trained multimodal

models that combined images with binary DNA-based assemblage data using intermediate fusion

(Boulahia *et al.*, 2021) (Figure 4). In these multimodal models, the image and assemblage data

for a given specimen were fed to the model separately. The images were fed through the ResNet-

50 architecture, ultimately producing a flat feature layer. DNA-based assemblage data was paired

with individual specimens based on their sampling event (the same approach as the classification

masks described in Section 2.4.2). This data is fed through a single fully-connected layer. The

flattened image layer and fully-connected DNA-based assemblage layer were then concatenated

(i.e. fused) and passed through another fully-connected layer before reaching the final

classification layer.

To understand the effect that DNA detection accuracy has on classification performance, we ran

three versions of the multimodal model using different types of assemblage data as input: (1)

using the DNA-based assemblage data, (2) using the image-based assemblage data, and (3) using

'zero-filled' assemblage data (all values in the assemblage data are set to zero). In all three

experiments the training and testing datasets used the same assemblage data type (i.e. DNA-

based, image-based, or zero-filled). All three experiments used the same overall model

architecture as described in Figure 4. The purpose of the image-based assemblage experiment

was to simulate the results of a model where the DNA detections perfectly aligned with the

ground truth labels. The purpose of the zero-filled assemblage experiment was to control for

differences in model architecture when comparing the multimodal models to models trained

without DNA-based assemblage data, as the zero-filled data would provide no informative value

to the model. The zero-filled assemblage data had the same dimensions as the other assemblage

data (17 values for each sampling event).

Figure 4: The described classification model architecture that combines image data with DNA-based
binary assemblage data. Images are fed through ResNet convolutional layers to produce a flat feature
layer, and DNA assemblage data produces a fully connected dense layer. The flat layer and dense layer
are then concatenated and passed through one more dense layer before final classification in the softmax

layer. The visual proportions of each layer have been simplified to ease interpretation and are not meant
to be interpreted as 1:1 representations of the exact layer sizes.

2.5 Refining taxonomic granularity using DNA-based assemblage data

To take advantage of the relatively fine taxonomic granularity of the raw DNA detections

compared to the computer vision classes, we refined the taxonomic granularity of the DNA

fusion model classifications by cross-referencing them with the DNA detections. In cases where

the model classifications and DNA detections agreed on the presence of a class, the granularity

of the classification improved until the number of subtaxa detected by the DNA metabarcoding

was greater than 1 or the granularity reached species-level, as that was the finest granularity

reported by the DNA (Figure 5a,b). In cases where the model classifications and DNA detections

disagreed on the presence of the class classified by the model, we implemented two methods

which we call "model-biased" and "DNA-biased". The model-biased method is simple. In cases

where the model and DNA metabarcoding disagreed, the model classification remained

unchanged (Figure 5c). When using the DNA-biased method, we compared the hierarchical label

of the classified specimen to the hierarchical labels of the sampling event as determined by the

DNA metabarcoding (Figure 5d, Table 1,

Table **2**). Starting from the original classification level, we coarsened the granularity of the label

until an agreement between the model and DNA metabarcoding was reached. The taxonomic

name at this level became an intermediate label, and the taxonomic granularity of the label was

refined until the number of subtaxa detected by the DNA metabarcoding was greater than 1 or

the granularity reached species-level.

All code required for running these methods can be found in the "Granularity_Refinement"

subdirectory of our GitHub repository (Blair, 2024).

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Figure 5: Four methods of changing a label's granularity using DNA detections. (a,b) When the
classification label and DNA detections are in agreement about the presence of a class, granularity will be
refined until the number of subtaxa detected by the DNA metabarcoding is > 1 or the classification
reaches species level. (c) Under the model-biased approach, when the classification label and DNA
metabarcoding do not agree on the presence of a class, the classification label remains unchanged. (d)
Under the DNA-biased approach, when the classification label and DNA metabarcoding do not agree on
the presence of a class, the granularity of the classification label is coarsened until a DNA detection for
the class is found ("intermediate label"). The granularity of the intermediate label is then refined using the
same rules as (a,b).

3. Results

3.1 DNA metabarcoding precision and recall

To generate the weights for the weighted mask, we calculated the DNA-based assemblage data's precision and recall for each class using the image-based assemblage data as the ground truth. This calculation only included sampling events from the training dataset. Across the 17 predicted classes, recall ranged from 0.905 to 0.000, with an average recall of 0.570. The weight for a negative detection was 1 - recall, so negative detection weights ranged from 1.000 to 0.095, with an average of 0.430. Two classes (Opilioacarida and Zygentoma) were never detected by the DNA. Across the 15 classes detected by the DNA, the average precision was 0.761. The precision and recall values per class are reported in Table S.1.

3.2 Classification accuracy

Compared to the baseline model, the DNA assemblage fusion model improved accuracy by 2.2% (79.6% vs 77.4%; Table 3). However, the DNA assemblage fusion model's accuracy was 1.0% lower than the zero-filled model's accuracy (80.6%). This suggests that some of the performance improvements seen in the fusion models could come from changes to the model architecture. The naïve classification mask recorded the lowest classification metrics, with an accuracy 22.6% below the baseline model (54.8%), and a top-3 accuracy of only 64.0%.

Experiments with image-based assemblage data performed better, with the fusion model reaching an average accuracy of 83.6% and a balanced accuracy (i.e. macro-averaged recall) of 0.713 (Table 4). The image-based naive mask accuracy was 25.8% better than the DNA-based

naive mask, and 3.2% better than the baseline model. It also had the highest top-3 accuracy

across all experiments at 93.2%.

Table 3: Performance metrics for experiments trained using DNA-based assemblage data, other than the
baseline model, which was trained only using images, and the 'zero-filled' experiment, which replaced all
assemblage data values with zero to control for the impact of model architecture. Underlined scores
indicate they are the highest for a given metric.

Experiment	Accuracy	Balanced Accuracy	Top-3 Accuracy
Baseline	0.774	0.674	0.952
Naive mask	0.548	0.509	0.640
Weighted mask	0.764	0.666	0.950
Fusion (DNA)	0.796	<u>0.680</u>	<u>0.957</u>
Fusion (zero-filled)	<u>0.806</u>	0.670	0.952

358 Table 4: Performance metrics for the image-based assemblage data experiments. These experiments used
359 binary assemblage data taken from the ground truth specimen labels. Underlined scores indicate they are
360 the highest for a given metric.

Experiment	Accuracy	Balanced Accuracy	Top-3 Accuracy
Mask	0.806	0.690	0.959
Fusion	<u>0.836</u>	<u>0.713</u>	<u>0.963</u>

3.3 Taxonomic granularity

Of the DNA fusion model classifications, 68.2% (3833/5617) were present in their

corresponding sampling event's DNA assemblage data. Nonetheless, both approaches for

handling disagreements between the DNA and classification model (model-biased or DNA-

biased) improved the average taxonomic granularity of the classifications (Figure 6). Despite

starting with no classifications finer than order-level, the DNA-biased approach resulted in 5.7%

of classifications improving to species-level and the model-biased approach resulted in 5.1% of

the classifications improving to species-level. The DNA-biased approach was more effective

overall at refining the granularity of classifications, with 72.2% of classifications becoming finer

than their original classification, and 43.1% reaching at least family-level. In the model-biased

approach, 51.7% of classifications improved their granularity, and 31.0% reached family-level or

lower. When looking exclusively at classifications where the DNA assemblage data and fusion

model classifications agreed on the presence of a class, 7.5% reached species level, 45.4%

reached family-level or lower, and 75.7% became finer than their original classifications. Both

the DNA-biased and model-biased approaches produced 89 unique final labels (Table S2).

Figure 6: Sankey diagrams showing the change in taxonomic granularity before (left) and after (right)
cross-referencing labels with the DNA detections. (a) DNA-biased approach. (b) Model-biased approach.
(c) Results when the model classification and DNA detections agree on the presence of the labelled class.

4 Discussion

Here we show that combining concurrent DNA-based assemblage data with computer vision can

improve the accuracy and taxonomic granularity of computer vision classifications. Unlike most

classification pipeline enhancements which only focus on improving the ability to classify

classes on which it was trained ("known classes"), this approach adds the ability for the pipeline

to infer classifications beyond the model's usual taxonomic scope ("unknown classes"). To

thoroughly explore the benefits and implications of this hybrid approach, we focused on the

following two research questions.

4.1 How does DNA metabarcoding accuracy affect specimen classification accuracy?

The effect of metabarcoding accuracy on classification accuracy differed between the

classification masks and the multimodal fusion models, illuminating a key difference between

them: classification masks (as used in this study) do not take class co-occurrence into

consideration, whereas the multimodal models do. Put another way, in a classification mask the

only factor that directly influences the weight given to a class is the presence or absence of the

class itself. Conversely, the neural networks of multimodal fusion models—with their fully-

connected structure—allow the presence or absence of all classes to holistically influence each

class's classification probability. This allows the model to use patterns of class co-occurrence to

inform its classification decisions.

The different mechanisms used by classification masks and multimodal models are best

demonstrated in Table 4, where the assemblage data was derived from the ground-truth image

labels. In the classification mask, the model's original classifications were exclusively based on

image data, and any classifications that did not match their respective assemblage data were

reclassified as the class with the highest softmax score that was present in the specimen's

assemblage. Given that the assemblage data was derived from the ground truth labels, this mask

acted as a sieve that filtered out any classes that could not possibly be the correct classification

based on the assemblage data. As a result, it could only have a positive impact on accuracy.

However, despite this, the fusion model still scored higher on all three metrics measured (top-1

accuracy, balanced accuracy, and top-3 accuracy). This implies that the fusion model was not

just using the assemblage data as a filter, but that it provided additional contextual information

(such as class co-occurrence or class exclusion) that further improved accuracy. Thus, due to the

fusion model's ability to holistically evaluate occurrence data, and as illustrated through its

superior performance compared to classification masks even under ideal conditions, multimodal

fusion models are likely to be preferable in most use cases. This conclusion is reinforced by the

results of Table 3, where both naïve and weighted masks showed negative effects on all

classification performance metrics when the DNA-based assemblage data contained substantial

amounts of error.

4.2 What are the strengths and limitations of each granularity refinement method?

Here we proposed two approaches for cross-referencing DNA metabarcoding data to achieve the

novel ability of refining the taxonomic granularity of computer vision classifications. The two

approaches differ in how they resolve disagreements between the detections of the DNA

metabarcoding and computer vision classifications, with the model-biased approach favouring

the computer vision classifications, and the DNA-biased approach favouring the DNA

detections. As such, each approach has its own set of advantages and limitations.

Through the ability to coarsen granularity before refining it, the DNA-biased method can make

classifications outside of the taxonomy of the original classification model (Figure S.3).

Explained another way, the model-biased approach and traditional hierarchical classifiers (e.g.

Badirli *et al.*, 2023) can only adjust classifications "vertically" (i.e. to supertaxa or subtaxa of the

original classifications), but the DNA-biased approach can also adjust classifications "laterally"

to out-of-distribution taxa through a combination of classification coarsening and refining.

Classification of out-of-distribution taxa is usually only possible using feature embedding

learning methods such as zero-shot learning (Badirli *et al.*, 2021). An illustrative example of this

comes from the DNA-biased approach's detection of taxa within the insect order Psocodea (e.g.

Valenzuela flavidus; Table S.2). As Psocodea was not included as a class in our model, and our

model's finest taxonomic granularity was order-level, Psocodea's branch of the taxonomy was

only accessible through a "lateral" taxonomic adjustment (Figure S.3). As such, it was only

detected by the DNA-biased approach, and not the model-biased approach (Table S.2). In theory,

this extends the range of possible classifications to the full taxonomic scope of the genetic

reference database being used (e.g. GenBank, Barcode of Life, etc.) (Ratnasingham and Hebert,

2007; Sayers *et al.*, 2024). In practice, it is likely best to self-impose limits on how much the

DNA-biased method can coarsen granularity. In our case we limited ourselves to phylum, as we

were only interested in classifications within our three focal phyla.

While it does not have the same potential taxonomic scope of the DNA-biased approach, an

advantage of the model-biased approach is that the taxonomic granularity of the final

classification cannot be coarser than the original classification. Applied to the DNA fusion model

classifications, 9.9% of all classifications became coarser when the DNA-biased method was

used (Figure 6). While the DNA-biased method classified more specimens at family-level or

finer (43.1% vs 31.0%), the ability to coarsen granularity resulted in more classifications above

order-level (11.7% vs 6.4%).

Even when granularity does not reach species, classifications that match with the DNA-based

assemblage data still provide more information than what is typically output from a classification

model. This is because we can also see the number and identity of subtaxa that the specimen

could be according to the DNA metabarcoding detections. For example, if the DNA

metabarcoding detected three species of the cricket genus *Gryllus* in a sample, we could say the

label of a specimen that would otherwise be classified simply as "*Gryllus* indet." is actually one

of three possible species of *Gryllus*, as detected by the DNA metabarcoding (e.g. *G.*

pennsylvanicus, *G. rubens*, or *G. veletis*). This might also be useful for future developments to

these methods, as the number of subtaxa detected by the DNA metabarcoding could be used to

inform clustering algorithms that separate the specimens into morphotaxa.

Of course, the granularity of classifications matters little if they are not accurate. A caveat of our

study is that we cannot verify the accuracy of granularity-refined classifications, as they are at

lower taxonomic levels than our ground truth (human-classified) labels. However, we know that

our classification models were more accurate than the DNA assemblage data when compared to

our ground-truth labels. Thus, the DNA-biased method of refining granularity will likely add

more error to the classifications than the model-biased approach. When deciding between the

two methods, this is likely to be a determining factor: does the computer vision model or DNA

metabarcoding contain more error?

4.3 Caveats and areas for future exploration

In an applied context, we cannot definitively conclude that image-DNA fusion models as we present here improve specimen classification accuracy. This is primarily due to the high rates of disagreement (or "error") between our DNA metabarcoding detections and image-based detections. When comparing our three fusion experiments, the zero-filled experiment had a top-1 accuracy 1.0% higher than the DNA-based assemblage data experiment, but 3.0% less than the image-based assemblage data experiment. This suggests that in an ideal situation where the DNA-based assemblage data has low amounts of error (i.e. it is more similar to the image-based assemblage data), image-DNA fusion models will positively impact classification accuracy. However, when the DNA-based assemblage data contains substantial error, differences in performance between the baseline and fusion models likely arise from changes in the model's architecture.

Reconciling genetic-based and morphology-based data—the two chief methods for invertebrate biodiversity monitoring—is a pressing need as previous studies have shown that assemblages determined by visual classification usually differ from assemblages determined using DNA metabarcoding. For example, Emmons *et al.* (2023) found that NEON benthic macroinvertebrate samples classified by taxonomists only shared 59% of order-level detections with DNA metabarcoding data derived from homogenized blends of the same samples. Marquina *et al.* (2019) also found that different DNA sampling protocols can produce inconsistent assemblage data, as DNA metabarcoded from ethanol vs homogenized blends of the same samples yielded significantly different assemblage data, with both methods detecting taxa not detected by the other. For the image-DNA fusion methods we propose here to be maximally effective, advances

will need to be made in DNA metabarcoding methodology to limit false positive and false

negative detections.

Beyond DNA metabarcoding accuracy, there are likely other factors that can impact the efficacy

of our methods, such as assemblage homogeneity and assemblage specificity. Assemblage

homogeneity refers to the variation among assemblages. For example, the zero-filled assemblage

experiment used data that was completely homogenous, as every sampling event had the same

assemblage data. Assemblage specificity refers to how many unique classes are detected within a

sample. A maximally specific assemblage would only detect one class as present, while a

minimally specific assemblage would detect every class as present. Reducing assemblage

homogeneity and increasing assemblage specificity should yield models with greater

classification performance. This is because heterogeneity is required for learnable patterns to

emerge in the data, and increased specificity allows more classes to be filtered out by the model.

This is partially demonstrated by comparing the results of Blair *et al.* (2020) to the results we

present here. In their study, which built classification models for NEON's carabid beetles, the

authors applied classification masks to their models based on the detected ground beetle

assemblages at each sampling site. On average, 2.93 out of 25 potential species (11.7%) were

detected per site, resulting in an accuracy improvement of 10.9% (84.7% → 95.6%) after

applying the classification masks. Comparatively, our image-based assemblages detected an

average of 9.09 out of 17 potential classes (53.5%) per sampling event. When compared to the

baseline model, this resulted in an accuracy improvement of 3.2% when using the classification

mask and 6.2% in the fusion model (Table 3, Table 4). Thus, methods to reduce assemblage

homogeneity (e.g. finer-grain class labels) and increase assemblage specificity (e.g. fewer

specimens per sample) will likely increase the efficacy of image-DNA metabarcoding fusion

classification pipelines.

4.4 Broader applications and implications

In this study, we used assemblage data derived from DNA metabarcoding to improve computer

vision classifications of terrestrial invertebrates. However, our general framework could be

applied to any study system where images and DNA metabarcoding data are collected

concurrently. Given that computer vision and DNA metabarcoding are emerging technologies in

ecological research, the number of research systems that include one or both is increasing

(Pichler and Hartig, 2023; Shea *et al.*, 2023). Projects that use both computer vision and DNA

metabarcoding also span a wide range of fauna and ecosystems, including freshwater, marine,

and terrestrial vertebrates (Takeuchi *et al.*, 2021; Mas-Carrió *et al.*, 2022; Holm *et al.*, 2023). By

leveraging the strengths of computer vision and DNA metabarcoding, our framework could

enhance the capabilities of projects like these.

Our framework is composed of two primary modules—a multimodal classification model and a

classification granularity refinement method—which can be used and modified independently of

each other. Our multimodal model requires image data and assemblage data, but the assemblage

data does not need to be derived from DNA. In this study we conducted experiments where the

DNA-derived assemblage data was substituted with image-derived assemblage data. Likewise,

assemblages derived from other sensor data (acoustic, lidar, etc.) could also be used (Gasc *et al.*,

2015; Kaplan *et al.*, 2015; Wedding *et al.*, 2019). Conversely, our classification granularity

refinement method requires DNA metabarcoding data and individual specimen classifications,

but the specimen classifications do not need to be derived from a computer vision model. We

encourage future studies to explore different variations and combinations of the modules we

present here.

Our framework's ability to refine classification granularity, which is typically not possible in

computer vision, could improve the feasibility of building broad-scope, fine-grain classification

models (e.g. models spanning entire classes or phyla and capable of producing species-level

classifications). This typically requires vast amounts of training data, as training examples need

to be provided for every species. Using the approach that we present here, classifiers could be

trained at coarser taxonomic levels such as order or family and still have the potential to produce

species-level classifications. This would decrease the number of classes in the model, and thus

data needed to train it, by orders of magnitude. Hence, the synergy between DNA metabarcoding

and computer vision outlined in this study paves the way for new possibilities in computer vision

classification of taxa, with the potential for improved accuracy and granularity with far less data

dependency.

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