CNValidatron, automated validation of CNV calls using computer vision

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Abstract

Motivation

For more than a decade, running PennCNV on SNP array data has been the gold standard for detecting Copy Number Variants (CNVs, deletions and duplications). It is generally assumed that PennCNV has high sensitivity but poor specificity, leading to a large portion of CNV calls being false positives. Researchers often rely on manual inspection of the raw data trends to validate CNV calls. However, this approach is not feasible for more than a handful of loci in large collections.

Results

Here we present an R package implementing a convolutional neural network capable of automating CNV validation with an accuracy comparable to a trained human analyst. We also present an in-depth analysis into PennCNV false positive and false negative rates. Finally, we propose an algorithm to simplify the analysis of genome-wide CNV calls computing CNV regions.

Availability and implementation

The code is available on GitHub https://github.com/SinomeM/CNValidatron_fl.

Introduction

Copy Number Variants (CNVs) are a class of structural genetic variation, representing a segment of chromosomal DNA sequence that has been deleted, duplicated, or otherwise misplaced compared to the reference genomic sequence.[1] For the purposes of this manuscript, we define CNVs as all deletions and duplications ranging between small structural variants and large chromosomal rearrangements, roughly corresponding to ~50kb to ~10Mb.

For more than a decade, running PennCNV[2] on SNP array data has been the gold standard for detecting CNVs, especially in large collections of samples. While collections of whole-genome sequenced (WGS) samples are growing rapidly[3,4] and WGS (especially from long read technologies) is the ideal data source for detecting small and complex structural variants (SV), WGS is not necessarily better than SNPs arrays in detecting CNVs with good accuracy.

All CNV calling programs rely on some measure of DNA intensity (log-R-ratio (LRR) for SNP arrays and read depth for WGS data), and some also include a measure of allelic composition (such as B-allele frequency (BAF) for Illumina arrays)[5,6]. PennCNV in particular, uses a Hidden Markov Model to predict the state (copy number) of each marker, based on the previous one, integrating both LRR and BAF. Sets of markers with the same state are then stitched together to create the actual calls. CNV calling from SNP array data using PennCNV is believed to have a generally high sensitivity, however it tends to have poor specificity, with more than 50% of calls typically being false positives, sometimes much more, depending on sample quality, array type and genomic location[7]. For this reason, researchers have used different approaches to control the false positive rate, including filtering whole samples as well as individual CNVs based on quality metrics, or using the intersection of calls across different CNV calling algorithms.[8] Moreover, especially when precision is extremely important (e.g. in very rare exposures such as recurrent CNVs)[9,10], visual inspection performed by a human analyst through inspection of LRR and BAF plots around the suspected CNV call, remains the best approach and is possibly second only to a wet-lab validation using a qPCR experiment. Clearly, such an approach is extremely time consuming, and its application is therefore limited to studies with a very specific focus, i.e., a handful of genomic loci.

In this study, we present a novel solution to this problem based on machine vision. We showcase an algorithm that is able to automate the visual inspection of CNVs with an accuracy and precision comparable to (if not better than) that of a human analyst and distribute it as an R package.

This solution provides us with an unprecedented quality of a genome-wide CNV dataset, which in turn creates new research opportunities as well as new analytical challenges. One of the most impelling being that CNVs are very heterogeneous, and often two CNVs that can be considered identical in practice, actually have different boundaries. In general, two CNVs can have different degrees of similarity, and this is not trivial to quantify unequivocally across genomic locations and CNV sizes. For this reason, we also developed a method to group CNVs into biologically-plausible CNV regions (CNVRs) based on network analysis, and we demonstrate its function in a selected set of well characterised loci.

Methods

CNV calling and processing

In this study we use CNV calls from two different sample cohorts; a subsample of full trios (offspring, father, mother) from genotyped Icelandic samples at deCODE genetics (Icelandic trios), and singleton samples from the UK Biobank (UKB). Samples were genotyped on different chips in different cohorts, Affymetrix UK Biobank Axiom Array for most UKB samples and multiple generations of Illumina arrays for the Icelandic trios.

All CNV calls were generated using PennCNV[2]. The CNV calling in the Icelandic trios and UKB was performed at deCODE genetics. In brief, a PennCNV pipeline was used, main settings differing from default were minimum number of SNPs set to 5 and using a filtered SNP list as described below. After calling, all calls were processed using our CNV protocol.[11] Samples were filtered for basic QC measures (LRR_SD < 0.35, BAF_DRIFT < 0.01, GCWF between -0.02 and 0.02) in the deCODE sets, while no QC filter was applied in the UKB. Then, all calls from each sample were processed in order to stitch those being close with the same copy number, two consecutive calls were combined if they had the same copy number and were close enough (gap not larger than 20% the combined length). SNP markers were also filtered as previously described,[11] i.e. only biallelic autosomal SNPs mapping uniquely to the Haplotype Reference Consortium (HRC) hg19 reference map[12], with a minor allele frequency of at least 0.1%. Finally, samples with full or partial chromosomal abnormalities (loosely defined as any deletion or duplication larger than 25Mbp) were excluded. These were selected as all chromosomes where CNV call covered more than 10% of the total markers and were manually validated by a human analyst.

Training data

A schematic of the datasets used in the study is shown in figure 1. The model was trained on ~16,000 examples from a collection of samples from the UKB and the Icelandic biobank at deCODE genetics obtained as follows: After filtering, 15,000 samples were selected at random from the UKB cohort as well as 800 offspring from the deCODE trios. In the UKB data, a large portion of CNVs belonged to a small set of groups of CNVs (CNV regions, CNVRs). In order to not introduce bias towards specific genomic regions in the model, such regions were down-sampled as follows. CNVRs were divided in three groups based on the frequency within the 15,000 selected samples, group A, CNVRs with a frequency up to 50, group B, frequency between 50 and 100, and group C, with a frequency above 100. For each CNVRs separately, CNVs from regions in group A were sampled with a 50% probability up to 20 CNVs maximum, CNVs from group B were sampled with a 35% probability up to 25 CNVs maximum, and CNVs from group C were sampled at 40 CNVs per CNVR. All CNVs above 25 SNPs and 15 SNPs for UKB and deCODE examples respectively, were manually validated using in-house software[11] (https://github.com/SinomeM/shinyCNV) by at least one human analyst. Each CNV was classified as either true or false, leading to three possible categories: true deletion, true duplication, false call. Very ambiguous calls (e.g., a missed chromosomal aneuploidy) were allowed to be excluded from the training set, however, we tried to limit this as much as possible.

Prediction model design and training

The data representation was designed to be a simplified and condensed version of what the human analyst sees when performing the visual inspection of CNVs (i.e., tracks of LRR and BAF around a

putative CNV in each sample). All the processing described here has two main objectives, first to fit all
necessary information in the smallest amount of data possible (here, the smallest picture) to minimise
computation, and second to make the pictures as similar as possible across different genomic loci,
different CNVs sizes, different markers numbers and distributions. We loosely tested different
resolutions before setting it to 96 by 96 pixels. As shown in supplementary figure 1, the picture is
composed of three rows, containing two views of the LRR values around the CNVs and one view of the
BAF. Horizontally the image is composed of three sectors, markers on the right of the CNV call, markers
within the CNV call and finally on the left of the CNV call. Depending on the size of the CNV call (below
100kbp, between 100kbp and 1Mbp, above 1Mbp) the two bottom rows will cover 19, 15 or 11 CNVs
lengths in total, with equal spacing on the side, while the top row is always zoomed out by a further
factor of three.
The pixel image is constructed as follows. For each of the three rows, all points are moved to the
coordinate system, i.e., from genomic position in x and LRR/BAF in y to 0-96 in x and [a-b] in y (where
a and b values depend on the specific row). Then, the counts for each individual pixel, n, are collected
(in R data.table syntax, dt[, .N, by = c('x', 'y')]). Then, n is first moved to the log scale and then to [0.1].
This is done in windows to minimise the effect of differential SNPs density across the locus of interest,
that could overwise drown the signal of normal regions, due to small segments of very high SNPs
coverage. Window size is 4, 8 or 32 pixels, depending on the CNVs length class, as described above.
LRR values are slightly processed before being moved to the pixel values system to reduce the effect
of outliers. This process is done independently for the three sectors of the image: left side of the CNV,
inside the CNV or right side of the CNV. In brief, the further a point is from the mean value of its sector
the more it is 'pulled' towards it, as in the following R pseudo-code (for values above the mean):
new_lrr = lrr - abs(lrr-mean_lrr) * shrink_lrr_factor, with shrink_lrr_factor set to 0.2 by default. In
practice, this has very little effect on most points, but should mitigate the effect that outliers might
have on the final image. This is done to simulate what the human eye does automatically during visual
inspection, i.e., give more "weight" to the centre of the distribution and ignore outliers, if rare. This
process does not alter the overall shape of the distribution, especially any waviness pattern that might
be present. After this step any remaining outlier, defined as a point outside three standard deviations
of the sector distribution, is removed.
We increased the number of examples using data augmentation in the form of image flipping on the
x axis with a probability of 0.5 per example. Other types of data augmentation, such as adding random
noise to each pixel, were considered but eventually discarded. Training was performed on the whole
dataset in a 75-25% configuration for training and validation set.
The model was built using torch[13] with the R packages torch[14], torchvision[15] and luz[16]. It is composed
of 5 convolutional layers (nn_conv2d) followed by a 10-layer linear classifier (nn_linear). Each layer
has a 5% dropout rate (nn_dropout2d(p = 0.05). Training was performed using luz::fit() with the
following settings: max learning rate of 0.2, max epochs of 50, and early stopping with a patience value
of 4.

Test data

Model accuracy was tested in a different set of deCODE samples, while precision was tested in both
UKB and deCODE data. The UKB set was designed to also test the calibration of the probability
outputted by the model as follows. 2800 predicted true CNVs were randomly selected, sampling 400
CNVs from each of the following prediction probability intervals [0.75, 0.85), [0.85, 0.90), [0.90, 0.92),
[0.92, 0.94), [0.94, 0.96), [0.96, 0.98), and [.98-1]. In the deCODE test set, all CNVs from 1200 randomly

sampled individuals were selected. For the UKB calibration set all selected CNVs were manually
validated by a human analyst. For the deCODE test set we partially relied on the genealogy for
validation, and we considered as true any CNVs predicted true by the program and present in at least
one of the carrier's parents with at least 50% overlap without the need of manual visual inspection.
All discordant CNVs (i.e., those predicted as true by the program but where no concordant call was
present in a parent or vice-versa) were manually validated. Accuracy is defined as (TP + TN) / (TP + FP
+ TN + FN), with the truth being the human analyst evaluation for UKB, and both model-genealogy
agreement and human evaluation in the Icelandic trios.

CNVR detection algorithm

The CNVR detection algorithm is composed of three separate steps. First, CNVs are divided into
networks, defined as the smallest set of mutually overlapping CNVs. By definition, the largest possible
network is thus a chromosomal arm (in our pipeline CNVs cannot span across the centromere), and
the smallest network is a single CNV that does not overlap with any neighbour. The second step is
where the CNVRs are created. For each network, an NxN matrix is constructed, where N is the number
of CNVs in the networks and each xy value is the intersection over the union (IOU) between CNVs X
and Y. Two identical CNVs will have an IOU of 1, two overlapping CNVs will have an IOU between 0
and 1, depending on the similarity, and two non-overlapping CNVs will have an IOU closer to -1 the
more distant they are. This matrix is then translated into a weighted igraph[17] network object where
all pairs with an IOU above a certain threshold (default value is 0.75) will be connected, with the IOU
values being the strength of the connection. This network is then processed with the community
detection algorithm Leiden[18] (igraph::cluster_leiden(), default resolution value is set to 1), and the
resulting networks are converted back into CNVRs with the boundaries being the median values of the
start and end of the constitutive CNVs respectively. CNVs with no CNVR (singletons) are given their
own group. The third and final step is an optional forced merge of CNVRs. For each chromosome, all
CNVRs are processed in order of start position. For any given CNVR x, all regions with a reciprocal
overlap above a certain threshold with x (default value is 0.75) are merged together, the new start
and end are computed again as the median from all the CNVs in the new group. This process continues
until all CNVRs have been either processed or merged with a previous one. This is done for a fixed
number of iterations, 5 by default.
When computing CNVRs on genome wide CNVs, we defined three groups of settings, very strict, loose,
and in between, defined as follows. Very strict (min_iou=0.90, max_force_merge_rounds=1,
force_merge_min_overlap=0.90) maximise intra-CNVR similarity, loose (min_iou=0.50,
max_force_merge_rounds=5, force_merge_min_overlap=0.75) minimise the number of regions
created, while the last group of setting (min_iou=0.75, max_force_merge_rounds=3,
force_merge_min_overlap=0.75) should be a balance between the two extremes.
The program is available as an R package at https://github.com/SinomeM/CNValidatron_fl/.
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Results

PennCNV false positive calls

In this study we use CNV calls from two different cohorts, genotyped on different arrays from two manufacturers to investigate and mitigate the burden of false positive CNV calls in large datasets. As described in the methods, these consist of UK Biobank (UKB)[19] and deCODE trios (deCODE genetics / Amgen, Reykjavík, Iceland).

We assessed the PennCNV false positive rate in three different CNV sets from two cohorts. These consist of the 1) UKB train set, 2) deCODE training set, 3) the deCODE test set. 15,000 samples were randomly selected in the UKB and 2,000 offspring from full trios in deCODE (800 train and 1,200 test respectively), for a total of 17,000 unique samples. All CNVs from these samples were processed as described in the methods and filtered for 25 minimum number of SNPs in the UKB and 15 in deCODE data (table 1). All CNVs were manually validated for the deCODE portion of the training set, while common CNVRs were down sampled in the UKB training set (see methods). This was done to reduce the model bias towards specific common loci and was deemed necessary only in the UKB portion of the training set. Finally, CNVs in the deCODE test set were validated only in the case of discordance with the genealogy, as described in the methods. In total almost 22,500 CNVs were validated (12,153 UKB train, 3,760 deCODE train, 6,255 deCODE test). CNVs were evaluated by at least one human analyst as described in the methods, and tagged as either true, false or undetermined/unknown (i.e., calls that could not be ruled out as being true while lacking strong indication of being so). In the deCODE sets, having access to the full trio allowed to assign every call as either true or false, while in UKB the undetermined flag was also necessary.

Results are shown in table 1. In summary, without any sample-wise filter on QC metrics (e.g., LRRSD and GCWF), from ~30% to ~60% of the CNV calls produced by PennCNV are false positives depending on the specific cohort and the minimum number of SNPs.

Prediction model training and testing

The model training was performed on a combined set of human-validated CNV calls from UKB and deCODE, for a total of ~16,000 unique examples, as described in the Methods. Training stopped after 12 epochs with an accuracy of 0,96.

Accuracy and precision are 95% and 92% in the deCODE test set respectively (table 2), while precision is 95% in the UKB calibrations set. We also tested the calibration of the probability outputted by the model in the UKB. We randomly selected a total of 2,800 predicted true CNVs from intervals of probabilities, as described in the methods. As shown in supplementary figure 4, the output probability is not properly calibrated, but can be used as a lower limit, meaning selecting CNVs predicted true with at least 0.75 probability will lead to a dataset where at least 75% of CNVs would be evaluated as true by a human analyst. In practice this percentage will likely be much higher (95% in this within-sample set).

PennCNV false negatives estimation and de novo CNV rate

In contrast with false positives, false negatives are essentially impossible to quantify without other means of detecting CNVs. We attempted to get an estimate of the false negative rate using the pedigrees of the deCODE trio. We analysed the mismatch between the genealogy and the model

prediction in all samples of the deCODE test set for a total of 637 CNVs (excluding the MHC region).
Of these, 99 were found to be true positives in the offspring and false negatives in the parent, meaning
the CNV was missed by PennCNV in the parent. The majority of these (96) are duplications and the
median length is ~90kbp, with 11 being larger than 200kbp. This would set the minimum false negative
CNV call rate at ~1.5% (99 out of (6522) CNVs) and ~4.0% (96 out of 2413) for duplications only.
Moreover, 42 CNVs (30 deletions, and 12 duplications) were found to be true in the offspring but not
present in the parents with a median length of ~161kbp, setting the minimum de novo CNV mutation
rate at ~3.5% (42 events in 1,200 samples).

False positives calls and QC measures

We investigated the link between false positive PennCNV calls and quality measures, LRR standard
deviation (LLR_SD), BAF drift, and GC waviness factor (GCWF). As shown in supplementary figure 3,
false CNVs (especially deletions) tend to be from samples with somewhat higher LRR SD and BAF drift,
but not GCWF. As expected, undetermined CNVs lie in between true and false ones. Moreover, true
CNVs (especially duplications) tend to be larger than false and undetermined ones (supplementary
figure 2). True duplications also tend to have a higher number of markers than any other categories.
This is consistent with our experience, as duplications tend to need more points to be reliably
considered true evaluated by the analyst compared to deletions.
We also compared our program accuracy with different filtering thresholds of these QC measures,
similar to those used in published research on CNVs. For UKB we used the same filter as in Kendall et
al.[20], excluding samples with a |WF| > 0.03, more than 30 CNVs or LRRSD > 0.35. In the UKB train set,
this excluded 144 (2%) true, 1,163 (54%) false and 122 (6%) undetermined CNVs respectively,
effectively removing 24% of the CNVs evaluated as not true (false + undetermined) by a human analyst
while sacrificing only 2% of the true positives.

Differences in distribution between true and false positive calls

In order to understand the effect that insufficient filtering of false positive CNVs can have on a genome
wide analysis, we plotted the genomic distribution of the UKB train set, marking human validated true
and not-true CNVs. Results are shown in supplementary figure 5. Similarly, to the overall CNVs
distribution, differences in true and not-true distribution vary heavily both within and across
chromosomes. In the UKB train set (panel a), the distribution of true and false CNV calls is very similar
for chromosomes 16 and 18, and 5 and 9 for deletions and duplications respectively. In contrast, they
are very different in chromosomes 9 and 20 for deletions, and 11 and 20 for duplications. In the
deCODE test set (panel b), we did not identify a chromosome where true and false CNVs distribution
followed each other as closely as in the UKB train set, potentially due to the lower number of CNVs. In
contrast the two distributions are very different in chromosomes 8, 13 and 17 for both deletions and
duplications.

CNV regions algorithm

CNV regions (CNVRs) do not have a unanimous definition in the literature. In this study we defined
them as the results of grouping CNVs based on similarity, maximising the within-group similarity while
minimising the number of different groups. We tested multiple algorithms based on incrementally
growing CNVRs, that is add a new CNV to a group if it is similar enough to its members (e.g., in terms
of reciprocal overlap or intersection over the union, IOU), or create a new group if no match is found.

We found that such approaches tend to be slow and more importantly, give potentially very different
results based on the order in which CNVs are evaluated. For this reason, we developed an algorithm
to compute CNVRs in a whole locus at the same time, based on the community detection method
Leiden, from network analysis. Our approach is described in detail in the methods section.
We applied our CNVR detection algorithm to all CNVs predicted as true deletions or duplication with
a probability above 75% in the UKB (~525,000). We tested three sets of settings (very stringent, mildly
stringent, and loose) and evaluated the results at four well characterised genomic loci: the NRXN1
gene locus on the 2p arm, and the recurrent CNV loci 15q11.2-13.3, 16p13.1-p12.3, and the 22q11.2
broader region. Results are shown in figure 2 and supplementary figure 6. The most stringent setting
(green in supplementary figure 6) creates too many groups, given the high internal similarity
requirements, and it's not shown in figure 2. Among the other two there is no clear winner. As shown
in figure 2, some CNVRs seems to be very specific, meaning all CNVs in them are extremely similar,
and are detected with the same number of carriers in both methods, two examples being the 127
carriers CNVR in 15q13.2 marked with '*' and the 30 carriers one in 16p13.11 marked with '~'.
However, in most cases the two settings will produce slightly different results. The looser setting tends
to create less CNVRs that are less specific, meaning CNVs in them can have less similar boundaries. In
figure 2 we marked two such cases in known CNV loci. In 15q13.3, with loose settings there is a CNVR
including 2,815 carriers overlapping the known CHRNA7 copy-number-variable region marked with '+'
that is separated into three different regions with 2,281, 484 and 168 carriers respectively when
applying the strict/intermediate setting. Conversely, in 16p13.11 there is a 756 carriers region marked
with '#' covering the known recurrent locus that the medium setting correctly separates in two groups,
the most frequent including an additional group of markers on the right (Mb 15.0-15.2), whereas the
loose setting groups the two CNV subtypes together in one CNVR. Depending on the application,
researchers can balance the number and carrier frequency of CNVRs with their specificity in terms of
internal similarity.
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Discussion

In this study we provide the first in-depth analysis of the extent of false positive CNV calls from PennCNV across two cohorts genotyped on different SNP arrays from two different manufacturers. We demonstrate that false positives constitute a large fraction of calls across cohorts, while depending somewhat on factors such as array type (Illumina or Affymetrix), sample quality, and the number of probes in each CNV call. Moreover, we show that standard filtering practice fails to solve the problem. Of notice, PennCNV produced less CNV calls on Affymetrix arrays compared to Illumina. Finally, we show that false and true CNV calls do not follow the same genomic distribution. Studies that do not use a strong method to exclude false positive calls (such as visual inspection) will therefore likely produce highly biased results.

Admittedly, we use only one algorithm (PennCNV) to call CNVs while other alternatives are also available. We do not think this is a strong limitation as, 1) PennCNV is by far the most used software to call CNV in SNP array data and 2) most programs (with the notable exception of ipattern[21]) uses the same raw data (LRR and BAF) and some implementation of the same HMM architecture as PennCNV.[5,22]

We also provide, to our knowledge, the first estimate of false negative rate in CNV calls. Given the high number of false positives, it is normally assumed that PennCNV is over-sensitive, and that false negatives are not an issue. Indeed, we find them to be most likely less than the false positives, with an estimate from the Icelandic trios data setting the minimum to 1.6%, and mostly confined to duplications. Considering most CNVs are rare or ultra-rare exposures they might still be a source of bias in some contexts, however hard to mitigate *in-silico*, especially without access to full pedigrees, as is the case in most modern biobanks.

Visual inspection remains the best solution to the false positives in PennCNV calls, and arguably the only one working, however, it is extremely time consuming, and remains unfeasible for genome wide applications in large collections. Here, we provide software to automate CNVs validation using computer vision, with an accuracy comparable to a trained human analyst, across multiple datasets.

In our view, the major limitation of this work is the absence of an "absolute truth" to compare with. Both the training examples and the test sets are based on visual inspection of a human analyst, and this leads to possible biases. Still, visual inspection remains the gold standard in the field, and the best option available on such a scale and given the sensitivity of the data. Moreover, having access to a full pedigree, allowing to compare the same region across closely related samples, reduces uncertainty in human evaluation.

We also propose an algorithm to compute CNV regions or CNVRs. Also in this case, there is no clear "gold standard" nor unanimous definition of what such regions should look like or how they should behave genome-wide. For our purposes we define CNVRs as "the smallest possible number of sets that can group CNVs that are as similar as possible together". Clearly, low number of groups and internal similarity cannot be maximised at the same time. We show how different settings of our algorithm can produce "biologically plausible" CNVRs at different well-characterised loci, however it's impossible to manually check the entire genome for coherence.

In conclusion, despite some important but mostly out-of-our-control limitations, we believe the software described is capable of producing good sets of CNV genome wide, opening the field to new and interesting research opportunities.

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Figures legends

Figure 1: Schematics representation of the training and test sets across the two cohorts.

Figure 2: IGV plot showing CNVRs computed with different settings. From the top, the light grey track shows the cytobands, the dark grey show known recurrent CNV loci, and the second dark grey shows the SNP markers coverage. The red track shows CNVRs computed with the looser setting, while the blue one shows the medium settings. The strict setting track is shown only in supplementary figure VII in green. The number below each CNVR is the number of CNV belonging to it. a) 15q13.3 b) 16p13.1-12.3.

388 # Figures

389 Figure 1.

391 Figure 2.

Tables legends

Table 1: Results from human visual validation in the different CNV sets. Training and test set consist

of all CNVs from a randomly selected set of samples, with some filters applied.

Table 2: Accuracy and precision in the different CNV sets.

398 # Tables

399 **Table 1**.
400

Dataset	Chip	Min length	Min SNPs	Tot samples	Tot CNVs	CNV/ sample	True (%)	False (%)	Unknown (%)
deCODE train*	Multiple	NA	15	800	3760	4.7	1547 (41%)	2213 (59%)	0 (0%)
deCODE test*	Multiple	NA	15	1200	6522	5.4	2790 (43%)	3732 (57%)	0 (0%)
UKB train**	Affymetrix	NA	25	15,000	12153	0.8	6829 (56%)	3296 (27%)	2028 (17%)
UBK calibration	Affymetrix	NA	15	NA	2800	NA	2665 (95%)	5 (0%)	130 (5%)

401
402 ***NB**: common CNVRs were down sampled in this set
403 ***NB**: for deCODE data, multiple full trios were inspected together, this essentially eliminated the need
404 for the undetermined/unknown tag.

405   **Table 2**.
406

Dataset	TP	TN	FP	FN	Accuracy (TP+TN)/All	Precision TP/(TP+FP)
deCODE test	2578	3639	93	212	95%	92%
UBK calibration	2666	NA	134	NA	NA	95%

Supplementary material

409   **Supplementary figure 1**. Examples of the 96x96 pixels image for the CNN. a) true deletions, b) true
410   duplications.
411

a   b

413   **Supplementary figure 2**. Log 10 number of SNPs makers (left) and length (right) in the true, false and
414   undetermined/unknown CNVs. Deletions in yellow, duplications in blue. a) UKB train, b) deCODE test.
415

417 **Supplementary figure 3**. LRR SD (left), BAF drift (middle), and GCWF (right) distributions in the true,
418 false and undetermined/unknown CNVs. Deletions in yellow, duplications in blue. Each CNV inherits
419 the QC measure of the sample. a) UKB train, b) deCODE test.
420

Supplementary figure 4. Results of Visual validation in the UKB calibration set. All CNVs have been
predicted as true by the model and have been validated by a human analyst. 400 CNVs were sampled
for each probability group, as follows. 1: [0.75, 0.85), 2: [0.85, 0.90), 3: [0.90, 0.92), 4: [0.92, 0.94), 5:
[0.94, 0.96), 6: [0.96, 0.98), and 7: [.98-1]. a) overall distribution of the prediction probability in the
true (green) and false (orange) CNVs. b) bar plot of the visual validation status in each prediction
probability group.
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Supplementary figure 5. Genomic distribution of the True and False CNV calls in the a) UKB train set, and b) deCODE test. True CNVs in green, false in orange. Deletion and duplications are plotted separately for a selection of chromosomes, both histograms, on the left, and density plots, on the right, are provided.

Supplementary figure 6. CNVRs showcase. This is an extended version of figure I. CNVRs computed
with different settings. Red: loose, blue: medium, green: strict.
a) NRXN1 gene locus (chr2:49,645,643-51,759,674).
b) 15q11.2-13.3 (chr15:22,600,000-32,600,000).
c) 16p13.1-12.3 (chr16:15,000,000-18,300,000).
d) 22q11.1-11.2 (chr22:17,200,000-23,800,000).
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443 a)

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445
446 b)

448   c)

450   d)

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