DATA NOTE

The FIP 1.0 Data Set: Highly Resolved Annotated Image Time Series of 4,000 Wheat Plots Grown in Six Years

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Abstract

Background: Understanding genotype-environment interactions of plants is crucial for crop improvement, yet limited by the scarcity of quality phenotyping data. This data note presents the Field Phenotyping Platform 1.0 data set, a comprehensive resource for winter wheat research that combines imaging, trait, environmental, and genetic data.
Findings: We provide time series data for more than 4,000 wheat plots, including aligned high-resolution image sequences totaling more than 151,000 aligned images across six years. Measurement data for eight key wheat traits is included, namely canopy cover values, plant heights, wheat head counts, senescence ratings, heading date, final plant height, grain yield, and protein content. Genetic marker information and environmental data complement the time series. Data quality is demonstrated through heritability analyses and genomic prediction models, achieving accuracies aligned with previous research.
Conclusions: This extensive data set offers opportunities for advancing crop modeling and phenotyping techniques, enabling researchers to develop novel approaches for understanding genotype-environment interactions, analyzing growth dynamics, and predicting crop performance. By making this resource publicly available, we aim to accelerate research in climate-adaptive agriculture and foster collaboration between plant science and computer vision communities.

Key words: Winter wheat; High-throughput phenotyping; Field phenotyping platform; Yield; Protein content; Image time series; Deep learning data set

Data Description

Aim

Winter wheat provides a crucial share of calories for human nutrition, with global demand steadily increasing [1]. However, crop production faces challenges due to limited resources like water, agrochemicals, and land [2]. Climate change further threatens crop yields, necessitating responsible and efficient resource use [3].

Crop yields are substantially driven by complex interactions between plant genetics and environmental factors. For instance, genes involved in fruit formation interact with temperatures at flowering, influencing growth and yield potential [4]. Limited phenotyping data is seen as the major reason for the incomplete understanding of such genotype-environment interactions [5].

High-throughput field phenotyping (HTFP) was developed to address this data gap [6]. Imaging HTFP platforms allow researchers to monitor crop canopy development over time, generating dense time series data of plant growth. There are many approaches to process such data ranging from extracting traits at critical time points to modeling growth dynamics and finally using end-to-end methods that directly analyze image time series.

This data set aims to provide a comprehensive foundation for these diverse approaches. Our goal is to foster collaboration between plant physiology, biometrics, and computer vision research, ultimately improving the ability to predict genotype-environment interactions for current and future climates.

Context

The Field Phenotyping Platform (FIP) at ETH was established in 2015 to collect image time series of crops growing under realistic field conditions. The FIP's cable carrying system is capable of carrying a 90 kg sensor head [7]. The original sensor head, hereafter referred to as the FIP 1.0 head, was equipped with a red, green, and blue (RGB) camera and a Terrestrial Laser Scanner (TLS), among other sensors. Wheat field experiments were observed using FIP 1.0 over an eight-year period from 2015 to 2022, yielding six years of data collection, with 2015 and 2020 excluded due to incomplete measuring seasons (Figure 1). Up to three times a week, RGB images of all experimental units (so-called 'plots') were collected, and plant heights were measured simultaneously using either the TLS (2016, 2017) [8, 9] or drones (2018−2022) [10, 11, 12]. In 2023, the FIP 1.0 sensor head was replaced with a new, multi-view RGB sensor head. The described data set includes all RGB and height data collected in winter wheat experiments up to this replacement.

The area of approximately one hectare that the FIP can monitor is divided into six smaller parts (so-called 'lots') that are integrated into a crop rotation. The two FIP lots dedicated to winter wheat provide space for ∼350 genotypes, replicated once per lot. For the first three years (2016−2018), the GABI-WHEAT [13] panel was grown as the genotype set. From 2019−2022, a subset of the GABI-WHEAT panel was grown in addition to other genotypes (Figure 2, green bars). The GABI-WHEAT panel consists of registered genotypes from different climatic regions of Europe [14, 13]. Genetic marker data and Multi-Environment Trial (MET) data from eight year-locations for GABI-WHEAT are publicly available.

The GABI-WHEAT panel was largely superseded by the Swiss breeding set in 2021 (Figure 2, gray bars). This new set primarily consists of eighth-generation (F8) breeding genotypes. For the Swiss breeding set, genetic marker data exists but remains confidential. The remaining genotypes, linked to specific projects such as Innovation in Variety Testing (INVITE), were present throughout all years but were generally only grown in a single year each (Figure 2, in purple). These genotypes currently lack available marker data.

Regular measurements with the FIP 1.0 head were accompanied by reference measurement campaigns as part of several projects. The heading date and senescence ratings were performed to investigate the relationships of senescence dynamics and diseases [15, 16, 17]. Yield measurements taken on the FIP field were combined with data from other locations to train phenomic prediction models [18]. The plant height measurements served as a basis to quantify the temperature response of wheat genotypes in the stem elongation phase [8, 9, 12]. The extracted plant height values demonstrated their usefulness in improving trait extraction methods from longitudinal data [19, 20, 21].

The images collected were used to quantify canopy cover values [22] and examine their relationship to frost damage events [23] using Convolutional Neural Networks (CNNs). Using a combination of drone data and the high-resolution images the rows in the individual plots were identified [11]. In a small subset (375 images), the wheat heads were annotated and the data was integrated into the public global wheat head detection data set [24]. The image-based canopy cover values served as a test data set to evaluate the cultivar-specific extensions of the thermal time concept [25].

The culmination of these efforts has resulted in a unique, multi-dimensional data set. Dense image time series of diverse wheat genotypes are integrated with trait measurements, genetic markers, and environmental data.

The data set has been designed to align with FAIR principles [26]:

- **Findable**: This publication and the Hugging Face data set card (`https://doi.org/10.57967/hf/3191`) provide detailed metadata and a comprehensive description of the data set's contents, making it discoverable to researchers.
- **Accessible**: The data is hosted on the Research Collection of ETH Zurich (`https://doi.org/20.500.11850/697773`), a reliable and openly accessible data storage.
- **Interoperable**: The use of the open-source Hugging Face datasets [27] package makes it easy to use and export to different formats.
- **Reusable**: The data is released under the CC-BY 4.0 licence (`https://creativecommons.org/licenses/by/4.0/`), a permissive licence that allows for further use of the data set.

Materials and Methods

Experimental Field Designs and Genotypes

All experiments were performed at the ETH research station of plant sciences in Lindau Eschikon, Switzerland (47.449 N, 8.682 E, 556 m a.s.l.). The soil characteristics were determined in 2015 (Eric Schweizer AG, Thun, Switzerland). The soil type is eutric cambisol consisting of 21% clay and 21% silt with an organic matter content of 3.5% and pH 6.7. A crop rotation was implemented during and before the start of wheat experiments beginning with a year of soybean (*Glycine max* (L.) Merr.), then a year of buckwheat (*Fagopyrum esculentum* Moench) and finally wheat (*Triticum aestivum* L.). After preliminary crops were harvested, the soil was plowed and harrowed before wheat was drill-sown. The wheat was sown in 9 rows per plot with a row length of ∼1.7 m, a row distance of 0.125 m and a sowing density of 370−400 plants m^{-2}.

A few days after sowing, herbicide (Herold SC, Bayer AG, Leverkusen, Germany) was applied to ensure weed-free plots. Several fungicides and insecticides were applied in spring to ensure healthy

plants. The fertilizer was split into three doses ($\sim$ 1:3:1), one at tillering stage, one at start of stem elongation, and one after heading. Approximately 140 kg N, 90 kg P_2O_5, and 100 kg K_2O per ha were applied, depending on site-specific soil analysis. No irrigation was applied. The sowing and harvest dates for each year are provided in Table 1.

For 2016−2018, a GABI-WHEAT panel subset (consisting of ~300 European winter wheat cultivars from the GABI-WHEAT panel [14, 28]) was complemented by 35−52 Swiss winter wheat varieties of commercial importance. For 2019, a small subset of the GABI-WHEAT panel (54 genotypes) was grown alongside genotypes from other experiments (e.g., Swiss variety testing). In 2019, these other genotypes were grown on larger plots with a row length of 5.5 m while GABI-WHEAT genotypes were grown on the same size plots as in the other years. In 2021 and 2022, sets of F8 genotypes from the Swiss breeding program of Agroscope (Nyon, Switzerland) were grown. For an overview of genotype overlaps between years, see Figure 2.

For all years, an experimental design following the principles of good practice—replication, randomization, and blocking [29]—was chosen. The described panels of, on average, 350 genotypes per year were replicated once, each replication was randomized and grown on a different lot in the FIP area (Figure 1). Each replication was augmented with checks in a 3×3 block arrangement. For further details on the experimental design, see [8, 9, 12].

Image Data

The FIP system is divided into two independent parts, (1) the carrier system built and maintained by Spidercam (Spidercam GmbH, Feistritz im Rosental, Austria), and (2) the custom-built FIP 1.0 sensor head and control software [7].

Carrier: The Spidercam Cable-Suspended System
The carrier system, detailed in Kirchgessner et al. [7], uses four corner-mounted poles with pulleys. Cables connect these pulleys to winches, enabling 3-D movement of the FIP 1.0 sensor head. A working distance of 2−3 m from the canopy was maintained during measurements.

Sensors: The FIP 1.0 Imaging Head
The FIP 1.0 sensor head carried, amongst other sensors, a 21 MP full frame DSLR camera (EOS 5D Mark II, 35 mm lens (Canon Inc., Tokyo, Japan) [7]. The camera was triggered automatically via a custom MATLAB script (The Mathworks [30]). The images were mostly captured using auto white balance, auto exposure, an ISO of 100, an exposure time of 1/250 second (4 ms), and zero exposure bias value. The ground sampling distance is approximately 0.55 mm.

Image registration
The positions of the captured images of the plots change throughout the season due to inaccuracies in the camera carrier system and intentional height adjustments due to plant growth. To allow for consistent image feature extraction, the time series needed to be aligned using an image registration pipeline. Image registration transforms the images so that points that are at the same physical location in the real world are aligned to the same point in the image plane. The used image registration pipeline consists of two steps: a deep learning-based feature matcher and a transformation estimation step. The feature matcher is used to find features that correspond to the same location between an image pair, which are then used to estimate the transformation between the images. The registration was performed between image pairs instead of the whole sequence directly, commonly referred to as image alignment.

To predict aligned polygons of the inner rows (Figure 1) for an image time series three individual steps were performed. First an initial reference polygon was aligned with a drone orthomosaic or prior data. Then subsequent aligned polygons were found based on this initial polygon or a previously aligned polygon. Finally, a single transformation between alignments and the inner plots was estimated and applied to all aligned polygons. The aligned result of a time series can be seen in Figure 3.

To find the initial reference polygon, the 3D-world-coordinates of the plot corners were first extracted from drone-based orthomosaics (2018−2022), from other projects [31, 10, 11, 32, 18, 12], or from extrapolations of these plot corners to earlier years (2016−2017). The 3D plot corners from this initial extraction process were matched to the best-fitting image in the image time series to find their 2D counterparts, which were used as the initial reference polygon.

Using the initial reference image and polygon, the initial image was matched with other images and the resulting transformation used to find the other aligned plot corners. Matching features between different time points in a crop season is challenging due to significant changes in conditions between images, such as varying lighting, plant growth and changing appearance of the plants. For this reason, a modified version of the deep learning LoFTR [33] feature matcher was fine-tuned to focus on consistent soil features, such as stones. Even these consistent objects slowly change their positions throughout the season or rapidly between strong precipitation events. Therefore, the transformations were estimated between image pairs and not the complete time series at a time. The estimated transformations between the image pairs are homographies based on the soil plane.

A prior alignment strategy employing Scale-invariant feature transform (SIFT) based feature matching required manual alignment of about 10,000 image pairs to fill gaps where the matcher failed. While suitable for smaller scale projects, this approach was deemed unviable for the complete data set. These manual alignments, created by choosing four point-pairs to find suitable homographies, were used to fine-tune the LoFTR feature matcher. The homographies correspond to the transformations between the common soil plane of the image pairs. This simplification was used to fine-tune the model to find matches solely in the soil plane, as features in the canopy are at incorrect positions due to not being on the homography plane. Since the canopy moves, sometimes significantly, between time-points, this reduces the number of incorrect matches that the feature matcher produces. The model was fine-tuned for 20 epochs with randomly cropped, rotated and distorted image pairs. These augmentations were applied to each image individually, adjusting the homographies accordingly. The augmentations were chosen such that the image pairs were always partially overlapping.

To verify the correctness of the matches and their homographies, several checks were employed. Basic checks, such as ensuring enough inliers, constraining the ratios of the side lengths and angles of the polygon spanned by the plot corners to their 3D counterparts, and other image-based checks were applied with high thresholds. The essential matrix was calculated, and the warped plot corners were compared to their closest point on the epipolar line. The essential matrix was used to triangulate the 3D points of the plot corners, and they were compared to the original 3D-world-coordinates by checking the ratios and angles of the polygons spanned by the plot corners. These ratios were used to scale the predicted relative camera movement and compare it individually to the maximum possible movements in each axis. Finally, these predictions and checks were done twice with the image pair swapped and compared to each other. This check filtered cases where LoFTR predicted structured noise that corresponded to the identity homography between the image pairs. To filter outliers these steps were iteratively repeated, and the best prediction based on the checks was chosen.

When an image could not be matched to the initial image, it was iteratively matched with the closest found alignment, based on the

number of transformations and then the date differences. Matches were used to find homographies using OpenCV [34], which were then used to warp the plot corners (Figure 1, 'Plot').

The complete process, except the initial 3D-world-coordinates extraction, was iteratively repeated by going from very tight to looser restrictions in the checks. The fine-tuned LoFTR model was bootstrapped, that is, further trained at each step by adding the trusted subset of its predictions that passed the checks in the previous step to the training set.

Finally after predicting all plot corners, a relative inner plot polygon was extracted to mitigate border effects and further correct the alignment. The seven inner rows of plants were detected based on segmented images showing plant and soil pixels. Then, plots were further rectified by rotating them step-wise (-1.5° to 1.5° in steps of 0.2°) to maximize the distance between the minimum and maximum numbers of plant pixels in image columns [25]. Inner plots were filtered if they did not contain the complete plot.

In total, the alignment and inner plot detection was successful for more than 95% of all images (151,150 out of 158,891 images).

Image preprocessing

The raw images were converted to PNG format, an accessible and lossless image format, using rawpy [35] with minimal post-processing, reducing resolution to half size, employing a linear demosaicing algorithm, and disabling auto adjustments in order to preserve the original sensor data with minimal artifacts or alterations. The inner plots were directly cut out of the pre-processed image by combining the plot and its relative inner plot transformation.

Reference Measurements

As part of several projects [8, 9, 15, 16, 18, 12], reference measurements such as grain yield and growth stage ratings were taken. Those traits can be divided into low-level traits (time series of traits that develop over time), intermediate traits (traits extracted from low-level traits that describe the growth dynamics over time [20, 19]) and target traits (observations that are usually targeted in breeding and agriculture, e.g., yield) (Table 4).

Low-level Traits

Plant height measurements were performed with a TLS (Focus 3D S 120, 905 nm laser, Faro Technologies Inc., Lake Mary, USA) for 2016 and 2017 on the same date as image acquisition [8]. From 2019−2022, drone RGB images [10, 11] were used to extract plant height estimations with Structure from Motion (SfM) [36]. FIP image collection dates and drone campaign dates were typically within days of each other but did not necessarily overlap.

From images, canopy cover was extracted using a deep learning model described in Zenkl et al. [22]. The percentage of soil covered by plant parts was determined for the seven-row inner plot (Figure 1) as described in Tschurr et al. [37]. On the same seven-row inner plot, wheat head count estimations were determined for all dates from May to end of season. As the wheat head detection method, the winning model of the global wheat head challenge [24] (https://github.com/ksnxr/GWC_solution) was used.

Senescence was assessed visually, separately for the flag leaf and the whole canopy, following guidelines provided by Pask et al. [38]. Flag leaf senescence and whole plot senescence was scored according to Anderegg et al. [16] based on the portion of green leaf area on a scale from 0 to 10, equivalent to 0 to 100 %.

Intermediate Traits

Heading date was visually assessed as the date when 50% of the spikes were fully emerged from the flag leaf sheath [17] (BBCH 59, [39]). Final height was extracted from TLS or SfM plant height measurements using the Quarter of Maximum Elongation Rate

(QMER) method described in Roth et al. [20].

Target Traits

Yield for all years was estimated based on two rows of nine rows (row seven and eight). Ears within these two rows were hand-harvested, dried for at least 24 hours at 30 °C, and threshed using a stand thresher (Saatmeister Allesdrescher K35; Saatzucht Baumann, Germany). Weight was determined using a scale, and water content with a Wile 55 moisture meter (Farmcomp Oy; FIN04360 Tuusula, Finland). Grain yield was mathematically normalized to 14 % water content. Grain protein content was determined using near-infrared transmission spectroscopy (InfratecTM 1241 Grain Analyzer; Foss, DK-3400 Hilleroed, Denmark).

Adjusted genotype means within year calculation

All intermediate and target traits were processed to adjusted genotype means (Best Linear Unbiased Estimate (BLUE)) using a linear mixed model in SpATS for low-level traits [40] and ASReml-R [41] for intermediate and target traits,

$$y_{ijk} = m_c + g_i + p_{r(k)} + p_{c(k)} + S(r(k)), c(k)) + e_{ijk}, \quad (1)$$

where y_{ijk} is the measured trait value for the ith genotype in the jth year for plot k in row $r(k)$ and column $c(k)$. m_c is a fixed effect marking check varieties ($m_c \in [0,1]$), g_i is a fixed genotype effect, $p_{r(k)}$ and $p_{c(k)}$ are fixed spatial row and column effects, and e_{ijk} a spatially independent residual. For SpATS, $S(r(k)), c(k))$ is a spatial smooth surface in row and column direction as defined in [40], whereas for ASReml-R, it is an auto-regression of order 1 in both row and column direction and two splines in row and column direction, $AR1_{r(k)} \times AR1_{c(k)} + Spl(r(k)) + Spl(c(k))$.

Environmental Covariates

Air temperature, relative humidity, short wavelength solar irradiance, and soil temperature were measured at a local weather station in proximity to the experimental field above or below a grass strip [25]. Air temperature and relative humidity were measured 2 m and 0.1 m above ground, short wavelength solar irradiance 2 m above ground, and soil temperature 0.05 m below ground, respectively. Precipitation data were taken from a close-by Agrometeo weather station at Strickhof (<800 m, https://www.agrometeo.ch). Measurement gaps caused by technical issues (e.g., sensor failure) were filled with data from the Strickhof station if available and with data from a Meteoswiss station at the Zurich Airport (9.5 km, https://gate.meteoswiss.ch/idaweb/) otherwise. Overall, more than 97% of the data after gap filling originated from the local weather station or Strickhof weather station.

Genetic marker data

Genetic marker data (90k SNP array) for the GABI-WHEAT panel are publicly available [28]. The private marker data were created using a 45k SNP array. Two sets were compiled: A pure GABI-WHEAT marker data set, and an extended marker set consisting of overlapping marker from both public and private markers. Marker locations on the reference genome IWGSC RefSeq v1.0 were collected with InterMine [42] from https://urgi.versailles.inrae.fr and complemented with locations previously mapped with blastn from an earlier project [12].

SNPs in both sets were first filtered for minor allele frequency (5%) and missing values (5%). Genotypes in both sets were then tested for missing marker data with a missing rate of 1% (all passed, no genotype had to be removed). Finally, missing marker data (0.44% for GABI-WHEAT set, 0.54% for extended set) were imputed based on a k-nearest-neighbour implementation in R (scrime [43]) per chromosome. Markers were sorted by chromosome and location for later use in local connectivity models such as CNNs.

Markers with ambiguous positions were left in the set but marked accordingly.

The resulting GABI-WHEAT genetic marker set includes 372 genotypes and 18'846 markers. The extended set includes 824 genotypes and 11'904 markers. Based on the marker data, kinship matrices [44] were calculated according to Yang [45].

Compilation as Data set

Train/Test Split According to Genetic Relatedness

The most interesting application of trait prediction approaches is to predict the performance of unseen genotypes in unseen years [46, 47]. The accuracy of such predictions typically depends on the relatedness of genotypes, usually assessed through cross-validation. However, cross-validation is computationally expensive for complex deep learning models. To address this issue, we propose an alternative approach that balances the train/test set using genetic relatedness [48]. This method theoretically yields performance close to the average of all cross-validation runs.

To implement this approach, we used the R package STPGA [49] to determine a test set complementing the training set with the algorithm 'D_{opt}' as suggested in [50]. The training set was further split into training and validation sets using the same method. We define four test sets to allow for specific evaluation of methods depending on their use. The test sets differ based on if their genotypes and environments occur in the train set (denoted as seen):

i. Test (P): Unseen plots with seen genotypes and seen environments (all years except 2019)
ii. Test(G): Unseen genotypes with seen environments
iii. Test(E): Unseen environment (2019) with seen genotypes
iv. Test(G and E): Unseen genotypes and unseen environment (2019)

To validate our balanced splitting approach, we also performed five-fold cross-validations, allowing for a quality check of the balanced splits. The splits were calculated for the pure GABI-WHEAT set and for the extended set, including F8 generation genotypes with private marker data in the latter. For the GABI-WHEAT set, this resulted in 262 genotypes in the training set, 24 in the validation set, and 30 in Test(G and E) test set (Figure 5). For the extended set, this resulted in 695 genotypes in the training set, 30 in the validation set, and 30 in Test(G and E) test set.

Preparation as Hugging Face Data set

All data was aggregated into a single table with a row for each plot containing the image sequence, the aligned image sequence, traits, environmental data, marker data, and additional metadata. The table was split using the aforementioned splits and converted to a single Hugging Face data sets DatasetDict using the schema shown in Table 5. The table and DatasetDict contain None values for completely missing entries. Missing data in sequences are absent.

Data Validation and Quality Control

Heritabilities of low-level traits

Heritability is a statistic used in breeding to quantify how much of a trait's variation is attributable to the examined genetic material, ranging from 0 to 1. For field phenotyping traits, heritability can indicate the quality of a trait, as one is interested in methods that extract highly genotype-specific values, i.e., traits with high heritability. To assess the quality of low-level traits, heritability was calculated for each time point by setting the genotype factor g_i in Equation 1 to random and estimating genetic and non-genetic variances, as described by Oakey [51]. The resulting heritabilities

(Figure 4) follow an expected temporal pattern: increasing with growth and decreasing towards the end of the growth phase. These findings align with previously reported values for the same data set, e.g. 0.77 for senescence traits (2016-2018) [16] and 0.61/0.59 for derived plant height traits (start/stop growth) [12]. Additionally, plant height measurements obtained using TLS have been shown to strongly correlate with drone-based height estimations (correlation of 0.99) [12].

Heritabilities of intermediate and target traits

To test for the quality of intermediate and target traits, heritability was calculated according to Cullis et al. [52] by setting the genotype factor g_i in Equation 1 to random and estimating genetic and non-genetic variances. The results (Table 3) are in accordance with values reported for the same data set before, e.g., 0.55 for grain yield in $2016-2018$ [16], 0.97 for heading date in $2016-2018$ [16], 0.84 for grain protein content in 2016 and 2017 [16], and 0.98 for final height in $2015-2018$ [12].

The quality of the public marker data set for the GABI-WHEAT panel was demonstrated in Gogna et al. by means of testing for genomic prediction ability [13]. The same quality check was performed on the data set presented herein, once with the public marker data from the GABI-WHEAT panel, once with the extended set that includes private marker data as well.

Three different GBLUP-based genomic prediction models were trained: One linear mixed model with simple main effect and identity variance (ID), one with simple main effect and diagonal variance (DIAG), and one with a simple main effect and random regression to environmental covariates [53]. As environmental covariates, metrics were based on the Standardized Precipitation and Evapotranspiration Index (SPEI) [54], Vapour Pressure Deficit (VPD), air temperature at 2.0 m above ground, and precipitation. For the SPEI and temperature, the mean, maximum and minimum value over the season were used, for VPD, the mean and maximum, and for precipitation, the sum of the values was used. All models were implemented in ASReml-R using code by [55].

The results suggest comparable accuracies to Gogna et al. [13] for final height, heading date and protein content, and inferior performance for grain yield (Table 6). These results are in accordance to the heritabilities found for the traits (Table 3). The random regression model could only outperform the two other models for the trait heading date.

Genomic prediction ability of unseen multi-environment trial

Gogna et al. have published a MET data set for yield, protein content, heading date and final height comprising eight environments (five locations and one to two years) for the GABI-WHEAT panel [13]. 312 of the measured genotypes overlap with the FIP 1.0 data set, 60 are unseen in the FIP 1.0 data set but marker data are available. The unseen genotypes (60) in unseen environments [13] were taken as independent test sets in new environments for a genomic prediction approach similar to the one described in the previous section. For the random regression model, hourly temperature, precipitation and relative humidity data for the German environments were extracted from the Climate Data Center (CDC) of the German Weather Service, those for the French environments from Meteo France (SYNOP, 3-hourly data only).

For grain yield, the random regression model outperformed the other models for both the GABI-WHEAT and extended marker set (Table 6). For all other traits, no clear advantage of the random regression model over the other models was visible. Again, the results suggest comparable accuracies to Gogna et al. [13] for final height, heading date and protein content, and slightly inferior performance for grain yield (Table 6).

Re-use Potential

In this work, we provide baselines for genomic prediction approaches, trait extractions from images, and subsequent trait dynamics modeling. Accordingly, we see the largest re-use potential of the presented data set for the development and evaluation of new modelling and prediction approaches in crop genomics and phenomics. The multi-faceted data set allows modelling approaches on various levels:

   i. Genomic prediction approaches that include genotype-environment interactions: The presented data enhance the data by Gogna et al. [13] by 6 environments, totalling to 14 environments that are characterized by environmental covariates. The presented benchmark of a genomic prediction with random regressions to environmental covariates [53] provides a baseline that novel approaches can challenge.

   ii. Modelling plant growth and development with longitudinal modelling approaches: The four low-level traits canopy cover, plant height, wheat head count and senescence cover the full growing season of winter wheat in 6 environments that are characterized by environmental covariates. Baseline approaches for plant height growth modelling [8, 9, 19, 20, 21, 12], canopy cover growth modelling [25] and senescence dynamics modelling [15, 16, 17] for subsets of the presented data exist.

   iii. Image-based phenomic predictions and combined phenomic and genomic prediction approaches: The dense time series of images allow training and analysing end-to-end modelling approaches (e.g., deep learning based) that predict target traits such as yield based on images.

Example 1: Basic access to data set via hugging face datasets package

```
1  import datasets
2  fip1 = datasets.load_dataset("mikeboss/FIP1")
3  fip1_train = fip1["train"]
4  print(fip1)
5  # Output:
6  DatasetDict({
7      train: Dataset({
8          features: ['plot_uid', 'yearsite_uid', 'crop_type',
           'experiment_number', 'plot_number', 'dates', 'times'
           , 'sowing_date', 'harvest_date', 'harvest_year', '
           images', 'image_dates', 'image_times', ...],
9          num_rows: 2930
10     })
11     validation: ...
12     test_plot: ...
13     test_genotype: ...
14     test_environment: ...
15     test_genotype_environment: ...
16 })
```
Listing 1. Example 1

Example 2: Load aligned inner plot cutouts as stacked pytorch tensor

```
1  fip1 = fip1.select_columns("inner_plot_images")
2  fip1 = fip1.cast_column("inner_plot_images", datasets.
       Sequence(datasets.Image()))
3  fip1 = fip1.with_format("pt")
4  print(fip1["train"][0]["inner_plot_images"].shape)
5  # Output:
6  torch.Size([26, 3, 640, 960])
```
Listing 2. Example 2

Example 3: Access low-level trait time series

```
1  print(fip1["train"][0]["height_values"])
2  # Output:
3  [0.3284, 0.3833, 0.4375, 0.4749, 0.5024, 0.5396, 0.582,
       0.7456, 0.9165, 0.9385, 1.018, 1.13, 1.2, 1.242,
       1.268, 1.37, 1.369, 1.372, 1.389, 1.355, 1.357,
       1.159]
```
Listing 3. Example 3

Example 4: Access target traits

```
1  fip1 = fip1.select_columns(["yield_value", "protein_value",
       "height_final_value", "heading_date_value"])
2  print(fip1["train"][0])
3  # Output:
4  {'yield_value': 12.04, 'protein_value': 13.61, '
       height_final_value': 1.346, 'heading_date_value':
       1576.0}
```
Listing 4. Example 4

Example 5: Access marker data

```
1  fip1 = fip1.with_format("numpy")
2  print(fip1["train"][0]["marker_biallelic_codes"])
3  print(fip1["train"][0]["marker_metadata_strings"])
4  # Output:
5  [2 2 2 ... 2 2 2]
6  ['0000000001:chr1A:1145398:1145498:BS00000713_51_T_C'
7   '0000000003:chr1A:1174887:1174987:
       Excalibur_c10657_1280_C_T'
8   '0000000004:chr1A:1176337:1176337:
       wsnp_Ex_c10657_17376086_C_T' ...
9   'wsnp_bf474966A_Ta_2_1_T_C' 'wsnp_bm138650D_Ta_2_2_G_A'
10  'wsnp_cd454041D_Ta_2_1_C_T']
```
Listing 5. Example 5

Example 6: Access environmental data in January

```
1  fip1 = fip1.select_columns(
2      ["temperature_air_10cm_values", "
       temperature_air_10cm_dates"]
3  )
4  fip1 = fip1.map(
5      lambda values, dates: {
6          "temperature_air_10cm_values_january": [
7              value for value, date in zip(values, dates,
       strict=True) if date.month == 1
8          ]
9      },
10     input_columns=["temperature_air_10cm_values", "
       temperature_air_10cm_dates"],
11 )
12 print(fip1["train"][0]["temperature_air_10cm_values_january
       "][:10])
13 # Output:
14 [2.6, 2.7, 2.8, 2.4, 0.6, 0.6, 1.3, 2.3, 2.6, 2.9]
```
Listing 6. Example 6

Availability of Source Code and Requirements

Trait data compilation

Project name: FIP 1.0 Data Set - Traits
Project home page: https://gitlab.ethz.ch/crop_phenotyping/fip-1.0-data-set-traits

Operating system(s): e.g. Platform independent
Programming language: R, Python
License: GNU GPL v3

Image data alignment

Project name: fip1-alignment
Project home page: `https://gitlab.ethz.ch/crop_phenotyping/fip1-alignment`
Operating system(s): e.g. Platform independent
Programming language: Python
License: GNU GPL v3

Data set compilation

Project name: fip1-dataset
Project home page: `https://gitlab.ethz.ch/crop_phenotyping/fip1-dataset`
Operating system(s): e.g. Platform independent
Programming language: Python
License: GNU GPL v3

Data Availability

· Data Repository: `http://doi.org/20.500.11850/697773`
· Hugging Face Data set: `https://huggingface.co/datasets/mikeboss/FIP1`
· Private Agroscope marker data repository: Confidential (Contact: Boulos Chalhoub, boulos.chalhoub@agroscope.admin.ch)

Declarations

Glossary

F8 Eighth Generation Breeding Material. 2, 3, 5

RGB Red, Green and Blue. 2, 4

Acronyms

BLUE Best Linear Unbiased Estimate. 4

CNNs Convolutional Neural Networks. 2, 4

FIP Field Phenotyping Platform. 2−4, 8
FIP 1.0 Field Phenotyping Platform 1.0. 2, 3, 5, 11

GABI-WHEAT Genomanalyse im Biologischen System Pflanze - Weizen. 2−5, 8, 10, 11

HTFP High-throughput field phenotyping. 2

INVITE Innovation in Variety Testing. 2

MET Multi-Environment Trial. 2, 5

QMER Quarter of Maximum Elongation Rate. 4

SfM Structure from Motion. 4
SIFT Scale-invariant feature transform. 3
SpATS Spatial Analysis of Field Trials with Splines. 4
SPEI Standardized Precipitation and Evapotranspiration Index. 5

TLS Terrestrial Laser Scanner. 2, 4, 5

VPD Vapour Pressure Deficit. 5

Consent for Publication

Not applicable.

Competing Interests

The author(s) declare that they have no competing interests.

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Author's Contributions

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Figure 1. The data set source: 12 wheat lots in 6 years (2016–2022) with >350 wheat plots each, resulting in >4,000 plots from which >160,000 images were taken. The background image shows the Field Phenotyping Platform (FIP) lot 1 with wheat plots. All wheat lots were integrated in a regular crop rotation with other crops (A) according to a permanent lot plan (B). Images taken with the FIP show one complete plot each, the positions of the complete plot and the inner 7 rows are annotated (C).

Figure 2. The examined genotype sets with their genetic relatedness visualized in SNP-marker based principal component analysis based on public GABI-WHEAT markers (A) and public and private markers combined (B), and year of cultivation of genotypes (C).

Table 1. Sowing and harvest dates

Year	Sowing Date	Harvest Date
2016	2015-10-13	2016-07-27
2017	2016-11-01	2017-07-19
2018	2017-11-02	2018-07-14
2019	2018-10-17	2019-07-23
2021	2020-10-21	2021-07-29
2022	2021-10-25	2022-07-19

Figure 3. An image time series of a plot over one season with the aligned inner plot cutouts in each second row. The initial alignment polygon, shown in light blue, is based on alignment with a drone orthophoto. All other alignment polygons, shown in orange, are transformed from the initial polygon or another aligned polygon. The inner plot polygons, shown in brown, are based on a single transform from an aligned polygon to the inner rows of the plot. Images are adjusted for visibility.

Table 2. Data set sizes and key characteristics. Numbers describe absolute sizes, i.e., how many plots and genotypes were examined in a specific year, and how many of this plots/time series are annotated with target traits yield, grain protein content, heading date, and final height.

Year	Plots/Time series	Genotypes	Grain yield	Protein content	Heading date	Final height
2016	710	335	710	685	710	710
2017	756	352	754	0	377	756
2018	756	353	756	674	369	756
2019	252	78	248	144	177	252
2021	792	346	661	781	453	792
2022	792	373	744	792	719	792
Total	4058	1837	3873	3076	2805	4058

Figure 4. Heritability of the four low-level traits per point in time for all years (2016−2022) (A) and normalized measured trait values (B). Indicated are means (points) and the 25% and 75% percentile (areas).

Figure 5. Training, validation and test splits for the GABI-WHEAT marker data based genotype set. The test set includes four subsets, unseen genotypes (G), unseen environments (E), unseen genotypes in unseen environments (G and E), and seen genotypes in seen years on unseen plots (plots). The validation set includes two subsets, unseen genotypes (default) and seen genotypes on unseen plots (plots). The splits are shown based on plots (A) and based on genotype count (B).

Table 3. Cullis heritabilities (H^2) of intermediate and target traits for all years.

Trait	Heritability (H^2)					
	2016	2017	2018	2019	2021	2022
Grain yield	0.61	0.40	0.35	0.76	0.39	0.46
Protein content	0.83	–	0.85	0.77	0.52	0.87
Heading date	0.96	N/A	0.81	0.91	0.71	0.90
Final height	0.97	0.98	0.97	0.92	0.96	0.97

N/A: Unreplicated measurement, heritability not available
-: No measurements in this year

Table 4. Measured traits that were used to annotate image time series. Label refers to the name used in the data set for the trait.

Trait	Unit	Label	Description
Low-level traits			
Canopy cover	(0…1)	canopy_cover	Soil coverage by plants from a nadir view
Plant height	m	height	Distance top of soil to top of canopy
Wheat head count	Count	spike_count	Number of visible wheat spikes
Senescence rating	(0…10)	senescence	End-of-season leaf decay ratings
Intermediate traits			
Heading date	Date	heading_date	Date when 50% of wheat spikes visible
Final height	m	height_final	Plant height at end-of-season
Target traits			
Grain yield	t/ha	yield	Total weight of harvested grains
Protein content	%	protein	Grain protein content

Table 5. A schema of the data set similar to the actual schema of the Hugging Face data set. Sequence indicates a variable length of values while Array2D indicates a consistent shape of the data.

Field Name	Type	Field Name	Type
identifiers		height_final_value	float16
plot_uid	string	height_final_date	date32
yearsite_uid	string	height_final_blue	float16
crop_type	string	height_final_heritability	float16
experiment_number	uint8	height_final_trait_id	uint8
plot_number	int16	height_final_method_id	uint16
dates		**target traits**	
sowing_date	date32	yield_value	float16
harvest_date	date32	yield_date	date32
harvest_year	uint16	yield_blue	float16
images		yield_heritability	float16
images	Sequence[string]	yield_trait_id	uint8
image_dates	Sequence[date32]	yield_method_id	uint16
image_times	Sequence[time32[s]]	protein_value	float16
alignments		protein_date	date32
alignment_plot_soil_polygons	Sequence[Array2D[float16]])	protein_blue	float16
alignment_num_steps	Sequence[uint8]	protein_heritability	float16
alignment_dates	Sequence[date32]	protein_trait_id	uint8
alignment_times	Sequence[time32[s]]	protein_method_id	uint16
alignment_initial_date	date32	**markers**	
alignment_inner_plot_transform	Array2D[float16]	genotype_id	string
inner_plot_images	Sequence[string]	marker_biallelic_codes	Sequence[uint8]
image_inner_plot_transforms	Sequence[Array2D[float16]]	marker_metadata_strings	Sequence[string]
low-level traits		**environment**	
canopy_cover_values	Sequence[float16]	temperature_air_10cm_values	Sequence[float16]
canopy_cover_dates	Sequence[date32]	temperature_air_10cm_dates	Sequence[date32]
canopy_cover_trait_ids	Sequence[uint8]	temperature_air_10cm_times	Sequence[time32[s]]
canopy_cover_method_ids	Sequence[uint16]	temperature_air_200cm_values	Sequence[float16]
height_values	Sequence[float16]	temperature_air_200cm_dates	Sequence[date32]
height_dates	Sequence[date32]	temperature_air_200cm_times	Sequence[time32[s]]
height_trait_ids	Sequence[uint8]	temperature_soil_5cm_values	Sequence[float16]
height_method_ids	Sequence[uint16]	temperature_soil_5cm_dates	Sequence[date32]
spike_count_values	Sequence[float16]	temperature_soil_5cm_times	Sequence[time32[s]]
spike_count_dates	Sequence[date32]	humidity_air_10cm_values	Sequence[float16]
spike_count_trait_ids	Sequence[uint8]	humidity_air_10cm_dates	Sequence[date32]
spike_count_method_ids	Sequence[uint16]	humidity_air_10cm_times	Sequence[time32[s]]
senescence_values	Sequence[float16]	humidity_air_200cm_values	Sequence[float16]
senescence_dates	Sequence[date32]	humidity_air_200cm_dates	Sequence[date32]
senescence_trait_ids	Sequence[uint8]	humidity_air_200cm_times	Sequence[time32[s]]
senescence_method_ids	Sequence[uint16]	precipitation_200cm_values	Sequence[float16]
intermediate traits		precipitation_200cm_dates	Sequence[date32]
heading_date_value	float16	precipitation_200cm_times	Sequence[time32[s]]
heading_date_date	date32	irradiance_solar_200cm_values	Sequence[float16]
heading_date_blue	float16	irradiance_solar_200cm_dates	Sequence[date32]
heading_date_heritability	float16	irradiance_solar_200cm_times	Sequence[time32[s]]
heading_date_trait_id	uint8		
heading_date_method_id	uint16		

Table 6. Genomic prediction accuracy (correlation) and bias (RMSE) of intermediate and target traits.

Split set	Trait	ID			DIAG			RREG			ID			DIAG			RREG		
		Correlation									RMSE								
		B	CV	MET	B	CV	MET	B	CV	MET	B	CV	MET	B	CV	MET	B	CV	MET
GABI-WHEAT	Grain Yield	0.11	0.29	0.21	0.11	0.29	0.23	0.1	0.29	0.33	1.21	1.21	1.35	1.2	1.21	1.35	1.48	1.59	1.05
GABI-WHEAT	Protein Content	0.42	0.52	0.44	0.39	0.51	0.44	0.38	0.4	0.46	0.61	0.62	1.2	0.62	0.63	1.19	0.86	0.86	1.45
GABI-WHEAT	Heading Date	0.59	0.54	0.67	0.59	0.54	0.67	0.59	0.54	0.67	6.26	6.95	5.72	6.23	6.92	5.72	5.07	5.76	5.81
GABI-WHEAT	Plant Height	0.83	0.77	NA	NA	NA	NA	0.83	NA	0.81	0.06	0.07	NA	NA	NA	NA	0.13	NA	0.13
Extended	Grain Yield	0.19	0.33	0.24	0.19	0.33	0.26	0.19	0.28	0.37	1.23	1.12	1.31	1.23	1.12	1.31	1.49	1.46	1.04
Extended	Protein Content	0.53	0.71	0.52	0.54	0.71	0.53	0.52	0.7	0.52	0.71	0.7	1.21	0.7	0.7	1.2	0.88	0.88	1.45
Extended	Heading Date	0.57	0.54	0.66	0.59	0.59	0.68	0.59	0.56	0.65	6.63	6.33	5.68	6.62	6.35	5.66	5.29	5	5.83
Extended	Plant Height	0.82	0.79	0.81	0.82	0.8	0.8	0.82	NA	0.8	0.06	0.06	0.08	0.06	0.06	0.08	0.11	NA	0.14

ID: Identical variances; DIAG: Varying variances per year; RREG: Random regression to environmental covariates; NA: Failed convergence of models

Test set: B: Balanced FIP 1.0 data set; CV: 5-fold cross-validation on FIP 1.0 data set; MET: Unseen multi-environment trial data set

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