Bees flexibly adjust decision strategies to information content in a foraging task

Johannes Spaethe[1], Selma Hutzenthaler[1], Alexander Dietz[1,2], Karl Gehrig[1], James Foster[2], Anna Stöckl[2,3]

[1] *Behavioral Physiology and Sociobiology (Zoology II), University of Würzburg, Biozentrum am Hubland, 97074 Würzburg, Germany*

[2] *Department of Biology, University of Konstanz, Universitätsstr. 10, 78464 Konstanz, Germany*

[3] *Zukunftskolleg, Universität Konstanz, Konstanz, Germany*

* corresponding author: anna.stoeckl@uni-konstanz.de

Abstract

When making decisions, humans and animals often rely on multiple sensory cues simultaneously. These provide complementary sources of information, which can help overcome ambiguity and noise, and increase the accuracy of decisions. While most studies have focused on the benefits of multimodal and within-mode integration for learning and decision making, their costs have received less attention. Processing, learning and memorizing multiple inputs requires more neural resources than for single cues, and might also require more time. In this study, we tested whether insects trade off the costs and benefits of learning multiple cues in a foraging task, using the buff-tailed bumblebee *Bombus terrestris*. To maximize comparability between cues, we presented combinations of visual-only features, as found on natural flowers: colours of varying discriminability, paired with shapes or patterns. We found that the bees relied exclusively on colours when these were easy to discriminate, and did not learn pattern or shape features presented simultaneously. With harder to discriminate colours, the bees learned both colour and shape or pattern features. Our results demonstrate that bumblebees flexibly adjust their learning strategies when presented with visual features of varying discriminability, to balance the costs and benefits of multi-cue learning. Our analysis of the learning rates of the bees with multi- and single attribute stimuli suggests that blocking could serve as a mechanism to implement this strategy switch. These results shed light on trade-offs in learning and decision making with multiple cues, and can directly be compared to studies in other insects, animals and humans.

Keywords: decision making, insect, multi-modal, foraging, trade-off, learning

Significance Statement:

When making decisions, animals often rely on multiple sensory cues simultaneously. These complementary sources of information can increase decision accuracy. Unlike the benefits of cue integration, their costs have received less attention. In this study, we tested whether insects trade off the costs and benefits of learning multiple cues in a foraging task. We trained buff-tailed bumblebees, *Bombus terrestris,* to feature combinations of natural flowers. Bees flexibly switched from linear integration to winner-takes-all decision strategies depending on the sensory information available, thereby balancing accuracy and time investment in the task. We find that this switch can be explained by the cognitive phenomenon of blocking; providing the ground for future investigations into the underlying neural mechanisms of flexible decision strategies.

Introduction

When animals and humans make decisions based on their sensory input, they often rely on multiple simultaneous cues, both within and across modalities [1-5]. We can, for example, hear and see an approaching car, and can tell a ripe from an unripe strawberry by its colour and size, scent and haptic properties. Such complementary sources of information can help overcome ambiguity when choosing between multiple options, or noise associated with one or multiple of the sensory cues [6-10], and thereby increase the accuracy of decisions in diverse species ranging from primates [11-14] to insects [15-20]. While the benefits of multimodal and within-modal integration of cues for learning and decision making are well demonstrated, the trade-offs between these benefits and potential costs have received less attention. Processing multiple inputs [21, 22], and even more so learning and memorizing them might be more costly in terms of time [23] (but see also [15, 17]), and can further lead to conflicts between the sensory inputs [24-26]. Thus, learning and integrating multiple cues might only be beneficial for decision making, when the increase in accuracy outweighs the additional costs, for example when cues are hard to detect or noisy [27-29]. When a decision can be made with high accuracy using a single cue, integrating multiple cues simultaneously might be an optimal decision-making strategy in terms of accuracy, but not in terms of efficiency [22, 30].

In this study, we tested whether insects trade off the costs and benefits of learning multiple cues in a choice task, using the buff-tailed bumblebee, *Bombus terrestris,* as a model. Insects make an ideal model system for these investigations, as they are able to take fast and accurate decisions, but possess very limited processing power [31, 32]. Much of our understanding of multimodal decision-making in insects is for visual and olfactory cues in a foraging context, for example of pollinating insects selecting and memorising flowers with visual and olfactory attributes [32-34]. Integrating cues in this context has been demonstrated to increase decision accuracy [15, 16, 18], reduce response time [15] and overcome ambiguity caused by noisy stimuli [19]. To avoid context dependent modulation as generated by olfactory cues [34, 35] and maximize comparability between cues, we presented combinations of visual-only features, as they are found on real flowers that bees visit: colours, shapes and patterns [36, 37]. We presented cue combinations which varied in the discriminability in one of the visual attributes to assess the strategies bees followed in tasks of varying difficulty.

Results & Discussion

To test which attributes bumblebees retained from flowers displaying multiple visual cues simultaneously, we used an experimental design in which the bees first learned to associate a combination of colour and configural cue (either pattern or shape) with a sucrose reward, and a second combination of these cues with a drop of water (Fig. 1B). We then set the two attributes in conflict, by swapping them across the stimulus pair (as in [46, 47]), to test which attribute the bees relied on more strongly to make their decisions. Subsequently, bees were trained on the original cue combination again, to then test whether they had learnt the attribute they did not choose in the first test. To assess if the bees used the same learning and decision strategy in different contexts, we designed two colour categories: *distant* colour pairs and *close* colour pairs (Fig. 1C), which were easier and harder to discriminate perceptually, respectively (Fig. S1).

Fig. 1 The importance of colour, pattern and shape for pollinator flower selection.
A Flowers provide a combination of different visual cues used by insect visitors for detection and discrimination; most prominently colour, patterns and shapes. **B** To assess which of these attributes insects attend to and learn, we presented bumblebees (*Bombus terrestris*) with a combination of cues: colour and configuration (patterns or shapes). The bees were trained differentially to a colour pair, combined with either a pair of patterns or shapes, and then had to choose between the colour or configural attribute in a conflict test. Subsequently, the animals' training was reinforced, and a second test assessed whether they learned the attribute they did not preferentially choose in the conflict test. **C** Each bee was presented with a stimulus pair out of four colour combinations for either patterns or shapes. Two of the colour pairs were distant in sensory perception, while the other two were close (see Fig. S1).

Before the training, the naïve preferences of all bees for the combination of stimuli they were trained on was assessed (Fig. S2A,B). They were then trained on the stimulus which they preferred less, to ensure that training did not reinforce innate preferences. With both configural cues, bees naively preferred blue over orange and teal over blue, irrespective of the pattern or shape the colours were combined with (Fig. S2E,F). Across colours, no significant preference for either pattern or shape emerged (Fig. S2C,D). These innate preferences also held up when stimuli were tested as single attributes (Fig. S2G).

Bees always chose colours over other flower features when in conflict

When presented with a conflicting combination of stimuli, bees chose colour significantly more often than the shape or pattern attributes (Fig. 2A,B). The relative fraction of choices for colour depended on the colour condition: while bees chose colour over the configural attribute nearly exclusively in the *distant* colour conditions, the median choice rates for colour were only between 60–80% in the *close* colour conditions. Moreover, the individual variation was much lower with distant colours pairs, while it ranged from bees choosing pattern or shape preferentially, to those choosing colour at up to 90% with close colour pairs.

As in many other cases of decision making in vertebrates [25, 48] and insects [34, 49], and
specifically in a flower recognition context [47, 50-53], we observed a clear hierarchy of the
cues the bumblebees relied on: they primarily relied on colours over configural attributes in all
conditions. Our results were highly robust, holding up qualitatively and quantitatively across
multiple bumblebee colonies and different experimenters, and were quantitatively similar
across the different pattern and shape features, even though these likely activate pattern and
shape recognition circuits quite differently [54-58], as they varied in edge contrasts and spatial
extents .

Not only was the observed hierarchy very robust, but it was also similar to that of honeybees
in a comparable task with combined visual attributes. Across studies, honeybees preferentially
relied on colour when recalling memorised combinations of colour, shapes or patterns [46, 59].
When cues are combined additively for decision making, the overwhelming majority of studies
suggests that the more reliable, or less noisy, cues, are given more weight [3, 12, 14, 60-62].
In our experiment it seems reasonable that colours would represent the more reliable cue,
since they are easier to detect at a distance than patterns and shapes [63-65], which require
high resolution vision and are likely used at a more close-range stage of flower interactions
[38, 66]. Moreover, under natural conditions, patterns and shapes suffer more readily from
obstruction by foliage than flower colours.

Fig. 2 Choices for flower attributes when set into conflict.
A,B Fraction of choices for the colour (above 0.5) or the pattern or shape (below 0.5) attribute in the
conflict test, when the learned attributes were swapped across the stimulus pair, as compared to the
training, so that each stimulus displayed only one of the two learned attributes associated with a reward.
C,D Fraction of choices for the second attribute, not chosen in the conflict test (which in majority was
the configural cue). For the results of animals that chose pattern or shape first, see Fig. S4B,D. Number
of bees tested is indicated in A and B, for pattern and shape combinations, respectively. The results of
a generalised linear mixed-effects model with a binomial family via the logit link, comparing the choice
distributions to random choice at 0.5 are shown at the bottom of each graph. Comparisons across
groups were performed with the same model, and are depicted where statistically significant. All
statistical results are abbreviated as * < 0.05, ** < 0.01, *** < 0.001, *n.s.* not significant.

Bees learned the pattern and shape attributes only with close colour pairs

Since most of the individuals chose colour over the pattern or shape attributes in all cue
combinations, we asked whether bumblebees did indeed learn both attributes of the flowers,
or only the colour feature. Unlike honeybees in previous studies, which always learned the
second attribute in combination training experiments [46, 59], bumblebees provided with
distant colour pairs chose patterns or shapes at random (Fig. 2C,D), suggesting they only

learned the colour, but not the pattern or shape attributes. Bees trained on the *close* colour
pairs, however, chose the trained pattern or shape attribute significantly above the random
choice rate (Fig. 2C,D). The few bees that did prefer the pattern or shape attribute in the
conflict tests also chose the colour attributes above random choice (Fig. S2B,D),
demonstrating that they learned both attributes of the combined stimuli with close colour pairs.

In previous studies with combined attributes [46, 59], honeybees learned both colour and
shape or pattern attributes (though see [67] for various learning strategies with combined
cues), while in our experiments, they only learned both when the two colours were perceptually
close. Thus, while honeybees and bumblebees are clearly capable of learning and integrating
multiple object attributes [68], and even generalise object *gestalt* across modalities [69], we
here demonstrate that bumblebees do not automatically learn all object attributes, but only do
so in certain contexts.

170
171
Fig. 3 Single choices and Bayesian model with decision weights.
A Fraction of choices after training to individual attributes (distant: orange–blue and close: blue–teal
colours, patterns and shapes on grey background). The statistical results were obtained with
generalised linear mixed-effects models with a binomial family using the logit link. They compare the
choice fractions to random choice at 0.5, depicted at the bottom of each graph, and across conditions.
All results are abbreviated as * < 0.05, ** < 0.01, *** < 0.001. **B** The predicting population choice
distributions in the conflict condition, modelled as posterior probabilities using a Bayesian decision
model (fitted to the corresponding experimental data shown in Fig. 2A,B), based on the experimental
results for choices with individual attributes (**A**) as priors (see methods). The priors for colour and pattern
or shape, respectively, were combined with a weighting factor, which was obtained by fitting the
estimated posterior probabilities to the observed choices (Fig. 2A,B). **C** Estimated weighting factors,
resulting from 10000 iterations of the model (depicted are mean and its 50% and 95% confidence
intervals). See Fig. S3 for the distributions of weighting factors.

Bees switched their decision strategy between distant and close colour pairs

We next assessed the strategy bees used to choose between cues in the conflict test for the
distant and close colour conditions, in particular with respect to the weights they assigned to
colour as compared with patterns or shapes, respectively. To this end, we designed a Bayesian
decision model, which included the bees' reliance on colour, pattern and shape cues, modelled
as priors, which were weighted relative to each other (see Methods). In order to obtain priors
for the distant and close colour conditions, as well as patterns and shapes, we trained a new
set of bees to individual features, instead of cue combinations: one distant (orange–blue) and
one close (teal–blue) colour pair, as well as patterns and shapes on grey background, using
the same methods as for the cue combination experiment. We then tested their choices for
the trained attributes (Fig. 3A). For both patterns and shapes, the resulting fractions of correct

choices were not significantly different from the fraction of choices for pattern and shapes after the combined attribute training (second test, Fig. 2C,D). Qualitatively, the same holds true for the fraction of choices for close colours in the second test (Fig. S4B,D), though the small number of individuals choosing the configural category first did not allow us to confirm this statistically. This comparison demonstrates that priors derived from individual attribute training can serve as priors for the combined cue experiment.

Using these priors, we fitted a decision model, to predict the bee's decisions for colour in the conflict situation (Fig. 3B), in which the prior probabilities for colour and shape or pattern were linearly combined and weighted (see Methods). A weighting factor of 1 indicated that the bees only relied on their prior for colour, a factor of 0.5 that they relied on colour and patterns or shapes equally, and a factor below 0.5 that they relied more strongly on patterns or shapes than colour. The resulting weights for the four tested conditions (distant and close colours for both patterns and shapes) supported the intuitive interpretation of the conflict test results (Fig. 2A,B): the bees relied (almost) exclusively on colour with distant colour pairs (Fig. 3C), while they relied on both colour and configural cues with close colour pairs, with a stronger weighting of colour (Fig. 3C).

Combining complementary sources of information about an object is only one of two possible integration strategies – the other is a winner-takes-all approach, where the more reliable cue is selected to rely on [44, 70]. Our results suggest that the bees switch between strategies: from an additive combination of information in the close colour condition, to a winner-takes-all strategy in the distant colour condition (Fig. 3C). At an individual level, honeybees and bumblebees have been shown to trade off foraging speed for accuracy, though these were individual traits, not a switch in strategy across the population [71-75].

Different learning rates for distant and close colour conditions suggest that blocking underlies the switch in decision strategies.

In search of a mechanistic explanation for this switch in decision strategies, we analysed the learning rates of the bees with distant and close colour pairs. With combined colour and configural attributes, the bees required fewer trials to reach a high fraction of correct choices for the distant colour pairs than the close ones (Fig. 4A,B). The fraction of correct choices was already significantly higher in the first learning block and remained higher throughout all learning trials. Across combined attribute and single attribute learning of distant colours, the final learning outcome, quantified as the fraction of correct choices in the final learning block, was not significantly different (Fig. 4D).

The combined attribute learning rates for the close colour pairs were distinctly slower than those of the distant colour pairs (Fig. 4A,B). One might argue this was the case because the bees did learn both attributes, colour and pattern or shape (Fig. 2C,D), and therefore required more learning trials. However, the learning rates of attribute combinations with close colours were not slower than those for the respective single attributes (Fig. 4C,D). This suggests that multi-cue learning did not diminish the learning rate, but that the slower learning of the individual attributes in these conditions was responsible for the comparably slow rates. Indeed, the single attribute learning curves for close colour pairs were even flatter than their multi-attribute counterparts, and reached a significantly lower fraction of correct choices in the final learning block than the multi-attribute ones (Fig. 4D). Thus, multi-cue learning in these conditions enhanced learning rates, as well as the final learning outcome.

Fig. 4 Learning performance with multi- and single attribute stimuli.
A,B Learning rates of the bumblebees for all combined attributes, as well as **C** single attribute training.
D Learning performance in the final training block, compared across multi – and single attribute learning.
All statistical results were obtained with generalised linear mixed-effects models with a binomial family
using the logit link, in A,B comparing the choice fractions for each block of animals with close and distant
colour pairs, in D comparing the choice fractions to random choice at 0.5, depicted at the bottom of
each graph. The same model was used to compare between groups, the results of which are depicted
where statistically significant. All statistical results are abbreviated as * < 0.05, ** < 0.01, *** < 0.001.

The difference in learning rates for distant and close colour pairs, as well as patterns and
shapes, were likely linked to the discriminability of the features, and thus the complexity of the
learning task. They mirrored results from previous studies which showed slower learning rates
for perceptually close than for distant colours [17, 71]. The different learning rates could
provide a mechanism for the change in learning and decision strategy between the two
conditions: blocking [76]. Blocking is a phenomenon typically described when animals learn
multiple attributes of an object or stimulus source sequentially. When one attribute is presented
alone and learned, a second attribute which is presented simultaneously with the first one is
not learned (as readily) any more [77, 78]. Blocking has been demonstrated across the animal
kingdom, from invertebrates to vertebrates to humans. In insects, it has been described across
modalities and in a variety of tasks [78-80], though the occurrence of the phenomenon can
vary with the stimulus type [81] and can be confounded by experimental designs [82, 83].

In our experiments, the stimuli were not presented sequentially, as typically done when testing
for blocking. But since the bees learned the distant colours much faster than shapes or
patterns when presented individually (Fig. 4C), the effect might have been similar to a blocking
paradigm: as the association of the reward and distant colour was already formed after a few
trials, when pattern or shape associations were not yet formed, any further association of the
configural attribute with the reward was blocked, as if the combination of cues had been
presented only after the initial colour training. Using blocking to enact the switch in decision
strategies would be a very simple, yet effective mechanism, to trade off learning speed with

decision accuracy, as blocking only comes into effect when one cue is learned much faster
than the other associated one. This aligns well with the general concept that the
computationally limited insect brain enables simple, yet effective and adaptive strategies to
perform complex behaviour, with a limited set of neurons [31, 84, 85].

Decision strategies trade off efficiency (learning speed) and accuracy

We observed a general strategy, across all tested individuals, from an additive to a winner-
takes-all approach with stimulus context, and specifically, the discriminability of one of the
cues. At first glance, this might be puzzling, as one might assume that more information about
a target is always better, and thus integrating complementary sources of information is optimal
[7, 8]. But this does not account for time as a resource. The bees learned the distant colour
pairs much faster than the close ones (Fig. 4C), which is in agreement with previous findings
for learning rates with perceptually similar and distant colours [17, 71]. Interestingly, bees
learned combined attributes with close colours equally fast, if not faster than when the
attributes were presented individually (Fig. 4A-C). This might be due to attentional cueing [86],
or valence signalling [17, 18] by one of the attributes, which are suggested to improve multi-
cue learning rates compared to single cue ones [15, 17] (though see [23]).

Thus, with distant colour pairs, the bees could arrive at a reliable decision strategy much faster
by learning only the colour attribute. Indeed, accounting for time as an important factor for
decisions, instead of only the available sensory information, can change the statistically
optimal decision strategy [21, 22]. This suggests that in insects as well, learning time, or
efficiency, is an important factor in decision making. Further tests would be required to
determine how efficiency is weighted relative to decision accuracy. This could be achieved by
varying the perceptual discriminability and resulting decision accuracy of one of the cues
relative to the other over a larger range, to find the point(s) at which the bees switch from a
single cue to multi-cue learning and decision strategy.

Conclusion

We found that the buff-tailed bumblebee *B. terrestris* flexibly adjusted their learning and
decision strategies when presented with visual attributes of varying discriminability, to balance
decision accuracy and learning efficiency. Our analysis of the bees' learning rates suggests
that blocking during learning could implement this strategy switch. This opens the door for
future investigations into the underlying neural control strategies, which will enable in-depth
comparisons of context-dependent learning and decision strategies in insects with the current
focus in vertebrates [6, 87].

Materials and Methods

Animals

Colonies of *Bombus terrestris* were obtained from commercial breeders (Biobest, Westerlo, Belgium). The colonies were housed in a two-chamber wooden box (28 cm×16 cm×11 cm), which provided one chamber for nest-building and one for feeding. Before experiments started, the bees were fed ad libitum with APIinvert (Südzucker, Germany), a 70% w/v sucrose solution, and with pollen grains (Bio-Blütenpollen, Naturwaren-Niederrhein, Germany).

Setup and Experimental Procedure

All experiments were conducted in a flight arena as previously described [38]. In brief, the bees' nesting boxes were connected to the arena (120 cm × 100 cm × 35 cm) via an acrylic tube. The floor of the arena was covered with grey cardboard (Mi-Taintes #122, Canson SAS, Annonay Cedex, France). The same cardboard was used for the training feeders (see *Stimuli*). The experiments were performed on several different bumblebee colonies per experimental condition (see *Experimental Procedures*), to ensure that the observed effects were robust against individual colony variation [39].

Stimuli

All artificial flowers were constructed from cardboard cut-outs, mounted on 10 mm tall, dark grey platforms 40 mm in diameter. The grey training stimuli were made from same cardboard as the floor of the arena. For testing, yellow, orange, teal and blue card were used (Tinted drawing paper #12, #19, #32 and #31, respectively; Buntpapierfabrik Ludwig Bähr, Kassel, Germany). The relative reflectance spectra for all stimuli are shown in Fig. S1A. To test the configural category *shape*, squares of 40 mm side length were used as neutral stimuli. For testing, circles of 40 mm diameter and five-armed star shapes with the same overall area were used for comparison (see Fig. 1E, insets). For the configural category *pattern*, we printed a circle-pattern consisting of two concentric black rings, and a radial pattern consisting of eight radially arranged stripes, each of 2.1 mm width onto square-shaped cardboard stimuli (see Fig. 1C, insets).

We performed two sets of experiments, in which combinations of shape-colour and pattern-colour were shown to separate groups of bumblebees. Both categories used the same pairs of colours. Two of which were *distant* in bumblebee colour space (Fig.S1), and thus should be easily distinguishable: yellow-blue, orange-blue; while two were *close*, and thus harder to distinguish: yellow-orange, teal-blue, either in combination with shapes (circle – star) or patterns (circle – radial). Neutral coloured stimuli were grey, and had a square shape in the pattern category, and star – circle shape in the shape category. Each bumblebee was only presented with one combination of colour and pattern or colour and shape, including the respective conflict and control tests (see *Experimental Procedure*).

Spectral measurements and colour vision modelling

The relative reflectance spectra of the coloured card from which the stimuli were constructed, as well as that of the grey background on which the stimuli were presented (Fig. S1A), were measured using a JAZ spectrometer equipped with a pulsed Xenon light source (Ocean Optics, Dunedin, FL, United States). The spectrometer was calibrated against a Spectralon white diffuse reflectance standard (WS-1-SL, Ocean Optics). Colour loci in the colour triangle were calculated using the method described by [40] with using the spectral sensitivities of *B. terrestris*' three photoreceptor classes from [41] (Fig. S1B).

Experimental Procedure

Foragers of *B. terrestris* were selected for experiments by scoring their prior foraging activity in the flight arena on grey training flowers supplied with 30% sucrose solution. For individual identification, bees were marked on the thorax with number tags. During experiments, only a single bee was allowed to enter the arena. Before being presented with the test stimuli, five grey training stimuli with 10 µl of 50 % sucrose solution in the centre were positioned in the arena in a random arrangement. The bees performed three to five foraging bouts, separated by the forager returning to the colony, on the grey flowers. Each stimulus was refilled immediately after the bumblebee departed.

Conflict experiments

The experiment began with a preference test (Fig. 1B), during which the bee was presented with a combination of colour and shape or pattern (for example a yellow star and an orange circle, or a teal square with a concentric pattern and a blue square with a radial pattern). Five instances of each stimulus pair were presented in the arena, each with 10 µl of water, to avoid pairing either with a reward. The first 10 choices of each bee were recorded. Subsequently, the bee was allowed to feed ad libitum from a grey feeder and returned to the colony.

The colour–pattern or colour–shape combination of the pair that the bee least preferred was then chosen as the rewarded stimulus for training (Fig. 1B). If both stimulus pairs were preferred equally, the stimulus that had been tested on fewer individuals was selected as the rewarded one. All instances of the rewarded stimulus were supplied with 10 µl of a 1M sucrose solution, while the un-rewarded pair was supplied with the same volume of water. During training, the stimuli were re-supplied immediately after the bee approached the next stimulus. Training continued until a bee had made 30 correct choices, and as many incorrect choices as were necessary to reach 30 correct choices. When the bee returned to the colony during training, the order of the stimuli in the arena was re-arranged to prevent spatial learning. After training, sucrose solution was provided ad libitum on a grey feeder, so that the bee would fill her crop and return to the colony.

When the bee subsequently returned to the foraging arena, a conflict test was performed (Fig. 1B). It was conducted in the same way as the preference test, but the attributes of the stimuli were swapped: the rewarded colour was combined with the unrewarded pattern / shape and vice versa (for example, instead of a yellow star and an orange circle, the bee was tested with a yellow circle and an orange star).

Afterwards, a second training session was conducted using the original stimuli, until the bee again reached thirty correct choices (Fig. 1B, Fig. S4A,C).

Subsequently, a final test was conducted, which assessed the preference for the attribute the bee did not choose preferentially in the conflict test (Fig. 1B; for example, if she chose colour over shape in the conflict test, in the final test the bee was presented with grey shapes. If she chose shape over colour, the bee was presented with square-shaped coloured stimuli). This test was conducted in the same way as the preference test.

Single attribute experiment

This experiment was performed as above, but with stimuli that comprised only one visual attribute (distant colour: orange-blue, close colour: blue-teal, pattern or shape on grey background). The experiment began with a preference test comprised of ten unrewarded choices, followed by a training session until thirty correct choices were performed, and an

397 unrewarded session, in which the stimulus pair, which was presented for training, was shown
398 unaltered.

Number of bees and colonies per experiment

For the colour and pattern conflict experiment, bumblebee foragers of four colonies were
trained and tested by two different experimenters (25 individuals in the yellow–blue, and 20
each in the orange–blue, teal–blue, and yellow–orange conditions), while four colonies were
tested by three different experimenters for the colour and shape experiment (24 individuals in
the yellow–blue, and 15 each in the orange–blue, teal–blue, and yellow–orange conditions).
Two additional colonies were used to test 10 foragers in each condition with single attribute
stimuli by one experimenter.

Bayesian decision model

408 We constructed a Bayesian decision model [42, 43], predicting the choice rates of bees for
409 colour in the conflict test as posterior probabilities p(H|O), which are generated by the
410 likelihood of the observations given the hypothesis p(O|H), and the prior probability of the
411 hypothesis p(H), which entails the animals' prior knowledge about the probability of a reward
412 on a given stimulus.

413
$$p(H \mid O) = \frac{p(O \mid H) \times p(H)}{p(O)}$$

414 The likelihood of the observations given the hypothesis p(O|H) was 0.5 in all experiments,
415 since we presented 2 choices of stimuli in equal numbers. The term p(O) provides a
416 normalising term, to retain the resulting probability within the bounds of [0,1], calculated as:

417
$$p(O) = \int p(O \mid H) \times p(H) \, dH$$

418 Since the decision model was designed to predict choices in the conflict situation, the priors
419 needed to reflect both prior probability of colour $p(H|C_1)$ and pattern or shape $p(H|C_2)$,
420 respectively. We therefore generated a combined prior, with a relative weighting (weighting
421 factor w) between the two terms [12, 44, 45]:

422
$$p(H) = \frac{p(H \mid C_1)^w \times p(H \mid C_2)^{1-w}}{\int p(H \mid C_1)^w \times p(H \mid C_2)^{1-w} \, d(H)}$$

423 The combined prior also included a normalising term, which integrates all possible prior
424 probabilities for H. The full model thus reads:

425
$$p(H \mid O) = \frac{p(O \mid H) \times p(H \mid C_1)^w \times p(H \mid C_2)^{1-w}}{\int p(O \mid H) \times p(H \mid C_1)^w \times p(H \mid C_2)^{1-w} \, d(H)}$$

We implemented the model in discrete terms in Matlab 2022a (The Mathworks, Natick, US),
and fitted the resulting posterior probabilities to the observed choices of the animals in the
conflict test, to obtain the weighting factor for each of the four conditions. As priors, we
assigned the fraction of choices for the rewarded colour or pattern/ shape obtained in the
individual attribute experiments, in which the animals were only trained two a single attribute
(distant or close colour, pattern, shape), instead of a colour combination (Fig. 3A). Since the
single attribute data was obtained from a different set of bumblebees than those that
performed the conflict experiments, we used a permutation approach: every choice data point
for the colour attribute was combined with every point for the pattern or shape attribute to
calculate the combined prior, resulting in a 10x10 prior matrix (as 10 bees were tested in both

single attribute colour and pattern or shape tests). From the resulting 100 posterior probabilities, we randomly selected a subset matched to the number of observed choices in the respective conflict conditions (15 or 20). For these, a weighting factor was fitted, using a sum of mean square error between the posterior probabilities and observed choice frequencies (using the fmincon function with bounds at 0 and 1 and a maximum of 10^6 iterations). This procedure was repeated 10000 times for different subsets, with each model run initiated with a randomised starting parameter drawn from a Gaussian distribution centred on 0.5, to arrive at the same number of weighting factor estimates for each of the four conditions (Fig. 3C, Fig. S4). Posterior probabilities were calculated for the mean of the weighting factor distribution, using the full 10x10 posterior matrix (Fig. 3B), for visual inspection of the goodness of fit.

Data analysis

To assess learning progress, the fraction of correct choices was calculated for each block of five correct choices, and as many incorrect choices as were made to arrive at the default value (Fig. 1C,D). This assured equal possibility for forming a positive association to the stimulus across bees. For all unrewarded preference tests, the fraction of correct choices was calculated. Statistical analysis was performed using with R v4.1.2 (R Foundation for Statistical Computing, Vienna, Austria).

To assess whether the preference for colour in the conflict experiment differed from random choice (50:50, since all stimuli were presented in pairs), a generalised linear mixed-effects model with the following formula was used:

$$correct\ choice \sim colour\ +\ (1\,|\,animalID)$$

These estimated the fixed-effect of the stimulus colour on the relative probability of choosing the stimulus – scored for each individual as 0 or 1, accounting for individual biases.

To analyse whether the preference for pattern or shape, if they were not preferred in the conflict experiment, differed from random choice (50:50, since all stimuli were presented in pairs) in the final test, a generalised linear mixed-effects model with the following formula was used:

$$correct\ choice \sim pattern +\ (1\,|\,animalID)$$

$$correct\ choice \sim shape\ +\ (1\,|\,animalID)$$

These estimated the fixed-effect of the stimulus pattern or shape on the relative probability of choosing the stimulus – scored for each individual as 0 or 1, accounting for individual biases.

To compare the choice fraction for colour in the conflict test, and the non-preferred attribute in the final test for patterns and shapes, we used a generalised linear model of the family "quasibinomial":

$$choice \sim\ pattern \times colour$$

$$choice \sim\ shape \times colour$$

To assess the fraction of choices of naïve bees for colour, shape or pattern, and the effects of their interaction, we used a generalised linear model of the family "quasibinomial":

$$choice \sim pattern\ \times colour$$

$$choice \sim shape\ \times colour$$

Author Contributions Conceptualization: J.S., A.S.; Methodology: J.S., A.S., J.F.; Validation: J.S.,
A.S., J.F.; Formal analysis: J.S., A.S.; Investigation: S.H., A.D., K.G.; Resources: J.S., A.S.; Data
curation: A.S., S.H., A.D., K.G.; Writing - original draft: A.S.; Writing - review & editing: J.S., A.S., J.F.;
Visualization: A.S.; Supervision: J.S., A.S.; Funding acquisition: A.S.

Acknowledgements We acknowledge funding to A.S. by the Bavarian Academy of Sciences and
Humanities, the Zukunftskolleg Konstanz, and the Emmy Noether Programme of the DFG (STO 1255/4-
1).

Competing Interest Statement: The authors declare no competing interests.

Data Availability

Source data for all behavioural experiments and spectral measurements:
https://figshare.com/s/c4c912de7dd7e24a9ec8

Custom-written analysis code: https://github.com/stoeckl-lab/Spaethe_et_al_2024_beeDecisions

Literature

[1]   Raposo, D., Sheppard, J.P., Schrater, P.R., and Churchland, A.K. (2012). Multisensory Decision-Making in Rats and Humans. The Journal of Neuroscience *32*, 3726–3735.

[2]   Guilford, T. and Dawkins, M.S. (1991). Receiver psychology and the evolution of animal signals. Animal Behaviour *42*, 1–14.

[3]   Angelaki, D.E., Gu, Y., and DeAngelis, G.C. (2009). Multisensory integration: psychophysics, neurophysiology, and computation. Current Opinion in Neurobiology *19*, 452–458.

[4]   Hebets, E.A. and Papaj, D.R. (2004). Complex signal function: developing a framework of testable hypotheses. Behavioral Ecology and Sociobiology *57*, 197–214.

[5]   Rubi, T.L. and Stephens, D.W. (2016). Does multimodality per se improve receiver performance? An explicit comparison of multimodal versus unimodal complex signals in a learned signal following task. Behavioral Ecology and Sociobiology *70*, 409–416.

[6]   Coen, P., Sit, T.P., Wells, M.J., Carandini, M., and Harris, K.D. (2023). Mouse frontal cortex mediates additive multisensory decisions. Neuron *111*, 2432–2447.e13.

[7]   Seilheimer, R.L., Rosenberg, A., and Angelaki, D.E. (2014). Models and processes of multisensory cue combination. Current Opinion in Neurobiology *25*, 38–46.

[8]   Jones, P.R. (2016). A tutorial on cue combination and Signal Detection Theory: Using changes in sensitivity to evaluate how observers integrate sensory information. Journal of Mathematical Psychology *73*, 117–139.

[9]   Partan, S.R. (2017). Multimodal shifts in noise: switching channels to communicate through rapid environmental change. Animal Behaviour *124*, 325–337.

[10]   Wilson, A.J., Dean, M., and Higham, J.P. (2013). A game theoretic approach to multimodal communication. Behavioral Ecology and Sociobiology *67*, 1399–1415.

[11]   Sumby, W.H. and Pollack, I. (1954). Visual Contribution to Speech Intelligibility in Noise. The Journal of the Acoustical Society of America *26*, 212–215.

[12]   Ernst, M.O. and Banks, M.S. (2002). Humans integrate visual and haptic information in a statistically optimal fashion. Nature *415*, 429–433.

[13]   Kuang, S. and Zhang, T. (2014). Smelling directions: Olfaction modulates ambiguous visual motion perception. Scientific Reports *4*.

[14]   Fetsch, C.R., Turner, A.H., DeAngelis, G.C., and Angelaki, D.E. (2009). Dynamic Reweighting of Visual and Vestibular Cues during Self-Motion Perception. The Journal of Neuroscience *29*, 15601–15612.

[15]   Kulahci, I.G., Dornhaus, A., and Papaj, D.R. (2008). Multimodal signals enhance decision making in foraging bumble-bees. Proceedings of the Royal Society B: Biological Sciences *275*, 797–802.

[16]   Leonard, A.S. and Masek, P. (2014). Multisensory integration of colors and scents: insights from bees and flowers. Journal of Comparative Physiology A *200*, 463–474.

[17] Gil-Guevara, O., Bernal, H.A., and Riveros, A.J. (2022). Honey bees respond to multimodal stimuli following the principle of inverse effectiveness. Journal of Experimental Biology *225*.

[18] Okray, Z., Jacob, P.F., Stern, C., Desmond, K., Otto, N., Talbot, C.B., Vargas-Gutierrez, P., and Waddell, S. (2023). Multisensory learning binds neurons into a cross-modal memory engram. Nature *617*, 777–784.

[19] Jordan, K.A., Sprayberry, J.D., Joiner, W.M., and Combes, S.A. (2024). Multimodal processing of noisy cues in bumblebees. iScience *27*, 108587.

[20] Buehlmann, C., Mangan, M., and Graham, P. (2020). Multimodal interactions in insect navigation. Animal Cognition *23*, 1129–1141.

[21] Crevecoeur, F., Munoz, D.P., and Scott, S.H. (2016). Dynamic Multisensory Integration: Somatosensory Speed Trumps Visual Accuracy during Feedback Control. The Journal of Neuroscience *36*, 8598–8611.

[22] Drugowitsch, J., DeAngelis, G.C., Klier, E.M., Angelaki, D.E., and Pouget, A. (2014). Optimal multisensory decision-making in a reaction-time task. eLife *3*, e03005.

[23] Strube-Bloss, M., Günzel, P., Nebauer, C.A., and Spaethe, J. (2023). Visual accelerated and olfactory decelerated responses during multimodal learning in honeybees. Frontiers in Physiology *14*.

[24] Parisi, G.I., Barros, P., Kerzel, M., Wu, H., Yang, G., Li, Z., Liu, X., and Wermter, S. (2017). A computational model of crossmodal processing for conflict resolution. In 2017 Joint IEEE International Conference on Development and Learning and Epigenetic Robotics (ICDL-EpiRob) (IEEE), pp. 33–38.

[25] De Gelder, B. and Bertelson, P. (2003). Multisensory integration, perception and ecological validity. Trends in Cognitive Sciences *7*, 460–467.

[26] Song, Y.H., Kim, J.H., Jeong, H.W., Choi, I., Jeong, D., Kim, K., and Lee, S.H. (2017). A Neural Circuit for Auditory Dominance over Visual Perception. Neuron *93*, 940–954.e6.

[27] Pecher, D. and Zeelenberg, R. (2022). Does multisensory study benefit memory for pictures and sounds? Cognition *226*, 105181.

[28] Munoz, N.E. and Blumstein, D.T. (2019). Optimal multisensory integration. Behavioral Ecology *31*, 184–193.

[29] Rhebergen, F., Taylor, R.C., Ryan, M.J., Page, R.A., and Halfwerk, W. (2015). Multimodal cues improve prey localization under complex environmental conditions. Proceedings of the Royal Society B: Biological Sciences *282*, 20151403.

[30] Fawcett, T.W. and Johnstone, R.A. (2003). Optimal assessment of multiple cues. Proceedings of the Royal Society of London. Series B: Biological Sciences *270*, 1637–1643.

[31] Chittka, L. and Niven, J. (2009). Are bigger brains better? Curr. Biol. *19*, R995–R1008.

[32] Barron, A.B., Gurney, K.N., Meah, L.F.S., Vasilaki, E., and Marshall, J.A.R. (2015). Decision-making and action selection in insects: inspiration from vertebrate-based theories. Frontiers in Behavioral Neuroscience *9*.

[33] Giurfa, M., Núñez, J., and Backhaus, W. (1994). Odour and colour information in the
foraging choice behaviour of the honeybee. Journal of Comparative Physiology A *175*.

[34] Thiagarajan, D. and Sachse, S. (2022). Multimodal Information Processing and
Associative Learning in the Insect Brain. Insects *13*, 332.

[35] Zhang, L.Z., Zhang, S.W., Wang, Z.L., Yan, W.Y., and Zeng, Z.J. (2014). Cross-
modal interaction between visual and olfactory learning in Apis cerana. Journal of
Comparative Physiology A *200*, 899–909.

[36] Leonard, A.S., Dornhaus, A., and Papaj, D.R. (2011). Forget-me-not: Complex floral
displays, inter-signal interactions, and pollinator cognition. Current Zoology *57*, 215–224.

[37] Orbán, L.L. and Plowright, C.M. (2014). Getting to the start line: how bumblebees
and honeybees are visually guided towards their first floral contact. Insectes Soc. *61*, 325–
336.

[38] Richter, R., Dietz, A., Foster, J., Spaethe, J., and Stöckl, A. (2023). Flower patterns
improve foraging efficiency in bumblebees by guiding approach flight and landing. Funct
Ecol *37*, 763–777.

[39] Maharaj, G., Horack, P., Yoder, M., and Dunlap, A.S. (2018). Influence of preexisting
preference for color on sampling and tracking behavior in bumble bees. Behavioral Ecology
30, 150–158.

[40] Chittka, L. and Kevan, P. (2005). Practical Pollination Biology, chapter Flower colors
as advertisement. (Cambridge, Canada.: Enviroquest), pp. 157 – 206.

[41] Briscoe, A.D. and Chittka, L. (2001). The evolution of color vision in insects. Annual
Review of Entomology *46*, 471–510.

[42] Berger, J.O. (1985). Statistical Decision Theory and Bayesian Analysis (Springer
New York).

[43] Jaynes, E.T. (2003). Probability Theory: The Logic of Science (Cambridge University
Press).

[44] Clark, J.J. and Yuille, A.L. (1990). Data Fusion for Sensory Information Processing
Systems (Springer US).

[45] Yuille, A. and Bülthoff, H. (1996). Bayesian decision theory and psychophysics
(Cambridge University Press), pp. 123–162.

[46] Gould, J.L. and Towne, W.F. (1988). Honey Bee Learning (Elsevier), pp. 55–86.

[47] Stöckl, A., Heinze, S., Charalabidis, A., El Jundi, B., Warrant, E., and Kelber, A.
(2016). Differential investment in visual and olfactory brain areas reflects behavioural
choices in hawk moths. Sci. Rep. *6*, 26041.

[48] Meijer, G.T., Mertens, P.E., Pennartz, C.M., Olcese, U., and Lansink, C.S. (2019).
The circuit architecture of cortical multisensory processing: Distinct functions jointly
operating within a common anatomical network. Progress in Neurobiology *174*, 1–15.

[49] Wessnitzer, J. and Webb, B. (2006). Multimodal sensory integration in insects -
towards insect brain control architectures. Bioinspiration &; Biomimetics *1*, 63–75.

[50] Kriston, I. (1973). Die Bewertung von Duft- und Farbsignalen als Orientierungshilfen
an der Futterquelle durchApis mellifera L. Journal of Comparative Physiology *84*, 77–94.

[51]   Kinoshita, M., Stewart, F.J., and Ômura, H. (2017). Multisensory integration in
Lepidoptera: Insights into flower-visitor interactions. BioEssays *39*.

[52]   Balkenius, A. and Kelber, A. (2006). Colour preferences influences odour learning in
the hawkmoth, Macroglossum stellatarum. Naturwissenschaften *93*, 255–258.

[53]   Dacke, M., Bell, A.T.A., Foster, J.J., Baird, E.J., Strube-Bloss, M.F., Byrne, M.J., and
el Jundi, B. (2019). Multimodal cue integration in the dung beetle compass. Proceedings of
the National Academy of Sciences *116*, 14248–14253.

[54]   Srinivasan, M. (1994). Pattern recognition in the honeybee: Recent progress. Journal
of Insect Physiology *40*, 183–194.

[55]   Heisenberg, M. (1995). Pattern recognition in insects. Curr. Opin. Neurobiol. *5*, 475–
481.

[56]   Dill, M. and Heisenberg, M. (1995). Visual pattern memory without shape recognition.
Phil. Trans. R. Soc. Lond. B *349*, 143–152.

[57]   Horridge, A. (2009). Generalization in visual recognition by the honeybee (Apis
mellifera). Journal of Insect Physiology *55*, 499–511.

[58]   Chen, L., Zhang, S., and Srinivasan, M.V. (2003). Global perception in small brains:
Topological pattern recognition in honey bees. Proc. Natl. Acad. Sci. U.S.A. *100*, 6884–6889.

[59]   Hsu, P.S. and Yang, E.C. (2012). The critical cue in pattern discrimination for the
honey bee: Color or form? Journal of Insect Physiology *58*, 934–940.

[60]   Fetsch, C.R., Pouget, A., DeAngelis, G.C., and Angelaki, D.E. (2011). Neural
correlates of reliability-based cue weighting during multisensory integration. Nature
Neuroscience *15*, 146–154.

[61]   Körding, K.P. and Wolpert, D.M. (2004). Bayesian integration in sensorimotor
learning. Nature *427*, 244–247.

[62]   Chandrasekaran, C. (2017). Computational principles and models of multisensory
integration. Current Opinion in Neurobiology *43*, 25–34.

[63]   Menzel, R., Gumbert, A., Kunze, J., Shmida, A., and Vorobyev, M. (1997). Pollinator's
strategies in finding flowers. Israel Journal of Plant Sciences *45*, 141–156.

[64]   de Ibarra, N.H., Langridge, K.V., and Vorobyev, M. (2015). More than colour
attraction: behavioural functions of flower patterns. Curr. Opin. Insect Sci. *12*, 64–70.

[65]   Hempel de Ibarra, N., Holtze, S., Bäucker, C., Sprau, P., and Vorobyev, M. (2022).
The role of colour patterns for the recognition of flowers by bees. Philosophical Transactions
of the Royal Society B: Biological Sciences *377*.

[66]   Kannegieser, S., Kraft, N., Haan, A., and Stöckl, A. (2024). Visual guidance fine-
tunes probing movements of an insect appendage. Proceedings of the National Academy of
Sciences *121*, e2306937121.

[67]   Horridge, A. (2007). The preferences of the honeybee (Apis mellifera) for different
visual cues during the learning process. Journal of Insect Physiology *53*, 877–889.

[68]   Rands, S.A., Whitney, H.M., and Hempel de Ibarra, N. (2023). Multimodal floral
recognition by bumblebees. Current Opinion in Insect Science *59*, 101086.

[69] Solvi, C., Gutierrez Al-Khudhairy, S., and Chittka, L. (2020). Bumble bees display
cross-modal object recognition between visual and tactile senses. Science *367*, 910–912.

[70] Battaglia, P.W., Jacobs, R.A., and Aslin, R.N. (2003). Bayesian integration of visual
and auditory signals for spatial localization. Journal of the Optical Society of America A *20*,
1391.

[71] Dyer, A. and Chittka, L. (2004). Bumblebees (Bombus terrestris) sacrifice foraging
speed to solve difficult colour discrimination tasks. Journal of Comparative Physiology A *190*.

[72] Chittka, L., Dyer, A.G., Bock, F., and Dornhaus, A. (2003). Bees trade off foraging
speed for accuracy. Nature *424*, 388–388.

[73] Wang, M.Y., Chittka, L., and Ings, T.C. (2018). Bumblebees Express Consistent, but
Flexible, Speed-Accuracy Tactics Under Different Levels of Predation Threat. Frontiers in
Psychology *9*.

[74] Ings, T.C. and Chittka, L. (2008). Speed-Accuracy Tradeoffs and False Alarms in Bee
Responses to Cryptic Predators. Current Biology *18*, 1520–1524.

[75] Burns, J.G. and Dyer, A.G. (2008). Diversity of speed-accuracy strategies benefits
social insects. Current Biology *18*, R953–R954.

[76] Kamin, L.J. (1969). Punishment and Aversive Behavior, chapter Predictability
Surprise, Attention, and Conditioning (New York: Appleton-Century-Crofts), pp. 279–296.

[77] Prados, J., Alvarez, B., Acebes, F., Loy, I., Sansa, J., and Moreno-Fernández, M.M.
(2013). Blocking in rats, humans and snails using a within-subjects design. Behavioural
Processes *100*, 23–31.

[78] Terao, K., Matsumoto, Y., and Mizunami, M. (2015). Critical evidence for the
prediction error theory in associative learning. Scientific Reports *5*.

[79] Couvillon, P.A., Arakaki, L., and bitterman, M.E. (1997). Intramodal blocking in
honeybees. Animal Learning & Behavior *25*, 277–282.

[80] Hosler, J.S. and Smith, B.H. (2000). Blocking and the detection of odor components
in blends. Journal of Experimental Biology *203*, 2797–2806.

[81] Guerrieri, F., Lachnit, H., Gerber, B., and Giurfa, M. (2005). Olfactory blocking and
odorant similarity in the honeybee. Learning & Memory *12*, 86–95.

[82] Blaser, R.E., Couvillon, P.A., and Bitterman, M.E. (2006). Blocking and
pseudoblocking: New control experiments with honeybees. Quarterly Journal of
Experimental Psychology *59*, 68–76.

[83] Blaser, R.E., Couvillon, P.A., and Bitterman, M.E. (2008). Within-subjects
experiments on blocking and facilitation in honeybees (Apis mellifera). Journal of
Comparative Psychology *122*, 373–378.

[84] Guiraud, M.G., Gallo, V., Quinsal-Keel, E., and MaBouDi, H. (2025). Bumblebee
visual learning: simple solutions for complex stimuli. Animal Behaviour, 221: 123070

[85] MaBouDi, H., Barron, A.B., Li, S., Honkanen, M., Loukola, O.J., Peng, F., Li, W.,
Marshall, J.A.R., Cope, A., Vasilaki, E., et al. (2021). Non-numerical strategies used by bees
to solve numerical cognition tasks. Proceedings of the Royal Society B: Biological Sciences
288, 20202711.

[86]   Eckstein, M.P., Mack, S.C., Liston, D.B., Bogush, L., Menzel, R., and Krauzlis, R.J.
(2013). Rethinking human visual attention: Spatial cueing effects and optimality of decisions
by honeybees, monkeys and humans. Vision Research *85*, 5–19.

[87]   Pagan, M., Tang, V.D., Aoi, M.C., Pillow, J.W., Mante, V., Sussillo, D., and Brody,
C.D. (2024). Individual variability of neural computations underlying flexible decisions.
Nature *10.1038/s41586-024-08433-6*.

700