Graphical Abstract

Deep Learning for Predicting Stem Cell Efficiency for use in Beta Cell Differentiation

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Highlights

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- Predictive model for successful iPSC differentiation from label-free images

- Explainability methods demonstrate biologically meaningful learned model features

- Deep learning combined with label-free imaging can reduce cost of beta-cell production

Deep Learning for Predicting Stem Cell Efficiency for use in Beta Cell Differentiation

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Abstract

Recent clinical trial data have shown that cell therapy holds curative potential for type-I diabetes. The required cell differentiation process exhibits substantial variability, even among clones of induced pluripotent stem cells (iPSC). We apply an EfficientNet-V2-S model to obtain a novel early prediction for the outcome of the differentiation process from patient-derived iPSC to β-cells using only phase-contrast images. In contrast to many established data sets in medical imaging, human experts struggle to predict the ground truth in this type of images. Therefore, to gain critical insight into the learned features, we applied layer-wise relevance propagation (LRP), and Fourier-based frequency analysis. LRP analysis shows that the negative class contains more hole-like regions between cells. We show that the model learns features related to patch variance, and that patch-normalization improves patch accuracies for times after cell washing with less cell debris.

Keywords: Cell therapy, diabetes, induced pluripotent stem cells, deep

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1. Introduction

1 in 10 adults were living with diabetes in 2022 globally with a rising trend [1]. Diabetes mellitus type 1 (T1D) is a chronic autoimmune disorder, defined by loss of pancreatic β-cells leading to insulin deficiency and thereby loss of the ability to regulate blood glucose levels [2]. Patients therefore require regular injections of insulin during their whole life [3].

Stem cells are a cell type which has the ability to self-renew and differentiate into other specialized cell types, opening up the possibility to utilize them in regenerative medicine and cell therapies. One promising application of cell therapy is T1D, where transplantation of functional β-cells could restore normal insulin production [4]. First clinical results have recently confirmed this potential [5].

Ideally, β-cells should be produced from patient-derived induced pluripotent stem cells (iPSC) in order to avoid immune rejection after transplantation. Based on previous studies on pluripotency induction [6, 7], procedures have been developed to differentiate iPSC into β-cells[8]. This differentiation process takes about 34 days, is costly and labor-intensive. The yield of functional β-cells is highly variable both inter- and intra-experimentally [9, 10]. In addition, the cost of cell therapy is substantial, making variability in experimental outcome an even bigger challenge.

We present a deep learning-based approach to identify successful experimental procedures already during the first four days of differentiation based on phase-contrast imaging. It involves a novel dataset of a single cell type (iPSC) changing over time, which is distinctively different from most other common datasets, such as tissue sections which contain many different cell types at one time. Our approach aims at acceleration of cell production *in vitro* by providing a criterion when to restart the process with another batch. In contrast to traditional methods for cell fate analysis, such as gene expression measurements or staining for specific markers, our live-cell imaging approach is non-invasive, meaning it does not require fixation or staining of the cells, which is especially important in this case where available cell material is very limited. Also, it allows us to monitor the same cells over extended time periods without disruptions. We focus on the first four days of the 34 day differentiation, which should result in Definitive Endoderm (DE) cells, also known as stage 1 [11].

Figure 1: **(A)** Cell therapy overview for T1D. Adult cells are taken from a patient and pluripotency is induced by cellular reprogramming *in vitro*, resulting in patient-specific iPSC. These iPSC are then differentiated into functional β-cells before they are transplanted into the original patient again. **(B)** Graphical abstract showing Deep Learning approach to classify phase-contrast images from different iPSC clones. First, images are taken with IncuCyte until cells reach Definitive Endoderm (DE) stage. These images are used to train a deep neural network. Later, images of an unseen clone are fed into the trained network to get a prediction of either good (class 1) or bad (class 0) clone. Figure created in BioRender.

The task of predicting cell fate has been demonstrated as possible before on other cell types [12, 13, 14], however most of these studies focus on classifying between differentiating and non-differentiating cells and differentiation towards separate cell types, or rely on different image modalities like fluorescence-stained or Raman spectroscopy images [15]. We classify here differentiating cells towards the same fate into a low and a high expression group. Morphological changes during differentiation are clearly visible at much later times, but differences between clones at such early time points are difficult to see even for a trained expert.

2. Methods

All data and code will be available at zenodo and github, respectively.

2.1. Data preparation

Cell culture: iPSC differentiation Six patient-derived iPSC clones were differentiated to Definitive endoderm (DE) stage using the STEMdiff Definitive Endoderm Kit (STEMCELL) following manufacturers instructions. The differentiation was carried out as biological duplicates in 6-well plates.

Image acquisition of cell cultures We utilized the IncuCyte® Live-Cell Analysis Systems (Sartorius), an automated microscope operating inside an incubator, ensuring optimal cell culture conditions and continuous imaging. 121 phase-contrast images per well were acquired for the first four days of differentiation (until DE stage) at 1 hour intervals. 136,488 1408 x 1040 pixels, 8-bit gray-scale images were obtained in total.

Ground truth label generation via flow cytometry For flow cytometric analysis, DE stage cells were trypsinized with 1x Trypsin (Lonza) for 5 min at 37 °C and stained for CXCR4, a DE stage specific marker. The cells were stained with a live/dead Fixable Near-IR Dead Cell Stain Kit (Life Technology). For CXCR4 staining, cells were incubated with antibody for 15 min at RT, then washed with FACS buffer and fixed with Cytofix/Cytoperm (BD Biosciences) for 20 min at 4 °C. Samples were then run through a FACS Canto Cytometer (BD) and cell counts were analyzed with FlowJo 10.8 (BD Life Sciences). Measured CXCR4 expression levels are shown in Table 1.

Clone	103	104	109	110	116	117
CXCR4	92.2	89.2	68.6	8.0	96.5	73.0

Table 1: CXCR4 expression in % of total cells of all six clones used in this study.

Dataset splitting Our dataset consists of the above described phase-contrast images and flow cytometry measurements of CXCR4 expression as ground truth labels. High levels of CXCR4 expression represent cells in the Definitive Endoderm stage, which is a measure of successful differentiation.

We decided to go for a classification setting since we had only 6 independent CXCR4 measurements. We defined two classes based on a CXCR4 expression with a threshold of 84.0% based on through biological analysis of the 6 clones. This analysis revealed that there are two distinct classes of clones, i.e. bad and good ones. The two classes have been shown to have differential expression of genes involved in stemness and trilineage specification as well as distinct success rates of differentiation into β-cells. These biological results will be available in a manuscript which is in preparation. The percentage of CXCR4-expressing cells correlates with the efficiency of final differentiation into functional mature β-cells; therefore, CXCR4 has been used in this study as a proxy for all differentially expressed genes. Clones with an expression higher than 84.0% represent class 1, while a lower CXCR4 expression represents class 0. Our dataset thus consists of 121 images from

12 wells at each of 91 time points for the 6 clones 103, 104, 109, 110, 116, 117 where blue indicates class 0 and red a class 1, respectively.

As our dataset consists of six fully independent samples, i.e. different cell clones, we split the data into training, validation and test set with a ratio of 3:2:1. We performed the splitting six times, such that each clone is used as a test set once. For every split, each clone only appears exclusively in either training, validation, or test set and never in more than one. See Table 2. This prevents unintended information leakage due to the memorization of cells from a clone across the splits. Given that the sample size could not be easily increased due to cost and scarcity of material, we performed the maximally meaningful data splitting to ensure the best possible generalizability.

Split	Train	Validation	Test
1	104, 109, 110	116, 117	103
2	103, 109, 117	110, 116	104
3	103, 110, 116	104, 117	109
4	104, 116, 117	103, 109	110
5	103, 110, 117	104, 109	116
6	104, 109, 116	103, 110	117

Table 2: List of data splits used in this study. 103 to 117 are numbers identifying the six clones. Every clone is used as test set once and only appears in one part of each split at a time. Blue indicates class 1 and red a class 0, respectively.

2.2. Network training

After initial experiments with different models, the results of which can be seen in Table 3, we finetuned an EfficientNet-V2-S [16] on the training subset, pretrained on Image-Net from torchvision 0.20.1+cu124 with PyTorch version 2.5.1+cu124. Preliminary runs showed better results for EfficientNet-V2-S than for the other tested models, see Table 3. Computational costs of all utilized models are shown in Table 4. It was trained for 15 epochs with a batch size of 64, cross entropy loss and SGD with momentum of 0.9 and learning rates between 0.01 and 0.0001. Random flipping and random cropping to 420 pixels were applied to training images. Training images for the initial set of experiments were augmented with brightness (in $[0.9, 1.1]$) and contrast (in $[0.9, 1.1]$) variations. Cropped input images will be referred to as patches in the following. Training was done independently for each of the used time points and repeated for all six data splits in Table 2 with five

Model	patch-level accuracy at 72h	clone-level accuracy at 72h
Resnet-50	69.6 ± 34.5	70.0%
Wide-Resnet-101	71.0 ± 29.7	80.0%
Swin-V2-S	51.9 ± 35.8	60.0%
ViT-B-32 224	56.4 ± 32.5	60.0%
LogReg SGD v1	49.5 ± 22.3	43.3%
LogReg SGD v2	48.1 ± 14.9	40.0%
EfficientNet-V2-S	77.0 ± 29.3	83.3%

Table 3: Comparison of different models on both patch- and clone-level at 72 hours. With the exception of the computationally much more costly Wide-ResNet-101 (see Table 4), performance is notably worse than the one of our chosen EfficientNet-V2-S. See the section 3.1 for the random guess baseline levels for these accuracy measures.

different seeds, resulting in 30 pairs of split/seed. A model was selected on the validation set of each split using highest patch accuracy per epoch over 15 epochs, with one final model for each of the 30 split/seed-pairs. These were then evaluated for accuracy on the test set of each split.

Models	GFLOPS
EfficentNet-V2-S	8.37
ResNet-50	4.09
WideResNet-101	22.75
SwinTransformer-V2-S	11.55

Table 4: Computational cost in GFLOPS according to the torchvision documentation `https://pytorch.org/vision/0.21/models.html`.

2.3. Methods for the analysis of the trained model

Layer-wise Relevance Propagation (LRP) We applied LRP to the convolution layers once using LRP-β with $\beta = 0$ [17], and once, using LRP-adaptive-β with $\beta_{max} = 2$ [18]. The last linear layer employed LRP-ε with $\epsilon = 10^{-3}$. Bias terms were ignored in the backward pass computation of the network as common for LRP modified gradient approaches. LRP was chosen due to its higher faithfulness compared to smoothed gradient methods [18].

Structure factor The structure factor $S(q)$, where $q = 1/r$ and r is the radial distance, [19], was calculated at certain time points for all images

$I(x, y)$, $x, y \in \{1 \ldots 1024\}$ in the following manner:

$$
\begin{aligned}
S(q) &= \frac{1}{2\pi q} \int_0^{2\pi} S(q, \omega(q_x, q_y)) d\omega, \quad q = \sqrt{q_x^2 + q_y^2} \quad (1) \\
S(q_x, q_y) &= \left| \mathcal{F}(\tilde{I} - \langle \tilde{I} \rangle) \right|^2 \\
\mathcal{F}(\tilde{I} - \langle \tilde{I} \rangle) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \left(\tilde{I}(x, y) - \langle \tilde{I}(x, y) \rangle \right) e^{-i2\pi(xq_x + yq_y)} dx \, dy \\
\tilde{I} &= \mathcal{G}\left((I/\sigma(I))^2, 2 \right),
\end{aligned}
$$

where $\mathcal{G}(I, 2)$ is a 2D Gaussian blur with standard deviation 2 pixels, $\langle I \rangle$ is the mean of I $\sigma(I)$ is the standard deviation of I. The 2D Fourier transform $\mathcal{F}(I)$ has been calculated with FFT using the Matlab function `fft2`.

The structure factor is a measure of the spatial correlations in live/dead cell matter distribution. Figure 4 shows the results.

3. Results

We show at first the predictive performance measurement. Afterwards we analyze the features which the model uses to arrive at a prediction.

3.1. Predictive Performance

In this study, we aimed to classify six patient-derived clones of induced pluripotent stem cells (iPSC) according to their respective level of CXCR4 expression on day 4 of differentiation. This gene expression level was used as a proxy for successful differentiation towards functional β-cells. Figure 2 shows representative crops of phase-contrast images of a clone of each class at different time points during early differentiation as used in this study. Representative images for all six clones can be found in Appendix C. iPSC clones were divided into two groups according to their CXCR4 expression levels with threshold of 84.0%. This threshold is based on the results of a gene expression analysis of the 6 clones, as described in section 2.1.

We report two metrics evaluating accuracy on the test set of each split, the *patch accuracy* and the *clone accuracy*. Next we describe how these are computed. At first, we draw m recorded images from each clone at random positions. Each image is further cropped down due to their high resolution to obtain a patch. Each patch is passed through the model with n

Figure 2: Representative sample image crops of a class 0 iPSC clone (clone 109) and a class 1 iPSC clone (clone 104). Scale bars, visible when zooming in, represent 100 μm. An enlarged version of the figure can be found in the Appendix B.

different split-seed pairs to give $m \times n$ individual patch results $p_{ij} \in \{0, 1\}$, where $i \in \{1 \ldots m\}$ and $j \in \{1 \ldots n\}$. For each split-seed pair, we calculate the seed result $s_j = (\frac{1}{m} \sum_{i=1}^{m} p_{ij}) > 0.5$ and summing over the seed results we obtain the *clone accuracy* $c = \frac{100}{n} \sum_{j=1}^{n} s_j$. We also calculate the *patch accuracy* $p = \frac{100}{m \cdot n} \sum_{i=1}^{m} \sum_{j=1}^{n} p_{ij}$. Specifically, *patch accuracy* is calculated as the percentage of correct predictions over all $m \times n$ patch/seed-pairs. *Clone accuracy* in contrast, is the percentage of correct classifications of a single clone over 5 seeds as obtained by majority vote. The random guess level for both patch and clone accuracy is 50%. This is given for clone accuracy due to an equal number of positive and negative labeled clones. For patch accuracy this was ensured by drawing an equal number of patches from each clone. Table 5 shows the results.

measure/time	24h	48h	53h*	72h	76h*
patch	74.3	74.3	81.0	77.0	77.3
accuracy (%)	±38.9	±39.1	±18.6	±29.3	±33.1
clone accuracy (%)	76.7	73.3	96.7	83.3	76.7

Table 5: Performance under brightness-augmented prediction. * indicates after washing.

Prediction at iPSC stage (0 hours) was not possible and resulted in random performance. This negative result is biologically plausible, as despite having several differentially expressed genes already before initiation of dif-

ferentiation, visible features, such as morphology, of all iPSC clones are still too similar. The fluctuation in test accuracy does not show a clear trend over time and is likely an effect of our low effective sample size of six.

3.2. Insights into the cues the model is using for predictions

Initial attribution map inspection We made two observations from LRP attribution maps. Examples using LRP-β are shown in Figure 3.

(O1) When predicted as positive, evidence for the positive class covers larger areas, compared to attribution maps computed for Image-Net trained models.

(O2) Evidence for the negative class 0 are clean holes without cells. Clean refers to low texture content.

Regarding (O1) we note that our dataset typically shows a dense matrix of relevant cells covering most of the image, unlike natural images from ImageNet which show objects of varying sizes, and, also unlike a number of samples of HE-stained cancer histopathology images which in many regions contain Haematoxylin-stained nuclei sparsely spread within large areas of Eosin-stained extracellular material. Appendix A shows Figures for the original ImageNet-trained network for comparison of the areas covered by evidence.

Regarding (O2) the model seems to learn the absence of a cue. Hole-type structures with a larger area showing absence of cells in it indicates lower cell confluency, which is an indication of lower quality for a cell type meant to form a closed monolayer.

Structure factor analysis To understand the typical scales of structure, we calculated the structure factor $S(q)$ for all images of a time point after correcting for brightness variance. Figure 4 shows the results of the Fourier analysis at times 0 hours and 53 hours. At 53 hours, there is a region in the graph where there is a visible difference between the good and bad clones' structure factor. The structure factor $S(q)$ measures periodic correlations over different length scales $r = 1/q$. A larger value of the structure factor in a range of wave vectors q signifies that in the corresponding range of length scales, there is a stronger correlation of intensities. Thus, the measurement that the bad clones have a significantly higher $S(q)$ in the range $r \in [50, 200]$ μm signifies that there are more persistent regions of high or low

Figure 3: Image and LRP heatmaps for the initial model at 53 hours. Left: predicted as negative (0), thus hole-type evidence (see observation (O2)) for class 0 is in red. Right: positive prediction as class 1, thus hole-type evidence for class 0 is in blue. Evidence for the positive class covers wide areas (O1). See Appendix D, Appendix E and Appendix H for more figures.

intensity over the range of 50 to 200 μm. Interestingly, the LRP heatmaps show red and blue regions over similar length scales, meaning our model likely learned these differences between the clones over this particular scale. Looking at the results at 0 hours, there is no difference between the two groups of clones visible, but there is a very clear spike at a scale of approximately 20 μm, the size of a single cell in our images.

Search for global cues Having seen that the cells cover large areas, we are inspecting global statistics and their relation to cues for the model.

Obvious candidates are the mean and variance per patch. Figure 5 shows the impact of cell washing on these variance. One can see that it reduces the variance notably in 2 of the 3 washing times, and still visibly in the last washing after 3d04h00m. Appendix G also shows these statistics in intervals of 12 hours. Note that the images were taken inside a dark chamber, so there is no influence from stray light, and the changes reflect dynamics of cells and the impact of washing. One notable consequence of cell washing is the removal of darker cell debris.

In the next step we measured the extent of correlation of the attribution maps to the patch mean, the patch variance, and pixel-wise edge strength. We did this by measuring Spearman rank correlation to the pixel-wise intensity, which sums up to the mean, to the pixel-wise square deviation from the mean, which sums up to the patch variance, and to pixel-wise edge norms obtained from a Prewitt filter [20] applied to the image patches. We obtain one Spearman rank correlation per image, and report the mean over 1200 images of the test set for each of 3 correlations. Table 6 shows the results.

Figure 4: Structure factor analysis of all images at time 0 hours and 53 hours, respectively. At time 0 there is no distinct difference between the structure factor of class 0 (red curves) and class 1 (black curves) images. There is a striking peak for all clones around wave number 0.05, which is approximately 20 μm. This corresponds to the size of a single cell in these images. At time 53 hours, the peak at wave number 0.05 is gone, but there is a distinguishable difference between class 0 and class 1 images at wave numbers between 0.005 and 0.02, corresponding to radial distances of 50 - 200 μm.

We see that pixel-wise variance is notably rank correlated to the attribution maps.

Attribution map	Patch mean	Patch variance	Edge norm
LRP-adaptive-β	0.03 ± 0.02	0.35 ± 0.15	-0.01 ± 0.05
LRP-β	0.01 ± 0.01	0.44 ± 0.19	0.01 ± 0.05

Table 6: Averaged Spearman Rank correlations in $[-1, 1]$ between attribution maps and Patch mean, Patch variance and Edge strength of patches

Variance normalized prediction We can see in Figure 5 that the variance is in parts different between the positive and negative clones. It is open whether the patch variance is causally related to the labels. To investigate, we devised an alternative protocol, in which we removed the brightness and contrast augmentation for training and used for all data subsets a patch-wise normalization of the standard deviation. Appendix H shows LRP attribution map for this variant at 53 hours, confirming observations (O1) and (O2). Table 7 shows partial improvements in patch accuracy and clone accuracy compared to the results in Section 3.1, namely for data sets from those times after washing which have less debris.

Figure 5: This shows 3 pairs of variances at 3 pairs of times before and after cell washing. Means are shown in Appendix F. One can see an impact of the procedure.

measure/time	24h	48h	53h*	72h	76h*
patch	70.9	71.0	90.3	76.0	83.2
accuracy (%)	±40.4	±37.6	±8.6	±34.0	±29.9
clone accuracy (%)	73.3	70.0	100.0	83.3	80.0

Table 7: Performance under variance-normalized prediction. * indicates after washing.

This initial result suggests as tradeoff that brightness augmentation is better for images with more debris, while variance normalization performs better when the amount of debris is reduced by washing.

4. Discussion and Conclusion

In this study, we present encouraging early results for accurate prediction of stem cell differentiation outcomes based on phase-contrast images.

Our model can classify high- and low-performing iPSC clones already at 24 hours after induction of the differentiation process. We further show, that our model decision is based on biologically relevant image features such as the hole structures as well as the variance of the image brightness.

Simplicity in the imaging modality is both the key advantage and key challenge of our approach. On the positive side, a simple imaging technique lowers the effort and cost of analysis of cell clones when using our final model.

However, phase-contrast images at 10x magnification only hold limited information about the imaged cells, when compared to staining for specific expressed proteins, and therefore make it harder for the algorithm to find meaningful features in them.

A major limitation of this study is the low effective sample size of six. Even though we tried to account for this, we have to be careful when interpreting our results. Further experiments with a larger and potentially more diverse, e.g. iPSC derived from several different patients, should be done to investigate the generalizability of our results.

Overall, our results show the potential of deep learning models in combination with automated, low-effort imaging techniques as a way to help bring cell therapy one step closer to the clinic.

5. CRediT authorship contribution statement

F.S. Conceptualization, Methodology, Data curation, Software, Writing-Original draft preparation. **A.B.** Conceptualization, Methodology, Software, Writing- Reviewing and Editing, Supervision. **V.Z.** Investigation. **V.S.** Conceptualization, Resources, Supervision. **H.S.** Conceptualization, Supervision. **A.M-S.** Conceptualization, Funding acquisition, Supervision. **D.K.D.** Conceptualization, Formal Analysis, Writing- Reviewing and Editing, Resources, Supervision.

6. Ethical statement

Induced pluripotent stem cells (iPSCs) were derived after obtaining written informed consent from the donor, in accordance with the Declaration of Helsinki and following approval by the appropriate institutional review board (IRB). All procedures were conducted in compliance with relevant national and international guidelines and regulations governing human biological materials.

7. Declaration of interest

The authors declare that there are no conflicts of interest associated with this publication. All authors have no financial or personal relationships that could impact the findings presented.

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Appendix A. LRP examples on ImageNet

This shows the explanations produced by LRP on samples from ImageNet for which the class-relevant cues are well understandable for non-experts.

Figure A.6: LRP heatmaps for EfficientNet-V2-S for a network pretrained on ImageNet, using images from its validation set, highlighting relevant predictive areas of the image. This shows the LRP-adaptive-β variant. Predicted classes are: tricycle, starfish, Afghan hound, porcupine. All images are from the Imagenet dataset [21].

Appendix B. Figure 2 enlarged

Figure B.7: Representative sample image crops of a class 0 iPSC clone (clone 109) and a class 1 iPSC clone (clone 104). Scale bars represent 100 μm.

Appendix C. Sample images of all iPSC clones

Figure C.8: Representative sample image crops of all six imaged iPSC clones over different time points. The upper three rows show clones below the threshold, class 0, the lower rows display clones with high CXCR4 expression, class 1. Scale bars represent 100 μm.

Appendix D. More LRP heatmaps for the initial, brightness-augmented model at 53 hours for LRP-adaptive-beta

Figure D.9: Additional images and LRP heatmaps for the initial, augmented model using LRP-adaptive-β. First and second row: predictions for class 1. For these, evidence for class 0 is in blue. Third and fourth row: predictions for class 0. For these, evidence for class 0 is in red. Time is 53 hours.

Appendix E. LRP heatmaps for the initial, brightness-augmented model at 53 hours for LRP-(nonadaptive)-beta

Figure E.10: Additional images and LRP heatmaps for the initial, augmented model using LRP-β, $\beta = 0$. First and second row: predictions for class 1. For these, evidence for class 0 is in blue. Third and fourth row: predictions for class 0. For these, evidence for class 0 is in red. Time is 53 hours. The images are the same as those in Appendix Appendix D.

Appendix F. Means before and after 3 cell washing times

Figure F.11: This shows 3 pairs of means at 3 pairs of times before and after cell washing. The time pairs are 01d21h00m/01d22h00m, 02d03h00m/02d04h00m and 03d03h00m/03d04h00m.

Appendix G. Mean and Variance in 12 hour intervals

Figure G.12: This shows variances in intervals of 12 hours.

Figure G.13: This shows means in intervals of 12 hours.

Appendix H. LRP heatmaps for the variance-normalized model at 53 hours

Figure H.14: Images and LRP heatmaps for the variance-normalized model using LRP-adaptive-β. Time is 53 hours. First and second row: predictions for class 1. For these, evidence for class 0 is in blue. Third and fourth row: predictions for class 0. For these, evidence for class 0 is in red. One can see again as evidence for the class 0 holes between cells. The images are different from those in Appendix Appendix D, because forward-pass predictions differ between the two models, and thus it makes sense to select different images for showing exemplary cases.

Appendix I. Exemplary side-by-side comparison LRP and smoothed gradient-based explanations

In case the question comes up, why we did not use gradient-based explanations, we show here a side-side comparison to demonstrate the difference in what is highlighted. There are technical reasons to use LRP heatmaps, due to their high faithfulness to the model prediction in the sense of faithfulness measures in XAI [22, 18], and the amount of gradient-shattering noise [23] inherent in gradient-based methods.

We used here smooth-grad, smooth-gradient times input and vargrad, all with 75 noised copies, and a noise standard deviation of $\sigma = 0.5$. The number of copies 75 was chosen because it is close to the limit of the GPU memory which allowed for one image to compute within one mini-batch of copies.

Figure I.15: Each row shows for the same input image: LRP-Adaptive-β, smooth-grad, smooth-gradient times input and vargrad. Images are those from the first and last row from Appendix Appendix D.

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