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# The influence of nonlinear resonance on human cortical oscillations

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# Abstract

A longstanding debate in neuroscience concerns whether macroscale brain signals can be described as purely linear Gaussian processes or they harbor the more complex statistics of nonlinear dynamics. We introduce BiSpectral EEG Component Analysis (BiSCA), a framework unifying power spectral and bispectral analysis to test for nonlinearity by identifying inter-frequency harmonic relationships and disambiguating them from superimposed components. Crucially, simulations confirm its ability to separate true nonlinearity from non-Gaussianity - a common confound. Applying this test to two large human brain recordings datasets (1,771 intracranial channels and 960 individuals' scalp EEG), we find the brain's broadband, aperiodic background behaves as a linear, Gaussian process, while narrowband Rho oscillatory - including the Alpha and Mu rhythms - are the primary source of cortical nonlinearity, exhibiting significant quadratic cross-frequency coupling. Both recordings show significant departures from linear Gaussian behavior. We observe a striking dissociation between signal power and nonlinearity. While the occipital Alpha rhythm dominates the power spectrum, the strongest nonlinear signatures arise from the less dominant parietal Mu rhythm. These findings suggest that nonlinear resonance is pervasive in cortical signals, primarily expressed through resonant oscillations rather than aperiodic activity. Without accounting for these intrinsic nonlinear interactions, a principled understanding of neural activity will be incomplete.

**Key words:** Resting-state iEEG; Nonlinear resonance; Bicoherence; Neural oscillations; Aperiodic activity

# 1. Introduction

A pivotal debate in neuroscience concerns whether mesoscale brain dynamics, as reflected in resting state EEG (rsEEG) and fMRI (rsfMRI), can be described entirely as linear, Gaussian stochastic processes. Recent studies, such as Nozari et al. (2024)[1] and Raffaelli et al. (2024)[2], argue that linear time series models suffice to describe these signals, suggesting that the intricate nonlinearities observed at the microscale—by neurons, synapses, and neural masses—are effectively "averaged out" at larger scales. This hypothesis carries profound implications: if true, it would imply that mesoscale signals lack observable nonlinear signatures, limiting our ability to infer microscale dynamics from macroscopic measurements. Conversely, empirical refutation of this claim would imply that neuronal signals possess correlations at all scales, sufficient to avoid the diffusive "washing out" of macroscopic averaging and thus retain nonlinear properties at large scale [3].

The high temporal resolution of the scalp or intracranial resting-state EEG (rsEEG) (Fig. 1A) makes it particularly suitable for investigating dynamic neural processes. Therefore, reports asserting linearity or Gaussianity are somewhat surprising since substantial evidence indicates that nonlinear dynamics are observable in rsEEG signals[4,5]. Nonlinear dynamics in neural systems, as evidenced by phenomena in the frequency domain such as nonlinear resonance, cross-frequency coupling (CFC), and phase-amplitude coupling (PAC), are critical for understanding the complex oscillatory interactions observed in resting-state EEG (rsEEG) and task-related EEG signals. One of these common features of nonlinear neural oscillations is their non-sinusoidal waveform shape, which is abundant in human electrophysiological recordings and reflects the complex biophysical dynamics of underlying neural generators [6], as modeled by early neural mass models [7–10]. This non-sinusoidality, often overlooked by conventional spectral analysis that assumes sinusoidal structure, carries important physiological information and can distinguish between different behavioral states, resting states [6,11–13]. The presence of these complex waveforms has significant implications, as it inevitably generates harmonic components in the frequency spectrum [14–18,18–22]. This asymmetric nonlinearity or quadratic phase coupling can be described by bicoherence [7,23]. Recent theoretical and empirical work has demonstrated the mathematical equivalence between phase-amplitude coupling measures and bispectral analysis, providing a unified framework for understanding nonlinear resonance in neural systems [24]. Furthermore, large-scale brain network models have shown that cross-frequency coupling emerges naturally from the nonlinear dynamics of interconnected neural populations, supporting the view that nonlinear resonance is a fundamental organizing principle of brain activity [25]. Critically, if macroscopic

signals were limited to low-order statistical properties (e.g., mean, variance), none of these nonlinear

resonance phenomena would have been observed. Moreover, widely and successfully used techniques

like Independent Component Analysis (ICA) — which relies on higher-order moments—would fail to

separate signal sources.

The debate whether the EEG is linear or nonlinear is obfuscated by ignoring a critical distinction

between linearity (the nature of a system's temporal evolution) and Gaussianity (the statistical

distribution of its variables). A linear system, such as an autoregressive model, can yield non-Gaussian

outputs if driven by non-Gaussian inputs (e.g., skewed or heavy-tailed noise). Conversely, a nonlinear

system can also produce approximately Gaussian output, a phenomenon arising from mechanisms such

as the summation of multiple independent processes (approximating a Central Limit Theorem scenario)

or as a direct result of the system's own intrinsic dynamics [26]. However, strongly nonlinear systems

frequently exhibit pronounced non-Gaussianity, such as multimodal or skewed distributions—especially

when involving harmonic coupling or multiplicative feedback. Thus, neural dynamics can embody any

combination of linearity/nonlinearity and Gaussianity/non-Gaussianity, and a given power spectrum can

arise from any of these four distinct generative mechanisms, as demonstrated in supplementary S.3.

Therefore, resolving the debate requires tools that can move beyond simple distributional analysis and

directly test for nonlinear interactions, such as those arising from nonlinear resonance phenomena like

phase coupling and harmonic generation.

It is also important to recognize that the EEG signal is likely a mixture of different types of processes

and that Gaussianity or linearity (or their absence) may vary across these processes. Understanding the

differential properties of distinct EEG components is crucial to our analysis, as it allows for a more

nuanced interpretation of the underlying neural mechanisms. By dissecting the contributions of various

subprocesses—such as oscillatory rhythms, aperiodic activity, and noise—it becomes possible to identify

which components adhere to linear dynamics and Gaussian statistics and which deviate due to nonlinear

interactions or non-Gaussian inputs.

A successful area of research for decomposing the EEG into such processes is based on the EEG

second-order cumulant $S(f)$ or spectrum for frequency $f$. For strictly stationary processes without

long-term memory [27], the distribution of optimized estimators $\hat{S}(f)$ (for example, with Multitaper)

completely characterizes linear time-invariant signals driven by noise. The separation of an EEG $\hat{S}(f)$

into distinct components defined by simple functional forms, each determined by only a few

parameters, is known as **Spectral Parameter Analysis (SPA)** (Fig. 1B & Supplementary S.2). An early

example of SPA is Pascual-Marqui et al. (1987)[28], who proposed the Xi-Alpha (ξα) model. They showed

that EEG spectra have two dominant components: an aperiodic Xi (ξ) component and multiple peaks

characterizing rhythmic activity (which we will call generically Rho components or ρ), the best known

being the Alpha (α) component (the Peak 1 in Fig. 1B). The FOOOF(Fitting Oscillations & One Over F)

model is a recent example of SPA [29]. Not only do these components have distinct behavioral correlates

[30–32], they may also derive from distinctive physiological processes [33,34].

However, SPA, which relies on second-order moments (the power spectrum), only provides a

sufficient characterization for linear Gaussian systems. For such systems, all higher-order cumulants are

zero. Consequently, SPA is thus blind to nonlinear dynamics. For this type of activity, higher-order

spectral tools, such as the bispectrum $B(f_1, f_2)$ and its normalized version, the bicoherence $b(f_1, f_2)$,

between frequencies $f_1$ and $f_2$ , are required to detect phenomena such as harmonic generation, phase

coupling, or other nonlinear interactions. Analysis of nonlinear time series (multiple lags) is therefore

needed. Another fundamental problem of state-of-the-art SPA is that the harmonic relationships

between second-order spectral peaks are not explicitly modeled despite their being ubiquitous in EEG

recordings.

We introduce **BiSCA** (**BiS**pectral EEG **C**omponent **A**nalysis), a generalized model of EEG spectral

components designed to detect and quantify nonlinear resonance and address the limitations of current

spectral analysis models. Whereas traditional approaches focus solely on isolated second-order spectral

peaks, BiSCA provides a combined model specifically designed to identify nonlinear resonance

phenomena in neural signals, allowing modeling of harmonically related second-order peaks and their

corresponding bispectral counterparts. Furthermore, BiSCA parameter estimation is based on maximum

likelihood, enabling direct statistical testing of linearity and Gaussianity for each component (Fig. 1E-G).

Following in-silico validation, we demonstrate how the BISCA model reveals substantial nonlinearities

and non-Gaussian characteristics in EEG data using 1,771 resting-state intracranial EEG (iEEG) recordings

from 106 patients.

# 2. Results

## 2.1 Overview of BiSpectral Components Analysis (BiSCA)

The BiSpectral Components Analysis (BiSCA) framework is designed to uncover nonlinearity and non-Gaussianity in resting-state EEG signals. Fig. 1 provides a schematic overview of this methodology. The analysis pipeline begins with electrophysiological data, including intracranial (iEEG) and scalp EEG recordings (Fig. 1A). From these timeseries, we compute initial data summaries using Multitaper estimators to obtain the power spectrum, denoted as $\widehat{S}(f)$, and the bispectrum, $\widehat{B}(f_1, f_2)$.

A conventional approach, Spectral Parameter Analysis (SPA), decomposes the power spectrum $\tilde{S}(f)$ on either a natural or logarithmic scale into a linear superposition of an aperiodic background component and several oscillatory peaks (Fig. 1B). However, SPA does not account for higher-order statistics, a limitation that prevents it from modeling the harmonic relationships between these peaks.

The BiSCA model extends this approach by jointly fitting both the power spectrum and the bispectrum (Fig. 1C&D). This joint modeling explicitly parameterizes the nonlinear resonances that manifest as harmonic relationships in the spectrum and corresponding peaks in the bispectrum. The model additively separates the signal into components, such as the aperiodic Xi (ξ) process and the oscillatory Rho (ρ) process. Fig. 1C shows the BiSCA model fits to the power spectrum, identifying a fundamental alpha peak and its harmonics. Fig. 1D illustrates the corresponding fit to the bicoherence $\widehat{b}(f_1, f_2)$ (the normalized bispectrum $\tilde{B}(f_1, f_2)$), where harmonic relationships are visible as distinct patterns. A key feature of BiSCA is the ability to decompose the total bicoherence into contributions from individual components (Fig. 1E-G). For instance, the total bicoherence (Fig. 1E) can be separated into the bicoherence arising from the Xi-component (Fig. 1F) and the Rho-component (Fig. 1G), isolating the source of nonlinearity.

Finally, to formally test for the presence of such phase-coupled interactions, statistical tests are applied based on the bicoherence estimates to assess Gaussianity and linearity (Fig. 1H). These tests are conducted jointly, are sensitive to quadratic nonlinearity, and distinguish whether deviations from a Linear Gaussian process stem from non-Gaussian inputs or from the system's nonlinear dynamics. As summarized in Fig. 1I, this parallel assessment classifies a signal as Gaussian Linear (GL), Non-Gaussian

Linear (NGL), Gaussian Nonlinear (GNL), or Non-Gaussian Nonlinear (NGNL), the latter three categories

(NGL, GNL, and NGNL) all manifest as non-Gaussian signals at the observational level.

***Fig. 1. Overview of the BiSpectral Components Analysis (BiSCA) framework.*** *(A) Data recording (iEEG and scalp EEG) and*
*calculation of Multitaper spectral and bispectral estimators. (B) Spectral Parameter Analysis (SPA) decomposing the power*
*spectrum into individual components. (C) BiSCA model fitting the power spectrum, capturing harmonic relationships. (D) BiSCA*
*model fitting the bicoherence to parametrize nonlinear interactions. (E-G) Additive decomposition of the BiSCA bicoherence into*
*(E) total bicoherence, (F) the Xi-component, and (g) the Rho-component. (H) Derivation of statistics for Gaussianity and linearity*
*tests from bicoherence measures. (I) Table for classifying a signal as Gaussian/Non-Gaussian and Linear/Nonlinear based on*
*statistical thresholds.*

## 2.2 Simulation Illustrating Asymmetric Waveforms and Quadratic Nonlinearity

To build a clear intuition for the bicoherence-based tests central to the BiSCA framework, we use a

targeted simulation to illustrate what they specifically detect: quadratic (or even-order) nonlinearities,

which manifest as waveform asymmetry. This comparison highlights the specific features our test

detects, rather than merely differentiating a linear-Gaussian process from a nonlinear one.

The analysis begins with an example of the "wicket wave" [35] from a 2.5-second iEEG segment Fig. 2A,

a waveform known for its strong asymmetry. A Nonparametric Nonlinear Autoregressive (NNAR) model

was fitted to this data and pruned to define its core dynamics. This model was then used to generate

two types of long-running simulations.

The right panel of Fig. 2 (G-K) shows the simulation that preserves the original asymmetry. For this

system, the estimated 2D potential landscape reveals a distinctly asymmetric basin of attraction ( Fig.

2I). The shape of this potential well geometrically constrains the system's trajectory. This constrained

path forces the system into the distorted, non-uniform limit cycle shown in the 3D phase portrait (Fig.

2H), which in turn generates the asymmetric morphology of the time-domain waveform (Fig. 2G). These

geometric features are a direct result of the underlying spectral properties: the power spectrum (Fig. 2J)

contains both even and odd harmonics of the fundamental frequency (around 8.7 Hz). This harmonic

structure generates significant quadratic phase coupling, which appears as high-valued peaks in the

bicoherence plot Fig. 2K, quantified by a bicoherence magnitude of $b^{(L)} = 1.0765$.

Conversely, the left panel (Fig. 2B-F) shows a synthetic simulation where the waveform is intentionally

symmetrized by enforcing odd symmetry in the model dynamics ($F(-\boldsymbol{x}) = -F(\boldsymbol{x})$, see details in

supplementary). This process generates a perfectly symmetric, albeit still non-sinusoidal, waveform (Fig.

2B). The corresponding state-space representations are also symmetric: a concentric 2D potential well

(Fig. 2D) allows the trajectory to trace a symmetric 3D limit cycle (Fig. 2C), which is plotted along with

the pruned states (coreset, gray dots) used by the model. Critically, the spectrum of this symmetric

system (Fig. 2E) contains only odd-order harmonics. Since bicoherence quantifies quadratic (even-order)

interactions, the absence of even harmonics results in a statistically negligible bicoherence value (Fig.

2F), with a magnitude of $b^{(L)} = 0.0161$. This directly addresses the observation that a non-sinusoidal

waveform can have minimal bicoherence if its nonlinearity is purely symmetric (odd-order).

This direct contrast demonstrates that geometric asymmetry in the estimated potential landscape and
limit cycle is a state-space representation of the quadratic phase coupling quantified by bicoherence.
Such behavior is inaccessible to a linear system, which is fundamentally constrained to a symmetric,
parabolic potential well, producing only elliptical trajectory and exhibiting negligible bicoherence. This
example clarifies that our test effectively identifies the presence of quadratic nonlinearities,
distinguishing them from other forms of nonlinear dynamics.

*Fig. 2. Comparison of asymmetric and symmetric nonlinear systems to illustrate quadratic nonlinearity. The simulations are*
*derived from an NNAR model fitted to an iEEG Wicket Wave segment (A). Left Panel (B-F): Synthetic symmetric system. (B)*
*Symmetric waveform; (C) symmetric 3D limit cycle phase portrait (red line) with pruned model states (gray dots) used for the*
*model fit; (D) symmetric 2D potential landscape; (E) corresponding power spectrum exhibiting only odd-order harmonics; and (F)*
*negligible bicoherence. Right Panel (G-K): Asymmetric system. (G) Asymmetric waveform; (H) asymmetric 3D limit cycle; (I)*
*asymmetric 2D potential well; (J) power spectrum containing both even and odd harmonics; and (K) significant bicoherence*
*peaks indicating quadratic phase coupling.*

**2.3 Nonlinear and non-Gaussian cortical dynamics in EEG/iEEG revealed by**
**Bicoherence.**

To assess the prevalence of nonlinear and non-Gaussian dynamics, we applied statistical tests for

linearity and Gaussianity to both the EEG and iEEG datasets. These tests are based on Multitaper

bicoherence estimates $\hat{b}(f_1, f_2)$, employing a modified Hinich test [36] with thresholds adjusted for

multiple comparisons using the Benjamini-Hochberg FDR procedure (q=0.001). Each recording was

classified by the joint outcome of two parallel tests—one for linearity and one for Gaussianity—placing it

into one of four categories: Gaussian Linear (GL), Non-Gaussian Linear (NGL), Gaussian Nonlinear (GNL),

or Non-Gaussian Nonlinear (NGNL).

The results, summarized in Table 1, indicate that deviations from linear Gaussian behavior are

widespread. A minority of recordings were classified as GL: only 14.7% for EEG and 25.7% for iEEG.

Conversely, a substantial majority—85.2% (81.6%+3.6%) of EEG and 74.3% (67.9%+6.4%) of iEEG

recordings—were identified as either nonlinear or non-Gaussian. Notably, signals that were strictly

linear but non-Gaussian (NGL) were uncommon, accounting for only 3.6% of EEG and 6.4% of iEEG

recordings.

*Table 1 Percentages of EEG and iEEG recordings that are Linear, Nonlinear, Gaussian or non-Gaussian*

|  | EEG | | | iEEG | | |
|---|---|---|---|---|---|---|
|  | Linear | Nonlinear | Total | Linear | Nonlinear | Total |
| Gaussian | 14.7 | 39.3 | 54 | 25.7 | 17.1 | 42.7 |
| Non-Gaussian | 3.6 | 42.3 | 46 | 6.4 | 50.9 | 57.3 |
| Total | 18.4 | 81.6 | 100 | 32.1 | 67.9 | 100 |

Topographic maps illustrate the spatial distribution of these classifications across electrodes, revealing

distinct patterns (Fig. 3A&C). For EEG, linear signals (both Gaussian and non-Gaussian) are most

frequently observed at central electrodes (Fig. 3A). In contrast, iEEG shows a predominance of GL signals

in the frontal region, while NGL signals are more frequent in the occipital area. GNL activity is strongly

expressed in the frontal areas for EEG but is less apparent in iEEG. Nonlinear Non-Gaussian (NGNL)

dynamics in EEG show an anterior-to-posterior gradient, peaking at occipital electrodes, whereas in

iEEG, they are concentrated centrally with a right-hemispheric asymmetry in the occipital lobes.

**Fig. 3. Results of Gaussianity and linearity tests applied to iEEG and scalp EEG recordings.** *(A) The topography map of the proportion of test classes of EEG data; (B) the proportion of test class of EEG along the bifrequency panel; (C) the surface plot interpolated by the statistical test result (0: accept, 1: reject) of iEEG channels; (D) the proportion of test class of iEEG along the bifrequency panel; (E-F) the spatial distribution of the frequency for the maximum spectrum peak and bicoherence peak after removing the Xi trend.*

240  An alternative perspective is offered by plotting the proportion of test result types over the triangular

241  bifrequency domain $(f_1, f_2)$ and $f_1 + f_2 \lesssim 50\,\text{hz}$ (corresponding to the bicoherence principal domain,

242  here after bifrequency panel) (Fig. 3B&D). Note that here, though we deal with statistics for each $(f_1, f_2)$

243  pair, the threshold for deciding tests is for the family of tests over the entire triangular plane, corrected

244  with FDR. Also, by construction, the Gaussianity threshold $c_\alpha^{(G)}$ and the linearity threshold $c_\alpha^{(L)}$ are

245  related as $c_\alpha^{(L)} > c_\alpha^{(G)}$ , for individual tests, resulting in a zero proportion of nonlinear but Gaussian results

246  (lower left of Fig. 3B&D). A diagonal ridge of Non-Gaussian Linear test results suggests time domain

247  asymmetries of waveforms for all frequencies. Note, however, the off-diagonal bands of interference

248  coupling for the Alpha frequency harmonics suggest frequency doubling and intermodulation effects.

249  Note the NGNL plot for EEG reveals a localized region of high proportion near at (10 Hz, 10 Hz)

250  associated with Nonlinearity and Non-Gaussianity. This result indicates evidence of intra-band nonlinear

251  coupling in the alpha rhythm. The bifrequency distribution for iEEG (Fig. 3D) shows a qualitatively similar

252  structure to the EEG results. However, these patterns in the iEEG data are more diffusely distributed

253  over the frequency triangle compared to scalp EEG data.

254  It is instructive to view the topographies of the peak frequencies at which the spectrum is maximum,

255  $f_{S_{\max}} = \underset{f}{\operatorname{argmax}}\,(S(f))$, and the frequency at which the bicoherence is maximal, determined using the

256  maximum of the main diagonal bicoherence $f_{b_{\max}} = \underset{f'}{\operatorname{argmax}}\,(b(f', f'))$, indicates that where the

257  frequency-doubling occurs (Fig. 3E&F). The latter is restricted to the bispectral values on the main

258  diagonal of the principal domain. The occipital and parietal areas possess these local maxima in the

259  alpha band, while the frontal region is in the theta band. The peak frequency of the bicoherence is

260  higher than the peaks found by the spectrum.

261 **2.4 Nonlinear resonances manifest in Rho peaks, while the Xi process remains linear**
262 **and Gaussian**

263  To understand how each process contributes to the signal's overall statistical properties, we analyzed

264  them separately. The aperiodic Xi process consistently behaved as a linear, Gaussian process: its

265  Gaussianity statistic ($b_\xi^{(G)}$) remained well below the significance threshold (Fig. 4A), and its nonlinearity

266  statistic ($b_\xi^{(L)}$) rarely exceeded the threshold (Fig. 4B).

In stark contrast, the periodic Rho processes were the primary source of nonlinearity. While being

largely Gaussian (with $b_\rho^{(G)}$ below threshold), their nonlinearity statistic ($b_\rho^{(L)}$) was significantly higher

than the threshold, mirroring the behavior of the full signal. These results clearly indicate that the

nonlinearity detected in the composite iEEG signal is driven by its rhythmic components, not its

aperiodic background.

We further examined how the statistical properties of the full signal are driven by its components. The

scatterplots reveal a strong correlation between the nonlinearity of the full signal and that of the Rho

processes (Fig. 4F), but no such relationship exists for the Xi process (Fig. 4E). Similarly, the full signal's

deviation from Gaussianity is also tied to the Rho components (Fig. 4C-D). An interesting question is the

extent to which tests for Linearity and Gaussianity of the original signal are influenced by those of each

spectral component. The scatterplots of the tests for both linearity and Gaussianity between the full

signal and its components shed light on this issue. A clear relation exists between the two types of tests

for the full signal and the Rho processes (Fig. 4F). This is not the case for the Xi process (Fig. 4E).

Therefore, the primary factors contributing to the rejection of Gaussianity and linearity in the iEEG

appear to be nonlinear resonances related to the Rho processes.

Another crucial aspect of each spectral component is the spatial distribution of their statistical

features across the brain (Fig. 4G-L). The energy (sum of the power spectrum over all frequencies) of the

aperiodical Xi process is broadly distributed, with notable concentrations in the occipital lobe, temporal

lobe, and left parietal lobe (Fig. 4G). The energy of the periodical Rho processes shows a more focal

distribution, with high energy localized explicitly in the occipital lobe, corresponding to the Alpha

rhythm, and an anterior-to-posterior decrease toward the prefrontal cortex with some energy in the

parietal lobes corresponding to the Mu rhythm (Fig. 4H). These energies have been harmonized across

recordings to account for differences in EEG amplifiers and site conditions with the Incomplete

Observed Linear Mixture Model (IOLMM) model [37].

Overall, the Gaussianity statistics are relatively low across space for both processes. Non-Gaussianity

tests for the Xi process are higher in the frontal region, while the Rho processes have a higher value in

the occipital and parietal regions. When observing the maps for the nonlinearity statistic the two

processes have distinct spatial distributions. The Xi process is barely considered nonlinear across the

entire brain (Fig. 4K). Conversely, the Rho processes show notable nonlinearity in regions that also

exhibit high energy, particularly in the parietal lobes (Fig. 4L), and to a lesser degree in the occipital

areas.

**Fig. 4. Statistical features of iEEG signals decomposed into Xi trends and periodical Rho components.** *(A-B) Violin plots showing the distribution of the (A) Gaussianity statistic $b^{(G)}$ and (B) nonlinearity (bicoherence) statistic $b^{(L)}$ for the full signal, the aperiodical Xi process (ξ), and the periodical Rho processes (ρ). The dashed line indicates the threshold for statistical significance. (C-F) Scatter plots showing the relationship between the full signal and its components. Plots (C-D) show the correlation between the Gaussianity statistics of the full signal and the (C) Xi processes and the (D) Rho process. Plots (E-F) show the correlation between the nonlinearity statistics of the full signal and the (E) Xi processes and the (F) Rho process. (G-L) Spatial distribution maps showing key statistics for the aperiodic Xi and Rho processes. (G-H) Spatial distribution of energy. (I-J) Spatial distribution of the Gaussianity statistic $b^{(G)}$. (K-L) Spatial distribution of the nonlinearity statistic $b^{(L)}$. Red indicates higher values, while blue indicates lower values.*

## 3. Discussion

By analyzing a dataset of 1,771 intracranial EEG (iEEG) and 960 subjects of scalp EEG, we reveal that only a small minority of recordings can be described as both linear and Gaussian. Over 81% of scalp EEG and 67% of intracranial EEG recordings deviate from this ideal, exhibiting significant nonlinearity and/or non-Gaussianity. This challenges the notion that mesoscale brain dynamics are predominantly linear and Gaussian [1,2]. By decomposing the iEEG signals with BiSCA, we find a clear separation between the aperiodic background activity and rhythmic oscillatory components. The broadband Xi process (aperiodic 1/f component) behaves largely as a linear, Gaussian process, whereas the narrowband Rho components (oscillatory peaks, e.g. the alpha rhythm and Mu rhythm) are the primary sources of nonlinearity in the EEG. In other words, the resonant oscillations in the brain carry nearly all of the detected quadratic nonlinear interactions (as evidenced by significant bicoherence), while the aperiodic component shows minimal nonlinear coupling. While previous SPA methods have successfully characterized the power-spectral features of these components, they are blind to phase relationships and therefore cannot assess their nonlinearity.

We observed clear signs of nonlinear resonance phenomena in the data. In the bifrequency domain analysis of the bicoherence, rhythmic peaks (especially the 10 Hz alpha rhythm) exhibited harmonic coupling – for example, frequency-doubling and intermodulation effects were visible as diagonal and off-diagonal bicoherence. These results confirm that well-known cross-frequency coupling phenomena (e.g. harmonics of alpha) are present even in resting-state activity and are quantitatively detectable with our approach. With our BiSCA model we can parameterize the coupling strength between oscillatory peaks.

### 3.1 Linear vs. Nonlinear Modeling Debate

These findings directly impact the debate concerning the nonlinearity of large-scale brain signals. Recent studies reporting evidence that macroscopic resting-state dynamics are adequately captured by linear models, suggest that microscopic nonlinearities are "averaged out" at the EEG/fMRI level. In contrast, in our analyses, most EEG channels showed higher-order statistical structure (non-zero bicoherence), implying that nonlinear interactions among neural population oscillations survive spatial and temporal averaging. In fact, our finding that a greater percentage of scalp EEG channels appeared nonlinear than iEEG channels suggests that, rather than decreasing nonlinearity as might be expected [15,38,39], volume conduction primarily spreads this activity across the scalp, contributing nonlinear

features to a wide array of channels. Prior work [7–10,12,6,13,11] showed that nonlinear phenomena like

cross-frequency coupling and harmonic generation can occur in neural mass models and actual EEG/LFP

recordings. Our empirical evidence builds on this, suggesting that large-scale measures retain higher-

order structure reflecting nonlinear resonance in neural circuits. This finding suggests a re-examination

of macroscale neural modeling: to capture brain dynamics fully, it may be necessary to incorporate

nonlinear terms. The debate should thus move beyond the binary question of "linear vs. nonlinear

models" and consider how specific nonlinear features (like those we observed in Rho oscillations) can be

integrated into interpretable models of brain activity. It would therefore be premature to assert the

superiority of linear models [1] without optimally tuning and evaluating nonlinear models on an equal

footing.

## 3.2 Interpretation of Oscillatory vs. Aperiodic Components

The biophysical separation [40] of components in BiSCA follows the assumption that two processes are

additive and independent, deriving from different layers of the cortex [41–45]. A recent study provides

further neurophysiological evidence for biophysical separation, further demonstrating with biophysical

modeling and experimental evidence that the Xi process is a genuine signal generated by arrhythmic

network activity, rather than merely an artifact of overlaid brain rhythms [33].

The analytical separation of components in BiSCA is theoretically grounded in two principles. First, for

statistically independent processes, the cumulant spectrum (including the bispectrum) is additive [27].

Second, and more broadly, even for single nonlinear systems described by Volterra functional series

[46,47], the bispectrum can be expressed as a sum of additive frequency components. Each component is

analytically defined by the system's linear and quadratic transfer functions, allowing for the formal

description and identification of nonlinear interactions.

A central finding of our study is that the aperiodic (Xi, ξ) component of the EEG signal—which is widely

considered to exhibit a 1/f-like power law—is predominantly linear. At first glance, this observation may

appear to challenge established theories where 1/f spectra can arise from critical, avalanche-like

processes. However, our conclusion is not a universal claim about the origin of all 1/f processes, but

rather a specific, data-driven insight into large-scale neural dynamics. The Xi component, corresponding

to the continuous 1/f-like background, showed negligible bicoherence and near-Gaussian amplitude

statistics across the cortex. This suggests that the aperiodic background can be modeled as a

superposition of many independent or weakly interacting sources (consistent with a linear Gaussian

process). In practical terms, the 1/f component likely reflects aggregate synaptic and neuronal activity

that, when summed over large populations, obeys the Central Limit Theorem and lacks strong phase

coupling. Our results empirically validate the common assumption that this broadband "noise floor" of

the EEG is relatively featureless and additive – an important baseline when isolating oscillatory

dynamics. The linearity of the Xi component can thus be understood as an emergent property, likely

arising from the superposition of numerous weakly correlated neural sources where nonlinearities are

averaged out at the macroscopic scale. This empirical finding is strongly corroborated by recent

theoretical models. For instance, Kramer & Chu, (2024)[34] demonstrated that a general, noise-driven

dynamical system, when linearized around a stable equilibrium, naturally generates spectra with 1/f-like

characteristics. This mechanism is conceptually identical to a basic linear filter in control theory, whose

characteristic Bode plot slopes produce such power-law spectra, offering a parsimonious explanation. It

provides a compelling theoretical foundation for why a macroscopically linear stochastic process can

produce the observed aperiodic background without invoking complex nonlinear mechanisms. It is also

crucial to consider the specificity of our methodology; the bicoherence is a powerful tool for detecting

quadratic nonlinearity, and our results show a definitive lack of such second-order interactions in the Xi

component. While we cannot formally exclude other, more complex forms of nonlinearity, our work

robustly refines the debate on neural linearity.

In contrast, the Rho components (distinct spectral peaks corresponding to oscillatory neural

generators) display robust nonlinear signatures. For the alpha rhythm (around 10 Hz) and other peaks,

we found significant bicoherence indicating phase-locked interactions, such as harmonics (e.g. 20 Hz, 30

Hz components related to alpha) and possible subharmonics or cross-frequency coupling with other

bands. The fact that the full EEG signal's nonlinearity closely tracked that of the Rho component (and

not Xi) implies that oscillatory networks are the loci of nonlinear dynamics. Mechanistically, this may

reflect the intrinsic properties of neural nonlinear resonances: oscillatory circuits (e.g., thalamocortical

loops for alpha, sensorimotor cortex for mu) can engage in feedback and coupling. This is consistent

with corticothalamic neural field models, which generate bursts of nonlinear alpha oscillations through

noise-driven exploration of a subcritical Hopf bifurcation [48].

**Dissociation Between Power and Nonlinearity:** An intriguing observation is the mismatch between

where the strongest oscillations occur and where the strongest nonlinear effects are generated. This

spatial dissociation suggests that high oscillatory power does not equate to continuously strong

nonlinearity. A more dynamic and plausible interpretation for the powerful occipital alpha rhythm is that

it reflects intermittent, high-amplitude bursts of nonlinear activity interspersed with periods of low-

amplitude, linear dynamics close to a stable fixed point [49]. Such bistable dynamics, which can emerge

from models near a subcritical Hopf bifurcation [48,50], would yield high spectral power due to the

amplitude of the bursts, but the bicoherence, when averaged over a long time window, would be

diluted by the intervening linear periods. In contrast, the less powerful parietal mu rhythm may operate

in a more persistently nonlinear state, resulting in a disproportionately stronger bicoherence signature.

This observation is consistent with a prior study[51], who reported that there are power peaks that

coexist in the Alpha and Beta bands in the parietal lobe, while only peaks in the Alpha band appear in

the occipital lobe. Our bicoherence analysis, however, advances these findings by pinpointing more

specific, functionally distinct sources of nonlinearity. This dissociation between the spatial patterns of

power and bicoherence is corroborated by a similar EEG source-reconstruction study [52].This finding

underscores that different neural circuits and networks have different dynamical regimes: some operate

mostly linearly (despite high power), while others operate in nonlinear regimes, projecting the statistical

signatures of these into the EEG.

## 3.3 Methodological Limitations

**Spatial Sampling and Data Considerations:** The scalp EEG dataset used here includes recordings from

960 multinational healthy subjects, while iEEG samples encompassed 1,771 channels across 106

patients. It is important to consider the nature of these data. The iEEG recordings come from

postoperative epilepsy patients, which might have influenced the prevalence or distribution of nonlinear

dynamics (e.g., due to cortical irritability or medication effects). However, we observed broadly

consistent patterns between iEEG and healthy EEG. In addition, these patterns also consistent with [52],

suggesting our conclusions are not driven by pathological activity. Another consideration is the volume

conduction and reference mixing in scalp EEG, which can smear true source interactions. We mitigated

this by focusing many analyses on iEEG (where signals are more focal) and by using a conservative

statistical threshold (FDR q=0.001). Still, some spurious coupling in scalp recordings cannot be entirely

ruled out. Future work might apply source separation or source localization before BiSCA to confirm that

the identified nonlinear interactions correspond to true neurophysiological coupling rather than mixing

artifacts.

## 3.4 Implications

**Nonlinear Resonance as an Organizing Principle:** The presence of nonlinear properties in the dominant oscillations of the cortex aligns with decades of theoretical work suggesting that brain oscillations do not operate in isolation but interact through nonlinear mechanisms. By explicitly linking the spectral "peaks" to bispectral evidence of coupling, we provide a more concrete basis for this principle. Going forward, this framework might help interpret phenomena like EEG cross-frequency coupling, nested oscillations (e.g. phase–amplitude coupling), and event-related harmonic responses within a unified resonance-based theory. It also suggests that modulatory relationships (such as those exploited in techniques like ICA or nonlinear signal decomposition) are inherent to brain signals and can be systematically characterized rather than treated as noise or anomalies.

**Refining Macroscale Models:** In practical terms, our findings encourage the development of new macroscale brain models that incorporate nonlinearity in a controlled way [53–60]. Rather than assuming the brain is either fully linear or arbitrarily nonlinear, models might treat the aperiodic background as an additive Gaussian noise process (as linear models do) while including nonlinear coupling for the oscillatory subsystems. This hybrid perspective – essentially what our data-driven BiSCA components represent – could improve how we simulate or predict EEG dynamics. For example, large-scale neural mass or neural field models might include nonlinear feedback only in certain frequency-generating circuits (like alpha or mu generators), which could reproduce the selective nonlinearity we observed. Our work provides empirical targets for such models (e.g., the degree of bicoherence at alpha or the spatial pattern of nonlinearity) that future simulations should aim to match.

**Extend the BiSCA to nonstationary EEG/iEEG:** This paper analyzes the system's quadratic nonlinearity (bispectrum/bicoherence) from the stationary perspective. Other nonlinear properties include multistability from a series of works in the time domain [48,49,61] of the EEG data, which show that a linear system with a single global attractor is an insufficient model. The bicoherence approach provides a complementary perspective. As an effective tool for analysis within local, quasi-stationary windows, it can specifically identify and isolate stationary quadratic interactions that may persist across transitions between attractor states [62]. This duality between stationary and dynamic perspectives underscores the complex nature of neural signals, which simultaneously exhibit both stable nonlinear features and transient dynamical shifts.

# 4. Materials and Methods

## 4.1 Materials

We analyzed resting state EEG data from 960 healthy participants drawn from the globally diverse HarMNqEEG dataset [63]. Participants were selected from normative or control groups, excluding those with neurological/psychiatric conditions. EEG recordings consisted of eyes-closed resting-state data. For all subjects, 18 channels were included (excluding Pz) from the 10-20 system after average referencing. Samples recorded for less than 1 minute, such as the Medicid-4-Cuba-2003, were excluded. Preprocessing involved converting signals to an average reference, segmenting data into 300 time points (1.5 seconds), and overlapping segments to have 157 segments per channel to maintain consistency with the iEEG data length and segmentation. We retained segments only if artifact-free, with no interictal discharges or slow-wave anomalies.

For Resting-state Intracranial EEG (iEEG), we used the dataset of eyes-closed resting-state wakefulness recordings, sEEG/ECoG recordings from the Montreal Neurological Institute iEEG atlas [51]. These iEEGs were recorded from 106 patients with refractory focal epilepsy (1,772 electrodes), ensuring that tracings retained were from non-lesional, non-seizure onset zones, free of interictal discharges, slow-wave anomalies, or post-seizure/stimulation effects. Preprocessing involved bandpass filtering (0.5–80 Hz), down-sampling to 200 Hz, and removing zero values. The study focused on 60-second eyes, in order to be consistent with the EEG data set.

## 4.2 Method

### 4.2.1 Multitaper Estimator for the Spectrum

Each segment of the signal was subjected to a Discrete Fourier transform $X(f) = \frac{1}{N_t} \sum_{n=0}^{N_t-1} x[n] e^{-j2\pi fn}$, where $N_t$ is the number of time points for each epoch. To balance the frequency resolution and computational resources, in our study, the window size was 300 time points (1.5 seconds) segments. To estimate the power spectrum, $S(f) = \mathrm{E}[X(f)X^*(f)]$ we used overlapped segments by 75% and also applied the Multitaper method, which creates windowed versions of the original time signal $x_k(n) = x(n)v_k(n)$ [64,65] in order to reduce frequency leakage bias and increase the consistency of the

482    spectral estimate, $k$ is the index of taper. For this purpose, we used the Sine tapers $v_k$ [66] to diminish

483    amplitude bias further. The resulting estimation procedure is then:

$$X_{k,e}(f) = \frac{1}{N_t} \sum_{n=0}^{N_t-1} x_{k,e}(n) e^{-j2\pi fn} \tag{1}$$

$$\hat{S}_k(f) = X_{k,e}(f) X_{k,e}^*(f) \tag{2}$$

$$\hat{S}(f) = \frac{1}{U_2} \sum_{k=0}^{K-1} \hat{S}_k(f) \tag{3}$$

where $U_2 = K/N_t$. In this paper, we use $NW = 1.5$, i.e. $K = 2NW - 1 = 4$ for the recordings. $NW$

This critical parameter controls the estimator's trade-off between frequency resolution and variance.

**4.2.2 Multitaper Estimator for the Bispectrum**

We apply the theory developed by Brillinger for nth order cumulant spectra [67,68]. The usual power

spectrum is the 2nd-order cumulant spectrum we just presented above. In this paper, we also deal with

the bispectrum, which is the 3rd-order cumulant spectrum, a function of the two frequencies

(bifrequency) $f_1$ and $f_2$

$$B(f_1, f_2) = \mathrm{E}[X(f_1) X(f_2) X^*(f_1 + f_2)] \tag{4}$$

495    As mentioned above, the bispectrum has the favorable properties of zeroing Gaussian processes,

496    being constant for linear systems with non-Gaussian input, and reflecting quadratic nonlinear

497    interactions between bifrequency pairs $f_1$ and $f_2$ and their sum $f_1 + f_2$.

498    The Multitaper estimator for the bispectrum and bicoherence [69,70]

$$\hat{B}_{k_1 k_2 k_3}(f_1, f_2) = X_{k_1, e}(f_1) X_{k_2, e}(f_2) X_{k_3, e}^*(f_1 + f_2) \tag{5}$$

$$\hat{B}(f_1, f_2) = \frac{1}{U_3} \sum_{k_1 k_2 k_3 = 0}^{K-1} P_{k_1 k_2 k_3} \hat{B}_{k_1 k_2 k_3}(f_1, f_2) \tag{6}$$

501    To preserve the correct scale, the 'bienergy' $P_{k_1 k_2 k_3} = \sum_{t=0}^{N_t-1} v_{k_1}(t) v_{k_2}(t) v_{k_3}(t)$ and $U_3 = \frac{1}{N_t} \sum_{k_1, k_2, k_3}^{K} P_{k_1 k_2 k_3}^2$.

502    We estimate the bicoherence $b(f_1, f_2)$ using the following normalization of the bispectrum [71], which

503    benefits the statistical tests defined in the next section:

504
$$b(f_1, f_2) = \frac{B(f_1, f_2)}{\sqrt{S(f_1)S(f_2)S(f_1 + f_2)}}$$
(7)

### 4.2.3 Test for Gaussianity and linearity through Higher-Order Spectrum

To characterize the underlying dynamics of the time-series data, we employed higher-order spectral

analysis to test for linearity and Gaussianity. Linear and nonlinear systems are fundamentally

distinguished by their properties of response to input frequencies: a linear system processes frequencies

independently, whereas a nonlinear system generates new harmonic and intermodulation components

through frequency interactions. Bicoherence is utilized to detect and quantify this quadratic phase

coupling.

The theoretical foundation for this method is predicated on the behavior of the bicoherence for a

linear time-invariant (LTI) system. For an LTI system driven by a non-Gaussian input, the magnitude of

the bicoherence, $|b(f_1, f_2)|$ , is constant across all frequency pairs and is determined solely by the input

signal's third-order ($\gamma_3^x$) and second-order ($\gamma_2^x$) cumulants [72]:

516
$$|b(f_1, f_2)| = \frac{|\gamma_3^x|}{(\gamma_2^x)^{3/2}}$$

This property yields a clear framework for hypothesis testing, used in Table 1:

1. A **Gaussian Linear (GL) process** is the null case. It has a third-order cumulant of zero, resulting in
a bicoherence that is identically zero across all frequencies.
2. A **Non-Gaussian Linear (NGL) process** is driven by a non-Gaussian input passing through a linear
system. This results in a **diffuse, widespread elevation** of bicoherence across the entire
frequency plane.
3. A **Gaussian Nonlinear (GNL) process** involves a Gaussian input passing through a nonlinear
system. The nonlinearity generates phase coupling at specific frequency interactions, producing
**sharp, localized peaks** in the bicoherence plot against a near-zero background.
4. A **Non-Gaussian Nonlinear (NGNL) process** represents the combined case where a non-Gaussian
input drives a nonlinear system. Its bicoherence exhibits both localized peaks superimposed on
a diffuse, non-zero background.

To achieve a more nuanced understanding of underlying dynamics and explicitly separate system

nonlinearity from input non-Gaussianity, this refined framework tries to detail the nonlinear case to GNL

and NGNL. The test for intrinsic non-Gaussian input assesses the diffuse, central tendency of

bicoherence, whereas the test for system nonlinearity targets sparse, high-magnitude peaks indicative

of quadratic phase coupling. It is important to note that the term "non-Gaussian" within this framework

refers to any deviation from Gaussianity in the observed time series that is not solely a result of system-

induced phase coupling. This includes both non-Gaussian properties of the system's innovations (inputs)

and the presence of independent additive non-Gaussian noise, both of which manifest as a diffuse, non-

zero bicoherence.

The statistical implementation of these tests relies on the asymptotic distribution of the bispectrum

estimator $\hat{B}(f_1, f_2)$. For a zero-mean stationary process, the bispectrum asymptotically follows the

complex Gaussian distribution, its expected value and variance are given [67]

$$\mathrm{E}\left[\hat{B}(f_1, f_2)\right] = B(f_1, f_2) \tag{8}$$

$$\mathrm{Var}\left[\hat{B}(f_1, f_2)\right] = S(f_1)S(f_2)S(f_1 + f_2)$$

Statistical tests for (quadratic) Gaussianity and linearity can be effectively formulated using

bicoherence, which measures quadratic phase coupling. The traditional test proposed by [36] relies on

the sum of squared bicoherence values, comparing the result to a chi-squared distribution. However,

this sum-based approach is overly sensitive to extreme values, which can arise from strong, localized

nonlinear interactions like narrow-band phase coupling. This sensitivity can cause the test to reject the

null hypothesis of Gaussianity even when the process only exhibits isolated nonlinearity, leading to false

positives. The sum is easily dominated by a few large values, misrepresenting the overall distribution as

non-Gaussian.

For testing linearity specifically, traditional methods like the interquartile range (IQR) test are often

inadequate. The IQR focuses on the central 50% of the bicoherence distribution, making it a poor

detector of narrow-band quadratic phase coupling. Such interactions manifest as sparse, extreme values

in the bicoherence map, which have little impact on the IQR. Consequently, the test lacks the power to

identify significant but isolated nonlinear peaks.

To address these limitations, we propose two robust tests that enhance the Hinich framework by

targeting distinct aspects of deviation from the null hypothesis. The first is a median-based test to assess

central tendency for Gaussianity, and the second is a maximum-based test to detect nonlinear

interactions. Both tests leverage bicoherence's ability to measure phase coupling, with their statistical

properties validated through the theoretical derivations below.

**4.2.3.1 Median-Based Test for Gaussianity**

To provide a robust assessment of Gaussianity that is less affected by outliers, we introduce a test

focused on the median of the squared bicoherence values. We first define a normalized statistic, $b^{(G)}$,

which represents the median bicoherence magnitude and serves as a measure of effect size for

asymmetricity:

$$b^{(G)} = \sqrt{\operatorname*{median}_{f_1,f_2}\{|b(f_1,f_2)|^2\}}$$

566    The formal test statistic, $t^{(G)}$, is a scaled version of this quantity:

$$t^{(G)} = 2N_s^{\mathrm{eff}} \cdot (b^{(G)})^2 = 2N_s^{\mathrm{eff}} \cdot \operatorname*{median}_{f_1,f_2}\{|b(f_1,f_2)|^2\}$$

568    where $N_s^{\mathrm{eff}}$ is the effective number of segments, and the median is computed over all bifrequency pairs

569    $(f_1,f_2)$. Under the null hypothesis of Gaussianity and linearity, this statistic follows an asymptotic

570    normal distribution. The test evaluates:

$$P\{t^{(G)} > c_\alpha^{(G)}\} \approx \alpha \qquad (9)$$

where $c_\alpha^{(G)}$ is the critical value from the asymptotic normal distribution at the significance level $\alpha$. This

test excels at detecting non-Gaussianity.

This test is derived from the asymptotical normal distribution of bicoherence. Under the null

hypothesis of Gaussianity, for each independent bifrequency pair, the scaled squared bicoherence

$x = 2N_s^{\mathrm{eff}}|b(f_1,f_2)|^2$ follows a chi-squared distribution with two degrees of freedom $x \sim \chi^2(2)$. The

test statistic $t^{(G)}$ is the sample median of $P$ such independent variables. For a large number of

bifrequency pairs $P$, the sample median is asymptotically normal. The population median of a $\chi^2(2)$

distribution is $m = 2\ln 2 \approx 1.386$. This is the expected value of our test statistic, $E[t^{(G)}] \approx 2\ln 2$. The

asymptotic variance of a sample median from a sample of size $P$ is given by $\dfrac{1}{4P\left[f\left(m\right)\right]^2}$, where $f\left(m\right)$

is the value of the probability density function (PDF) at the population median $m$. The PDF of a $\chi^2\left(2\right)$

distribution is $f\left(x\right)=\dfrac{1}{2}e^{-x/2}$. At the median $m=2\ln 2$, the PDF value is $f\left(2\ln 2\right)=\dfrac{1}{2}e^{-\ln 2}=1/4$.

Therefore, the variance is:

$$\mathrm{Var}(t^{(G)})=\frac{1}{4P\left(1/4\right)^2}=\frac{4}{P}$$

585    Thus, the test statistics follow the asymptotic distribution:

$$t^{(G)}\sim\mathcal{N}\left(2\ln 2,\sqrt{\frac{4}{P}}\right)$$

587    **4.2.3.2 Maximum-Based Test for Nonlinearity**

588    To identify nonlinear interactions that may be missed by the median test, we introduce a test based

589    on the maximum squared bicoherence value. The normalized statistic, $b^{(L)}$, directly captures the

590    magnitude of the strongest quadratic phase coupling:

$$b^{(L)}=\max_{f_1,f_2}\{|b\left(f_1,f_2\right)|\}$$

592    The corresponding test statistic, $t^{(L)}$, is its scaled squared value:

$$t^{(L)}=2N_s^{\mathrm{eff}}\cdot\left(b^{(L)}\right)^2=2N_s^{\mathrm{eff}}\cdot\max_{f_1,f_2}\{|b\left(f_1,f_2\right)|^2\}$$

594    To distinguish localized linearity from background non-Gaussianity, we estimate a non-centrality

595    parameter $\hat{\lambda}_0$. The distribution of $t^{(L)}$ is modeled using extreme value theory, specifically a Gumbel

596    distribution. The test evaluates:

$$P\{t^{(L)}>c_{\alpha}^{(L)}\}\approx\alpha \tag{10}$$

598    where $c_{\alpha}^{(L)}$ is the critical value from the Gumbel distribution at the significance level $\alpha$. This test is

599    designed to pinpoint significant localized nonlinearity.

600     To account for baseline non-Gaussianity, we estimate a non-centrality parameter $\lambda_0$:

$$\hat{\lambda}_0 = \max\left(\underset{f_1, f_2}{\text{median}}\{2N_s^{\text{eff}}|b\,(f_1, f_2)|^2\} - 2\ln 2, 0\right)$$

602     This reflects that the median of a non-central $\chi^2(2, \lambda_0)$ distribution is approximately $2\ln 2 + \lambda_0$ for

603     small $\lambda_0$. Using extreme value theory (EVT), the maximum of $P$ independent $\chi^2(2, \lambda_0)$ variables is

604     approximated by a Gumbel distribution. The normalizing constants are: $b_P = F^{-1}(1 - 1/P)$, the value

605     where the cumulative distribution function (CDF) $F$ of $\chi^2(2, \lambda_0)$ reaches $1 - 1/P$. And $a_P = \dfrac{1}{Pf(b_P)}$,

606     where $f$ is the PDF of $\chi^2(2, \lambda_0)$. Thus, the nonlinearity test statistic is distributed as:

$$t^{(L)} \sim \text{Gumbel}(b_P, a_P)$$

**4.2.3.3 Estimation of the Effective Number of Segments**

The theoretical distributions described above assume that bicoherence values are derived from

independent data segments. However, modern spectral estimation techniques like the multitaper

method we used here and the use of overlapping segments introduce dependencies. This means the

nominal number of segments, $N_s$, is larger than the effective number of independent segments, $N_s^{\text{eff}}$.

Using the nominal $N_s$ in the test statistics will lead to incorrect scaling, thresholds, and p-values.

To ensure accuracy, we estimate $N_s^{\text{eff}}$ with the following procedure:

1. Fit an AR model: Fit an autoregressive (AR) model to the observed time series $x(t)$ using the Burg
method. Select the optimal model order using the Corrected Akaike Information Criterion (AICc).
2. Generate surrogate data: Generate $M$ surrogate time series (e.g., $M = 100$) using the fitted AR model
with Gaussian white noise as innovations. Each series should have the same length $N$ as the original data.
3. Compute bicoherence: For each of the $M$ surrogate series, compute the bicoherence $b\,(f_1, f_2)$ using the
exact same parameters (e.g., Multitaper settings, window length, overlap) as used for the original data.
4. Calculate the mean squared bicoherence: For each surrogate series, calculate the mean of the squared
bicoherence magnitudes over all $P$ valid bifrequency pairs:

$$\text{mean}(|b\,(f_1, f_2)|^2) = \frac{1}{P}\sum_{f_1, f_2}|b\,(f_1, f_2)|^2$$

624      5.    Estimate $N_s^{\text{eff}}$: Average the result from step 4 across all $M$ simulations. Under the null hypothesis,

625         $E\left[|b\left(f_1, f_2\right)|^2\right] \approx 1/N_s^{\text{eff}}$ Therefore, the effective number of segments can be estimated as:

$$N_s^{\text{eff}} = \frac{1}{\text{mean}_M\left[\text{mean}(|b\left(f_1, f_2\right)|^2)\right]}$$

This estimated $N_s^{\text{eff}}$ should replace $N_s$ in all calculations for the $t^{(G)}$ and test statistics and their

corresponding distributions, thereby accounting for dependencies and ensuring the validity of the

statistical tests.

**4.2.4 BiSpectral EEG Component Analysis (BiSCA)**

**4.2.4.1 Whole model**

After obtaining the empirical and higher-order spectra, this paper proposed a BiSCA model specifically

designed to detect nonlinear resonance by jointly parametrizing the spectrum and bispectrum. This

combined model approach is essential for identifying nonlinear resonance phenomena that cannot be

detected by traditional spectral analysis alone. Here, the Xi trend and Rho peaks (including Alpha and all

other oscillatory peaks) are modeled with two types of independent processes, allowing them to be

additive on the natural scale. Additionally, the analysis includes both the spectrum and the bispectrum

to understand the components comprehensively.

$$S(f; \theta_{2,\xi}, \theta_{2,\rho}) = S_\xi(f; \theta_{2,\xi}) + S_\rho(f; \theta_{2,\rho}) \tag{11}$$

$$B(f_1, f_2; \theta_3) = B_\xi(f_1, f_2; \theta_{3,\xi}) + B_\rho(f_1, f_2; \theta_{3,\rho}) \tag{12}$$

where different $\theta$ are the parameters for different components in each order.

**4.2.4.2 Model for Spectrum**

In this paper, we put all peaks in the group of Rho processes for several reasons. 1) To be consistent

with the conventional XiAlpha model, we model the trend as the Xi process and the oscillatory rhythms

as the Alpha process. 2) The models of oscillation peaks have similar structures. 3) We focus on

univariate analysis, which views the neural masses as a single integrated oscillator. For the spectra, each

component consists of a sum of squares of kernel functions. Since here we use the transfer function to

connect different orders of spectra, the sum of the squares of the frequency transfer function of each

component approximates the modeled theoretical power spectra here

$$S_\xi(f; \sigma_\xi, \nu_\xi, d_\xi) = h_{S,\xi} t(f; 0, \sigma_\xi, \nu_\xi, d_\xi)^2$$

(13)

$$S_\rho(f; \mu_\rho, \sigma_\rho, \nu_\rho, d_\rho) = \sum_{k=1}^{K} h_{S,\rho,k} t(f; \mu_\rho, \sigma_\rho, \nu_\rho, d_\rho)^2$$

The kernel function $t(\cdot)$ models the oscillatory rhythm peaks in the spectrum domain. The $h$ is the

scale parameter for each peak, and the peak number $K$ represents the number of harmonics to be

modeled. We offered two strategies for determining the center frequency of peaks: (1) the $\{\mu_{\rho,k}\}$ is

$\left\{ \cdots, \frac{1}{3}\mu_\alpha, \frac{1}{2}\mu_\alpha, \mu_\alpha, 2\mu_\alpha, 3\mu_\alpha, \cdots \right\}$, in practice, the order $k$ is chosen with the Akaike information

criteria. This circumstance models the alpha rhythm with the simplest condition that the resting state

EEG is the output of the system excited with Gaussian white innovation, and the 1st-order transfer

function has a single tone at Alpha; the rest of the peaks in other bands are the harmonics of the

fundamental oscillation peak. (2) fit each of the $\{\mu_{\alpha,k}\}$ through the spectra and then adjust with the

joint fitting with the bispectrum. Option (1) offers frequency peak organization following the

conventional broadband analysis; option (2) will fit the components better but is more complicated. This

paper demonstrates the result with option (2), which is more general and can use the parameter for

bicoherence to interpolate the phase relationship between the peaks. The goodness of both option fit is

shown in the supplementary.

The student t kernel function has been used in previous studies of spectrum fitting [73–75]. Here, we

modified the student t function to model the amplitude of the 1st-order frequency transfer function,

which also extends the adjustable heavy-tail version of the Lorentzian (Cauchy-Lorentz distribution

function).

(14)

$$t(f, \mu, \sigma, \nu, d) = \frac{1}{\left[ 1 + \left( \frac{f - \mu}{\sigma} \right)^d \right]^\nu}$$

The parameter $\sigma$ controls the width of the kernel function. The parameter $d$ controls the flat top of

the kernel since the Multitaper method is smooth in the frequency domain and distorts the shape

function; in practice, the value is larger than 2. The parameter $\nu$ controls the kurtosis or the heavy tail

of the peak. Special case: $d = 2$ it turns to the student t function; $\nu = 1$, $d = 2$ it turns to the

Lorentzian kernel.

### 4.2.4.3 Model for bispectrum

To simplify the modeling process, we did not directly use the theoretical composition form of transfer

function kernels to each order of the spectrum [46,47,76–78]. Instead, we focus on capturing the primary

relationships of position and order by parameterizing the theoretical bispectrum $M_3(f_1, f_2)$ as follows:

678
$$
\begin{aligned}
\mathrm{Re}\left[M_3(f_1, f_2)\right] &= \mathrm{Re}(h_{B,\xi})\, t_2(f_1, f_2; \mu_\xi, \mu_\xi, \sigma_\xi, \nu_\xi, d_\xi) \qquad\qquad\qquad\quad \text{`}\xi\text{'} \qquad (15)\\
&\quad + \sum_{m=1}^{K}\sum_{n=1}^{m} \mathrm{Re}(h_{B,\rho,m,n})\, t_2(f_1, f_2; \mu_{\rho,m}, \mu_{\rho,n}, \sigma_\rho, \nu_\rho, d_\rho) \qquad \text{`}\rho\text{'}\\
\mathrm{Im}\left[M_3(f_1, f_2)\right] &= \mathrm{Im}(h_{B,\xi})\, t_2(f_1, f_2; \mu_\xi, \mu_\xi, \sigma_\xi, \nu_\xi, d_\xi)\\
&\quad + \sum_{m=1}^{K}\sum_{n=1}^{m} \mathrm{Im}(h_{B,\rho,m,n})\, t_2(f_1, f_2; \mu_{\rho,m}, \mu_{\rho,n}, \sigma_\rho, \nu_\rho, d_\rho)
\end{aligned}
$$

679 This formula captures the essential features of the bispectral peaks without resorting to complex

680 transfer function compositions. The BiSCA models the real and imaginary parts of the bispectrum

681 separately since the phase information of the bispectrum is necessary for the discrimination of systems

682 [79]. The kernel function for the bispectrum is

683
$$
t_2(f_1, f_2; \mu_1, \mu_2, \sigma, \nu, d) = \frac{1}{t(f_1; \mu_1, \sigma, \nu, d)\, t(f_2; \mu_2, \sigma, \nu, d)\, t(f_1 + f_2; \mu_1 + \mu_2, \sigma, \nu, d)}
$$

684 ### 4.2.4.4 Likelihood

685 The likelihood of the model follows the asymptotically Gaussian distribution of the log-scale spectrum

686 [80] and natural scale bispectrum[81].

687 To ensure that the Xi process exhibits a wide spectrum, we add a likelihood term for the Xi process to

688 encourage fits that adhere to the overall trend. The joint likelihood for the full model is:

689
$$
\begin{aligned}
L\left(\theta_2, \theta_3 \mid \hat{S}, \hat{B}\right) &= L\left(\theta_2 \mid \tilde{S}\right) + L\left(\theta_3 \mid \tilde{B}\right)\\
&= -\frac{1}{N_S}\sum_f \left(\frac{\log\left(\hat{S}(f)\right) - \log\left(\tilde{S}(f; \theta_2)\right)}{\widehat{Var}\left[\log\left(\hat{S}(f)\right)\right]}\right)^2\\
&\quad - \frac{1}{N_B}\sum_{f_1}\sum_{f_2} \frac{\left|\hat{B}(f_1, f_2) - \tilde{B}(f_1, f_2; \theta_3)\right|^2}{\tilde{S}(f_1; \theta_2)\, \tilde{S}(f_2; \theta_2)\, \tilde{S}(f_1 + f_2; \theta_2)}
\end{aligned}
$$

690 where the $\hat{S}(f)$ and $\hat{B}(f_1, f_2)$ is the Multitaper power spectrum and bispectrum estimate by formula (3)

691 and (6), $\tilde{S}(f; \theta_2)$ and $\tilde{B}(f_1, f_2; \theta_3)$ is the modeled theoretical power spectrum and bispectrum.

692    This likelihood-based method makes it advantageous to use statistical methods to do the model

693    comparison.

### 4.2.4.5 Fit with the Levenberg-Marquardt method

We estimate the model parameters using the Levenberg-Marquardt (LM) optimization algorithm. The

LM method is a standard technique for solving nonlinear least squares problems, effectively balancing

the Gauss-Newton algorithm and gradient descent. It is particularly suitable when the objective function

is the sum of squares of loss functions, as in our joint likelihood estimation, which is also a

heteroscedastic curve/surface fitting problem. Employing the LM method, we iteratively update the

parameter estimates to minimize the discrepancy between the empirical and theoretical spectrum and

bispectrum, ensuring convergence to an optimal solution. The LM algorithm is not a global optimization

method. Therefore, we fit the spectra parameters first and then share the parameters with the

bispectrum as a warmup for the joint fit.

### 4.2.4.6 Bicoherence for each component

705    We can then obtain the bicoherence for each component

$$\tilde{b}_\xi(f_1, f_2) = \frac{\tilde{B}_\xi(f_1, f_2)}{\sqrt{S(f_1)S(f_2)S(f_1 + f_2)}}$$

$$\tilde{b}_\rho(f_1, f_2) = \frac{\tilde{B}_\rho(f_1, f_2)}{\sqrt{S(f_1)S(f_2)S(f_1 + f_2)}}$$

707    We use full variance to normalize the component bicoherence to avoid instability and ensure the

708    additive way to model the bicoherence.

### 4.2.4.7 Test for components

710    Then we recall the test (9) and (10) for testing the non-Gaussianity and linearity of each component.

## 5. Conflict of Interest

712    The authors declare no conflict of interest.

## 6. Data availability

The scalp EEG and intracranial EEG (iEEG) data analyzed in this study were obtained from the work of Li

et al., (2022)[63] and Frauscher et al. (2018)[51], respectively. Ethical approval was not required for this

specific study as it exclusively analyzed pre-existing, publicly available, and anonymized datasets (the

HarMNqEEG dataset and the Montreal Neurological Institute iEEG atlas). The collection of the original

data received ethical approval from the respective local authorities, as detailed in the original

publications [51,63].

## 7. Code availability

721 The analysis code used in this study is publicly available on GitHub at https://github.com/rigelfalcon/BiS

722 CA.

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# Supplementary Materials

## S.1 Mathematical notations

*Table S 1 Summary of symbols*

| Symbol | Definition |
|---|---|
| $x \in \mathbb{C}$ or $x \in \mathbb{C}$ | Scalar |
| $\boldsymbol{x} \in \mathbb{C}^d$ | Vector of size $d$ (e.g., $\boldsymbol{x} = [x_i \mid i = 1, \cdots, d]$) |
| $\boldsymbol{X} \in \mathbb{C}^{d_1 \times d_2}$ | Matrix of size $d_1 \times d_2$ |
| $i$ | Index of individual $i \in \{1, 2, \cdots N_i\}$, $N_i$ is the total participants or subjects in the study |
| $c$ | Index of the channel $c \in \{1, 2, \cdots, N_c\}$, $N_c$ is total EEG channels |
| $e$ | Index of EEG epochs $e \in \{1, 2, \cdots, N_e\}$, $N_e$ is the disjoint segments selected from the continuous EEG |
| $f$ | Physical frequencies with unit $\mathrm{Hz}$ |
| $t$ | Physical time of each epoch |
| $k$ | Index of taper, $k \in \{1, 2, \cdots, N_k\}$, where $N_k = 2NW - 1$ |
| $NW$ | Time-bandwidth product. $N$ is the number of time samples in a single EEG epoch. $W$ is the half-bandwidth of the tapers |

*Table S 2 Symbol of quantities and operators*

| Symbol | Name | Definition |
|---|---|---|
| $v_{i,c,e}(t) \in \mathbb{R}$ $v_{i,c,e}(f) \in \mathbb{C}$ | EEG potential and its Discrete Fourier transform | EEG potential of the individual $i$, channel $c$ of $e$-th epoch at a time $t$ or frequency $f$ for the Discrete Fourier transform. |
| $S_{i,c}(f) \in \mathbb{R}$ | Theoretical spectra | The theoretical spectrum of an individual $i$ channel $c$ at the frequency $f$ |
| $\widehat{S}_{i,c}(f) \in \mathbb{R}$ | Power spectra | The empirical variance vector of $v_{i,c,e}(f)$ across all epochs for an individual $i$ at the frequency $f$ |

| | | |
|---|---|---|
| $B_{i,c}(f_1, f_2) \in \mathbb{C}$ | Theoretical Bispectrum | The theoretical bispectrum of an individual channel $c$ at the bifrequency $(f_1, f_2)$ |
| $\hat{B}_{i,c}(f_1, f_2) \in \mathbb{C}$ | Empirical Bispectrum | The empirical bispectrum of process $v_{i,c,e}(t)$ across all epochs for an individual $i$ channel $c$ at the bifrequency $(f_1, f_2)$ |
| $b_{i,c}(f_1, f_2) \in \mathbb{C}$ | Population Bicoherence | Population normalized bispectrum for individual $i$ and channel $c$ at the bifrequency $(f_1, f_2)$ |
| $\hat{b}_{i,c}(f_1, f_2) \in \mathbb{C}$ | Multitaper Bicoherence | Multitaper bicoherence estimator for individual $i$ and channel $c$ for bifrequency $(f_1, f_2)$ |
| $\tilde{b}_{i,c}(f_1, f_2) \in \mathbb{C}$ | BiSCA Bicoherence | BiSCA -model estimator for individual $i$ and channel $c$ for bifrequency $(f_1, f_2)$ |
| $\mathrm{E}[\cdot]$ | Expectation | The expectation of a random variable |
| $\mathrm{Var}[\cdot]$ | Variance | The variance of a random variable |
| $[\cdot]^*$ | Complex conjugate | The complex conjugate of a variable |

## S.2 Summary of EEG Spectral Parameterization Methods

As a typical machine learning problem, many toolboxes implemented the curve fitting for

spectroscopic data analysis — such as SpectroChemPy [82], PNNL Chemometric Toolbox[83] astronomy

data modeling [84], SLM (Shape Language Modeling) [85], LMFIT (Levenberg-Marquardt least-squares

minimization ) [74]. This paper emphasizes studies that have been applied specifically to EEG spectral

analysis with certain constraints of biophysical prior.

908                 *Table S 3 Summary of EEG Spectral Parameterization Methods*

| Method | Feature |
|---|---|
| SPA (Spectral Parameter Analysis)[86–88] | Calculate the resonance peaks information from the poles and zeros of the autoregressive model |
| Xi-Alpha (ξα)[28] | Additive t-student kernels in nature scale fitted with maximum Whittle's likelihood |
| BOSC (Better Oscillation Detection)[89–91] | Thresholds for time and amplitude to detect and parametrize the burst of rhythm in time frequency |

| | |
|---|---|
| Gaussian peak fit[22] | Least square Gaussian peak fit |
| IRASA (Irregular-Resampling Auto-Spectral Analysis)[92] | Resampling to shift the spectra and using a media curve to get components |
| SpecParam (Spectral parameterization) or FOOOF (Fitting Oscillations & One Over F)[29] | Sequentially fit peaks through least square Gaussian fit in the log-scale |
| SPRiNT (Spectral Parameterization Resolved in Time)[93] | Parametrize the peaks in the smoothed short-time Fourier transforms |
| PaWNextra (Pink and White Noise extraction)[94] | Least square fit |
| Cortical Xi-Alpha[40] | Nonnegative matrix decomposition for multichannel |
| Xi-Pi (ξ-π)[95] | Fit nonparametric spectrum components with Whittle's likelihood |
| Xi-Alpha Net[96] | Hierarchical Bayesian model for solving the State space model with Xi-Alpha prior to reconstruct the source space spectrum |
| Our BiSCA (Higher-order Xi-Alpha Model) | Parametrize both spectrum and bispectrum with joint likelihood |

## S.3 Simulation

**Fig. S 1. Flowchart of the Simulation and Analysis Pipeline.** *This diagram illustrates the methodology for analyzing real intracranial EEG (iEEG) data and generating four corresponding types of synthetic surrogate data to test for nonlinearity and non-Gaussianity. (1) Direct Analysis of Real Data (Top Path, Ref: Fig. S2 i): The process begins with a real iEEG time series. This signal is directly subjected to spectral and bispectral analysis to compute its empirical power spectrum and bicoherence as a real-data baseline. (2) Linear and Nonlinear Surrogate Generation (Middle Path, Ref: Fig.S2 ii-v): A linear Autoregressive (AR) and a Nonparametric Nonlinear Autoregressive (NNAR) model is fitted to the real iEEG data. The optimal model order is selected using the Akaike Information Criterion corrected (AICc). This AR model and NNAR model are then used to generate two types of time series by driving it with different stochastic innovations: Linear/Nonlinear Gaussian: Using Gaussian (normal) distributed noise. Linear/Nonlinear Non-Gaussian: Using skewed, non-Gaussian noise (Pearson Type III distribution). (3). Simulation demonstration of the bicoherence and time domain Geometric for the Fig.2: after fitting the NNAR model to the real data, only the states close to the equilibrium is be maintained in the model and used to simulate to get spectrum, bicoherence and 2d embedded potential (density) function.*

### S.3.1 Simulation for the Hinich's test and BiSCA parametrization demonstration

Here is an example of our bicoherence analysis for different types of signals, we put a simulation demonstration consisting of one channel of real data and 4 corresponding synthetic data (linear Gaussian, linear non-gaussian, nonlinear Gaussian, and nonlinear non-gaussian).

1. Real data: one channel from the MNI atlas data, with Fs=200Hz and 12000 time points samples.
2. Linear Gaussian process: This simulation used an Autoregressive (AR) model with Gaussian innovation.

$$\tilde{x}_{t+1} = \sum_{i=0}^{p-1} \hat{a}_i \tilde{x}_{t-i} + \tilde{u}_t \left( t = p, ..., N + p - 1 \right) \tag{16}$$

The AR coefficient is fitted with the real data using Burg's method. In this example, a 45-order

AR model is selected with AICc criteria, and the innovation is $N(0,1)$. We simulated

$N = 12000$ samples with this AR model, also the same length for the rest 3 simulations.

3.  Linear non-gaussian process: Instead of using the Gaussian innovation, here we use the Pearson

type III distribution[97] as the innovation enables us to control the first to third-order moment for

the distribution. The probability density function is

$$f(u) = \begin{cases} \dfrac{(u-\xi)^{\alpha-1}e^{-(u-\xi)/\beta}}{\beta^{\alpha}\Gamma(\alpha)}, & \gamma > 0 \\[2ex] \dfrac{1}{\sqrt{2\pi}}e^{-\frac{1}{2}\left(\frac{u-\mu}{\sigma}\right)^{2}}, & \gamma = 0 \\[2ex] \dfrac{(u-\xi)^{\alpha-1}e^{-(\xi-u)/\beta}}{\beta^{\alpha}\Gamma(\alpha)}, & \gamma < 0 \end{cases} \tag{17}$$

where the parameter of the distribution $\alpha = 4/\gamma^{2}$, $\beta = \dfrac{1}{2}\sigma|\gamma|$ and $\xi = \mu - 2\sigma/\gamma$. The

parameter $\mu$ is the center of distribution, $\sigma$ is the standard deviation, $\gamma$ is the skewness. Here

we take $\mu = 0$, $\sigma = 1$ and $\gamma = 10$.

4.  Nonlinear Gaussian process: Instead of linear $p$-lag AR model in the linear case, here we used a

nonparametric nonlinear autoregressive (NNAR) model to fit the data [98], and simulate 12000

timepoints data recursively. Given timeseries $\{x_{t}\}_{t=1}^{N_{t}}$, reconstruct phase space via delay

embedding:

$$\boldsymbol{x}_{t} = [x_{t}, x_{t-1}, ..., x_{t-p+1}]^{T} \in \mathbb{R}^{p} \tag{18}$$

947        The state evolution is modeled as the discrete nonlinear state space model

$$\tilde{\boldsymbol{x}}_{t+1} = F(\tilde{\boldsymbol{x}}_{t}) + \tilde{\boldsymbol{u}}_{t} \tag{19}$$

949        where $F(\cdot):\mathbb{R}^{p} \to \mathbb{R}^{p}$ is a $p$ dimensional nonparametric function estimated via adaptive local

950        constant regression (Nadaraya-Waston regression). To simplify the notation to fit regression

951        notation, define embedding vector keys set $\{\boldsymbol{x}_{k}, \boldsymbol{y}_{k}\}_{k=1}^{n}$ stored all observed data with $\boldsymbol{x}_{k} = \boldsymbol{x}_{t}$

952        and $\boldsymbol{y}_{k} = \boldsymbol{x}_{t+1}$, $n = N_{t} - p - 1$.

$$\hat{F}(\boldsymbol{x}_q^*) = \frac{\sum_{k=1}^{n} K_{h_k}(\boldsymbol{x}_k, \tilde{\boldsymbol{x}}_q)\boldsymbol{y}_k}{\sum_{k=1}^{n} K_{h_k}(\boldsymbol{x}_k, \tilde{\boldsymbol{x}}_q)}$$

(20)

954 $\tilde{\boldsymbol{x}}_q$ is the query vector state during the N-step forward forecasting. The local weights are

955 calculated by the kernel distance $K_{h_k}(\boldsymbol{x}_k, \boldsymbol{x}_q) = \exp\left(-\frac{\|\boldsymbol{x}_k - \boldsymbol{x}_q\|^2}{2h_k^2}\right)$ with bandwidth $h_k$. The

956 $h_k$ is the hyper parameter of model, in order to handle non-uniform distribution of the states in

957 the $p$ dimension space, we use the $\kappa$-th nearest neighborhood $\boldsymbol{x}_{[k,\kappa]}$ of each $\boldsymbol{x}_k$ to determine

958 the local bandwidth

$$h_k = \frac{\|\boldsymbol{x}_{[k,\kappa]} - \boldsymbol{x}_k\|}{\sqrt{p}}$$

(21)

960 To select $\kappa$, this paper used a generalized cross-validation (GCV) on the real data $\{x_t\}_{t=1}^{N}$ from

961 case 1, to find the best $\kappa$ of and record the corresponding $h_k$ for each states $\boldsymbol{x}_k$ in the one-step

962 forward prediction task.

$$\mathrm{GCV}(\kappa) = \frac{\mathrm{MSE}(\kappa)}{(1 - \mathrm{tr}(\boldsymbol{L}(\kappa))/n)^2}$$

964 where the smoother matrix with elements

$$L_{k,q}(\kappa) = \frac{K_{h_k}(\boldsymbol{x}_k, \boldsymbol{x}_q)}{\sum_{k=1}^{n-1} K_{h_k}(\boldsymbol{x}_k, \boldsymbol{x}_q)}$$

To be computationally efficient, here we use scalar $h_k$, bandwidth is equal for all dimensions.

The embedding dimensions $p$ are used the same as linear simulation case 2 and case 3. The

nonparametric function $\hat{F}(\cdot)$ represent all the information of the original (Hankel embedded)

state space or the differential manifold of the system, therefore, we didn't update this

nonparametric function during evolution. In the simulation the innovation $\boldsymbol{u}_t^*$ is a multivariable

gaussian distribution $\boldsymbol{z}_t$ and scaled with covariance from the residual of the one-step forward

prediction $\boldsymbol{u}_t^* = \boldsymbol{L}\boldsymbol{z}_t$, where $\boldsymbol{L}$ is the Cholesky of the covariance matrix of the residual

$\boldsymbol{L}\boldsymbol{L}^T = \boldsymbol{\Sigma}$, and $\boldsymbol{\Sigma} = \dfrac{1}{n-1}\boldsymbol{\epsilon}^T\boldsymbol{\epsilon} + \lambda\boldsymbol{I}_p$ with $\boldsymbol{\epsilon} = \boldsymbol{X} - \hat{\boldsymbol{X}} = [\epsilon_{t,1}, \epsilon_{t,2}, ..., \epsilon_{t,p}]_{t=1}^n$.

Nonlinear non-gaussian process: The nonlinear system follows the configuration of case 4. Instead of

Gaussian innovation, we use Pearson type III (17) to generate the innovation $\boldsymbol{z}_t$ and then the $\boldsymbol{u}_t^*$.

All 5 cases apply the Multitaper estimation and the BiSCA model fitting with the same parameters as

the analysis for real data.

**Fig. S 2. Simulation demonstration.** *Column from left to right are the 5 cases described in the simulation (i) real iEEG of MNI atlas data; (ii) linear Gaussian; (iii) linear non-Gaussian ; (iv) nonlinear Gaussian; (v) nonlinear non-Gaussian; Row from top to bottom is the result of analysis of each step (a) empirical spectrum calculated with Multitaper method; b) empirical modulus bicoherence calculated with Multitaper method with color scale indicating bicoherence modulus amplitude.; (c) threshold bicoherence with parametric test of p≤0.001: providing a clearer view of which frequency interactions are nonlinearly coupled beyond test level; (d) the spectrum from the fitted BiSCA model; (e) the bicoherence from the fitted BiSCA model.*

Fig. S 2 illustrates how non-Gaussianity and nonlinearity impact neural time series analyses; we

synthesized intracranial EEG (iEEG) signals under five distinct scenarios—real iEEG data (MNI atlas),

linear Gaussian, linear non-Gaussian, nonlinear Gaussian, and nonlinear non-Gaussian—and compared

their power spectrum and bicoherence pattern. The real iEEG data Fig. S 2i exhibits a characteristic 1/f-

like power spectrum with modest but significant bicoherence clusters after thresholding (p ≤ 0.001). This

empirical baseline reveals that genuine neural signals naturally contain nonlinear and Gaussian input
features.

In the Fig. S 3 we show the result of statistic test of Fig. S 2 Real iEEG (Top-Left): Both tests are
significant, indicating the presence of both nonlinear interactions and non-Gaussian characteristics in
the neural data. Linear Gaussian (Middle-Left): As expected for the null case, neither test is significant,
correctly identifying the signal as linear and Gaussian. Linear Non-Gaussian (Middle-Right): Only the
Gaussian test is significant, demonstrating the method's ability to isolate non-Gaussian properties in the
absence of nonlinearity. Nonlinear Gaussian (Bottom-Left): Only the linear test is significant, successfully
detecting nonlinear dynamics driven by Gaussian innovations. Nonlinear Non-Gaussian (Bottom-Right):
Both tests are significant, correctly identifying the joint presence of nonlinearity and non-Gaussianity.
Overall, this figure demonstrates how the combined use of maximum and median bicoherence statistics
provides a robust framework for disentangling the distinct contributions of nonlinearity and non-
Gaussianity in complex time series.

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*Fig. S 3. Statistical analysis of bicoherence for real and simulated time series. The figure displays the results of statistical tests*
*applied to the bicoherence of five different time series signals to distinguish between nonlinearity and non-Gaussianity. The five*
*cases are: (Top-left) Real intracranial EEG (iEEG) data; (Middle-left) A simulated linear Gaussian process; (Middle-right) A*
*simulated linear non-Gaussian process; (Bottom-left) A simulated nonlinear Gaussian process; and (Bottom-right) A simulated*
*nonlinear non-Gaussian process. Each subplot shows: Bicoherence Histogram (Light Blue): The distribution of the t-statistic*
*calculated from the empirical bicoherence values of the signal. Chi-square Distributions: The theoretical central chi-square*
*distribution with 2 degrees of freedom (blue line, $\chi^2(2)$ ), which is expected for a linear Gaussian process. A non-central chi-*
*square distribution (orange line) is fitted to the data, where the non-centrality parameter ($\lambda_0$) captures deviations from the null*
*hypothesis, related to non-Gaussianity. Statistic PDFs (Gray and Dark Red): The probability density functions for the 'Max' and*

The result shows that the bicoherence can be different even if the second-order spectrum is similar. In

the linear non-Gaussian scenario Fig. S 2iii, the data deviate from Gaussianity but do not exhibit intrinsic

nonlinear dependencies. This linear yet non-Gaussian structure typically manifests as a uniform or

"constant" offset in the bicoherence[72]. In other words, rather than showing localized peaks at specific

bifrequencies, the bicoherence tends to exhibit a more diffuse elevation across the entire frequency

domain. Conversely, the bicoherence in the nonlinear Gaussian scenario is limited to well-defined

regions (i.e., specific bifrequencies where nonlinearity introduces phase coupling), with otherwise

negligible values. This difference underscores that nonlinearity and non-Gaussianity can contribute

distinctly to the observed cross-frequency coupling patterns, helping to explain why the bicoherence in

the linear non-Gaussian simulation diverges markedly from that of real iEEG data.

We further fitted each case with our BiSCA model, which accurately reproduced both the power

spectral density and bicoherence for each scenario (rows of *d* and *e* in Fig. S 2). Notably, the model

faithfully recapitulated the real iEEG features, mirroring the 1/f-like spectral decay and the subtle,

significant cross-frequency interactions. These results highlight the model's capacity to disentangle and

reconstruct complex neural signals, shedding light on the interplay of Gaussianity and nonlinearity that

shapes iEEG dynamics.

**S.3.2 Simulation for the Geometric view of bicoherence**

The simulation of Fig. 2 shows the geometric point of view of the bicoherence. The simulation

employed an NNAR method to analyze nonlinear dynamics in intracranial iEEG data containing Wicket

wave. The pipeline began with preprocessing a 2-second iEEG segment (sampled at 200 Hz) from a

subject with normal variant activity. After reconstructing the phase space using a 23rd-order

embedding, the NNAR model was trained to capture the system's dynamics. A pruning step removed

non-equilibrium states, retaining only key dynamics with weighted contributions exceeding 1e-2.

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$$\mathcal{S} = \left\{ \boldsymbol{x}_k \mid \sum_{q=1}^{n_{eq}} w_k^{(q)} > \tau \right\}, \quad w_k^{(q)} = K_{h_k}(\| \boldsymbol{x}_k - \boldsymbol{x}_q^{eq} \|)$$

Deterministic and stochastic forecasts were generated using the pruned model. The deterministic

(noise free) simulation to show the 3D phase portrait skeleton visualization, spectrum and bicoherence

of this limit cycle. The stochastic forecasts with innovations modeled as Gaussian noise scaled by

residual covariance to obtain potential landscape of 2D state space. The system's geometry was

projected into 2D/3D state spaces via PCA of the high dimensional states set $\mathcal{S}$, and potential

landscapes were estimated using kernel density methods on 100×100 grids, this is a nonparametric

version of the landscape estimation[99]. Spectrum and bicoherence, was implemented also with

Multitaper estimators ($NW = 2.5$) across 300-sample windows with 75% overlap.

To contrast with the asymmetric dynamics, we simulated symmetric nonlinear oscillations by

enforcing the nonparametric state evolution function to satisfy $F(-\boldsymbol{x}) = -F(\boldsymbol{x})$, making the system

dynamics invariant under state inversion $(\mathbf{X} \rightarrow -\mathbf{X})$. The modified state evolution becomes:

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$$\tilde{\boldsymbol{x}}_{t+1} = \frac{F(\tilde{\boldsymbol{x}}_t) - F(-\tilde{\boldsymbol{x}}_t)}{2} + \tilde{\boldsymbol{u}}_t$$

where the averaging ensures cancellation of even-order nonlinearities.

The reconstructed phase portrait revealed a stable limit cycle (Fig. 2C), confirming the system's

oscillatory nature. The potential landscape exhibited asymmetric minima (Fig. 2I), explaining the spikes'

directional morphology. Spectral analysis showed harmonically related peaks at 8.7Hz and 17.4Hz (Fig.

2J), with total harmonic distortion (THD) -4.08dB. Bicoherence analysis demonstrated significant phase

coupling between fundamental and harmonic components (Fig. 2K), quantifying the nonlinear

interactions. The symmetric version of the system, depicted in subplot (B) to (F), provides a contrasting

perspective to the asymmetric case. Besides the symmetricity of the time domain analysis (B) to (D), the

spectrum shows it only has the odd order harmonics, therefore, the bicoherence shows zero

everywhere.

The asymmetric bicoherence profile (Fig. 2K) reflects directionally biased nonlinear interactions,

characteristic of depolarization-hyperpolarization asymmetry in the neuronal networks. The

reconstructed limit cycle (Fig. 2H) suggests possible self-sustaining oscillations stabilized by voltage-

gated ion channel dynamics during the sample time interval. The potential landscape's asymmetry (Fig.

2) aligns with the greater energy required for spike initiation versus termination, consistent with sodium

channel inactivation kinetics. The 9 Hz spectral peak corresponds to thalamocortical resonance

frequencies implicated in spike-wave generation. While the model successfully captured short-term

dynamics ($\tau$ < 100 ms), longer simulations showed phase drift, this could be introduced by the step of

pruning removed the activities shifted by the slow variables, the underlying attractor may not perfect

limit cycle but quasiperiodic or chaotic, suggesting the need for additional slow variables in future

extensions [100,101]. These analysis bridges the spectral domain nonlinear analysis with the time domain

evolution, providing a framework for quantifying stability landscapes in the nonlinear oscillations

The geometric interpretation of bicoherence provides critical insights into system dynamics. For an

asymmetric system (Fig. 2G-K), significant bicoherence between the fundamental frequency (8.7 Hz) and

its second harmonic (17.4 Hz) signifies quadratic phase coupling. This interlocking of phases constrains

the system's trajectory in phase space to a specific manifold, manifesting as an asymmetric "wicket"

waveform and a distorted limit cycle in the phase portrait. Conversely, for a symmetric system (Fig. 2B-

F), the bicoherence is zero, reflecting the absence of phase coupling. The system's trajectory is

unconstrained, resulting in a uniform limit cycle and a time-domain waveform with only odd-order

harmonics. This contrast highlights how bicoherence geometrically quantifies the degree of asymmetry

in the system's underlying potential landscape. Furthermore, bicoherence helps distinguish system-

based nonlinearity from non-Gaussian noise. In a nonlinear system, the energy landscape imposes state-

dependent constraints, suppressing noise-induced perturbations more effectively in regions with strong

recovery forces (e.g., steep potential wells). This state-specific "filtering" of non-Gaussian inputs reduces

the measured bicoherence compared to a linear system, where such perturbations propagate

homogeneously (Fig. 2). This distinction underscores the importance of modeling both system

nonlinearity and noise non-Gaussianity when interpreting higher-order spectral features.

The geometric interpretation of bicoherence reveals critical insights into the nonlinear dynamics of

the system, particularly in how phase coupling shapes its oscillatory behavior. In the asymmetric system,

the bicoherence plot (Fig. 2K) shows significant phase coupling between the fundamental frequency at

8.7 Hz and its second harmonic at 17.4 Hz, indicating quadratic nonlinear interactions that constrain the

system's trajectory in phase space to a manifold reflecting these phase-locked oscillations. This

interlocking of phases manifests as the asymmetric morphology in the time-domain waveform of the

Wicket (Fig. 2A), with the directional bias corresponding to imbalanced phase relationships. The

reconstructed phase portrait Fig. 2H) supports this, as these nonlinear constraints shape the stable limit

cycle's trajectory. Conversely, in the symmetric system, the bicoherence is zero everywhere (Fig. 2F),

aligning with the regular, balanced oscillations in the time domain (Fig. 2B) and the presence of only

odd-order harmonics (Fig. 2E). Here, the absence of phase coupling results in an unconstrained

trajectory in phase space, producing a more uniform limit cycle (Fig. 2C). This contrast highlights how

bicoherence geometrically quantifies the degree of nonlinearity and asymmetry in the system's

dynamics, linking spectral domain insights to the time-domain evolution and the underlying potential

landscape (Fig. 2D and Fig. 2I). These findings underscore the utility of bicoherence in analyzing stability

and morphology in nonlinear oscillatory systems, offering a framework to explore the interplay between

structure and dynamics.

## S.4 Goodness of fit

1111    To demonstrate how much variance can be explained by the model, here we put the cumulative

1112    density function of the $R^2$. In the formula defined in formula (13) and (15), the parameter $\{\mu_{\rho,k}\}$ has two

1113    options: 1) Harmonic fixed with the harmonic relationship of the "fundamental oscillation", 2) Free:

1114    initialize with spectrum and optimize the joint fit. We put the $R^2$ of both cases here.

1115

***Fig. S 4 Distributions of the coefficient of determination*** $R^2$ ***in three different conditions.*** *a) is the $R^2$ of the full model; b) is*
*the $R^2$ for the spectrum; c) is the $R^2$ for the bispectrum*

The $R^2$ distribution is calculated for the fit of each channel shown in the Fig. S 4. The goodness of fit

suggests that the model's goodness of fit varies considerably across the entire dataset. The "free" option

of the peak center fits with a greater degree of freedom. Therefore, its $R^2$ is concentrated on the right

side, compared to the "harmonic" organized center peak option. Some phenomena, such as split Alpha,

may not be described by the "harmonic" organized model.

Fig. S 4A shows a broad distribution of overall $R^2$ values, suggesting that the model's goodness of fit

varies considerably across the entire dataset. A noticeable upward trend toward higher $R^2$ (up to $\approx 1$)

indicates that many data segments exhibit strong fits, although a small portion remains at the lower end

of the scale. Since the variance of the spectrum and the variance of the bispectrum is quite different,

which also vary with subject the $R_S^2$ and $R_B^2$ are more intuitive. Fig. S 4B $R_S^2$ are comparatively narrower

near the high value but rise sharply toward $R_S^2 \approx 1$. This pattern implies that many single-subject

spectral fits are quite robust, with fewer cases in the middle range of goodness of fit. Fig. S 4C presents a

more bell-shaped distribution of baseline $R_B^2$ values. Most of these are clustered around moderate

goodness-of-fit levels $R_B^2 \approx 0.4 - 0.6$, with fewer instances at the extremes (near 0 or near 1). Overall,

bispectrum fits appear to be consistent but rarely reach near-perfect levels.

## S.5 Peak relation from the spectrum

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***Fig. S 5. the ratio of the peaks identified in the spectrum.*** *The left is from harmonized 1563 × 18 channels scalp EEG data. The*
*right is from 1771 channels of iEEG data.*

Besides integer harmonic peaks of periodic oscillations, other proportions between peak frequency

reveal possible quasi-periodic motion and chaotic; the distribution of the proportions showed possible

scale free of the organization of peaks. On the Exponent Scale, the slope is 2.2531 for EEG and 2.0493

for iEEG. However, metaphysical models attempt to impose intriguing physical interpretations on

empirical data without necessarily ensuring that these interpretations adhere to rigorous statistical or

biophysical validity. Evertz et al. (2022)[102] point out correctly that there is doubt that the aperiodic

component is either "scale-free" or a reflection of criticality. An alternative is to look at biophysical

models with effects of the extracellular space [103] as mentioned by Evertz et al. (2022)[102]. In addition to

interest and questions about the scale-free nature of $\xi$ process [104]. This question was discussed in

Valdés-Sosa et al. in 1999[98,105], when people argue that the EEG is chaos, the neural activity is a

nonlinear stochastic system driven by the noise. We reserve these possibilities, and these conclusions

still need to be verified by rigorous statistical methods. One possibility is that using the bicoherence in

this paper to study the relationship between the components is possible when all the ratios here are the

intermodulation combination of the integer peaks.

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