**Occupancy estimation of wild species in a palm oil plantation**

**using unstructured data**

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## Abstract

In 2020-2024, plantation workers at a large oil palm plantation in West Kalimantan recorded sightings of wild species of several species groups. They did not use a standardized field method and produced no comprehensive reports but recorded only one or a few species per visit. Such unstructured data are generally viewed as challenging for statistical analysis. Here, we used occupancy models to estimate what proportion of spatial units (both non-natural and forest) a given species occupied annually in the plantation. We tested models with different covariates for species for which most data were available: 13 birds, 3 reptiles and 7 mammals, among which the iconic Orangutan (*Pongo pygmaeus*). For each species, the model which best fitted the data was selected. Two shortcomings in our data complicated the analyses. First, occupancy models require detection and non-detection records, but because no fixed species lists were used, there is no unique way to generate non-detections. We generated non-detection records in several ways and ran the models again to evaluate the consequences for occupancy estimates. Second, imbalances in sampling may occur because of a lack of sampling design to select study sites. Most concerning are sites surveyed only once in 2020-2024. We ran the models without those sites to examine whether results were different. Although the shortcomings mentioned turned out not to distort our results, the occupancy estimates were imprecise for many study species because of low detection rates, and extra efforts are needed to improve that.

## Introduction

The expansion of oil palm (*Elaeis guineensis* Jacq.) plantations in tropical areas affects

wildlife negatively [1-3]. Over time, the palm oil industry has been increasingly willing to

mitigate the negative effects by taking protection and management measures. Examples are

setting aside areas with High Conservation Values (HCV-areas) which are protected against

illegal logging, burning and land-clearing [4] and the protection of "forest islands" within

plantations [5].

Effective biodiversity protection and management measures require detailed

knowledge about local wildlife, but collecting standardized data on many species by trained

field workers is usually not feasible in tropical areas [6]. Furthermore, protection and

management measures are more likely to succeed if there is considerable support among

plantation workers and other stakeholders. We believe that obtaining more data and

increasing support can go hand in hand by encouraging plantation workers and others to

collect sighting records of wild species.

For these two reasons, in 2019, the Indonesian oil palm company Austindo Nusantara

Jaya (ANJ) launched a special program, called PENDAKI — the Indonesian acronym for

Care for Biodiversity — to stimulate the recording of sightings of wild animals and plants by

plantation workers in their concessions [6]. One of these areas is the KAL ("Kayung Agro

Lestari") oil palm estate in West Kalimantan. This estate contains hundreds of production

blocks planted with oil palms and several small forest islands (total area 9583 ha; Fig 1). The

estate also includes several large HCV-areas (together 3,845 ha) with remnants of the original

tropical moist forest. Since 2019, many observers have participated in the program to collect

wildlife data, both in the planted areas and in the HCV-areas. To enable everyone to

participate, there are hardly any rules that observers must adhere to. For each sighting,

location (identity of production block or forest site), date and species must be noted, as well

as the number of individuals observed. Apart from this, there is no prescribed, standardized

field method and most of the records are casual sightings.

**Fig 1. Map of the KAL- estate in West Kalimantan, Indonesia using the Tropical Moist**
**Forest baseline data from EC JRC [7].**

To make these data usable for the management of plantations, the collected data need

to be converted into relevant information, such as local differences in occurrence of species or

in species diversity, which may then be related to environmental factors or management

practices. Unfortunately, retrieving reliable information from casual sightings is challenging.

Data as collected here are referred to in the scientific literature as unstructured or

opportunistic data [8, 9]. Such data are collected by volunteer observers in many countries

around the world and are also known as citizen science data [10].

Because the field method is unstandardized, it is difficult to determine whether the

difference in occurrence between two locations is real or due to one location being more

intensively surveyed than the other. For unstructured data, it is therefore mandatory to adjust

for variation in field effort. This is not an easy task, especially if there is no information at all

available about the field effort applied, as in the current study. It is difficult to derive

inferences on abundance of species from unstructured data [though see 11], but it is often

feasible to estimate occupancy, *i.e.*, the proportion of spatial units occupied by the species.

Analyses of unstructured data are particularly successful when occupancy models are used [8,

12-14]. But not all applications have been fruitful [9], and much depends on the dataset

available.

Our ultimate goal is to apply citizen science data with occupancy models on a routine

basis to support wildlife management in large plantations in tropical regions [6]. This is an

ambitious goal, and, as far as we know, we are the first to scientifically explore this. Here we

report on the first step towards that goal by examining the quality of the occupancy estimates.

The aim of this paper is to develop custom occupancy models for species living in an oil palm

plantation and to test whether several complications in the data might distort the results.

This study exemplifies the analysis of opportunistic data, an emerging field of

research. Globally, the number of opportunistic data records has increased significantly

through data portals such as iNaturalist (https://www.inaturalist.org), Online databases like

GBIF (https://www.gbif.org) and eBird (https://ebird.org) already contain many millions of

records and also cover a significant portion of historical data from museum collections and

protected nature areas. It is therefore expected that opportunistic citizen science data will play

an increasingly important role in biodiversity research, for example in assessments of Red

Lists of threatened species [15]. Applications can only be successful if the statistical

weaknesses of the data are considered, and fortunately, in recent years significant progress has

been made to address these issues [e.g., 11, 13, 16]. Most applications using unstructured data

concern temperate regions of the Northern Hemisphere; applications in tropical regions are

still scarce.

# Material and methods

## Inclusivity in global research

Additional information regarding the ethical, cultural, and scientific considerations specific to inclusivity in global research is included in the Supporting Information (S1 Checklist).

## Area and data

Defining the production blocks and forest sites in the KAL plantation area as our sampling sites, we distinguish 463 sites in the KAL-area, 21 of which are completely covered with forest. The latter are not only the large HCV areas mentioned earlier, but also smaller forest islands within the estate which are not in use for palm oil production (Fig 1). The other sites (from now on referred to as non-natural sites) are dominated by oil palms and infrastructure, but may also contain ponds, waterways and small patches of forest regrowth. The surface area of the non-natural sites is 30 ha on average but varies between sites (Fig 1). Most forest sites are considerably larger, especially the HCV-sites, which unfortunately could not be split into smaller subsites because sightings in the HCV-sites were not precisely localized.

More than 400 observers provided data. Observers were allowed to record any species group they wanted. But because most records cover five species groups only — namely birds, mammals, reptiles, higher plants (*i.e.*, only *Magnoliopsida*) and insects (mainly butterflies and dragonflies) — we focused on these groups, abandoning data on other groups. This is our standard dataset, in which records are available from 387 sites for the 2020-2024 period. For about 200 sites, annual records are available (Table 1). On average, sites were visited 6-8 times per year (see Nvisits per site in Table 1), often by different observers who typically

reported only one or a few species (rarely > 10) per visit (see List Length in Table 1). Some

sites were never surveyed; these are mainly situated in recent plantings at the western and

eastern border of the estate. Records of the same species on the same date and site collected

by different observers were deduplicated because these may refer to the same sighting as

observers are frequently in the field together.

**Table 1. Annual field effort in the KAL standard dataset. Nsites: number of sites with**

**observations, Nrecs: total number of presence records, Nvisits: mean number of visits**

**per site, List Length: mean number of all observed species per visit.**

| Year | Nsites | Nrecs | Nvisits | List Length |
|------|--------|-------|---------|-------------|
| 2020 | 191 | 3047 | 8.3 | 1.9 |
| 2021 | 232 | 4055 | 7.1 | 2.4 |
| 2022 | 139 | 4462 | 7.4 | 4.3 |
| 2023 | 185 | 3348 | 7.5 | 2.4 |
| 2024 | 269 | 2567 | 6.0 | 1.6 |

## Occupancy models

Occupancy models aim to estimate occupancy of a species while considering the detection

probability [14]. This means that a different detection probability of a species due to

differences in *e.g.,* field effort, observer experience or species abundance, does not translate

into a different occupancy estimate of the species [12]. This can be particular useful for

unstructured data because these models may still be able to properly estimate occupancy even

when no standardized field method has been used and no information about field effort is

available [8, 12, 13]. To be able to separate occupancy from detection, occupancy models

consist of two hierarchically coupled Generalized Linear Models (GLMs), one to describe the

true state of sites (presence or absence) and one to describe the detection in sites, given that

the species does occur [14].

The occupancy submodel estimates the annual proportion of occupied sites in the

statistical population represented by the sampled sites. We estimated annual occupancy using

a multi-season model for single species [17]. Our most comprehensive submodel is specified

as follows:

$z_{it} \sim$ Bernoulli($\psi_{it}$)                                                            [1]

logit($\psi_{it}$) = intercept + year + habitat of site + distance to large forest + site size          [2]

where $z_{it}$ is the estimated occupancy (0 or 1) and $\psi_{it}$ represents the occupancy probability of

the species in site $i$ and year $t$. This submodel includes covariates that describe the differences

in occupancy between sites: year, habitat of the site, distance of the site to large forest and site

size. Habitat of the site can be forest or non-forest; forest is taken when the site is a forest site

or a non-natural site with a forest patch. Distance to large forest represents the distance of the

center of a site to the nearest large forest areas; these are either forests around the estate or the

HCV-areas within the estate. Site size is included to adjust for variation in surface area of the

sites. Our main interest is in the annual occupancy estimates which we assessed for each

species by summing the estimated $z_i$ values over sites and year [finite sample occupancy; 14].

The detection submodel estimates detection per visit and the most comprehensive

model is specified as:

$y_{ijt} \sim$ Bernoulli($p_{ijt} \times z_{it}$)                                                    [3]

logit(detection) = intercept + list length + habitat of observation + observer          [4]

in which the observations $y_{ijt}$ indicate that the species was detected ($y_{ijt} = 1$) or not ($y_{ijt} = 0$) at

location $i$ during visit $j$ in year $t$. The observations are considered as the product of occupancy

$z_{it}$ and the probability $p_{ijt}$ of detecting the species in location $i$ during visit $j$ in year $t$. [14]. This

submodel includes covariates that describe the differences in detection between sites and

visits: list length, observer and habitat of observation. There are no year effects in this model

because data were too sparse to estimate reliable detection estimates which vary between the

years. Length of species lists per visit was used as covariate because we expected lower

detections in shorter lists. We did not apply list length categories [as in 8], but used list length

as a linear detection predictor. Habitat of the observation can be forest or non-forest; forest is

taken when the observation was in a forested part of a site; a species may be more difficult to

spot there. Observer identity was modelled as a random effect to take into account the

variation in detection between observers [18]. Estimating detection $p$ is only possible if

repeated visits are available for at least some sites [14]. The replicated visits need to be done

in a period of closure, meaning that the state of all locations (occupied or not occupied) has

not changed during the period between the visits. In contrast to studies using European data

[e.g., 8], we here consider an entire calendar year as the closure period, thereby assuming that

the study species reside in the area all year round. This does not necessarily mean that a

species is present in a site during the entire year, but rather that a species may use the site

year-round [14]. Our preliminary analyses showed no effect of Julian date on detection, so we

did not include Julian date as a covariate in the model.

Occupancy models require detection and non-detection records while our dataset only

contains presence records (detections) of five species groups. We created a non-detection

record for all species of these five groups not being observed during a field visit [8]. We ran

the models in a Bayesian framework using the R-package *spOccupancy* [19] in R v. 4.3.3

[20]. All quantitative covariates (distance to large forest, site size and list length) were

standardized to have mean 0 and standard deviation 1 [19]. *spOccupancy* allows accounting

for spatial autocorrelation of occupancy sites, which may be useful for our study area where

sites are adjacent to each other. Unfortunately, the large inaccuracy in the locations of

observations within the large HCV-sites made it impossible to apply a spatially explicit

model. With the covariate distance-to-large-forest, however, we included a variable in the

model describing spatial gradients in the study area.

More than 300 different species of the five species groups were reported in 2020-2024,

but for most of them too few presence records had been collected to allow statistical analysis.

Models were only run for species with at least five presence records each year and more than

150 records in total. These were 23 species: 13 birds, 7 mammals and 3 reptiles. To find the

model which best fitted the data, we ran 18 different models per species. In these models, one

or several covariates were omitted from the model described by [2] and [4] (see S2 Table for

an overview of the 18 models). The model with the lowest value of the Widely Applicable

Information Criterion (WAIC) was considered the best model [19]. For these top models we

performed posterior predictive checks to compute Bayesian *p*-values as a measure of model

fit. More specific, following the recommendation of Doser & Kéry [21], we used both the

Freeman-Tukey statistic and the Chi-Square statistic, and grouped the data across sites as well

as across replicates. Ideally, each Bayesian *p*-value is around 0.5.

We adopted the default priors of *spOccupancy* and ran the models with three parallel

Markov chains of 60,000 iterations each, discarding the first 50,000 as burn-in and a thinning

rate of 10. A parameter was considered significant when the 95% Bayesian credible interval

(CRI) of the posterior sample of a parameter did not include 0. The standard deviation of the

sample from the posterior distribution of parameter was interpreted as standard error of that

parameter.

## Alternative datasets

We created several alternative datasets to study the effect of two complications in the data and

applied the same 18 models as for the standard dataset. Firstly, observers did not make

complete checklists of species groups, nor did they use a fixed list of species to consider.

Consequently, there is no unique way to generate non-detection records. If an observer only

noticed, say, plant species, and ignored any sighting of the other four species groups, non-

detections generated for other species groups are not justified. To examine if this affects

occupancy estimates, we created three alternative datasets differing in the way non-detections

were created: (1) we filtered data from the three most often reported groups (birds, mammals

and reptiles) and discarded records from higher plants and insects. This implies that we

generated non-detections for our 23 study species only from sightings of birds, mammals and

reptiles and no longer from plants and insects, (2) in addition to using only data from these

three species groups, we included only observers with records of the same species group as

the study species. So, if the study species were a mammal, only sightings of observers

reporting mammals were used to generate non-detections and the same goes for birds and

reptiles; (3) in addition to using data from three species groups, we included only observers

who had recorded all three species groups, thereby further reducing the number of observers

(Table 2). The three extra datasets are called (1) Nondet3grp, (2) Nondet3grp+obs1grp and

(3) Nondet3grp+obs3grp and occupancy results were compared with those of the standard

dataset. All filtering actions reduced the number of non-detections, and to a lesser extent also

the number of detections (Table 2).

**Table 2. Properties of datasets per species obtained under different procedures (see text**

**for explanation). Nsites: number of sites with observations, Nvisits: mean number of**

**visits per site, List Length: mean number of all observed species per visit, Nobservers:**

**number of observers, Ndetect. and Nnon-detect.: mean number of detection and non-**

**detection records of the 23 study species.**

| Dataset | Nsites | Nvisits | List Length | Nobservers | N detect. | Nnon-detect. |
|---|---|---|---|---|---|---|
| Standard data | 387 | 7.2 | 2.4 | 372 | 534 | 6757 |
| Nondet3grp | 386 | 7.0 | 2.2 | 367 | 534 | 6499 |
| Nondet3grp+obs1grp | 382 | 7.1 | 2.3 | 255 | 534 | 6336 |
| Nondet3grp+obs3grp | 374 | 7.2 | 2.3 | 132 | 512 | 6135 |
| Remove_sites1year | 279 | 7.8 | 2.4 | 365 | 523 | 6570 |
| Remove_sites2024 | 340 | 7.4 | 2.4 | 370 | 530 | 6681 |

Secondly, unstructured data as our dataset not only lack a standardized field method

but also have no sampling design to properly select study sites. In our case, forest sites and

non-natural sites surrounding forest sites have been oversampled, so the measurements might

not be representatives for the entire estate [22]. On the other hand, data came from almost the

entire area, which does not suggest obvious spatial bias. There is, however, an imbalance in

sampling which we are concerned about: 108 sites (28% of all 387 sites) have only been

surveyed in one year, most frequent in 2024. If the differences in occupancy between 2020

and 2024 would depend on the sites that were surveyed only once, then we have no

convincing evidence of a change. To check this, we created two more datasets: one in which

all sites surveyed in one year only were deleted (Remove_sites1year) and one in which sites

visited only in 2024 were deleted (Remove_sites2024), and compared annual occupancies.

Obviously, these two datasets contain fewer sites than the standard dataset (Table 2).

# Results

## Standard dataset

Almost all models applied to the standard dataset converged according to the Gelman-Rubin

Rhat statistic (Rhat < 1.1). Only nine out of 414 models (18 different models * 23 species) did

not converge in all parameters, most frequently not in case of *Spilornis cheela,* a bird of prey

species. The top model according to the WAIC-value varied between species (Table 3). For

several species, the most comprehensive model (model 1 in S2 Table) fitted best, for example

in case of *Hylobates albibarbis* (Gibbon) and *P. pygmaeus*. For other species, simpler models

performed better, *e.g.*, for *Liopeltis tricolor*, a snake species. The top model for the latter

species contained only effects of site size, species list length and observer and no ecological

variables at all. The Bayesian *p*-values produced by three out of the four tests for the top

models were mostly between 0.2-0.75, suggesting a reasonable fit. But for half of the species

*p*-values < 0.2 were obtained according to the Freeman-Tukey test when data were grouped

across sites (Table 3).

**Table 3. Detection parameter estimates under the top model per species. See S2 Table**

**for the meaning of model IDs. Bayesian *p*-values are a measure of model fit according to**

**the Freeman-Tukey statistic with data grouped by sites [21]. *p* is mean detection**

**probability in 2020-2024 (± se), *i.e.,* the backtransformed intercept as specified in**

**formula [4]. Coefficients of list length, habitat of observation and observer are on the**

**logit scale. No entry indicates that the covariate is not included in the model. Asterisks**

**refer to significant differences from zero, derived from 95% credible intervals.**

| Species | Model ID | Bayesian p-value | p (detection) | List Length | Habitat of observation | Observer |
|---|---|---|---|---|---|---|
| *Birds* | | | | | | |
| *Acridotheres javanicus* | 8 | 0.32 | 0.08 ± 0.01 | 0.69 * | -1.25 * | 1.00 * |
| *Alcedo meninting* | 1 | 0.07 | 0.02 ± 0.01 | 0.73 * | -0.4 * | 3.33 * |
| *Amaurornis phoenicurus* | 8 | 0.11 | 0.09 ± 0.01 | 0.67 * | -1.59 * | 0.77 * |
| *Anthracoceros malayanus* | 10 | 0.16 | 0.03 ± 0.01 | 0.48 * | | 1.23 * |
| *Centropus sinensis* | 8 | 0.34 | 0.17 ± 0.01 | 0.63 * | -0.63 * | 0.37 * |
| *Corvus enca* | 13 | 0.27 | 0.02 ± 0.01 | 0.46 * | | 2.14 * |
| *Egretta garzetta* | 1 | 0.18 | 0.07 ± 0.01 | 0.49 * | -0.98 * | 1.25 * |
| *Elanus caeruleus* | 12 | 0.10 | 0.06 ± 0.01 | 0.6 * | | 1.24 * |
| *Gracula religiosa* | 1 | 0.08 | 0.06 ± 0.01 | 0.46 * | -0.59 * | 0.51 * |
| *Halcyon smyrnensis* | 14 | 0.51 | 0.06 ± 0.01 | 0.69 * | -1.02 * | 1.31 * |
| *Hirundo tahitica* | 11 | 0.38 | 0.02 ± 0.01 | 0.41 * | -1.43 * | 2.01 * |
| *Spilopelia chinensis* | 11 | 0.19 | 0.14 ± 0.01 | 0.59 * | -1.15 * | 0.38 * |
| *Spilornis cheela* | 13 | 0.28 | 0.01 ± 0.01 | 0.67 * | | 2.69 * |
| *Reptiles* | | | | | | |
| *Liopeltis tricolor* | 15 | 0.31 | 0.01 ± 0.01 | 0.7 * | | 2.14 * |
| *Malayopython reticulatus* | 2 | 0.37 | 0.05 ± 0.02 | 0.49 * | -1.37 * | 3.10 * |
| *Varanus salvator* | 14 | 0.17 | 0.26 ± 0.02 | 0.86 * | -0.31 * | 0.67 * |

| Mammals (rodents) | | | | | | |
|---|---|---|---|---|---|---|
| *Callosciurus notatus* | 7 | 0.61 | 0.04 ± 0.01 | 0.65 * | | 0.78 * |
| *Callosciurus prevostii* | 3 | 0.23 | 0.02 ± 0.01 | 0.54 * | 0.39 * | 1.35 * |
| *Nannosciurus melanotis* | 1 | 0.03 | 0.05 ± 0.01 | 0.57 * | -0.39 * | 1.72 * |
| **Mammals (monkeys)** | | | | | | |
| *Hylobates albibarbis* | 1 | 0.06 | 0.04 ± 0.01 | 0.47 * | 1.22 * | 2.20 * |
| *Macaca fascicularis* | 7 | 0.01 | 0.16 ± 0.02 | 0.59 * | | 1.56 * |
| *Macaca nemestrina* | 1 | 0.02 | 0.07 ± 0.01 | 0.57 * | 0.37 * | 1.31 * |
| *Pongo pygmaeus* | 1 | 0.08 | 0.06 ± 0.02 | 0.55 * | 0.99 * | 2.93 * |

Detection probability varied between species, with *Varanus salvator* (a large monitor

lizard) having the highest rate of 0.26 (Table 3). This means that *V. salvator* has been reported

during one-quarter of the visits to occupied sites. Here, a visit stands for a single visit of an

average observer collecting a species list of mean length outside forest habitat. For most

species detection is low, frequently even below 0.1 (Table 3). Detection increased with longer

species lists (Table 3; see example in Fig 2A). In line with our expectation, many species

appeared to be less visible in forest habitat, such as *Centropus sinensis*, a cuckoo species

(Table 3), although this may also be because these species spend less time in forest habitat. In

contrast some others were better detectable in forest habitat or spend more time in forest

habitat, *e.g.*, *Macaca nemestrina* (a monkey species). Furthermore, observer effects were

relevant for all species, as we already suspected. Models without observer effects consistently

finished low in the model selection.

**Fig 2. Relationship between (A) expected detection (± credible intervals) of *Varanus***

***salvator* and the number of species observed during a visit and (B) between expected**

**occupancy of *Hylobates albibarbis* and distance to large forest.**

Mean probability of occupancy of *V. salvator* is 0.97 (Table 4), suggesting that this

species makes use of nearly the entire study area. *P. pygmaeus*, for example, has a much

lower mean occupancy of 0.26. Several species benefitted from the availability of forest

habitat in the site including *M. nemestrina*, *Macaca fascicularis* and *P. pygmaeus* (Table 4).

Furthermore, the distance to the nearest large forest affected the occupancy probability for

about half of the species. Not surprisingly, *H. albibarbis* had a significantly higher occupancy

in sites with forest habitat and in the vicinity of large forest areas (Table 4; Fig 2B), and the

same applies to *P. pygmaeus*. Some other species, however, achieved their highest occupancy

rate further away from the large forest, *e.g.*, *Spilopelia chinensis*, a dove species. For almost

all species, occupancy was higher in larger sites (Table 4). Fig 3 shows examples of annual

occupancy, for *P. pygmaeus* and *Amaurornis phoenicurus* (a waterbird species).

**Table 4. Occupancy parameter estimates under the top model per species (see table 3 for**

**model ID's). $\psi$ is the mean finite sample annual occupancy, averaged over 2020-2024.**

**SE is the standard error of annual occupancy, also averaged over 2020-2024.**

**Coefficients of habitat of site, distance to forest and site size are on the logit scale. No**

**entry indicates that the covariate is not included in the model. Asterisks refer to**

**significant differences from zero, derived from 95% credible intervals.**

| Species | $\psi$ | SE | Habitat of site | Distance to forest | Site size |
|---------|--------|----|-----------------|--------------------|-----------| 
| *Birds* | | | | | |

| | | | | | |
|---|---|---|---|---|---|
| *Acridotheres javanicus* | 0.65 | 0.09 | | | 1.83 * |
| *Alcedo meninting* | 0.83 | 0.07 | -1.21 | 0.45 * | 1.34 * |
| *Amaurornis phoenicurus* | 0.84 | 0.06 | | | 1.21 |
| *Anthracoceros malayanus* | 0.53 | 0.12 | 1.11 | -0.61 * | |
| *Centropus sinensis* | 0.84 | 0.05 | | | 1.71 * |
| *Corvus enca* | 0.30 | 0.11 | 0.99 | | 2.04 * |
| *Egretta garzetta* | 0.69 | 0.08 | -0.40 | 0.44 * | 2.28 * |
| *Elanus caeruleus* | 0.55 | 0.08 | | -0.64 * | 1.42 * |
| *Gracula religiosa* | 0.24 | 0.07 | 1.47 * | -0.38 | 2.14 * |
| *Halcyon smyrnensis* | 0.57 | 0.09 | | | |
| *Hirundo tahitica* | 0.59 | 0.09 | | 0.3 | |
| *Spilopelia chinensis* | 0.90 | 0.05 | | 1.15 * | |
| *Spilornis cheela* | 0.52 | 0.18 | 2.00 * | | |
| *Reptiles* | | | | | |
| *Liopeltis tricolor* | 0.41 | 0.12 | | | 2.23 * |
| *Malayopython reticulatus* | 0.38 | 0.10 | | -0.44 * | 2.02 * |
| *Varanus salvator* | 0.97 | 0.02 | | | 1.83 * |
| *Mammals (rodents)* | | | | | |
| *Callosciurus notatus* | 0.48 | 0.09 | 0.64 | -0.66 * | 1.55 * |
| *Callosciurus prevostii* | 0.63 | 0.14 | 1.22 | | 1.63 * |
| *Nannosciurus melanotis* | 0.33 | 0.07 | 1.47 * | -0.31 | 2.05 * |
| *Mammals (monkeys)* | | | | | |
| *Hylobates albibarbis* | 0.33 | 0.08 | 1.33 * | -1.22 * | 1.53 * |
| *Macaca fascicularis* | 0.39 | 0.05 | 1.61 * | -0.58 * | 1.69 * |
| *Macaca nemestrina* | 0.47 | 0.09 | 1.10 * | -0.89 * | 1.56 * |
| *Pongo pygmaeus* | 0.26 | 0.07 | 1.22 * | -0.59 * | 2.08 * |

**Fig 3. Annual occupancy (± se) of (A) *Pongo pygmaeus* and (B) *Amaurornis phoenicurus*.**

**Alternative datasets**

The models converged somewhat less often in the alternative datasets than in the standard

dataset. To enable comparisons between datasets, we did not delete any of the species from

the results. Often but not always in the alternative dataset, the same model was selected as top

model as in the standard set (S3 Table). Mean detection in 2020-2024 derived from the three

datasets with alternative procedures to generate non-detections was significantly higher than

when based on the standard dataset (Fig 4A; paired t-tests; P<0.05; n=23). This is not

unexpected because the three alternative datasets all have fewer non-detection records than

the standard data (Table 2). Mean occupancy estimates in 2020-2024, however, did not differ

between those derived from the standard dataset and those based on the three alternative

datasets (Fig 4B; paired t-tests; P>0.05; n=23). Thus, the occupancy estimates do not appear

to depend on the exact way non-detections were generated.

**Fig 4. (A) Mean detection (± se; backtransformed intercept; see text) and (B) mean**

**occupancy (± SE) in 2020-2024 of 23 species. Each bar represents a different dataset.**

**Asterisk indicates significant difference with standard dataset (paired t-test; P <0.05; n=**

**23).**

The two datasets for studying the removal of poorly surveyed sites produced similar

detection and occupancy estimates as found for the standard dataset (Fig 4 A & B; paired t-

test; P>0.05; n=23). Also, differences between 2020 and 2024 derived from these datasets

were strongly correlated with those based on the standard dataset (Pearson's r > 0.99; P

<0.01; n=23).

# Discussion

Many researchers have pointed out the downsides of the collection and analysis of

unstructured data: bias when field effort is not taken into account, spatial bias due to lack of

sampling design, low detection when field efforts are limited and uncertainty about non-

detections when it is not sure which species are being considered [e.g., 16, 23]. In some

citizen science projects, these shortcomings are reduced by discouraging the collection of

casual records and instead focusing on complete checklists, *i.e.*, lists of all species observed

and identified by a participant at a particular time and place [e.g., eBird, see 24]. This

provides more clarity about non-detections, and higher detection probabilities. If more

information about the observation process is provided, for example time spent or length of

route during the visit, there are more opportunities in statistical analyses to adjust for field

effort [25, 26]. With a smartphone app such information may be generated automatically [16].

The collection of data in the KAL area is slowly moving in this direction. A subgroup

of observers has recently been selected to use a fixed list of species which should be recorded

when observed [6]. The hope is that this will lead to longer species lists. This group will work

with a smartphone app that can record the spatial coordinates of each observation, which

makes it possible to derive field efforts to some extent. The availability of spatial coordinates

makes it possible to localize observations on a small scale afterwards. This will solve one of

the obvious shortcomings of the current KAL data, namely the overly large forest sites.

Yet, it is not the intention to limit data collection to fixed lists only. On the contrary,

the idea remains to encourage as many workers as possible to participate in data collection, to

promote awareness about and involvement in the protection of biodiversity. There may still be

considerable potential, because there are many observers who contributed only a few records

so far. That leaves us little choice but to deal with all shortcomings of the data. We have

shown that the occupancy estimates were unaffected by the way non-detection records were

generated. The fact that many records were collected by a relatively small group of dedicated

observers can partly explain this, as they collected records from all five groups. We also

showed that visiting sites only once did not influence the results. It is encouraging that the

models yielded meaningful relationships between occupancy and distance to large forest and

forest habitat preference. These relationships confirm existing knowledge [e.g., 27, 28],

thereby enhancing confidence in the usefulness of the data being collected in the KAL estate.

With longer time series data, it may be interesting to study whether these relationships are

changing over time. An increase in occurrence further away from large forest areas may

indicate greater use of non-natural sites and/or higher permeability of the plantation. Such

changes have been demonstrated for orangutans in Malaysian oil palm who increasingly make

use of oil palm areas around forest fragments [29].

But methodological problems remain, the biggest one being the short species lists in

our data (Table 1). This leads to the generation of many non-detections (one for each species

not observed) which induces low detection rates per visit. Although there are quite a few

replicated visits per site (Table 1), these do not fully compensate for the low detection, and

the result is that occupancy estimates for many species are far from precise [14]. Using

simulation data, Kery & Royle [30; p. 588] showed that the precision of the occupancy

estimates becomes low when $p$ is less than about 0.1-0.2. Most of our species have detection

rates $< 0.2$ and indeed, annual occupancy estimates are quite imprecise, with standard errors

of annual occupancy $> 0.05$ or even $> 0.1$ (Table 4). To improve this, more data are needed,

preferably in the form of longer species lists. Another problem is that model fit was not yet

sufficient for all species, which contributes to the uncertainty of inferences. The lack-of-fit

test revealed that spatial variation in occupancy and detection is not yet adequately modeled

for a number of species [Table 3; 21]. Model fit might be enhanced by including more

adequate covariates as well as spatial autocorrelation in the model. With more annual data it

also becomes more feasible to include year-dependent detection estimation. So far, we

assumed detection probability was equal in all five years. But it is better to consider potential

changes in detection, for example because of increasing average skill of observers [12].

In conclusion, although we have made progress in model development and solved

several data complications, the quality of the occupancy estimates is not yet sufficient to be

useful for the nature management of the plantation. More data is needed to obtain more

precise occupancy estimates for the 23 study species and for additional species. More data

will also make spatially more refined applications feasible. We are confident that we will

achieve this in the long run.

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# Supporting information

**S1. Inclusivity in global research**

**S2 Table. Overview of models. Model 1 is the most comprehensive model described in**

**the main text. The others are models in which one or more covariates have been omitted.**

**No entry indicates that the covariate is not included in the model.**

**S3 Table. Top model per species per dataset according to WAIC. See S2 Table for the**

**meaning of model IDs.**