Mechanical conditions preventing live cell extrusion during primary neurulation in amniotes

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Highlights:

- PMA treatment induces live apical cell extrusion in the chick embryo neural plate
- Our energy-based vertex model mechanically simulates a pseudostratified epithelium
- Higher apical/basal compared to lateral surface tension lead to epithelial stability
- Lower apical/basal surface tension lead to epithelial instability and cell extrusion
- A power law between cell density and surface tension defines the stability threshold

Abstract

During primary neurulation in amniote embryos, the neural plate gives rise to the neural tube in a process requiring the coordination of forces at different scales throughout a geometrically complex tissue. The ways in which this process fails inform us of the complex mechanical conditions required for its correct completion. Previous results showed that the functional disruption of MARCKS, a protein which simultaneously interacts with the plasma membrane and actin filaments, resulted in neural tube closure defects with apical cell extrusion. Here, we show that this is an example of "live cell extrusion", wherein extruded cells are not undergoing apoptosis. This suggests that extrusion in this case might be due to a mechanical instability in the neural plate. Using an expanded energy-based vertex model of pseudostratified epithelia we then show that extrusion may be elicited by a reduction in the relative surface tension of apical and basal interfaces with respect to cell-cell interfaces. Finally, by considering a continuum description of a simplified epithelium we derive an approximate quantitative threshold for single-layered epithelial stability in the form of a power law relating cell density to the relative value of interfacial surface tensions. Our work serves to explain an example of how alterations in polarization and forces at the single-cell level can produce tissue-scale instabilities which not only greatly alter its morphology but can also ultimately lead to severe developmental defects.

1. Introduction

In vertebrates, the central nervous system almost entirely derives from a specialization at the dorsal ectoderm, termed the neural plate, an epithelium that eventually deforms to ingress into the embryo as a whole and forms the neural tube. Particularly in amniotes, this "primary neurulation" process involves the invagination and folding of the neuroepithelium along the cephalo-caudal axis of the embryo to become a tube separated from the epidermal ectoderm that remains at the surface. The series of morphogenetic movements that drive neurulation arise from intrinsic and extrinsic forces exerted over the neuroepithelial cells, which all along the process remain cohesive and highly polarized (Colas and Schoenwolf, 2001; de Goederen et al., 2022). The intrinsic forces deforming the neural plate are generated at different levels, including actions mediated by the cytoskeleton. In addition, forces extended along several cells in the neural plate, such as those generated by convergent-extension movements (Schoenwolf and Smith, 1990), or coming from the surrounding non-neural ectoderm (Alvarez and Schoenwolf, 1992; Moury and Schoenwolf, 1995), could contribute to bending. In this regard, the early work by Lee and Nagele has indicated that neural plate-intrinsic forces would be sufficient for the formation of the neural tube in chick embryo explants (Lee and Nagele, 1988).

All these forces are applied to cells that, in addition, greatly increase their proliferation rate from the neural plate stage on, becoming a quickly growing population (Copp and Greene, 2010). Cells remain attached to both apical and basal surfaces, but they increase their height and reduce their width, generating a tall pseudostratified epithelium. In this organization, cells display interkinetic nuclear migration (INM), by which cell divisions occur at the apical border of the neuroepithelium, while S-phase tends to occur in nuclei closer to the basal side (Norden, 2017; Sauer, 1936). The combination of all these factors results in neuroepithelial cells with extremely complex shapes (Gómez et al., 2021; Iber and Vetter, 2022).

How is it possible that this epithelial cell population tolerates the enormous forces that drive neurulation while proliferating at a high rate, without disruption? Different lines of evidence indicate that the key might be in the strict maintenance of apico-basal cell polarity. Among other factors, this is achieved through a tight binding of each cell to the basal lamina on the basal side, and to their neighboring cells at the sub-apical border through integrin- and cadherin-based cell adhesions, respectively (Saade and Martí, 2025). These adhesion complexes tightly, but dynamically, bind to the cytoskeleton, establishing a mechanically

continuous meshwork that spans across cells, and that can be modulated in response to different external and internal cues (Campàs et al., 2024; Sluysmans et al., 2017; Zhang and Wei, 2025).

It has been generally accepted that microtubules extend, elongating cells along the apico-basal axis, while the actin cytoskeleton acts in different ways, allowing cells to take a wedge-like shape (Cearns et al., 2016; Schoenwolf and Powers, 1987). The maximal accumulation of actin filaments is observed close to the apical cell border, in association with the cadherin-based zonula adherens, and acto-myosin contraction at this level has been indicated as an important motor in apical surface reduction (Ampartzidis et al., 2023; Escuin et al., 2015; Martin and Goldstein, 2014; Sawyer et al., 2011). This apical constriction would be more relevant in highly-bent areas of the neural plate, when they exist, such as the ventromedial and the dorso-lateral hinges. Here, other cell processes, like basal positioning of nuclei and localized programmed cell death were also shown to contribute to epithelial bending, highlighting the importance of regulating cell crowding during neurulation (Roellig et al., 2022; Smith and Schoenwolf, 1988).

It is not surprising, then, that several polarized actin-modulating proteins have been demonstrated to be necessary for primary neurulation. Among these are the MARCKS family members. MARCKS (Myristoylated Alanine Rich C-Kinase Substrate) and MARCKS-Like 1 are ubiquitous proteins present only in vertebrates, which simultaneously interact with the plasma membrane and actin filaments (Arbuzova et al., 2002; El Amri et al., 2018). Phosphorylation by PKC (or interaction with calcium-calmodulin) causes MARCKS to detach from the membrane and to lose one of the two actin-binding sites (McLaughlin and Aderem, 1995). Hence, MARCKS acts as a molecular switch connecting extracellular signals to the cell cortex. Disruption of MARCKS family protein expression causes severe neurulation defects in both mice and zebrafish embryos (Chen et al., 1996; Prieto and Zolessi, 2017; Stumpo et al., 1995). Further, we found that MARCKS is accumulated at the apical membrane in neural plate cells of the chick embryo only during neural tube closure, and that its knockdown causes a failure of neural tube closure (Aparicio et al., 2018; Zolessi and Arruti, 2001). Interestingly, the local cellular phenotype observed in these embryos was very similar to the effect obtained after treatment with a strong agonist of PKC, the phorbol ester PMA: loss of apico-basal cell polarity accompanied by apical cell extrusion. This effect of PMA was effectively rescued by

the expression of a non-phosphorylatable form of MARCKS, where all serines at the ED were substituted by asparagines (Aparicio et al., 2018).

Apical cell extrusion, that is, the expulsion of a cell through the apical side of the epithelium, has been generally reported as an active mechanism for maintaining epithelial density and integrity, and involves biochemical and mechanical signaling such as the secretion of sphingosine-1-phosphate (S1P) by extruding cells, which activates Rho and actomyosin in neighboring cells (Eisenhoffer and Rosenblatt, 2013; Nanavati et al., 2020). One function of this process is the elimination of dying cells from the epithelium ("apoptotic cell extrusion"; Villars and Levayer, 2022), and implies medium-scale epithelial topological irregularities, pulsatile contractions and loss of tissue tension (Atieh et al., 2021; Saw et al., 2017), together with the local activation of lamellipodial protrusions and the assembly of a basally-localized contractile actomyosin ring, in a cadherin-dependent manner (Duszyc et al., 2021; Lubkov and Bar-Sagi, 2014; Rosenblatt et al., 2001). Conversely, "live apical cell extrusion" appears as a counterbalancing mechanism to avoid cell overcrowding in a proliferating cell population, and occurs regularly in many physiological processes of epithelia, like in cell shedding in intestinal microvilli and in the control of carcinogenic transformation (Madara, 1990; Tanimura and Fujita, 2020). It requires stretch-activated ion channels (Piezo), S1P and the Rho-myosin pathway, and also produces regular topological changes in the organization of the epithelium, based on the collective action of surrounding cells (Eisenhoffer et al., 2012). During this type of extrusion, the cell being expelled remains alive and plays an active part in the process, eventually dying by anoikis after the extrusion has been completed (Marinari et al., 2012; Slattum and Rosenblatt, 2014).

Taking all this information, we wondered if apical cell extrusion of neuroepithelial cells upon MARCKS knockdown or PKC activation could be a live cell extrusion mechanism related to an imbalance in the mechanical forces in the cell population. This could be caused either by the alteration of the actin cytoskeleton or by the downregulation of apico-basal cell polarity. By pharmacologically inhibiting caspase activity on PMA-treated chick neurulas, we demonstrate here that the observed massive apical cell extrusion is mediated by a live mechanism. Secondly, we aimed at explaining the experimental observations by generating a theoretical model and performing computational simulations. We present an expanded 2D vertex model of a pseudostratified epithelium, to show that alterations in the balance of forces imposed to

cells on the apical or basal plasma membrane domains compared to lateral domains, was enough to robustly obtain situations that could only be solved by massive cell extrusion.

2. Methods

2.1. Embryo culture

Wildtype chicken eggs were provided by a local producer (PRODHIN) and incubated at 37° C for at least 28 h, corresponding to stage HH 8 (Hamburger and Hamilton, 1951). Chick embryos were cultivated *ex ovo* with ventral side up over a semi-solid agar/albumen substrate in 35 mm Petri dishes using the EC culture technique (Chapman et al., 2001). Cultured embryos corresponding to stages lower than HH8-/8 were incubated until they reached the desired stage. A total of 72 embryos were processed, spread across five experiments.

2.2. Pharmacological treatments

Cultured embryos were divided into four groups according to treatment: those receiving treatment with PMA, QVD-OPh, neither (control) or both (double, PMA+QVD). Stock solutions were prepared for PMA (Sigma-Aldrich P-8139) at 5 mM and QVD-OPh (MedChem Express #HY-12305) at 20 mM, both diluted in 100% DMSO.

All embryos were pre-incubated for 30 min. at 37° C with a 20 µl drop containing either 0,83 % DMSO in 1x PBS (control and PMA) or 167 µM QVD-OPh (1:120 dilution; QVD-OPh and double), applied ventrally. Afterwards, the excess liquid was removed and embryos were moved to a new culture dish containing 0.93% DMSO (control), 5 µM PMA (1:1000 dilution) and 0.83% DMSO (PMA), 167 µM QVD-OPh and 0.1% DMSO (QVD-OPh) or PMA and QVD-OPh (double) embedded in the substrate. Additionally, a new 20 µl droplet containing either DMSO or QVD-OPh was applied as before. Embryos were then incubated for 3 h at 37° C.

2.3. Cryo-sections

After incubation, embryos were collected and fixed in 4% paraformaldehyde (PFA, in 1x PBS) at 4° C overnight. Excess tissue was then cut and excess PFA was removed by washing 3x with 1x PBS for 1 h. Embryos were cryoprotected by being incubated first in a 5% sucrose/PBS for 3 h and then in a 20 % sucrose/PBS solution at 4° C overnight, and were then embedded in a

medium containing 7.5 % gelatin and 15 % sucrose dissolved in PBS, in a 35 mm Petri dish. Gelatin was left to set at room temperature and then stored at 4° C for up to a few days. Blocks were cut from these media and frozen using liquid nitrogen. 10 µm transversal slices were cut from these blocks using a cryostat (Reichert-Jung Cryocut E) at -21° C and placed onto gelatinized microscope slides (0.5 % gelatin, 0.05% chrome alum in water).

2.4. Immunofluorescence

Indirect immunofluorescence on the slices was performed following (Stern and Holland, 1993). All antibodies were diluted in a 1 % BSA/PBS solution. Primary antibodies used were rabbit anti-MARCKS (1:1000, Toledo et al., 2013), rabbit anti-cleaved Caspase 3 (1:200, Cell Signaling Technologies #9661), rabbit anti-ɣ tubulin (1:100, Sigma-Aldrich #T5192) and mouse anti-ZO-1 (1:50, Invitrogen #33-9100). Secondary antibodies used were anti-rabbit Alexa 488 (1:500, Invitrogen #A21206) and anti-mouse Alexa 488 (Invitrogen #A11001). Phalloidin-TRITC (1:8000-10000, Sigma) was included during the incubation with secondary antibodies. Hoechst 33342 DNA staining was performed during the final PBS washes.

2.5. Image Acquisition and processing

Slices were mounted for imaging using 70 % glycerol in Tris buffer (20 mM, pH 8), covered with a coverslip and sealed using nail polish. Imaging was performed on a confocal Zeiss LSM 800 microscope using a 20x (dry, NA = 0.8) or 25x (glycerol immersion, NA = 0.8) objective lens. Images consisted of stacks of optical sections every 1 µm, in slices corresponding approximately to the fourth somite. Image processing and analysis was done using FIJI (Schindelin et al., 2012).

2.6. Cell extrusion and cell death quantification

In order to determine the number of embryos exhibiting cell extrusion and indications of cell death (pyknotic nuclei and cleavage of caspase 3), mounted slices were examined under a Nikon Microphot FXA epifluorescence microscope, using 20x (dry, NA = 0.75) and 40x (dry, NA = 0.95) objective lenses. Extruded cells were identified as lying apical to the actin accumulation line corresponding to the apical side of the neuroepithelium in normal

conditions, occasionally checking nuclear staining for confirmation. In order to determine that an embryo had not experienced any cell extrusion, four different nearby slices were checked. Counting of pyknotic nuclei and cells showing cleaved caspase 3 (i.e.: those labelled with the anti-cleaved caspase 3 antibody) was done in four nearby (non-damaged) slices of each embryo and adding the resulting numbers.

2.7. Protein distribution quantification

Starting with stacks of optical sections, distribution of fluorescent signals was determined from average intensity projections of three slices. Our region of interest was the mostly flat section of the neural plate adjacent to the medial hinge. Images were then rotated so as to make the apical side of our region of interest face left, and from there, the fluorescence profile was obtained along an approximately 20 µm wide transect (71 px, corresponding to 20.09 µm). Background signal intensity was obtained as the mean intensity of a 40 px square outside the tissue and subtracted from all values.

Phalloidin intensity profiles in control embryos typically showed two peaks corresponding to the basal and apical side of the tissue respectively, which we used to define these regions in the apico-basal axis. The apical region was defined as the interval within 9 px (2.5 µm) of the appropriate phalloidin signal maximum, which was observed to correspond approximately to a 50 % decrease in signal intensity in control embryos. The sub-apical region was defined as the interval between the basal phalloidin maximum and the apical region. In cases with cellular extrusion more apical peaks were observed, but a peak corresponding to the apical side of non-extruded cells was usually identifiable. Analysis of the tissue morphology was used to clear any doubts regarding multiple possible basal or apical peaks.

The ratio of apical to sub-apical signal for MARCKS and ZO-1 immunostaining was then calculated as the largest value found in the apical region divided by the average value in the sub-apical region.

2.8. Statistical analysis

Statistical analyses were performed for the values for the ratio of the maximum immunofluorescent signal intensity in the apical regions relative to the average signal

intensity of the sub-apical region for both MARCKS and ZO-1 for each experimental condition, using GraphPad Prism (version 8.0.2 for Windows; GraphPad Software, Boston, Massachusetts USA, www.graphpad.com). All distributions passed the Shapiro-Wilk, Anderson-Darling and D'Agostino & Pearson lognormality tests ($\alpha = 0.05$), with the exception of the MARCKS distribution in control embryos, in which N was too small for the Anderson-Darling and D'Agostino & Pearson tests. Differences of means between pairs of experimental conditions were determined using Welch's t-test for the natural logarithm of the presented values.

2.9. Theoretical description

In looking for a model that was able to reflect the complex geometry and the mechanical preponderance of the nucleus in pseudostratified epithelial cells, we based our model on the augmented vertex model previously described by Kim et al. (2021, 2024). In this model, cell-cell interfaces are represented by vertices joined by straight edges, and nuclei are represented as solid-like objects constrained by the cell membrane. The use of vertices and straight edges is similar to the case for prior vertex models (VMs), where vertices usually represent the point where three or more cells meet, and cell edges are taken as a straight line (Alt et al., 2017), but this model also includes vertices where only two cells meet (or where one meets the external milieu). We refer to these vertices as 2-fold, 3-fold, etc. by the number of edges connected to them. By allowing for 2-fold vertices along cell-cell interfaces, cellular curvature may be approximated, a condition which can't be achieved in ordinary VMs.

Our model is based on an energy functional (Eq. 1) depending on all cell areas, the length of all cell-cell (or cell-exterior milieu) interfaces and the total "overlapping" radial distance of a cell's nucleus with respect to its membrane, integrated along the cell's contour.

$$E = \sum_{i,j} T_{ij} L_{ij} + \sum_i K \left(\frac{A_i}{A_0} - log\left(\frac{A_i}{A_0}\right) \right) + \frac{1}{2} K_n \oint_{\partial C_i} (R_i(s) - r_i(s))^2 H(R_i(s) - r_i(s)) \, ds \quad (1)$$

where L_{ij} and T_{ij} are the length and the surface tension of the interface between cells i and j respectively, K is the cell compressibility modulus, A_i is the area of cell i, $A_0 = K/P_0$ is a characteristic area based on P_0 the external medium's pressure, K_n is the nuclear elastic modulus, $r_i(s)$ is the distance measured from the center of the nucleus of cell i to a point in the cell boundary ∂C_i (parametrized by arc-length s), $R_i(s)$ is the distance between the

nuclear center and its border in the same direction and $H(x)$ is the Heaviside function, which ensures only points in which the nucleus overlaps its cell's membrane are included in the line integral (taken over cell's i membrane ∂C_i). The first sum is over all cell-cell (and cell-exterior) interfaces ij, the second one over all cells i. Note that in the case of a circular nucleus, $R_i(s)$ is simply the nucleus' radius.

The first two terms in Eq. 1 are similar to those in previously defined energy functionals (Alt et al., 2017; Bi et al., 2015; Farhadifar et al., 2007), but we follow Kim et al. (2021) in not including a second-order term on the perimeter and in defining pressure ($\partial E / \partial A_i$) as inversely proportional to cell volume, here represented by the cell area. Similarly, although the forces arising from the interaction between nuclei and membranes can be likened to those proposed by Kim et al. (2024), they are not necessarily identical (see Appendix A.3). While this kind of model has usually been used to represent the apical surface of epithelia, our work represents the epithelium as a lateral cross-section, similar to those presented in the experimental results (Fig. 1A).

In order for dynamical simulations to be performed, cell boundaries may be approximated by a set of points (vertices) joined by straight edges. Forces acting on these vertices may then be derived from the energy functional and used to calculate their position in time. Alternatively, equilibrium states may be found in a continuous version of the model (which can be seen as the limit in which inter-vertex distances tend to zero) by minimizing the energy of the whole tissue.

2.10. Simulations

All simulations were based on a non-dimensionalized version of E (Equation 1; Appendix A.1) defining certain characteristic scales P_0 (pressure of the external medium), T_0 (surface tension of cell-cell interfaces), $L_0 = \sqrt{A_0} = \sqrt{K/P_0}$ (characteristic length-scale) and τ_R (characteristic timescale for vertex relaxation). When not explicitly stated, we followed Kim et al. (2024) in their estimation for all corresponding parameters. Assuming a viscous medium where frictional forces dominate, the positions of all vertices follow first-order differential equations in which velocities are proportional to the sum of all non-viscous external forces (Odell et al., 1981), which may be obtained as the negative gradient of E with respect to their respective positions. The same can be applied to nuclei, which are defined as solids by their centers of

mass and rotation angles, with this last variable being ignored by considering only spherical (circular) nuclei in all simulations.

Dynamic simulations were carried out using custom scripts written for GNU Octave (Eaton et al., 2020) by numerically integrating these first-order differential equations using the Euler method with a time step $\Delta t = 0.005\,\tau_R$. Unless stated otherwise, all simulations were initialized with periodic boundary conditions of length $\lambda = 10$ and with $N = 20$ rectangular cells of area 1, a limit of our computational implementation. Edge length was maintained by adding or joining vertices between 1/16 and 1/8 of the average cell width, defined as $b = \lambda/N$. In the cases in which this resulted in the formation of a 4-fold vertex, a T1 transition (neighbour exchange; necessary for extrusion in our model) was evaluated and computed using the method described by (Duclut et al., 2021). The surface tension of all apical and basal interfaces was defined as T_a, relative to T_0. Whether the system had reached an equilibrium state was determined by (qualitatively) checking whether the energy had stabilized to a minimum over time.

In addition to these dynamical simulations, we analyzed the (dimensionless) energy minima for a simplified tissue made up of wedge-shaped cells without nuclei under different values of parameters T_a/T_0 and b (inversely related to the tissue's cell density), as shown in Figure 1B.

3. Results

3.1. Experimental assessment of the mode of apical cell extrusion in PMA-treated embryos

With the aim of elucidating if the PMA-induced apical cell extrusion in the neural plate was live or apoptotic extrusion, we set up the conditions for treating neurulating chick embryos simultaneously with PMA and the pan-caspase inhibitor QVD-OPh. Since both drugs must be administered solubilized in DMSO, and given the relatively low dilution rate needed for QVD-OPh, we used the lowest possible amount of DMSO which did not cause obvious effects on embryo or cell survival: 0.93%. In these conditions, control embryos developed normally, not showing delays in general development or neurulation (Fig. 2A).

Widespread apical cell extrusion was observed throughout the neural plate in all embryos treated with PMA (n = 20) and those treated with both PMA and QVD-OPh (n = 20), while no cell extrusion was observed in control embryos (n = 15) or those under QVD-OPh treatment alone (n = 17) (Fig. 2B). As expected, PKC activation with PMA caused in all cases a redistribution of MARCKS from the plasma membrane to the cytoplasm, in addition to a loss of its apical accumulation (Fig. 3A). QVD-OPh-only treated embryos, on the contrary, showed a MARCKS distribution that resembled control embryos. To further check the effect of these treatments on apico-basal polarity, we decided to analyze the distribution of the sub-apical cell adhesion–associated protein ZO-1. As previously reported (Aparicio et al., 2018), PMA treatment provoked a clear loss of apical accumulation of this apical marker, and this was not affected by co-incubation with QVD-OPh (Fig. 3B). In order to compare apical protein accumulation across the different treatments, we measured the ratio of apical signal with respect to the average sub-apical signal intensity for both proteins, MARCKS and ZO-1 (see section 2.7). QVD-OPh-only-treated embryos showed a similar distribution to control embryos, while those treated with PMA exhibited a significant decrease in apical protein accumulation (Fig. 3C). Similarly, double treated embryos showed a significant difference with respect to embryos treated only with QVD-OPh. These results further indicated that treatment with the anti-apoptotic drug did not affect cell extrusion or cell polarity by itself.

DNA staining indicated the presence of few scattered apparently dying cells in all embryonic tissues, at all treatment conditions. But, as previously described (Aparicio et al., 2018), PMA treatment greatly increased the number of pyknotic nuclei mostly on cells extruded from the neural plate (see Fig. 3B, for example). This was confirmed by immunolabeling of activated

Caspase 3 (Fig. 4A). Most of these dying cells were observed beyond the apical border of the mass of extruded cells, indicating they were detaching from the epithelium. The double treatment of embryos with PMA and QVD-OPh, on the other hand, showed a sharp reduction in cell death as assessed by quantifying both parameters, demonstrating that the observed apical extrusion happens independently of cell death in these embryos, and can be defined as live cell extrusion (Fig. 4B).

3.2. Computational model of a pseudostratified epithelium

Since our experimental results support the idea that PMA treatment causes live cell extrusion during development, we focused on determining the conditions under which an epithelium like the neural plate could become mechanically unstable, leading to the elimination of live cells from the tissue. Our first goal was to produce a model which could reproduce the morphology of pseudostratified epithelia, that is, a single layer of columnar cells in which the nucleus occupies a large proportion of the cell volume, resulting in curved cell-cell interfaces shaped so as to accommodate all nuclei at different heights along the apico-basal axis. Although *in vivo* these cells must necessarily change shape in time due to INM and cell division, experimentally the cellular response to PMA treatment is seen to be faster than the cell cycle (8-12 h; Schoenwolf, 2018), meaning that the observed defects should not be greatly affected by these changes.

With this in mind, we searched for system conditions which would result in stable equilibrium solutions for which the previous description holds. To do this, we used a modified version of an augmented vertex model previously developed to represent the dynamics of epithelia from an apical point of view (Kim et al., 2024, 2021), to now represent a lateral view of an epithelial tissue under periodic boundary conditions (see Fig. 1A). Our model consists of a set of cells and solid-like nuclei for which an energy functional E is defined, which depends on the different cells' areas, boundary lengths and position of the nuclei within the cell (Equation 1; see section 2.9).

It can be proven that in the absence of nuclear repulsion forces, the angle between adjacent edges at equilibrium depends only on the interface they belong to (Appendix A.2). As a corollary, this means that all interfaces not overlapping with a nucleus approximate circular arcs at equilibrium. This indicates that an equilibrium state resembling a pseudostratified

morphology could only be observed in cells with nuclei larger than the average cell width b, defined in this model as the (dimensionless) length of the tissue in the *x*-axis divided by the total number of cells. Supporting this, our initial dynamical simulations showed that cell layers containing nuclei smaller than their expected width reached an equilibrium state consisting of identical columnar cells with straight cell-cell and convex cell-medium interfaces (Supplementary Fig. 1). This happened in less than twice the characteristic timescale for vertex relaxation τ_R.

3.3. Conditions leading to widespread cell extrusion in the simulation

We followed by including wide nuclei distributed alternatingly, so that a cell with an "apical nucleus" (tangent to the initial apical boundary) has neighbours with "basal nuclei" and vice versa (Fig. 5A). For low values of the apical/basal surface tension T_a (with respect to lateral surface tension T_0), this led to widespread extrusion, with cells losing either their apical or basal interfaces depending on their initial nuclear position and stabilizing into a more rounded shape. Larger values of T_a/T_0 allowed for the tissue to stabilize into a single layer of columnar cells with curved cell-cell interfaces determined by the position of nuclei, corresponding to the pseudostratified morphology we sought. More rarely, cells formed a single layer but stabilized into a columnar, wedge-like shape, with straight cell-cell interfaces, and with the nucleus being located in a region of the cell wider than itself. Parameters $b = 0.5, T_a/T_0 = 5$ prevented extrusion not only in tissues with alternating nuclei, but also in simulations initialized under different nuclear distributions (Fig. 5B-D).

3.4. Analysis of energetic minima in a simplified model

In order to investigate the conditions under which extrusion occurred beyond the limitations of our computational implementation, and based on the results obtained from simulations with alternating nuclei, we studied as a first approximation the equilibrium states and stability for a single-layered tissue formed by alternating wedge-shaped cells without nuclei (see Fig. 1B; Appendix A.4). We assumed these cells to have straight cell-cell boundaries, and their apical/basal interfaces to be circular arcs. Equations were derived for such a tissue allowing us to compute the energy per cell in terms of its height (h) and basal width (b_b), with T_a, b and L_0 as parameters. Setting $L_0 = 10\,T_0/P_0$ initially (as in our dynamical simulations) we

numerically computed the energy minimum for different values of b and T_a, with h ranging between 0 and $1/b$ (we assume the final area will be less than 1) and b_b between 0 and $2b$.

In general, low values of b have energy minima with $b_b = 0$, and high values of b have $b_b = b$, with an intermediary transition range (Fig. 6A). For high values of T_a/T_0, this creates an apparently clear division of the b range into three connected regions, but this is not the case for lower values ($T_a < 0.8 \, T_0$, approximately), for which deviations may be observed. For example, low values of b may have a non-null equilibrium basal width b_b. We observe that this system is symmetrical (i.e.: a tissue with basal width b_b yields a mirror image of one with basal width $2b - b_b$), that an energy minimum with $b_b = 0$ would lead either to extrusion or to a persistent 4-fold vertex (usually considered mechanically unstable), and that the case in which $b_b = b$ corresponds to a symmetrical equilibrium state which may be found in simulations with no nuclei. Equations for this particular state can be found for all values of b as long as $T_a/T_0 > 0.5$ (Appendix A.5), which means the behaviour of b_b/b (and therefore, the stability of the monolayer morphology) as b increases represents a supercritical pitchfork bifurcation, with one unstable ($b_b = b$) and two stable states for each b lower than a certain critical $b_1(T_a/T_0)$. Furthermore, we may define $b_0(T_a/T_0)$ as the maximum value of b for which the energy minimum occurs at $b_b = 0$ (or $2b$, equivalently).

Plotting both b_0 and b_1 against T_a/T_0 divides the parameter space into three regions according to the different long-time behaviours of the system (Fig. 6B). The upper and lower regions correspond to $b_b = b$ (stable monolayer composed of columnar cells of constant width) and $b_b = 0$ (leading to extrusion) respectively, with the distance between them tending to 0 for large T_a. We observe that $b_1(T_a/T_0)$ follows a power-law equation, and that the same can be said of $b_0(T_a/T_0)$ for sufficiently large values of T_a, obtaining equations

$$b_0 = k_0 \left(\frac{T_a}{T_0}\right)^{-\alpha_0} \quad and \quad b_1 = k_1 \left(\frac{T_a}{T_0}\right)^{-\alpha_1} \tag{2}$$

with $k_0 = exp(-0.4237) \approx 0.65$, $\alpha_0 = 0.5612$ (linear fit of log-log data with $R^2 > 0.998$ for $T_a/T_0 > 1.6842$) and $k_1 = exp(-0.3729) \approx 0.69$, $\alpha_1 = 0.5761$ (linear fit of log-log data with $R^2 > 0.999$). It should be noted that these values depend on the remaining parameter, the cell compressibility modulus K, with k_0, k_1 increasing and α_0, α_1 decreasing as K increases, seemingly reaching an asymptote (Supplementary Fig. 2).

Although this classification does not take into account the nuclear repulsion forces, we may reasonably assume that for a system with nuclei to have a stable one-layered equilibrium

state, it should also reach a similar state when nuclei are absent. Namely, if b is low (high cell density) and h correspondingly high, nuclei may be wider than b but much shorter than h, in which case they would only interact with a small number of vertices. We tested whether this assumption held for $b = 0.5$ using different values of T_a and found some good agreement between these predictions and the simulations, in that values of T_a/T_0 higher than 1.527 (the highest value for which $b_0 = 0.5$) led to stable single-layer conformations, while lower values led to extrusion (Fig. 7A; Supplementary Videos 1-2). Notably, although $T_a/T_0 = 0.55$ is above the b_0 curve for $b = 0.5$, cell extrusion was also observed in this case along with simulation artefacts (Fig. 7B). Although wedge-shaped cells might be a good approximation when nuclei are placed in alternating apical/basal positions, this might not be the case for other nuclear distributions. To test this, we used parameters $b = 0.5$ and $T_a/T_0 = 1.6$ as before and ran simulations with other initial nuclear configurations which we had shown to be stable far away from the theoretical limit at $T_a/T_0 = 5$ (see Figure 5B-D). An initial "staircase" distribution prevented extrusion, while initial random configurations did not (Fig. 7C,D), indicating a dependence between the exact threshold for extrusion and the initial nuclear positioning. b_0 reaches a maximum of height $b = 0.6040$ between $T_a/T_0 = 0.8$ and 0.8167, meaning that extrusion should not happen in any system with b larger than this value. We tested this by reducing the cell number so that $b = 10/16 = 0.625$ and found that while extrusion was prevented by lower values than before, it was still possible to see extrusion for sufficiently low T_a/T_0 values (Fig. 7E).

4. Discussion

It was previously shown that MARCKS knockdown, or its phosphorylation upon PMA treatment, induced a loss of apico-basal polarity and extensive apical cell extrusion in chick embryos neural plate. This happened without an evident increase in cell death, except for cells that appeared completely detached from the epithelium, suggesting a live cell extrusion mechanism (Aparicio et al., 2018). In the present work, we have confirmed this to be the case: cell extrusion covering the full width of the neural plate occurred in all embryos under PMA treatment even when apoptosis was effectively inhibited with the anti-apoptotic drug QVD-OPh. Despite similar amounts of extruded cells, the treatment produced a near-total loss of signs of cell death. This allowed us to conclude that the observed apical cell extrusion occurred independently of apoptosis, indicating this to be an example of live cell extrusion that could be explained by mechanical alterations in the neuroepithelium (Eisenhoffer et al., 2012; Eisenhoffer and Rosenblatt, 2013).

Having cleared this point experimentally, we decided to proceed with a theoretical model of the neuroepithelium which could reproduce a pseudostratified morphology and show cell extrusion purely as a product of an imbalance of mechanical forces along the apico-basal cell axis. Previously published models, along with experimental studies, have pointed to losses in apical surface tension, tissue irregularities (i.e.: anisotropy and topological defects) and high in-plane cell densities as important conditions determining the occurrence of cell extrusion (Drozdowski and Schwarz, 2024; Marinari et al., 2012; Okuda and Fujimoto, 2020; Saw et al., 2017). Excluding apical tension, the mechanical meaning of such predictors becomes difficult to discern in pseudostratified epithelia, where cell density is much higher than in previously considered situations and where cells develop complex three-dimensional shapes and arrangements in order to accommodate high nuclear densities (Gómez et al., 2021). Furthermore, these geometrical characteristics have been largely simplified or ignored by prior models of pseudostratified epithelia (Hecht et al., 2022; Ishii et al., 2021).

Although simulated extrusion may not perfectly reflect the *in vivo* mechanisms, we may use the model to find conditions under which a pseudostratified morphology might become unstable in a mechanical sense, leading to a live cell extrusion-like behavior. We found that a low ratio of apical/basal to lateral interfacial surface tension (T_a/T_0) led to widespread extrusion, while higher values prevented it. In particular, when wide nuclei (i.e.: wider than

the average cell width) were present and T_a/T_0 was sufficiently large, the tissue reached an equilibrium state which was reminiscent of a pseudostratified epithelium: a single layer of cells with curved boundaries shaped so as to accommodate all nuclei at different heights along the apico-basal axis.

With these considerations in mind, the results obtained from our model would suggest that, under normal conditions, the surface tension in apical and basal interfaces must be larger than that in lateral cell-cell interfaces so as to mechanically stabilize the pseudostratified morphology. To quantitatively assess this, we approximated the stability of cells in a dense tissue where the nucleus mechanically interacts with a small fraction of the cell's surface by analyzing a simple tissue composed of identical wedge-shaped cells without nuclei. We found that the minimum average cell width b_0 required for a tissue with relative apical/basal surface tension T_a/T_0 to be stable approximately follows a power law, with parameters depending on the cell compressibility modulus K. This approximation, while correct for large values of T_a/T_0 and certain regular nuclear distributions, was not enough to predict cell extrusion in general, particularly when nuclei had random initial positions. These results serve to point out the limitations of our approximation and show that the exact conditions for extrusion may depend on the actual nuclear distribution adopted by the tissue. The importance of nuclear positioning, as well as the forces it exerts on the cell cortex through interactions with the cytoskeleton, have been demonstrated in different epithelial morphogenetic processes (Ambrosini et al., 2019; Ferme et al., 2025; Roby and Rauzi, 2025).

Although the relative simplicity of this theoretical model does not reflect most of the complex features of a real epithelium, the concomitant inclusion of a surface tension and an non-deformable nucleus can be used to simulate morphogenetic processes in which both factors are important (Kim et al., 2024). Deformability is nevertheless an intrinsic property of living cell nuclei, although with some limitations (Kalukula et al., 2022). Interestingly, in the extension of the Drosophila embryo germband, the simultaneous genetic alteration of nuclear deformability and the pharmacological destabilization of microtubules, affecting nuclear positioning in the apico-basal cell axis, causes both morphogenetic defects and cell extrusion (de Leeuw et al., 2024).

Based on the previous analysis, we can give an interpretation of our experimental results simply by assuming that PMA treatment alters the relative surface tension of the apical

and/or basal interface (e.g.: by diminishing apico-basal polarization in each cell) without altering cell compressibility. The change required to destabilize the single-layered morphology of the tissue would imply reducing T_a/T_0 so that the new minimum stable cell width $b_0{}^{PMA}$ became larger than the average cell width b of the tissue. Furthermore, although the previous approximation of the tissue as formed by wedge-shaped cells no longer applies to the whole tissue once extrusion begins, we may use it to approximate only the basalmost layer of cells, for which the main effect of extrusion is to reduce the cellular density, that is, to increase b. If extrusion eventually stops and the tissue reaches a new stable state, then the average cell in the basalmost layer should reach an expected final width greater than $b_0{}^{PMA}$. In this simplified explanation, both the occurrence and the extent to which cell extrusion happens should be mainly determined by the relative decrease in the value of T_a/T_0 due to PMA treatment.

When extrapolating these observations to the living tissue, we could assimilate polarized changes in surface tension to alterations in cell polarization (Moazzeni et al., 2025; Narayanan et al., 2023). Treatment with PMA causes a loss of apico-basal cell polarity, evidenced by a redistribution of the apical marker ZO-1, as well as of actin filaments. As expected, there was also a re-localization of the main PKC substrate MARCKS, previously shown to be in great part responsible for PMA-induced cell polarity downregulation and cell extrusion in the chick neural plate (Aparicio et al., 2018). Evidence from this previous work also indicated that the PMA effect on these cells could involve a destabilization of cortical actin filaments (and, although not analyzed there, this would probably lead to a general reduction in cell surface tension; Chugh et al., 2017). This cortical actin destabilization could be explained by an alteration in MARCKS function owed to its phosphorylation at the effector domain by PKC, blocking its ability of sequestering PIP$_2$ at the plasma membrane (Laux et al., 2000). Different lines of evidence have linked MARCKS to the modulation of epithelial cell mechanical stability, and its involvement in processes such as morphogenesis and carcinogenesis (Veloz et al., 2021). All the mentioned experimental evidence points to an effect of PMA mostly on apical membrane tension, given the high apical accumulation of MARCKS and actin filaments in neural plate cells, and that the basal membrane domain is tightly associated to a rigid external scaffold, the basal lamina.

We have presented here evidence of the occurrence of live cell extrusion in the neuroepithelium during neurulation, which could be caused by a reduction in cortical actin cytoskeleton integrity and a concomitant down-regulation of apico-basal cell polarity. In order to find a way of explaining these results within a mechanical framework, we have introduced an expanded energy-based vertex model allowing for the presence of nuclei and curved interfaces which is able to represent pseudostratified epithelial morphology. In line with previous research, our work points to a high relative apical/basal surface tension as being the main stabilizing factor against cell extrusion in high-density tissues such as the developing neural plate. Furthermore, we derive a novel approximate condition for live cell extrusion relating cell density and surface tension, which follows a power-law equation. Measurements of surface tensions and cell densities in the developing neural plate could help validate these results and contrast our approximation with other similar pre-existing models.

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Author contributions

SABR: Conceptualization, Data curation, Formal analysis, Investigation, Methodology, Software, Writing – original draft, Writing – review and editing; JAH: Conceptualization, Formal analysis, Methodology, Supervision, Writing – review and editing; FRZ: Conceptualization, Data curation, Formal analysis, Funding acquisition, Methodology, Project administration, Resources, Supervision, Writing – original draft, Writing – review and editing.

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Figure 1: Diagrams illustrating the different simulations considered in the analysis of the energy model. A. State of a typical system at time t as obtained by dynamical simulation. Vertices are colored according to the type of interface they belong to (cell-cell interfaces are blue, while apical and basal interfaces are orange and yellow, respectively), and each cell contains a nucleus tagged according to the cell number. Periodic boundary conditions are used in the x-axis. Both axes are taken to be relative to the characteristic length scale $L_0 = \sqrt{A_0}$. **B.** To study the stability of a simple cell layer we consider an infinite tissue made up of alternating, identical wedge-shaped cells. The shape of one of these cells may be determined by its height (h) and its basal width (b_b), assuming that the apical and basal interfaces correspond to circular arcs and that cell-cell interfaces are straight. The width of any two adjacent cells adds up to double the average cell width b, which is used to characterize cellular density.

Figure 2: Comparison of chick embryos after treatment with PMA and QVD-OPh. **A.** Macroscopic view of treated embryos. Embryos treated with the pan-anti-caspase drug QVD-OPh seemed to develop similarly to Control embryos. Those treated with PMA, both alone and together with QVD-OPh, showed several defects, as described previously (Aparicio et al., 2018), including decreased length, neural tube closure failure and abnormally open anterior (filled arrowheads) and posterior (hollow arrowheads) neuropores. Scalebar: 1 mm. **B.** Transverse sections of the neural plate and adjacent tissues. Control and QVD-OPh-treated embryos displayed a thick pseudostratified epithelium. Treatment with PMA (including double treatment with QVD-OPh) produced widespread apical cell extrusion, evidenced by the presence of cells beyond the line of F-actin accumulation (dashed line; corresponding to the apical side of the layer of cells attached to the basal lamina), which are present along all regions of the neural plate. Scalebar: 50 μm

Figure 3: Distribution of MARCKS and ZO-1 along the apico-basal axis of the neuroepithelium. Intracellular distribution of MARCKS (**A**) and ZO-1 (**B**) in different experimental conditions. Both proteins accumulate near the apical side in control embryos, but have seemingly altered distributions under PMA and PMA + QVD-OPh double treatment, sometimes even presenting anomalous accumulations away from the line of F-actin

accumulation (arrowheads). **C**. Example of intensity profiles used to determine the fluorescence intensity around the apical border (in gray; defined as the area of maximal F-actin accumulation) and along the sub-apical portion of the neuroepithelium in different conditions (only control condition example is shown). **D**. Plots for the ratio of the maximum immunofluorescent signal intensity in the apical regions relative to the average signal intensity of the sub-apical region for both proteins. Data shows significant differences between the geometric mean values for PMA-treated embryos with respect to Control (p-values = 0.0416 (ZO-1); 0.0279 (MARCKS)) and QVD-OPh-treated embryos (p-values = 0.0044 (ZO-1); <0.0001 (MARCKS)), and between QVD-OPh- and double-treatment embryos (p-values = 0.0233 (ZO-1); 0.0390 (MARCKS), indicating altered apico-basal polarity. Data are presented along with geometric mean and geometric standard deviation.

Figure 4: Occurrence of cell death among different experimental conditions. A. Examples taken from slices of embryos treated with PMA or PMA + QVD-OPh, illustrating the differences in signs of cell death. In PMA-treated embryos cells undergoing cell death were often observed, as indicated by the presence of pyknotic nuclei and/or caspase-3 activity (arrowheads). **B**. The number of pyknotic nuclei and cells displaying active caspase-3 immunodetection was higher in PMA-treated embryos than in all other experimental conditions. Most notably, double treatment with PMA and QVD-OPh abolished cell death while still inducing widespread cell extrusion. The dashed line marks the line of F-actin accumulation, corresponding to the apical side of the layer of cells attached to the basal lamina. Filled arrowheads: Cells exhibiting both pyknotic nuclei and active caspase-3. Hollow arrowhead: A cell with a pyknotic nucleus but no active caspase-3 immunoreactivity. Data presented along with median and 95% confidence interval.

Figure 5: Long-term behaviour of dynamic simulations in tissues with average cell width b = 0.5. A. Starting from a layer of identical rectangular cells with unit area and alternating nuclei, different morphologies are observed under different values of T_a/T_0 after 20 characteristic timelengths (τ_R). For low values, a single layer morphology is unstable and cell extrusion ensues. For larger values, a single layer is maintained at equilibrium. For values larger than 5, a stable equilibrium solution resembling the pseudostratified epithelial

morphology is reached. Simulations were also performed for other nuclear configurations namely a "staircase" distribution with intermediate nuclei (**B**) and random distributions (**C,D**), all of which proved stable when $T_a/T_0 = 5$. All simulations performed for 20 characteristic time lengths (τ_R). Energy profiles indicated an apparent equilibrium state for all cases except in (**A**) when $T_a/T_0 = 1.5$.

Figure 6: Long-term stability analysis for a monolayer composed of identical alternating wedge-shaped cells in terms of tissue parameters. A. Value of the basal width b_b (expressed as a fraction of average cell width b) at the global energy minimum as a function of b for different values of the ratio between apical/basal and lateral surface tension T_a/T_0. Although for low values of T_a/T_0 these graphs seem more complex, for values larger than 0.87, the value of b_b/b seems to be divided into three distinct ranges: a low range where $b_b = 0$, a middle range, and a high range where the energy minimum corresponds to $b_b = b$. Values b_0 and b_1 limit the low and high ranges for each T_a/T_0 (Arrowheads). **B**. Plot of b_0(blue) and b_1 (orange) as functions of T_a/T_0. For sufficiently large T_a/T_0, systems with parameters lying in the region above the b_1 curve have their energy minima when $b_b = b$, while those below b_0 tend to $b_b = 0$ at equilibrium, which leads to cellular extrusion. (Inset) Natural log-log plot of b_0 and b_1 vs. T_a/T_0. Fitted (dashed) lines correspond to equations $log(b_0) = -0.5612\ ln(T_a/T_0) - 0.4237$ and $log(b_1) = -0.5761 ln(T_a/T_0) - 0.3729$. When simulations yielded values of b_b/b larger than one, they were replaced by $2 - b_b/b$, using the tissue's apico-basal symmetry.

Figure 7: Comparison between dynamical simulations and stability predictions based on a tissue composed of wedge-shaped cells. A. Starting with nuclei distributed alternatingly, $T_a/T_0 = 1.6$ was enough to prevent cell extrusion while $T_a/T_0 = 1.5$ was not, which agrees with our predictions for $b = 0.5$ (see Supplementary Videos 1, 2). **B**. In our dynamical simulation with $T_a/T_0 = 0.55$ not only did cell extrusion occur (contrary to our predictions) but also artefacts were introduced in the form of overlapping cell boundaries (arrowheads; detail in inset). **C,D**. Systems with $T_a/T_0 = 1.6$ (close to the b_0 boundary) proved to be stable when using a "staircase" initial nuclear configuration (C) but could not prevent extrusion when initiated under random nuclear distributions (two examples of which are shown in D).

E. Lowering cell density to 16 cells ($b = 0.625$) means the system lies above b_0 in our approximation regardless of surface tension, but we observed extrusion when $T_a/T_0 = 0.55$ which was avoided when $T_a/T_0 = 1$. **F**. Detail of b_0 and b_1 as functions of T_a/T_0, showing points corresponding to the previously shown simulations. I: $b = 0.5, T_a/T_0 = 1.5$ (below b_0, see A); II: $b = 0.5, T_a/T_0 = 1.6$ (above b_0, see A,C,D); III: $b = 0.5, T_a/T_0 = 0.55$ (above b_0, see B); IV: $b = 0.625, T_a/T_0 = 0.55$ (above b_0, see E); V: $b = 0.625, T_a/T_0 = 1$ (above b_0, see E). Initial conditions in A-D were exactly the same as those used in Fig. 5A-D.

Figure 1

A

$y\ (L_0)$

$x\ (L_0)$

B

h

b_b

$2b$

Figure 2

A

Control   PMA   QVD-OPh   PMA + QVD

1 mm

B

F-Actin   DNA

Control   PMA 5 µM

QVD-OPh 167 µM   PMA + QVD

50 µm

Figure 3

Figure 4

A

B

Figure 5

Figure 6

Figure 7

Supplementary Figure 1

Supplementary Figure 1: Initial simulations performed without nuclei quickly reach equilibrium in less than $2\tau_R$. (A) Starting from an initial configuration of *N* identical rectangular cells with unit area, a stable state was reached composed of cells with straight cell-cell and convex cell-exterior interfaces, here pictured for *N = 16, 18, 20* after 400 integration steps (equivalent to twice the characteristic time for vertex relaxation). This state was achieved even when the initial vertex distribution was not homogeneous, as in the case of *N = 18*. (B) Plot of energy E per cell in time. Initial and final values were quantitatively similar for all cases, although the relaxation time became larger the smaller the average cell width b, with t_{50} (the time required to lose half the total lost energy) being $0.165\tau_R$, $0.235\tau_R$ and $0.27\tau_R$ for *N = 16, 18* and *20* respectively. Here we continued the simulation until $3\tau_R$, but we can qualitatively see that the system has reached equilibrium before that. $T_a/T_0 = 3$ for all shown simulations.

Supplementary Figure 2

Supplementary Figure 2: Dependence of curves b_0 and b_1 with parameter K. (a) Plot of $b_0(T_a/T_0)$ and $b_1(T_a/T_0)$ for K = 1, 25, 100. Increasing K makes b_0 and b_1 generally have larger values, although the difference becomes smaller for larger K. (b) Plot of $b0(K)$ and $b1(K)$ for $Ta/T0$ = 1, 1.5. As shown in (a), at each T_a/T_0, both b_0 and b_1 grow monotonically with K, seemingly reaching an asymptote at high K. (c) Plot of parameters k_0, k_1 (open circles, broken lines), $-a_0$ and $-a_1$ (closed circles, lines) as functions of K, obtained by fitting $b_0(T_a/T_0)$ and $b_1(T_a/T_0)$ to a power-law equation $k(T_a/T_0)^{-a}$. Because values for a_0 and k_0 seemed to be parallel to each other, in order to better visualize them together we defined c_0 as the average difference between them, finding c_0 = -1.2125. Correspondingly for a_1 and k_1, we found c_1 = -1.2756.

Supplementary Video 1: Evolution in time of a simulated tissue in which extrusion occurs, as shown in Figure 7A. In this simulation the average cell width is $b = 0.5$ and $T_a/T_0 = 1.5$, which leads to extrusion. Although initially the tissue morphology seems to stabilize, several T1 transitions happen at $t = 11.8\,\tau_R$, causing the state of the tissue to change greatly. At $t = 20\,\tau_R$ the system has not yet reached a new equilibrium. That the stability threshold for tissues with $b = 0.5$ is between $T_a/T_0 = 1.5$ and 1.6 is supported by the stability analysis performed on a simplified model.

Supplementary Video 2: Evolution in time of a simulated tissue in which extrusion does not occur, as shown in Figure 7A. In this simulation the average cell width is $b = 0.5$ and $T_a/T_0 = 1.6$. The time it takes for the energy to relax 90% into its final value is less than $t = \tau_R$, but in this example the tissue qualitatively can be seen to stabilize in around $6\,\tau_R$. That the stability threshold for tissues with $b = 0.5$ is between $T_a/T_0 = 1.5$ and 1.6 is supported by the stability analysis performed on a simplified model.

Appendix A

A.1 Non-dimensional version of energy functional

For all simulations and for the following derivations, a non-dimensional version of the energy functional E (eq. 1) was used. The formula can be obtained as $\epsilon = E/T_0L_0$, with T_0 being a characteristic surface tension equal to the surface tension of any cell-cell interface, and $L_0 = \sqrt{A_0} = \sqrt{K/P_0}$ a characteristic length, where P_0 is the pressure of the external medium. Using this, we obtain

$$\epsilon = \sum_{i,j} \frac{T_{ij}}{T_0} \frac{L_{ij}}{L_0} + \sum_i \frac{P_0 L_0}{T_0} \left(\frac{A_i}{A_0} - log \left(\frac{A_i}{A_0} \right) \right) + \frac{1}{2} \frac{K_n L_0}{T_0} \oint_{\partial C_i} \left(\frac{R_i(s) - r_i(s)}{L_0} \right)^2 H \left(\frac{R_i(s) - r_i(s)}{L_0} \right) ds \quad (A1)$$

where all variables are relative to L_0 and A_0 and three dimensionless parameter groups (T_{ij}/T_0, P_0L_0/T_0 and K_nL_0/T_0) have been defined. We will use the dimensional and dimensionless names for these variables interchangeably throughout this appendix (i.e.: E for ϵ, L_{ij} for L_{ij}/L_0, etc.).

A.2 Force balance and shape of an interface at equilibrium (without nuclear overlap)

Two types of forces act on all vertices which don't interact with the nucleus: a tangential force coming from the surface tension term and a force derived from the pressure term in E (eq. 1). Let $\vec{\alpha}$ be a 2-fold vertex on the boundary between cells i and j (any of which we might take as the external medium, substituting $A = 1/P_0$), with clockwise neighbour vertex (x_-, y_-) and counter-clockwise neighbour (x_+, y_+). Then the force acting on $\vec{\alpha}$ is given by:

$$\vec{F_\alpha} = -\frac{\partial E}{\partial \vec{\alpha}} = - \left\{ \frac{\partial E}{\partial L_{ij}} \frac{\partial L_{ij}}{\partial \vec{\alpha}} + \frac{\partial E}{\partial A_i} \frac{\partial A_i}{\partial \vec{\alpha}} + \frac{\partial E}{\partial A_j} \frac{\partial A_j}{\partial \vec{\alpha}} \right\} \quad (A2)$$

Because $\partial L_{ij}/\partial \vec{\alpha} = -(\hat{t}_+ + \hat{t}_-)$ ($\hat{t}_+$ and $\hat{t}_-$ being the tangent vectors pointing away from vertex $\vec{\alpha}$) and $\partial A_i/\partial \vec{\alpha} = \frac{1}{2}(y_+ - y_-, x_- - x_+) = -\partial A_j/\partial \vec{\alpha}$ (Fletcher *et al.*, 2013), we can rewrite equation (A2) as

$$\vec{F_\alpha} = \frac{T_{ij}}{T_0}(\hat{t}_+ + \hat{t}_-) + \frac{1}{2} \frac{P_0 L_0}{T_0} \left(\frac{1}{A_i} - \frac{1}{A_j} \right) (y_+ - y_-, x_- - x_+) \quad (A3)$$

We observe that $\hat{t}_{\alpha+} + \hat{t}_{\alpha-}$ always points in the average direction between the two edges and that $(y_+ - y_-, x_- - x_+)$ is perpendicular to the line between (x_-, y_-) and (x_+, y_+). In equilibrium $F_\alpha = 0$ and therefore the two terms in equation (A3) must be in the same direction (since $T_{ij} \neq 0$), meaning $\hat{t}_+ + \hat{t}_-$ is perpendicular to $(x_+ - x_-, y_+ - y_-)$. Since $\hat{t}_+ + \hat{t}_-$ bisects the angle between both edges, it follows that both edges must have the same length l, and since $(y_+ - y_-, x_- - x_+)$ has the same length as $(x_+ - x_-, y_+ - y_-)$, we may write

$$0 = T_{ij} \cos(\omega) - K \left| \frac{1}{A_i} - \frac{1}{A_j} \right| l \sin(\omega) \qquad (A4)$$

where 2ω the inner angle between the two edges.

Since T_{ij} and $\left| 1/A_i - 1/A_j \right|$ depend only on the cells involved, the inner angle 2ω is only a function of edge length, which is equal between any two adjacent 2-fold edges and therefore constant along an interface. This means that any interface between two cells (or between a cell and the external medium) with no overlapping nucleus approximates a circular arc at equilibrium. Additionally as expected, the edge curves towards the cell with the least pressure (largest area).

A.3 Deduction of nuclear repulsion forces and relation to the model by Kim *et al* (2024)

In vertices experiencing nuclear repulsion, $\overrightarrow{F_\alpha}$ includes terms of the form

$$\vec{F}_{i,\alpha} = -\frac{1}{2} \frac{K_n L_0}{T_0} \frac{\partial}{\partial \vec{\alpha}} \left\{ \oint_{\partial C_i} (R_i(s) - r_i(s))^2 H(R_i(s) - r_i(s)) \, ds \right\} \qquad (A5)$$

This derivative involves changes in both the path for the integral and the value of $r_i(s)$ along that path. The integral is only modified along subsequent straight paths γ_- and γ_+, which go from $\overrightarrow{x_-} = (x_-, y_-)$ to $\vec{\alpha} = (x_\alpha, y_\alpha)$ and from $\vec{\alpha}$ to $\overrightarrow{x_+} = (x_+, y_+)$, respectively. For example, the integral I_- along γ_- can be written as

$$I_- = \int_a^b \left(R_i(s) - \left| t\vec{\alpha} + (1-t)\overrightarrow{x_-} - \overrightarrow{x_{N,i}} \right| \right)^2 |\vec{\alpha} - \overrightarrow{x_-}| \, dt \qquad (A6)$$

where $\overrightarrow{x_{N,i}} = (x_{N,i}, y_{N,i})$ is the nuclear center, $|\vec{v}|$ is the Euclidean norm, and where we have omitted the Heaviside function by only integrating in the interval where it is non-zero (a and b are both functions of $\vec{\alpha}$ with values in the interval $[0,1]$). This integral is of the form

$\int_{a(\vec{x})}^{b(\vec{x})} f(\vec{x}, t) \, dt$ and therefore its derivative with respect to $\vec{\alpha}$ (i.e.: taken with respect to $\vec{x}$ and evaluated at $\vec{x} = \vec{\alpha}$) follows the Leibniz Integral Rule:

$$\frac{\partial}{\partial \vec{\alpha}} \left\{ \int_{a(\vec{x})}^{b(\vec{x})} f(\vec{x}, t) dt \right\} = f(\vec{\alpha}, b) \frac{\partial b}{\partial \vec{\alpha}} - f(\vec{\alpha}, a) \frac{\partial a}{\partial \vec{\alpha}} + \int_a^b \frac{\partial f}{\partial \vec{\alpha}} \, dt \qquad (A7)$$

with $a = a(\vec{\alpha}), b = b(\vec{\alpha})$. Since a is the lower limit where the (smooth) integrand of equation A6 is positive, either $f(\vec{\alpha}, a) = 0$ or a is the beginning of the edge (i.e.: $a = 0$) in which case $(da/d\vec{x}) = 0$ at $\vec{\alpha}$. Applying a similar reasoning to b simplifies equation (A7) to

$$\frac{\partial}{\partial \vec{\alpha}} \left\{ \int_{a(\vec{x})}^{b(\vec{x})} f(\vec{x}, t) dt \right\} = \int_a^b \frac{\partial f}{\partial \vec{\alpha}} dt \qquad (A8)$$

For simplicity, we assume circular/spherical nuclei –as in our simulations– and take $R_i(s) = R$. Rewriting $\vec{r_-}(t) = t\vec{\alpha} + (1-t)\vec{x_-} - \vec{x_{N,i}}$, differentiation of the integral along γ_- (eq. A6) with respect to the position of vertex $\vec{\alpha}$ yields

$$\frac{\partial I_-}{\partial \vec{\alpha}} = \int_a^b (R - |\vec{r_-}(t)|)^2 \frac{\vec{\alpha} - \vec{x_-}}{|\vec{\alpha} - \vec{x_-}|} - 2t|\vec{\alpha} - \vec{x_-}|(R - |\vec{r_-}(t)|) \frac{\vec{r_-}(t)}{|\vec{r_-}(t)|} dt \qquad (A9)$$

Defining $\vec{r_+}(t) = (1-t)\vec{\alpha} + t\vec{x_+} - \vec{x_{N,i}}$ and redefining a and b appropriately, one may differentiate along γ_+, resulting in

$$\frac{\partial I_+}{\partial \vec{\alpha}} = \int_a^b -(R - |\vec{r_+}(t)|)^2 \frac{\vec{x_+} - \vec{\alpha}}{|\vec{x_+} - \vec{\alpha}|} - 2(1-t)|\vec{x_+} - \vec{\alpha}|(R - |\vec{r_+}(t)|) \frac{\vec{r_+}(t)}{|\vec{r_+}(t)|} dt \qquad (A10)$$

Finally, the nuclear repulsion force acting on vertex $\vec{\alpha}$ is proportional to the sum of both these integrals, that is

$$\vec{F}_{i,\alpha} = -\frac{1}{2} \frac{K_n L_0}{T_0} \left\{ \frac{\partial I_+}{\partial \vec{\alpha}} + \frac{\partial I_-}{\partial \vec{\alpha}} \right\} \qquad (A11)$$

Our integral term in the energy functional E may be seen as a potential for the repulsive interaction included by Kim *et al.* (2024) in their force-based model. Although the force derived from our model is not equal to that proposed by them, we may state a similarity in the formula for the total force arising from the repulsion of a single edge. This is equivalent to the sum of the derivatives of a single edge's path integral, differentiated with respect to the position of both of its endpoints. Using the integral along γ_- as an example, we obtain a force $\vec{F_-}$ of the form

$$\vec{F_-} = -\frac{1}{2}\frac{K_n L_0}{T_0}\left\{\frac{\partial I_-}{\partial \vec{\alpha}} + \frac{\partial I_-}{\partial \vec{x_-}}\right\} = \frac{K_n L_0}{T_0}\int_a^b (R - |\vec{r_-}(t)|)|\vec{\alpha} - \vec{x_-}|\frac{\vec{r_-}(t)}{|\vec{r_-}(t)|}dt \qquad (A12)$$

Re-introducing the Heaviside function, parametrizing by arc-length and writing the edge length as L_- we can write this as

$$\vec{F_-} = \frac{K_n L_0}{T_0}\int_0^{L_-}\left(\vec{R} - \vec{r_-}(x)\right)H(R - |\vec{r_-}(x)|)dx \qquad (A13)$$

which follows the form proposed by Kim *et al.* 2024 as $F_{\alpha\beta}$.

A.4 Derivation of energy formula for wedge-shaped cells

Without nuclei, the dimensionless energy functional (eq. A1) becomes

$$E = \sum_{i,j}\frac{T_{ij}}{T_0}L_{ij} + \frac{P_0 L_0}{T_0}\sum_i A_i - \log(A_i) \qquad (A14)$$

Therefore, all we need to determine its minima are formulas for the cell areas and interfacial lengths. Surface tension is T_0 at cell-cell and T_a at apical/basal interfaces. The energy per cell is thus

$$E_{cell} = \frac{1}{2}L_l + \frac{T_a}{T_0}(L_a + L_b) + \frac{P_0 L_0}{T_0}(A - log(A)) \qquad (A15)$$

with L_l, L_a and L_b the lateral, apical and basal interface lengths, defined as in Figure A1a. The average cell width is $b = (b_a + b_b)/2$, equal to the sum of the apical (basal) widths of any two adjacent cells.

The apical/basal sides are circular arcs (Fig. A1b; see above) and we see that for a generic circular arc of base b and angle θ with respect to baseline, the radius of curvature is given by $\rho = b/2sin(\theta)$. The arc length is then given by

$$L = 2\theta\rho = \frac{b\theta}{\sin(\theta)} \qquad (A16)$$

while the cap area is equal to

$$A = 2\int_0^{\frac{b}{2}}\sqrt{\rho^2 - x^2}dx - \eta b = \frac{b^2}{4}\left(\frac{\theta}{sin^2(\theta)} - \frac{1}{\tan(\theta)}\right) \qquad (A17)$$

where the integral corresponds to the shaded area in Fig. A1b, and we have substituted $\rho = b/2sin(\theta)$, $\rho^2 = \eta^2 + (b/2)^2$ and $\eta = b/2tan(\theta)$.

Finally, the interface lengths and total area are given by

$$L_l = \sqrt{h^2 + (b_b - b)^2}, L_a = (2b - b_b)\frac{\theta_a}{\sin(\theta_a)}, L_b = b_b \frac{\theta_b}{\sin(\theta_b)} \qquad (A18)$$

$$A = bh + \frac{b_b{}^2}{4}\left(\frac{\theta_b}{\sin^2(\theta_b)} - \frac{1}{\tan(\theta_b)}\right) + \frac{(2b - b_b)^2}{4}\left(\frac{\theta_a}{\sin^2(\theta_a)} - \frac{1}{\tan(\theta_a)}\right) \qquad (A19)$$

where we have substituted $b_a = 2b - b_b$ and $b_b - b_a = 2(b_b - b)$.

Although four variables (plus parameter b) appear in equations (A18) and (A19) (and consequently in E_{cell}), θ_a and θ_b are actually functions of h and b_b. This can be proven by considering a 3-fold vertex in the tissue, defined by angles θ_a, θ_b and ϕ (Fig. A1c). In the limit in which inter-vertex distance tends to 0, pressure-derived forces disappear (see eq. A3, A4), so the tensions must add up to 0 in equilibrium, that is

$$T_a\big(\cos(\theta_b), \sin(\theta_b)\big) + T_a\big(-\cos(\theta_a), \sin(\theta_a)\big) + T_0\big(\sin(\phi), -\cos(\phi)\big) = 0 \qquad (A20)$$

or equivalently

$$\cos(\phi) = \frac{T_a}{T_0}(\sin(\theta_b) + \sin(\theta_a))$$

$$\sin(\phi) = \frac{T_a}{T_0}(\cos(\theta_a) - \cos(\theta_b)) \qquad (A21)$$

These equations can be solved by introducing variables $\alpha = (\theta_a + \theta_b)/2$ and $\beta = (\theta_a - \theta_b)/2$, so that

$$\cos(\phi) = 2\frac{T_a}{T_0}\sin(\alpha)\cos(\beta)$$

$$\sin(\phi) = -2\frac{T_a}{T_0}\sin(\alpha)\sin(\beta) \qquad (A22)$$

Dividing the second equation of (A22) by the first, we obtain

$$\frac{b_b - b}{h} = \tan(\phi) = -\frac{\frac{T_a}{T_0} 2\sin(\alpha)\sin(\beta)}{\frac{T_a}{T_0} 2\sin(\alpha)\cos(\beta)} = -\tan(\beta) \qquad (A23)$$

where we used the fact that $\tan(\phi) = (b_b - b_a)/2h = (b_b - b)/h$ (Fig. A1a). Because $\theta_a, \theta_b \in (0, \pi/2)$ and $\theta_a < \theta_b$, there is only one value of $\beta \in (-\pi/2, 0)$ which satisfies equation A22. This means that $\phi = -\beta$, which in turn simplifies the first equation in A21 to

$$\frac{T_0}{2T_a} = sin(\alpha) \tag{A24}$$

with angle $\alpha \in (0, \pi/2)$ being uniquely determined. From eq. A23 and A24 we obtain

$$\theta_{\frac{a}{b}} = arcsin\left(\frac{T_0}{2T_a}\right) \mp arctan\left(\frac{b_b - b}{h}\right) \tag{A25}$$

which proves that E_{cell} is a function of variables h and b_b only.

Figure A1: Diagrams for the derivation of cell area and interfacial lengths in the simplified tissue composed of wedge-shaped cells. A. Diagram of two neighbouring cells, indicating basal and apical widths (b_b and b_a), contact angles (θ_b and θ_a) and surface lengths (L_b and L_a), as well as the lengths and angles for cell-cell contacts (L_l and ϕ). **B**. In the continuous limit, both the apical and basal caps are circular arcs with generic radius of curvature ρ, base b and contact angle θ. **C**. Diagram showing the relation between angles θ_a, θ_b and ϕ at 3-fold vertices.

A.5 Existence of a symmetrical single-layered equilibrium state

As seen in our analysis of a tissue composed of wedge-shaped cells, for fixed $L_0 = \sqrt{A_0} = \sqrt{K/P_0}$, a bifurcation in the energy minima happens as parameter T_a/T_0 increases, with extrusion ($b_b = 0$ or $b_b = 2b$) being favored for low T_a/T_0 and a symmetrical tissue

configuration in which $b_b = b_a = b$ becoming stable when T_a/T_0 is large. In fact, this equilibrium state exists for all values of $T_a/T_0 > 0.5$, indicating that this system undergoes a supercritical pitchfork bifurcation.

As this is a special case of a tissue composed of wedge-shaped cells, we search for solutions of $\nabla E_{cell} = 0$. Because of the tissue's symmetry, $E(b_b, h) = E(2b - b_b, h)$, which means $\partial E_{cell}/\partial b_b = 0$ when $b_b = b_a = b$. In that case, $\theta_{a/\beta} = \theta = arcsin\left(\frac{T_0}{2T_a}\right)$, which necessitates $T_a/T_0 > 0.5$. Under these conditions, equations (A18-19) simplify to

$$L_l = h, \ \ L_a = b\frac{\theta}{\sin(\theta)} = L_b \tag{A26}$$

$$A = bh + \frac{b^2}{2}\left(\frac{\theta}{\sin^2(\theta)} - \frac{1}{\tan(\theta)}\right) \tag{A27}$$

which depend only on variable h. Differentiating E_{cell} (Eq. A15) with respect to h gives us

$$dE_{cell} = \frac{1}{2} + \frac{P_oL_0}{T_0}\left\{b - \frac{b}{bh + \frac{b^2}{2}\left(\frac{\theta}{\sin^2(\theta)} - \frac{1}{\tan(\theta)}\right)}\right\} = \frac{1}{2} + \frac{P_0L_0b}{T_0}\left\{1 - \frac{1}{A(h)}\right\} \tag{A28}$$

which, when equal to 0, leads to

$$\left(\frac{T_0}{2P_0L_0b} + 1\right)^{-1} = A(h) = bh + \frac{b^2}{2}\left(\frac{\theta}{\sin^2(\theta)} - \frac{1}{\tan(\theta)}\right) \tag{A29}$$

from which h may be obtained for any positive value of b, P_0 and L_0 as long as $T_a/T_0 > 0.5$.