**Mechanical conditions preventing live cell extrusion during primary neurulation in amniotes**

Santiago A. Bosch-Roascio[1,2], Julio A. Hernández[2], Flavio R. Zolessi[1,3,*]

1- Sección Biología Celular, Facultad de Ciencias, Universidad de la República, Uruguay.

2- Sección Biofísica y Biología de Sistemas, Facultad de Ciencias, Universidad de la República, Uruguay.

3- Institut Pasteur de Montevideo, Uruguay.

* Corresponding author: fzolessi@fcien.edu.uy

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**Highlights:**

- PMA treatment induces live apical cell extrusion in the chick embryo neural plate
- Our energy-based vertex model mechanically simulates a pseudostratified epithelium
- Higher apical/basal compared to lateral surface tension leads to epithelial stability
- Lower apical/basal surface tension leads to epithelial instability and cell extrusion
- A power law between cell density and surface tension defines the stability threshold

**Abstract**

During primary neurulation in amniote embryos, the neural plate gives rise to the neural tube in a process requiring the coordination of forces at different scales throughout a geometrically complex tissue. The ways in which this process fails inform us of the complex mechanical conditions required for its correct completion. Previous results showed that the functional disruption of MARCKS, a protein which simultaneously interacts with the plasma membrane and actin filaments, resulted in neural tube closure defects with apical cell extrusion. Here, we demonstrate that this is an example of "live cell extrusion", wherein extruded cells are not undergoing apoptosis. This suggests that extrusion in this case might be due to a mechanical instability in the neural plate. Using an expanded energy-based vertex model of pseudostratified epithelia we then show that extrusion may be elicited by a reduction in the relative surface tension of apical and basal interfaces with respect to cell-cell interfaces. Finally, by considering a continuum description of a simplified epithelium we derive an approximate quantitative threshold for single-layered epithelial stability in the form of a power law relating cell density to the relative value of interfacial surface tensions. Our work serves to explain an example of how alterations in polarization and forces at the single-cell level can produce tissue-scale instabilities which not only greatly alter its morphology but can also ultimately lead to severe developmental defects.

## 1. Introduction

In vertebrates, the central nervous system almost entirely derives from a specialization at the dorsal ectoderm, termed the neural plate, an epithelium that eventually deforms to ingress into the embryo as a whole and forms the neural tube. Particularly in amniotes, this "primary neurulation" process involves the invagination and folding of the neuroepithelium along the cephalo-caudal axis of the embryo to become a tube separated from the epidermal ectoderm that remains at the surface. The series of morphogenetic movements that drive neurulation arise from intrinsic and extrinsic forces exerted over the neuroepithelial cells, which all along the process remain cohesive and highly polarized (Colas and Schoenwolf, 2001; de Goederen et al., 2022). The intrinsic forces deforming the neural plate are generated at different levels, including actions mediated by the cytoskeleton. In addition, forces extended along several cells in the neural plate, such as those generated by convergent-extension movements (Schoenwolf and Smith, 1990), or coming from the surrounding non-neural ectoderm (Alvarez and Schoenwolf, 1992; Moury and Schoenwolf, 1995), could contribute to bending. In this regard, the early work by Lee and Nagele has indicated that neural plate-intrinsic forces would be sufficient for the formation of the neural tube in chick embryo explants (Lee and Nagele, 1988).

All these forces are applied to cells that, in addition, greatly increase their proliferation rate from the neural plate stage on, becoming a quickly growing population (Copp and Greene, 2010). Cells remain attached to both apical and basal surfaces, but they increase their height and reduce their width, generating a tall pseudostratified epithelium. In this organization, cells display interkinetic nuclear migration, by which cell divisions occur at the apical border of the neuroepithelium, while S-phase tends to occur in nuclei closer to the basal side (Norden, 2017; Sauer, 1936). The combination of all these factors results in neuroepithelial cells with extremely complex shapes (Gómez et al., 2021; Iber and Vetter, 2022).

How is it possible that this epithelial cell population tolerates the enormous forces that drive neurulation while proliferating at a high rate, without disruption? Different lines of evidence indicate that the key might be in the strict maintenance of apico-basal cell polarity. Among other factors, this is achieved through a tight binding of each cell to the basal lamina on the basal side, and to their neighboring cells at the sub-apical border through integrin- and cadherin-based cell adhesions, respectively (Saade and Martí, 2025). These adhesion complexes tightly, but dynamically, bind to the cytoskeleton, establishing a mechanically

continuous meshwork that spans across cells, and that can be modulated in response to different external and internal cues (Campàs et al., 2024; Sluysmans et al., 2017; Zhang and Wei, 2025). It has been generally accepted that microtubules extend during neurulation, elongating cells along the apico-basal axis, while the actin cytoskeleton acts in different ways, allowing cells to take a wedge-like shape (Cearns et al., 2016; Schoenwolf and Powers, 1987). The maximal accumulation of actin filaments is observed close to the apical cell border, in association with the cadherin-based *zonula adherens*, and acto-myosin contraction at this level has been indicated as an important motor in apical surface reduction (Ampartzidis et al., 2023; Escuin et al., 2015; Martin and Goldstein, 2014; Sawyer et al., 2011). This apical constriction would be more relevant in highly-bent areas of the neural plate, when they exist, such as the ventromedial and the dorso-lateral hinges. Here, other cell processes, like basal positioning of nuclei and localized programmed cell death were also shown to contribute to epithelial bending, highlighting the importance of regulating cell crowding during neurulation (Roellig et al., 2022; Smith and Schoenwolf, 1988).

It is not surprising, then, that several polarized actin-modulating proteins have been demonstrated to be necessary for primary neurulation. Among these are the MARCKS family members. MARCKS (Myristoylated Alanine Rich C-Kinase Substrate) and MARCKS-Like 1 are ubiquitous proteins present only in vertebrates, which simultaneously interact with the plasma membrane and actin filaments (Arbuzova et al., 2002; El Amri et al., 2018). Phosphorylation by PKC (or interaction with calcium-calmodulin) causes MARCKS to detach from the membrane and to lose one of the two actin-binding sites (McLaughlin and Aderem, 1995). Hence, MARCKS acts as a molecular switch connecting extracellular signals to the cell cortex. Disruption of MARCKS family protein expression causes severe neurulation defects in both mice and zebrafish embryos (Chen et al., 1996; Prieto and Zolessi, 2017; Stumpo et al., 1995). Further, we found that MARCKS is accumulated at the apical membrane in neural plate cells of the chick embryo only during neural tube closure, and that its knockdown causes a failure of neural tube closure (Aparicio et al., 2018; Zolessi and Arruti, 2001). Interestingly, the local cellular phenotype observed in these embryos was very similar to the effect obtained after treatment with a strong agonist of PKC, the phorbol ester PMA: loss of apico-basal cell polarity accompanied by apical cell extrusion. This effect of PMA was effectively rescued by the expression of a non-phosphorylatable form of MARCKS, where all serines at the ED were substituted by asparagines (Aparicio et al., 2018).

Apical cell extrusion, that is, the expulsion of a cell through the apical side of the epithelium,

has been generally reported as an active mechanism for maintaining epithelial density and

integrity, and involves biochemical and mechanical signaling such as the secretion of

sphingosine-1-phosphate (S1P) by extruding cells, which activates Rho and actomyosin in

neighboring cells (Eisenhoffer and Rosenblatt, 2013; Nanavati et al., 2020). One function of

this process is the elimination of dying cells from the epithelium ("apoptotic cell extrusion"),

and implies medium-scale epithelial topological irregularities, pulsatile contractions and loss

of tissue tension (Atieh et al., 2021; Saw et al., 2017), together with the local activation of

lamellipodial protrusions and the assembly of a basally-localized contractile actomyosin ring,

in a cadherin-dependent manner (Duszyc et al., 2021; Lubkov and Bar-Sagi, 2014; Rosenblatt

et al., 2001). Conversely, "live apical cell extrusion" appears as a counterbalancing mechanism

to avoid cell overcrowding in a proliferating cell population, and occurs regularly in many

physiological processes of epithelia, like in cell shedding in intestinal microvilli and in the

control of carcinogenic transformation (Madara, 1990; Tanimura and Fujita, 2020). It requires

stretch-activated ion channels (Piezo), S1P and the Rho-myosin pathway, and also produces

regular topological changes in the organization of the epithelium, based on the collective

action of surrounding cells (Eisenhoffer et al., 2012). During this type of extrusion, the cell

being expelled remains alive and plays an active part in the process, eventually dying by

anoikis after the extrusion has been completed (Marinari et al., 2012; Slattum and Rosenblatt,

2014).

Taking all this information, we wondered if apical cell extrusion of neuroepithelial cells upon

MARCKS knockdown or PKC activation could be a live cell extrusion mechanism related to an

imbalance in the mechanical forces in the cell population. This could be caused either by the

alteration of the actin cytoskeleton or by the downregulation of apico-basal cell polarity. By

pharmacologically inhibiting caspase activity on PMA-treated chick neurulas, we demonstrate

here that the observed massive apical cell extrusion is mediated by a live mechanism.

Secondly, we aimed at explaining the experimental observations by generating a theoretical

model and performing computational simulations. We present an expanded 2D vertex model

of a pseudostratified epithelium, to show that alterations in the balance of forces imposed to

cells on the apical or basal plasma membrane domains compared to lateral domains, was

enough to robustly obtain situations that could only be solved by massive cell extrusion.

## 2. Methods

### 2.1. Embryo culture

Wildtype chicken eggs were provided by a local producer (PRODHIN) and incubated at 37° C for at least 28 h, corresponding to stage HH 8 (Hamburger and Hamilton, 1951). Chick embryos were cultivated *ex ovo* with ventral side up over a semi-solid agar/albumen substrate in 35 mm Petri dishes using the EC culture technique (Chapman et al., 2001). Cultured embryos corresponding to stages lower than HH8-/8 were incubated until they reached the desired stage. A total of 72 embryos were processed, spread across five experiments.

### 2.2. Pharmacological treatments

Cultured embryos were divided into four groups according to treatment: those receiving treatment with PMA, QVD-OPh, neither (control) or both (double, PMA+QVD). Stock solutions were prepared for PMA (Sigma-Aldrich P-8139) at 5 mM and QVD-OPh (MedChem Express #HY-12305) at 20 mM, both diluted in 100% DMSO.

All embryos were pre-incubated for 30 min. at 37° C with a 20 µl drop containing either 0,83 % DMSO in 1x PBS (control and PMA) or 167 µM QVD-OPh (1:120 dilution; QVD-OPh and double), applied ventrally. Afterwards, the excess liquid was removed and embryos were moved to a new culture dish containing 0.93% DMSO (control), 5 µM PMA (1:1000 dilution) and 0.83% DMSO (PMA), 167 µM QVD-OPh and 0.1% DMSO (QVD-OPh) or PMA and QVD-OPh (double) embedded in the substrate. Additionally, a new 20 µl droplet containing either DMSO or QVD-OPh was applied as before. Embryos were then incubated for 3 h at 37° C.

### 2.3. Cryo-sections

After incubation, embryos were collected and fixed in 4% paraformaldehyde (PFA, in 1x PBS) at 4° C overnight. Excess tissue was then cut and excess PFA was removed by washing 3x with 1x PBS for 1 h. Embryos were cryoprotected by being incubated first in a 5% sucrose/PBS for 3 h and then in a 20 % sucrose/PBS solution at 4° C overnight, and were then embedded in a medium containing 7.5 % gelatin and 15 % sucrose dissolved in PBS, in a 35 mm Petri dish. Gelatin was left to set at room temperature and then stored at 4° C for up to a few days. Blocks were cut from these media and frozen using liquid nitrogen. 10 µm transversal slices

190 were cut from these blocks using a cryostat (Reichert-Jung Cryocut E) at -21° C and placed

191 onto gelatinized microscope slides (0.5 % gelatin, 0.05% chrome alum in water).

**2.4. Immunofluorescence**

Indirect immunofluorescence on the slices was performed following (Stern and Holland,

1993). All antibodies were diluted in a 1 % BSA/PBS solution. Primary antibodies used were

rabbit anti-MARCKS (1:1000, Toledo et al., 2013), rabbit anti-cleaved Caspase 3 (1:200, Cell

Signaling Technologies #9661), rabbit anti-γ tubulin (1:100, Sigma-Aldrich #T5192) and mouse

anti-ZO-1 (1:50, Invitrogen #33-9100). Secondary antibodies used were anti-rabbit Alexa 488

(1:500, Invitrogen #A21206) and anti-mouse Alexa 488 (Invitrogen #A11001). Phalloidin-TRITC

(1:8000-10000, Sigma) was included during the incubation with secondary antibodies.

Hoechst 33342 DNA staining was performed during the final PBS washes.

**2.5. Image Acquisition and processing**

Slices were mounted for imaging using 70 % glycerol in Tris buffer (20 mM, pH 8), covered

with a coverslip and sealed using nail polish. Imaging was performed on a confocal Zeiss LSM

800 microscope using a 20x (dry, NA = 0.8) or 25x (glycerol immersion, NA = 0.8) objective

lens. Images consisted of stacks of optical sections every 1 μm, in slices corresponding

approximately to the fourth somite. Image processing and analysis was done using FIJI

(Schindelin et al., 2012).

**2.6. Cell extrusion and cell death quantification**

In order to determine the number of embryos exhibiting cell extrusion and indications of cell

death (pyknotic nuclei and cleavage of caspase 3), mounted slices were examined under a

Nikon Microphot FXA epifluorescence microscope, using 20x (dry, NA = 0.75) and 40x (dry,

NA = 0.95) objective lenses. Extruded cells were identified as lying apical to the actin

accumulation line corresponding to the apical side of the neuroepithelium in normal

conditions, occasionally checking nuclear staining for confirmation. In order to determine that

an embryo had not experienced any cell extrusion, four different nearby slices were checked.

Counting of pyknotic nuclei and cells showing cleaved caspase 3 (i.e.: those labelled with the

anti-cleaved caspase 3 antibody) was done in four nearby (non-damaged) slices of each
embryo and adding the resulting numbers.

**2.7. Protein distribution quantification**

Starting with stacks of optical sections, distribution of fluorescent signals was determined
from average intensity projections of three slices. Our region of interest was the mostly flat
section of the neural plate adjacent to the medial hinge. Images were then rotated so as to
make the apical side of our region of interest face left, and from there, the fluorescence
profile was obtained along an approximately 20 µm wide transect (71 px, corresponding to
20.09 µm). Background signal intensity was obtained as the mean intensity of a 40 px square
outside the tissue and subtracted from all values.

Phalloidin intensity profiles in control embryos typically showed two peaks corresponding to
the basal and apical side of the tissue respectively, which we used to define these regions in
the apico-basal axis. The apical region was defined as the interval within 9 px (2.5 µm) of the
appropriate phalloidin signal maximum, which was observed to correspond approximately to
a 50 % decrease in signal intensity in control embryos. The sub-apical region was defined as
the interval between the basal phalloidin maximum and the apical region. In cases with
cellular extrusion more apical peaks were observed, but a peak corresponding to the apical
side of non-extruded cells was usually identifiable. Analysis of the tissue morphology was used
to clear any doubts regarding multiple possible basal or apical peaks.

The ratio of apical to sub-apical signal for MARCKS and ZO-1 immunostaining was then
calculated as the largest value found in the apical region divided by the average value in the
sub-apical region.

**2.8. Statistical analysis**

Statistical analyses were performed for the values for the ratio of the maximum
immunofluorescent signal intensity in the apical regions relative to the average signal
intensity of the sub-apical region for both MARCKS and ZO-1 for each experimental condition,
using GraphPad Prism (version 8.0.2 for Windows; GraphPad Software, Boston,
Massachusetts USA, www.graphpad.com). All distributions passed the Shapiro-Wilk,

Anderson-Darling and D'Agostino & Pearson lognormality tests ($\alpha$ = 0.05), with the exception

of the MARCKS distribution in control embryos, in which N was too small for the Anderson-

Darling and D'Agostino & Pearson tests. Differences of means between pairs of experimental

conditions were determined using Welch's t-test for the natural logarithm of the presented

values.

**2.9. Theoretical description**

We based our model on the augmented vertex model previously described by Kim et al. (2021,

2024), in which cell-cell interfaces are represented by vertices joined by straight edges, and

nuclei are represented as solid-like objects constrained by the cell membrane. While this kind

of model has usually been used to represent the apical surface of epithelia, our work

represents the epithelium as a lateral cross-section, similar to those presented in the

experimental results. Our 2D model is based on an energy functional (Eq. 1) depending on all

cell areas, the length of all cell-cell (or cell-exterior milieu) interfaces and the total

"overlapping" radial distance of a cell's nucleus with respect to its membrane, integrated

along the cell's contour.

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$$E = \sum_{i,j} T_{ij}L_{ij} + \sum_{i} K \left( \frac{A_i}{A_0} - log\left(\frac{A_i}{A_0}\right) \right) + \frac{1}{2}K_n \oint_{\partial C_i} (R_i(s) - r_i(s))^2 H(R_i(s) - r_i(s))\, ds \quad (1)$$

where $L_{ij}$ and $T_{ij}$ are the length and the surface tension of the interface between cells $i$ and

$j$ respectively, $K$ is the cell compressibility modulus which measures how much pressure the

cell exerts while being compressed, $A_i$ is the area of cell $i$, $A_0 = K/P_0$ is a characteristic area

based on $P_0$ the external medium's pressure, $K_n$ is the nuclear elastic modulus which

determines the repulsion force generated when the nucleus overlaps the cell boundary, $r_i(s)$

is the distance measured from the center of the nucleus of cell $i$ to a point in the cell boundary

$\partial C_i$ (parametrized by arc-length $s$), $R_i(s)$ is the distance between the nuclear center and its

border in the same direction, and $H(x)$ is the Heaviside function, which ensures only points

in which the nucleus overlaps its cell's membrane are included in the line integral (taken over

cell's $i$ membrane $\partial C_i$). The first sum is over all cell-cell (and cell-exterior) interfaces $ij$, the

second one over all cells $i$. Note that in the case of a circular nucleus, $R_i(s)$ is simply the

nucleus' radius (see a graphical description in Figure 1).

### 2.10. Simulations

All simulations were based on a non-dimensionalized version of $E$ (Equation 1; Appendix A.1) defining certain characteristic scales: $P_0$ (pressure of the external medium), $T_0$ (surface tension of cell-cell interfaces), $L_0 = \sqrt{A_0} = \sqrt{K/P_0}$ (characteristic length-scale) and $\tau_R$ (characteristic timescale for vertex relaxation). When not explicitly stated, we followed Kim et al. (2024) in their estimation for all corresponding parameters. Assuming a viscous medium where frictional forces dominate, the positions of all vertices follow first-order differential equations in which velocities are proportional to the sum of all non-viscous external forces (Odell et al., 1981). These forces may be obtained as the negative gradient of $E$ with respect to their respective positions. The same can be applied to nuclei, which are defined as solids by their centers of mass and rotation angles, with this last variable being ignored by considering only circular nuclei in all simulations.

Dynamic simulations were carried out using custom scripts written for GNU Octave (Eaton et al., 2020) by numerically integrating these first-order differential equations using the Euler method with a time step $\Delta t = 0.005\,\tau_R$. Unless stated otherwise, all simulations were initialized with periodic boundary conditions of length $\lambda = 10$ and with $N = 20$ rectangular cells of area 1, a limit of our computational implementation. Edge length was maintained by adding or joining vertices between 1/16 and 1/8 of the average cell width, defined as $b = \lambda/N$. In the cases in which this resulted in the formation of a 4-fold vertex, a T1 transition (neighbour exchange; necessary for extrusion in our model) was evaluated and computed using the method described by (Duclut et al., 2021). The surface tension of all apical and basal interfaces was defined as $T_a$, relative to $T_0$. Whether the system had reached an equilibrium state was determined by qualitatively checking whether the energy had stabilized to a minimum over time.

In addition to these dynamical simulations, we analyzed the dimensionless energy minima for a simplified tissue made up of wedge-shaped cells without nuclei under different values of parameters $T_a/T_0$ and $b$ (inversely related to the tissue's cell density).

## 3. Results

### 3.1. Experimental assessment of the mode of apical cell extrusion in PMA-treated embryos

With the aim of elucidating if the PMA-induced apical cell extrusion in the neural plate was live or apoptotic extrusion, we set up the conditions for treating neurulating chick embryos simultaneously with PMA and the pan-caspase inhibitor QVD-OPh. Since both drugs must be administered solubilized in DMSO, and given the relatively low dilution rate needed for QVD-OPh, we used the lowest possible amount of DMSO which did not cause obvious effects on embryo or cell survival: 0.93%. In these conditions, control embryos developed normally, not showing delays in general development or neurulation (Fig. 2A). Widespread apical cell extrusion was observed throughout the neural plate in all embryos treated with PMA (n = 20) and those treated with both PMA and QVD-OPh (n = 20), while no cell extrusion was observed in control embryos (n = 15) or those under QVD-OPh treatment alone (n = 17) (Fig. 2B).

As expected, PKC activation with PMA caused in all cases a redistribution of MARCKS from the plasma membrane to the cytoplasm, in addition to a loss of its apical accumulation (Fig. 3A). QVD-OPh-only treated embryos, on the contrary, showed a MARCKS distribution that resembled control embryos. To further check the effect of these treatments on apico-basal polarity, we decided to analyze the distribution of the sub-apical cell adhesion–associated protein ZO-1. As previously reported (Aparicio et al., 2018), PMA treatment provoked a clear loss of apical accumulation of this apical marker, and this was not affected by co-incubation with QVD-OPh (Fig. 3B). In order to compare apical protein accumulation across the different treatments, we measured the ratio of apical signal with respect to the average sub-apical signal intensity for both proteins, MARCKS and ZO-1 (see section 2.7). QVD-OPh-only-treated embryos showed a similar distribution to control embryos, while those treated with PMA exhibited a significant decrease in apical protein accumulation (Fig. 3C). Similarly, double treated embryos showed a significant difference with respect to embryos treated only with QVD-OPh. These results further indicated that treatment with the anti-apoptotic drug did not affect cell extrusion or cell polarity by itself.

DNA staining indicated the presence of few scattered apparently dying cells in all embryonic tissues, at all treatment conditions. But, as previously described (Aparicio et al., 2018), PMA treatment greatly increased the number of pyknotic nuclei mostly on cells extruded from the neural plate (see Fig. 3B, for example). This was confirmed by immunolabeling of activated

Caspase 3 (Fig. 4A). Most of these dying cells were observed beyond the apical border of the

mass of extruded cells, indicating they were detaching from the epithelium. The double

treatment of embryos with PMA and QVD-OPh, on the other hand, showed a sharp reduction

in cell death as assessed by quantifying both parameters, demonstrating that the observed

apical extrusion happens independently of cell death in these embryos, and can be defined

as live cell extrusion (Fig. 4B).

**3.2. Computational model of a pseudostratified epithelium and conditions leading to cell**

**extrusion in the simulation**

Since our experimental results support the idea that PMA treatment causes live cell extrusion

during development, we focused on determining the conditions under which an epithelium

like the neural plate could become mechanically unstable, leading to the elimination of live

cells from the tissue. Our first goal was to produce a model which could reproduce the

morphology of pseudostratified epithelia, that is, a single layer of columnar cells in which the

nucleus occupies a large proportion of the cell volume, resulting in curved cell-cell interfaces

shaped so as to accommodate all nuclei at different heights along the apico-basal axis. We

are not considering in the model the continuous cell shape changes that would be caused by

interkinetic nuclear migration in a living neuroepithelium because the experimental time-

scale of the PMA-induced cell extrusion (less than 3 h) is much shorter than the average

extension of the cell cycle in this cell population (8-12 h; Schoenwolf, 2018).

In order to achieve this, we developed a modification of the augmented vertex model

originally described by Kim and collaborators to represent the dynamics of epithelia from an

apical point of view (Kim et al., 2024, 2021). In our version of the model, we chose to represent

a lateral view of an epithelial tissue under periodic boundary conditions (Fig. 5A). The model

consists of a set of cells and solid-like nuclei for which an energy functional $E$ is defined, which

depends on the different cell areas, boundary lengths and position of the nuclei within the

cell (see section 2.9 and Equation 1). Although we followed the force-based model of Kim et

al. (2021, 2024) in defining this energy, the forces arising from our description are not

necessarily identical to theirs, particularly in the case of the nuclear repulsion forces (for

example, our calculations are based on vertices, not edges; see Appendix A.3). It can be

proven that in the absence of nuclear repulsion forces, the angle between adjacent edges at

equilibrium depends only on the interface they belong to (Appendix A.2). As a corollary, all

interfaces not overlapping with a nucleus should approximate circular arcs at equilibrium. This

indicates that an equilibrium state resembling a pseudostratified morphology could only be

observed in cells with nuclei larger than the average cell width $b$, defined in this model as the

dimensionless length of the tissue in the *x*-axis divided by the total number of cells. Supporting

this, our initial dynamical simulations showed that cell layers containing no nuclei reached an

equilibrium state consisting of identical columnar cells with straight cell-cell and convex cell-

medium interfaces (Supplementary Fig. 1). This happened in less than twice the characteristic

timescale for vertex relaxation $\tau_R$.

Based on the previous considerations, we followed by performing initial exploratory

simulations including wide nuclei distributed alternatively in the model, so that a cell with an

"apical nucleus" (tangent to the initial apical boundary) has neighbors with "basal nuclei" and

vice versa (Fig. 5B). Ratios of the apical/basal surface tension ($T_a$) with respect to lateral

surface tension ($T_0$) of 1.5 or lower led to variable extensions of cell extrusion, with cells losing

either their apical or basal interfaces, depending on their initial nuclear position, and

stabilizing into a more rounded shape (Fig. 5B). Larger values of $T_a/T_0$, on the other hand,

allowed for the tissue to stabilize into a single layer of columnar cells with curved cell-cell

interfaces determined by the position of nuclei, corresponding to the pseudostratified

morphology we sought (Fig. 5B). At values just above this threshold, cells formed a single layer

but stabilized into a wedge-like shape with straight cell-cell interfaces, as would be expected

in the absence of nuclei or with nuclei located in a region of the cell wider than itself (see Fig.

5B for $T_a/T_0 = 2$). Parameters $b = 0.5, T_a/T_0 = 5$ prevented extrusion also in simulations

initialized under different nuclear distributions (Fig. 5C-E).

**3.3. Analysis of energetic minima in a simplified model**

While the dynamical described simulations suggest a qualitative relation between relative

surface tensions ($T_a/T_0$) and extrusion, we could not clearly express it in quantitative terms.

Furthermore, we are limited by our computational implementation in the parameter ranges

we can study, as well as by our lack of experimental measurements of these parameters in

this particular tissue. For example, even though we know the neural plate is a highly dense

tissue and suspect that this high density may be related to cell extrusion, we cannot perform

dynamical simulations to directly test this for our system.

To avoid these limitations, we looked for general stability conditions by constructing a

simplified version of our model for which we could better analyze equilibrium states and

stability. Based on the results obtained from simulations with alternating nuclei, we

considered a single-layered tissue formed by alternating wedge-shaped cells without nuclei

(Fig. 6A; see Appendix A.4). We assume these cells to have continuous straight cell-cell

boundaries (i.e.: no vertices), and their apical/basal interfaces to be circular arcs. Equations

can be derived for such a tissue in terms of two geometrical variables: cell height ($h$) and basal

width ($b_b$), under parameters $T_a/T_0$ (apical/basal surface tension relative to lateral surface

tension), $b$ (average cell width, the inverse of cell density) and $L_0$ (characteristic length,

related to the cell compressibility module $K$). Setting $L_0 = 10\,T_0/P_0$ initially as in our

dynamical simulations, we numerically computed the energy landscape for different cell

shapes. Assuming the final area will be less than 1, we considered $0 \le h \le 1/b$ and $0 \le b_b \le$

$2b$, between the limits where apical and basal extrusion occur. From these, we found the

values of $h$ and $b_b$ which minimized the energy of the system for different values of

parameters $b$ and $T_a/T_0$, and searched for ways in which these might be related to extrusion

or to single-cell layer stability.

We observe that this system is symmetrical in that a tissue with basal width $b_b$ is equivalent

to one with basal width $2b - b_b$, and that an energy minimum with $b_b = 0$ would lead either

to extrusion or to a persistent 4-fold vertex, usually considered to be mechanically unstable.

In general, low values of $b$ lead to energy minima with $b_b = 0$, and high values of $b$ lead to

$b_b = b$, with an intermediary transition range (Fig. 6B). For high values of $T_a/T_0$, this creates

an apparently clear division of the $b$ range into three connected regions, but this is not the

case for lower values ($T_a < 0.8\,T_0$, approximately), for which deviations may be observed. For

example, low values of $b$ may have a non-null equilibrium basal width $b_b$.

The cases in which $b_b = b$ correspond to a symmetrical equilibrium state which may be found

in simulations when cells do not interact with the nuclei (Supplementary Fig. 1). This state

always exists as a possible equilibrium solution, as equations for it can be found for all values

of $b$ as long as $T_a/T_0 > 0.5$ (Appendix A.5). We may define $b_0(T_a/T_0)$ as the maximum value

of $b$ for which the energy minimum occurs at $b_b = 0$ (or $2b$, equivalently) and $b_1(T_a/T_0)$ as

the minimum value of $b$ for which the energy minimum occurs at $b_b = b$.

Plotting both $b_0$ and $b_1$ against $T_a/T_0$ divides the parameter space into three regions

according to the different long-time behaviours of the system (Fig. 6C). The upper region

corresponds to $b_b = b$ (stable monolayer composed of columnar cells of constant width),

whiled the lower region corresponds to $b_b = 0$ (leading to extrusion). The distance between

them tends to 0 for large $T_a/T_0$ values. We observe that $b_1(T_a/T_0)$ follows a power-law

equation (Fig. 6D), and that the same can be said of $b_0(T_a/T_0)$ for sufficiently large values of

$T_a/T_0$,                         obtaining                         equations

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$$b_0 = k_0 \left(\frac{T_a}{T_0}\right)^{-\alpha_0} \quad and \quad b_1 = k_1 \left(\frac{T_a}{T_0}\right)^{-\alpha_1} \tag{2}$$

with $k_0 = exp(-0.4237) \approx 0.65$, $\alpha_0 = 0.5612$ (linear fit of log-log data with $R^2 > 0.998$ for

$T_a/T_0 > 1.6842$) and $k_1 = exp(-0.3729) \approx 0.69$, $\alpha_1 = 0.5761$ (linear fit of log-log data with

$R^2 > 0.999$). It should be noted that these values depend on the remaining parameter, the

cell compressibility modulus $K$, with $k_0, k_1$ increasing and $\alpha_0$, $\alpha_1$ decreasing as $K$ increases,

seemingly reaching an asymptote (Supplementary Fig. 2). We could not find similar simple

equations for other geometric parameters which might characterize the stability of the

system, such as the cell height or aspect-ratio ($b/h$) at equilibrium.

**3.4. Dynamic simulations of pseudostratified epithelia in conditions of near instability**

Because of our simplification, this classification does not take into account the nuclear

repulsion forces. Nevertheless, we may reasonably assume that for a system with nuclei to

have a stable one-layered equilibrium state, it should also be stable in the absence of nuclei.

Namely, in a highly dense tissue, where $b$ is low and $h$ is high, nuclei may be wider than $b$ but

much shorter than $h$, in which case they would only interact with a small number of vertices.

If this approximation is correct, then the curve $b_0$ should allow us to predict the threshold

value of $T_a/T_0$  needed to stabilize a tissue for a given $b$ even in the presence of nuclei. Our

data show that $b_0$ reaches a global maximum of $b = 0.6040$ between $T_a/T_0 = 0.8$ and $0.8167$,

meaning: (1) that extrusion should not happen in any system with $b > 0.6040$ and (2) that

every value $b < 0.6040$ has two possible threshold values for extrusion. We tested both

situations by performing dynamical simulations using $b = 0.5$ and $b = 10/16 = 0.625$ (Fig.

7A).

Our data predict that $b_0 = 0.5$ when $T_a/T_0 = 1.527$ (Fig. 7A), meaning that systems with $b =$

$0.5$ should be unstable for $T_a/T_0 \leq 1.527$ and stable for larger values, which agrees with our

results for alternating nuclei (Fig. 7B,C; Supplementary Videos 1-2). Simulations using

different initial nuclear distributions produced mixed results, with extrusion being prevented

under a "staircase" distribution but not under random distributions (Fig. 7B) which had shown

to be stable far away from this theoretical threshold, at $T_a/T_0 = 5$ (see Figure 5C-E). As

mentioned above, there exists another possible threshold value for $b = 0.5$, meaning that

extrusion should be prevented in a system with $T_a/T_0 = 0.55$. Nevertheless, extrusion was

observed in this case along with simulation artefacts, indicating a limitation of our

computational implementation (Fig. 7D). In agreement with our predictions, on the other

hand, no extrusion was observed in the case where $b = 0.625$ when starting with an

alternating distribution of nuclei, even for a low $T_a/T_0$ value (Fig. 7E,F). Taken together, these

results partially validate our approximation but point to a dependence between the initial

distribution of nuclei and the actual stability threshold.

## 4. Discussion

It was previously shown that MARCKS knockdown, or its phosphorylation upon PMA treatment, induced a loss of apico-basal polarity and extensive apical cell extrusion in the neural plate of chick embryos. This happened without an evident increase in cell death, except for cells that appeared completely detached from the epithelium, suggesting a live cell extrusion mechanism (Aparicio et al., 2018). In the present work, we have confirmed this to be the case: cell extrusion covering the full width of the neural plate occurred in all embryos under PMA treatment even when apoptosis was effectively inhibited with the anti-apoptotic drug QVD-OPh. Despite similar amounts of extruded cells, the treatment produced a near-total loss of signs of cell death. This allowed us to conclude that the observed apical cell extrusion occurred independently of apoptosis, indicating this to be an example of live cell extrusion that could be explained by mechanical alterations in the neuroepithelium (Eisenhoffer et al., 2012; Eisenhoffer and Rosenblatt, 2013).

Having cleared this point experimentally, we decided to proceed with a theoretical model of the neuroepithelium which could reproduce a pseudostratified morphology and show cell extrusion purely as a product of an imbalance of mechanical forces along the apico-basal cell axis. Previously published models, along with experimental studies, have pointed to losses in apical surface tension, tissue irregularities (i.e.: anisotropy and topological defects) and high in-plane cell densities as important conditions determining the occurrence of cell extrusion (Drozdowski and Schwarz, 2024; Marinari et al., 2012; Okuda et al., 2010; Saw et al., 2017). Excluding apical tension, the mechanical meaning of such predictors becomes difficult to discern in pseudostratified epithelia, where cell density is much higher than in previously considered situations and where cells develop complex three-dimensional shapes and arrangements in order to accommodate high nuclear densities (Gómez et al., 2021). Furthermore, these geometrical characteristics have been largely simplified or ignored by prior models of pseudostratified epithelia (Hecht et al., 2022; Ishii et al., 2021).

Although simulated extrusion may not perfectly reflect the *in vivo* mechanisms, we may use the model to find conditions under which a pseudostratified morphology might become unstable in a mechanical sense, leading to a live cell extrusion-like behavior. We found that a low ratio of apical/basal to lateral interfacial surface tension ($T_a/T_0$) led to widespread extrusion, while higher values prevented it. In particular, when wide nuclei (i.e.: wider than

the average cell width) were present and $T_a/T_0$ was sufficiently large, the tissue reached an

equilibrium state which was reminiscent of a pseudostratified epithelium: a single layer of

cells with curved boundaries shaped so as to accommodate all nuclei at different heights

along the apico-basal axis.

With these considerations in mind, the results obtained from our model would suggest that,

under normal conditions, the surface tension in apical and basal interfaces must be larger

than that in lateral cell-cell interfaces so as to mechanically stabilize the pseudostratified

morphology. To quantitatively assess this, we approximated the stability of cells in a dense

tissue where the nucleus mechanically interacts with a small fraction of the cell's surface by

analyzing a simple tissue composed of identical wedge-shaped cells without nuclei. Under this

simplification, we found that the minimum average cell width $b_0$ required for a tissue with

relative apical/basal surface tension $T_a/T_0$ to be stable approximately follows a power law,

with parameters depending on the cell compressibility modulus $K$. This approximation, while

correct for large values of $T_a/T_0$ or $b$ and certain regular nuclear distributions, was not enough

to predict cell extrusion in general, particularly when nuclei had random initial positions which

had been shown to be stable under higher $T_a/T_0$ values. These results serve to point out the

limitations of our approximation and show that the exact conditions for extrusion may

depend on the actual nuclear distribution adopted by the tissue. Unlike alternating nuclei,

some configurations require nuclear rearrangements to reach stability, particularly those with

initially overlapping nuclei such as the random distributions tested here. In our model these

rearrangements would alter the force balance on the cell boundary in complex ways, which

may explain these differences in stability thresholds. The importance of nuclear positioning,

as well as the forces it exerts on the cell cortex through interactions with the cytoskeleton,

have been experimentally demonstrated in different epithelial morphogenetic processes

(Ambrosini et al., 2019; Ferme et al., 2025; Roby and Rauzi, 2025).

Although the relative simplicity of this theoretical model does not reflect most of the complex

features of a real epithelium, the concomitant inclusion of a surface tension and a non-

deformable nucleus can be used to simulate morphogenetic processes in which both factors

are important (Kim et al., 2024). Deformability is nevertheless an intrinsic property of living

cell nuclei, although with some limitations (Kalukula et al., 2022). Interestingly, in the

extension of the Drosophila embryo germband, the simultaneous genetic alteration of

nuclear deformability and the pharmacological destabilization of microtubules, affecting

nuclear positioning in the apico-basal cell axis, causes both morphogenetic defects and cell

extrusion (de Leeuw et al., 2024).

Based on the previous analysis, we can give an interpretation of our experimental results

simply by assuming that PMA treatment alters the relative surface tension of the apical

and/or basal interface (e.g.: by diminishing apico-basal polarization in each cell) without

altering cell compressibility. The change required to destabilize the single-layered

morphology of the tissue would imply reducing $T_a/T_0$ so that the new minimum stable cell

width $b_0^{PMA}$ became larger than the average cell width $b$ of the tissue. Furthermore, although

the previous approximation of the tissue as formed by wedge-shaped cells no longer applies

to the whole tissue once extrusion begins, we may use it to approximate only the basal-most

layer of cells, for which the main effect of extrusion is to reduce the cellular density, that is,

to increase $b$. If extrusion eventually stops and the tissue reaches a new stable state, then the

average cell in the basalmost layer should reach an expected final width greater than $b_0^{PMA}$.

In this simplified explanation, both the occurrence and the extent to which cell extrusion

happens should be mainly determined by the relative decrease in the value of $T_a/T_0$ due to

PMA treatment, a consequence of the approximate power-law structure of the stability

threshold.

When extrapolating these observations to the living tissue, we could assimilate polarized

changes in surface tension to alterations in cell polarization (Moazzeni et al., 2025; Narayanan

et al., 2023). Treatment with PMA causes a loss of apico-basal cell polarity, evidenced by a

redistribution of the apical marker ZO-1, as well as of actin filaments. As expected, there was

also a re-localization of the main PKC substrate MARCKS, previously shown to be in great part

responsible for PMA-induced cell polarity downregulation and cell extrusion in the chick

neural plate (Aparicio et al., 2018). Evidence from this previous work also indicated that the

PMA effect on these cells could involve a destabilization of cortical actin filaments, probably

leading to a general reduction in cell surface tension (Chugh et al., 2017). This cortical actin

destabilization could be explained by an alteration in MARCKS function owed to its

phosphorylation at the effector domain by PKC, blocking its ability of sequestering $PIP_2$ at the

plasma membrane (Laux et al., 2000). Different lines of evidence have linked MARCKS to the

modulation of epithelial cell mechanical stability, and its involvement in processes such as

morphogenesis and carcinogenesis (Veloz et al., 2021). All the mentioned experimental
evidence points to an effect of PMA mostly on apical membrane tension, given the high apical
accumulation of MARCKS and actin filaments in neural plate cells, and that the basal
membrane domain is tightly associated to a rigid external scaffold, the basal lamina.

In summary, we have presented here evidence of the occurrence of live cell extrusion in the
neuroepithelium during neurulation, which could be caused by a reduction in cortical actin
cytoskeleton integrity and a concomitant down-regulation of apico-basal cell polarity. In order
to find a way of explaining these results within a mechanical framework, we have introduced
an expanded energy-based vertex model allowing for the presence of nuclei and curved
interfaces which is able to represent pseudostratified epithelial morphology. In line with
previous research, our work points to a high relative apical/basal surface tension as being the
main stabilizing factor against cell extrusion in high-density tissues such as the developing
neural plate. Furthermore, we derive a novel approximate condition for live cell extrusion
relating cell density and surface tension, which follows a power-law equation. Measurements
of surface tensions and cell densities in the developing neural plate could help validate these
results and contrast our approximation with other similar pre-existing models.

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**Author contributions**

SABR: Conceptualization, Data curation, Formal analysis, Investigation, Methodology, Software, Writing – original draft, Writing – review and editing; JAH: Conceptualization, Formal analysis, Methodology, Supervision, Writing – review and editing; FRZ: Conceptualization, Data curation, Formal analysis, Funding acquisition, Methodology, Project administration, Resources, Supervision, Writing – original draft, Writing – review and editing.

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**Data availability statement:** Original data and custom scripts written for GNU Octave are available at: Bosch, Santiago; Hernandez, Julio; Zolessi, Flavio (2025), "Data for "Mechanical conditions preventing live cell extrusion during primary neurulation in amniotes"", Mendeley Data, V1, doi: 10.17632/pc7ytf2xt7.1. Other data and materials are available from the corresponding author upon reasonable request.

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**Figure 1: Diagram of terms included in the energy equation of our model.** Here the vertices defining the boundary of cell i are represented along with its nucleus and its neighboring cells, similar to our simulation results. The first energy term in Eq. 1 depends on interface length $L_{ij}$ which depends on the cells involved in the interface (e.g.: ij, ik, ig, as shown here). Apical and basal surfaces are here composed of yellow and orange vertices, with lengths marked as $L_i^a$ and $L_i^b$ respectively. The third term in Eq. 1 corresponds to interactions with the nuclei and depends, for every point in the cell boundary, on its distance from the nuclear center $r_i$ and on $R_i$, the "radius" of the nucleus in the same direction. Note that this third term is only non-zero when $R_i > r_i$, i.e.: when the nucleus overlaps the cell boundary.

**Figure 2: Comparison of chick embryos after treatment with PMA and QVD-OPh**. **A.** Macroscopic view of treated embryos. Embryos treated with the pan-anti-caspase drug QVD-OPh seemed to develop similarly to Control embryos. Those treated with PMA, both alone and together with QVD-OPh, showed several defects, as described previously (Aparicio et al., 2018), including decreased length, neural tube closure failure and abnormally open anterior (filled arrowheads) and posterior (hollow arrowheads) neuropores. Scalebar: 1 mm. **B.** Transverse sections of the neural plate and adjacent tissues. Control and QVD-OPh-treated embryos displayed a thick pseudostratified epithelium. Treatment with PMA (including double treatment with QVD-OPh) produced widespread apical cell extrusion, evidenced by the presence of cells beyond the line of F-actin accumulation (dashed line; corresponding to the apical side of the layer of cells attached to the basal lamina), which are present along all regions of the neural plate. Scalebar: 50 μm

**Figure 3: Distribution of MARCKS and ZO-1 along the apico-basal axis of the neuroepithelium.**  Intracellular distribution of MARCKS (**A**) and ZO-1 (**B**) in different experimental conditions. Both proteins accumulate near the apical side in control embryos, but have seemingly altered distributions under PMA and PMA + QVD-OPh double treatment, sometimes even presenting anomalous accumulations away from the line of F-actin accumulation (arrowheads). **C**. Example of intensity profiles used to determine the fluorescence intensity around the apical border (in gray; defined as the area of maximal F-actin accumulation) and along the sub-apical portion of the neuroepithelium in different

conditions (only control condition example is shown). **D**. Plots for the ratio of the maximum

immunofluorescent signal intensity in the apical regions relative to the average signal

intensity of the sub-apical region for both proteins. Data shows significant differences

between the geometric mean values for PMA-treated embryos with respect to Control (p-

values = 0.0416 (ZO-1); 0.0279 (MARCKS)) and QVD-OPh-treated embryos (p-values = 0.0044

(ZO-1); <0.0001 (MARCKS)), and between QVD-OPh- and double-treatment embryos (p-

values = 0.0233 (ZO-1); 0.0390 (MARCKS), indicating altered apico-basal polarity. Data are

presented along with geometric mean and geometric standard deviation.

**Figure 4: Occurrence of cell death among different experimental conditions. A**.  Examples

taken from slices of embryos treated with PMA or PMA + QVD-OPh, illustrating the

differences in signs of cell death. In PMA-treated embryos cells undergoing cell death were

often observed, as indicated by the presence of pyknotic nuclei and/or caspase-3 activity

(arrowheads). **B**. The number of pyknotic nuclei and cells displaying active caspase-3

immunodetection was higher in PMA-treated embryos than in all other experimental

conditions. Most notably, double treatment with PMA and QVD-OPh abolished cell death

while still inducing widespread cell extrusion. The dashed line marks the line of F-actin

accumulation, corresponding to the apical side of the layer of cells attached to the basal

lamina. Filled arrowheads: Cells exhibiting both pyknotic nuclei and active caspase-3. Hollow

arrowhead: A cell with a pyknotic nucleus but no active caspase-3 immunoreactivity. Data

presented along with median and 95% confidence interval.

**Figure 5:  Dynamic simulations of pseudostratified epithelia including nuclei, using the**

**energy model. A.** Diagram depicting the state of a typical system at time t as obtained by

dynamical simulation. Vertices are colored according to the type of interface they belong to

(cell-cell interfaces are blue, while apical and basal interfaces are orange and yellow,

respectively), and each cell contains a nucleus tagged according to the cell number. Periodic

boundary conditions are used in the x-axis. Both axes are taken to be relative to the

characteristic length scale $L_0 = \sqrt{A_0}$. **B.** Long-term behavior of dynamic simulations in tissues

with 20 cells, and an average cell width b = 0.5, under different values of $T_a/T_0$. All simulations

start from a layer of identical rectangular cells with area $A_0$ (= 1) and alternating nuclei, and

are left to run for 20 characteristic time-lengths ($\tau_R$). These initial and final states are marked

as $t_0$ and $t_f$, respectively. Energy profiles indicated an apparent equilibrium state for all cases

except for when $T_a/T_0 = 1.5$. For low values of $T_a/T_0$, a single layer morphology is unstable

and cell extrusion ensues, while for larger values the single layer is maintained at equilibrium.

For values larger than 5, a stable equilibrium solution resembling the pseudostratified

epithelial morphology is reached. **C-E.** Simulations were performed at this stable value of

$T_a/T_0 = 5$ for other nuclear configurations, all of which also proved stable in these conditions:

a "staircase" distribution with intermediate nuclei (**C**) and different random nuclear

distributions (**D,E**).

**Figure 6: Long-term stability analysis for a monolayer composed of identical alternating**

**wedge-shaped cells with no nuclei in terms of tissue parameters. A**. To study the stability of

a simple cell layer we consider an infinite tissue made up of alternating, identical wedge-

shaped cells. The shape of one of these cells may be determined by its height ($h$) and its basal

width ($b_b$), assuming that the apical and basal interfaces correspond to circular arcs and that

cell-cell interfaces are straight. The width of any two adjacent cells adds up to double the

average cell width $b$, which is the inverse of cellular density. For each set of parameters, we

find the basal width and height that minimize the total tissue energy. **B.** Value of the basal

width $b_b$ (expressed as a fraction of average cell width $b$) corresponding to the energy

minimum vs $b$, here represented for different values of the ratio between apical/basal and

lateral surface tension $T_a/T_0$. Although for low values of $T_a/T_0$ these graphs seem more

complex, for values larger than 0.87, the plot of $b_b/b$ vs $b$ seems to be divided into three

distinct ranges: a low range where $b_b = 0$, a middle range, and a high range where the energy

minimum corresponds to $b_b = b$. Values $b_0$ and $b_1$ limit the low and high ranges for each

$T_a/T_0$ (arrowheads). **C**. Plot of $b_0$ (blue dotted line) and $b_1$ (orange dotted line) as functions

of $T_a/T_0$. For sufficiently large $T_a/T_0$, systems with parameters lying in the region above the

$b_1$ curve have their energy minima when $b_b = b$ (epithelial stability) while those below $b_0$

tend to $b_b = 0$ at equilibrium, which leads to cell extrusion. C' shows the natural log-log plot

of $b_0$ and $b_1$ vs. $T_a/T_0$. Fitted (dashed) lines correspond to equations $log(b_0) =$

$-0.5612 \, ln(T_a/T_0) - 0.4237$ and $log(b_1) = -0.5761 ln(T_a/T_0) - 0.3729$. When

simulations yielded values of $b_b/b$ larger than 1, they were replaced by $2 - b_b/b$, making use

of the tissue apico-basal symmetry.

**Figure 7: Comparison between dynamical simulations and stability predictions based on a**

**tissue composed of wedge-shaped cells.** Dynamical simulations like those of Fig. 5 were run

here based on the quantitative analysis shown in Fig. 6, in and around the area in which

wedge-shaped cells are expected in equilibrium, close to the stability threshold. **A**. Detail of

$b_0$ and $b_1$ as functions of $T_a/T_0$, showing points corresponding to the simulations shown in B-

F. Dashed gray lines point to the threshold value found for $T_a/T_0$ at $b = 0.5$. The dotted gray

line marks the calculated value of $b = 0.604$, above which there would be no cell extrusion.

**B**. Starting with nuclei distributed alternatingly and $b = 0.5$, we observe cell extrusion for

$T_a/T_0 = 1.5$ (see Supplementary Video 1). **C.** Also at $b = 0.5$, we can have many different

outcomes for variable initial nuclear positions, at a tension ratio value that is slightly higher

than the predicted threshold ($T_a/T_0 = 1.6$). When nuclei start in an alternated position like

in B or in a "staircase" distribution, cell extrusion is prevented (Supplementary Video 2).

Random nuclear distributions, on the other hand, resulted in cell extrusion, as shown in the

two bottom examples. **D.** In dynamical simulations with $b = 0.5$ and $T_a/T_0 = 0.55$, not only

did cell extrusion occur (contrary to our predictions) but also artefacts were introduced in the

form of overlapping cell boundaries (arrowheads; detail in inset). **E,F**. Lowering cell density to

16 cells ($b = 0.625$) means the system should lie above $b_0$ according to our approximation

regardless of surface tension. Although in these conditions and $T_a/T_0 = 0.55$ the cells adopt

a rounded morphology, with a great expansion of one of their external surfaces, there is no

cell extrusion (E). When the tension ratio was increased to $T_a/T_0 = 1$, cells adopted a less-

extreme wedge shape, also without extrusion as expected (F).

Figure 1

# Figure 2

A

Control PMA QVD-OPh PMA + QVD

1 mm

B

F-Actin DNA

Control PMA 5 µM

50 µm

QVD-OPh 167 µM PMA + QVD

# Figure 3

# Figure 4

**A**

DNA      Active Caspase 3      Active Caspase 3 F-Actin DNA

PMA

PMA + QVD

20 μm

**B**

Pyknotic nuclei

Cells displaying caspase-3 activity

# Figure 5

# Figure 6

# Figure 7

# Supplementary Figure 1

a)

b)

**Supplementary Figure 1: Initial simulations performed without nuclei quickly reach equilibrium in less than $2\tau_R$.** (A) Starting from an initial configuration of *N* identical rectangular cells with unit area, a stable state was reached composed of cells with straight cell-cell and convex cell-exterior interfaces, here pictured for *N = 16, 18, 20* after 400 integration steps (equivalent to twice the characteristic time for vertex relaxation). This state was achieved even when the initial vertex distribution was not homogeneous, as in the case of *N = 18*. (B) Plot of energy E per cell in time. Initial and final values were quantitatively similar for all cases, although the relaxation time became larger the smaller the average cell width b, with $t_{50}$ (the time required to lose half the total lost energy) being $0.165\tau_R$, $0.235\tau_R$ and $0.27\tau_R$ for *N = 16, 18* and *20* respectively. Here we continued the simulation until $3\tau_R$, but we can qualitatively see that the system has reached equilibrium before that. $T_a/T_0 = 3$ for all shown simulations.

# Supplementary Figure 2

**Supplementary Figure 2: Dependence of curves** $b_0$ **and** $b_1$ **with parameter** $K$. (a) Plot of $b_0(T_a/T_0)$ and $b_1(T_a/T_0)$ for *K = 1, 25, 100*. Increasing $K$ makes $b_0$ and $b_1$ generally have larger values, although the difference becomes smaller for larger $K$. (b) Plot of $b0(K)$ and $b1(K)$ for $Ta/T0$ *= 1, 1.5*. As shown in (a), at each $T_a/T_0$, both $b_0$ and $b_1$ grow monotonically with $K$, seemingly reaching an asymptote at high $K$. (c) Plot of parameters $k_0$, $k_1$ (open circles, broken lines), -$a_0$ and -$a_1$ (closed circles, lines) as functions of $K$, obtained by fitting $b_0(T_a/T_0)$ and $b_1(T_a/T_0)$ to a power-law equation $k(T_a/T_0)^{-a}$. Because values for $a_0$ and $k_0$ seemed to be parallel to each other, in order to better visualize them together we defined $c_0$ as the average difference between them, finding $c_0$ = *-1.2125*. Correspondingly for $a_1$ and $k_1$, we found $c_1$ = *-1.2756*.

**Supplementary Video 1:** Evolution in time of a simulated tissue in which extrusion occurs, as shown in Figure 7B. In this simulation the average cell width is $b = 0.5$ and $T_a/T_0 = 1.5$, which leads to extrusion. Although initially the tissue morphology seems to stabilize, several T1 transitions happen at $t = 11.8\,\tau_R$, causing the state of the tissue to change greatly. At $t = 20\,\tau_R$ the system has not yet reached a new equilibrium. That the stability threshold for tissues with $b = 0.5$ is between $T_a/T_0 = 1.5$ and $1.6$ is supported by the stability analysis performed on a simplified model.

**Supplementary Video 2:** Evolution in time of a simulated tissue in which extrusion does not occur, as shown in Figure 7C. In this simulation the average cell width is $b = 0.5$ and $T_a/T_0 = 1.6$. The time it takes for the energy to relax 90% into its final value is less than $t = \tau_R$, but in this example the tissue qualitatively can be seen to stabilize in around $6\,\tau_R$. That the stability threshold for tissues with $b = 0.5$ is between $T_a/T_0 = 1.5$ and $1.6$ is supported by the stability analysis performed on a simplified model.

**Appendix A**

**A.1 Non-dimensional version of energy functional**

For all simulations and for the following derivations, a non-dimensional version of the energy functional $E$ (eq. 1) was used. The formula can be obtained as $\epsilon = E/T_0 L_0$, with $T_0$ being a characteristic surface tension equal to the surface tension of any cell-cell interface, and $L_0 = \sqrt{A_0} = \sqrt{K/P_0}$ a characteristic length, where $P_0$ is the pressure of the external medium. Using this, we obtain

$$\epsilon = \sum_{i,j} \frac{T_{ij}}{T_0} \frac{L_{ij}}{L_0} + \sum_i \frac{P_0 L_0}{T_0} \left( \frac{A_i}{A_0} - log\left( \frac{A_i}{A_0} \right) \right) + \frac{1}{2} \frac{K_n L_0}{T_0} \oint_{\partial C_i} \left( \frac{R_i(s) - r_i(s)}{L_0} \right)^2 H\left( \frac{R_i(s) - r_i(s)}{L_0} \right) ds \quad (A1)$$

where all variables are relative to $L_0$ and $A_0$ and three dimensionless parameter groups ($T_{ij}/T_0$, $P_0 L_0/T_0$ and $K_n L_0/T_0$) have been defined. We will use the dimensional and dimensionless names for these variables interchangeably throughout this appendix (i.e.: $E$ for $\epsilon$, $L_{ij}$ for $L_{ij}/L_0$, etc.).

**A.2 Force balance and shape of an interface at equilibrium (without nuclear overlap)**

Two types of forces act on all vertices which don't interact with the nucleus: a tangential force coming from the surface tension term and a force derived from the pressure term in $E$ (eq. 1). Let $\vec{\alpha}$ be a 2-fold vertex on the boundary between cells $i$ and $j$ (any of which we might take as the external medium, substituting $A = 1/P_0$), with clockwise neighbour vertex $(x_-, y_-)$ and counter-clockwise neighbour $(x_+, y_+)$. Then the force acting on $\vec{\alpha}$ is given by:

$$\vec{F_\alpha} = -\frac{\partial E}{\partial \vec{\alpha}} = -\left\{ \frac{\partial E}{\partial L_{ij}} \frac{\partial L_{ij}}{\partial \vec{\alpha}} + \frac{\partial E}{\partial A_i} \frac{\partial A_i}{\partial \vec{\alpha}} + \frac{\partial E}{\partial A_j} \frac{\partial A_j}{\partial \vec{\alpha}} \right\} \quad (A2)$$

Because $\partial L_{ij}/\partial \vec{\alpha} = -(\hat{t}_+ + \hat{t}_-)$ ($\hat{t}_+$ and $\hat{t}_-$ being the tangent vectors pointing away from vertex $\vec{\alpha}$) and $\partial A_i/\partial \vec{\alpha} = \frac{1}{2}(y_+ - y_-, x_- - x_+) = -\partial A_j/\partial \vec{\alpha}$ (Fletcher *et al.*, 2013), we can rewrite equation (A2) as

$$\vec{F_\alpha} = \frac{T_{ij}}{T_0} (\hat{t}_+ + \hat{t}_-) + \frac{1}{2} \frac{P_0 L_0}{T_0} \left( \frac{1}{A_i} - \frac{1}{A_j} \right)(y_+ - y_-, x_- - x_+) \quad (A3)$$

We observe that $\hat{t}_{\alpha+} + \hat{t}_{\alpha-}$ always points in the average direction between the two edges and that $(y_+ - y_-, x_- - x_+)$ is perpendicular to the line between $(x_-, y_-)$ and $(x_+, y_+)$. In equilibrium $F_\alpha = 0$ and therefore the two terms in equation (A3) must be in the same direction (since $T_{ij} \neq 0$), meaning $\hat{t}_+ + \hat{t}_-$ is perpendicular to $(x_+ - x_-, y_+ - y_-)$. Since $\hat{t}_+ + \hat{t}_-$ bisects the angle between both edges, it follows that both edges must have the same length $l$, and since $(y_+ - y_-, x_- - x_+)$ has the same length as $(x_+ - x_-, y_+ - y_-)$, we may write

$$0 = T_{ij} \cos(\omega) - K \left| \frac{1}{A_i} - \frac{1}{A_j} \right| l \sin(\omega) \qquad (A4)$$

where $2\omega$ the inner angle between the two edges.

Since $T_{ij}$ and $\left| 1/A_i - 1/A_j \right|$ depend only on the cells involved, the inner angle $2\omega$ is only a function of edge length, which is equal between any two adjacent 2-fold edges and therefore constant along an interface. This means that any interface between two cells (or between a cell and the external medium) with no overlapping nucleus approximates a circular arc at equilibrium. Additionally as expected, the edge curves towards the cell with the least pressure (largest area).

**A.3 Deduction of nuclear repulsion forces and relation to the model by Kim *et al* (2024)**

In vertices experiencing nuclear repulsion, $\overrightarrow{F_\alpha}$ includes terms of the form

$$\vec{F}_{i,\alpha} = -\frac{1}{2} \frac{K_n L_0}{T_0} \frac{\partial}{\partial \vec{\alpha}} \left\{ \oint_{\partial C_i} (R_i(s) - r_i(s))^2 H(R_i(s) - r_i(s)) \, ds \right\} \qquad (A5)$$

This derivative involves changes in both the path for the integral and the value of $r_i(s)$ along that path. The integral is only modified along subsequent straight paths $\gamma_-$ and $\gamma_+$, which go from $\overrightarrow{x_-} = (x_-, y_-)$ to $\vec{\alpha} = (x_\alpha, y_\alpha)$ and from $\vec{\alpha}$ to $\overrightarrow{x_+} = (x_+, y_+)$, respectively. For example, the integral $I_-$ along $\gamma_-$ can be written as

$$I_- = \int_a^b \left( R_i(s) - \left| t\vec{\alpha} + (1-t)\overrightarrow{x_-} - \overrightarrow{x_{N,i}} \right| \right)^2 |\vec{\alpha} - \overrightarrow{x_-}| dt \qquad (A6)$$

where $\overrightarrow{x_{N,i}} = (x_{N,i}, y_{N,i})$ is the nuclear center, $|\vec{v}|$ is the Euclidean norm, and where we have omitted the Heaviside function by only integrating in the interval where it is non-zero ($a$ and $b$ are both functions of $\vec{\alpha}$ with values in the interval $[0,1]$). This integral is of the form

$\int_{a(\vec{x})}^{b(\vec{x})} f(\vec{x}, t) \, dt$ and therefore its derivative with respect to $\vec{\alpha}$ (i.e.: taken with respect to $\vec{x}$ and evaluated at $\vec{x} = \vec{\alpha}$) follows the Leibniz Integral Rule:

$$\frac{\partial}{\partial \vec{\alpha}} \left\{ \int_{a(\vec{x})}^{b(\vec{x})} f(\vec{x}, t) dt \right\} = f(\vec{\alpha}, b) \frac{\partial b}{\partial \vec{\alpha}} - f(\vec{\alpha}, a) \frac{\partial a}{\partial \vec{\alpha}} + \int_a^b \frac{\partial f}{\partial \vec{\alpha}} \, dt \qquad (A7)$$

with $a = a(\vec{\alpha}), b = b(\vec{\alpha})$. Since $a$ is the lower limit where the (smooth) integrand of equation A6 is positive, either $f(\vec{\alpha}, a) = 0$ or $a$ is the beginning of the edge (i.e.: $a = 0$) in which case $(da/d\vec{x}) = 0$ at $\vec{\alpha}$. Applying a similar reasoning to $b$ simplifies equation (A7) to

$$\frac{\partial}{\partial \vec{\alpha}} \left\{ \int_{a(\vec{x})}^{b(\vec{x})} f(\vec{x}, t) dt \right\} = \int_a^b \frac{\partial f}{\partial \vec{\alpha}} dt \qquad (A8)$$

For simplicity, we assume circular/spherical nuclei –as in our simulations– and take $R_i(s) = R$. Rewriting $\vec{r_-}(t) = t\vec{\alpha} + (1-t)\vec{x_-} - \vec{x_{N,i}}$, differentiation of the integral along $\gamma_-$ (eq. A6) with respect to the position of vertex $\vec{\alpha}$ yields

$$\frac{\partial I_-}{\partial \vec{\alpha}} = \int_a^b (R - |\vec{r_-}(t)|)^2 \frac{\vec{\alpha} - \vec{x_-}}{|\vec{\alpha} - \vec{x_-}|} - 2t|\vec{\alpha} - \vec{x_-}|(R - |\vec{r_-}(t)|) \frac{\vec{r_-}(t)}{|\vec{r_-}(t)|} dt \qquad (A9)$$

Defining $\vec{r_+}(t) = (1-t)\vec{\alpha} + t\vec{x_+} - \vec{x_{N,i}}$ and redefining $a$ and $b$ appropriately, one may differentiate along $\gamma_+$, resulting in

$$\frac{\partial I_+}{\partial \vec{\alpha}} = \int_a^b -(R - |\vec{r_+}(t)|)^2 \frac{\vec{x_+} - \vec{\alpha}}{|\vec{x_+} - \vec{\alpha}|} - 2(1-t)|\vec{x_+} - \vec{\alpha}|(R - |\vec{r_+}(t)|) \frac{\vec{r_+}(t)}{|\vec{r_+}(t)|} dt \qquad (A10)$$

Finally, the nuclear repulsion force acting on vertex $\vec{\alpha}$ is proportional to the sum of both these integrals, that is

$$\vec{F}_{i,\alpha} = -\frac{1}{2} \frac{K_n L_0}{T_0} \left\{ \frac{\partial I_+}{\partial \vec{\alpha}} + \frac{\partial I_-}{\partial \vec{\alpha}} \right\} \qquad (A11)$$

Our integral term in the energy functional $E$ may be seen as a potential for the repulsive interaction included by Kim *et al.* (2024) in their force-based model. Although the force derived from our model is not equal to that proposed by them, we may state a similarity in the formula for the total force arising from the repulsion of a single edge. This is equivalent to the sum of the derivatives of a single edge's path integral, differentiated with respect to the position of both of its endpoints. Using the integral along $\gamma_-$ as an example, we obtain a force $\vec{F_-}$ of the form

$$\vec{F_-} = -\frac{1}{2}\frac{K_n L_0}{T_0}\left\{\frac{\partial I_-}{\partial \vec{\alpha}} + \frac{\partial I_-}{\partial \vec{x_-}}\right\} = \frac{K_n L_0}{T_0}\int_a^b (R - |\vec{r_-}(t)|)|\vec{\alpha} - \vec{x_-}|\frac{\vec{r_-}(t)}{|\vec{r_-}(t)|}dt \qquad (A12)$$

Re-introducing the Heaviside function, parametrizing by arc-length and writing the edge length as $L_-$ we can write this as

$$\vec{F_-} = \frac{K_n L_0}{T_0}\int_0^{L_-}\left(\vec{R} - \vec{r_-}(x)\right)H(R - |\vec{r_-}(x)|)dx \qquad (A13)$$

which follows the form proposed by Kim *et al.* 2024 as $F_{\alpha\beta}$.

**A.4 Derivation of energy formula for wedge-shaped cells**

Without nuclei, the dimensionless energy functional (eq. A1) becomes

$$E = \sum_{i,j}\frac{T_{ij}}{T_0}L_{ij} + \frac{P_0 L_0}{T_0}\sum_i A_i - \log(A_i) \qquad (A14)$$

Therefore, all we need to determine its minima are formulas for the cell areas and interfacial lengths. Surface tension is $T_0$ at cell-cell and $T_a$ at apical/basal interfaces. The energy per cell is thus

$$E_{cell} = \frac{1}{2}L_l + \frac{T_a}{T_0}(L_a + L_b) + \frac{P_0 L_0}{T_0}(A - log(A)) \qquad (A15)$$

with $L_l$, $L_a$ and $L_b$ the lateral, apical and basal interface lengths, defined as in Figure A1a. The average cell width is $b = (b_a + b_b)/2$, equal to the sum of the apical (basal) widths of any two adjacent cells.

The apical/basal sides are circular arcs (Fig. A1b; see above) and we see that for a generic circular arc of base $b$ and angle $\theta$ with respect to baseline, the radius of curvature is given by $\rho = b/2sin(\theta)$. The arc length is then given by

$$L = 2\theta\rho = \frac{b\theta}{\sin(\theta)} \qquad (A16)$$

while the cap area is equal to

$$A = 2\int_0^{\frac{b}{2}}\sqrt{\rho^2 - x^2}dx - \eta b = \frac{b^2}{4}\left(\frac{\theta}{sin^2(\theta)} - \frac{1}{\tan(\theta)}\right) \qquad (A17)$$

where the integral corresponds to the shaded area in Fig. A1b, and we have substituted $\rho = b/2sin(\theta)$, $\rho^2 = \eta^2 + (b/2)^2$ and $\eta = b/2tan(\theta)$.

Finally, the interface lengths and total area are given by

$$L_l = \sqrt{h^2 + (b_b - b)^2}, L_a = (2b - b_b)\frac{\theta_a}{\sin(\theta_a)}, L_b = b_b\frac{\theta_b}{\sin(\theta_b)} \qquad (A18)$$

$$A = bh + \frac{b_b{}^2}{4}\left(\frac{\theta_b}{sin^2(\theta_b)} - \frac{1}{\tan(\theta_b)}\right) + \frac{(2b - b_b)^2}{4}\left(\frac{\theta_a}{sin^2(\theta_a)} - \frac{1}{\tan(\theta_a)}\right) \qquad (A19)$$

where we have substituted $b_a = 2b - b_b$ and $b_b - b_a = 2(b_b - b)$.

Although four variables (plus parameter $b$) appear in equations (A18) and (A19) (and consequently in $E_{cell}$), $\theta_a$ and $\theta_b$ are actually functions of $h$ and $b_b$. This can be proven by considering a 3-fold vertex in the tissue, defined by angles $\theta_a$, $\theta_b$ and $\phi$ (Fig. A1c). In the limit in which inter-vertex distance tends to 0, pressure-derived forces disappear (see eq. A3, A4), so the tensions must add up to 0 in equilibrium, that is

$$T_a\big(cos(\theta_b), sin(\theta_b)\big) + T_a\big(-cos(\theta_a), sin(\theta_a)\big) + T_0\big(sin(\phi), -cos(\phi)\big) = 0 \qquad (A20)$$

or equivalently

$$\cos(\phi) = \frac{T_a}{T_0}(\sin(\theta_b) + \sin(\theta_a))$$

$$\sin(\phi) = \frac{T_a}{T_0}(\cos(\theta_a) - \cos(\theta_b)) \qquad (A21)$$

These equations can be solved by introducing variables $\alpha = (\theta_a + \theta_b)/2$ and $\beta = (\theta_a - \theta_b)/2$, so that

$$\cos(\phi) = 2\frac{T_a}{T_0}\sin(\alpha)\cos(\beta)$$

$$\sin(\phi) = -2\frac{T_a}{T_0}\sin(\alpha)sin(\beta) \qquad (A22)$$

Dividing the second equation of (A22) by the first, we obtain

$$\frac{b_b - b}{h} = tan(\phi) = -\frac{\frac{T_a}{T_0}\,2\sin(\alpha)\sin(\beta)}{\frac{T_a}{T_0}\,2\sin(\alpha)\cos(\beta)} = -tan(\beta) \qquad (A23)$$

where we used the fact that $tan(\phi) = (b_b - b_a)/2h = (b_b - b)/h$ (Fig. A1a). Because $\theta_a, \theta_b \in (0, \pi/2)$ and $\theta_a < \theta_b$, there is only one value of $\beta \in (-\pi/2, 0)$ which satisfies equation A22. This means that $\phi = -\beta$, which in turn simplifies the first equation in A21 to

$$\frac{T_0}{2T_a} = sin(\alpha) \tag{A24}$$

with angle $\alpha \in (0, \pi/2)$ being uniquely determined. From eq. A23 and A24 we obtain

$$\theta_{\frac{a}{b}} = arcsin\left(\frac{T_0}{2T_a}\right) \mp arctan\left(\frac{b_b - b}{h}\right) \tag{A25}$$

which proves that $E_{cell}$ is a function of variables $h$ and $b_b$ only.

**Figure A1: Diagrams for the derivation of cell area and interfacial lengths in the simplified tissue composed of wedge-shaped cells. A**. Diagram of two neighbouring cells, indicating basal and apical widths ($b_b$ and $b_a$), contact angles ($\theta_b$ and $\theta_a$) and surface lengths ($L_b$ and $L_a$), as well as the lengths and angles for cell-cell contacts ($L_l$ and $\phi$). **B**. In the continuous limit, both the apical and basal caps are circular arcs with generic radius of curvature $\rho$, base $b$ and contact angle $\theta$. **C**. Diagram showing the relation between angles $\theta_a$, $\theta_b$ and $\phi$ at 3-fold vertices.

**A.5 Existence of a symmetrical single-layered equilibrium state**

As seen in our analysis of a tissue composed of wedge-shaped cells, for fixed $L_0 = \sqrt{A_0} = \sqrt{K/P_0}$, a bifurcation in the energy minima happens as parameter $T_a/T_0$ increases, with extrusion ($b_b = 0$ or $b_b = 2b$) being favored for low $T_a/T_0$ and a symmetrical tissue

configuration in which $b_b = b_a = b$ becoming stable when $T_a/T_0$ is large. In fact, this equilibrium state exists for all values of $T_a/T_0 > 0.5$, indicating that this system undergoes a supercritical pitchfork bifurcation.

As this is a special case of a tissue composed of wedge-shaped cells, we search for solutions of $\nabla E_{cell} = 0$. Because of the tissue's symmetry, $E(b_b, h) = E(2b - b_b, h)$, which means $\partial E_{cell}/\partial b_b = 0$ when $b_b = b_a = b$. In that case, $\theta_{a/\beta} = \theta = arcsin\left(\frac{T_0}{2T_a}\right)$, which necessitates $T_a/T_0 > 0.5$. Under these conditions, equations (A18-19) simplify to

$$L_l = h, \quad L_a = b \frac{\theta}{sin(\theta)} = L_b \tag{A26}$$

$$A = bh + \frac{b^2}{2}\left(\frac{\theta}{sin^2(\theta)} - \frac{1}{tan(\theta)}\right) \tag{A27}$$

which depend only on variable $h$. Differentiating $E_{cell}$ (Eq. A15) with respect to $h$ gives us

$$dE_{cell} = \frac{1}{2} + \frac{P_0 L_0}{T_0}\left\{b - \frac{b}{bh + \frac{b^2}{2}\left(\frac{\theta}{sin^2(\theta)} - \frac{1}{tan(\theta)}\right)}\right\} = \frac{1}{2} + \frac{P_0 L_0 b}{T_0}\left\{1 - \frac{1}{A(h)}\right\} \tag{A28}$$

which, when equal to 0, leads to

$$\left(\frac{T_0}{2P_0 L_0 b} + 1\right)^{-1} = A(h) = bh + \frac{b^2}{2}\left(\frac{\theta}{sin^2(\theta)} - \frac{1}{tan(\theta)}\right) \tag{A29}$$

from which $h$ may be obtained for any positive value of $b$, $P_0$ and $L_0$ as long as $T_a/T_0 > 0.5$.