Sexual dimorphism in sensorimotor transformation of optic flow

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Abstract

Motion vision underpins a wide range of adaptive behaviours essential for individual and species survival. Some visual behaviours are sexually dimorphic, including for example male hoverfly high-speed pursuit of conspecifics, matched by improved optics, and faster photoreceptors. Other visual behaviours are monomorphic, with for example similar foraging flight speeds in male and female hoverflies. However, whether the descending neurons responsible for sensorimotor transformation of optic flow are sexually dimorphic is unknown. To redress this, we combined morphological analysis with electrophysiology of optic flow sensitive descending neurons and compared neural responses to the wing beat amplitude in tethered hoverflies. We found that while optomotor flight behaviour is largely sexually monomorphic, the underlying neural responses are sexually dimorphic, especially at higher optic flow velocities. Additionally, neural and behavioural responses to roll stimuli had a slower onset compared to lift, revealing stimulus specific encoding. Together, our findings uncover a nuanced, sex- and stimulus- dependant sensorimotor transformation, shaped by both neural architecture and behavioural demands.

Keywords

Sexual dimorphism, hoverfly, descending neuron, optic flow, optomotor response

Introduction

Motion vision is a fundamental sensory modality across the animal kingdom, enabling animals to navigate, to maintain a straight trajectory, to avoid collisions, and to identify prey, predators or mates. Among the most potent cues for self-motion is optic flow, the coherent motion of the entire visual field, generated by an animal's own movement through the world. In insects, the neural mechanisms underlying optic flow processing have been studied extensively (for a review, see e.g. Ref [1]), offering a powerful model for understanding how compact nervous systems extract behaviourally relevant information from dynamic visual scenes.

To generate appropriate responses to widefield optic flow, the visual input needs to be integrated across space. In flies, this spatial pooling occurs in lobula plate tangential cells (LPTCs), each matched to a particular type of self-generated optic flow[2]. For example, neurons of the horizontal system (HS cells) respond optimally to rotations around the yaw axis, whereas neurons in the vertical system (VS cells) are tuned to pitch and roll rotations[3]. While LPTCs process widefield optic flow their role in the resulting behaviours[4,5] is indirect, via optic flow sensitive descending neurons that therefore play a key role in sensorimotor transformation[6,7]. In *Drosophila* and blowflies, there are three main optic flow sensitive descending neurons. DNHS1, also called NDp15[8], receives input from HS cells[6,7] and is physiologically similar to the optic flow sensitive descending neuron type 1 (OFS DN1) in the hoverfly *Eristalis tenax*[9]. DNHS1 has been implicated in the control of head yaw movements and abdominal ruddering and may engage with the haltere motor system for

flight stabilization[6]. DNOVS1, or DNp20[8], receiving input from the ocelli and VS cells[6,10], is

likely involved in rapid head movements, possibly facilitating gaze stabilization during

flight[6]. DNOVS2, or DNp22[8], also receives input from the ocelli but a different subset of VS

cells[6,11] and is physiologically similar to the *Eristalis tenax* optic flow sensitive descending

neuron type 2 (OFS DN2)[9]. DNOVS2 is well suited to initiate the fast body saccades that

support rapid re-orientation[6] during flight in response to dynamic visual cues.

Hoverflies are interesting in the context of motion vision, which they use both to maintain a

hovering stance, and to fly at high speed[12]. Indeed, hoverflies show striking sexually

dimorphic flight behaviour, where males establish territories which they guard rigorously[13] to

chase away any intruding insects and/or pursue conspecific females for courtship and

mating[12,14]. Accompanying this behaviour, male *E. tenax* have larger lenses than females in a

dorso-frontal bright zone[15], with faster motion detection and increased signal-to-noise ratio[16].

In many fly species, the photoreceptors in this part of the eye are also faster in males[17]. In

hoverflies, some LPTCs are sexually dimorphic, with males having a smaller HSN receptive

field[18] and velocity tuning shifted to higher velocities[15,19]. The differences in optics,

photoreceptor dynamics, and LPTC receptive field size and velocity tuning, have been

interpreted as required by males in the fast flight used during sexually dimorphic territorial

behaviours. Interestingly, male hoverflies are also smaller than females[20,21], which introduces

an aerodynamic component to these behavioural and sensory specializations by reducing

inertia and enabling finer control over rapid flight adjustments[22]. However, there is no sexual

dimorphism in flight speed during non-courtship activities such as foraging between

flowers[23] nor when flying within the confines of an indoor arena[24].

To investigate the discrepancy between sexually dimorphic visual processing and sexually

monomorphic behaviours, we compared the electrophysiological response characteristics and

morphology of optic flow sensitive descending neurons in male and female hoverflies and

linked these findings to the wing beat amplitude (WBA) of tethered hoverflies viewing

similar stimuli. The optomotor responses confirm free flight observations by showing limited

sexual dimorphism at speeds up to 2 m/s for translation and 200°/s for rotation. However,

while neural morphology, receptive fields and direction sensitivity of the descending neurons

showed minimal sex differences, there was a significant and noticeable difference in the

velocity response functions between males and females, especially at higher speeds.

Critically, neural differences were not only velocity dependent but also varied between

stimuli (occurring only for sideslip, lift and thrust, but not roll) and neuron type. Furthermore,

we found a striking difference in response onset between lift and roll in OFS DN2 and WBA,

but not OFS DN1. These neuron-, stimulus-, and sex-specific differences uncovers a

previously unrecognized complexity in the neural encoding of visual motion, revealing for

the first time, a sex-dependent transformation from sensory input to motor output.

Results

Two distinct types of optic flow sensitive descending neurons can be identified by their

receptive field location and preferred direction

Optic flow sensitive descending neurons can be readily identified by mapping their receptive

field using small sinusoidal gratings[9,15]. Based on the receptive fields of 100 reference

neurons recorded from 90 male hoverflies, we found that two key parameters, the position of

the receptive field centre and its preferred direction of motion, are sufficient to reliably

ascertain neuron type (Fig. 1). OFS DN1 has a preferred direction up and away from the

midline, either leftward (range from 137° to 171°) or rightward (range from 16° to 40°) for

neurons on the left- and right-hand side of the visual field, respectively (Fig. 1a, b and c;

green, Fig. 1g, h and i). OFS DN2 neurons respond preferentially to downward motion (range

from 228° to 293°; Fig. 1d, e and f; yellow and orange, Fig. 1g, h and i) with the position of

the receptive field centre relative to the midline separating left hand side (LHS) from right

hand side neurons (RHS, Fig. 1g, h and i).

We used the maximum local motion sensitivity (LMS, Fig. 1c, f), the extent of the receptive

fields (number of positions with LMS over 50%, Fig. 1c, d) and the local preferred direction

(LPD, Fig. 1c, d) variance from these 100 reference neurons (grey data, Supplementary Fig.

1a, b and c) to set strict exclusion criteria (dashed red, Supplementary Fig. 1a, b and c) of the

neurons used in the rest of the paper. This resulted in the exclusion of two neurons from

males and seven from females (grey, Supplementary Fig. 1d, e) due to either low LMS (less

than 20 spikes/s, Supplementary Fig. 1a), a small number of locations where LMS exceeded

50% of the maximum (4 positions or less, Supplementary Fig. 1b) or high LPD variance

(above 30°, Supplementary Fig. 1c). A comparison of the remaining 33 male and 29 female

neurons showed no significant sexual dimorphism in receptive field size for either neuron

type (Supplementary Fig. 1f, unpaired t-test, $p = 0.52$ and 0.09 for width and height of OFS

DN1, and $p = 0.19$ and 0.13 for width and height of OFS DN2).

Directional tuning of optic flow sensitive descending neurons exhibits limited sexual

dimorphism

Some LPTCs, which are upstream of the descending neurons, show distinct sexual
dimorphism, whilst others do not[15,18]. To determine the extent of sexual dimorphism in the
descending neurons, we compared the direction tuning of males and females in response to
full screen stimuli. When presented with full-screen sinusoidal gratings (wavelength 7°, 5
Hz), the preferred direction of both OFS DN1 and OFS DN2 matched their receptive field
preferred directions (Supplementary Fig. 1d, e and Supplementary Fig. 2c, d), i.e. up and
away from the visual midline for OFS DN1 (range from 359° to 52°) or downwards for OFS
DN2 (range from 273° to 297°, Fig. 2a). Whilst OFS DN1 showed no difference in preferred
direction between the sexes (Watson-Williams two-sample test, $p = 0.38$), male OFS DN2
had a slightly more lateral preferred direction compared to females (Fig. 2a; median = 285.4°
compared to 281.5°, Watson-Williams two-sample test, $p = 0.046$).

We next looked at the responses to 3-dimensional starfield stimuli simulating the type of
optic flow that would be generated by self-motion through space[25]. Neither the spontaneous
rate nor the responses of OFS DN1 to a stationary starfield pattern differed between the sexes
(circles, Supplementary Fig. 3a, two-way ANOVA, $p = 0.29$). Conversely, OFS DN2
exhibited significant sexual dimorphism, with a higher spontaneous rate and response to
stationary stimuli in females compared to males (circles, Supplementary Fig. 3b, two-way
ANOVA, $p < 0.001$). To determine if there was additional sexually dimorphic dependence on
the type of optic flow, we subtracted the response to the stationary stimulus from the

responses to each direction of the optic flow (0.5 m/s for translations and 50°/s for rotations)

within each trial. As predicted from the receptive fields (Fig. 1) OFS DN1 was excited by

stimuli moving either up or away from the midline, such as rightward sideslip and yaw, and

upwards lift and pitch (Fig. 2b), whilst OFS DN2 showed the strongest responses to

downwards lift and pitch (Fig. 2c). Both neuron types respond strongly to clockwise roll, as

predicted by their receptive fields (Fig. 1a, b) and shown previously for males[9]. However,

neither neuron type showed any sexual dimorphism (Fig. 2b, c, two-way ANOVA, $p = 0.81$

and 0.92, OFS DN1 and OFS DN2, respectively).

Sexual dimorphism in optic flow descending neurons is velocity dependent

As the velocity tuning of some LPTCs is sexually dimorphic[15,19], we tested the responses of

optic flow sensitive descending neurons using a continuous velocity step stimulus (Fig. 3,

Supplementary movie 1). Six velocities for each direction of the stimuli (e.g. anticlockwise

roll -10 to -200°/s and clockwise roll +10 to +200°/s) and a stationary control were presented

3 times each in random order for 2 s each (see example, Fig. 3a).

We confirmed that the spontaneous rate and response to stationary stimuli was significantly

higher in females compared to males for OFS DN2 but not for OFS DN1 (triangles,

Supplementary Fig. 3b, two-way ANOVA, $p = 0.18$ and $p < 0.001$, OFS DN1 and OFS DN2,

respectively). As above, we subtracted each trial's average response to the stationary stimulus

from the responses to moving optic flow. The resulting data show that both neuron types

exhibit sexual dimorphism to certain types of optic flow (Fig. 3e, f and Table 1). For

example, the OFS DN1 response to thrust show a significant interaction between sex and

velocity, with female neurons responding stronger to positive thrust compared to males (Fig.

3e and Table 1). The OFS DN2 response to sideslip was significantly different between males

and females, and there was a significant interaction between sex and velocity in the responses

to sideslip, lift, and thrust, with males responding stronger to sideslip, lift and thrust (Fig. 3f

and Table 1).

Morphological reconstruction suggests optic flow sensitive neurons could control wing

movements

By recording from the descending neurons intracellularly we could iontophoretically fill them

with 3% neurobiotin following identification based on receptive field (as in Fig. 1). We found

that OFS DN1 and OFS DN2 of either sex receive their input in the part of the brain where

LPTCs have their output (Fig. 4). Both neuron types also have wide branches projecting to

the area of the thoracic ganglion where the prothoracic and pterothoracic nerves likely get

their inputs (T1 LN and PtN, Fig. 4a), suggesting they could contribute to controlling the

wings and/or the forelegs. Whilst there was no indication of extensive sexual dimorphism in

the structural morphology of these neurons, OFS DN2 appears to be slightly wider along the

length of the cervical connective in females (Supplementary Fig. 4b). In part, this may be due

to female hoverflies being bigger[20,21] and therefore having a wider cervical connective

(Supplementary Fig. 4c).

Wing beat amplitude changes are velocity dependent but not sexually dimorphic

Given that the morphological data suggest that both neuron types could control the wings

(Fig. 4), we conducted behavioural experiments in an open-loop tethered flight arena using

the same continuous velocity stimulus as in electrophysiology (see Fig. 3a). We tracked the

wing beat amplitude (WBA) for each wing (Fig. 5a, b, Supplementary movie 2) using

DeepLabCut models[26,27] while the tethered animal was viewing different starfield velocities

(Fig. 5c-f). Changes in the sum of the left and right WBA (WBAS) reflect variations in flight

force generation, potentially contributing to either lift or thrust, while the difference between

left and right WBA (WBAD) indicates yaw turning behaviour[28-30] or adjustments to body

orientation[31].

The male WBAS is higher when viewing stationary stimuli compared with pre-stimulation

("pre stim", Fig. 5c, d; two-way ANOVA followed by Uncorrected Fisher's LSD test,

$p < 0.0001$, blue squares, Supplementary Fig. 3c). The male WBAS was also larger than in

female hoverflies viewing stationary stimuli (two-way ANOVA followed by Uncorrected

Fisher's LSD test, $p = 0.02$, Supplementary Fig. 3c). In contrast, when comparing responses

to each type of optic flow, after subtracting the response to stationary stimuli, both the

WBAD and WBAS depended strongly on velocity, however, evidence for sexual dimorphism

was limited (Fig. 5g, h and Table 1). Indeed, only the WBAS in response to lift showed a

significant sex-velocity interaction (Fig. 5g, h and Table 1).

The limited extent of sexual dimorphism observed in behaviour (Fig. 5g, h and Table 1)

contrasts with the neural responses (Fig. 3e, f and Table 1). Additionally, it is difficult to

align the behavioural responses to different types of optic flow with the neuronal input. For

example, in response to higher clockwise roll velocities of (100 - 200°/s), hoverflies exhibit a

decreased WBAD (positive roll, Fig. 5g) and a slightly increased WBAS (positive roll, Fig.

5h) indicating either a leftward turn or an anticlockwise body correction. Similarly, both RHS

neuron types give strong responses to clockwise roll (positive roll, Fig. 3e, f). However,

sideslip moving leftwards also elicits a decreased WBAD (negative sideslip, Fig. 5g) and an

increased WBAS (negative sideslip, Fig. 5h) but neither neuron type responds strongly to this

(negative sideslip, Fig. 3e, f).

We found that neither lift nor thrust evoke large turning responses (Fig. 5g), however, large

and significant increases in the WBAS were observed in hoverflies experiencing the

sensation of falling (positive lift, Fig. 5h and Table 1) or being pushed backwards (negative

thrust, Fig. 5h and Table 1). Interestingly, each neuron type responds to lift and thrust in a

different manner, with OFS DN1 being excited by upwards lift and approaching thrust (Fig.

3e), whereas OFS DN2 is excited by downwards lift and receding thrust (Fig. 3f).

In electrophysiology we used a horizontally oriented visual monitor (Fig. 1), whereas in

behaviour the monitor was rotated 90°[27]. To ensure that this did not substantially affect the

shape of the velocity-response functions, we reduced the stimuli to the central square in both

behaviour and electrophysiology. This reduction caused a slight but significant change in

neuronal (central square; Supplementary Fig. 5a, two-way ANOVA, $p = 0.04$) and

behavioural responses (central square; Supplementary Fig. 5b, two-way ANOVA, $p = 0.04$).

However, it did not alter the shape of the velocity response function nor produce a significant

interaction between velocity and screen size (two-way ANOVA, $p = 0.36$ and 0.49, OFS

DN2 and WBAS, respectively).

Response onset varies depending on stimulus type

It has been previously shown that while neuronal responses are fast[25] behavioural responses

occur on a much slower time scale and differ depending on stimulus type[32,33]. We here found

that there is no significant effect of sex on either neuronal or behavioural response onset (Fig.

6, two-way ANOVA, $p = 0.21$, 0.79 and 0.31, OFS DN1, OFS DN2 and WBAS,

respectively). However, the onset for roll compared to lift is significantly longer for OFS

DN2 and WBAS but not for OFS DN1 (Fig. 6, two-way ANOVA, $p < 0.0001$ for both OFS

DN2 and WBAS compared to $p = 0.08$ for OFS DN1).

Discussion

In the hoverfly, the optics, photoreceptors, and HS cells exhibit clear sexual

dimorphism[15,16,18,19]. In line with this, our findings reveal that optic flow sensitive descending

neurons also show sexually dimorphic velocity response functions (Fig. 3). Yet, despite the

multi-level anatomical and neural sexual dimorphism, the wing beat amplitude remains

mostly monomorphic (Fig. 5). Moreover, differences between neural and wing beat

amplitude velocity response functions (Fig. 3, 5) and response latency (Fig. 6) highlight the

likely involvement of downstream processing mechanisms that could reconcile sex-specific

sensory encoding with conserved flight control.

Although male hoverflies pursue and capture female conspecifics at high speeds[14], previously

reported cruising speeds in both field[23] and indoor settings[24] do not differ between sexes. In

addition, the median reported speeds are around 0.3 m/s[23,24], well below the 10 m/s reported

during outdoor pursuit[14]. In comparison, our results show limited sex-related differences in

WBA in response to optic flow speeds up to 2 m/s (Fig. 5), yet we detected pronounced

sexual dimorphism in neural responses at velocities as low as 0.5 m/s (Fig. 3, Table 1). This

suggests that sensory processing differences emerge at lower velocities than the velocities

where motor output diverges. Moreover, the WBA response latency to roll is much longer

that to lift, and much longer than the corresponding neural activity (Fig. 6), implying that

temporal integration or additional circuit-level modulation may delay and refine motor

execution. Together, these findings suggest a complex transformation between sex-specific

sensory encoding and conserved motor behaviour, potentially mediated by downstream

integration or additional alternate neural pathways that bypass the descending neurons

studied here.

Both neurons project broadly within the thoracic ganglion, including in zones associated with

prothoracic and pterothoracic nerve input (Fig. 4), suggesting involvement in wing and

foreleg motor control. Nevertheless, there is currently no direct evidence implicating them in

the control of wingbeat amplitude. Interestingly, DNOVS2 in *Drosophila*, a physiologically

similar neuron to OFS DN2[9], has been indirectly linked to rapid turning behaviour[6].

Furthermore, silencing HS and VS cells, the presumed presynaptic LPTCs to these

descending neurons, results in reductions in WBA only at higher stimulus speeds[34]. These

findings suggest that HS and VS cells, along with their downstream targets, may be

specialized for driving fast optomotor responses under high-speed visual motion (>180°/s),

rather than broadly regulating WBA across all velocities, including those examined in this

study.

Beyond their potential involvement in wingbeat amplitude modulation, OFS DNs may play a

role in coordinating head and body positioning during flight, especially in contexts requiring

precise visual alignment and rapid manoeuvring. Indeed, the *Drosophila* physiological

homologs of OFS DN1 and OFS DN2[9], DNHS1 and DNOVS2, have been implicated in

controlling head movements, abdominal ruddering, and engagement with the haltere motor

system for flight stabilization[6]. Moreover, the sexual dimorphism in neural responses (Fig. 3)

could reflect an evolutionary tuning of visuomotor pathways in males, optimized for fast,

directional adjustments rather than gross changes in WBA. For instance, whilst changes in

WBAS are similar when generating either lift or thrust (Fig. 5), body pitch dynamically

adjusts their ratio, driving behavioural variation[35]. Thus, OFS DNs may serve as integral

components of a broader flight control architecture, interfacing optic flow detection with

dynamic body and head positioning systems to support complex, sex-specific behavioural

outcomes, particularly in males engaging in high-speed pursuits.

Flight speed in insects results from a complex integration of multiple kinematic parameters,

not solely from changes in wingbeat amplitude. Many species refine their aerodynamic

output by modulating wingbeat frequency, angle of attack, wing tip trajectory, deviations

from the mean stroke plane and through precise adjustments to the timing and duration of the

up- and downstrokes[36]. These control strategies support agile manoeuvring, particularly

during visually guided behaviours such as the high-speed pursuits undertaken by male

hoverflies. Furthermore, the smaller body size of male hoverflies compared to females[20,21]

may confer biomechanical advantages, including reduced mass, facilitating faster

acceleration, heightened responsiveness, and lower metabolic costs for executing flight

manoeuvres[22,37], which do not appear in a tethered flight set-up. Such enhanced agility is

likely crucial for rapid direction changes required during courtship and may enable male

hoverflies to outperform female flies without relying on increased wingbeat amplitude.

Taken together, our findings reveal significant differences between sexually dimorphic

sensory encoding and conserved motor output in hoverfly flight at cruising speeds. Although

OFS DNs and their upstream visual circuits display clear sex-specific tuning, wingbeat

amplitude changes in response to optic flow stimuli remain relatively similar between the

sexes, suggesting additional mechanisms downstream of sensory input. This likely reflects a

complex interplay of biomechanical properties, multisensory integration and circuit-level

modulation, each shaping and refining behavioural outcomes to meet distinct demands,

preserving the consistency of low-speed manoeuvres whilst enabling sex-specific tuning

during high-speed pursuits.

Methods

Animals

For all experiments, male and female *Eristalis tenax* were reared and housed as described

previously[21]. Briefly, eggs were collected from females captured under permit in Wittunga

Botanic Garden, Adelaide, South Australia. Upon hatching, larvae were reared in a rabbit

dung slurry until third instar larvae emerged to pupate. Eclosion occurred 1-2 weeks post-

pupation. Adult hoverflies were used for behavioural experiments at 17-87 days post-

eclosion, for intracellular electrophysiology and subsequent morphological reconstruction at

38-54 days, and for extracellular electrophysiology at 8-204 days.

Electrophysiology

Before recording the animal was immobilised, mounted dorsal side down and secured using a

mixture of beeswax and resin. A small region of cuticle was removed at the anterior end of

the thorax to expose the cervical connective. If required, any excessive gut or tracheal tissue

obstructing the recording site was removed and a small volume of PBS was added to prevent

drying within the ventral cavity. A fine wire hook was positioned under the cervical

connective for mechanical support, and a silver wire was inserted into the cavity to serve as a

reference electrode and grounding wire[9].

For extracellular recordings, a sharp tungsten microelectrode (2 MΩ, polyimide-insulated;

Microprobes) was inserted into the cervical connective[9]. Signals were amplified 1000 times

and band-pass filtered between 10–3000 Hz using a DAM50 differential amplifier (World

Precision Instruments), followed by noise reduction with a HumBug (Quest Scientific). Data

were digitized via a PowerLab 4/30 interface (ADInstruments) and acquired at 40 kHz. Spike

sorting was performed in LabChart 7 Pro (ADInstruments) based on the amplitude and width

of individual action potentials.

For intracellular recordings, aluminosilicate electrodes were pulled using a Sutter P-1000

micropipette puller, achieving a resistance of approximately 40-70 MΩ. Electrode tips were

filled with 3% neurobiotin (Vector Laboratories), then backfilled with 1 M KCl using a

syringe, leaving a small air bubble between the two solutions. Electrodes were inserted into

the cervical connective for recording, and the resulting signal was amplified using an

Axoclamp-2B amplifier (Axon Instruments), followed by 50 Hz noise reduction with a

HumBug (Quest Scientific). Data acquisition and digitization were performed at 10 kHz

using an NI USB-6210 16-bit data acquisition card (National Instruments) and the MATLAB

Data Acquisition Toolbox (Mathworks), using in house software

(https://github.com/HoverflyLab/SampSamp).

Morphological reconstructions

Following intracellular recordings, neurons were stained iontophoretically with neurobiotin

using currents in the 1 nA range for 3–12 minutes. The nervous system was then carefully

dissected and fixed in 4% paraformaldehyde overnight. Tissue was incubated with a Cy3-

streptavidin conjugate (1:100; Jackson ImmunoResearch) for 2 hours, then dehydrated

through an ethanol series (50–100%) for 15-20 minutes per step. After washing in PBT, the

tissue was cleared in RapiClear (SUNJIN Lab) and mounted with spacers. Imaging was

performed using a Zeiss LSM 880 Fast Airyscan confocal microscope at the institutional

microscopy facility. Neuron morphology and cervical connective width were quantified using

ImageJ[38].

Tethered flight

Prior to flight recordings, hoverflies were tethered at a 32° angle using a beeswax–resin mixture to a small pin inserted into a hypodermic needle (BD Microlance, 23G × 1¼"). Flight was initiated by manually providing airflow for 1–10 minutes until consistent flight behaviour was observed. Once positioned at the centre of the flight arena, hoverflies were filmed from above at 100 Hz using a Sony PlayStation 3 Move Eye Camera (SLEH- 00448, Sony) with the IR filter removed, and equipped with an infrared pass filter (R72 INFRARED, 49 mm, HOYA; for details see Ref[27]). Illumination was provided by infrared LEDs inserted into USB lights (JANSJÖ LED USB lamp, IKEA) and a Musou Black (Shin Kokushoku Musou black, KOYO Orient Japan) surface was placed beneath the hoverfly to enhance contrast and minimize optical interference.

We used DeepLabCut (DLC) version 2.3.3[26] to train a model to track the thorax, and the peak downstroke angle, referred to as the wing beat amplitude (WBA), of the left and right wing (WBA_L and WBA_R; Fig. 5a, b), as described previously[27]. Briefly, we manually labelled six anatomical landmarks: the tegula and wing tip of both left and right wing, the anterior thorax, and the anterior abdomen (Fig. 5a, b), across 16 extracted video frames per individual from four hoverflies (2 males, 2 females). In addition to examples where the hoverfly was not flying, these frames included responses to yaw rotation and forward translation. The DLC model was trained for 300,000 iterations, yielding train and test errors of 1.2 and 1.16 pixels, respectively.

To identify potential tracking errors from DLC, we smoothed the WBA time series using

MATLAB's *smooth* function with both *loess* and *rloess* methods. Because *rloess* is more

resistant to outliers, we used it to detect abnormal data points. For each wing, if the absolute

difference between the *loess*- and *rloess*-smoothed signals exceeded 5% for more than 1 s,

the data were excluded due to suspected tracking artifacts. The smoothing was used only for

error detection; all subsequent analyses were performed on the unsmoothed data. In addition,

we excluded data if the WBA of either wing dropped below 40° for at least 0.5 s, as this

indicated a cessation of flight. Finally, entire trials were excluded if the hoverfly was not

flying for more than 50% of the trial duration.

Visual stimuli

Visual stimuli were generated using custom software

(https://github.com/HoverflyLab/FlyFly/releases/tag/v4.2.3) written in MATLAB,

incorporating the Psychophysics Toolbox[39,40]. All screens had a refresh rate of 165 Hz and a

linearized contrast with a mean illuminance of 200 Lux. For intracellular recordings, the

hoverfly was placed 13 cm away from a ViewSonic screen with a resolution of 2560 × 1440

pixels, corresponding to 143° × 107° of the visual field. For extracellular recordings, the

hoverfly was placed 6.5 cm away from a 2560 × 1440 pixel Asus screen, yielding a projected

visual field of 155° × 138°. For behavioural recordings, the hoverfly was placed 10 cm from

a vertically orientated Asus screen (1440 × 2560 pixel) producing a projected size of 118° ×

142°. To evaluate the impact of different screen orientations in electrophysiology and

behaviour, visual stimuli were presented either full-screen or using the central 1440×1440

pixel square (Supplementary Fig. 5).

Receptive field mapping

To map each neuron's receptive field, we presented local sinusoidal gratings (average $38 \times$

$38°$) drifting in 8 directions for 0.36 s each, across 48 overlapping locations, as previously[9].

Stimuli were full contrast, with an average spatial frequency of 0.14 cycles/° and a temporal

frequency of 5 Hz. At each location, we calculated the local maximum spike frequency (red,

inset, Fig. 1b, e). After subtracting the spontaneous rate, calculated for 0.8 s preceding

stimulus onset (dotted, inset, Fig. 1b, e), we spatially interpolated the resulting local

maximum responses 10 times (colour coding, Fig. 1a, d). Receptive field centres (red circle,

Fig. 1b, e) and sizes (Supplementary Fig. 1f) were defined using the resulting 50% contour

line (black, Fig. 1b, e). As recordings were performed with the animal ventral side up,

receptive fields were rotated to display them with the dorsal side up (Supplementary Fig. 2a).

Next, at each location, we fit a cosine function to the responses to the different directions of

motion, to extract the local preferred direction (LPD) and local motion sensitivity (LMS;

inset, Fig. 1c, f). These were visualized as vectors where angle indicates LPD and length

indicates LMS (arrows, Fig. 1a, d). We defined the receptive field preferred direction as the

median of LPDs at locations where LMS exceeded 50% of the maximum (black and red

arrows; Fig. 1c, f), using circ_median from the CircStat toolbox for MATLAB[41]. We

calculated the LPD variance using the circ_var functions from CircStat toolbox for

MATLAB[41], of LPDs at locations where LMS exceeded 50% of the maximum (black and red

arrows; Fig. 1c, f).

We extracted unpublished receptive field data from 100 reference neurons (other data from 5

of these optic flow sensitive descending neurons has been published previously[42]) to set

exclusion criteria (red shading, Supplementary Fig. 1a, b and c) and to classify the OFS DNs

used in the rest of this study. OFS DN1 LHS neurons were defined by receptive field

preferred directions between 120° and 200° (light green, Fig. 1g). OFS DN1 RHS neurons

were defined by receptive field preferred directions between 340° and 60° (dark green, Fig.

1g). OFS DN2 neurons were classified by receptive field preferred directions between 220°

and 320° (yellow and orange, Fig. 1g), with the location of the receptive field centre relative

to the midline determining whether they were LHS or RHS (yellow and orange, Fig. 1h).

Directional sensitivity

Full-screen sinusoidal gratings were presented at full contrast, using the same spatial (0.14

cycles/°) and temporal (5 Hz) frequencies as in receptive field mapping. Directional

responses were rotated to account for the ventral-side-up recording position, and data from

LHS neurons were mirrored across the midline to display all neurons as RHS (Supplementary

Fig 2a). For each stimulus direction, mean spike frequency was calculated over the stimulus

duration, excluding the first 100 ms to avoid onset transients[43]. A cosine function was fit to

these responses, to extract its amplitude and preferred direction (Supplementary Fig 2b).

Responses to optic flow

We used a starfield stimulus to generate the type of perspective-corrected optic flow that would have been seen by the hoverfly if it was moving through a space of 2 cm diameter spheres (for details, see Ref[9,25]). These simulated translations at 0.5 m/s (sideslip, lift, and thrust, Supplementary movie 2) or rotations (pitch, yaw, and roll, Supplementary movie 1), at 50°/s. To quantify neural responses, the mean spike frequency was calculated over the 0.97 s stimulus duration, excluding the first 0.1 s to avoid onset-related transients[43]. The spontaneous firing rate, averaged across 0.48 s immediately preceding stimulus onset (circles, Supplementary Fig 3a, b), was subtracted from the response.

Velocity response functions

We used four types of optic flow: three translations (sideslip, lift and thrust) and one rotation (roll). Translations were presented at velocities of −2, −1.5, −1, −0.4, −0.2, −0.1, 0, 0.1, 0.2, 0.4, 1, 1.5, and 2 m/s, while rotations were presented at 200, −150, −100, −40, −20, −10, 0, 10, 20, 40, 100, 150, and 200°/s. The sign of the velocity indicates the direction of motion as seen by the fly when corrected for its position, with positive values corresponding to counterclockwise roll, leftward sideslip, downward lift, and thrust moving away. Conversely, negative values indicate clockwise roll, rightward sideslip, upward lift, and thrust moving toward the hoverfly. The upper limit was defined by the movement of the individual dots within the starfield stimulus between frames, i.e. was limited by the refresh rate of the screen.

Each trial consisted of 39 stimuli (13 unique velocities × 3 repetitions), presented in a random

order, with each stimulus lasting 2 s, immediately followed by the next velocity. Trials began

with a 1 s blank screen, which served as the pre-stimulation baseline (Fig. 3a and Fig. 5a).

Each optic flow condition was repeated multiple times, resulting in at least nine repetitions

for each velocity and neuron, and five repetitions for each velocity and animal in behaviour.

For neuronal recordings, velocity response function trials were interleaved with the optic

flow stimuli described above. In behavioural experiments, a flight refresher sequence

interspersed each velocity tuning trial. This consisted of sinusoidal gratings (200°

wavelength, 5 Hz) drifting rightward, leftward, and rightward again for 4 s each.

Neural responses were quantified as the mean spike frequency during the final second of

stimulation (grey shaded areas, Fig. 3a–c). We then calculated the median across trials for

each velocity (Fig. 3d). Pre-stimulation activity (spontaneous rate) was measured over a 2 s

window immediately preceding stimulus onset. In behavioural experiments, we extracted the

mean wing beat amplitude of the left and right wings ($\overline{WBA_L}$, $\overline{WBA_R}$, Fig. 5b) during the

final second of stimulation (grey shaded areas, in Fig. 5 c, d and e). For each velocity, we

calculated the WBA difference (WBAD, defined as $\overline{WBA_L} - \overline{WBA_R}$) and the WBA sum

(WBAS, defined as $\overline{WBA_L} + \overline{WBA_R}$, Fig. 5b). We then calculated the median across

repetitions for each individual (Fig. 5f). Pre-stimulation responses were averaged over a 0.5 s

time window immediately preceding stimulus onset.

Response onset

For neuronal recordings, we compared onset times for clockwise roll (+50°/s) and either

upwards lift (+0.5 m/s) for OFS DN 1 or downwards lift (-0.5 m/s) for OFS DN2, stimuli

which generated strong responses in these neurons (Fig. 3 e, f). Mean spike frequency was

calculated over the stimulus duration, excluding the first 0.1 s to avoid onset transients[43].

Onset was defined as the first time point after the first 0.1 s, where spike rate exceeded 80%

of the mean.

For behaviour, we used responses to roll (-200°/s) and lift (+2 m/s). Mean WBAS was

defined as the average response during the final second of stimulation, and onset was defined

as the first time point where WBAS exceeded 80% of this mean.

Data availability and statistics

All data and analysis scripts have been submitted to DataDryad (private link for peer review:

doi:10.5061/dryad.tb2rbp0fd).

Throughout the text n refers to individual repetitions, whereas N refers to individual neurons

(electrophysiology) or animals (behaviour). All data are presented as median and interquartile

range, unless otherwise indicated.

Statistical analyses were performed in Prism 10.4 (GraphPad Software), except for circular

statistics, which were conducted using the CircStat toolbox for MATLAB[41]. The results of

the statistical tests are given in figure legends and in Table 1.

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Declaration of interests

499   The authors declare no competing interests.

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Figure legends

Fig. 1. Classification of optic flow sensitive (OFS) descending neurons (DN) in *Eristalis tenax*. a Receptive field of a representative OFS DN1 recorded from a male hoverfly. Colour coding indicates the local maximum spike frequency, and the direction of the arrows shows the local preferred direction (LPD) and their length the local motion sensitivity (LMS). **b** Contour line representing the 50% receptive field boundary based on local maximum spike frequency from panel a. Inset: example response at one central location to eight directions of motion (black circles), showing local maximum spike frequency (local max, red line) above spontaneous rate (spont, black dotted line). **c** Preferred direction map of the same example neuron at locations where local motion sensitivity (LMS) exceeds 50% of the maximum (red arrow). Inset: example response at one location to eight directions of motion with a sinusoidal fit (black line), illustrating LMS (red line) and LPD (red open arrowhead). **d** Receptive field of a representative male OFS DN2. **e** 50% receptive field contour and receptive field centre of the neuron shown in panel d. **f** Preferred direction map of the same OFS DN2. **g** Distribution of receptive field preferred directions across 100 male reference neurons, colour-coded by neuron classification. Dashed lines in corresponding colours indicate the thresholds used for neuron type classification. **h** Receptive field centres of the same 100 reference neurons, using the same colour coding. **i** Relationship between preferred direction and receptive field centre for the 100 neurons.

Fig. 2. Sex-based comparison of direction sensitivity in OFS DNs. a Polar plot showing the preferred direction of male (blue) and female (red) OFS DNs in response to a full-screen,

full-contrast sinusoidal grating (spatial wavelength 7º, temporal frequency 5 Hz). Individual

data points represent the response amplitude and preferred direction of each OFS DN. Larger,

salient circles indicate the population median, with error bars showing the interquartile range.

The dashed lines indicate the directional thresholds used to classify neuron type, as OFS DN1

(male: N = 9; female: N = 12) or OFS DN2 (male: N = 20; female: N = 14). Asterisk

indicates a statistically significant difference ($p < 0.05$), Watson-Williams two-sample test. **b**

Comparison of male and female OFS DN1 responses to translational optic flow at 0.5 m/s:

sideslip, lift and thrust; and rotational optic flow at 50 º/s: pitch, yaw and roll (male: N = 9;

female: N = 12). **c** Comparison of male and female OFS DN2 responses to the same optic

flow stimuli (male: N = 20; female: N = 14). Data presented as median and interquartile

range.

Fig. 3. Velocity response functions in male and female OFS DNs. a Example stimulus

profile over time, with roll velocity on the y-axis. **b** Representative spike histogram from a

single trial from a male OFS DN2, smoothed using a 100 ms square-wave filter with 0.025

ms resolution, and time-aligned to the stimulus shown in panel a. Grey shading in panels a

and b highlight the analysis windows used to calculate response. **c** Example extracellular raw

data traces extracted from the analysis windows in panel b, illustrating neuronal responses to

roll velocities of –150, 10, and 200 º/s. **d** Average spike frequency (grey circles) was

calculated for each repetition from each neuron (N = 1 neuron, n = 18 repetitions), and the

median of these (black) was used for further analysis. **e** Velocity response functions of OFS

DN1 in male (blue) and female (red) hoverflies in response to roll (N = 4 males, 5 females),

sideslip (N = 5, 6), lift (N = 4, 4), and thrust (N = 3, 5). **f** Velocity response functions of OFS

DN2 to roll (N = 10 males, 8 females), sideslip (N = 6, 7), lift (N = 6, 7), and thrust (N = 6,

7). Data in panels e and f are presented as median and interquartile range. Asterisks indicate

statistically significant differences, two-way ANOVA with Šídák's multiple comparisons test

(** $p < 0.01$ and **** $p < 0.0001$), see also Table 1.

Fig. 4. Morphological reconstruction of OFS DNs. a Schematic diagram of the hoverfly

central brain and thoracic ganglia showing the projections of OFS DN1 (green) and OFS

DN2 (orange). Key anatomical landmarks are labelled: OL, optic lobe; CB, central brain; CC,

cervical connective; T1 LN, prothoracic leg nerve; T2 LN, mesothoracic leg nerve; T3 LN,

metathoracic leg nerve; TAG, thoracic-abdominal ganglion; FN, frontal nerve; PtN,

pterothoracic nerve; HN, haltere nerve; AbN, abdominal nerve. **b** Confocal image of a

reconstructed male OFS DN2. White boxes indicate regions magnified in panels c and d**. c**

Input dendrites of OFS DN2 around the sub-oesophageal ganglion. **d** Output projections of

the same OFS DN2 neuron within the thoracic ganglia. **e** Input dendrites of a female OFS

DN2. **f** Output projections of the same neuron. **g** Input dendrites of a male OFS DN1. **h**

Output projections from the same neuron.

Fig. 5. WBA velocity response functions in male and female hoverflies. a Screenshot from

a video labelled with trained DeepLabCut models[26,27,44]. Coloured dots correspond to those in

panel b, used to extract the wing beat amplitude (WBA). **b** Pictogram illustrating a higher

wing beat amplitude on the left wing (WBA$_L$) compared to the right wing (WBA$_R$),

suggesting a turn to the right. Equations used to calculate wing beat amplitude difference

(WBAD) and wing beat amplitude sum (WBAS). **c** Example stimulus with sideslip velocity

on the y-axis. **d** Representative WBA for the left (pale colour) and right (salient colour)

wings from a single trial, time-aligned with the stimulus shown in panel c. Grey shading in

panels c and d indicate the analysis windows used to calculate WBAD and WBAS. **e**

Magnified view of example WBA, showing behavioural responses to sideslip velocities of -2,

0.2, and 2 m/s. **f** Average WBAS (grey circles) calculated across repetitions (N = 1 animal, n

= 19-36 repetitions). Black circles represent the median WBAS per stimulus condition, used

for further analysis. **g** WBAD in male (blue) and female (red) hoverflies in response to

different optic flow velocities: roll (N = 5 males, 7 females), sideslip (N = 6, 6), lift (N = 7,

5), and thrust (N = 6, 5). **h** WBAS to the same stimuli in the same animals. Data in panels g

and h are presented as median and interquartile range.

Fig. 6. Response onset to roll and lift stimuli in male and female hoverflies. a Time to

response onset in OFS DN1 to roll (+50 °/s) or lift (+0.5 m/s) stimuli in males (blue, N = 5)

and females (red, N = 8). **b** Response onset in OFS DN2 to roll (+50 °/s) or lift (-0.5 m/s)

measured in males (N = 20) and females (N = 14). **c** Onset of WBAS responses to roll (-200

°/s) and lift (+2 m/s) in males (N = 5 for roll, 9 for lift) and females (N = 7 for roll, 5 for lift).

Data are presented as individual repeats with lines indicating median. Asterisks indicate

statistically significant differences, two-way ANOVA with uncorrected Fisher's LSD test

(** $p < 0.01$ and *** $p < 0.001$).

Table 1. Statistical summary of neural and behavioural velocity response functions.

Results from two-way ANOVA analyses evaluating the effects of stimulus velocity and sex

on both neural (OFS DN1 and DN2) and behavioural (WBAS and WBAD) responses.

Asterisks denote levels of statistical significance: *** $p < 0.001$, **** $p < 0.0001$.

a
OL
CB
OFS DN1
OFS DN2
CC
FN
T1 LN
PtN
TAG
T2 LN
HN
AbN
T3 LN

b
CB
TAG
200 μm

c
OFS DN2
Male
100 μm

e
OFS DN2
Female
100 μm

g
OFS DN1
Male
100 μm

d
50 μm

f
50 μm

h
50 μm

a

b

A
L ┼ R
P

WBA_L 130°

WBA_R 82°

WBAD = WBA_L - WBA_R

WBAS = WBA_L + WBA_R

c

Sideslip velocity [m/s]

pre stim

d

WBA [°]

Time [s]

e

-2 m/s   0.2 m/s   2 m/s

WBA [°]

Time [s]   Time [s]   Time [s]

f

N = 1, n = 19-36

$\overline{WBAS}$ [°]

Sideslip velocity [m/s]

g

WBAD [°]

Right

Left

h

WBAS [°]

● Male
● Female

CCW   CW   Left   Right   Down   Up   Away   Towards

Roll velocity [°/s]   Sideslip velocity [m/s]   Lift velocity [m/s]   Thrust velocity [m/s]

Stimulus		Velocity	Sex	Interaction		Velocity	Sex	Interaction
Roll	**OFS DN1**	****	0.35	0.14	**OFS DN2**	****	0.31	>0.99
Sideslip		****	0.90	0.12		****	**0.01**	****
Lift		**0.002**	0.86	>0.99		****	0.18	***
Thrust		****	0.11	****		****	0.10	**0.02**
Roll	**WBAD**	****	0.11	0.66	**WBAS**	****	0.13	0.76
Sideslip		****	0.76	0.35		****	0.61	0.79
Lift		**0.03**	0.79	0.52		****	0.09	**0.02**
Thrust		0.29	0.66	0.72		***	0.57	0.83

1   **Supplementary information**

2   **Sexual dimorphism in sensorimotor transformation of optic flow**

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Supplementary Figure legends

Supplementary Fig 1. Exclusion criteria and receptive field comparisons in male and

female OFS DNs. a Distribution of maximum local motion sensitivity (LMS) in 100 male

reference neurons (grey histogram, N = 100) compared to the neurons used for quantification

in the rest of the paper (N = 35 males, 36 females). Six neurons with a maximum LMS below

20 spikes/s (red cross-hatched region or dashed line) were excluded from further analysis. **b**

Number of stimulus positions with LMS greater than 50% of the neuron's maximum LMS

(black and red arrows in Fig. 1c and f). Neurons with fewer than 4 positions were excluded.

c Distribution of LPD variance. Neurons with directional variance exceeding 30° were

excluded. **d** Classification of male neurons based on receptive field centre and preferred

direction. The top panel shows the preferred directions across neurons, with dashed lines

indicating the directional thresholds used for neuron type classification. The middle panel

shows receptive field centre locations, and the bottom panel illustrates the relationship

between receptive field centre and the receptive field preferred direction for all 35 male

neurons, with 2 neurons excluded from further analysis (grey). **e** Same classification criteria

applied to 36 female neurons, with 7 neurons excluded (grey). **f** The receptive field width and

height at the 50% contour line for the remaining OFS DN 1 (N = 10 males, 12 females) and

OFS DN2 (N = 23 males, 17 females). Individual data points shown, with black lines

representing the median.

Supplementary Fig 2. Schematic illustration showing the steps used to standardize data across recordings. a. Top panel, ventral-side-up position of hoverfly during electrophysiology recordings. Middle panel, reorientation to display the dorsal visual field at the top. Bottom panel, neurons with receptive fields in the left-hand side (LHS) of the visual field have been mirrored to the right-hand side (RHS). **b** Response of an example neuron to a full-screen, full-contrast sinusoidal grating (spatial wavelength 7°; temporal frequency 5 Hz) moving in eight different directions. The plots illustrate the effect of compensating for hoverfly orientation (middle panel) and receptive field location (bottom panel). The red arrowhead shows the neuron's preferred direction, and the red line indicates response amplitude for full-screen sinusoidal gratings. **c** Preferred direction of male hoverfly OFS DNs (N = 29). Neurons are colour coded by classification, with dashed lines indicating the receptive field thresholds. The plots show the effect of compensating the original data (top) for orientation (middle) and receptive field location (bottom). **d** Preferred direction of female hoverfly OFS DNs (N = 26), as in panel c.

Supplementary Fig. 3. Comparison of spontaneous activity and responses to stationary stimuli. a Spontaneous activity (open shapes) and responses of OFS DN1 to the stationary starfield (filled shapes), from data extracting directional sensitivity (as in Fig. 2; circles) or velocity response functions (as in Fig. 3; triangles). **b** Spontaneous activity and responses of OFS DN2 as in panel a. **c** WBAS before stimulus presentation (open squares) or when viewing the stationary starfield (filled squares), quantified during velocity response function experiments (as in Fig. 5). Individual data points are shown, with lines representing the median. Asterisks denote statistical significance, two-way ANOVA with uncorrected Fisher's LSD test: * $p < 0.05$, ** $p < 0.01$, *** $p < 0.001$ and **** $p < 0.0001$.

Supplementary Fig 4. Morphological quantification of OFS DN2. a Schematic diagram of

the hoverfly central brain and thoracic ganglia showing locations where the cervical

connective (CC) and the OFS DN2 (orange) widths were measured. **b** Width measurements

of OFS DN2 axons along the cervical connective at four anatomical landmarks: (1)

immediately posterior to the central brain, (2) upper third of the CC, (3) lower third of the

CC, and (4) immediately anterior to the thoracic ganglion. Data are shown for 3 male (blue)

and 3 female (red) hoverflies. **c** Width of the anterior end of the cervical connective in the

same individuals. All data are presented as individual repeats with the horizontal lines

indicating median.

Supplementary Fig 5. Impact of stimulus size on neural and behavioural velocity

response functions. a Velocity response functions of male OFS DN2 neurons when the

stimulus covered either the full screen (blue) or the central square (black, N = 7). **b** Velocity

response functions of WBAS in male hoverflies when the stimulus covered either the full

screen (blue) or the central square (black, N = 5). All data are presented as median and

interquartile range.

Supplementary Movies

Supplementary Movie 1. Neural response to roll optic flow. The video shows the raw

extracellular response of an OFS DN2 in red when the hoverfly was viewing an example roll

stimulus, as in Fig. 3 of the main paper.

Supplementary Movie 2. WBA response to sideslip optic flow. The video on the left

shows the hoverfly filmed from above, with the coloured dots indicating the points tracked by

DeepLabCut to extract the WBA. The stimulus the hoverfly was viewing is displayed on the

right, as in Fig. 5 of the main paper.

a

Down
Right ┼ Left
Up

Up
Left ┼ Right
Down

LHS → RHS

Midline

Equator

OFS DN2, male, N = 1

b

○ Response
— Curve fit
▼ Prefered direction
⊢⊣ Amplitude

N = 1

100 spikes/s

c

90°
180° ┼ 0°
270°

● OFS DN1 LHS
● OFS DN1 RHS
● OFS DN2 LHS
● OFS DN2 RHS

Male
N = 29

d

Female
N = 26