CASPULE: A computational tool to study sticker spacer polymer condensates

Aniruddha Chattaraj, David S. Kanovich, Srivastav Ranganathan, Eugene I. Shakhnovich

Department of Chemistry and Chemical Biology, Harvard University, MA 02138, USA

Correspondence: shakhnovich@chemistry.harvard.edu

Abstract

Phase separated condensates are recognized as a ubiquitous mechanism of spatial
organization in cell biology. Biophysical modeling of condensates provides critical insights into
the dynamics and functions of these subcellular structures that are difficult to extract via
experiments. Here we present an efficient computational pipeline, CASPULE (**C**ondensate
Analysis of **S**ticker Spacer **P**olymers **U**sing the **L**AMMPS **E**ngine), to simulate and analyze the
biological condensates made of sticker-spacer polymers. CASPULE implements a unique force
field that combines traditional Langevin dynamics with a "detailed-balance proof" protocol for
single-valent bond formation between stickers. This framework allows us to study the non‑trivial
biophysics that emerge from single‑valent sticker interactions, coupled with the effect of
separating the energetic contributions of stickers and spacers. We provide detailed
documentation on how to setup the simulation environment, perform simulations and analyze
the results. Through case studies, we highlight the utility and efficacy of our pipeline.
Importantly, we provide statistical parameters to characterize the cluster size distribution often
observed in biological systems. We envision this tool to be broadly useful in decoding the
interplay of kinetics and thermodynamics underlying the formation and function of biological
condensates.

Code and documentation: https://caspule.github.io/caspule/

Author Summary

Living cells contain droplet-like compartments called biomolecular condensates that organize important molecules and reactions without a surrounding membrane. Understanding how these condensates form and behave helps us learn more about healthy cellular function and diseases. Condensate forming biopolymers (proteins and nucleic acids) often contain a sticker spacer architecture that gives rise to interesting emergent properties when they assemble into a condensate. Here we report an easy-to-use computational pipeline, called CASPULE, that allows us to simulate and analyze the condensation of polymer chains. Unlike previous tools, CASPULE models both the physical motion of these molecules and specific bonding interactions between sticker segments. This user-friendly tool will enable researchers to explore the governing principles underlying the formation and function of biomolecular condensates.

Introduction

Biomolecular condensates are membraneless, phase‑separated compartments that organize and regulate diverse biochemical processes across the cytoplasm, nucleus, and cellular membranes (1-4). Condensates are now widely recognized as viscoelastic network fluids that often arise when phase separation is coupled to percolation (PSCP) in multivalent, sticker– spacer macromolecules (5). In this view, stickers form transient, *specific* physical crosslinks while spacers tune solubility, chain flexibility, and the coupling between density and networking transitions. This modular architecture endows condensates with rheological behaviors and kinetic responses that differ sharply from those of simple homopolymer fluids, motivating computational frameworks that can connect molecular parameters to mesoscale organization and dynamics.

In many sticker–spacer systems, each sticker can bind only one partner at a time (strict 1:1 valency). This single‑occupancy constraint changes condensate kinetics, topology, and rheology in ways that are not reproduced by purely isotropic, short‑range attractions (e.g., Lennard Jones forces). For example, a polymer model with stickers that form at most one specific bond can result in an exhaustion of free valencies within nascent clusters. This in turn produces metastable, long‑lived multi‑droplet states even without active processes (6). This kinetic arrest is not captured by simple isotropic attractions because it depends on the book‑keeping of available bonding sites and on valency‑limited crosslinking within and between clusters (7).

Patchy‑particle simulations (8) likewise demonstrate that valency and patch topology reorganize condensates across scales, from multilayered interiors to differential client/scaffold partitioning. In a minimal model, Sanchez‑Burgos et al. (9) show that higher‑valency species preferentially populate condensate cores while lower‑valency species enrich interfaces. Additionally, Polyansky et al. (10) connect interaction valency and protein compactness to the fractal dimension of condensates, providing an analytical bridge from atomistic contacts to droplet‑scale structure. These trends, which reflect network‑connectivity maximization under valency constraints, further underscore that single‑site occupancy (not just attraction strength) is a first‑order control knob. Furthermore, studies also suggest that the nature of interactions matters for regulation of condensates. Using in-vitro experiments and patchy-particle simulations, Ghosh et al. (11) establish three archetypal classes of macromolecular regulators -- volume‑exclusion promoters, weak‑attraction suppressors, and strong‑attraction promoters.

The classification is an outcome of site-resolved interactions which depend on the relative
strengths of specific versus non-specific attractions which reiterate the need to model specific
and non-specific contributions separately rather than by a single isotropic interaction term.
Taken together, these studies show that systems with strict 1:1 sticker binding can
phase-separate yet display distinct cluster statistics, slowed coarsening, metastable
multi-droplet states, multilayered composition, and different viscoelastic responses compared
with systems modeled by simple isotropic attractions. Therefore, the incorporation of single-
valent and anisotropic specific interactions is critical in simulations aimed at predicting dynamic
properties, assembly kinetics and architectures.

Current simulation tools cover parts of this landscape but leave a practical gap. Lattice-based
Monte Carlo engines such as LASSI (12) can map equilibrium phase behavior for multivalent
polymers efficiently. However, they do not furnish time-resolved dynamics of cluster growth,
aging, and coalescence. On the other hand, despite capturing the dynamics, conventional
coarse-grained MD, such as OpenABC (13) or Martini-3 (14), typically lacks a principled,
efficient mechanism to enforce single-valent sticker binding. The existing software, such as
Readdy (15) or SpringSaLaD (16), serves as standalone applications to model polymer
crosslinking; but they are limited in terms of the system size due to the lack of parallel
execution.

Here we introduce CASPULE (**C**ondensate **A**nalysis of **S**ticker Spacer **P**olymers **U**sing the
LAMMPS **E**ngine), a pipeline that enforces strict 1:1 site valency while preserving physical
polymer dynamics. CASPULE can leverage the broad and diverse capabilities of LAMMPS (17),
a coarse-grained MD engine extremely popular amongst multiple scientific communities. Within
LAMMPS, CASPULE encodes chain connectivity via harmonic bonds and bending elasticity,
non-specific cohesion via truncated Lennard-Jones interactions with tunable well depth (E_{ns}),
and specific sticker–sticker bonds via a shifted-harmonic well of depth (E_s) that forms and
breaks stochastically. Critically, each sticker can hold at most one bond at a time, ensuring
single-valent, reversible crosslinking. This design decouples the energetics of specific binding
(E_s) from weaker non-specific (E_{ns}) interactions, enabling cleaner titrations of distinct
interaction types.

We formalize CASPULE as an end-to-end, reproducible protocol and provide reference tests
that (a) highlight how E_s and E_{ns} independently tune network connectivity and density
transitions , (b) validate that dynamics obeys detailed balance, and thus converges to canonical

distribution (c) map phase boundaries in parameter space using standardized readouts (energy
traces, sticker‑bond saturation, cluster statistics), and (d) display scalability of our approach.

Figure 1: Overview of the CASPULE pipeline. It has three components – setup (step 1), simulation (step 2) and analysis (step 3). In step 1, we create a sticker spacer polymer chain in a template-based manner, where a pattern of sticker-spacer serves as a building block. Multiple repeats of such blocks create a chain. Red and grey beads represent stickers and spacers, respectively. Once the chains are created, we pack multiple copies inside the simulation box using the Moltemplate and PACKMOL software packages. This creates an initial condition which may contain many copies of multiple chain types. In step 2, we simulate the polymer condensation using the LAMMPS software. In step 3, we analyze various biophysical properties (cluster size distribution, extent of sticker saturation, radial location of stickers inside the condensate etc.) of the system.

Materials and Methods

The overall workflow of CASPULE contains three steps – setup, simulate and analyze (Fig. 1). We have provided stepwise instructions in our CASPULE website (https://caspule.github.io/caspule/). For convenience, we will summarize the key steps here.

A. Step 1 – simulation setup

A.1. Construction of sticker spacer polymer: First, we define a building block consisting of stickers and spacers. This block segment is then repeatedly combined into a chain of arbitrary length where the number of segments define the length of chain, and arrangement of sticker-spacer within a segment determines the overall spatial pattern of the chain. This method allows us to create chains with arbitrary lengths and patterns.

A.2. Setting up data file: Once multiple chain types are created, we use Moltemplate (18) and PACKMOL (19) to create the initial condition of the simulation. Moltemplate allows us to instantiate multiple copies of a given chain, and PACKMOL provides initial coordinates of those chain beads that can be fit into a simulation box prescribed by the user. The initial condition is stored as a "data" file.

A.3. Force-field: We use the LAMMPS package (17) to perform Langevin Dynamics simulations of our sticker spacer polymers. An input file contains all the force-field information to model polymer movement and structure.

1) **Chain connectivity:** To ensure connectivity within a chain, intra-chain beads are connected by harmonic springs ("*bond_style harmonic*" in LAMMPS). Stretching energy of each harmonic bond,

$$E_{bond} = K_b (R - R_0)^2$$

where K_b is the spring constant and R_0 is the equilibrium bond distance. R measures the distance between the bonded beads at any given time. Typical values used in our model, R_0 = 10 Å and $K_b = 3 \frac{kcal}{mol*Å^2}$.

2) **Chain flexibility:** To allow chain flexibility, angle (θ) between three successive beads is modelled with a cosine function ("*angle_style cosine*" in LAMMPS):

$$E_{bending} = \kappa * (1 - cos\theta)$$

where κ determines the bending stiffness. Typical value used in our model, $\kappa = 2\ kcal.mol^{-1}$.

3) **Specific interaction:** To encode "specific" interactions between complementary sticker
types, we introduce reversible bonds (Fig. 2B). We use "*fix bond/create/random*", first
described here (20), and "*fix bond/break*" functionality to implement a reversible bond
formation scheme. When two stickers approach each other within a cut-off radius (R_{cut}), they
can form a "bond" with a probability, p_{on}. The bond can be broken with a probability of p_{off}, if
the distance, $R \geq R_{cut}$. These are "specific" interactions because once a sticker pair is
bonded, they can't form another bond with complementary stickers that are still within R_{cut}.
In other words, each sticker has a valency of 1. The inter-sticker bonds are modelled with a
shifted harmonic potential ("*bond_style harmonic/shift/cut*" in LAMMPS),

$$E = \frac{E_s}{(R_0 - R_{cut})^2} [(R - R_0)^2 - (R_{cut} - R_0)^2]$$

R is the inter-sticker distance. At the resting bond distance (R_0), the energy is $-E_s$. We refer
to this well depth parameter as <u>specific energy</u>. When two complementary stickers form a
bond, the gain in energy is Es. We also note that, at $R = R_{cut}, E = 0.$ For $R > R_{cut}, E$ is set
to be zero. In our model, $R_0 = 1.122 * \sigma, \sigma = 10\,\text{Å}, R_{cut} = R_0 + 1.5\text{Å}, p_{on} = 1, p_{off} = 1.$

4) **Non-specific interaction:** Apart from inter-sticker interaction, each pair of beads (stickers +
spacers) interacts via a non-bonded isotropic interaction (Fig.2C), modelled by Lennard-
Jones (LJ) potential ("*pair_style lj/cut*" in LAMMPS),

$$E_{LJ} = 4 * E_{ns} * \left[\left(\frac{\sigma}{r}\right)^{12} - \left(\frac{\sigma}{r}\right)^6 \right]$$

where σ represents the bead diameter and r is the separation between the beads. E_{ns} is the
depth of LJ energy-well that determines the strength of attractive potential. To distinguish it from
specific interaction (described above), we refer to this parameter as <u>non-specific energy</u>. To
achieve computational efficiency, the LJ potential is truncated at a cut-off distance (R_{max}). In our
model, $\sigma = 10\,\text{Å}, R_{max} = 2.5 * \sigma.$ We also turn off the LJ interactions for bonded beads with
"*special_bonds lj 0 1 1 angle yes*". This also includes stickers who can reversibly switch
between bonded and unbonded states.

Our previous studies (7, 21) utilized this implementation of Es and Ens, and a precursor form
here (6), to probe the biophysics of sticker spacer condensates.

B. Step 2 - Simulation

B.1. Langevin dynamics: We perform Langevin dynamics simulations, in a 3D cuboid
volume with periodic boundary conditions, using LAMMPS' "*fix langevin*" thermostat coupled
with NVE integrator ("*fix nve*"). We use the "real" unit convention ("*units real*" in LAMMPS) in our
simulations. Temperature of the system is usually kept at 310 Kelvin. Mass of each bead can
vary depending on the system of interest; a typical value is 100 grams/mole. A typical timestep
of 15 to 30 femtoseconds (fs) is used in our simulation. There is a damping (t_{damp}) parameter in
Langevin thermostat which mimics the viscosity of the medium; typical value, t_{damp}= 500 fs. A
titration of t_{damp} provides insights on dynamic behaviors (kinetic arrest for condensate size
distribution (6), for instance) of the system. The solver attempts to form or break the sticker-
sticker crosslinking once in every 20 timesteps.

We generally utilize multiple CPUs to run simulations with MPI-enabled LAMMPS solver. As a
rule of thumb, we allocate 500 beads per CPU. A typical system can have 10^4 to $5*10^4$ beads
which may require 20 to 100 CPUs. Since condensate formation can be spatially
heterogeneous, we also employ the CPU load balancing strategy ("*comm_style tiled*" & "*fix*
balance" in LAMMPS) that adapts a dynamic spatial decomposition of the simulation volume
based on the chain density.

B.2. Metadynamics: For certain molecular simulation process, standard Langevin
dynamics may be a time-consuming strategy. To expedite the process, we employ
metadynamics (22, 23) ("*fix colvars*" in LAMMPS) which deposits auxiliary gaussian potentials to
bias the system to move along the user-defined collective variable (CV). For instance, clustering
of chains (process) can be achieved via radius of gyration (CV) axis of the system or merging of
two condensates (process) can be achieved via inter-condensate distance (CV) axis (7).

C. Step 3 - Data analysis

Once the LAMMPS simulations are over, we can analyze the results guided by questions of
interest. Since Langevin dynamics has a stochastic component, we typically run 5 trials and
sample the output to obtain statistically robust behavior. A multitude of analysis sheds light on
the kinetic and thermodynamic state of the system. Time course of the potential energy informs
us about whether the system converges to a steady state or not. How the bonded sticker
fraction evolves with time is another important variable to analyze. During the course of
simulation, we also save the system configuration ("system_timestamp.restart") at some regular
interval. These restart files contain information about the location and connectivity of chains
which can be converted into a network. Extending the capabilities of MolClustPy (24), we then

employ graph-based analysis to identify subnetworks at a given timepoint and to examine how

the sub-network

Figure 2: Quantification of clustering dynamics. (**A**) Illustration of the two-component sticker-spacer system. Each component consists of 10 stickers (red and cyan beads) and 40 spacers (yellow beads). We only allow heterotypic interactions, that is, red stickers interact with cyan stickers, but red-red or cyan-cyan are not allowed. (**B**) Stickers engage in specific interactions (Es). A complementary sticker (red and cyan) pair can form a reversible bond within a cutoff radius, Rcut. Once bonded, they cannot engage with another sticker that may be present within Rcut. In other words, each sticker has a valency of 1. (**C**) All beads (except bonded stickers) in the system experience non-specific interactions (Ens), modelled by Lennard-Jones (LJ) potential. One bead can interact with multiple beads, permitted by volume exclusions. A bead diameter (σ) is set by the minimum distance between two bead centers. (**D**) Snapshots of a multi-chain system undergoing clustering as a function of time. A total of 400 chains (200 chains each type) are placed uniformly inside a cubic box (length = 800Å). Sticker-sticker (Es = 6kT) interactions drive inter-chain crosslinking and weaker spacer-spacer (Ens = 0.3kT) interactions tune the cluster compaction. (**E**) Energy time course of the system. E_{bond} includes all the bonds (permanent and breakable) present in the system. E_{pair} refers to the sum of contact energies coming from the pairwise Lennard-Jones interactions. E_{angle} is angular energy. $E_{potential} = E_{bond} + E_{pair} + E_{angle}$. Energy unit is kcal/mol. (**F**) Time course of radius of gyration (R_g^{system}) and sticker saturation. Inset shows the zoomed in version of the first half. The red dashed line indicates the time needed to equilibrate the system's Rg, while the blue dashed line indicates the time needed by the stickers to reach to a steady saturation level. In (**E,F**), data is averaged over 5 stochastic runs. Solid line is mean, shaded area is standard deviation.

distribution evolves over time. Since a sub-network is a cluster of connected chains, this
analysis provides detailed statistics of cluster size distribution and extent of sticker saturation
within those clusters. This method can also be used to extract spatial topology of the cluster;
one example is to compute the radial density profile of stickers and spacers within a cluster and
how it changes as a function of sticker pattern in a chain. In the next section, with example
simulations, we demonstrate the key strengths of our pipeline.

Results and Discussion

1. Dynamics of condensate formation

We consider a two-component heterotypic system (Fig. 2A) where complementary stickers from
different chains form crosslinks and drive clustering. Each chain contains a total of 50 beads
where 10 stickers are distributed uniformly along the sequence. Red-stickers from chain type A
can interact with cyan-stickers from chain type B. Specific energy (Fig. 2B), Es = 6kT and non-
specific energy (Fig. 2C), Ens = 0.3kT.

Fig. 2D displays temporal snapshots of the system as the chains undergo clustering, while Fig.
2E reports the corresponding energy trend that gradually drops and reaches a plateau. The
potential energy has three components – bonded (E_{bond}), non-bonded (E_{pair}) and angular (E_{angle})
energy. As more stickers form reversible bonds, bonded energy (blue line) drops since each
inter-sticker bond lowers the energy by Es (6kT in this case). The E_{pair} trace closely follows $E_{bond,}$
but with a slight delay (magenta line), which indicates that the spacer mediated interactions kick
in once the specific bonds hold the chains together. This secondary interaction controls the
density of the cluster. The slight downward trend in angular energy (yellow line) shows
relaxations of individual chains once they are fully integrated within the cluster. At an earlier
stage, there are more smaller clusters with higher surface area which put angular strains to
more chains – an effect akin to surface tension. When those segments merge to become one
large spherical cluster, due to reduction in surface-to-volume ratio, more chains adopt relaxed
conformations with an overall drop in angular energy.

Figs. 2F highlights the interplay of two processes – sticker saturation and clustering of chains.
Sticker saturation is defined as the fraction of stickers that are in bonded state. R_g^{system} is the
radius of gyration computed for all the beads in the system. Around 40 million steps, sticker

Figure 3: Test of detailed balance for specific interactions. (A) Thermodynamic criteria of detailed balance for a two-sticker (orange and green) specific interaction scheme. π_U and π_B are stationary probabilities of finding the system in unbound (U) and bound (B) state, respectively. $P_{B\rightarrow U}$ and $P_{U\rightarrow B}$ are transition rates from bound to unbound, and vice versa. K_{eq} is equilibrium constant that varies exponentially with the depth of the energy well (Es). **(B)** Simulation setup consisting of two stickers. The expediate the diffusion driven search process, a pseudo-one-dimensional box (with periodic boundaries) is considered where both stickers can switch between bonded and unbonded states. **(C)** A representative time course of bonding dynamics (1 is bonded and 0 is unbonded). At two successive frames (t and t'), the system (s) can display one of the four possibilities; $BB: s[t] = 1 \ and \ s[t'] = 1$, $BU: s[t] = 1 \ and \ s[t'] = 0$, $UB: s[t] = 0 \ and \ s[t'] = 1$, $UU: s[t] = 0 \ and \ s[t'] = 0$. **(D)** Scaling behavior of equilibrium quantities with specific interaction strength, Es. Two sides of vertical axis show two different quantities (color coded). The black dashed line is the linear fit. A linear regression with R² = 0.99 and a p-value of 2×10⁻☐ indicates an excellent linear fit.

saturation reaches the maximal level (~ 0.72) while the system takes about 170 million steps to
reach the highest compaction or lowest R_g^{system}. This is consistent with the slight delay in time
trace between E_{bond} and E_{pair} (Fig. 2E). At Es = 6kT and Ens = 0.3kT, sticker-sticker bonds act as
primary drivers of clustering; spacer interactions operate on a secondary level and make the
clusters more compact. We note here that spacers alone can't trigger clustering, and the chains
will remain in a dispersed state in the absence of stickers. This provides a biological control
mechanism where phase separation can be reversibly induced by changing the sticker state (on
and off). More importantly, the kinetic interplay of sticker saturation and clustering can lead to
non-trivial outcomes as a function of energy parameters (Es, Ens) and simulation volume. For
stronger Es and larger simulation box, chains will collapse into smaller clusters with high degree
of saturated intra-chain stickers; this yields a metastable system (6, 7) with many long-living
clusters instead of one large cluster.

2. Specific interaction scheme conforms to the detailed balance

Next, we set out to test whether our specific interaction scheme (between stickers) conforms to
the principle of microscopic reversibility a.k.a. detailed balance. When two stickers form a bond,
the system gains Es amount of energy; breaking that bond requires overcoming the energy well
(Figs. 3A, 2B). If we consider a two-state (bound: B and unbound: U) system, then requirements
of detailed balance read:

$$\pi_U P_{U \to B} = \pi_B P_{B \to U} \quad (1)$$

$$K_{eq} = \frac{\pi_U}{\pi_B} = \frac{P_{B \to U}}{P_{U \to B}} \propto e^{-\frac{E_S}{kT}} \quad (2)$$

$[\pi_{U,}\pi_B]$ indicates stationary probabilities of finding the system in unbound and bound states,
respectively. $P_{U \to B}$ corresponds to the unbound-to-bound transition rate, while $P_{B \to U}$ reflects the
reverse rate. Equation 1 denotes the equality of fluxes. Equation 2 posits that equilibrium
configuration of such two-state system should obey the Boltzmann distribution.

To test out the validity of detailed balance criteria, we set up a two-particle simulation (Fig. 3B)
in a pseudo 1D box where two stickers can diffuse and form a bond reversibly. Since there are
only two stickers, the system can only switch between bond = 0 and bond = 1 (Fig. 3C). To
quantify switching frequency, we capture the system at two successive timeframes which
displays one of the four configurations: BB, BU, UB and UU. Collecting these statistics from a
long trajectory (10 million frames), we can extract stationary and dynamic information of the

system by the following method: $\pi_U = \frac{N_U}{N_U + N_B}, \pi_B = \frac{N_B}{N_U + N_B}, P_{U \to B} = \frac{N_{UB}}{N_U}, P_{B \to U} = \frac{N_{BU}}{N_B}$, where

$N_U = N_{UU} + N_{UB}, N_B = N_{BB} + N_{BU}$. N_{ij} refers to the number of frames where the system can

be found in state i and j at two successive timeframes.

Fig. 3D summarizes the results from the two-particle simulations. There are two major findings:

a. for a given Es, the cyan circle perfectly coincides with the red triangle, that is, $\frac{\pi_U}{\pi_B} = \frac{P_{B \to U}}{P_{U \to B}} =>$

$\pi_U P_{U \to B} = \pi_B P_{B \to U}$. This proves the validity of first criteria shown by Equation 1.

b. the logarithm of thermodynamic constant drops linearly with Es, that is, $\log(K_{eq}) \propto -E_s =>$

$K_{eq} \propto e^{-E_s}$. This is the second validation as outlined in Equation 2.

Hence, the two-particle simulation provides evidence in favor of the detailed balance. The
reversible bond-formation protocol between stickers seems to be consistent with the basic
tenets of statistical physics.

3. Phase transition boundary and bond lifetime

One major application of CASPULE is to probe the phase transition behavior of biopolymers. To
demonstrate an example (Fig. 4A), we consider a preformed cluster (as formed in Fig. 2D, last
snapshot) and titrate the specific interaction energy (Es) between stickers. At a low Es, the
cluster dissolves (Fig. 4A). Above a threshold level of Es, the cluster is stable. If we
systematically compute the clustering state of the system as a function of Es, we observe a
switch-like behavior (Fig. 4B). Here, ACO measures the average clustering state of the system,
as introduced here (24). The fraction of total chains in the cluster of size S_i,

$$f_i = \frac{n_i S_i}{N_{total}}$$

277 where n_i is the number of clusters of size S_i and N_{total} is the total chain count. Then,

$$ACO = \sum_i f_i S_i = \frac{1}{N_{total}} \sum_i n_i S_i^2$$

278 ACO is then normalized by the total chain count. The upper limit of this normalized parameter is
279 now 1, which includes all chains in one large cluster. When the system is fully dispersed (all
280 chains are in monomeric state), $ACO \sim \frac{1}{N_{total}} \ll 1$. We note that ACO can provide useful

281   information once the system contains a mix of large clusters. This quantification of cluster

282   distribution is important

Figure 4: Quantification of the phase transition boundary. (**A**) Illustration of phase transition by titrating specific energy (Es). The cluster dissolves at Es lower than a critical value. Above the critical level of Es, cluster is stable. (**B**) Average cluster occupancy (ACO) normalized by the total number of chains in the system. See main text for definition. (**C**) Fraction of bonded sticker $\left(\frac{Bonded\ stickers}{Total\ stickers}\right)$ or sticker saturation. (**D**) Inter-sticker dissociation events. The shaded area indicates a region after the phase transition.

Figure 5: Scaling of execution time with system size. (**A**) Three representative clusters with different chain counts (N_{chain}) that are simulated with higher number of CPUs (N_{CPU}) in parallel. (**B**) Execution time (reported in seconds, log10 scale) as a function of the system size.

as biological systems often display a size distributed state that may be functionally critical (21).

In our current system, we are dealing with a transition between the dispersed state and a single-

cluster state. The sharp change in ACO (Fig. 4B) indicates a phase transition where the energy

threshold lies around Es = 4kT. When we look at the bonded sticker fraction (Fig. 4C), it also

shows sigmoidal behavior but with more gradual change. Nevertheless, a critical fraction of

stickers needs to be bonded to trigger the phase transition which is cooperative in nature. It is

important to note that the numerical accuracy and execution time of our simulations depends on

the timestep (Fig. S1). Shorter timesteps improve the accuracy of results while delaying the

execution time. The viscosity (damping time) parameter in Langevin dynamics does not affect

the potential energy (Fig. S2) of the system. However, it controls the kinetics by tuning the

diffusion coefficients (Fig. S3) in an expected manner consistent with the Einstein-Stokes

relation. It is worth highlighting that the diffusivity-mediated kinetic effect plays an important role

in controlling the size of metastable condensates (6) where chains get arrested in smaller

droplets in a viscosity dependent manner. In the current work, we overcome this barrier by

starting the simulations in a smaller volume (Fig. 2D). However, with larger box size and

identical Es, the sticker saturation kinetics remains the same, but the timescale related to

diffusion increases – this leads to multiple smaller droplets (kinetic arrest) in place of a single

large droplet (equilibrium-like). Such effect is not expected to emerge in a slab-like geometry

(which is a commonly used technique to access the two-phase equilibrium) since diffusion in

three-dimensional space is qualitatively different than the one observed in "pseudo-one-

dimensional" geometry.

We observe another interesting trend when we compute the inter-sticker dissociation events for

a given time interval (10^6 steps in this case). Fig. 4D shows a non-monotonic trend of events as

we titrate up the Es. Before the phase transition, chains majorly remain as monomers and small

oligomers. In this regime, lifetime of individual bond is short, hence we get more dissociation

events. After phase transition, the dissociation events gradually go down with Es. Importantly,

on a logarithm scale, the decay trend is linear. This suggests that sticker dissociation kinetics

follow an Arrhenius-like form, $event \propto e^{-E_s}$. Since inter-sticker bond formation is diffusion-limited

in nature ($pOn = 1\ when\ R \leq R_{cut}$) and bond dissociation requires overcoming the harmonic

energy well (depth is Es), this Arrhenius-like expression extends the validity of the detailed

balance criteria (Fig. 3) for this many-particle system.

4. Effect of system size on simulation time

Probing condensate biophysics often requires variation of the system size in terms of the
simulation volume or molecular counts. Fig. 5A shows a scenario where we systematically
create clusters with different sizes (N_{chain}) and simulate the system, in parallel, with different
numbers of CPUs. The MPI enabled LAMMPS solver can efficiently simulate a system across
multiple CPUs. In this computational experiment, we first place N/2 chains of each type
$(N_A + N_B = N_{chain} = 40,80,120,160,200,400,600,800)$ in a smaller box and let them cluster. The
fully formed clusters are then placed in a larger box (L = 120nm) and simulated for 10 million
steps with a proportionately higher number of CPUs (Fig. 4A). For example, cluster of 120
chains with 12 CPUs and cluster of 800 chains with 800 CPUs. We also should highlight that the
load_balance feature ("*comm_style tiled*" & "*fix balance*") of LAMMPS is enabled here which
allows dynamic spatial decomposition of the simulation volume and allocate CPUs based on
spatial density. Family of CPUs used in these simulations belong to "Intel Xeon Platinum
8480CL" (sapphire partition in Harvard FAS RC HPC, as of October 2025).

Fig. 5B shows the execution time trend as we increase the system size. The data is plotted on a
log-log scale. Let's say, the execution time (t) scales with system size (N) by a power-law,
$t \sim N^m$. For a linear regime, m = 1 where time to simulate a system grows proportionately with
the size of the system. On the other end, due to parallelization, if execution time is insensitive to
system size, then m = 0. To our satisfaction, we find that m = 0.18 for our simulations. This
smaller exponent verifies the scalability of our approach provided computational resource (N_{CPU})
is not a constraint.

Summary

Embedded in the powerful and popular MD engine (LAMMPS), CASPULE is a versatile and
reproducible protocol to simulate and analyze biological condensates. In this pipeline, single
valent sticker interactions drive polymer crosslinking and weaker non-specific interactions aid in
cluster compaction. The reversible bond formation between stickers is consistent with the
detailed balance criteria, and the lifetime of inter-sticker bonds decays exponentially with the
interaction energy, Es. Due to parallel execution across multiple CPUs, our approach is efficient
and scalable that aims to bridge the gap between traditional MD (molecular dynamics) and MC
(Monte Carlo) based solvers. Our goal here is to give researchers an MD framework rooted in a
mainstream engine that treats stickers properly with limited valency. We believe that our
framework makes it practical to explore design rules for condensate formation, stability,
composition, and function in scenarios where directionality and valency of interactions is a key
governing factor for phase separation.

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Competing interests

The authors declare that there are no competing interests.

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Setup, Simulate, Analyze

CA░PULE

Step 1: System Setup

Building block

Sticker spacer polymer

n = 5

n = 5

Python

Moltemplate

Packmol

Initial condition
(multiple chains of multiple types)

Step 2: Langevin Dynamics

LAMMPS

Condensates

Step 3: Data Analysis

Python

Fraction of Bonded Stickers

Case 1   Case 2

Radial Density

Stickers
Spacers

Radial Distance (Å)

Fraction of total chains

System 2
System 1

Cluster size (chains)

A

A-sticker
B-sticker
Spacers

B Specific interactions (valence = 1)

R_{cut}

Es = 5kT
Es = 10kT

C Non-specific (LJ) interactions

Ens = 0.3kT
Ens = 0.6kT

D

Δt_1 Δt_2 Δt_3

E

E_{bond}

E_{angle}

E_{pair}

$E_{potential}$

Timesteps (10^6)

F

$Rg^{system}(\text{Å})$

Sticker saturation

Timesteps (10^6)

A

Low Es ← Unstable cluster (below PTT)

High Es → Stable cluster (above PTT)

PTT = phase transition threshold

B

Normalized ACO vs Es (kT)

C

Fraction of bonded stickers vs Es (kT)

D

Dissociation events vs Es (kT)

$event \propto e^{-E_s}$

$\log(event) \propto -E_s$

A

$N_{chain} = 120$
$N_{CPU} = 12$

$N_{chain} = 400$
$N_{CPU} = 40$

$N_{chain} = 800$
$N_{CPU} = 80$

B

$t \sim N^m$

Execution Time, log(t)

System Size, log(N)

m = 0.18