Testing the parasite mass burden effect on host behaviour alteration in the

***Schistocephalus*-stickleback system**

Running title: Effect of an artificial macroparasite on host behaviour

Lucie Grécias[1], Julie Valentin[1], Nadia Aubin-Horth[1]

[1]Département de Biologie et Institut de Biologie Intégrative et des Systèmes

(IBIS), Université Laval, Quebec, Canada

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Corresponding author
e-mail: Nadia.Aubin-Horth@bio.ulaval.ca

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ABSTRACT

Many parasites with complex life cycles modify their intermediate hosts'
behaviour, which has been proposed to increase transmission to their definitive
host. This behavioural change could result from the parasite actively
manipulating its host, but could also be explained by a mechanical effect, where
the parasite's physical presence affects host behaviour. We created an artificial
internal parasite using silicone injections in the body cavity to test this *mechanical*
effect hypothesis. We used the *Schistocephalus solidus*- threespine stickleback
(*Gasterosteus aculeatus*) system, as this cestode can reach up to 92% of its fish
host mass. Our results suggest that the mass burden brought by this
macroparasite alone is not sufficient to cause behavioural changes in its host.
Furthermore, our results show that wall-hugging (thigmotaxis), a measure of
anxiety in vertebrates, is significantly reduced in *Schistocephalus*-infected
sticklebacks, unveiling a new altered component of behaviour that may result
from manipulation by this macroparasite.

Introduction

Many parasites have complex life cycles with multiple hosts, and alter various aspects of their host's biology (Poulin, 2010). Infection can be accompanied by changes in morphology, physiology, life history and behaviour of the host (Poulin and Thomas, 1999). Those phenotypic modifications can stem from non-exclusive causes: specific manipulation, side effects (pathological consequences) or by-products, which can be coincidentally beneficial (Thomas et al., 2005). Understanding these mechanisms will shed light on host–parasite interactions and coevolution (Poulin, 2007). However, in most host-parasite systems, the proposed causes of those changes are not tested using experimental confirmation (Moore, 1983). This is in part because it is technically complicated to do so, as multiple proximal causes may intervene to result in these altered host phenotypes (Grécias et al., 2017).

In host-parasite systems where the parasite infects its host internally, the presence of this foreign body could cause modification in the host phenotype, including its behaviour. The parasite's "mechanical effect" can be defined as all physical or behavioural impacts of the parasite that are related to its presence and that have consequences on host phenotype in the time window in which the parasite exerts those physical or behavioural modifications. For example, the metacercariae of the *Tylodelphys* trematode infects the vitreous humour of the eyes of its fish host (Stumbo and Poulin, 2016). The parasite is not encysted and can cross from one side of the eye to the other. This trematode shows a daily rhythm of movement within the eye, obstructing its host's retina during the day when its final fish-eating bird host is active, while leaving the eye fully functional at dusk and night. This example shows the combined effect of mechanical and parasite behaviour as a cause of potential host behaviour modification. Another example of manipulative parasite that might change its host behaviour through a mechanical modification combined with its behaviour is the trematode

Leucochloridium paradoxum, which forms broodsacs, migrate to the tentacles of
terrestrial snails and pulsate rapidly. Thanks to this parasite presence and
behaviour, the snails' eye stalks resemble caterpillars, resulting in increased
predation by the definitive bird host (Wesołowska and Wesołowski, 2014). In both
cases, the parasite's behaviour (circadian movement in the eye, migrating to eye
stalk and pulsating) is coupled with the effect of physical presence to affect the
host's phenotype, but it is conceivable that the sole parasite presence could
affect its host.

In some cases, the mass of the internal parasite approaches the mass of its host
(Arme and Owen, 1967). The threespine stickleback (*Gasterosteus aculeatus*)
can be infected by a tapeworm, *Schistocephalus solidus.* This macro parasite
can attain 40% of the host weight and, as multi infection is common, combined
worms can weigh up to 92% of the host weight (Hopkins and Smyth, 1951). The
space taken by the parasite in the body cavity of the host could have major
impact on the fish physiology. Size of visceral organs is forced to be smaller
because of the lack of space (Pascoe and Mattey, 1977; Walkey and Meakins,
1970). The stomach's capacity for expansion may thus be limited in heavy
infections (Milinski, 1985), potentially resulting in a decrease in food intake
(Wright et al., 2006).The fish's abdomen becomes grossly distorted as the
parasite grows inside it (Arme and Owen, 1967). This abdomen distortion may
make sticklebacks more vulnerable to predatory birds that select the largest
available fish from the population (Van der Veer et al., 1997). *S. solidus* might
also alter the buoyancy of its fish host, as the density of the cestode is higher
than that of the stickleback (LoBue and Bell, 1993). This means that the host
must use its swim bladder to reach higher buoyancy despite the parasite mass
(Talarico et al., 2017). Concurrently with morphological changes, a suite of
behaviours is changed in sticklebacks harbouring at least one infective parasite.
They show more risky behaviours: they lose their anti-predator response and
forage at a higher rate, even under the risk of predation (Milinski, 1985; Giles,

1987; Godin and Sproul, 1988; Barber et al., 2004) (Tierney et al., 1993). They

also spend less time swimming with a group than uninfected ones when satiated

(Barber et al., 1995; Barber et al., 1998). Moreover, infected fish tend to stay at

the water surface both in nature and in the laboratory, contrary to healthy

sticklebacks (they show "reversed geotaxis", LoBue and Bell, 1993; Quinn et al.,

2012). Several studies on host manipulation have aimed to unravel the most

plausible cause of behaviour modification. But to our knowledge, no study has

tested the mechanical effect hypothesis of host alteration by a parasite using an

experimental approach, in this system or another.

The aim of this study was to assess the impact of a parasite mass burden on the

behaviour of its host in order to test whether there is a causal link between the

parasite "mechanical effect" and behaviour alteration in the stickleback-cestode

system. We used phenotypic engineering, the experimental modification of an

organismic phenotype, as it allows to separate a complex phenotype into its part

and to focus on the effects of a single trait (Kliman, 2016) that allows testing

predictions in a specific manner (Andersson, 1992; Aubret et al., 2003). We

manipulated the space available in the body cavity of the fish by injecting an

artificial silicone "worm" that is inert but similar in physical property to a live

parasite, allowing isolating the mechanical effect of *Schistocephalus* on its host.

We quantified four different behaviours: reversed geotaxis (tendency to use the

top of the water column), response to a predator, feeding, and thigmotaxis (wall-

hugging tendency). We predicted that sticklebacks harbouring an artificial worm

would increase the time they spend swimming at the surface (reversed geotaxis)

because of their buoyancy, as infected sticklebacks do. We also predicted that

the sticklebacks harbouring an artificial worm would decrease their latency to

start feeding, to freeze after an attack (they would freeze immediately instead of

displaying a typical fleeing anti-predator response, because of an impairment in

locomotion) and to resume moving. Finally, we measured a behaviour not

previously quantified in infected sticklebacks, the tendency to avoid exposure to

potential threats by hugging walls in an open field (thigmotaxis or centrophobic behaviour). This behaviour is used as a measure of anxiety in mammals, fish and insects (Maximino et al., 2010; Webster and Laland, 2015; Mohammad et al., 2016) and has been observed in other infected hosts (Poulin, 2001). We predicted that infected sticklebacks would have a low thigmotaxis (they would spend less time near the walls of the aquarium and more time in the center) and that sticklebacks harbouring artificial worms would have the same behaviour.

Materials and Methods

Sampling

We caught *Gasterosteus aculeatus* juveniles (n=40) from Lac Témiscouata (47°40'33"N 68°50'15"O, Québec, Canada, August 2015) and kept them for 10 months in a common environment before the behavioural tests. They were kept with the same conditions (1-2 fish per 2 liters) under a natural light:dark cycle mimicking their natural environment (Québec City, Québec, Canada) and a water temperature of 15 °C. Fish were fed every morning with a mix of blood worms and artemia.

Experimental treatments

To evaluate the influence of parasite presence on fish behaviour, we implanted an artificial worm in uninfected sticklebacks. We used an injection of silicone (Mold Star 16 – Fast, Smooth-On, Inc., USA) to recreate the presence of the parasite in the body cavity of its host. This specific type of silicone was selected for its similarity in density with *S. solidus* (see Fig. S1 for a direct comparison). To replicate the mass of the parasite, we injected 80 ul of silicone per injection every two days on three occasions (see below) to achieve a 150 mg mass. In parallel, to discriminate the effect of the mere exposure to silicone on behaviour from the effect of the volume of the artificial worm, we injected a small amount of silicone

to a separate group of fish used as controls (15 ul / injection, for a total mass of 30 mg), also every two days on three occasions.

We had four groups: Silicone Artificial Parasite (80 ul of silicone / injection, n=15), Silicone Control (15 ul of silicone / injection, n=14), infected fish (infected with *S. solidus,* n=5) and control fish (no material injected, n=6). Infected and control fish were handled in the same way as other groups, but instead of injecting them, we only inserted a needle in their body cavity.

Fish were isolated in a 2L tank at the start of the experiment (Day 1). We assigned them randomly to a treatment for the rest of the experiment. Fish were fed every day, except on the day before the behavioural tests. Fish were handled every two days. During the first week (Control week) we handled the fish to recreate the experimental manipulation, but without any injection (day 1, 3, and 5). Fish were taken out of the tank, held in a moist sponge on their back to have easy access to the body cavity. At the end of the Control week (Day 7), we measured their behaviour (see "behavioural experiments" below) and placed them back in their tank where they were fed. The second week (Engineering week) started on day 8. Handling procedure was the same, but we injected the fish according to their treatment (day 8, 10 and 12). At the end of the Engineering week (Day 14), we measured the same behaviours. On day 15, we euthanized the fish. Total length (6.6 ± 0.59 cm), mass (1.6 ± 0.84 g), sex, and the presence of parasite were noted.

Behavioural experiments

Two cameras (on the top and side of the aquarium) recorded all behavioural trials in the test aquarium (30Wx30Dx90L cm, 20cm of water depth).

At the start of the experiment, an isolated focal fish was placed inside an opaque container (500 mL), which was placed horizontally into the behaviour test tank. As soon as the fish exited the container (or after 150 sec), the container was taken out of the aquarium and the behavioural trial started. The first 30 seconds

after the container removal were not used because of the water movement due to
its removal.

Thigmotaxis: Latency to enter the center of the tank and time spent in the center
of the tank (at more than 5 cm of the edge of the aquarium) were analyzed during
120 seconds.

Geotaxis: The time spent near the surface (in the 10 cm upper zone) was also
quantified during this 120-second period.

Latency to feed: Right after the preceding measurements, the fish was fed with
blood worms released in the water using a plastic pipette. Food was released in
front of the fish to ensure it was detected in all trials. Latency to feed was
quantified, up to a maximum of 150 seconds.

Response to a predator: As soon as the fish had fed (or after 150 sec), we
attacked the fish with an artificial heron head to simulate a predator attack. We
quantified the time taken to freeze after the attack, and the time spent frozen until
activity was resumed, up to 150 seconds.

Behavioural and statistical analysis

Latency to enter the center and time spent in the center, as well as time spent
near the surface were analyzed using au automatic tracking module in the
Ethovision software (Ethovision XT 11.5, Noldus Information Technology,
Wageningen, The Netherlands, Noldus et al., 2001). Latency to feed, latency to
freeze after a predator attack and latency to resume activity after the attack were
analyzed by hand. All analyses were done while blind to treatment.

We performed all statistical analyses in R software version 3.0.2 (R Foundation
for Statistical Computing, Vienna, Austria). We conducted analyses of variance
on aligned rank transformed data with the package "ARTool" (Wobbrock et al.,
2011). We aligned and rank transformed our data and ran a nonparametric

ANOVA. Individuals, weeks and treatments and their interaction
(treatment*week) were added to the statistical model. To account for variation in
behaviour between individual sticklebacks even before any manipulation, we
included tank, mass, length and sex of the fish along with the parasite weight as
fixed effects, and fish id as a random effect (for repeated measurements). We
checked the effect of tank, mass, length, sex, parasite weight with visual
validation of multiple PCAs and no effects (clusters) were found on any
behaviour. We then excluded those factors from the model. Finally, we did a post
hoc pairwise comparison with the package "lsmeansLT" (Lenth, 2016) which
reports p-values that are Tukey-corrected for multiple comparisons. We report
significant differences in these post-hoc tests.

Results and discussion

Infection-associated changes in host behaviour are often explained as direct
manipulation by the parasite that facilitate life cycle completion, often by
increasing transmission rates to the final host. However, there are alternative
explanations for these observations that do not necessarily invoke any active
manipulation. We designed the experiment to test the impact of the parasite
mass burden on stickleback behaviour and to compare it to the effect of a *S.*
solidus infection using an artificial worm. Contrary to our predictions,
phenotypically manipulated individuals with an artificial worm mass did not show
similar behavioural responses to infected ones. In fact, the largest difference we
quantified between treatments was between infected fish and fish injected with
an artificial worm. Infected fish spent more time performing risky behaviour while
fish implanted with an artificial worm did not differ from control fish. Thigmotaxis
was different between infected and phenotypically-engineered fish: infected fish
spent significantly more time in the center than fish with an artificial parasite (p =
0.007) and fish used a silicone controls (p=0.039) (Fig. 1a, Table S1 and S2).
Infected fish also had a shorter latency to enter the center of the test tank than

the artificial parasite-implanted fish, but this difference was not significant (post-hoc test, p = 0.055) (Fig. 1b, Table S1 and S2). Geotaxis was not affected: there were no differences in the time spent in the upper part of the aquarium across any of the treatments (Fig. S2, Table S1 and S2). Feeding also differed between groups: infected fish had a significantly shorter latency to feed than fish with the artificial worm (p = 0.022) and fish used as silicone controls (p=0.031) (Fig. 1c, Table S1 and S2). Furthermore, infected fish had a shorter latency to freeze after a predator attack than the artificial parasite-implanted fish (p=0.0003) and the fish injected with a small amount of silicone (p=0.008) (Fig. 1d, Table S1 and S2). There were no significant differences in the time spent frozen after an attack across any of the treatments (Fig. S3, Table S1). Our results show that the experimental behavioural tests were appropriate to detect previously described changes in behaviour in infected fish, but that the phenotypic engineering approach using silicone injections did not result in the predicted behavioural changes. Our results also show that thigmotaxis (wall hugging, a measure of anxiety in several vertebrates) is significantly lowered in infected sticklebacks, a behaviour change not previously reported for this system that can be reliably quantified and used in future studies.

This study was the first to test a strictly mechanical effect hypothesis to explain to behavioural alteration in a parasitized host. Our results suggest that the space taken by a *Schistocephalus* worm at its infective stage when behavioural modifications are usually measured is not the cause of the behavioural changes in its host, at least not in isolation. Indeed, *S. solidus* is alive in the body cavity of its host, and hence is not only a mass burden but is also moving and can impact fish physiology, including the digestive track, when moving between organs. We did not try to reproduce the movement of the parasite in the body cavity of its host as a cause of behavioural modification. Therefore, the "parasite behaviour" component of the mechanical effect hypothesis remains to be tested alone and in combination with other causes such as the immune response, hunger or

neuromodulation (Grécias et al., 2017). Even though we did not measure

significant differences in behaviour between the two volumes of silicone

treatments used, we suggest that the treatment where a small amount of material

is injected is an essential control to have to include in phenotypic engineering

studies trying to mimic the mass of a parasite with inert substances.

Sticklebacks captured during the day near the surface of a lake have a greater

likelihood of being infected with *S. solidus* and have larger parasites than infected

fish caught at the surface only at night (Quinn et al., 2012). Furthermore, in the

laboratory, infected sticklebacks spend significantly more time foraging in the

upper part of an experimental tank than control fish (Talarico et al., 2017).

However, contrary to our prediction, we did not find significant differences in time

spent at the surface between groups (Fig. S2). In a previous laboratory

experiment, we tested if individuals prefer to swim in shallow waters versus in the

deeper part of a tank and showed variation among treatments and also among

individuals from a given treatment (Grécias et al., 2017). We expected that

allowing individuals to use the full water column (rather than giving them a binary

choice) would result in a better discrimination of geotaxis, but it did not in the

experimental set-up used, which was much shallower than in Talarico et al. 2017

(20 cm water depth in the present study versus 50 cm). As a cautionary note, we

only had five infected fish available for the experiment, which limited our

statistical power to detect a geotaxis tendency if this behaviour is more variable

among individuals. Furthermore, we did not use experimental infections but

rather relied on wild infected-individuals. Another study showed no differences in

the water column position at which parasitized and healthy sticklebacks were

caught, and propose that buoyancy problems may increase with larger parasite

mass, but that the worms do not usually attain this mass in the wild because its

host is predated earlier (Ness and Foster, 1999). In freshwater fish, the swim

bladder takes 7% of the body volume (Fänge, 1983). While it has been reported

that there is no significant reduction in swim bladder size of infected fish (Arme

and Owen, 1967), it would be interesting to not only analyze the space taken by

the parasite as in the present study, but also its impact on the swim bladder, as

previously suggested by Meakins and Walkey (1975).

The "wall hugging tendency" (thigmotaxis) was lower in infected sticklebacks, as

they swam readily in the center of the tank, which could reflect lower anxiety

brought-about directly or indirectly by the *Schistocephalus* infection. Thigmotaxis

has been previously measured in wild healthy ninespine sticklebacks (*Pungitius*

pungitius), a closely related species to threespine sticklebacks, and has been

shown to be consistent when measured more than once on the same individual

(Webster and Laland, 2015). Wall-hugging ninespine sticklebacks (high

thigmotaxis) also showed lower activity and a higher latency to explore a new

environment (Webster and Laland, 2015). In zebrafish, avoidance behaviour

measured as thigmotaxis is used to assess anxiety level, and can be lowered

using anxiety-lowering drugs or ethanol exposure (Maximino et al., 2010). The

quantitative assay we used in this study could thus be used in future studies of

the mechanistic proximal causes of behavioural alteration in *Schistocephalus*-

infected sticklebacks. Furthermore, additional investigation of anxiety alteration in

these infected individuals is warranted.

Modification of host behaviour by parasites is a fascinating but controversial

phenomenon, since it is often difficult to disentangle if it is an adaptation of the

parasite or simply a side-effect of the infection that has no fitness consequence

for both the host and the parasite (Thomas et al., 2005). Our findings suggest

that the use of silicone might not be the correct substitute to recreate the parasitic

mass of *S. solidus.* We thus cannot conclude nor reject that the mechanical

hypothesis is a possible cause of behaviour modification by a parasite. However,

the general approach of using phenotypic engineering to create artificial parasites

is a potentially fruitful avenue to dissect the proximal causes of parasitic
manipulation.

Ethics statement

All work was carried out in compliance with Animal Care and Use Guidelines,
under a permit of the Comité de Protection des Animaux de l'Université Laval
(CPAUL, permit 2014-069-3).

Data accessibility

The complete dataset is available as supplementary material

Competing interests

The authors declare no competing or financial interests.

Authors' contributions

L.G. designed the study with input from N.A.-H. L.G. performed the manipulation
experiments, carried out the statistical analysis. L.G. and J.V. analyzed the
behaviours. L.G. and N.A.-H. drafted the manuscript. All authors have reviewed
and agreed on the final manuscript.

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Figures

Figure 1 Behavioural phenotypes across the four experimental conditions.

Lines represent the reaction norm and the standard error for each condition (a)

Thigmotaxis, time spent in the center, (b) Latency to enter the center of the

aquarium, (c) Latency to feed, (d) Latency to freeze after an attack. CTRL: non-

infected (dotted green line, n=6), SC: silicone control (dashed grey line, n=14),

DP: dummy parasite (dash-dotted black line, n=15), INF: infected (solid red line,

n=5).

Supplementary tables

460 Table S1 Statistical parameters of ANOVAS testing the effect of treatment, week
461 of measurement and their interaction on a given behaviour.

Behaviour	Results ANOVA		
	Factor	F	Df	p-value
Latency to enter the center	Treatment	3.24	3	0.03
	Week	1.59	1	0.21
	Treatment*week	0.80	3	0.50
Time in the center	Treatment	5.24	3	0.0042
	Week	1.22	1	0.28
	Treatment*week	2.17	3	0.11
Time spent near the surface	Treatment	2.99	3	0.44
	Week	0.41	1	0.53
	Treatment*week	1.14	3	0.34
Latency to feed	Treatment	3.20	3	0.035
	Week	0.60	1	0.44
	Treatment*week	0.19	3	0.90
Latency to freeze	Treatment	6.49	3	0.001
	Week	0.45	1	0.50
	Treatment*week	0.14	3	0.93
Time spent frozen	Treatment	2.48	3	0.076
	Week	3.86	1	0.057
	Treatment*week	0.87	3	0.46

465 Table S2 Statistically significant comparisons between two treatments for a given
466 behaviour test. INF: infected. DP: artificial worm. SC: silicone control.
467

Behaviour	Results post hoc tests			
	Comparisons	Estimate	Std. Error	p-value
Latency to enter the center	INF - DP	-22.3	8.62	0.0554
Time in the center	INF – DP	25.53	7.77	0.0084
	INF - SC	28.38	7.84	0.003
Time spent near the surface	INF– SC	-24.67	9.63	0.0601
Latency to feed	INF– DP	-24.8	8.41	0.0218
	INF – SC	-23.9	8.48	0.0306
Latency to freeze	INF– DP	-36.3	8.36	0.0003
	INF – SC	-27.8	8.43	0.0082

Supplementary figures

Figure S1. Representation of the relationship between mass and volume of the dummy parasite in silicone (red) and the parasite *S. solidus* (green), representing their similar density.

Figure S2. Time spent in the upper section of the aquarium across the four experimental conditions. Lines represent the reaction norm and the standard error for each condition. CTRL: non-infected (dotted green line, n=6), SC: silicone control (dashed grey line, n=14), DP: dummy parasite (dash-dotted black line, n=15), INF: infected (solid red line, n=5).

Figure S3. Time spent frozen after an attack across the four experimental conditions. Lines represent the reaction norm and the standard error for each condition. CTRL: non-infected (dotted green line, n=6), SC: silicone control (dashed grey line, n=14), DP: dummy parasite (dash-dotted black line, n=15), INF: infected (solid red line, n=5).