

Using biological control data to understand host-pathogen dynamics

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Abstract

Mathematical models have provided important insights into infectious disease spread in animal populations, but are only rarely used in environmental management. Part of the problem may be that direct tests of the models have focused on long-term model predictions, whereas short-term epizootics (= epidemics in animals) can sometimes be more informative about mechanisms of disease transmission. To illustrate this point, we tested models of density-dependent disease transmission and host variation in infection risk using multiple, single-host-generation epizootics of a fatal baculovirus of the Douglas-fir tussock moth (*Orgyia pseudotsugata*). The tussock moth baculovirus causes epizootics naturally, but because of its narrow host range, it is used in biological control to mitigate defoliation, an approach known as “microbial control”. Using a combination of experiments, observational data, and nonlinear-fitting algorithms, we fit a set of stochastic epidemiological models to data from tussock moth microbial control programs. We then used formal model comparisons to show that there are strong effects of host and pathogen density and host variation on epizootic severity, and that transmission events at small scales help explain epizootic severity at large scales. When host density is high, even very low initial virus densities can lead to high cumulative infection rates, suggesting that, in some cases, baculovirus sprays may have been applied to populations that would have collapsed from natural epizootics, even without intervention. Our study illustrates the usefulness of linking epidemiological modeling and nonlinear fitting routines in understanding animal diseases, and shows that simple models can provide important guidance for microbial control programs.

21

Introduction

Efforts to use epidemiological theory to understand animal host-pathogen interactions often focus on long-term dynamics (Keeling and Rohani, 2008), following Anderson and May's championing of host-pathogen models that allow for host reproduction (Anderson and May, 1979; May and Anderson, 1979). Anderson and May's point that host reproduction is important over the long term is inarguable, but for many pathogens, seasonality prevents transmission for part of the year (Altizer et al., 2006). Seasonality may prevent transmission if there are seasons when the vector is not present (Ruder et al., 2015), or when the pathogen does not co-occur with its host (Mihaljevic et al., 2017), or when the host is in a life stage that the pathogen cannot infect (Cory and Myers, 2003). In such cases, models of single epizootics (= epidemics in animals) may be more useful than models of long term disease dynamics.

Comparison of single-epizootic models to short-term data may also be more useful for answering basic questions in disease ecology (O'Dea et al., 2014). Here we ask, how do host and pathogen density and host heterogeneity in infection risk affect disease spread? Simple models have shown that both factors can strongly affect disease spread (Keeling and Rohani, 2008), but the importance of either factor in nature is unclear (McCallum, 2016). Part of the problem may be that, over the long term, the effects of density and host heterogeneity are manifest mostly through changes in equilibrium host and pathogen densities (Anderson and May, 1980), but inferring mechanisms of population change from equilibrium densities is notoriously difficult (Bolker, 2008). Over the short-term in contrast, changes in host and pathogen densities can dramatically alter infection rates (Dwyer and Elkinton, 1993), while heterogeneity in host infection risk can strongly modulate the effects of density (Anderson and May, 1992; Dwyer et al., 1997).

Here we use data on single epizootics to infer the effects of host and pathogen density and host heterogeneity on the spread of an insect baculovirus. Because baculoviruses have narrow host ranges and are obligately lethal (Hunter-Fujita et al., 1998; Moscardi, 1999), baculovirus insecticides have minimal effects on non-target species, a type of biological control known as "mi-

crobial control” (Lacey et al., 2015). The data that we use come from microbial control programs
48 aimed at the Douglas-fir tussock moth, *Orgyia pseudotsugata* (Otvos et al., 1998, 1987), a major
pest of Douglas-fir, *Pseudotsuga menziesii*, and true firs, *Abies* spp., in western North America
(Shepherd et al., 1988). Because managers often monitor infection rates in both sprayed treat-
51 ment populations and unsprayed control populations, and because microbial sprays can sharply
raise pathogen densities, microbial control data allow for a broader range of infection rates and
pathogen densities than data from natural epizootics (Otvos et al., 1987).

54 In microbial-control data sets, even the sprayed populations are fundamentally observational,
in the sense that post-spray conditions are uncontrolled. This is important because factors such as
host density and host heterogeneity in infection risk affect the rate at which individuals contact
57 each other and transmit the disease (Keeling and Rohani, 2008), but inferring individual-level
mechanisms from observational data alone can be very difficult (King et al., 2008). Experiments
in contrast can provide deep insights into individual-level mechanisms, but may not include
60 mechanisms that occur in natural epizootics (Cory and Hoover, 2006). The problem of inferring
how individuals affect population-level disease spread is especially difficult for baculoviruses,
because transmission occurs when uninfected larvae, while feeding on foliage, consume infec-
63 tious “occlusion bodies” released from dead, infected larvae (Cory and Myers, 2003). Baculovirus
epizootics at the scale of forests are therefore widely assumed to be driven by transmission at
the scale of branches (Cory and Myers, 2003), but it is not obvious how this assumption can be
66 tested.

The problem of how to relate individual-level mechanisms to population-level phenomena is
long-standing in ecology (Levin, 1992), however, and methods have therefore been proposed to
69 solve the problem. In one such method, the parameters of a mechanistic model are first estimated
from data collected at the individual level, the parameters are then used in the model to make
predictions, and finally the model predictions are compared to data collected at the population
72 level (Kareiva and Odell, 1987). Agreement between model predictions and population-level data
is then taken as confirmation that individual-level mechanisms can help explain population-level

phenomena, on the grounds that agreement between large-scale data and a model parameterized
75 from small-scale data is unlikely to occur by chance.

Implementations of this approach, however, typically use only point estimates of the model
parameters (Grimm et al., 2005; Keeling et al., 2003; Longini et al., 2005), neglecting the substan-
78 tial uncertainty in the parameter values (Elder et al., 2006). Here we instead follow a formal
Bayesian statistical approach, in which experimental data are used to construct prior distributions
on model parameter values, and observational epizootic data are used to calculate posteriors. To
81 assess whether our experimental data do in fact help us to understand the observational data, we
then use the WAIC model-selection criterion (Gelman et al., 2014), to compare the fit of models
with priors constructed from experiments, to the fit of models with uninformative or “vague”
84 priors. As we will show, models with priors constructed from experimental data can some-
times explain the observational data as well as models with uninformative priors, suggesting
that transmission at the scale of branches helps explain epizootics at the scale of forests.

87 Irrespective of the priors, the epizootic data are best explained by models that allow for
density-dependent transmission and host variation in infection risk. This result is important
for microbial control, because naturally occurring epizootics have often decimated unsprayed
90 populations in the same year and in the same general area as epizootics initiated by baculovirus
sprays (Polivka et al., 2012; Scott and Spiegel, 2002). The occurrence of epizootics in low density,
unsprayed populations has been a surprise to pest managers, but our results suggest that host
93 densities in control plots have been high enough to drive intense epizootics even when initial
infection rates are very low, confirming basic epidemiological theory (Keeling and Rohani, 2008).
Using microbial control data to test disease models can thus produce useful insights into disease
96 ecology, while providing guidance for pest control.

Methods

At roughly 10-year intervals (Mason, 1996), tussock moth densities rise from levels at which larvae are undetectable, to levels at which defoliation is severe (Shepherd et al., 1988). The economic costs of timber losses drove the USDA Forest Service to propagate naturally occurring virus in the lab, producing a formulation known as Tussock Moth Biocontrol-1, or "TMB-1" (Martignoni, 1999). The USDA Forest Service has used TMB-1 widely in the western USA (Polivka et al., 2012; Scott and Spiegel, 2002; Shepherd et al., 1984), while the Canadian Forest Service has deployed a similar formulation in British Columbia (Maclauchlan et al., 2009).

In spray formulations, baculovirus from lab-reared insects is mixed with water or oil and sprayed onto foliage from the air using helicopters, or more rarely from the ground using hoses. Unsprayed control populations are often established in areas that are of lesser concern, because of lower tussock moth densities or less valuable timber. The occurrence of epizootics in controls has been surprising not just because initial infection rates were consistently low, roughly 0.5% in one study (Polivka et al., 2012), but also because the controls were far enough from spray plots (1-50km) that virus drift between plots was unlikely (Otvos et al., 1987; Polivka et al., 2012; Scott and Spiegel, 2002).

Because higher initial densities of virus in sprayed plots have not always led to higher mortality relative to control plots, managers have hypothesized that naturally occurring virus may be more infectious than sprayed virus (Polivka et al., 2012), possibly because of the effects of prolonged low-temperature storage on the sprayed virus (Reed et al., 2003). Epidemiological theory, however, suggests that high virus mortality in control plots may instead have been due to the amplifying effects of multiple rounds of transmission. To test these competing hypotheses, and to test general theories of pathogen spread, we built competing epidemiological models, and we fit the models to data on epizootics in sprayed and unsprayed Douglas-fir tussock moth populations. Our competing models assume either that sprayed and naturally occurring baculoviruses have the same transmission rates, or that sprayed virus has a different (presumably

123 lower) transmission rate. We fit our models using a non-linear model-fitting algorithm (Kennedy
et al., 2014), and we chose the best model using the Watanabe-Akaike Information Criterion
(WAIC), a Bayesian generalization of the more traditional Akaike Information Criterion (AIC)
126 (Gelman et al., 2014; Hooten and Hobbs, 2015; Watanabe, 2010, 2013).

We also tested whether parameters based on our experiments produce accurate model predic-
tions. To do this, we used our experimental data to construct prior distributions on the
129 parameters, and we used our observational data to calculate the likelihood of the parameters.
Under Bayes's law, priors and likelihoods together make up the posterior distribution of the
parameters, which can be used to calculate WAIC scores. We then compared WAIC scores for
132 the case in which we used uninformative priors, to the cases in which we used priors based on
experimental data.

Priors that are constructed from data are usually referred to as "informative priors", because
135 they constrain the prior distribution in a way that improves the model's ability to make predic-
tions. Informative priors therefore add information to the model, much in the way that including
additional data in a likelihood calculation adds information to the model (Bernardo and Smith,
138 2009). When we use ecological field experiments to construct priors, however, the priors may not
improve the model's ability to predict observational data, because experiments are often carried
out at smaller scales than the scales at which natural phenomena occur (Kareiva and Andersen,
141 1988). This is especially true in our case, because our experiments were carried out on single
branches, whereas the epizootic data were collected in forest plots of up to 10 hectares.

Our experiment-based prior distributions might therefore be constrained in a way that biases
144 the model predictions and leads to a poorer likelihood. In our case, testing whether priors based
on our experiments lead to inaccurate or imprecise model predictions is equivalent to testing
whether branch-scale transmission processes help determine the dynamics of forest-scale epi-
147 zootics. By allowing us to compare models with vague priors to models with priors constructed
from the experimental data, the WAIC therefore allowed us to test whether our experiment-based
priors provided useful information about our observational data, and thus whether small-scale

150 transmission helps drive large-scale epizootics.

Because our experiments were carried out at a much smaller scale than the scale of epizootics, it was almost inevitable that priors based on the experiments would produce larger, inferior
153 WAIC scores than models with uninformative priors. As we will show, however, for models with priors based on experiments, WAIC scores were only moderately worse. Experiment-based priors therefore improved our understanding of the mechanisms driving epizootics, even though
156 these priors slightly reduced the accuracy and precision of the model predictions.

Baculovirus Natural History and a Stochastic SEIR Model

In herbivorous insects like the tussock moth, baculovirus transmission occurs when larvae ac-
159 cidentally consume infectious virus particles known as "occlusion bodies", leading to death roughly two weeks later (Cory and Myers, 2003). Shortly after death, viral enzymes dissolve the insect integument, releasing occlusion bodies onto the foliage, where they are available to be
162 consumed by additional larvae (Miller, 1997). Multiple rounds of infection can occur during the larval period, which is early June to mid-August in our study areas in Washington, Idaho, and Colorado, USA, and British Columbia, Canada. The severe epizootics that result can decimate the
165 insect population, especially when larval densities are high (Otvos et al., 1987; Shepherd et al., 1984).

Epizootics are terminated by larval pupation, or by reductions in host density that are so
168 severe that the probability of transmission is extremely low (Fuller et al., 2012). The virus then survives until the next spring by contaminating egg masses, although survival on the forest floor may also play a role (Thompson and Scott, 1979). So far as can be known, the Douglas-fir tussock
171 moth is the only organism in its range that is susceptible to the baculovirus, although *Orgyia* spp. from other parts of North America have been successfully infected in the lab (Rohrmann, 2014).

Because pathogen transmission and host reproduction occur at different times of the year, we can describe baculovirus epizootics using a model of a single epizootic. We began with a standard

Susceptible-Exposed-Infectious-Recovered or "SEIR" model from human epidemiology (Keeling and Rohani, 2008), and we modified the model to allow for heterogeneity in host infection risk. Heterogeneity in infection risk includes a stochastic component that reflects the effects of weather, and a deterministic component that reflects inherent differences between hosts. The model is:

$$\frac{dS}{dt} = -\bar{\nu}e^{\epsilon t}SP \left[\frac{S(t)}{S(0)} \right]^{C^2}, \quad (1a)$$

$$\frac{dE_1}{dt} = \bar{\nu}e^{\epsilon t}SP \left[\frac{S(t)}{S(0)} \right]^{C^2} - m\delta E_1, \quad (1b)$$

$$\frac{dE_i}{dt} = m\delta E_{i-1} - m\delta E_i \quad (i = 2, \dots, m), \quad (1c)$$

$$\frac{dP}{dt} = m\delta E_m - \mu P. \quad (1d)$$

174 As in standard SEIR models, susceptible hosts S that become infected proceed through m
 exposed classes, E_i . Exposed hosts eventually die of the infection, joining the infectious-cadaver
 class P , which is equivalent to the the I class of standard models. Cadaver infectiousness de-
 177 cays at rate μ , due mostly to UV radiation (Thompson and Scott, 1979). Hosts move between
 exposed classes at rate $m\delta$, so that the time spent in a single exposed class follows an exponential
 distribution with mean time $1/(m\delta)$. The total time in the m exposed classes is the sum of m
 180 such distributions, and a well-known theorem has shown that the sum follows a gamma distri-
 bution with mean, $1/\delta$, and variance, $1/(m\delta^2)$ (Keeling and Rohani, 2008). For the tussock moth
 virus, the variance in the speed of kill is quite low (Dwyer (1991), also Online Appendices), so in
 183 practice we fixed $m = 200$, rather than estimating m from the observational data.

The term $\left[\frac{S(t)}{S(0)} \right]^{C^2}$ allows for inherent host variation in infection risk, following models origi-
 nally developed for the gypsy moth baculovirus (Dwyer et al., 1997). This term reflects an
 186 assumption that there is a distribution of infection risk in the host, with mean $\bar{\nu}$ and coefficient
 of variation C , where individual infection risk is represented by the transmission rate ν (Dwyer
 et al., 2000). This is an approximation to a more computationally intensive partial-differential
 189 equation model. The approximation is highly accurate if transmission rates follow a gamma
 distribution, but it is also reasonably accurate if transmission rates instead follow a log-normal

distribution, which has a fatter tail than a gamma distribution (G. Dwyer, unpublished). In general, we assume that transmission occurs among larvae in the fourth instar (= larval stage), the instar that has the biggest impact on cumulative infection rates (Dwyer, 1991; Otvos et al., 1987). To allow for the smaller size of hatchlings, we multiply the initial virus density by the “ratio” parameter, ρ , which is equivalent to the ratio of the number of virus particles produced by a first-instar cadaver to the number produced by a fourth-instar cadaver.

By including the parameter ϵ_t , we allow for daily, stochastic fluctuations in average transmission \bar{v} , such that the value of ϵ_t for a given day is drawn from a normal distribution with mean 0 and standard deviation, σ . By exponentiating ϵ_t , we eliminate the possibility of negative transmission, which would be biologically meaningless. Allowing for stochasticity is important because baculovirus transmission varies due to changes in insect feeding behavior, which in turn may respond to stochastic fluctuations in weather (Eakin et al., 2015). Also, stochasticity may interact in complex ways with disease dynamics, such that the model predictions become more or less variable as an epizootic proceeds, or as initial host and pathogen densities vary between epizootics. By including stochasticity, we allow for this type of variation, ensuring that our estimation procedures are statistically robust. Because weather conditions likely also varied between populations, we estimated a value of the standard deviation σ for each population in our observational data set.

Although the model includes biological details that are not included in classical disease models (Kermack and McKendrick, 1927), the model’s dynamics are qualitatively similar to the dynamics of classical models, as shown by fig. 1 for the deterministic case (stochasticity $\sigma = 0$). Notably, there is a threshold value of the uninfected-host density at $\frac{h}{\bar{v}}$, above which the introduction of a small density of infectious hosts will lead to an increase in the density of infected hosts, and below which the density of infected hosts will always decline. If the density of uninfected hosts is far enough above the threshold, severe epizootics may occur even if the initial density of infected individuals is very low. This behavior is a basic feature of density-dependent disease models (Keeling and Rohani, 2008), and it plays a key role in explaining baculovirus epizootics

in unsprayed populations.

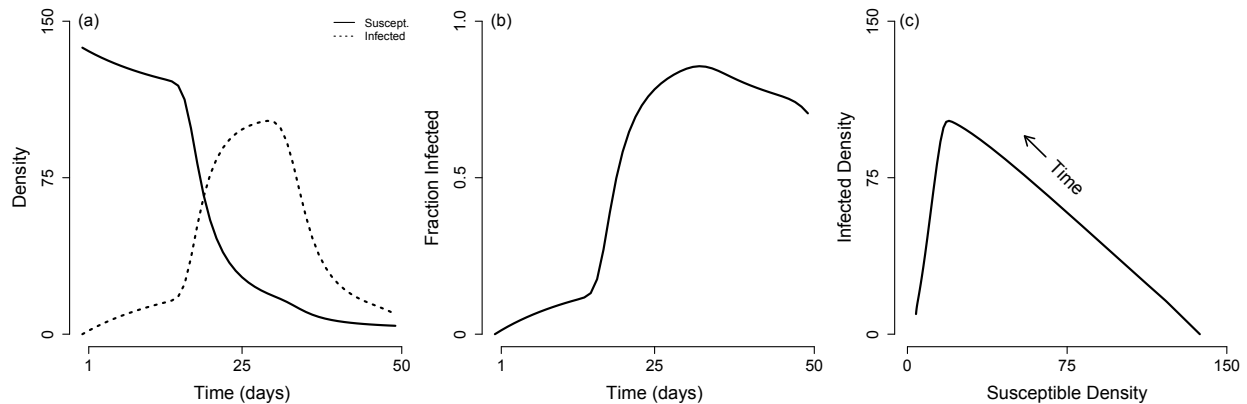


Figure 1: Dynamics of the deterministic version of the stochastic SEIR model, equations 1. (a) Simulated 50-day epizootic, showing only infected and susceptible host densities. In the model, the total infected host density is equivalent to the sum of the densities in the exposed classes, $\sum E_m$. (b) From the same simulation, the fraction of the host population that is infected, calculated as $\frac{\sum E_m}{\sum E_m + S}$. (c) Phase portrait of the same simulation.

219 To test whether naturally occurring virus and sprayed virus differ in infectiousness \bar{v} , we
 fit two classes of models (Polivka et al., 2017). In the “1- \bar{v} ” class, we assumed that the average
 transmission rate was the same for naturally occurring virus and sprayed virus. The 1- \bar{v} models
 222 therefore assume that differences in infection rates between epizootics were due only to differ-
 ences in initial densities of hosts and pathogens. In the “2- \bar{v} ” class of models, we instead allowed
 for the possibility that sprayed virus has a different infectiousness than natural virus, as reflected
 225 in differences in transmission parameters \bar{v} between sprayed and unsprayed plots.

The epizootic data

Our epizootic data came from 7 unsprayed control plots and 5 sprayed treatment plots. At the
 228 beginning of the larval period at each site, initial host and pathogen population densities were
 estimated using standard methods, which provided initial conditions for our models (Online

Appendices). The data consist of approximately weekly observations of the fraction of larvae
231 infected with the virus, for up to 50 days, approximately mid-June to mid-August. In sprayed
plots, insects were collected within 7 days after application of the virus, while in control plots,
the start of collections was more variable, particularly at sites where there was no concurrent
234 spray project. Collected insects were reared in the lab in individual 2 oz (59.1 ml) cups with
artificial diet at 25°C until pupation or death. Smears from dead insects were examined under
a light microscope for the presence of occlusion bodies, which are easily visible at 400× power
237 (Fleming-Davies et al., 2015; Polivka et al., 2017).

Experimental data

To estimate average transmission \bar{v} and heterogeneity in transmission C , we used a field ex-
240 periment in which we allowed for a single round of transmission on Douglas-fir branches in
the field. Measuring transmission in the field ensures that larval feeding, and thus baculovirus
transmission, occur naturally (Cory and Hoover, 2006). We then fit a simplified version of our
243 SEIR model to the fraction of insects infected in the experiment (Online Appendices). We used
three baculovirus isolates: TMB-1, the isolate used for biocontrol, and two naturally occurring
isolates collected from Washington and New Mexico, which we refer to as “WA” and “NM”.
246 Each branch encompassed roughly 0.15 m^2 of foliage, whereas our epizootic data were collected
in populations that covered roughly 10 hectares.

To estimate the average speed of kill, $1/\delta$, we infected larvae by allowing them to feed on
249 Douglas-fir foliage that was contaminated with a sprayed virus solution (Online Appendices).
Because there is no reason to believe that laboratory conditions lead to biased estimates of the
speed of kill, this experiment was carried out in the laboratory. Because speed of kill is affected
252 by temperature, we were careful to hold the larvae at temperatures typical of field conditions
(Polivka et al., 2017).

To estimate the ratio parameter, ρ , we again infected larvae in the laboratory, but in this case
255 we infected both hatchlings and fourth instars using virus-contaminated artificial diet (Online

Appendices). We held these larvae in the lab until death or pupation, and we counted the number of occlusion bodies per dead larva for both instars, using a light microscope and a
258 hemocytometer.

Model fitting and model selection

Modern methods of fitting models to data generally rely on calculations of likelihood scores,
261 which are measures of the goodness of fit of a model. On a log scale, and with a normal likelihood function, maximizing the log likelihood is equivalent to minimizing the sum of squares. In our case, however, the data are fractional infection rates, and so we used a beta-binomial likelihood function, which allows for the binomial nature of the data, while also allowing for the
264 possibility of extra-binomial variation ((McCullagh and Nelder, 1989), also Online Appendices). Because our experimental and observational data sets are independent, we could have calculated
267 likelihoods by simply adding the log likelihoods of the two data sets, following a maximum-likelihood approach (Bolker, 2008). If we had added experimental and observational likelihoods, however, the total likelihood score would have been very different than if we had only calculated
270 likelihoods based on the observational data. A maximum likelihood approach would thus make it impossible to formally compare model predictions with and without the experimental data.

We therefore followed a Bayesian approach. Bayes' theorem can be written as:

$$P(\theta|D) \propto \pi(\theta)\mathcal{L}(\theta|D), \quad (2)$$

273 where $P(\theta|D)$ is the posterior probability of the model fit to data D . The symbol $\pi(\theta)$ is the prior probability of the parameter values, and $\mathcal{L}(\theta|D)$ is the likelihood of the parameters. Because in general posterior probabilities are only used for comparison purposes, we only need to calculate
276 the posterior probability up to a constant of proportionality, hence our use of the proportion symbol \propto .

The posterior distribution of the parameters for each model can then be used to calculate a
279 WAIC score for that model. Like AIC and other model-selection criteria (Konishi and Kitagawa,

2008), WAIC identifies the best model by balancing the poorer fit of simpler models against the more uncertain predictions of more complex models (Gelman et al., 2014). Unlike AIC, however, WAIC is fully Bayesian, and so in calculating the ability of the model to predict future or out-of-sample data, WAIC takes into account the effects of the model's priors on the model's predictive performance (Online Appendices). Although it is possible for a model with priors constructed from experimental data to have a better (lower) WAIC score than a model with uninformative priors, given the difference in scales between our experimental data and our epizootic data, such an outcome seems unlikely. For models with priors based on experiments, we therefore treat WAIC scores that are only modestly worse (larger) than the best score as an indication that mechanisms at a small scale help to explain disease spread at a large scale.

Results

Epizootics

The number of larvae collected varied between studies due to differences in overall design, initial host density, and the resources available for collections. Also, near the end of epizootics, sample sizes usually dropped because high baculovirus mortality made it hard to find live larvae (cadavers disintegrate too rapidly to allow for meaningful collections). The number of larvae collected per week therefore ranged from 7 to 197, with a mean of 95.6, and with a total across sites of 5830 (Otvos et al., 1987; Polivka et al., 2012; Scott and Spiegel, 2002). In fitting our models, we then had 61 observations of virus infection rates, 30 at control sites and 31 at sprayed sites. Initial host densities spanned almost two orders of magnitude, ranging from 7.20 to 232.0 larvae/ m^2 , with a mean of 103.2. The control and sprayed sites had similar ranges and means of initial larval host density (Online Appendices).

Initial infection rates in controls were low, but increased slowly over the larval period (fig. 2), as expected, such that it took weeks for the infection rate in populations with lower initial host densities to reach high levels. Sprayed sites in contrast received an initial inundation of the

pathogen, and so infection rates in those sites increased within a week or two after the spray
306 application. Host population collapse was therefore rapid in the sprayed sites, leading to weaker
effects of initial host density.

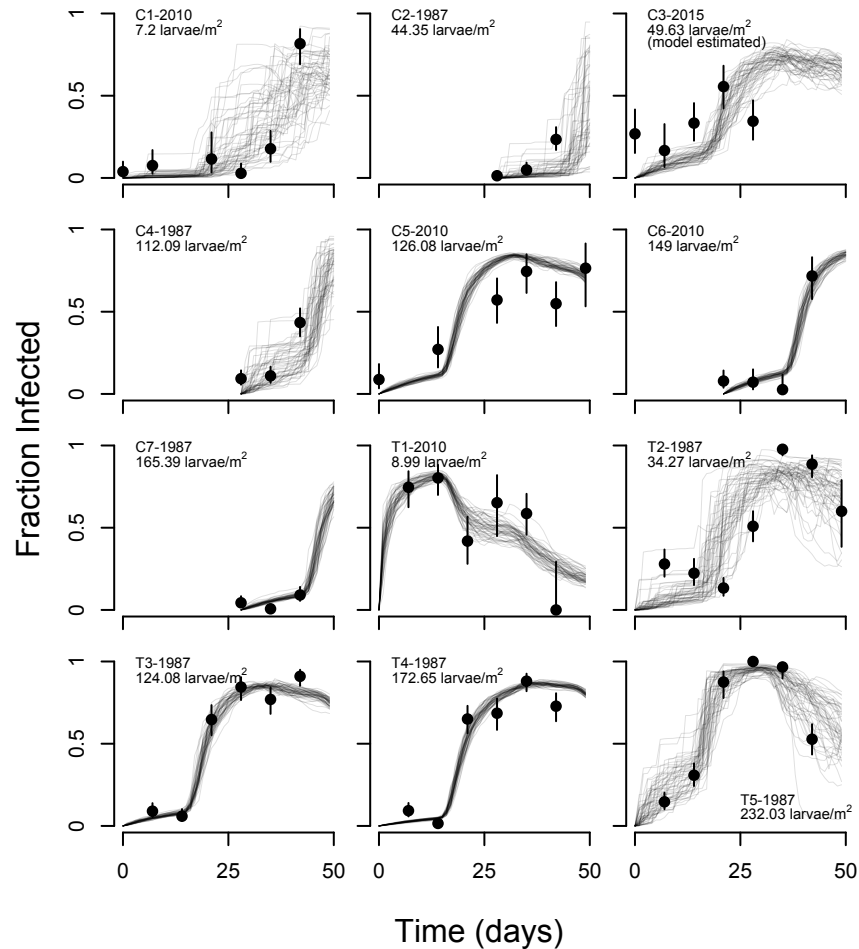


Figure 2: Stochastic realizations of the best fitting model (gray lines), which uses uninformative priors on all parameters, versus the data (black points with 95% binomial confidence intervals as error bars). The labels C and T stand for Control and Treatment, respectively, and are followed by the year of observation. The initial larval host density is also shown. Note that for the Colorado site (C3-2015), the initial larval host density was estimated from the data. Here and in subsequent figures, for two of the populations (C3-2015, C4-1987), we show the model's predictions after the last data point was collected, to illustrate the overall dynamics of the pathogen.

Experiments

309 Compared to the case in which hosts are identical, variation in risk leads to higher infection rates
at low virus density, because some hosts are highly susceptible, and lower infection rates at high
virus density, because some hosts are highly resistant (Dwyer et al., 1997). On a log scale, the
312 fraction uninfected is then a nonlinear (concave) function of baculovirus density (Online Appen-
dices). For two of the three strains that we tested, the best-fit model has a strongly nonlinear
shape (fig. 3), and so the model that provides the best overall explanation for our experimental
315 data includes host heterogeneity in infection risk.

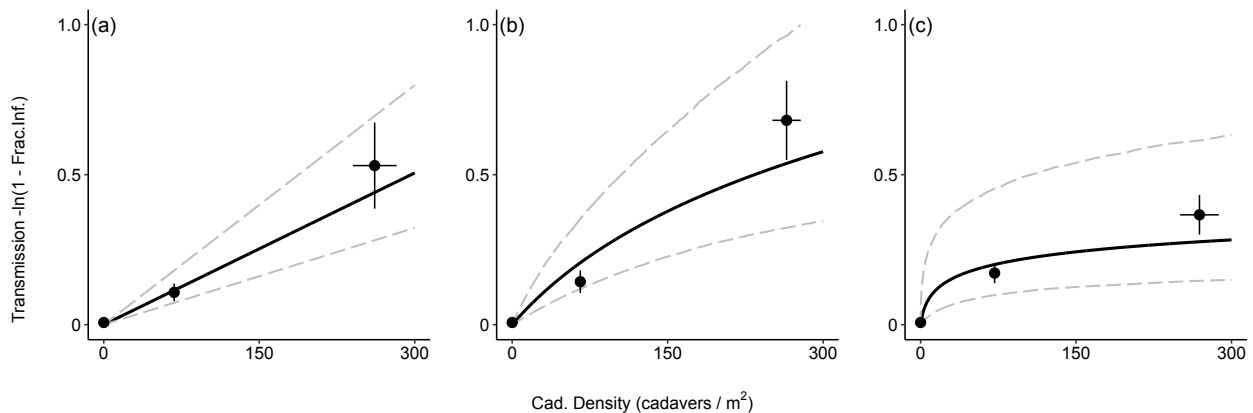


Figure 3: Results of the field transmission experiment. Best-fit transmission parameters (average transmission, \bar{v} , and heterogeneity, C) for three viral isolates, in terms of medians with interquartile ranges. (a) WA (\bar{v} : 0.006 (0.004, 0.007); C : 0.60 (0.34, 0.93)), (b) TMB-1 (\bar{v} : 0.012 (0.009, 0.017); C : 1.52 (1.17, 1.88)), and (c) NM (\bar{v} : 0.076 (0.027, 0.309); C : 4.11 (3.31, 4.96)). In the figure, the solid lines represent the median fitted expectations assuming heterogeneity. The gray dashed lines represent boot-strapped 95% credible intervals. Error bars are one standard error of the mean.

Fig. 3 also shows that the three isolates differed strongly, such that the NM isolate had much
higher heterogeneity in transmission, and in general higher average transmission rates \bar{v} were
318 associated with higher variation in transmission C . With only 3 isolates, we cannot reach general

conclusions, but in the gypsy moth baculovirus, more extensive data revealed a negative correlation between the average and the CV of transmission, consistent with this pattern (Fleming-Davies et al., 2015). A similar correlation may therefore occur in the tussock moth baculovirus. More immediately, the variation across isolates is important when we use our experimental data to explain the epizootic data, because in the epizootic data, we have no information about the isolates that were present. In constructing informative priors from our experimental data, we therefore allowed for uncertainty due to isolate variation by pooling the marginal posterior distributions for the three isolates and inflating the pooled variance slightly (Online Appendices).

When we measured the speed of kill of infected larvae in the laboratory, the average was $14.9d$, with very low variance. The mean value of the death rate is then $\delta = 1/14.9 = 0.067$. Because our sample size was modest ($n = 38$ larvae), we inflated the variance on the prior for δ (Online Appendices). This precautionary variance inflation, however, had no effect on our results.

Model selection

In general, our MCMC routines converged rapidly, except for models with no heterogeneity in infection risk ($C = 0$, table 1). Relative to the no-heterogeneity case, heterogeneity in infection risk modulates the effect of host density, such that, at high host density, heterogeneity reduces infection rates, due to the dominating effects of resistant individuals, while at low host density, heterogeneity increases infection rates, due to the presence of at least a few highly susceptible individuals (Dwyer et al., 1997). This effect is roughly apparent in fig. 2, in that infection rates were high across a very broad range of densities. Because of this effect, models that do not account for heterogeneity provide poor fits to data from populations at either very low or very high density.

This lack of fit led to a biased and highly uncertain value of the death rate parameter δ . In this obligately lethal pathogen, a fast death rate of infected-but-not-yet-infectious hosts causes more rapid disease spread and thus higher infection rates. When fitting the no-heterogeneity model

345 to the data from low-density populations, the fitting routine therefore attempted to improve the
fit by increasing δ , so that the best (median) estimate was much higher than our experimental
estimate (median speed of kill $(1/\delta) = 5.17d$, compared to an experimental median of $14.9d$).
348 The necessity of also fitting the high-density populations, however, meant that δ was not well-
identified, leading to a large upper bound (95% credible interval (Bayesian confidence bound)
on the speed of kill: $2.45 - 16.10d$). Moreover, as we will show, the lower bounds on the credible
351 intervals for the heterogeneity parameters for all the $1-\bar{\nu}$ models are well above zero (lowest 95%
credible interval for $C = 0.61$, Online Appendices). Heterogeneity in infection risk therefore
appears to be substantial in tussock moth populations. We therefore conclude that heterogeneity
354 in infection risk plays a key role in epizootics of the tussock moth virus, and we do not consider
the no-heterogeneity models further.

WAIC scores (table 1) then showed that the best explanation for the epizootic data comes from
357 models that assume that there is no difference between sprayed virus and naturally occurring
virus. As table 1 shows, two of the $2-\bar{\nu}$ models had $\Delta\text{WAIC} < 3$, and were thus indistinguishable
from the best $1-\bar{\nu}$ models (Bolker, 2008). For the best $2-\bar{\nu}$ model, however, the credible interval
360 on the difference between the two values of $\bar{\nu}$ for the model included zero (CI: $-0.13, 2.56$, Online
Appendices), indicating that the best $1-\bar{\nu}$ model and the best $2-\bar{\nu}$ model are effectively identical.
Because the $1-\bar{\nu}$ model is more parsimonious, we conclude that differences in infectiousness
363 between sprayed virus (TMB-1) and naturally occurring virus were negligible. The epizootic data
are thus better explained by models that allow only for differences in initial host and pathogen
densities across populations.

366 Table 1 also shows that, within the $1-\bar{\nu}$ class of models, the model with uninformative priors
on all parameters is the best model, as we expected. Nevertheless, for three $1-\bar{\nu}$ models with pri-
ors based on experimental data, WAIC scores were less than about 3, and thus were effectively
369 indistinguishable from the score for the best model. These three models were the model with an
informative prior on the death rate δ , a model with an informative prior on the heterogeneity pa-
rameter C , and a model with informative priors on δ , C , and the ratio parameter ρ . In the Online

Model	Informative Priors	Average Likelihood $\sum -\log(\hat{L})$	Penalty Score $p\text{WAIC}_2$	WAIC	ΔWAIC
1 \bar{v}	None	-197.33	5.95	406.58	0
	δ	-197.05	6.34	406.79	0.21
	$C \rho \delta$	-197.77	7.00	409.52	2.94
	C	-197.09	7.71	409.61	3.03
	ρ	-198.38	7.44	411.64	5.06
	\bar{v}	-199.20	7.08	412.57	5.99
	$C \rho \delta \bar{v}$	-198.13	8.55	413.37	6.79
	None, $C = 0^a$	-208.62	No Convergence		
2 \bar{v} , Spray & Control	δ	-196.63	6.74	406.74	0.16
	None	-196.89	7.35	408.47	1.89
	$C \rho \delta$	-196.46	8.81	410.54	3.96
	\bar{v} , TMB-1 ^b	-198.24	9.10	414.68	8.10

Table 1: WAIC model selection for observational data. Models for which $\Delta\text{WAIC} < \approx 3$ are considered to be indistinguishable from the best model, and are therefore shown in bold face. ^aBecause the model with no heterogeneity in transmission ($C = 0$) did not converge, the likelihood score for that model is a rough estimate based on non-converged MCMC samples. ^bFor this model, the prior on the \bar{v} value in the sprayed plots was based on our experimental estimate for the sprayed virus, TMB-1.

372 Appendices, we show that the visual fit of these models to the data is almost indistinguishable from the fit of the best model, and here we discuss what this result means for the relevance of our experiments for understanding epizootics.

375 First, our laboratory measure of the speed of kill, the inverse of δ , apparently provides a reasonably accurate representation of speeds of kill in nature. This is at least moderately surprising, given that temperatures control death rates, and given that temperatures in nature likely

378 fluctuate in a complex way, while temperatures in our lab experiment were tightly constrained.
Temperature variation in nature may therefore play only a minor role in epizootic dynamics.
Our measure of the ratio parameter ρ may similarly be not that far from typical values of ρ in
381 nature. This result is perhaps less surprising, given that ρ depends only on counts of occlusion
bodies, which are likely to be the same in the lab as in the field. The success of models with
experiment-based priors on heterogeneity C is more surprising, given that C was measured in
384 a field experiment. Mechanisms that affect variation in infection risk across individuals may
therefore act in similar ways at the scale of single branches, and at the scale of entire epizootics.

In contrast, models that had informative priors on \bar{v} provided meaningfully worse explanations
387 tions than the best model, with Δ WAIC values of 6 or more (Table 1). There may therefore be
mechanisms operating at large spatial scales and long temporal scales that are not accounted for
in our experiments. For example, Douglas-fir tussock moth larvae tend to occur at slightly higher
390 densities near the crowns of trees (C. Mehmel, unpublished), and this aggregation may increase
infection rates relative to our experiments (Dwyer and Elkinton, 1993).

Evidence for effects of such large-scale mechanisms on the transmission of this or other bac-
393 uloviruses, however, is almost entirely lacking (D'Amico and Elkinton, 1995; Dwyer, 1991). More-
over, failed efforts to estimate the decay rate μ experimentally suggest that μ may be very low
for this virus (Dwyer (1991), Online Appendices). This is important because the median values
396 of μ estimated for models with experiment-based priors on transmission \bar{v} are much lower than
the median values of μ estimated for the other models. Better experimental estimates of μ might
thus support the models with experiment-based priors on \bar{v} .

399 The worse fit provided by the models with informative priors on \bar{v} therefore may not have a
direct biological interpretation. Instead, it may arise from the statistical effects of compounded
error in the observational and experimental data sets. Notably, our experimental estimate of \bar{v}
402 depends on our estimate of the ratio parameter ρ , such that high values of ρ lead to low estimates
of \bar{v} (Online Appendices). Estimating ρ is difficult enough that such underestimation may have
been a significant problem (Online Appendices), and this may be why our experimental estimate

405 of \bar{v} is substantially lower than the posterior median values of \bar{v} from the cases in which we
 used uninformative priors (fig. 4). For the other parameters the posterior medians when we
 used experiment-based priors were remarkably similar to the posterior medians when we used
 408 uninformative priors.

Also, the predictions of the SEIR model, equations (1a)-(1d), are quite sensitive to small
 changes in the transmission parameter \bar{v} , but are only moderately sensitive to changes in the
 411 heterogeneity parameter C (Dwyer et al., 1997). The models with informative priors on \bar{v} may
 therefore have performed poorly because small errors in our estimate of \bar{v} have bigger effects
 than small errors in our estimate of C . This problem may have been made worse by the strong
 414 variation across pathogen isolates that is apparent in our experimental data (fig. 3), a point that
 we consider further in the Discussion. Moreover, the fit to data of the model with experiment-
 based priors on C , ρ , δ , and \bar{v} is only slightly worse (fig. 5) than the fit of the model with all
 417 uninformative priors (fig. 2), in spite of the former model's substantially worse WAIC score.

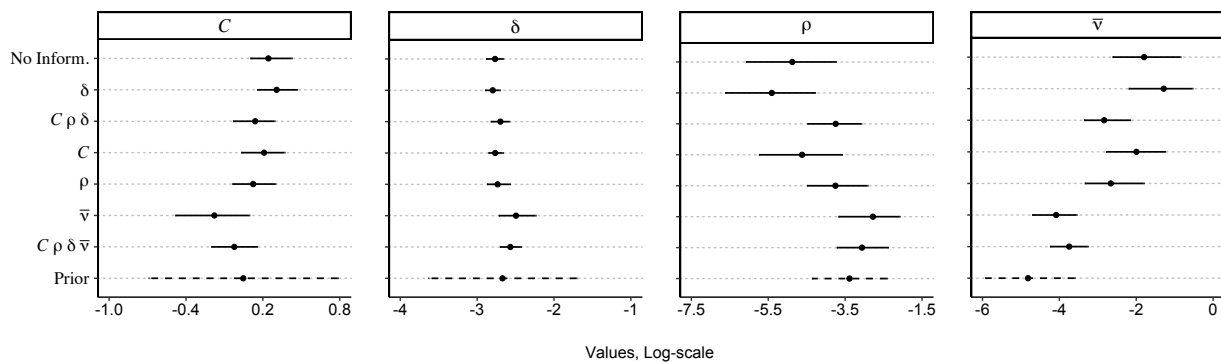


Figure 4: Marginal posterior parameter estimates (columns) from the $1-\bar{v}$ class of models (rows), compared to the informative prior distributions derived from experiments (dashed lines). Dots are median values, while bars are 95% credible intervals. Note that each panel has a different scale on its horizontal axis.

Another reason why the models with informative priors on the transmission parameter have
 larger (poorer) WAIC scores is that the best way for these models to fit the low-density plots
 420 is by assuming that stochasticity was higher in those plots, an effect that is clearly apparent

in fig. 5. Increased stochasticity produces poorer WAIC scores because the model-complexity term increases with the variance in the likelihood, which of course increases with stochasticity. Surprisingly, however, increased stochasticity also increases infection rates. This is because increased stochasticity raises the rate at which both very low and very high transmission rates occur in our simulations, but higher transmission rates have disproportionately strong effects (in the Online Appendices, we prove this assertion). When fitting models with an informative prior on the transmission rate, the fitting algorithm therefore compensates for low transmission rates by increasing the stochasticity parameter σ .

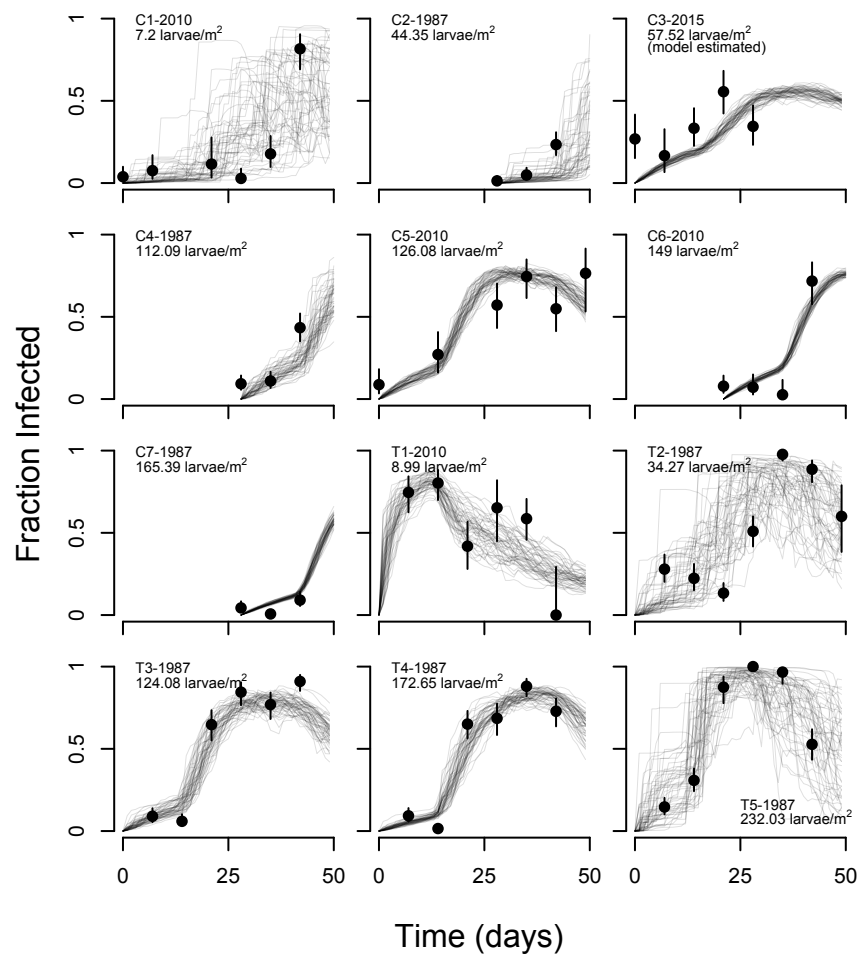


Figure 5: Stochastic realizations of the model with informative priors on \bar{v} , C , ρ , and δ , with symbols and labels as in fig. 2

429

The Disease-density Threshold

As table 2 shows, our estimates of the disease-density threshold μ/\bar{v} are remarkably consistent, even though our estimates of μ and \bar{v} differ depending on whether we take into account our
432 experimental data. This is a consequence of a strong correlation in the posterior samples of \bar{v} and μ (Online Appendices), which in turn reflects the similar effects that transmission rates and removal rates have on disease dynamics. From a statistical perspective, the correlation means that
435 separate estimation of \bar{v} and μ requires more data than if the two parameters were not correlated, supporting our use of experimental data.

Model (Informative Priors)	Disease-Density Threshold (μ/\bar{v})
None	0.29 (0.01, 1.04)
δ	0.16 (0.003, 0.60)
$C \rho \delta$	0.29 (0.001, 1.66)
C	0.40 (0.03, 1.19)
$C \rho \delta \bar{v}$	0.29 (0.01, 1.57)
ρ	0.47 (0.01, 2.18)
\bar{v}	1.05 (0.03, 4.38)

Table 2: Estimates of the disease-density threshold for each model, presented in order of increasing WAIC scores. Estimates are shown as medians with 95% credible intervals in parentheses. Thresholds are in units of larvae/ m^2 .

Our estimates of the disease-density threshold suggest that it may be effective to spray tussock
438 moth populations that are well below densities at which significant defoliation occurs. Densities slightly above the threshold are too low to produce defoliation, but are apparently high enough to support at least modest epizootics. The reason why epizootics do not normally occur at such
441 densities is probably that there is a delay between when the insect population begins to increase,

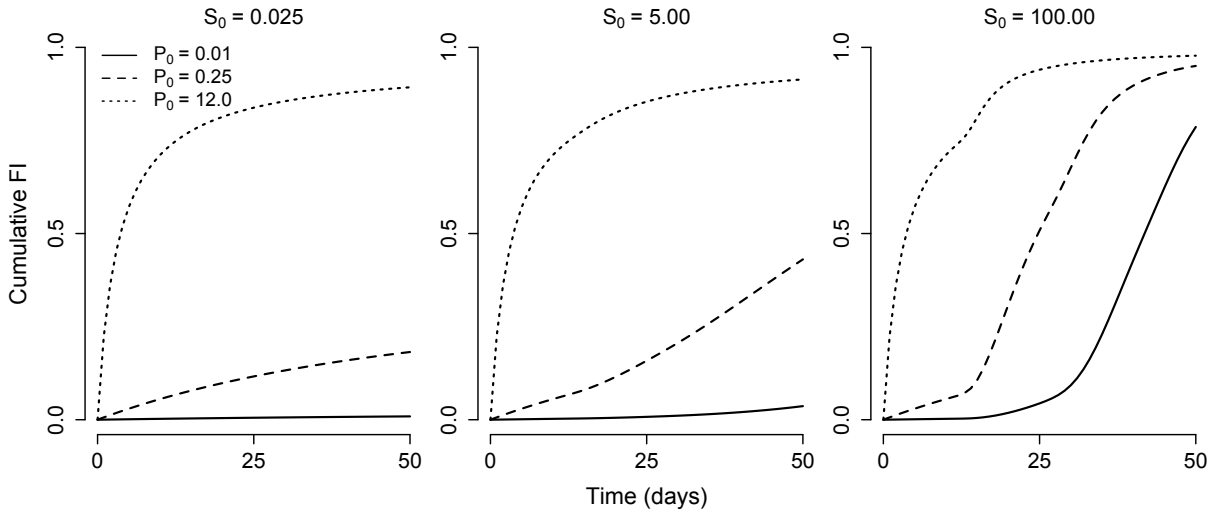


Figure 6: Simulated trajectories of cumulative mortality (i.e. cumulative fraction infected (FI)), where S_0 and P_0 are the initial host densities (larvae m^{-2}) and virus densities (infectious cadaver equivalents m^{-2}), respectively.

and when the baculovirus population begins to increase. This effect is known from both long-term insect outbreak models (Dwyer et al., 2000), and classical predator-prey models (Kot, 2001).

444 In the case of the tussock moth baculovirus, the delay may be so severe that it may make economic sense to spray tussock moth populations that would otherwise require an additional 2 or 3 years of increases before natural baculovirus epizootics would occur.

447 This point can be made more explicit by considering how the model behavior varies with initial host and pathogen densities. The middle panel in fig. 6 shows that, for an initial density of 5 larvae/ m^2 , the input of a modest amount of virus can lead to a reasonably severe epizootic.
450 This density is lower than all but one of the spray plots in our data set (fig. 2), emphasizing that spray programs could be successful even at low densities. In the data for the treatment plot in 2010, for example, spraying a population with an initial density of 9 larvae/ m^2 produced high
453 mortality.

Meanwhile, at high host densities, infection rates are likely to be high even for very low ini-

tial pathogen densities, an effect that is well known from epidemiological theory (Keeling and
456 Rohani, 2008). This effect is apparent in the rightmost panel in fig. 6, for which the initial host
density of 100 larvae/ m^2 is lower than in 3 of our 5 spray plots. Virus mortality may therefore
have been high in those 3 plots even if they had not been sprayed. Previous researchers recom-
459 mended that “a natural virus level greater than 25% indicates a [tussock moth] population that
is already about to collapse from an epizootic, so direct control is not necessary” (Brookes et al.,
1978; Stelzer, 1979). Our work suggests that this rule of thumb is too conservative, especially in
462 high-density populations.

Discussion

The success of our models (fig. 2) strongly supports the hypothesis that density-dependent trans-
465 mission drives epizootics of the tussock moth baculovirus. For many vertebrate diseases in con-
trast, the logistical hurdles of data collection often make it difficult to test for effects of density on
transmission (McCallum, 2016; McCallum et al., 2001). In the insect pathology literature, the im-
468 portance of density is widely acknowledged (Moreau and Lucarotti, 2007), but there is also a long
tradition of explaining epizootics by invoking complex mechanisms other than density (Fuxa and
Tanada, 1987). Perhaps for this reason, disease-density thresholds are invoked less commonly in
471 microbial control than in wildlife conservation, yet the unexpected natural epizootics discussed
here are not unusual in microbial control (Moreau and Lucarotti, 2007; Podgwaite, 1985; Wollam
et al., 1978). A clearer consideration of the effects of host and pathogen densities could therefore
474 improve control strategies (Brown, 1987; Moscardi, 1999; Podgwaite, 1985).

This is especially true for efforts to control tussock moth populations, which rarely consider
host density as a factor influencing the effectiveness of control. Instead, host density is used
477 to predict how much defoliation damage will occur, and thus whether control measures should
be implemented (Maclauchlan et al., 2009; Mason and Wickman, 1991). Previous protocols in
this system have nevertheless suggested that host densities are important and that costs could

480 be reduced by spraying earlier, lowering the dosage of sprayed virus, or reducing the area of application (Maclauchlan et al., 2009; Otvos et al., 1998). By forecasting the severity of natural epizootics relative to microbial control, parameterized epidemiological model like ours could
483 serve as useful tools in such efforts (Otvos et al., 1998), leading to decisions that incorporate the relative costs of spraying versus defoliation.

Indeed, our models confirm that in some cases the best way to reduce the costs of tussock
486 moth control is to forgo a spray program altogether (fig. 6, table 2). Previous efforts to estimate initial virus incidence in tussock moth populations, however, have often relied on small sample sizes (Stelzer, 1979). At small sample sizes, the virus may be undetected even though it is present
489 at a high enough density to cause a severe epizootic in a dense host population. Inaccurate estimation of the initial fraction infected can therefore lead to the unnecessary application of virus spray, suggesting that more intensive sampling may be worth the effort. This is especially
492 true given that the model predictions are more strongly affected by such inaccurate estimation when host densities are intermediate. It is nevertheless important to recognize that low initial infection rates may mean that it takes weeks or months for substantial mortality to occur. During
495 this delay, defoliation may be economically significant, and so microbial control may be necessary despite a high observed population density.

Our estimates of the heterogeneity parameter C are mostly greater than 1, and thus high
498 enough to prevent outbreaks in insect-pathogen models unless there is fluctuating selection for disease resistance (Elder et al., 2008). Natural selection may therefore play a key role in tussock moth population cycles, as in the gypsy moth (Páez et al., 2017). More broadly, genetic variation
501 in susceptibility to disease is omnipresent (Keeling and Rohani, 2008), and so it seems likely that the lack of evidence for host-variation effects in other pathogens is due to a lack of consideration of host-variation effects, rather than to an actual lack of host variation. From a biological-control
504 perspective, high heterogeneity means that a substantial fraction of the population will survive even a severe epizootic. This does not mean, however, that defoliation will occur in the following year, because over-wintering virus may decimate the host population in the following year.

507 It is also important to point out the ways in which our models do not explain the data. First,
the success of models with experiment-based priors on the heterogeneity parameter suggests that
transmission at a small scale helps drive epizootics at a large scale, but the poor performance of
510 models that use priors on the transmission rate suggests that larger scale mechanisms also play
a role. Second, our models require at least moderate stochasticity in transmission to explain the
epizootic data, but they do not identify the source of this stochasticity. An important future di-
513 rection is therefore to consider aspects of the biology of the disease that are not in the model. For
example, there are two morphotypes of the baculovirus that may differ in infectiousness (Mar-
tignoni and Iwai, 1977), and the frequency of the morphotypes varies with latitude (Williams
516 et al., 2011). Allowing for this variation in our models was impractical, because the data do
not include information about which morphotype was present in each epizootic, but pathogen
variation may help explain why models with informative priors on transmission were less suc-
519 cessful. More concretely, the latitudinal variation in the virus means that microbial control of
the Douglas-fir tussock moth may be improved if different morphotypes are used at different
latitudes. Understanding the consequences of morphotype variation for epizootic severity is
522 therefore a key priority in future work. Long-term host-pathogen models have shown that insect
pathogens can drive host population cycles (Anderson and May, 1980; Hochberg, 1989), and our
work suggests that more mechanistic versions of such models (Dwyer et al., 2000) could be useful
525 in guiding microbial control. Previous efforts to model Douglas-fir tussock moth population dy-
namics in contrast have focused on insect population growth and forest biology (Bousfield et al.,
1984; Colbert et al., 1979; Mason and Wickman, 1991; Monserud and Crookston, 1982; Moore
528 and Hatch, 1981), while providing only highly simplified descriptions of baculovirus dynamics
(Brookes et al., 1978). Another future direction is therefore to extend the SEIR-type models that
we have presented here to allow for long-term dynamics.

531 Parameterized models of baculovirus dynamics that could be used in microbial control pro-
grams are exceedingly rare (Brown, 1987). This is partly because baculovirus sprays are not
widely used, due to the high cost of *in vivo* propagation, and the failure of *in vitro* propagation

534 methods, which lead to the emergence of strains that do not produce occlusion bodies (Lacey
et al., 2015). As is often the case in environmental management, however, a major obstacle to
the development of useful models has been the difficulty of estimating model parameters (Gren-
537 fell et al., 2002). As our works shows, high-performance computing and advanced statistical
algorithms are now sufficient to provide reasonably accurate parameter values. The high levels
of computing resources that we used are nevertheless often unavailable to environmental man-
540 agers, emphasizing the usefulness of collaborations between managers and university researchers
(Joseph et al., 2013).

Our Bayesian approach has the advantage that it allowed us to test the extent to which our
543 small-scale, experimental data help us to understand large-scale epizootic data. More conven-
tional maximum-likelihood methods have driven the development of flexible “plug-and-play”
software, which has been used to fit complex models like ours to data (Ionides et al., 2006, 2015;
546 King et al., 2016), leading to important insights into disease dynamics (King et al., 2016; Mar-
tinez et al., 2016; Ranjeva et al., 2017). Maximum likelihood methods, however, do not allow
for comparison of models that do and do not take into account prior information, thus prevent-
549 ing comparison of models that do and do not take into account experimental data. A Bayesian
version of particle filtering shows great promise, but sometimes fails to converge on the best
parameters (Ionides et al., 2015).

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